

**AUTOSAR Overview** 

### Agenda

#### > AUTOSAR Overview

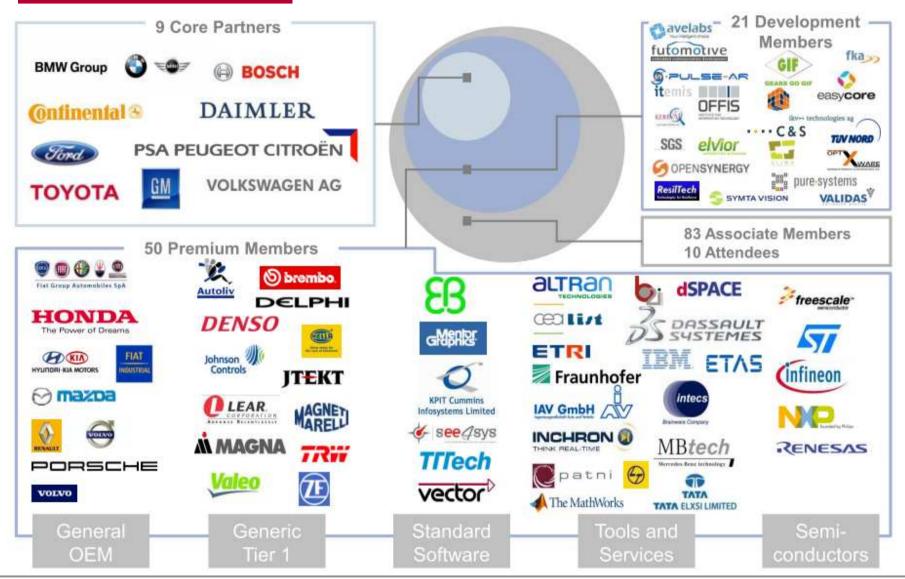
**AUTOSAR Solution** 

AUTOSAR on the way



### Overview and Objectives

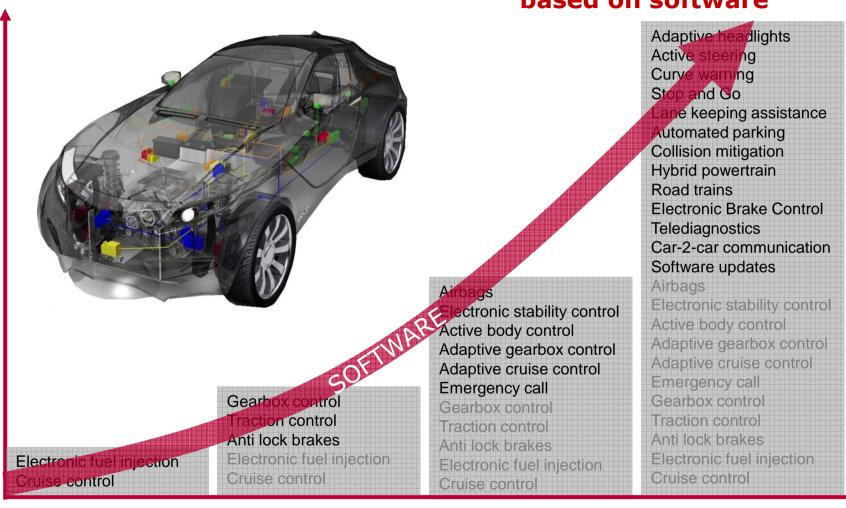
### **AUTOSAR Partnership**





### **Development of Functionality**

## >80% of automotive innovations are based on software



1975 1985 1995 2005 2015



### Why AUTOSAR?

#### The challenge:

- ► E/E **complexity** is growing fast
- Quantity of software is exploding
- Many different hardware platforms are used
- Development processes and data formats are not harmonized

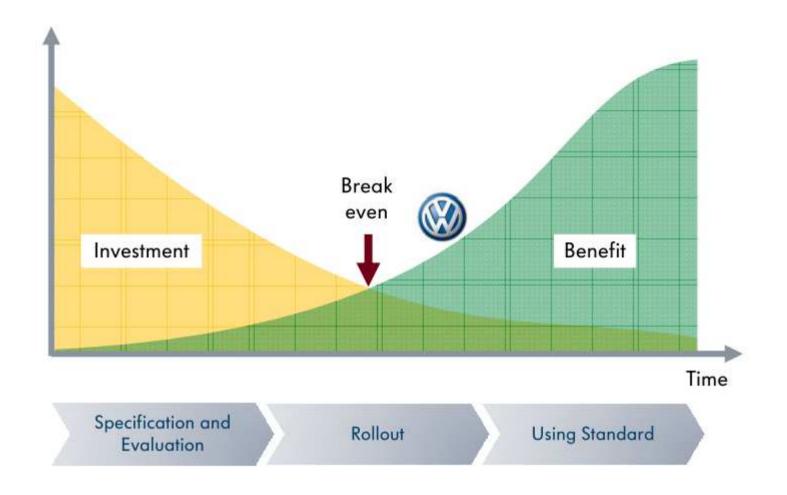
### The main objective of **AUT SAR**

### → Improve software quality and reduce costs by re-use

- ▶ Re-use of functions across carlines and across OEM boundaries
- ▶ Re-use of basic software
- ▶ Re-use of development methods and tools



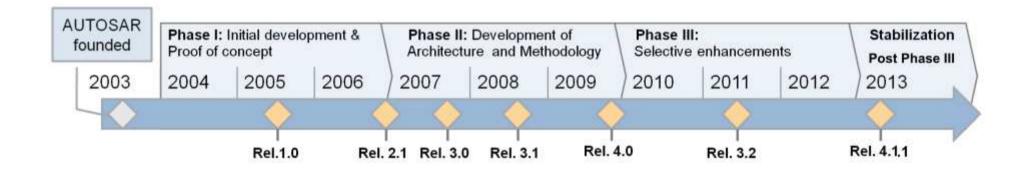
### Why AUTOSAR???



Source: Explore AUTOSAR Conference in Pune 2012



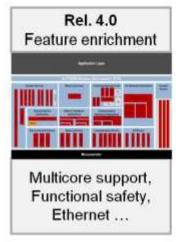
### 10 Years









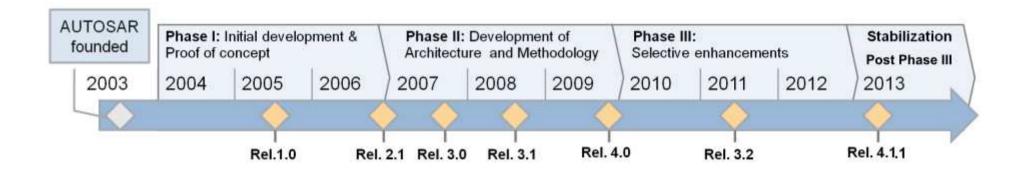


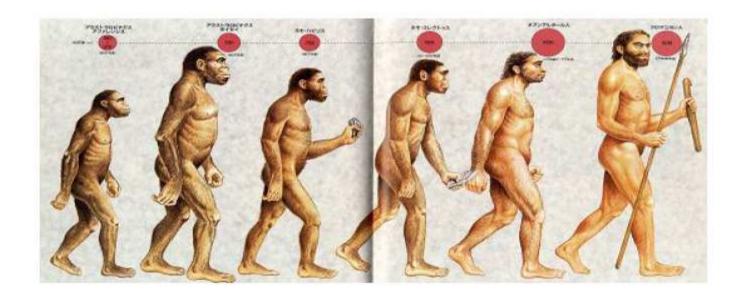


Source: 6th AUTOSAR Open Conference



### 10 Years





Source: 6th AUTOSAR Open Conference



## Introduction to AUTOSAR AUTOSAR Status

**AUTOSAR** is a broadly used standard in Europe

#### **AUTOSAR 3.x:**

► First specification: 2007

→ Mature solution used for series production 2010ff

→ Adaptations necessary → OEM-specific extensions

#### **AUTOSAR 4.x:**

▶ First specification: 2009

→ First mature specification: 2012 (4.0.3)

→ 4.0.3 is the right version for development start in 2012

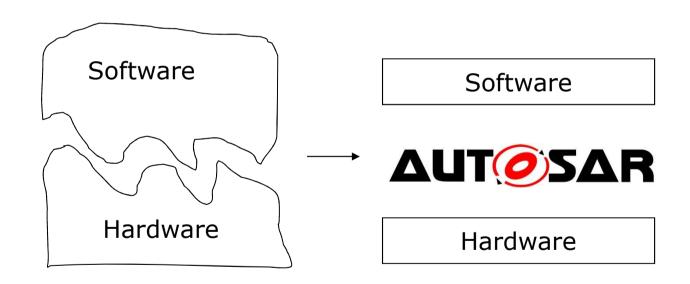
→ New functions: safety, Ethernet/IP, multicore, ...



# Overview and Objectives AUTOSAR Slogan

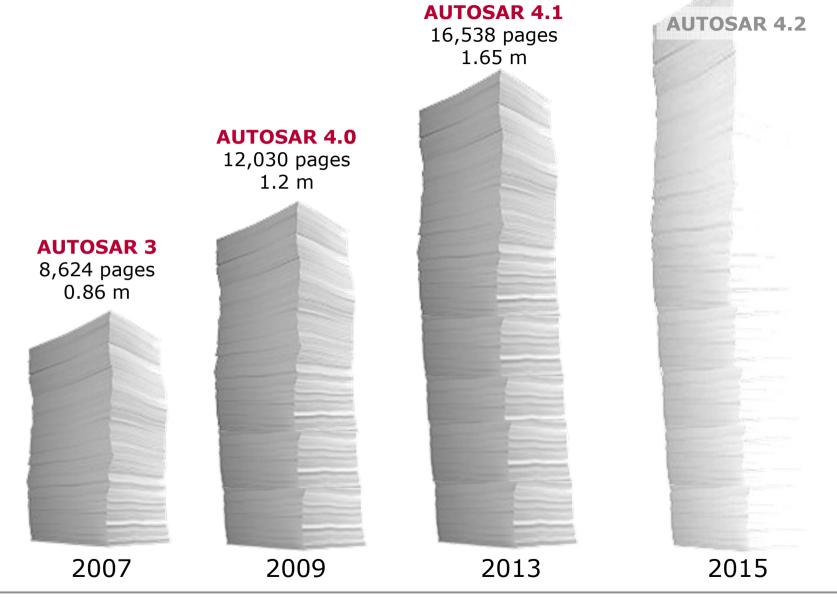
#### Two different AUTOSAR statements:

### "Cooperate on standards – compete on implementation"





### AUTOSAR Specification – "In the beginning was the word"

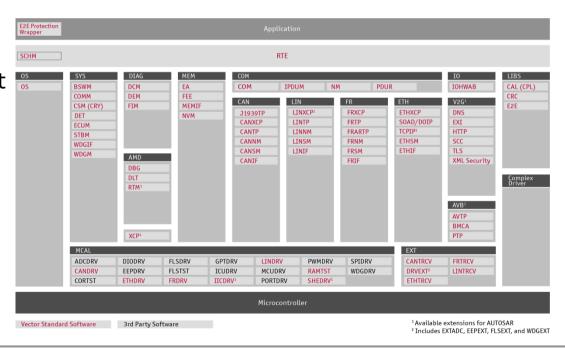




2003

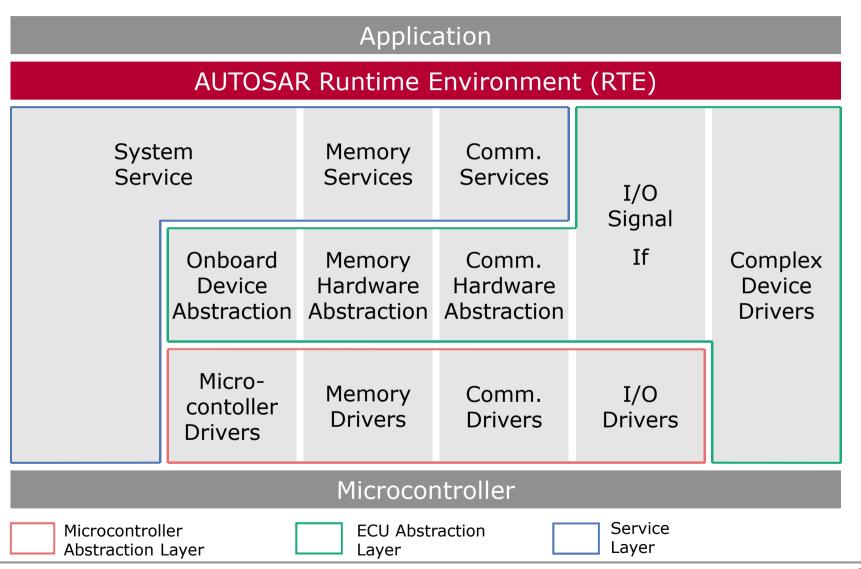
### **AUTOSAR Accomplishments**

- ▶ **Standardization** of methods and data exchange formats
- ▶ **Standardization** of application software interfaces
- ▶ Standardization of basic software and network behavior
  - > Network Management
  - > Partial Networking
  - > ECU State Management
  - > Transport Protocols
  - > Non-Volatile Memory
  - > ...





Layered View: Detailed

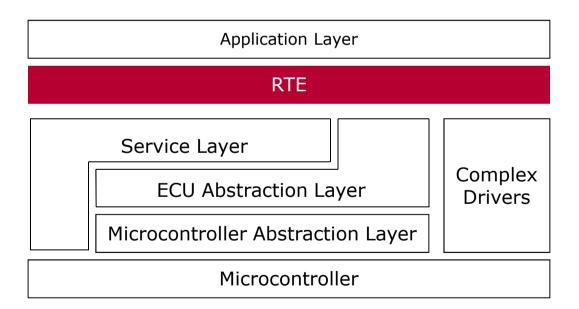




### **AUTOSAR RTE**

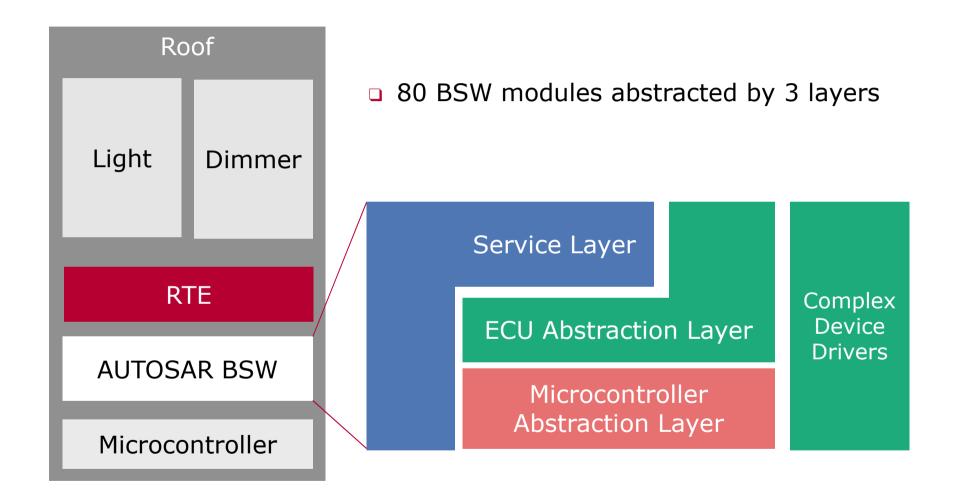
### Architecture

- ▶ Task
  - Components independent of ECU mapping
- Functionality
  - Middleware providing communication services (intra / inter ECU)





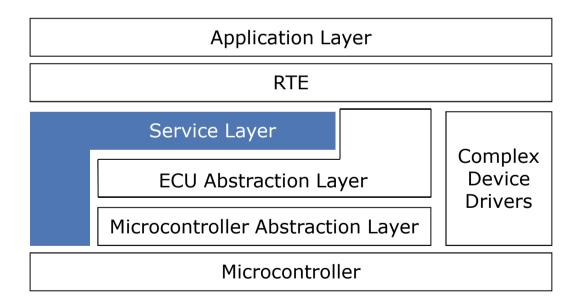
Layered View: Simplified





### Service Layer

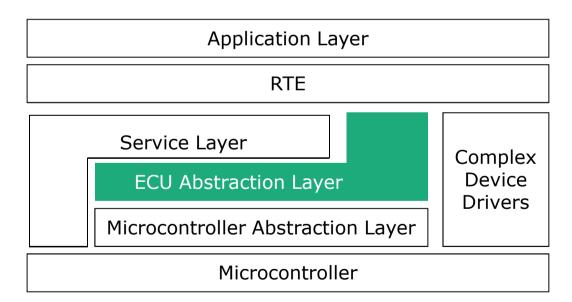
- ► Task
  - Services for application
- Functionality
  - ▶ Diagnostics, NVRAM Management, OS, Communication
  - Memory and ECU management





### ECU Abstraction Layer

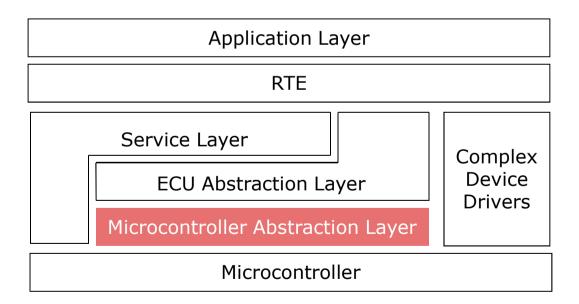
- ▶ Task
  - Make higher levels independent of ECU hardware
- Functionality
  - Driver for external devices
  - ▶ Interface for internal and external periphery (IO)





### Microcontroller Abstraction Layer

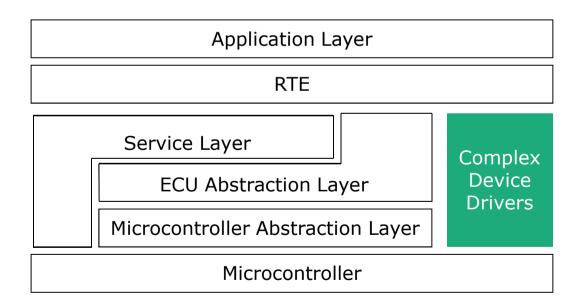
- ▶ Task
  - ▶ Make higher layers independent of microcontroller
- Functionality
  - Drivers with direct access to internal periphery of μC
  - Memory-mapped devices external to μC





### Complex Device Drivers

- ▶ Task
  - Offer functionality for complex sensors and actuators
- Functionality
  - Direct access to resources for critical applications
  - ▶ Examples: Injection control, tire pressure monitoring





### Agenda

**AUTOSAR Overview** 

#### > AUTOSAR Solution

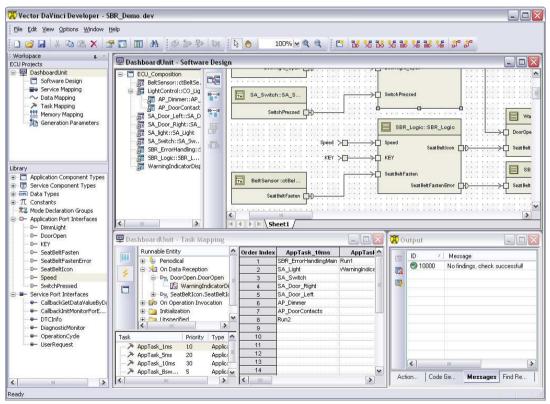
AUTOSAR on the way



### Designing AUTOSAR SWCs

DaVinci Developer: SWC Design

- ▶ Define application architecture of AUTOSAR ECUs
- ▶ Integrate the SWC with the ECU basic SW
- Configure the AUTOSAR RTE



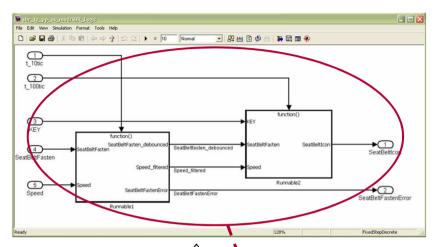


### Designing AUTOSAR SWCs

### DaVinci Developer: Interaction with model-based development tools

#### Simulink/EmbedderCoder or TargetLink

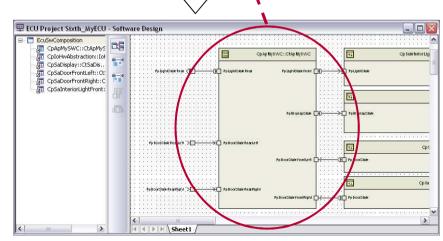
- Develop the behavior model
- ▶ Generate SWC implementation code



SWC description (e.g. ports, runnables) is exchanged via AUTOSAR XML

#### DaVinci Developer

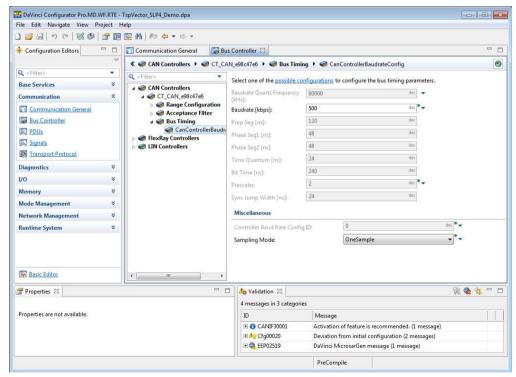
- Define SWC structure
- Integrate the SWC into the ECU application architecture
- Configure the RTE





## DaVinci Configurator Pro Configuring Basic Software

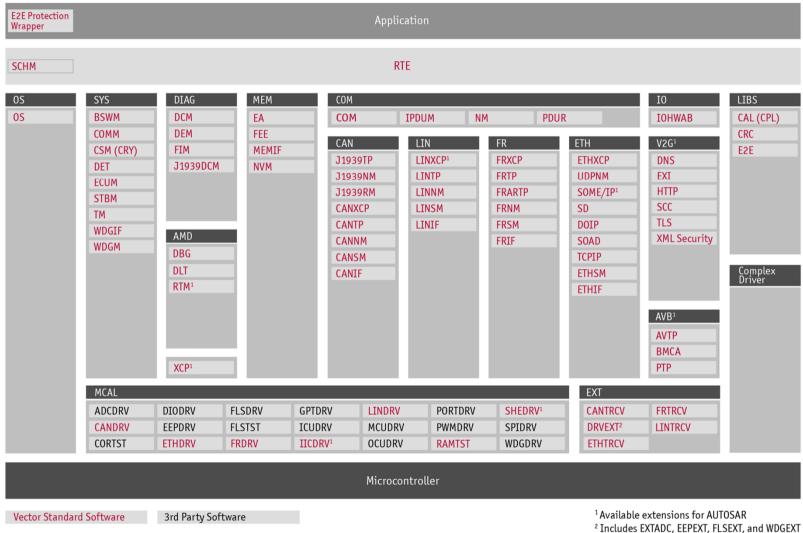
- One tool for configuration of complete BSW and RTE
- ► Comfort Editors and Assistants to support specific use cases
- ▶ Basic Editors (GCE) for native ECU-C view
- Easy navigation between editors





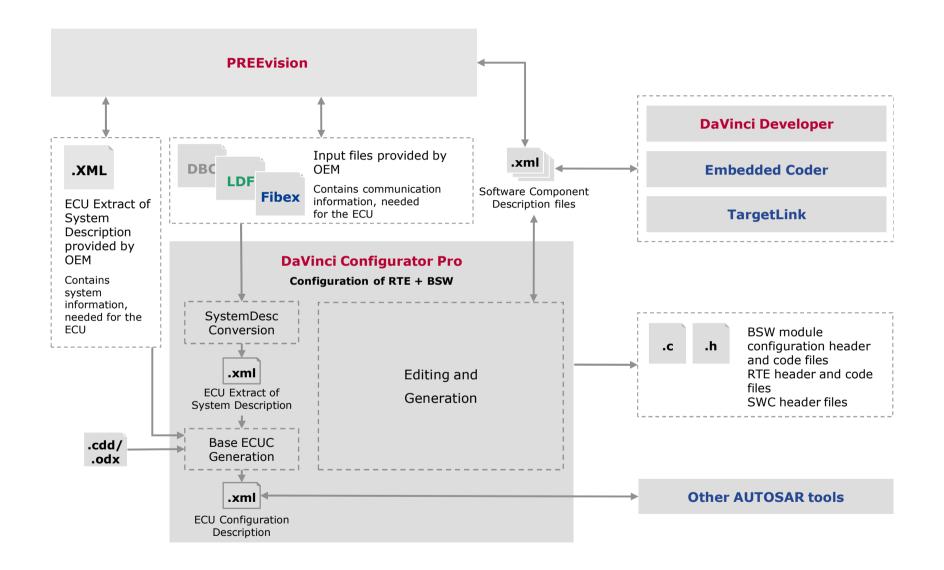
### Vector Embedded AUTOSAR Software

### MICROSAR





### Workflow AUTOSAR 4.x

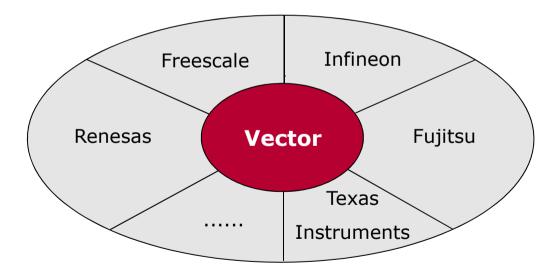




### MICROSAR - Vector AUTOSAR Basic Software

### Large variety of platforms supported

- ► Vector cooperates with microcontroller manufacturers to integrate the MCAL (Microcontroller Abstraction Layer) which are provided by them
- An individual solution for your favored microcontroller is possible at any time





### Agenda

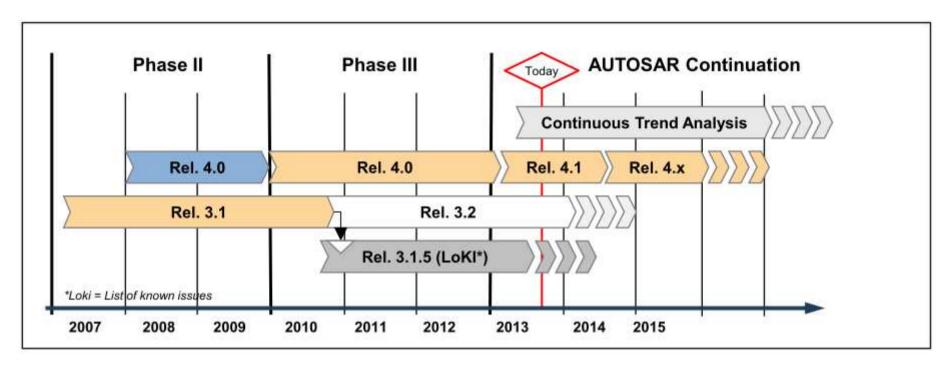
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### **AUTOSAR Releases**



- ► AUTOSAR is stabilizing with R3.2 and 4.x
- ▶ AUTOSAR is worldwide in massive series roll-out
- ▶ High acceptance in the market is achieved
- Existing releases will be used over long period of time in many applications
  Source: 6th AUTOSAR Open Conference



### **AUTOSAR - Exploitations**

**▶ SOP of a complete AUTOSAR solution** (BSW + RTE)

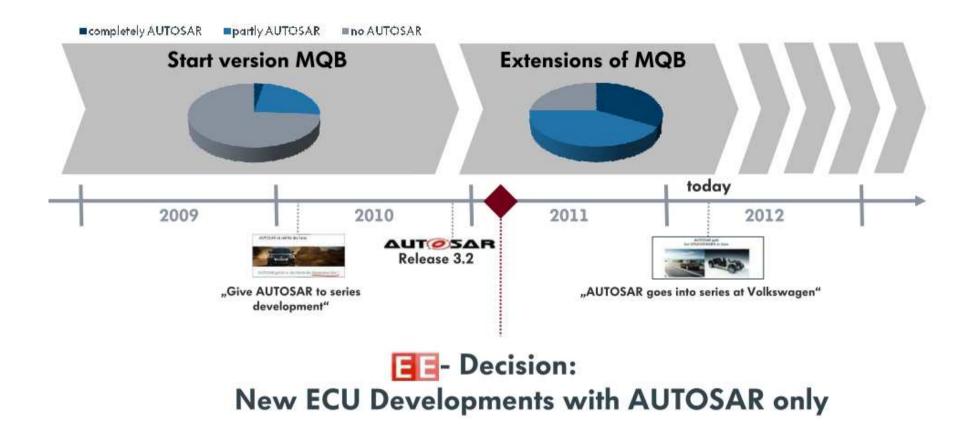
	2010	2011	2012	2013	2014	2015	2016	
AUTOSAR 3.x								
AUTOSAR 4.x								

- ▶ **AUTOSAR 3.x** is used in serial production projects by:
  - Audi / Volkswagen / Porsche
  - Daimler
  - ► Fiat / Chrysler
  - Volvo Trucks (incl. Construction Machines)
- ▶ **AUTOSAR 4.x** is used in serial production projects by:
  - **▶** BMW
  - ► GM
  - Toyota
  - Volvo Cars
- ▶ AUTOSAR 4.x is generally announced by
  - Ford
  - PSA
  - **...**



### **AUTOSAR in VW**

Slide: 30

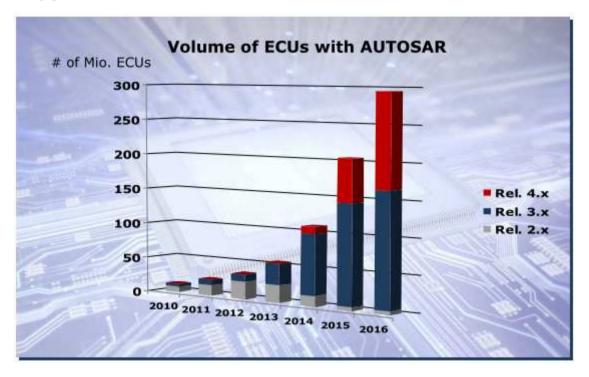


Source: Explore AUTOSAR Conference in Pune 2012



### AUTOSAR's market

▶ At least 25% of the total number of ECUs produced in 2016 will have AUTOSAR inside (based on planning of AUTOSAR OEM Core Partner only)

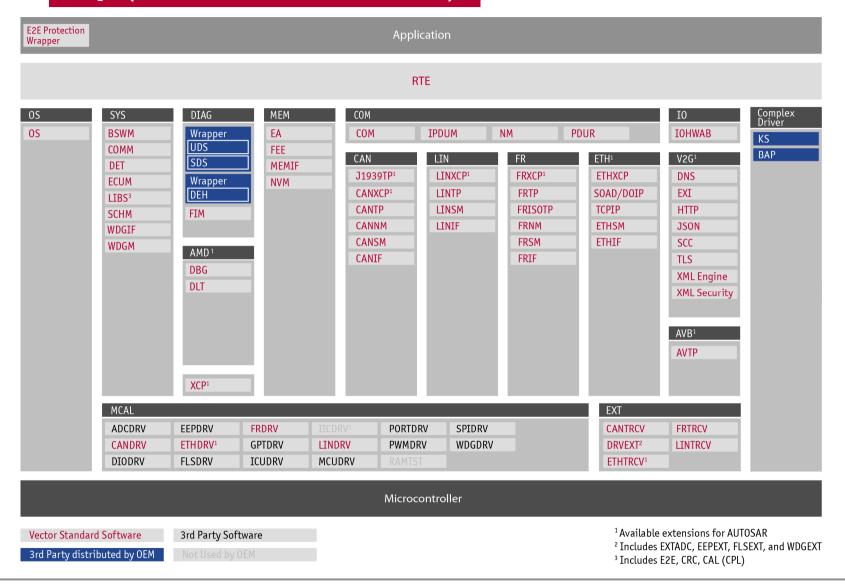


Source: Explore AUTOSAR Conference in Pune 2012



### MICROSAR 3 for VW Group

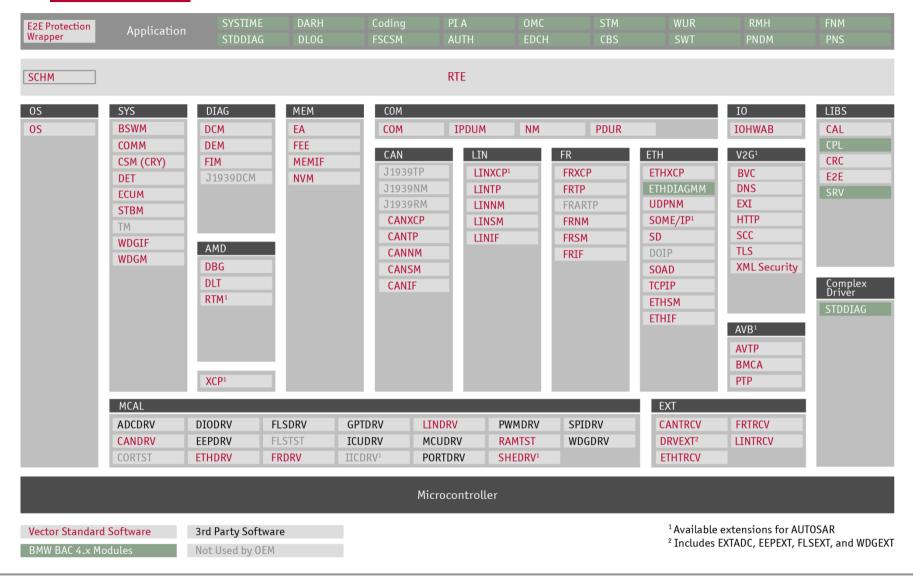
### MQB (technical identical to MLBevo)





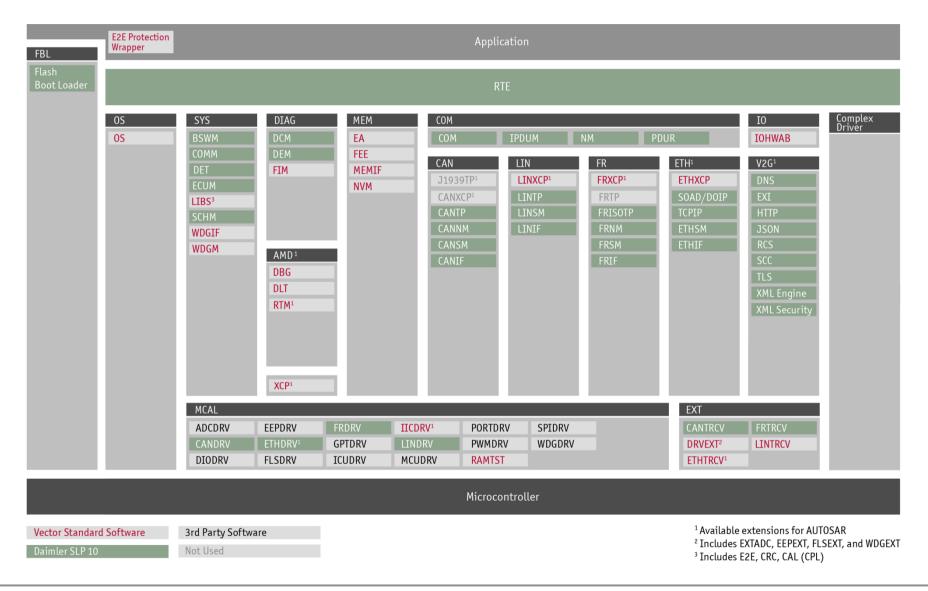
### BAC 4.0 MICROSAR Basic-Software for BMW

### Overview



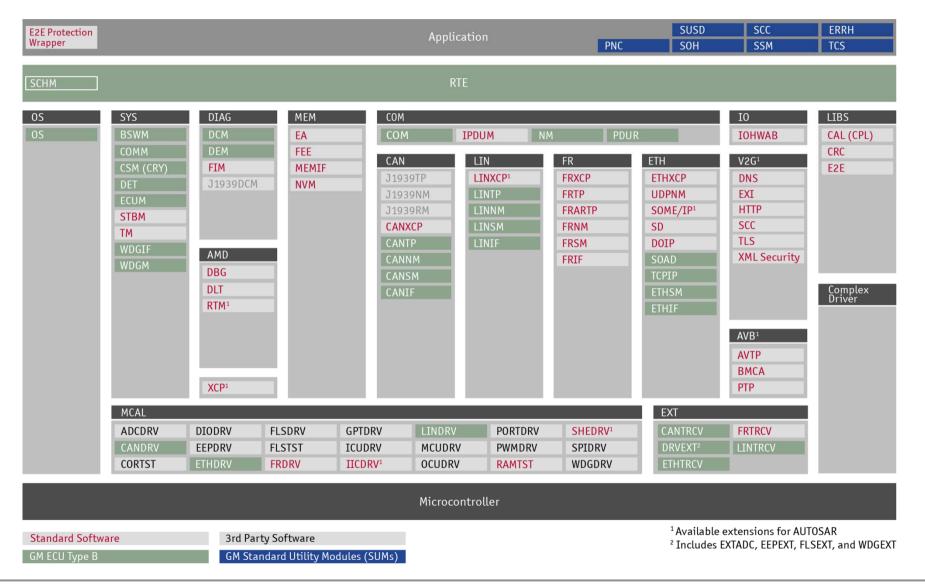


### MICROSAR 3 for Daimler SLP10





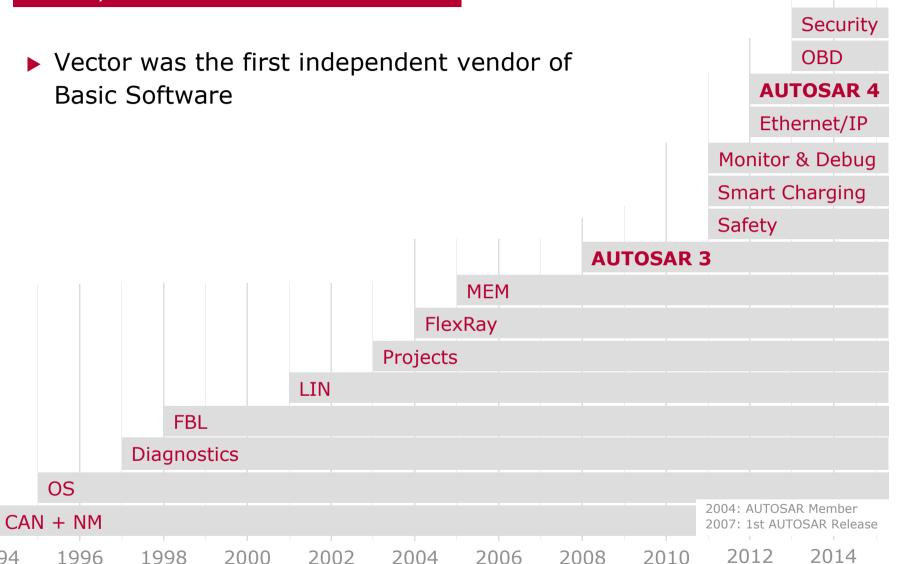
### MICROSAR for General Motors (GM)





### Why Vector

### History Embedded Software at Vector



2004



2000

1996

1998

1994

### **AUTOSAR** in China

- ► Cooperation with Chinese customers from 2009
- ► FAW, ChangAn, Foton, PATAC, DFM...



### **Case Study**

Developing a driver library for engine controllers with AUTOSAR Complex Device Drivers (CDD)





Thank you for your attention.

For detailed information about Vector and our products please have a look at:

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