COMP 551 – Applied Machine Learning Lecture 2: Linear regression

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Today's Quiz (informal)

Write down the 3 most useful insights you gathered from the article:

"A Few Useful Things to Know About Machine Learning".

Supervised learning

- Given a set of <u>training examples</u>: $x_i = \langle x_{i1}, x_{i2}, x_{i3}, \dots, x_{in}, y_i \rangle$
 - x_{ii} is the *j*th feature of the *i*th example

 y_i is the desired **<u>output</u>** (or <u>target</u>) for the *i*th example.

 X_i denotes the *j*th feature.

• We want to learn a function $f: X_1 \times X_2 \times ... \times X_n \to Y$

which maps the input variables onto the output domain.

tumor size	texture	perimeter	 outcome	time
18.02	27.6	117.5	Ν	31
17.99	10.38	122.8	Ν	61
20.29	14.34	135.1	R	27

3

Supervised learning

- Given a dataset $X \times Y$, find a function: $f : X \to Y$ such that f(x) is a good predictor for the value of y.
- Formally, *f* is called the *hypothesis*.

- Output Y can have many types:
 - If $Y = \Re$, this problem is called <u>regression</u>.
 - If Y is a finite discrete set, the problem is called <u>classification</u>.
 - If Y has 2 elements, the problem is called **binary classification**.

Prediction problems

• The problem of predicting <u>tumour recurrence</u> is called:

classification

• The problem of predicting the <u>time of recurrence</u> is called:

regression

• Treat them as two separate supervised learning problems.

tumor size	texture	perimeter	 outcome	time
18.02	27.6	117.5	N	31
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Variable types

- **Quantitative**, often real number measurements.
 - Assumes that similar measurements are similar in nature.
- **Qualitative**, from a set (categorical, discrete).
 - E.g. {Spam, Not-spam}
- **Ordinal**, also from a discrete set, without metric relation, but that allows ranking.
 - E.g. {first, second, third}

The i.i.d. assumption

• In supervised learning, the examples x_i in the training set are assumed to be independently and identically distributed.

- Independently: Every x_i is freshly sampled according to some probability distribution *D* over the data domain *X*.

– Identically: The distribution *D* is the same for all examples.

• Why?

Empirical risk minimization

For a given function class *F* and training sample *S*,

• Define a notion of error (*left intentionally vague for now*):

 $L_{S}(f) = #$ mistakes made on the sample S

• Define the Empirical Risk Minimization (ERM):

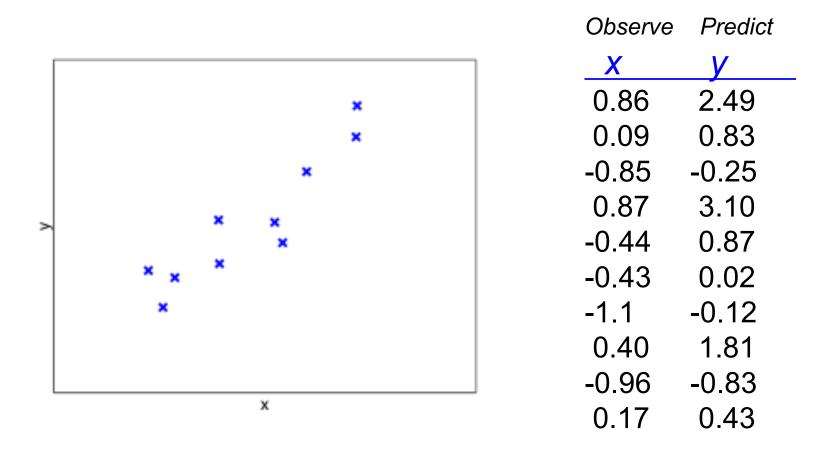
 $ERM_{F}(S) = argmin_{f in F} L_{S}(f)$

where *argmin* returns the function *f* (or set of functions) that achieves the minimum loss on the training sample.

• Easier to minimize the error with i.i.d. assumption.

A regression problem

What <u>hypothesis class</u> should we pick?



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Linear hypothesis

• Suppose Y is a **linear function** of X:

$$f_{W}(X) = w_{0} + w_{1} x_{1} + \dots + w_{m} x_{m}$$
$$= w_{0} + \sum_{j=1:m} w_{j} x_{j}$$

- The *w_i* are called **parameters** or **weights**.
- To simplify notation, we add an attribute $x_0=1$ to the *m* other attributes (also called **bias term** or **intercept**).

How should we pick the *weights*?

Least-squares solution method

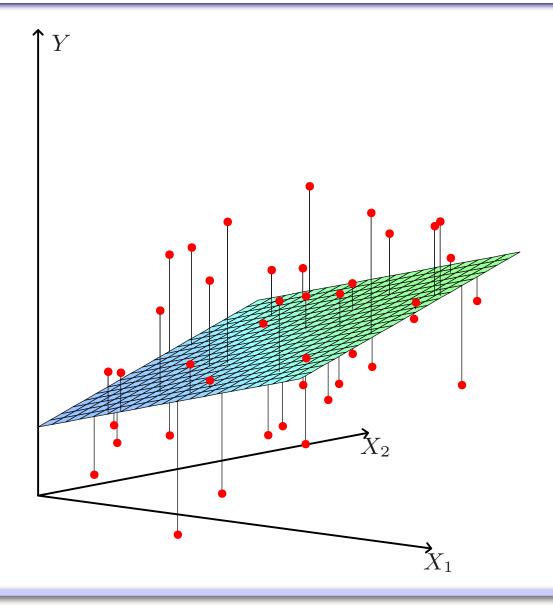
• The linear regression problem: $f_w(X) = w_0 + \sum_{j=1:m} w_j x_j$ where *m* = the dimension of observation space, i.e. number of features.

- Goal: Find the best linear model given the data.
- Many different possible **evaluation** criteria!
- Most common choice is to find the **w** that minimizes:

 $Err(w) = \sum_{i=1:n} (y_i - w^T x_i)^2$

(A note on notation: Here w and x are column vectors of size m+1.)

Least-squares solution for $X \in \Re^2$



Least-squares solution method

• Re-write in matrix notation: $f_w(X) = Xw$

 $Err(\mathbf{w}) = (Y - X\mathbf{w})^T (Y - X\mathbf{w})$

where X is the n x m matrix of input data,
Y is the n x 1 vector of output data,
w is the m x 1 vector of weights.

• To minimize, take the derivative w.r.t. w:

 $\partial Err(\mathbf{w})/\partial \mathbf{w} = -2 X^{T} (Y - X \mathbf{w})$

– You get a system of *m* equations with *m* unknowns.

• Set these equations to 0:

 $X^{T}(Y - Xw) = 0$

Least-squares solution method

- We want to solve for w: $X^{T}(Y Xw) = 0$
- Try a little algebra:

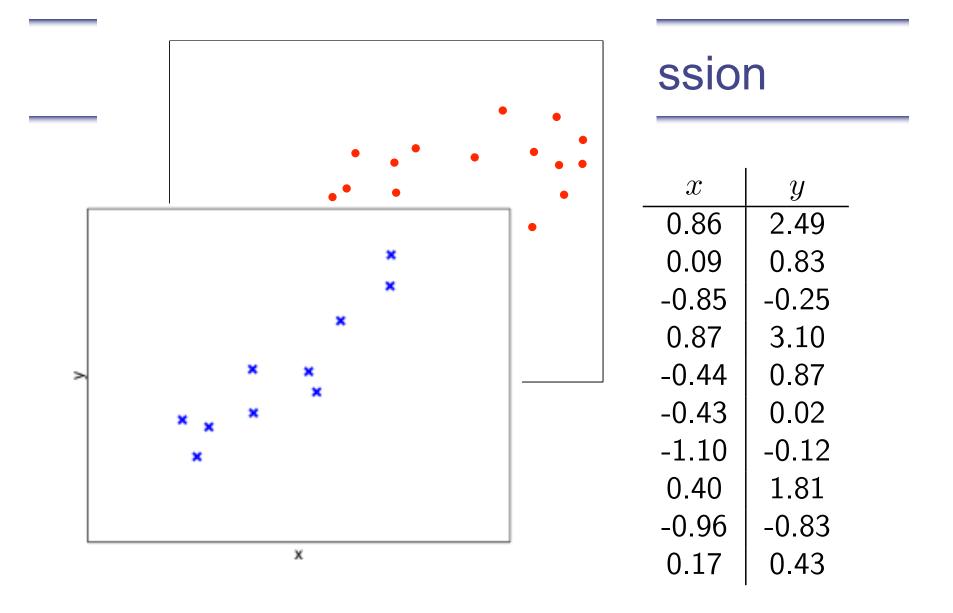
 $X^{T} Y = X^{T} X w$

 $\hat{\boldsymbol{w}} = (\boldsymbol{X}^{T}\boldsymbol{X})^{-1} \boldsymbol{X}^{T} \boldsymbol{Y}$

(ŵ denotes the estimated weights)

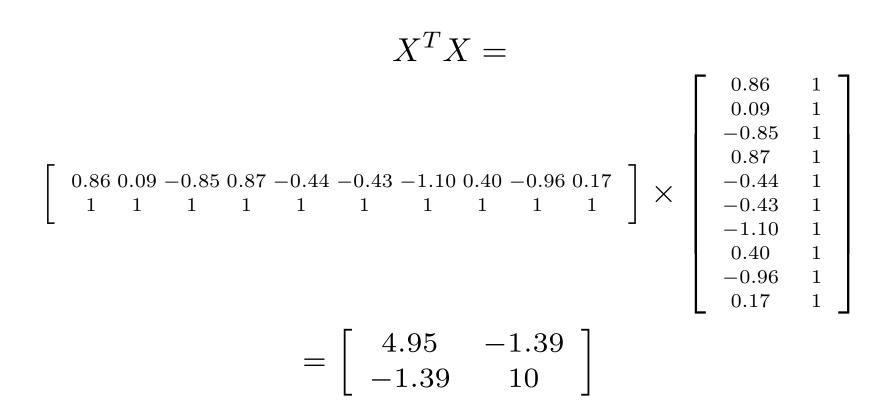
- The fitted data: $\hat{Y} = X\hat{w} = X (X^T X)^{-1} X^T Y$
- To predict new data $X' \rightarrow Y'$: $Y' = X'\hat{w} = X' (X^T X)^{-1} X^T Y$

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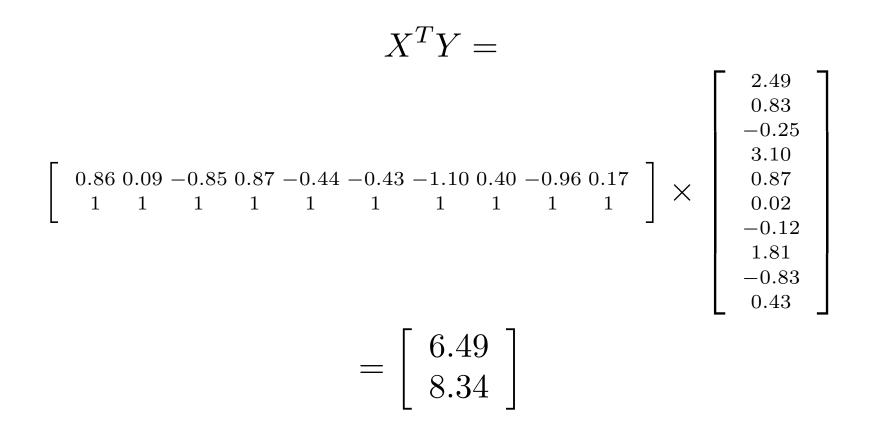


What is a plausible estimate of **w**? **Try it!**

Data matrices



Data matrices

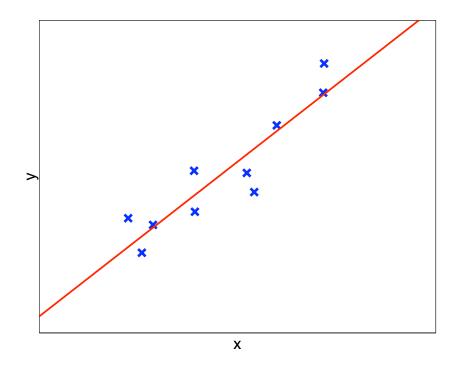


Solving the problem

COMP-652, Lecture 1 - September 6, 2012

$$\mathbf{w} = (X^T X)^{-1} X^T Y = \begin{bmatrix} 4.95 & -1.39 \\ -1.39 & 10 \end{bmatrix}^{-1} \begin{bmatrix} 6.49 \\ 8.34 \end{bmatrix} = \begin{bmatrix} 1.60 \\ 1.05 \end{bmatrix}$$

So the best fit line is y = 1.60x + 1.05.



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Interpreting the solution

- Linear fit for a prostate cancer dataset
 - Features X = {lcavol, lweight, age, lbph, svi, lcp, gleason, pgg45}
 - Output y = level of PSA (an enzyme which is elevated with cancer).
 - High coefficient weight (in absolute value) = important for prediction.

Te	erm	Coefficient	Std. Error
Interc	ept	$w_0 = 2.46$	0.09
lca	vol	0.68	0.13
lwei	ght	0.26	0.10
	age	-0.14	0.10
1	bph	0.21	0.10
	svi	0.31	0.12
	lcp	-0.29	0.15
glea	son	-0.02	0.15
pg	g45	0.27	0.15

Computational cost of linear regression

- What operations are necessary?
 - Overall: 1 matrix inversion + 3 matrix multiplications
 - $X^T X$ (other matrix multiplications require fewer operations.)
 - X^{T} is *mxn* and *X* is *nxm*, so we need *nm*² operations.
 - $(X^T X)^{-1}$
 - $X^T X$ is *mxm*, so we need m^3 operations.

• We can do linear regression in polynomial time, but handling large datasets (many examples, many features) can be problematic.

An alternative for minimizing mean-squared error (MSE)

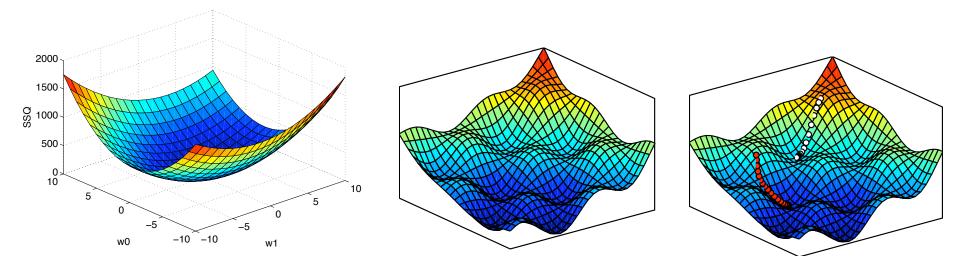
- Recall the least-square solution: $\hat{w} = (X^T X)^{-1} X^T Y$
- What if X is too big to compute this explicitly (e.g. $m \sim 10^6$)?

• Go back to the gradient step: $Err(w) = (Y - Xw)^T(Y - Xw)$

$$\frac{\partial Err(\mathbf{w})}{\partial \mathbf{w}} = -2 X^{\mathsf{T}} (Y - X\mathbf{w})$$
$$\frac{\partial Err(\mathbf{w})}{\partial \mathbf{w}} = 2(X^{\mathsf{T}} X \mathbf{w} - X^{\mathsf{T}} Y)$$

Gradient-descent solution for MSE

• Consider the error function:



- The gradient of the error is a vector indicating the direction to the minimum point.
- Instead of directly finding that minimum (using the closed-form equation), we can take small steps towards the minimum.

Gradient-descent solution for MSE

• We want to produce a sequence of weight solutions, w_0 , w_1 , w_2 ..., such that: $Err(w_0) > Err(w_1) > Err(w_2) > ...$

• The algorithm:

Given an initial weight vector \mathbf{w}_0 , Do for k=1, 2, ... $\mathbf{w}_{k+1} = \mathbf{w}_k - \alpha_k \frac{\partial Err(\mathbf{w}_k)}{\partial \mathbf{w}_k}$ End when $|\mathbf{w}_{k+1} - \mathbf{w}_k| < \varepsilon$

• Parameter $\alpha_k > 0$ is the step-size (or <u>learning rate</u>) for iteration k.

Convergence

• Convergence depends in part on the α_k .

- If steps are too large: the w_k may oscillate forever.
 - This suggests that $\alpha_k \rightarrow 0$ as $k \rightarrow \infty$.

 If steps are too small: the w_k may not move far enough to reach a local minimum.

Robbins-Monroe conditions

• The α_k are a Robbins-Monroe sequence if:

$$\sum_{k=0:\infty} \alpha_k = \infty$$
$$\sum_{k=0:\infty} \alpha_k^2 < \infty$$

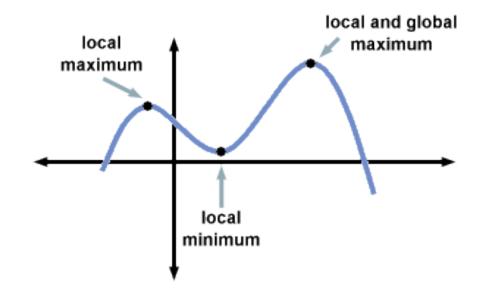
• These conditions are sufficient to ensure convergence of the w_k to a **local minimum** of the error function.

E.g. $\alpha_k = 1 / (k + 1)$ (averaging) E.g. $\alpha_k = 1/2$ for k = 1, ..., T $\alpha_k = 1/2^2$ for k = T+1, ..., (T+1)+2Tetc.

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Local minima

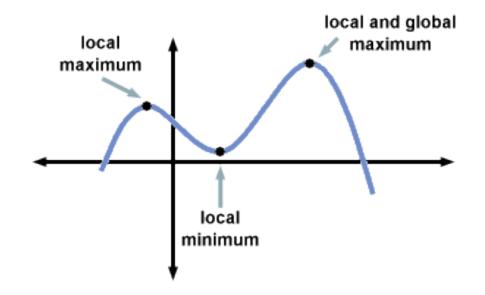
• Convergence is **<u>NOT</u>** to a global minimum, only to local minimum.



 The blue line represents the error function. There is <u>no guarantee</u> regarding the amount of error of the weight vector found by gradient descent, compared to the globally optimal solution.

Local minima

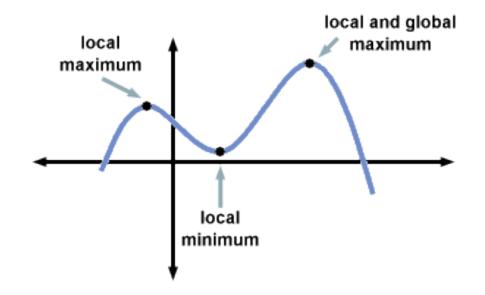
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- For linear function approximations using Least-Mean Squares (LMS) error, this is not an issue: only ONE global minimum!
 - Local minima affects many other function approximators.

Local minima

• Convergence is **NOT** to a global minimum, only to local minimum.



- For linear function approximations using Least-Mean Squares (LMS) error, this is not an issue: only ONE global minimum!
 - Local minima affects many other function approximators.
- Repeated random restarts can help (in all cases of gradient search).

A 3rd optimization method: QR decomposition (optional)

 $X^{T}(Y - Xw) = 0$

 $(QR)^T Y = (QR)^T (QR) w$

 $R^{T}Q^{T}Y = R^{T}Q^{T}QRw$

- Consider the usual criteria:
- Assume X can be decomposed: X = QR where Q is an nxm <u>orthogonal</u> matrix (i.e. Q^TQ=I), and R is an mxm upper triangular matrix.
- Replace X in equation above:
- Distribute the transpose:
- Let $Q^T Q = I$ and multiply by $(R^T)^{-1}$ $Q^T Y = R w$
- Solution: $\hat{w} = R^{-1}Q^TY$ The fitted outputs are: $\hat{Y} = QQ^TY$
- This method is more numerically stable than others, and R⁻¹ is fast to compute because upper triangular.
- Alternately, we can use **singular value decomposition**.

What you should know

- Definition and characteristics of a supervised learning problem.
- Linear regression (hypothesis class, cost function, algorithm).
- Closed-form least-squares solution method (algorithm, computational complexity, stability issues).
- Gradient descent method (algorithm, properties).

To-do

- Reproduce the linear regression example (slides 15-18), solving it using the software of your choice.
- Suggested complementary readings:
 - Ch.2 (Sec. 2.1-2.4, 2.9) of Hastie et al.
 - Ch.3 of Bishop.
 - Ch.9 of Shalev-Schwartz et al.
- Write down midterm date in agenda: Nov. 22, 6-8pm, Leacock 132.
- Tutorial times (appearing soon): www.cs.mcgill.ca/~jpineau/comp551/schedule.html
- Office hours (confirmed): www.cs.mcgill.ca/~jpineau/comp551/syllabus.html