# Happy Endings for Flip Graphs 

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## Rotation in binary trees



Rearrange links in and out of two adjacent nodes while preserving in-order traversal ordering of all nodes

Fundamental to many balanced binary search tree data structures

## Equivalence of binary trees and polygon triangulations



Tree with n leaves

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\Leftrightarrow
```

polygon with n vertices

Root + leaves of tree $\Leftrightarrow$
edges of polygon

Internal nodes of tree $\Leftrightarrow$
triangles of triangulation
(a form of planar duality)

Rotation between trees $\Leftrightarrow$
Flip between triangulations

## Rotation graph and rotation distance



Vertices: n-node binary trees
Edges: rotations
Rotation distance:

## minimum \#rotations

to change one tree into another
(shortest path length in rotation graph)

Rotation graph is skeleton of ( n -1)-dimensional Stasheff polytope

D. Eppstein, UC Irvine, SoCG 2007

## Rotation distance and hyperbolic geometry

[Thurston, Sleator, Tarjan 1986]
Max distance among n -node trees is exactly $2 \mathrm{n}-6$

- Use flipping of polygons instead of rotation of trees
- Form polyhedron with triangulations as its top and bottom
- Flip sequence = partition of polyhedron into tetrahedra
- Use hyperbolic geometry: all tetrahedra have volume $\leq \pi$
- Find polyhedra with large hyperbolic volume

Obvious open problem: how to compute flip distance?
Little progress since then...

## Natural generalization: flip graphs of point sets

(shown: all triangulations of a 9-point square grid)

Flipping is important in mesh improvement

Flip distance can be quadratic [Lawson 1972]

More complex than polygons?

## The Happy Ending theorem



Five points in general position have four forming a convex quadrilateral [E. Klein]
More generally, for any n, sufficiently many points (no three collinear) include the vertices of a convex $n$-gon
Erdős and Szekeres (1935); "happy ending" = Klein-Szekeres marriage

## Empty convex polygons in point sets

Five points in general position always contain an empty quadrilateral
Ten points in general position always contain an empty convex pentagon [Harborth 1978]

Sufficiently many points in general position always contain an empty convex hexagon [Gerken 2006; Nicolás 2006]

Arbitrarily many points in general position do not always contain an empty convex heptagon [Horton 1983]

## But what if they're not in general position?

Point sets without empty convex quadrilaterals: highly constrained (we'll see later: can describe them all simply)

Point sets without empty convex pentagons: many examples

points on two lines, any convex subset of a lattice, ...

## Point sets with no empty quadrilateral

= point sets with exactly one triangulation
= vertices of planar graphs connecting any two points by a straight path


Four infinite families and one special case...
[E. 1997; Dujmovic, E., Suderman, Wood 2006]
Flip distance is trivial!

## If there are empty quadrilaterals...

describe them all using the quadrilateral graph
vertices $=$ line segments between input points
edges $=$ pairs of diagonals of empty quadrilaterals


## Partial cubes

Graphs that can be labeled by bitvectors so graph distance = Hamming distance

## Examples:



## Point sets with no empty pentagon

= point sets for which quadrilateral graph is a forest
= point sets for which flip graph is a partial cube
(our main results)

Idea for proof that no empty pentagon => forest:

- transform point set so Delaunay triangulation unique
- parent of edge = replacement edge of Delaunay flip
- there can be only one

Idea for proof that flip graph is partial cube:

- triangulation has one edge per tree in forest
- find short paths via constrained DT of shared edges


## Algorithm for flip distance

(for point sets with no empty pentagon)
Flip both triangulations to Delaunay
Find edges that occur in one flip sequence but not both
Flip distance = number of such edges

Total time: $\mathrm{O}\left(\mathrm{n}^{2}\right)$

Condition that input has no empty pentagon can also be tested in $\mathrm{O}\left(\mathrm{n}^{2}\right)$

## Estimating flip distance for more general point sets

Represent triangulation as subset of quad graph vertices
For each quad graph vertex in T1, find path connecting it to a corresponding quad graph vertex in T2

Minimize total length of paths (min weight matching)
Flip distance $\geq$ total path length

Underestimate of true distance, suitable for A* algorithm

## Point sets with no empty hexagon

necessary condition for estimated distance $=$ flip distance
conjecture: also sufficient condition

flip graph of a hexagon
top, bottom triangulation have flip distance $=4$ estimated distance $=3$

## Conclusion

first progress on computing flip distance in nontrivial family of instances
complexity hierarchy for point sets? (bigger empty polygons => more complex)
sometimes general-position assumptions hide interesting geometry

