Deep Learning Part 3

Yin Li

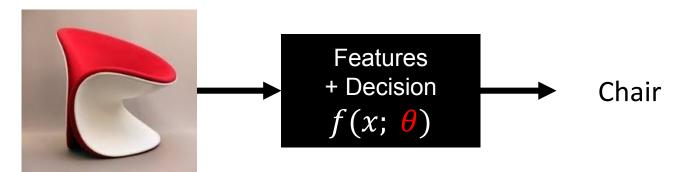
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[Some of the slides from Lana Lazebnik, Kaiming He and others]

Deep Learning = Deep Neural Networks

 Deep Learning: Composing a set of (nonlinear) functions g

$$f(\boldsymbol{x};\boldsymbol{\theta}) = g_1(\dots g_{n-1}(g_n(\boldsymbol{x};\boldsymbol{\theta}_n),\boldsymbol{\theta}_{n-1})\dots,\boldsymbol{\theta}_1)$$

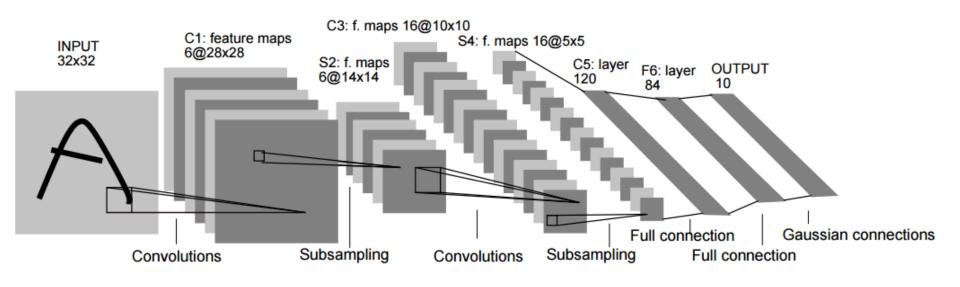


- Each of the function g is represented using a layer of a neural network
- Key element: Linear operations + Nonlinear activations, e.g., $\mathbf{a} = \sigma(\mathbf{W}^T \mathbf{x} + \mathbf{b})$

What we have talked about so far

- The linear functions
 - Fully connected layer: dense W
 - Convolutional layer: sparse and structured W
- The nonlinear activations
 - Sigmoid
 - Rectified linear unit (ReLU)
 - Many others …
- Pooling
- Output normalization
- Loss functions

Case study: LeNet-5 (1998)



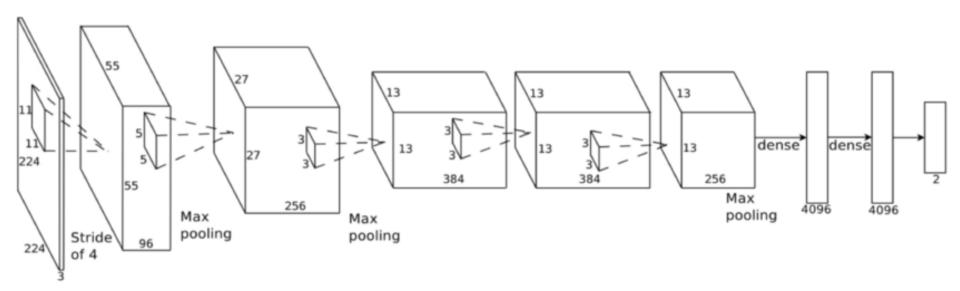
- convolutional layers + fully connected layers
- Sigmoid as the activation function
- [Conv + sigmoid + average pooling] x 2 + fully connected x 3

Figure from *Gradient-based learning applied to document recognition,* by Y. LeCun, L. Bottou, Y. Bengio and P. Haffner

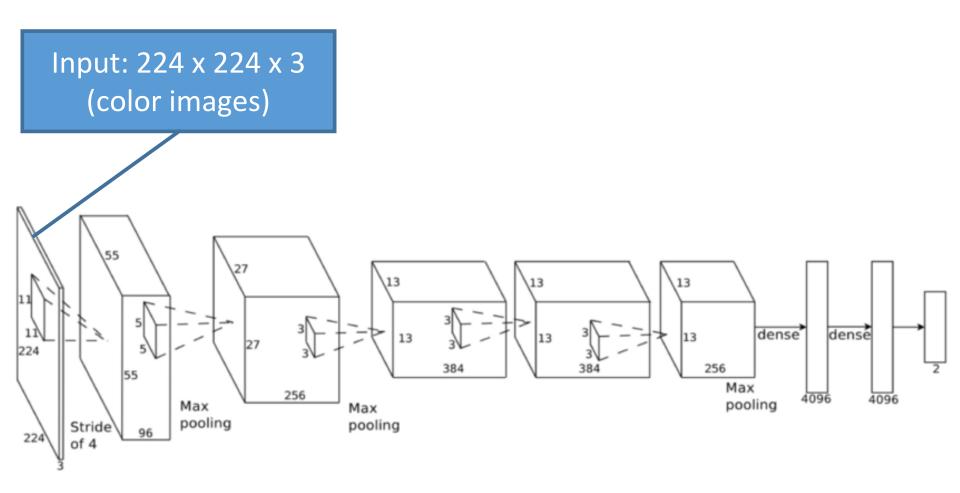
ImageNet challenge (2010-2017)

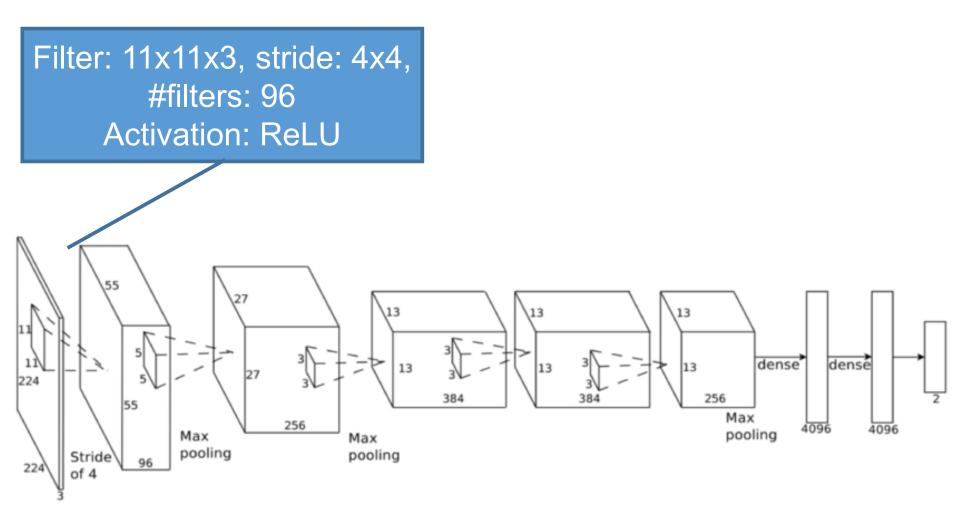


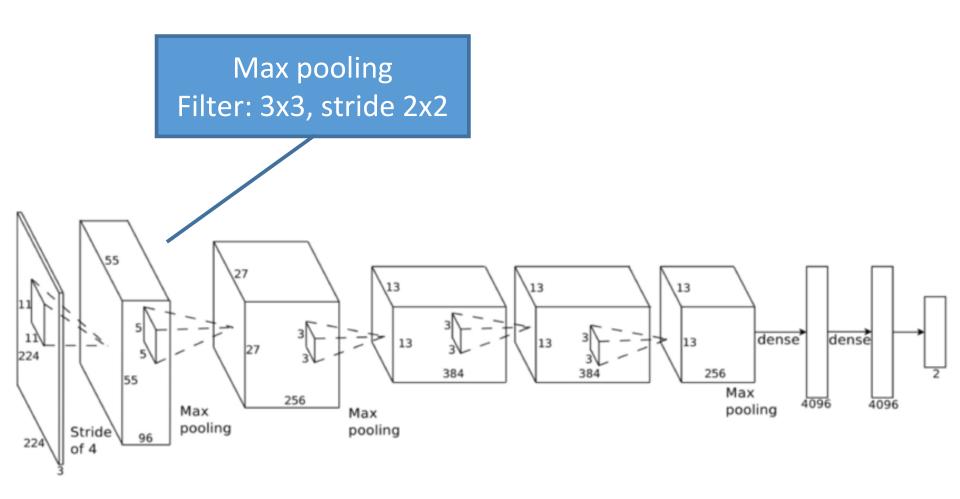
- ~14 million labeled images, 20K classes
- Images gathered from Internet
- Labels provided by humans
- ImageNet Large-Scale Visual Recognition Challenge (ILSVRC):
 - 1.2 million training images, 1000 classes



- A modern deep neural network
- Winner of ImageNet challenge 2012
- +10% better than everything else in 2012!







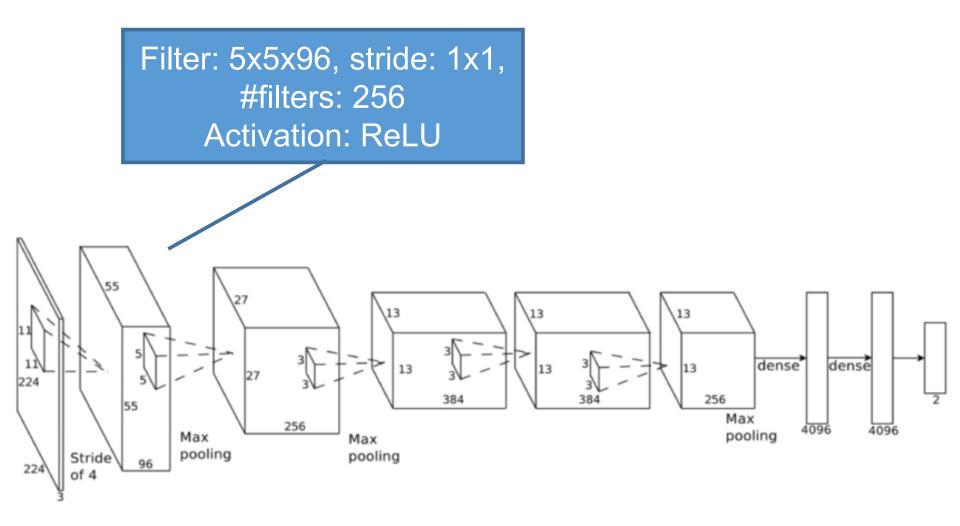


Figure from ImageNet Classification with Deep Convolutional Neural Networks, by A. Krizhevsky, I. Sutskever, and G. Hinton

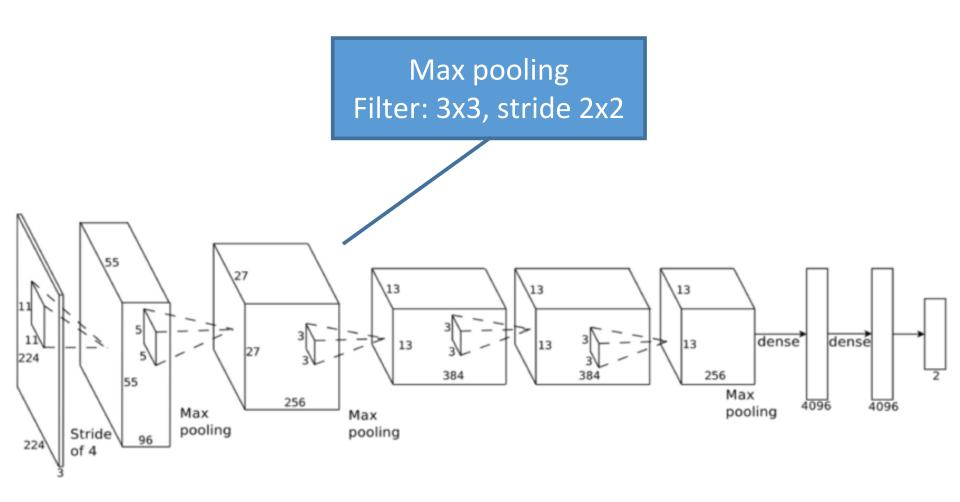
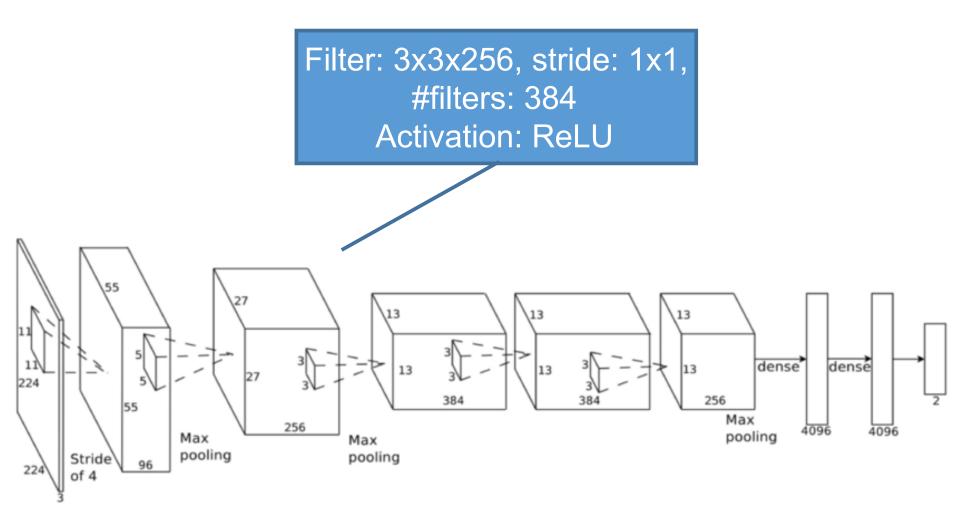
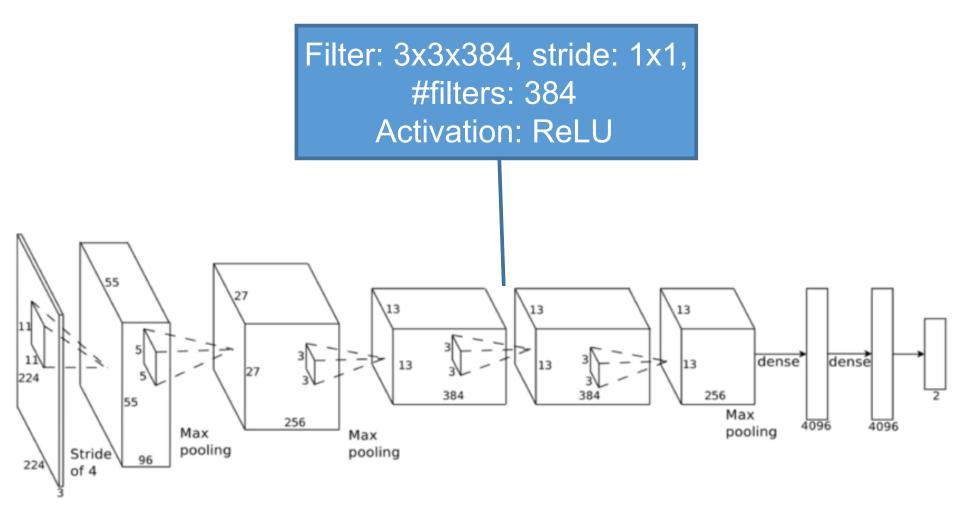
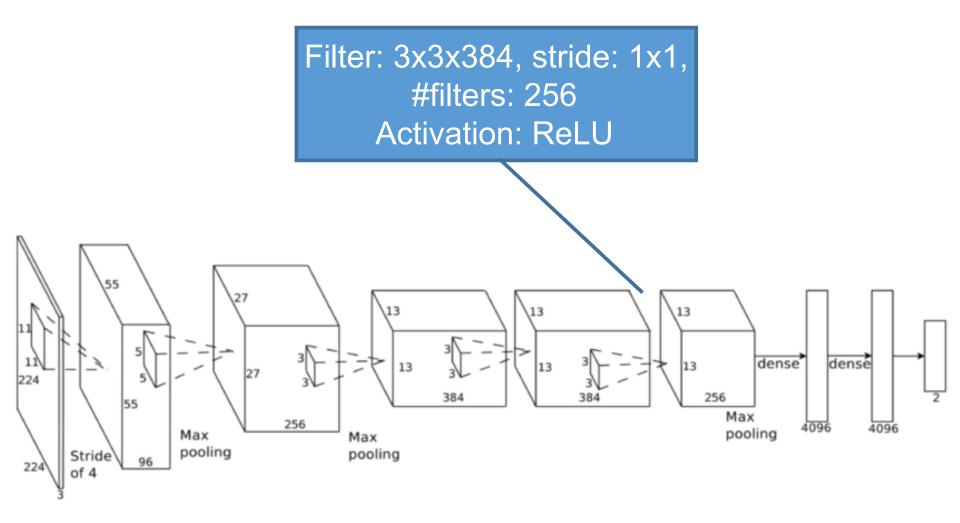


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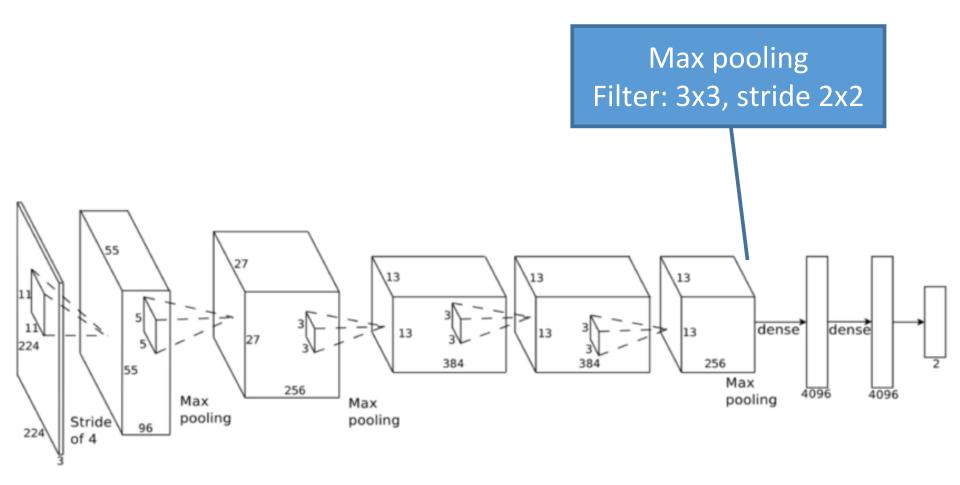


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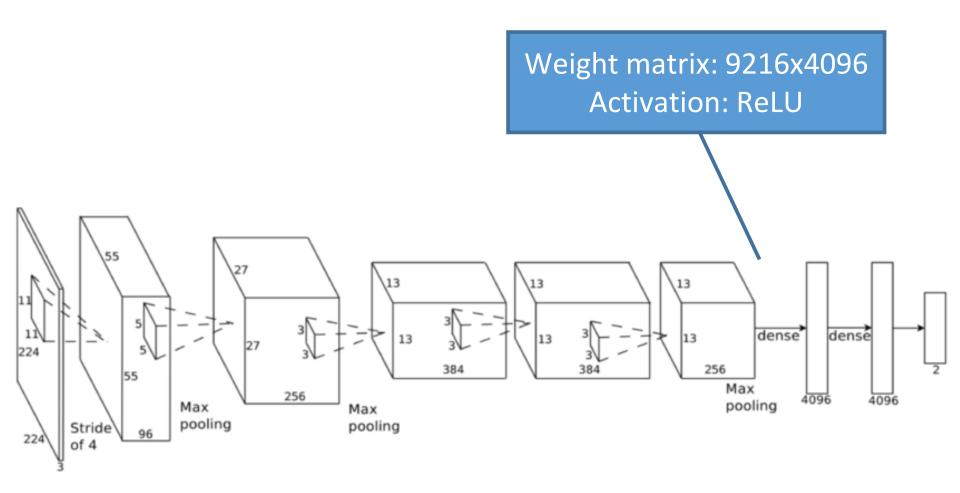


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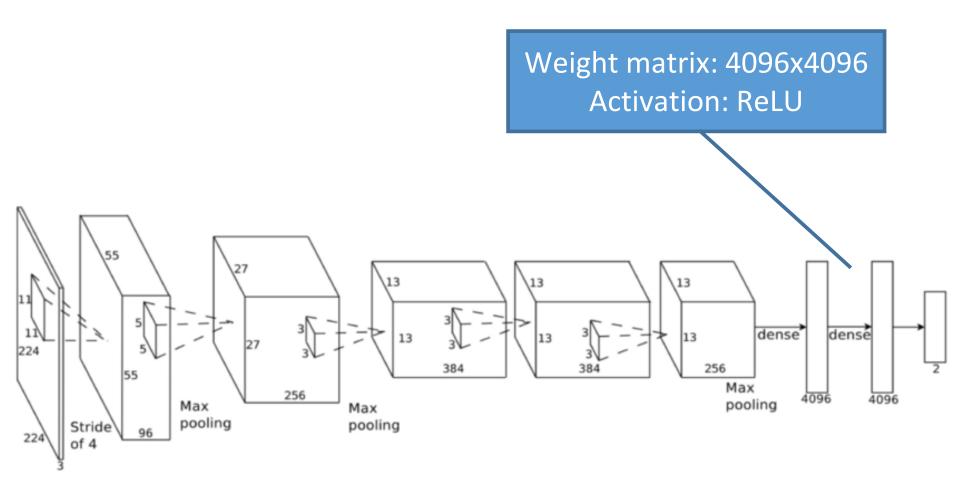


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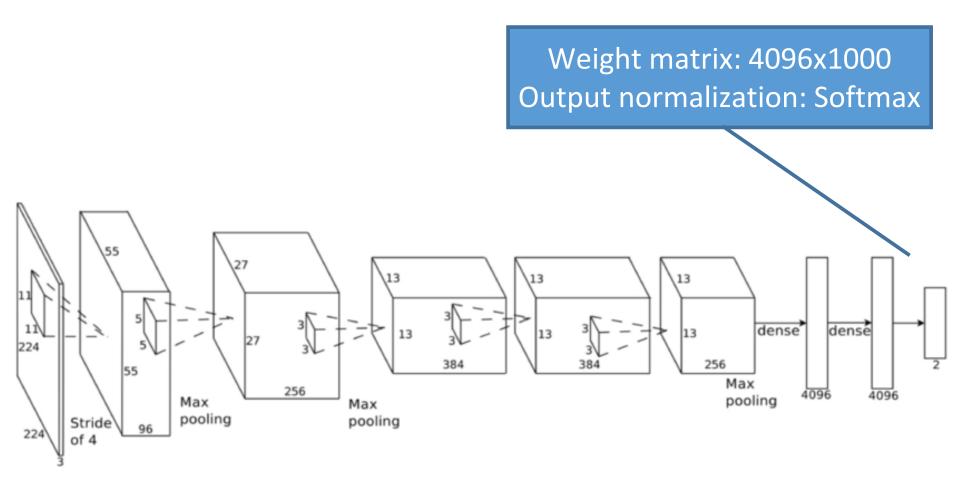
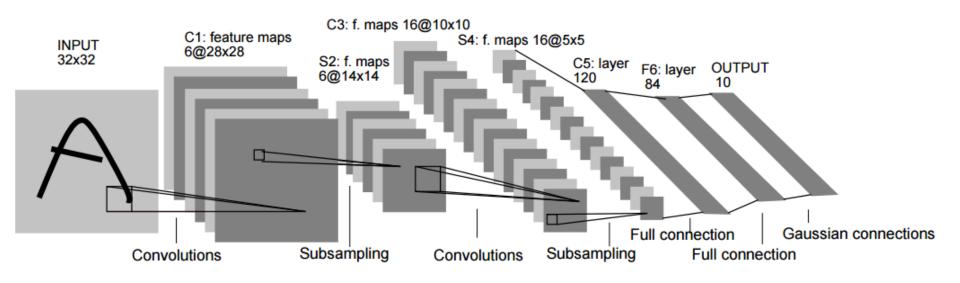


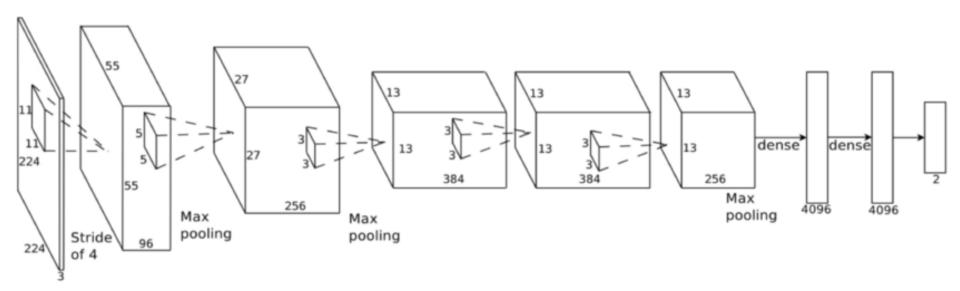
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Case study: LeNet-5 (1998)



- convolutional layers + fully connected layers
- Sigmoid as the activation function
- [Conv + sigmoid + average pooling] x 2 + fully connected x 3
- Trained on MNIST with 60K training samples

Figure from *Gradient-based learning applied to document recognition,* by Y. LeCun, L. Bottou, Y. Bengio and P. Haffner



- convolutional layers + fully connected layers
- ReLU as the activation function
- [Conv + ReLU + max pooling] x 5 + fully connected x 3
- Most importantly: 1.2 millions of training images!

Deep convolutional networks: basic design

- [Conv + ReLU] + Pooling
- A few fully connected (FC) layers at the end
- Output normalization + Loss function
- Training: mini-batch stochastic gradient descent
- Inference: use the (normalized) outputs

- What makes deep learning work?
 - A modern design of neural network architectures
 - Large scale training dataset
 - A lot of computing power (GPUs)
- Why does deep learning work so well?
 - Still a mystery to a large extent
 - Intuitively, a deep neural network builds a hierarchical representation of data

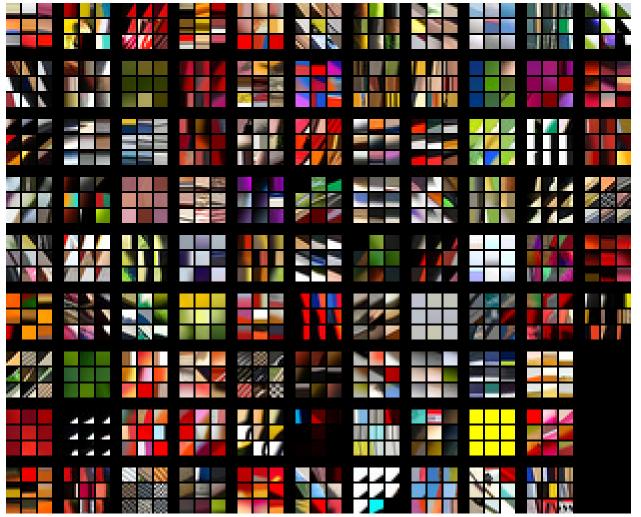
Layer 1 Filters



Figures from Visualizing and Understanding Convolutional Networks by *M. Zeiler and R. Fergus*

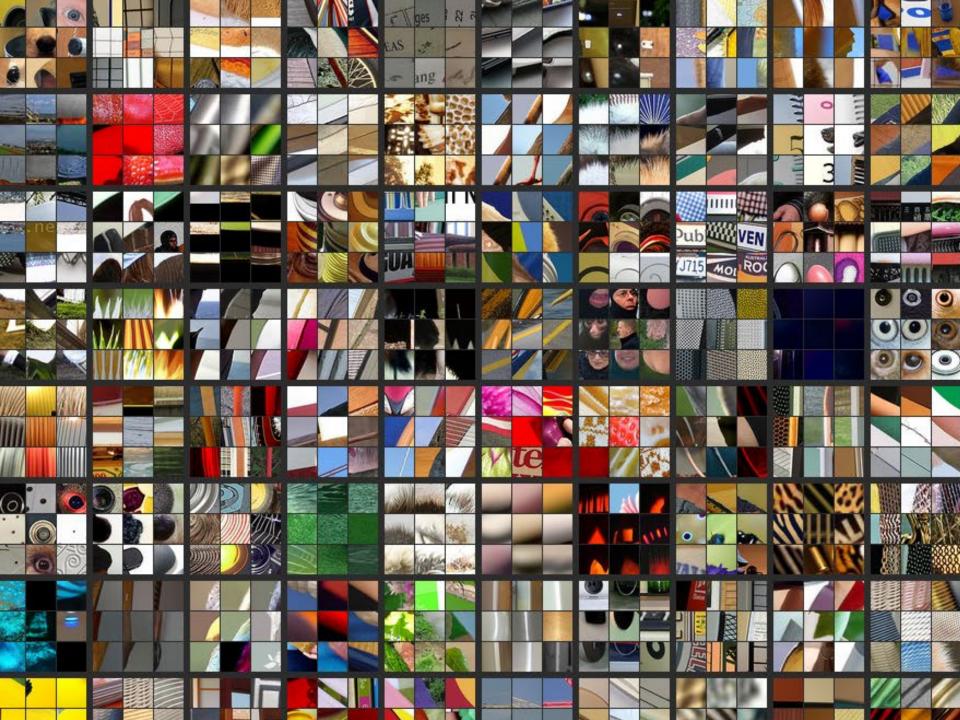
Layer 1: Top-9 Patches

 Select patches on the validation set with maximum activation of a given convolutional filter / kernel

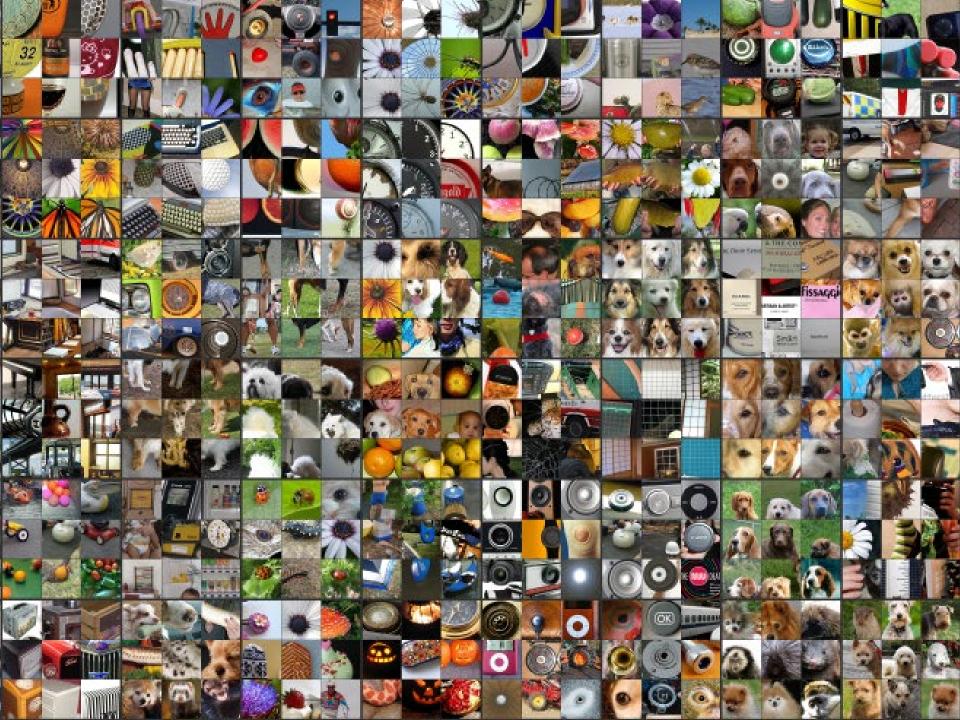


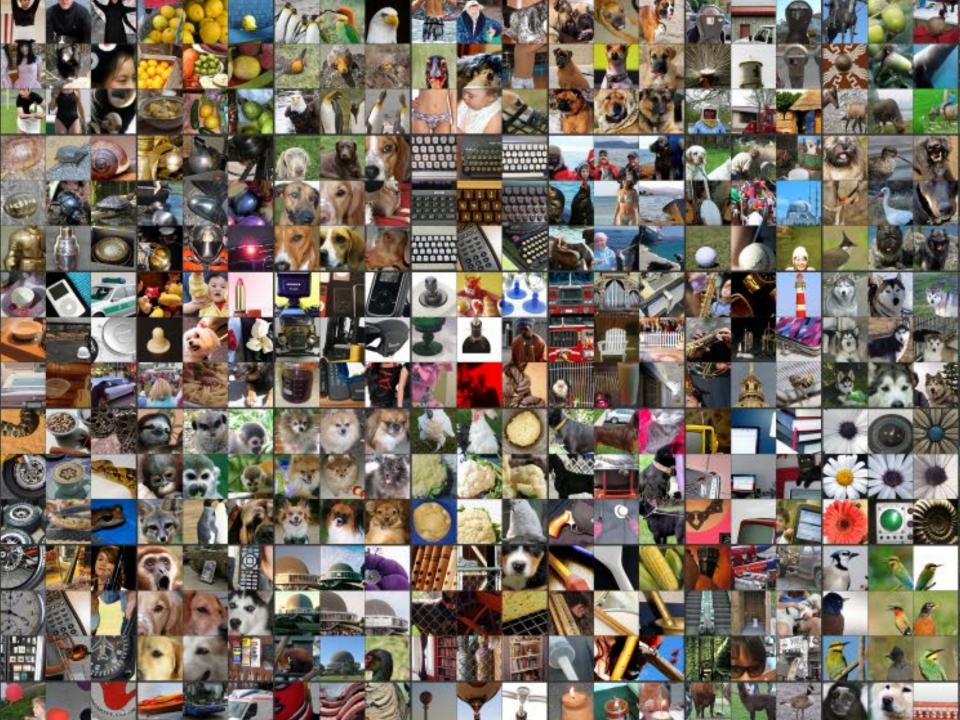


Layer 2 - 5: Top-9 Patches

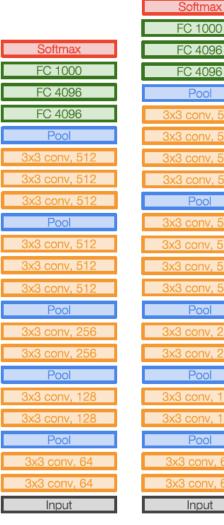


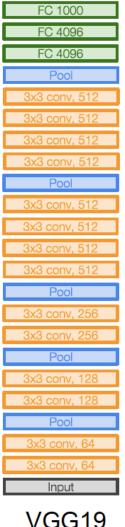






Case study: VGGNet (2014)





- 2nd place in ImageNet challenge 2014
- Make the network deeper
 - AlexNet (5 conv + 3 FC)
 - VGGNet (12/14 conv + 3 FC)
- Use smaller filter / kernel size
 - AlexNet (11x11, 5x5, 3x3)
 - VGGNet (3x3)
- Large receptive fields replaced by successive layers of 3x3 convolutions (with ReLU in between)

Image source

VGG16

Case study: GoogLeNet (2014)

- The Inception Module
 - Parallel paths with different receptive field sizes and operations

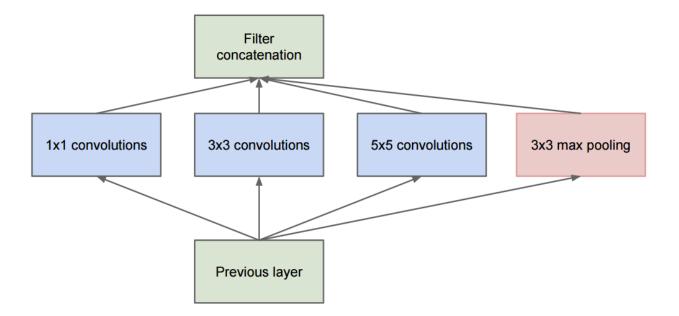


Figure from Going deeper with convolutions by C. Szegedy et al.

Case study: GoogLeNet (2014)

- The Inception Module
 - Parallel paths with different receptive field sizes and operations
 - Use 1x1 convolutions for dimensionality reduction
 before expensive convolutions

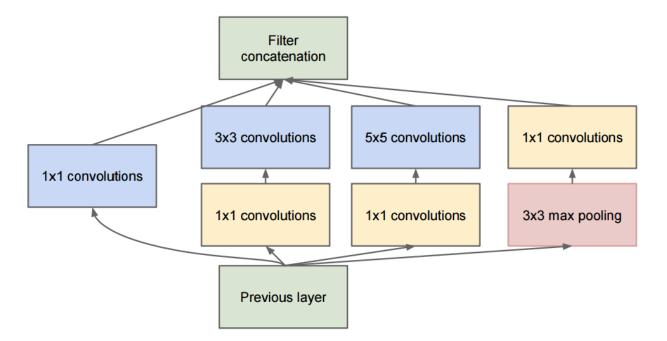
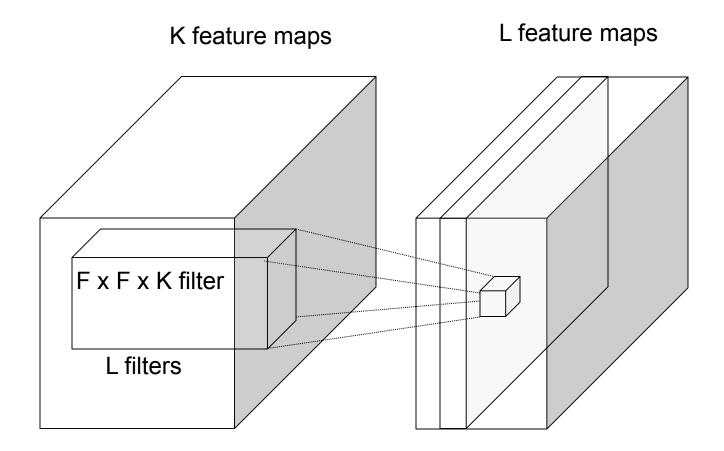


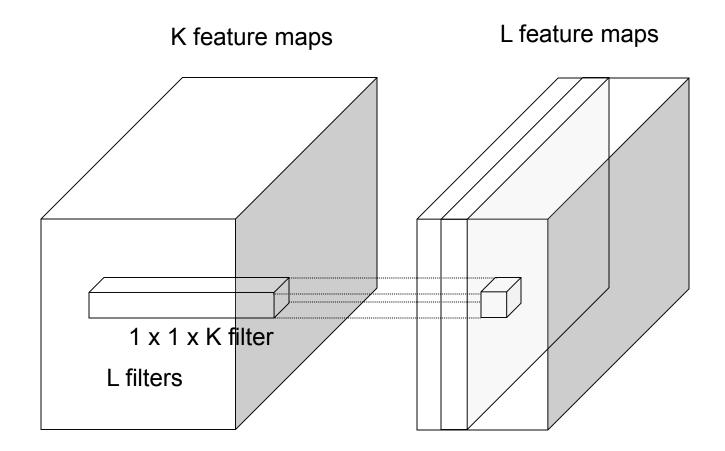
Figure from Going deeper with convolutions by C. Szegedy et al.

FxF convolutions



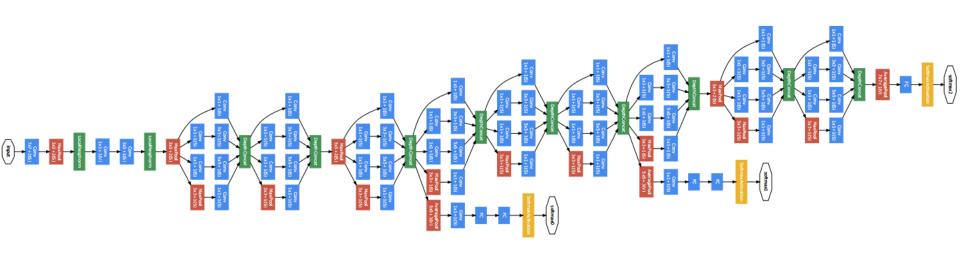
conv layer

1x1 convolutions



1 x 1 conv layer

Case study: GoogLeNet (2014)



Inception module

Figure from Going deeper with convolutions by C. Szegedy et al.

Case study: GoogLeNet (2014)

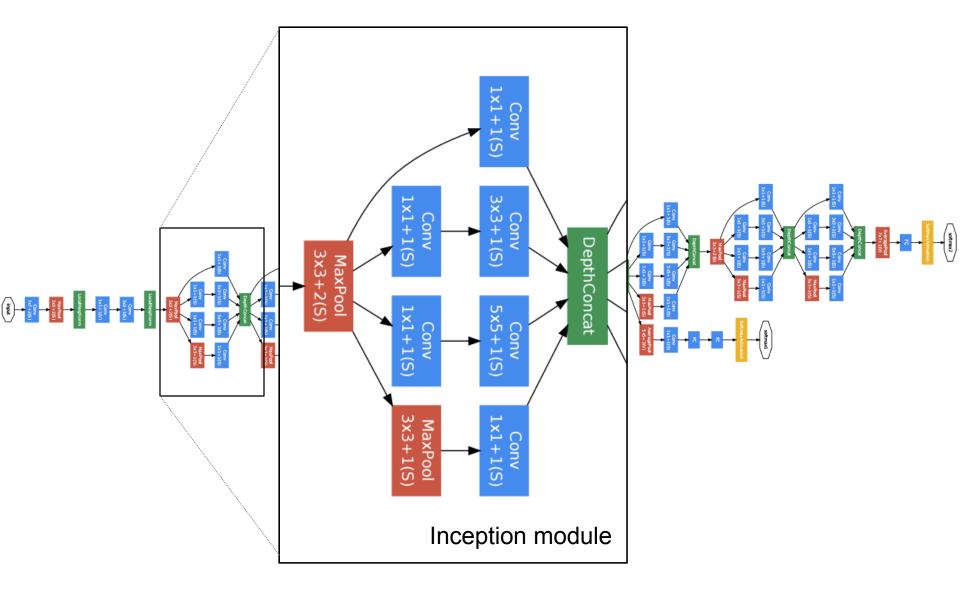


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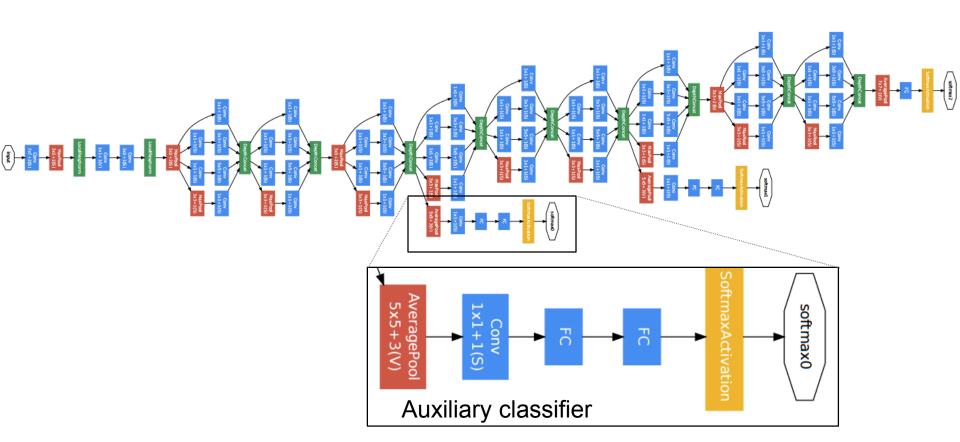


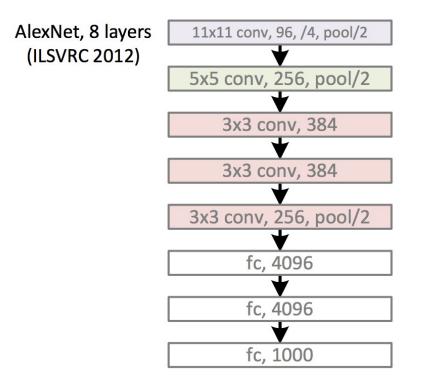
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ImageNet challenge 2012-2014

Team	Year	Place	Error (top-5)	External data
SuperVision – Toronto (8 layers)	2012	-	16.4%	no
SuperVision	2012	1st	15.3%	ImageNet 22k
Clarifai – NYU (7 layers)	2013	-	11.7%	no
Clarifai	2013	1st	11.2%	ImageNet 22k
VGG – Oxford (16/19 layers)	2014	2nd	7.32%	no
GoogLeNet (22 layers)	2014	1st	6.67%	no
Human expert*			5.1%	

http://karpathy.github.io/2014/09/02/what-i-learned-fromcompeting-against-a-convnet-on-imagenet/

Revolution of Depth

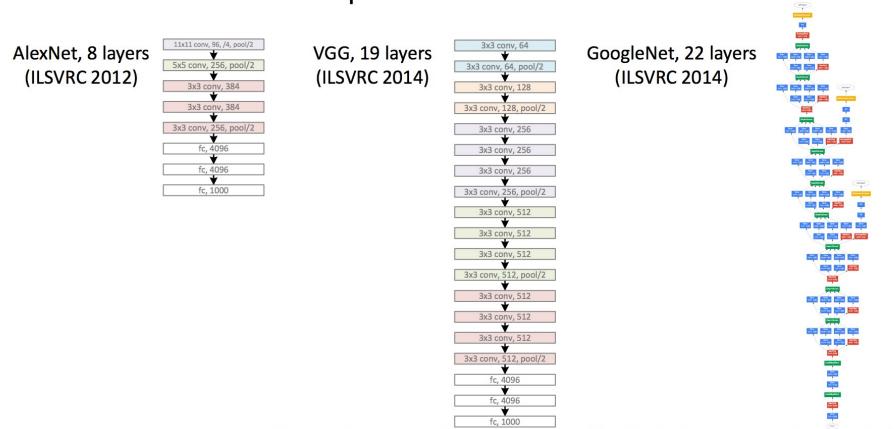


Kaiming He, Xiangyu Zhang, Shaoqing Ren, & Jian Sun. "Deep Residual Learning for Image Recognition". arXiv 2015.

Slide Credit: Kaiming He

slide 39

Revolution of Depth



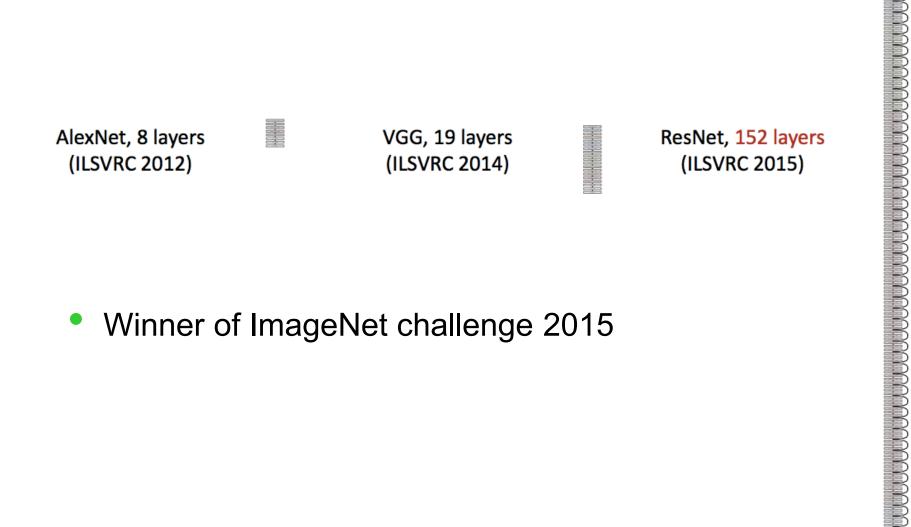
Kaiming He, Xiangyu Zhang, Shaoqing Ren, & Jian Sun. "Deep Residual Learning for Image Recognition". arXiv 2015.

Slide Credit: Kaiming He

AlexNet, 8 layers (ILSVRC 2012) VGG, 19 layers (ILSVRC 2014)

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Slide Credit: Kaiming He



Winner of ImageNet challenge 2015

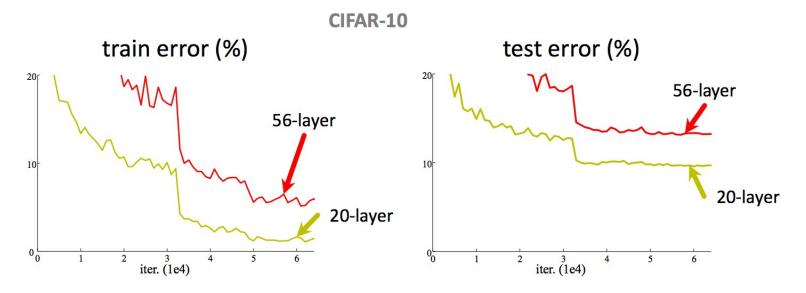
Slide Credit: Kaiming He



Source (?)

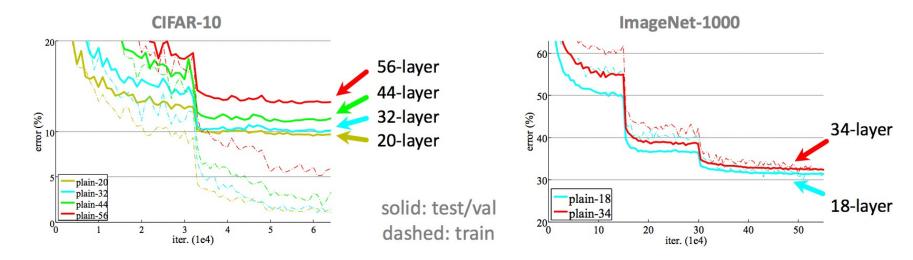
slide 43

Simply stacking layers?

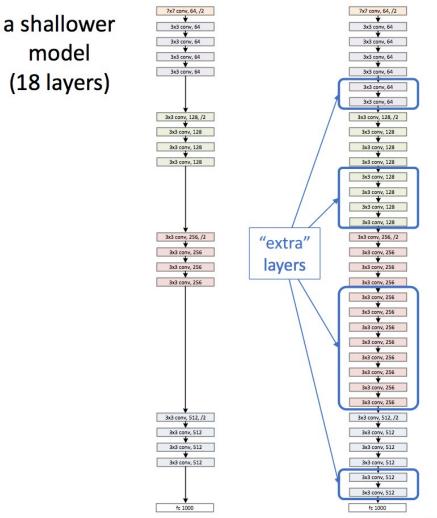


- *Plain* nets: stacking 3x3 conv layers...
- 56-layer net has higher training error and test error than 20-layer net

Simply stacking layers?



- "Overly deep" plain nets have higher training error
- A general phenomenon, observed in many datasets



a deeper counterpart (34 layers)

- A deeper model should not have higher training error
- A solution by construction:
 - original layers: copied from a learned shallower model
 - extra layers: set as identity
 - at least the same training error
- Optimization difficulties: solvers cannot find the solution when going deeper... e.g., Gradient vanishing?

Kaiming He, Xiangyu Zhang, Shaoqing Ren, & Jian Sun. "Deep Residual Learning for Image Recognition". arXiv 2015.

- The residual module
 - Introduce skip or shortcut connections (existing before in various forms in literature)
 - Make it easy for network layers to represent the identity mapping
 - Also produce better gradients during training

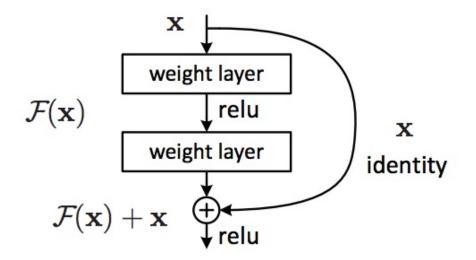


Figure from Deep Residual Learning for Image Recognition by *K. He, X. Zhang, S. Ren, and J. Sun*

Architectures for ImageNet:

layer name	output size	18-layer	34-layer	50-layer	101-layer	152-layer	
conv1	112×112	7×7, 64, stride 2					
		3×3 max pool, stride 2					
conv2_x	56×56	$\left[\begin{array}{c} 3\times3, 64\\ 3\times3, 64 \end{array}\right]\times2$	$\left[\begin{array}{c} 3\times3, 64\\ 3\times3, 64 \end{array}\right]\times3$	[1×1,64]	[1×1,64]	[1×1,64]	
				3×3, 64 ×3	3×3, 64 ×3	3×3, 64 ×3	
				[1×1, 256]	[1×1, 256]	[1×1, 256]	
conv3_x	28×28	$\begin{bmatrix} 3\times3, 128\\ 3\times3, 128 \end{bmatrix} \times 2 \begin{bmatrix} 2\\ 2\\ 3\end{bmatrix}$	[2.42 100]	[1×1, 128]	[1×1, 128]	[1×1, 128]	
			$\begin{vmatrix} 3 \times 3, 120 \\ 2 \times 3, 128 \end{vmatrix} \times 4$	3×3, 128 ×4	3×3, 128 ×4	3×3, 128 ×8	
				[1×1, 512]	[1×1, 512]	[1×1, 512]	
	14×14	$14 \times 14 \begin{bmatrix} 3 \times 3, 256 \\ 3 \times 3, 256 \end{bmatrix} \times 2$	$\begin{bmatrix} 3 \times 3, 256 \\ 2 \times 2, 256 \end{bmatrix} \times 6$	[1×1, 256]	[1×1, 256]	[1×1, 256]	
conv4_x				3×3, 256 ×6	3×3, 256 ×23	3×3, 256 ×36	
		[3×3, 230]		↓ 1×1, 1024	L 1×1, 1024 」	↓ 1×1, 1024	
	7×7	7×7 $\begin{bmatrix} 3\times3,512\\ 3\times3,512 \end{bmatrix} \times 2 \begin{bmatrix} 3\times3,512\\ 3\times3,512 \end{bmatrix} \times 3$		[1×1,512]	[1×1, 512]	[1×1,512]	
conv5_x			$\begin{vmatrix} 3 \times 3, 512 \\ 2 \times 2, 512 \end{vmatrix} \times 3$	3×3, 512 ×3	3×3, 512 ×3	3×3, 512 ×3	
			1×1, 2048	L 1×1, 2048 」	↓ 1×1, 2048		
	1×1	average pool, 1000-d fc, softmax					
FLOPs		1.8×10^9	3.6×10 ⁹	3.8×10^9 7.6×10^9 11.3		11.3×10^9	
				A			

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GoogLeNet (22 layers)	2014	1st	6.67%	no
ResNet (152 layers)	2015	1st	3.57%	
Human expert*			5.1%	

http://karpathy.github.io/2014/09/02/what-i-learned-from-competing-against-a-convnet-on-imagenet/

Summary: Deep Convolutional Networks

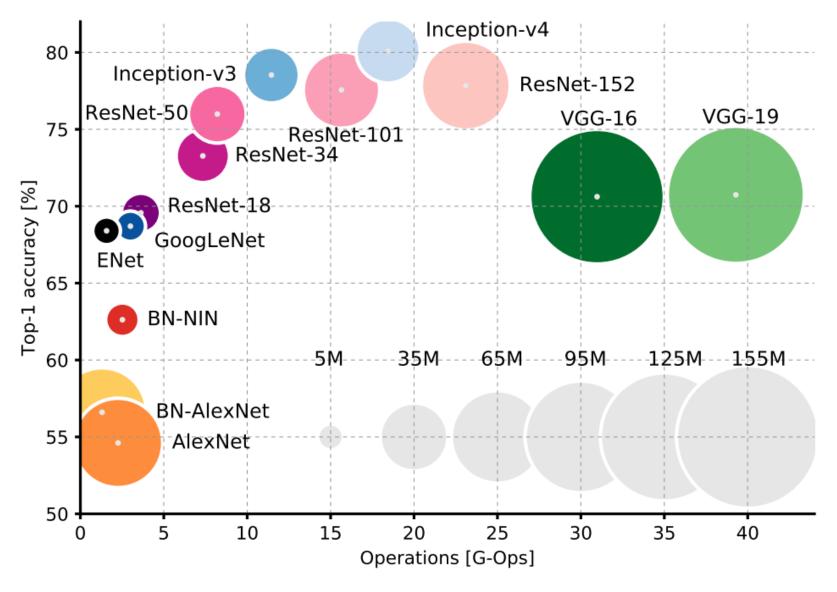


Figure from An Analysis of Deep Neural Network Models for Practical Applications by A. Canziani, A. Paszke, E. Culurciello