Microprocessors, Lecture 9:

# Interrupts in AVR Microcontrollers (Chapter 10 of the text book)



# Contents

- Interrupts ATmega32
- Using interrupts in C programming

#### **Interrupts in AVR**



#### Interrupts: A way o improve performance

#### How do interrupts work?



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#### Interrupt vs. polling

- Polling:
  - Continuously check the flags to know when the expected event occurs, then go for the next event
  - Example: Timer time-out problem of the previous lecture:

```
void T0Delay ( )
{
    TCNT0 = 0x20; //load TCNT0
    TCCR0 = 0x01; //Timer0, Normal mode, no prescaler
    while ((TIFR&0x1)==0); //wait for TF0 to roll over
    TCCR0 = 0;
    TIFR = 0x1; //clear TF0
}
```

# Interrupt vs polling

- Polling: wasting time to check the devices continuously
- What if we are to generate two delays at the same time?

– Example: Toggle bit PB.5 every 1s and PB.4 every 0.5s.

- What if there are some task to be done simultaneously with the timers?
  - Example: (1) read the contents of port A, process the data, and send them to port D continuously, (2) toggle bit PB.5 every 1s, and (3) PB.4 every 0.5s.

# Interrupt vs polling

• Interrupts

- A mechanism to work with peripheral devices

- No need for the processor to monitor the status of the devices and events
- Let the events notify the processor when they occur
  - By sending an interrupt signal to processor

# Interrupt vs polling

- Interrupts:
  - Example: Copy the contents of port A to port D continuously and toggle bit PB.5 every 1s and PB.4 every 0.5s.
  - Solution:
    - » Copying the contents of port A to port D as the main program
    - » Get timers 0 and 1 to generate the delays
    - » Define two interrupts for timers 0 and 1 to notify the processor when they finish counting
    - » Upon an interrupt, stop the main program, service the timers and continue the main program

#### Interrupts

- Interrupting mechanism in all microprocessors and microcontrollers is almost the same:
  - Define the set of devices and events that can generate an interrupt
  - Write a function for each interrupt that will be executed when the corresponding interrupt is activated
    - » The address of this function must be saved somewhere
  - Set a priority scheme among interrupts
  - A mechanism is needed to disable all or some interrupts

#### Interrupts

- ISR: Interrupt Service Routine
  - The function that is executed when an interrupt is enabled
- Interrupt Vector Table: a table that keeps the address of each ISR in the instruction memory

#### **Interrupt sources in AVR**

آدرس یا وکتور روتین سرویس وقفه					
میکروکنترلر ATtiny :AVR	<i>میکروکنترلر</i> ATmega32 :AVR	<i>میکروکنترلر</i> ATmega16 :AVR	<i>میکر وکنتر لر</i> ATmega8 :AVR	دستكاه تقاضاكننده وقفه	
0x000	0x000	0x000	0x000	*** Reset	
0x001	0x002	0x002	0x001	وقفه خارجي شماره 0 درپايه INTO	
—	0x004	0x004	0x002	وقفه خارجی شماره ۱ در پایه INT۱	
—	0x006	0x024	_	وقفه خارجی شماره 2 در پایه INT2	
—	0x008	0x006	0x003	تایمر 2 در Compare Match	
	0x00A	0x008	0x004	تایمر 2 در سرریز Overflow	
	0x00C	0x00A	0x005	تایمر ۱ در input capture	
0x003	0x00E	0x00C	0x006	تایمر 1 در Compare Match A	
	0x010	0x00E	0x007	تایمر 1 در Compare Match B	
0x004	0x012	0x010	0x008	مر ۱ در سرریز یا Overflow	
0x005	0x016	0x012	0x009	مر 0 در سرریز یا Overflow	
	0x014	0x026		تایمر <sup>*</sup> 0 در Compare Match	
	0014	0010	000	پورت سری USART برای دریافت کامل	
	UXUTA	0x016	0X008	یک بایت (RXC)	
0x008	0x020	0x01C	0x00E	مبدل آنالوگ به دیجیتال ADC	
0x007	0x024	0x020	0x010	مقايسهكننده أنالوگ	

#### **External interrupts**

#### 3 pins of ATmega32



# **Interrupts in AVR**

- Just 2-bytes for each interrupt service routine
- Too small to write the interrupt service routine
- → Write the routine somewhere in the memory and put a code to jump to the address of the function in the 2-byte assigned to the ISR

	ين سرويس وقفه				
میکروکنترلر ATtiny :AVR	میکروکنترلر ATmega32 :AVR	<i>میکروکنترلر</i> ATmega16 :AVR	<i>میکر وکنتر لر</i> ATmega8 :AVR	دستكاه تقاضاكننده وقفه	
0x000	0x000	0x000	0x000	Reset	
0x001	0x002	0x002	0x001	وقفه خارجی شماره 0 درپایه INT0	
-	0x004	0x004	0x002	وقفه خارجی شماره ۱ در پایه INT۱	
-	0x006	0x024	_	وقفه خارجي شماره 2 در پايه INT2	
_	0x008	0x006	0x003	تایمر 2 در Compare Match	
—	0x00A	0x008	0x004	تایمر 2 در سرریز Overflow	
-	0x00C	0x00A	0x005	تایمن 1 در input capture	
0x003	0x00E	0x00C	0x006	تایمر 1 در Compare Match A	
-	0x010	0x00E	0x007	مر 1 در Compare Match B	
0x004	0x012	0x010	0x008	یمر ۱ در سرریز یا Overflow	
0x005	0x016	0x012	0x009	یمر 0 در سرریز یا Overflow	
	0x014	0x026		تايمر <sup>®</sup> 0 در Compare Match	
				پورت سری USART برای دریافت کامل	
	0x01A	0x016	0x00B	یک بایت (RXC)	
0x008	0x020	0x01C	0x00E	مبدل آنالوگ به دیجیتال ADC	
0x007	0x024	0x020	0x010	مقایسهکننده آنالوگ	

# **Interrupts in AVR**

- How is an interrupt serviced?
- 1. Stop fetching the next instruction and save PC
- 2. Go to Interrupt Vector Table to find the address of the ISR of the interrupting device
- 3. Execute the function
- 4. Resume normal execution by retrieving PC

# **Enabling Interrupts**

- Interrupts can be enabled or disabled by programmer
  - Bit7 (I) in SREG (status register)
  - SREG keeps the processor status (remember the first lecture on AVR)
  - Disabled on reset (I=0)



# **Enabling Interrupts**

- In addition to Bit7 (I) in SREG each interrupt should be enabled independently
- The enable bit of each interrupt is in some register
  - Example: TIMSK register to enable/disable timer interrupts
  - TIMSK= Timer Interrupt Mask
  - پوشاندن ، غيرفعال كردن ?Mask –
- To enable timer1 overflow interrupt:
  - Bit7 (I) in SREG  $\leftarrow$  1
  - Bit 0 of TIMSK (TOIE0) ← 1



# **Interrupt priority**

- What if two or more interrupts occur at the same time?
  - The interrupt with lower ISR address is prioritized (external int. 0 has the highest priority)
- When an interrupt is serviced, the *I* bit becomes automatically 0 to disable interrupts
  - Will be enabled when returning from the ISR

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نرلر میکروکنترل ATtiny:AVR ATme	میکروکنآ ga32 :AVR	<i>میکروکنترلز</i> ATmega16 :AVR	میکروکنترلر ATmega8 :AVR	دستكاه تقاضاكننده وقفه	
0x000 0	x000	0x000	0x000	Reset	
0x001 0	x002	0x002	0x001	رقفه خارجی شماره 0 درپایه INT0	
- 0	x004	0x004	0x002	وقفه خارجی شماره ۱ در پایه ۱NT۱	
- 0	x006	0x024	_	وقفه خارجی شماره 2 در پایه INT2	
- 0	x008	0x006	0x003	تایمر 2 در Compare Match	
- 0	x00A	0x008	0x004	تایمر 2 در سرریز Overflow	
- 0	x00C	0x00A	0x005	تایمر ۱ در input capture	
0x003 0	x00E	0x00C	0x006	تایمر 1 در Compare Match A	
_ 0	x010	0x00E	0x007	تایمر 1 در Compare Match B	
0x004 0	x012	0x010	0x008	مر ۱ در سرریز یا Overflow	
0x005 0	x016	0x012	0x009	مر 0 در سرریز یا Overflow	
0	x014	0x026		یمر <sup>©</sup> 0 در Compare Match	
		0.010	0.000	پورت سری USART برای دریافت کامل	
0	XUIA	0x016	0×008	یک بایت (RXC)	
0x008 0	x020	0x01C	0x00E	ل آنالوگ به دیجیتال ADC	
0x007 0	x024	0x020	0x010	مقايسهكننده أنالوك	

# **TIMSK register**

**D**0

OCIE2 TOIE2 TICIE1 OCIE1A OCIE1B TOIE1 OCIE0 TOIE0

TOIE0	Timer0 overflow interrupt enable
	= 0 Disables Timer0 overflow interrupt
	= 1 Enables Timer0 overflow interrupt
OCIE0	Timer0 output compare match interrupt enable
	= 0 Disables Timer0 compare match interrupt
	= 1 Enables Timer0 compare match interrupt
TOIE1	Timer1 overflow interrupt enable
	= 0 Disables Timer1 overflow interrupt
	= 1 Enables Timer1 overflow interrupt
OCIE1B	Timer1 output compare B match interrupt enable
	= 0 Disables Timer1 compare B match interrupt
	= 1 Enables Timer1 compare B match interrupt
OCIE1A	Timer1 output compare A match interrupt enable
	= 0 Disables Timer1 compare A match interrupt
	= 1 Enables Timer1 compare A match interrupt
TICIE1	Timer1 input capture interrupt enable
	= 0 Disables Timer1 input capture interrupt
	= 1 Enables Timer 1 input capture interrupt
TOIE2	Timer2 overflow interrupt enable
	= 0 Disables Timer2 overflow interrupt
	= 1 Enables Timer2 overflow interrupt
OCIE2	Timer2 output compare match interrupt enable
	= 0 Disables Timer2 compare match interrupt
	= 1 Enables Timer2 compare match interrupt

D7

# Interrupt programming in C

- Enable interrupts
- Set the mask register (TIMSK for timers)

   Example: TIMSK=0x01;
- Write the ISR function to specify what operation should be done when the interrupt occurs
- → Compiler dependent: different in different compilers!

# Interrupt programming in C

 A way to use assembly instructions in C:

#asm("instruction")

- SEI: (Set I) an assembly instruction that enables interrupts (bit 7 of SREG=1)
- CLI: Clear I
- #asm("sei"); enable interrupts in C
- No way to access SREG.7 in C
- Mazidi's book uses a different compiler→ different instructions: sei() instead of #asm("sei"), different ISR names

Example 10-8 (C version of Program 10-1) Using Timer0 generate a square wave on pin PORTB.5, while at the same time transferring data from PORTC to PORTD. Solution: #include "avr/io.h" #include "avr/interrupt.h" int main () DDRB  $| \approx 0 \times 20;$ //DDRB.5 = outputTCNT0 = -32;//timer value for 4  $\mu$ s  $TCCR0 = 0 \times 01;$ //Normal mode, int clk, no prescaler TIMSK = (1 << TOIE0);//enable Timer0 overflow interrupt //enable interrupts #asm("sei"); DDRC = 0x00;//make PORTC input //make PORTD output DDRD = 0xFF;//wait here while (1) PORTD = PINC; interrupt [TIM0\_OVF] void timer0\_ovf\_isr(void) TCNT0 = -32;PORTB  $^{=}$  0x20; //toggle PORTB.5  $\rightarrow$  On entering the timers ISR, the TOV0 bit is automatically cleared, no need to be cleared by software University of Tehran 20

#### Interrupt programming in C

#include <mega32.h>

 In codevision, ISR is generated during project setup. Just fill the function body!

🚯 CodeWizardAVR - untitled.cwp 🛛 💽					
File Help	0				
USART 12C LCD Chip Timer 0 Clock S Clock V	Analog Comparator   ADC   SPI   1 Wire   2 Wire (I2C)   Bit-Banged   Project Information   Ports   External IRQ   Timers   Timer 1   Timer 2   Watchdog   Source: System Clock /alue: Timer 0 Stopped				
Mode:	Mode: Normal top=FFh				
Output: Disconnected					
I Over Timer ↓ Compa	erflow Interrupt npare <u>Match Interrupt</u> /alue: 0 h re: 0 h				

// Timer 0 overflow interrupt service routine
interrupt [TIM0\_OVF] void timer0\_ovf\_isr(void)
{
// Place your code here

// Declare your global variables here
void main(void)

TCCR0=0x00; TCNT0=0x00; OCR0=0x00;

ł

// Timer(s)/Counter(s) Interrupt(s) initialization
TIMSK=0x01;

// Global enable interrupts
#asm("sei")

while (1)
 {
 // Place your code here

}

};

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#### **External Interrupts**

- To allow external sources interrupt the microcontroller
- Can be masked by CIGR register
- GICR: General interrupt control register



#### **External Interrupts- GICR**

#### D7

D0

						_	
INT1	INT0	INT2	-	-	-	IVSEL	IVCE

INTO	External Interrupt Request 0 Enable
	= 0 Disables external interrupt 0
	= 1 Enables external interrupt 0
INT1	External Interrupt Request 1 Enable
	= 0 Disables external interrupt 1
	= 1 Enables external interrupt 1
INT2	External Interrupt Request 2 Enable
	= 0 Disables external interrupt 2
	= 1 Enables external interrupt 2

These bits, along with the I bit, must be set high for an interrupt to be responded to.

#### **External interrupts**

- Interrupts can be edge triggered or level triggered
- Edge trigger: activated when a change in signal level occurs
- Level trigger: activated when a signal has a specific value
- INT0 and INT1 can be programmed to be edge or level triggered

- Low-level active by default

• INT 2 is only edge triggered

#### **External interrupts**

 A register called ISC (interrupt sense control) can set the interrupt type of INT0 and INT1

menonecommencement managementers and an	TOOLL	TOOLO	TOCOL	ICCOO
SE SM2 SM1 SM0	ISCII	ISCIO	ISCOI	ISCOO

ISC01	ISC00	d. Explain	Description
0	0		The low level of INT0 generates an interrupt request.
0	1	71	Any logical change on INT0 generates an interrupt request.
1	0	1	The falling edge of INT0 generates an interrupt request.
1	1	f	The rising edge of INT0 generates an interrupt request.

ISC10 and ISC11 set the same setting for INT1

#### External Interrupts- C programming

#### Example 10-12 (C version of Example 10-5)

Assume that the INTO pin is connected to a switch that is normally high. Write a program that toggles PORTC.3, whenever INTO pin goes low. Use the external interrupt in level-triggered mode.

#### Solution: