Beam Design and Deflections

Notation:

= shorthand for live load

LRFD = load and resistance factor design

 M_{max} = maximum internal bending moment

= internal bending moment

LL

= name for width dimension $M_{max-adi}$ = maximum bending moment = name for area adjusted to include self weight $A_{rea'd-adi}$ = area required at allowable stress M_n nominal flexure strength with the full when shear is adjusted to include section at the yield stress for LRFD = maximum moment from factored self weight M_{u} A_{web} = area of the web of a wide flange loads for LRFD section P = name for axial force vector = width of a rectangle b Q = first moment area about a neutral = total width of material at a axis horizontal section R = radius of curvature of a deformed = name for height dimension beam = largest distance from the neutral S = section modulus С axis to the top or bottom edge of a $S_{rea'd}$ = section modulus required at allowable stress = coefficient for shear stress for a T= torque (axial moment) c_1 rectangular bar in torsion = internal shear force d = calculus symbol for differentiation V_{max} = maximum internal shear force $V_{max-adj} = \text{maximum internal shear force}$ DL= shorthand for dead load E= modulus of elasticity adjusted to include self weight f_b = bending stress V_u = maximum shear from factored loads = bearing stress (see P) for LRFD = shear stress = name for distributed load w_{selfwt} = name for distributed load from self f_{v-max} = maximum shear stress = allowable bending stress F_b weight of member F_{ν} = allowable shear stress = horizontal distance \boldsymbol{x} = allowable bearing stress = vertical distance F_p = yield strength Δ_{actual} = actual beam deflection F_{vweb} = yield strength of the web material $\Delta_{allowable}$ = allowable beam deflection = height of a rectangle Δ_{limit} = allowable beam deflection limit Δ_{max} = maximum beam deflection I = moment of inertia with respect to neutral axis bending = resistance factor for flexure in = moment of inertia of trial section LRFD design $I_{rea'd}$ = moment of inertia required at = resistance factor for shear for ϕ_{v} limiting deflection **LRFD** J= polar moment of inertia = density or unit weight γ L= name for span length

 ρ

Σ

= slope of the beam deflection curve

= radial distance

= symbol for integration

= summation symbol

Criteria for Design

Allowable bending stress or bending stress from LRFD should not be $F_b \ge f_b = \frac{Mc}{I}$ exceeded:

Knowing M and F_b , the minimum section modulus fitting the limit is: $S_{req'd} \ge \frac{M}{F_b}$

Besides strength, we also need to be concerned about *serviceability*. This involves things like limiting deflections & cracking, controlling noise and vibrations, preventing excessive settlements of foundations and durability. When we know about a beam section and its material, we can determine beam deformations.

Determining Maximum Bending Moment

Drawing V and M diagrams will show us the maximum values for design. Remember:

$$V = \Sigma(-w)dx$$

$$M = \Sigma(V)dx$$

$$\frac{dV}{dx} = -w$$

$$\frac{dM}{dx} = V$$

Determining Maximum Bending Stress

For a prismatic member (constant cross section), the maximum normal stress will occur at the maximum moment.

For a *non-prismatic* member, the stress varies with the cross section AND the moment.

Deflections

If the bending moment changes, M(x) across a beam of constant material and cross section then the curvature will change: $\frac{1}{R} = \frac{M(x)}{EI}$

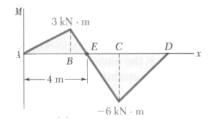
The slope of the n.a. of a beam, θ , will be tangent to the radius of curvature, R: $\theta = slope = \frac{1}{EI} \int M(x) dx$

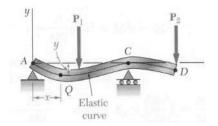
The equation for deflection, y, along a beam is: $y = \frac{1}{EI} \int \theta dx = \frac{1}{EI} \iint M(x) dx$

Elastic curve equations can be found in handbooks, textbooks, design manuals, etc...Computer programs can be used as well.

Elastic curve equations can be **superpositioned** ONLY if the stresses are in the elastic range.

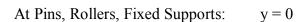
The deflected shape is roughly the shame shape as the bending moment diagram flipped but is constrained by supports and geometry.





Boundary Conditions

The boundary conditions are geometrical values that we know – slope or deflection – which may be restrained by supports or symmetry.



At Fixed Supports: $\theta = 0$

At Inflection Points From Symmetry: $\theta = 0$

The Slope Is Zero At The Maximum Deflection y_{max}:.

$$\theta = \frac{dy}{dx} = slope = 0$$

$y_A = 0$ $y_B = 0$ (a) Simply supported beam $y_A = 0$ $y_B = 0$ (b) Overhanging beam $y_A = 0$ $y_A = 0$ $y_A = 0$

(c) Cantilever beam

Allowable Deflection Limits

All building codes and design codes limit deflection for beam types and damage that could happen based on service condition and severity. $y_{\max}(x) = \Delta_{actual} \le \Delta_{allowable} = \frac{L}{value}$

Use	LL only	DL+LL
Roof beams:		
Industrial	L/180	L/120
Commercial		
plaster ceiling	L/240	L/180
no plaster	L/360	L/240
Floor beams:		
Ordinary Usage	L/360	L/240
Roof or floor (damageable elements)		L/480

Beam Loads & Load Tracing

In order to determine the loads on a beam (or girder, joist, column, frame, foundation...) we can start at the top of a structure and determine the *tributary area* that a load acts over and the beam needs to support. Loads come from material weights, people, and the environment. This area is assumed to be from half the distance to the next beam over to halfway to the next beam.

The reactions must be supported by the next lower structural element ad infinitum, to the ground.

Design Procedure

The intent is to find the most light weight member satisfying the section modulus size.

- 1. Know F_b (allowable stress) for the material or F_v & F_u for LRFD.
- 2. Draw V & M, finding M_{max}.
- 3. Calculate $S_{req'd}$. This step is equivalent to determining $f_b = \frac{M_{max}}{S} \le F_b$ 4. For rectangular beams $S = \frac{bh^2}{6}$
- - For steel or timber: use the section charts to find S that will work and remember that the beam self weight will increase $S_{req'd}$. And for steel, the design charts show the lightest section within a grouping of similar S's. $W_{self\ wt} = \gamma A$
 - For any thing else, try a nice value for b, and calculate h or the other way around.

****Determine the "updated" V_{max} and M_{max} including the beam self weight, and verify that the updated S_{req'd} has been met.*****

- 5. Consider lateral stability
- 6. Evaluate horizontal shear stresses using V_{max} to determine if $f_v \leq F_v$

 $f_{v-max} = \frac{3V}{2A} \approx \frac{V}{A_{web}} \text{ or } \frac{VQ}{Ib}$ For rectangular beams, W's, and others:

- $f_p = \frac{P}{A} \le F_p$ 7. Provide adequate bearing area at supports:
- $f_{v} = \frac{T\rho}{J} \text{ or } \frac{T}{c_{v}ah^{2}} \leq F_{v}$ 8. Evaluate shear due to torsion

(circular section or rectangular)

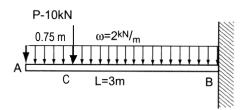
- 9. Evaluate the deflection to determine if $\Delta_{maxLL} \leq \Delta_{LL-allowed}$ and/or $\Delta_{maxTotal} \leq \Delta_{T-allowed}$
- **** note: when $\Delta_{calculated} > \Delta_{limib}$ $I_{required}$ can be found with: and $S_{req'd}$ will be satisfied for similar self weight ***** $I_{req'd} \ge \frac{\Delta_{toobig}}{\Delta_{toobig}} I_{trial}$

FOR ANY EVALUATION:

Redesign (with a new section) at any point that a stress or serviceability criteria is NOT satisfied and re-evaluate each condition until it is satisfactory.

Example 1 (changed from pg 284) (superpositioning) Example Problem 8.5 (Semi-Graphical Method)

A cantilever beam supports a uniform load of $\omega=2^{kN}\!\!/_m$ over its entire span, plus a concentrated load of 10 kN at the free end. . *Investigate using Beam Diagrams and Formulas*.

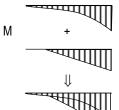


SOLUTION:

By examining the support conditions, we are looking for a cantilevered beam from Cases 18 through 23.

There is a case for uniformly distributed load across the span (19) and for a load at any point (21).

For both these cases, it shows that the maximum shear AND maximum moment are located at the fixed end. If we add the values, the shear and diagrams should look like this:



We can find the maximum shear (at B) from $V = P + wl = 10^{kN} + 2^{kN/m} \cdot 3^m = 16^{kN}$

The maximum moment (at B) will be M = Pb+wl²/2 = $10^{kN} \cdot 2.25^{m} + 2^{kN/m}(3^{m})^{2}/2 = \frac{31.5^{kN-m}}{2}$

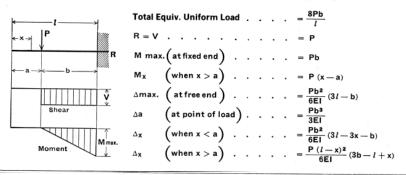
The key values for the diagrams can be found with the general equations (V_x and M_x): $V_{C_{\leftarrow}} = -wx = -2^{kN/m} \cdot 0.25^m = -0.5^{kN}$; $V_{C_{\rightarrow}} = -P - wx = -10^{kN} - 2^{kN/m} \cdot 0.25^m = -10.5^{kN}$ $M_C = -wx^2/2 = 2^{kN/m}(0.25^m)^2/2 = 0.0625^{kN-m}$

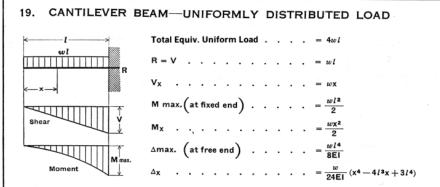
We can find the maximum deflection by looking at the cases. Both say Δ_{max} (at free end), so the values can be added directly. Superpositioning of values <u>must</u> be at the same x location. Assume E = $70x10^3$ MPa and I = $45x10^6$ mm⁴

$$\Delta_{\text{\tiny solut}} = \frac{Pb^2}{6EI} (3l - b) + \frac{wl^4}{8EI} = \frac{10^{\text{\tiny LN}} (2.25m)^2 (10^3 \text{ m/m/})^3 (10^3 \text{ N/k})}{6(70 \times 10^3 \text{ MPa})(45 \times 10^6 \text{ mm}^4)} (3 \cdot 3m - 2.25m) + \frac{2^{\frac{\text{\tiny LN}}{m}} (3m)^4 (10^3 \text{ m/m/})^3 (10^3 \text{ N/k})}{8(70 \times 10^3 \text{ MPa})(45 \times 10^6 \text{ mm}^4)} (3 \cdot 3m - 2.25m) + \frac{2^{\frac{\text{\tiny LN}}{m}} (3m)^4 (10^3 \text{ m/m/})^3 (10^3 \text{ N/k})}{8(70 \times 10^3 \text{ MPa})(45 \times 10^6 \text{ mm}^4)} (3 \cdot 3m - 2.25m) + \frac{2^{\frac{\text{\tiny LN}}{m}} (3m)^4 (10^3 \text{ m/m/})^3 (10^3 \text{ N/k})}{8(70 \times 10^3 \text{ MPa})(45 \times 10^6 \text{ mm}^4)} (3 \cdot 3m - 2.25m) + \frac{2^{\frac{\text{\tiny LN}}{m}} (3m)^4 (10^3 \text{ m/m/})^3 (10^3 \text{ N/k})}{8(70 \times 10^3 \text{ MPa})(45 \times 10^6 \text{ mm}^4)} (3 \cdot 3m - 2.25m) + \frac{2^{\frac{\text{\tiny LN}}{m}} (3m)^4 (10^3 \text{ m/m/})^3 (10^3 \text{ N/k})}{8(70 \times 10^3 \text{ MPa})(45 \times 10^6 \text{ mm}^4)} (3 \cdot 3m - 2.25m) + \frac{2^{\frac{\text{\tiny LN}}{m}} (3m)^4 (10^3 \text{ m/m/})^3 (10^3 \text{ N/k})}{8(70 \times 10^3 \text{ MPa})(45 \times 10^6 \text{ mm}^4)} (3 \cdot 3m - 2.25m) + \frac{2^{\frac{\text{\tiny LN}}{m}} (3m)^4 (10^3 \text{ m/m/})^3 (10^3 \text{ N/k})}{8(70 \times 10^3 \text{ MPa})(45 \times 10^6 \text{ mm}^4)} (3 \cdot 3m - 2.25m) + \frac{2^{\frac{\text{\tiny LN}}{m}} (3m)^4 (10^3 \text{ m/m/})^3 (10^3 \text{ N/k})}{8(70 \times 10^3 \text{ MPa})(45 \times 10^6 \text{ mm}^4)} (3 \cdot 3m - 2.25m) + \frac{2^{\frac{\text{\tiny LN}}{m}} (3m)^4 (10^3 \text{ m/m/})^3 (10^3 \text{ N/k})}{8(70 \times 10^3 \text{ MPa})(45 \times 10^6 \text{ mm}^4)} (3 \cdot 3m - 2.25m)} (3m)^4 (10^3 \text{ MPa})(45 \times 10^6 \text{ mm}^4)} (3m)^4 (10^3 \text{ m/m/})^3 (10^3 \text{ N/m})^3 (10^3 \text{ N/m/})^3 (1$$

= 18.08 mm + 6.43 mm = 24.5 mm

21. CANTILEVER BEAM-CONCENTRATED LOAD AT ANY POINT

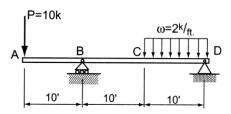




Example 2 (pg 275) (superpositioning)

Example Problem 8.2(Equilibrium Method)

Draw V and M diagrams for an overhang beam (Figure 8.12) loaded as shown. Determine the critical $V_{\rm max}$ and $M_{\rm max}$ locations and magnitudes $using\ Beam\ Diagrams\ and\ Formulas$.



SOLUTION:

By examining the support conditions, we are looking for beam with an overhang on one end from Cases 24 through 28. (Even though the overhang is on the right, and not on the left like our beam, we can still use the information by recognizing that we can mirror the figure about the left end.)

There is a case for a load at the end (26) but none for a load in between the supports. This is because it behaves exactly like a simply supported beam in this instance (no shear or bending on the overhang). The case for this is #5 (reversed again).

If we "flip" the diagrams (both vertically and horizontally) and add the values, the resulting shear and bending moment should look like this: V

We still have to find the peak values of shear and the location of the zero shear to find the critical moment values.

(Notice R₁ is shown down.)

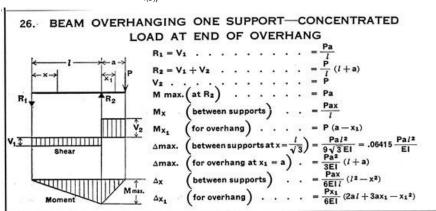
$$R_{1(D)} = -\frac{Pa}{l} + \frac{wa}{2l} (2l - a) = -\frac{10^k \cdot 10^{ft}}{20^{ft}} + \frac{2^{\frac{1}{f}} \cdot 10^{ft}}{2 \cdot 20^{ft}} (2 \cdot 20^{ft} - 10^{ft}) = 10^k$$

$$R_{\rm 2(B)} = 10^{\it ft} + 2^{\it k/ft} \cdot 10^{\it ft} - 10^{\it k} = 20^{\it k} \quad \text{(from the total downward load - R}_{\rm 1(D)})$$

$$\begin{array}{ll} V_A = -10^k & V_B = -10^k + 20^k = 10^k \\ V_D = 10^k - 2^{k/ft}(10ft) = -10^k \\ x \mbox{ (from B)} = 10^k/2^{k/ft} = 5 \mbox{ ft} \\ M_B = -10^k(10^{ft}) = -100^{k-ft} \\ (M_C = -100^{k-ft} + 10^k(10^{ft}) = 0) \\ M_x = 0 + 10^{k/ft}(5^ft)/2 = 25^{k-ft} \end{array}$$

$$V_{MAX} = 10 \text{ k } M_{MAX} = -100 \text{ k-ft}$$

We can calculate the deflection between the supports. (And at the end for case 5 if we derive the slope!) Assume E = 29x10³ ksi and I = 103 in⁴



We'll investigate the maximum between the supports from case 26 (because it isn't obvious where the maximum will be.)

$$x = \frac{1}{\sqrt{3}} = \frac{20^{9}}{\sqrt{3}} = 11.55^{9}$$
 (to left of D) and $\Delta_{local} = \Delta_{max-case 26} + \Delta_{x-case 5}$ with x (11.55ft) greater than a (10ft):

$$\Delta_{\text{\tiny Local}} = .06415 \frac{Pal^2}{EI} + \frac{wa^2(l-x)}{24EIl} \left(4xl - 2x^2 - a^2 \right)$$
 Note: Because there is only negative moment, the deflection is actually up!

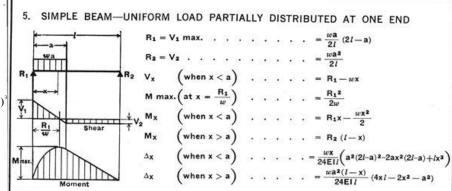
$$= -.06415 \frac{10^{k} (10^{f})(20^{f})^{2} (12^{(n+f)})^{3}}{(29 \cdot 10^{3} ksi)(103in^{4})} +$$

$$\frac{2^{k/f} (10^{f})^{2} (20^{f} - 10^{f})}{24 (29 \cdot 10^{3} ksi) (103in^{4}) (20^{f})} \times \dots$$

$$(4.11.55^{f} \cdot 20^{f} - 2(11.55^{f})^{2} - (10^{f})^{2})(12^{ff/f})^{3}$$

6

$$= -1.484 \text{ in} + 1.343 \text{ in} = -0.141 \text{ in (up)}$$



Beam Design Flow Chart

