AME 3623: Embedded Real-Time Systems Andrew H. Fagg Symbiotic Computing Laboratory **Biomedical Engineering Center and** School of Computer Science University of Oklahoma

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#### What is an Embedded System?

Andrew H. Fagg: Embedded Real-Time Systems: Introduction

## What is an Embedded System?

- Computing system with a non-standard interface (often no keyboard or screen)
- Often involved in sensing and control (and may not even talk to a human)
- Typically a custom system for a very specific application

# What is an Embedded System? (cont)

- Limited processing capabilities:
  - Can be extremely small
  - Can require a small amount of power
- Can have significant real-time constraints

   Act on inputs very quickly
  - Generate outputs that can change quickly
- Often a higher expectation of reliability

#### What is an Embedded System?

Fundamentally about the bit meeting the atom and the photon...

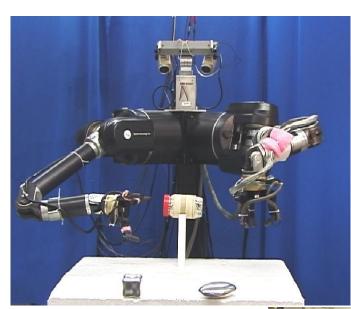
#### Examples of Embedded Systems

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#### Humanoid Robotics

#### NASA/JSC Robonaut





#### **UMass Torso**

#### OU "Yatima"



#### **Robotics**

Mark Tilden Los Alamos National Labs and Wowwee

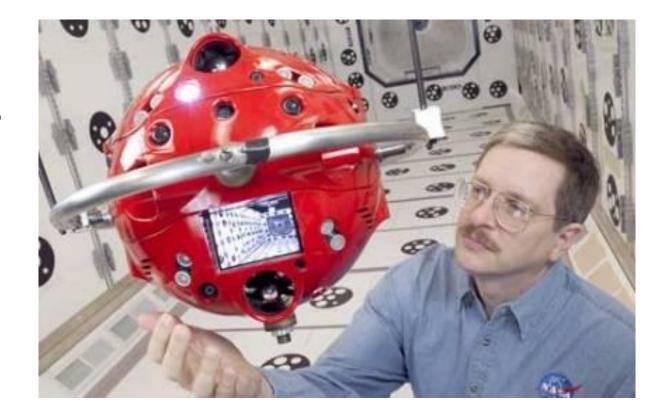
picture from *Robosapiens* 



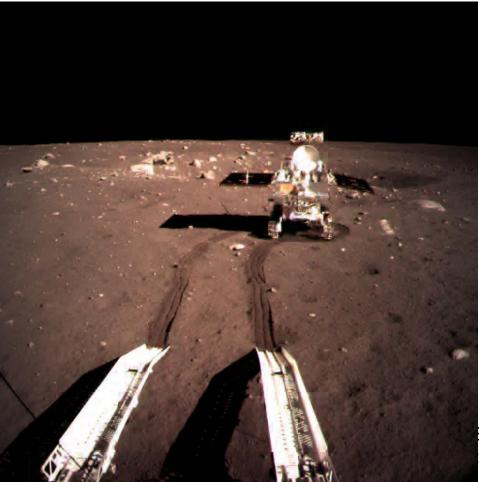
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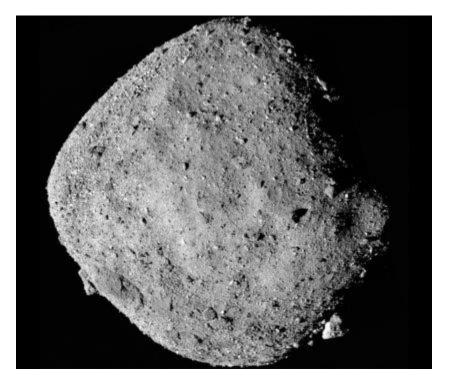
#### Personal Satellite Assistants

NASA Ames Research Center

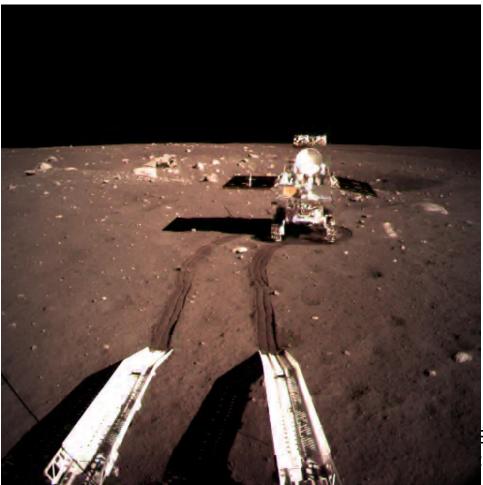


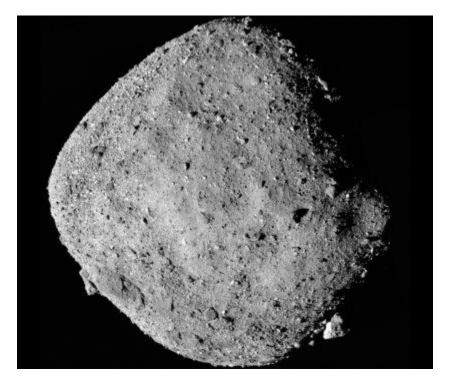
### Space Missions





#### Space Missions





#### Bennu

#### Chang'e 4

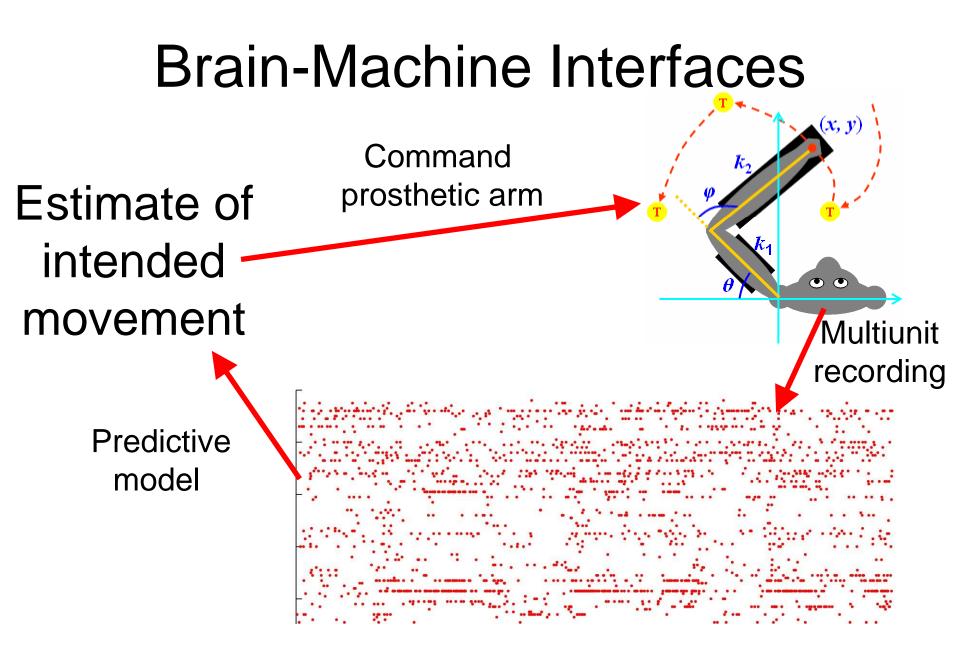
Embedded Real-

#### Intelligent Prosthetics

#### Hugh Herr MIT Leg Lab

## picture from *Robosapiens*





In collaboration with Nicholas G. Hatsopoulos and Lee E. Miller

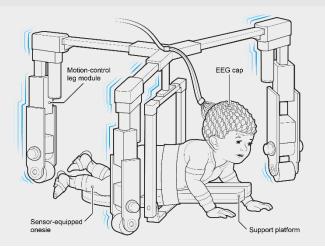
#### Real-Time Activity Recognition for Assistive Robotics





OU Crawling Assistant (Kolobe, Fagg, Miller, Ding) **How It Works** 

The SIPPC robot supports infants in a crawling position as they learn how to explore their surroundings.



Scientific American (Oct 2016)

#### Sensor Networks



1000 sensor

nodes



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#### **Embedded Systems Challenges**

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## **Embedded Systems Challenges**

- Sensing the environment:
  - Sensors are typically far from ideal (noise, nonlinearities, etc.)
  - Sensors/subsystems can fail
  - Hard to get a 'complete' view of the environment
- Affecting the environment through "actuators"
  - Application can require fast, precise responses

#### Embedded Systems Challenges (cont)

- Testing/debugging can be very difficult:
  - Hard to identify and replicate all possible situations
  - Often involves the interaction of many different components
  - Often no standard user interface
  - Limited on-board resources with which to record system state
- Competing requirements of cost, complexity, design time, size, power...

#### Embedded Systems Challenges (cont)

 Lack of reliability can be a killer ..... literally

## My Assumptions About You

- Circuits and sensors class (or equivalent):
  - Boolean logic
  - Analog circuits (in particular, resistive-capacitive circuits)
- One course background in programming
  We will be using C for all projects
- Everyone has a functional laptop that can be used for the projects

### How We Will Proceed

*Embedded Systems* is a mix of software, circuit, actuation, sensing and control

- Blend of theory and practice
- Practice requires practice:
  - Very hands-on
  - Don't be afraid to try things (but care must be taken)

#### **Course Goals**

In this course, you will:

- Design embedded circuits,
- Use code design tools,
- Design, program and debug embedded sensing and control software,
- Work in teams, and
- Practice your communication skills.

#### Sources of Information

- Primary readings:
  - Book: Programming Embedded Systems from Zyante
  - Selected web pages
- Class web page:

www.cs.ou.edu/~fagg/classes/ame3623

- Canvas: canvas.ou.edu
- Slack: discussion application

## You are responsible for making sure that you have access to all of these resources



## Preparing for Lecture

- Readings: you are responsible for reading these before our class time.
- The Zyante book includes a set of questions listed under "Participation Activities" in each chapter.
   Doing these questions is your homework (due by 8am the day that the reading is assigned).

"Challenge Activities" are not required

 In class, we will address any questions that you have about the materials, expand on what you have already done, and do quizzes/in-class exercises (some of which will be graded)

#### **Class Schedule**

www.cs.ou.edu/~fagg/classes/ame3623/schedule.html

- Lecture plans
- Required reading
- Assignments
- Due dates

#### Note: this schedule can change

## **Channels of Communication**

- Lecture
- Canvas announcements
  - You can configure Canvas to send you an email message or an alert on your phone every time a message is posted
- Slack application: you may post questions and answers
- Private email or office hours for non-public questions/discussions

## Grading

- Components of your grade:
  - Midterm exam: 15%
  - Final exam: 15%
  - Zyante activities: 15% (Keep highest N-1)
  - In-class quizzes and exercises: 15% (Keep highest M-1)
  - Eleven small projects:
    - 20% the work by your group
    - 20% your personal contributions to programming
- Grades will be posted on Canvas
- Final letter grades boundaries will be selected based on the overall class distribution

#### Exams

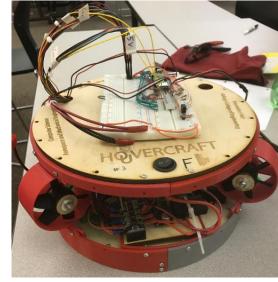
- On-line and real-time
- Mix of multiple choice and numerical questions
- Grading questions must be addressed within one week of return

#### In-Class Exercises

- Expand on readings
- Mixture of individual and group work
- Often graded

## **Group Projects**

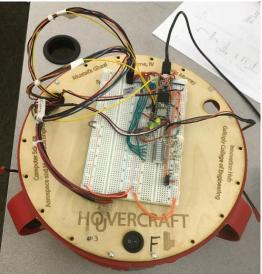
Focus: hovercraft control system



Each project:

- Discuss new project on Thursday
- In most cases: due the following Thursday (8:00am)
- Different components: circuit, mechanical, software, documentation

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## **Project Topics**

- Embedded processor programming (we are using "Teensies" this year)
- Analog processing and sensor models (distance sensing)
- Sensing lateral velocity
- Sensing heading and heading change
- Proportional-derivative control
- Finite state machines for mission-level control

## **Project Groups**

- Groups of ~3
- Projects 0 4:
  - Everyone will have their own hardware kit & work on each project
  - But collaboration within groups is fine
- Projects 5-10
  - One group member will have the full hovercraft kit for two weeks & be responsible for hardware/software/testing

## **Project Grading**

Project grades are a function of:

- Code correctness and readability
- Documentation of code and circuits
- Demonstration

These are assessed during a short "code review" with me or the TA

## Project Grading (projects 5-10)

Individual grades:

- Group grade scaled by the degree of your contribution to the group work (generally, this is balanced)
- Personal contributions: your pair of projects

## Group Projects (cont)

- Be ready to demonstrate project by the due date
- Projects require more than a day to complete
- Code/documentation will be handed in through Canvas/Gradescope
- Projects may be late (but I do not recommend this): 0-24 hrs: 10% penalty; 24-48 hrs: 20% penalty; 48+ hrs: 100% penalty

#### "Classroom" Conduct

- Ask plenty of questions
- Contribute to the discussions
- No: cell phone use and laptop use (except for classroom exercises)

\*\*\*More details in the syllabus

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#### **Proper Academic Conduct**

Homework assignments (Zyante) :

- All work must be your own: no looking at or copying solutions from other students or from the net
- General discussion is okay (e.g., the fundamental skills that we are learning)

• When in doubt: ask me or the TA

#### **Proper Academic Conduct**

Projects:

- All work must be that of your group: no looking at, discussing or copying solutions from other groups or from the net
- General discussion is okay

Secure your data

#### Next Time

- Zyante
  - Registration: access through Canvas
  - First assignment due Thursday morning
- Readings:
  - Introduction to Embedded Systems
  - Analog circuits review
  - Diodes
- Catme survey coming soon via email