

A proposal for Standards Adoption: An architecture for distributed systems of medical devices in high acuity environments

Joint meeting of IEEE EMBS 11073 & HL7 Health Care Devices (DEV) WG,
2014/01/21, Stefan Schlichting, Stephan Poehlsen, Stan Wiley

A Proposal For Standards Adoption

Agenda

1. **Introduction**
2. Clinical Workplace SOMDA
3. MDPWS
4. BICEPS
5. Results
6. DDS
7. Discussion
8. Formal Request to IEEE 11073 Committee

We seek this proposal for
an architecture of distributed medical devices
to

**be adopted by the IEEE 11073 Standards Committee for inclusion
into IEEE 11073-20401.**

Background

Work was initiated as a research project in 2004, and has culminated into an open framework which is supported by several German consortia consisting of medical device manufacturers, research institutes, and clinical partners.

Introduction

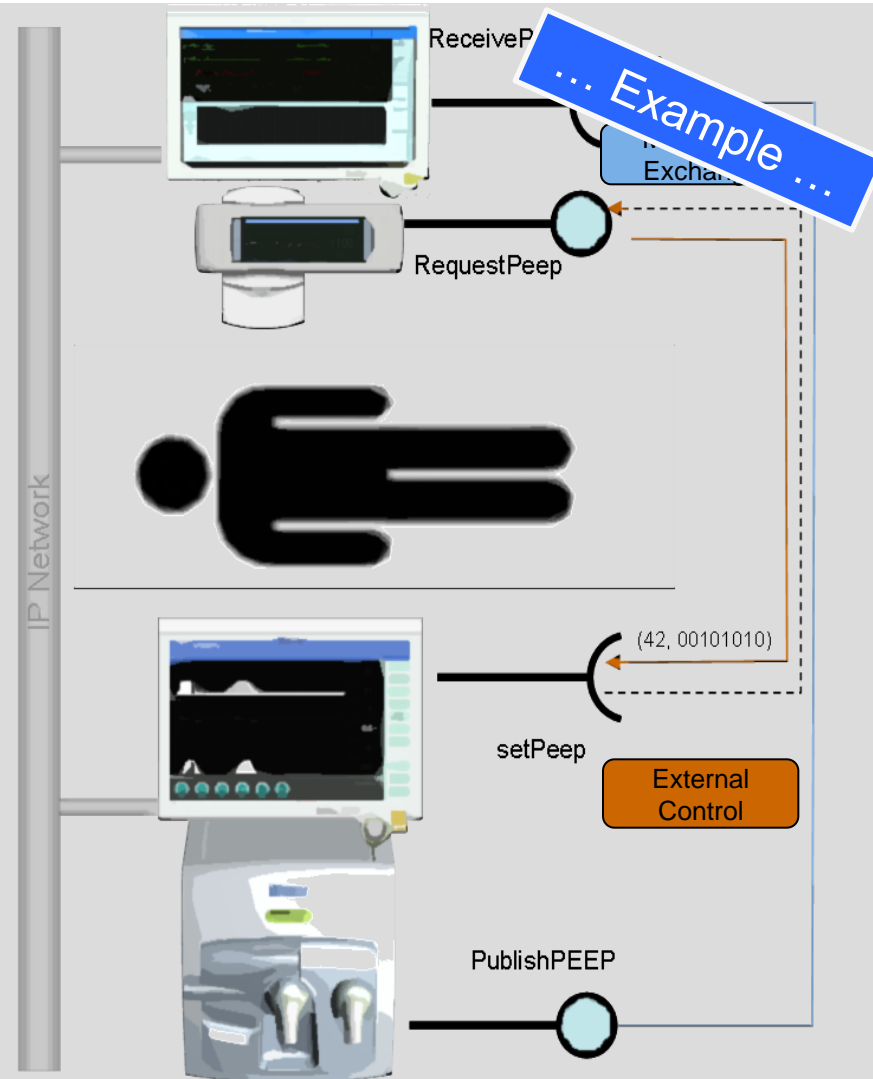
Scope of research project

Medical Device Interoperability in high acuity clinical workplace environments ,

that is

- ... reliable cross-device data exchange between medical devices
- ... external control with focus on patient safety

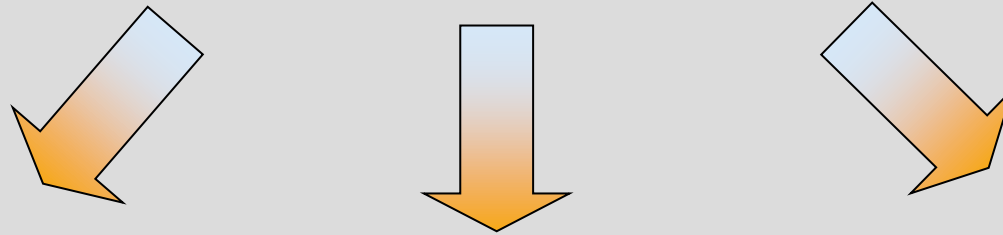
without tight system integration, yielding a flexible technical infrastructure for smart clinical applications.



Introduction

Examples for High Acuity Environments

High Acuity Environments



Intensive Care



Anesthesia



Surgery

Introduction

Medical device interoperability requirements in an ICE

Functional

Plug'n Play

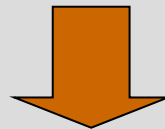
- Discovery and Binding
- Device capability description at runtime
- Extensibility & Openness

Communication (1-1, 1-n, n-n)

- Event Notification
- Data reporting
- External control

Non-Functional

- Risk Management
- Safe communication
- Access control
- Trust establishment between participants
- Privacy of patient-related data
- Latency in milliseconds range



Core Concept

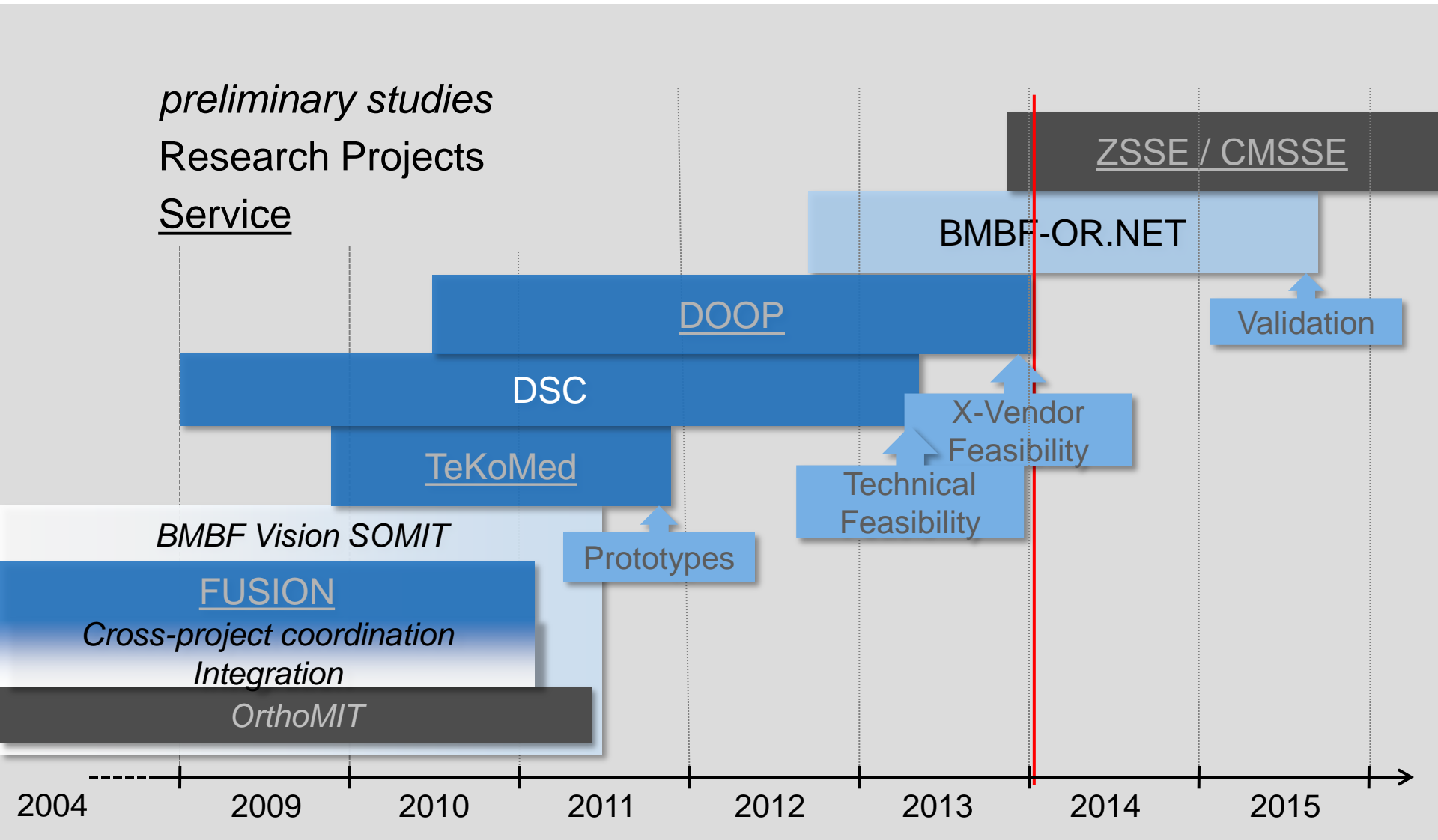
Develop an interoperability architecture & protocol stack

- based on **standardized technologies for syntactic interoperability**
- and proprietary or **standardized protocols** for semantic interoperability.

e.g. Standardized payload based on hRTM

Introduction

Project History



Introduction OR.NET



CURRENT ISSUES ▾ APPOINTMENTS ▾ PROJECT ▾ SUB-PROJECTS ▾ PARTNER AREA ▾

PROJECT > PARTNERS

Board

Within the project OR.NET, providers of integrated operating rooms work together with manufacturers of medical devices such as medical equipment and medical components, as well as (IT) service providers and software vendors. They are supported by numerous research institutes and clinics. Not only clinics and clinics IT departments, but also equipment operators are involved in the project. In order to make the project results internationally known, the OR.NET project is actively involved in standardization processes. This is also supported by the appropriate committees and regulatory bodies. Following partners run the project OR.NET forward and in the mean time they are receiving the support of the associate partners:

Provider of integrated operating rooms:

- Karl Storz GmbH & Co. KG
- Richard Wolf GmbH

Manufacturers of medical devices and medical equipment components:

- SurgiTAIX AG
- Inomed Medizintechnik GmbH, Research and Development
- Localite GmbH
- KLS Martin Group
- Möller-Wedel GmbH ImageNET (R&D)
- Ziehm Imaging GmbH
- Söring GmbH

(IT) service provider:

- UTK – UniTransferKlinik GmbH
- Synagon GmbH
- MedPlan Engineering GmbH
- MT2IT GmbH & Co. KG

Software and IT solutions for networking:

- MEDNOVO Medical Software Solutions GmbH
- how to organize
- Conworx Technology GmbH
- VISUS Technology Transfer GmbH/ R & D

Research institutes:

- Fraunhofer-Institut MEVIS
- Fraunhofer-Institut FOKUS
- Technische Universität München, Lehrstuhl für Mikroelektronik und Medizingerätetechnik
- ITM – Institut für Telematik, Universität zu Lübeck
- ISP -Institut für Softwaretechnik und Programmiersprachen, Universität zu Lübeck
- ICCAS – Innovation Center Computer Assisted Surgery, Universität Leipzig
- MediT – Lehrstuhl für Medizinische Informationstechnik, RWTH Aachen
- mediTEC – Lehrstuhl für Medizintechnik, RWTH Aachen
- OFFIS – Institut für Informatik e.V. / FuE-Bereich Gesundheit
- Institut für Angewandte Mikroelektronik und Datentechnik, Universität Rostock
- Institut für Medizinische Informatik, Universität zu Lübeck
- Universitätsklinikum RWTH Aachen, Integrierte Teleanästhesiologie
- Technische Universität München, Lehrstuhl für Automatisierung und Informationssysteme
- Technische Universität München, Institut für Informatik, Robotics and Embedded Systems
- Technische Universität München, MITI, Minimal-invasive Interdisziplinäre Therapeutische Intervention
- Universität Augsburg, FMPR, Forschungsstelle für Medizinproduktrecht

Specialist Clinics:

- Uniklinik Tübingen, Universitätsklinik für Urologie
- Uniklinik Tübingen, Universitätsklinik für Radiologie
- Uniklinik Tübingen, Universitäts-Frauenklinik
- Klinikum Rostock Anästhesie, Klinik für Anästhesiologie und Intensivmedizin
- Uniklinik Schleswig-Holstein, Klinik für Chirurgie
- Uniklinik Leipzig, Klinik für Herzchirurgie
- Uniklinik der RWTH Aachen, Klinik für Anästhesiologie
- Uniklinik der RWTH Aachen, Orthopädische Klinik
- Uniklinik der RWTH Aachen, Neurochirurgie
- Uniklinikum Heidelberg, Fachkliniken für Chirurgie, Urologie und Orthopädie

Clinic-IT departments and operators:

- Uniklinikum Heidelberg, Zentrum für Informations- und Medizintechnik
- Rhön-Kliniken AG
- Uniklinik Schleswig-Holstein, IT-Planung und -Strategie

<http://www.ornet.org/>

A Proposal For Standards Adoption

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- 2. Clinical Workplace SOMDA**
3. MDPWS
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Clinical Workplace SOMDA

What is it?

The concept of a

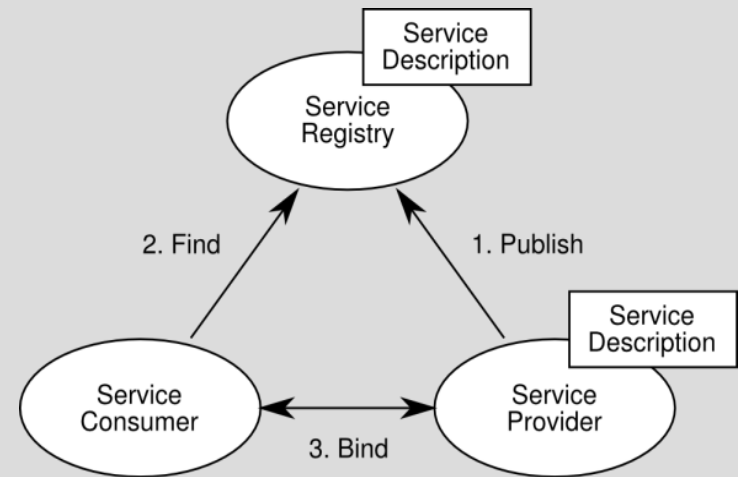
clinical workplace service-oriented medical device architecture

transfers the concept of a

service-oriented architecture

to the domain of

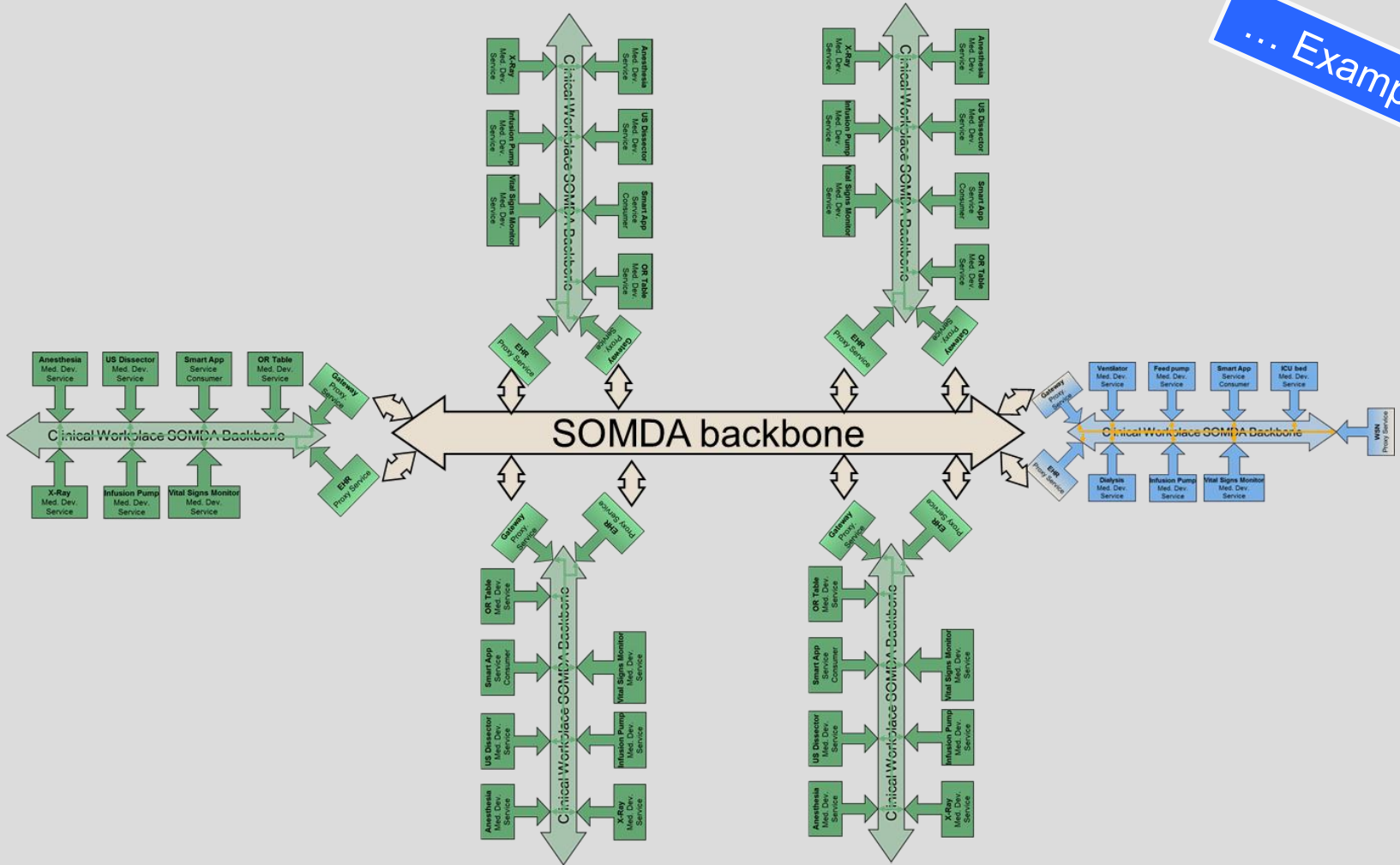
distributed system of medical devices for one clinical workplace.



Clinical Workplace SOMDA

What is it?

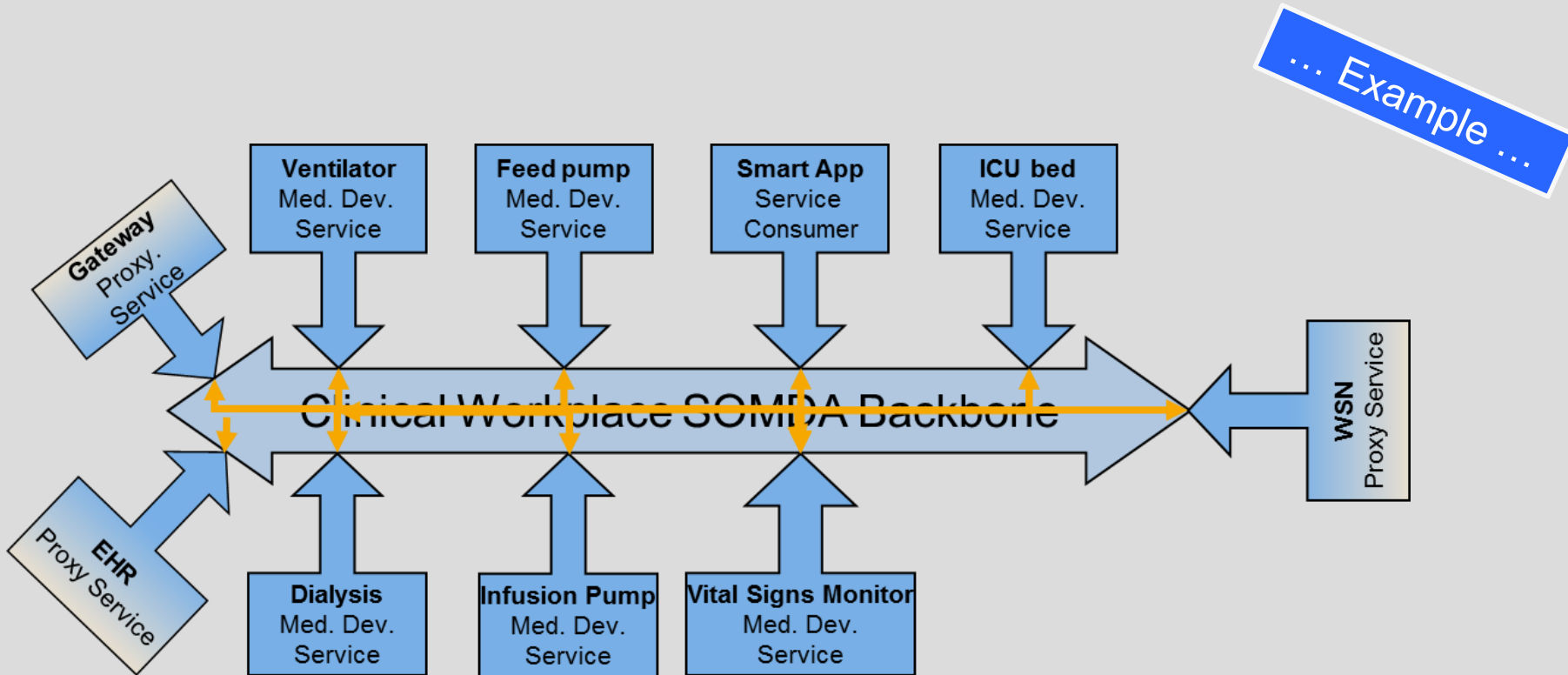
... Example ...



This is a SOMDA: 5 ORs & 1 ICU Bed.

Clinical Workplace SOMDA

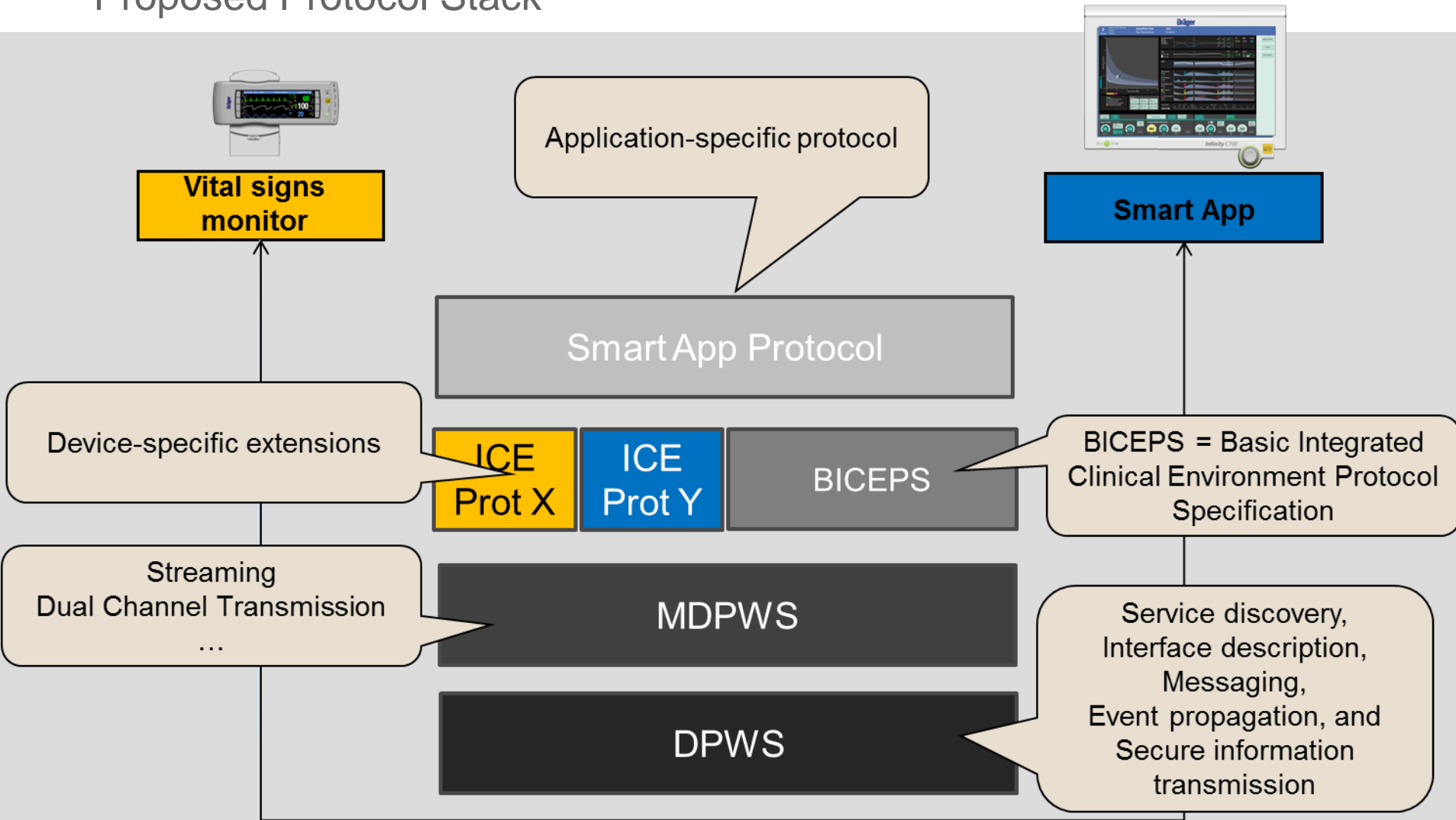
What is it?



Conceptual view of a SOMDA for a clinical workplace

Concept of a clinical workplace SOMDA does not make any assumptions of the underlying network topology.

Clinical Workplace SOMDA Proposed Protocol Stack



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MDPWS

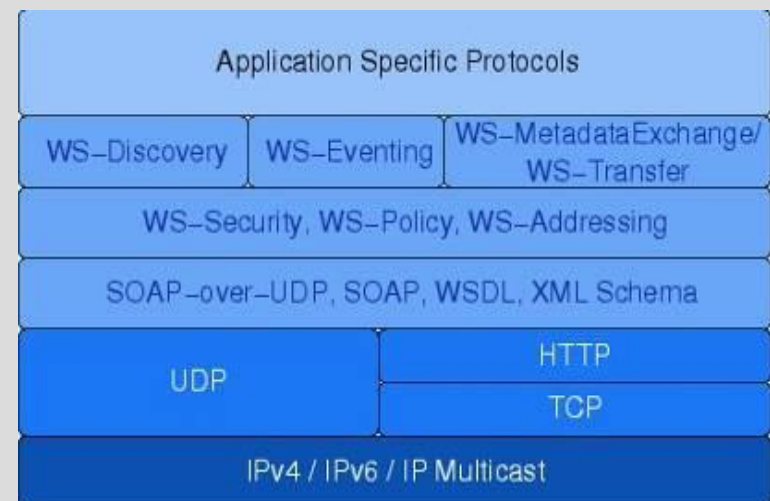
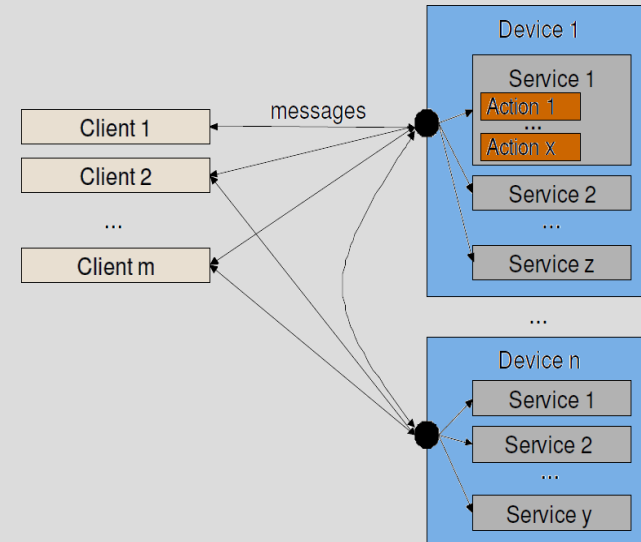
Medical Device Profile for Web Services

- DPWS:2009* is the core of MDPWS

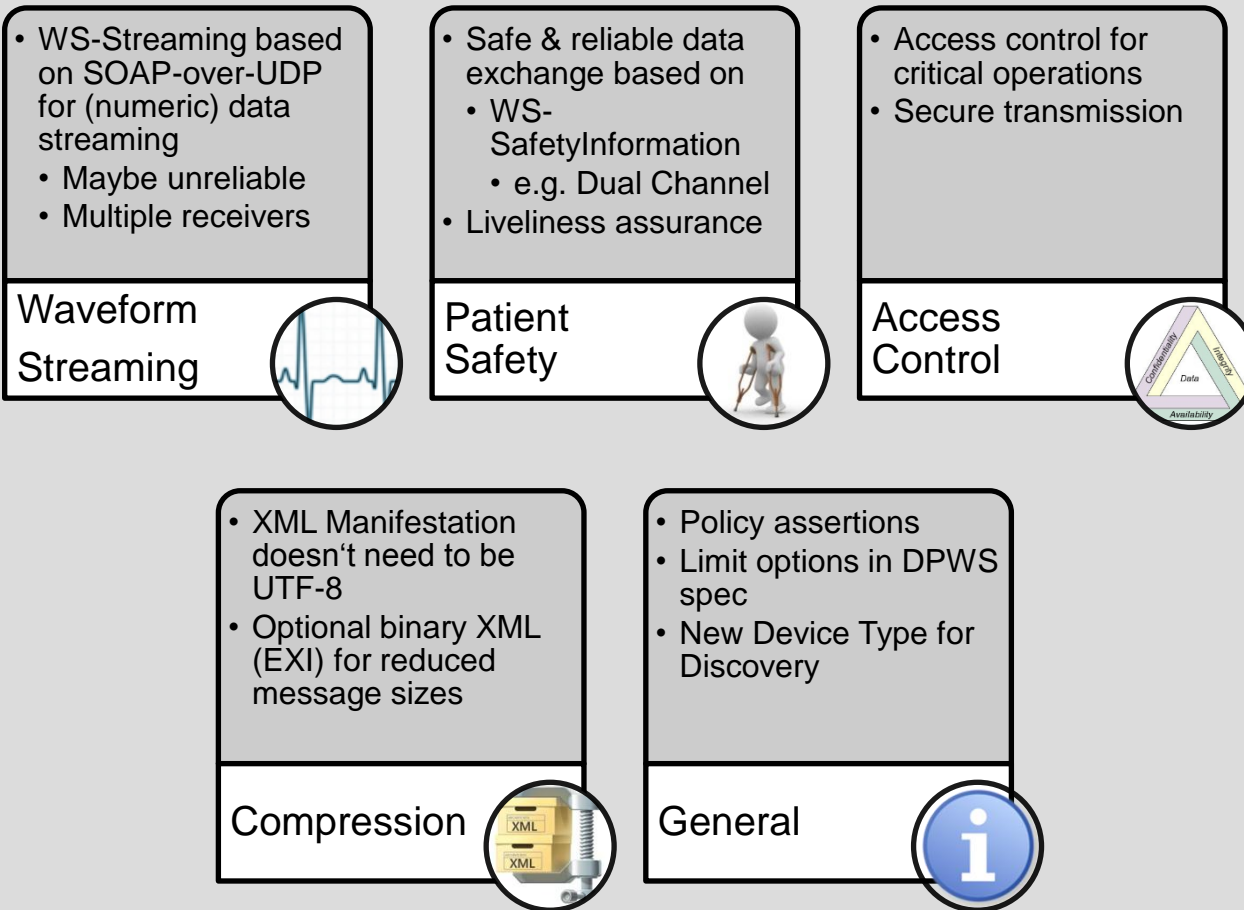
- OASIS standard (since 07/2009)
- Utilizes a subset of the WS-* standard
- Covers
 - Service discovery,
 - Interface description,
 - Messaging,
 - Event propagation, and
 - Secure information transmission
- Designed for resource-constrained devices

- MDPWS

- Added some missing parts e.g. safe transmission of control requests



*See <https://www.oasis-open.org/committees/ws-dd/>



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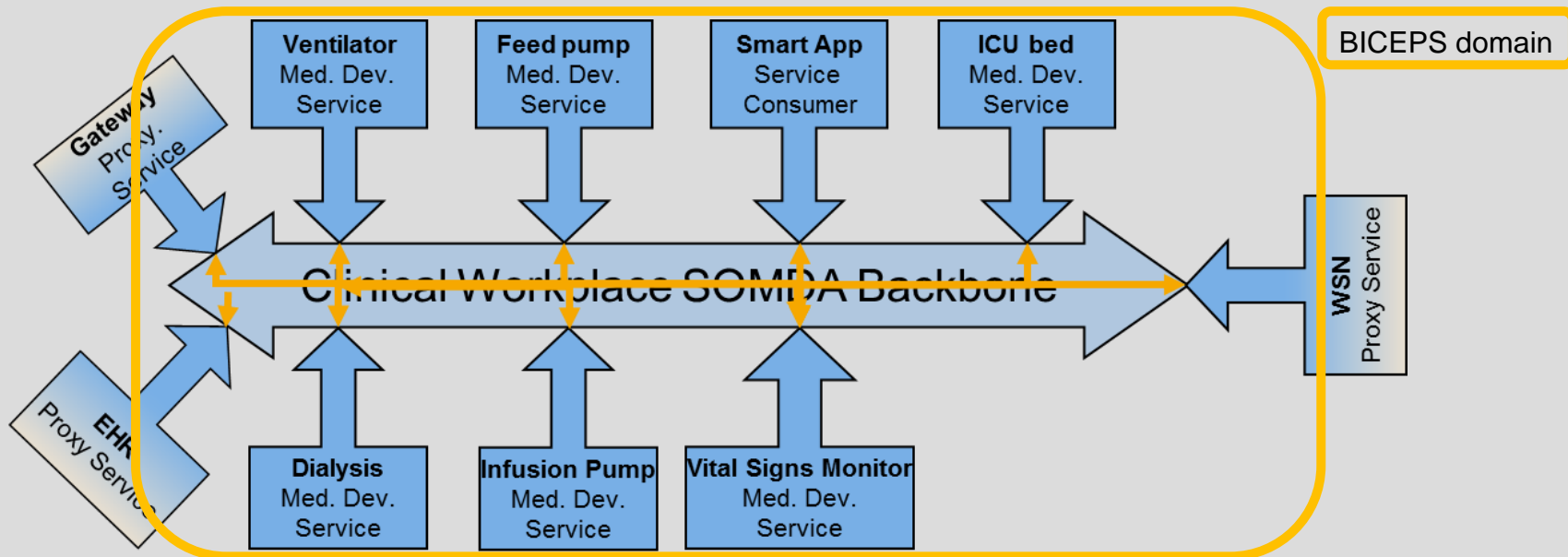
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BICEPS

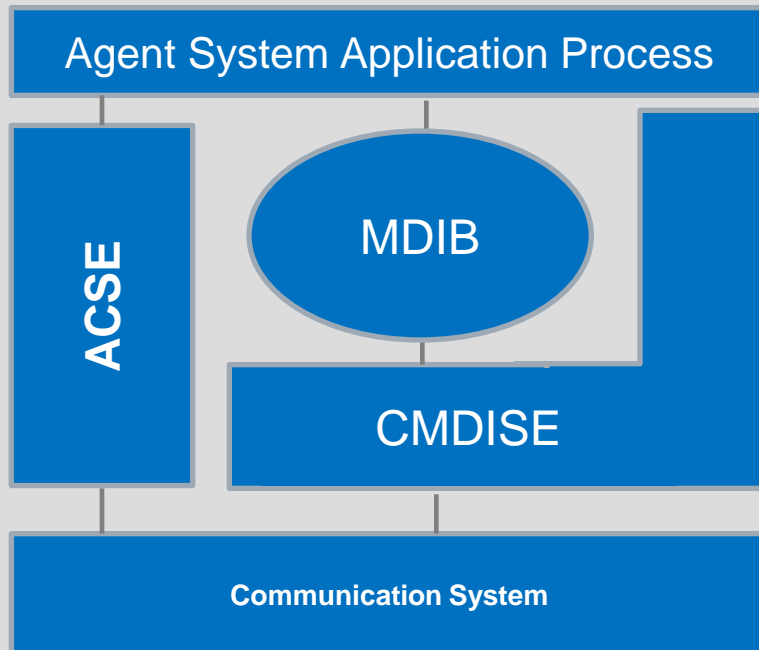
What is BICEPS?

BICEPS is communication protocol specification that has the objective to allow communication between participants in a **distributed system of medical devices** in high acuity environments that directly interact with, monitor, provide treatment to, or are by some other means directly associated with a **single patient**.

- facilitate medical device interoperability in a distributed system of medical devices that follows the **clinical workplace SOMDA architecture paradigm**

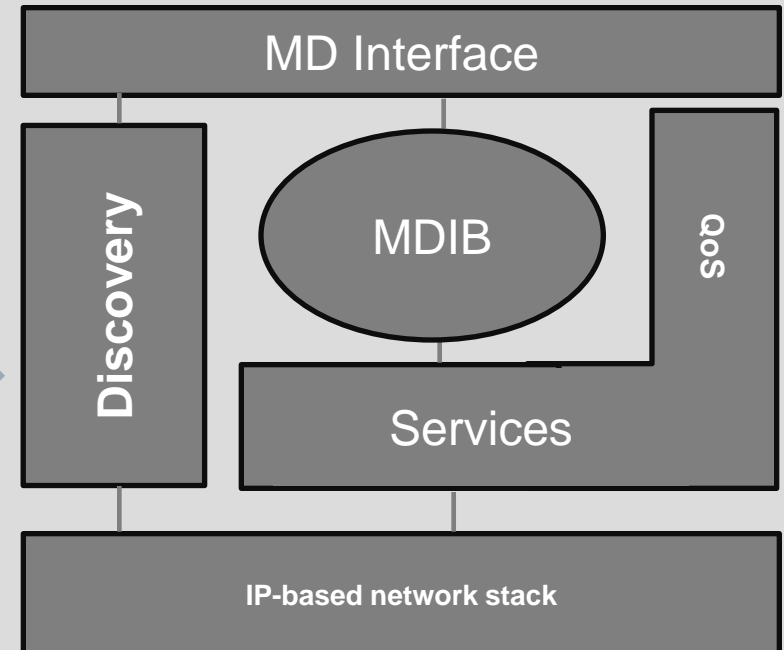


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- ACSE, which provides services to establish logical connections between Agent & Manager
- Managed medical objects are accessible only through services provided by CMDISE

BICEPS



- **BICEPS Discovery**, which provides services to establish logical connections between Device & Client
- Managed medical objects are accessible only through **BICEPS services** hosted by the Device

BICEPS

Parts of the specification

BICEPS Services

- Control access to the managed objects
- Extensible, functional groups of operations
- No transport protocol defined

BICEPS Discovery

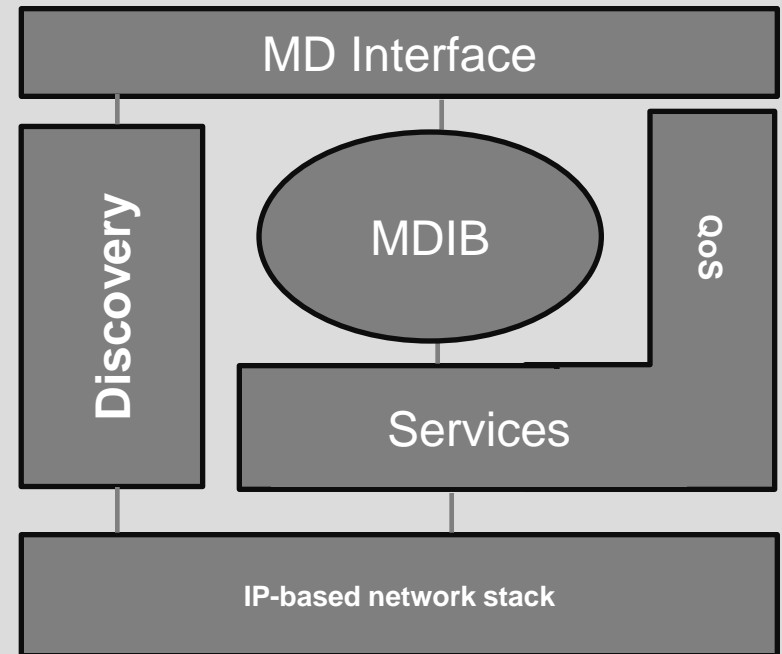
- Fosters Plug & Play by defining requirements for transport protocol
- Implicit & explicit discovery
- No mandatory central service registry
- Utilizes the BICEPS Get Service

BICEPS Message Information Model

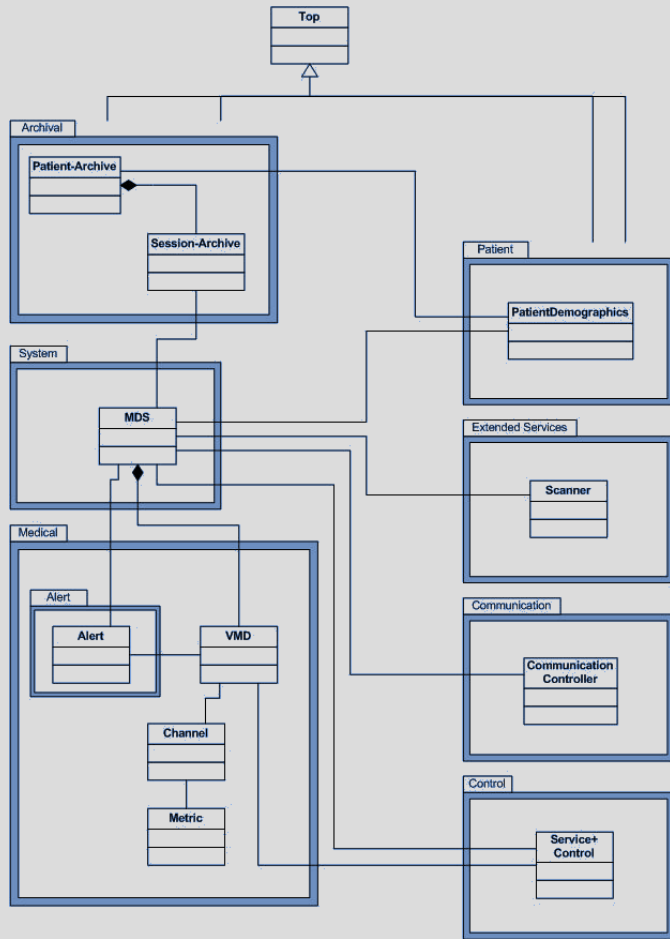
- Message for conveying state data and descriptive meta-information
- Extensibility points
- No transport protocol defined

BICEPS QoS

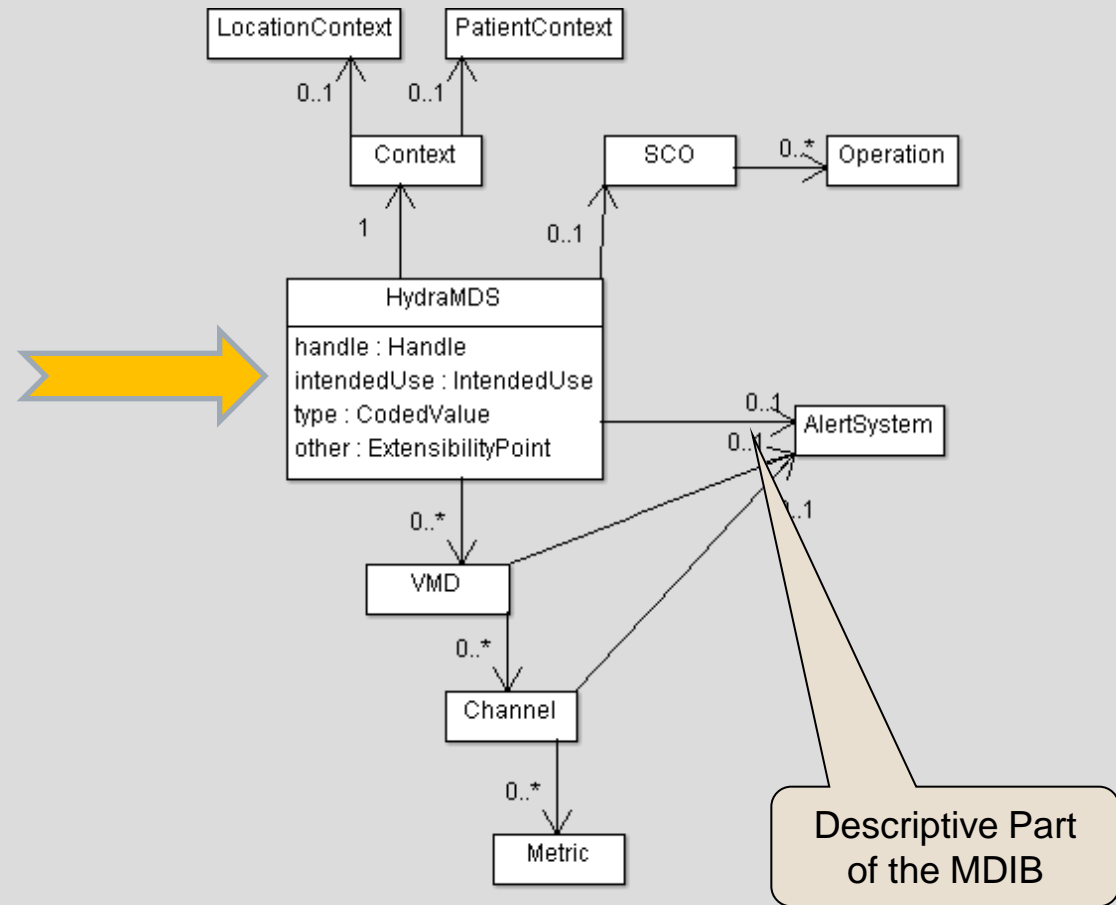
- No QoS on its own, as QoS may be transport protocol specific
- Extensibility points for transport



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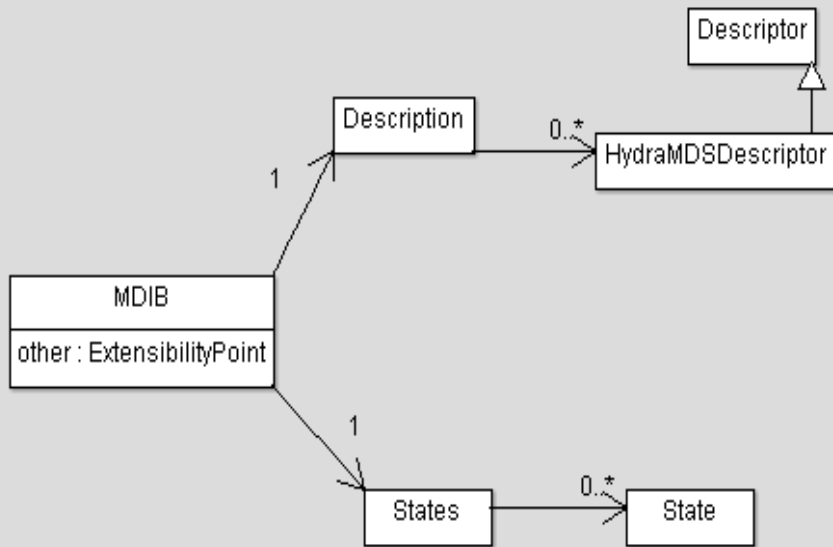


BICEPS Domain Model



BICEPS

Message Information Model



Descriptive Part

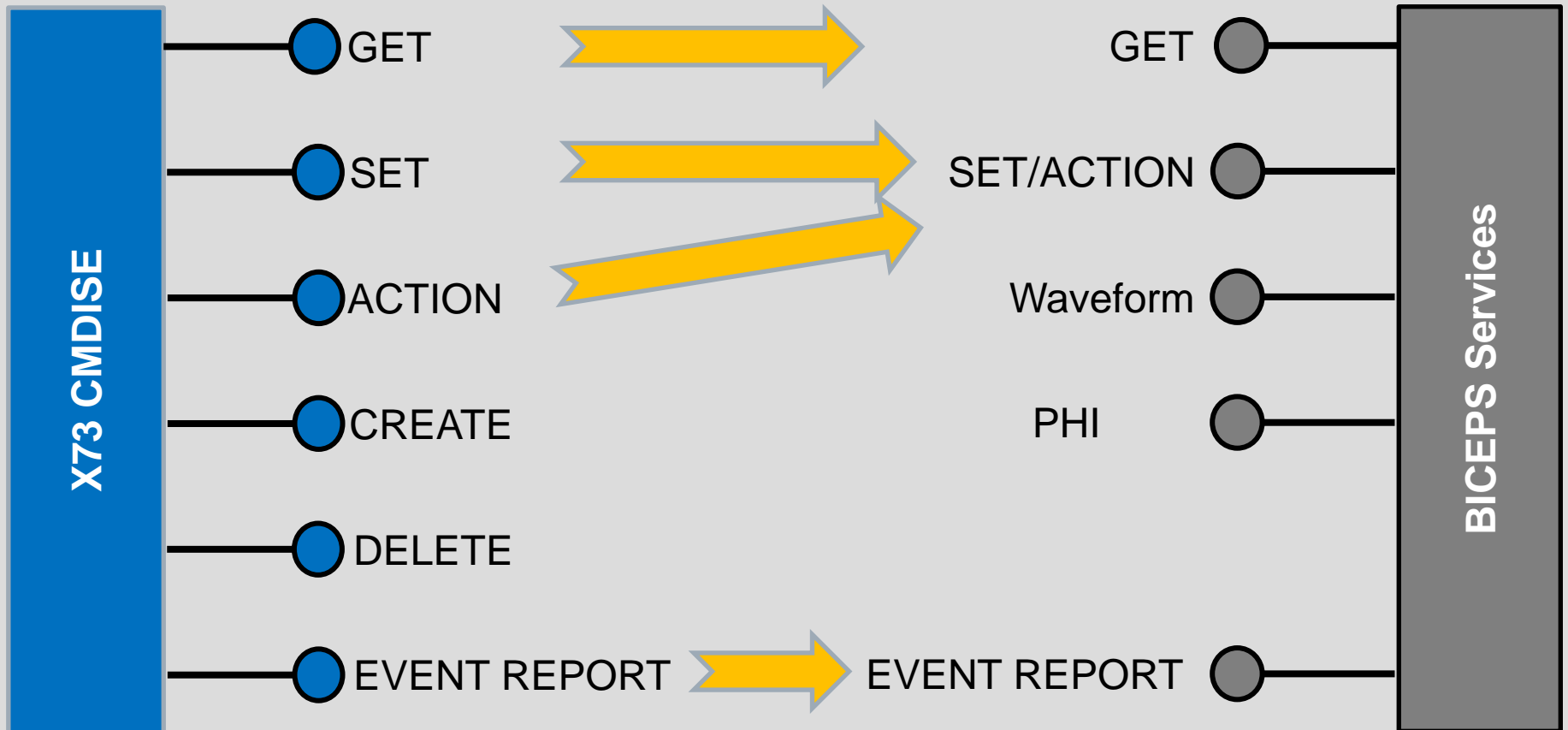
- Capabilities of the MD
- CodedValue concept
- (Rare) Update Reports

State Part

- Dynamic State of the MD
- All States reference to one Descriptor
- Episodic/Periodic Update Reports
- Streams

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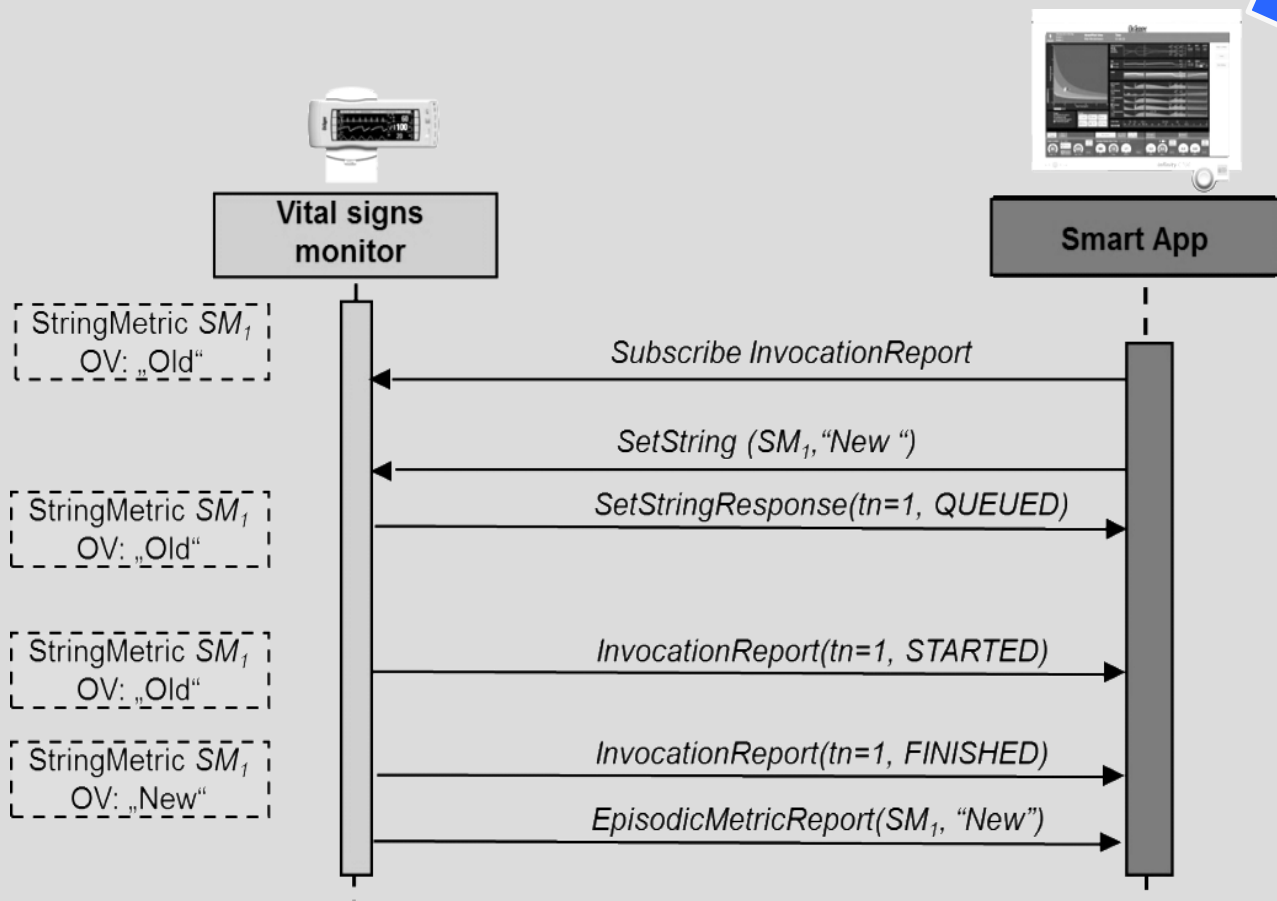
BICEPS Services



BICEPS

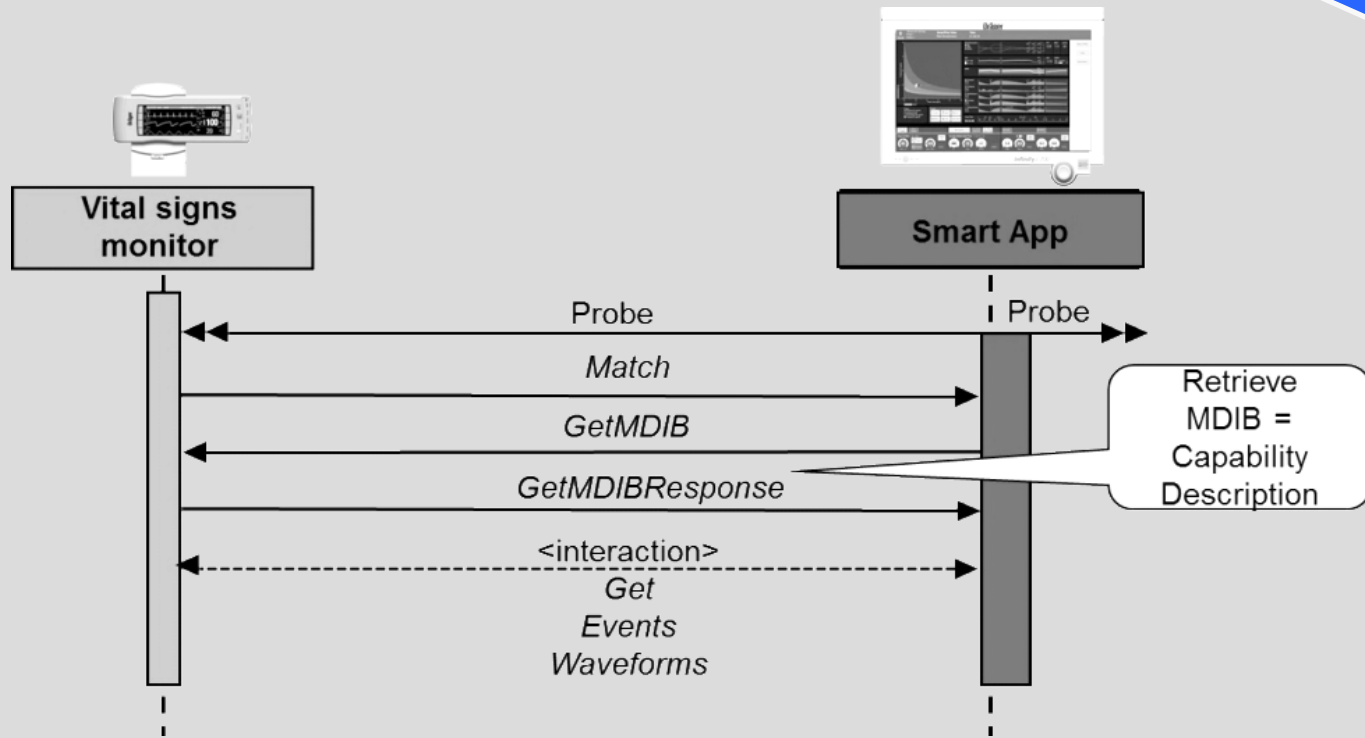
Remote invocation

... Example ...



Remote invocation via Set Service

... Example ...



Exemplary Discovery sequence

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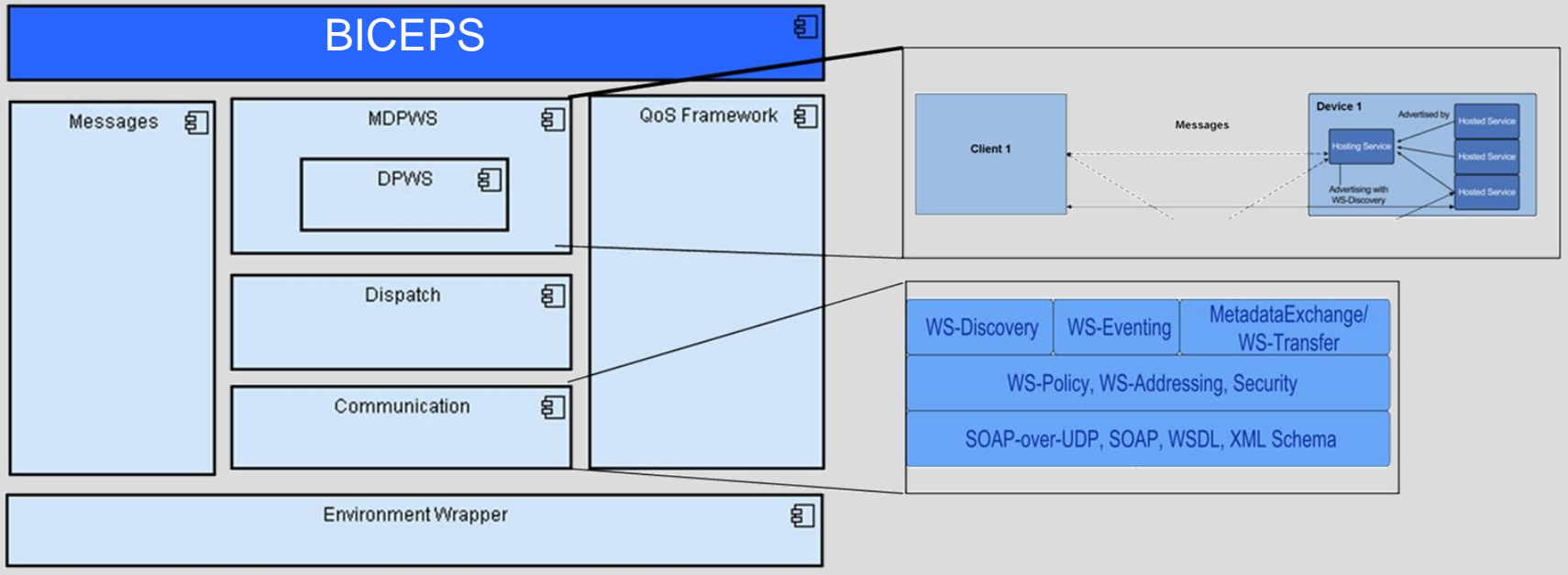
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Results

Developed Middleware

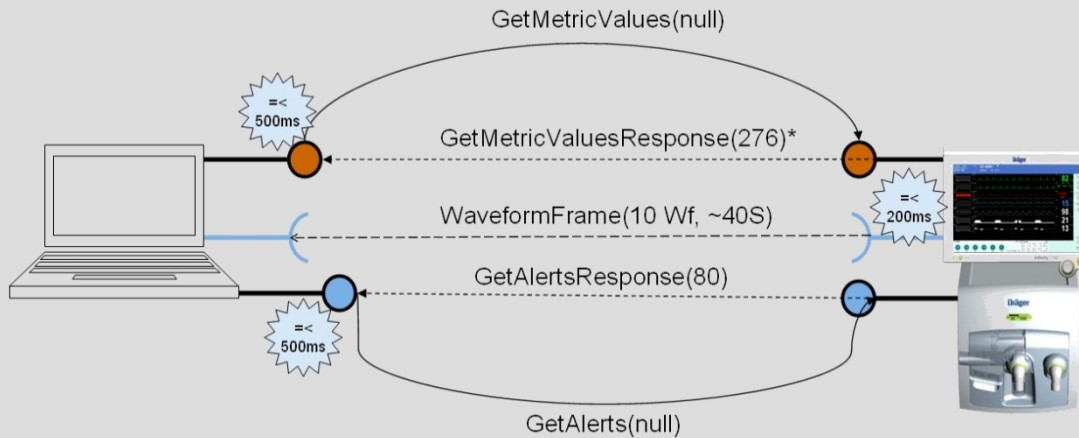
Java-based reference implementation

- \geq Java SE 1.6

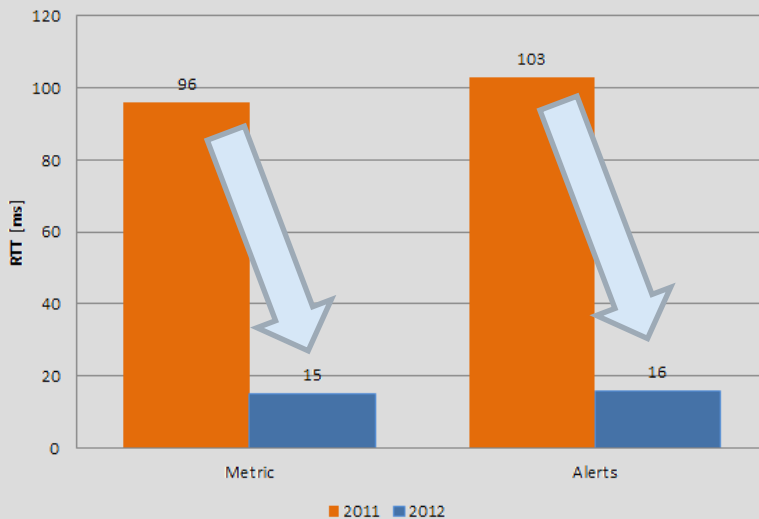


Results

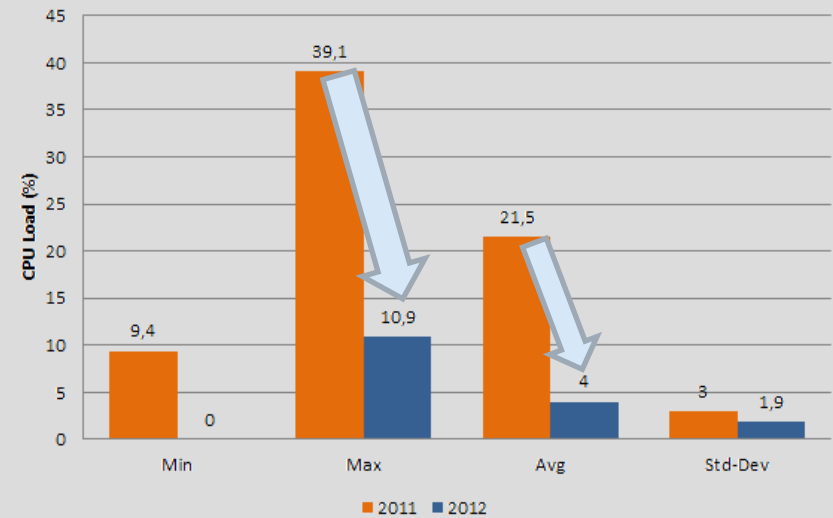
Test Scenario



Ventilator running JRE 6.
 Client running JRE 6.
 Direct Ethernet connection.



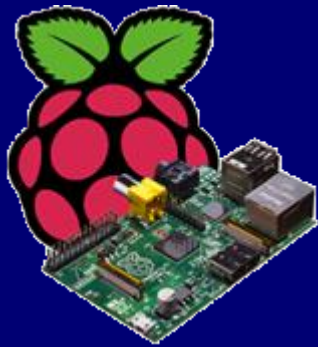
Round Trip Time



CPU Load

Results

Test Scenario



```

CA\Windows\system32\cmd.exe
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0
[GetAlertStates];RTT;104;380;19;77;675;RTTM;104;400;20;82;167;CNT;81;0;0;81;81
[GetMetricStates];RTT;100;728;26;71;395;RTTM;100;892;29;73;171;CNT;276;0;0;276;276
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0
[GetAlertStates];RTT;104;380;19;77;675;RTTM;111;645;25;82;195;CNT;81;0;0;81;81
[GetMetricStates];RTT;100;728;26;71;395;RTTM;106;542;23;75;169;CNT;276;0;0;276;276
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0
[GetAlertStates];RTT;104;380;19;77;675;RTTM;105;640;25;80;173;CNT;81;0;0;81;81
[GetMetricStates];RTT;100;728;26;71;395;RTTM;101;1655;40;74;270;CNT;276;0;0;276;276
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0
[GetAlertStates];RTT;104;380;19;77;675;RTTM;104;406;20;82;168;CNT;81;0;0;81;81
[GetMetricStates];RTT;100;728;26;71;395;RTTM;101;1655;40;74;270;CNT;276;0;0;276;276
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0
[StatisticsStreamHandler];Cnt;9;0;0;1;10;UCnt;0;0;0;0;0

```

```

pi@raspberrypi: ~/java/SimpleDevice2
[DEBUG] Read property header:<null><Service>
[DEBUG] Read property :<ConfigurationId>=<1>
[DEBUG] Read property header:<null><Service>
[DEBUG] Read property :<ConfigurationId>=<12>
[DEBUG] Read property header:<null><Service>
[DEBUG] Read property :<ConfigurationId>=<13>
[DEBUG] Read property header:<null><Service>
[DEBUG] Read property :<ConfigurationId>=<31>
[DEBUG] Read property header:<null><Service>
[DEBUG] Read property :<ConfigurationId>=<53>
[DEBUG] Read property header:<Streaming>
[DEBUG] Read property :<PropertiesHandler>=<de.draeger.configuration.streaming.StreamingConfigurationPropertiesHandler>
[DEBUG] Read property header:<null><Stream>
[DEBUG] Read property :<ConfigurationId>=<1>
[DEBUG] Read property header:<Global>
[DEBUG] Read property :<PropertiesHandler>=<org.w34d.java.propertiesHandler>
[DEBUG] Read property header:<null><Logging>
[DEBUG] Read property :<LogLevel>=<1>
[DEBUG] GlobalPropertiesHandler.setProperties: <LogLevel>
[SimpleWaveformGenerator] waveformsEnabled=true
Connected

```

```

pi@raspberrypi: ~
top - 22:45:34 up 14:28, 2 users, load average: 0.04, 0.06, 0.06
Tasks: 63 total, 1 running, 60 sleeping, 2 stopped, 0 zombie
%Cpu(s): 38.4 us, 3.6 sy, 0.0 ni, 57.0 id, 0.0 wa, 0.0 hi, 1.0 si, 0.0 st
KiB Mem: 188112 total, 176116 used, 11996 free, 4332 buffers
KiB Swap: 102396 total, 0 used, 102396 free, 39880 cached

  PID USER      PR  NI  VIRT  RES  SHR  S  %CPU  %MEM    TIME+  COMMAND
 1524 pi         20   0  119m  61m 4056 S  40.4  33.5  361:21.96 java
 1729 pi         20   0  4660 1372 1048 R   1.0   0.7   0:01.56 top
    6 root        -2   0    0    0    0 S   0.3   0.0   0:29.06 rcu_kthread
    1 root        20   0  2128  720  620 S   0.0   0.4   0:04.08 init
    2 root        20   0    0    0    0 S   0.0   0.0   0:00.00 kthreadd
    3 root        20   0    0    0    0 S   0.0   0.0   0:00.00 ksoftirqd/0
    5 root        20   0    0    0    0 S   0.0   0.0   0:08.46 kworker/u:0
    7 root        20   0  -20   0    0 S   0.0   0.0   0:00.00 khelper
    8 root        20   0    0    0    0 S   0.0   0.0   0:00.01 kdevtmpfs
    9 root        20   0  -20   0    0 S   0.0   0.0   0:00.00 netns
   10 root        20   0    0    0    0 S   0.0   0.0   0:00.59 sync_supers
   11 root        20   0    0    0    0 S   0.0   0.0   0:00.01 bdi-default
   12 root        20   0  -20   0    0 S   0.0   0.0   0:00.00 kblockd
   13 root        20   0    0    0    0 S   0.0   0.0   0:00.37 khubd
   14 root        20   0    0    0    0 S   0.0   0.0   0:00.00 rpciod
   15 root        20   0    0    0    0 S   0.0   0.0   0:07.06 kworker/0:1
   16 root        20   0    0    0    0 S   0.0   0.0   0:00.06 khungtaskd

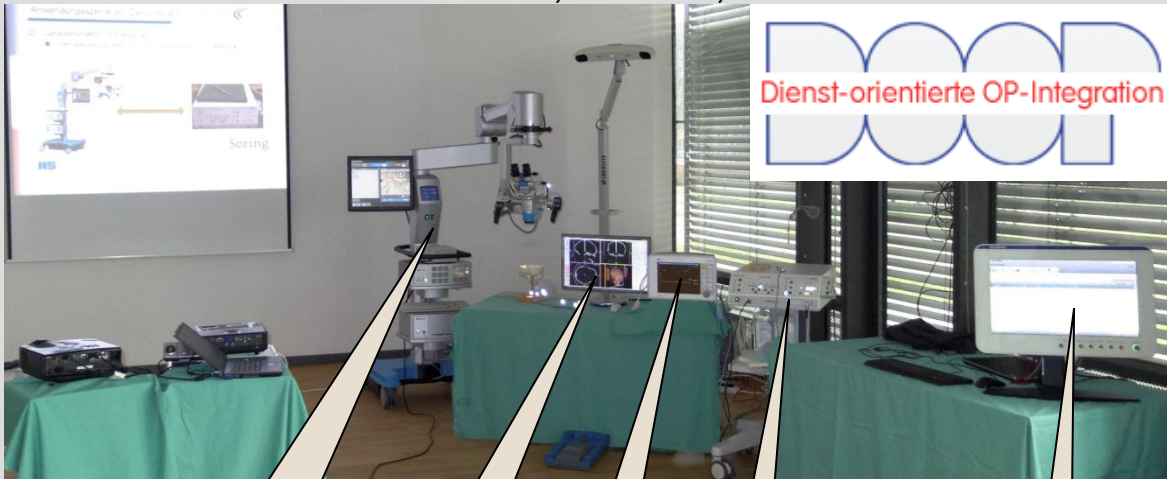
```

Raspberry PI runs as a device in the test scenario. No optimization performed.

Results

Demonstrators

DOOP Demonstrator, Lübeck, 2013-12-11



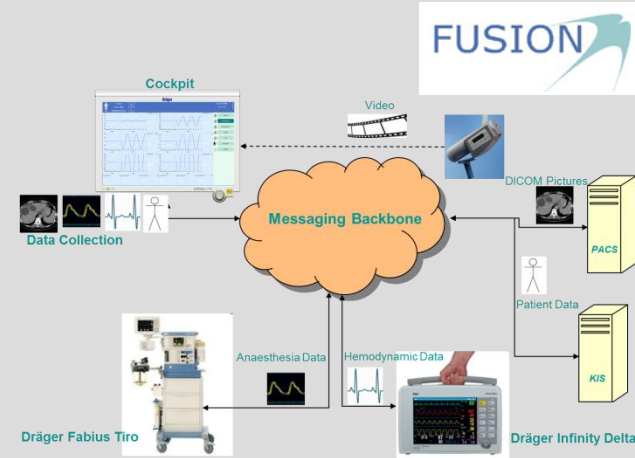
Surgical microscope

Neuro Navigation

Vital Signs Monitor

US Dissector

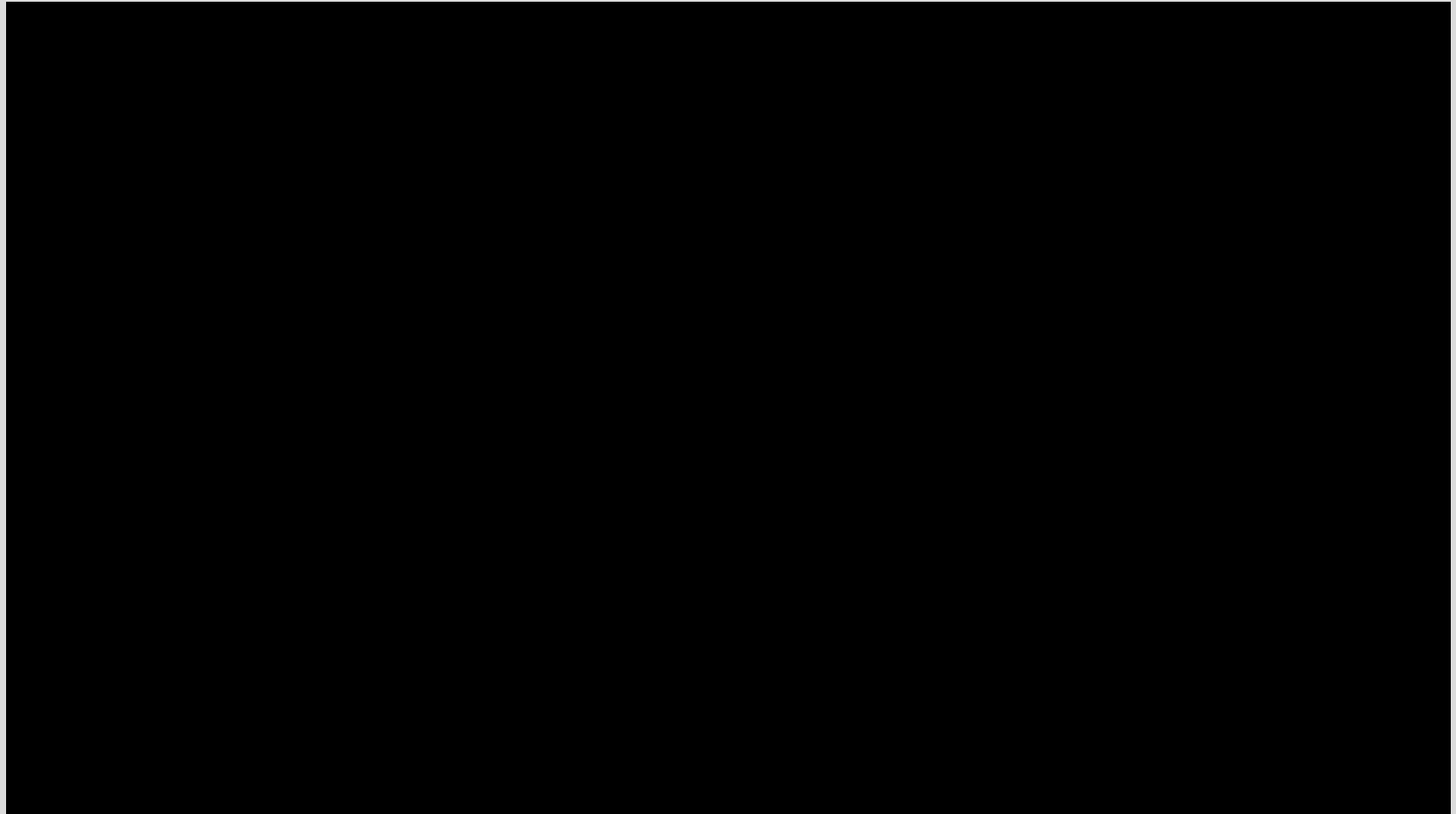
OR Management



Demonstrator, 2009



Demonstrator, 2011






DOOP Demonstrator, Lübeck, 2013-12-11




Proposed Architecture Summary

Functional

Plug'n Play

- Discovery and Binding 
- Device capability description at runtime 
- Openness 

Communication (1-1, 1-n, n-n)

- Event Notification 
- Data reporting 
- External control 

Non-Functional

- Risk Management 
- Safe communication 
- Access control 
- Trust establishment between participants 
- Privacy of patient-related data 
- Latency in milliseconds range 

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DDS

What is DDS?

Date: January 2007

Data Distribution Service for Real-time Systems
Version 1.2

OMG Available Specification
formal/07-01-01


Date: January 2009



The Real-time Publish-Subscribe Wire Protocol
DDS Interoperability Wire Protocol
Specification

Version 2.1

Date: November 2012



Extensible and Dynamic Topic Types for DDS

Version 1.0

DDS

- OMG standard for distributed systems
- utilize an architecture that relies on the indirect communication paradigm that is based on a data-centric publish-subscribe (DCPS) model
- several QoS features
 - HISTORY, LIFESPAN, RELIABILITY, PARTITION, DEADLINE, OWNERSHIP, PRESENTATION, TIME_BASED_FILTER, RESOURCE_LIMITS,...
- Conformance profiles: minimal, Content-subscription, Persistence, ...
- API standard
 - Different DDS implementations may be incompatible on the wire

RTPS

- RTPS extension to DDS or stand alone specification
- Messages & Behavior of participants
- Simple Discovery mechanisms
- One transport module based on UDP

XTypes

- DDS has a static, non extensible type model
- Limited support for extensions
- Data types must be known at compile time
- Xtypes extension for DDS & RTPS

DDS

Evaluation Results of DDS standards family

... Evaluation
in 2009 &
2013...

Benefits

- DDS is a non-proprietary specification for a data distribution API for distributed systems
- Proven to allow implementation of scalable DS
- Rich set of QoS parameters
- RTPS to ensure interoperability on the wire
- XTypes to ensure model extensibility



- RTPS & XTypes are the relevant specifications for an open distributed system
 - Original DDS standard is just an API specification

Weaknesses of RTPS & XTypes as perceived by Dräger




- Transport security not standardized
 - Only vendor specific options available at the moment
- RTPS doesn't support all DDS QoS features on its own as most are not wire-protocol related
- RTPS is designed for data distribution, not remote invocation
- Indirect communication may complicate implementation of risk measures
- Topic-based model may lead to intermingling of message model & transport channel related safety implementations

RTPS & XTypes




Summary of Evaluation

Functional

Plug'n Play

- Discovery and Binding 
- Device capability description at runtime 
- Openness 

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RTPS & XTypes is great for distributed systems of one vendor where data distribution is the focus

Examples: Airplane, Car, Inside of a CT

It is not our first choice for implementation of an open distributed system of medical devices from multiple vendors

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8. Formal Request to IEEE 11073 Committee




Discussion Summary

Functional

Plug'n Play

- Discovery and Binding 
- Device capability description at runtime 
- Openness 

Communication (1-1, 1-n, n-n)

- Event Notification 
- Data reporting 
- External control 

Non-Functional

- Risk Management 
- Safe communication 
- Access control 
- Trust establishment between participants 
- Privacy of patient-related data 
- Latency in milliseconds range 

BICEPS + MDPWS meets the requirements of the project ...

Discussion openSDC

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openSDC Beta

OpenSDC facilitates development of dist. systems of medical devices.
Brought to you by: klotzt, schlich09, steph96

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Description

The openSDC libraries are communication library that facilitate the development of distributed systems of medical devices in high-acuity environments.

OpenSDC has been developed in an Dräger-internal technology project called "Device & System Connectivity" that had the goal to meet increasing demand for medical device interoperability in an Integrated Clinical Environment (ICE). An ICE is a distributed system of medical devices for one clinical workplace that may have an external interface to other systems. ASTM F2761-1:2009 describes the components that are required for safe and effective "Plug & Play" operation of an ICE in high-acuity environments.

The project had the objective to develop an efficient, future-proof architecture, protocol stack, and middleware that satisfies the derived requirements and facilitates the implementation of the concept of an ICE.

... Feedback requested ...

... and you can evaluate it yourself by downloading the **open-source reference implementation** from sourceforge

<https://sourceforge.net/projects/opensdc>

A Proposal For Standards Adoption

Agenda

1. Introduction
2. Clinical Workplace SOMDA
3. MDPWS
4. BICEPS
5. Results
6. DDS
7. Discussion
- 8. Formal Request to IEEE 11073 Committee**

We seek adoption of the DPWS architecture as the basis for IEEE 11073-20401.

- We have demonstrated the strong functional and non-functional attributes of the proposed architecture to meet both near-term and longer-term requirements for the point of care integration of medical devices.
- We have disclosed a list of collaborating partners who have evaluated and are utilizing the proposed architecture as strong references for its ease of use and its adaptability.
- We are prepared to work with the Committee in the development of IEEE 11073-20401 to support its completion.
- In order to accelerate acceptance and allow evaluation, Dräger is announcing to the IEEE 11073 Standards Committee that a reference implementation of this architecture is now available as open source.
- We respectfully ask for your favorable and timely consideration to our proposal.

**Thank you for your
attention.**

Contact

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