

G 364: Mobile and Wireless Networking

CLASS 11, Wed. Feb. 11 2004

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Spring 2004

M-W, 11:40am-1:20pm, 109 Rob

Wireless Sensor Networks (WSNs)

- ◆ Motivating applications
- ◆ Enabling technologies
- ◆ Unique constraints
- ◆ Application and architecture taxonomy

(Based on Mani Srivastava tutorial)

Wireless Networking & Computing Technology

Until Now

- ◆ People and human-mediated data sources interaction (other people, web services)
- ◆ # of users \sim # of networked nodes
- ◆ Resource-rich nodes
- ◆ Facilitate human-centered decision making
- ◆ Communicate bits among geographically distributed nodes

Focus on networking interactive computers

The Future

- ◆ Interaction between people and the instrumented physical world (sensors, actuators)
- ◆ # of users \ll # of networked nodes
- ◆ Resource-constrained nodes
- ◆ Facilitate human-supervised autonomous decision making

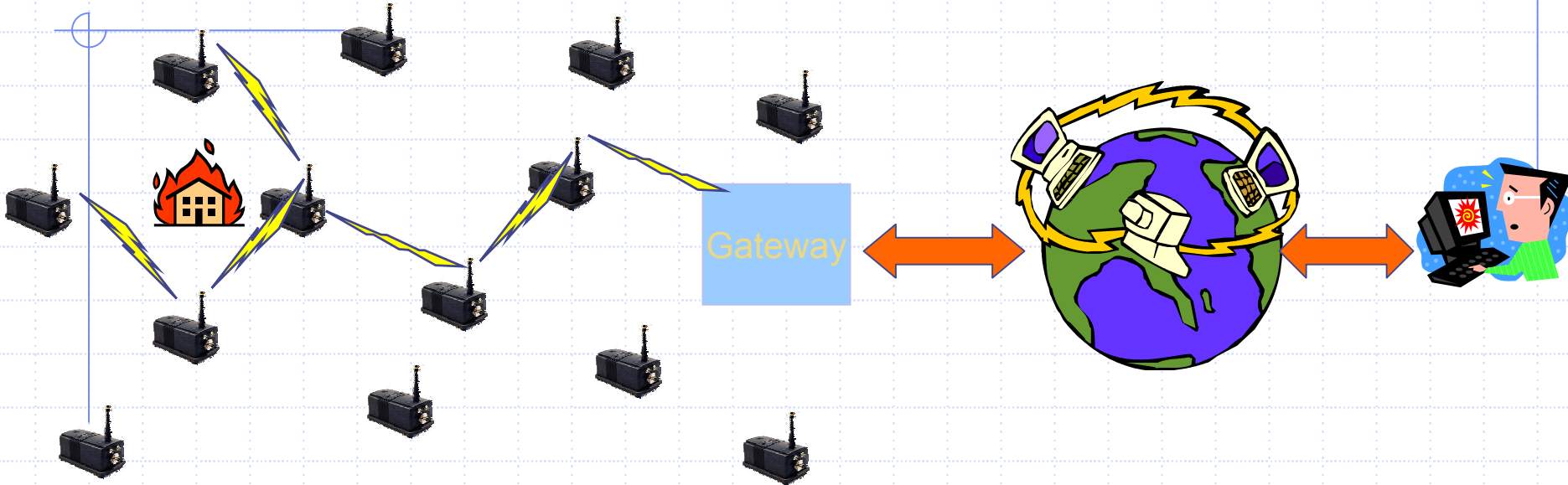
Focus on distributed embedded computation

Networked Sensing & Actuation

- ◆ “Communication” between people and their physical environment
 - Allow users to query, sense, and manipulate the state of the physical world
- ◆ Technology enablers
 - Cheap, ubiquitous, high-performance, low-power embedded processing
 - ◆ e.g. low-power processor cores
 - Cheap, ubiquitous (wireless) networking
 - ◆ e.g. single-chip CMOS radios
 - Cheap, ubiquitous, high-performance sensors and actuators
 - ◆ e.g. MEMS devices

Soon, all on a single system-on-chip!

“The Network is the Sensor”



- ◆ Distributed and large-scale like the current Internet
- ◆ But:
 - physical instead of virtual
 - resource constrained
 - real-time control loops instead of interactive human loops

Wirelessly Networked Sensor Nodes

LWIM III

UCLA, 1996

Geophone, RFM
radio, PIC, star
network



AWAIRS I

UCLA/RSC 1998

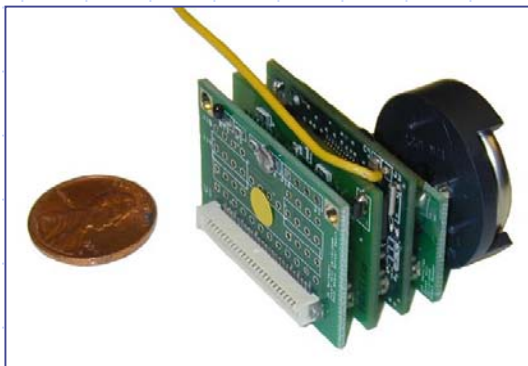
Geophone, DS/SS
Radio, strongARM,
Multi-hop networks



Sensor Mote

UCB, 2000

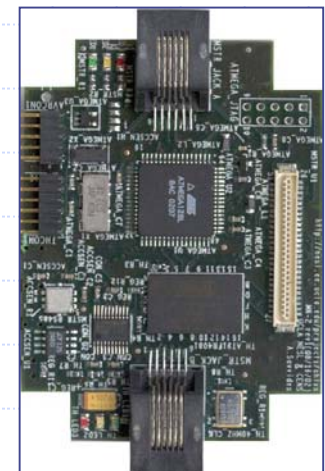
RFM radio,
PIC



Medusa, MK-2

UCLA NESL

2002

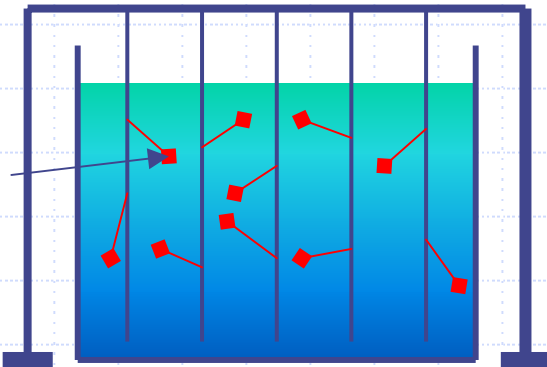


WSNs in the Environment



Ecosystems, Biocomplexity

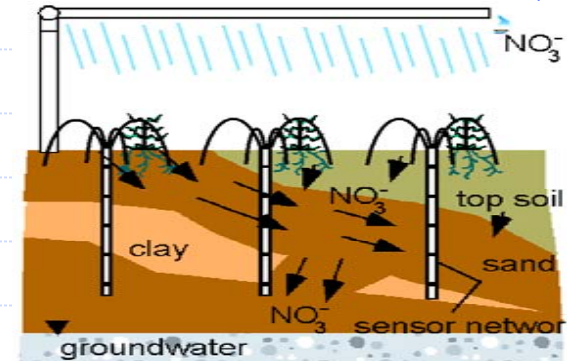
Marine Microorganisms



◆ Micro-sensors, on-board processing, wireless interfaces feasible at very small scale--can monitor phenomena "up close"

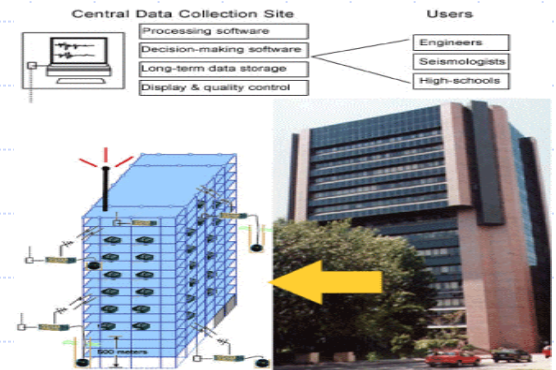
◆ Enables spatially and temporally dense environmental monitoring

Embedded Networked Sensing will reveal previously unobservable phenomena



Contaminant Transport

Seismic Structure Response



Example Application: Seismic

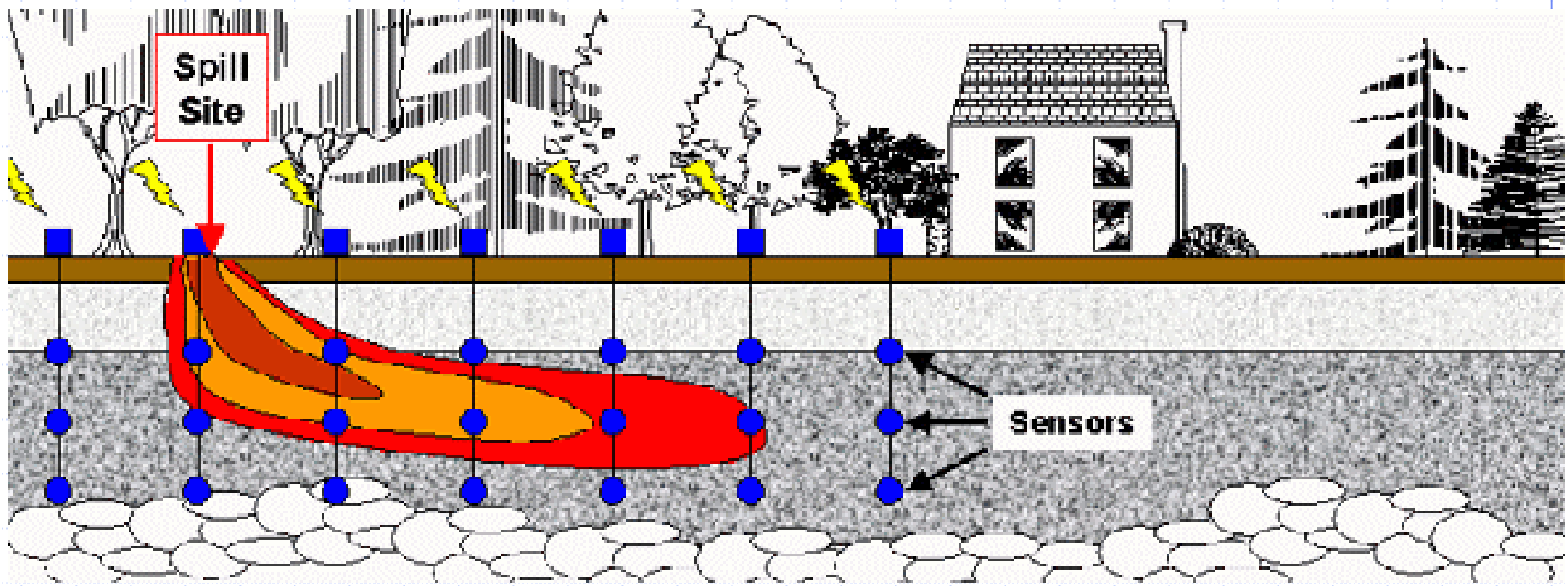


- ◆ Interaction between ground motions and structure/foundation response not well understood.
 - **Current seismic networks not spatially dense enough** to monitor structure deformation in response to ground motion, to sample wavefield without spatial aliasing.
- ◆ Science
 - Understand response of buildings and underlying soil to ground shaking
 - Develop models to predict structure response for earthquake scenarios.
- ◆ Technology/Applications
 - Identification of seismic events that cause significant structure shaking.
 - Local, at-node processing of waveforms.
 - Dense structure monitoring systems.

Research Challenges

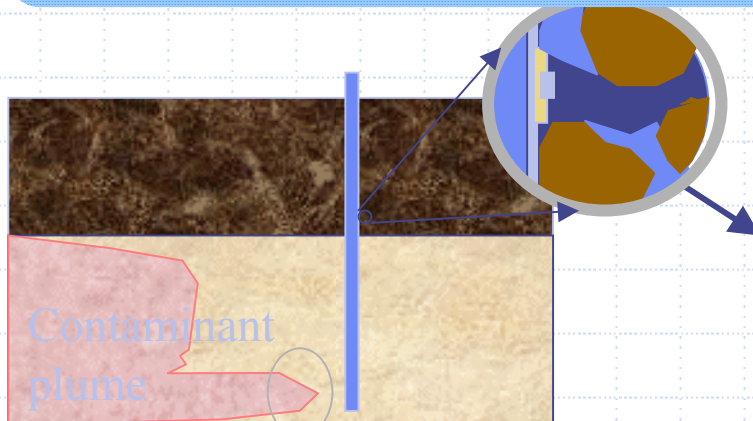
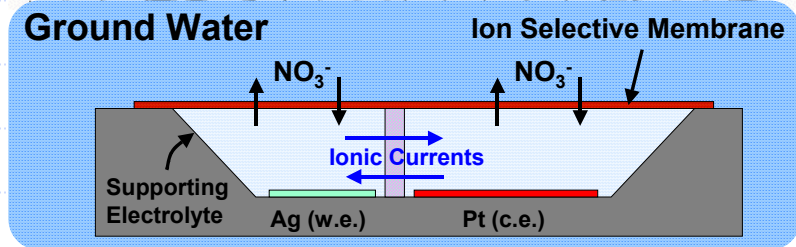
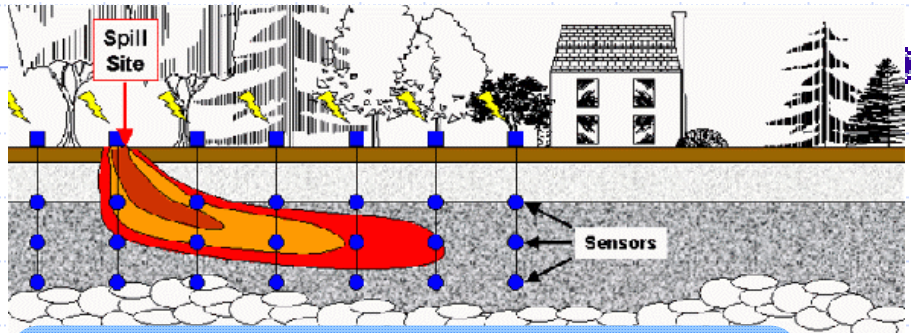
- ◆ Real-time analysis for rapid response
- ◆ Massive amount of data → Smart, efficient, innovative data management and analysis tools
- ◆ Poor signal-to-noise ratio due to traffic, construction, explosions
- ◆ Insufficient data for large earthquakes → Structure response must be extrapolated from small and moderate-size earthquakes, and force-vibration testing

Application Scenario



- ◆ Ecological/Health: Contaminant monitoring/mapping
- ◆ Agricultural: Precision farming

Research Implications



Environmental Micro-Sensors

- Sensors capable of recognizing phases in air/water/soil mixtures
- Sensors that withstand physically and chemically harsh conditions
- Microsensors

◆ Signal Processing

- Nodes capable of real-time analysis of signals.
- **Collaborative signal processing to expend energy only where there is risk.**

◆ Calibration

Ecosystem Monitoring

Science: Response of wild populations (plants and animals) to habitats over time.

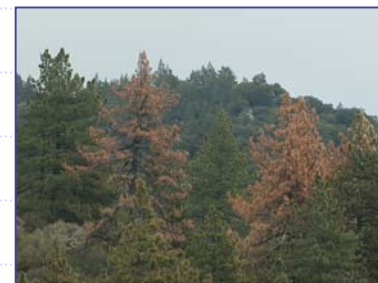
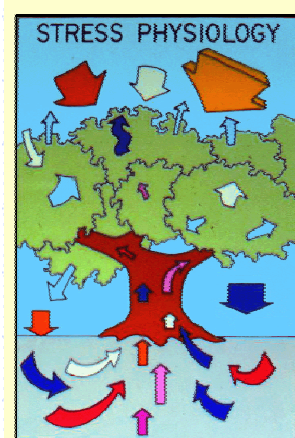
- ◆ Develop in situ observation of species and ecosystem dynamics

Techniques: Data acquisition of physical and chemical properties, at various spatial and temporal scales

- ◆ Automatic identification of organisms (current techniques involve close-range human observation)
- ◆ Measurements over long period of time, taken *in-situ*
- ◆ Harsh environments with extremes in temperature, moisture, obstructions, ...

Field Experiments

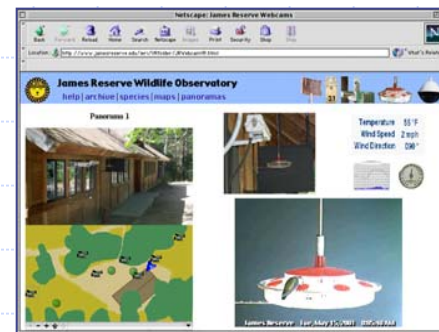
- ◆ **Monitoring ecosystem processes**
 - **Imaging, ecophysiology, and environmental sensors**
 - **Study vegetation response to climatic trends and diseases**
- ◆ **Species Monitoring**
 - Visual identification, tracking, and population measurement of birds and other vertebrates
 - Acoustical sensing for identification, spatial position, population estimation
- ◆ **Education outreach**
 - Bird studies by High School Science classes



Vegetation change detection



Avian monitoring

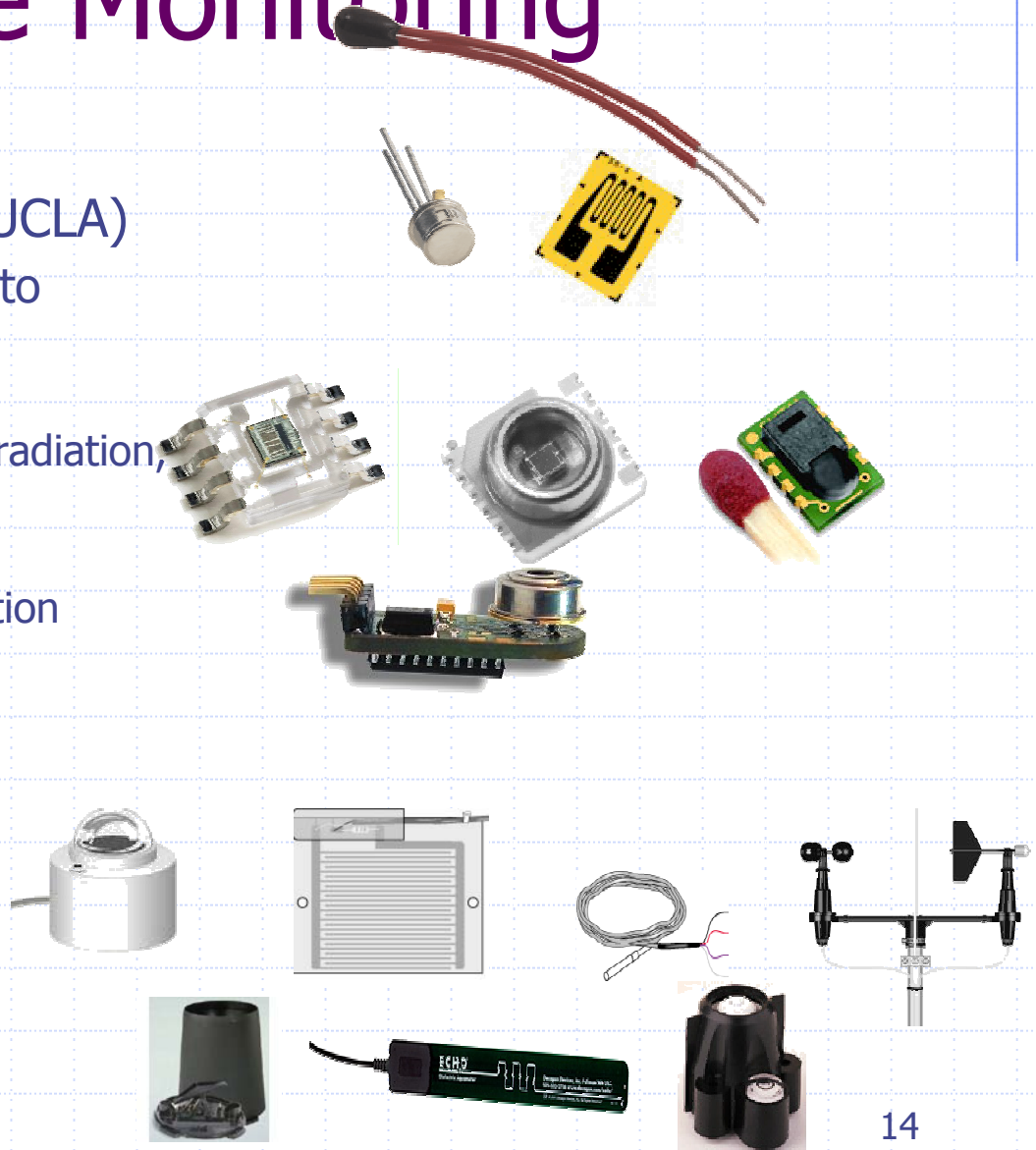


Virtual field observations

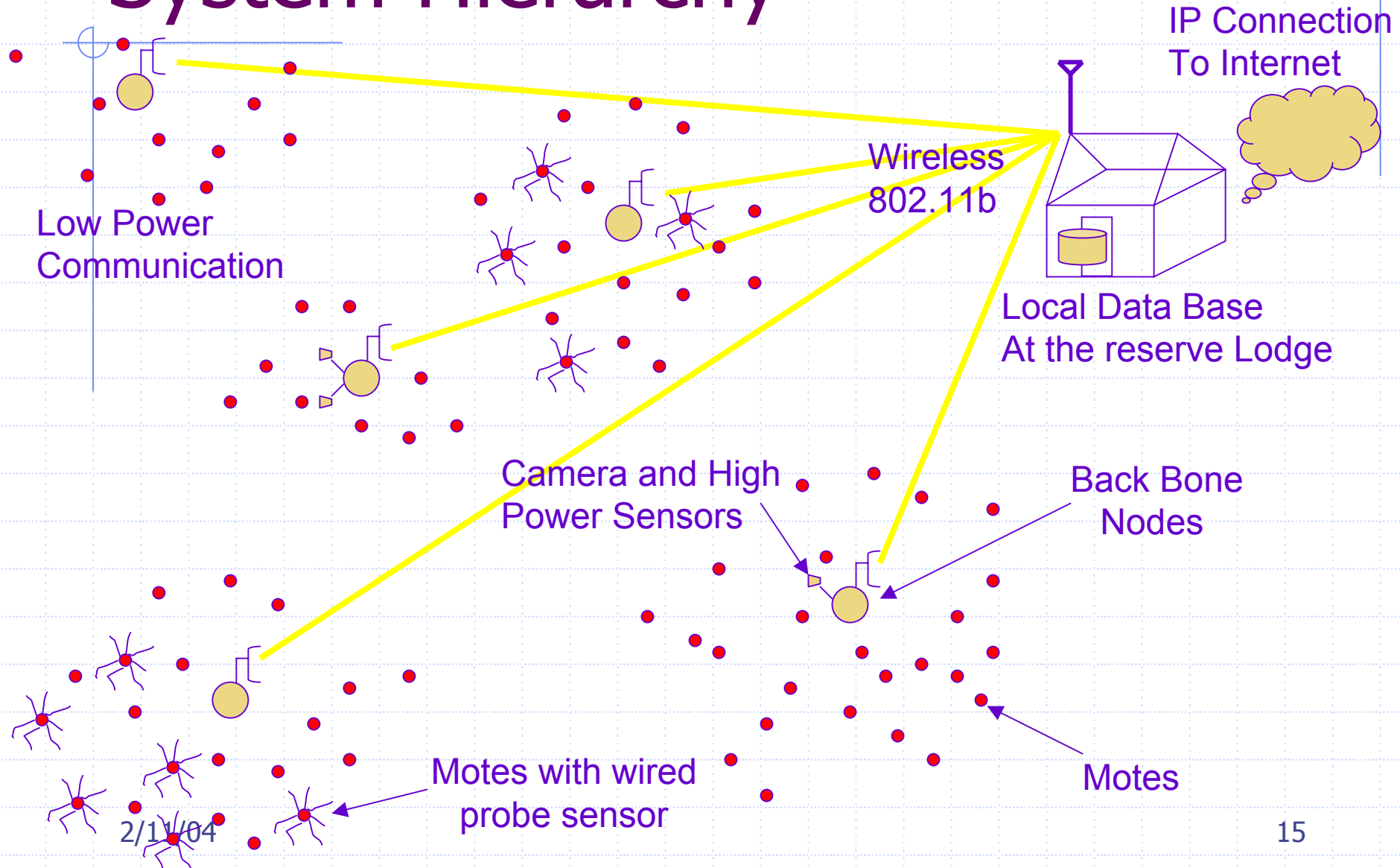
Micro-Climate Monitoring

◆ Weather-motes (Berkeley Intel Lab and UCLA)

- Miniature wired probes to off-board sensors
 - ◆ Leaf wetness
 - ◆ Light: PAR, UV, Solar radiation, Visible light
 - ◆ Rain fall
 - ◆ Wind speed and direction
 - ◆ Soil moisture
 - ◆ Temperature probes
- Onboard
 - ◆ Temp
 - ◆ Humidity
 - ◆ Pressure
 - ◆ Thermopile
 - ◆ Light



System Hierarchy



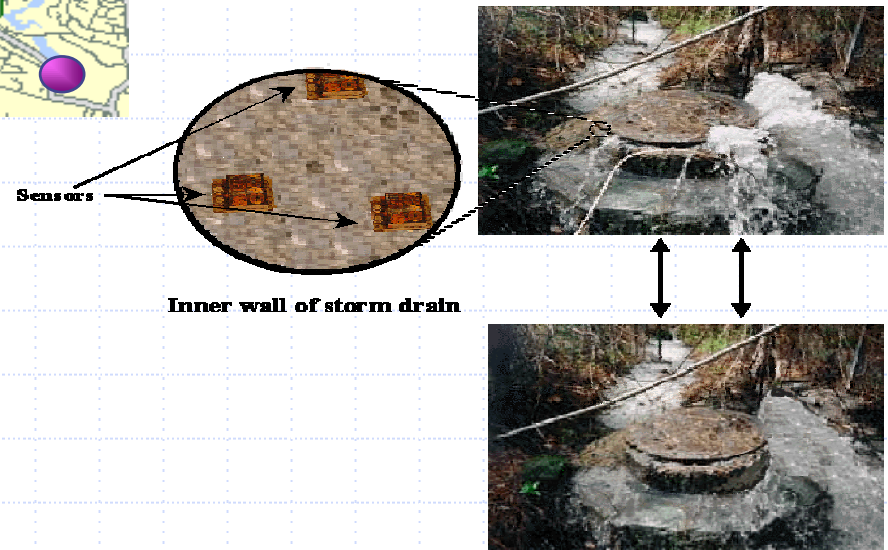
Requirements for Habitat Applications, 1

- ◆ Diverse sensor sizes (1-10 cm), sampling intervals (1cm to 100m), and temporal sampling intervals ($1\mu\text{s}$ to days), depending on habitats and organisms
- ◆ Naive approach → Too many sensors
→ Too many data

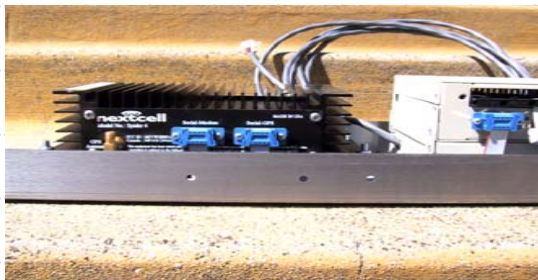
Requirements for Habitat, 2

- ◆ Wireless communication due to climate, terrain, thick vegetation
- ◆ **Adaptive Self-Organization** to achieve reliable, long-lived, operation in dynamic, resource-limited, harsh environment
- ◆ Mobility for deploying scarce resources (e.g., high resolution sensors)

Transportation and Urban Monitoring



Intelligent Transportation Project



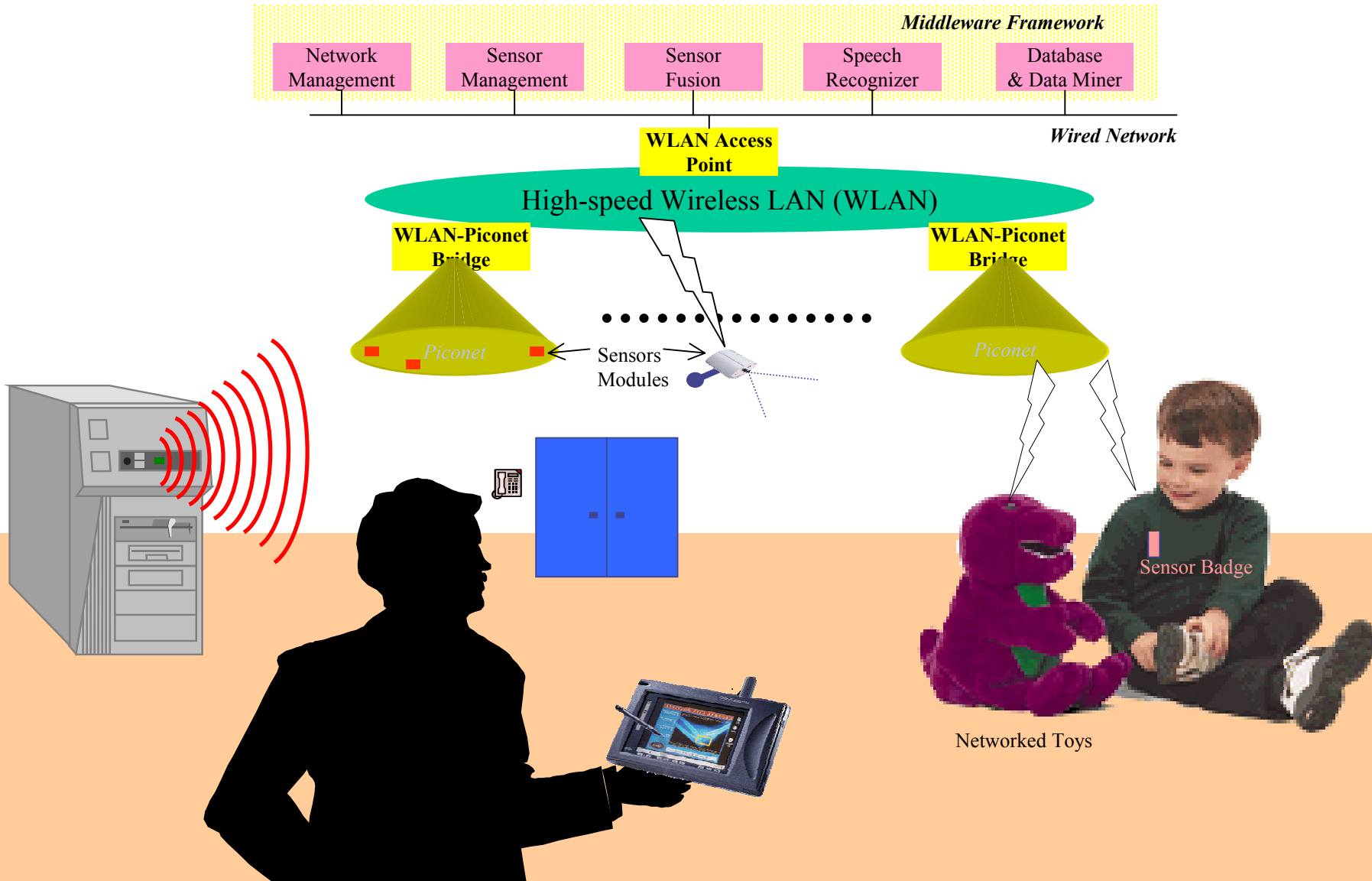
Smart Kindergartens: Physical and the Cognitive, 1

- ◆ Wireless networked sensors densely embedded in a kindergarten room
 - create a problem solving environment that can be continually sensed in detail
 - kids, toys, blocks, playthings, classroom “woodwork”
- ◆ Background computing & data management infrastructure for on-line and off-line sensor data processing and mining

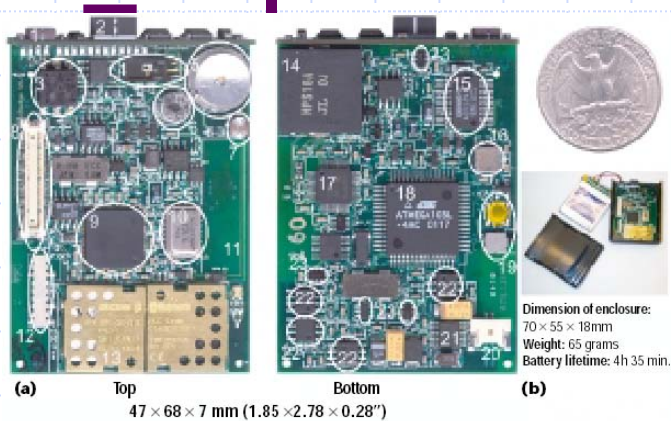
Smart Kindergartens, 2

- ◆ Sensor information used for
 - assessment of student learning and group dynamics
 - problem solving tasks that are adaptive and reactive
 - services beneficial to teacher and students

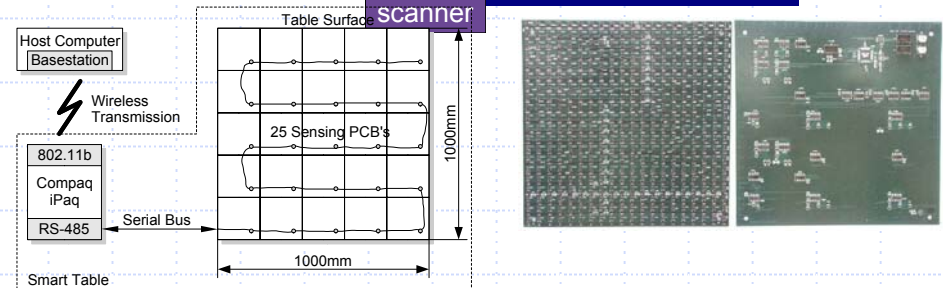
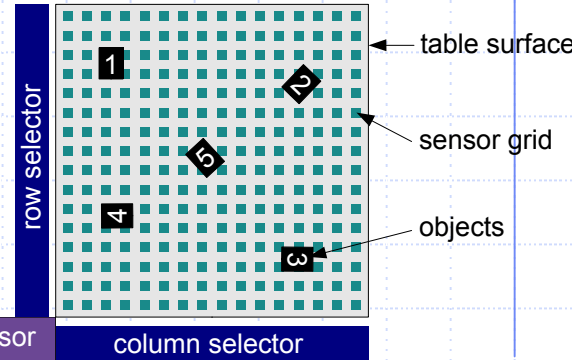
Smart Kindergarten Project: Sensor-based Wireless Networks of Toys for Smart Developmental Problem-solving Environments



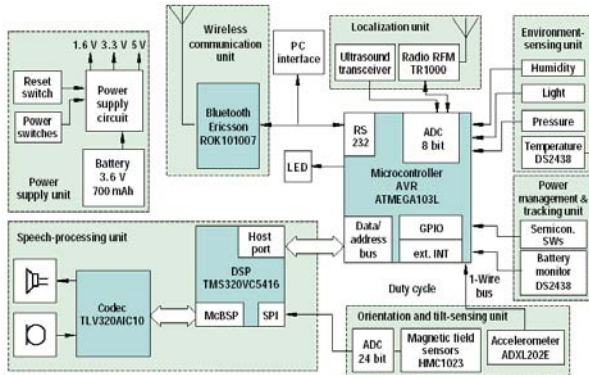
The Smart Kindergarten



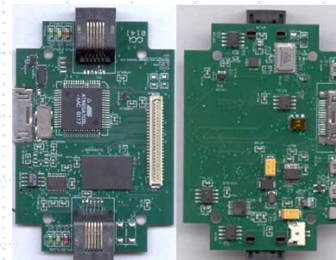
- | | | |
|--------------------------------|----------------------------------|----------------------------------|
| 1. Accelerometer for x, y-axis | 9. DSP | 17. Codec chip |
| 2. Magnetic field sensor | 10. RFM radio (for localization) | 18. Microcontroller |
| 3. Pressure sensor | 11. PCB antenna for RFM radio | 19. Switches (Power, Reset) |
| 4. Humidity sensor | 12. Blue tooth antenna | 20. Battery connector |
| 5. Ultrasound transceiver | 13. Blue tooth module | 21. Power supply |
| 6. Microphone | 14. Loudspeaker | 22. Battery monitors |
| 7. Light sensor | 15. ADC magnetic field sensor | 23. Switches to functional units |
| 8. Connector (SW download) | 16. Accelerometer for x-axis | |



Smart Table: Sensor-instrumented Surface for Object Id and Localization

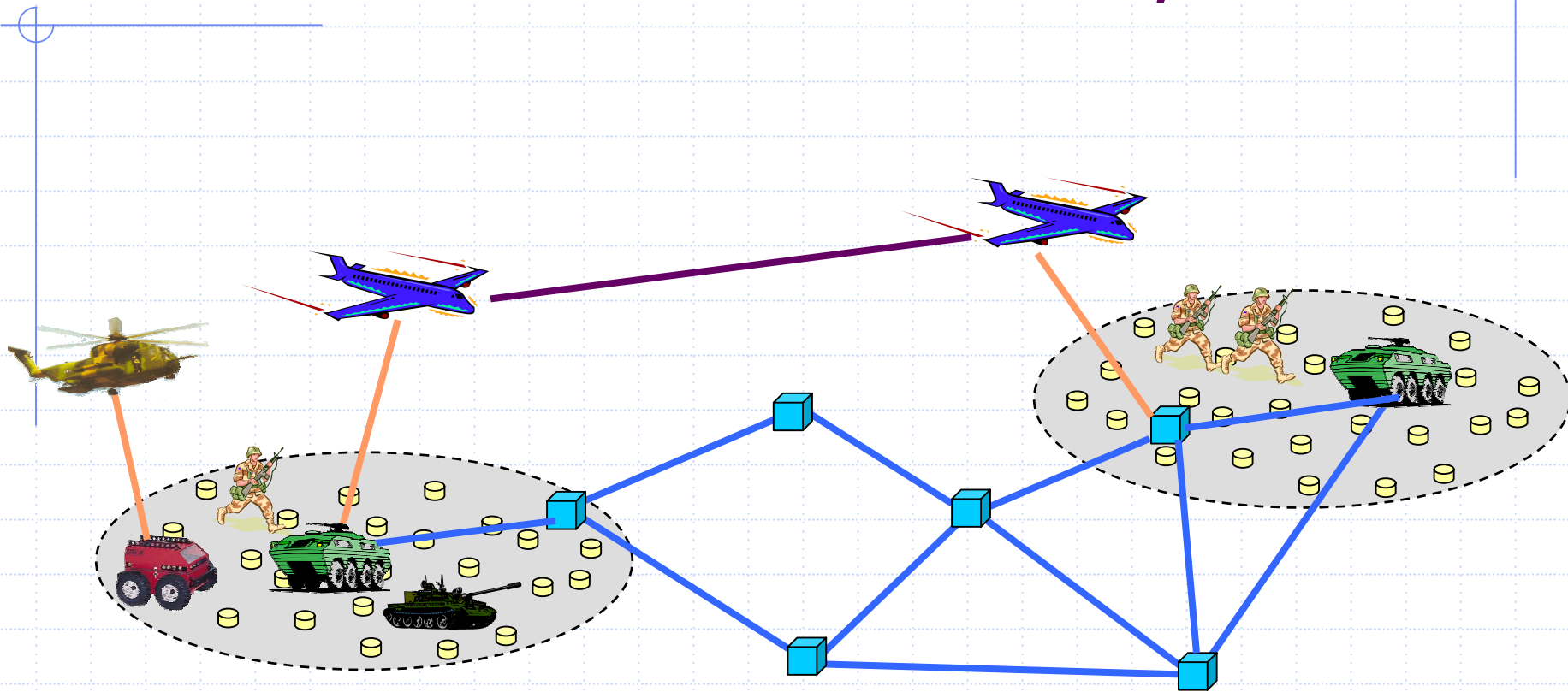


iBadge: Wearable Sensor Node



Medusa MK-2 == Motes + StrongThumb + Ultrasound

WSNs and the Battlefield, 1



WSNs and the Battlefield, 2

- ◆ Mobile 'users' query and track mobile targets in a battle space instrumented with a number of 'sensor networks' composed of a large number of energy limited air-borne and ground-based 'sensor nodes' (e.g. cameras)
 - Users: rovers, UAVs, soldiers
 - Sensors: rovers & UAVs carrying sensors, static sensor nodes
 - Targets: vehicles, soldiers
- ◆ UCLA Minuteman Project

Existing Systems Inadequate in Understanding WSN

- ◆ Large-scale
- ◆ Distributed
- ◆ Real-time (control loops and events)
- ◆ Physically-coupled
- ◆ Resource-constrained
- ◆ Wireless
- ◆ Computation, and not just communication

**Combines the hard problems of the Internet,
Embedded Systems, Wireless Networks, and
Distributed Computing!**

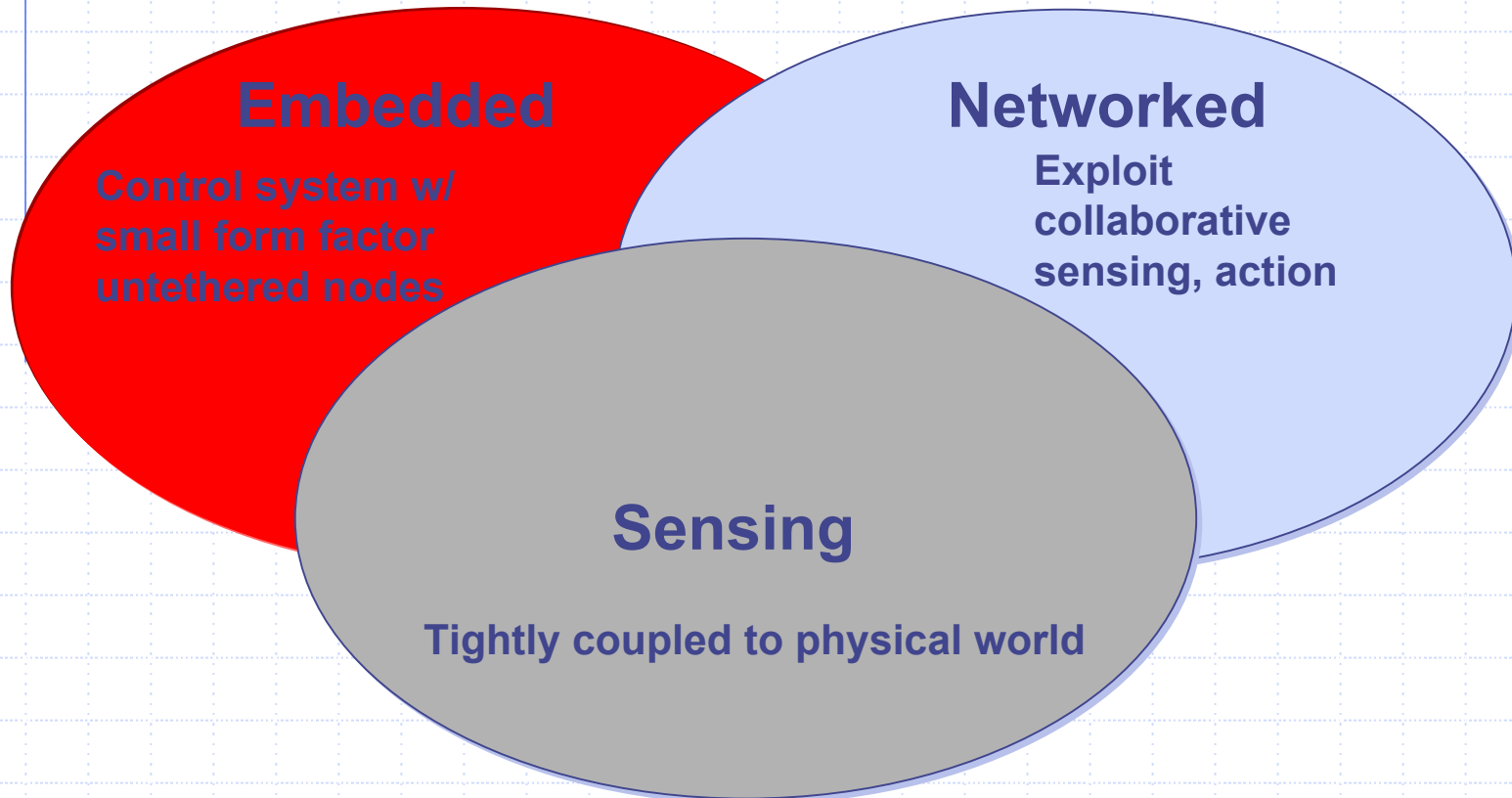
New Design Themes for WSNs

- ◆ Long-lived systems that can be untethered (wireless) and unattended
 - Communication is the primary consumer of scarce energy resources
 - “Every bit transmitted brings a sensor node one moment closer to death” (G. Pottie)
- ◆ Leverage data processing inside the network
 - Exploit computation near data to reduce communication
 - Achieve desired global behavior with localized algorithms (distributed control)
- ◆ “The network is the sensor” (Manges&Smith, Oakridge Natl Labs, 10/98)
 - Requires robust distributed systems of thousands of physically-embedded, unattended, and often untethered, devices

Enabling Technologies

Embed numerous distributed devices to monitor and interact with physical world

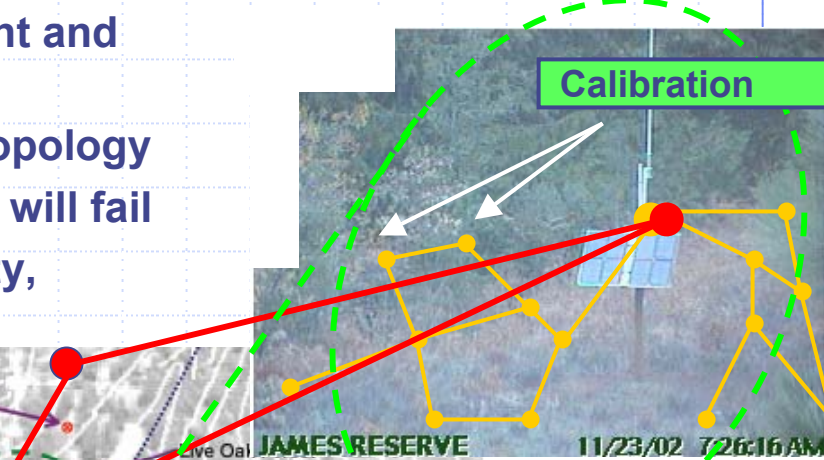
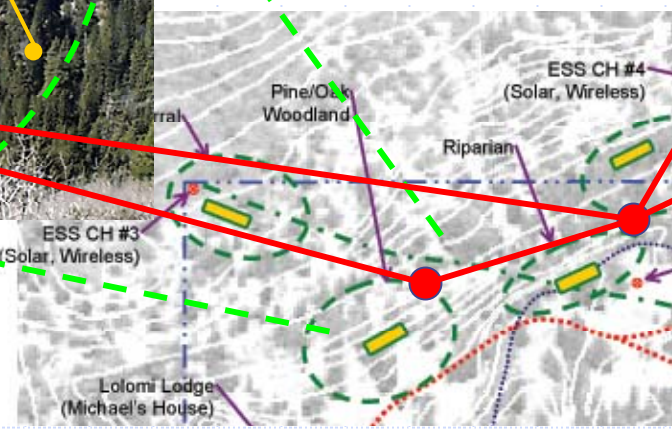
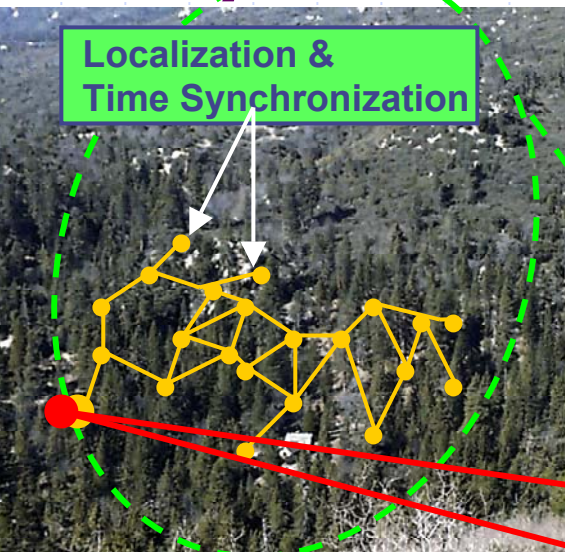
Network devices to coordinate and perform higher-level tasks



Exploit spatially and temporally dense, in situ, sensing and actuation

Long-lived Self-Configuring Systems

- ◆ Irregular deployment and environment
- ◆ Dynamic network topology
- ◆ Hand configuration will fail
 - Scale, variability, maintenance



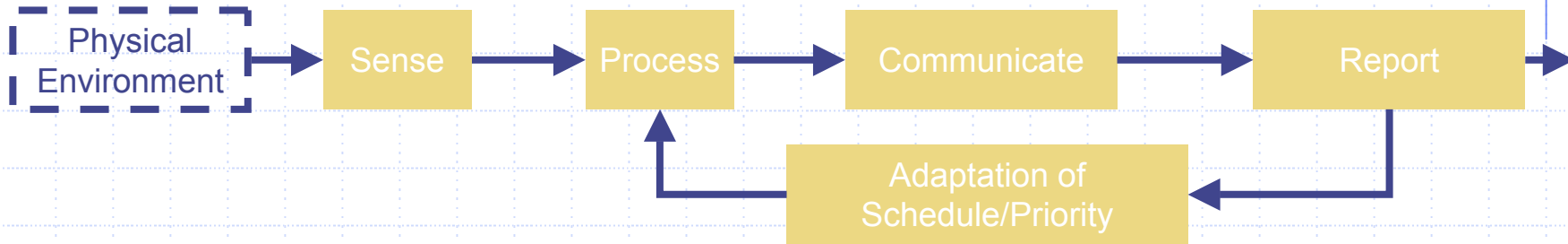
Solution:
local adaptation and redundancy

Information Aggregation and Storage

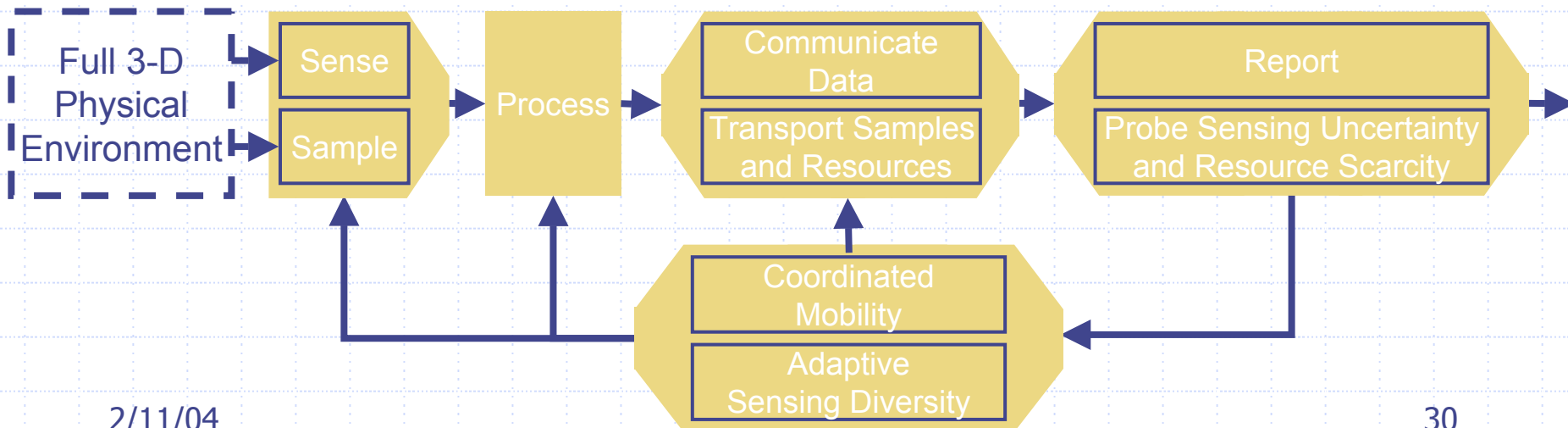


NIMS vs. Static WSNs

- Static Sensor Network



Networked InfoMechanical Systems (NIMS)



From Embedded Sensing to Embedded Control

- ◆ Embedded in **unattended “control systems”**
 - Different from traditional Internet, PDA, Mobility applications
 - More than control of the sensor network itself
- ◆ **Critical applications** extend beyond sensing to control and actuation
 - Transportation, Precision Agriculture, Medical monitoring and drug delivery, Battlefield applications
 - Concerns extend beyond traditional networked systems: Usability, Reliability, Safety

Sample Layered Architecture



Resource constraints call for more tightly integrated layers

Open Question:

Can we define an Internet-like architecture for such application-specific systems?

Systems Taxonomy

- ◆ Spatial and Temporal Scale
 - Extent
 - Spatial Density (of sensors relative to stimulus)
 - Data rate of stimuli
- ◆ Variability
 - Ad hoc vs. engineered system structure
 - System task variability
 - Mobility (variability in space)
- ◆ Autonomy
 - Multiple sensor modalities
 - Computational model complexity
- ◆ Resource constraints
 - Energy, BW
 - Storage, Computation

Load/Event Models

- ◆ Frequency
 - spatial and temporal density of events
- ◆ Locality
 - spatial, temporal correlation
- ◆ Mobility
 - Rate and pattern

Metrics

- ◆ Efficiency
 - System lifetime/System resources
- ◆ Resolution/Fidelity
 - Detection, Identification
- ◆ Latency
 - Response time
- ◆ Robustness
 - Vulnerability to node failure and environmental dynamics
- ◆ Scalability
 - Over space and time

Architecture Drivers

DRIVERS

Varied and variable environments

Energy and scalability

Heterogeneity of devices

Smaller component size and cost

RESEARCH AREAS

Adaptive Self-Configuring Wireless Systems

Distributed Signal and Information Processing

Sensor Coordinated Actuation

Embeddable Microsensors

Research Opportunities, 1

- ◆ Self-configuration and Resource Management
 - Timing Synchronization, Node Localization, Sensor Calibration
 - Topology Management, Coverage and Deployment, Exploiting Hierarchy
 - Sensor Network Management
 - Controlled mobility
- ◆ Programming the Aggregate
 - Storage Framework
 - Programming Framework
 - Runtime Mechanisms for Macroprogramming

Research Opportunities, 2

- ◆ Signal Processing & Information Theory
 - Distributed detection, identification, tracking
 - Information theoretic limits and trade-offs
- ◆ Technology
 - Advanced node platforms (energy scavenging, mobile etc.)
 - Advanced sensors (biochemical, genetic, self-calibrating etc.)
- ◆ Tools
 - Simulation, Emulation, Analysis, and Optimization, Tools

Summary, 1

- ◆ Wireless technology focus is moving towards improving the interaction between people & their physical world
- ◆ Distributed embedded systems (cheap low power processors and sensors, all cooperatively networked) are the key enabling technology
- ◆ Requires combination of wireless, networking, embedded systems, and energy-aware
 - Distributed embedded computation in ad hoc, resource constrained environments

Summary, 2

- ◆ Limitations of analysis and simulations in physically-coupled resource-constrained embedded systems
- ◆ Important to
 - build real embedded system hardware and software in the context of real applications
 - do all of: algorithms, protocols, systems, tools, & applications
 - have a multidisciplinary team: embedded systems, networking, signal processing, distributed computing etc.

Assignments

- ◆ Download the survey on sensor nets
- ◆ Updated information on the class web page:

www.ece.neu.edu/courses/eceg364/2004sp