RE Industrial Electronic Actuator General Specifications

All industrial electric/electronic actuators used for valve applications and air damper control shall incorporate adjustable current limiting as a means of protecting the actuator from over-torque situations. Actuators shall be available from 150 in-lbs to 10,200 in-lbs with these features.

Voltage Offering

All actuators must be capable of accepting 24 VAC or VDC power and 120 or 220 VAC with the addition of a transformer.

Duty Cycle

All actuators shall be rated for 100% duty cycle regardless of application.

Motor Protection

All actuators shall have adjustable current limiting accurate to 1%. Thermal overloads or torque switches shall not be acceptable. The current limiting feature must activate a light upon exceeding the current limit set to allow for easy field diagnostics. The actuator must also have a separate light that stays latched (ON) until power is reset to provide diagnostics for intermittent over-torque situations. An optional solid-state relay (electrically isolated) rated for a minimum of 130 mA from 9 to 130 VAC or VDC shall be available as an option for critical applications where remote indication of the exceeded current limit is required.

Speed Control

All actuators shall have field adjustable speed control as a standard feature.

Operating Temperature - Ambient

Actuators shall be designed for temperatures ranging from -40°F to 150°F (-40°C to 65°C). For temperatures below 32°F (0°C), outdoor applications, high humidity or wet locations the actuators shall be supplied with an electric heater and thermostat.

Signal Range/Acceptance

For On/Off (two-position) or tri-state control, the actuator shall be capable of accepting a wide signal input range of 9 to 130 VAC or VDC without the need for special add on isolation modules.

Signal and Power Isolation

All actuators shall have optically isolated signal inputs so that power and signal do not have to come from the same source to control the actuator. Signal inputs shall not be polarity sensitive.

Braking

All actuators shall have a solid state braking system, which works with or without power, (rated to 1-1/4 times the torque rating of the actuator). Electro-Mechanical brakes or clutches shall not be acceptable.

Manual Override

All units shall be equipped with a manual override which will allow the actuator to be rotated in the clockwise or counter-clockwise direction. Optional solid cast aluminum override handwheels shall be available. Spoked handwheels shall not be acceptable due to safety issues.

Enclosure

The actuator housing shall be a high strength aluminum casting with an exterior grade polyurethane enamel coating for excellent wear, corrosion, impact and UV resistance. All actuators shall be NEMA 4/4X type minimum. All cover fasteners shall be stainless steel. All actuators shall have a position indicator with the angle of rotation clearly marked. All actuators used in outdoor applications shall have white covers to lessen the solar heat load.



Mounting

All actuators shall have interchangeable female output drive shafts to allow for direct mounting and easy mounting for a wide variety of applications.

Conduit Entry

All units shall have two conduit entries. One shall be used for signal and one for power.

Gear Train

All gearing shall be high strength and heat-treated with permanent lubrication. All cluster gears shall be single piece design. Two gears pressed together to form a single cluster shall not be acceptable.

Actuators with Modulating Control

All modulating actuators shall have control circuitry capable of a minimum of 180 points of discrete control in 90 degrees of movement. All internal feedback potentiometers shall be direct mounted to the output shaft. Gear driven potentiometers shall not be acceptable.

Input Signals

The actuator shall be capable of accepting 4-20 mA with 250 Ohms impedance, 0-10 VDC or 2-10 VDC signals. Input signal isolation shall be provided to isolate the input signal from the actuator power so that the signal and power can come from different sources, without the need for exterior isolation modules. Modulating circuitry shall come standard with 4-20 mA and 0-10 VDC feedback circuits and not require additional modules.

Limit Switches

All limit switches shall be independently activated by adjustable cams, one for each direction. An individual light must be provided for each direction of rotation. A separate limit switch and cam shall be provided for customer use rated for 125/250 VAC 10 Amp, 1/3 H.P.

Agency Certification

Entire actuator must be UL508 Listed or certified to CSA C22.2 No. 14-M91. Actuators that only have their motors or individual components recognized are not acceptable.

How to Select the RE Industrial Actuator Part Number



Note:

 H/S at end of part number indicates heater and stat (use for very moist or outdoor applications).

	Torque	Part No.
Example:	1000 in-lb	RE10
	5100 in-lb	RE20T





RE Series Industrial Actuators
Features and Benefits

Features	Benefits				
Solid state industrial 1/4 turn actuators with current limiting	Actuator stops and holds position when current setpoint is exceeded. Can continue to operate if driven in the opposite direction.				
Field adjustable speed setting standard	Can slow speed of actuator by a factor of 2 (i.e. 90 degrees of rotation can be slowed from 35 seconds to 70 seconds).				
Optically isolated signal inputs	Power and signal do not have to come from the same source (no more ground loop problems).				
Inputs are not polarity sensitive for on/off or tri-state control	Positive and negative are interchangeable. Easier wiring, application and troubleshooting.				
LED diagnostic indicators 2 end of travel and 2 torque related	Simple troubleshooting.				
Standard 4 Amp knife blade standard automotive fuse	Commonly available.				
True 100 % Duty Cycle	Requires no rest period between cycles.				
Solid state braking system works with or without power (rated to 1-1/4 X torque)	Prevents valve or damper from drifting when power is absent. Not moisture sensitive. Elect./Mechanical brakes tend to be extremely sensitive to moisture and can lock up.				
Heavy duty terminals for field interface	Fast, reliable field hook-up.				
Designed with higher voltage electronic components	Reduces typical static and handling problems.				
Automatic adjustment for damper or valve seal wear	Current limiting feature ensures positive close-off. Prevents jamming the damper or driving the valve too far into seat.				
Two-position control: Wide input signal voltage range (9 - 130 VAC or VDC)	Allows for long distance signal runs. Flexibility also allows for early commissioning.				
Entire Actuator is UL508 and cUL C22.2 No. 14-M91 listed.	Meets rigid engineering specifications				



RE Series Industrial NEMA 4/4X Type Actuators Torque: 150 In-Lb to 10,200 In-Lb

Technical Data	RE1.5F - RE8.5F	RE1.5G - RE8.5G	RE10F-RE30XF	RE10G - RE30XG				
Power supply	12 VDC, 2	available						
Power Consumption**	30 VA (Class 2 pow	ver source required)	56 VA (Class 2 pc	ower source required)				
Electrical connection	Dual conduit entry (1/2") Dual conduit entry (3/4")							
Overload protection		Electronic - Solid State						
Control signal	Two-pos./tri-state*	0-10 VDC,	Two-pos./tri-state*	0 -10 VDC,				
Control signal	(floating)	4-20 mA std., field adj.	(floating)	4-20 mA std., field adj.				
Input impedance		250 Ohms for	· 4 - 20 mA					
Operating range	0 to 10 VI	DC, 2 to 10 VDC, 4 to 20 mA	A, custom signal ranges	available				
Feedback output		0 to 10 VDC standard,	4 to 20 mA optional					
Angle of rotation		Typically 90°, Option: a	djustable 65° to 320°					
Minimum torque		Depends on mod	lel - see Table					
Direction of rotation	S	tandard: increase signal =	CCW (jumper selectable	2)				
Position indication		Visual mechanical p	osition indicator					
Gear train		Heat treated metal gears, j	permanently lubricated					
Brakes		Solid State braking system	m (power not required)					
Manual override	De-c	lutching shaft with flats, o	ptional override handw	heel				
Duty cycle		100%	6					
Auxiliary switches	1 standard, up to 3 optional							
- Switch		Form C; S	SPDT					
- Range usage	0 - 320°							
- Factory setting	None							
- Ratings (Resistive)	- 125/250 VAC: 10 Amps, 1/3 hp							
		- 12 VDC: 5.0 Amps;	30 VDC: 2.0 Amps					
		Customs Available - Cal	ll Dodge Engineering					
Switch connections:		Male quick conn	ect type tabs	1				
Control signal adjustment:								
(for modulating units)								
- Offset (startpoint)	-	0 - 3 VDC	-	0 - 3 VDC				
- Factory setting		0 - 10 VDC or 4-20 mA		0 - 10 VDC or 4-20 mA				
- Span		Adjustable		Adjustable				
Running time (90°)(nominal)	A	djustable - See RE Series II	ndustrial Actuators Tab	le				
Humidity		95% RH, nonc	condensing					
Operating temperature†		-40°F to 150°F (-	40°C to 65°C)					
Agency Compliance	UL 508 Listed, File	E253925; cUL Certified to	Canadian standard C22	.2 No. 14-M91***				
Housing type		Type 4/4X accord	ing to UL, cUL					
Housing material	Cast alı	minum, with exterior grade	e polyurethane enamel c	coating.				
Options:								
- Heater & thermostat †	For outdoor and moist environments							
- Override handwheel		Non-spoked	for safety					
- Alarm relay		Output - rating 130 mA	max., 9 - 130 VAC/DC					
Servicing		Maintenar	nce free					
Weight	17	lbs	25	lbs ††				

Notes:

* Input signal range from 9 - 130 VAC or VDC. Use normal switched signals only (i.e. relay contacts or switches). **Do Not Use Triacs.**

** Does not include line loss. Add 16 VA if heater and stat (H/S) is used.

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RE Series Industrial Actuators									
Actuator	Output	Torque	Speed*	Speed**	Speed**				
Model No.	in-lb	N-m	sec./90°	sec./270°	sec./360°				
RE1.5	150	17	10 - 25	_	_				
RE3†	300	34	10 - 25	_	_				
RE6	600	68	10 - 25	—	_				
RE8.5	850	96	10 - 25	_	_				
RE10†	1000	114	35 - 70	_	-				
RE15	1500	170	35 - 70	_	-				
RE20	2000	227	35 - 70	_	-				
RE25	2500	284	35 - 70	_	_				
RE30	3000	340	35 - 70	_	-				
RE15T**	3825	434	_	105 - 210	-				
RE20T**	5100	579	—	105 - 210					
RE25T**	6375	724	_	105 - 210					
RE30T**	7650	869	_	105 - 210	_				
RE30X**	10200	1158	_	_	140-280				



RE Series Industrial Actuators Dimensions									
Actuator	Dimensions (Inches)								
Model No.	А	В	С	D	Е	F	G	Н	
RE1.5 - RE8.5	9.93	5.15	3.48	7.42	0.75 sq. 0.63 deep	N/A	5/16-18UNC-2B 0.625 deep BC: 3.25	1/2" NPT	
RE10 - RE30	11.65	6.07	4.40	9.75	1.00 sq. 2.00 deep	3/8-16UNC-2B 1.12 deep BC: 4.00	7/16-14UNC-2B 1.50 deep BC: 4.965	3/4" NPT	

Notes:

^{*} Speed is adjustable and varies slightly with load.

^{**} When using a Torque Maximizer, see page AC-11 in our DEI catalog for further details and requirements.

[†] Faster speeds available. Please call DEI.



AC-7





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Torque Maximizer

The Torque Maximizer permits DEI's actuators to operate at required torques up to 10,200 in-lbs. It also allows the actuator to be mounted in applications with space or location limitations.

Operation: The Torque Maximizer provides added gear reduction between the actuator and the valve or damper, thereby increasing the torque of the actuator. This product is 85% efficient in transferring the torque from the input to output drive shaft. This unit bolts directly onto the base of the DEI actuator, then the combined actuator/gear operator unit is mounted to the valve, damper or other application.*



Model	Weight	Dimensions in (mm)							
Widdei	lbs (kg)	А	В	С	D	Е			
т	38	7.25	10.63	5.25	4.63	7.00			
1	(17)	(184)	(270)	(133)	(118)	(178)			
v	78	11.25	15.50	5.25	6.63	9.88			
Х	(35)	(286)	(394)	(133)	(169)	(251)			

Rotation Time: The Torque Maximizer gear unit model T (3:1 gear ratio) requires 270° of rotation to the input shaft to rotate the output shaft 90° . Model X (4:1 gear ratio) requires 360° of rotation for 90° of rotation at the output shaft. Therefore, the time it takes to rotate the output shaft of the Model T 90° is 3 times the values listed on the "RE" product specification sheet for 90° rotation. The Model X requires 4 times the values listed for the respective actuator. Please note that many applications do not require the output shaft to turn a full 90° , thereby reducing the time.

Both models are furnished with a semi-gloss black, baked epoxy, powder coat paint finish.

Torque Maximizer Input/Output										
Model	Input	Forque	Output	Torque	Gear	Mech.				
Model	in-lb	N-m	in-lb	N-m	Ratio	Advantage				
RE15T	1,500	169	3,825	432	3:1	2.55				
RE20T	2,000	225	5,100	576	3:1	2.55				
RE25T	2,500	282	6,375	720	3:1	2.55				
RE30T	3,000	338	7,650	864	3:1	2.55				
RE30X	3,000	338	10,200	1,152	4:1	3.40				

Notes:

- Pictures not drawn to scale.

* For overall assembly dimension to valve, call DEI. Bracket height is not included in dimensions.



Rack & Pinion Pneumatic Actuators





FEATURES & BENEFITS

DEI's Rack & Pinion Pneumatic Actuators are designed for high reliability operation. They are permanently lubricated and feature a corrosion resistant hard anodized finish.

- **ISO MOUNTING** conforms to the ISO 5211 mounting standard, which fits more mounting configurations with less hardware variation (on models PN/PS20 through PN/PS1750 only).
- **SUBSTANTIAL PINION BEARINGS** provide protection against side loading which increases cycle life.
- **CORROSION RESISTANT** rugged hard anodized finish (standard) ensures protection from most corrosive environments. Optional baked epoxy finish available for severe environments. Call DEI for more information.
- NAMUR ACCESSORY MOUNTING PATTERN allows for more combinations of solenoids, positioners and limit switches with minimal or no mounting hardware.
- **INDIVIDUAL SPRINGS** allow for torque adjustment. Springs can be added or deleted to "fine tune" the torque output. All the springs in each actuator are the same size.
- ACCESSORIES are available for a wide variety of control signals, controller, computer and control panel interface.

TECHNICAL DATA

- Maximum Working Pressure 150 PSIG
- Standard Working Temperature -20°F to 175°F
- Air Supply Double Acting and Spring Return 40-150 PSIG
- **Rotation** 90° Travel Travel Stops standard
- Operating Media Clean, dry air, noncorrosive gas or light hydraulic oil

 \square

Port "A"

Counter Clockwise



Clockwise

Spring-Return Only



Double Acting Operation

Counter Clockwise

Air is supplied to Port A which forces the pistons away from each other (toward ends). This rotates the drive pinion counter clockwise which exhausts air out of Port B.

Clockwise

Air is supplied to Port B which forces the pistons toward each other (toward center). This rotates the drive pinion clockwise which exhausts air out of Port A.

Spring Return Operation

Counter Clockwise

Port "B'

Air is supplied to Port A which forces the pistons away from each other (toward ends). This rotates the drive pinion counterclockwise which compresses the springs and exhausts the air out of Port B.

Fail Clockwise (CCW optional, call DEI)

Air failure (loss of pressure) allows the compressed springs to force the pistons toward each other (toward center). This rotates the drive pinion clockwise and exhausts air out of Port A.



Rack & Pinion Pneumatic Actuators Dimensional Information

Double Acting Actuators



Double Acting Actuators									
Actuator Model No	Dimen	Cycle Times (secs/90°)							
WIDDEI IND.	Α	В	С	CW	CCW				
PN20	2.68	6.81	2.58	0.5	0.5				
PN40	3.39	7.68	3.25	0.6	0.6				
PN80	4.45	8.23	4.33	1	0.6				
PN130	4.88	9.60	4.76	1	0.7				
PN200	5.28	9.96	5.22	1	0.7				
PN300	6.18	11.30	5.98	1.5	1				
PN500	6.93	12.56	6.69	2	1.5				
PN850	8.27	16.69	7.64	2.5	2				
PN1200	9.17	15.67	7.83	4	3				
PN1750	10.08	19.84	9.29	5	4				

Spring Return Actuators

→ B →		Spring D	tum Aa	tuotore		
A Dodge Engineering & Controls Choined MA (779) 244-1622 Model #	Actuator Model No	Dimen	Cycle Times (secs/90°)			
Serial # Maximum Operating Pressure: 150 psi	widdel ind.	Α	В	С	CW	CCW
	PS20	2.68	8.39	2.58	0.5	0.5
	PS40	3.39	7.56	3.25	0.6	0.6
←	PS80	4.45	8.94	4.33	1	0.6
	PS130	4.88	10.39	4.76	1	0.7
	PS200	5.28	11.50	5.22	1	0.7
	PS300	6.18	13.23	5.98	1.5	1
[]	PS500	6.93	16.26	6.69	2	1.5
	PS850	8.27	20.24	7.64	2.5	2
	PS1200	9.17	19.80	7.83	4	3
DEI Rack & Pinion Spring Return Pneumatic Actuator	PS1750	10.08	28.15	9.29	5	4



Rack & Pinion Pneumatic Actuators

			Air Supply							
Actuator Model No	Spring	Torque	60	60 PSI		PSI	100 PSI			
WIOUCI NO.	End	Break	End	Break	End	Break	End	Break		
PS20	49	84	25	60	61	96	105	140		
PS40	82	142	43	103	103	164	165	226		
PS80	215	410	109	304	282	477	455	651		
PS130	315	573	127	385	357	614	607	864		
PS200	420	760	220	560	549	889	879	1219		
PS300	880	1605	485	1210	1184	1909	1874	2599		
PS500	1325	2300	750	1725	1759	2734	2769	3744		
PS850	1815	3050	1719	2345	2429	3664	3709	4944		
PS1200	2625	4550	1460	3385	3349	5274	5169	7094		
PS1750	3475	6075	2480	5080	5234	7834	7884	10484		

Spring Return Torque (in-lbs)

Notes:

Torques are actual. Please be sure to include appropriate safety factors and all service conditions variables when sizing.
Three-way (master-slave) assemblies should use a 35% safety factor. Call factory for assistance.

- Thee-way (master-slave) assembles should use a 55% safety factor. Can factory for assist

Double Acting Torque (in-lbs)

Actuator	Air Supply								
Model No.	40 PSI	60 PSI	80 PSI	100 PSI	120 PSI				
PN20	69	109	145	180	229				
PN40	103	185	246	308	370				
PN80	346	519	693	866	1038				
PN130	460	700	930	1180	1390				
PN200	650	980	1310	1640	1968				
PN300	1390	2090	2790	3480	4270				
PN500	2030	3050	4060	5070	6090				
PN850	2930	4160	5480	6760	8200				
PN1200	3850	6010	7910	9780	11830				
PN1750	5480	8555	11310	13960	16960				





Scotch Yoke Design Pneumatic Actuators PN2500, PN3500, PS2500 & PS3500



Actuator Model No.	Dimensions (inches)			Cycle Times (secs/90°)		Volume (cu. in./90°)	
1100011101	А	A B Base Width		CW	CCW	CW	CCW
Double Acting							
PN2500	7.25		9.38	5	5	525	310
PN3500	12.58		9.38	9	9	650	585
Spring Return							
PS2500	-	7.25	9.38	5	5	525	310
PS3500	_	19.43	9.38	9	9	1650	585

Double Acting Torque (in-lbs)						
Actuator Model No./PSI	0°	40°	90°			
PN2500						
60 psi	13627	7858	9196			
80 psi	18734	8276	12456			
100 psi	24411	10366	15382			
PN3500						
60 psi	26919	12791	18141			
80 psi	35864	17054	24160			
100 psi	45060	21318	30196			

Spring Return Torque (in-lbs)							
Actuator	Air Break	Run	Air End	Spring Break	Run	Spring End	
Widder No./1 Si	0°	60°	90°	90°	30°	0°	
PS2500							
60 psi	6890	2852	4039	7224	2974	4241	
80 psi	9152	3784	5368	9592	3960	5632	
100 psi	11510	4744	6758	12038	4972	7066	
PS3500							
60 psi	13780	5702	8078	14449	5948	8483	
80 psi	18304	7568	10736	19184	7920	11264	
100 psi	22978	9486	13464	24076	11264	14132	

Air Consumption (scf per 90°) = $\frac{\text{Volume } x}{1,728} \frac{\text{Supply Pressure + 14.7}}{14.7}$

Notes:

⁻ Accessory mounting holes are not intended for Manual Gear Overrides or Stop Blocks. Cycle times are under no load conditions. Air line size, air capacity and valve torque characteristics affect these cycle times. Faster or slower cycle times can be accomplished using special control components.



Pneumatic - Pneumatic Positioner: Rotary Type IP5100



Positioner body

ork pin unit

ctuator shaft

ork lever assembly

• High performance positioner

- Resistant to hostile environments
- Exceptional shock and vibration performance

Energy Saving:

• Air consumption is approximately 30% less than existing types

Complete Optional Specifications:

- Opening indicator
- Built-in equalizing valve (OUT1-OUT2)

Easy Maintenance:

Maintenance and parts replacement made easy by modular construction

Standardization of Fork Lever Joint:

• Linkage design tolerates a slight misalignment of shafts



Employs the combination of the check valve and the labyrinth effect.

Approved by JISF8007IP55:

A centralized exhaust system enhances both dust-proof and waterproof qualities. Epoxy-type coating inside the body prevents corrosion due to moisture.

Overall Dimensions:





Pneumatic - Pneumatic Positioner: Rotary Type IP5100

IP5100					
Rotary type cam feedback					
Single or double action					
Supply air pressure	20-101 PSI				
Input pressure signal	3-15 PSI				
Stroke	$60^{\circ} \sim 100^{\circ}$				
Sensitivity	within 0.5% full scale				
Linearity	within +/-2% full scale				
Hysteresis	within 1% full scale				
Repeatability	within +/-0.5% full scale				
Air consumption	0.18 CFM* or less (SUP=20 PSI), 0.39 CFM* or less (SUP=58 PSI)**				
Output flow	2.83 CFM* or less (SUP=20 PSI), 7.06 CFM* or less (SUP=58 PSI)**				
Ambient and air temperature	-4°F - 176°F (standard)				
Coefficient of temperature	within 0.1% full scale/°C				
Air port	Rc(PT)1/4 (standard)				
Main component parts	Aluminum diecast, Stainless steel, Brass, Nitrile rubber				
Weight	Approx. 2.65 lbs				
Dimensions	4.65" x 3.62" x 3.05" (body)				

Notes: * Standard atmospheric conditions

** Standard air temp: 68°F (20°C); absolute pressure: 14.7 PSI; relative humidity: 65%





Pneumatic - Pneumatic Positioner: Rotary Type IP5100



Single Action

Positive Operation When the input signal is increased, the actuator shaft rotates in a clockwise direction.



Reverse Operation When the input signal is increased, the actuator shaft rotates in a counterclockwise direction.



Double Action

Positive Operation

When the input signal is increased, the actuator shaft rotates in a clockwise direction.



Reverse Operation

When the input signal is increased, the actuator shaft rotates in a counterclockwise direction.



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NAMUR Interface 5 Port Solenoid Valve

•



Application: Interface Solenoid Valve for Pneumatic Actuators

Features:

- NAMUR interface
 - Electrical entry: conduit connection with terminals
- Manual override/classification: non-locking, push type (flush)
- Thread type: NPT

		Specifications			
		Fluid		Air, inert gas	
		Max. operating pressure		130 PSI (0.9 MPa)	
		Min. operating pressure		22 PSI (0.15 MPa)	
bol		Ambient and fluid temperature		14°F to 140°F (-10°C to 60°C) [*]	
Single Selensid		Lubrication		Not required **	
Single Solenoid	Valve	Pilot operator manual override		Non-locking push type (Flush type)	
		Protection structure		Dust proof	
		Port size		1/4	
513		Cv factor (effective area)		$1.4 (1 \text{ in}^2, 25 \text{ mm}^2)$	
		Weight		0.57 lb (0.26 kgf)	
Double Solenoid		Other		Cyl. port should be NAMUR hole pattern	
4 2		Rated voltage [†]	AC	24/100/200 V (50/60 Hz)	
		Allowable voltage range		-15% to 10% of rated voltage	
		Coil insulation		Class B or equivalent	
513	Electrical	Apparent power AC (power consumption)	Inrush	5.0 VA / 60 Hz, 5.6 VA / 50 Hz	
	Entry		Holding	2.3 VA (1.5 W) / 60 Hz	
	-		notaling	3.4 VA (2.1 W) / 50 Hz	
		Power consumption DC		1.8 W	
		Electrical entry		Grommet, Grommet terminal, Conduit terminal DIN connector	



Notes:

Symbol

- * Use dry-air at low temperature
- ** Use turbine oil No. 1 (ISO VG32), if lubricated
- † Other voltages available with special order

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Low Pressure (20-30 PSI) Pneumatic Piston Type Spring Return Actuators for Butterfly Valves



The Pneumatic Piston Type Spring Return Actuators provide actuation on butterfly valves in sizes up to 10 inches. These actuators are sized and installed for 70° disc rotation and require 20 to 30 PSIG (140 to 210 kPa) maximum input air pressure at the diaphragm to deliver the rated torque output.

Maximum Available Force* (lbs)						
Actuator Model No	Stroke	20 PSIG Air Supply Nominal Spring Range (PSI)				
Widder No.		3 to 7	to 7 5 to 10	8 to 13		
DC 1	Power	195.0	150.0	105.0		
PS-1	Return	45.0	75.0	120.0		
DC 0	Power	-	-	163.8		
F 5 -2	Return	-	-	187.2		
	Power	-	-	163.8		
13-3	Return	-	-	187.2		
PS-4	Power	-	-	327.6		
	Return	-	-	374.4		
DC 5	Power	-	_	327.6		
13-3	Return	-	_	374.4		

Notes:

- Nominal Spring Range is the interval over which the piston moves from one extreme to the other when no external load is applied to the actuator. It is expressed in terms of the control pressure on the diaphragm.

- Return Force based on 0 PSIG supply.

* Work = Force x Stroke

Actuator Torque (Comparison Data
-------------------	-----------------

	Torque (in-lbs)/PSI**	Actuator Model No.
	22.5	PS-1
	46.8	PS-2
Notes	70.2	PS-3
	93.6	PS-4
	140.2	PS-5

- Total Torque = Supply Pressure - Spring

– Pressure x Torque/PSI (Power Stroke)

Total Torque = Spring Pressure x Torque/PSI (Return Stroke)
 ** The torque is based on 90° angular rotation and computed for 1 PSI.

Electronic Industrial and Pneumatic Actuators

Electronic Industrial - NEMA 4/4X Type

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