

Vanderbilt University School of Engineering

# EECE/CS 4353 Image Processing

Lecture Notes: Color Correction

### Richard Alan Peters II Department of Electrical and Computer Engineering Fall Semester 2021



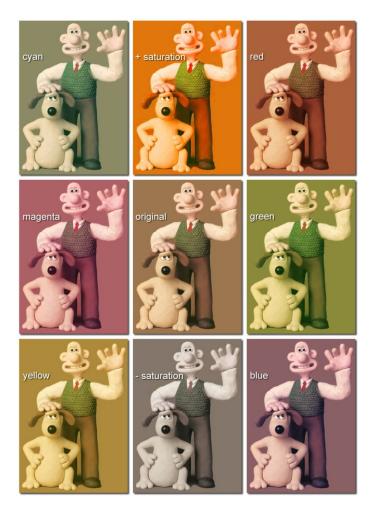
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## Color Correction

is a global change in the coloration of an image to alter its tint, its hues, or the saturation of its colors with minimal changes to its luminant features.

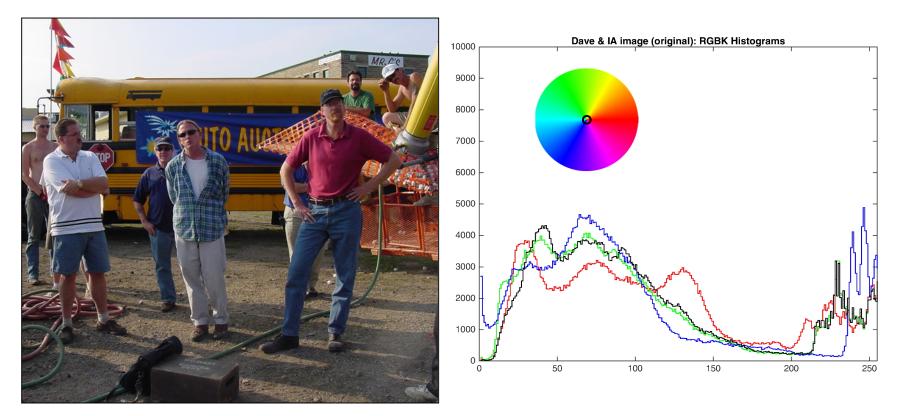




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original

## Gamma Adjustment of Color Bands



David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



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red  $\gamma$ =2

## Gamma Adjustment of Color Bands

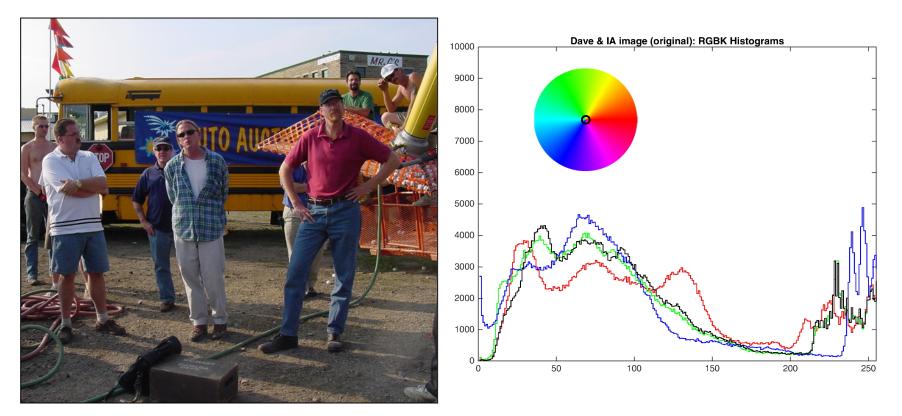




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original

## Gamma Adjustment of Color Bands



David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



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red  $\gamma = 0.5$ 

## Gamma Adjustment of Color Bands

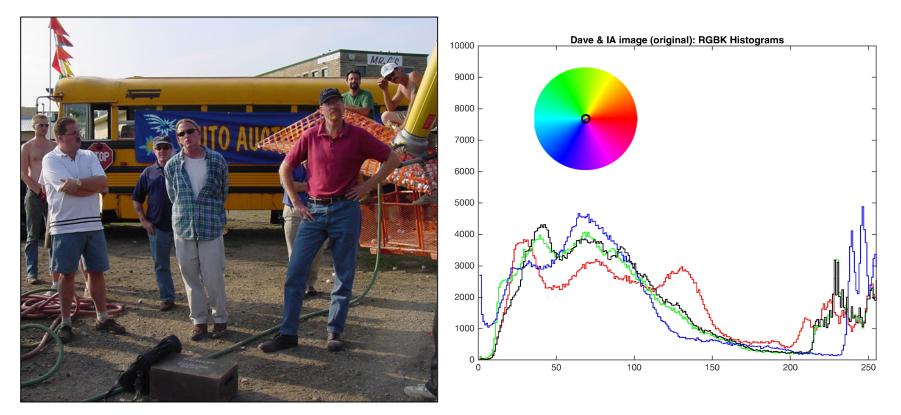




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original

## Gamma Adjustment of Color Bands



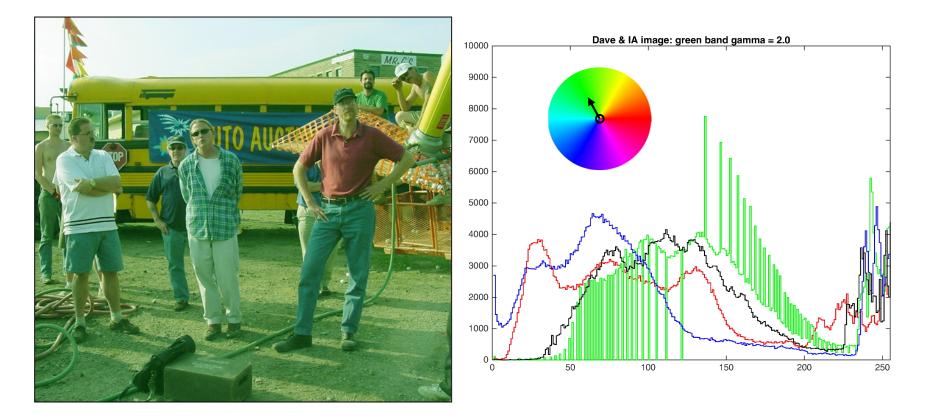
David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



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green γ=2

## Gamma Adjustment of Color Bands

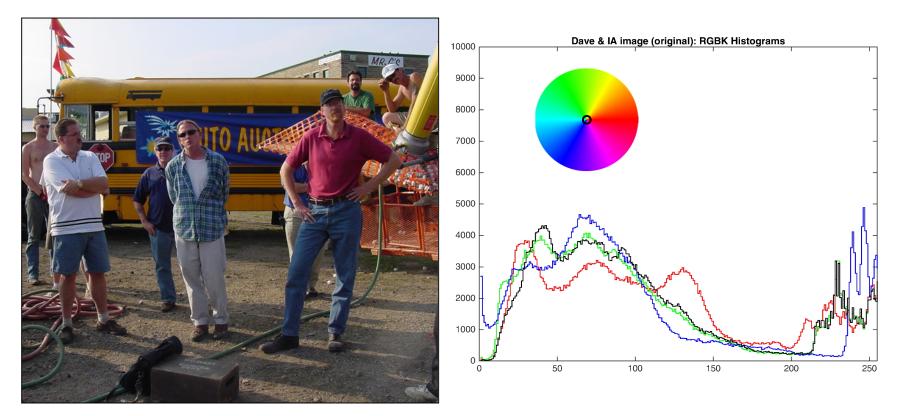




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original

## Gamma Adjustment of Color Bands



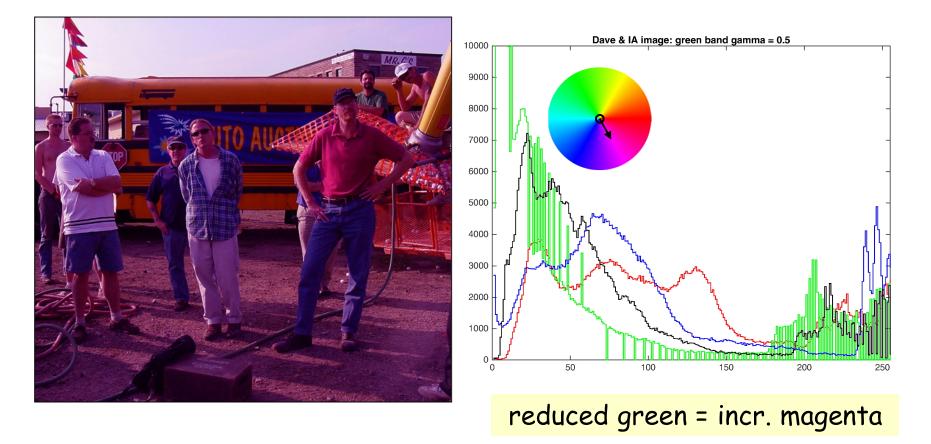
David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



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green  $\gamma$ =0.5

## Gamma Adjustment of Color Bands

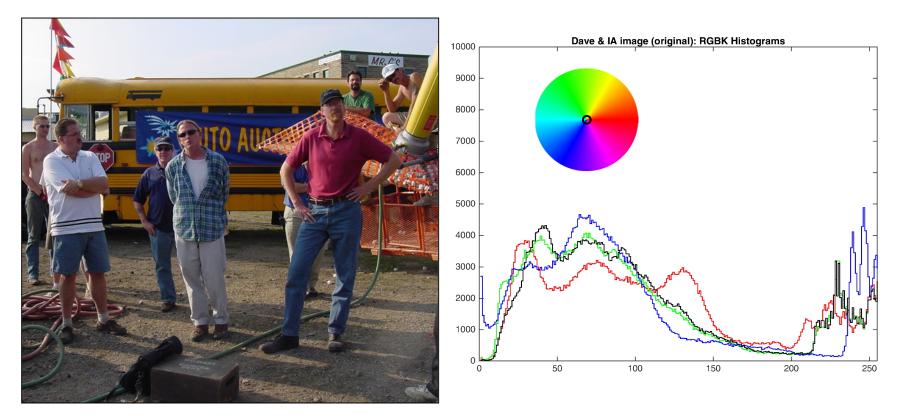




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original

## Gamma Adjustment of Color Bands



David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



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blue  $\gamma$ =2

## Gamma Adjustment of Color Bands

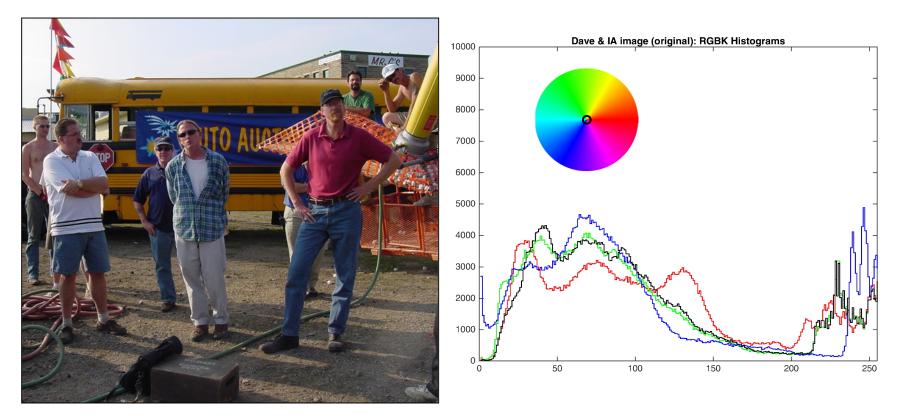




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original

## Gamma Adjustment of Color Bands



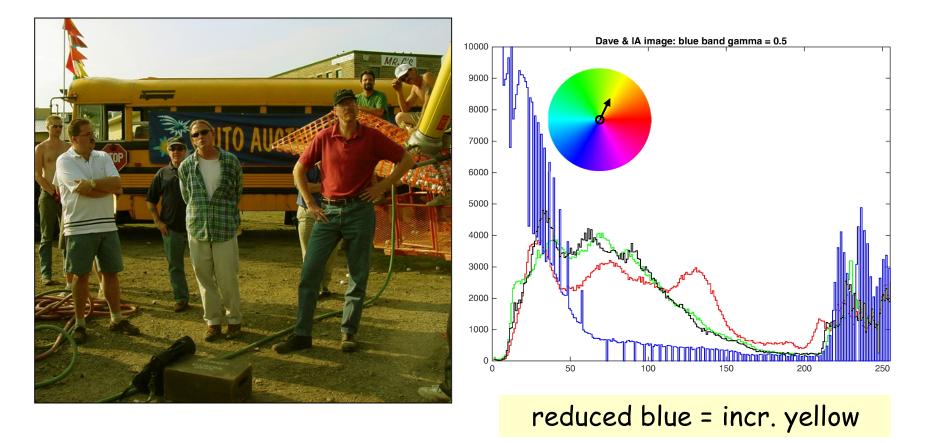
David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



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blue  $\gamma$ =0.5

## Gamma Adjustment of Color Bands

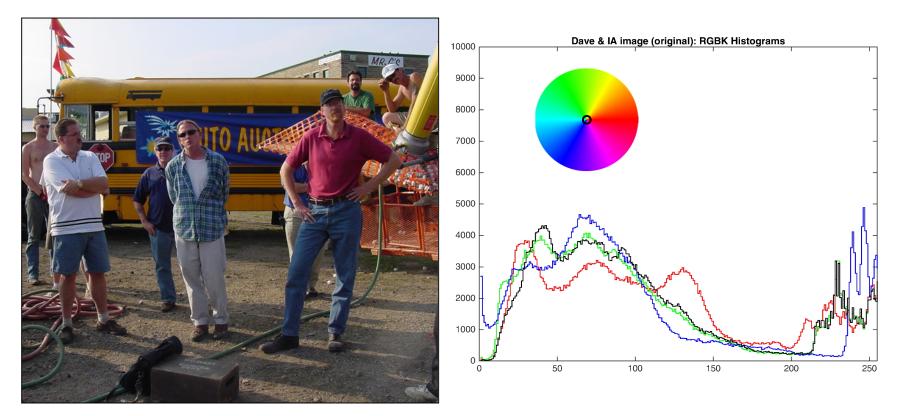




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original

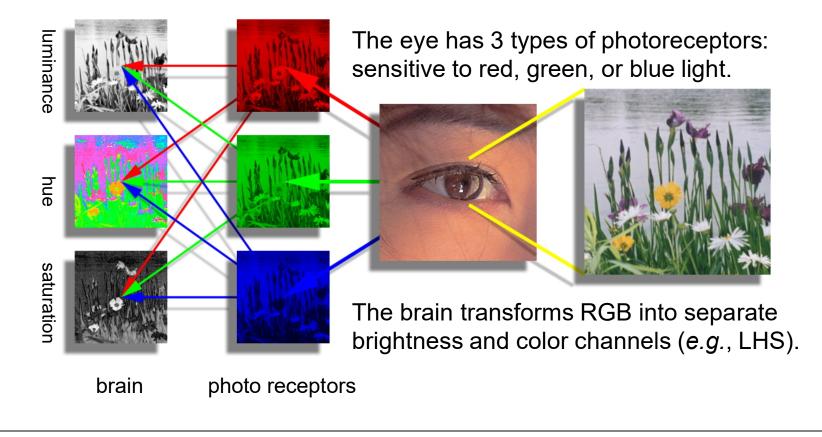
## Gamma Adjustment of Color Bands



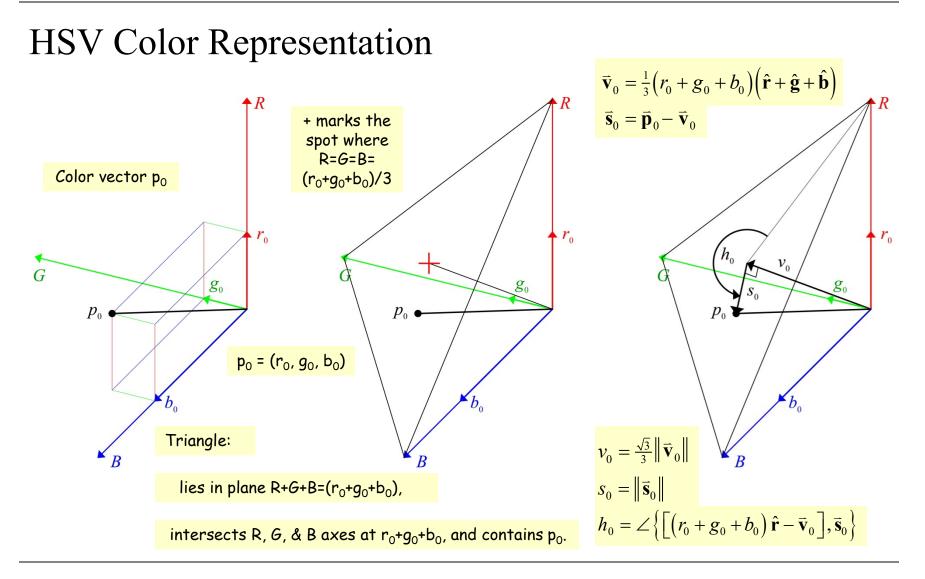
David Peters, producer, and representatives of the IA, The International Alliance of Theatrical Stage Employees, Moving Picture Technicians, Artists and Allied Crafts, on the set of *Frozen Impact* (PorchLight Entertainment, 2003).



## RGB to LHS: A Perceptual Transformation









## A Fast RGB to HSV Algorithm

Given color  $\mathbf{p} = [R \ G \ B]^T$  where  $R, G, B \in \{0, ..., 255\}$ , to compute [h s v]<sup>T</sup> where s, v  $\in [0,1]$  and h  $\in [0,360)$  the algorithm proceeds as follows:

Compute [r g b] = [R G B]/255.
 Set m = min(r,g,b) , M = max(r,g,b).
 Set v = M.
 Compute C = M - m.
 If C == 0 then s=0, h=0. Return [h s v]<sup>T</sup>.
 s = C/M.
 If M==r then h = ((g-b)/c) modulo 6.
 else if M==g then h = 2 + (b-r)/c.
 else h = 4 + (r-g)/c.
 h = 60h.

R,G,B are numbers here not images.

Experiments with Matlab show this algorithm to be 3 times faster than Algorithm 1 and 1.13 faster than Algorithm 2 (EECE\_4353\_06\_RGBandHSVColor). The numbers output by this one differ from the other two.

Reference: HSL and HSV - Wikipedia, the free encyclopedia



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# HSV to RGB Conversion

Therefore, the rotation matrix is

$$A = \frac{\sqrt{6}}{6} \begin{bmatrix} 2 & 0 & \sqrt{2} \\ -1 & \sqrt{3} & \sqrt{2} \\ -1 & -\sqrt{3} & \sqrt{2} \end{bmatrix}.$$

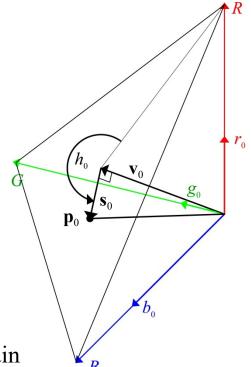
Substitute that into the  $2^{nd}$  equation on slide <u>94</u> to get:

$$\begin{bmatrix} \mathbf{s} \end{bmatrix}_{\mathbf{rgb}} = s \frac{\sqrt{6}}{6} \cos(h) \begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix} + s \frac{\sqrt{2}}{2} \sin(h) \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} + 0 \frac{\sqrt{3}}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$
$$= s \frac{\sqrt{6}}{6} \cos(h) \begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix} + s \frac{\sqrt{2}}{2} \sin(h) \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}.$$

Finally,  $[s]_{rgb}$  must be translated to the value vector to obtain the rgb color of  $\mathbf{p}_0$ :

$$\mathbf{p}_0 = [\mathbf{p}]_{rgb} = [\mathbf{s}]_{rgb} + [\mathbf{v}]_{rgb}$$
, where  $\mathbf{s}_0 = [\mathbf{s}]_{rgb}$  and  $[\mathbf{v}]_{rgb} = \mathbf{v}_0$  as def'd. on slide 81.

The x, y, & z unit vectors in r, g, & b coordinates are the columns of the rotation matrix:





## A Fast HSV to RGB Algorithm

Given vector  $\mathbf{h}^{\mathrm{T}} = [h \ s \ v]$  where  $h \in [0, 360), s \in [0, 1]$ , and  $v \in [0, 1]$ , to compute  $\mathbf{p}^{\mathrm{T}} = [r \ g \ b]$  where  $r, g, b \in \{0, ..., 255\}$ :

1. $H = h/60$ .
2. $C = v \cdot s$ .
3. $D = v - C$ .
4. $X = C \cdot (1 -   (H \mod 2) - 1  )$ .
5. if $0 \le H < 1$ then [r g b] = [C X 0]
else if $1 \le H < 2$ then [r g b] = [X C 0]
else if $2 \le H < 3$ then [r g b] = [0 C X]
else if $3 \le H < 4$ then [r g b] = [0 X C]
else if $4 \le H < 5$ then [r g b] = [X 0 C]
else if $5 \le H < 6$ then [r g b] = [C 0 X]
else [r g b] = [0 0 0]
6. [r g b] = 255*[r+D g+D b+D]

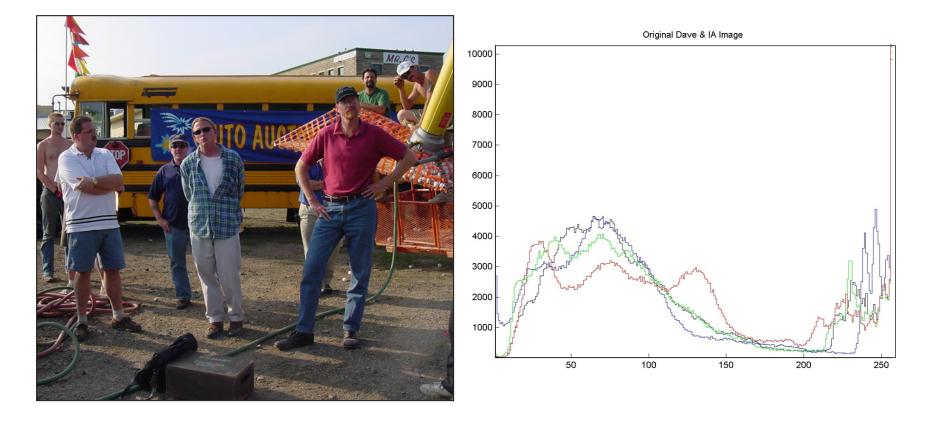
h, s, & v are numbers here not images.

Reference: HSL and HSV - Wikipedia, the free encyclopedia



### Saturation Adjustment

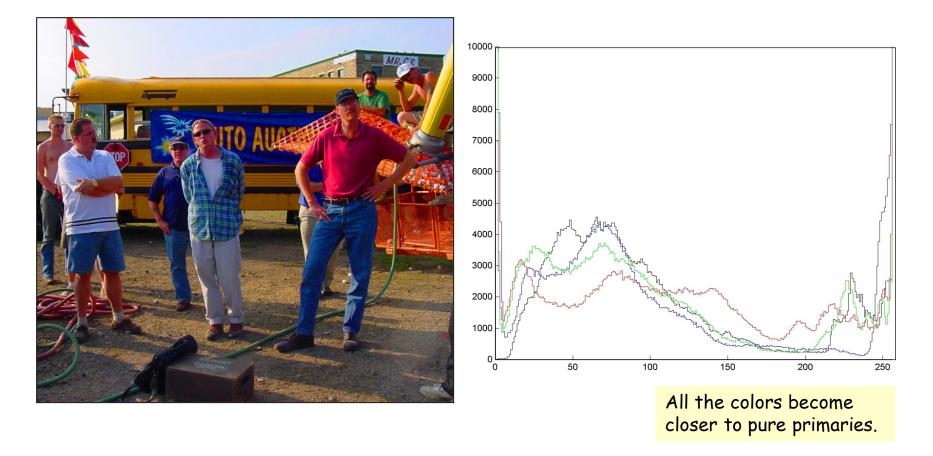






## Saturation Adjustment

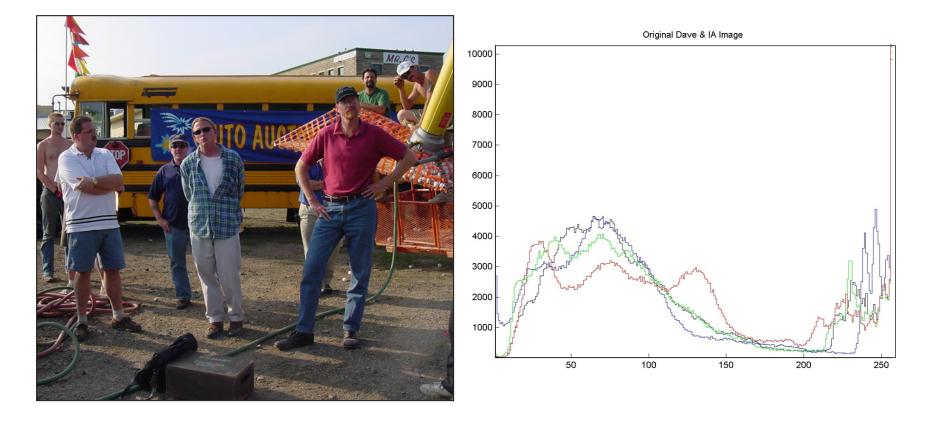
saturation + 50%





### Saturation Adjustment

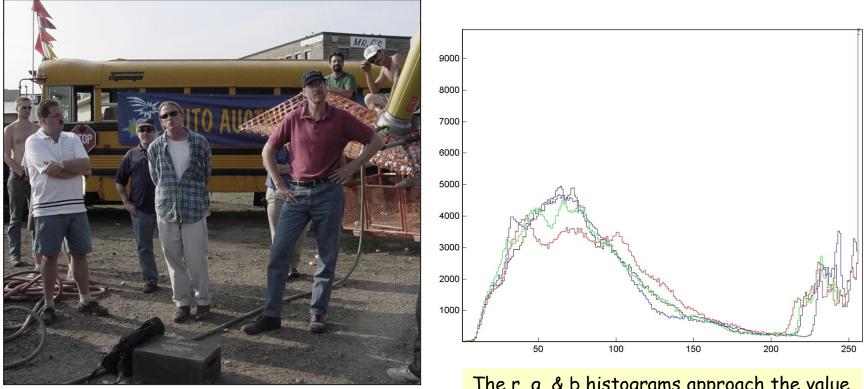






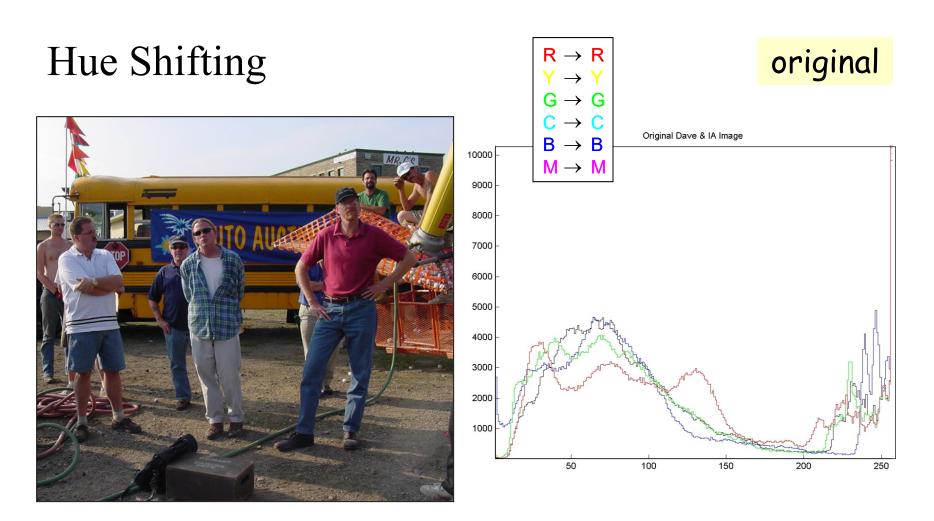
## Saturation Adjustment

saturation - 50%



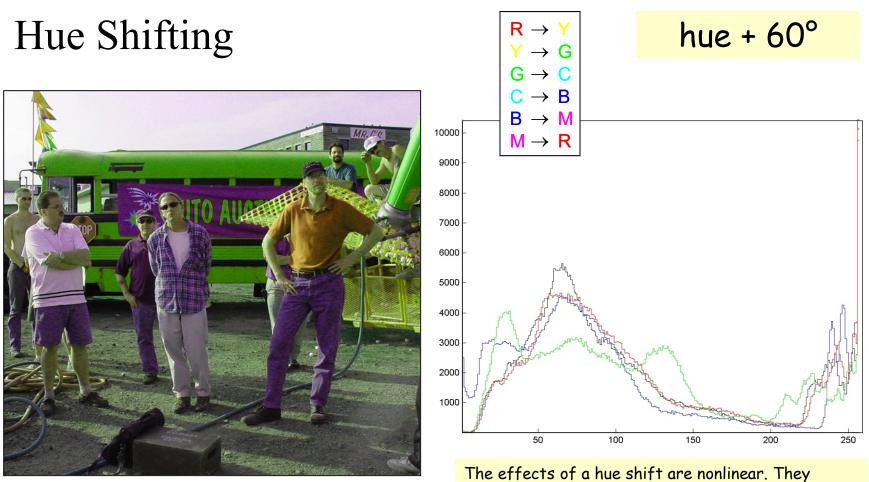
The r, g, & b histograms approach the value histogram as the color fades to grayscale.





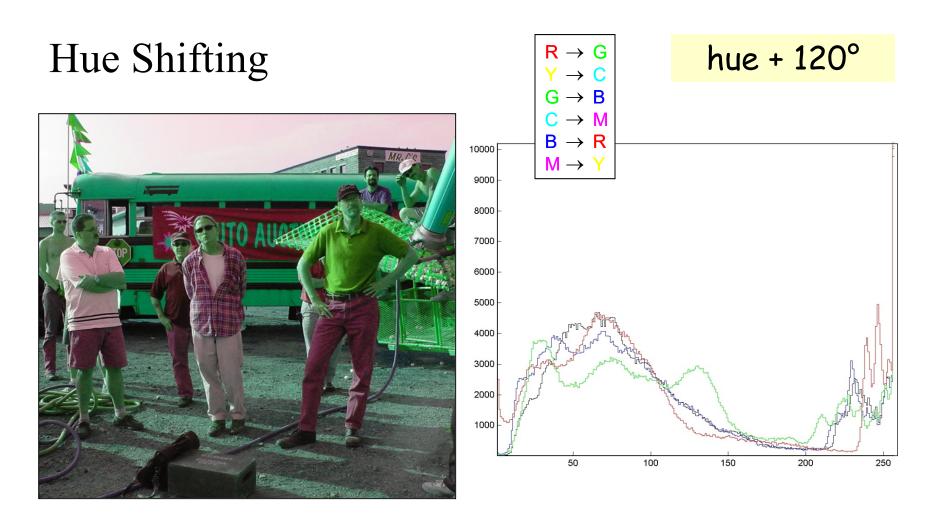


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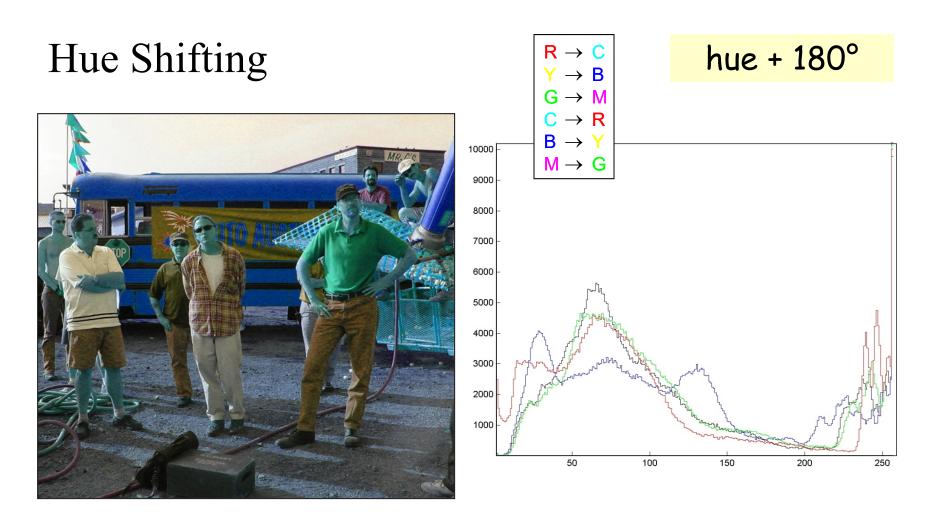


difficult to characterize on the r, g, & b histograms

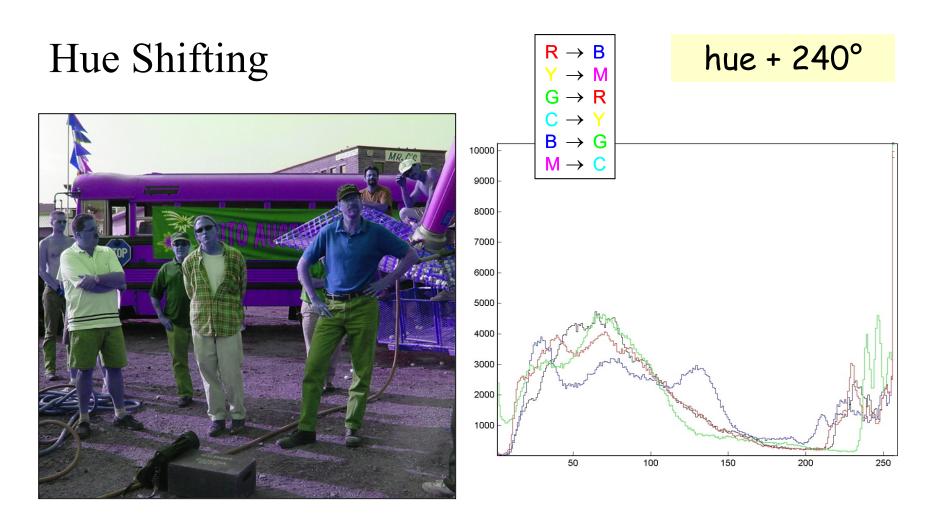




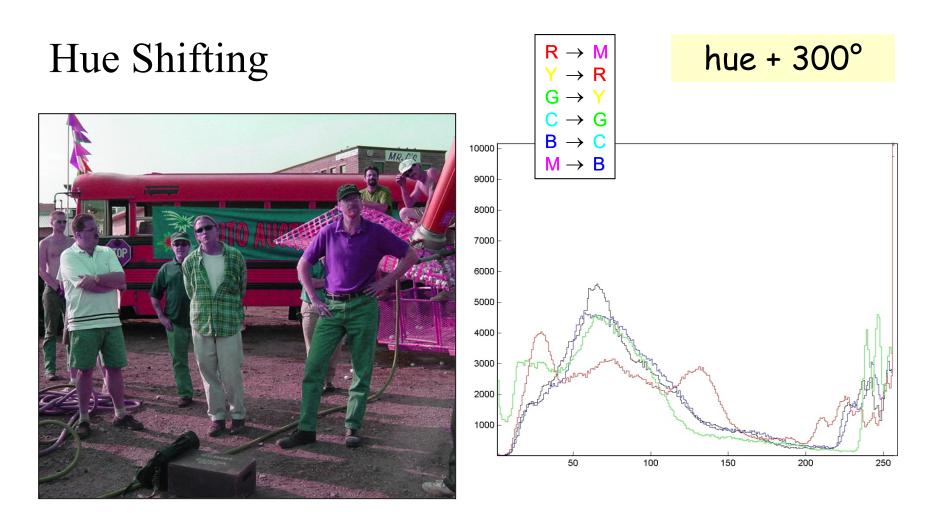




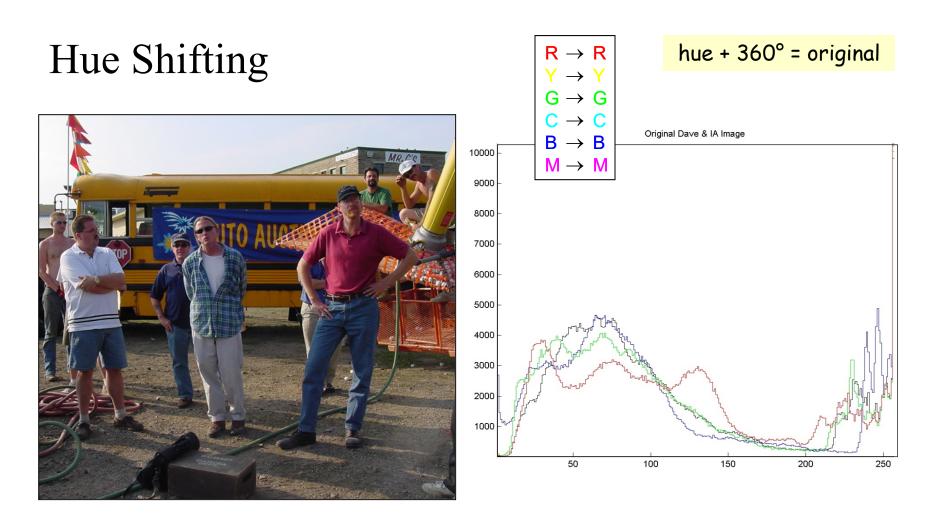




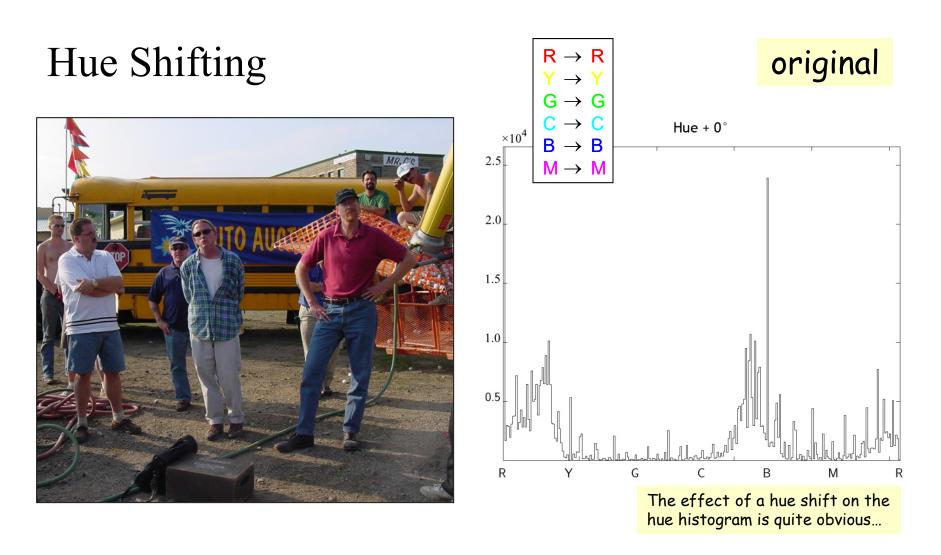




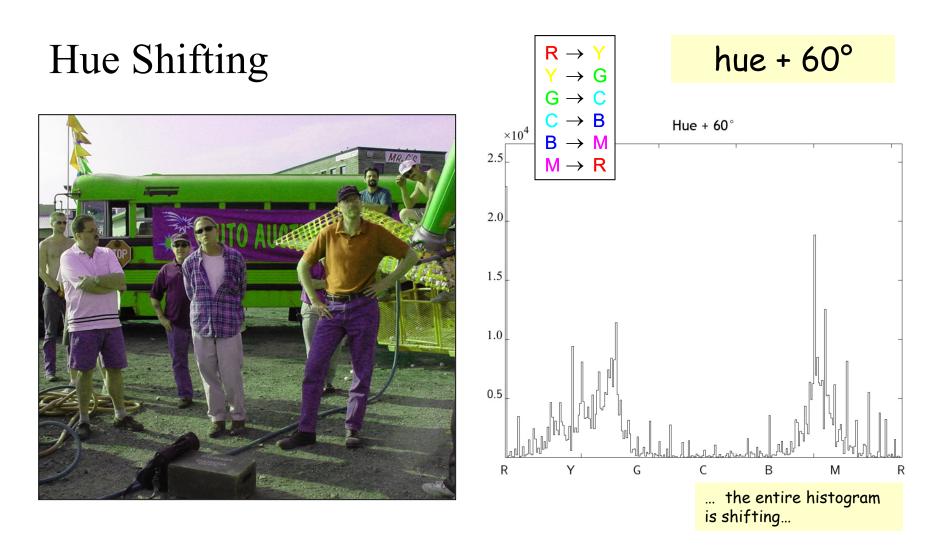




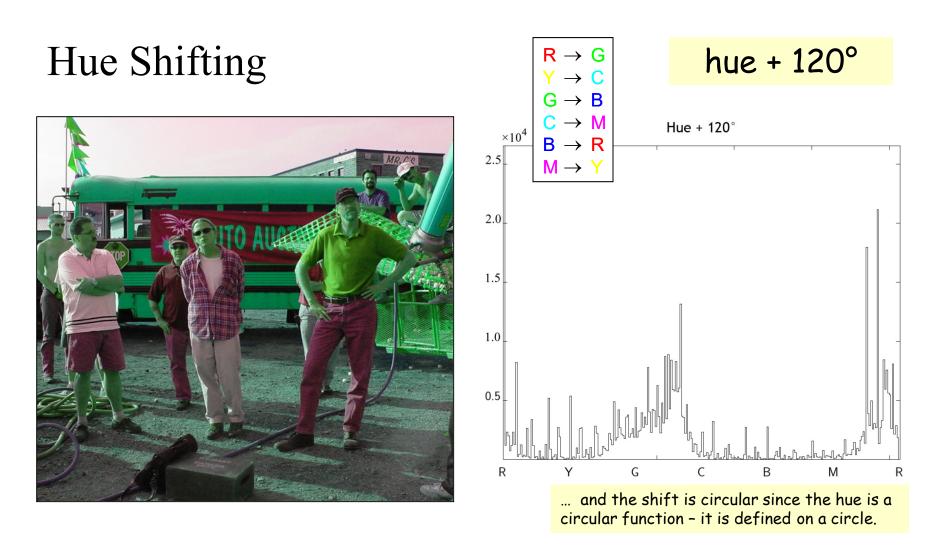




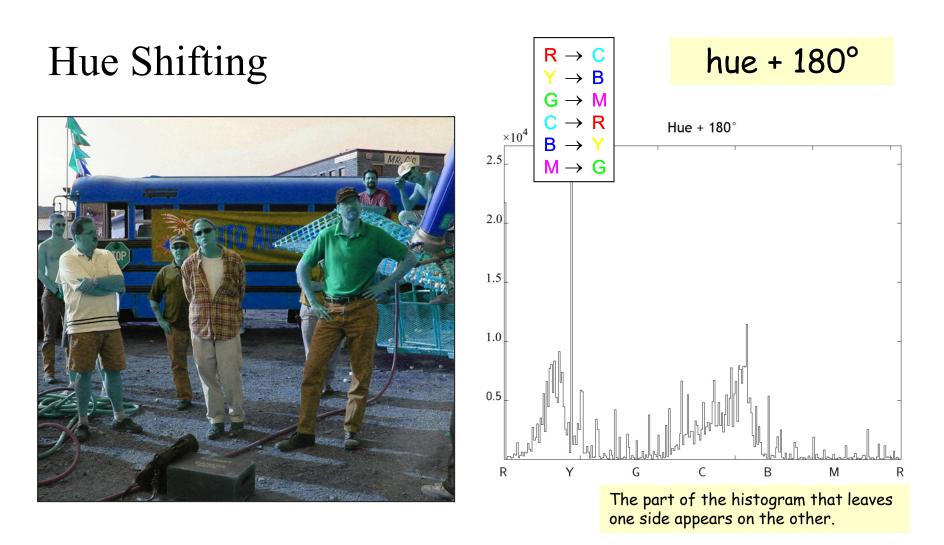




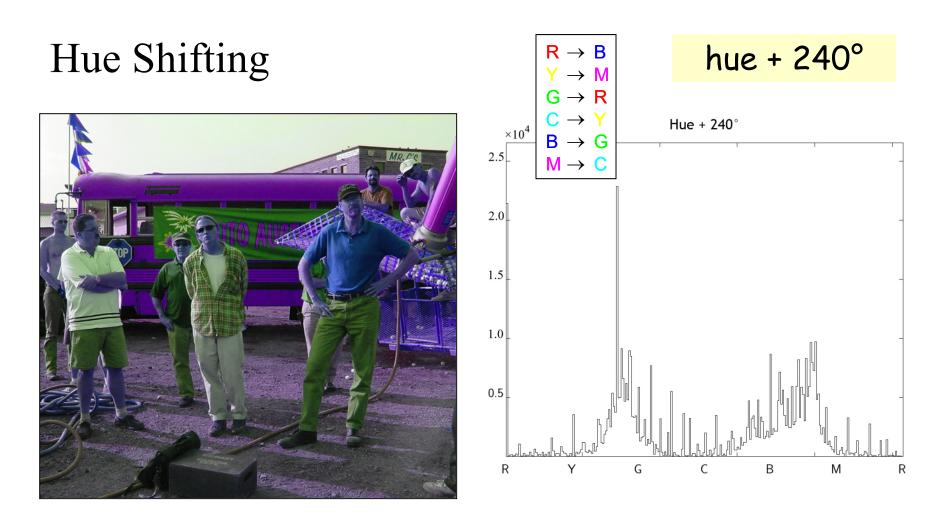




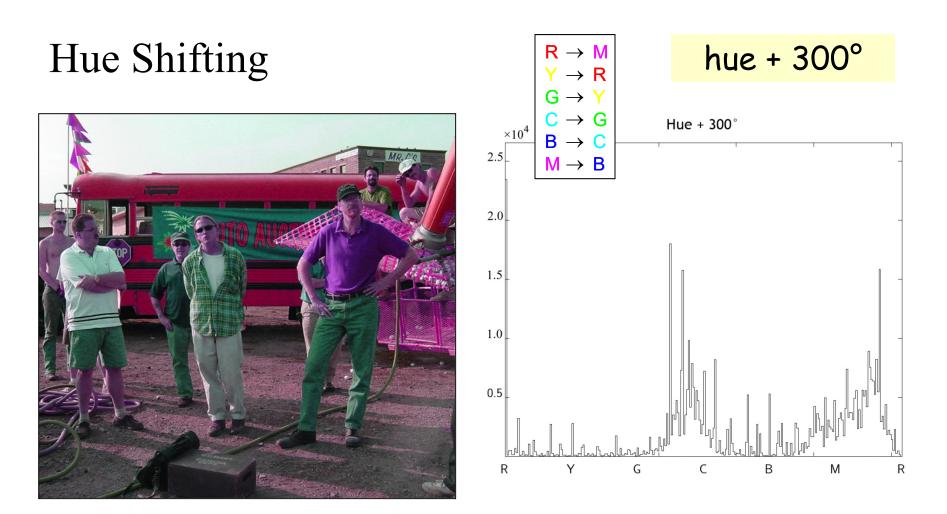




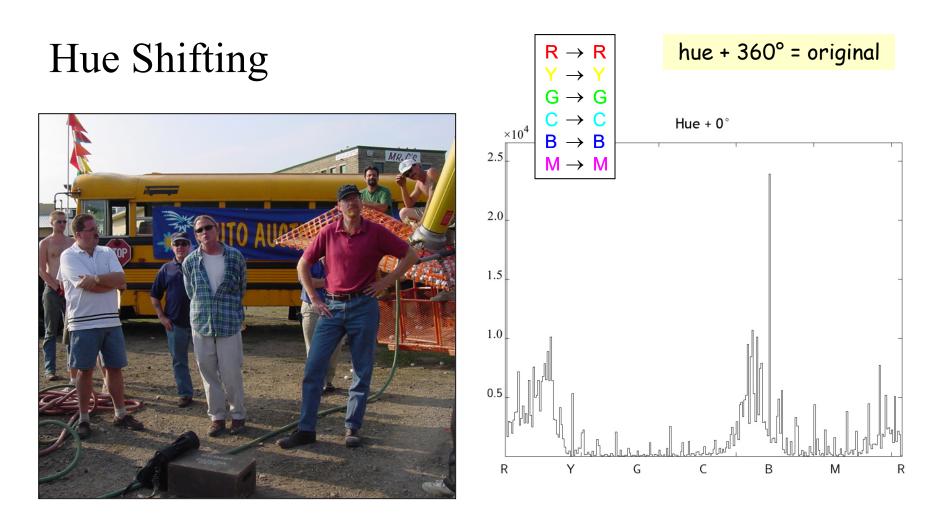














#### Linear Transformation of Color

#### EECE 4353 Image Processing





## Color Correction via Linear Transformation

is a point process; the transformation is applied to each pixel as a function of its color alone.

$$\mathbf{J}(r,c) = \Phi[\mathbf{I}(r,c)], \quad \forall (r,c) \in \operatorname{supp}(\mathbf{I}).$$

Each pixel is vector valued, therefore the transformation is a vector space operator.

$$\mathbf{I}(r,c) = \begin{bmatrix} \mathbf{R}_{\mathbf{I}}(r,c) \\ \mathbf{G}_{\mathbf{I}}(r,c) \\ \mathbf{B}_{\mathbf{I}}(r,c) \end{bmatrix}, \ \mathbf{J}(r,c) = \begin{bmatrix} \mathbf{R}_{\mathbf{J}}(r,c) \\ \mathbf{G}_{\mathbf{J}}(r,c) \\ \mathbf{B}_{\mathbf{J}}(r,c) \end{bmatrix} = \Phi \left\{ \mathbf{I}(r,c) \right\} = \Phi \left\{ \begin{bmatrix} \mathbf{R}_{\mathbf{I}}(r,c) \\ \mathbf{G}_{\mathbf{I}}(r,c) \\ \mathbf{B}_{\mathbf{I}}(r,c) \end{bmatrix} \right\}.$$



## Color Vector Space Operators

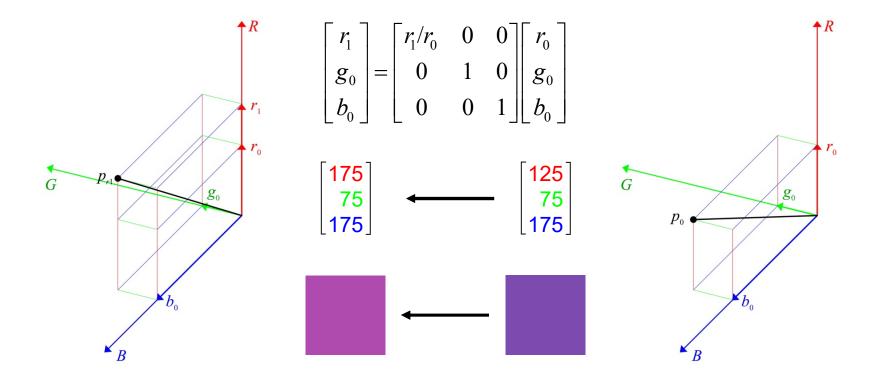
Linear operators are matrix multiplications

$$\begin{bmatrix} r_1 \\ g_1 \\ b_1 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} r_0 \\ g_0 \\ b_0 \end{bmatrix}$$

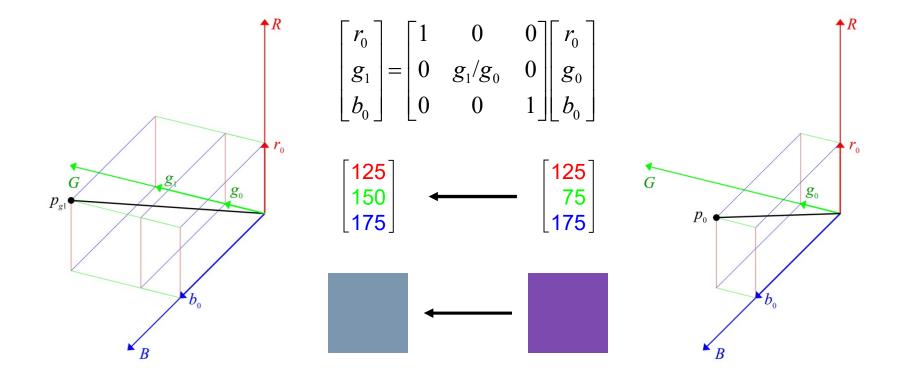
$$\begin{bmatrix} r_{1} \\ g_{1} \\ b_{1} \end{bmatrix} = 255 \cdot \begin{bmatrix} (r_{0} / 255)^{1/\gamma_{r}} \\ (g_{0} / 255)^{1/\gamma_{g}} \\ (b_{0} / 255)^{1/\gamma_{b}} \end{bmatrix}$$

Example of a nonlinear operator: gamma correction

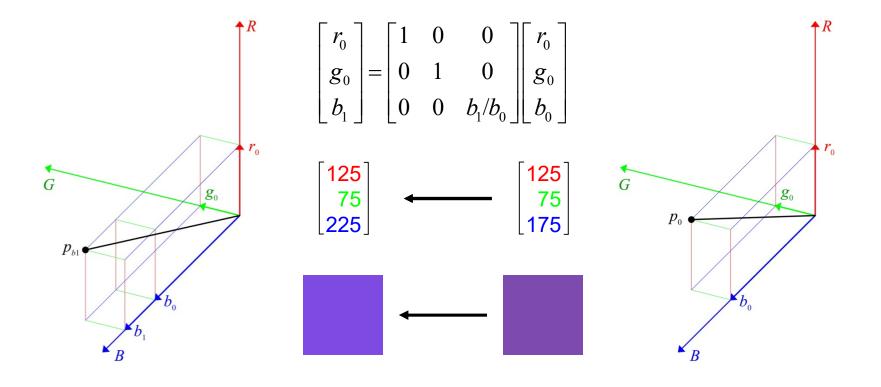




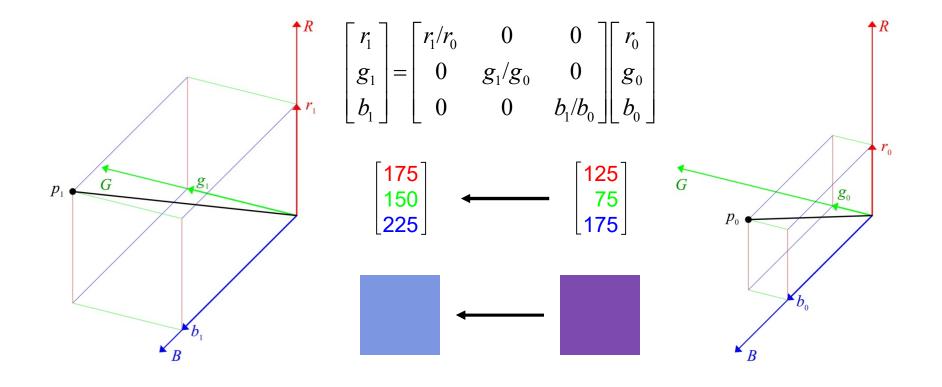














## **Color Transformation**

Assume **J** is a discolored version of image **I** such that  $\mathbf{J} = \Phi[\mathbf{I}]$ . If  $\Phi$  is linear then it is represented by a 3×3 matrix, **A**:

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}.$$

Then  $\mathbf{J} = \mathbf{AI}$  or, more accurately,  $\mathbf{J}(r,c) = \mathbf{AI}(r,c)$  for all pixel locations (r,c) in image I.  $\mathbf{I}(r,c) \in \mathbb{Z}^3$ .



## **Color Transformation**

Each color in the output vector is a linear combination of the colors in the input vector.

If at pixel location (r,c), image  $\mathbf{I}(r,c) = \begin{bmatrix} \rho_{\mathbf{I}} \\ \gamma_{\mathbf{I}} \\ \beta_{\mathbf{I}} \end{bmatrix}$  and image  $\mathbf{J}(r,c) = \begin{bmatrix} \rho_{\mathbf{J}} \\ \gamma_{\mathbf{J}} \\ \beta_{\mathbf{J}} \end{bmatrix}$ , image  $\mathbf{J}(r,c) = \begin{bmatrix} \rho_{\mathbf{J}} \\ \gamma_{\mathbf{J}} \\ \beta_{\mathbf{J}} \end{bmatrix}$ ,  $\begin{aligned}
\text{then} \quad \mathbf{J}(r,c) = \mathbf{A}\mathbf{I}(r,c), \text{ or} \\
\begin{bmatrix} \rho_{\mathbf{J}} \\ \gamma_{\mathbf{J}} \\ \beta_{\mathbf{J}} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} \rho_{\mathbf{I}} \\ \gamma_{\mathbf{I}} \\ \beta_{\mathbf{I}} \end{bmatrix} \\
= \begin{bmatrix} a_{11}\rho_{\mathbf{I}} + a_{12}\gamma_{\mathbf{I}} + a_{13}\beta_{\mathbf{I}} \\ a_{21}\rho_{\mathbf{I}} + a_{22}\gamma_{\mathbf{I}} + a_{23}\beta_{\mathbf{I}} \\ a_{31}\rho_{\mathbf{I}} + a_{32}\gamma_{\mathbf{I}} + a_{33}\beta_{\mathbf{I}} \end{bmatrix}.$ 



## Color Transformation

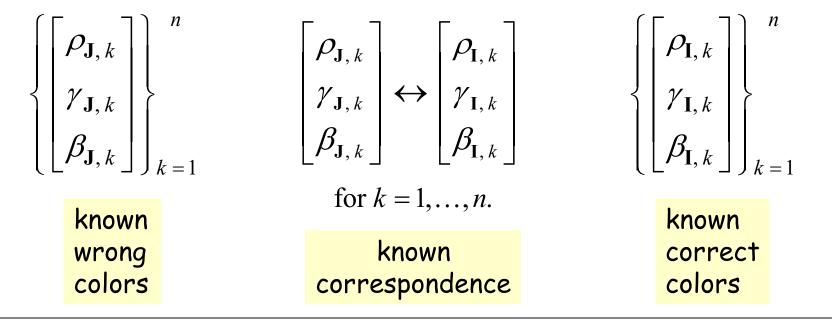
The inverse transform  $\Phi^{-1}$  (if it exists) maps the discolored image, **J**, back into the correctly colored version, **I**, *i.e.*,  $\mathbf{I} = \Phi^{-1}[\mathbf{J}]$ . If  $\Phi$  is linear then it is represented by the inverse of matrix **A**:

$$\mathbf{A}^{-1} = \begin{bmatrix} a_{11}a_{22}a_{33} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33} + & \mathbf{A}^{-1} \text{ may or may not exist.} \\ a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31} \end{bmatrix}^{-1} \bullet \qquad \mathbf{A}^{-1} \text{ may or may not exist.} \\ \begin{bmatrix} a_{22}a_{33} - a_{23}a_{32} & a_{13}a_{32} - a_{12}a_{33} & a_{12}a_{23} - a_{13}a_{22} \\ a_{23}a_{31} - a_{21}a_{33} & a_{11}a_{33} - a_{13}a_{31} & a_{13}a_{21} - a_{11}a_{23} \\ a_{21}a_{32} - a_{22}a_{31} & a_{12}a_{31} - a_{11}a_{32} & a_{11}a_{22} - a_{12}a_{21} \end{bmatrix}.$$



## Color Correction

Assume we know n colors in the discolored image, **J**, that correspond to another set of n colors (that we also know) in the original image, **I**.





## Color Correction

To remap the discolored image so that the result matches the original image in a linearly optimal way, we need to find the matrix, **A**, that minimizes

$$\varepsilon^{2} = \sum_{k=1}^{n} \left\| \begin{bmatrix} \rho_{\mathbf{I},k} \\ \gamma_{\mathbf{I},k} \\ \beta_{\mathbf{I},k} \end{bmatrix} - \mathbf{A}^{-1} \begin{bmatrix} \rho_{\mathbf{J},k} \\ \gamma_{\mathbf{J},k} \\ \beta_{\mathbf{J},k} \end{bmatrix} \right\|^{2}$$



## Color Correction

To find the solution of this problem, let

$$\mathbf{Y} = \begin{bmatrix} \begin{bmatrix} \rho_{\mathbf{I},1} \\ \gamma_{\mathbf{I},1} \\ \beta_{\mathbf{I},1} \end{bmatrix} \cdots \begin{bmatrix} \rho_{\mathbf{I},n} \\ \gamma_{\mathbf{I},n} \\ \beta_{\mathbf{I},n} \end{bmatrix} \end{bmatrix}, \text{ and } \mathbf{X} = \begin{bmatrix} \begin{bmatrix} \rho_{\mathbf{J},1} \\ \gamma_{\mathbf{J},1} \\ \beta_{\mathbf{J},1} \end{bmatrix} \cdots \begin{bmatrix} \rho_{\mathbf{J},n} \\ \gamma_{\mathbf{J},n} \\ \beta_{\mathbf{J},n} \end{bmatrix} \end{bmatrix}.$$

Then **X** and **Y** are known  $3 \times n$  matrices such that

$$\mathbf{Y} \approx \mathbf{A}^{-1} \mathbf{X},$$

where A is the  $3 \times 3$  matrix that we want to find.



## Color Correction

The linearly optimal solution is the least mean squared solution that is given by

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^{\mathsf{T}} \left(\mathbf{X}\mathbf{X}^{\mathsf{T}}\right)^{-1}$$

where  $\mathbf{X}^{\mathsf{T}}_{n\times 3}$  represents the transpose of matrix  $\mathbf{X}_{3\times n}$ .

Notes: 1. *n*, the number of color pairs, must be  $\geq 3$ ,

2.  $[\mathbf{X}\mathbf{X}^{\mathsf{T}}]_{3\times 3}$  must be invertible, *i.e.*, rank $(\mathbf{X}\mathbf{X}^{\mathsf{T}}) = 3$ ,

3. If 
$$n=3$$
, then  $X^{T}(XX^{T})^{-1} = X^{-1}$ 

important



## Color Correction

The linearly optimal soluti solution that is given by

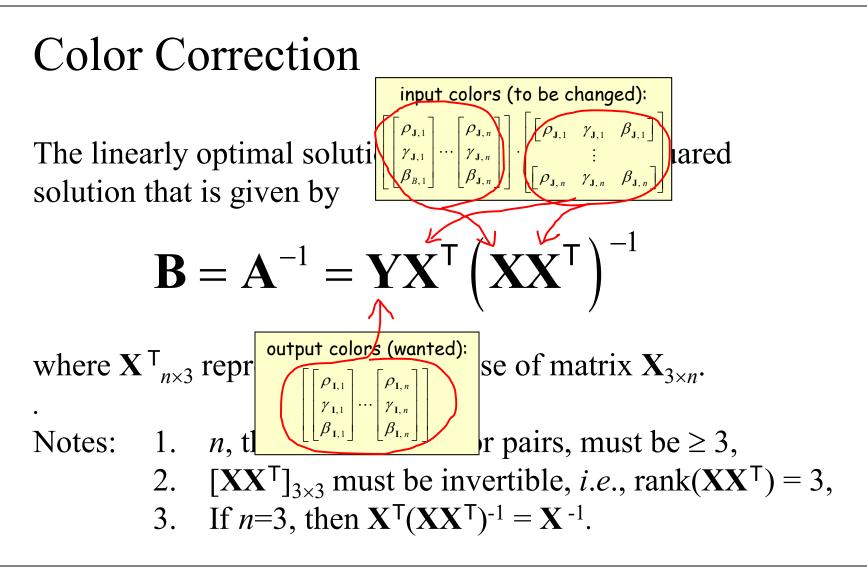
input colors (to be changed):  

$$\begin{bmatrix} \rho_{\mathbf{J},1} \\ \gamma_{\mathbf{J},1} \\ \beta_{B,1} \end{bmatrix} \cdots \begin{bmatrix} \rho_{\mathbf{J},n} \\ \gamma_{\mathbf{J},n} \\ \beta_{\mathbf{J},n} \end{bmatrix} \cdot \begin{bmatrix} \left[ \rho_{\mathbf{J},1} & \gamma_{\mathbf{J},1} & \beta_{\mathbf{J},1} \right] \\ \vdots \\ \left[ \rho_{\mathbf{J},n} & \gamma_{\mathbf{J},n} & \beta_{\mathbf{J},n} \right] \end{bmatrix} \text{ ared}$$

$$\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^{\mathsf{T}}\left(\mathbf{X}\mathbf{X}^{\mathsf{T}}\right)^{-1}$$

where 
$$\mathbf{X}_{n\times 3}^{\mathsf{T}}$$
 represent the set of matrix  $\mathbf{X}_{3\times n}$ .  
Notes: 1. *n*, the set of matrix  $\mathbf{X}_{3\times n}$ .  
2.  $[\mathbf{X}\mathbf{X}^{\mathsf{T}}]_{3\times 3}$  must be invertible, *i.e.*, rank $(\mathbf{X}\mathbf{X}^{\mathsf{T}}) = 3$ ,  
3. If  $n=3$ , then  $\mathbf{X}^{\mathsf{T}}(\mathbf{X}\mathbf{X}^{\mathsf{T}})^{-1} = \mathbf{X}^{-1}$ .







## Color Correction

Then the image is color corrected by performing

$$\mathbf{I}(r,c) = \mathbf{B}\mathbf{J}(r,c), \text{ for all } (r,c) \in \operatorname{supp}(\mathbf{J}).$$

In MATLAB this is easily performed by

```
>> I = reshape(((B*(reshape(double(J),R*C,3))')'),R,C,3);
>> m = min(I(:));
>> M = max(I(:));
>> I = uint8(255*(I-m)/(M-m));
```

where  $\mathbf{B} = \mathbf{A}^{-1}$  is computed directly through the LMS formula on the previous page, and *R* & *C* are the number of rows and columns in the image.



## Color Correction

Then the image is color corrected by performing The first reshape must be as

$$\mathbf{I}(r,c) = \mathbf{B} \, \mathbf{J}(r,c)$$

In MATLAB this is easil R\*C matrix, it will not work.

```
>> I = reshape(((B*(reshape(double(J),R*C,3))')'),R,C,3);

>> m = min(I(:));

>> M = max(I(:));

>> I = uint8(255*(I-m)/(M-

where \mathbf{B}=\mathbf{A}^{-1} is computed dir reshaped to R by C by 3. mula

on the previous page, and R & C are the number of rows and

columns in the image.
```

R\*C rows by 3 columns. Then it

must be transposed to be premultiplied by B. If you



## Color Correction

Then the image is color corrected by performing

$$\mathbf{I}(r,c) = \mathbf{B}\mathbf{J}(r,c), \text{ for all } (r,c) \in \operatorname{supp}(\mathbf{J}).$$

In MATLAB this is easily performed by

>> I = reshape(((B\*(reshape(double(J),R\*C,3))')'),R,C,3);
>> m = min(I(:));
>> M = max(I(:));
>> I = uint8(255\*(I-m)/(M-m));

Depending on the image, you might get better results if you directly convert I to uint8 rather than scaling it first. Try both, and select the version that looks best.

ted directly through the LMS formula nd R & C are the number of rows and



## Linear Color Correction

**Original Image** 

NASA Summer Faculty Fellows at Ellington Air Force Base, Houston, TX, July 2002. Airplane is a T-38.





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## Color Mapping 1

**Original Image** 





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## Color Mapping 2

**Original Image** 





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## Color Mapping 3

**Original Image** 





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## Color Mapping 4

**Original Image** 





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## **Color Transformations**



The aging process was a transformation,  $\Phi$ , that mapped:

$\begin{bmatrix} 17\\122 \end{bmatrix} = \Phi \left\{ \begin{bmatrix} 17\\121 \end{bmatrix} \right\}$		$\begin{bmatrix} 240\\171 \end{bmatrix} = \Phi \left\{ \begin{bmatrix} 240\\171 \end{bmatrix} \right\}$	$\begin{bmatrix} 236\\227 \end{bmatrix} = \Phi \left\{ \begin{bmatrix} 240\\230 \end{bmatrix} \right\}$
	$\begin{bmatrix} 222\\222 \end{bmatrix} = \Phi \left\{ \begin{bmatrix} 222\\222 \end{bmatrix} \right\}$	$ 171  = \Phi \{  171  \}$	$ 227  = \Phi \{  230  \}$
		$\lfloor 103 \rfloor$ $\lfloor 160 \rfloor$	



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## **Color Transformations**



To undo the process we need to find,  $\Phi^{-1}$ , that maps:

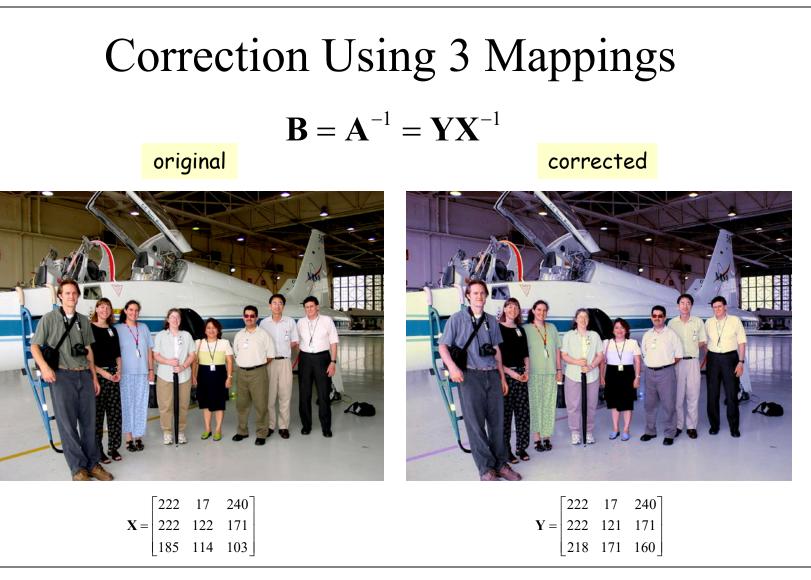
[17]	([ 17 ]]	[222]	[222]]	[240]	[[240]]	[240]	[[236]]
$ 121  = \Phi^{-1}$	{  122   }	$\begin{bmatrix} 222\\222\\218 \end{bmatrix} = \Phi^{-1}$		$ 171  = \Phi^{-}$		$ 230  = \Phi^{-1}$	{  227  }
[171]		218		[160]		$\begin{bmatrix} 240\\230\\166 \end{bmatrix} = \Phi^{-1}$	



# **Correction Using 3 Mappings** $\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^{-1}$

	222	17	240		222	17	240
$\mathbf{X} =$	222	122	171	$\mathbf{Y} =$	222	121	171
	185	114	103		218	171	160







218 171 166

## Another Correction Using 3 Mappings

 $\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^{-1}$ 



185 114 106



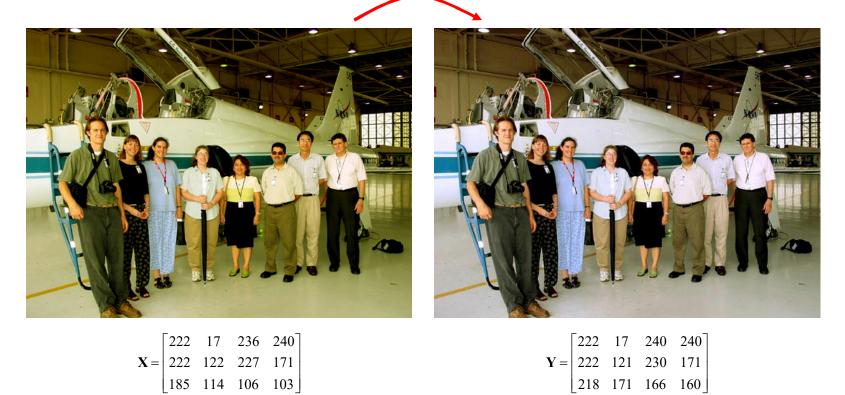
## Another Correction Using 3 Mappings $\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^{-1}$ original corrected

	222	17	236		222	17	240
<b>X</b> =	222	122	227	Y =	222	121	230
	185	114	106		218	171	166



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## Correction Using All 4 Mappings $\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^{\mathsf{T}} \left(\mathbf{X}\mathbf{X}^{\mathsf{T}}\right)^{-1}$





218 171 166 160

## Correction Using All 4 Mappings $\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^{\mathsf{T}} \left(\mathbf{X}\mathbf{X}^{\mathsf{T}}\right)^{-1}$ original corrected



185 114 106 103

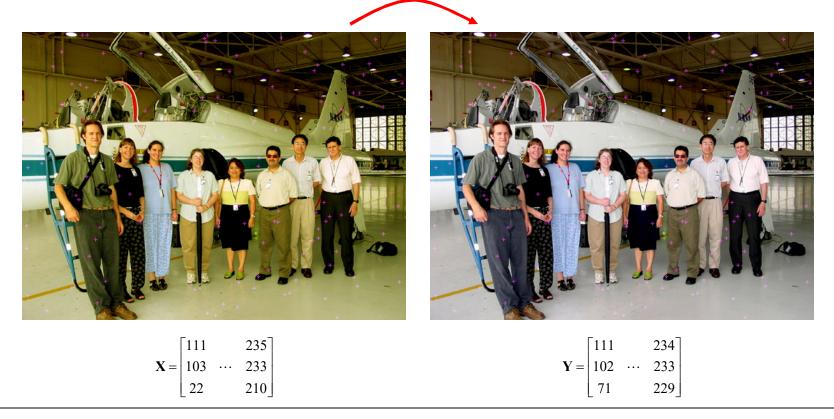


### Random Sampling of Color Values

<pre>&gt;&gt; rr = round(R*rand([1 n])); &gt;&gt; rc = round(C*rand([1 n]));</pre>	R = number of rows in image C = number of columns in image n = number of pixels to select			
>> idx = [rr;rc];				
<pre>&gt;&gt; Y(:,1) = diag(I(rr,rc,1)); &gt;&gt; Y(:,2) = diag(I(rr,rc,2)); &gt;&gt; Y(:,3) = diag(I(rr,rc,3)); &gt;&gt; X(:,1) = diag(J(rr,rc,1));</pre>	rand([1 n]): 1 × n matrix of random numbers between 0 and 1.			
<pre>&gt;&gt; X(:,2) = diag(J(rr,rc,2)); &gt;&gt; X(:,3) = diag(J(rr,rc,3));</pre>	diag(I(rr,rc,1)): vector from main diagonal of matrix I(rr,rc,1).			

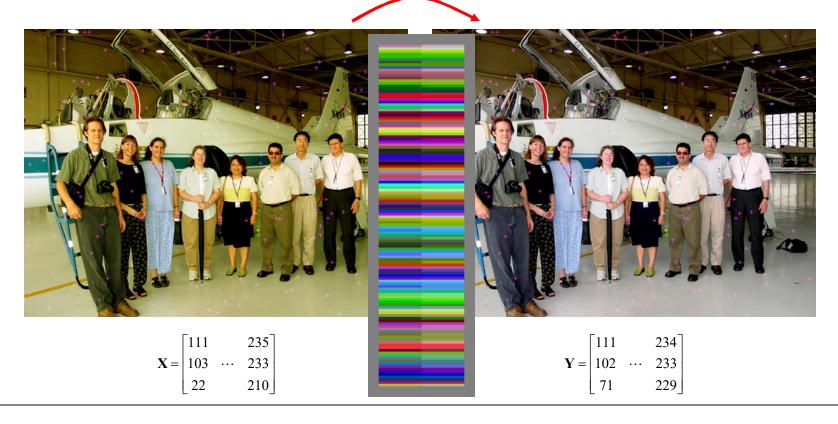


## Correction Using 128 Mappings $\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^{\mathsf{T}} \left(\mathbf{X}\mathbf{X}^{\mathsf{T}}\right)^{-1}$

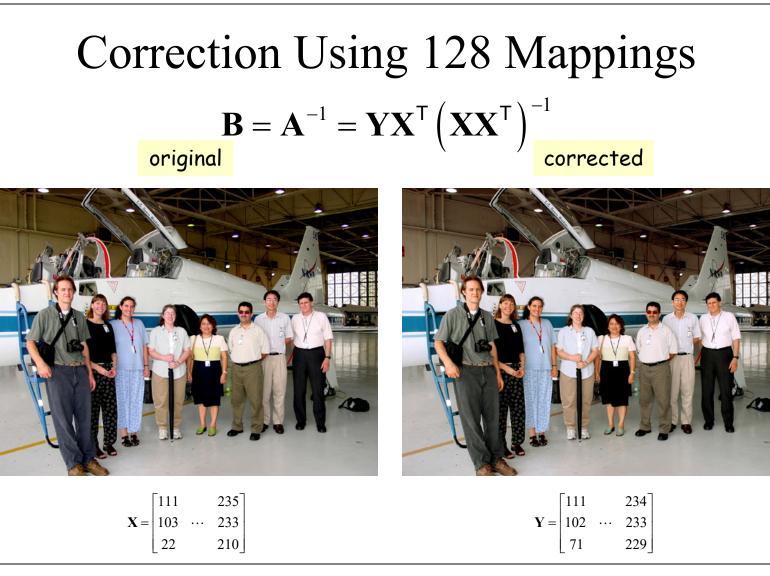


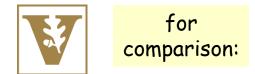


## Correction Using 128 Mappings $\mathbf{B} = \mathbf{A}^{-1} = \mathbf{Y}\mathbf{X}^{\mathsf{T}} (\mathbf{X}\mathbf{X}^{\mathsf{T}})^{-1}$









## $\begin{array}{l} \textbf{Correction Using 4 Mappings} \\ \textbf{B} = \textbf{A}^{-1} = \textbf{Y} \textbf{X}^{\mathsf{T}} \left( \textbf{X} \textbf{X}^{\mathsf{T}} \right)^{-1} \\ \textbf{original} \end{array}$



	222	17	236	240		222	17	240	240
<b>X</b> =	222	122	227	171	$\mathbf{Y} =$	222	121	230	171
	185	114	106	103		218	171	166	160



## MATLAB Linear Color Transformation Function

```
function J = LinTrans(I,B)
    [R C D] = size(I);
    if D ~= 3
       error('Image must have 3 bands');
    end
    I = double(I);
    J = reshape(((B*(reshape(I,R*C,3))'))),R,C,3);
end;
                                   This function returns an image of
                                   class double. To get a good uint8
                                   you may have to linearly scale the
                                   result as shown on slide 55. Or not.
```