



Design For Scale- GPU Based Infrastructure for Autonomous Vehicles

Manish Harsh | Global Developer Relations,
Enterprise Automotive, NVIDIA

AGENDA

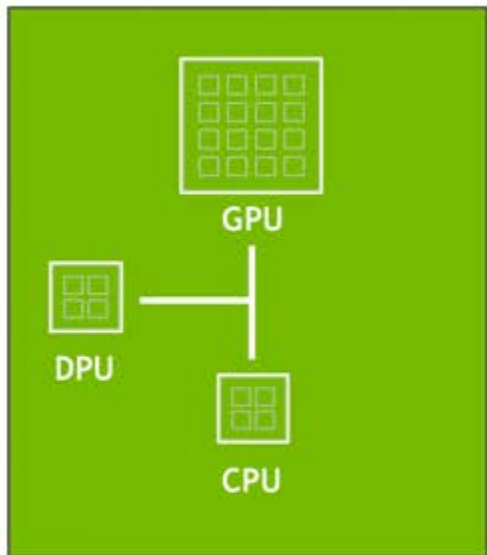
Autonomous Vehicle Development

- GPU Platform Overview
- Fundamentals of AV Stack Architecture
- AV Workflow and Platform: Training and Inference
- Architecture to Scale
- NVIDIA DRIVE – End to End Infra for AV development

Conclusion

- Key Pointers
 - Developer Engagement Platforms
 - NGC – NVIDIA Software Hub
- 

FUNDAMENTALS OF NVIDIA PLATFORM



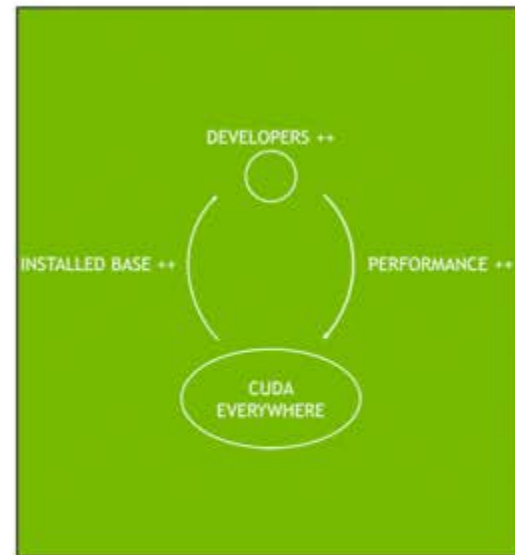
X-FACTOR SPEED UP



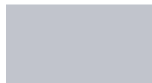
FULL STACK



DATA-CENTER SCALE



ONE ARCHITECTURE



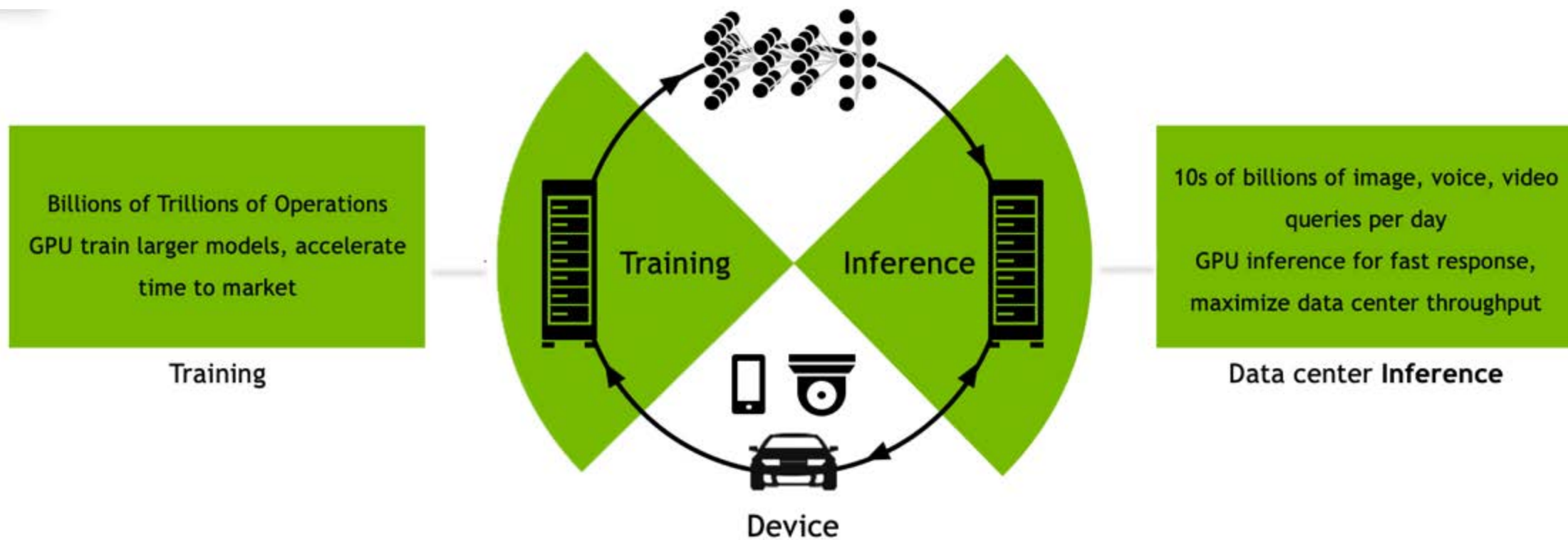


AV Development Workflows
Auto AV Training and Inference
NGC FOR PERFORMANCE
Architecture to Scale



AUTONOMOUS VEHICLES

Training and Inference at Scale



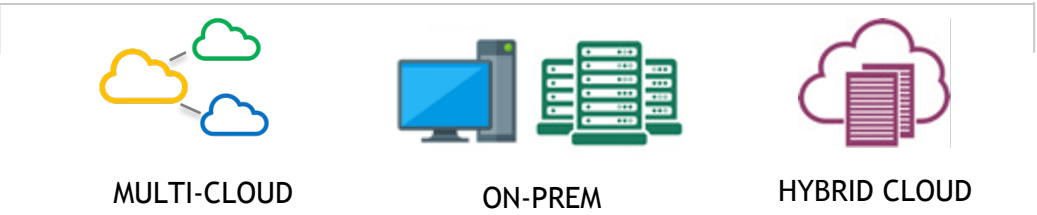
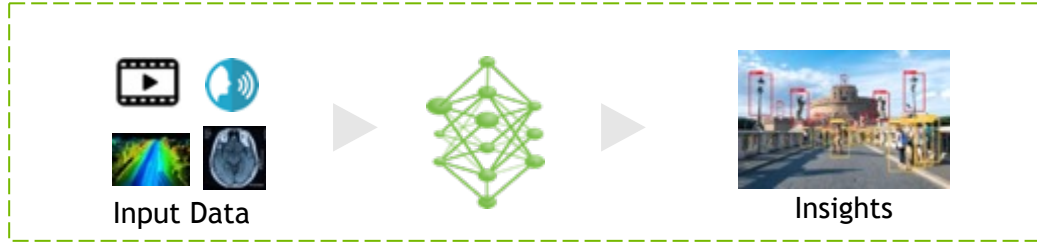
AI WORKFLOW

Training and Inference

TRAINING



INFERENCE



CAMBRIAN EXPLOSION OF AI MODELS

Convolutional Networks



Encoder/Decoder



ReLu



BatchNorm



Concat



Dropout



Pooling

Recurrent Networks



LSTM



GRU

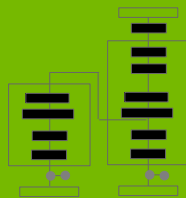


WaveNet

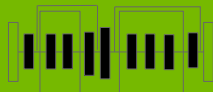


Beam Search

Transformer



BERT



Megatron

Generative Adversarial Networks



3D-GAN



MedGAN



Conditional GAN



Coupled GAN



Speech Enhancement GAN

Reinforcement Learning



DQN



Simulation



DDPG

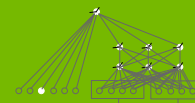
New Species



Capsule Nets



Mixture of Experts



Wide and Deep

NVIDIA DRIVE INFRASTRUCTURE

HW & SW Infrastructure | Applications, Tools, Services

Applications / Solutions

DATASET

TRAINING

REPLAY

SIMULATION

Datacenter Workflow
& Management Software

DATASET GENERATION

MODEL GENERATION

TESTING / VALIDATION

DATA MANAGEMENT

WORKFLOW MANAGEMENT

DATA CENTER BACKBONE

Hardware Appliances
(SaturnV @ NVIDIA)

DGX

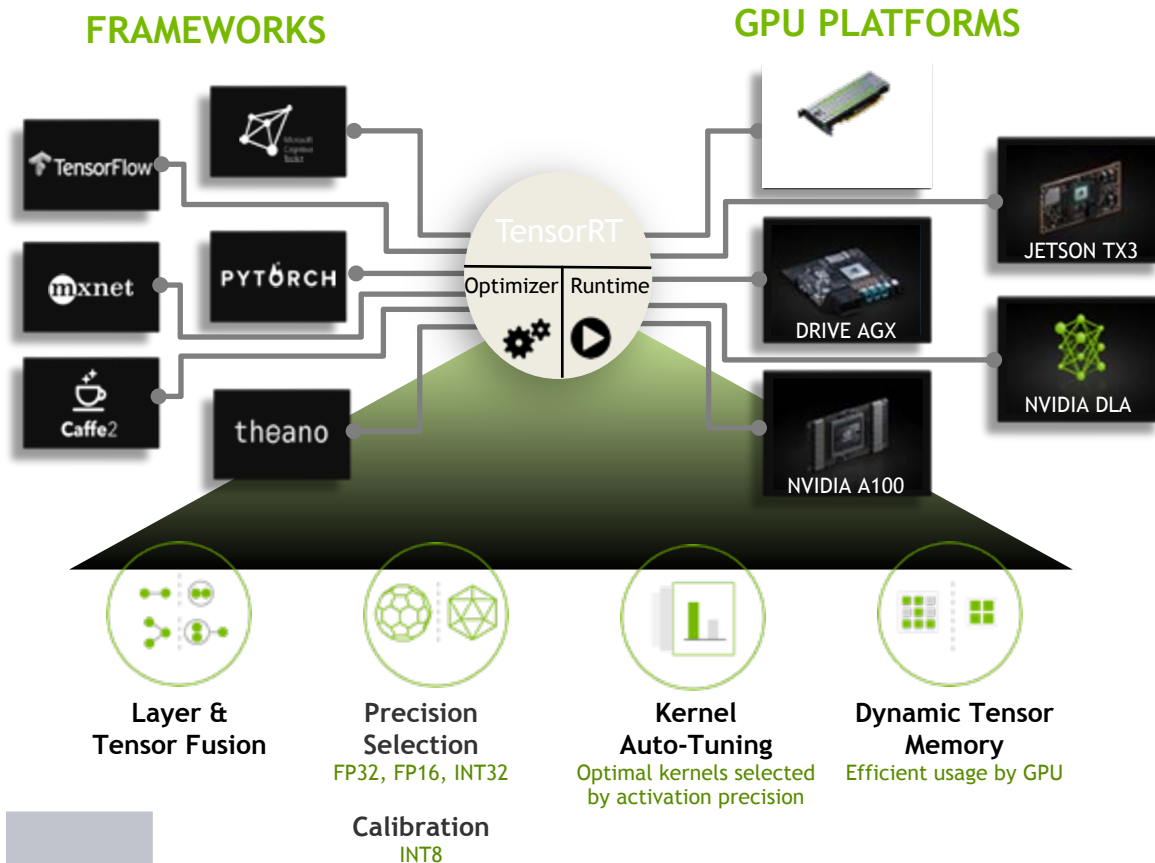


CONSTELLATION



NVIDIA TENSORRT INFERENCE PLATFORM

- AV Stack Pillars: Frameworks and Infrastructure



Automotive



Drive



Embedded



Jetson

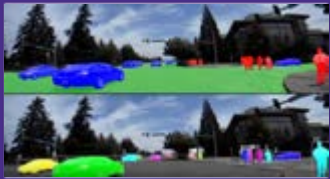


Data Center

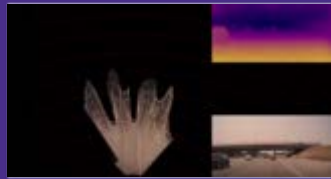


DRIVE SOFTWARE MODELS

Perception | Mapping | Planning | Driver Monitoring



Obstacles



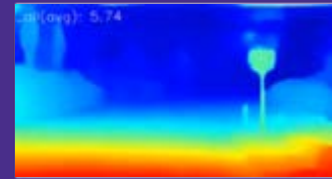
Distance



Time to Collision (RNN)



Free Space



Structure from Motion



Lidar



Paths



Signs



Map



High Beam



Parking



Camera Blindness



Intersection



Traffic Lights



Gestures/Pose



Gaze

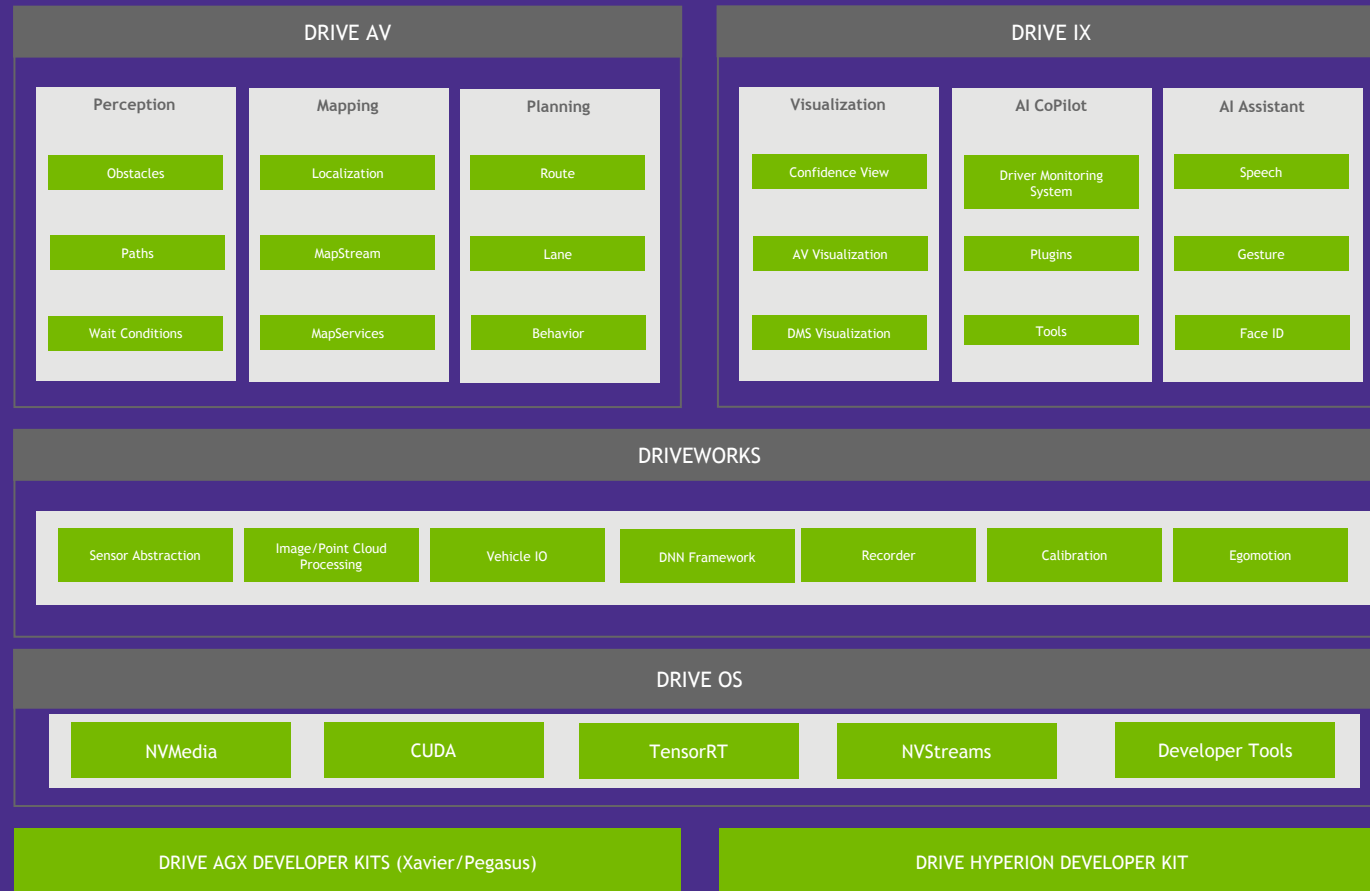


Prediction (RNN)



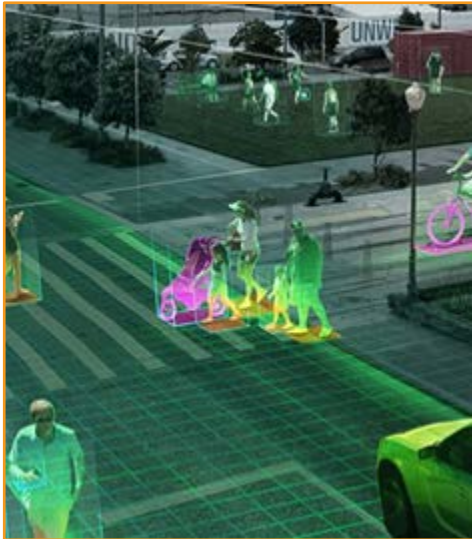
Radar

NVIDIA DRIVE SOFTWARE

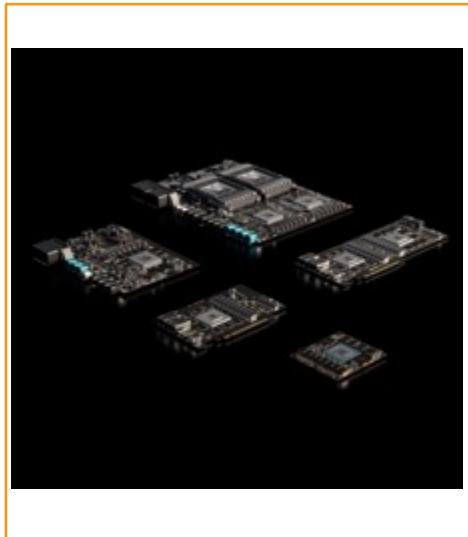


DRIVE OS FOR SAFETY

The First Functional Safety (FuSa) Operating System for Accelerated Computing and Artificial Intelligence



Automotive Industry
Safety Standards



Scalable
from L2 to L5



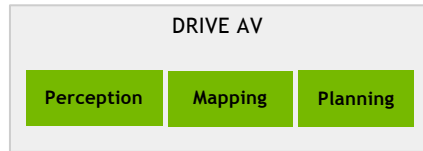
Comprehensive
Security Model



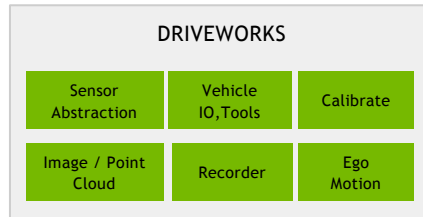
Industry Partners
And Experience

NVIDIA DRIVE

E2E AV flow to enable large scale AV development & testing



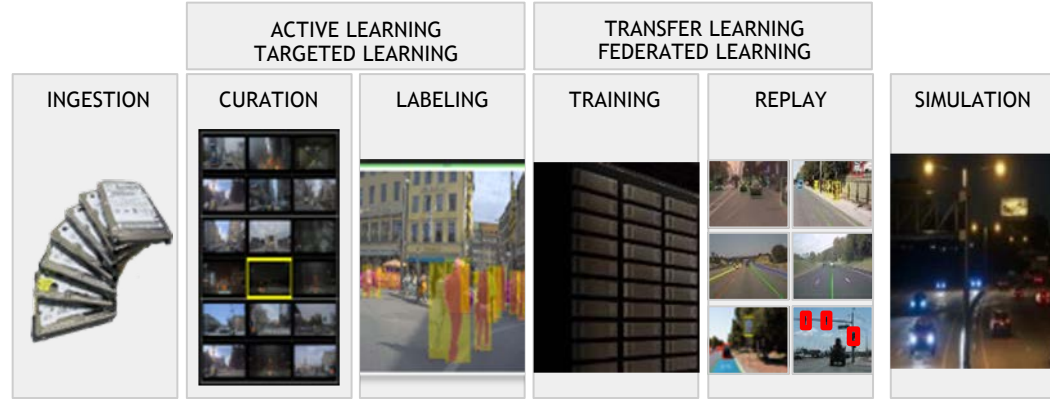
1,000's Engineers
20+ DNNs, 50 Parallel Experiments



1,000's Engineers HW & SW
20 million lines of code



Sensor Data+Logs

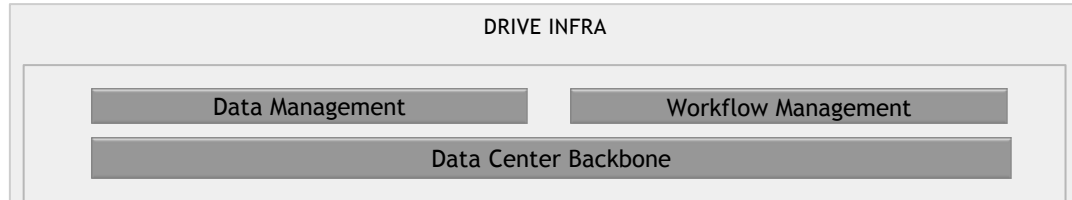


300k hours, 300M frames
10 PB/wk data collected

1,500 labelers
50M+ labeled images

100's DGX
Saturn V

1M+ virtual miles driven
200+ DRIVE Constellations



1,000's of engineering hours develop and run Deep Ops & Dev Ops SW on Saturn V



ENABLING PORTABILITY WITH NGC CONTAINERS

NGC Deep Learning Containers

Extensive

- Diverse range of workloads and industry specific use cases

Optimized

- DL containers updated monthly
- Packed with latest features and superior performance

Secure & Reliable

- Scanned for vulnerabilities and crypto
- Tested on workstations, servers, & cloud instances

Scalable

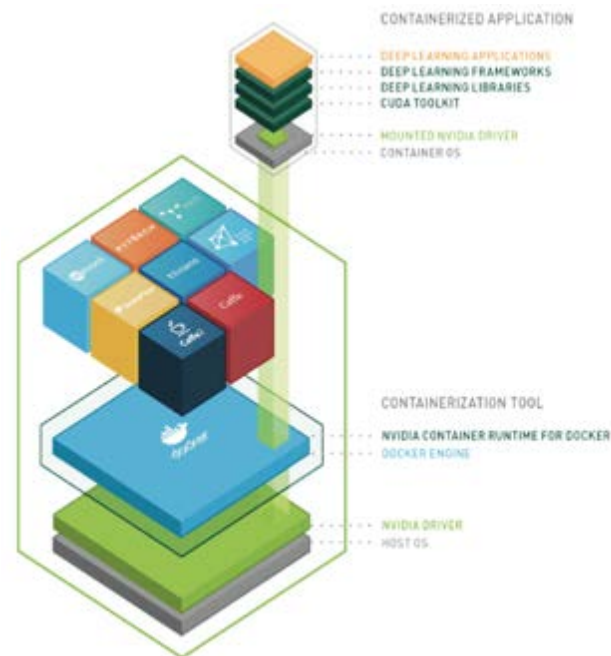
- Supports multi-GPU & multi-node systems

Designed for Enterprise & HPC

- Supports Docker, Singularity & other runtimes

Run Anywhere

- Bare metal, VMs, Kubernetes
- x86, ARM, POWER
- Multi-cloud, on-prem, hybrid, edge



CONVERSATIONAL AI



JARVIS

HEALTHCARE



CLARA

SMART CITIES



DEEPSTREAM &
SMART PARKING

TELECOM



AERIAL

AUTONOMOUS DRIVING



DRIVE

ROBOTICS



ISAAC

HPC



HPC SDK

[Learn more about NGC Containers](#)

CONCLUSION

- Key Pointers
 - NVIDIA AV Full Stack Scalable solution
 - AV Infrastructure addressing Training, Replay and Inference at Scale
 - AV stack developed on Standardized Frameworks
 - Customizable AV Workflow management tools
 - DRIVE AGX Platform for production deployment
 - HW Platform: DRIVE Xavier / Orin + Auto-grade discrete GPU
 - SW Platform: DRIVE OS, DRIVEWORKS, DRIVE AV, DRIVE IX
 - Safety certified HW and SW platform

DEVELOPER ENGAGEMENT PLATFORMS

Information, downloads, special programs, code samples, and bug submission	developer.nvidia.com
Containers for cloud and workstation environments	ngc.nvidia.com
Insights & help from other developers and NVIDIA technical staff	devtalk.nvidia.com
Technical documentation	docs.nvidia.com
Deep Learning Institute: workshops & self-paced courses	courses.nvidia.com
In depth technical how to blogs	devblogs.nvidia.com
Developer focused news and articles	news.developer.nvidia.com
Webinars	nvidia.com/webinar-portal
GTC on-demand content	gputechconf.com



DEVNET
Create