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EXPERIMENTAL ANALYSIS OF A CANTILEVER BEAM WITH A SHUNTED PIEZOELECTRIC PERIODIC ARRAY

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ABSTRACT

The use of both shunted piezoelectric elements and periodic arrays have been investigated independently as well as used in conjunction to modify the vibration of a system. Piezoelectric patches bonded to a cantilever beam which are shunted with an active circuit, specifically a negative capacitance shunt, can control broadband flexural vibrations of a structure. Also, periodic arrays integrated into a structure allow for modification of propagating waves through the mechanical “stop-bands”. The performance of a combined shunted periodic piezoelectric patch array will be analyzed here by investigating the velocity amplitude of the beam upstream and downstream of the array section, and the number of control elements in the array. The negative capacitance shunts caused a global spatial average velocity reduction of 5 dB at the modal peaks from 500 to 5000 Hz. The reduction is shown to be greater in the downstream section of the beam. Also, by increasing the number of patches in the array the attenuation of the resonances increased nonlinearly. The results show that a negative capacitance periodic control array is an effective global vibration reduction system and has the ability to localize energy near the forcing of a structure.

INTRODUCTION

Piezoelectric materials have been studied extensively as a means to reduce vibration and noise. Specifically in this paper, the use of negative capacitance shunts connected to a periodic piezoelectric transducer array applied to a cantilever beam will be investigated. Two recent shunt tuning theories have found negative capacitance elements to be necessary for optimal vibration reduction by either reflected wave reduction maximization (Park and Palumbo 2004) or minimization of reactive input power (Cunefare 2006). Theory and experiments have also shown that negative capacitance shunts produce a broadband reduction in vibration amplitude of beam structures (Behrens, Fleming et al. 2001; Park 2005; Park and Baz 2005; Beck, Cunefare et al. 2008).

Forward first suggested the use of an electrical impedance connected across the electrodes of a piezoelectric patch, or shunt, to modify the physical properties of a system to control vibration (Forward 1979). A typical control shunt connected to a piezoelectric patch is shown in Figure 1. Hagood and von Flotow used piezoelectric equations to approximate how a passive (or impedance based active) shunt will modify the material stiffness (Hagood and von Flotow 1991; Park and Palumbo 2004)

$$E_p^{SU}(\omega) = E_p^E \frac{i\omega C_p^T + Y^{SU}}{i\omega C_p^T (1 - k_{31}^2) + Y^{SU}} \quad (1)$$

where $1/Z_e = Y^{SU}$. This equation allowed them to realize that the addition of an inductor would create another degree of freedom. Therefore, the use of a RL shunt demonstrates behavior analogous to a tuned-mass absorber/damper (Hagood and von Flotow 1991; Neubauer, Oleskiewicz et al. 2005). Yet, this type of shunt only has the ability to control vibration at one resonance. Many recent electrical blocking circuit devices have allowed multiple passive resonant shunts connected to one patch to obtain broadband control (Hollkamp 1994; Wu 1998; Fleming and Moheimani 2002; Fleming and Moheimani 2003). Synthetic impedance shunts have been devised that act as active impedance control systems to reduce broadband vibration (Fleming, Behrens et al. 2002; Fleming and Moheimani 2004; Quaegebeur, Micheau et al. 2009).

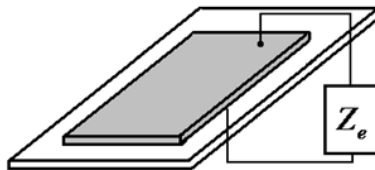


Figure 1 - Shunted piezoelectric patch with arbitrary impedance

This paper will focus on negative capacitance shunts which are simple active feedback control circuit. Behrens demonstrated that the shunting of a piezoelectric patch is analogous to feedback control (Behrens, Fleming et al. 2001). Combining this concept with the necessary active operation amplifier within a negative capacitance circuit creates active feedback control which greatly modifies the stiffness and damping of a connected piezoelectric patch to reduce vibration of a system. The value of the negative capacitance is limited by the stability of the circuit (Behrens, Fleming et al. 2001; Park and Baz 2005; Beck, Cunefare et al. 2008; Beck, Cunefare et al. 2009). Therefore, experimentally, the negative capacitance magnitude is set as close to the inherent capacitance of the patch before reaching instability.

Another research area in vibration mitigation is the use of periodic structures. Some of the periodic structures studied for their wave modification include periodic stiffened beams and plates (Mead 1986; Mead and Yaman 1991), SMA inserts (Ruzzene and Baz 2000), and periodic piezoelectric structures (Hofer, Finger et al. 2006; Collet, Cunefare et al. 2009; Spadoni, Ruzzene et al. 2009). These structures have shown creation of “stop-bands” and “pass-bands” which either reduce or allow wave propagation. The elements of these periodic structures can be modified to increase the “stop-band” frequency bandwidth (Baz 2001) therefore enhancing vibration control over a greater frequency range.

The physical effects that a negative capacitance periodic array has on a vibrating beam will be explored by analyzing numerical predictions of wave attenuation through finite elements, an array length study, and the velocity response of different sections of the beam. These investigations will explore how the periodic array enhances the control ability of the negative capacitance shunt. Through the modification of the “stop-bands” of the periodic array, the negative capacitance shunt is expected to have more control over a wider frequency range. The wave attenuation calculations will give perspective to the frequency dependence of the shunt parameters and these parameters will be used as a starting point for the experimental investigations. The array length study will give insight into how much control effort is done with increasing the number of patches. Also, Beck et al. (Beck, Cunefare et al. 2008) remarked that the action of the negative capacitance shunt applied to the boundary of a cantilever beam causes the beam to act as if it is infinite. Therefore, by comparing the velocity response of beam between the forcing and the array, the array area, and between the array and clamp this effect can be further investigated. The results of these studies on a

periodic beam will give greater insight into the physical effects of the negative capacitance shunted piezoelectric periodic array and how a modal system responds to periodic arrays.

FINITE ELEMENT ANALYSIS

A numerical study of a coupled mechanical-piezoelectric system is developed to obtain predictions of experimental results. The system of interest is a thin cantilever beam shown in Figure 2. There are 12 equally spaced piezoelectric patch pairs located at the center on the beam, with each patch pair connected to its own individual shunt circuit. These 12 patches constitute the periodic array. The upstream and downstream labels in Figure 2 are such because a point force is located at the tip. The patch array section of beam can be studied by employing a dispersion analysis of single unit cell of the periodic array, Figure 3. The dispersion analysis computes which frequencies are attenuated when a wave is passed through the array. A finite element model for both the full system and the unit cell is developed. The result of interest for the finite element calculations for the beam is the spatial average transverse velocity. The unit cell finite element model obtains the complex wave number that represents the attenuation of propagating waves.

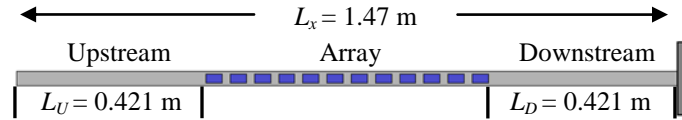


Figure 2 - Cantilever beam with a bonded piezoelectric array, centered on beam face



Figure 3 - Single unit cell of periodic array

Energy Functional

The finite element derivation of the equations of motion for a thin vibrating system is based on the work done by Casadei et al (Casadei, Beck et al. 2009) and Spadoni et al (Spadoni, Ruzzene et al. 2009). The principle of virtual work

$$\delta L_{tot} = \delta L_{ext} - \delta L_{def} = 0 \quad (2)$$

is first applied to an arbitrary piezoelectric structure shown in Figure 4. The total work done, δL_{tot} , is the difference of both the external and internal forces and the work done by virtual deformation. Rewriting Equation (2) in terms of virtual displacement δu_i and potential $\delta\phi$ functions and arbitrary space-variables yields

$$\int_{V_s} \delta \varepsilon_{ij} \sigma_{ij,j} - \delta u_i \rho \ddot{u}_i + \delta \phi D_{i,i} dV = \int_{S_f} \delta u_i \bar{f}_i dS - \int_{S_q} \delta \phi \bar{q} dS. \quad (3)$$

The forcing terms of Equation (3) include the mechanical dynamic forces, \bar{f}_i , and the imposed electric charges, \bar{q} , which are both defined along the system boundaries, S_f and S_q . The term u_i is the mechanical displacement which is defined over the structural domain V_s . The piezoelectric constitutive equations are needed to obtain the electrical displacement D_i and the stress tensor σ_{ij} in terms of linear strain ε_{kl} and electric potential ϕ . These constructive equations for piezoelectric materials are

$$\sigma_{ij} = c_{ijkl} \varepsilon_{kl} + e_{kij} \phi_k \quad (4)$$

$$D_i = e_{ikl} \varepsilon_{kl} - \xi_{ik} \phi_k \quad (5)$$

where c_{ijkl} , e_{kij} , and ξ_{ik} are material properties. Equations (4) and (5) are substituted into Equation (3) to give the governing equations which are obtained through integration by parts,

$$\int_{V_s} \delta \varepsilon_{ij} (c_{ijkl} \varepsilon_{kl} + e_{kij} \phi_k) dV + \int_{V_s} \delta u_i \rho \ddot{u}_i dV = \int_{S_f} \delta u_i \bar{f}_i dS \quad (6)$$

and

$$\int_{V_s} \delta \phi_i (e_{ikl} \varepsilon_{kl} - \xi_{ik} \phi_k) dV = - \int_{S_q} \delta \phi \bar{q} dS. \quad (7)$$

Also, the strain field can be expressed in terms of the displacement variables with the use of the following gradient equation,

$$\varepsilon_{ij} = \frac{1}{2} (u_{i,j} + u_{j,i}). \quad (8)$$

The Kirchhoff kinematic assumptions for thin plate behavior are then applied which state

$$u_1 = -zw(x, y)_x, \quad u_2 = -zw(x, y)_y, \quad \text{and} \quad u_3 = w(x, y) \quad (9)$$

where w is the transverse displacement of the mid-surface of the beam. These conditions result in a plane strain state where the only non-zero components of strain are ε_{11} , ε_{22} and γ_{12} .

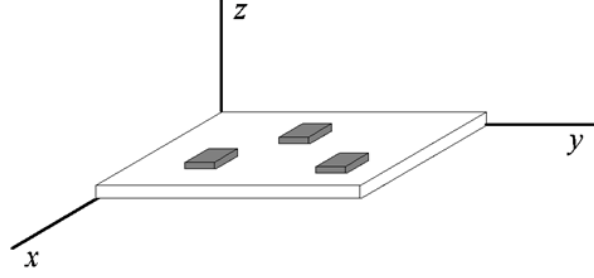


Figure 4 - 2D structure with bonded piezoelectric patches

Finite Element Discretization

The solution to the governing equations of motion is obtained through a Kirchhoff plate finite element discretization. The use of shape functions and nodal degrees of freedom gives the vertical displacement and surface potential,

$$w = [N_w] \{d\} \quad (10)$$

and

$$\phi = [N_\phi] \{\phi\} \quad (11)$$

where N_w and N_ϕ are the proper shape functions. The transverse displacement of the mid-surface of the beam at any point within an element is

$$w(x, y) = a_1 + a_2x + a_3y + a_4xy + a_5x^2 + a_6y^2 + a_7x^2y + a_8xy^2 + a_9x^3 + a_{10}y^3 + a_{11}x^3y + a_{12}xy^3. \quad (12)$$

The a_i constants are computed in terms of the nodal variables, w_i , $\partial w_i / \partial x$, and $\partial w_i / \partial y$. Therefore, a pair of matrix equations of motion is obtained by substituting Equations (10) and (11) into Equations (6) and (7) yielding

$$[M_{uu}] \{\ddot{d}\} + [K_{uu}] \{d\} + [K_{u\phi}] \{\phi\} = \{f\} \quad (13)$$

and

$$[K_{\phi u}] \{d\} + [K_{\phi\phi}] \{\phi\} = \{q\}. \quad (14)$$

The system mass and stiffness matrices are found using the shape functions and material properties; refer to the work of Cook for exact equations (Cook, Malkus et al. 1989).

To obtain one equation of motion encompassing both electrical and mechanical degrees of freedom, Equations (13) and (14) are coupled by application of piezoelectric assumptions and a shunting matrix. To start, the electric field at any point on the surface of a piezoelectric patch is considered constant. Also, the electric field potential is assumed to vary linearly through the thickness of a patch. These two assumptions simplify the electrical equation of motion to a scalar equation

$$\left[K_{u\phi} \right]^T \{d\} + K_{\phi\phi} \phi_p = q_e. \quad (15)$$

The shunting matrix is found by realizing that the electric potential can be expressed in terms of the charge when an arbitrary impedance is connected across the patch electrodes. Assuming a harmonic response, the electric potential is

$$\phi_{p_0} = i\omega Z_e(\omega) q_{e_0} \quad (16)$$

where Z_e is the shunt impedance. Therefore, combining Equations (13) and (15) produces

$$\left[\left[K_{uu} \right] - \omega^2 \left[M_{uu} \right] + \left[S_{Z_e}(\omega) \right] \right] \{d_0\} = \{f_0\} \quad (17)$$

which is the single harmonic motion equation where the shunting matrix is

$$\left[S_{Z_e}(\omega) \right] = i\omega \left[K_{u\phi} \right] \left(i\omega K_{\phi\phi} - \frac{1}{Z_e(\omega)} \right)^{-1} \left[K_{\phi u} \right]. \quad (18)$$

Through inspection of the above equation, the electrical shunt allows for modification of stiffness, mass, and damping of the system depending on the selection of shunt and patch parameters. This formulation will be used to find the velocity frequency response of a complete cantilever beam with a driving point force as well as to analyze a periodic unit cell.

Dispersion Analysis

As stated earlier, the implementation of a periodic array will modify which wave frequencies will propagate through a structure. To study this physical behavior, the use of a Bloch Theorem analysis is applied to a single repeated cell, Figure 5 (Brioullin 2003). The cell's motion can be found using the above finite element formulas by solving the equation of motion

$$\left[\left[K_{uu} \right] - \omega^2 \left[M_{uu} \right] + \left[S_{Z_e}(\omega) \right] \right] \{d\} = \left[K_D(\omega) \right] \{d\} = \{f\} \quad (19)$$

where $[K_D]$ is the dynamic stiffness of the element with an applied electrical shunt. Because of the cell periodic, the displacement and forcing at the boundaries of the cell must be continuous from one cell to the next with respect to the wave number. To determine the attenuation of the propagating wave, the wave number must be solved; where the real part of the wave number represents attenuation. To begin, the equations of motion are rewritten in terms of wave number,

$$\left[K_D(\mu_x, \mu_y, \omega) \right]^{(r)} \{d\}^{(r)} = 0 \quad (20)$$

where μ_x and μ_y are the x and y components of wave number. The solution to this equation is found by holding the frequency and one wave number component constant while solving for the second term, which is equivalent to varying the wave-number vector along the contour of the first irreducible Brioullin zone (Spadoni, Ruzzene et al. 2009). Because of the symmetry of the unit cell, the frequency wave-number period is square as shown in Figure 6. The real positive term that expresses attenuation is called the propagation constant, δ .

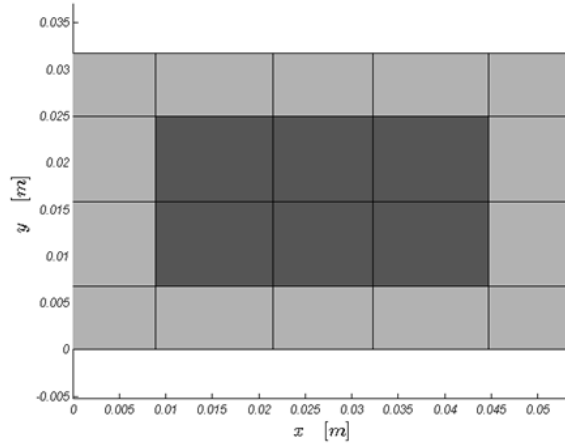


Figure 5 - Schematic of a discretized unit cell

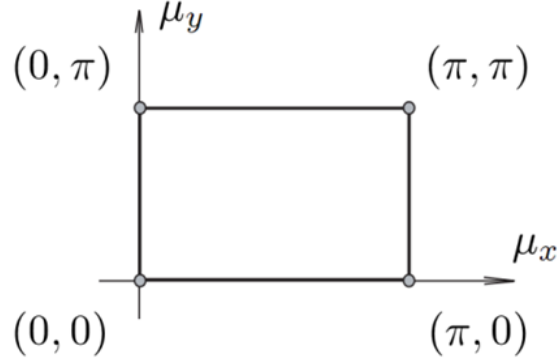


Figure 6 - Sketch of the first irreducible Brioullin zone

EXPERIMENTAL SETUP

A long cantilever beam with a patch array and necessary data acquisition equipment was assembled to investigate the effect of the negative capacitance shunts. The beam, Figure 2, has been tested in previous work (Beck, Cunefare et al. 2010). A photograph of the beam is shown in Figure 7. The long thin aluminum beam which is clamped on one end has 12 piezoelectric patch pairs bonded symmetrically on both sides, for a total of 24 patches. The construction of the beam consisted of gluing a thin kapton film to both faces of the beam to electrically isolate the bottom surfaces of the piezoelectric patches which are bonded to the kapton. The bottom face of the surface of the piezoelectric was electroded by a thin copper tape that was attached to the piezoelectric by conductive epoxy. The material properties and physical dimensions of the beam and patches are shown in Table 1. Each pair of patches is electrically connected in parallel. The individual pairs are connected to individual shunt circuits which creates 12 single input, single output (SISO) control systems. The beam is also separated into three sections, labeled as: upstream, array, and downstream. These sections will be analyzed separately to investigate force localization.



Figure 7 - Photograph of the cantilever beam with periodic array

Table 1 - Beam and patch physical parameters

Beam	Young's modulus	$E_b = 73 \text{ GPa}$
	Density	$\rho_b = 2700 \text{ kg/m}^3$
	Length	$L = 1.47 \text{ m}$
	Width	$w = 18.2 \text{ mm}$
	Thickness	$t = 3.3 \text{ mm}$
Piezoelectric	Young's modulus, shorted	$E_p = 63 \text{ GPa}$
	Density	$\rho_p = 7800 \text{ kg/m}^3$
	Coupling coefficient	$k_{31} = 0.35$
	Thickness	$t = 0.8 \text{ mm}$
	Capacitance	$C_p = 58.5 \text{ nF}$

The negative capacitance shunts used in this work consist of a resistor and a negative capacitance element. The negative capacitance is created using a basic circuit configuration called a negative impedance converter (Horowitz and Hill 1996). The schematic for a negative impedance converter is shown in Figure 8, which consists of three passive circuit elements with impedance Z_i and an operational amplifier (op-amp). The equation

$$Z_{in} = -\frac{Z_3 Z_2}{Z_4} \quad (21)$$

is used to compute the amount of negative impedance achieved with the implementation of the circuit. To obtain a negative capacitance, a capacitor was placed in the Z_2 location and a potentiometer was used as resistors in the Z_3 and Z_4 locations. The use of a potentiometer allowed for tuning of the circuit with a single reference capacitor, C_2 . Figure 9 is the schematic for the negative capacitance used; the resistor in parallel to the capacitor is necessary for stability of the circuit at DC. At the frequencies of interest, the resistor has negligible impact on the impedance of the shunt. The full shunt diagram is shown in Figure 10. A resistor is added in series with the negative capacitance for positive real impedance. The resistor and negative capacitance are connected in series to the piezoelectric patch.

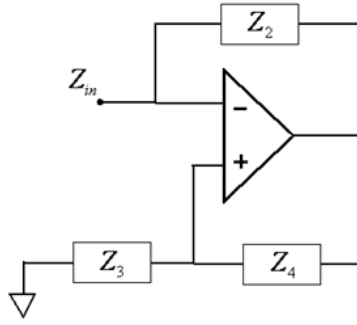


Figure 8 - Negative impedance converter schematic

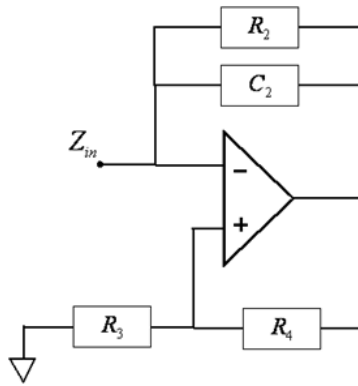


Figure 9 - Negative capacitance schematic

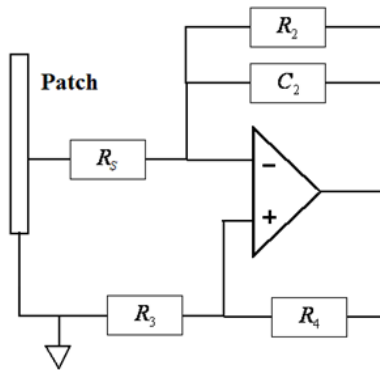


Figure 10 - Full shunt schematic

The response of the cantilever beam is measured by the use of a laser Doppler vibrometer. The vibrometer consists of a computer module, function generator, and scanning laser head. The computer controls the necessary settings for data acquisition and links with the function generator to create a signal output. The output is sent to an

electromechanical shaker that forces the beam at the tip. The velocity of beam is measured by the scanning laser head at 125 equally spaced locations along the length of the beam. The data from these points are used to compute the spatial average velocity in the regions of interest, either the full length or the three sections of the beam.

RESULTS AND ANALYSIS

To begin, the results of the dispersion theorem analysis will be presented to express the frequency impact of the control shunt on a unit cell. As stated above, the negative capacitance of the shunt is set to a stable value as close to the magnitude of the patch capacitance. The negative capacitance value is 66.7 nF, which will be used for both numerical calculations and experiments. The frequency dependence of the shunt will be explored by changing the resistance in series with the negative capacitance, R_2 in Figure 10. Figure 11 shows the propagation constant for three values of resistance. For low resistance values, the inherent stop band of the patch geometry at 2600 Hz is amplified when the circuit is applied. Yet, with higher resistance the increased damping in the shunt minimizes the periodic effect but does increase the control effectiveness at lower frequencies. For the 100 Ω resistance, the propagation constant reaches the same increased stop band level of lower resistance and is greater for both higher and lower frequencies. From this figure, the propagation constant predicts for small resistances the control shunt will have a frequency localized impact. The shunt should have the most effect at lower frequencies with higher resistance.

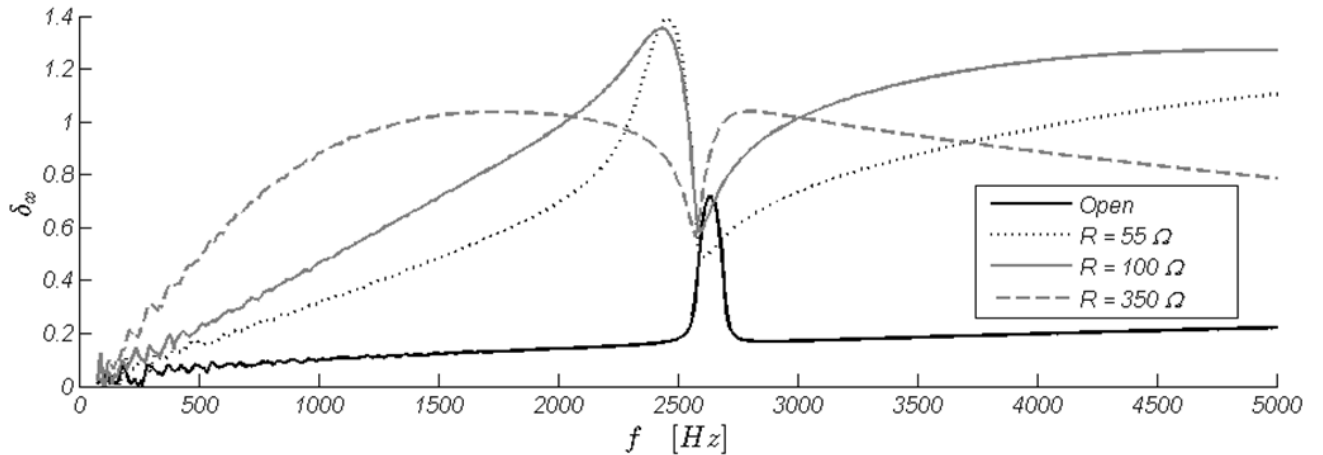


Figure 11 - Propagation constant for negative capacitance shunts

The spatial average velocity frequency response function (FRF) comparison between a base line (open circuit) case and the control shunt connected expresses an overall reduction in vibration of the beam. The squared spatial average velocity is defined as

$$\langle |u(f)|^2 \rangle = \frac{1}{L_x} \int_0^{L_x} \frac{u^2(f, x)}{F(f)} dx \quad (22)$$

where f is the frequency and u is the velocity at a point x along the length of the beam. Beginning with a finite element simulation, Figure 12, the negative capacitance shunt significantly reduces the velocity of the beam from 600 to 5000 Hz. The maximum numerically predicted reduction is 11 dB at the 2300 Hz resonance. The resonance at 2500 Hz cannot be controlled by the shunts, but both resonances above and below this exhibit maximum attenuation. This behavior agrees with the dispersion analysis results where the effectiveness dips at 2500 Hz but has a maximum at the frequencies immediately lower. As was also predicted in Figure 11, the frequency dependant behavior is obtained from the finite element model. The 100 Ω resistor creates the largest attenuation at frequencies above the uncontrolled mode. In addition, the high resistance configuration produces the largest control at low frequencies. The numerical spatial average velocity response is verified experimentally as shown in Figure 13. Both the propagation constant predictions and the numerical results are confirmed by the experimental velocity response of the beam. Figure 13 shows the spatial average velocity of the beam for the same three values of resistance. The resonance at 2600 Hz is also not controlled. Yet, the maximum suppression is found to be 12 dB at 2100 Hz for the 100 Ω resistor. The frequency nature of the three shunt configurations can be seen as well, with the 55 Ω resistor having a strong localized effect around 2400 Hz. A minimum of 5 dB velocity reduction is obtained at all modal peaks from 600 to 5000 Hz with the 100 Ω resistor. It should also be noted that these attenuation values represent a global measure for the reduction in vibration amplitude because $\langle |u| \rangle$ is a spatial average over the entire length.

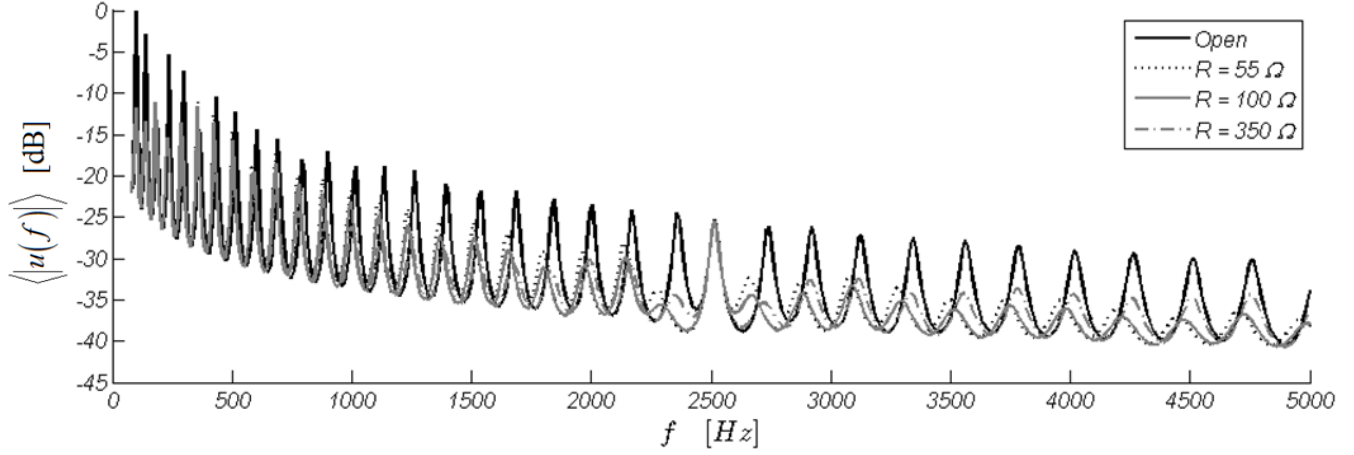


Figure 12 – Finite element numerical spatial average velocity FRF

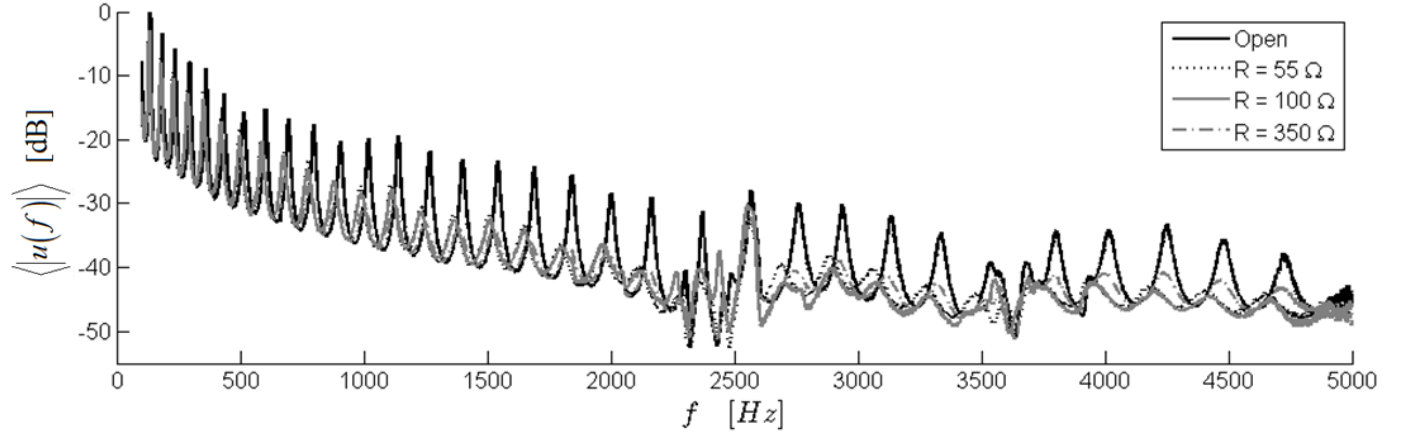


Figure 13 - Experimental spatial average velocity FRF

The three sections of the beam behave differently when the control shunt is applied. Figure 14 and Figure 15 show the spatial average velocity response of the upstream and downstream sections of the beam. The negative capacitance control causes the velocity minima to increase in the upstream section of the beam as seen in Figure 14. In contrast, Figure 15 shows the average velocity decreases at the anti-resonances of the downstream section. These changes are caused by the vibration localization of the shunt array. This can be quantified by summing the spatial average kinetic energy of each section over all frequencies. The frequency integrated kinetic energy difference between the open and control cases is defined as

$$\Delta T = 10 \log_{10} \left[\int_f^{f_{\max}} \frac{T_c}{T_{uc}} df \right] \quad (23)$$

where T_c is the controlled kinetic energy and T_{uc} is the uncontrolled kinetic energy. The kinetic energy change between the open circuit and control cases for the upstream and downstream sections of the beam are shown in Table 2. This table displays the difference between uncontrolled and controlled kinetic energy for three lower integration limits. As the integration is confined to higher frequencies, the greater the difference between the controlled and uncontrolled cases. This shows that the shunt reduces the energy of the vibration as the waves pass through the array. Therefore for higher frequencies, the circuit has a greater vibration localization effect. This trend is expressed in Figure 16, also. The two curves show the kinetic energy difference for the upstream and downstream sections of the beam. The separation between the two curves increases as the frequency of the lower integration limit increases. In summary, the spatial average velocity of the whole beam decreased when the control is added, but the array has a greater effect in reducing the energy in the area downstream of the array. The effect of the array can also be considered an anechoic boundary, because the vibration energy is dissipated and not reflected back upstream.

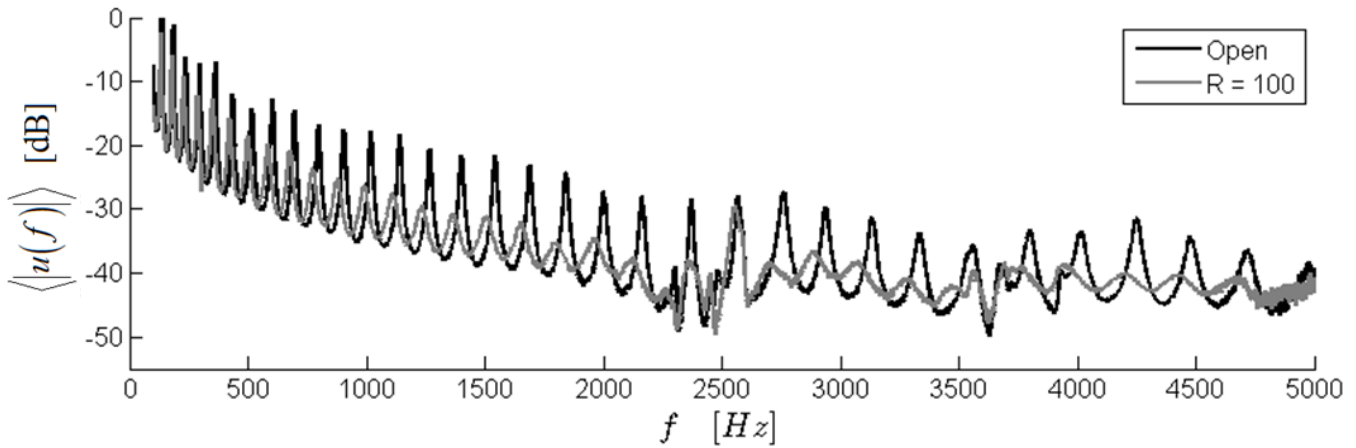


Figure 14 - Spatial average velocity FRF for left section

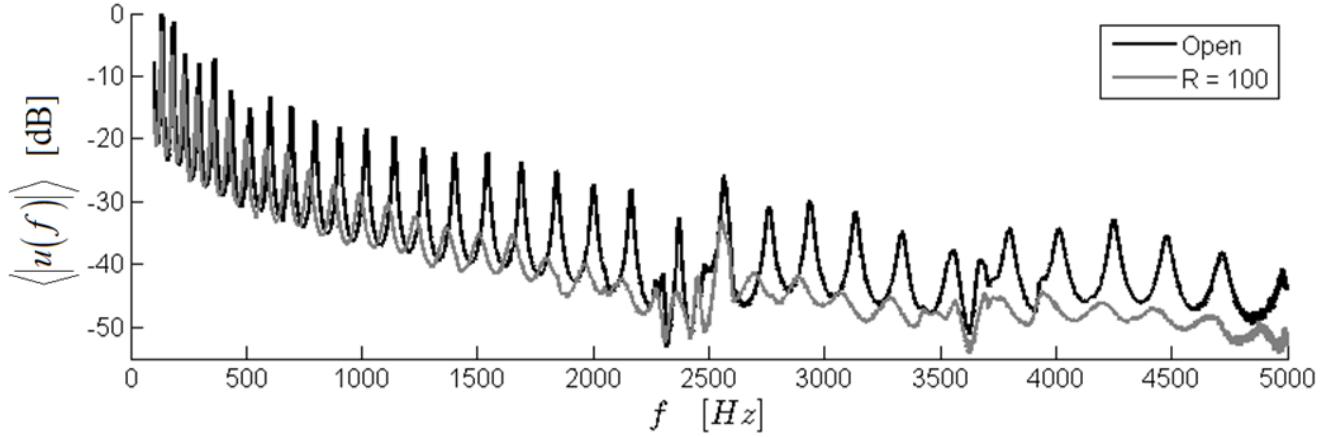


Figure 15 - Spatial average velocity FRF for right section

Table 2 – Frequency integrated total kinetic energy difference

Range	Upstream	Downstream
0.1 - 5 kHz	-4.2 dB	-5.7 dB
0.5 - 5 kHz	-6.6 dB	-10.4 dB
1.5 - 5 kHz	-6.2 dB	-13.7 dB

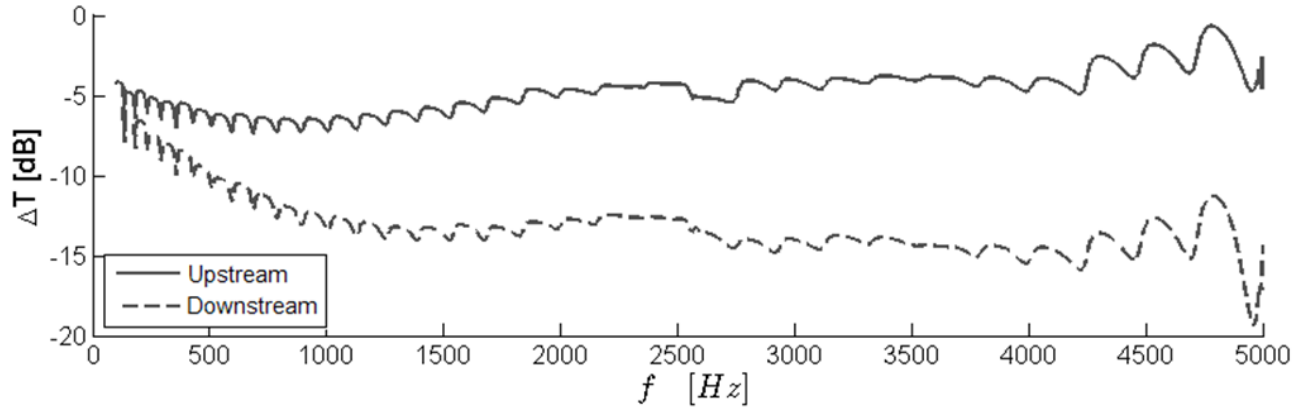


Figure 16 – Frequency integrated kinetic energy difference

The number of patches with the control connected impacts the reduction in velocity of the resonant peaks. Figure 17 shows the numerical prediction of attenuation for the 15th and 16th resonant peaks of the beam relative to the open circuit case as more patches are added to the array length. The 15th and 16th resonances are located at 1400 and 1550 Hz. A pair of sequential resonances was needed to analyze the behavior of the control when increasing the array length, and these two were chosen arbitrarily with average modal attenuation. The overall trend is an increasing reduction with increasing array length, yet the addition of certain patches has more control than others. Also, the modes are affected differently when more patches are applied. The attenuation increases by increasing the

number of patches in the array; but not smoothly increasing, rather, exhibiting ramps and plateaus. The behavior is attributed to the modal response of the beam, which affects the locations where a patch can exert control. The ramps are present when the addition of a single patch causes significantly more control to the overall vibration. In contrast, a plateau occurs when adding another patch to the array length does not cause any increase in attenuation. The reduction in modal amplitude therefore depends on the location of the additional patch in the array with respect to the mode shape. Therefore, the propagation constant cannot be considered an exact prediction between reduction in vibration of a modal system at every frequency.

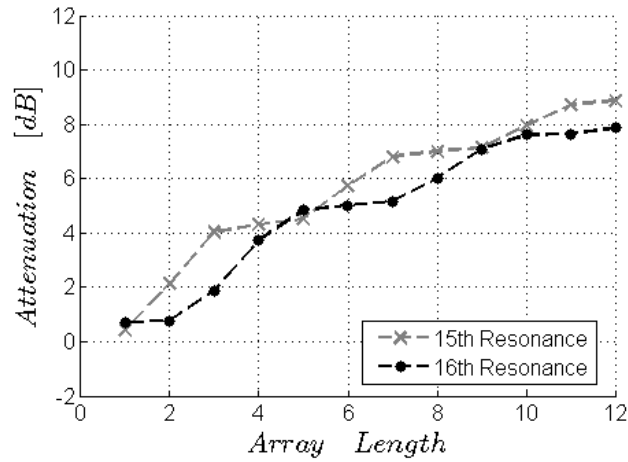


Figure 17 – Numerical vibration reduction versus array length, # of patches

The experimental data shows a similar ramps and plateaus in the increasing attenuation with increased array length, Figure 18. The corresponding resonances show after 8 patches there is only incremental increases in attenuation. Therefore, more attenuation may not be possible with a longer array.

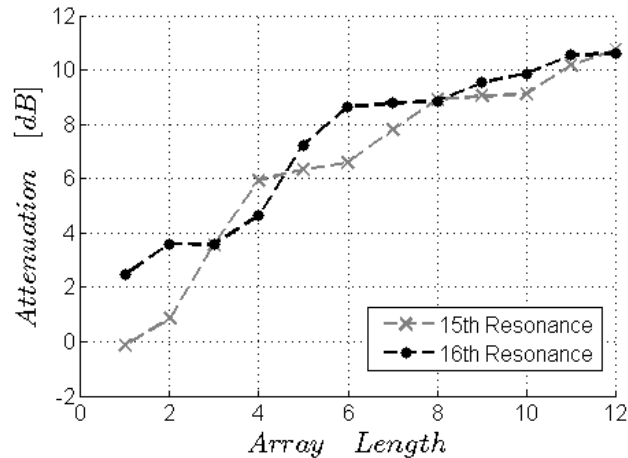


Figure 18 - Experimental velocity reduction versus array length, # of patches

CONCLUSION

The effect of the negative capacitance shunted piezoelectric patch on a cantilever beam is a reduction in overall vibratory response. A dispersion analysis approximates the frequency dependence effect of the shunt, but the propagation constant does not give a precise measure for each resonance of a modal system. Yet, increasing array length causes an increase in vibration control, with a maximum of 12 dB. The control array also results in the beam to begin to act as if it there is an anechoic termination where more of the vibration energy is localized between the forcing location and the patch array.

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