



---

# Autonomous Moisture Continuum Sensing Network

Dara Entekhabi (PI, MIT)

Mahta Moghaddam (Co-I, USC)

Agnelo R. Silva (Consultant, METER Corp.)

**Ruzbeh Akbar** (Postdoc, MIT)

AIST-16-0049 ESTO Forum

06/14/2018

Silver Spring, MD



METER





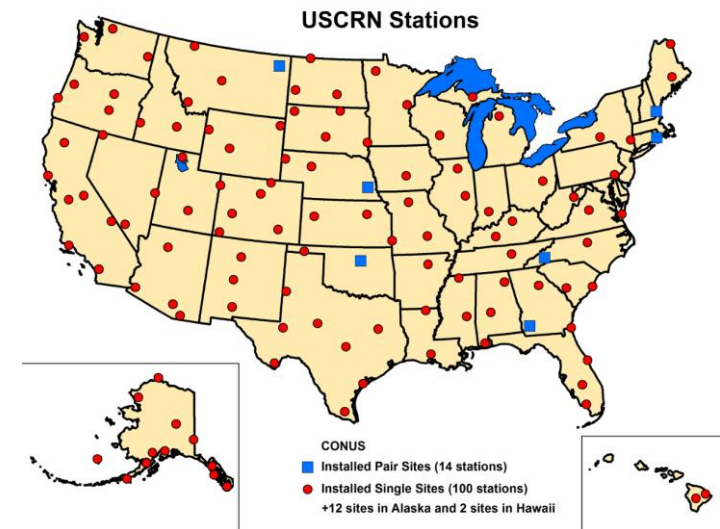
# Presentation Contents



- Motivation and Overview
- Background: SoilSCAPE.
- Technical Development ( $TRL_{in} = 2$ ):
  - Wakeup-on Radio
  - Machine Learning Decision Making
- Summary

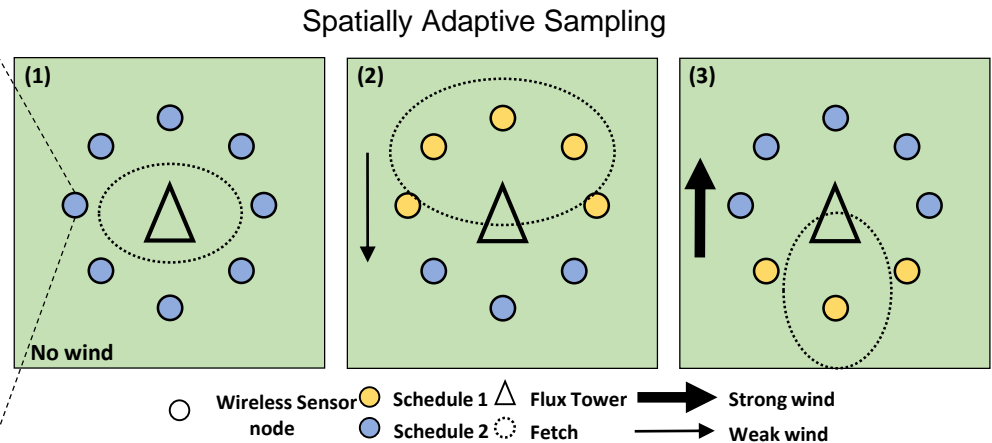
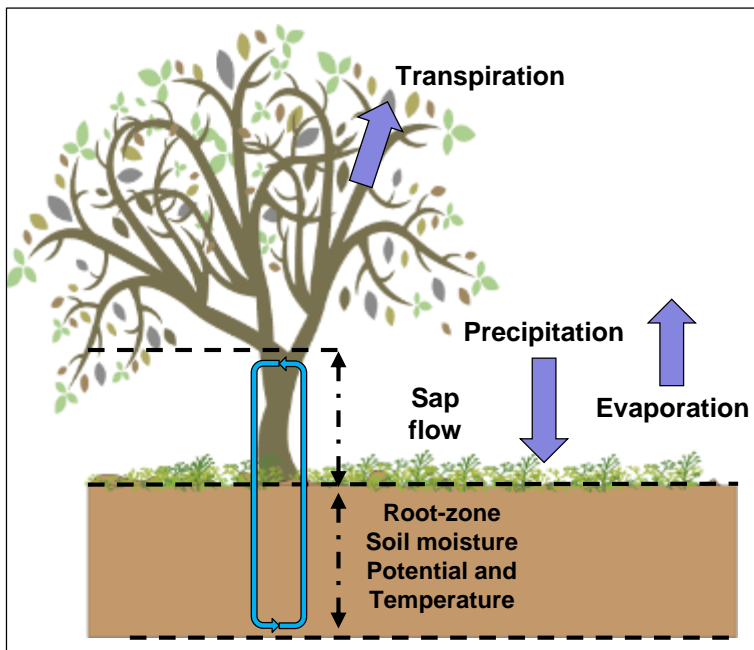
- Environmental *in situ* sensor networks:
  - Key components in our study of Earth.
  - Long-term records and observations of different Earth processes, e.g., SCAN, USCRN, AmeriFlux, FluxNet, SoilSCAPE, etc.
  - Near real-time ground truth for Earth Science missions. e.g., Cal/Val support for SMAP, etc.
  - Predetermined and fixed sampling rates, e.g., hourly.
  - Solar panels and rechargeable batteries.

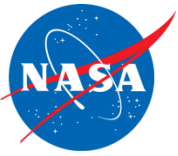
AmeriFlux Site, Tonzi Ranch ,CA



<https://www.ncdc.noaa.gov/crn/>

- Keeping track of the soil moisture state is of particular interest.
  - We can learn about biome adaptation to climate change by monitoring the flow and distribution of water between land and atmosphere.
  - A distributed sensor network observing hydrologic processes, both in the spatial and temporal domains, is required.



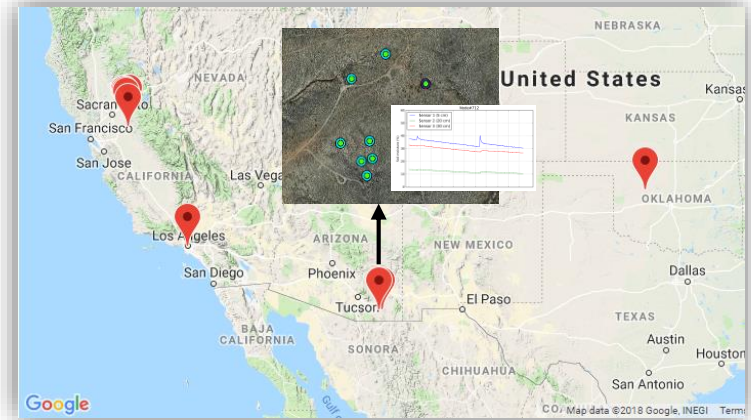


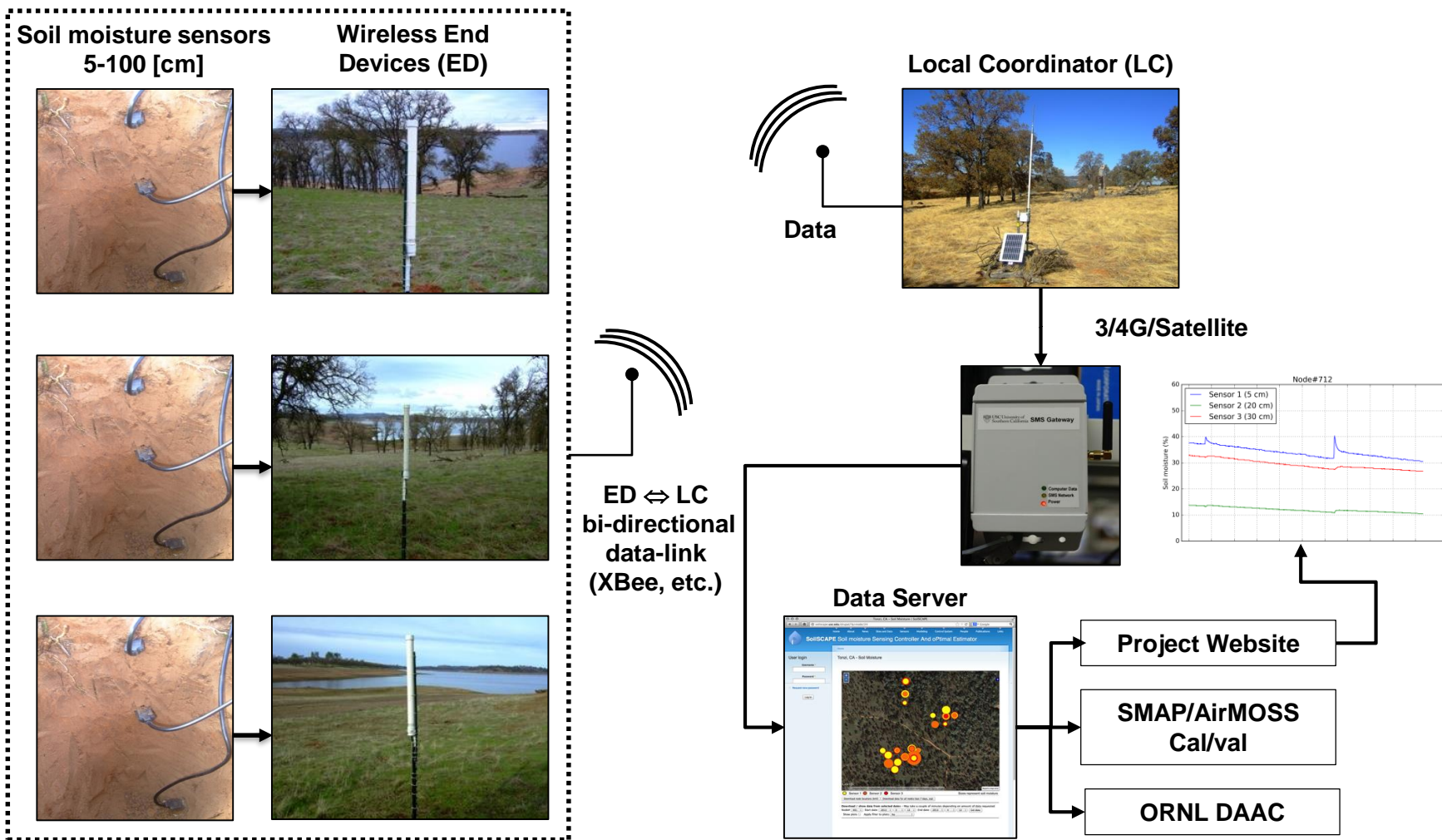
# Background

## Soil Moisture Sensing Controller and Optimal Estimation (SoilSCAPE) USC METER



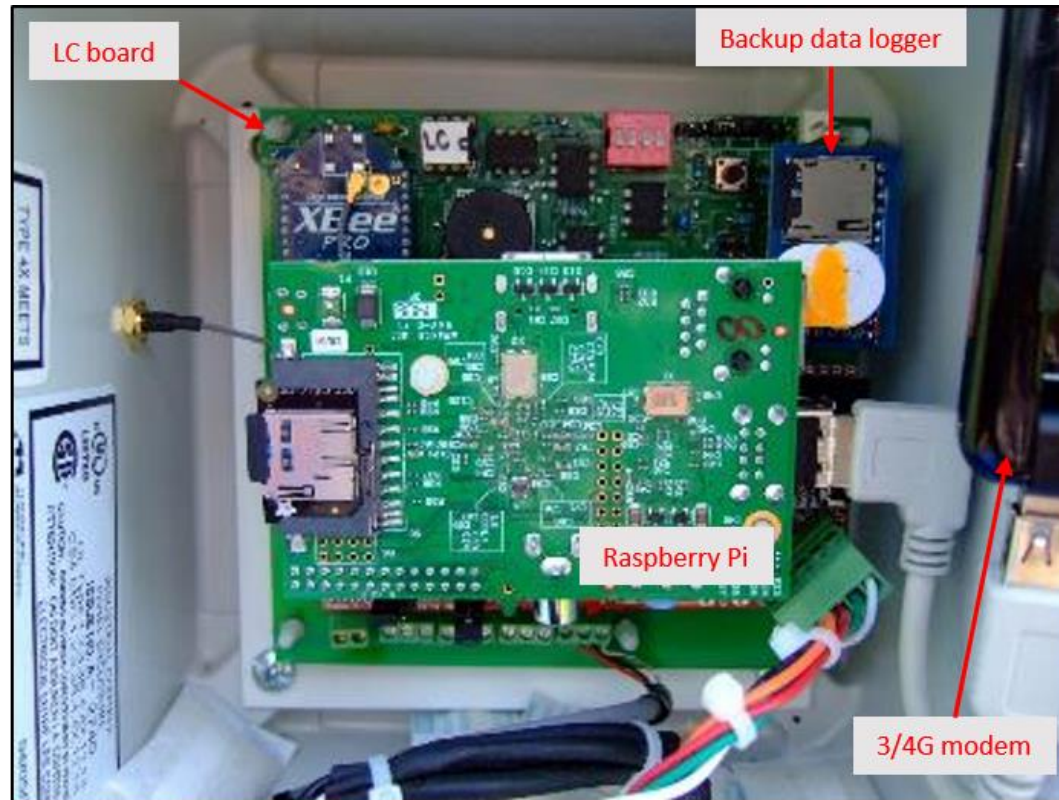
- Significant heritage from prior ESTO support: SoilSCAPE (PI: Moghaddam, USC)
- Multiple large scale *in situ* wireless sensor networks
  - AK, AZ, and CA with over 3 years of operation
- Fully in-house and custom built hardware and software.
- End-to-end measurement acquisition and distribution.
- AirMOSS & SMAP cal/val support
- 20-min sampling schedule
- Data available for free:
  - [soilscape.usc.edu](http://soilscape.usc.edu)
  - ORNL DAAC





# SoilSCAPE Overview

## Local Coordinator (LC) & End Device (ED)



Sensor Interface      Batteries      ED Electronics      Wireless transceiver and antenna

←..... Length ~ 20" .....→

- Over 150 WSN nodes installed
- SoilSCAPE system, end-to-end, TRL~ 7

### 1. Enable the WSN to autonomously “decide” when to collect new data

- Machine Learning applications + Energy management/awareness
- Generally speaking:

*make a “prediction” about current field conditions, then decide whether to acquire new data or not.*

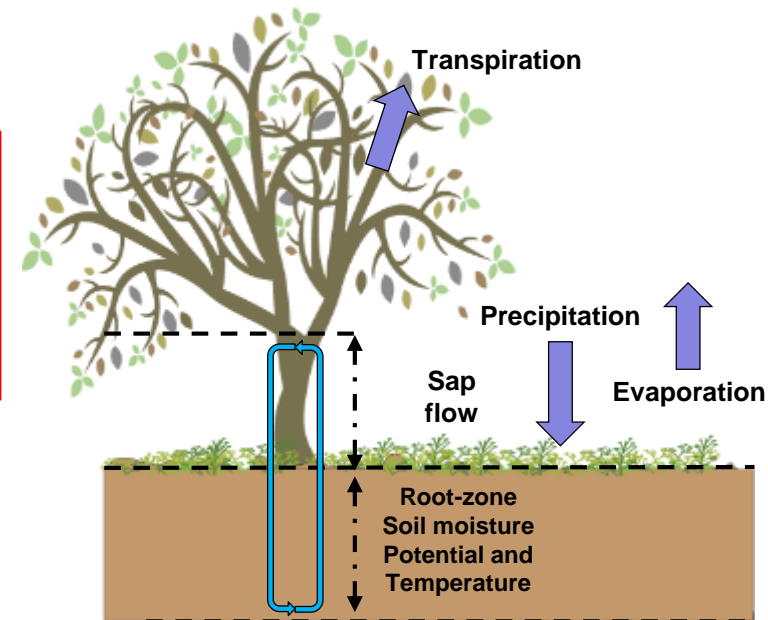
### 2. Wakeup-on-Radio (WoR) wireless module

- On-demand end-device command and control.

(1) and (2) collectively make the WSN fully autonomous.

*Inspiration from Industry:*

*Integrate ML-techniques as components within sensing system, e.g., Apple “Neural Engine”, AI accelerators, TPUs, etc.*







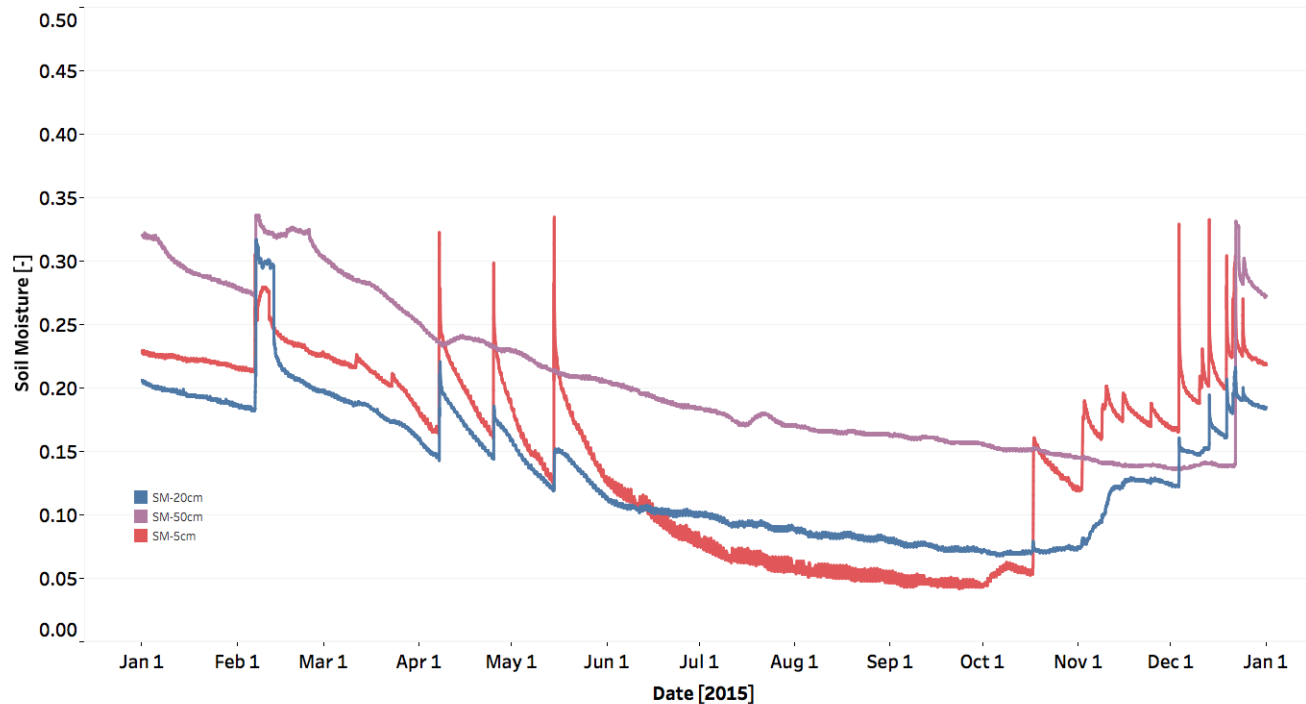
# Project Objectives

## SoilSCAPE 2.0!



- Battery powered devices → finite number of measurements!
- Soil moisture dynamics are highly variable.

Example Soil Moisture Time Series, Tonzi Ranch, CA, 2015





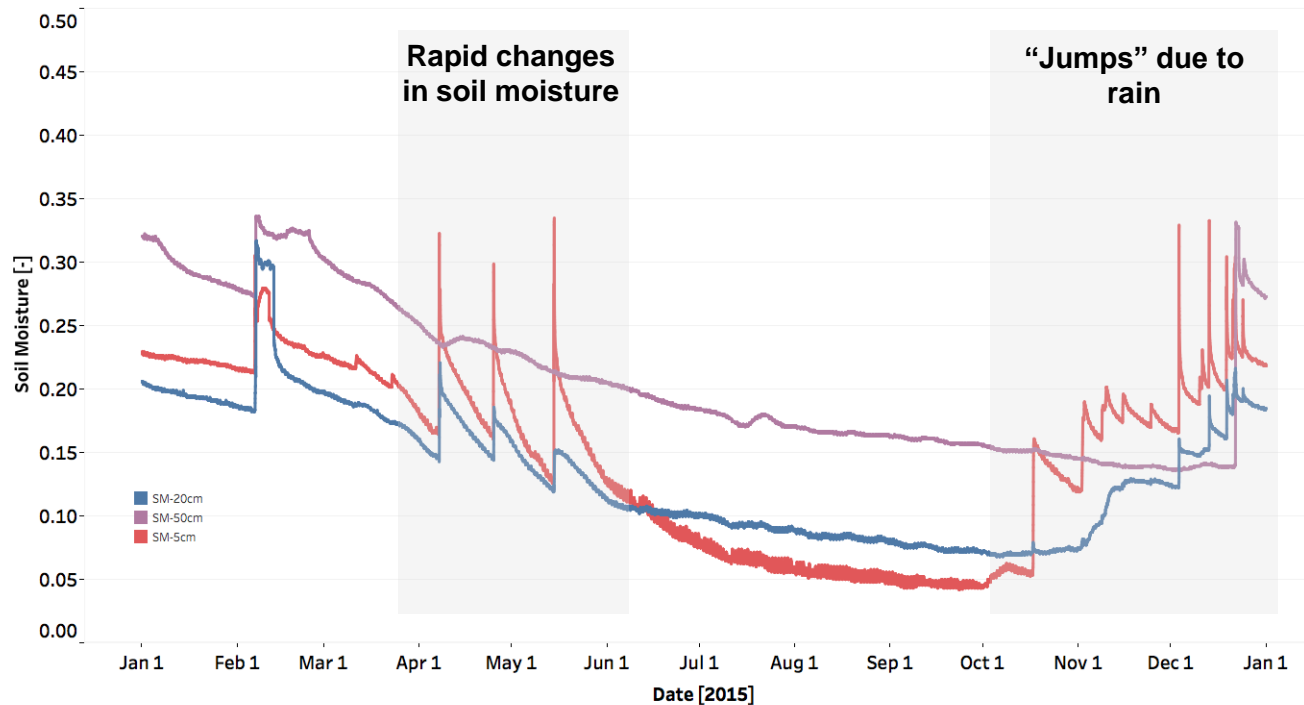
# Project Objectives

## SoilSCAPE 2.0!



- Battery powered devices → finite number of measurements!
- Soil moisture dynamics are highly variable.

Example Soil Moisture Time Series, Tonzi Ranch, CA, 2015





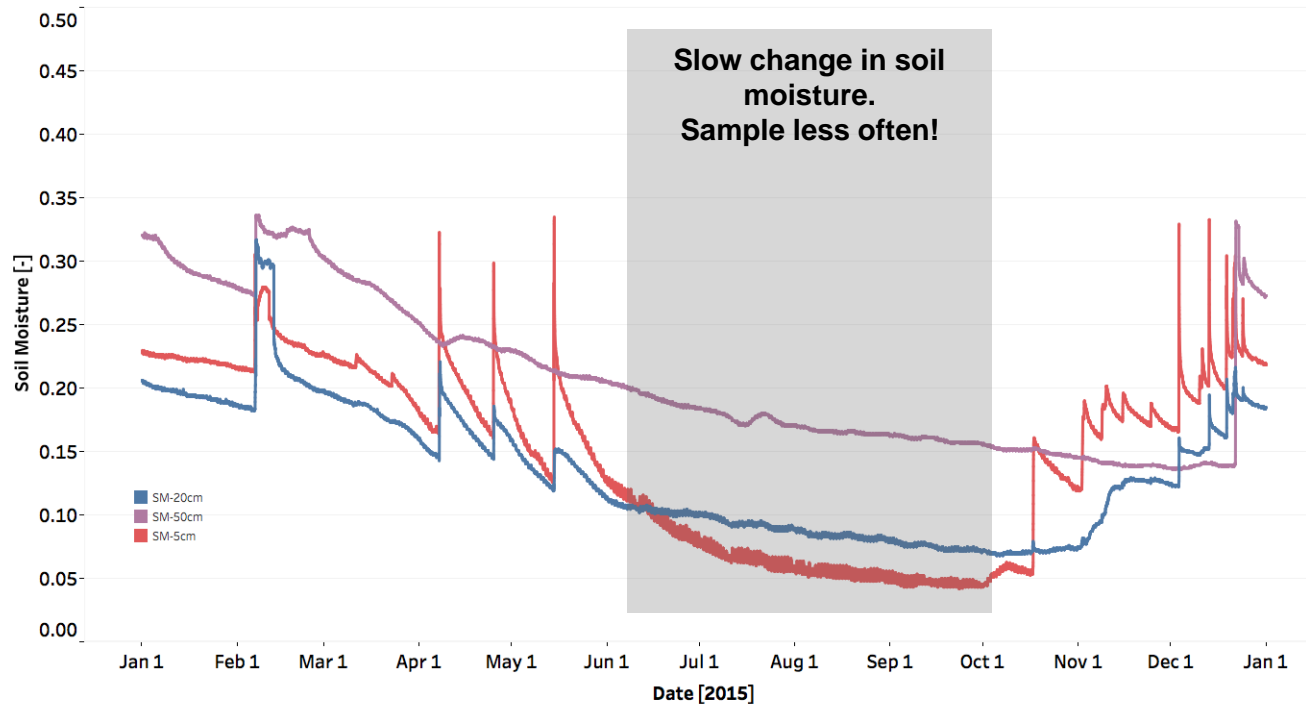
# Project Objectives

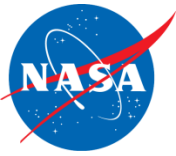
## SoilSCAPE 2.0!



- Battery powered devices → finite number of measurements!
- Soil moisture dynamics are highly variable.

Example Soil Moisture Time Series, Tonzi Ranch, CA, 2015



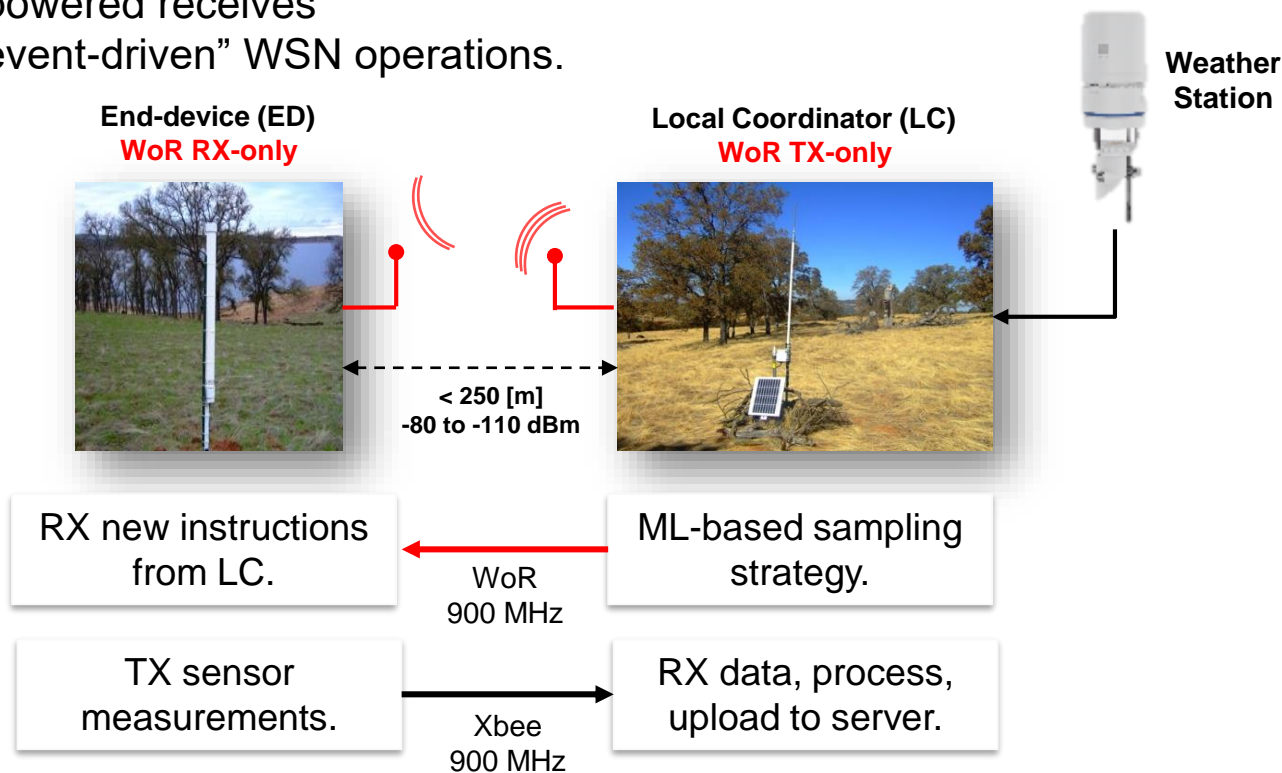


# Presentation Contents



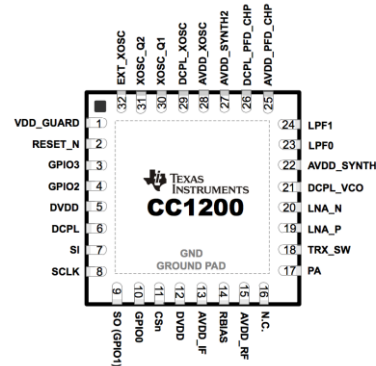
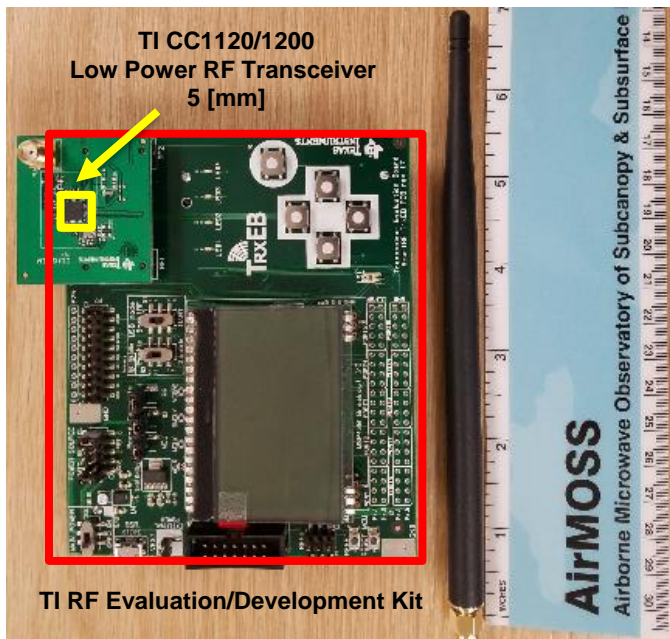
- Background and Overview
- Technical Development ( $TRL_{in} = 2$ ):
  - Wakeup-on Radio
  - Machine Learning Decision Making
- TRL Assessments
- Updated Project Schedule
- Project Finances
- List of Acronym

- Wakeup-on-Radio
  - Ultra low-powered receives
  - Enables “event-driven” WSN operations.

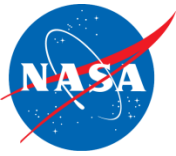


- Not a feature in most existing networks.
- Design Objectives:
  - Can we add “event-reaction” to SoilSCAPE with **same** energy-efficiency?
  - Can we still **improve** energy-efficiency of the solution?

- Criteria For Evaluating Wireless Wake-up Technologies:
  - 1) LC-ED distance > 100m (250m is desired, not required)
  - 2) Energy consumption of new technology < 20 J per day
  - 3) Wake-up latency < 2minutes (i.e., max. time to wake-up ED)
  - 4) Wake-up likelihood > 99%
  - 5) Implementation feasibility in less than 6-8 months (2-year project)
- Investigating two design options using TI CC1200 RF Transceiver.



- Chip needs to be integrated within current wireless end-devices.
- Allows for “addressed” WoR, spatially selective wake-ups
- 900 MHz ISM
- 0.5-23 mA Peak current

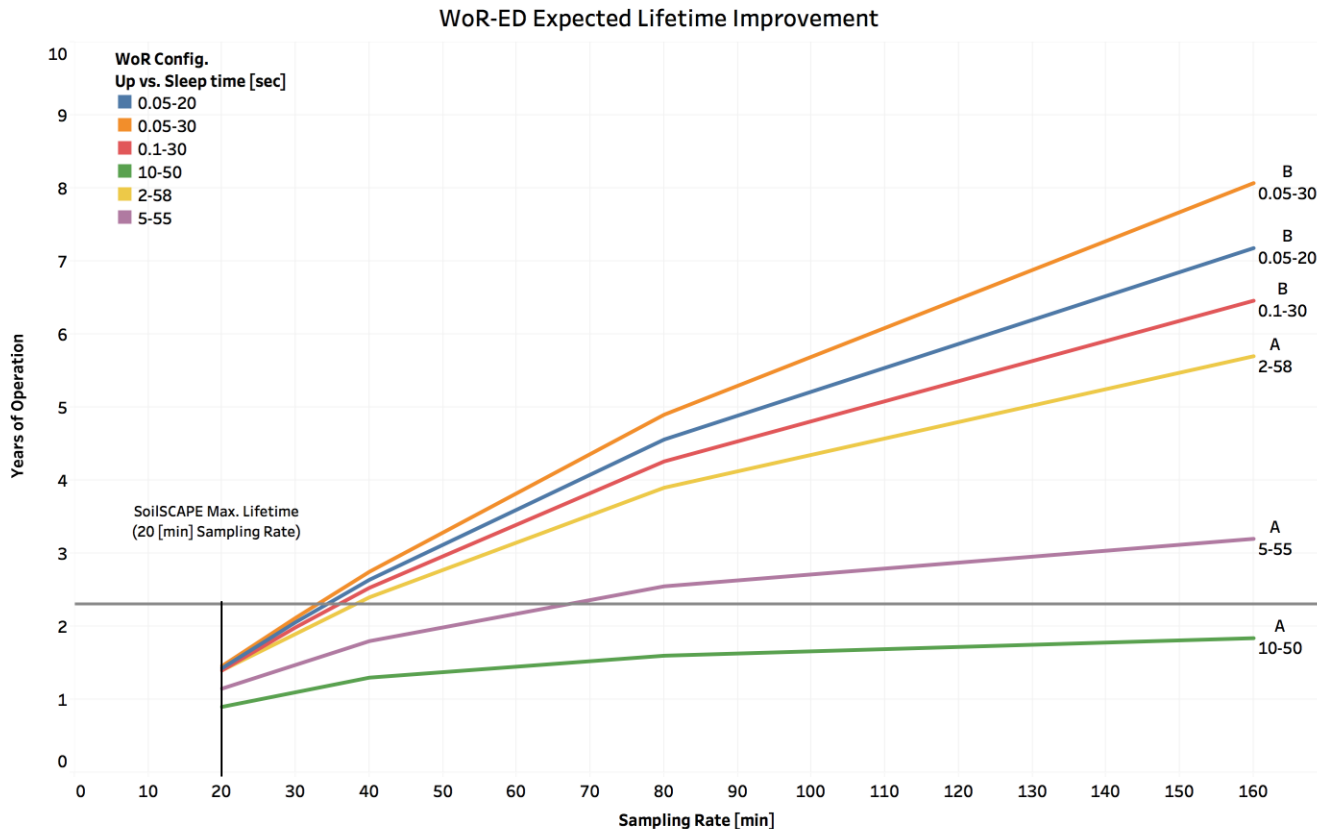


# Wakeup-On Radio (WoR) (3)

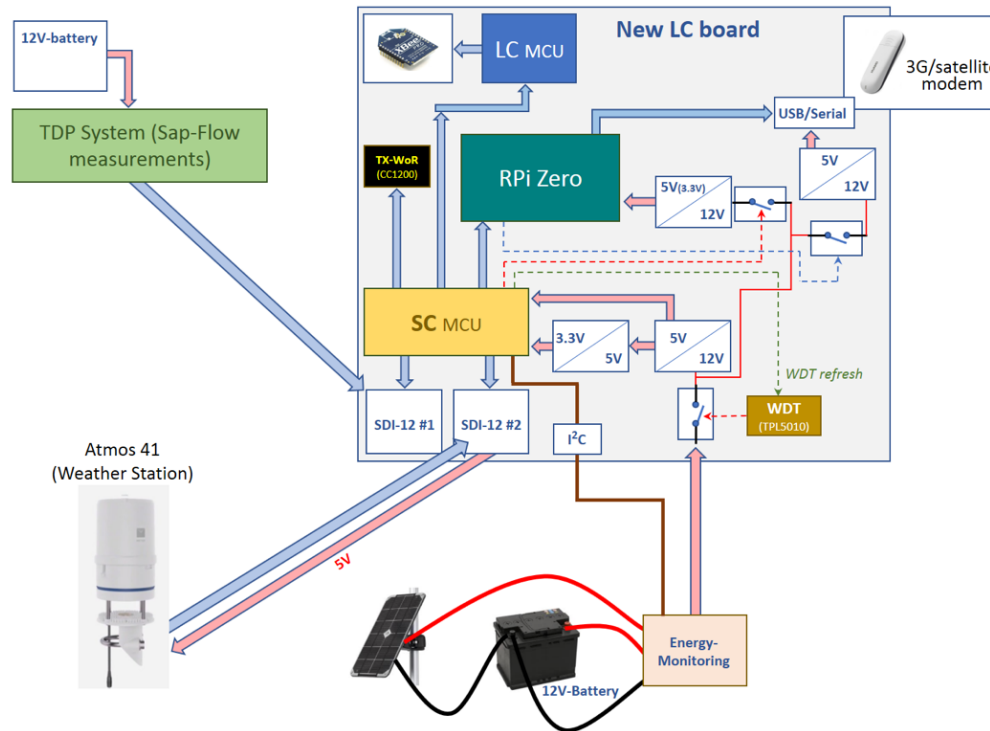
## Baseline and Expected Lifetime improvement



- Active WoR: must periodically wake-up to check for signal.
- Two custom design option:
  - Option-A: Simpler implementation, less energy efficient. "Wake-up beacons."
  - Option-B: complex, but more energy efficient. CW wake-up signal.



- New WSN features too much for current LC.
- Not enough onboard processing power nor memory.



- **LC MCU:** LC-ED communication (used in SoilSCAPE for +3 years)
- **RPi:** ML-automation and 3G/Satellite Communication
- **SC MSU:** Top-level scheduler, TX-WoR, weather station, sap-flow system.



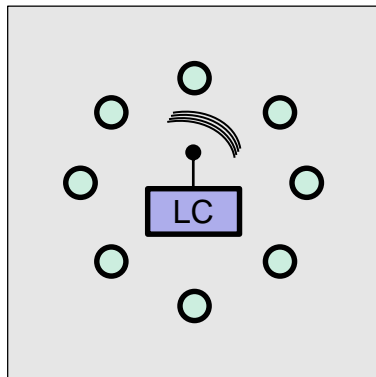


# Presentation Contents

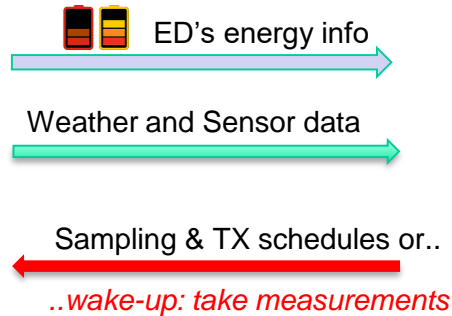


- Background and Overview
- Technical Development ( $TRL_{in} = 2$ ):
  - Wakeup-on Radio
  - Machine Learning Decision Making
- TRL Assessments
- Updated Project Schedule
- Project Finances
- List of Acronym

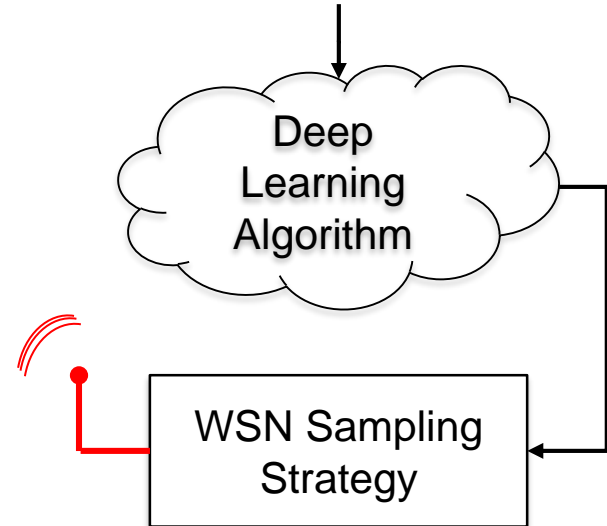
### Wireless Sensor Network



- Local Coordinator
- Wireless Node



Training Data  
Long term high frequency measurements

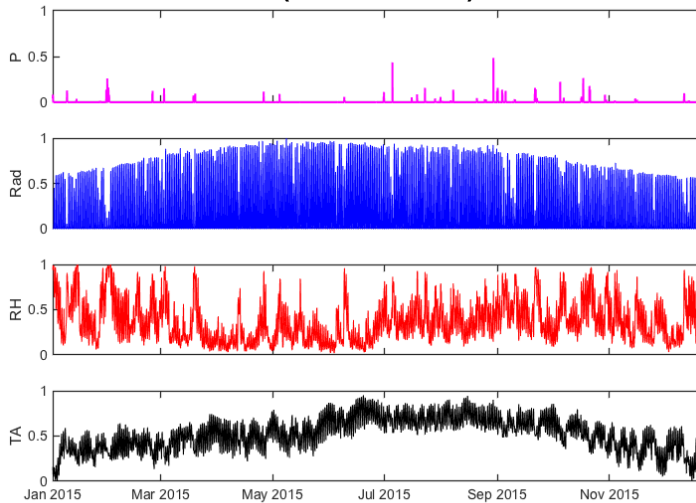


- Expand WSN to include a Weather Station (WS)
  - “Environmental awareness”
  - Event-driven sampling, e.g., rain.

Local Coordinator (LC)

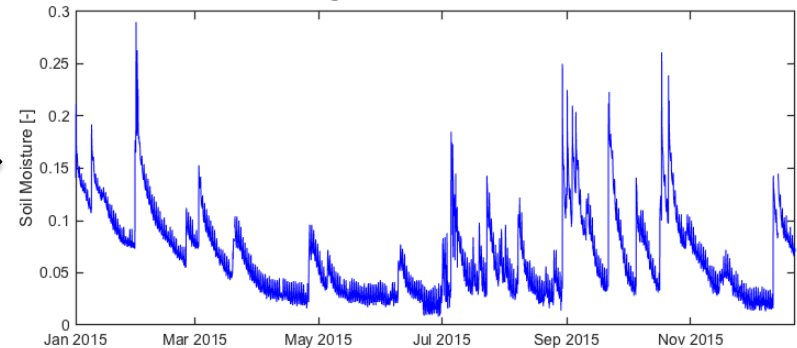


**Feature Variables**  
Precipitation, Radiation, Humidity, Air Temp  
(all normalized)

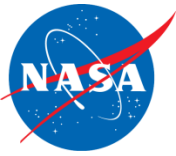


Physically  
Related

**Target: Soil Moisture**



- “Jumps” in soil moisture due to rain.
- Decays mostly a function of atmospheric conditions.



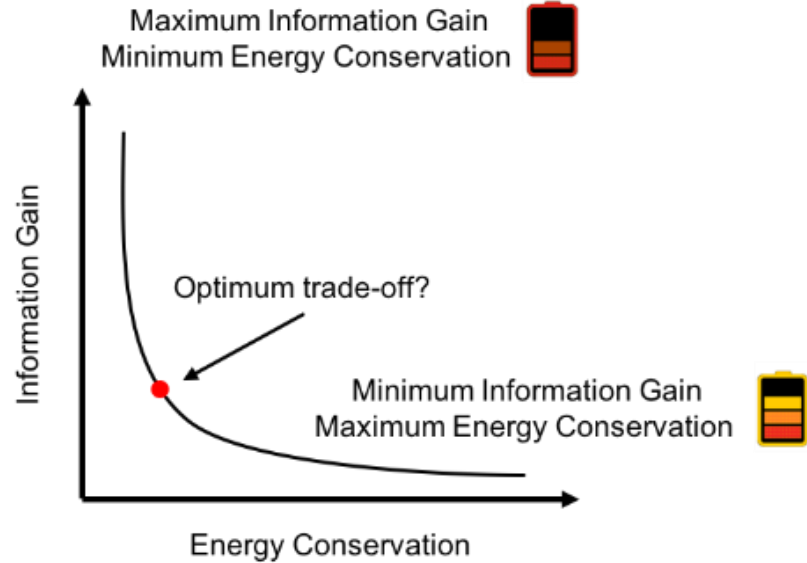
# Machine Learning Autonomous Control(2)

## “Meta-Objectives”

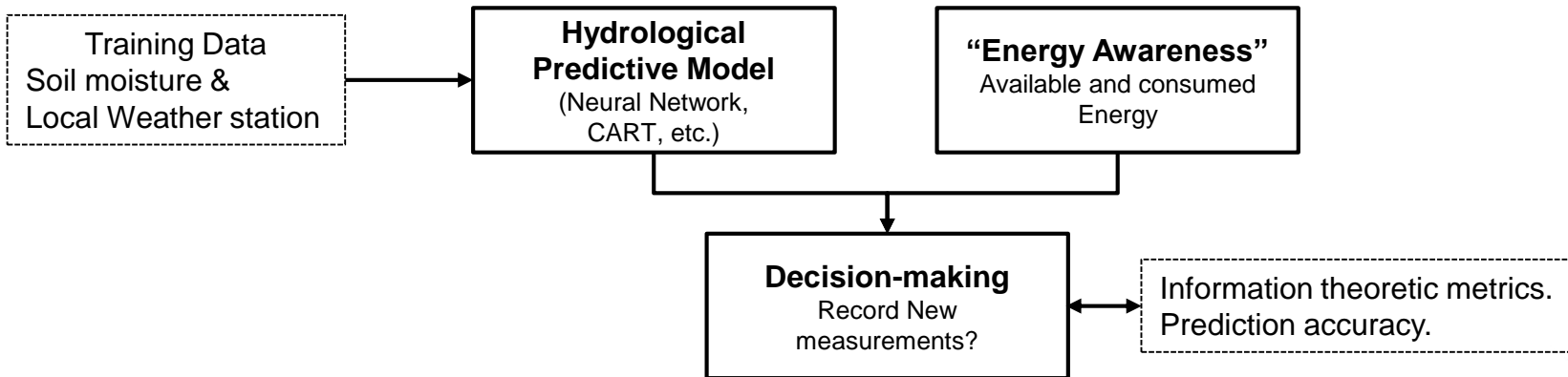


- Two competing objectives define “intelligent” WSN operations:

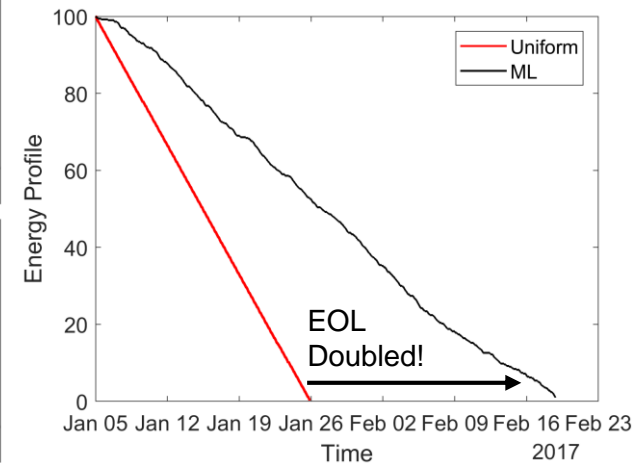
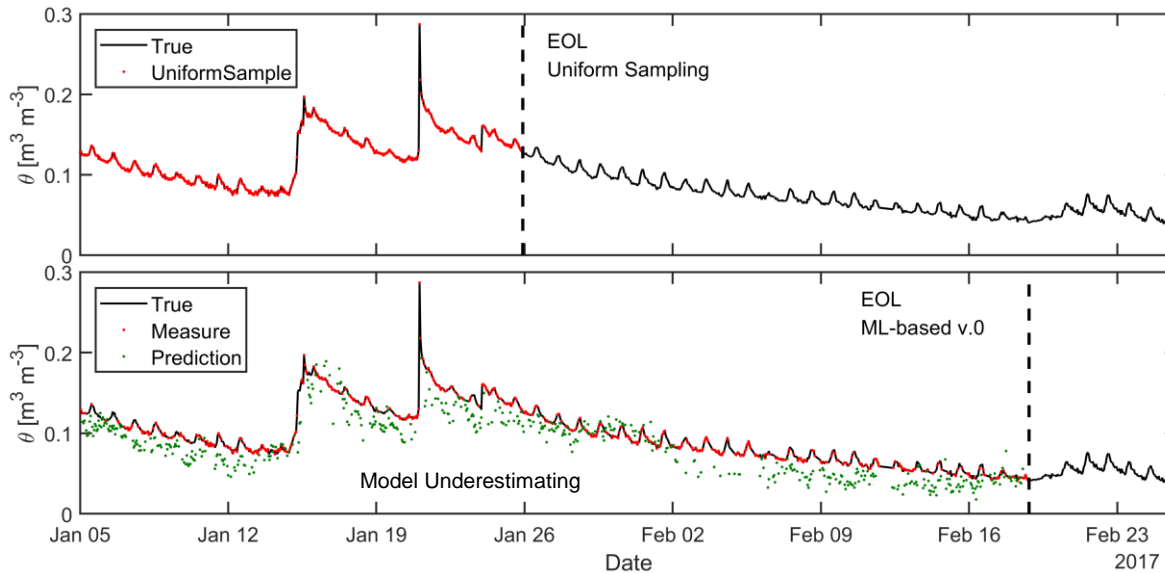
**Minimize Energy Consumption**  
**Maximize Information Content**



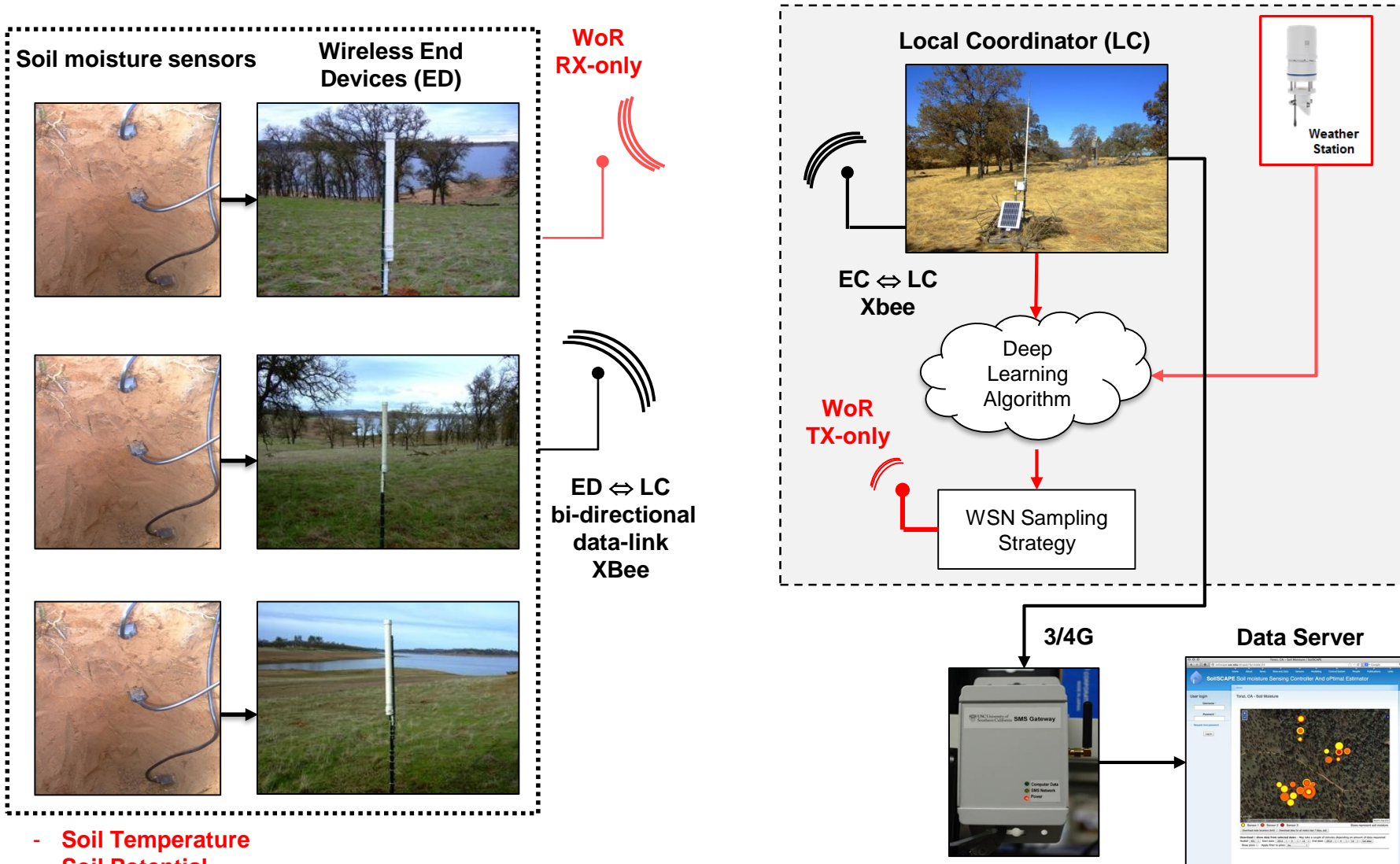
Modular Implementation:



- One-Step-Ahead soil moisture prediction using prior weather station observations.
- Ensemble Gradient Boosting Regression Trees.
- Simple decision making: If  $\begin{cases} \Delta CI > \epsilon_1 \\ \Delta \hat{\theta} > \epsilon_2 \end{cases}$  record new measurement (we can “learn” this too!).



- True vs. **Predicted** Error standard deviation  $0.0135 [m^3m^{-3}]$ , with  $R^2 = 0.8$
- Error less than  $0.04 [m^3m^{-3}]$  generally accepted.
- But, plenty of room for improvement.



- Soil Temperature
- Soil Potential
- Sap-flow

- Desire for “fully autonomous” wireless *in situ* sensing networks
  - Maximize information content vs. minimize energy use.
  - Close-up view of biome adaptation and dynamics at Plant/Plot level.
- Planned field work for Summer 2018
  - Small-scale field deployment, Southern AZ.
  - Prototype WoR and new LC demonstration.
- Plans for Year 2:
  - Improvements in prediction and ML models.
  - New End-device and LC boards.
  - External Sap-flow systems.
  - Larger-scale field deployment.



*Many thanks to ESTO for their generous support!*



---

Thank you!

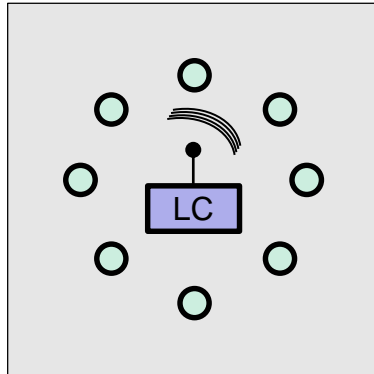
[rakbar@mit.edu](mailto:rakbar@mit.edu)



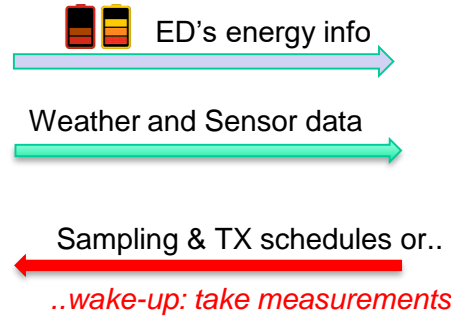




## Wireless Sensor Network



- Local Coordinator
- Wireless Node



Training Data  
Long term high frequency measurements

