AUTOSAR^M

10BASE-T1S in AUTOSAR

Stéfany Chourakorn (BMW) Ethernet & IP @ Automotive – Virtual Event

14 Sept 2020 IEEE SA



BOSCH (Ontinental)

DAIMLER







VOLKSWAGEN

Agenda

- > 10BASE-T1S what is new ?
- > AUTOSAR overview
- > AUTOSAR solution for 10BASE-T1S
 - > Impact
 - Solution approach



Situation today

Diverse technologies co-existing

- Legacy buses
 Signal based, gateways
- Ethernet

Service oriented, switches, mostly for high data rates

More than 90% communication below 10Mbps

AUTOSAR Ethernet support today

- Switched network only
- 10Mbps up to Gbps



11-2009	1 st Ethernet specification in AUTOSAR
11-2019	10BASE-T1S publication, IEEE 802.3cg
11-2020	AUTOSAR R20-11, target for 10BASE-T1S support





10BASE-T1S what is new ?

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> AUTOSAR solution for 10BASE-T1S

Impact

Solution approach



10BASE-T1S what is new ? 1. More PHY products





10BASE-T1S what is new ? 2. New E/E architecture

10BASE-T1S enables Ethernet bus/multidrop topologies



10BASE-T1S what is new ?

3. Efficient medium access

- PLCA as an efficient new medium access allows for:
 - Reuse of the existing CSMA/CD structure
 - Fair medium access for all participant (Round robin)
 - Bandwidth optimization

Example early rescheduling scenarios

- Case 1 (Cycle N): only one node transmits.
 - ⇒ Transmission at t1 instead of t1'.
- Case 2 (Cycle N+1): one node does send shorter packet.
 Transmission at t2 instead of t2'







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AUTOSAR motivations

AUTOSAR aims to improve complexity management of integrated E/E architectures through increased reuse and exchangeability of SW modules between OEMs and suppliers:

- Decouple SW application from the HW
- Defines clear interfaces
- Specifies data exchange format



Sources: AUTOSAR

AUTOSAR standard

- Set of open specifications (application and basis software stack)
- Unified methodology and exchange format for system description as well as configuration
- Two platforms



Source: AUTOSAR





>

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Integration of 10BASE-T1S in AUTOSAR step by step

Milestones





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10BASE-T1S impacts in AUTOSAR

MS2: Elaboration

Which PLCA specificities are relevant for AUTOSAR ?

- Reconciliation Sublayer located in Layer 1
- Remains transparent from MAC perspective
- Half-duplex in multidrop / P2P or P2P for full-duplex / half-duplex

Pre-analysis of the main topics to details in MS3a:

- Component above driver layer untouched
- New configurations parameter related to PLCA
- Multidrop topology

Use cases

✓ Multidrop✓ Burst

✓ DoIP / OBD

- Partial network
- ✓ TimeSync (static Pdelay)

plcaActive plcaStatus toTimer nodeID nodeCount burstCounter burstTimer	PLCA Configuration Parameters	
plcaStatus toTimer nodeID nodeCount burstCounter burstTimer	plcaActive	
toTimer nodeID nodeCount burstCounter burstTimer	plcaStatus	
nodeID nodeCount burstCounter burstTimer	toTimer	
nodeCount burstCounter burstTimer	nodeID	
burstCounter burstTimer	nodeCount	
burstTimer	burstCounter	
	burstTimer	



10BASE-T1S impacts in AUTOSAR

MS2: Elaboration

First approach is to identify all the concerned working group within the consortium

- 10BASE-T1S is a physical layer
- Constrains: one head node per cluster and all nodes must have same time configuration



Source: AUTOSAR

New AUTOSAR Working Group for Time Synchronization is initiated for September 2020



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Solution approach

MS3a: Detail

Software Specification:

- Impact localized in the low level layers: Eth Driver and Eth Trcv
- Addition configuration parameter for PLCA (node id, burst, ...)
- Buffer handling to prioritize traffic

System Template / Manifest:

- Implement multidrop topology for Ethernet in model
- Constrain related (Head node unique in sub-cluster,...)





<u>Scheduler</u> SW FIFOs Stéfany Chourakorn | Ethernet & IP @ Automotive 14 Sept 2020 19

Prio 6 Prio 4

8

6

Prio 7

5

SW Buffer pools

Affects SWS EthDriver

- Optional implementation
- Scheduling before transmission
- Scheduler : simplified CBS (tocken bucket)
- Priorities from socket connexion



Step1

Step2

Bufldx 0

Eth_transmit

Eth ProvideTxBuffer

Prio 7

Bufldx 0



C> Eth MainFunction

ThresholdCounter

Step3

Solution approach

MS3b: Prototype validation



Head-node Routing N2 Node A 100BASE HN 1-0 CN 1-1 N1 10BASE-T1S 10BASE-T1S interface 100BASE-TX interface PLCA Mode for 10BASE-T1S CN 1-2 NX, 10BASE-T1S = Network IDX with 10BASE-T1S Client Node from Network 1. PLCA Node ID 1

The 10BASE-T1S support should be validated by a prototypical implementation mostly focused on the Ethernet driver and transceiver driver (CP) for multidrop scenario.

Head-node

client-node

CN 1-1

Scope:

- Ensure message routing through the stack and timing are respected
- Buffer handling
- Error scenarios:
 - Lost of Head-node
 - Reactivation Head-node (Reset)



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Summary

Concept split in 2 parts

- R20-11: 10BASE-T1S MII/Transceiver PHY
- R21-11: 10BASE-T1S with SPI interface and 10BASE-T1S switch integration

10BASE-T1S keeps evolving...

- IEEE
- Open Alliance

...and so does Autosar

- Will keep track on the coming modifications on the Ethernet stack



Thank you for your attention

Concept owners

S. Chourakorn M. Zajicek G. Veloso Cauce

Supporters and Reviewers

B. Sostawa K. Matheus Microchip IVC-CP

