Chapter 8: Friction

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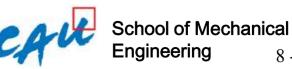
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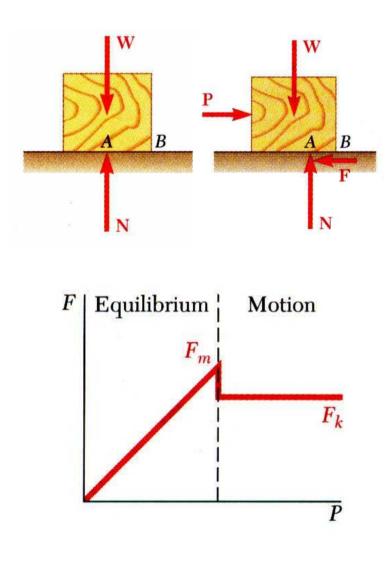


Introduction

- In preceding chapters, it was assumed that surfaces in contact were either *frictionless* (surfaces could move freely with respect to each other) or rough (tangential forces prevent relative motion between surfaces).
- Actually, no perfectly frictionless surface exists. For two surfaces in contact, tangential forces, called *friction forces*, will develop if one attempts to move one relative to the other.
- However, the friction forces are limited in magnitude and will not prevent motion if sufficiently large forces are applied.
- The distinction between frictionless and rough is, therefore, a matter of degree.
- There are two types of friction: *dry* or *Coulomb friction* and *fluid friction*. Fluid friction applies to lubricated mechanisms. The present discussion is limited to dry friction between nonlubricated surfaces.



The Laws of Dry Friction. Coefficients of Friction



- Block of weight *W* placed on horizontal surface. Forces acting on block are its weight and reaction of surface *N*.
- Small horizontal force *P* applied to block. For block to remain stationary, in equilibrium, a horizontal component *F* of the surface reaction is required. *F* is a *static-friction force*.
- As P increases, the static-friction force F increases as well until it reaches a maximum value F_m .

$$F_m = \mu_s N$$

• Further increase in P causes the block to begin to move as *F* drops to a smaller *kinetic-friction force F*_k.



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The Laws of Dry Friction. Coefficients of Friction

Table 8.1.ApproximateValues of Coefficient of StaticFriction for Dry Surfaces

Metal on metal	0.15 - 0.60
Metal on wood	0.20 - 0.60
Metal on stone	0.30 - 0.70
Metal on leather	0.30 - 0.60
Wood on wood	0.25 - 0.50
Wood on leather	0.25 - 0.50
Stone on stone	0.40 - 0.70
Earth on earth	0.20 - 1.00
Rubber on concrete	0.60 - 0.90

• Maximum static-friction force:

$$F_m = \mu_s N$$

• Kinetic-friction force:

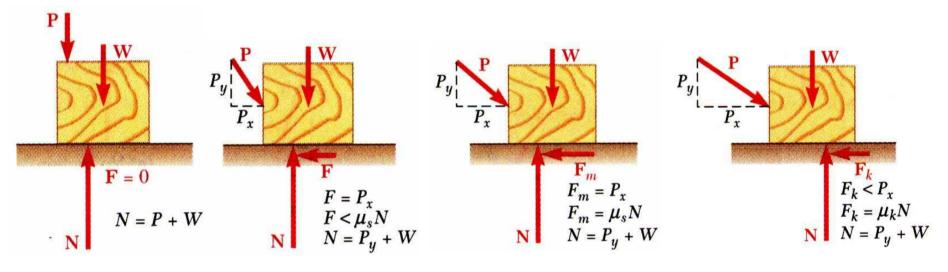
$$F_k = \mu_k N$$
$$\mu_k \cong 0.75 \mu_s$$

- Maximum static-friction force and kineticfriction force are:
 - proportional to normal force
 - dependent on type and condition of contact surfaces
 - independent of contact area



The Laws of Dry Friction. Coefficients of Friction

• Four situations can occur when a rigid body is in contact with a horizontal surface:

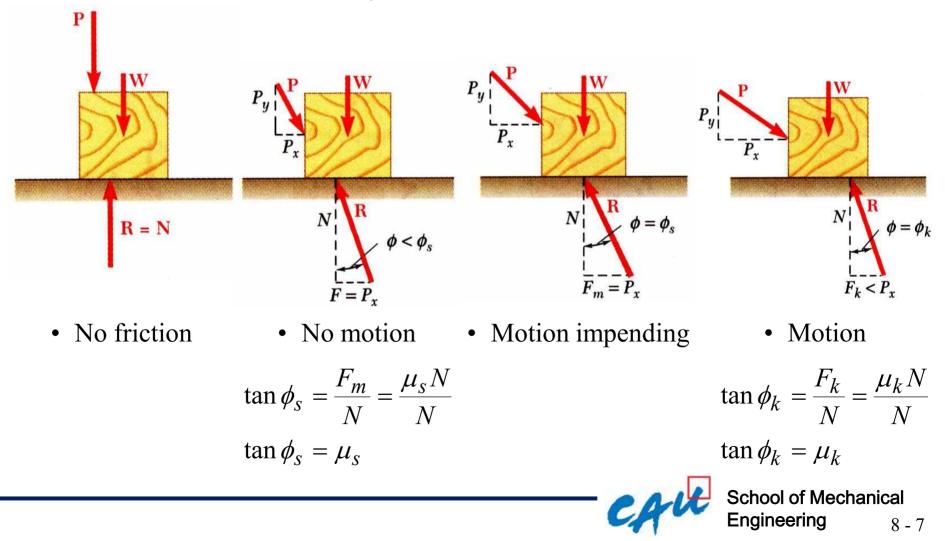


- No friction, No $(P_x = 0)$ (P
- No motion, $(P_x < F_m)$ • Motion in $(P_x = F_m)$
- Motion impending, $(P_x = F_m)$
- Motion, $(P_x > F_m)$



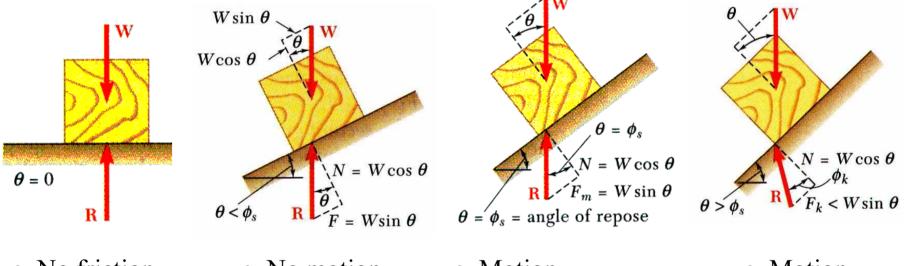
Angles of Friction

• It is sometimes convenient to replace normal force N and friction force F by their resultant **R**:



Angles of Friction

• Consider block of weight W resting on board with variable inclination angle θ .



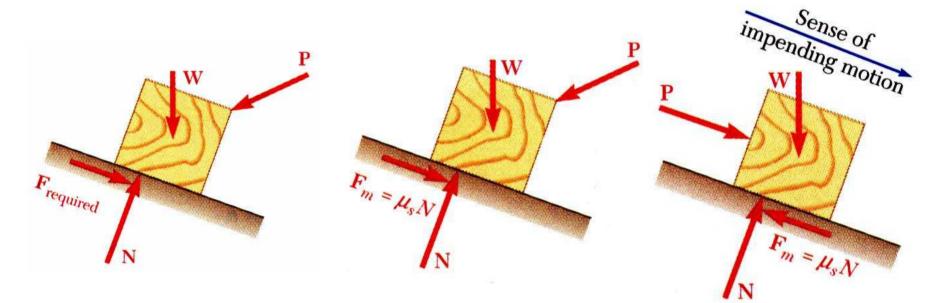
• No friction

- No motion
- Motion impending

• Motion



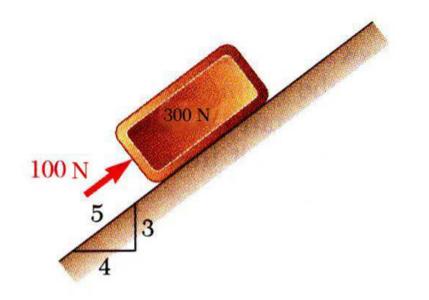
Problems Involving Dry Friction



- All applied forces known
- Coefficient of static friction is known
- Determine whether body will remain at rest or slide

- All applied forces known
- Motion is impending
- Determine value of coefficient of static friction.
- Coefficient of static friction is known
- Motion is impending
 - Determine magnitude or direction of one of the applied forces



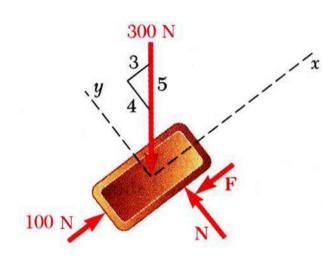


A 100 N force acts as shown on a 300 N block placed on an inclined plane. The coefficients of friction between the block and plane are $\mu_s = 0.25$ and $\mu_k = 0.20$. Determine whether the block is in equilibrium and find the value of the friction force.

SOLUTION:

- Determine values of friction force and normal reaction force from plane required to maintain equilibrium.
- Calculate maximum friction force and compare with friction force required for equilibrium. If it is greater, block will not slide.
- If maximum friction force is less than friction force required for equilibrium, block will slide. Calculate kinetic-friction force.





SOLUTION:

Determine values of friction force and normal reaction force from plane required to maintain equilibrium.

$$\sum F_x = 0: \quad 100 \text{ N} - \frac{3}{5}(300 \text{ N}) - F = 0$$
$$F = -80 \text{ N}$$
$$\sum F_y = 0: \quad N - \frac{4}{5}(300 \text{ N}) = 0$$

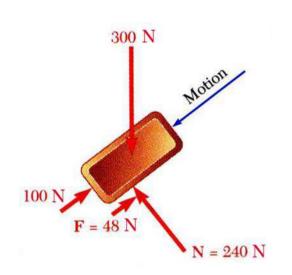
N = 240 N

• Calculate maximum friction force and compare with friction force required for equilibrium. If it is greater, block will not slide.

$$F_m = \mu_s N$$
 $F_m = 0.25(240 \text{ N}) = 60 \text{ N}$

The block will slide down the plane.

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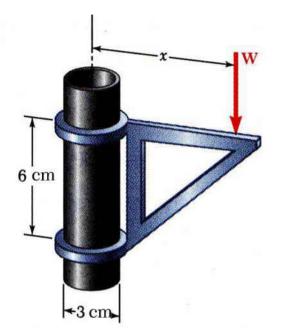


• If maximum friction force is less than friction force required for equilibrium, block will slide. Calculate kinetic-friction force.

$$F_{actual} = F_k = \mu_k N$$
$$= 0.20(240 N)$$

$$F_{actual} = 48 \text{ N}$$



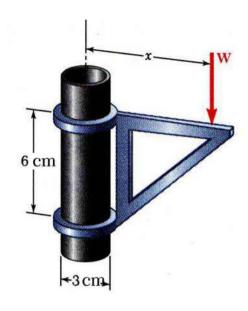


The moveable bracket shown may be placed at any height on the 3-cm diameter pipe. If the coefficient of friction between the pipe and bracket is 0.25, determine the minimum distance x at which the load can be supported. Neglect the weight of the bracket.

SOLUTION:

- When *W* is placed at minimum *x*, the bracket is about to slip and friction forces in upper and lower collars are at maximum value.
- Apply conditions for static equilibrium to find minimum *x*.





←x – 1.5 cm →

FA

6 cm

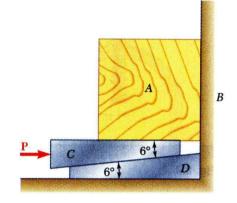
+3 cm

SOLUTION:

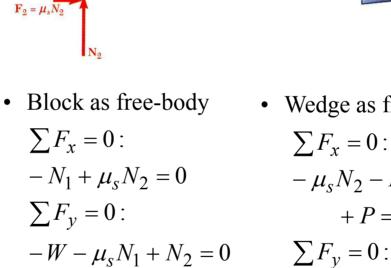
- When *W* is placed at minimum *x*, the bracket is about to slip and friction forces in upper and lower collars are at maximum value.
 - $F_A = \mu_s N_A = 0.25 N_A$ $F_B = \mu_s N_B = 0.25 N_B$
- Apply conditions for static equilibrium to find minimum x. $\sum F_x = 0: \quad N_B - N_A = 0 \qquad N_B = N_A$ $\sum F_y = 0: \quad F_A + F_B - W = 0$ $0.25N_A + 0.25N_B - W = 0$ $0.5N_A = W \qquad N_A = N_B = 2W$ $\sum M_B = 0: N_A (6 \text{ cm}) - F_A (3 \text{ cm}) - W(x - 1.5 \text{ cm}) = 0$ $6N_A - 3(0.25N_A) - W(x - 1.5) = 0$ 6(2W) - 0.75(2W) - W(x - 1.5) = 0School of Mechanical Engineering School of Mechanical Engin

Wedges

 $\mathbf{F}_1 = \mu_s N_1$

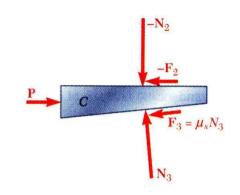


- *Wedges* simple machines used to raise heavy loads.
- Force required to lift block is significantly less than block weight.
- Friction prevents wedge from sliding out.
- Want to find minimum force *P* to raise block.



or

 $\vec{R}_1 + \vec{R}_2 + \vec{W} = 0$



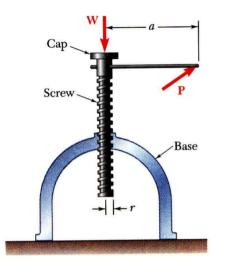
• Wedge as free-body $\sum F_x = 0:$ $-\mu_s N_2 - N_3 (\mu_s \cos 6^\circ - \sin 6^\circ)$ + P = 0 $\sum F_y = 0:$ $-N_2 + N_3 (\cos 6^\circ - \mu_s \sin 6^\circ) = 0$

$$\vec{P} - \vec{R}_2 + \vec{R}_3 = 0$$

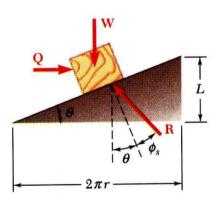
or



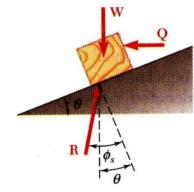
Square-Threaded Screws



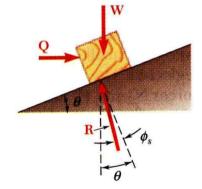
- Square-threaded screws frequently used in jacks, presses, etc. Analysis similar to block on inclined plane. Recall friction force does not depend on area of contact.
- Thread of base has been "unwrapped" and shown as straight line. Slope is $2\pi r$ horizontally and lead *L* vertically.
- Moment of force Q is equal to moment of force P. Q = Pa/r



• Impending motion upwards. Solve for *Q*.



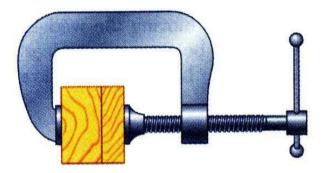
• $\phi_s > \theta$, Self-locking, solve for *Q* to lower load.



• $\phi_s > \theta$, Non-locking, solve for Q to hold load.



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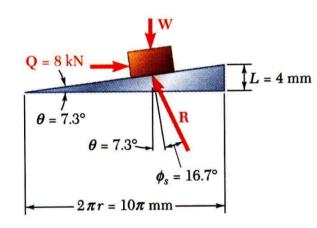
A clamp is used to hold two pieces of wood together as shown. The clamp has a double square thread of mean diameter equal to 10 mm with a pitch of 2 mm. The coefficient of friction between threads is $\mu_s = 0.30$.

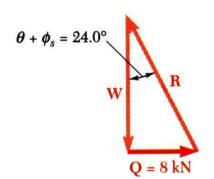
If a maximum torque of 40 N*m is applied in tightening the clamp, determine (a) the force exerted on the pieces of wood, and (b) the torque required to loosen the clamp.

SOLUTION

- Calculate lead angle and pitch angle.
- Using block and plane analogy with impending motion up the plane, calculate the clamping force with a force triangle.
- With impending motion down the plane, calculate the force and torque required to loosen the clamp.







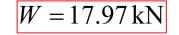
SOLUTION

• Calculate lead angle and pitch angle. For the double threaded screw, the lead *L* is equal to twice the pitch.

$$\tan \theta = \frac{L}{2\pi r} = \frac{2(2 \text{ mm})}{10\pi \text{ mm}} = 0.1273 \qquad \theta = 7.3^{\circ}$$
$$\tan \phi_s = \mu_s = 0.30 \qquad \phi_s = 16.7^{\circ}$$

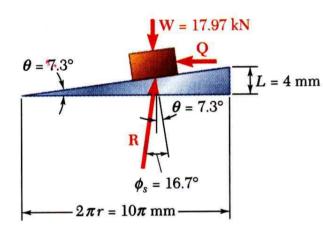
• Using block and plane analogy with impending motion up the plane, calculate clamping force with force triangle.

$$Qr = 40 \text{ N} \cdot \text{m}$$
 $Q = \frac{40 \text{ N} \cdot \text{m}}{5 \text{ mm}} = 8 \text{ kN}$
 $\tan(\theta + \phi_s) = \frac{Q}{W}$ $W = \frac{8 \text{ kN}}{\tan 24^\circ}$



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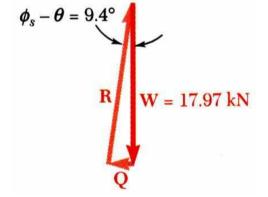
• With impending motion down the plane, calculate the force and torque required to loosen the clamp.

$$\tan(\phi_s - \theta) = \frac{Q}{W} \qquad Q = (17.97 \text{ kN}) \tan 9.4^{\circ}$$
$$Q = 2.975 \text{ kN}$$

Torque =
$$Qr = (2.975 \text{ kN})(5 \text{ mm})$$

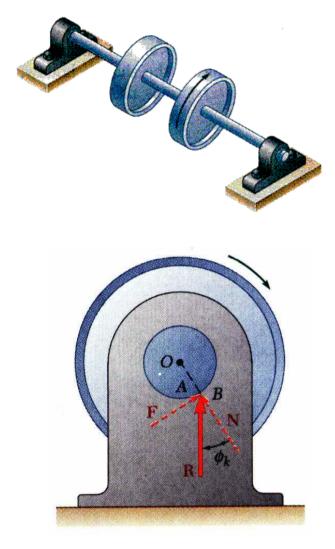
= $(2.975 \times 10^3 \text{ N})(5 \times 10^{-3} \text{ m})$

 $Torque = 14.87 \,\mathrm{N} \cdot \mathrm{m}$





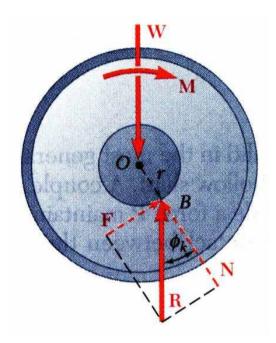
Journal Bearings. Axle Friction



- Journal bearings provide lateral support to rotating shafts. Thrust bearings provide axial support
- Frictional resistance of fully lubricated bearings depends on clearances, speed and lubricant viscosity. Partially lubricated axles and bearings can be assumed to be in direct contact along a straight line.
- Forces acting on bearing are weight *W* of wheels and shaft, couple *M* to maintain motion, and reaction *R* of the bearing.
- Reaction is vertical and equal in magnitude to W.
- Reaction line of action does not pass through shaft center *O*; *R* is located to the right of *O*, resulting in a moment that is balanced by *M*.
- Physically, contact point is displaced as axle
 "climbs" in bearing.
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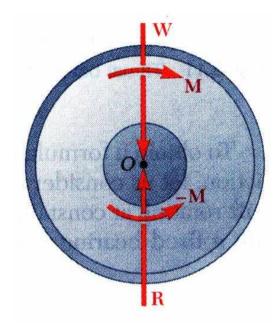
Journal Bearings. Axle Friction



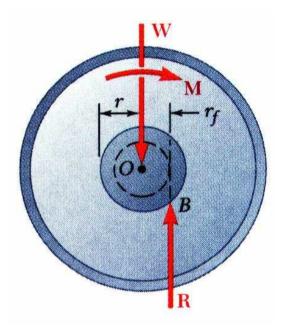
• Angle between *R* and normal to bearing surface is the angle of kinetic friction φ_k .

$$M = Rr\sin\phi_k$$

$$\approx Rr\mu_k$$



• May treat bearing reaction as force-couple system.



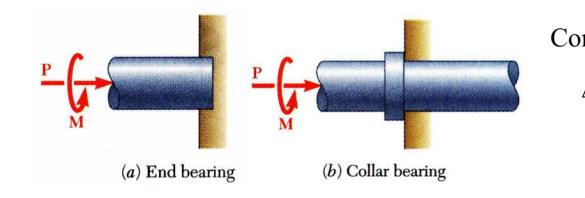
• For graphical solution, *R* must be tangent to *circle of friction*.

 $r_f = r \sin \phi_k$

 $\approx r\mu_k$



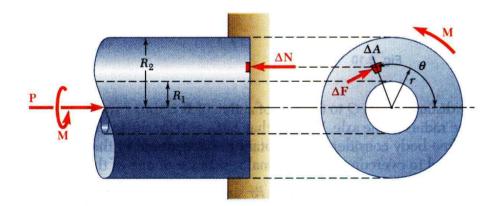
Thrust Bearings. Disk Friction



onsider rotating hollow shaft:

$$\Delta M = r\Delta F = r\mu_k \Delta N = r\mu_k \frac{P}{A} \Delta A$$

$$= \frac{r\mu_k P\Delta A}{\pi (R_2^2 - R_1^2)}$$



$$M = \frac{\mu_k P}{\pi \left(R_2^2 - R_1^2\right)} \int_{0}^{2\pi} \int_{R_1}^{R_2} r^2 dr d\theta$$
$$= \frac{2}{3} \mu_k P \frac{R_2^3 - R_1^3}{R_2^2 - R_1^2}$$

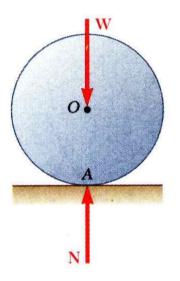
For full circle of radius R,

$$M = \frac{2}{3}\,\mu_k PR$$



Wheel Friction. Rolling Resistance

W

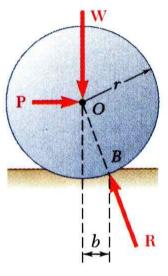


• Point of wheel in contact with ground has no relative motion with respect to ground.

Ideally, no friction.

• Moment *M* due to frictional resistance of axle bearing requires couple produced by equal and opposite *P* and *F*.

Without friction at rim, wheel would slide.



• Deformations of wheel and ground cause resultant of ground reaction to be applied at *B*. *P* is required to balance moment of *W* about *B*.

Pr = Wb b = coef of rolling resistanceSchool of Mechanical Engineering 8 - 23

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 $\sim 0.055 \text{ m} \rightarrow \sim 0.045 \text{ m}$

W = 500 N

A pulley of diameter 0.1m can rotate about a fixed shaft of diameter .05 m. The coefficient of static friction between the pulley and shaft is 0.20.

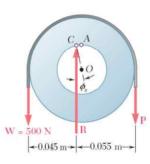
Determine:

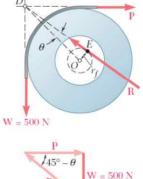
- the smallest vertical force *P* required to start raising a 500 N load,
- the smallest vertical force *P* required to hold the load, and
- the smallest horizontal force P required to start raising the same load.

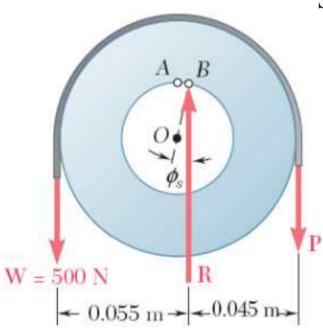
SOLUTION:

- With the load on the left and force *P* on the right, impending motion is clockwise to raise load. Sum moments about displaced contact point *B* to find *P*.
- Impending motion is counterclockwise as load is held stationary with smallest force *P*. Sum moments about *C* to find *P*.
- With the load on the left and force *P* acting horizontally to the right, impending motion is clockwise to raise load. Utilize a force triangle to find *P*.









SOLUTION:

With the load on the left and force P on the right, impending motion is clockwise to raise load. Sum moments about displaced contact point B to find P.

The perpendicular distance from center *O* of pulley to line of action of *R* is

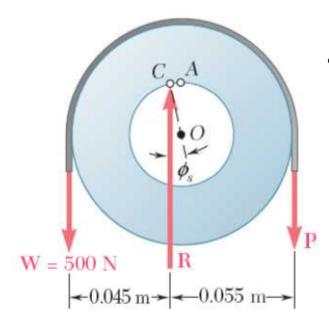
$$r_f = r \sin \varphi_s \approx r \mu_s$$
 $r_f \approx (.025 \text{ m}) 0.20 = 0.005 \text{ m}$

Summing moments about B,

$$\sum M_B = 0$$
: $(0.055 \text{ m})(500 \text{ N}) - (0.045 \text{ m})P = 0$

 $P = 611 \,\mathrm{N}$





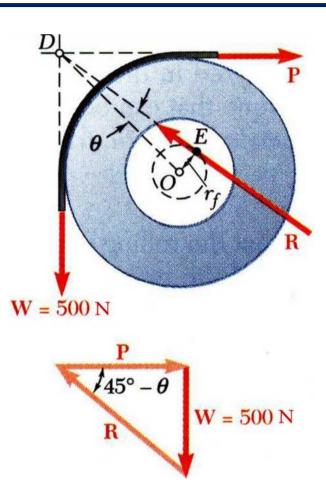
• Impending motion is counter-clockwise as load is held stationary with smallest force *P*. Sum moments about *C* to find *P*.

The perpendicular distance from center O of pulley to line of action of R is again 0.20 cm. Summing moments about C,

$$\sum M_C = 0:$$
 (0.045 m)(500 N) - (0.055 m)P = 0

 $P = 409 \, \text{N}$





• With the load on the left and force *P* acting horizontally to the right, impending motion is clockwise to raise load. Utilize a force triangle to find *P*.

Since *W*, *P*, and *R* are not parallel, they must be concurrent. Line of action of *R* must pass through intersection of *W* and *P* and be tangent to circle of friction which has radius $r_f = .005$ m.

$$\sin \theta = \frac{OE}{OD} = \frac{0.20 \,\mathrm{cm}}{(2 \,\mathrm{cm})\sqrt{2}} = 0.0707$$
$$\theta = 4.1^{\circ}$$

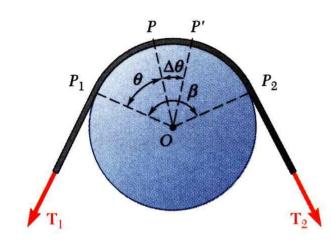
From the force triangle,

 $P = W \cot(45^{\circ} - \theta) = (500 \text{ N}) \cot 40.9^{\circ}$

 $P = 577 \, \text{N}$



Belt Friction



 ΔN

 $\Delta \mathbf{F} = \boldsymbol{\mu}_s \Delta N$

- Relate T_1 and T_2 when belt is about to slide to right.
- Draw free-body diagram for element of belt

 $\sum F_x = 0$: $(T + \Delta T)\cos\frac{\Delta\theta}{2} - T\cos\frac{\Delta\theta}{2} - \mu_s\Delta N = 0$ $\sum F_y = 0$: $\Delta N - (T + \Delta T) \sin \frac{\Delta \theta}{2} - T \sin \frac{\Delta \theta}{2} = 0$

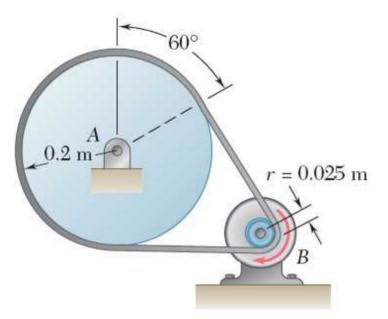
• Combine to eliminate ΔN , divide through by $\Delta \theta$,

$$\frac{\Delta T}{\Delta \theta} \cos \frac{\Delta \theta}{2} - \mu_s \left(T + \frac{\Delta T}{2}\right) \frac{\sin(\Delta \theta/2)}{\Delta \theta/2}$$

- $f_{\mathbf{T}'=\mathbf{T}+\Delta \mathbf{T}}$ In the limit as $\Delta \theta$ goes to zero, $\frac{dT}{d\theta} - \mu_s T = 0$
 - Separate variables and integrate from $\theta = 0$ to $\theta = \beta$

$$\ln \frac{T_2}{T_1} = \mu_s \beta \quad \text{or} \quad \frac{T_2}{T_1} = e^{\mu_s \beta}$$

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A flat belt connects pulley *A* to pulley *B*. The coefficients of friction are $\mu_s = 0.25$ and $\mu_k = 0.20$ between both pulleys and the belt.

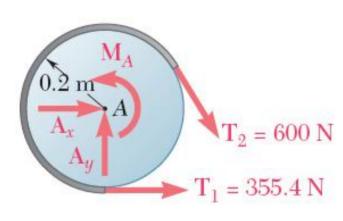
Knowing that the maximum allowable tension in the belt is 600 N, determine the largest torque which can be exerted by the belt on pulley *A*.

SOLUTION:

- Since angle of contact is smaller, slippage will occur on pulley *B* first.
 Determine belt tensions based on pulley *B*.
- Taking pulley A as a free-body, sum moments about pulley center to determine torque.



SOLUTION:



• Since angle of contact is smaller, slippage will occur on pulley B first. Determine belt tensions based on pulley *B*.

$$\frac{T_2}{T_1} = e^{\mu_s \beta} \quad \frac{600 \,\mathrm{N}}{T_1} = e^{0.25(2\pi/3)} = 1.688$$
$$T_1 = \frac{600 \,\mathrm{N}}{1.688} = 355.4 \,\mathrm{N}$$

• Taking pulley *A* as free-body, sum moments about pulley center to determine torque.

$$\sum M_A = 0: M_A - (600 \text{ N}) (0.2 \text{ m}) + (355.4 \text{ N}) (0.2 \text{ m}) = 0$$

 $M_A = 48.9 \text{ N} \cdot m$

