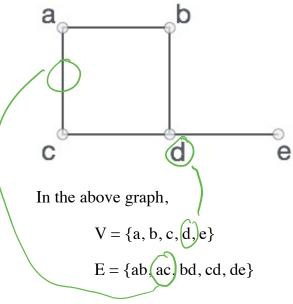
Data Structure - Graph Data Structure

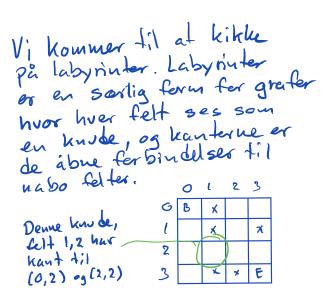
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A graph is a pictorial representation of a set of objects where some pairs of objects are connected by links. The interconnected objects are represented by points termed as vertices, and the links that connect the vertices are called edges.

Dansk: Kuyler

Formally, a graph is a pair of sets V, E, where V is the set of vertices and E is the set of edges, connecting the pairs of vertices. Take a look at the following graph –



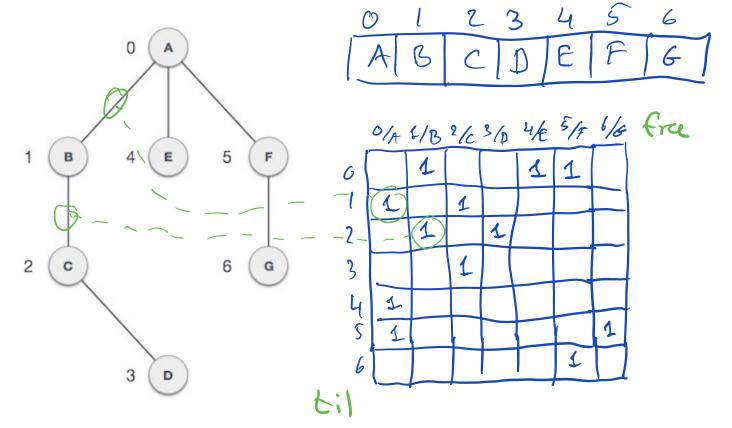


Graph Data Structure

Mathematical graphs can be represented in data structure. We can represent a graph using an array of vertices and a two-dimensional array of edges. Before we proceed further, let's familiarize ourselves with some important terms –

- **Vertex** Each node of the graph is represented as a vertex. In the following example, the labeled circle represents vertices. Thus, A to G are vertices. We can represent them using an array as shown in the following image. Here A can be identified by index 0. B can be identified using index 1 and so on.
- Edge Edge represents a path between two vertices or a line between two vertices. In the following example, the lines from A to B, B to C, and so on represents edges. We can use a two-dimensional array to represent an array as shown in the following image. Here AB can be represented as 1 at row 0, column 1, BC as 1 at row 1, column 2 and so on, keeping other combinations as 0.
- Adjacency Two node or vertices are adjacent if they are connected to each other through an edge. In the following example, B is adjacent to A, C is adjacent to B, and so on.
- Path Path represents a sequence of edges between the two vertices. In the following example, ABCD represents a path from A to D.

De tegninger der er har ihr retning på hanture så A er forbundlt fil B, men husk at B også er forbundet til



Basic Operations

Following are basic primary operations of a Graph –

• **Display Vertex** – Displays a vertex of the graph.

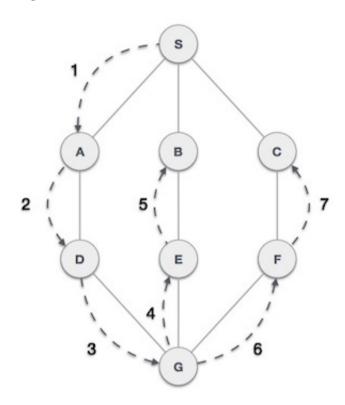
Illowing are basic primary operations of a Graph – Her Kover de put
 Add Vertex – Adds a vertex to the graph.
 Add Edge – Adds an edge between the two vertices of the graph.
 Display Vertex – Display

To know more about Graph, please read Graph Theory Tutorial. We shall learn about traversing a graph in the coming chapters.

Data Structure - Depth First Traversal

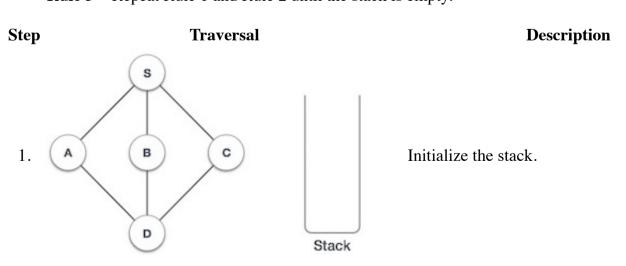
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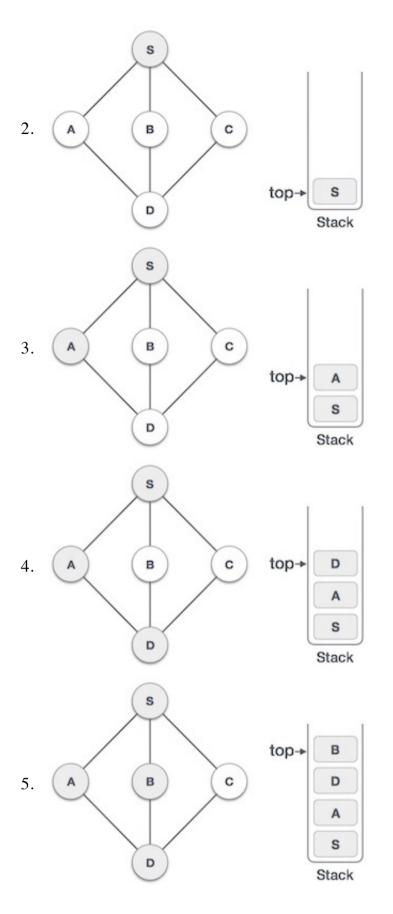
Depth First Search *DFS* algorithm traverses a graph in a depthward motion and uses a stack to remember to get the next vertex to start a search, when a dead end occurs in any iteration.



As in the example given above, DFS algorithm traverses from A to B to C to D first then to E, then to F and lastly to G. It employs the following rules.

- Rule 1 Visit the adjacent unvisited vertex. Mark it as visited. Display it. Push it in a stack.
- **Rule 2** If no adjacent vertex is found, pop up a vertex from the stack. *Itwillpopupallthevertices from the stack, which do not have adjacent vertices.*
- Rule 3 Repeat Rule 1 and Rule 2 until the stack is empty.





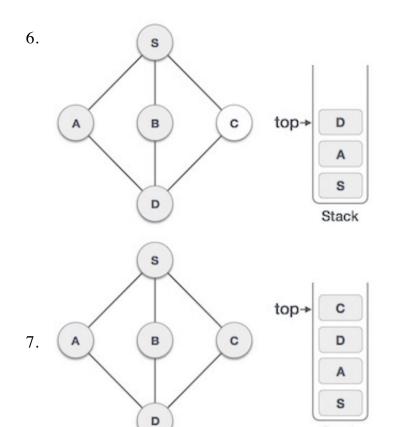
Mark S as visited and put it onto the stack. Explore any unvisited adjacent node from S. We have three nodes and we can pick any of them. For this example, we shall take the node in an alphabetical order.

Mark **A** as visited and put it onto the stack. Explore any unvisited adjacent node from A. Both **S** and **D** are adjacent to **A** but we are concerned for unvisited nodes only.

Visit **D** and mark it as visited and put onto the stack. Here, we have **B** and **C** nodes, which are adjacent to **D** and both are unvisited. However, we shall again choose in an alphabetical order.

Huis vi var ude på blot at finde en vei fra Stil D, så bemærk at den sti vi skal bruge er på stakken

We choose **B**, mark it as visited and put onto the stack. Here **B** does not have any unvisited adjacent node. So, we pop **B** from the stack.



previous node and check if it has any unvisited nodes. Here, we find $\bf D$ to be on the top of the stack.

Only unvisited adjacent node is from **D** is **C** now. So we visit **C**, mark it as visited and put it onto the stack.

As C does not have any unvisited adjacent node so we keep popping the stack until we find a node that has an unvisited adjacent node. In this case, there's none and we keep popping until the stack is empty.

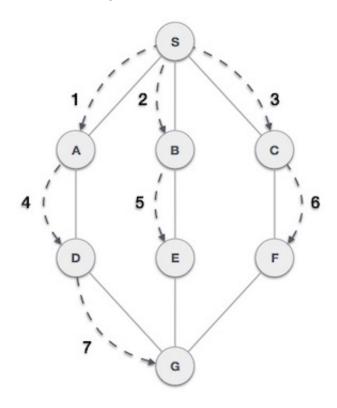
To know about the implementation of this algorithm in C programming language, click here.

Stack

Data Structure - Breadth First Traversal

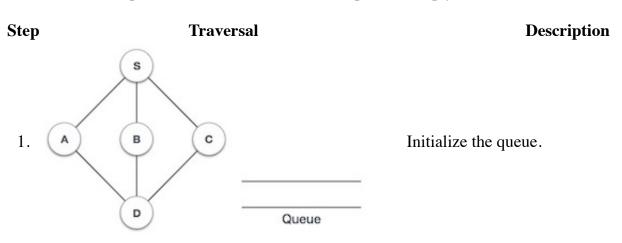
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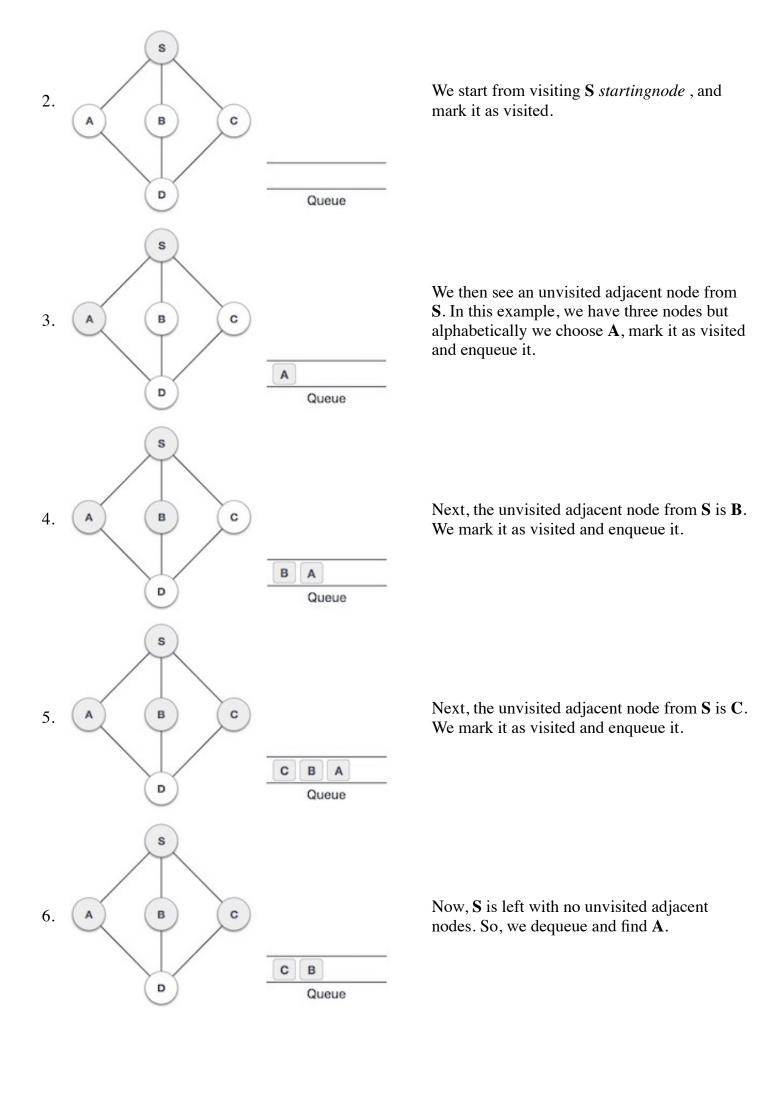
Breadth First Search *BFS* algorithm traverses a graph in a breadthward motion and uses a queue to remember to get the next vertex to start a search, when a dead end occurs in any iteration.

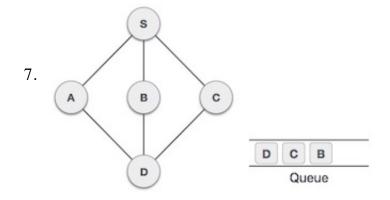


As in the example given above, BFS algorithm traverses from A to B to E to F first then to C and G lastly to D. It employs the following rules.

- Rule 1 Visit the adjacent unvisited vertex. Mark it as visited. Display it. Insert it in a queue.
- Rule 2 If no adjacent vertex is found, remove the first vertex from the queue.
- Rule 3 Repeat Rule 1 and Rule 2 until the queue is empty.







From **A** we have **D** as unvisited adjacent node. We mark it as visited and enqueue it.

At this stage, we are left with no unmarked *unvisited* nodes. But as per the algorithm we keep on dequeuing in order to get all unvisited nodes. When the queue gets emptied, the program is over.

The implementation of this algorithm in C programming language can be seen here.