

#### **Data sheet**

## NovoCon® S

## Description



NovoCon® S is a high accuracy multi-functional field bus actuator, specifically designed for use in combination with the Pressure Independent Balancing Control Valve type AB-QM in sizes from DN 10-32.

The flow is modulated by the AB-QM pressure independent control valve to avoid overflow and reduced boiler and/or chiller efficiency.

The actuator with AB-QM is used to control water supply to fan coil units, chilled beams, induction units, small re-heaters, re-coolers, AHU's and other terminal units for zone control, in which heating/chilled water is the controlled medium. Due to its accuracy, remote functionality and flow indication features, this product facilitates an accelerated commissioning process, allows easy maintenance, improves indoor comfort, increases energy savings and allows for fair cost allocation of heat/cool energy.

The high position accuracy of the actuator, together with the pressure independent and linear characteristic of the AB-QM valve, allow NovoCon® S to be used as a flow indicator.

Setup of the actuator and valve parameters are made via fieldbus. Control is achieved via field bus or via analog inputs to NovoCon® S.

## Typical applications are:

- Radiant ceiling panels, supplied by 4 pipes (Heating supply and return and cooling supply and return).
- Fan coil units, with single coils supplied by 4 pipes (Heating supply and return and cooling supply and return).

## **General features:**

- Remote commissioning/Pre-set/Flush features
- · Flow indication
- High position accuracy
- Energy management applications
- 4/2-pipe changeover applications
- I/O applications
- LED bar displaying status
- No tools required for mounting
- · Maintenance-free lifetime
- Self-positioning process
- Low-noise operation
- Plug-in halogen free cables
- Auto MAC addressing for BACnet
- Auto baud rate detection

- Intrinsic alarm reporting for BACnet
- Valve blockage alarm
- Broken wire detection on analog control and ground signal
- Choice of BACnet MS/TP or Modbus RTU in the same product
- Mis-wiring protection on any wire up to 30 V

Combined with the Actuator NovoCon® ChangeOver6, NovoCon® S offers a unique solution in controlling both the AB-QM valve and a 6-port motorised ball valve that performs a diverting function between two water circuits in 4-pipe changeover systems.

This diverting function, primarily used for radiant panels, also allows the cooling and heating capacity of a fan coil unit to be increased for the same compact size compared to a double coil model where the heating and cooling water circuits each have their own coil.

The 6-port diverting valve and actuator work in combination with an AB-QM PIBCV valve and NovoCon® S bus actuator. The AB-QM balances the flow and the NovoCon® S bus actuator controls the flow. NovoCon® S also controls the 6-port diverting valve actuator which switches between heating and cooling. This unique functionality is characterized by the following:

- There is only one single field bus and power supply connection cable to the NovoCon® S actuator. This powers both the NovoCon® S and controls the 6-port actuator. Furthermore, there is feedback from the 6-port actuator to
- The NovoCon® S actuator automatically faultdetects, by means of comparing 0-10V control & feedback signals, if the 6-port actuator is in manual operation mode, removed from the valve or if the 6-port valve is blocked.
- The NovoCon® S actuator has two Design Flow Rate pre-settings: one for heating and another for cooling.
- The NovoCon® S actuator indicates power emission and logs energy usage for heating and cooling energy based on flow, supply and return pipe temperature measurement.
- While in maintenance mode, the 6-port actuator is able to fully close the valve and prevent any leakage, thereby saving on stop valves.
- Logic contained within the NovoCon® S actuator, ensures that only one actuator in each pair (NovoCon® S and 6-port valve actuator) drives. This ensures that 2 actuators in the pair never drive at the same time. This reduces voltage booster demands in daisy chains.
- The NovoCon® S actuator detects if the 6-port actuator cable is disconnected. If this is the case an alarm is initiated.



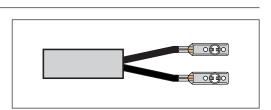
## **Description** (continued)

## Features CO6:

- NovoCon® S + ChangeOver<sup>6</sup> actuator represents only ONE device on the fieldbus network needing no physical I/O
- · No cross-flow between heating and cooling
- Simple connection and control
- Feedback for position status and alarms
- Quiet and reliable operation
- · Maintenance free
- Teflon seal and polished chrome valve ball to prevent valve sticking
- Blocked valve alarm
- Manual override

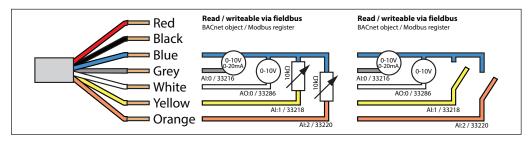
## Features Energy:

- · Supply and return temperature measurement
- Power/emission indication reading
- Energy Management functionality for both heating and cooling e.g. minimum delta t management
- Energy logging of both heating and cooling



#### Features I/O:

- Connect to other devices and present them on the field bus, e.g. room thermostat, window contact, CO2 sensor, humidity sensors, fan control, 0-10V actuator etc.
- Select temperature units, Ohms or use as
- potential free contacts. Closed circuit <900 $\Omega$ , open circuit 100k $\Omega$ .
- Available connections: 1 x analog output (V), 1 x analog input (V/mA) and 2 x resistance based inputs (°C/°F/Ohms)



## **Ordering**



| Туре       | Code No. |
|------------|----------|
| NovoCon® S | 003Z8504 |

## **Accessories**



| Туре                                | Length | Connections                      | Cable material | Code No. |
|-------------------------------------|--------|----------------------------------|----------------|----------|
| Cable NovoCon® Digital              | 1.5 m  | bus / power                      | Halogen free   | 003Z8600 |
| Cable NovoCon® Digital              | 5 m    | bus / power                      | Halogen free   | 003Z8601 |
| Cable NovoCon® Digital              | 10 m   | bus / power                      | Halogen free   | 003Z8602 |
| Cable NovoCon® Digital, daisy chain | 0.5 m  | actuator / actuator              | Halogen free   | 003Z8609 |
| Cable NovoCon® Digital, daisy chain | 1.5 m  | actuator / actuator              | Halogen free   | 003Z8603 |
| Cable NovoCon® Digital, daisy chain | 5 m    | actuator / actuator              | Halogen free   | 003Z8604 |
| Cable NovoCon® Digital, daisy chain | 10 m   | actuator / actuator              | Halogen free   | 003Z8605 |
| Cable NovoCon® Analog               | 1.5 m  | 0-10 V / power / voltage booster | Halogen free   | 003Z8606 |
| Cable NovoCon® Analog               | 5 m    | 0-10 V / power / voltage booster | Halogen free   | 003Z8607 |
| Cable NovoCon® Analog               | 10 m   | 0-10 V / power / voltage booster | Halogen free   | 003Z8608 |
| Cable NovoCon® I/O                  | 1.5 m  | actuator / free wires            | Halogen free   | 003Z8612 |

Note! Cables are not included with actuator and must be ordered separately.



| Cable NovoCon® Energy | 1.5 m | Plug-in cable with PT1000 surface temperature sensors             | PVC | 003Z8610 |
|-----------------------|-------|---|-----|----------|
| Cable NovoCon® Energy | 1.5 m | Plug-in cable with PT1000 Immersed /universal temperature sensors | PVC | 003Z8611 |

**Note!** If separate PT1000 temperature sensors are needed, Danfoss has an array of PT1000 sensors that can be used with NovoCon® S. See Danfoss PT1000 sensors ESMT, ESM-10, ESM-11, ESMB-12, ESMC and ESMU.

## ChangeOver6 actuators



| Actuator NovoCon ChangeOver <sup>6</sup>             | 1 m                       | Plug-in  | Halogen free                 | 003Z8520 |
|--|---------------------------|--|------------------------------|----------|
| Actuator NovoCon ChangeOver <sup>6</sup><br>Energy   | 1 m<br>Temp. sensors 1.5m | Plug-in incl. PT1000 surface temperature sensors | Halogen free,<br>sensors PVC | 003Z8521 |
| Actuator NovoCon ChangeOver <sup>6</sup><br>Flexible | 2 m                       | Actuator / open wires                            | PVC                          | 003Z8522 |



## **Ordering** (continued)

| Туре                               | DN | Fire load class <sup>1)</sup> | Code No. |
|------------------------------------|----|-------------------------------|----------|
| ChangeOver <sup>6</sup> insulation | 15 | B2                            | 003Z3159 |

<sup>&</sup>lt;sup>1)</sup> According to D/N 4102



| Туре                    | DN | <b>k</b> <sub>vs</sub> (m <sup>3</sup> /h) | Connection | Code No. |
|-------------------------|----|--|------------|----------|
| ChangeOver <sup>6</sup> | 15 | 2,4  | Rp ½       | 003Z3150 |
| valve                   | 20 | 3,8  | Rp ¾       | 003Z3151 |

## Service kit - combination with old AB-QM

| Туре  | Code No. |
|---|----------|
| NovoCon® adapter for AB-QM, DN 10-32 (5 pcs.) | 003Z0239 |

## **Approvals**



EMC Directive 2014/30/EU, EN 60730-2-14:1997, EN 60730-2-14/A1:2001, EN60730-1:2011 RoHS Directive 2011/65/EU

## **Technical data**

| Power supply range                        | 24 V AC/DC, 50 / 60 Hz *   |
|---|--|
| Power consumption                         | 3.3 VA@24VAC / 1.4 W@24V DC / Standby: 0.9 W   |
| Protection class                          | III safety extra-low voltage   |
| Control signal NovoCon® S                 | BACnet MS/TP, Modbus RTU<br>0-10 VDC, 0-5 VDC, 2-10 VDC, 5-10 VDC, 2-6 VDC, 6-10 VDC, 0-20 mA, 4-20 mA |
| Actuator speed selections (open to close) | 3 sec/mm, 6 sec/mm, 12 sec/mm, 24 sec/mm, Constant Time  |
| Stroke                                    | 7 mm   |
| Force                                     | 90 N   |
| Position accuracy                         | ± 0.05 mm  |
| Ambient temp. range                       | −10° C to 50° C  |
| Ambient humidity                          | 98% r.h., non-condensing (according to EN 60730-1)   |
| Max. medium temp.                         | 120° C   |
| Storage temp. range                       | −40 to 70 °C   |
| Grade of enclosure                        | IP 54 (IP 40 upside down)  |
| Weight                                    | 0.4 kg   |

<sup>\*</sup> NovoCon $^{\circ}$  S is designed to operate at power deviations up to  $\pm 25\%$ .

## **BACnet data**

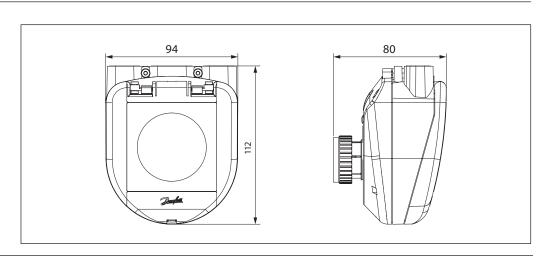
| Туре                        | Length   |  |  |
|-----------------------------|--|--|--|
| BACnet device profile       | BACnet Application Specific Controller (B-ASC)   |  |  |
| BACnet protocol             | BACnet Master Slave / Token Passing (MS/TP)  |  |  |
| BACnet baud rates supported | Auto baud rate detection* / 9600 bps / 19200 bps / 38400 bps / 56700 bps / 76800 bps / 115200bps |  |  |

## **Modbus RTU data**

| Supported baud rates   | $Auto\ baud\ rate\ detection ** / 9600\ bps\ /\ 19200\ bps\ /\ 38400\ bps\ /\ 56700\ bps\ /\ 76800\ bps\ /\ 115200bps\ /\ 10000000000000000000000000000000000$ |  |
|------------------------|--|--|
| Supported transmission | Parity: None (1-8-N-2) / Odd (1-8-O-1) / Even (1-8-E-1) / None (1-8-N-1) / Auto parity*  |  |
| modes                  | Data format: Parity (Start bit - Data bits - Parity - Stop bits)   |  |

<sup>\*</sup> Default

## **Dimensions**



VD.HU.X2.02

## NovoCon® S



## **Presetting**

Pre-setting of flow (maximum allowable flow though the valve) is achieved electronically with the NovoCon® S actuator. The pre-set scale on the AB-QM valve is not used under normal operation.

## **Normal operation**

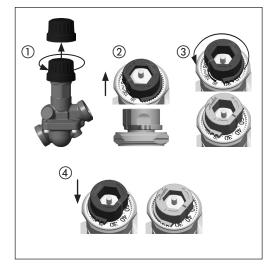
Leave valve at default factory pre-set (100 %).

## **High flow operation**

In order to achieve a more efficient flush and enable pre-setting of the valve more than 100%, it is recommended to manually pre-set the AB-QM valve to maximum flow. This is done by turning the pre-set scale counter-clockwise until it stops.

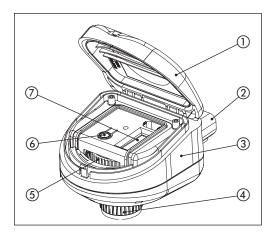
See drawing.

Details about AB-QM pre-setting can be found in the AB-QM data sheet.



## Design

- (1) Removable lid
- 2 Bus and power connections
- 3 LED window
- (4) Locking ring
- (5) Manual override
- 6 Reset button
- 7 DIP switches

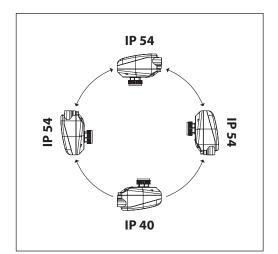


## **Mounting Orientation**

NovoCon® S can be mounted in any position. However, mounting orientation affects the IP classification. See illustration.

#### Note!

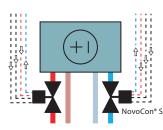
*IP classification is only valid when cable or plugs are present in all connections.* 





## Application principles NovoCon® S I/O

When combining the NovoCon® S and the Cable NovoCon® I/O, many options are possible



## **Operation example (DDC command)**

| Object /Register | Write value | Description  |
|------------------|-------------|--|
| AV:1 / 33280     | 85          | DDC writes % opening value of the AB-QM valve  |
| AO:0 / 33286     | 5.5         | DDC writes level of voltage on NovoCon® S analog output,<br>which is sent to the connected remote device |

## Con<sup>®</sup>S Read on the BMS example

Resistance inputs can also be used as galvanic insulated digital inputs for detection of window contact, condensation switch etc. Connected: <900 Ohm. Disconnected 100 KOhm.

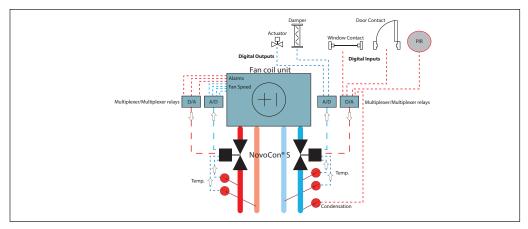
| Object /Register | Read value | Description   |
|------------------|------------|---|
| AO:0 / 33286     | 5.5        | Voltage output from NovoCon® S to remote device   |
| AI:0 / 33216     | 6.5        | Voltage level on the analog control input measured by<br>the actuator<br>(may also be mA) |
| AI:1 / 33218     | 1160       | Resistance value (Ohm) received from remote device 1                                      |
| AI:2 / 33220     | 1263       | Resistance value (Ohm) received from remote device 2                                      |

## Application principles NovoCon® I/O and Multiplexers/Relays

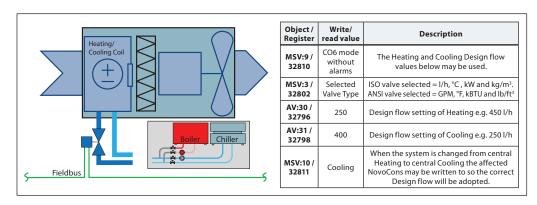
Multiplexers and relays (analog-digital-analog convertors) in combination with NovoCon® S, may be used to gather information on, or control on/off devices.

Using NovoCon's 0-10V output signal (AO:0 / 33286), multiplexer relays convert this signal in order to switch devices on or off e.g. 7V signal from NovoCon® S is converted inside the multiplexer so device1=on, device 2=on, device3=off. E.g. 4V signal from NovoCon® S is converted inside the multiplexer so the device1=on, device 2=off, device3=off.

Using NovoCon's 0-10V input signal (Al:0 / 33216) received from the multiplexers, the DDC can decipher the meaning of the voltage signal e.g. 7V signal to NovoCon® S from the multiplexer is deciphered by the DDC as meaning device1=on, device 2=on, device3=off. 4V signal to NovoCon® S from the multiplexer is deciphered by the DDC as meaning device1=on, device 2=off, device3=off.



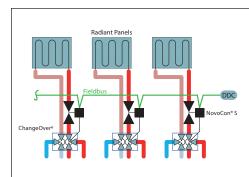
Application principles: Central Plant Changeover - 2 pipe system



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## Application principles ChangeOver<sup>6</sup> - 4 pipe system

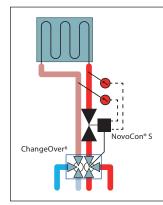


Separate maximum flow pre-setting for heating and for cooling

#### Setup

| Object /<br>Register                 | Write/<br>read value | Description  |  |  |  |  |
|--------------------------------------|----------------------|--|--|--|--|--|
| MSV:9/<br>32810                      | CO6 mode             | While in CO6 mode, the V/mA input and output signals are used purely for controlling the 6-port valve actuator |  |  |  |  |
| MSV:3 / Selected<br>32802 Valve Type |                      | ISO valve selected = I/h, °C, kW and kg/m³.  ANSI valve selected = g/min, °F, kBTU and lb/ft³                  |  |  |  |  |
| AV:30 /<br>32796                     | 400                  | Design flow setting of Heating e.g. 400 l/h  |  |  |  |  |
| AV:31 /<br>32798                     | 250                  | Design flow setting of Cooling e.g. 250 l/h  |  |  |  |  |

## Application principles ChangeOver<sup>6</sup> Energy



#### Setup

| Object /Register | Write/read value       | Description  |
|------------------|------------------------|--|
| MSV:9 / 32810    | CO6 mode               | While in CO6 mode, the V/mA input and output signals are used purely for controlling the 6-port valve actuator |
| AV:32 / 33288    | Power emission         | Calculates energy based on values from flow feedback (AV:2) and temperature (Al:1 and Al:2)                    |
| AV:33 / 33290    | Heating Energy Counter | Accumulate Energy counter for heating  |
| AV:34/33292      | Cooling Energy Counter | Accumulate Energy counter for cooling  |
| MSV:3 / 32802    | Selected Valve Type    | ISO valve selected = I/h, °C , kW and kg/m³.  ANSI valve selected = g/min, °F, kBTU and lb/ft³                 |
| AI:1 / 33218     | Temperature            | Select between temperature units or ohms   |
| AI:2 / 33220     | Temperature            | Select between temperature units or ohms   |
| AV:30 / 32796    | 400                    | Design flow setting of Heating e.g. 400 l/h  |
| AV:31 / 32798    | 250                    | Design flow setting of Cooling e.g. 250 l/h  |

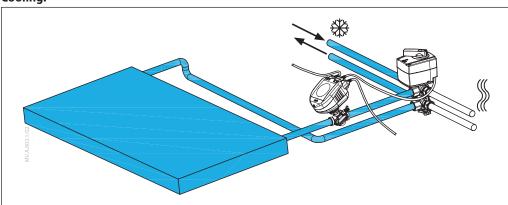
# Application principles ChangeOver<sup>6</sup>

## Anti-sticking requirements:

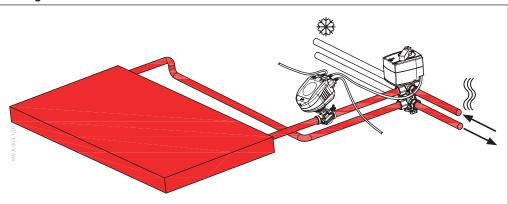
To reduce the risk of the ball valve sticking due to water quality, the valve must be partially rotated at least every 7 days. This is a factory default setting and is handled by the object MSV:11 / register 32812.

The ChangeOver<sup>6</sup> is a 6-port valve with a rotary actuator that switches the flow between heating and cooling. An AB-QM pressure independent balancing and control valve with an actuator is used to balance the system and modulate the flow. When using the NovoCon<sup>®</sup> S for flow control, both NovoCon<sup>®</sup> S and the Actuator NovoCon<sup>®</sup> ChangeOver<sup>6</sup> are represented on the fieldbus network and need no physical I/O for control.

## Cooling:

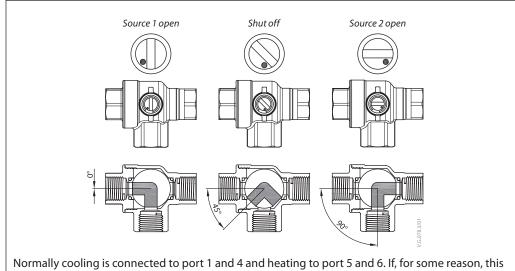


## **Heating:**





#### No mixing and shut off



is not the case, then Inverted CO6 mode (MSV:9/32810) must be used instead.

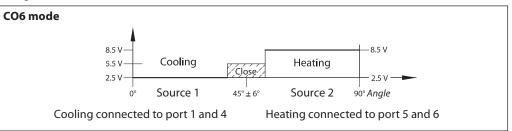
CO6, contrary to other ball valves, includes a shut off function. This function should only be used during maintenance and not during operation. This replaces the need for four ball valves. The Shut off command can only be performed when the Flow Rate Setpoint (AV:1/33280) is 0.

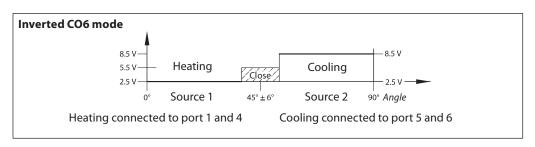
## MSV:9/32810 Application mode

## State 3: CO6 Mode

Normally cooling is connected to ports 1 and 4 and heating to ports 5 and 6. If that is not possible, then this may be switched and state 4: Inverted CO6 Mode must be selected.

NovoCon® S and the ChangeOver6 actuator communicate with voltage control and feedback signal. Whole functionality is available by using simple bus commands. For easier technical understanding, please see below detailed explanation of the communication between NovoCon® S and the ChangeOver<sup>6</sup> actuator.





## Signal from NovoCon® S to the Actuator NovoCon® ChangeOver6

|                   | Stop the motor | Cooling | Shut-off | Heating |
|-------------------|----------------|---------|----------|---------|
| CO6 mode          | 1.0 V          | 2.5 V   | 5.5 V    | 8.5 V   |
| Inverted CO6 mode | 1.0 V          | 8.5 V   | 5.5 V    | 2.5 V   |

#### Feedback signal from the Actuator NovoCon® ChangeOver6

| Unable to move | Cooling | Moving direction:<br>Cooling to Heating | Shut-off | Moving direction:<br>Heating to Cooling | Heating |
|----------------|---------|---|----------|---|---------|
| 1.0 V          | 2.5 V   | 4.0                                     | 5.5 V    | 7.0 V                                   | 8.5 V   |

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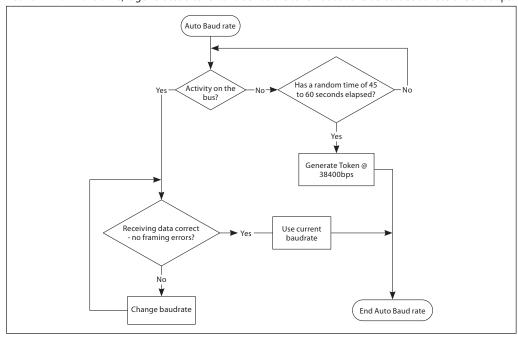


#### **Auto baud rate**

NovoCon® S should be connected after, or at the same time as, other BACnet devices. NovoCon® S will then adapt to it's network's baud rate automatically.

#### Baud rate MSV:6 / 32804 must be set to 1 (default).

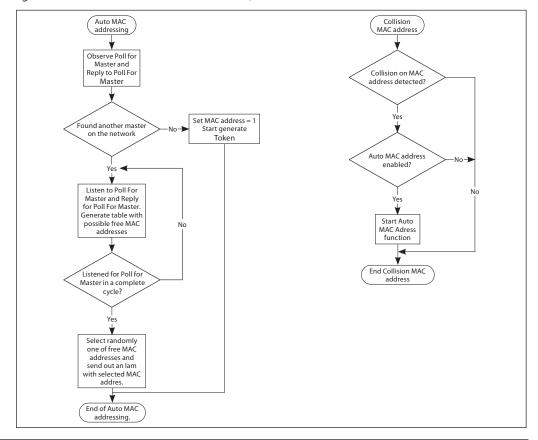
If the NovoCon® S observes activity on the bus within 45 seconds after powering up, then it adopts the baud rate presently used on the network by other BACnet devices. If the actuator does not see activity on the network within this time, it generates a token and sends the token out at the default baud rate of 38400bps.



# Auto MAC Addressing - BACnet only

## MAC address assignment method MSV:5 must be set to 1 (default).

The NovoCon® S actuator observes for used which MAC addresses on the sub-network that are taken and then automatically assign an available MAC address to the actuator on first power up, if the address has not already been manually selected by DIP Switches. If a MAC address collision arises later and Auto MAC addressing is enabled, this function will start the search for an available MAC address again. When an available MAC address is found, an "I-Am" notification will be sent out via BACnet.





#### Wiring

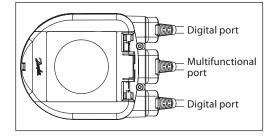


The wiring of BACnet MS/TP or Modbus RTU (*RS485*) must be carried out in accordance with applicable standard ANSI/TIA/EIA-485-A-1998.

Galvanic separation shall be provided for segments crossing buildings.

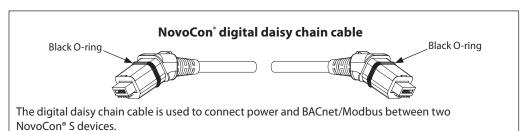
Common ground shall be used for all devices on the same network inclusive router, gateways etc.

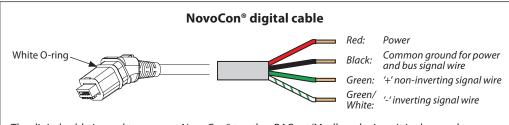
All BACnet bus connections in the cables are made with twisted wires.



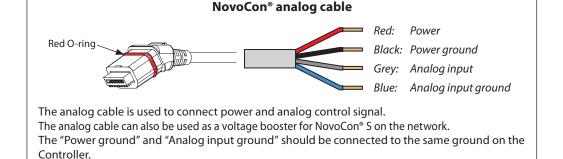
The cable type used for NovoCon® analog, digital and I/O cables is AWG22/0.32mm². If other cables are used to extend the length, always use twisted pair wire for bus signal and include ground for the bus signal. The recommended cable type for this is AWG22/0.32 mm². If used for longer distances please use a AWG20/0.5mm² or AWG18/0.75mm² cable. The cables characteristic impedance shall be between 100-130 $\Omega$  The capacitance between conductors shall be less than 100 pf per meter. Note: the length of the cables influence on the communication speed. Longer cable lengths should mean lower baud rate. Maximum cable length allowed is 1200m.

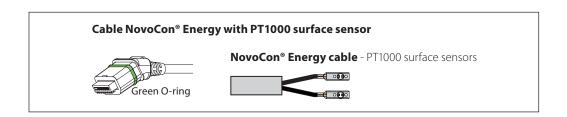
Use a minimum 20 cm distance between 110V/230V/400V power line cables and bus cables. NovoCon® S has mis-wiring protection on up to 30 V AC/DC on all wires, but be aware that if 30V AC are connected to the Analog input the external power supply will see this as a short circuit and blow the fuse in the external power supply.





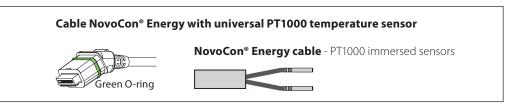
The digital cable is used to connect NovoCon® to other BACnet/Modbus devices. It is also used to connect NovoCon to a longer length of power/communication cable other than standard sales codes.

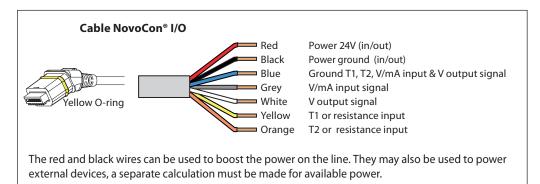






## Wiring (continued)





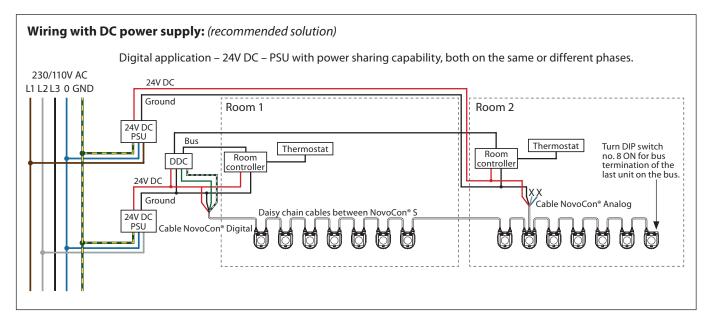


To avoid electrical short-circuiting, ensure that loose cable-ends have been connected or isolated before inserting the plug-in connector to the NovoCon® S actuator.

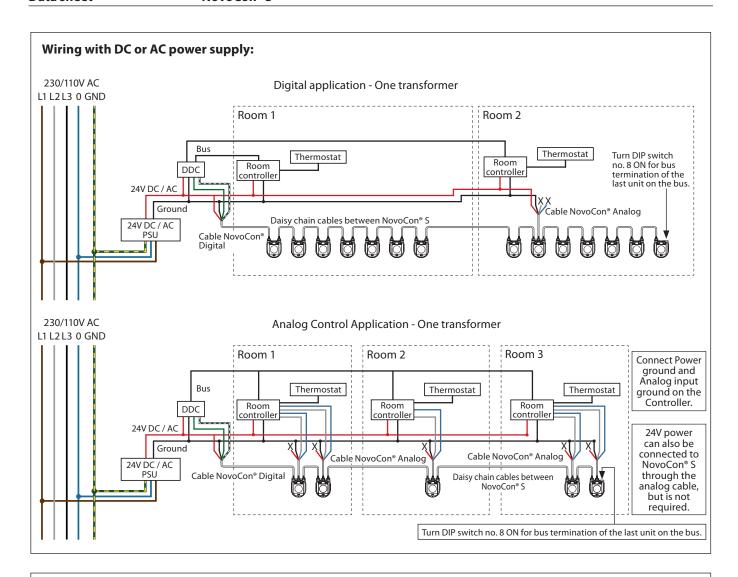
## Wiring considerations

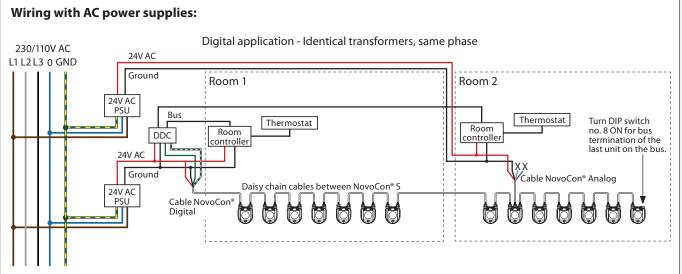
## The important factors here are:

- Common ground
- 24VDC power supply is recommended
- In case more 24VAC power supplies are used always separate the 24VAC power supplies if different types of power supplies are used and / or different phases are used.









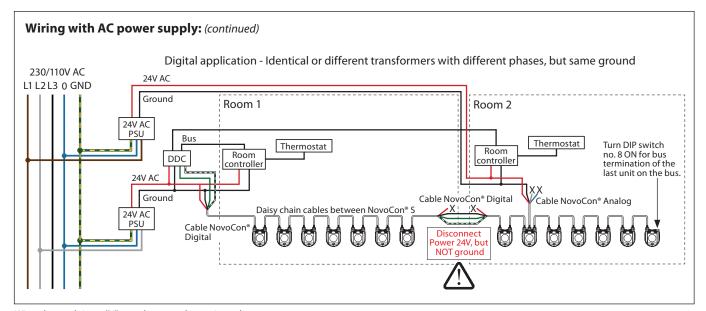


If the NovoCon® S network is supplied with two or more AC power boosters, caution must be observed when disconnecting one of the transformers from the high voltage power line. As the NovoCons are connected in a daisy chain, there may be high voltage on the primary side of the disconnected power supply. Disconnect always both the primary and secondary side of the transformer.

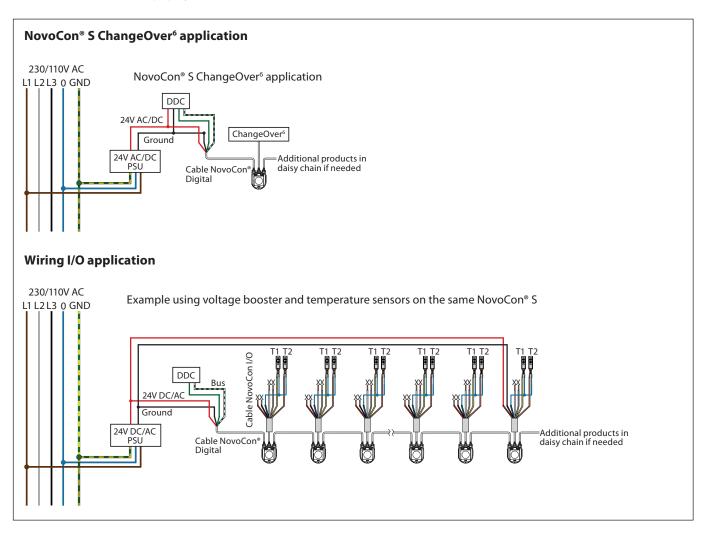
The power boosters must be protected against overload, otherwise the power booster may be damage if one of the other power boosters in the network is disconnected.

Wires that ends in an "X" must be properly terminated.





Wires that ends in an "X" must be properly terminated.





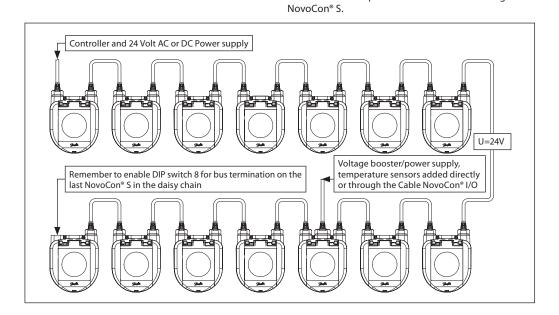
## **Daisy chain**

## DC Power supply (recommended)

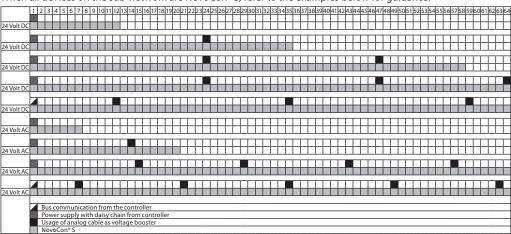
When daisy chaining with 10m NovoCon® cables and using a 24V DC power supply, additional voltage boosters/power supply is needed when 12 NovoCons in series is exceeded. See table below.

## **AC Power supply**

When daisy chaining with 10m NovoCon® cables and using a 24V AC power supply, additional voltage boosters/power supply is needed when 7 NovoCons in series is exceeded. See table below. Important: The power supply used must be able to deliver 60% more power than the nominal rating of



When all devices on the sub-network are NovoCon® S, refer to the examples below for guidance.



If NovoCon $^{\circ}$  S is used to power external devices, a separate calculation must be made for power booster amount and location.

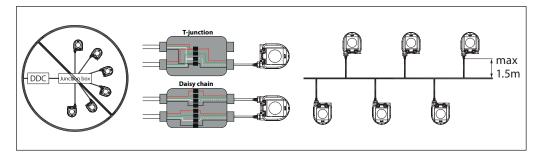
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#### **Daisy chain** (continued)

Use daisy chain connection for NovoCon® S. Danfoss recommend that star topology is NEVER used with NovoCon® S as debugging the system becomes very difficult. T-junction connections (stub lines) are not recommended. In the event of T-junction connections being used, Danfoss accepts no responsibility although it is advised that the following limitations are never exceeded:

- max T-junction cable lenght 1.5m (shortest standard digital cable)
- total length of Network max 640m (+ 100m stub length)
- max baud rate 76 kb/s 1)
- max number of devices on network 64 1)
- main cable should be standard RS485 bus, twisted pair, min thickness AWG22 / 0.32mm<sup>2</sup>.
- 1) When using less than 32 devices you may attempt to raise the speed to 115 kb/s.



If the supply voltage to the first device in the daisy chain is lower than 24V AC/DC, or long thin cables other than NovoCon® cables are used, then the quantity of devices in the daisy chain may have to be reduced.

The recommended maximum quantities of NovoCon® S are 64 pcs in one daisy chain connection. If other BACnet devices are added with NovoCon® S in the same daisy chain connection, Danfoss recommends a maximum of 32 pcs. to ensure sufficient network speed.

Danfoss recommends that NovoCon® S should be used on its own sub-network for optimal performance.

General requirements and recommendations:

- Use Danfoss daisy chain cable to connect two NovoCon® S devices.
- Use Danfoss digital cable to connect NovoCon® S with another BACnet device.
- The current in cables should not exceed 3Arms at 30°C.
- Use the termination resistor (DIP switch 8) at the end of daisy chain.
- Voltage boosting may be achieved via any port.
- Generally, the same type of power supply is preferred.
- If two power supplies are used, they must have the same polarity and the same common ground.
- A common ground must be used for all devices on the same sub-network, including routers and gateways.
- Galvanic separation shall be provided for segments crossing buildings.
- Total maximum cable length of sub-network 1200m.

# Optimize BACnet network speed

## **Reducing Unnecessary PollforMaster Traffic**

Setting for the last NovoCon® in the daisy chain:

The MAX\_MASTER setting in NovoCon® S shall be set to the number of the highest used MAC address in the MS/TP sub network. The MAX\_MASTER property is found in the Device object and has a default value of 127. It should be noted that the MAX\_MASTER property value should be adjusted accordingly at a later stage if more devices are added to the network and the highest MAC address exceeds the MAX\_MASTER property value.

Before MAX\_MASTER can be set it is needed to ensure all devices are within the MAX\_MASTER value. If MAX:MASTER is set to 20 communication will not work with a device, which uses MAC address 22, even though e.g. MAC address 15 is not used.

## Allocating Correct INFO\_FRAMES

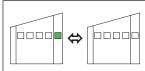
## Setting for Controller:

Network Routers and Controller devices that transport traffic in the MS/TP network require a higher number of INFO\_FRAMES than NovoCon® S. Therefore, these devices should have a higher value than NovoCon® S e.g. A general rule of thumb for the sub network router's MAX\_INFO\_FRAMES property value is equal to the amount of MS/TP devices in the router's sub network. The MAX\_INFO\_FRAMES property is found in the Device object of MS/TP devices. NovoCon's default MAX\_INFO\_FRAMES value is 1.



## **LED Display**

## BACnet/Modbus (RS485) activity



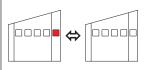
## BACnet/Modbus (RS485) activity

No light from LED: Actuator sees no activity on the network.

LED turn on and off quickly, 10x/second:

Normal operation on the network communication is OK.

LED turn on and off slowly with green light, 3x/second: Normal operation on the network - communication over longer time directly with this actuator.



#### BACnet/Modbus (RS485) activity with ERRORS

LED turns on and off slowly, 3x/second, with RED color: Actuator sees activity, but with errors.

LED turn on and off quickly, 10x/second, with RED color: Communication is OK, EXCEPT that another device may be using the same MAC address.

## Position of valve/actuator



AB-QM valve is fully closed.



AB-QM is 1-24% open.



AB-QM is 25-49% open.



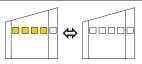
AB-QM is 50-74% open



AB-QM is 75-99% open.



AB-QM valve is fully open.



Flush is active

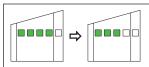
All LEDs turns on/off with specific period.

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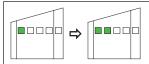
## **LED Display** (continued)

#### Movement of valve/actuator



#### NovoCon® S is closing the valve

All green LEDs are turned ON, then turned OFF one at the time (repeatedly).



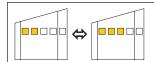
#### NovoCon® S is opening the valve

All green LEDs are turned OFF, then turned ON one at the time (repeatedly).



#### NovoCon® S is calibrating

Green light moves forward and backwards, one by one.



#### De-air is active

Yellow LEDs are turned ON one by one, then turned OFF one by one (repeatedly).

#### Information from actuator



**Blinking function**, all green LEDs turns on/off. Used to physically identify individual actuator on the bus.



## Error during closing

 $De bris\ might\ be\ trapped\ under\ the\ AB-QM\ valve\ cone.\ Flushing\ may\ solve\ the\ problem.$ 



#### Temperature inside NovoCon® S is out of the recommended range

LEDs change between showing the alarms and showing normal operation. Ambient temperature has likely exceeded 60°C.



## Internal NovoCon® S error

LEDs change between showing the alarms and showing normal between operation. Try: A: Re-calibrate.

B: Turn power off and on.

C: If the error does not disappear actuator replacement can be necessary.



## Error during NovoCon® S calibration

LEDs change between showing the alarms and showing normal operation. Verify if the NovoCon $^\circ$ S is correctly attached to the valve and recalibrate.



## Power supply is outside limits

LEDs change between showing the alarms and showing normal operation. Use analog cables as voltage booster.



## No Control Signal

In analog mode the broken control wire is detected.

In CO6 mode or Inverted CO6 mode the ChangeOver  $^{\rm 6}$  actuator is not connected or damaged.



## ChangeOver<sup>6</sup> actuator

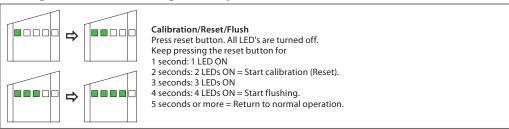
The ChangeOver<sup>6</sup> actuator is in manual override or unable to reach position.

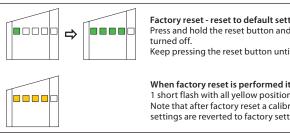
 ${\it LEDs change between showing the alarms and showing normal operation}.$ 



#### **LED Display** (continued)

#### Pressing the reset button during normal operation





#### Factory reset - reset to default settings

Press and hold the reset button and then power up the actuator, all LED's are initially

Keep pressing the reset button until 4 LED's are turned on = Reset to default settings.

#### When factory reset is performed it is shown by:

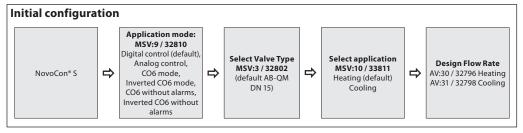
1 short flash with all vellow position LED's.

Note that after factory reset a calibration will be automatically be performed and all settings are reverted to factory settings.

## **BACnet objects and** Modbus registers usage - Design flow rate setting

#### General

There are simple BACnet and Modbus settings that are essential to the basic setup configuration of NovoCon® S in order to communicate and control. These are contained in the BACnet objects or in decimal format Modbus registers.



## **BACnet objects and** Modbus registers usage

- Advanced configuration and features

If the default setup of the actuator isn't suitable, special attention has to be payed to the following objects:

MSV:9 / 32810 Application mode MSV:3 / 32802 Selected Valve Type AV:30 / 32796 **Design Flow Rate Heating** Design Flow Rate Cooling AV:31 / 32798 MSV:10 / 33811 Application command & status Temperature T1 or resistance input Al·1 / 32791 AI:2 / 32792 Temperature T2 or resistance input AV:32 / 33288 **Power Emission** 

MSV:13 / 32814 **Energy management** 

#### **Application mode:**

The default Application mode is Digital Control. In this mode the NovoCon® S is controlled via fieldbus and the the voltage inputs and outputs are available to connect other devices.

If the CO6 functionality is needed the Application mode must be changed to CO6 mode. This is where the NovoCon® S actuator is ready to be used with the Actuator NovoCon® ChangeOver<sup>6</sup>. If the heating and cooling pipes are connected inverted to that shown on the data sheet, then CO6 Inverted mode must be selected. The object/register MSV:9 / 32810 Application mode is used to select this. Analog Control is also possible if required.

Select if the application is Heating, Cooling or CO6 in Application command & status MSV:10 / 33811.

#### Selection of AB-QM valve type:

After selecting Application mode (see above), it is then necessary to select the AB-QM valve type that the actuator is mounted on. This is done with the object MSV:3 / 32802 Selected Valve Type. The present value of MSV:3 / 32802 may be set to values between 1 and 17. Each number represents a specific AB-QM valve type, which can be found in the table: Valve type selection. The default value for MSV:3 / 32802 is 4 i.e. ABQM ISO DN15 valve.

## Selection and setting of engineering units:

If there is a need to change the default engineering units, this is done in BACnet via the object's engineering units property or in separate objects, and in Modbus via separate registers. Se the BACnet and Modbus tables for more details.



# BACnet objects and Modbus registers usage

# - Advanced configuration and features (continued)

#### **Setting the Design Flow Rate:**

Now we come to the point where the designed maximum flow rate of the controlled system should be set if the nominal flow of the valve does not correspond to the designed maximum flow rate. The Design Flow Rate is set by changing the present value of:

- MSV:30 / 32796 Design Flow Rate for Heating
- MSV:31 / 32798 Design Flow Rate for Cooling

Note: If the Design Flow Rate is set to more than the nominal flow value of the valve, the mechanical pre-setting on the valve must be set to maximum open i.e. fully opening the mechanical pre-setting wheel on the AB-QM valve (100% open is the default mechanical pre-setting from our factory).

#### Changing from Heating to cooling in CO6 and Inverted CO6 mode:

The object / register MSV:10 / 32811 CO6 command & status is used to change from heating function to cooling function as well as giving feedback as to the ball position status. A more detailed description of this is found in the tables for BACnet objects / Modbus registers.

#### Temperature measurements:

Al:1  $\dot{/}$  32791 Temperature T1 or resistance input and Al:2  $\dot{/}$  32792 Temperature T2 or resistance input are used to measure the temperature with PT1000 temperature sensors. The resistance value may also be show directly if selected, allowing these inputs to be used for other purposes than measuring temperature e.g. window contacts or another potential free contacts. Closed circuit <900 $\Omega$ , open circuit >10k $\Omega$ .

#### **Power emission:**

AV:32 / 33288 Power Emission is used to show the present hydronic power emission of the terminal unit, based on calculations from water flow rate and the temperature difference between supply and return pipes.

#### **Energy Counter:**

Both the Cooling and Heating hydronic energy used are counted and logged under AV:33 / 33290 and AV:34 / 33292. This function is enabled and disabled with MSV:12 / 32813.

#### Flushing a system:

Actuator Mode and Special Features MSV:0 / 33284 has an option which allows the user to flush the system via the field bus. To start flushing the system, set MSV:0 / 33284 to 3, Flush. The actuator will then open up the AB-QM valve completely. Flush will end when:

- MSV:0 / 33284 is set back to 1 = Normal operation
- Power is cycled.
- · Or flush function times-out after 1 hour.

When flushing ends, the actuator returns to normal operation.

## De-Airing of a system:

With MSV:0 / 33284, is it also possible to start the De-Air function in the actuator. This function will open and close the AB-QM valve a number times, helping getting rid of trapped air in the hydronic system. Start De-Air by setting MSV:0 / 33284 to 4. De-air will run undisturbed until it ends. The state of the actuator will then go back to normal operation i.e. MSV:0 / 33284 = 1, Normal.

#### Controlling the actuator:

Under normal operation Digital (MSV:9 / 32810 Application mode in CO6 mode, Inverted CO6 mode and Digital mode) of the actuator, where the flow through the AB-QM valve is to be controlled, the object Flow Rate Setpoint AV:1 / 33280 is used. The default setting for the Flow Rate Setpoint engineering unit is %.

This is the most suitable setting as the controller does not need to know anything about the Design Flow Rate setting of the actuator. The output signal from the controller needs only to be set up so it regulates from 0 to 100% of the Heating Design Flow Rate AV:30 / 32796 or Cooling Design Flow Rate AV:31 /32798. Alternative Design Flow Rate AV:0 / 32768 can be used.

To change the flow rate through the valve, the present value of AV:1 / 33280 is written-to, in the range 0 - 100%.

If the engineering unit selected for AV:1 / 33280 must be I/h, the Flow Rate Setpoint through the valve must be written-to in integers representing I/h. An example of this could be a controller writing values to the actuator in the range 0 to 450 I/h for a DN15 valve.

## Alarms and warnings:

System issues can be detected by using BACnet object values BV:10 to BV:24 or Modbus register 33536, see BACnet and Modbus tables for more details.

MSV:9 / 32810 has also a state called "CO6 without alarms" meaning that essentially the same CO6 functionality is present (2 Design flows and the changeover signal) without alarms, so the analog input signal may be used to connect other devices if required.



# Energy management MSV:13 / 32814

#### State 1: Not active

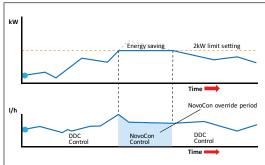
Energy management applications are disabled.

## **Power Manager**

## State 2: Power limitation (cooling water example)

NovoCon® S calculates the instantaneous hydronic power used and will then override the DDC control signal and limit the flow rate / hydronic power according to the user defined values in object / register AV:35 or 36 / 32832 or 32834. The hydronic power is limited by closing the valve until the kW value measured, once again, falls below the defined limit. There are user defined limits for both Cooling Power and Heating Power. When this limitation is active, the warning object BV:23 / bit 23 in register 33536 will be set to 'on'.

Application example: When the "Power" is limited in this way we are able to prevent over consumption (during peak load) and save money.



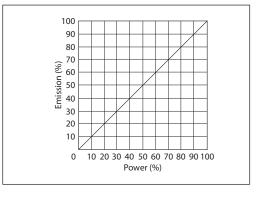
| Object/<br>Register | Write/read<br>value         | Description  |
|---------------------|-----------------------------|--|
| MSV:9 /<br>32810    | Digital                     | NovoCon/AB-QM opening degree command via BUS   |
| MSV:3 /<br>32802    | Selected<br>Valve Type      | ISO valve selected = $l/h$ , °C , kW and kg/m <sup>3</sup> .<br>ANSI valve selected = $g/min$ , °F and kBTU. |
| AV:31 /<br>32798    | Cooling                     | Design flow setting of Cooling e.g.<br>400 l/h   |
| MSV:13<br>/32814    | Power<br>Limitation         | The Cooling max hydronic power value that NovoCon will not exceed e.g. 2kW                                   |
| AV:36<br>/32834     | Cooling max.<br>power value | The value that NovoCon will ensure T2 will not fall below e.g. 13°C  |

#### **Power Manager**

#### **State 3: Power control**

Emission is controlled directly in kW or kBTU and not % or l/hr / GPM. The flowrate through the valve is controlled by the Flow Rate setpoint AV:1 in kW or kBTU/h (selected in MSV:21 / 32788) and is based on the flowrate and temperature inputs which are used to calculate the power consumption.

Application example: Tempering a space (e.g. in storage hall) where we can set and keep the energy output constant.



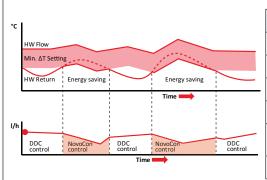
#### **Delta T Manager**

#### State 4: Min. Delta T limitation (heating water example)

NovoCon® S overrides the DDC control signal and maintains a minimum temperature difference between the flow and return temperatures by closing the valve when the user defined minimum delta T is not achieved. As the flow temperature increases/decreases, so will the calculated minimum set-point for the return temperature. This always ensures a minimum energy transfer to the FCU irrespective of the flow temperature. This state may also be used in CO6 mode and will apply the appropriate value whilst in cooling/heating mode.

The delta T value is set in object / register AV:37 / 32836 and/or AV:38 / 32838. When this limitation is active, the warning object BV:23 / bit 23 in register 33536 will be set to 'on'.

Application example: When we would like to improve the efficiency of boiler/chiller we can define the Minimum Delta T in the system.



|   | Object/<br>Register | Write/<br>read value       | Description   |
|---|---------------------|----------------------------|---|
|   | MSV:9 /<br>32810    | Digital                    | NovoCon/AB-QM opening degree command via BUS  |
|   | MSV:3 /<br>32802    | Selected<br>Valve Type     | ISO valve selected = I/h, °C and kW.<br>ANSI valve selected = GPM, °F and kBTU.                   |
| - | MSV:10 /<br>32811   | Heating                    | Any control algorithms used are with Al:1>Al:2 in mind  |
|   | AV:30 /<br>32796    | 250                        | Design flow setting of Heating e.g.<br>250 l/h  |
|   | MSV:13 /<br>32814   | Min. Delta T<br>limitation | Constantly ensures the flow and return temperature difference do not fall below a specified value |
|   | AV:37 /<br>32836    | Heating<br>Delta T value   | The delta T value that NovoCon will not fall below e.g. 20°C                                      |

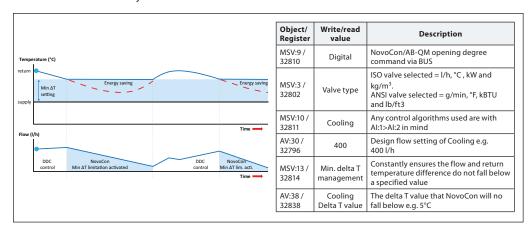
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# Energy management MSV:13 / 32814 (continued)

#### State 4: Min. Delta limitation (Colling water example)

Application example: When we would like to improve the efficiency in the system we can define the Minimum Delta T in the system.

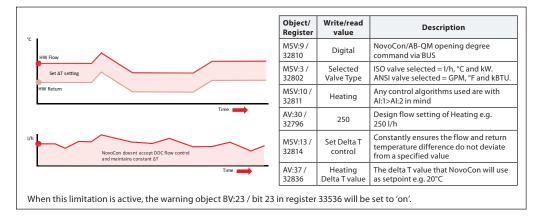


## State 5: Set Delta T control (heating water example)

NovoCon® S overrides the DDC control signal and maintains a constant temperature difference between the flow and return temperatures by opening and closing the valve when the user defined delta T is exceeded or not achieved. When the flow temperature increases/decreases, so will the calculated delta T set-point for the return temperature. This always ensures a constant delta T across the FCU irrespective of the flow temperature. This state may also be used in CO6 mode and will apply the appropriate value whilst in cooling/heating mode.

The constant delta T is set in object / register AV:37 / 32836 and/or AV:38 / 32838.

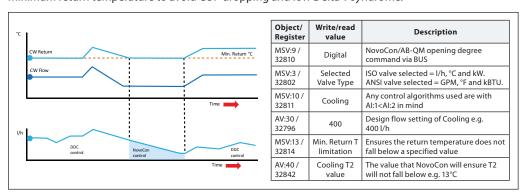
Application example: Tempering a space (e.g. in storage hall) where we can set and keep a constant Delta T.



## State 6: Min. Return T limitation (cooling water example)

NovoCon® S ensures the min. return temp. which is set in register / object AV:40 / 32842. This function will mainly be used for a Cooling application where the return temperature is higher than the flow temperature. NovoCon® S overrides the DDC control signal and maintains a minimum return temperature closing the valve when the user defined minimum return temperature is not achieved. When this limitation is active, the warning object BV:23 / bit 23 in register 33536 will be set to 'on'. Application example:

To improve chiller efficiency and ensure proper flow temperature for cooling systems, we can prescribe minimum return temperature to avoid COP dropping and low Delta T syndrome.



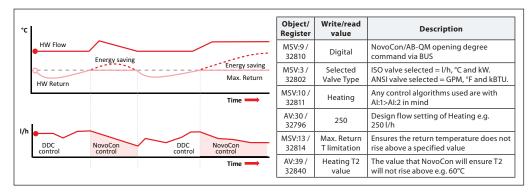


# Energy management MSV:13 / 32814 (continued)

#### State 7: Max. Return T limitation (heating water example)

NovoCon® S ensures the max return temp. set in register / object AV:39 / 32840.

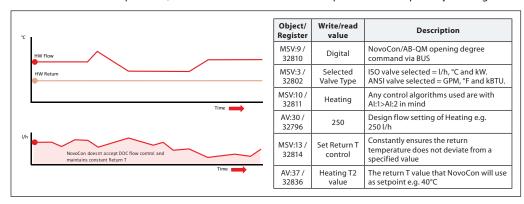
This function will mainly be used for a Heating application where the return temperature is lower than the flow temperature. NovoCon® S overrides the DDC control signal and maintains a maximum return temperature closing the valve when the user defined maximum return temperature is not achieved. When this limitation is active, the warning object BV:23 / bit 23 in register 33536 will be set to 'on'. Application example: Free cooling (e.g. river based) application where we would like to avoid river overheating.



## State 8: Set Return T control (heating water example)

A constant return temperature T2 value is set in object / register AV:37 / 32836 and/or AV:38 / 32838. NovoCon® S overrides then the DDC control signal and maintains a constant return temperature by opening and closing the valve when the user defined Return T is exceeded or not achieved. When the flow temperature increases/decreases, the Return T set-point remains the same. This will ensure a constant return temperature back to the boiler/chiller if all terminal units (Fan Coils, radiant panels etc.) are set with the same parameters.

Application example: When we intend to use the return water for secondary usage (e.g. floor heating) with constant inlet temperature, worth to set constant return temperature of the primary heating water.



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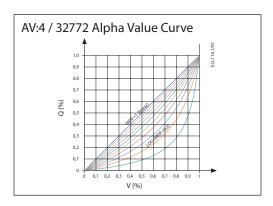
# **BACnet Objects - Analog Value**

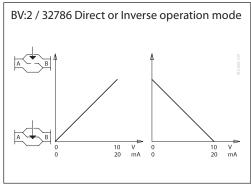
| Ident        | Object /<br>Parameter name                                     | Unit  | Read/<br>Write | Min                                      | Max   | Default   | Resolution  | Description   | Persistent<br>Yes/No |
|--------------|--|---|----------------|--|---|---|---|---|----------------------|
| AV:0         | Design Flow Rate   | 98: %<br>136: L/h<br>89: GPM  | R/W            | Recommended<br>20% of<br>nominal<br>flow | Setting Range Maximum from<br>Valve table   | Nominal value<br>from the Valve<br>table in L/h     | 0.1   | Recommended to use AV:30 for Heating and/or AV:31 for cooling.<br>Pre-set value for the Design Flow Rate when control signal is<br>at 100%, if the Application mode is Analog or Digital control<br>otherwise not used.<br>Units can be changed via the object's engineering units property<br>and/or MSV:20. The units I/h (ISO valves) or GPM (ANSI valves)<br>comes from the object MSV:3 Selected Valve type. | Yes                  |
| AV:1         | Flow Rate Setpoint   | 98: %<br>136: L/h<br>89: GPM<br>48: kW<br>157: kBTU/h   | R/W            | 0  | 100% or Design Flow value   | 100%  | 0.01  | The Flow Rate Setpoint (max. flow rate) through the AB-QM valve.<br>Units can be changed via the object's engineering units property<br>and/or MSV: 21.<br>NOTE: For kW or kBTU/h to become active, MSV:13 Power<br>Controller (state:3) must be chosen.  | No                   |
| AV:2         | Actual Flow Rate feedback                                      | %, L/h, GPM   | R              | 0  | If L/h (GPM) is selected then<br>the valve flow rate is set to<br>the selected valve's (MSV:3)<br>maximum value. Otherwise 100%   | L/h or GPM<br>depending on<br>the selected<br>valve | 0.001   | Flow rate indication based on the position of the Actuator stem.<br>Units can be changed via the object's engineering units property<br>and/or MSV:22.  This object is supported by COV.  | No                   |
| AV:3         | Control Fallback Time  | 72: Minutes   | R/W            | 0  | 60  | 10  | 1   | Time before actuator reacts to a missing analog control signal. i.e. when MSV:9=1 Analog control and not receiving an analog control signal.  | Yes                  |
| AV:4         | Alpha Value  | 95: No units  | R/W            | 0.05                                     | 1.0   | 1,0   | 0.01  | Value used for shaping the curve in Manual Defined Function (MDF) mode to fit the characteristic curve of a heat exchanger. Linear setting: MDF=1. See curve below table. If $AV1$ is in $L/h$ in Digital mode, the alpha setting is ignored. See Alpha value diagram.  | Yes                  |
| AV:5         | Valve closing or opening time                                  | 73: Seconds   | R/W            | 18                                       | 700   | na  | 1   | The time the actuator needs to move from 0% to 100% of Design Flow Rate. Use with MSV:4.  | Yes                  |
| AV:6         | Rectified voltage measured by the actuator                     | Volts   | R              | 12                                       | 50  | na  | 0.01  | Rectified voltage which powers the actuator. Too low voltage: 16.1-17.5V. Too high voltage: 38.3-43.4V. Use to check power booster numbers an layout.   | No                   |
| AV:7         | MAC Address  | 95: No units  | R/W            | 1  | 126   | na  | 1   | MAC Address used for BACnet communication.  | Yes                  |
| AV:8         | Temperature in the Actuator                                    | °C,°F   | R              | -20                                      | 100   | °C  | 0.5   | Temperature measured inside the actuator. Units can be changed via the object's engineering units property.   | No                   |
| AV:9         | Total Operating Hours  | Hours   | R              | 0  | MAX   | na  | 1   | Total Operating Hours of the actuator.  | Yes                  |
| AV:10        | Minutes since last power-up                                    | Minutes   | R              | 0  | MAX   | na  | 1   | Minutes since the last power-up of the actuator.  | No                   |
| AV:11        | Minutes since last calibration                                 | Minutes   | R              | 0  | MAX   | na  | 1   | Minutes since the last time the actuator was calibrated to an AB-QM valve.  | Yes                  |
| AV:12        | Minutes since fully closed                                     | Minutes   | R              | 0  | MAX   | na  | 1   | Minutes since the last time the AB-QM valve was fully closed.   | Yes                  |
| AV:13        | Minutes Since fully Opened                                     | Minutes   | R              | 0  | MAX   | na  | 1   | Minutes since the last time the AB-QM valve was fully opened.   | Yes                  |
| AV:14        | Lifetime estimate  | na  | R              | 0  | MAX   | na  | 0.01  | Calculated percentage of expended lifetime. At 100% the valve and actuator have reached the estimated minimum lifetime. Replacement of valve and actuator is recommended.   | Yes                  |
| AV:15        | Server Message Count   | na  | R              | 0  | MAX   | na  | 1   | Server Message Count  | No                   |
| V:16<br>V:17 | Server Message Received Server Error Count                     | na<br>na  | R<br>R         | 0  | MAX<br>MAX  | na<br>na  | 1   | Server Message Received Server Error Count  | No<br>No             |
| V:18         | Server Message sent  | na  | R              | 0  | MAX   | na  | 1   | Server Message sent   | No                   |
| \V:19        | Server Timeout Error   | na  | R              | 0  | MAX   | na  | 1   | Server Timeout Error  | No                   |
| AV:20        | Serial Number of the actuator                                  | na  | R              | na                                       | na  | na  | 1   | Description of this object holds the serial number of the actuator programmed at the time of production.  | na                   |
| AV:21        | The name of the Selected valve is shown here                   | L/h or GPM, Unit type<br>comes from MSV:3<br>Selected Valve Type                                | R              | na                                       | na  | na  | 1   | Nominal flow of the selected AB-QM valve type.  | na                   |
| AV:22        | Valve position at nominal flow                                 | Millimetre  | R              | na                                       | na Setting Range Maximum from   | na  | 1   | Position in mm for nominal flow of the selected AB-QM valve.  | na                   |
| AV:23        | Maximum value for the Design<br>Flow Rate                      | %   | R              | na                                       | Valve table   | %   | 1   | Maximum level the Design Flow Rate can be increased to for the selected AB-QM valve.  | na                   |
| AV:24        | The name of the User Defined<br>Valve is shown here            | 136: L/h or 89: GPM.<br>Unit type written here<br>is copied to the Valve<br>Table. Default: L/h | R/W            | 1  | 5000  | 450   | 0.1   | Name and Nominal Flow for the User Defined Valve. This Object is used only if NovoCon* 5 is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the desired connection is possible.   | Yes                  |
| AV:25        | Valve position at nominal flow<br>for User Defined Valve       | 30: Millimetre  | R/W            | 1.5                                      | 5.8   | 2.25  | 0.01  | Position in mm for nominal flow of the User Defined Valve. This Object is used only if NovoCon*5 is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the desired connection is possible.   | Yes                  |
| AV:26        | Maximum value for the Design<br>Flow in the User Defined Valve | 98: %   | R/W            | 100                                      | 150   | 120   | 1   | Maximum level the Design Flow can be increased to for the User Defined Valve. This Object is used only if NovoCon" S is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the desired connection is possible.   | Yes                  |
| AV:27        | Alarm summary count  | 95: No units  | R              | na                                       | Coding for Av.22 Alarm summar  If Bv:10 is active then Av.27  If Bv:11 is active then Av.27  If Bv:12 is active then Av.27  If Bv:13 is active then Av.27  If Bv:13 is active then Av.27  If Bv:15 is active then Av.27  If Bv:16 is active then Av.27  If Bv:16 is active then Av.27  If Bv:16 is active then Av.27  If Bv:18 is active then Av.27  If Bv:18 is active then Av.27  If Bv:19 is active then Av.27  If Bv:20 is active then Av.27  If Bv:21 is active then Av.27  If Bv:22 is active then Av.27  If Bv:23 is active then Av.27  If Bv:24 is active then Av.27 is  If Bv:24 is active then Av.27 is |   | Numerical overview about pending errors detected. Coding for AV.27 Alarm summary count is: If BV:10 is active then AV:27 is 1.0. If BV:11 is active then AV:27 is 2.0. If BV:13 is active then AV:27 is 4.0. If BV:13 is active then AV:27 is 8.0. If BV:14 is active then AV:27 is 8.0. If BV:16 is active then AV:27 is 8.0. If BV:16 is active then AV:27 is 16.0. If BV:17 is active then AV:27 is 128.0. If BV:18 is active then AV:27 is 128.0. If BV:19 is active then AV:27 is 128.0. If BV:19 is active then AV:27 is 128.0. If BV:20 is active then AV:27 is 1024.0. If BV:20 is active then AV:27 is 1024.0. If BV:22 is active then AV:27 is 1024.0. If BV:23 is active then AV:27 is 1024.0. If BV:24 is active then AV:27 is 1024.0. If BV:25 is active then AV:27 is 1024.0. If BV:26 is active then AV:27 is 1024.0. | No  |                      |
| AV:30        | Heating Design Flow Rate                                       | 98: %<br>136: L/h<br>89: GPM  | R/W            | Recommended<br>20% of<br>nominal flow    | Setting Range Maximum from<br>Valve table   | Nominal value<br>from the Valve<br>table in L/h     | 0.1   | Pre-set value for the Design Flow Rate in heating mode, when the control signal is at 100%.  The units L/h (ISO valves) or GPM (ANSI valves) comes from the object MSV:3 Selected Valve type  | Yes                  |
| AV:31        | Cooling Design Flow Rate                                       | 98: %<br>136: L/h<br>89: GPM  | R/W            | Recommended<br>20% of<br>nominal flow    | Setting Range Maximum from<br>Valve table   | Nominal value<br>from the Valve<br>table in L/h     | 0.1   | Pre-set value for the Design Flow Rate in cooling mode, when the control signal is at 100%.  The units L/h (ISO valves) or GPM (ANSI valves) comes from the object MSV:3 Selected Valve type.   | Yes                  |
|              | Power emission   | 48: kW  | R              | 0  | na  | kW  | 0.01  | The hydronic power emission of the terminal unit, based on calculations from water flow rate and the temperature difference   | No                   |



## **BACnet Objects - Analog Value** (continued)

| Ident | Object /<br>Parameter name | Unit                            | Read/<br>Write | Min | Max | Default | Description  | Information  | Persistent<br>Yes/No |
|-------|----------------------------|---------------------------------|----------------|-----|-----|---------|--|--|----------------------|
| AV:33 | Heating Energy<br>counter  | 19: kWh<br>126: MJ<br>147: kBTU | R/W            | 0   | na  | 19: kWh | Accumulative Energy counter for heating.                 | Activated/Deactivated via MSV:12. Units set via MSV:27   | Yes                  |
| AV:34 | Cooling Energy<br>counter  | 19: kWh<br>126: MJ<br>147: kBTU | R/W            | 0   | na  | 19: kWh | Accumulative Energy counter for cooling.                 | Activated/Deactivated via MSV:12. Units set via MSV:27   | Yes                  |
| AV:35 | Heating max.<br>Power      | 48: kW<br>157: kBTU/h           | R/W            | 0   | na  | 48: kW  | Pre-set value for the design flow rate, in heating mode. | When using MSV:13 state Power limiter this is the maximum allowed hydronic energy output. This value is intended to limit the heating power through the terminal unit. | Yes                  |
| AV:36 | Cooling max.<br>power      | 48: kW<br>157: kBTU/h           | R/W            | 0   | na  | 48: kW  | Pre-set value for the design flow rate, in cooling mode. | When using MSV:13 state Power limiter this is the maximum allowed hydronic energy output. This value is intended to limit the cooling power through the terminal unit. | Yes                  |
| AV:37 | Heating Delta T            | 62:°C<br>64°F                   | R/W            | na  | na  | 62:°C   | Set value for Delta T                                    | For MSV:13 state Min. delta T management and Set Delta T control, this is the value the control is based on for heating.   | Yes                  |
| AV:38 | Cooling Delta T            | 62:°C<br>64°F                   | R/W            | na  | na  | 62:°C   | Set value for Delta T                                    | For MSV:13 state Min. delta T management and Set Delta T control, this is the value the control is based on for cooling.   | Yes                  |
| AV:39 | Heating T2                 | 62:°C<br>64°F                   | R/W            | na  | na  | 62:°C   | Set value for Heating T2 (Heating return)                | For MSV:13 state Max. Return T management and Set return T control, this is the value the control is based on for heating.   | Yes                  |
| AV:40 | Cooling T2                 | 62: °C<br>64 °F                 | R/W            | na  | na  | 62:°C   | Set value for Cooling T2 (Cooling return)                | For MSV:13 state Min. Return T management and Set return T control, this is the value the control is based on for cooling.   | Yes                  |





# BACnet Objects - Multi State Value

| Ident | Object /<br>Parameter name                   | Read/<br>Write | State Text  | Default State                                   | Description  | Persistent<br>Yes/No               |
|-------|--|----------------|---|---|--|------------------------------------|
| MSV:0 | Actuator Mode<br>and special<br>features     | R/W            | 1: Normal<br>2: Calibration<br>3: Flush <sup>1)</sup><br>4: De-Air <sup>2)</sup><br>5: Alarm                                | 1: Normal                                       | Shows present mode of actuator. Calibration, flushing and de-air may be started from here.   | Yes,<br>except<br>state 3,4<br>& 5 |
| MSV:1 | Analog Control<br>signal type and<br>range   | R/W            | 1: 0-5 VDC<br>2: 0-10 VDC<br>3: 2-10 VDC<br>4: 5-10 VDC<br>5: 2-6 VDC<br>6: 6-10 VDC<br>7: 0-20 mA<br>8: 4-20 mA            | 2: 0-10 VDC                                     | Used to select the analog control signal input type and range.   | Yes                                |
| MSV:2 | Missing Control<br>Signal Fallback<br>Action | R/W            | 1: No action<br>2: CLOSE<br>3: OPEN<br>4: 50% of Design Flow  | 1: No action                                    | The action that the actuator will commence upon a missing analog control signal when MSV:9=1.  | Yes                                |
| MSV:3 | Selected Valve<br>Type                       | R/W            | See table "Valve Type Selection"  | 4: AB-QM DN 15                                  | This is the AB-QM valve type that the actuator is set-up to control.   | Yes                                |
| MSV:4 | Actuator Speed                               | R/W            | 1: 3 sec/mm<br>2: 6 sec/mm<br>3: 12 sec/mm<br>4: 24 sec/mm<br>5: Constant Time  | 4: 24 sec/mm                                    | The amount of time the actuator takes to move 1mm or alternatively, a specified constant time function (see AV:5). The Constant Time value range is 18-700 seconds.  | Yes                                |
| MSV:5 | MAC Address<br>assignment<br>method          | R/W            | DIP Switch Settings or Auto     Addressing     User configuration over BACnet     or Auto Addressing                        | 1: DIP Switch<br>Settings or Auto<br>Addressing | The MAC address selection method.  If the MAC address is not set by DIP Switch, the actuator will automatically assign itself an available MAC address.  | Yes                                |
| MSV:6 | Baud Rate                                    | R/W            | 1: Auto Baud Rate Detection<br>2: 9600 bps<br>3: 19200 bps<br>4: 38400 bps<br>5: 57600 bps<br>6: 76800 bps<br>7: 115200 bps | 1: Auto Baud<br>Rate Detection                  | Baud Rate used for BACnet communication.   | Yes                                |
| MSV:7 | LED Control                                  | R/W            | 1: Normal LED mode<br>2: Show alarms only<br>3: All LED's OFF<br>4: Blink   | 1: Normal LED<br>mode                           | The LED display options.   | Yes                                |
| MSV:8 | Select field bus<br>protocol                 | R/W            | 1: DIP switch<br>2: BACnet<br>3: Modbus   | 1: DIP switch                                   | Selection of field bus protocol. See also the DIP Switch Settings section of the data sheet. When the protocol is changed, a power cycle is required to make the actuator adopt the newly selected protocol. | Yes                                |

 $<sup>^\</sup>eta$  Opens the valve fully for one hour or until a new state is selected  $^{2}$  Opens and closes the valve 5 times at maximum speed

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BACnet Objects
- Multi State Value (continued)

| Ident  | Object /<br>Parameter name                   | Read/<br>Write          | State Text   | Default State      | Description  | Persistent<br>Yes/No |
|--------|--|-------------------------|--|--------------------|--|----------------------|
| MSV:9  | Application<br>mode                          | R/W                     | 1: Analog control 2: Digital control 3: CO6 mode 4: Inverted CO6 mode 5: CO6 without alarms 6: Inverted CO6 without alarms   | 2: Digital control | Select the actuator application mode.  State 1: Analog Control. Flow is controlled with an analog signal e.g. 0-10V, Design Flow Rate set via AV:30 Heating and/or AV:31 Cooling. Alternative AV:0 can be used.  State 2: Digital Control. AV:1 is used to control the flow. Design Flow Rate set via AV:30 Heating and/or AV:31 Cooling. Alternative AV:0 can be used.  State 3: CO6 mode. AV:1 is used to control the flow. Heating Design Flow Rate set via AV:30 and AV:31 for Cooling Design Flow Rate. Heating is connected to the CO6 valve to ports 5 & 6 and cooling to ports 1 & 4.  State 4: Inverted CO6 mode. AV:1 is used to control the flow. Heating Design Flow Rate set via AV:30 and AV:31 for Cooling Design Flow Rate. Ports are inverted in relation to State 3.  State 5: CO6 without alarms. AV:1 is used to control the flow. Heating Design Flow Rate set via AV:30 and AV:31 for Cooling Design Flow Rate. Ports are inverted in relation to State 3.  State 5: CO6 without alarms. AV:1 is used to control the flow. Heating Design Flow Rate set via AV:30 and AV:31 for Cooling Design Flow Rate. Ports are inverted to be used other than CO6 feedback. Be aware that in this state the status for the CO6 valve is not shown.  State 6: Inverted CO6 without alarms. AV:1 is used to control the flow. Heating Design Flow Rate set via AV:30 and AV:31 for Cooling Design Flow Rate. Ports are inverted in relation to State 3. This state may be used if the Analog Input is required to be used other than CO6 feedback. Be aware that in this state the status for the CO6 valve is not shown. | Yes                  |
| MSV:10 | Application<br>command &<br>status           | R/W<br>(1-4)<br>R (5-9) | 1: Heating 2: Cooling 3: CO6 Shut Off **  4: CO6 Start exercise 5: CO6 Moving towards Cooling 6: CO6 Moving towards Heating 7: CO6 Alarm 8: CO6 Exercising   | 1: Heating         | States 1 to 4 are commands for the Actuator NovoCon* ChangeOver6 and impact Energy Management Application MSV:13. States 5 to 8 are feedback from the Actuator NovoCon* ChangeOver6. State 3, shut-off mode may only be used for maintenance and is only possible when the Flow Rate Setpoint is 0%. In Central ChangeOver applications, state 1 and 2 are used to command heating or cooling.   | Yes                  |
| MSV:11 | CO6 auto<br>exercise                         | R/W                     | 1: ON<br>2: OFF  | 1: ON              | ON: The ChangeOver <sup>4</sup> valve will be moved from current position to shut off and back again once per week to maintain free movement, if CO6 mode is selected.  OFF: Exercising the valve should be handled by BMS.  | Yes                  |
| MSV:12 | Energy counter activation                    | R/W                     | 1: Off<br>2: On  | 1: Off             | Enable or disable energy counter   | Yes                  |
| MSV:13 | Energy<br>management                         | R/W                     | 1: Not active  Power Manager: 2: Power limitation 3: Power control  Delta T Manager: 4: Min. Delta T limitation 5: Set Delta T control 6: Min. Return T limitation 7: Max. Return T limitation 8: Set Return T control | 1: Not used        | Activate functions to optimize system performance.  State 1: Not active  State 2: If opwer is above the set value in AV:35/36, NovoCon will  regulate to the specified limit AV:35 and/or AV:36. When this limitation is active, the warning BV:23 will be set to 'on'.  State 3: The flowrate through the valve is controlled by AV:1 in kW or kBTU/h (selected in MSV:26) and is based on the flowrate and temperature inputs calculation.  State 4: If delta T value in AV:37 and/or AV:38 is exceeded, NovoCon will begin to close the valve until the AV:37 and/or AV:38 values are reached. When this limitation is active, the warning BV:23 will be set to 'on'.  State 5: The constant delta T is set in AV:37 and/or AV:38 and NovoCon will regulate within these limits. When this limitation is active, the warning BV:23 will be set to 'on'.  State 6: NovoCon ensures the min. return temp. set in AV:39 & AV:40. Used mainly for cooling apilications. When this limitation is active, the warning BV:23 will be set to 'on'.  State 7: NovoCon ensures the max return temp. set in AV:39 & AV:40. Used mainly for heating applications. When this limitation is active, the warning BV:23 will be set to 'on'.  State 8: NovoCon ensures the max return temp. set in AV:39 & AV:40. Used mainly for heating applications. When this limitation is active, the warning BV:23 will be set to 'on'.  State 8: No constant TV avalue is set in AV:39 and/or AV:40. NovoCon will regulate to maintain these values constant.   | Yes                  |
| MSV:20 | Units used to<br>set Design Flow<br>Rate     | R/W                     | 1: L/h<br>2: %<br>3: GPM<br>1: L/h   | 1: L/h             | Engineering Units used for the Design Flow AV:0, AV:30 and AV:31   | Yes                  |
| MSV:21 | Units used to<br>set Flow Rate<br>Setpoint   | R/W                     | 2: %<br>3: GPM<br>4: kW<br>5: kBTU/h   | 2:%                | Engineering Units used for the desired Flow AV:1.  NOTE: If kW or kBTU/h chosen then MSV:13 Power Controller (state:3) also becomes active   | Yes                  |
| MSV:22 | Units used to<br>set Actual Flow<br>feedback | R/W                     | 1: L/h<br>2: %<br>3: GPM   | 1: L/h             | Engineering Units used for AV:2  | Yes                  |
| MSV:23 | Units used to set<br>Temperature             | R/W                     | 1: °C<br>2: °F   | 1: ℃               | Engineering Units used for AV:8, AV:37-40  | Yes                  |
| MSV:24 | Units used to<br>set T1                      | R/W                     | 1: °C<br>2: °F<br>3: Ohm   | 1:℃                | Engineering Units used for Al:1  | Yes                  |
| MSV:25 | Units used to<br>set T2                      | R/W                     | 1: °C<br>2: °F<br>3: Ohm   | 1:°C               | Engineering Units used for Al:2  | Yes                  |
| MSV:26 | Units used to set<br>Power                   | R/W                     | 1: kW<br>2: kBTU/h   | 1: kW              | Engineering Units used for AV:32   | Yes                  |
| MSV:27 | Units used to set<br>Energy counter          | R/W                     | 1: kWh<br>2: MJ<br>3: kBTU   | 1: kWh             | Engineering Units used for AV:33 and AV:34   | Yes                  |

<sup>&</sup>lt;sup>1)</sup> A zero Flow Rate Setpoint command (AV:1) closes the AB-QM, so that there is neither heating nor cooling. Do not use the CO6 maintenance shut-off function for this purpose.



The CO6 valve shut-off function should only be used for maintenance and only when the water temperature in terminal unit is equal to ambient temperature or the terminal unit is not mounted. A water temperature change inside of a closed coil could result in rising pressure and possible damage of to the terminal unit.



## **BACnet Objects**

## - Binary Value

| Ident | Object /<br>Parameter name                                       | Read/<br>Write | Active<br>Text (1) | Inactive<br>Text (0) | Default  | Description  | Persistent<br>Yes/No |
|-------|--|----------------|--------------------|----------------------|----------|--|----------------------|
| BV:2  | Direct or Inverse operation Mode                                 | R/W            | Inverse            | Direct               | Direct   | Selection between Direct and Inverse operation mode. See Direct/Inverse diagram.   | Yes                  |
| BV:3  | Analog feedback signal   | R/W            | Active             | Inactive             | Inactive | By activating this feature, the analog output signal (AO:0) and the position of the valve opening become linked. The voltage output type and range is linked to the MSV:1 present value. This feature may be used for FCU fan control for example and is only made available when MSV:9 Application Mode are in State 1: Analog control or State 2: Digital control. If BV:3 is active and the analog output signal (AO:0) is written to manually it must be relinquished i.e. write "NULL" to return to the original setting of BV:3. | Yes                  |
| BV:10 | Warning: Temperature of the actuator is out of recommended range | R              | ON                 | OFF                  | na       | The Temperature inside the Actuator is out of the recommended range.   | No                   |
| BV:11 | Alarm: No Control Signal   | R              | ON                 | OFF                  | na       | The actuator has detected that it has no analog control signal.  | No                   |
| BV:12 | Alarm: Error during Closing                                      | R              | ON                 | OFF                  | na       | Actuator can't completely close the AB-QM valve.   | No                   |
| BV:13 | Warning: Pre-set Conflict  | R              | ON                 | OFF                  | na       | Conflict between the Mechanical AB-QM valve setting and the NovoCon® S. The mechanical valve setting must be 100% or above. The warning will also be activated if the Selected Valve Type has different stroke than the actually valve used. Validated during calibration.   | No                   |
| BV:14 | Warning: Voltage of power supply is too high                     | R              | ON                 | OFF                  | na       | Voltage of power supply is measured to be too high. When the measured voltage exceeds 43.4V the alarm will be turned ON for too high voltage. When the measured voltage is once more below 38.3V, the alarm will be turned OFF.  | No                   |
| BV:15 | Warning: Voltage of power supply<br>is too low                   | R              | ON                 | OFF                  | na       | Voltage of power supply is measured to be too low. When the measured voltage level drops below 16.5V the alarm will be activated for too low voltage. When the measured voltage level drops below 16.1V the motor will also be turned off. When the measured voltage is once more above 17.5V, the motor will be activated again.  | No                   |
| BV:16 | Alarm: Error during Calibration                                  | R              | ON                 | OFF                  | na       | There was an error during calibration of the actuator. E.g. the NovoCon® S actuator is not mounted on the valve or the valve is stuck.   | No                   |
| BV:17 | Warning: BACnet MAC-address<br>Conflict was Detected             | R              | ON                 | OFF                  | na       | Two or more devices on the same BACnet sub-network have the same MAC-address.  | No                   |
| BV:18 | Warning: Faults on the BACnet was detected                       | R              | ON                 | OFF                  | na       | Problems with communication on the network are detected.   | No                   |
| BV:19 | Alarm: An internal Error has been detected                       | R              | ON                 | OFF                  | na       | Re-calibrate or power cycle actuator to reset - actuator replacement may be necessary  | No                   |
| BV:20 | Alarm: CO6 in manual override or CO6 unable to move              | R              | ON                 | OFF                  | na       | ChangeOver <sup>6</sup> actuator is in manual override or is unable to reach position.   | No                   |
| BV:21 | Alarm: CO6 actuator not connected or damaged                     | R              | ON                 | OFF                  | na       | The ChangeOver® actuator is not connected or is damaged.   | No                   |
| BV:22 | Warning: Temp. sensors are missing or misconnected               | R              | ON                 | OFF                  | na       | Temp. sensors are missing or misconnected  | No                   |
| BV:23 | Warning: Energy limitation is active                             | R              | ON                 | OFF                  | na       | Limitation is active. E.g. Power limitation, min. delta T or min/max return T management limitation.   | No                   |
| BV:24 | Warning: Energy management controller out of range               | R              | ON                 | OFF                  | na       | Power, delta T or return T setpoint out of range or the setpoint can't be achieved.  | No                   |

# BACnet Objects - Device Object

## List with some selected important Device Object properties.

| Property                | Value  | Read / Write | Description   | Persistent<br>Yes/No |
|-------------------------|--|--------------|---|----------------------|
| Object ID               | Instance Range: 0 to 4194302                       | R/W          | This property is normally called Device Instance number or Unique ID.   | Yes                  |
| Object-Name             | Combination of "NovoCon S" +<br>Type and Object ID | R/W          | Product name.<br>Max. 25 characters.  | Yes                  |
| Firmware revision       | Current firmware version                           | R            | BACnet software revision.   | Yes                  |
| Application S/W version | Current Application SW version                     | R            | Actuator Application Software version.  | Yes                  |
| Location                | This string is emty when actuator is new.          | R/W          | Free text can be used to describe location etc.<br>Max. 50 characters.  | Yes                  |
| Description             | Danfoss NovoCon actuator<br>with BACnet MS/TP      | R/W          | Product description.<br>Max. 50 characters.   | Yes                  |
| Segmentation-supported  | NO SEGMENTATION                                    | R            | Actuator does not support segmentation.   | Yes                  |
| Max-master              | Default: 127<br>Range: 0-127                       | R/W          | The MAX_master setting in NovoCon® S should be set to the number of devices (or the highest used MAC address) in the MS/TP sub network. | Yes                  |

# BACnet Objects - Analog Input

| Ident | Object /<br>Parameter name               | Unit               | Read /<br>Write | Min          | Max           | Default units | Description  | Persistent<br>Yes/No |
|-------|--|--------------------|-----------------|--------------|---------------|---------------|--|----------------------|
| AI:0  | Voltage or<br>Current on analog<br>input | 5: Volts<br>2: mA  | R               | 0            | 10V<br>20mA   | Volts         | Voltage(V) or Current(mA) level on the analog control input,<br>measured by the actuator.<br>Units comes from MSV: I analog Control signal type and<br>range.<br>This object is supported by COV.<br>In CO6 and Inversed CO6 mode mA cannot be selected. | No                   |
| AI:1  | T1 or resistance<br>input                | 62: °C             |                 | -10°C        | 120°C         |               | Temperature/resistance measured from connected PT1000 sensors. For Power emission AV:32, Al:1 is temperature on the flow pipe and Al:2 is temperature on the return pipe. When used as potential free contacts: Closed circuit <900Ω,                    |                      |
| Al:2  | T2 or resistance<br>input                | 64: °F,<br>4: Ohms | R               | 10°F<br>900Ω | 250°F<br>10kΩ | °€            | open circuit 100kΩ.<br>Recommended max. cable length 2m.<br>Units can be changed via the object's engineering units<br>property.<br>This object is supported by COV.   | No                   |

# BACnet Objects - Analog Output

| Ident | Object /<br>Parameter name | Unit  | Read /<br>Write | Min | Max | Default units | Description  | Persistent<br>Yes/No |
|-------|----------------------------|-------|-----------------|-----|-----|---------------|--|----------------------|
| AO:0  | Voltage on analog output   | Volts | R/W             | 0   | 10  | Volt          | Output Voltage value in Digital and Analog mode MSV:9.<br>Note: In CO6 modes the present value is not writeable. | No                   |

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## NovoCon® S



## **BACnet Objects**

## - Notification class

| Ident | Object / Parameter name                   | Description                            |
|-------|---|--|
| NC:0  | Alarm Notifier, Subscribe here for alarms | Subscribe devices for receiving alarms |

NC:0 is an object where other BACnet devices can subscribe to be informed directly from this device if an alarm or warning is activated or cleared. A maximum of 4 devices can subscribe to this service. Subscribers of this object will be informed if any of the Warning or Alarms BV:10 to BV:24 is activated or cleared.

When the notification class NC:0 is going to be used to notify about changes with status of Warnings and Alarms (BV:10 - BV24), is it necessary to subscribe for notifications for the entire day and week: From 00:00:00:00 to 23:59:59:99 and all 7 days of the week. This is because the actuator does not have a clock built in and will therefore not be able to handle notifications with respect to time.

## **BACnet Objects**

## - Averaging

| Ident | Object /<br>Parameter name                         | Min.<br>Value |                              |  | Window<br>Interval | Window<br>Sample | Description  | Persistent<br>Yes/No |
|-------|--|---------------|------------------------------|--|--------------------|------------------|--|----------------------|
| AVO:0 | Average rectified voltage measured by the actuator |               | d according t<br>measurement |  | 1 Day              | 24               | Average of the rectified voltage that powers the actuator. | No                   |

## **Valve Type Selection**



Values for flow are valid for water applications. For glycol mixtures, please use correction factor.

| Index            | Name                   | Nominal Flow | Units | Valve position for nominal flow [mm] | Setting Range Maximum [%] |
|------------------|------------------------|--------------|-------|--------------------------------------|---------------------------|
| 1                | AB-QM ISO DN 10LF      | 150          | L/h   | 2.25                                 | 120                       |
| 2                | AB-QM ISO DN 10        | 275          | L/h   | 2.25                                 | 120                       |
| 3                | AB-QM ISO DN 15LF      | 275          | L/h   | 2.25                                 | 120                       |
| 41)              | AB-QM ISO DN 15        | 450          | L/h   | 2.25                                 | 120                       |
| 5                | AB-QM ISO DN 20        | 900          | L/h   | 2.25                                 | 120                       |
| 6                | AB-QM ISO DN 25        | 1700         | L/h   | 4.5                                  | 110                       |
| 7                | AB-QM ISO DN 32        | 3200         | L/h   | 4.5                                  | 110                       |
| 8                | AB-QM ISO DN 15HF      | 1135         | L/h   | 4                                    | 110                       |
| 9                | AB-QM ISO DN 20HF      | 1700         | L/h   | 4                                    | 110                       |
| 10               | AB-QM ISO DN 25HF      | 2700         | L/h   | 4.5                                  | 110                       |
| 11               | AB-QM ISO DN 32HF      | 4000         | L/h   | 4.5                                  | 110                       |
| 12               | AB-QM ANSI DN ½" LF    | 1.2          | GPM   | 2.25                                 | 100                       |
| 13               | AB-QM ANSI DN 1/2"     | 2            | GPM   | 2.25                                 | 100                       |
| 14               | AB-QM ANSI DN ½" HF    | 5            | GPM   | 4                                    | 100                       |
| 15               | AB-QM ANSI DN ¾"       | 4            | GPM   | 2.25                                 | 100                       |
| 16               | AB-QM ANSI DN ¾" HF    | 7.5          | GPM   | 4                                    | 100                       |
| 17               | AB-QM ANSI DN 1"       | 7.5          | GPM   | 4.5                                  | 100                       |
| 18               | AB-QM ANSI DN 1" HF    | 12           | GPM   | 4.5                                  | 100                       |
| 19               | AB-QM ANSI DN 11/4"    | 14.1         | GPM   | 4.5                                  | 100                       |
| 20               | AB-QM ANSI DN 11/4" HF | 17.5         | GPM   | 4.5                                  | 100                       |
| 21 <sup>2)</sup> | User Defined Valve     | NF           | UF    | VPNF                                 | SRM                       |

<sup>1)</sup> Default

when an ISO valve is selected.

## **BACnet BIBBs services**

| Service                          | BIBBs     | Init/Exe |
|----------------------------------|-----------|----------|
| ReadProperty                     | DS-RP-B   | exe      |
| WriteProperty                    | DS-WP-B   | exe      |
| Who-Is                           | DM-DDB-A  | init     |
| Who-Is                           | DM-DDB-B  | exe      |
| I-Am                             | DM-DDB-B  | init     |
| I-Am                             | DM-DDB-A  | exe      |
| Who-Has                          | DM-DOB-B  | exe      |
| I-Have                           | DM-DOB-B  | init     |
| DeviceCommunicationControl       | DM-DCC-B  | exe      |
| ReinitializeDevice <sup>1)</sup> | DM-RD-B   | exe      |
| ConfirmedEventNotification       | AE-N-I-B  | init     |
| UnconfirmedEventNotification     | AE-N-I-B  | init     |
| AcknowledgeAlarm                 | AE-ACK-B  | exe      |
| GetEventInformation              | AE-INFO-B | exe      |

| Service               | BIBBs     | Init/Exe |
|-----------------------|-----------|----------|
| GetAlarmSummary       | AE-ASUM-B | exe      |
| GetEnrollmentSummary  | AE-ESUM-B | exe      |
| AddListElement        | DM-LM-B   | exe      |
| RemoveListElement     | DM-LM-B   | exe      |
| ReadPropertyMultiple  | DS-RPM-B  | exe      |
| WritePropertyMultiple | DS-WPM-B  | exe      |
| SubscribeCOV 2)       | DS-COV-B  | exe      |
| Restart               | DM-R-B    | exe      |
| AtomicWriteFile       | na        | exe      |

<sup>1)</sup> NovoCon® S supports BACnet warm reset (power cycle) and Cold reset (factory reset). Note that after Cold/factory reset a calibration will be automatically performed and all settings will be reverted to factory settings.

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<sup>&</sup>lt;sup>2)</sup> The "User Defined Valve" is used only if NovoCon® S is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the desired connection is possible.

When an ANSI valve is selected the units for flow and temperature are default changed from I/h to GPM and Celsius to Fahrenheit, and vice versa

<sup>&</sup>lt;sup>2)</sup> COV is implemented for the following: Analog Inputs Al:0, Al:1 and Al:2, and for the following Analog Values AV:2 and AV:27.



## **DIP Switch Settings**

BACnet: Auto MAC addressing is default. For manual MAC addressing using DIP Switches, MSV:5 must be set to: DIP Switch Settings.

Modbus: Manual MAC addressing is default. Automatic addressing is not available for Modbus. However, if an address has been assigned in BACnet before switching to Modbus, the address will also be used in Modbus if the DIP Switched are left in the default positions.

| DIP Switch                               | Configuration name                       | OFF state (default)        | ON state                                      |
|--|--|----------------------------|---|
| 1. 1 2 3 4 5 6 7 8 9 10 ON OFF           | BACnet address / Modbus<br>unit ID bit 0 | Logic '0'                  | Logic '1'                                     |
| 2. 2 3 4 5 6 7 8 9 10 ON OFF             | BACnet address / Modbus<br>unit ID bit 1 | Logic '0'                  | Logic '1'                                     |
| 3. 1 2 3 4 5 6 7 8 9 10 ON OFF           | BACnet address / Modbus<br>unit ID bit 2 | Logic '0'                  | Logic '1'                                     |
| 4. 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | BACnet address / Modbus<br>unit ID bit 3 | Logic '0'                  | Logic '1'                                     |
| 5. 1 2 3 4 5 6 7 8 9 10 ON OFF           | BACnet address / Modbus<br>unit ID bit 4 | Logic '0'                  | Logic '1'                                     |
| 6. 0 ON OFF                              | BACnet address / Modbus<br>unit ID bit 5 | Logic '0'                  | Logic '1'                                     |
| 7. 1 2 3 4 5 6 7 8 9 10 ON OFF           | BACnet address / Modbus<br>unit ID bit 6 | Logic '0'                  | Logic '1'                                     |
| 8. 1 2 3 4 5 6 7 8 9 10 ON OFF           | Termination resistor (120 $\Omega$ )     | No<br>termination          | Termination resistor<br>enabled <sup>1)</sup> |
| 9. 1 2 3 4 5 6 7 8 9 10 ON OFF           |  | Not used                   |   |
| 10. 1 2 3 4 5 6 7 8 9 10 ON OFF          | -  | BACnet MS/TP <sup>2)</sup> | Modbus RTU <sup>2)</sup>                      |

## **DIP Switch Settings** - Manual Addressing

BACnet MAC address/Modbus Slave ID is set by DIP switch 1 to 7.

0 = OFF, 1 = ON

| DIP switch<br>1, 2, 3, 4 |      |      |      |      |      |      |      |      |      |      |      | DIP switch |      |      |      |       |
|--------------------------|------|------|------|------|------|------|------|------|------|------|------|------------|------|------|------|-------|
| 0000                     | 1000 | 0100 | 1100 | 0010 | 1010 | 0110 | 1110 | 0001 | 1001 | 0101 | 1101 | 0011       | 1011 | 0111 | 1111 | 5,6,7 |
| 0*                       | 1    | 2    | 3    | 4    | 5    | 6    | 7    | 8    | 9    | 10   | 11   | 12         | 13   | 14   | 15   | 000   |
| 16                       | 17   | 18   | 19   | 20   | 21   | 22   | 23   | 24   | 25   | 26   | 27   | 28         | 29   | 30   | 31   | 100   |
| 32                       | 33   | 34   | 35   | 36   | 37   | 38   | 39   | 40   | 41   | 42   | 43   | 44         | 45   | 46   | 47   | 010   |
| 48                       | 49   | 50   | 51   | 52   | 53   | 54   | 55   | 56   | 57   | 58   | 59   | 60         | 61   | 62   | 63   | 110   |
| 64                       | 65   | 66   | 67   | 68   | 69   | 70   | 71   | 72   | 73   | 74   | 75   | 76         | 77   | 78   | 79   | 001   |
| 80                       | 81   | 82   | 83   | 84   | 85   | 86   | 87   | 88   | 89   | 90   | 91   | 92         | 93   | 94   | 95   | 101   |
| 96                       | 97   | 98   | 99   | 100  | 101  | 102  | 103  | 104  | 105  | 106  | 107  | 108        | 109  | 110  | 111  | 011   |
| 112                      | 113  | 114  | 115  | 116  | 117  | 118  | 119  | 120  | 121  | 122  | 123  | 124        | 125  | 126  | 127* | 111   |

<sup>\*</sup> Addresses no. 0 and 127 must not be used.

Example Setting MAC address to 37:

| DIP 1 | DIP 2 | DIP 3 | DIP 4 | DIP 5 | DIP 6 | DIP 7 |
|-------|-------|-------|-------|-------|-------|-------|
| ON    | OFF   | ON    | OFF   | OFF   | ON    | OFF   |

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<sup>&</sup>lt;sup>1)</sup> The actuator possesses a resistor, DIP Switch no. 8, that can be activated in the last actuator on the bus for correct termination of the bus.
<sup>2)</sup> When the protocol is changed on DIP Switch no. 10, a power cycle is required to make the actuator adopt the newly selected protocol.



# Modbus registers - Configuration

| Modbus<br>register | Read/<br>Write | Modbus<br>function | Modbus<br>Data Type | Object /<br>Parameter<br>name  | Description  | Default  | Unit   | Description of usage   | Persistent<br>Yes/No |
|--------------------|----------------|--------------------|---------------------|--|--|--|--|--|----------------------|
| 0x8000<br>32768    | R/W            | 3,4 & 16           | FLOAT               | Design Flow<br>Rate  | Recommended to use 32796 for Heating<br>and/or 32798 for cooling.<br>Pre-set value for the Design Flow Rate<br>when control signal is at 100%. Unit<br>follows 32787   | Nominal<br>value from<br>the Valve<br>table in L/h | %, L/h, GPM  | Design Flow Rate in Liters per hour i.e. 150450 correspond to 150450 L/h or in percent, i.e. 20 100 correspond to 20 100%. The maximum setting range is depending on the selected valve. See Valve Type Selection. | Yes                  |
| 0x8002<br>32770    | R/W            | 3,4 & 6            | WORD                | Control Fallback<br>Time   | Time before actuator reacts to a missing analog control signal   | 10   | Minutes  | Control Fallback Time in minutes, i.e 0 60 correspond to 0 60 minutes  | Yes                  |
| 0x8004<br>32772    | R/W            | 3,4 & 16           | FLOAT               | Alpha Value  | Value used for shaping the curve in<br>Manual Defined Function (MDF) mode<br>to fit the characteristics curve of a heat<br>exchanger. If 33280 is in L/h in Digital<br>mode, the alpha setting is ignored.   | 1.0  | na   | Alpha Value curve, i.e. 0.05 1.00 correspond to 0.05 1.00. Alpha = 1.00 is liniar. Alpha = 0.2 is equal to the LOG function. See Alpha value diagram.  | Yes                  |
| 0x8006<br>32774    | R/W            | 3,4 & 16           | WORD                | Valve closing or opening time  | The time the actuator needs to move from 0% to 100% of Design Flow Rate. Use with 32803.   | na   | Seconds  | Valve closing or opening time in seconds i.e<br>18 700 correspond to 18 700 seconds  | Yes                  |
| 0x8008<br>32776    | R              | 3,4 & 6            | FLOAT               | Nominal Flow of<br>the user defined<br>valve                         | The Nominal flow of the user defined valve is shown here. This Object is used only if NovoCon® S is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the desired connection is possible.                          | na   | L/h or GPM,<br>Unit type<br>comes from<br>Valve Table            | Nominal flow e.g. in Liters per hour i.e. 0450 correspond to 0450 L/h  | Yes                  |
| 0x800A<br>32778    | R              | 3 & 4              | FLOAT               | Valve position<br>at nominal flow<br>for User Defined<br>Valve       | Position in mm for nominal flow of the User Defined Valve. This Object is used only if NovoCon® S is not used with an AB-OM valve. Please contact your Danfoss representative to verify if the desired connection is possible.                         | 2.25   | Millimetre   | Valve position for nominal flow in millimetre, i.e. 0.5 5.8 correspond to 0.5 5.8 millimetre   | Yes                  |
| 0x800C<br>32780    | R/W            | 3,4 & 6            | FLOAT               | Maximum value<br>for the Design<br>Flow in the User<br>Defined Valve | Maximum level the Design Flow Rate can be increased to for the User Defined Valve. This Object is used only if NovoCon® S is not used with an AB-OM valve. Please contact your Danfoss representative to verify if the desired connection is possible. | 120  | Unit type<br>follows 32787<br>selection:<br>% or (L/h or<br>GPM) | i.e. 0150 correspond to 0150 %   | Yes                  |
| 0x8012<br>32786    | R/W            | 3,4 & 6            | WORD                | Direct or Inverse operation Mode                                     | Selection between Direct and Inverse operation mode. See Direct/Inverse diagram.   | 0: Direct  | 0: Direct<br>1: Inverse  | Selection between Direct and Inverse operation mode. See Direct/Inverse diagram.   | Yes                  |
| 0x8013<br>32787    | R/W            | 3,4 & 6            | WORD                | Units used to<br>set and display<br>the Design Flow<br>Rate          | Units used to set and display the Design<br>Flow Rate. Units for L/h & GPM comes<br>from Selected Valve Type.  | 0: L/h   | 0: L/h<br>1: %<br>2: GPM   | Engineering Units used for the Design Flow<br>Rate.  | Yes                  |
| 0x8014<br>32788    | R/W            | 3,4 & 6            | WORD                | Units used to<br>set and display<br>Flow Rate<br>Setpoint            | Units used to set and display Flow Rate<br>Setpoint  | 1: %   | 0: L/h<br>1: %<br>2: GPM<br>3: kW<br>4: kBTU/h                   | Engineering Units used for the desired Flow<br>33280.<br>Note: If kW or kBTU/h chosen then 32814<br>Power Controller (state 3) also becomes active.  | Yes                  |
| 0x8015<br>32789    | R/W            | 3,4 & 6            | WORD                | Units used to<br>set and display<br>the Actual Flow<br>Rate feedback | Units used to set and display the Actual<br>Flow Rate feedback   | 0: L/h   | 0: L/h<br>1: %<br>2: GPM   | Engineering Units used for 33282.  | Yes                  |
| 0x8016<br>32790    | R/W            | 3,4 & 6            | WORD                | Units used to set temperature  | Select between °C or °F to set and display temperature   | 0: ℃   | 0: °C<br>1: °F   | Engineering Units for 33796, 32836. 32838, 32840 & 32842.  | Yes                  |
| 0x8017<br>32791    | R/W            | 3,4 & 6            | WORD                | Units used to set<br>and display T1                                  | Units used to read the temperature or  | 0.05   | 0: °C  | Engineering Units used for 33218.  |                      |
| 0x8018<br>32792    | R/W            | 3,4 & 6            | WORD                | Units used to set<br>and display T2                                  | resistance value.  | 0:℃  | 1: °F<br>2: Ohms   | Engineering Units used for 33220.  | Yes                  |
| 0x8019<br>32793    | R/W            | 3,4 & 6            | WORD                | Units used to set<br>Power   | Units used to read the power usage.  | 0: kW  | 0: kW,<br>1: kBTU/h  | Engineering Units for 33288.   | Yes                  |
| 0x801A<br>32794    | R/W            | 3,4 & 6            | WORD                | Endian type  | Byte ordering for LONG and FLOAT types   | 0: Big   | 0: Big<br>1: Little  | Used endian type for float and long registers  | Yes                  |
| 0x801C<br>32796    | R/W            | 3,4 & 16           | FLOAT               | Heating Design<br>Flow Rate  | Pre-set value for the Design Flow Rate when the control signal is at 100%.   | Nominal<br>value from<br>the Valve                 | %, L/h, GPM  | Design Flow Rate in Liters per hour i.e. 150450 correspond to 150450 L/h or in percent,  | Yes                  |
| 0x801E<br>32798    | R/W            | 3,4 & 16           | FLOAT               | Cooling Design<br>Flow Rate  | Unit follows 32787   | the valve<br>table in L/h                          |  | i.e. 20 100 correspond to 20 100%.<br>The maximum setting range is depending on<br>the selected valve. See Valve Type Selection.   |                      |



## **Modbus registers - Configuration** (continued)

| Modbus<br>register |     | Modbus<br>function | Modbus<br>Data Type | Object /<br>Parameter<br>name                 | Description   | Default      | Description of usage   | Persistent<br>Yes/No |
|--------------------|-----|--------------------|---------------------|---|---|--------------|--|----------------------|
| 0x802A<br>32810    | R/W | 3,4 & 6            | WORD                | Application<br>mode                           | 1: Analog control<br>2: Digital control<br>3: CO6 mode<br>4: Inverted CO6 mode<br>5: CO6 without alarms<br>6: Inverted CO6 without alarms   | 2: Digital   | Select the actuator application mode.  State 1: Analog Control. Flow is controlled with an analog signal e.g. 0-10V. Design Flow Rate set via register 32796 Heating and/or 32798 Cooling. Alternative 32738 can be used.  State 2: Digital Control. Register 33280 is used to control the flow. Design Flow Rate set via register 32796 Heating and/or 32798 Cooling. Alternative 32738 can be used.  State 3: CO6 mode. Register 33280 is used to control the flow. Heating Design Flow Rate set via register 33280 is used to control the flow. Heating Design Flow Rate. Heating is connected to the CO6 valve to ports 5 & 6 and cooling to ports 1 & 4.  State 4: Inverted CO6 mode. Register 33280 is used to control the flow. Heating Design Flow Rate set via register 33280 is used to control the flow. Heating Design Flow Rate set via register 32796 and 32798 for Cooling Design Flow Rate. Ports are inverted in relation to State 3.  State 5: CO6 without alarms. Register 33280 is used to control the flow. Heating Design Flow Rate set via register 32796 and 32798 for Cooling Design Flow Rate. This state may be used if the Analog Input is required to be used other than CO6 feedback. Be aware that in this state the status for the CO6 valve is not shown.  State 6: Inverted CO6 without alarms. register 33280 is used to control the flow. Heating Design Flow Rate set via register 32796 and 32798 for Cooling Design Flow Rate. Ports are inverted in relation to State 3. This state may be used if the Analog Input is required to be used other than CO6 feedback. Be aware that in this state the status for the CO6 valve is not shown. | Yes                  |
| 0x802B<br>32811    | R/W | 3,4 & 6            | WORD                | Application command & status                  | 1: Heating 2: Cooling 3: CO6 Shut Off 1) 4: CO6 Start exercise 5: CO6 Moving towards Cooling 6: CO6 Moving towards Heating 7: CO6 Alarm 8: CO6 Exercising   | 1: Heating   | States 1 to 4 are commands for the Actuator NovoCon® ChangeOver6 and impact Energy Management Application register 32814. States 5 to 8 are feedback from the Actuator NovoCon® ChangeOver6. State 3, shut-off mode may only be used for maintenance and is only possible when the Flow Rate Setpoint is 0%. In Central ChangeOver applications, state 1 and 2 are used to command heating or cooling.   | Yes                  |
| 0x802C<br>32812    | R/W | 3,4 & 6            | WORD                | CO6 auto<br>exercise                          | 1: ON<br>2: OFF   | 1: ON        | 1: ON: The ChangeOver6 valve will be moved from current position to shut off and back again once per week to maintain free movement, if CO6 mode is selected.  2: OFF: Exercising the valve should be handled by BMS.  | Yes                  |
| 0x802D<br>32813    | R/W | 3,4 & 6            | WORD                | Energy counter activation                     | 1: Off<br>2: On   | 1: Off       | Enable or disable energy counter   | Y                    |
| 0x802E<br>32814    | R/W | 3,4 & 6            | WORD                | Energy<br>management                          | 1: Not active  Power Manager: 2: Power limitation 3: Power control  Delta T Manager: 4: Min. Delta T limitation 5: Set Delta T control 6: Min. Return T limitation 7: Max. Return T control 8: Set Return T control | 1: Not used  | Activate functions to optimize system performance.  State 1: Not active.  State 2: If power is above the set value in register 32832 or register 32834, NovoCon will regulate to the specified limit register 32832 and/or 32834. When this limitation is active, the warning bit 23 in register 33536 will be set to 'on'.  State 3: The flowrate through the valve is controlled by register 33280 in kW or kBTU/h (selected in 32793) and is based on the flowrate and temperature inputs.  State 4: If delta T value in register 32836 and/or 32838 is exceeded, NovoCon will begin to close the valve until the register 32836 and/or 32838 values are reached. When this limitation is active, the warning bit 23 in register 33536 will be set to 'on'.  State 5: The constant delta T is set in register 32836 and/or 32838 and NovoCon will regulate within these limits. When this limitation is active, the warning bit 23 in register 33536 will be set to 'on'.  State 6: NovoCon ensures the min. return temp. set in register 32840 & 32842. Used mainly for cooling aplications. When this limitation is active, the warning bit 23 in register 33536 will be set to 'on'.  State 7: NovoCon ensures the max return temp. set in register 32840 & 32842. Used mainly for heating applications. When this limitation is active, the warning bit 23 in register 33536 will be set to 'on'.  State 8: A constant T2 value is set in register 32840 and/or 32842. NovoCon will regulate to maintain these values constant.   | Y                    |
| 0x8020<br>32800    | R/W | 3,4 & 6            | WORD                | Analog<br>Control signal<br>type and<br>range | Used to select the analog control signal input type and range   | 2: 0-10 VDC  | Select 1, 2 or based on the table below: 1: 0-5 VDC 2: 0-10 VDC 3: 2-10 VDC 4: 5-10 VDC 5: 2-6 VDC 6: 6-10 VDC 7: 0-20 mA 8: 4-20 mA   | Yes                  |
| 0x8021<br>32801    | R/W | 3,4 & 6            | WORD                | Missing<br>Control Signal<br>Fallback Action  | The action that the actuator will commence upon a missing analog control signal.  | 1: No action | Select 1, 2 or based on the table below: 1: No action 2: CLOSE 3: OPEN 4: Go to 50% of Design Flow Rate  | Yes                  |

 $<sup>^{\</sup>eta}$  A zero Flow Rate Setpoint command (33280) closes the AB-QM, so that there is neither heating nor cooling, do not use the CO6 maintenance shut-off function for this purpose.



The CO6 valve shut-off function should only be used for maintenance and only when the water temperature in terminal unit is equal to ambient temperature or the terminal unit is not mounted. A water temperature change inside of a closed coil could result in rising pressure and possible damage of to the terminal unit.

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## **Modbus registers - Configuration** (continued)

| Modbus<br>register | Read/<br>Write | Modbus<br>function | Modbus<br>Data Type | Object /<br>Parameter<br>name       | Description  | Default   | Unitw                      | Description of usage   | Persistent<br>Yes/No |
|--------------------|----------------|--------------------|---------------------|-------------------------------------|--|---|----------------------------|--|----------------------|
| 0x8022<br>32802    | R/W            | 3,4 & 6            | WORD                | Selected Valve<br>Type              | This is the AB-QM valve type that the actuator is set-up to control  |   |                            | See table "Valve Type Selection 1-17"  | Yes                  |
| 0x8023<br>32803    | R/W            | 3,4 & 6            | WORD                | Actuator Speed                      | The amount of time the actuator takes to move 1mm or alternatively, a specified constant time function (see 32774). The Constant Time value range is 18-700 seconds.  Select 1, 2 or based on the table below: 1: 3 sec/mm 2: 6 sec/mm 3: 12 sec/mm 4: 24 sec/mm 5: Constant Time (set by register 0x8006) |   | Yes                        |  |                      |
| 0x8024<br>32804    | R/W            | 3,4 & 6            | WORD                | Baud Rate                           | Baud Rate used for bus communication  Baud Rate used for bus communication  Baud Rate Detection  1: Auto Baud Rate Detection 2: 9600 bps 3: 19200 bps 4: 38400 bps 5: 57600 bps 6: 76800 bps 7: 115200 bps 7: 115200 bps   |   | Yes                        |  |                      |
| 0x8025<br>32805    | R/W            | 3,4 & 6            | WORD                | Select UART<br>mode                 | Supported transmission modes   | Supported transmission modes  5: Auto parity  Data format: (Start bit-Data bits-Parity-Stop bits) |                            | Yes  |                      |
| 0x8026<br>32806    | R/W            | 3,4 & 6            | WORD                | Slave ID                            | Slave ID used for communication.   | na na Slave ID used for communication   |                            | Slave ID used for communication  | Yes                  |
| 0x8027<br>32807    | R/W            | 3,4 & 6            | WORD                | Slave<br>ID asignment<br>method     | Settings   will automatically check if a Slave ID is present   |   |                            | Yes  |                      |
| 0x8028<br>32808    | R/W            | 3,4 & 6            | WORD                | BUS protocol                        | Select field bus protocol to be used. See also the DIP Switch Settings section of the data sheet.  When the protocol is changed, a power cycle is required to make the actuator adopt the newly selected protocol.  Select 1, 2 or 3 based on the table below:  1: DIP switch 2: BACnet 3: Modbus          |   | 1: DIP switch<br>2: BACnet | Yes  |                      |
| 0x8029<br>32809    | R/W            | 3,4 & 6            | WORD                | LED Control                         | The LED display options.   | 1: Normal<br>LED mode   | na                         | Select 1, 2 or based on the table below: 1: Normal LED mode 2: Show alarms only 3: All LED's OFF 4: Blink (can be used to locate the actuator)   | Yes                  |
| 0x8030<br>32816    | R/W            | 3,4 & 6            | WORD                | Units used to set<br>Energy counter | Units used to set energy counter   | 0: kWh  | 0: kWh<br>1: MJ<br>2: kBTU | Engineering Units used for 33290 & 33292.  | Yes                  |
| 0x8031<br>32817    | R/W            | 3,4 & 6            | WORD                | Analog feedback<br>signal           | Set analog output according to valve position  | 0: Inactive   | na                         | 0: Inactive 1: Active By activating this feature, the analog output signal (33286) and the position of the valve opening become linked. The voltage output type and range is linked to the 32800 present value. This feature may be used for FCU fan control for example and is only made available when 32810 Application Mode are in State 1: Analog control or State 2: Digital control. If 32817 is active and the analog output signal (33286) must be written to manually, it is necessary to change the setting of 32817 to inactive. | Yes                  |
| 0x8500<br>34048    | w              | 6                  | WORD                | Reset                               | Warm reset = Power cycle. Cold reset = Factory reset. Note that after factory reset a calibration will be automatically be performed and all settings will be reverted to factory settings.  | Warm reset = Power cycle. Cold reset = Factory reset. ote that after factory reset a calibration vill be automatically be performed and all settings will be reverted to factory                                  |                            | 0x5741 / 22337: Warm reset<br>0x434F / 17231: Cold reset.  | na                   |

## **Modbus registers - Operating**

| Modbus<br>register | Read/<br>Write | Modbus<br>function | Modbus<br>Data Type | Object /<br>Parameter name               | Description   | Default      | Unit                          | Description of usage   | Persistent<br>Yes/No            |
|--------------------|----------------|--------------------|---------------------|--|---|--------------|-------------------------------|--|---------------------------------|
| 0x8200<br>33280    | R/W            | 3,4 & 16           | FLOAT               | Flow Rate<br>Setpoint                    | The Flow Rate Setpoint through the AB-QM valve.<br>Unit follows 32788   | 100%         | %, L/h,<br>GPM, kW,<br>kBTU/h | Flow Rate Setpoint in percent, i.e.0 100 correspond to 0 100%  | No                              |
| 0x8202<br>33282    | R              | 3 & 4              | FLOAT               | Actual Flow Rate<br>feedback             | Flow Rate Indication based on the position of the<br>Actuator stem.<br>Unit follows 32788   | na           | %, L/h,<br>GPM                | Design Flow Rate feedback in percent, i.e. 0<br>100 correspond to 0 100%.<br>If L/h (GPM) is selected in 32787 then the<br>valve flow rate is set to the selected valve's<br>32776 maximum value. Otherwise 100% | No                              |
| 0x8204<br>33284    | R/W            | 3,4 & 6            | WORD                | Actuator Mode<br>and special<br>features | Shows present mode of actuator, Calibration, Flush and de-air may be started from here  | 1:<br>Normal | na                            | Select 1, 2 or based on the table below:<br>1: Normal<br>2: Calibration<br>3: Flush<br>4: De-Air<br>5: Alarm   | Yes, except<br>state 3,4<br>& 5 |
| 0x8206<br>33286    | R/W            | 3,4 & 16           | FLOAT               | Voltage on<br>analog output              | Output Voltage value in Digital and Analog mode 32810.<br>Note: In CO6 and Inversed CO6 mode the present value<br>is not writeable  | V            | Volts                         | Voltage level<br>i.e. 0.00 10.00 correspond to 0.00<br>10.00 V   | No                              |
| 0x8208<br>33288    | R/W            | 3,4 & 16           | FLOAT               | Power emission                           | The hydronic power emission of the terminal unit, based on calculations from water flow rate and the temperature difference between supply (33218) and return (33220) pipes.  Positive values reflect heating power emission.  Negative values reflect cooling power emission.  Units can be changed via the object's engineering units property. | kW           | kW,<br>kBTU/h                 | Power in kW or kBTU/h i.e1000.00 1000.00 correspond to -1000.00 1000.00 kW or in kBTU/h, i.e1000.00 1000.00 correspond to -1000.00 1000.00 kBTU/h  | No                              |



## **Modbus registers - Operating** (continued)

| Modbus<br>register | Read/<br>Write | Modbus<br>function | Modbus<br>Data Type | Object /<br>Parameter name | Description   | Default | Unit             | Description of usage   | Persistent<br>Yes/No |
|--------------------|----------------|--------------------|---------------------|----------------------------|---|---------|------------------|--|----------------------|
| 0x820A<br>33290    | R/W            | 3,4 & 16           | FLOAT               | Heating Energy<br>counter  | Energy counter for heating  | kWh     | kWh, MJ,<br>kBTU | Accumulative Energy counter for heating.<br>i.e. 0.00 1000.00 correspond to 0.00 1000.00 kWh   | Yes                  |
| 0x820C<br>33292    | R/W            | 3,4 & 16           | FLOAT               | Cooling Energy<br>counter  | Energy counter for cooling  | kWh     | kWh, MJ,<br>kBTU | Accumulative Energy counter for cooling.<br>i.e. 0.00 1000.00 correspond to 0.00 1000.00 kWh   | Yes                  |
| 0x8040<br>32832    | R/W            | 3,4 & 16           | FLOAT               | Heating max.<br>Power      | Pre-set value for the design<br>power, in heating mode, when<br>control signal is at 100% | kW      | kW,<br>kBTU/h    | When using register 32814 state Power limiter this is the maximum allowed hydronic energy output. This value is intended to limit the heating power through the terminal unit. i.e. 0.00 10.00 correspond to 0.00 10.00 kW | Yes                  |
| 0x8042<br>32834    | R/W            | 3,4 & 16           | FLOAT               | Cooling max.<br>power      | Pre-set value for the design power,<br>in cooling mode, when control<br>signal is at 100% | kW      | kW,<br>kBTU/h    | When using register 32814 state Power limiter this is the maximum allowed hydronic energy output. This value is intended to limit the cooling power through the terminal unit. i.e. 0.00 10.00 correspond to 0.00 10.00 kW | Yes                  |
| 0x8044<br>32836    | R/W            | 3,4 & 16           | FLOAT               | Heating Delta T            | Set value for delta T   | °C      | °C or °F         | For register 32814 state Minimum Delta T management and Set Delta T control, this is the value the control is based on for heating. i.e. 5 50 correspont to 5°C 50°C   | Yes                  |
| 0x8046<br>32838    | R/W            | 3,4 & 16           | FLOAT               | Cooling Delta T            | Set value for delta T   | °C      | °C or °F         | For register 32814 state Minimum Delta T management and Set Delta T control, this is the value the control is based on for cooling. i.e. 5 50 correspont to 5°C 50°  | Yes                  |
| 0x8048<br>32840    | R/W            | 3,4 & 16           | FLOAT               | Heating T2                 | Set value for T2 (return)   | °C      | °C or °F         | For register 32814 state Max. Return T management and Set return T control, this is the value the control is based on for heating. i.e. 5 50 correspont to 5°C 50°   | Yes                  |
| 0x804A<br>32842    | R/W            | 3,4 & 16           | FLOAT               | Cooling T2                 | Set value for T2 (return)   | °C      | °C or °F         | For register 32814 state Min. Return T management and Set return T control, this is the value the control is based on for cooling. i.e. 5 50 correspont to 5°C 50°   | Yes                  |

## **Modbus registers - Information**

| Modbus<br>register | Read/<br>Write | Modbus<br>function | Modbus<br>Data Type | Object /<br>Parameter name                       | Description  | Default                                      | Unit   | Description of usage   | Persistent<br>Yes/No |
|--------------------|----------------|--------------------|---------------------|--|--|--|--|--|----------------------|
| 0x8100<br>33024    | R              | 3 & 4              | FLOAT               | Nominal flow of<br>the selected valve<br>type    | Nominal flow of the selected valve type  | 450  | L/h or GPM, Unit<br>type comes from<br>Valve Table | Nominal flow e.g. in Litres per hour i.e. 0450 correspond to 0450 L/h.   | na                   |
| 0x8102<br>33026    | R              | 3 & 4              | FLOAT               | Valve position at nominal flow                   | Position in mm for nominal flow of the selected valve  | na   | Millimetre   | Valve position for nominal flow in millimetre, i.e., 0.5 5.8 correspond to 0.5 5.8 millimetre.   | na                   |
| 0x8104<br>33028    | R              | 3 & 4              | FLOAT               | Maximum value<br>of the Design<br>Flow Rate      | Maximum level the Design Flow Rate can be increased to for the selected valve  | Setting Range<br>Maximum from<br>Valve table | %  | Maximum level of the Design Flow Rate<br>in percent,<br>i.e. 20 100 correspond to 20 100%.   | na                   |
| 0x8120<br>33056    | R/W            | 3 & 4              | STRING              | Device name                                      | Product name   | NovoCon S                                    | na   | Ascii coded STRING   | Yes                  |
| 0x8140<br>33088    | R              | 3 & 4              | STRING              | Model name                                       | Type of the actuator   | CO6  | na   | Ascii coded STRING   | Yes                  |
| 0x8160<br>33120    | R              | 3 & 4              | STRING              | Vendor name                                      | Name of the Manufacture  | Danfoss A/S                                  | na   | Ascii coded STRING   | Yes                  |
| 0x8180<br>33152    | R/W            | 3, 4 & 16          | STRING              | Location description                             | Free text can be used to describe location etc. E.g. Room 1  | na   | na   | Ascii coded STRING. Max. 50 characters.  | Yes                  |
| 0x81A0<br>33184    | R              | 3, 4               | String              | Serial number                                    | Serial number of the actuator  | na   | 1  | Description of this object holds the serial number of the actuator, programmed at the production time.   | Yes                  |
| 0x8108<br>33032    | R              | 3, 4               | LONG                | Product ID                                       | Serial number of the actuator  | na   | 1  | Unique Product id. The last part of the serial number.   | Yes                  |
| 0x810A<br>33034    | R              | 3 & 4              | WORD                | SW version                                       | Software version of the actuator   | na   | na   | Ascii coded WORD   | Yes                  |
| 0x810B<br>33035    | R              | 3 & 4              | WORD                | HW version                                       | Hardware version of the actuator   | na   | na   | Ascii coded WORD   | Yes                  |
| 0x81C0<br>33216    | R              | 3 & 4              | FLOAT               | Voltage or<br>Current on analog<br>input         | Voltage(V) or Current(mA) level on the<br>analog control input, measured by the<br>actuator. In CO6 modes mA cannot be<br>selected.  | na   | Volts / mA   | Voltage level measured<br>i.e. 0.00 10.00 correspond to 1.00 10.00 V<br>or in mA,<br>i.e. 0.00 20.00 correspond to 0.00 20.00 mA   | No                   |
| 0x81C2<br>33218    | R              | 3 & 4              | FLOAT               | T1 or resistance<br>input                        | Temperature/resistance measured from connected PT1000 sensors. For Power emission 33288, register 33218 is temperature on the flow pipe and 33220 is temperature on the return pipe. | °C   | °C, °F, Ohms                                       | Temperature measured in °C i.e10°C 120°C or resistance measured i.e. $900\Omega$ $10k\Omega$ . When used as potential free contacts: Closed circuit $<900\Omega$ , open circuit $100k\Omega$ . Recommended max. cable length 2m. | No                   |
| 0x81C4<br>33220    | R              | 3 & 4              | FLOAT               | T2 or resistance<br>input                        | Temperature/resistance measured from connected PT1000 sensors. For Power emission 33288, register 33218 is temperature on the flow pipe and 33220 is temperature on the return pipe. | °C   | °C, °F, Ohms                                       | Temperature measured in °C i.e10°C 120°C or resistance measured ie. 900Ω 10kΩ. When used as potential free contacts: Closed circuit <900Ω, open circuit 100kΩ. Recommended max. cable length 2m.                                 | No                   |
| 0x8402<br>33794    | R              | 3 & 4              | FLOAT               | Rectified voltage<br>measured by the<br>actuator | Measured rectified voltage which powers the actuator   | na   | Volts  | Rectified voltage which powers the actuator.<br>Too low voltage: 16.1-17.5V<br>Too high voltage: 38.3-43.4V  | No                   |
| 0x8404<br>33796    | R              | 3 & 4              | FLOAT               | Temperature in<br>the actuator                   | Temperature measured inside the<br>Actuator  | na   | na   | Temperature measured inside the actuator. Unit is decided by 32790.  | No                   |
| 0x8406<br>33798    | R              | 3 & 4              | LONG                | Total Operating<br>Hours                         | Total Operating Hours of the actuator  | Hours  | Hours  | Total Operating Hours of the actuator  | Yes                  |
| 0x8408<br>33800    | R              | 3 & 4              | LONG                | Lifetime estimate                                | Calculated percentage of expended lifetime   | %  | na   | At 100% the valve and actuator have reached the estimated minimum lifetime. Replacement of valve and actuator is recommended.  | Yes                  |
| 0x8410<br>33808    | R              | 3 & 4              | LONG                | Minutes since last power-up                      | Minutes since the last power-up of the actuator  | Minutes                                      | Minutes  | Minutes since the last power-up of the actuator  | No                   |
| 0x8412<br>33810    | R              | 3 & 4              | LONG                | Minutes since last calibration                   | Minutes since the last time the actuator was calibrated to an AB-QM valve  | Minutes                                      | Minutes  | Minutes since the last time the actuator was calibrated to a valve   | Yes                  |
| 0x8414<br>33812    | R              | 3 & 4              | LONG                | Minutes since fully closed                       | Minutes since the last time the AB-QM valve was fully closed   | Minutes                                      | Minutes  | Minutes since the last time the valve was fully closed   | Yes                  |
| 0x8416<br>33814    | R              | 3 & 4              | LONG                | Minutes Since<br>Fully Opened                    | Minutes since the last time the AB-QM valve was fully opened   | Minutes                                      | Minutes  | Minutes since the last time the valve was fully opened   | Yes                  |

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## **Alarms & warning**

| Modbus<br>register | Read/<br>Write | Modbus function | Modbus<br>Data Type         | Object / Parameter name                             | Description  | Default   | Description of usage | Persistent<br>Yes/No                 |  |                                 |   |   |   |                           |  |        |  |   |   |                     |                     |    |
|--------------------|----------------|-----------------|-----------------------------|---|--|---|----------------------|--------------------------------------|--|---------------------------------|---|---|---|---------------------------|--|--------|--|---|---|---------------------|---------------------|----|
|                    |                |                 |                             | Alarm: No Control Signal                            | The actuator has detected that is has no analog control signal                         | 0: OFF  | Bit 0: 0:OFF; 1:ON   | No                                   |  |                                 |   |   |   |                           |  |        |  |   |   |                     |                     |    |
|                    |                |                 | Alarm: Error during Closing | Actuator can't completely close the AB-QM valve     | 0: OFF   | Bit 1: 0:OFF; 1:ON                                      | No                   |                                      |  |                                 |   |   |   |                           |  |        |  |   |   |                     |                     |    |
|                    |                |                 |                             |   |  |   |                      |                                      |  | Alarm: Error during Calibration | There was an error during calibration of the actuator. E.g. the NovoCon® S actuator is not mounted on the valve or the valve is stuck | 0: OFF                                      | Bit 2: 0:OFF; 1:ON  | No                        |  |        |  |   |   |                     |                     |    |
|                    |                |                 |                             | Alarm: An internal Error<br>has been detected       | Re-calibrate or power cycle actuator to reset - actuator replacement may be necessary  | 0: OFF  | Bit 3: 0:OFF; 1:ON   | No                                   |  |                                 |   |   |   |                           |  |        |  |   |   |                     |                     |    |
|                    |                |                 |                             | Alarm: CO6 in manual override or CO6 unable to move | ChangeOver <sup>6</sup> actuator is in manual override or is unable to reach position. | 0: OFF  | Bit 4: 0:OFF; 1:ON   | No                                   |  |                                 |   |   |   |                           |  |        |  |   |   |                     |                     |    |
|                    |                |                 |                             | Alarm: CO6 actuator not connected or damaged        | The ChangeOver actuator is not connected or is damaged.                                | 0: OFF  | Bit 5: 0:OFF; 1:ON   | No                                   |  |                                 |   |   |   |                           |  |        |  |   |   |                     |                     |    |
|                    |                |                 | LONG                        | LONG  | Alarm: Temp. sensors are missing or misconnected                                       | Temp. sensors are missing or misconnected               | 0: OFF               | Bit 6: 0: OFF; 1:ON                  | No   |                                 |   |   |   |                           |  |        |  |   |   |                     |                     |    |
|                    |                |                 |                             |   | LONG   | LONG  | LONG                 | LONG                                 | LONG   |                                 |   | LONG  | LONG  |                           |  |        |  | Warning: Temperature of the actuator is out of recommended range  | The Temperature inside the Actuator is out of the recommended range | 0: OFF              | Bit 16: 0:OFF; 1:ON | No |
| 0x8300<br>33536    | R              | 3&4             |                             |   |  |   |                      |                                      |  |                                 |   |   |   | Warning: Pre-set Conflict | Warning: Conflict between the Mechanical AB-QM valve setting and the NovoCon® 5. The mechanical valve setting must be 100% or above. The warning will also be activated if the Selected Valve Type has different stroke than the actually valve used.  Validated during calibration. | 0: OFF | Bit 17: 0: OFF; 1:ON                         | No  |   |                     |                     |    |
|                    |                |                 |                             |   |  |   |                      |                                      |  |                                 |   |   |   |                           |  |        | Warning: Voltage of power supply is too high | Voltage of power supply is measured to be too high. When the measured voltage exceeds 43.4V the alarm will be turned ON for too high voltage. When the measured voltage is below 38.3V the alarm will be turned OFF | 0: OFF  | Bit 18: 0:OFF; 1:ON | No                  |    |
|                    |                |                 |                             |   |  |   |                      |                                      |  |                                 |   | Warning: Voltage of power supply is too low | Voltage of power supply is measured to be too low. When the measured voltage level drops below 16.5V the alarm will be activated for too low voltage. When the measured voltage level drops below 16.1V the motor will also be turned off. When the measured voltage is once more above 17.5V the motor will be activated | 0: OFF                    | Bit 19: 0:OFF; 1:ON  | No     |  |   |   |                     |                     |    |
|                    |                |                 |                             |   | Warning: Faults on communication was detected  | Problems with Communication on the network are detected | 0: OFF               | Bit 21: 0:OFF; 1:ON                  | No   |                                 |   |   |   |                           |  |        |  |   |   |                     |                     |    |
|                    |                |                 |                             | Warning: Invalid Slave ID setting                   | Slave ID assignment was done incorrectly to either 0 or 127                            | 0: OFF  | Bit 22: 0:OFF; 1:ON  | No                                   |  |                                 |   |   |   |                           |  |        |  |   |   |                     |                     |    |
|                    |                |                 |                             |   |  |   |                      | Warning: Energy limitation is active | Limitation is active. E.g. Power limitation, min. delta T or min/max return T management limitation. | 0: OFF                          | Bit 23: 0: OFF; 1:ON  | No  |   |                           |  |        |  |   |   |                     |                     |    |
|                    |                |                 |                             | Warning: Energy management controller out of range  | Power, delta T or return T setpoint out of range or the setpoint can't be achieved.    | 0: OFF  | Bit 24: 0: OFF; 1:ON | No                                   |  |                                 |   |   |   |                           |  |        |  |   |   |                     |                     |    |

## Firmware update

## Manual update

## Using BACnet MS/TP

| Ident  | Object /<br>Parameter name | Read/Write | State Text  | Default State | Description   |
|--------|----------------------------|------------|---|---------------|---|
| MSV:19 | Firmware update            | R/W        | 1: Normal<br>2: Prepare<br>3: Ready<br>4: Error<br>5: Received<br>6: Update | 1: Normal     | Commands & status for firmware update. Method used to update the firmware: • Send 'Prepare' command to MSV:19. NovoCon * S will prepare for the firmware update and change status to 'Ready'. • Send file to FIL:0. If successful, status should be 'Received'. • Send 'Update' command. NovoCon * S will reboot and update the firmware. The status should be 'Normal' after a successful firmware update. |

| Ide | ent | Object /<br>Parameter name | Read/Write | State Text                             | Default State | Description                                       |
|-----|-----|----------------------------|------------|--|---------------|---|
| FIL | L:0 | File                       | W          | File used to<br>update the<br>firmware | na            | Used to transfer the new firmware to NovoCon * S. |

## Using Modbus RTU

| Modbus<br>register | Read/<br>Write | Modbus<br>function | Modbus<br>Data Type | Object /<br>Parameter<br>name | Description   | Default   | Description of usage  |
|--------------------|----------------|--------------------|---------------------|-------------------------------|---|-----------|---|
| 0x8501<br>34049    | R/W            | 3,4&6              | WORD                | Firmware<br>update            | 1: Normal<br>2: Prepare<br>3: Ready<br>4: Error<br>5: Received<br>6: Update | 1: Normal | Commands & status for Firmware update. Method used to update the Firmware: - Send 'Prepare' command to 34049. NovoCon ® S will prepare for the firmware update and change status to 'Ready' Send file using Modbus function 21. If successful, status should be 'Received' Send 'Update' command. NovoCon ® S will reboot and update the software. The status should be 'Normal' after a successful software update |

When using modbus function 21 (0x15) to update the firmvare in NovoCon® S it is nessecasy to perform the upload in smaller sections due to modbus limitations in file size, please see the modbus standard for more details.

Broadcast, update multiple NovoCon® S by sending the firmware to Slave Id 0, is supported in modbus. However each NovoCon® S must be Prepared before the firmware upload is performed.

## **Danfoss NovoCon® Configuration tool**

Easy configuration, commissioning and firmware updates can be performed with the Danfoss configuration tool. Please see separate operating manual.





#### **Temperature sensors**

#### **Functional description**

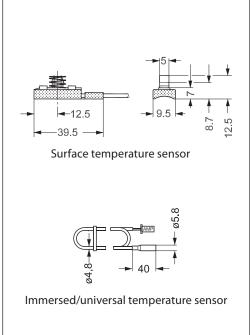
The sensor unit consists of a platinum element, the resistance value of wich, changes proportionally with the temperature.

Pt 1000 ohm sensor (1000 ohm at 0°C). The sensor is adjusted and meets the tolerance requirements of EN 60751 Class B.

The accuracy of temperature measurement is approximately 0.5° in typical operating range. It is unlikely, that during calculation of  $\Delta T$ , deviation of both sensors would be summed up. Therefore, it is estimated that ΔT measurement accuracy is 0.5° when the sensors are mounted correctly.

It is not recommended to use longer wires on temperature sensors than 2m due to risk of electromagnetic interference. If long or thin wires are used it may be necessary to make an offset of the temperature reading in the BMS system.

| R (Typ.)<br>Ohm | Temp.<br>°C | Temp.<br>°F | Tolerance.<br>°C |
|-----------------|-------------|-------------|------------------|
| 1117            | 30          | 86          | 0.45             |
| 1078            | 20          | 68          | 0.40             |
| 1039            | 10          | 50          | 0.35             |
| 1000            | 0           | 32          | 0.30             |
| 961             | -10         | 14          | 0.35             |
| 922             | -20         | -4          | 0.40             |
| 882             | -30         | -22         | 0.45             |



#### **Tender text**

#### NovoCon® S actuator

Modulating geared actuator with field bus (BACnet MS/TP and Modbus RTU) connectivity used to control pressure independent balancing and control valves DN10-32.

Control signal: BACnet MS/TP, Modbus RTU, 0-10V/2-10V, 0-20/4-20mA

Direct connection to 6-port ball valve actuator with position feedback signal 1)

Direct connection to 2x PT1000 surface/immersed sensors and emission power indication

Direct connection I/O: 2x resistance, AO and AI 3)

Actuator functionality is remotely accessible via the field bus:

- Design flow pre-setting
- Flushing the valve and terminal unit
- Error during closing intrinsic alarm reporting
- Alarm if CO6 6-port ball valve actuator is blocked, in manual override or disconnected 1)
- Supply and return temperature readings, emission power indication <sup>2)</sup>
- Energy counter (kWh, MJ, kBTU) 2)
- Alarm high/low deltaT and temperature sensors disconnected 2)
- Alpha characteristics setting
- Speed selection 3/6/12/24 s/mm
- Opening/closing time selection from 18s to 700s
- Auto MAC addressing (BACnet only)
- Auto Baud rate detection
- Flow indication based on measured stroke in I/h

Eu.bac interchangeability approved in combination with PIBCV valve

Supply Voltage: 24V DC/AC 50/60Hz Spindle position accuracy: ±0.05mm

Cables: Halogen free plug-in available in 1.5m, 5m and 10m length

Temperature sensors: plug-in 2x PT1000 surface or immersed 1.5m length

64 actuators can be connected to the same network

IP Class: 54 Stroke: 7mm

BACnet Testing Laboratories (BTL) listed BACnet MS/TP fieldbus device 4)

Manual override function

Configuration tool available easy configuration, commissioning and firmware updates Commissioning tool available for addressing, parametrization and hydronic continuous commission

- 1) CO6 application
- <sup>2)</sup> Energy application
- 3) Remote I/O application
- 4) Certification in progress



## **Trouble shooting**

#### **BACnet Fieldbus check:**

It is possible to check the fieldbus state by examining error messaging related to the actuator in order to verify communication and detect early potential fieldbus related problems. This is done by the object values AV:15 to AV:19.

## **Quality of the BACnet network:**

An important thing for good operation of the actuator is a well functioning network. Some values that tell you about the quality of the network can be found in the objects AV:15 to AV:19. The most important values are AV:17 Server Error Count and AV:19 Server Timeout Error. These two values should be much lower than AV:15, AV:16 and AV:18. As a general rule, it is important that AV:17 and AV:19 are not constantly increasing their count.

#### Quality of power supply:

The object / register AV:6 / 33794 may be used to check if the power supply and cabling, used to supply the actuator with power, is according to specification requirements. The present value of AV:6 / 33794 represents the current voltage measured inside the actuator. This is the voltage that the actuator monitors at all times and subsequently reacts on if outside the recommended range. See in the table below how the actuator reacts at different voltage levels.

| Voltage (Present value of AV:6 / 33794 | Reaction  |
|--|---|
| Voltage below 16.5V                    | Start alarm indication with LED. Initiate and alarm BV: 15 / 33536 Bit 19 and that the supply voltage is too low.                           |
| Voltage below 16.1V                    | Motor is stopped. The LEDs indicating alarm and actuator still initiating alarm BV:15 / 33535 Bit 19 if the voltage hasn't dropped too low. |
| When voltage rises above 17.5V again   | Motor can run again. LED alarm indication stops and returns to normal operation.<br>Alarm BV:15 / 33536 Bit 19 returns to normal operation. |
| When voltage rises above 43.4V         | Start alarm indication with LED. Initiate an alarm BV:14 / 33536 Bit 18.  |
| When voltage drops below 38.3V again   | LED alarm indication stops and returns to normal operation. Alarm BV:14 / 33536 Bit 18 returns to normal operation.                         |

**NB:** the voltage level will be constantly changing depending on the operational activity of the entire group of actuators and other devices connected. The supply voltage will go up and down in value if:

- Power supply is not strong and stable
- If long cables are used in a daisy chain setup

A higher number of actuators running at the same time will reduce the supply voltage (for the last devices on a daisy chain cable, in particular).

The actuator's voltages are considered to be OK when all values of AV:6 / 33794 are above 18V, when all actuators are moving the motor/running. To ensure voltage in each device is OK under worst case operational conditions, the following is recommended:

- Run all the actuators on the daisy chain cable at the same time. While all are running, check each value of AV:6 / 32794. These values should still be above 18V and no previously mentioned voltage level alarms should be initiated or indicated. If LEDs indicate an alarm state or a BACnet/Modbus alarm is initiated, or a value less than 18V is observed, then cabling should be reviewed.
- Check the values of AVO:0. This BACnet object holds 3 values: Average measured voltage,
   Maximum measured voltage and Minimum measured voltage. The most important value here is
   the Minimum measured voltage. It can tell you the lowest voltage that has been measured during
   operation of the actuator.





Data sheet NovoCon® S

#### Danfoss A/S

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