

Fundamentals of Computer Vision: Introduction

CMSC 828D

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Introduction

- Policies and other administrativia
- What is this course about?
- Problems you should be able to solve at the end of the course
- Introduction to Matlab
- Homework 1

Tag Team Instruction 😊

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Course Policies

- Exams
 - Exam 1 (25%) November 1, 2000
 - Exam 2 (25%) handed out Dec 11. Due back Dec. 13
- Homework (50%)
 - Handed out last class of current week
 - Due first class of next week (almost no exceptions)
 - Late homework will not be graded
- Attendance/homework submission mandatory
- Counts as a Ph.D. qualifying course

Texts

1. *A Guided Tour of Computer Vision*, by V. S. Nalwa, Addison-Wesley, 1993.
2. *Introductory Techniques for 3-D Computer Vision*, by Emanuele Trucco, Alessandro Verri, Prentice-Hall, 1998
3. *Multiple View Geometry*, by Richard Hartley, Andrew Zisserman, Cambridge University Press, 2000.
4. *Numerical Recipes in C*, by William Press et al., Cambridge Univ Press, 1992.
5. *Pattern Classification and Scene Analysis*, by Richard O. Duda, Peter E. Hart, John Wiley & Sons, 1973.

Web

- Computer Vision home page
 - <http://www.cs.cmu.edu/afs/cs/project/cil/ftp/html/vision.html>
- CV Online texts
 - <http://www.dai.ed.ac.uk/CVonline/>
- Many others ... any good ones please provide them to instructors
- Course home page
<http://www.umiacs.umd.edu/~ramani/cmsc828.html>
 - Lecture Slides
 - Homework
 - Solutions (?)

Course outline

- **Computer Vision**
 - Focus is on basic computer vision skills
 - Tools for research
- **Mathematical Background**
 - Basic material
- **Numerical/computational Skills**
- **Matlab**
 - Quick prototyping
 - tool for checking out ideas

Computer Vision

- Computer vision basics
 - Image creation
 - Cameras, Eyes, Calibration
 - Features, correspondence
 - 3D vision
 - Optical Flow
 - Tracking
 - Compression, vision for content delivery

Mathematics

- Basic Mathematical tools
 - Linear systems, matrix decompositions
 - Vector space, Basis, eigenvalues, eigenvectors
 - Calculus: gradients, Taylor series, maxima
- Projective geometry
 - Homographies, projectivities, constraints
 - Fundamental matrix
 - Trifocal tensor
- Probability, Random Variables, Classification

Numerical Methods

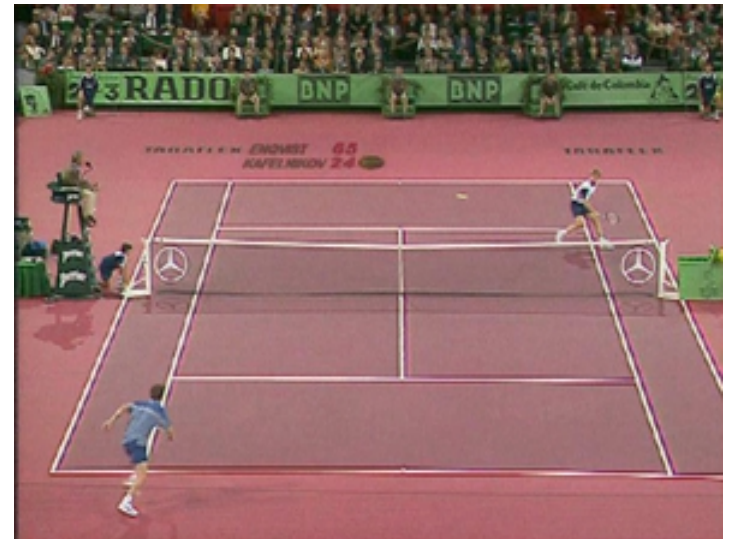
- Solving linear systems of equations
- Matrix decompositions
 - LU, Eigenvalue, SVD,
- Optimization
- Use Matlab as a tool to quickly try ideas
- Familiarity with image types
- “Practical computer vision”

Problems we should be able to solve

- Calibrate a camera
- Rectify an image
- Create a three dimensional reconstruction
- Insert model into image
- Track objects
- Track people
- Read papers on these topics and do thesis research
- Recommended course CMSC 828C
 - Computer vision seminar (for people doing research in vision)



Detect ground plane in video and introduce pictures on them



<http://www.symah-vision.fr/vhtml/epsis.htm>



Calibrate video sequences and insert new objects into them

Tracking



What is vision?

- Recognize objects
 - people we know
 - things we own
- Locate objects in space
 - to pick them up
- Track objects in motion
 - catching a baseball
 - avoiding collisions with cars on the road
- Recognize actions
 - walking, running, pushing

Vision is

- Deceivingly easy
- Deceptive
- Computationally demanding
- Critical to many applications

Vision is deceptively easy

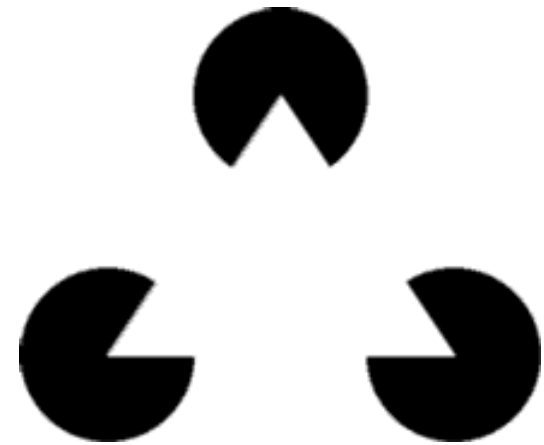
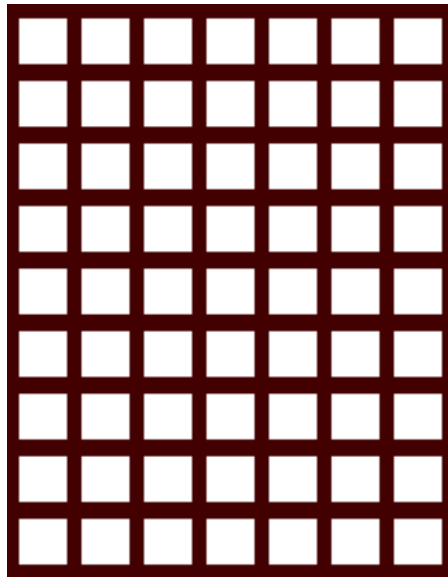
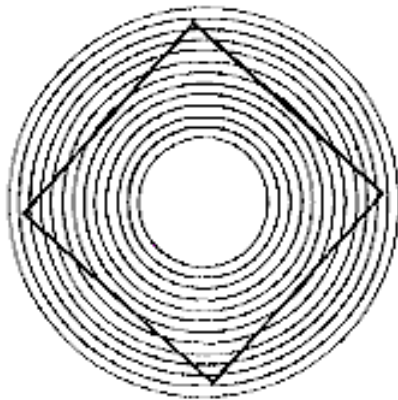
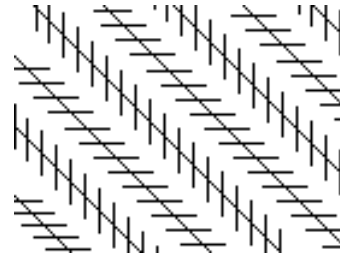
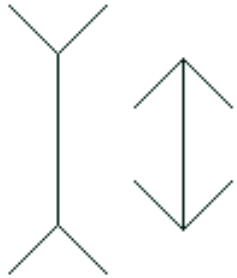
- We see effortlessly
 - seeing seems simpler than “thinking”
 - we can all “see” but only select gifted people can solve “hard” problems like chess
 - we use nearly 70% of our brains for visual perception!
- All “creatures” see
 - frogs “see”
 - birds “see”
 - snakes “see”

but they do not see alike

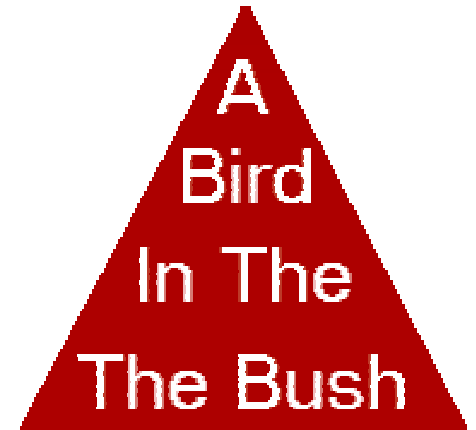
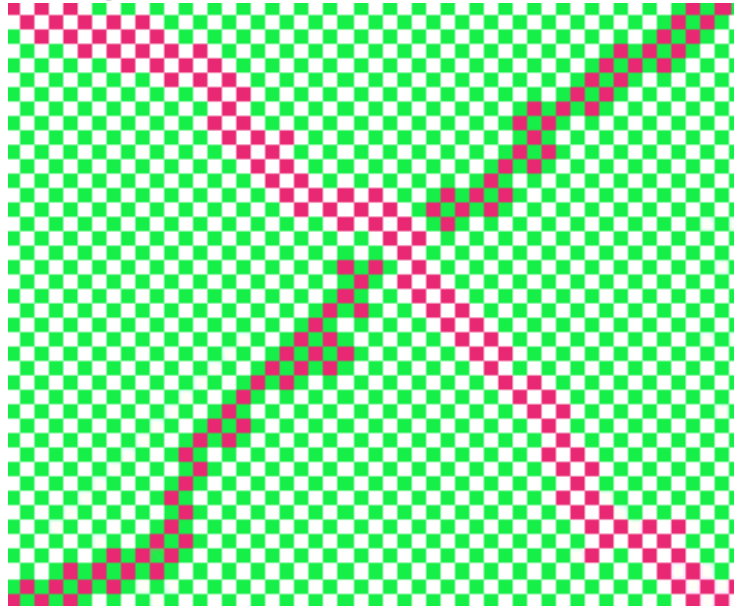
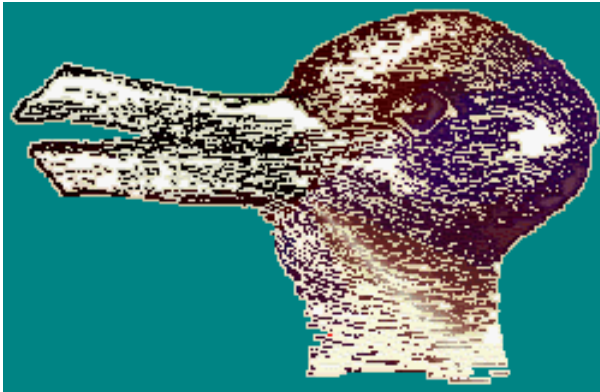
Vision is deceptive

- Vision is an exceptionally strong sensation
 - vision is immediate
 - we perceive the visual world as external to ourselves, but it is a reconstruction within our brains
 - we regard how we see as reflecting the world “as it is;” but human vision is
 - subject to illusions
 - quantitatively imprecise
 - limited to a narrow range of frequencies of radiation
 - passive

Some Illusions



Higher illusions



Human vision is passive

- It relies on external energy sources (sunlight, light bulbs, fires) providing light that reflects off of objects to our eyes
- Vision systems can be “active” - carry their own energy sources
 - Radars
 - Bat acoustic imaging systems

Spectral limitations of human vision

- We “see” only a small part of the energy spectrum of sunlight
 - we don’t see ultraviolet or lower frequencies of light
 - we don’t see infrared or higher frequencies of light
 - we see less than .1% of the energy that reaches our eyes
- But objects in the world reflect and emit energy in these and other parts of the spectrum

Matlab

- Started out as “Matrix laboratory” a piece of freeware (80s)
- Written by mathematicians
- Integrated programming environment
- Includes a rich set of features
- Very good online help
 - Within program
 - On pdf and html files on disk
 - On the web
 - On newsgroups

Matlab

- Using Matlab allows programming without the need to do routine tasks
 - E.g., Reading and writing image files
- However Matlab is
 - Interpreted and hence slow
 - Does not support all data types and hence is a memory hog
 - natural data type is a double instead of a 8 bit uint
- Does not utilize multiprocessors
- **Prototyping Tool**

Matlab

- Vectorization can make code faster
 - But code then loses readability
- Some defects can be overcome
 - by interfacing with external compiled code in C/C++/Fortran
 - Active X and Mex files
- New developments
 - Parallel Matlab (<http://www.ai.mit.edu/projects/ppserver>)
 - New data types in new versions
- Good tool for learning and prototyping

Other tools

- Khoros (a little too old)
- Target Jr. (C++ library)
- DirectX graphedit with Intel Open Computer Vision Library (a little too new)
 - Encourage students pursuing computer vision research to work with this library
 - <http://www.egroups.com/group/OpenCV>