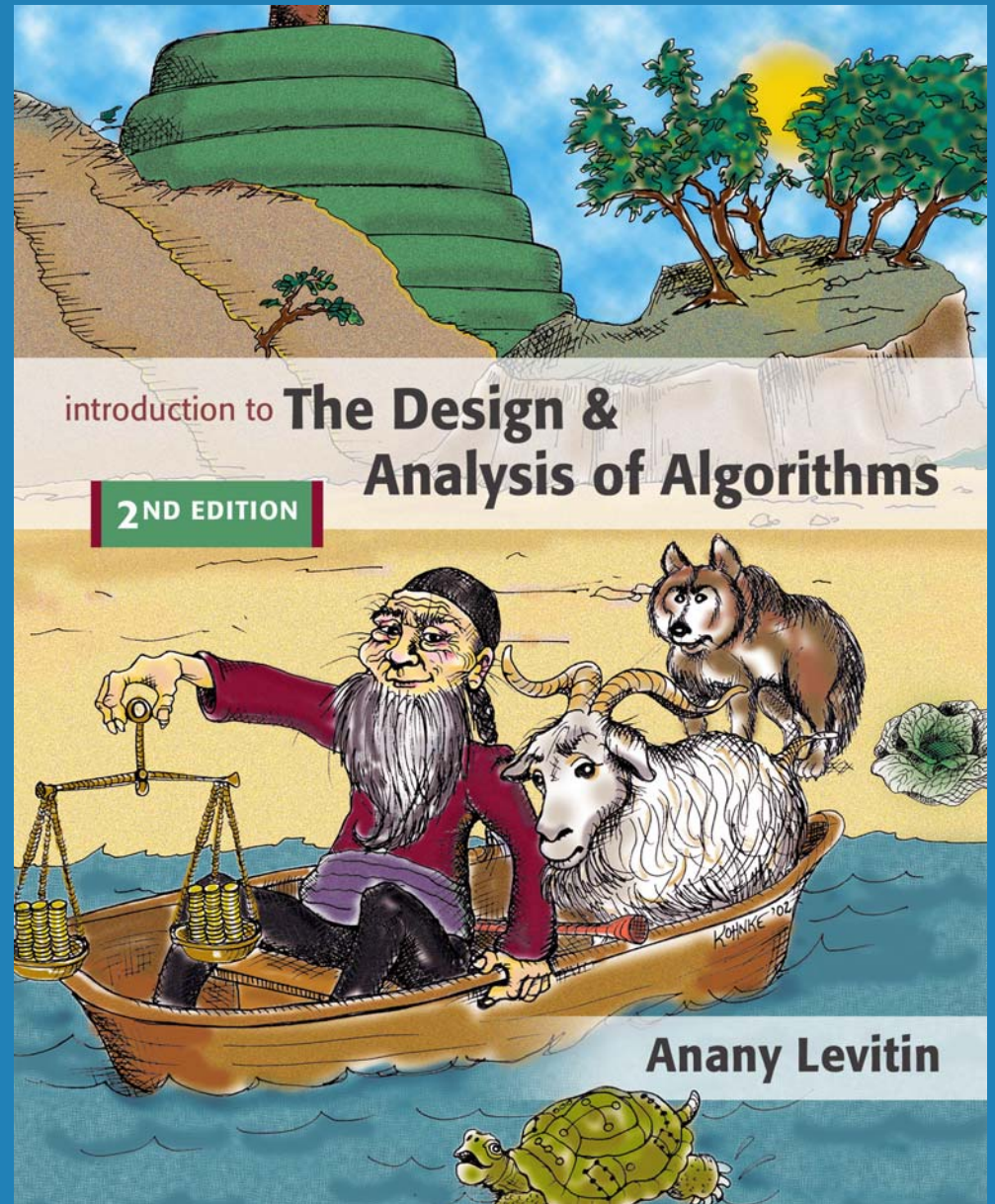
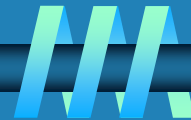


Chapter 8

Dynamic Programming



Dynamic Programming



Dynamic Programming is a general algorithm design technique for solving problems defined by recurrences with overlapping subproblems

- Invented by American mathematician Richard Bellman in the 1950s to solve optimization problems and later assimilated by CS
- “Programming” here means “planning”
- Main idea:
 - set up a recurrence relating a solution to a larger instance to solutions of some smaller instances
 - solve smaller instances once
 - record solutions in a table
 - extract solution to the initial instance from that table

Example: Fibonacci numbers



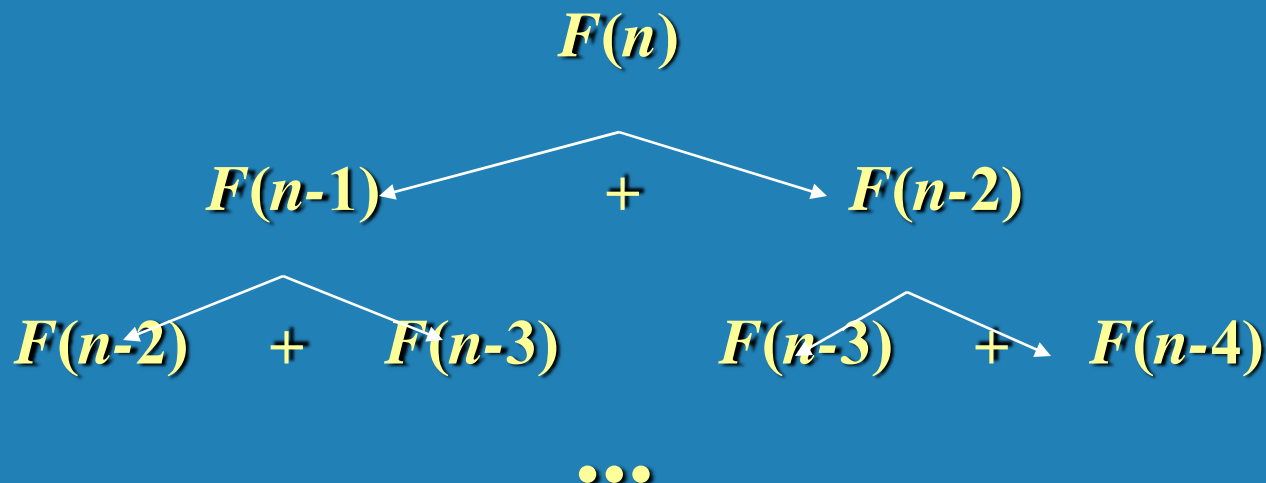
- Recall definition of Fibonacci numbers:

$$F(n) = F(n-1) + F(n-2)$$

$$F(0) = 0$$

$$F(1) = 1$$

- Computing the n^{th} Fibonacci number recursively (top-down):



Example: Fibonacci numbers (cont.)



Computing the n^{th} Fibonacci number using bottom-up iteration and recording results:

$$F(0) = 0$$

$$F(1) = 1$$

$$F(2) = 1 + 0 = 1$$

...

$$F(n-2) =$$

$$F(n-1) =$$

$$F(n) = F(n-1) + F(n-2)$$

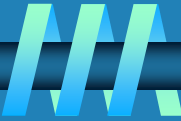
| | | | | | | |
|---|---|---|-----|----------|----------|--------|
| 0 | 1 | 1 | ... | $F(n-2)$ | $F(n-1)$ | $F(n)$ |
|---|---|---|-----|----------|----------|--------|

Efficiency:

- time

- space

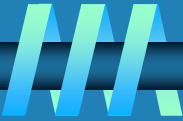
Examples of DP algorithms



- **Computing a binomial coefficient**
- **Warshall's algorithm for transitive closure**
- **Floyd's algorithm for all-pairs shortest paths**
- **Constructing an optimal binary search tree**
- **Some instances of difficult discrete optimization problems:**
 - **traveling salesman**
 - **knapsack**



Computing a binomial coefficient by DP



Binomial coefficients are coefficients of the binomial formula:

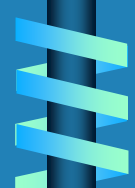
$$(a + b)^n = C(n,0)a^n b^0 + \dots + C(n,k)a^{n-k}b^k + \dots + C(n,n)a^0 b^n$$

Recurrence: $C(n,k) = C(n-1,k) + C(n-1,k-1)$ for $n > k > 0$

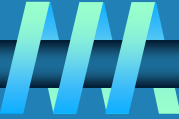
$$C(n,0) = 1, \quad C(n,n) = 1 \quad \text{for } n \geq 0$$

Value of $C(n,k)$ can be computed by filling a table:

| | 0 | 1 | 2 | ... | $k-1$ | k |
|-------|---|---|---|-----|--------------|------------|
| 0 | 1 | | | | | |
| 1 | 1 | 1 | | | | |
| . | | | | | | |
| . | | | | | | |
| . | | | | | | |
| $n-1$ | | | | | $C(n-1,k-1)$ | $C(n-1,k)$ |
| n | | | | | | $C(n,k)$ |



Computing $C(n, k)$: pseudocode and analysis



ALGORITHM *Binomial*(n, k)

//Computes $C(n, k)$ by the dynamic programming algorithm

//Input: A pair of nonnegative integers $n \geq k \geq 0$

//Output: The value of $C(n, k)$

for $i \leftarrow 0$ **to** n **do**

for $j \leftarrow 0$ **to** $\min(i, k)$ **do**

if $j = 0$ **or** $j = i$

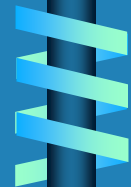
$C[i, j] \leftarrow 1$

else $C[i, j] \leftarrow C[i - 1, j - 1] + C[i - 1, j]$

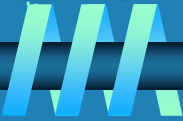
return $C[n, k]$

Time efficiency: $\Theta(nk)$

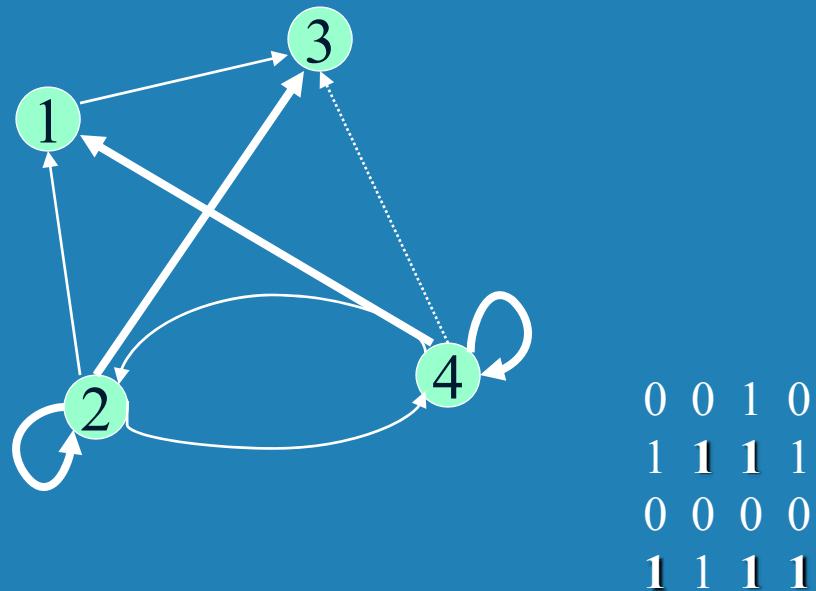
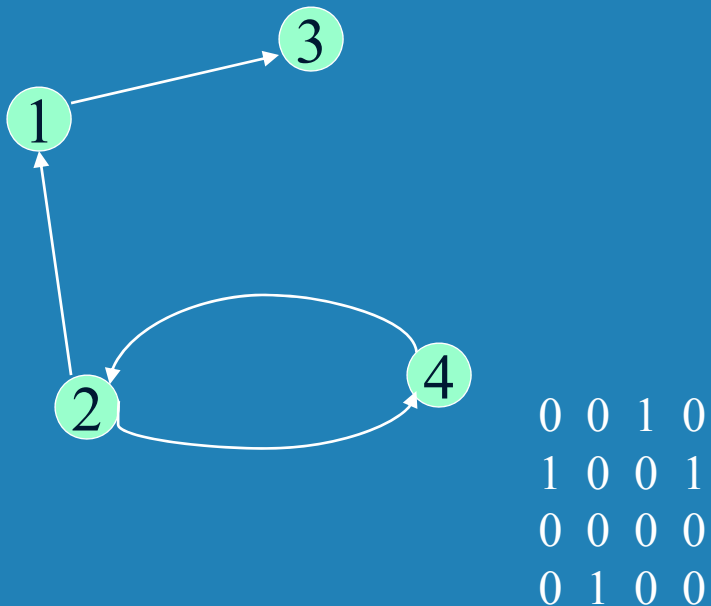
Space efficiency: $\Theta(nk)$



Warshall's Algorithm: Transitive Closure



- Computes the transitive closure of a relation
- Alternatively: existence of all nontrivial paths in a digraph
- Example of transitive closure:

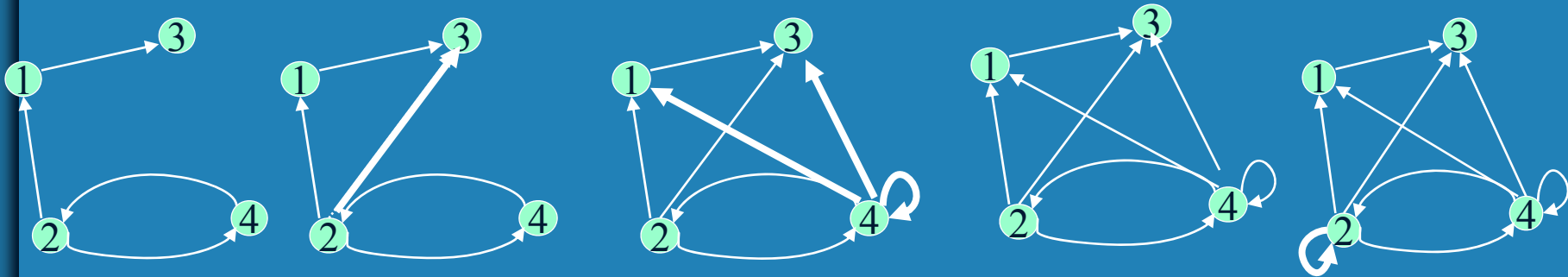


Warshall's Algorithm

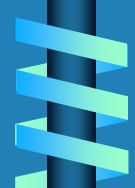


Constructs transitive closure T as the last matrix in the sequence of n -by- n matrices $R^{(0)}, \dots, R^{(k)}, \dots, R^{(n)}$ where $R^{(k)}[i,j] = 1$ iff there is nontrivial path from i to j with only first k vertices allowed as intermediate

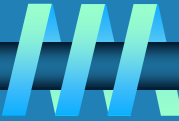
Note that $R^{(0)} = A$ (adjacency matrix), $R^{(n)} = T$ (transitive closure)



| $R^{(0)}$ | $R^{(1)}$ | $R^{(2)}$ | $R^{(3)}$ | $R^{(4)}$ |
|-----------|-----------|-----------|-----------|-----------|
| 0 0 1 0 | 0 0 1 0 | 0 0 1 0 | 0 0 1 0 | 0 0 1 0 |
| 1 0 0 1 | 1 0 1 1 | 1 0 1 1 | 1 0 1 1 | 1 1 1 1 |
| 0 0 0 0 | 0 0 0 0 | 0 0 0 0 | 0 0 0 0 | 0 0 0 0 |
| 0 1 0 0 | 0 1 0 0 | 1 1 1 1 | 1 1 1 1 | 1 1 1 1 |

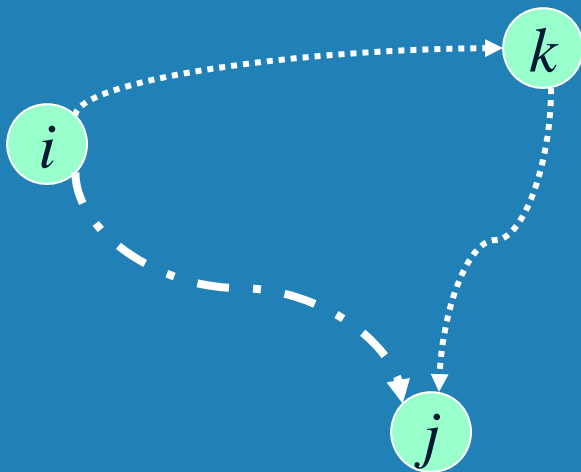


Warshall's Algorithm (recurrence)

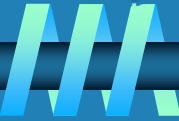


On the k -th iteration, the algorithm determines for every pair of vertices i, j if a path exists from i and j with just vertices $1, \dots, k$ allowed as intermediate

$$R^{(k)}[i,j] = \begin{cases} R^{(k-1)}[i,j] & \text{(path using just } 1, \dots, k-1) \\ \text{or} \\ R^{(k-1)}[i,k] \text{ and } R^{(k-1)}[k,j] & \text{(path from } i \text{ to } k \\ & \text{and from } k \text{ to } i \\ & \text{using just } 1, \dots, k-1) \end{cases}$$



Warshall's Algorithm (matrix generation)



Recurrence relating elements $R^{(k)}$ to elements of $R^{(k-1)}$ is:

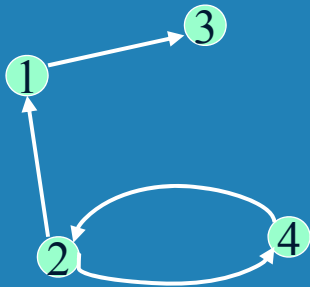
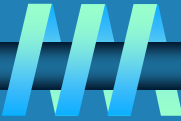
$$R^{(k)}[i,j] = R^{(k-1)}[i,j] \text{ or } (R^{(k-1)}[i,k] \text{ and } R^{(k-1)}[k,j])$$

It implies the following rules for generating $R^{(k)}$ from $R^{(k-1)}$:

Rule 1 If an element in row i and column j is 1 in $R^{(k-1)}$, it remains 1 in $R^{(k)}$

Rule 2 If an element in row i and column j is 0 in $R^{(k-1)}$, it has to be changed to 1 in $R^{(k)}$ if and only if the element in its row i and column k and the element in its column j and row k are both 1's in $R^{(k-1)}$

Warshall's Algorithm (example)



$$R^{(0)} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

$$R^{(1)} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

$$R^{(2)} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

$$R^{(3)} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

$$R^{(4)} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

Warshall's Algorithm (pseudocode and analysis)



ALGORITHM *Warshall*($A[1..n, 1..n]$)

//Implements Warshall's algorithm for computing the transitive closure

//Input: The adjacency matrix A of a digraph with n vertices

//Output: The transitive closure of the digraph

$R^{(0)} \leftarrow A$

for $k \leftarrow 1$ **to** n **do**

for $i \leftarrow 1$ **to** n **do**

for $j \leftarrow 1$ **to** n **do**

$R^{(k)}[i, j] \leftarrow R^{(k-1)}[i, j]$ **or** ($R^{(k-1)}[i, k]$ **and** $R^{(k-1)}[k, j]$)

return $R^{(n)}$

Time efficiency: $\Theta(n^3)$

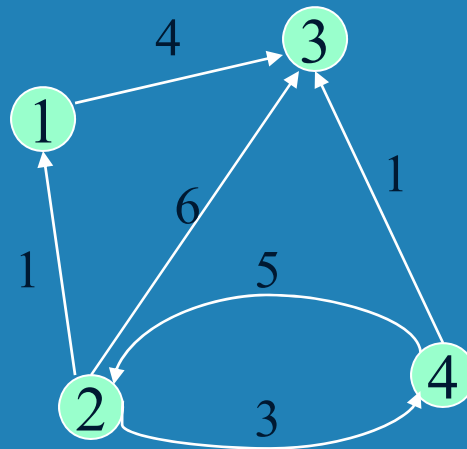
Space efficiency: Matrices can be written over their predecessors

Floyd's Algorithm: All pairs shortest paths

Problem: In a weighted (di)graph, find shortest paths between every pair of vertices

Same idea: construct solution through series of matrices $D^{(0)}$, ..., $D^{(n)}$ using increasing subsets of the vertices allowed as intermediate

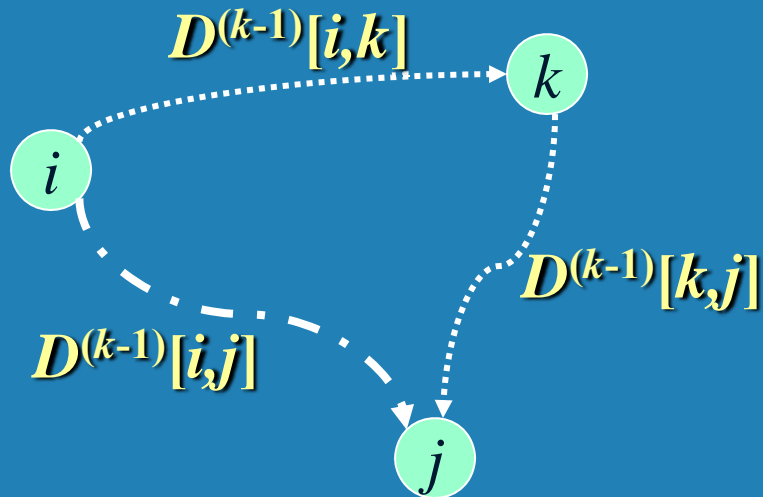
Example:



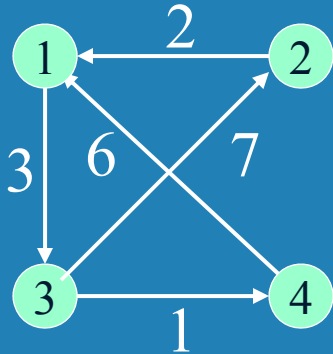
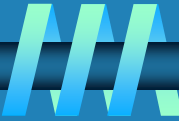
Floyd's Algorithm (matrix generation)

On the k -th iteration, the algorithm determines shortest paths between every pair of vertices i, j that use only vertices among $1, \dots, k$ as intermediate

$$D^{(k)}[i,j] = \min \{D^{(k-1)}[i,j], D^{(k-1)}[i,k] + D^{(k-1)}[k,j]\}$$



Floyd's Algorithm (example)



$$D^{(0)} =$$

| | | | |
|----------|----------|----------|----------|
| 0 | ∞ | 3 | ∞ |
| 2 | 0 | ∞ | ∞ |
| ∞ | 7 | 0 | 1 |
| 6 | ∞ | ∞ | 0 |

$$D^{(1)} =$$

| | | | |
|----------|----------|---|----------|
| 0 | ∞ | 3 | ∞ |
| 2 | 0 | 5 | ∞ |
| ∞ | 7 | 0 | 1 |
| 6 | ∞ | 9 | 0 |

$$D^{(2)} =$$

| | | | |
|---|----------|---|----------|
| 0 | ∞ | 3 | ∞ |
| 2 | 0 | 5 | ∞ |
| 9 | 7 | 0 | 1 |
| 6 | ∞ | 9 | 0 |

$$D^{(3)} =$$

| | | | |
|---|----|---|---|
| 0 | 10 | 3 | 4 |
| 2 | 0 | 5 | 6 |
| 9 | 7 | 0 | 1 |
| 6 | 16 | 9 | 0 |

$$D^{(4)} =$$

| | | | |
|---|----|---|---|
| 0 | 10 | 3 | 4 |
| 2 | 0 | 5 | 6 |
| 7 | 7 | 0 | 1 |
| 6 | 16 | 9 | 0 |

Floyd's Algorithm (pseudocode and analysis)

ALGORITHM *Floyd*($W[1..n, 1..n]$)

//Implements Floyd's algorithm for the all-pairs shortest-paths problem

//Input: The weight matrix W of a graph with no negative-length cycle

//Output: The distance matrix of the shortest paths' lengths

$D \leftarrow W$ //is not necessary if W can be overwritten

for $k \leftarrow 1$ **to** n **do**

for $i \leftarrow 1$ **to** n **do**

for $j \leftarrow 1$ **to** n **do**

$D[i, j] \leftarrow \min\{D[i, j], D[i, k] + D[k, j]\}$

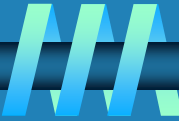
return D

Time efficiency: $\Theta(n^3)$

Space efficiency: Matrices can be written over their predecessors

Note: Shortest paths themselves can be found, too

Optimal Binary Search Trees



Problem: Given n keys $a_1 < \dots < a_n$ and probabilities $p_1 \leq \dots \leq p_n$ searching for them, find a BST with a minimum average number of comparisons in successful search.

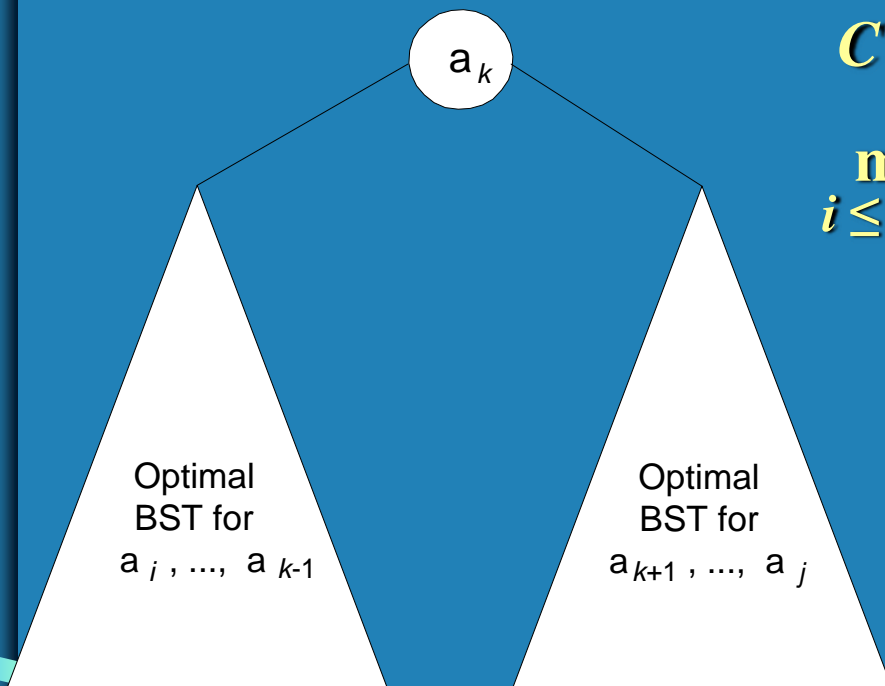
Since total number of BSTs with n nodes is given by $C(2n, n)/(n+1)$, which grows exponentially, brute force is hopeless.

Example: What is an optimal BST for keys $A, B, C,$ and D with search probabilities 0.1, 0.2, 0.4, and 0.3, respectively?

DP for Optimal BST Problem



Let $C[i,j]$ be minimum average number of comparisons made in $T[i,j]$, optimal BST for keys $a_i < \dots < a_j$, where $1 \leq i \leq j \leq n$. Consider optimal BST among all BSTs with some a_k ($i \leq k \leq j$) as their root; $T[i,j]$ is the best among them.



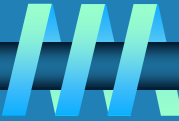
$$C[i,j] =$$

$$\min_{i \leq k \leq j} \{p_k \cdot 1 +$$

$$\sum_{s=i}^{k-1} p_s (\text{level } a_s \text{ in } T[i,k-1] + 1) +$$

$$\sum_{s=k+1}^j p_s (\text{level } a_s \text{ in } T[k+1,j] + 1)\}$$

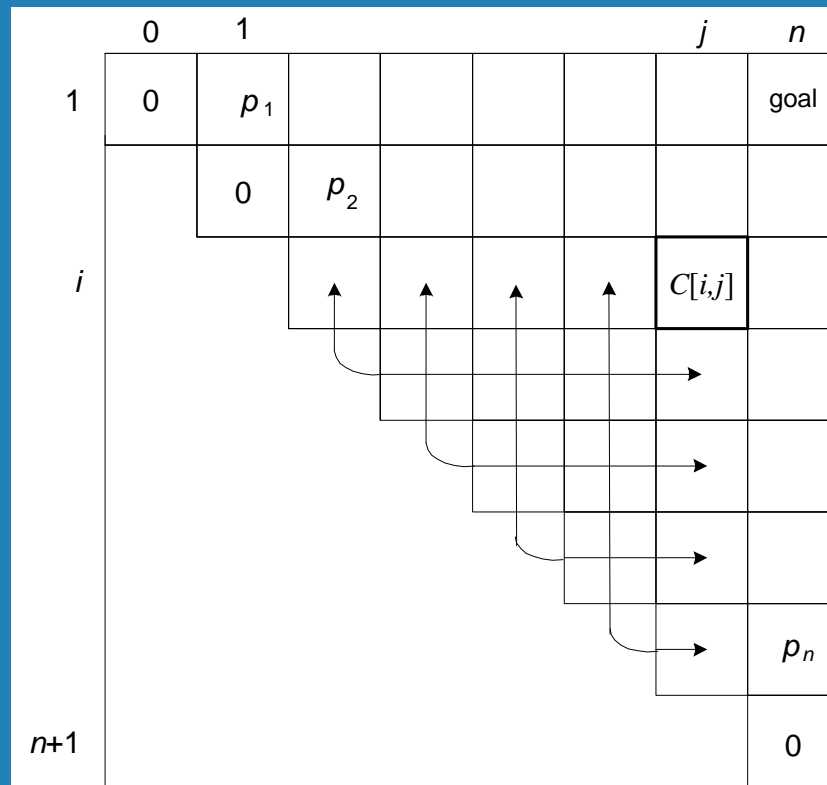
DP for Optimal BST Problem (cont.)



After simplifications, we obtain the recurrence for $C[i,j]$:

$$C[i,j] = \min_{i \leq k \leq j} \{C[i,k-1] + C[k+1,j]\} + \sum_{s=i}^j p_s \quad \text{for } 1 \leq i \leq j \leq n$$

$$C[i,i] = p_i \quad \text{for } 1 \leq i \leq j \leq n$$



Example: key *A* *B* *C* *D*
 probability 0.1 0.2 0.4 0.3

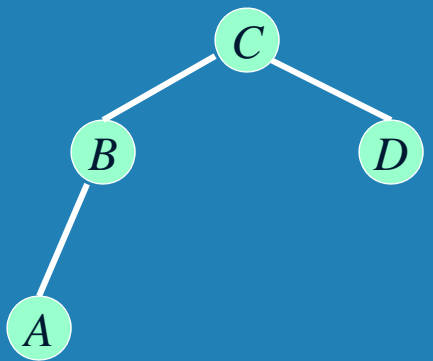
The tables below are filled diagonal by diagonal: the left one is filled using the recurrence

$$C[i,j] = \min_{i \leq k \leq j} \{C[i,k-1] + C[k+1,j]\} + \sum_{s=i}^j p_s, \quad C[i,i] = p_i;$$

the right one, for trees' roots, records *k*'s values giving the minima

| <i>i</i> \ <i>j</i> | 0 | 1 | 2 | 3 | 4 |
|---------------------|---|----|----|-----|-----|
| 1 | 0 | .1 | .4 | 1.1 | 1.7 |
| 2 | | 0 | .2 | .8 | 1.4 |
| 3 | | | 0 | .4 | 1.0 |
| 4 | | | | 0 | .3 |
| 5 | | | | | 0 |

| <i>i</i> \ <i>j</i> | 0 | 1 | 2 | 3 | 4 |
|---------------------|---|---|---|---|---|
| 1 | | 1 | 2 | 3 | 3 |
| 2 | | | 2 | 3 | 3 |
| 3 | | | | 3 | 3 |
| 4 | | | | | 4 |
| 5 | | | | | |



optimal BST

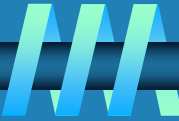
Optimal Binary Search Trees



ALGORITHM *OptimalBST*($P[1..n]$)

```
//Finds an optimal binary search tree by dynamic programming
//Input: An array  $P[1..n]$  of search probabilities for a sorted list of  $n$  keys
//Output: Average number of comparisons in successful searches in the
//        optimal BST and table  $R$  of subtrees' roots in the optimal BST
for  $i \leftarrow 1$  to  $n$  do
     $C[i, i - 1] \leftarrow 0$ 
     $C[i, i] \leftarrow P[i]$ 
     $R[i, i] \leftarrow i$ 
 $C[n + 1, n] \leftarrow 0$ 
for  $d \leftarrow 1$  to  $n - 1$  do //diagonal count
    for  $i \leftarrow 1$  to  $n - d$  do
         $j \leftarrow i + d$ 
         $minval \leftarrow \infty$ 
        for  $k \leftarrow i$  to  $j$  do
            if  $C[i, k - 1] + C[k + 1, j] < minval$ 
                 $minval \leftarrow C[i, k - 1] + C[k + 1, j]$ ;  $kmin \leftarrow k$ 
             $R[i, j] \leftarrow kmin$ 
         $sum \leftarrow P[i]$ ; for  $s \leftarrow i + 1$  to  $j$  do  $sum \leftarrow sum + P[s]$ 
         $C[i, j] \leftarrow minval + sum$ 
return  $C[1, n], R$ 
```

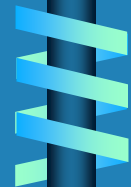
Analysis DP for Optimal BST Problem



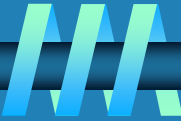
Time efficiency: $\Theta(n^3)$ but can be reduced to $\Theta(n^2)$ by taking advantage of monotonicity of entries in the root table, i.e., $R[i,j]$ is always in the range between $R[i,j-1]$ and $R[i+1,j]$

Space efficiency: $\Theta(n^2)$

Method can be expended to include unsuccessful searches



Knapsack Problem by DP



Given n items of

integer weights: $w_1 \ w_2 \ \dots \ w_n$

values: $v_1 \ v_2 \ \dots \ v_n$

a knapsack of integer capacity W

find most valuable subset of the items that fit into the knapsack

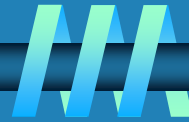
Consider instance defined by first i items and capacity j ($j \leq W$).

Let $V[i,j]$ be optimal value of such instance. Then

$$V[i,j] = \begin{cases} \max \{V[i-1,j], v_i + V[i-1,j-w_i]\} & \text{if } j-w_i \geq 0 \\ V[i-1,j] & \text{if } j-w_i < 0 \end{cases}$$

Initial conditions: $V[0,j] = 0$ and $V[i,0] = 0$

Visualizing this Relationship



| | | | | | |
|------------|-------|---|-----------------|-------------|------|
| | | 0 | $j-w_i$ | j | W |
| | 0 | 0 | 0 | 0 | 0 |
| | $i-1$ | 0 | $V[i-1, j-w_i]$ | $V[i-1, j]$ | |
| w_i, v_i | i | 0 | | $V[i, j]$ | |
| | n | 0 | | | goal |

$$V[i, j] = \begin{cases} \max \{V[i-1, j], v_i + V[i-1, j-w_i]\} & \text{if } j-w_i \geq 0 \\ V[i-1, j] & \text{if } j-w_i < 0 \end{cases}$$

- ⌚ So we can build up the table, left to right by repeatedly applying the result of this expression
- ⌚ The initial conditions are shown by the first row and first column with 0 values

Knapsack Problem by DP (example)



Example: Knapsack of capacity $W = 5$

| <u>item</u> | <u>weight</u> | <u>value</u> |
|-------------|---------------|--------------|
| 1 | 2 | \$12 |
| 2 | 1 | \$10 |
| 3 | 3 | \$20 |
| 4 | 2 | \$15 |

We know the solution is 37; the next question is how we find the items actually involved.

$$w_1 = 2, v_1 = 12$$

$$w_2 = 1, v_2 = 10$$

$$w_3 = 3, v_3 = 20$$

$$w_4 = 2, v_4 = 15$$

| | capacity j | | | | | |
|-----|--------------|----|----|----|----|----|
| i | 0 | 1 | 2 | 3 | 4 | 5 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | 0 | 0 | 12 | 12 | 12 | 12 |
| 2 | 0 | 10 | 12 | 22 | 22 | 22 |
| 3 | 0 | 10 | 12 | 22 | 30 | 32 |
| 4 | 0 | 10 | 15 | 25 | 30 | 37 |

Top Down Approach with Memorization



- ⌚ We can use a top down approach by storing all results
- ⌚ When we need a value we first ask have we stored it

ALGORITHM *MFKnapsack*(*i*, *j*)

```
//Implements the memory function method for the knapsack problem
//Input: A nonnegative integer i indicating the number of the first
//       items being considered and a nonnegative integer j indicating
//       the knapsack's capacity
//Output: The value of an optimal feasible subset of the first i items
//Note: Uses as global variables input arrays Weights[1..n], Values[1..n],
//and table V[0..n, 0..W] whose entries are initialized with -1's except for
//row 0 and column 0 initialized with 0's
if V[i, j] < 0
    if j < Weights[i]
        value ← MFKnapsack(i - 1, j)
    else
        value ← max(MFKnapsack(i - 1, j),
                    Values[i] + MFKnapsack(i - 1, j - Weights[i]))
    V[i, j] ← value
return V[i, j]
```

Example of Memorization



| | capacity j | | | | | |
|-----|--------------|---|----|----|----|----|
| i | 0 | 1 | 2 | 3 | 4 | 5 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | 0 | 0 | 12 | 12 | 12 | 12 |
| 2 | 0 | – | 12 | 22 | – | 22 |
| 3 | 0 | – | – | 22 | – | 32 |
| 4 | 0 | – | – | – | – | 37 |

- ⌚ Notice that not all values need to be calculated
- ⌚ Only eleven out of twenty of the nontrivial values (the zeros) need to be computed