

# Open Ethernet Connectivity via Modbus/TCP – Product Note

# Background

Ethernet, or more exactly, Ethernet TCP/IP networks, operating at 10MBits/sec or higher, are becoming increasingly popular in an industrial production environment. This is due to their speed, versatility, and commonality with other business level networks based on the same networking standards within a plant location. Many industrial level products now offer an Ethernet interface, either direct to the equipment or through a hardware bridge. The protocols used within this Ethernet environment are an important factor in connectivity between a software package running in a PC and the field hardware.

A Modbus RTU protocol interface has been used as a defacto standard for many years in lower speed, RS-485 serial network applications and is available for most of Honeywell's data recording and control products. A relatively new protocol standard gaining popularity, Modbus/TCP (also called Modbus TCP/IP), is now available as a communications driver in many popular software application packages used for operator interface and data acquisition. Modbus/TCP combines the Modbus RTU protocol with Ethernet TCP/IP, allowing data access over an Ethernet LAN (Local Area Network) connection. Since standard Modbus addressing is used, interfacing is well known.

HC900 controllers support the Modbus/TCP protocol as standard via a direct Ethernet connection. This is also the case for Trendview paperless recorders. Honeywell's other serial RS-485 Modbus products such as UDC3300 controllers or UMC800 support the protocol via an external Ethernet/Modbus bridge hardware device or an internal bridge card.

For reference, a section provided later in this document provides a review of Ethernet TCP/IP networks and protocols and a Glossary of Terms.

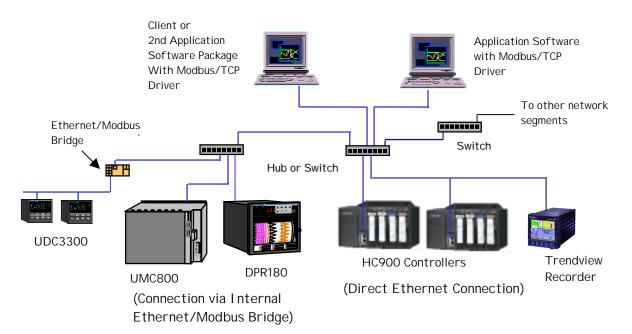


Fig. 1 Ethernet TCP/IP Network with 10Base-T Star Topology

## Why is Ethernet communications using Modbus/TCP protocol important?

- Customer demand Ethernet LAN connection to application software is becoming a requirement for many customers, most of which have business or production networks using Ethernet with IT (Information Technology) support.
- **Growing popularity of Modbus/TCP over Ethernet** most HMI and data acquisition software packages offer a Modbus/TCP driver, it is becoming an open standard
- **Modbus familiarity** Data access for read and write is via normal serial Modbus RTU methods using the same function code and parameter definitions, known to many users. Real-time data available in the HC900 such as control loop parameters, signal tags, variables, analog inputs, etc. can be accessed real-time via the appropriate Modbus address.
- **Speed** Ethernet networks (now normally 10Base-T star topology) offer higher speed data access versus serial RS-485 networks. This is especially true for direct Ethernet-connected products such as the HC900. Depending on Networks will not be slowed significantly as more units are placed on the network due to Ethernet's higher "bandwidth". A 10Base-T network offers 10MBits/sec. data rates although there is possible contention for network access due to Ethernet CSMA/CD principles.
- Ethernet Multi-Channel Support Many applications can operate concurrently over an Ethernet LAN between Ethernet "nodes" using separate "channels". The HC900 can support up to 5 concurrent connections to software applications. As an example, 2 separate HMI packages, HC900's Hybrid Control Designer software, a Visual BASIC and an EXCEL application at different network locations can all address the same controller concurrently. On the other hand, RS-485 supports only a single channel connection.

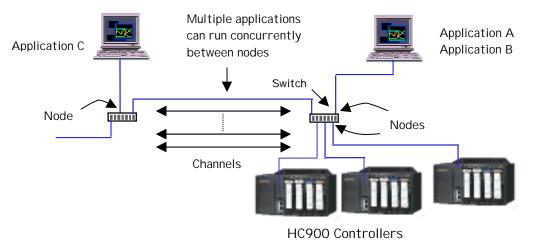
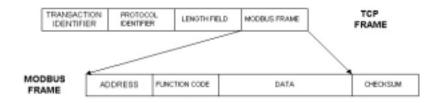


Fig. 2 – Multiple Channel Application Support

# Modbus/TCP Protocol

The Modbus/TCP protocol was released publicly in 1999 by Groupe Schneider's Modicon division to provide open, vendor-independent access to PLC's, I/O modules, Ethernet/Modbus bridges, or other process instrumentation over Ethernet TCP/IP networks. This is simply an encapsulation of Modicon's Modbus RTU protocol within a TCP/IP frame as shown in Fig. 3. Function codes and data registers are accessed the same as with Modbus RTU. The address in the Modbus frame is set to 00 since addressing to direct Ethernet-connected devices utilizes the IP address. In addition, there is no checksum for error checking since this is implemented at the TCP/IP network levels. The specification is available for royalty-free licensing from Modicon. To review the specification, access the Modicon website at:

http://www.modicon.com/openmbus/standards/openmbus.htm.



### Fig. 3 Modbus/TCP frame

### HC900 Modbus/TCP Setup

The HC900 Ethernet network connection for Modbus/TCP is inherent once the Ethernet IP address for the controller host port is established. The HC900 predominantly uses an IEEE floating point format for communicating data to software applications supported by Modbus/TCP protocol. A floating point value is sent as (2) consecutive 16-bit registers, each register of which consists of two 8-bit bytes. Some software packages require the registers to be sent in a certain order. The HC Designer software tool allows this order to be selected. The following table lists the selections provided.

Modbus TCP double register format:	FB B - Big Endian (0,1,2,3)
Requires return to RUN mode to	FB B - Big Endian (0.1,2,3) FB BB - Big Endian Byte Swap (1,0,3,2) FB L - Little Endian (3,2,1,0) FB LB - Little Endian Byte Swap (2,3,0,1)

Selection	Register (Word) Order	Floating Pt Format	Comment
FB B	First word High	Big Endian (0,1,2,3)	Default
FB BB	Big Endian Byte-		
		Swapped (1,0,3,2)	
FBL		Little Endian (3,2,1,0)	
FB LB	First word low	Little Endian Byte-	Most
		Swapped (2,3,0,1)	common

The Modbus TCP double register transmission format selection, FB LB "Little Endian Byte-Swapped", would be selected for interface to most third party software packages which use this format as standard. Our default, FB B "Big Endian" is used with SpecView32 or PlantScape software and follows the "Honeywell" default format of other control and recording products. Fortunately, most PC software packages offer a word swap selection in their driver package anyway, so there should never be an incompatibility.

The application software Modbus/TCP driver (server) must be configured per the software vendor's documentation for dialog box entries. This usually involves setting up a communications channel based on using an installed Ethernet NIC (Network Interface Card or adapter), a TCP/IP port (default is 502), entry of the unit's IP address, use (or non-use) of zero-based register addressing, and connection timeout.

### What Data Can Be Communicated?

HC900 controllers provide access to an array of parameters that are categorized by function in the HC900 Ethernet Modbus/TCP Communications User's Manual, 51-52-25-111. The HC900 retains all of the Modbus addresses available for the UMC800 and expands the listing due to its greater capacity and functionality. Table 1 summarizes this parameter access, including the read/write capability, when using an Ethernet Modbus/TCP or Modbus Ethernet protocol driver (server) for the host software application. The HC Designer tool also provides the Modbus addresses for <u>all</u> Signal Tags and Variables plus the starting Modbus addresses for the major functions supporting a Modbus address set such as control loops, SP programmers, etc. The Tag Information and the Block Modbus Addresses reports may be viewed on-line and printed out for reference when configuring the database for the host software application.

#### Entering Modbus Addresses in Third Party Software

After selecting the driver for the TCP/IP channel in a third party software package, the tag database would then be created in some cases via a Wizard. The tag definition dialog box would have entries typically for Data Type (Float, Integer, etc.) and decimal (or Hex) parameter addressing, typically decimal with a range of 1 to 65535. The Modbus function code (1, 2, 3, 4, 16, etc.) may also be a separate entry or part of the decimal address. These function codes are defined as follows:

Function Code 1: Read Digital Output Status Function Code 2: Read Digital Input Status Function Code 3: Read Holding Registers Function Code 4: Read Input Registers (Analog Inputs) Function Code 5: Force Single Digital Output Function Code 6: Preset Single Register (Write) Function Code 16 (10 hex): Preset Multiple Registers (Writes) Function Code 17 (11 hex): Report HC900 ID

Floating point values take (2) consecutive 16-bit registers (32 bits) and it is normal to just address the first register. For example, Analog Input 1 on an AI card (8 inputs) in Rack 1, Slot 1 would be addressed, using function code 4, by entering 0000, Analog Input 2 would have address 0001, and so on. Integers use only (1) 16-bit register. Sometimes the driver will add a leading 4 or 40 to the address, e.g. 400065 for Loop1 PV, to represent "Holding" registers accessed using Modbus Function Code 3, or a 3 or 30 to the address (to represent "Input" registers accessed using Function Code 4). The application via the communications driver knows by data type how many registers to obtain in sequence.

The table lists only the starting address for the first parameter of many for a certain type or for a set of parameters such as for control loops. The addresses are the same as for the UMC800 to the extent of the UMC800 capacity. There is extending addressing in the HC900 due to its greater capacity. This necessitated creation of duplicate addressing to provide full contiguous address space for some parameter types as noted. For further detail on Modbus addressing, consult the HC900 Ethernet Modbus/TCP Communications User Manual.

Parameter	Data Type	Access	Modbus Function Code (Dec)	*Modbus Starting Address	Same As UMC800?	Comments (Offsets are for decimal addressing), see Table 1 in User Manual 51-52-25-111
Analog Inputs – Al's	Float	Read	3	6145 (1800 h)	Yes	First 8 slots (64 Al's) of Rack 1 only
74.0	Float,	Read	4	0 (0 h)	No	All Al's (up to 128), addressed on a consecutive rack basis
Digital Inputs	Integer	Read	01	0 (0 h)	Yes, up to capacity.	See 51-52-25-111 User Manual for address map.
Digital Outputs	Integer	Read, Write	02,05	0 (0 h)	Yes, up to capacity.	See 51-52-25-111 User Manual for address map.
Signal Tags	Float	Read	3	8193 (2000 h)	Yes	Access to Signal Tags 1 to 1000. Digital tags read as 0.0 and 1.0 for logic 0 and 1
	Float	Read	3	15201 (3B60 h)	No	Access to Signal Tags 1 to 2000. Digital tags read as 0.0 and 1.0 for logic 0 and 1
Variables	Float	Read/Write	3, 16	6337 (18C0 h)	Yes ( up to Variable 150)	Access to Variables 1 to 600. Digital Variables read/write as 0.0 and 1.0 for logic 0 and 1
Loop Parameters (approx. 50)	Float (& some Integer)	Read and Read/Write	3, 16	65 (40 h) (for Loop 1, starting with PV)	Yes ( up to loop 16)	For all loops beyond Loop 1 up Loop 24, add 256 to decimal address for parameters applied to successive loops. Loop 25 starts at 30785 decimal (7840 h), add 256 up through Loop 32
PV, Loop 1	Float	Read	3	65 (40 h)	Yes	
WSP (Working SP), Loop 1	Float	Read	3	69 (44 h)	Yes	
Output, Loop1	Float	Read/Write	3	71 (46 h)	Yes	
LSP (Local SP), Loop1	Float	Read/Write	3, 16	107 (6A h)	Yes	
Auto/Manual, Loop 1	Integer	Read/write	3, 16	251 (FA h)	Yes	Bit 0 = 0 for Manual and 1 for Auto.
Remote/Local, Loop 1	Integer	Read/write	3, 16	253 (FA h)	Yes	Bit 0 = 0 for LSP and 1 for RSP.
Set Point Programmer Parameters (10)	Float & Integer	Read and Read/Write	3, 16	7681(1E00 h)	Yes	Provides status and control of loaded program, add 16 to decimal address for successive programmers 1-4. Programmers 5-8 start at address 32769.
Set Point Programmer Add. Parameters (15)	Float & Integer	Read and Read/Write	3, 16	7681(1E00 h)	Yes	Provides loading of new profile and other setup parameters, add 64 to decimal address for successive programmers 1-4. Programmers 5-8 start at address 32881.
Set Point Programmer Segment Data (5 per segment)	Float & Integer	Read/Write	3, 16	10241(2800 h)	Yes	Allows read/write of segment data, add 512 to decimal address for successive programmers 1-4. Programmers 5-8 start at address 33281
Set Point Scheduler Parameters (Approx. 37)	Float & Integer	Read and Read/Write	3, 16	12289 (3000 h)	Yes (for Sched 1 Only)	Provides status and control of loaded program for all outputs and events. SP Scheduler 2 starts at 12369 decimal.

Parameter	Data Type	Access	Modbus Function Code (Dec)	*Modbus Starting Address	Same As UMC800?	Comments (Offsets are for decimal addressing), see Table 1 in User Manual 51-52-25-111
Set Point Scheduler Segment Data (28 per segment)	Float & Integer	Read/Write	3, 16	12801 (3200 h)	Yes (for Sched 1 Only)	Allows read/write of segment data. SP Scheduler 2 starts at 27649 decimal.
Sequencer Parameters	Float & Integer	Read and Read/Write	3,6, 16	23201(5AA0)	No	Provides status and control of loaded sequence for all outputs and events. Add 608 for each successive sequencer.
Sequencer Step Table	Float & Integer	Read/Write	3,6, 16	23233 (5AC0)	No	Allows read/write next step data, step time, Aux. Out, (up to 64). Add 608 for each successive sequencer.
Sequencer State Table	Integer	Read/Write	3,6, 16	23745 (5CC0)	No	Allows read/write of state # assignment to steps. Add 608 for each successive sequencer. Note: state table is configured by HC Designer config. Tool only.
Stage	Float & Integer	Read & Read/Write	3,6, 16	25089 (6200h)	No	Add 48 for each Stage
Ramp	Float & Integer	Read & Read/Write	3,6, 16	25601(6400h)	No	Add 48 for each Ramp
Hand-Off-Auto	Integer	Read and Write	3, 6, 16	26113(6600h)	Yes	Add 16 as offset for each HOA
Alternator	Integer & Float	Read & Read/Write	3, 6, 16	26369 (6700h)	No	Add 48 as offset for each Alternator
Alternator Output Order Scratch Pad	Integer	Read/Write	3, 6, 16	27137(6A00h)	No	
Device Control	Float & Integer	Read & Read/Write	3, 6, 16	27393(6B00)	Yes	Add 16 as offset for each Device Control

\* This is the decimal equivalent address for zero-based Hex addressing (add 1 after conversion of Hex to decimal). You may need to subtract 1 from that listed if entry is not zero-based. In other cases, such as with Honeywell's PlantScape Modbus driver, you are required to add 1 to this listing. See HC900 Ethernet Modbus/TCP Communications User Manual 51-52-25-111 for more information.

# What Software Packages Provide Modbus/TCP Drivers?

The following software packages are known to have Modbus/TCP (also called Modbus Ethernet or Modbus TCP/IP) drivers (or servers). Most of these packages only provide this interface for certain operating environments such as Windows NT or 2000. HC900 Signal Tags and Variables are floating point format regardless of whether it is digital or analog (digital values are communicated as 0.0 for logic 0 or OFF and 1.0 for logic 1 or ON). Some software packages support use of analog floating point values for digital objects. Please consult with the software vendor for further information. This list does not imply that Honeywell certifies interface compatibility for third party software.

Vendor	Package	Comments on Interface	Honeywell Support
Specview	Specview32	Modbus addressing is transparent, data is selected by name from groups called Instrument Views. Windows 98, Me, NT, 2000, XP supported.	Yes
Honeywell	PlantScape Vista/SCADA	*Specify Modicon PLC, Modbus Interface (uses Modbus register addressing) which includes Modbus/TCP driver. Available for R320 (NT-based) and later. Latest R400 requires Windows 2000. Standard in Vista, Model # MZ-NTIF05 in SCADA. Improved interface including acronym- addressing and SP Programmer/Recipe displays is planned for mid-2002.	Yes
Wonderware	In Touch	Specify mbenet.exe v7,5,0,9 I/O Server	
Ci Technologies	CiTect	Specify MODNET driver Ethernet (Modbus/TCPIP), Win95, NT support	
Intellution	iFIX	Specify Modicon Modbus Ethernet Driver (MBE), Win NT, 2000 support	

\*This is as of March, 2002. Consult IPC Marketing for updates relative to driver improvements.

### **Other Ethernet Interface Protocols**

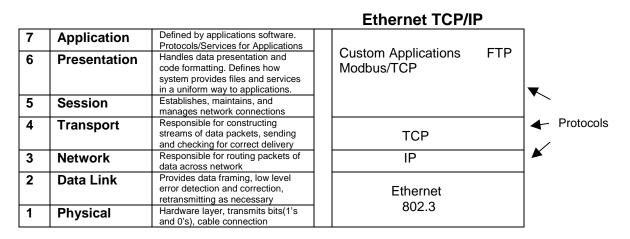
Modbus/TCP is not to be confused with Ethernet/IP. This is also an emerging open standard that bundles TCP/IP with DeviceNet and ControlNet protocols.

### **Review of Ethernet TCP/IP Networks and Protocols**

Networking of data in an Ethernet environment actually involves a suite of communication protocols to assure that the proper data is delivered and understood between devices at separate nodes on the network. TCP/IP is a networking protocol as is Modbus/TCP. However, each is part of a different "layer" in a networking communications structure.

Ethernet TCP/IP networks, widely popular today, use TCP/IP (Transportation Control Protocol/Internet Protocol) to transport messages between PC's. TCP/IP is the basis for Internet connectivity. It is actually two protocols that provide a set of services that devices use to communicate over Ethernet LAN's. Using TCP/IP does not guarantee that a recorder or controller will communicate with a PC; it only guarantees that messages will be transferred successfully. To establish understanding and interoperability between devices, a common *application* protocol is needed. This is where Modbus /TCP protocol is utilized as part of a software application.

As indicated, a suite of networking protocols is necessary to allow various types of equipment to reliably communicate. A networking protocol structure developed by the International Standards Organization, popularly known as the OSI (Open Standards Interface) 7-layer Model, provides a framework for defining network communications. Fig. 4 shows the generalized model with the layer definitions at the left and how Ethernet TCP/IP networks apply to the model at the right. Each higher layer depends on services provided by a lower level layer. The acronyms for some of the various protocols that apply at various layers are shown. See the Glossary for a full definition.



# Fig. 4 OSI 7-Layer model and Ethernet TCP/IP Representation

It is important to note that Ethernet alone is only the lower level part of a communications structure – the physical, bit transmission, data framing, and data flow control portion (Physical and Data Link Layers). The Ethernet hardware interfaces in our products support the physical connection (typically RJ-45 connector for 10 Base-T networks) and the CSMA/CD (Carrier Sense Multiple Detection/Collision Detection) feature of Ethernet communications.

Ethernet is non-deterministic meaning that any node can broadcast a request for information at any time. The CSMD/CD feature allows a collision (more than one node communicating at once) to be detected and will cause a variable timeout at each node before trying again. This is normally not a problem due to the high Ethernet communications bandwidth if the network segment assigned to the data acquisition task is isolated in some way from other plant Ethernet LAN operations. If the LAN is to be linked to another LAN at the plant location, it is typical to use switches to protect against non-pertinent data traffic from other LAN segments. The plant IT department would need to be consulted in this matter.

# Glossary of Terms

Name/Acronym	Name/Definition	Comments
10Base-T	Ethernet network using twisted pair wiring and RJ-45 connectors, used in star topologies	Most popular Ethernet standard. In the name 10Base-T, the "10" refers to 10 Mbps transmission speed, the "Base" refers to Baseband, which means that no frequency multiplexing is applied, and the "-T" refers Twisted Pair conductors in the cable.
CSMA/CD	Carrier Sense Multiple Access with Collision Detection	All nodes on the same network are free to initiate message transmission. If two nodes transmit simultaneously, the Collision is detected, both nodes abort transmission and attempt to re- transmit after a pause.
Data Link Layer	Layer 2 of the OSI Model that is media-independent, and functions above Layer 1 (Physical Layer).	Defines protocols for data packets and how they are transmitted between networking devices. Includes two sublayers: Medium Access Control (MAC), and Logical-Link Control (LLC).
Default Gateway	A PC that controls traffic between subnets	
Ethernet	LAN protocol defined by IEEE 802.3 networking standard (physical and data link layers). Uses CSMA/CD access method at a variety of speeds and using several different media	10 or 100 Mbps, Baseband network that uses various media (twisted pair, thick coax, thin coax, or fiber optic cable). Example: 10Base-T is 10 Mbps Twisted Pair.
Ethernet/Modbus Bridge	A hardware device that serves as an interface between serial Modbus RTU devices and host applications using Modbus/TCP protocol	Most bridges support sub-addressing for multiple devices connected to its serial RS-485 port
FTP	File Transfer Protocol	Use to send and receive files between a PC acting as an FTP client and a PC acting as an FTP Server.
Hub	A hardware device with multiple ports enabling one device to be connected to several others	A hub forwards all messages on one of its ports to all of its other ports with no isolation between devices.
IEEE 802.3	The basis for the Ethernet standard. It defines the physical and data link communication layers, uses the CSMA/CD access method at a variety of speeds with a variety of media such as unshielded twisted pair.	
Internet	A system of networks (local, regional, national, and international) linked by the TCP/IP protocol suite that function as single, cooperative, virtual network.	

Name/Acronym	Name/Definition	Comments
IP Address	Internet Protocol Address	A 32 bit numeric address written as 4 "octets" (eight bits, translating to integers from 0 to 255) separated by periods, e.g., 164.142.145.065. It is a software address. Within an isolated network you can assign the addresses at random as long as each is unique, but connecting a private network to the Internet requires registered IP addresses to avoid duplication.
LAN	Local Area Network	Networked devices, logically isolated from other networks and devices.
MAC Address	MAC coded ID	A Data Link layer address also known as hardware address, physical address. Unique code is "burned-in" into the product by its manufacturer. A set (6) 2-digit hexadecimal numbers.
Modbus/TCP or Modbus TCP/IP	Variant of Modbus protocol	Modbus/TCP is a derivative of related Modbus RTU protocol used with RS232/RS-485 data acquisition and supervisory structures. Basically, Modbus/TCP encapsulates Modbus RTU frames in TCP frames for transport over an Ethernet network.
Node	An intelligent device on a network that has a hardware address such as a PC, printer, a controller or recorder	
OSI 7-Layer Model	Open Systems Interconnection Reference Model	The OSI model is established by International Standards Organization (ISO) to enable computer communications using disparate media and protocols. Includes seven "Layers" refer to OSI Reference Model" for more information.
Packet	A bit sequence that is transmitted as an entity on a network.	The content of a packet varies with the protocols that are applied. It includes the data message itself and various routing and control information such as source and destination addresses. In many cases, a packet includes a set of frames for one protocol embedded (or encapsulated) in a set of frames for another protocol. (Several levels of encapsulation could be incorporated in a packet.)
Protocol	A system of rules for communicating over a network.	
Segment	A section of a network connecting 2 or more computers separated by switches, hubs or routers	Recorders, controllers, and PC's may be in a segment
Subnet	A portion of the network that shares a common address component	

Name/Acronym	Name/Definition	Comments
Subnet Mask	Acts as a filter when identifying IP addresses on a subnet. It is simply a screen that indicates which numbers to access. 255.255.255.0 is an example default.	A single IP network can be divided into many subnets by using some of the most significant bits of the host address portion of an IP address as a subnet.
Switch	A multi-port Ethernet device that switches traffic between two or more network segments on an address- selective basis. Also called switching hubs.	An Ethernet switch looks like a hub, but unlike a hub automatically determines and remembers where an Ethernet device is located and routes messages only through the appropriate port. This minimizes network loading and enables true deterministic communications over Ethernet by eliminating "collisions".
TCP/IP	Transport Control Protocol/Internet Protocol	Transmission Control Protocol (TCP): - Operates at the Transport Layer of the OSI Model manages connections between computers. Internet Protocol (IP): - operates at the Network Layer (one step below TCP) - defines how data is addressed (source/destination)