



**Red Hat**

# DASH AND PLOTLY FOR INTERACTIVE PLOTTING

Tutorial with a case-study of the Bifurcation Diagram

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# DASH+PLOTLY

## Presentation

### Dash

<https://plot.ly/dash/>

- “Dash is the fastest way to build interactive analytic apps” (says their website)
- Open source under MIT licensing
- Dash is available for both Python and R (similar to RStudio)
  - good&illustrated documentation: <https://dash.plot.ly/>

### Plotly

- HTML/JS/SVG plotting **from** Python
- many ways to customize graphs
- works with or without Dash
  - good&illustrated documentation: <https://plot.ly/python/>

```
pip install --user dash==1.8.0 # installs plotly as well
```

# DASH LAYOUT

HTML ... in Python

```
import dash_html_components as html
app.layout = html.Div(children=[
    html.H1(
        children='Hello Dash',
        style={'textAlign': 'center',
              'color': colors['text']}),

    html.Div(
        id='my-div',
        children='Dash: A web app framework for Python.',
        style={'textAlign': 'center',
              'color': colors['text']
        }
    ),
])
```

# DASH LAYOUT

HTML ... in Python ... plus complex components

```
import dash_core_components as dcc
dcc.Dropdown(value='MTL', options=[
    {'label': 'New York City', 'value': 'NYC'},
    {'label': 'Montréal', 'value': 'MTL'},
    {'label': 'San Francisco', 'value': 'SF'}])

dcc.Checklist(...), dcc.RadioItems(...)
dcc.Slider(min=0, max=9, value=5)

dcc.Tabs(value='tab-1-example', children=[
    dcc.Tab(label='tab one', value='tab-1-example'),
    dcc.Tab(label='tab two', value='tab-2-example')])

dcc.Graph(id='example-graph-2', figure={'data': [...], 'layout':
```

# DASH CALLBACKS

HTML ... in Python ... plus complex components **and callbacks!**

```
@app.callback(  
    Output('my-div', 'children'),  
    [Input('my-slide-id', 'value')])  
def update_output(slide_value):  
    return f"You've entered '{slide_value}'"
```

- 
- when the value of `my-slide-id` changes,
  - then `update_outout(value)` gets called.
  - and its return value replaces `my-div`'s children.

# DASH CALLBACKS

HTML ... in Python ... plus complex components **and callbacks!**

```
@app.callback(  
    Output('my-div', 'children'),  
    [Input('my-slide-id', 'value')])  
def update_output(slide_value):  
    return f"You've entered '{slide_value}'"
```

---

```
@app.callback(  
    Output('my-graph', 'figure'),  
    [Input('my-slide-id', 'value')])  
def update_graph(slide_value):  
    return go.Figure(data=go.Scatter(x=[...]), y=[...]))
```

# DASH CALLBACKS

you can get Dash callbacks from ...

- button clicks, text (Div/P) clicks
- dropdown list value entered/changed
- graph hover/click on value
- period timers, URL address change, ...

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- period timers, URL address change, ...

from Dash callbacks, you can ...

- update input values
- generate new HTML elements
- update the CSS style of layout HTML elements
- generate any kind of plotly graph

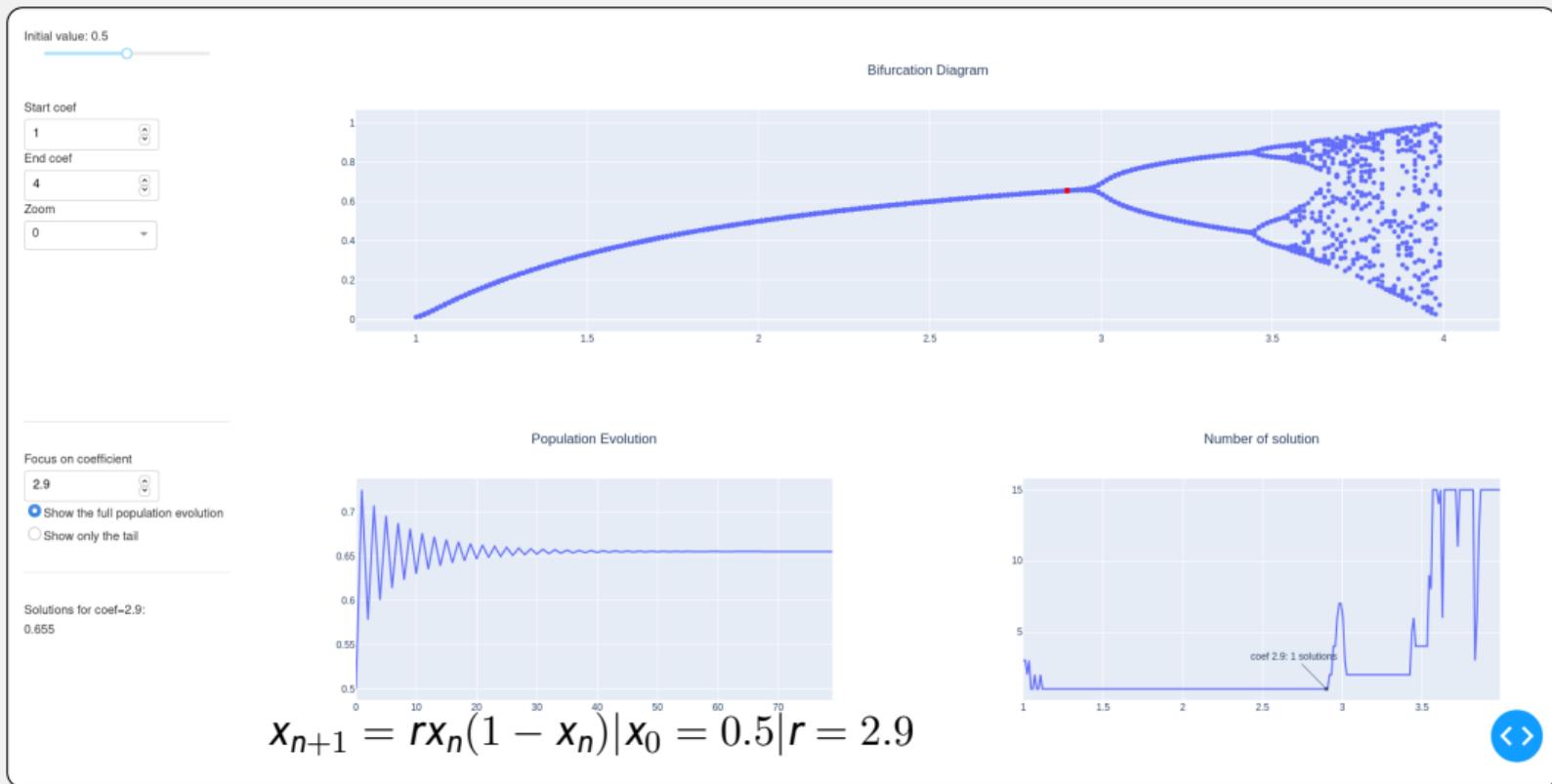
# DASH CALLBACKS

from Dash callbacks, you CANNOT ...

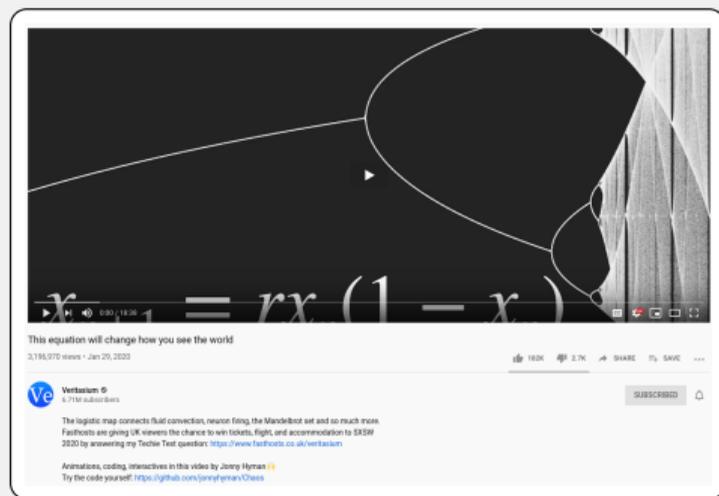
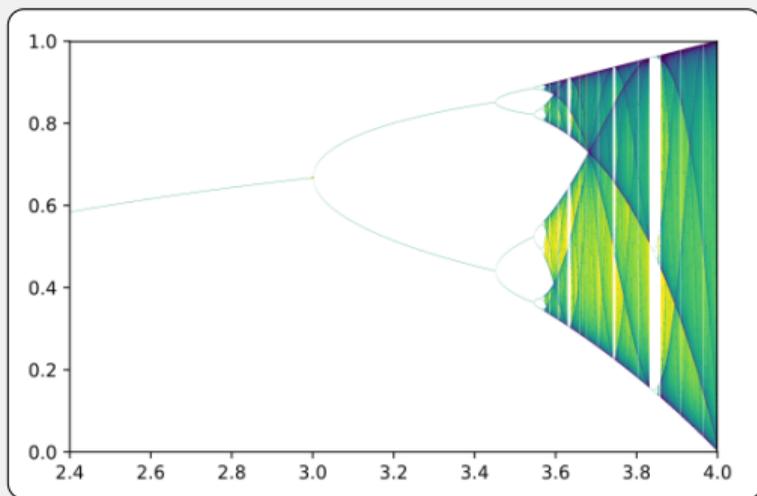
- use global variables to store anything
  - multi-process WSGI backends might bite you :)
- set callbacks to generated HTML elements
  - callbacks+inputs/outputs must be defined at app creation time
  - workaround: use CSS style to hide/show elements instead (`display: none`)
- have more than one callback updating a given property
  - You have already assigned a callback to the output with ID “...” and property “...”. An output can only have a single callback function. Try combining your inputs and callback functions together into one function.
- have dependency cycles (X generates Y, Y generates X)

# CASE STUDY: BIFURCATION DIAGRAM

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# CASE STUDY: BIFURCATION DIAGRAM



- **Case-study repository** (check the branches)
  - <https://github.com/kpouget/bifurq>
- Veritasium video *“This equation will change how you see the world”*
  - <https://www.youtube.com/watch?v=ovJcsL7vyrk>
- Matplotlib Bifurcation diagram my Morn, Creative CC BY SA

[https://en.wikipedia.org/wiki/File:Logistic\\_Map\\_Bifurcation\\_Diagram,\\_Matplotlib.svg](https://en.wikipedia.org/wiki/File:Logistic_Map_Bifurcation_Diagram,_Matplotlib.svg)

# CASE STUDY: BIFURCATION DIAGRAM

**Initial value: 0.6** **Callback 1**

Start coef: 1  
End coef: 4  
**Zoom: 0**

**Callback 3**

**Callback 2**

Population Evolution

Focus on coefficient: 3.56  
 Show the full population evolution  
 Show only the tail

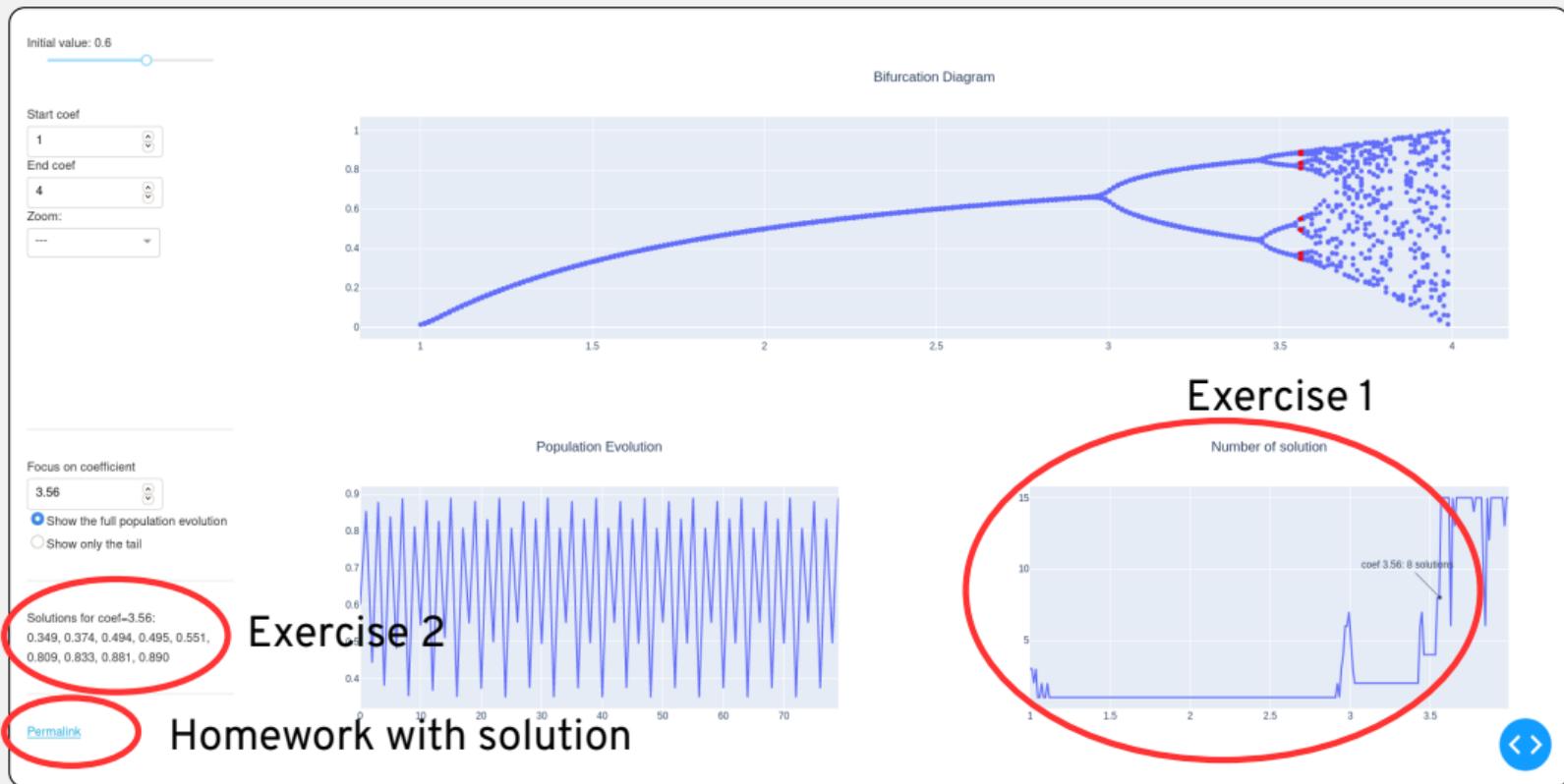
Solutions for coef=3.56:  
0.349, 0.374, 0.494, 0.495, 0.551,  
0.809, 0.833, 0.881, 0.890

Bifurcation Diagram

```
graph TD; input-zoom[input-zoom value] --> input-start-coef[input-start-coef value]; input-zoom --> input-end-coef[input-end-coef value]; input-zoom --> input-focus-coef[input-focus-coef value]; input-zoom --> input-initial-value[input-initial-value value]; input-zoom --> input-show-full[input-show-full value]; input-start-coef --> graph-overview[graph-overview clickData figure]; input-end-coef --> graph-distrib[graph-distrib figure]; input-focus-coef --> graph-focus[graph-focus figure]; input-initial-value --> span-initial-value[span-initial-value children]; input-show-full --> span-initial-value; graph-overview --> focus-solutions[focus-solutions children]; graph-distrib --> focus-solutions; graph-focus --> focus-solutions; span-initial-value --> focus-solutions;
```

git clone <https://github.com/kpouget/bifurq>

# CASE STUDY: BIFURCATION DIAGRAM



# DASH CALLBACK 1

Update initial-value label

Initial value: 0.6 **Callback 1**

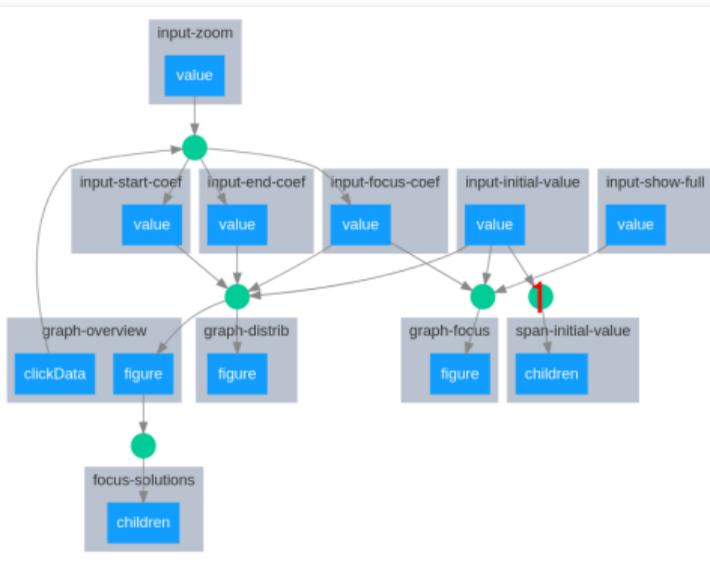
Start coef: 1  
End coef: 4  
Zoom: 0



Population Evolution

Focus on coefficient: 3.56  
 Show the full population evolution  
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Solutions for coef=3.56:  
0.349, 0.374, 0.494, 0.495, 0.551,  
0.809, 0.833, 0.881, 0.890



Bifurcation Diagram



1 1.5 2 2.5

Callback Graph Errors

# DASH CALLBACK 1

Update initial-value label

```
@app.callback(  
    Output('span-initial-value', 'children'),  
    [Input('input-initial-value', 'value')])  
def update_initial_value(value):  
    return str(value) # or f"{value*100:.0f}%"
```

# DASH CALLBACK 2

Draw focus graph

Initial value: 0.6

Start coef

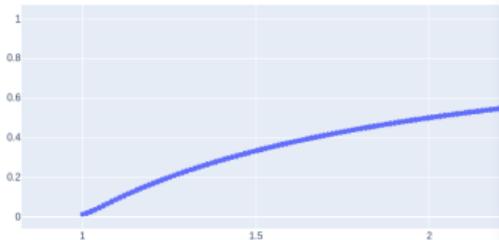
1

End coef

4

Zoom

0



## Callback 2

Population Evolution

Focus on coefficient

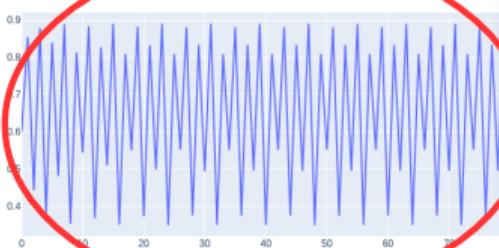
3.56

Show the full population evolution

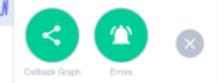
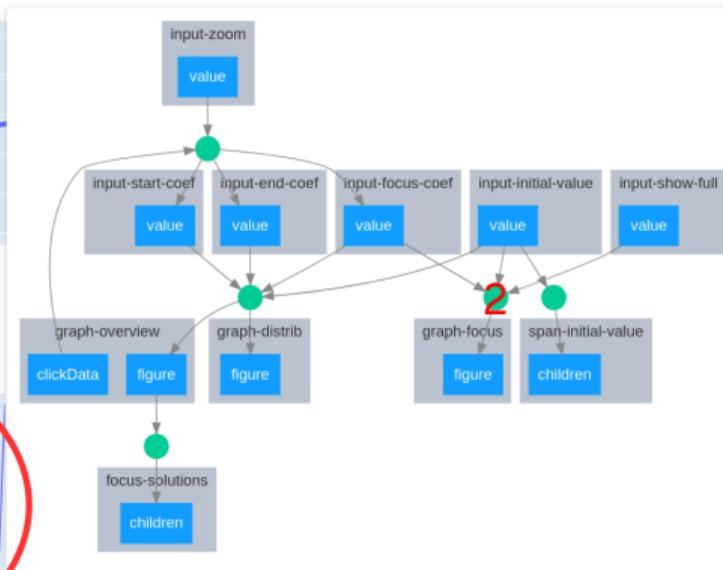
Show only the tail

Solutions for coef=3.56:

0.349, 0.374, 0.494, 0.495, 0.551,  
0.809, 0.833, 0.881, 0.890



Bifurcation Diagram



git clone <https://github.com/kpouget/bifurq>

# DASH CALLBACK 2

Draw focus graph

```
@app.callback(
    Output('graph-focus', 'figure'),
    [Input('input-initial-value', 'value'),
     Input('input-focus-coef', 'value'),
     Input('input-show-full', 'value')]) # on/off actually
def draw_focus(init_value, coef, full):
    x = range(N_COMPUTE) if full else \
        range(N_COMPUTE - KEEP, N_COMPUTE)
    y = compute_evolution(init_value, coef, full=full)

    fig = go.Figure(data=go.Scatter(x=list(x), y=y))
    fig.update_layout(title={'text': "Population Evolution"})

    return fig
```

# DASH CALLBACK 3: ZOOM ON COEF

Initial value: 0.6

Start coef: 1

End coef: 4

Zoom: 0

Callback 3

Population Evolution

Focus on coefficient: 3.56

Show the full population evolution

Show only the tail

Solutions for coef=3.56:  
0.349, 0.374, 0.494, 0.495, 0.551,  
0.809, 0.833, 0.881, 0.890

Bifurcation Diagram

```
graph TD; input_zoom[input-zoom value] --> node1(( )); input_start_coef[input-start-coef value] --> node1; input_end_coef[input-end-coef value] --> node1; input_focus_coef[input-focus-coef value] --> node2(( )); input_initial_value[input-initial-value value] --> node2; input_show_full[input-show-full value] --> node2; node1 --> graph_overview[graph-overview clickData]; node1 --> graph_distrib[graph-distrib figure]; node2 --> graph_focus[graph-focus figure]; node2 --> span_initial_value[span-initial-value children]; graph_overview --> focus_solutions[focus-solutions children];
```

# DASH CALLBACK 3: ZOOM ON COEF

```
@app.callback(  
    [Output('input-start-coef', 'value'),  
     Output('input-end-coef', 'value'),  
     Output('input-focus-coef', 'value')],  
    [Input('input-zoom', 'value'),  
     Input('graph-overview', 'clickData')])  
def update_coef(zoom, clickData):  
    trigger = dash.callback_context.triggered[0]["prop_id"]  
    if trigger.startswith('graph-overview'):  
        # triggered by click on graph-overview point  
        return [no_update]*2, clickData['points'][0]['x']  
  
    # triggered by zoom-input value changed  
    try: return ZOOMS[zoom]  
    except KeyError: return START_COEF, END_COEF, FOCUS_COEF
```

# CASE STUDY: EXERCISES

Initial value: 0.6

Start coef

1

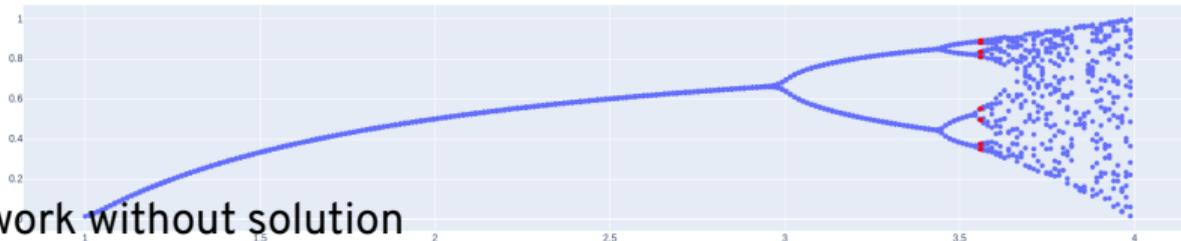
End coef

4

Zoom:

---

Bifurcation Diagram



More controls

Homework without solution

Exercise 1

Focus on coefficient

3.56

Show the full population evolution

Show only the tail

Solutions for coef=3.56:

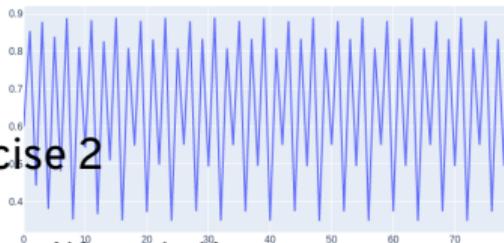
0.349, 0.374, 0.494, 0.495, 0.551,  
0.809, 0.833, 0.881, 0.890

Exercise 2

[Permalink](#)

Homework with solution

Population Evolution



Number of solution



# CASE STUDY: EXERCISES

## Exercise 1: 'Number of solution' diagram

- add `dcc.Graph` in the layout
- add `Output(id, 'figure')` in the `draw_overview` callback
- build `go.Figure(data=[go.Scatter(x=count_x, y=count_y)])`
- add `go.layout.Annotation` text annotation

## Exercise 2: 'solutions for coef' text

- add `html.Div` in the layout
- new callback with `Input('graph-overview', 'figure')`
- add state info `State('input-focus-coef', 'value')`
- build text with `solutions = graph['data'][1]['y']`
  - (the solutions are already computed and plotted in red in the 2nd graph figure)

# CASE STUDY: PERMALINK HOMEWORK

**Key feature**, but not so easy to build ...

```
@app.callback(Output('permalink', 'href'),
               [Input(f"input-{input}", 'value') for input in INPUT_NAMES])
def get_permalink(*args):
    return "?"+"&".join(f"{k}={v}" \
                       for k, v in zip(INPUT_NAMES, map(str, args)))
```

```
@app.callback(Output('page-content', 'children'),
               [Input('url', 'search')])
def display_page(search):
    search_dict = urllib.parse.parse_qs(search[1:])
    return build_layout(search_dict)
```