National Aeronautics and Space Administration



Human Mars Architecture

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Space Policy Directive-1



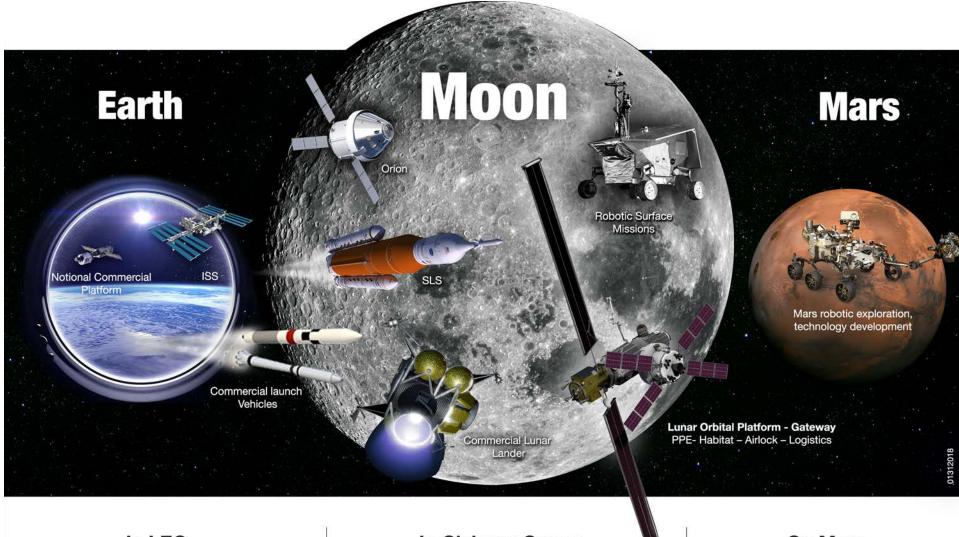


"Lead an innovative and sustainable program of exploration with commercial and international partners to enable human expansion across the solar system and to bring back to Earth new knowledge and opportunities.

Beginning with missions beyond low-Earth orbit, the United States will lead the return of humans to the Moon for long-term exploration and utilization, followed by human missions to Mars and other destinations."

EXPLORATION CAMPAIGN





In LEO Commercial & International partnerships In Cislunar Space A return to the moon for long-term exploration On Mars Research to inform future crewed missions Robotic arm

Lunar Orbital Platform-Gateway

EVA/science airlock elements, logistic element, more docking

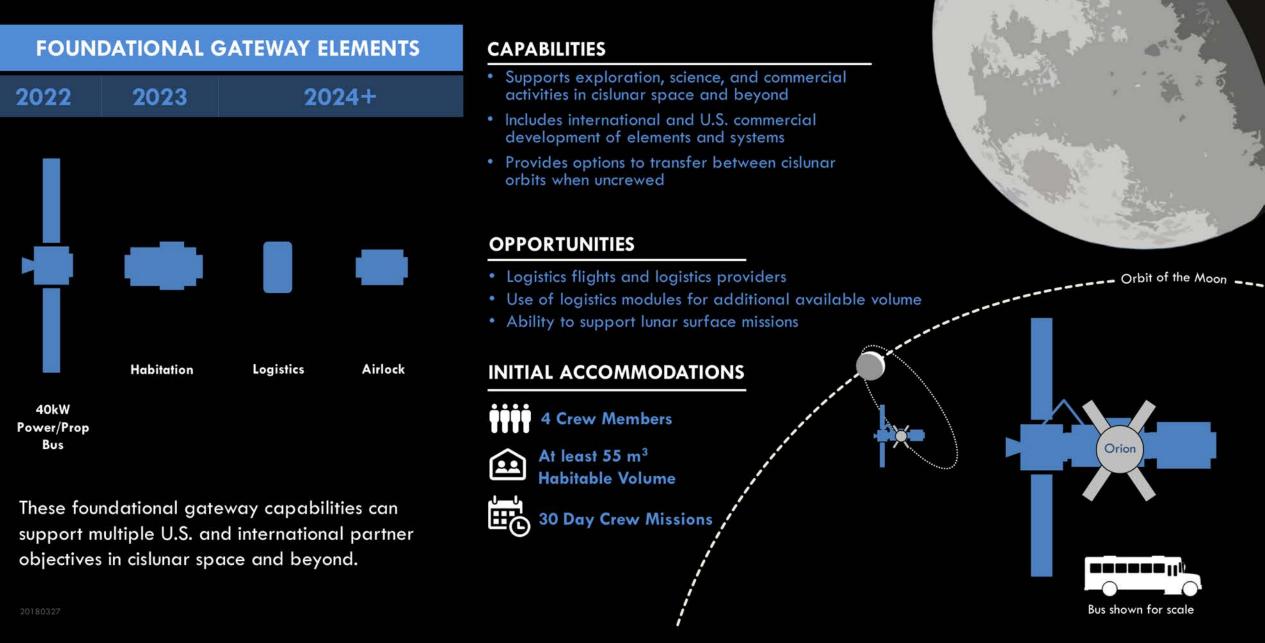
Habitation element, docking

Power Propulsion Element (PPE)

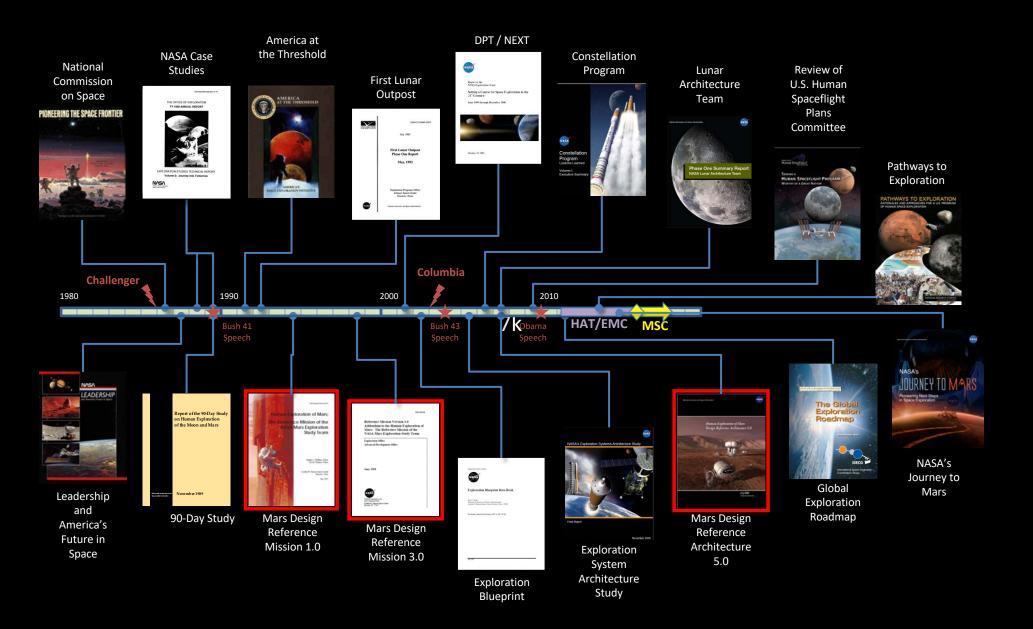
Orion

LUNAR ORBITAL PLATFORM-GATEWAY DEVELOPMENT

Establishing leadership in deep space and preparing for exploration into the solar system



A Brief History of Human Exploration Beyond LEO



NASA

- A myriad of choices define the "Architecture" of a human Mars mission
- A large menu of human Mars architecture choices can be organized into three distinct segments
 - End State: Describing long-term architecture goals and objectives
 - Transportation: Getting crew and cargo to Mars and back
 - Surface: Working effectively on the surface of Mars
- Human exploration of Mars may represent one of the most complex systems-ofsystems engineering challenges that humans will undertake
 - Multiple systems must work seamlessly together
- Work will continue to define the optimal human Mars architecture, and the following is ONE possible solution.



Design Choices



Mission Architecture / End State								Transportation Earth-to-Orbit								The	cu	rre	nt b <u>i</u>	g pic	ture <u>c</u>	design	
Primary Program Focus		Ticis-Earth Infrastructure								ransportation Deep Space						choices offers up 5.3 x 10 ³⁷							
Flags & Footprint Lewis & Clark	Initial Orbit	Long Sta	-Term Sp	orting		In-S	Space Earth Retu	ırn Cis-Lur	nar M	ars Orbit Ch Transporta	· ·	Space In-S	Space No. of					pos	sik	ole co	mbi	natio	ns
Research Base / Antarctic Field Analog	DRO	Cis-Lu				1			Deep S	pace					E	arth Retu	urn						
Primary Activity Science & Resear	Near Rectilinear Halo Orbit		Destination	M	lars Parking		Drbit Mars Orbit	Mars Orbit	Mars	Ascent Vehic	e Ascent Vehi	le MAV	Earth Ear Surface		re- Desc	ent to Eart	h Entry						
Primary Activity Resource Utilizati Primary Activity	(NRHO) LEO		Mars Orbit		Radiation	Coun	1	Design	First Surfa	ce Crew Surfa	ce No. of Crev	Lander	Landed Mas	s Lander Ent	rv La	nding	. <u>.</u>	Landin	g		7		
Human Expansio	HEO		· Phobos										Surface										
	-		Mars' Surface	e 5C	Passive Active	Zero-	ISRU	Power	Habitat Type	Life Plane Support Out		Length of		Laboratory Sciences	ECLSS	Trash	Robotics	Landing Zone Surveys	Cargo Handling	Surface g Communication			
			Combinatior	n Are		Artifi	Neze	Solar	Monolith	ic Open for I Expec	ach < 10 km	n 7 sols	Teleoperation of Instrument / Networks	f None	Open	Containers	Low Latency Telerobotics		Crane/ Hoist	Line of Sight			
			Areosynchronc Mars Flyby Backflip	bus			Demonstration Only	Nuclear	Modular	Closed Sin		cm 14 sols	Recon Geology / Geophysiology		50 - 75% Closed	Recycle	Autonomous	Robotic	Ramp	Relay Satellite			
			Grand Tour Fast				Atmospheric Oxygen	RTG	Inflatable	e Mul Outr		n 30 sols	Field Work	Moderate Geochemical + Life Science		Combinatio	n Crew Partnered		ATHLETE				
							Water from Regolith	Combinatio	n Rigid			90 sols	Drilling / Geophysical Test	Full-Scale Life s Science	e > 90% Closed				Other				
							Water from from Subsurface Ice		Local Features and Resource			300 - 500 sols											
							Fabrication / Manufacturing					500 - 1000 sols											
							Combination					> 1000 sols overlapping crews	'1										
							Export																



Mission Architecture / End State										
Primary Program Focus	Mission Class	Level of Human Activity	Earth Based Mission Support	Cost Emphasis	Reusability					
Flags & Footprints / Lewis & Clark	Opposition Class - Short Stay (1-60 sols)	Robotic / Telerobotic	Continual Control	Low Cost / Gradual Build-Up	None					
Research Base / Antarctic Field Analog	Conjunction Class - Long Stay (300+ sols)	Expeditions	Moderate Intervention	High Cost / Gradual Build-Ui	In-Space Habitation					
Primary Activity: Science & Research	All-Up vs. Split Mission	Human-Tended	No Daily Intervention	Low Cost / Fast Build-Up	In-Space Transportation					
Primary Activity: Resource Utilization		Continuous Presence	Minimal	High Cost / Fast Build-Up	EDL and Ascent					
Primary Activity: Human Expansion		Human Settlements			Surface Systems					
		Human Colonization			Infrastructure for Permanent Habitation					

- A single surface site lends itself to a "field station" approach for development of a centralized habitation zone / landing site. The first mission to this site would deploy habitation, power, and other infrastructure that would be used by at least two subsequent surface missions.
- Reusable surface elements (first 3 landed missions)
 - Provides some infrastructure for missions to follow
- Reusable in-space transportation and habitation (at least 3 missions)
 - Based in cis-lunar space
- Cost can be spread via gradual buildup of transportation/orbital capability → short surface stay → long surface stay

SUMMARY – NASA Example Mission

• End State: First 3 human Mars mission visit a common "Field Station"

- Single landing site for first 3 (min) surface missions
- Long-distance (100 km-class) surface mobility
- Major decisions that "frame" this example architecture
 - Reusable in-space transportation and habitation*
 - Split mission architecture (predeploy)
 - Conjunction-class, long-stay, minimum energy
 - Hybrid in-space propulsion
 - Use of ISRU from the very first landed mission

• Priority elements and technological capabilities:

- Reusable, refuelable in-space propulsion (SEP and chemical)
- Long-lifetime, high reliability in-space habitation
- 20-25 mt payload to Mars surface delivery (E/D/L)
- Surface nuclear power
- Atmospheric ISRU, evolving to atmosphere + water
- Affordability and sustainability: TBD

• Target milestones: First human orbital mission 2033, first human landed mission 2037





Beyond Cis-lunar Space

First Human Mission to Mars Sphere of Influence

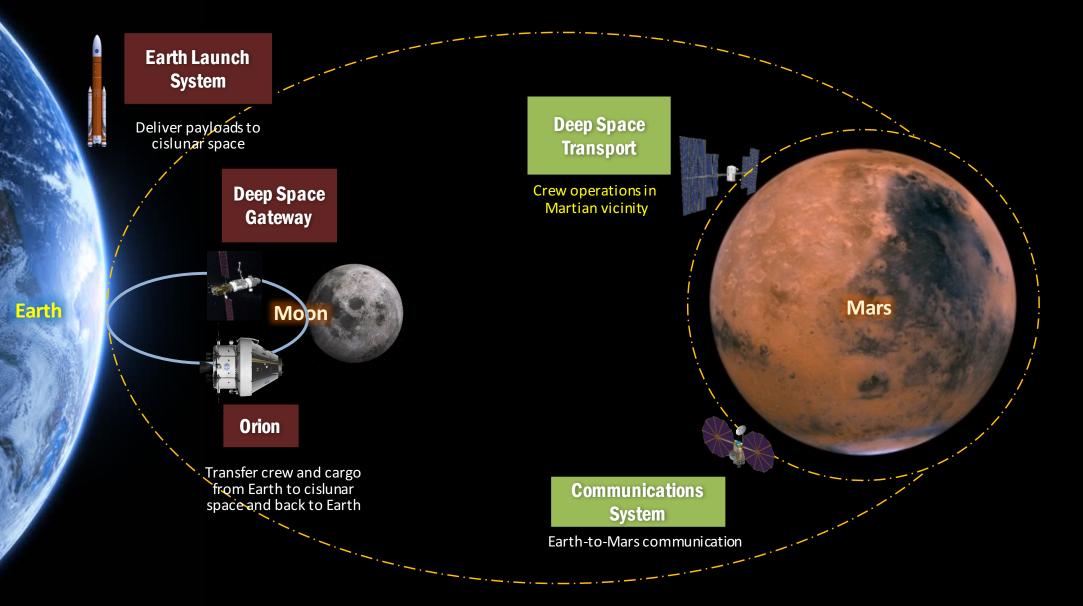
Deep Space Transport (DST)

- Emphasis on first human mission to Mars' sphere of influence
 - First long duration flight with self sustained systems
 - Autonomous mission with extended communication delay
 - First crewed mission involving limited abort opportunities
- Example Assumptions

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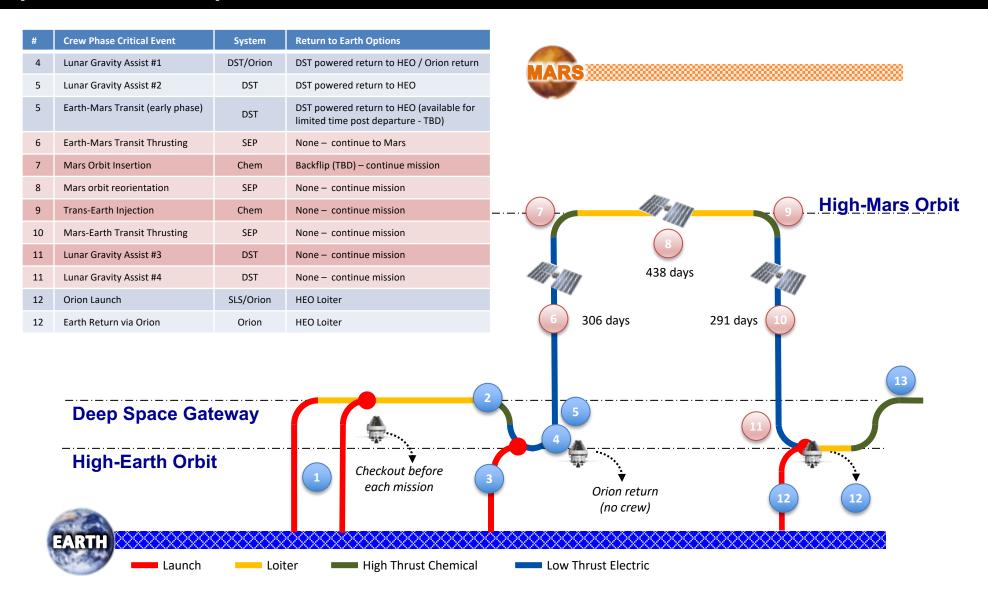
- 8.4 m Cargo Fairing for SLS launches
- Crew of 4 for Mars class (1000+ day) mission independent of Earth
- Orion used for crew delivery and return to/from cislunar space
- Re-usable DST/Habitat and Propulsion Stage
 - Hybrid (SEP/Chemical) In-Space Propulsion System
 - Gateway used for aggregation and re-fueling of DST

Mars Orbital Mission Elements and Systems



Mars Orbital Mission Example Operational Concept





Mars Surface Mission

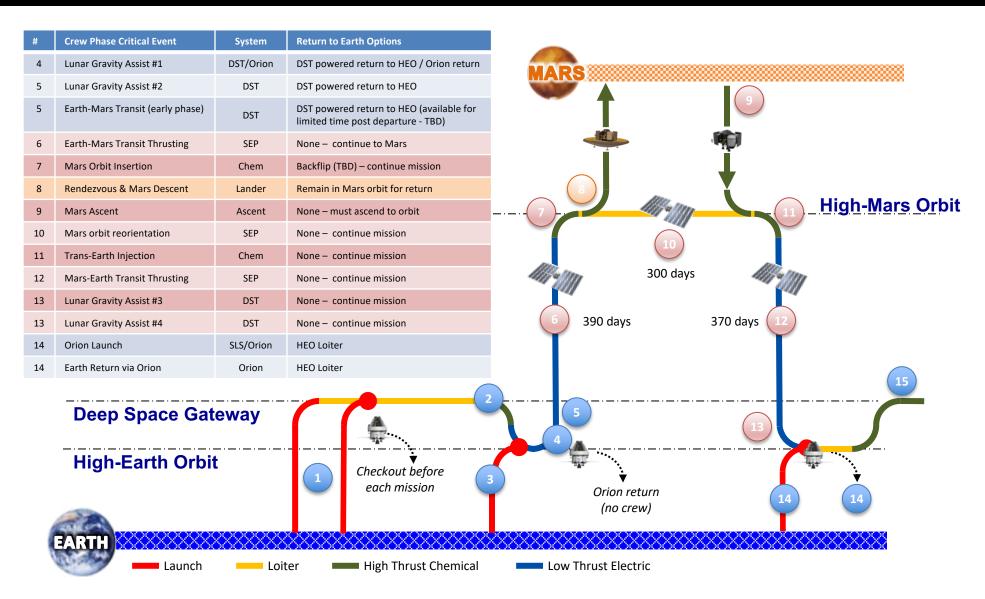
Mars Surface Mission



- Emphasis on establishing Mars surface field station
 - First human landing on Mars' surface
 - First three missions revisit a common landing site
- Example Assumptions
 - Re-use of Deep Space Transport for crew transit to Mars
 - 4 additional, reusable Hybrid SEP In-Space Propulsion stages support Mars cargo delivery
 - 10 m cargo fairing for SLS Launches
 - Missions to Mars' surface include the following:
 - Common EDL hardware with precision landing
 - Modular habitation strategy
 - ISRU used for propellant (oxidizer) production
 - Fission Surface Power
 - 100 km-class Mobility (Exploration Zone)

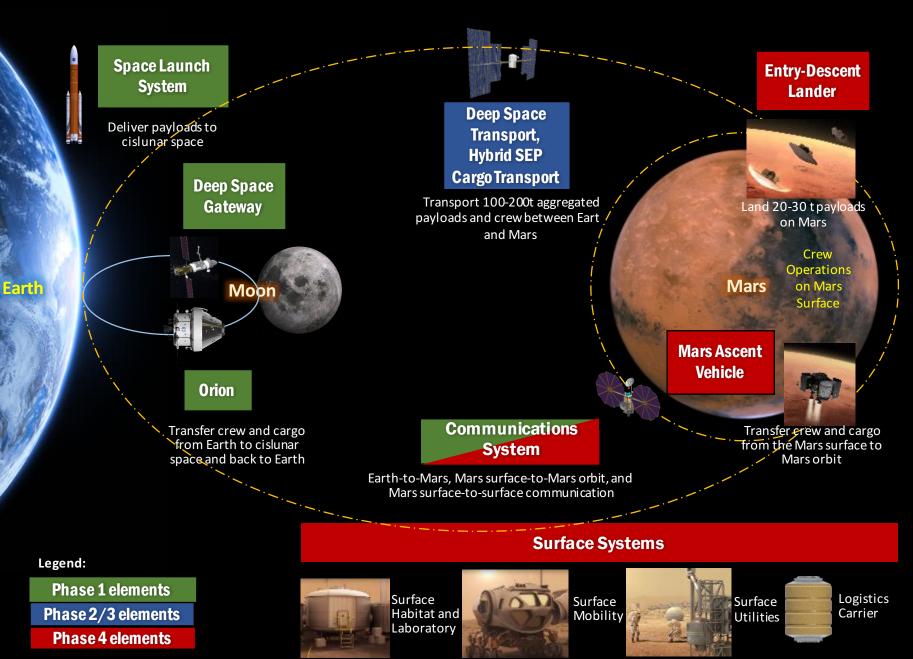
Mars Surface Mission Example Operational Concept

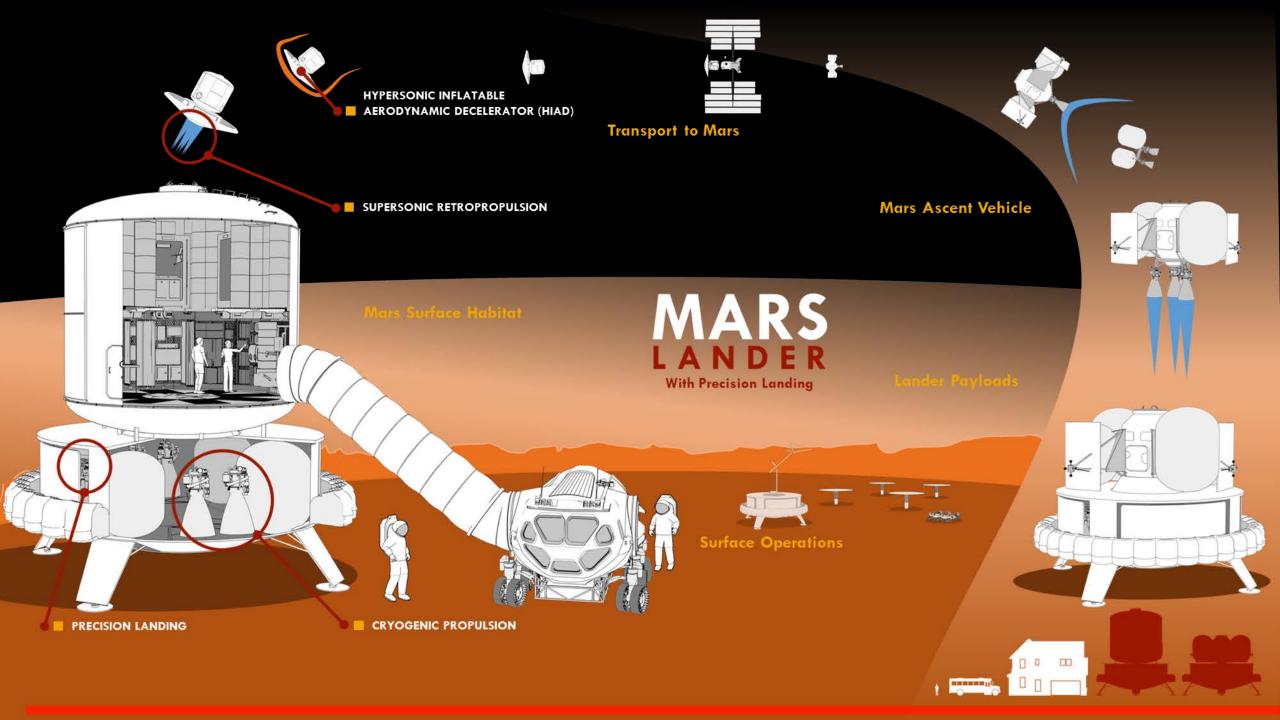




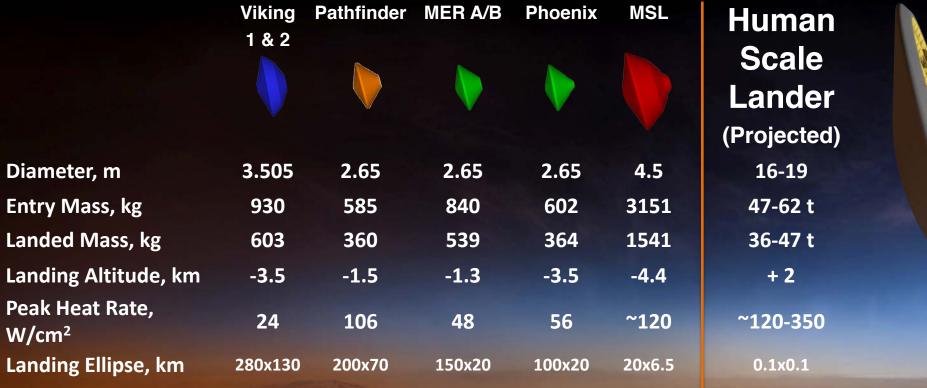
Mars Surface Mission Key Elements and Systems







Human Landers: A Leap in Scale



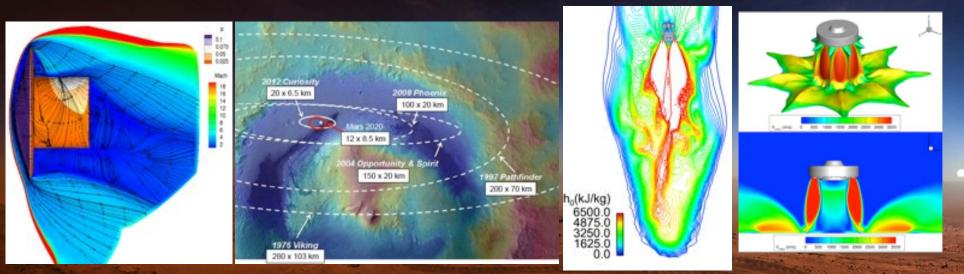
Steady progression of "in family" EDL



New Approach Needed for Human Class Landers

Human Mars Lander Challenges

- 20x more payload to the surface
- 200x improvement in precision landing
- Dynamic atmosphere; poorly characterized
- New engines; performing Supersonic RetroPropulsion
- Terrain hazard detection improving, but not perfect
- Surface plume interaction debris ejecta could damage vehicles



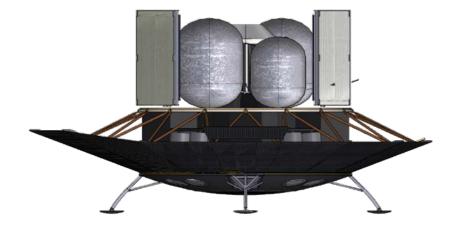
Concept Quad Chart



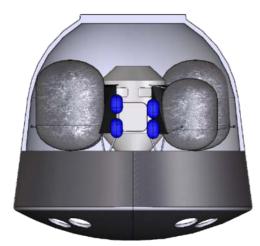
HIAD: Hypersonic Inflatable Aerodynamic Decelerator



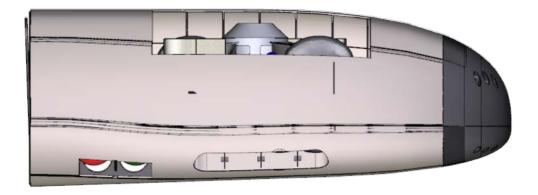
ADEPT: Adaptable Deployable Entry & Placement Technology



Capsule

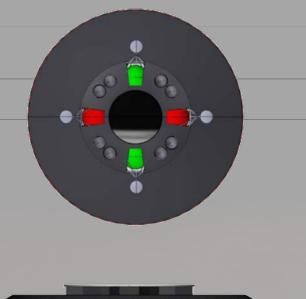


Mid L/D

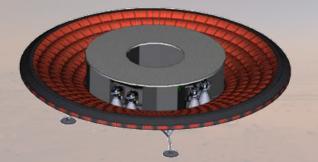


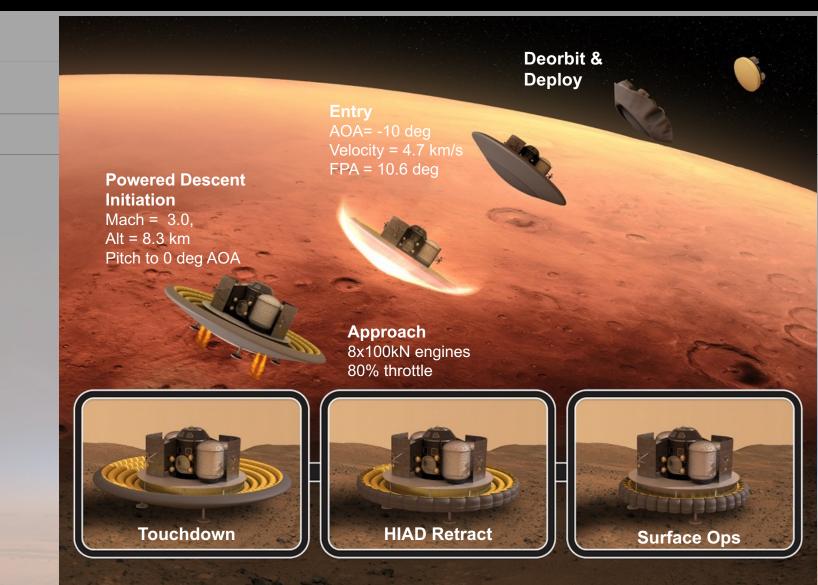
HIAD EDL Sequence











NASA LUNAR EXPLORATION

ARTEMIS

(2010)

LRO (2009) ORION SPACECRAFT 2019

2018

SMALL COMMERCIAL LANDERS 2019 ONWARD POWER & PROPULSION ELEMENT 2022

ORION CREWED

MID-SIZE ROBOTIC LANDERS 2022

2022

GATEWAY IN LUNAR ORBIT 2024

ADVANCED EXPLORATION LANDER 2026

2026

