# EFFICIENT IMPLEMENTATION OF 16-BIT MULTIPLIER-ACCUMULATOR USING RADIX-2 MODIFIED BOOTH ALGORITHM AND SPST ADDER USING VERILOG

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#### ABSTRACT

In this paper, we propose a new multiplier-and-accumulator (MAC) architecture for low power and high speed arithmetic. High speed and low power MAC units are required for applications of digital signal processing like Fast Fourier Transform, Finite Impulse Response filters, convolution etc. For improving the speed and reducing the dynamic power, there is a need to reduce the glitches (1 to 0 transition) and spikes (0 to 1 transition). Adder designed using spurious power suppression technique (SPST) avoids the unwanted glitches and spikes, thus minimizing the switching power dissipation and hence the dynamic power. Radix -2 modified booth algorithm reduces the number of partial products to half by grouping of bits from the multiplier term, which improves the speed. The proposed radix-2 modified Booth algorithm MAC with SPST gives a factor of 5 less delay and 7% less power consumption as compared to array MAC.

#### **KEYWORDS**

Radix -2 modified booth algorithm, Digital signal processing, spurious power suppression Technique, Verilog.

### **1. INTRODUCTION**

The important operations in digital signal processing are filtering, convolution, and inner products. For such operations the required essential elements are multiplier and multiplier-and-accumulator (MAC). Most digital signal processing methods use non-linear functions such as discrete cosine transform (DCT) [2] or discrete wavelet transform (DWT) [3]. Basically the operations consists of repetitive application of multiplication and addition, so the speed and performance of the operation depends on the speed of the multiplication and addition. For high speed multiplication, the modified radix-4 Booth's algorithm (MBA) [4] is commonly used. However, this cannot completely solve the problem due to long critical path for multiplication [5], [6].

Multiplication is an important operation in digital signal processing algorithms. It needs large area, and consumes considerable power. Therefore, there is need of designing low power

multiplier for DSP applications. Extensive work has been carried out on low power multipliers at technology, physical, circuit and logic levels. These low-level techniques are not unique to multiplier modules and they are generally applicable to other types of modules. Moreover, power consumption is directly related to data switching patterns. However, it is difficult to consider application-specific data characteristics in low-level power optimization.

The objective of realizing a good multiplier is to have a small size, high speed and low power consumption. To save significant power consumption of a VLSI design, the focus to be to reduce its dynamic power, the bulk of total power dissipation.

The purpose of this work is to design and implement a low power MAC unit with block enabling technique to save power. Firstly, a 1-bit MAC unit is designed, with appropriate geometries that give optimized power, area and delay. For low power and delay reduce the path in the pipeline stages for data flow between the MAC blocks.

A multiplier design consists of three operational steps. The first is radix-2 Booth encoding in which a partial product is generated from the multiplicand X and the multiplier Y. The second is adder array or partial product compression to add all partial products and convert them into the form of sum and carry. The last is the final addition in which the final multiplication result is produced by adding the sum and the carry. When the multiplier results are to be accumulated, an additional step is needed, as shown in figure 1.



Figure 1: Basic arithmetic steps of multiplication and accumulation

General hardware architecture of MAC is shown in figure 2. It executes the multiplication operation by multiplying the multiplier X and the multiplicand Y. This is added to the previous multiplication result Z as the accumulation step.



Figure 2: Hardware Architecture of general MAC Array Multiplier

A 4 x 4 array multiplier and the functions of M0, M1, M2, and M4 (M's are either half adders or full adders) are shown in figure 3.  $X_3X_2X_1X_0$  is the 4 bit multiplicand and  $Y_3Y_2Y_1Y_0$  is the 4 bit multiplier.

Full adder is the important component in each cell. Each cell consist of AND gate, which determines whether a multiplicand bit,  $X_j$  is added to the incoming partial product bit based on the value of the multiplier bit  $Y_i$ . PP<sub>i</sub> is unchanged and passed vertically downward if  $Y_i$ =0,else each row adds the multiplicand (appropriately shifted) to the incoming partial product, PP<sub>i</sub> to generate the outgoing partial product PP<sub>(i+1)</sub>. The path from the upper right corner of the array to the high order product bit output at the bottom left corner of the array is the worst case signal propagation delay



Figure 3: A 4 x 4 Array Multiplier

Booth's algorithm, given below, involves repeatedly adding one of two predetermined values A and S to a product P, then performing a rightward arithmetic shift on P. Let X and Y be the multiplicand and multiplier, respectively; and let m and r represent the number of bits in X and Y.

- 1. Determine the values of A and S, and the initial value of P. All of these numbers should have a length equal to (m + r + 1).
  - (a) A: Fill the most significant (leftmost) bits with the value of X. Fill the remaining (r + 1) bits with zeros.
  - (b) S: Fill the most significant bits with the value of (-X) in two's complement notation. Fill the remaining (r + 1) bits with zeros.
  - (c) P: Fill the most significant m bits with zeros. To the right of this, append the value of Y. Fill the least significant (rightmost) bit with a zero.
- 2. Determine the two least significant (rightmost) bits of *P*. If they are
  - (a) 01, find the value of P + A. Ignore any overflow.
  - (b) 10 find the value of P + S. Ignore any overflow.
  - (c) 00 do nothing. Use P directly in the next step.
  - (d) 11 do nothing. Use *P* directly in the next step.
- 3. Arithmetically shift the value obtained in the second step by a single place to the right. Let *P* now equal this new value.
- 4. Repeat steps 2 and 3 for r number of times.
- 5. Drop the least significant (rightmost) bit from *P*. The result is the product of X and Y.

#### **2. IMPLEMENTATION**

The low power multiplier with SPST consists of i) modified Booth Encoder, ii) detection Unit, and

iii) Register as shown in figure 4.



Figure 4: Proposed low power SPST equipped multiplier

Radix-2 modified booth MAC with SPST performs both multiplication and accumulation. Multiplication result is obtained by multiplying multiplicand and multiplier. This multiplication result is accumulated with previous result. The black box view of radix-2 modified Booth MAC with SPST module is shown in figure 5.



Figure 5: MAC with SPST module

# **3. MODIFIED BOOTH ENCODER**

Modified Booth algorithm has been proposed for high speed multiplication .This type of multiplier operates much faster than an array multiplier for longer operands because its computation time is proportional to the logarithm of the word length of operands. Booth multiplication is a technique that allows faster multiplication by grouping the multiplier bits. The grouping of multiplier bits and Radix-2 Booth encoding reduce the number of partial products to half. So we take every second column, and multiply by  $\pm 1$ ,  $\pm 2$ , or 0, instead of shifting and adding for every column of the multiplier term and multiplying by 1 or 0.The advantage of this method is halving of the number of partial products. For Booth encoding the multiplier bits are formed in blocks of three, such that each block overlaps the previous block by one bit. Start from the LSB for grouping, and the first block only uses two bits of the multiplier. Figure 6 shows the grouping of bits from the multiplier term.



Figure 6: Grouping of bits from the multiplier term

To obtain the correct partial product each block is decoded. Table 1 shows the encoding of the multiplier Y, using the modified Booth algorithm, generates the following five signed digits, -2, -1, 0, +1, +2. Each encoded digit in the multiplier performs a certain operation on the multiplicand X.

Block	Re - coded digit	Operation on X
000	0	0 X
001	+1	+1 X
010	+1	+1 X
011	+2	+2 X
100	-2	-2 X
101	-1	-1 X
110	-1	-1 X
111	0	0 X

Table 1: Operations on the multiplicand

# 4. SPURIOUS POWER SUPPRESSION TECHNIQUES AND REGISTER

Spurious transitions (also called glitches) in combinational CMOS logic are a well known source of unnecessary power dissipation. Reducing glitch power is a highly desirable target because in the vast majority of digital CMOS circuits, only one signal transition per clock cycle is functionally meaningful. Unfortunately, glitch power is heavily dependent on the low-level implementation details, namely, gate propagation delays and input transitions misalignments. The procedure for glitch minimization is based on a well known idea. Glitches are eliminated by

adding some redundant logic that prevents spurious transitions. This can be done by inserting latches in a gate-level net list.

Figure 7 shows a 16-bit adder/subtractor based on the proposed SPST. In this, the 16-bit adder / subtractor is divided into MSP (Most Significant Part) and LSP (Least Significant Part) between the 8<sup>th</sup> and 9<sup>th</sup> bits. The MSP of the original adder is modified to include detection logic circuits, data controlling circuits, sign extension circuits, logic for calculating carry-in and carry-out signals.

Simple logic gates are used to implement the latches and the sign extension circuits in order to reduce the additional overhead as for as possible. Low power adder/subtractor consists of i) latch,

ii) Detection logic, and iii) sign extension logic.



Figure 7: Low-power adder design using SPST

#### (a) Detection Logic

The most important part of detection logic is design of the control signal asserting circuit, shown in figure 7. Although this asserting circuit brings evident power reduction, it may induce additional delay. An approach for implementing the control signal assertion circuit is using registers and is illustrated as shaded area in figures 9 and 10.





Figure 8: Detection logic circuit using registers to assert the control signals



Figure 9: Detection logic circuit using AND gates to assert the control signals

# (b) Applying SPST to the Modified Booth Encoder

The SPST equipped modified Booth encoder, which is controlled by a detection unit. One of the two operands as input to the detection unit, which decide whether the Booth encoder calculates redundant computations. As shown in Figure 10, the latches can, respectively, freeze the inputs of MUX-4 to MUX-7 or only those of MUX-6 to MUX-7 when  $PP_4$  to  $PP_7$  or  $PP_6$  to  $PP_7$  are zero, to reduce the transition power dissipation.



Figure 10: SPST equipped modified Booth encoder

# 5. ARRAY MULTIPLIER AND ACCUMULATOR

A 4x4 array multiplier consists of 16 AND gates, 4 HAs, 8FAs (total 12 Adders) is shown in figure 11.Therefore, for an m x n Array Multiplier, m\*n AND gates, n HAs, (m-2)\*n FAs, i.e. a total of (m-1)\*n adders are required. Figure 13 also illustrates generation of partial products in a 4x4 array multiplier. A total of 8 partial products are generated by the 4x4 array multiplier. Similarly, a 16 x16 array multiplier takes 16- bit multiplicand and 16- bit multiplier and generates 32 partial products.



Figure 11: A 4x4 array multiplier

Array MAC performs both multiplication and accumulation. Multiplication result is obtained by multiplying 16 -bit multiplicand and 16- bit multiplier. The result is accumulated with previous result. Figure 12 shows array MAC module.

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Figure 12: Array MAC module

# 6. RESULTS

The simulation results for 16-bit Radix-2 modified Booth algorithm with SPST adder multiplier and MAC are shown in figures 13 and 14 respectively. The simulation results for 16-bit array multiplier and MAC are shown in figures 15 and 16 respectively.

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Figure 13: Simulation results for a 16-bit multiplier using radix-2 modified Booth algorithm with SPST adder

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INPUT CLOCK	-													
/TOP_MAC/MBA/clock	StO													
SYSTEM RESET														
👉 /TOP_MAC/rst	StO													
INPUTS X & Y	-													
👉 /TOP_MAC/X	-3	0				1		2		3		4		5
🖕 /TOP_MAC/Y	2	0				1		2		3		4		5
OUTPUT OF BOOTH ENCODING														
/TOP_MAC/MBA/PP_out_final1	0000000000000011	0000000	0000000	000		0000000	0000	1111111	1111	1111111	1111	0000000	0000	0000000000000
/TOP_MAC/MBA/PP_out_final2	111111111111111110	0000000	0000000	000				0000000	0000	0000000	0000	0000000		000000000000
/TOP_MAC/MBA/PP_out_final3	000000000000000000000000000000000000000	0000000	0000000	000										
/TOP_MAC/MBA/PP_out_final4	000000000000000000000000000000000000000	0000000	0000000	000										
/TOP_MAC/MBA/PP_out_final5	000000000000000000000000000000000000000	0000000	0000000	000										
/TOP_MAC/MBA/PP_out_final6	000000000000000000000000000000000000000	0000000	0000000	000										
/TOP_MAC/MBA/PP_out_final7	000000000000000000000000000000000000000	0000000	0000000	000										
/TOP_MAC/MBA/PP_out_final8	000000000000000000000000000000000000000	0000000	0000000	000										
MULTIPLICATION OUTPUT [X * Y]														
/TOP_MAC/MBA/Final_OUT	-6	lo 👘				1		4		19		116		25
ACCUMULATOR														
✓ /TOP MAC/acc	209	-x	0				Ĭ1		)5		J14		)30	
FINAL OUTPUT[(X * Y + ACC)]														
/TOP_MAC/Result	209	io –				1		15		14		130		55

Figure 14: Simulation results for a 16-bit multiplier and accumulator using radix-2 modified Booth algorithm and SPST adder

Current Simulation Time: 1000 ns		20	10	4(	0	61	0	80	0
🗄 🚮 p[31:0]	3	Q 32%00000002	321100000020	32'h00000010	32'h00000000	32'h00000008	32'h00000050	32%0000001C	32%00000020
🗄 👧 a(15:0)	1	0 16%0002	16%0004	16'h0008	16'h0000	16'h0004	16'h0010	16'h0002	16'h0008
🗄 👧 b(15:0)	1	0 16%0001	16'h0008	16'h0002	16'h0014	16'h0002	16'h0005	16'h000E	16'h0004

Figure 15: Simulation results for a 16- bit array multiplier

Current Simulation Time: 1000 ns		0	200		400	E	600 		800	
🗉 刻 multipli	3	32%00000000	32%00000	00C X	32'h0000	0010 X	32'h0000	0008	32'h000	00003
🏽 🚮 finalout[33:0]	3	34'hXXXXXXXXXX	34'h0000	00000	34'h000	1000010	X 34'h000	000018	34'h00	00000
👌 Clk	0									
👌 rst	0									
🎞 🚮 x[15:0]	1	16'h0000	16'h00	04	16'h00	08	16'h00	02	16'h0	001
🎟 🚮 y[15:0]	1	16%0000	16'h00	16%0003		16'h0002		X 16'h0004		003

Figure 16: Simulation results for a 16- bit array multiplier and accumulator

Table 2 shows the synthesis report for array MAC and radix-2 modified Booth algorithm with SPST adder MAC. Table 3 shows the comparisons of power consumption and delay of the array MAC and radix-2 modified Booth algorithm with SPST adder MAC. The code is dumped onto

the target device Spartan 3E (Xc3s500eft256 -4), inputs (Set frequency of asynchronous nets as10MHz), signals (Set frequency of asynchronous nets as10MHz) and outputs (Set capacitive load of outputs as 28000 pf).

Device parameters	Array MAC	SPST MAC
Number of Slices	365 out of 14752	587 out of 14752
Number of Slice Flip Flops	34 out of 29504	34 out of 29504
Number of 4 input LUTs	636 out of 29504	1093 out of 29504
Number of IOs	100	100
Number of bonded IOBs	100 out of 250	100 out of 250
Number of GCLKs	1 out of 24	1 out of 24

Table 2: Synthesis report for array MAC and SPST MAC

Table 3: Comparison of radix-2 modified Booth algorithm with SPST adder MAC and array MAC

Multiplier type	Array multiplier and accumulator	Radix-2 modified Booth algorithm with SPST adder multiplier and accumulator		
Vendor	Xilinx	Xilinx		
Device and family	Spartan3E xc3s500eft256-4	Spartan3E xc3s500eft256-4		
Estimated delay(ns)	217.8	39.69		
<b>Power consumption</b> (mw)	154	144		

# 7. CONCLUSION

The SPST adder avoids the unwanted glitches and thus minimizes the switching power dissipation. Radix -2 modified booth algorithm reduces the number of partial products to half by grouping of bits from the multiplier term, which improves the speed. The implemented radix-2 modified Booth algorithm MAC with SPST gives a factor of 5 less delay and 7% less power consumption as compared to array MAC.

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