FANUC Robot R-20001C

FANUC CORPORATION

Export Control:

 □ Controlled (Related item No. of Foreign Exchange Order Attachment List of Japan:
☑ Non-controlled for item No. 2 to 15 of

Foreign Exchange Order Attachment List of Japan

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Full-model change of R-20001B

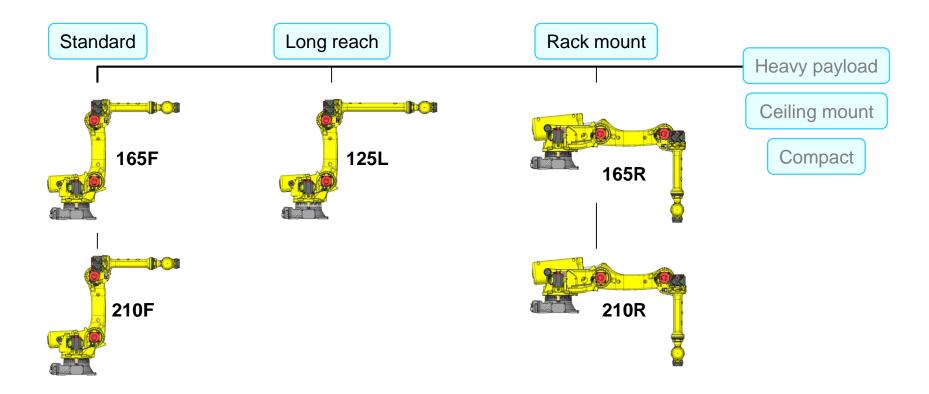
Over 70,000 units of previous model R-2000iB have been operating throughout the world since 2006.



R-2000*i*C

- High reliability proven by past results
- More convenient use due to slimmer body
- Higher productivity due to speeding up
- Extensive application due to enhanced wrist load capability
- Less varieties of spare parts due to common units among main models
- No need of spare entire cable assembly due to modular configuration
- New motor
 - Quick-release connector, Enhanced waterproof

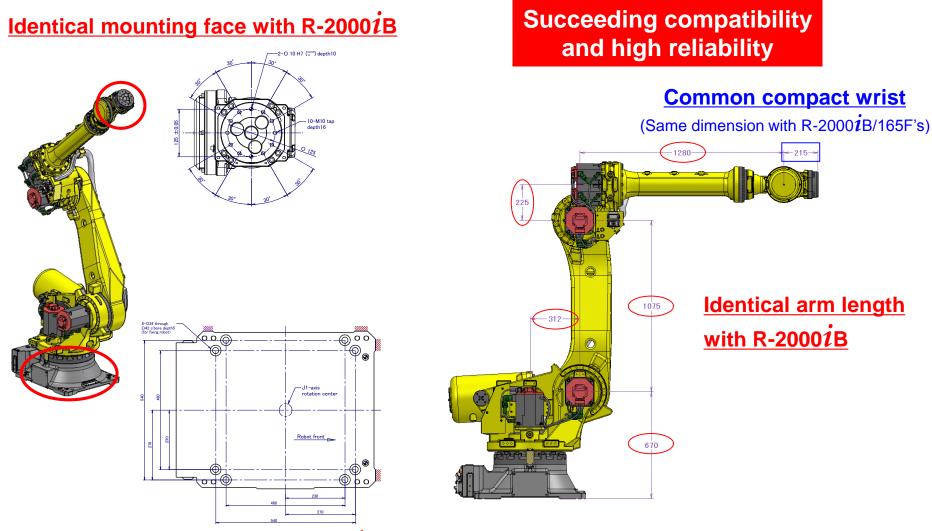
Line up



• Various options for multiple applications

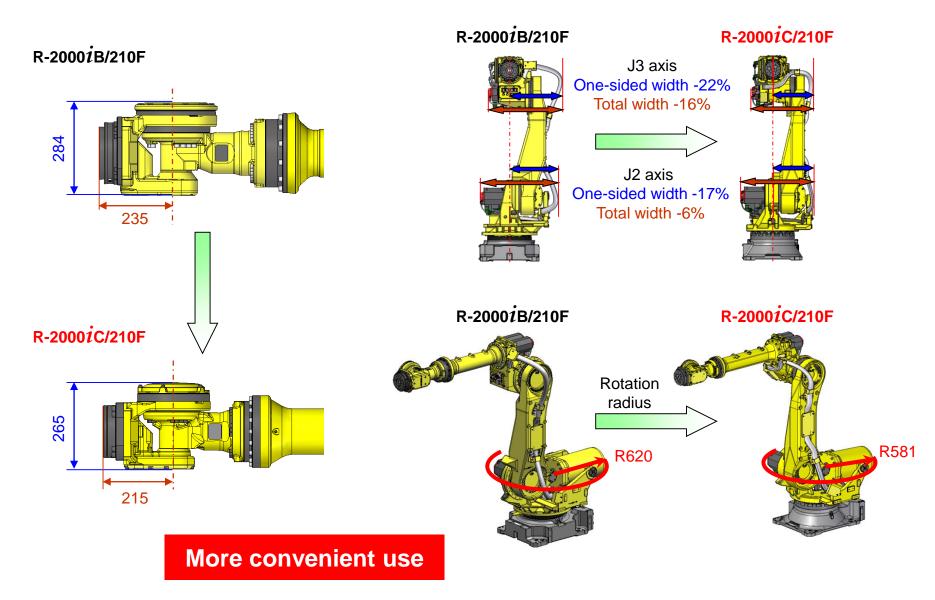


Successor to R-20001B



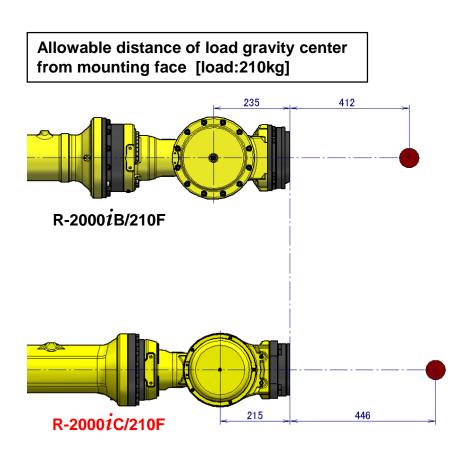
Identical installation with R-2000*i*B

Slimmer body



Speed up & Enhanced wrist load capability

			_		
		R-2000 <i>i</i> B /210F		R-2000 i C /210F	Conventional ratio
Max. load at wrist [kg]				210	-
Reach [mm]		2655		2655	-
	J1	95		120	26% up
	J2	90		105	17% up
Max. speed	J3	95		110	17% up
[deg/sec]	J4	120		140	17% up
	J5	120		140	17% up
	J6	190			220
Allowable	J4	1333		1360	5% up
load moment at wrist	J5	1333		1360	(Converted to actual capability)
[Nm]	J6	706		735	4% up
Allowable	J4	141.1		147	10/
load inertia at wrist	J5	141.1		147	4% up
[kgm²]	J6	78.4		82	5% up
Mass [kg]		1240		1090	12% down



210F

Speed up & Enhanced wrist load capability 165F,125L

		R-2000 <i>i</i> B /165F	
Max. load at wrist [kg]		165	
Reach [mm]		2655	
	J1	110	
	J2	110	
Max. speed	J3	110	
[deg/sec]	J4	150	
	J5	150	
	J6	220	
Allowable	J4	921	
load moment at wrist	J5	921	/
[Nm]	J6	461	
Allowable	J4	78.4	
load inertia at wrist	J5	78.4	
[kgm²]	J6	40.2	
Mass [kg]		1170	

-2000 iC /165F	Conventional ratio
165	-
2655	-
130	18% up
115	5% up
125	14% up
180	20% up
180	20% up
260	18% up
940	29/ 100
940	2% up
490	6% up
89	1/10/ 100
89	14% up
46	14% up
1090	7% down

		R-2000 <i>i</i> B /125L
Max. load at wrist [kg]		125
Reach [mm]		3005
	J1	110
	J2	110
Max. speed	J3	110
[deg/sec]	J4	170
	J5	170
	J6	260
Allowable	J4	588
load moment at wrist	J5	588
[Nm]	J6	343
Allowable	J4	58.8
load inertia at wrist	J5	58.8
[kgm²]	J6	22.5
Mass [kg]		1190

Conventional ratio	
-	
3% up	
18% up	
5% up	
14% up	
6% up	
6% up	
-	
210/ 00	
21% up	
3% up	
229/ 40	
22% up	
78% up	
6% down	

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Speed up & Enhanced wrist load capability 165R,210R

		R-2000 <i>i</i> B /165R	
Max. load at wrist [kg]		165	
Reach [mm]		3095	
	J1	110	
	J2	100	
Max. speed	J3	110	
[deg/sec]	J4	150	
	J5	150	
	J6	220	
Allowable	J4	921	
load moment at wrist	J5	921	
[Nm]	J6	461	
Allowable	J4	78.4	
load inertia at wrist	J5	78.4	
[kgm²]	J6	40.2	
Mass [kg]		1480	

R-2000 i C /165R	Conventional ratio
165	-
3095	-
115	5% up
110	10% up
125	14% up
180	20% up
180	20% up
260	18% up
940	29/ 100
940	2% up
490	6% up
89	1/10/ 100
89	14% up
46	14% up
1370	7% down

		R-2000 <i>i</i> B /200R
Max. load at wrist [kg]		200
Reach [mm]		3095
	J1	90
	J2	85
Max. speed	J3	95
[deg/sec]	J4	120
	J5	120
	J6	190
Allowable	J4	1333
load moment at wrist	J5	1333
[Nm]	J6	706
Allowable	J4	141.4
load inertia at wrist	J5	141.4
[kgm ²]	J6	78.4
Mass [kg]		1540

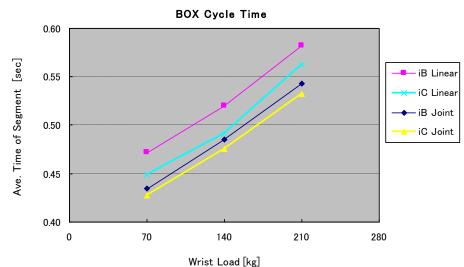
R-2000 <i>i</i> C /210R	Conventional ratio
210	3% up
3095	-
105	17% up
97	14% up
110	16% up
140	17% up
140	17% up
220	17% up
1360	5% up
1360	(Converted to actual capability)
735	4% up
147	40/
147	4% up
82	5% up
1370	11% down

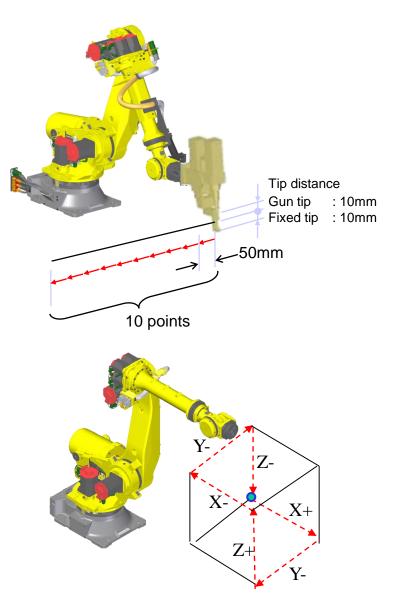
Speeding up on spot welding motion

• Drastically reducing cycle time

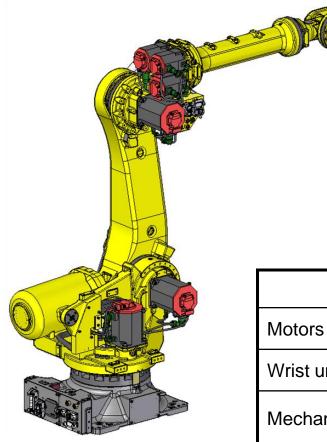
		o gun motion ssuring time)	
50mm interval x 10 points Average time	R-2000 1 B/210F with R-30 1 B (Actual)	R-2000 İ C/210F with R-30 İ B (Actual)	
X (Back & Forth) direction	0.485 [sec]	0.402 [sec]	▲17%
Y (Side to side) direction	0.493 [sec]	0.412 [sec]	▲16%
Z (Up & Down) direction	0.495 [sec]	0.417 [sec]	<mark>▲16%</mark>

• Reducing cycle time depending on wrist load





Common units among main models



Less varieties of spare parts

Common units among main models

- Motors
- Wrist unit (including reducers)
- Mechanical inner cable
- Balancer unit

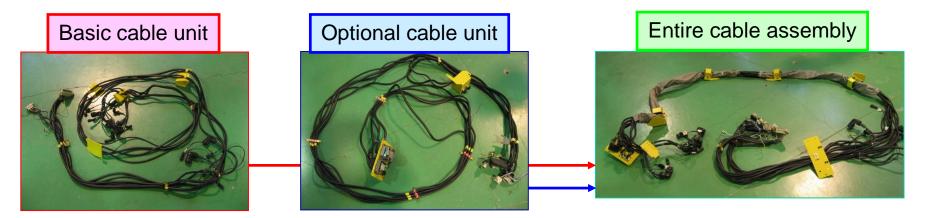
	210F	165F	125L	210R	165R
Motors	Same configuration for 5 models				
Wrist unit	Common for 5 models				
Mechanical inner cable	Common for 3 modelsCommon for 2 models				
Balancer unit			Comm 2 mc		

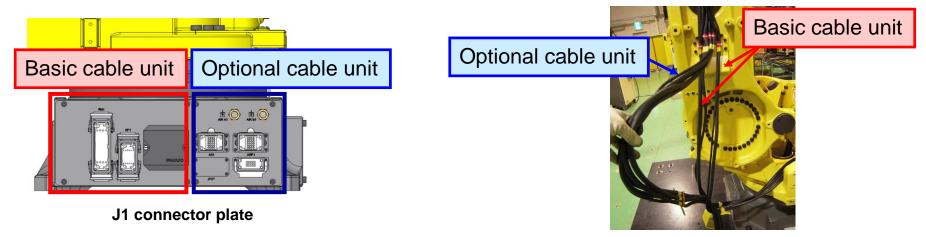
Modular configuration of mechanical inner cable

Basic cable unit (for driving 6 motors) and other optional one are separated.

Available to individually replace or install each cable unit.

No need of spare entire cable assembly

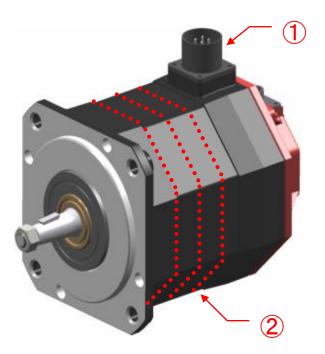




Side of J2 arm

New motor

- Easy maintenance
- High reliability
- *1 Quick-release connector
- *2 Enhanced waterproof by improved seals

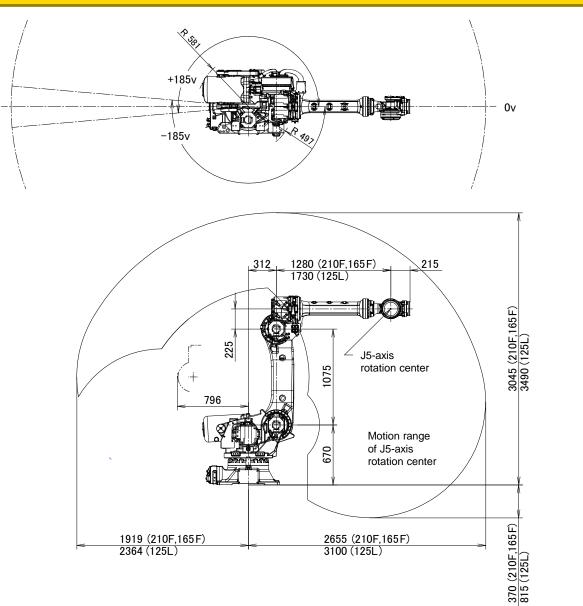


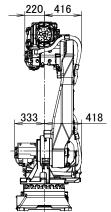
Motor configuration

Axis	R-2000 <i>i</i> B	R-2000 i C
J1	α <i>i</i> SR30/3000 A06B-0041-B605#S042	α <i>i</i> SR22/4000 A06B-2048-B605#0042
J2	α <i>i</i> SR30/3000 A06B-0041-B605#S042	α <i>i</i> SR30/3000 A06B- 2041 -B605# 0042
J3	α i SR30/3000 A06B-0041-B605#S042	α <i>i</i> SR30/3000 A06B- 2041 -B605# 0042
J4	α i S12/4000 A06B-0238-B605#S000	α <i>i</i> SR10/4000 _{A06B-2047-B605}
J5	α i S12/4000 A06B-0238-B605#S000	α <i>i</i> SR10/4000 _{A06B-2047-B605}
J6	α i S12/4000 A06B-0238-B605#S000	α <i>i</i> SR10/4000 _{A06B-2047-B605}
Pulsecoder	α <i>i</i> AR128 _{A860-2010-T341}	α <i>i</i> AR128 ^{A860-2060-T321}

Outline (Standard)

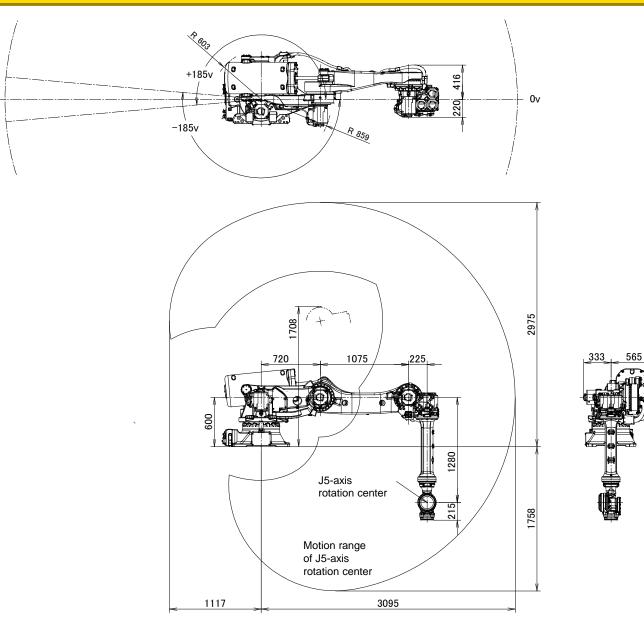
210F,165F,125L





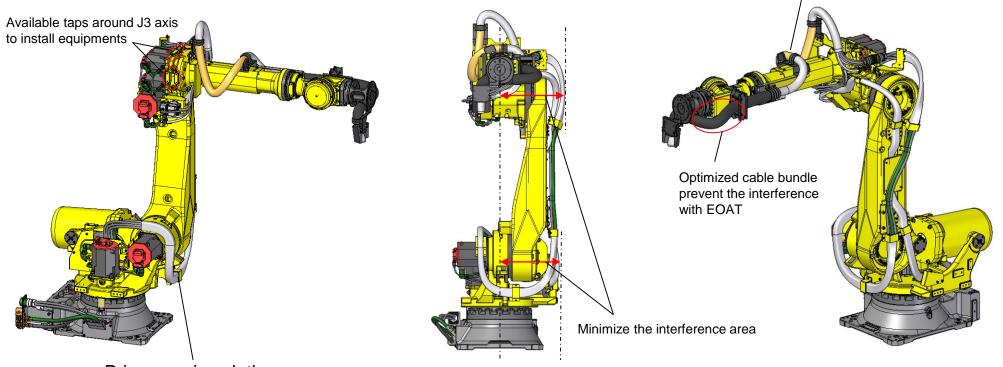
Outline (Standard)

210R,165R



Solution arm (Option)

- Compact dressout including weld power cables and hoses
- Highly reliable durability of weld cables and hoses
- Unnecessary to check the interference due to optimized cable bundle
- Ease of maintenance realizes shorter downtime to replace the unit



Primary axis solution arm

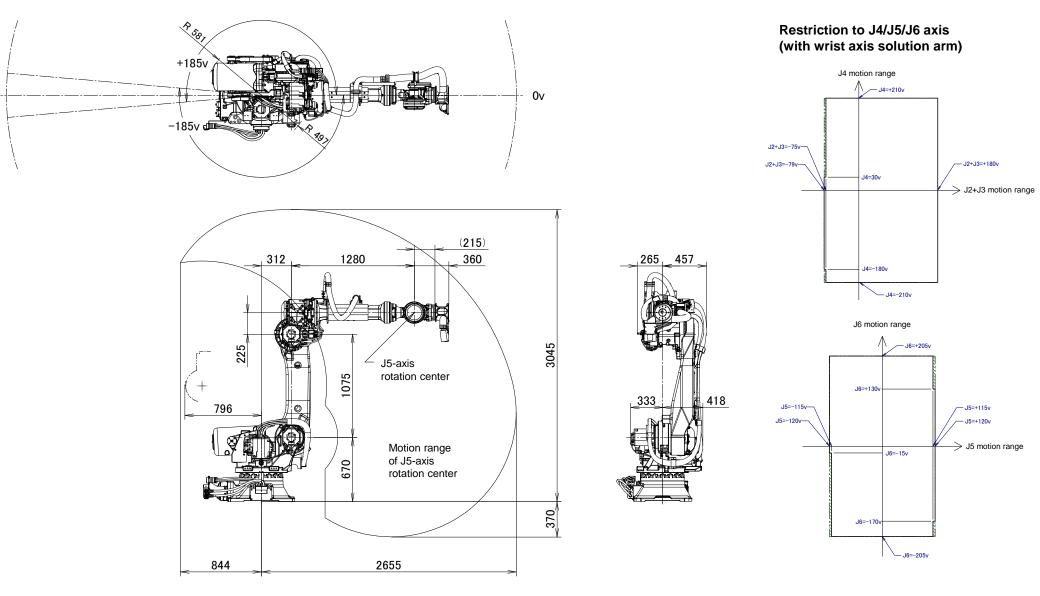
Note

- 1. In case of primary axis solution arm is ordered, its motion range is changed from the standard one.
- 2. In case of wrist axis solution arm is ordered, motion range restriction is applied to J4/J5/J6 axis.
- 3. Wrist axis solution arm is available for standard reach, not for R-2000iC/125L.

Wrist axis solution arm

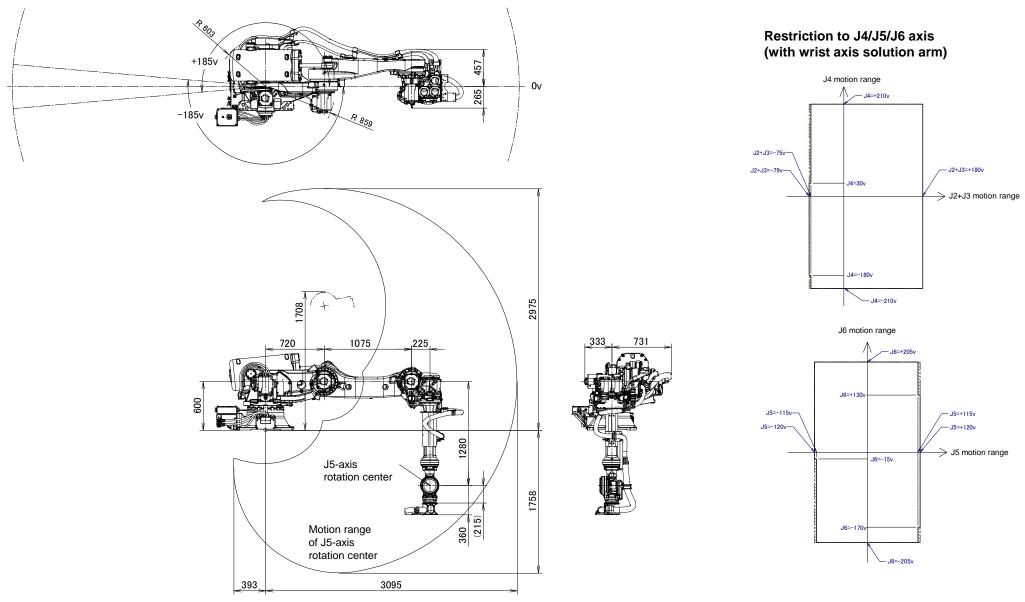
Outline (with solution arm)

210F,165F



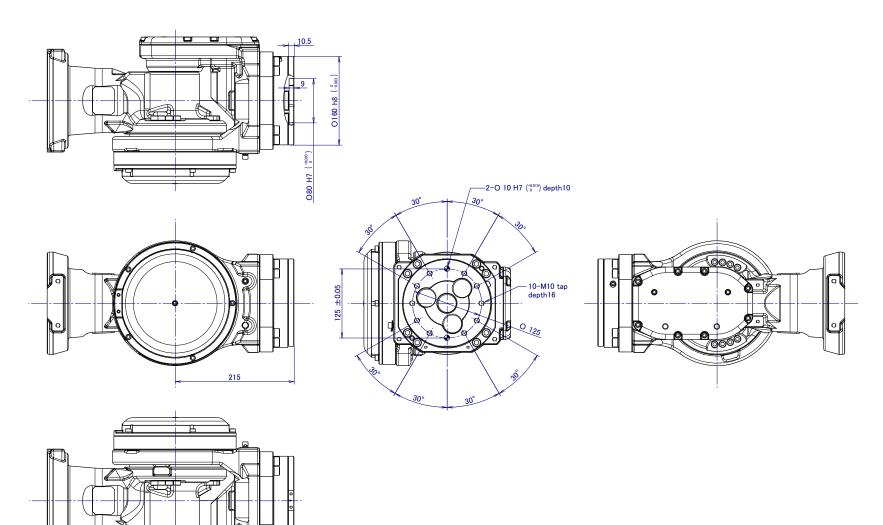
Outline (with solution arm)

210R,165R



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210F,165F,125L **End effecter mounting face**



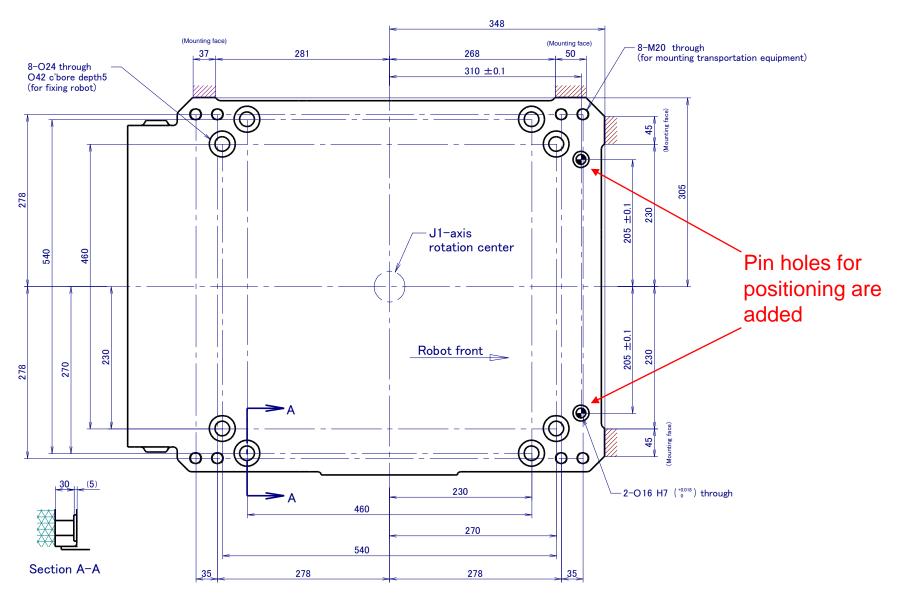
Based on ISO 9409-1-A125

210R,165R

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Installation

210F,165F,125L 210R,165R

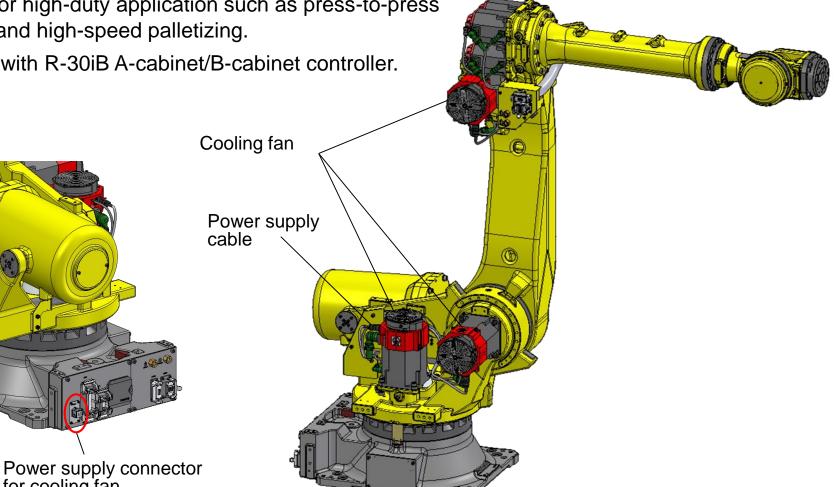


July 29th 2014

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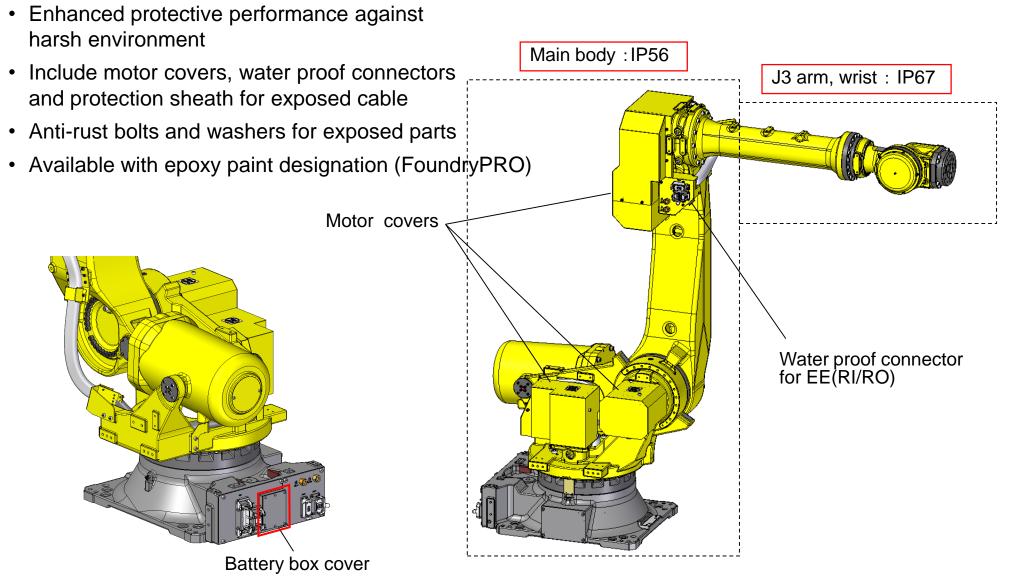
Press handling package (option)

- The cooling fans for J1/J2 axis or J1/J2/J3 axis motor ٠ improve duty performance.
- Suitable for high-duty application such as press-to-press • handling and high-speed palletizing.
- Available with R-30iB A-cabinet/B-cabinet controller. •



for cooling fan

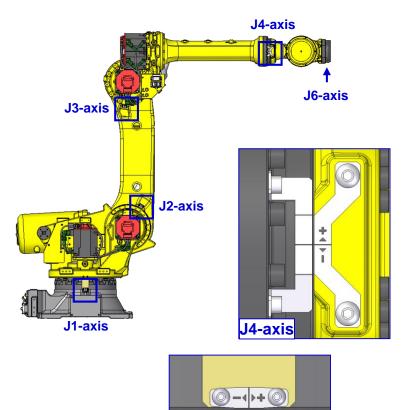
Severe dust and liquid protection (option)



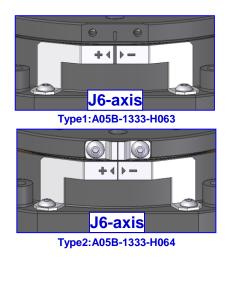
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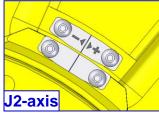
Zero-positioning plate (option)

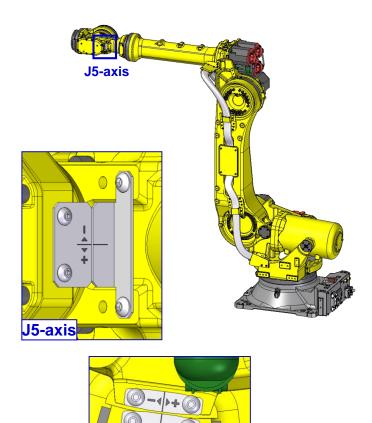
- New option for zero degree mark in addition to scribe mark and vernier mark seal
- Stainless plate and bolts for all
- Suitable for harsh environment



J1-axis







J3-axis