Communications

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- Case Studies

Spread Spectrum Systems, Mobile radio concepts, GSM and Multiple Access Schemes Mobile radio

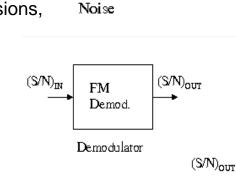
Introduction to Modulation and Demodulation

The purpose of a communication system is to transfer information from a source to a destination.

Tx

In practice, problems arise in baseband transmissions, the major cases being:

 Noise in the system – external noise and circuit noise reduces the signal-to-noise (S/N) ratio at the receiver (Rx) input and hence reduces the quality of the output.



Channel

(S/N)

Rx

T Improvement due to FM

Loudspeaker

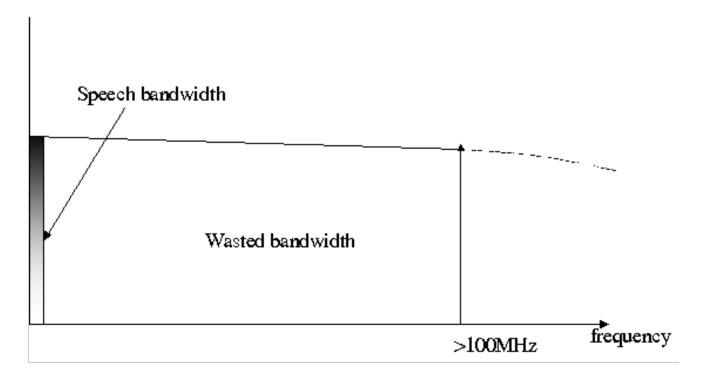
• Such a system is not able to fully utilise the available bandwidth, for example telephone quality speech has a bandwidth \simeq 3kHz, a co-axial cable has a bandwidth of 100's of Mhz.

Mic

- Radio systems operating at baseband frequencies are very difficult.
- Not easy to network.

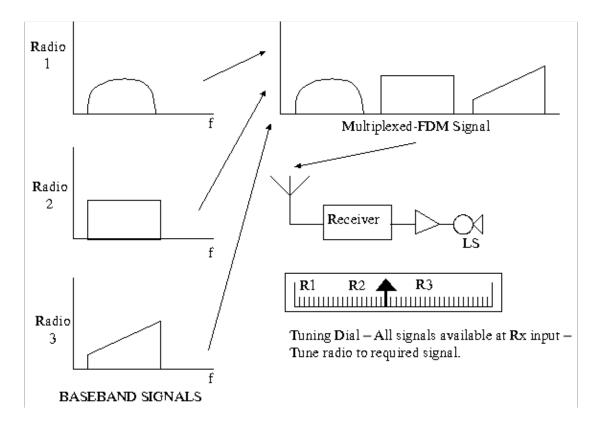
Multiplexing

Multiplexing is a modulation method which improves channel bandwidth utilisation. For example, a co-axial cable has a bandwidth of 100's of Mhz. Baseband speech is a co-axial cable has a bandwidth of 100's of Mhz.



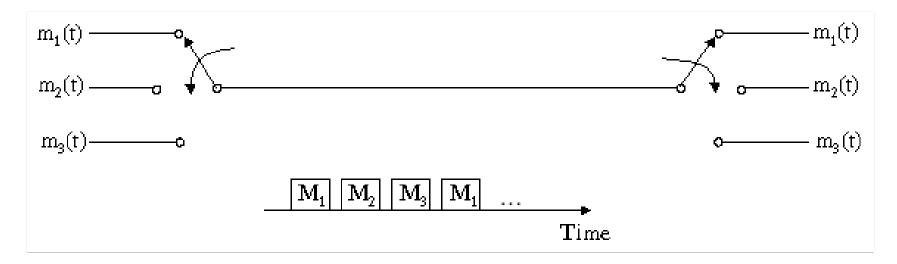
1) Frequency Division Multiplexing FDM

This allows several 'messages' to be translated from baseband, where they are all in the same frequency band, to adjacent but non overlapping parts of the spectrum. An example of FDM is broadcast radio (long wave LW, medium wave MW, *etc.*)



2) Time Division Multiplexing TDM

TDM is another form of multiplexing based on sampling which is a modulation technique. In TDM, samples of several analogue message symbols, each one sampled in turn, are transmitted in a sequence, *i.e.* the samples occupy adjacent time slots.



Radio Transmission

•Aerial dimensions are of the same order as the wavelength, λ , of the signal (*e.g.* quarter wave $\lambda/4$, $\lambda/2$ dipoles).

 λ is related to frequency by $\left| \lambda = \frac{c}{f} \right|$ where c is the velocity of an electromagnetic wave, and $c = \frac{c}{f}$ $3x10^8$ m/sec in free space.

For baseband speech, with a signal at 3kHz, (3x10³Hz)

 $\lambda = \frac{3x10^8}{2x10^3} = 10^5 \text{ metres or } 100 \text{ km}.$

- Aerials of this size are impractical although some transmissions at Very Low Frequency (VLF) for specialist applications are made.
- A modulation process described as 'up-conversion' (similar to FDM) allows the baseband signal to be translated to higher 'radio' frequencies.
- Generally 'low' radio frequencies 'bounce' off the ionosphere and travel long distances around the earth, high radio frequencies penetrate the ionosphere and make space communications possible. The ability to 'up convert' baseband signals has implications on aerial dimensions and design, long distance terrestrial communications, space communications and satellite communications. Background 'radio' noise is also an important factor to be considered.
- In a similar content, optical (fibre optic) communications is made possible by a modulation process in which an optical light source is modulated by an information source.

Networks

- A baseband system which is essentially point-to-point could be operated in a network. Some forms of access control (multiplexing) would be desirable otherwise the performance would be limited. Analogue communications networks have been in existence for a long time, for example speech radio networks for ambulance, fire brigade, police authorities *etc.*
- For example, 'digital speech' communications, in which the analogue speech signal is converted to a digital signal via an analogue-to-digital converter give a form more convenient for transmission and processing.

What is Modulation?

In modulation, a <u>message</u> signal, which contains the <u>information</u> is used to control the parameters of a <u>carrier</u> signal, so as to impress the information onto the carrier.

The Messages

The message or modulating signal may be either: analogue – denoted by m(t)digital – denoted by d(t) - i.e. sequences of 1's and 0's The message signal could also be a multilevel signal, rather than binary; this is not considered further at this stage.

The Carrier

The carrier could be a 'sine wave' or a 'pulse train'. Consider a 'sine wave' carrier:

$$v_c(t) = V_c \cos(\omega_c t + \varphi_c)$$

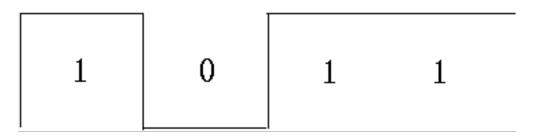
• If the message signal *m*(*t*) controls amplitude – gives AMPLITUDE MODULATION AM

- If the message signal m(t) controls frequency gives FREQUENCY MODULATION FM
- If the message signal m(t) controls phase- gives PHASE MODULATION PM or ϕM

• Considering now a digital message *d*(*t*):

If the message *d*(*t*) controls amplitude – gives **AMPLITUDE SHIFT KEYING ASK**. As a special case it also gives a form of Phase Shift Keying (PSK) called **PHASE REVERSAL KEYING PRK**.

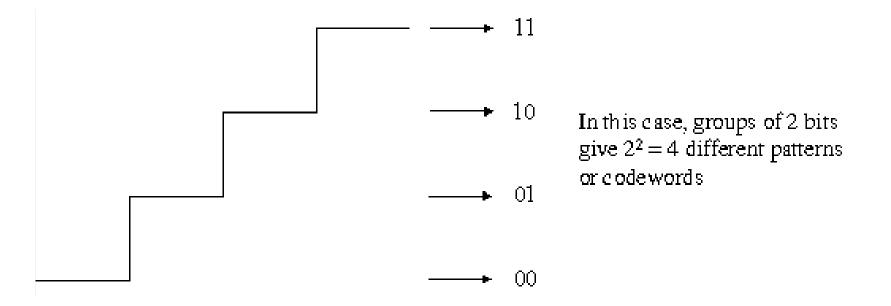
- If the message *d*(*t*) controls frequency gives **FREQUENCY SHIFT KEYING FSK**.
- If the message *d*(*t*) controls phase gives **PHASE SHIFT KEYING PSK**.
- In this discussion, d(t) is a binary or 2 level signal representing 1's and 0's



- The types of modulation produced, *i.e.* ASK, FSK and PSK are sometimes described as binary or 2 level, *e.g.* Binary FSK, BFSK, BPSK, *etc.* or 2 level FSK, 2FSK, 2PSK *etc.*
- Thus there are 3 main types of Digital Modulation: ASK, FSK, PSK.

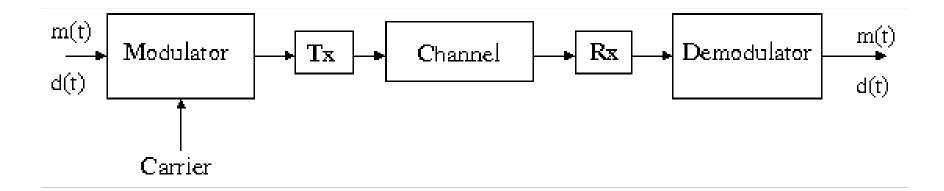
Multi-Level Message Signals

As has been noted, the message signal need not be either analogue (continuous) or binary, 2 level. A message signal could be multi-level or m levels where each level would represent a discrete pattern of 'information' bits. For example, m = 4 levels

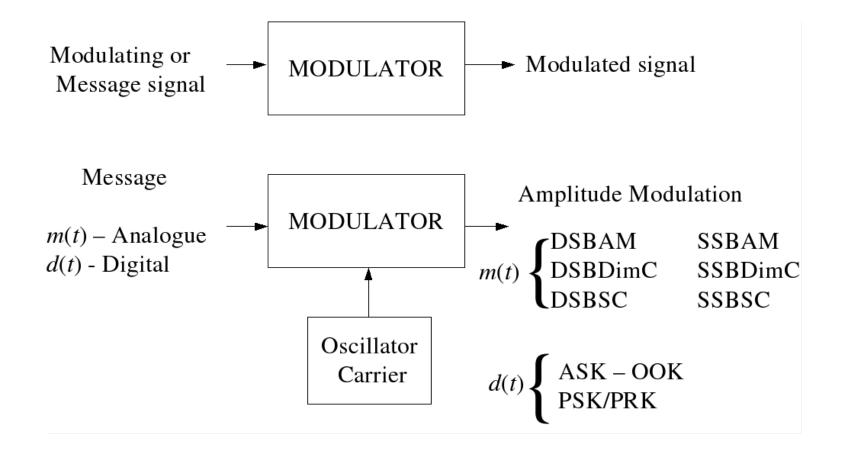


What is **Demodulation**?

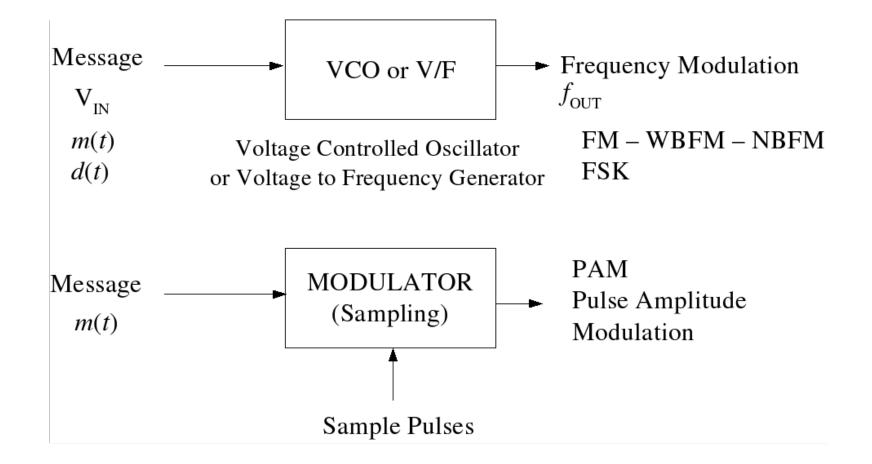
Demodulation is the reverse process (to modulation) to recover the message signal m(t) or d(t) at the receiver.



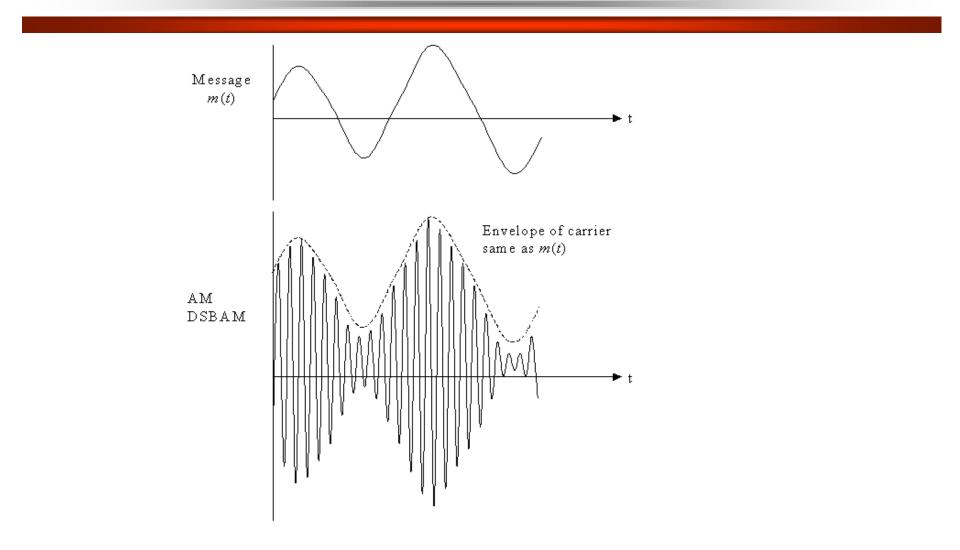
Summary of Modulation Techniques 1



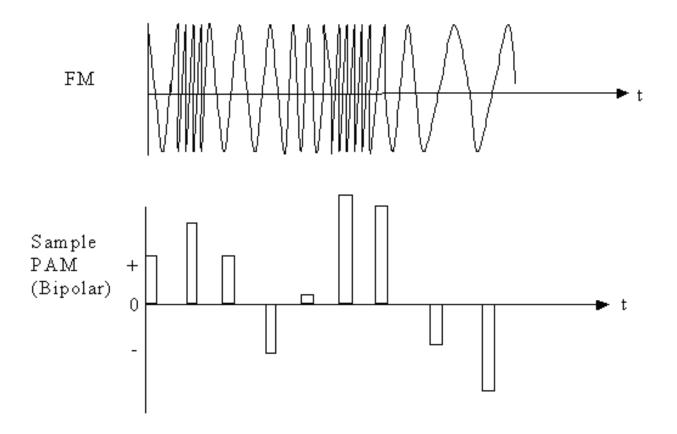
Summary of Modulation Techniques 2



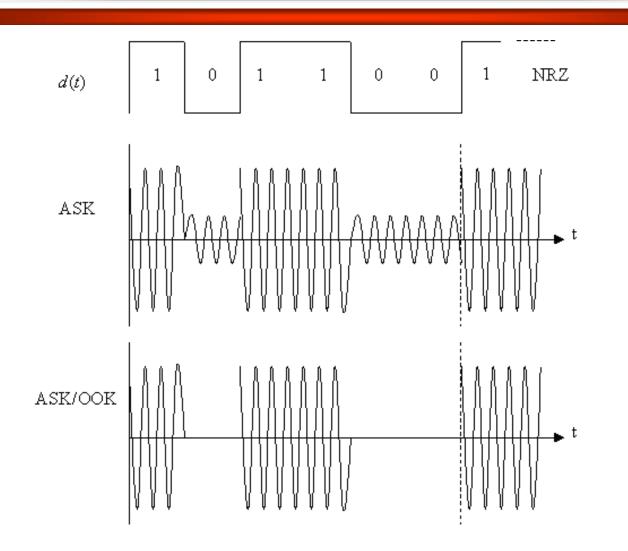
Modulation Types AM, FM, PAM



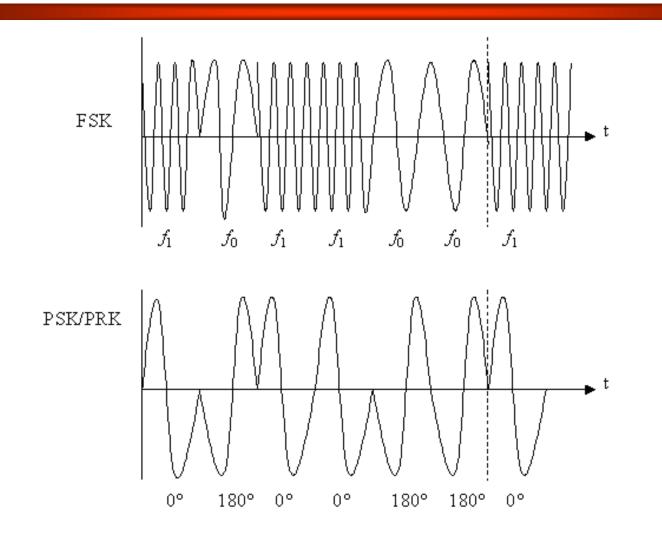
Modulation Types AM, FM, PAM 2



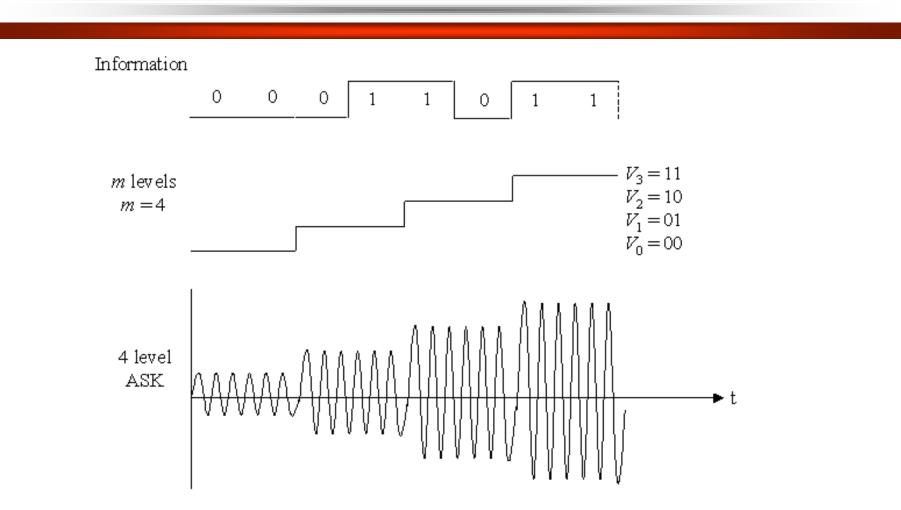
Modulation Types (Binary ASK, FSK, PSK)



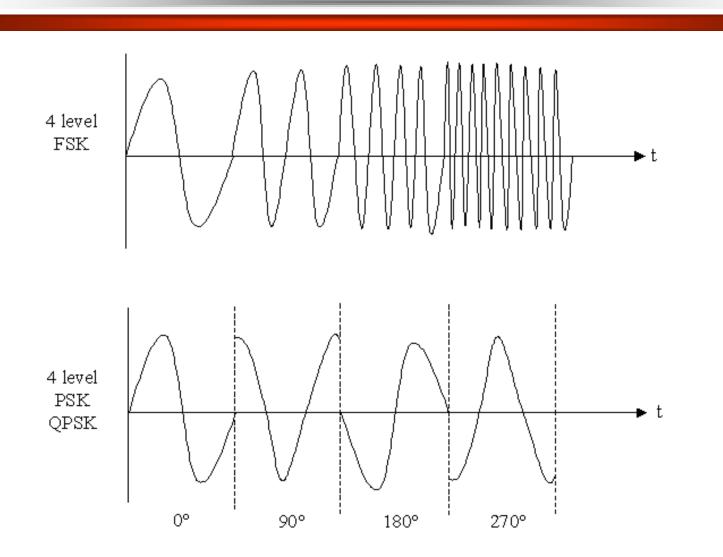
Modulation Types (Binary ASK, FSK, PSK) 2



Modulation Types – 4 Level ASK, FSK, PSK

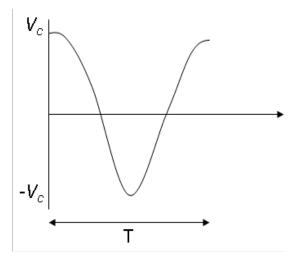


Modulation Types – 4 Level ASK, FSK, PSK 2



Analogue Modulation – Amplitude Modulation

Consider a 'sine wave' carrier.



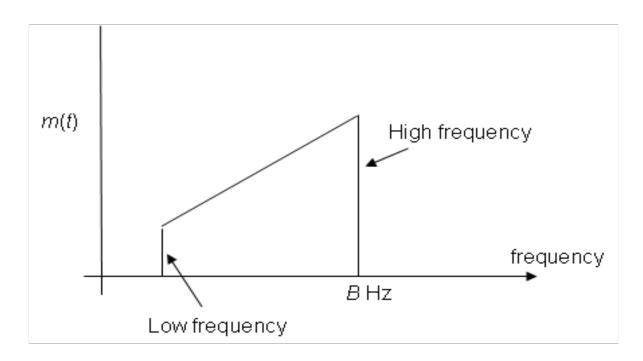
 $v_c(t) = V_c \cos(\omega_c t)$, peak amplitude = V_c , carrier frequency ω_c radians per second. Since $\omega_c = 2\pi f_c$, frequency = f_c Hz where $f_c = 1/T$.

Amplitude Modulation AM

In AM, the modulating signal (the message signal) m(t) is 'impressed' on to the amplitude of the carrier.

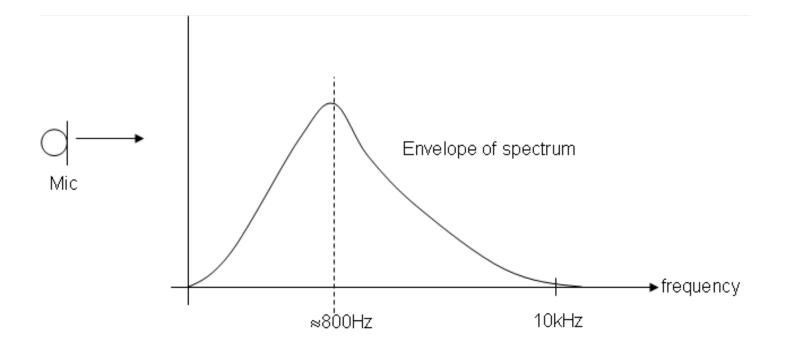
Message Signal m(t)

In general m(t) will be a band of signals, for example speech or video signals. A notation or convention to show baseband signals for m(t) is shown below

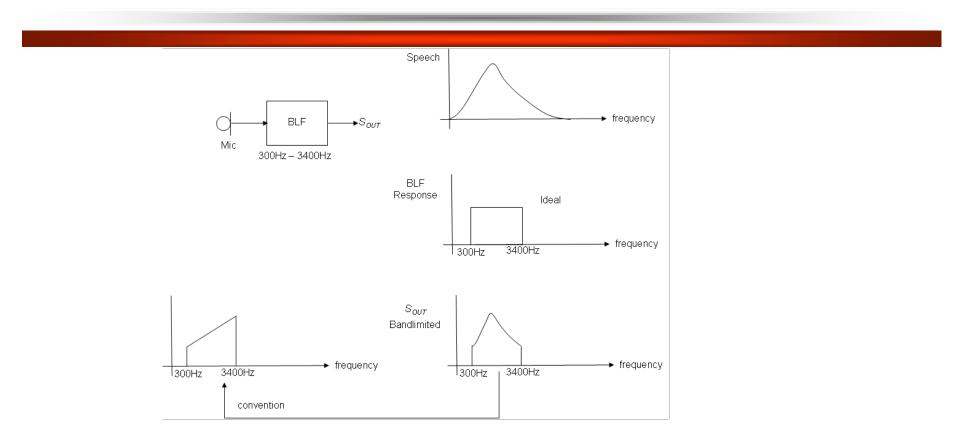


Message Signal m(t)

In general m(t) will be band limited. Consider for example, speech via a microphone. The envelope of the spectrum would be like:



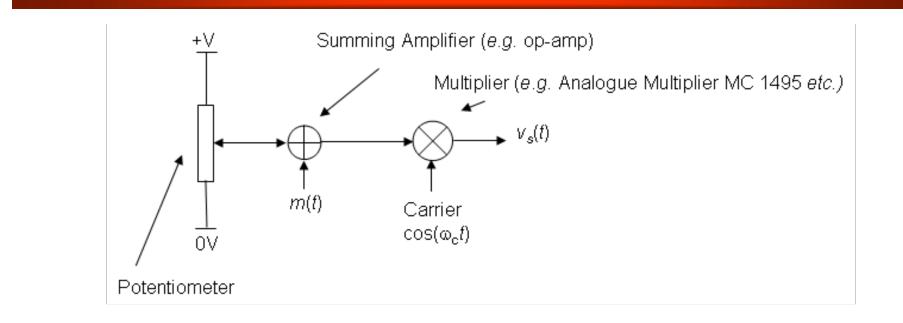
Message Signal m(t)



In order to make the analysis and indeed the testing of AM systems easier, it is common to make m(t) a test signal, *i.e.* a signal with a constant amplitude and frequency given by

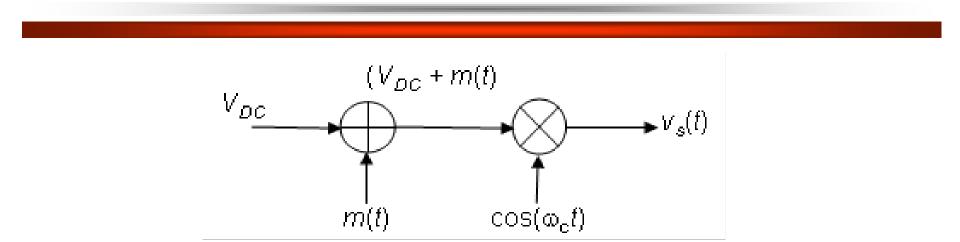
$$m(t) = V_m \cos(\omega_m t)$$

Schematic Diagram for Amplitude Modulation



 V_{DC} is a variable voltage, which can be set between 0 Volts and + V Volts. This schematic diagram is very useful; from this all the important properties of AM and various forms of AM may be derived.

Equations for AM



From the diagram $v_s(t) = (V_{DC} + m(t))\cos(\omega_c t)$ where V_{DC} is the DC voltage that can be varied. The equation is in the form Amp cos $\omega_c t$ and we may 'see' that the amplitude is a function of m(t) and V_{DC} . Expanding the equation we get:

$$\overline{V_s(t)} = V_{DC} \cos(\omega_c t) + m(t) \cos(\omega_c t)$$

Equations for AM

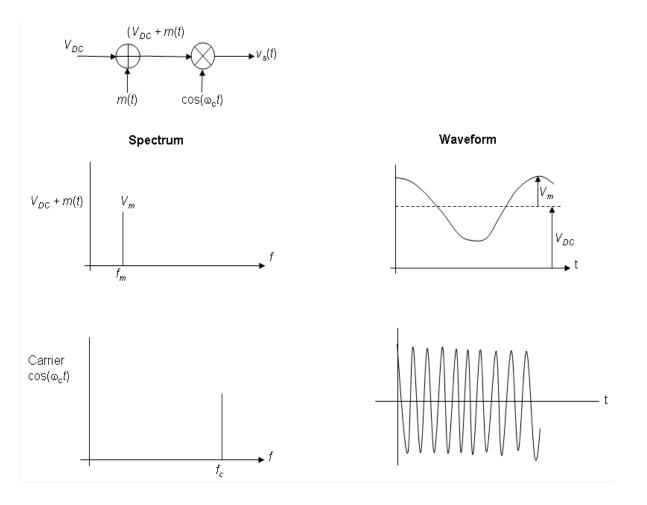
Now let
$$m(t) = V_m \cos \omega_m t$$
, *i.e.* a 'test' signal, $v_s(t) = V_{DC} \cos(\omega_c t) + V_m \cos(\omega_m t) \cos(\omega_c t)$
Using the trig identity $\left[\cos A \cos B = \frac{1}{2} \left[\cos(A + B) + \cos(A - B) \right] \right]$
we have $v_s(t) = V_{DC} \cos(\omega_c t) + \frac{V_m}{2} \cos((\omega_c + \omega_m)t) + \frac{V_m}{2} \cos((\omega_c - \omega_m)t) \right]$

Components:Carrier upper sideband USBIower sideband LSBAmplitude: V_{DC} $V_m/2$ $V_m/2$ Frequency: ω_c $\omega_c + \omega_m$ $\omega_c - \omega_m$ f_c $f_c + f_m$ $f_c + f_m$

This equation represents **Double Amplitude Modulation – DSBAM**

Spectrum and Waveforms

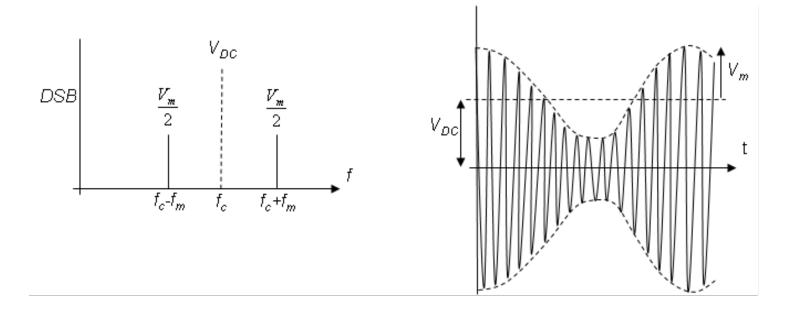
The following diagrams represent the spectrum of the <u>input</u> signals, namely ($V_{DC} + m(t)$), with $m(t) = V_m \cos \omega_m t$, and the carrier $\cos \omega_c t$ and corresponding waveforms.



Spectrum and Waveforms

The above are input signals. The diagram below shows the spectrum and corresponding waveform of the <u>output</u> signal, given by

$$V_{s}(t) = V_{DC}\cos(\omega_{c}t) + \frac{V_{m}}{2}\cos((\omega_{c}+\omega_{m})t) + \frac{V_{m}}{2}\cos((\omega_{c}-\omega_{m})t)$$

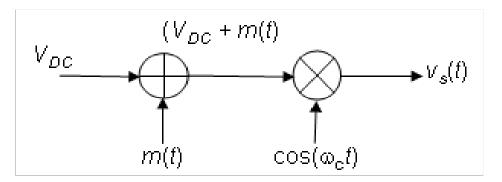


Double Sideband AM, DSBAM

The component at the output at the carrier frequency f_c is shown as a broken line with amplitude V_{DC} to show that the amplitude depends on V_{DC} . The structure of the waveform will now be considered in a little more detail.

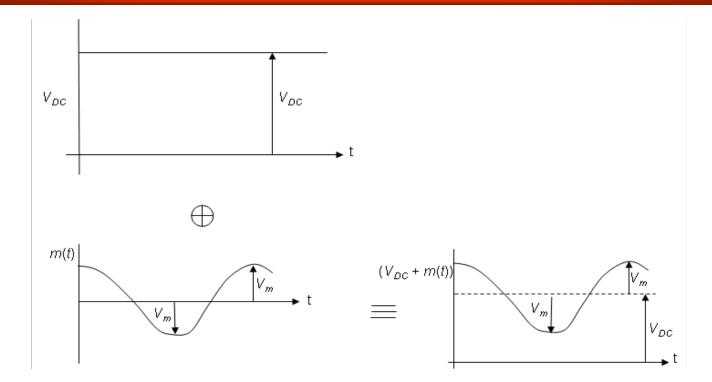
Waveforms

Consider again the diagram



 V_{DC} is a variable DC offset added to the message; $m(t) = V_m \cos \omega_m t$

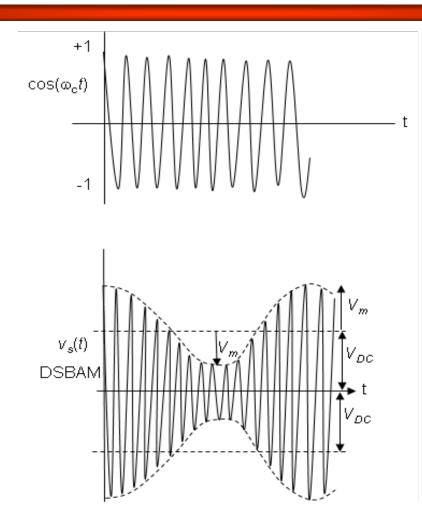
Double Sideband AM, DSBAM



This is multiplied by a carrier, $\cos \omega_c t$. We effectively multiply ($V_{DC} + m(t)$) waveform by +1, -1, +1, -1, ...

The product gives the output signal $V_s(t) = (V_{DC} + m(t)) \cos(\omega_c t)$

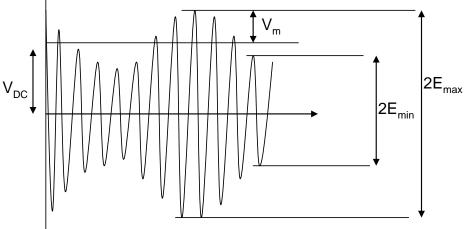
Double Sideband AM, DSBAM



Modulation Depth

Consider again the equation $v_s(t) = (V_{DC} + V_m \cos(\omega_m t))\cos(\omega_c t)$, which may be written as $v_s(t) = V_{DC} \left(1 + \frac{V_m}{V_{DC}}\cos(\omega_m t)\right)\cos(\omega_c t)$ The ratio is $\frac{V_m}{V_{DC}}$ defined as the modulation depth, m, *i.e.* Modulation Depth $m = \frac{V_m}{V_{DC}}$

From an oscilloscope display the modulation depth for Double Sideband AM may be determined as follows:



Modulation Depth 2

 $2E_{max}$ = maximum peak-to-peak of waveform $2E_{min}$ = minimum peak-to-peak of waveform

Modulation Depth $m = \frac{2E_{max} - 2E_{min}}{2E_{max} + 2E_{min}}$ This may be shown to equal $\frac{V_m}{V_{DC}}$ as follows:

$$2E_{max} = 2(V_{DC} + V_m)$$
 $2E_{min} = 2(V_{DC} - V_m)$

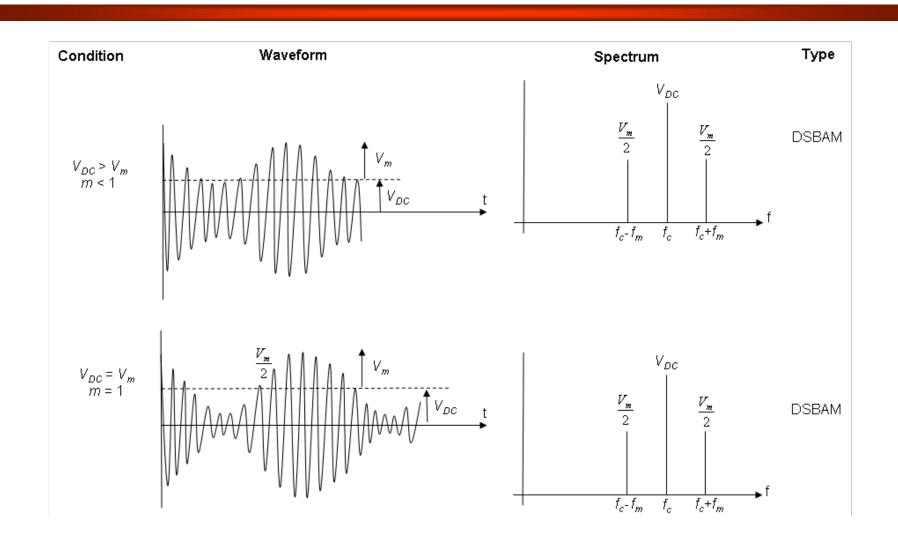
$$m = \frac{2V_{DC} + 2V_m - 2V_{DC} + 2V_m}{2V_{DC} + 2V_m + 2V_{DC} - 2V_m} = \frac{4V_m}{4V_{DC}} = \frac{V_m}{V_{DC}}$$

Double Sideband Modulation 'Types'

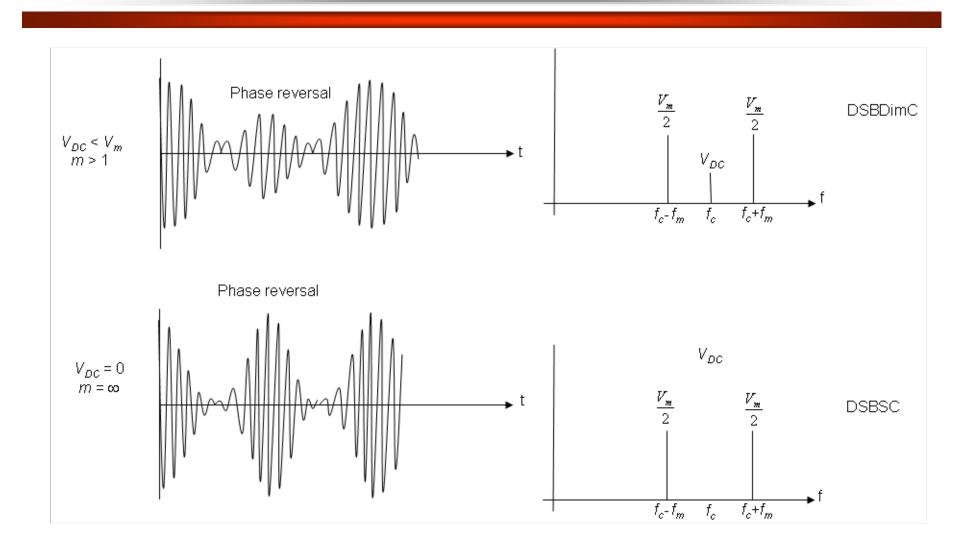
There are 3 main types of DSB

- Double Sideband Amplitude Modulation, DSBAM with carrier
- Double Sideband Diminished (Pilot) Carrier, DSB Dim C
- Double Sideband Suppressed Carrier, DSBSC
- The type of modulation is determined by the modulation depth, which for a fixed m(t) depends on the DC offset, V_{DC} . Note, when a modulator is set up, V_{DC} is fixed at a particular value. In the following illustrations we will have a fixed message, $V_m \cos \omega_m t$ and vary V_{DC} to obtain different types of Double Sideband modulation.

Graphical Representation of Modulation Depth and Modulation Types.



Graphical Representation of Modulation Depth and Modulation Types 2.

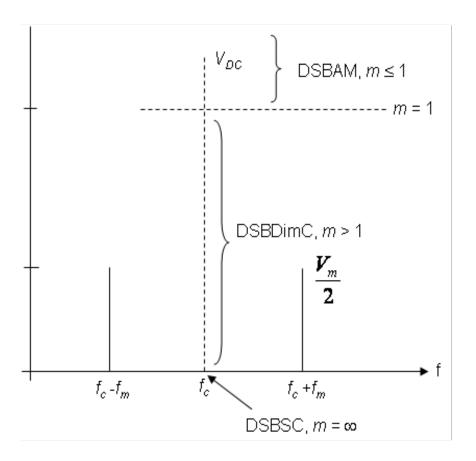


Graphical Representation of Modulation Depth and Modulation Types 3

Note then that V_{DC} may be set to give the modulation depth and modulation type.

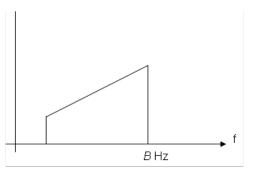
DSBAM $V_{DC} >> V_m, m \le 1$ DSB Dim C $0 < V_{DC} < V_m, m > 1$ ($1 < m < \infty$) DSBSC $V_{DC} = 0, m = \infty$

The spectrum for the 3 main types of amplitude modulation are summarised

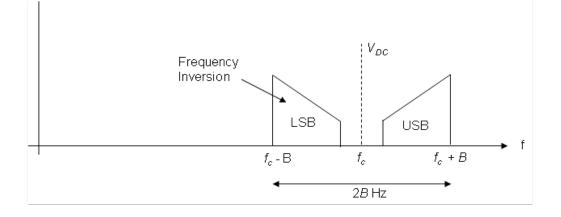


Bandwidth Requirement for DSBAM

In general, the message signal m(t) will not be a single 'sine' wave, but a band of frequencies extending up to B Hz as shown



Remember – the 'shape' is used for convenience to distinguish low frequencies from high frequencies in the baseband signal.



Bandwidth Requirement for DSBAM

Amplitude Modulation is a linear process, hence the principle of superposition applies. The output spectrum may be found by considering each component cosine wave in m(t) separately and summing at the output. Note:

- Frequency inversion of the LSB
- the modulation process has effectively shifted or frequency translated the baseband m(t) message signal to USB and LSB signals centred on the carrier frequency f_c
- the USB is a frequency shifted replica of m(t)
- the LSB is a frequency inverted/shifted replica of m(t)
- both sidebands each contain the same message information, hence either the LSB or USB could be removed (because they both contain the same information)
- the bandwidth of the DSB signal is 2B Hz, *i.e.* twice the highest frequency in the baseband signal, m(t)
- The process of multiplying (or mixing) to give frequency translation (or up-conversion) forms the basis of radio transmitters and frequency division multiplexing which will be discussed later.

Power Considerations in DSBAM

Remembering that Normalised Average Power = $(V_{RMS})^2 = \left(\frac{V_{pk}}{\sqrt{2}}\right)^2$

we may tabulate for AM components as follows:

$$v_s(t) = V_{DC}\cos(\omega_c t) + \frac{V_m}{2}\cos((\omega_c + \omega_m)t) + \frac{V_m}{2}\cos((\omega_c - \omega_m)t)$$

Total Power P_T =

Carrier Power P_c

 $+ P_{USB}$

 $+ P_{LSB}$

Component	Carrier	USB	LSB
Amplitude pk	V _{DC}	$\frac{V_m}{2}$	$\left[\frac{V_m}{2}\right]$
Power	$\frac{V_{DC}^{2}}{2}$	$\left(\frac{V_m}{2\sqrt{2}}\right)^2 = \frac{{V_m}^2}{8}$	$\left(\frac{V_m}{2\sqrt{2}}\right)^2 = \frac{V_m^2}{8}$
Power	$\frac{V_{DC}^{2}}{2}$	$\frac{m^2 V_{DC}^2}{8}$	$\frac{m^2 V_{DC}^2}{8}$

Power Considerations in DSBAM

From this we may write two equivalent equations for the total power P_{T} , in a DSBAM signal

$$P_{T} = \frac{V_{DC}^{2}}{2} + \frac{V_{m}^{2}}{8} + \frac{V_{m}^{2}}{8} = \frac{V_{DC}^{2}}{2} + \frac{V_{m}^{2}}{4} \quad \text{and} \quad P_{T} = \frac{V_{DC}^{2}}{2} + \frac{m^{2}V_{DC}^{2}}{8} + \frac{m^{2}V_{DC}^{2}}{8}$$
The carrier power
$$P_{c} = \frac{V_{DC}^{2}}{2} \quad i.e. \quad P_{T} = P_{c} + P_{c} \frac{m^{2}}{4} + P_{c} \frac{m^{2}}{4} \quad \text{or} \quad P_{T} = P_{c} \left(1 + \frac{m^{2}}{2}\right)$$

Either of these forms may be useful. Since both USB and LSB contain the same information a useful ratio which shows the proportion of 'useful' power to total power is

$$\frac{P_{USB}}{P_T} = \frac{P_c \frac{m^2}{4}}{P_c \left(1 + \frac{m^2}{2}\right)} = \frac{m^2}{4 + 2m^2}$$

Power Considerations in DSBAM

For DSBAM ($m \le 1$), allowing for m(t) with a dynamic range, the average value of m may be assumed to be m = 0.3

Hence,
$$\frac{m^2}{4+2m^2} = \frac{(0.3)^2}{4+2(0.3)^2} = 0.0215$$

Hence, on average only about 2.15% of the total power transmitted may be regarded as 'useful' power. (\approx 95.7% of the total power is in the carrier!)

Even for a maximum modulation depth of m = 1 for DSBAM the ratio

$$\frac{m^2}{4+2m^2} = \frac{1}{6}$$

i.e. only 1/6th of the total power is 'useful' power (with 2/3 of the total power in the carrier).

Example

Suppose you have a <u>portable</u> (for example you carry it in your ' back pack') DSBAM transmitter which needs to transmit an average power of 10 Watts in each sideband when modulation depth m = 0.3. Assume that the transmitter is powered by a 12 Volt battery. The total power will be

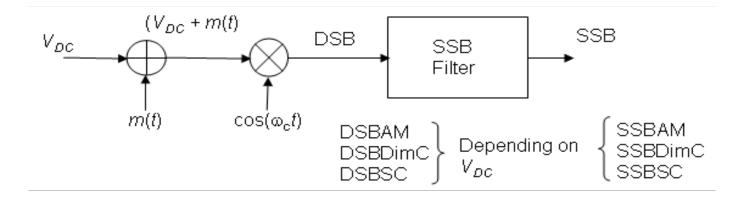
where
$$P_c \frac{m^2}{4} = 10$$
 Watts, *i.e.* $P_c = \frac{4(10)}{m^2} = \frac{40}{(0.3)^2} = 444.44$ Watts

Hence, total power $P_T = 444.44 + 10 + 10 = 464.44$ Watts.

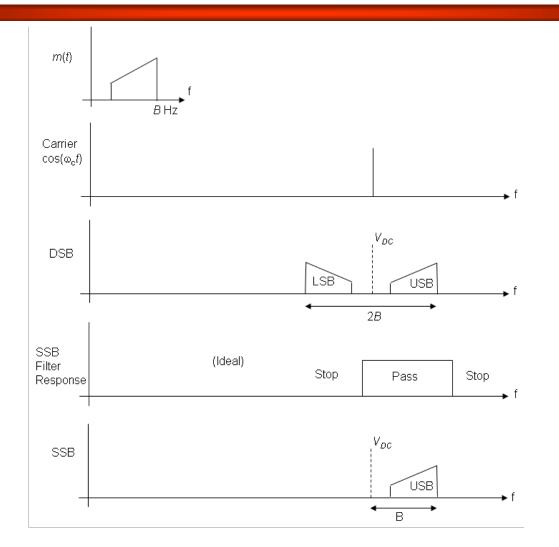
Hence, battery current (assuming ideal transmitter) = Power / Volts = $\frac{464.44}{12}$ amps! *i.e.* a large and heavy 12 Volt battery.

Suppose we could remove one sideband and the carrier, power transmitted would be 10 Watts, *i.e.* 0.833 amps from a 12 Volt battery, which is more reasonable for a portable radio transmitter.

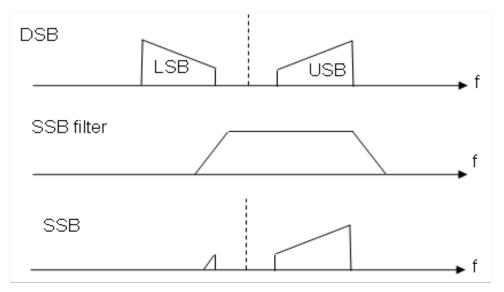
One method to produce signal sideband (SSB) amplitude modulation is to produce DSBAM, and pass the DSBAM signal through a band pass filter, usually called a single sideband filter, which passes one of the sidebands as illustrated in the diagram below.



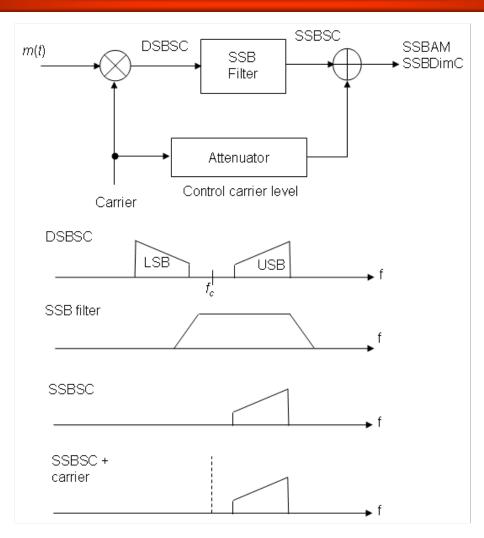
The type of SSB may be SSBAM (with a 'large' carrier component), SSBDimC or SSBSC depending on V_{DC} at the input. A sequence of spectral diagrams are shown on the next page.

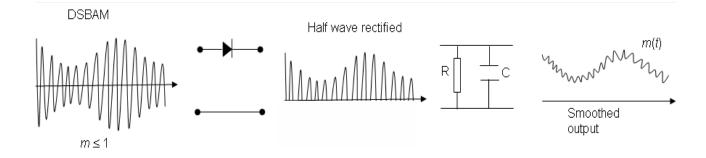


Note that the bandwidth of the SSB signal *B* Hz is half of the DSB signal bandwidth. Note also that an ideal SSB filter response is shown. In practice the filter will not be ideal as illustrated.



As shown, with practical filters some part of the rejected sideband (the LSB in this case) will be present in the SSB signal. A method which eases the problem is to produce SSBSC from DSBSC and then add the carrier to the SSB signal.





with $m(t) = V_m \cos \omega_m t$, we may write:

$$v_s(t) = V_{DC}\cos(\omega_c t) + \frac{V_m}{2}\cos((\omega_c + \omega_m)t) + \frac{V_m}{2}\cos((\omega_c - \omega_m)t)$$

The SSB filter removes the LSB (say) and the output is

$$V_{s}(t) = V_{DC}\cos(\omega_{c}t) + \frac{V_{m}}{2}\cos((\omega_{c} + \omega_{m})t)$$

Again, note that the output may be SSBAM, V_{DC} large SSBDimC, V_{DC} small SSBSC, $V_{DC} = 0$

For SSBSC, output signal =

$$v_s(t) = \frac{V_m}{2} \cos((\omega_c + \omega_m)t)$$

Power in SSB

From previous discussion, the total power in the DSB signal is $\left|P_T = P_c \left(1 + \frac{m^2}{2}\right)\right|$

=
$$P_T = P_c + P_c \frac{m^2}{4} + P_c \frac{m^2}{4}$$
 for DSBAM.

Hence, if P_c and *m* are known, the carrier power and power in one sideband may be determined. Alternatively, since SSB signal =

$$v_{s}(t) = V_{DC}\cos(\omega_{c}t) + \frac{V_{m}}{2}\cos((\omega_{c} + \omega_{m})t)$$

then the power in SSB signal (Normalised Average Power) is

$$P_{SSB} = \frac{V_{DC}^{2}}{2} + \left(\frac{V_{m}}{2\sqrt{2}}\right)^{2} = \frac{V_{DC}^{2}}{2} + \frac{V_{m}^{2}}{8}$$

Power in SSB signal =
$$\frac{V_{DC}^2}{2} + \frac{V_m^2}{8}$$

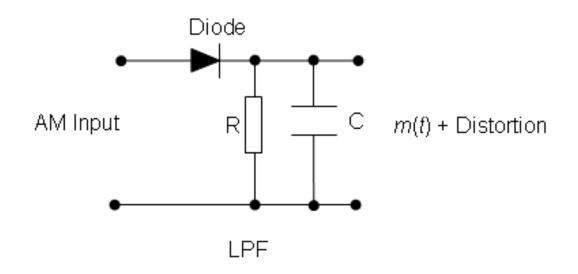
Demodulation of Amplitude Modulated Signals

There are 2 main methods of AM Demodulation:

- Envelope or non-coherent Detection/Demodulation.
- Synchronised or coherent Demodulation.

Envelope or Non-Coherent Detection

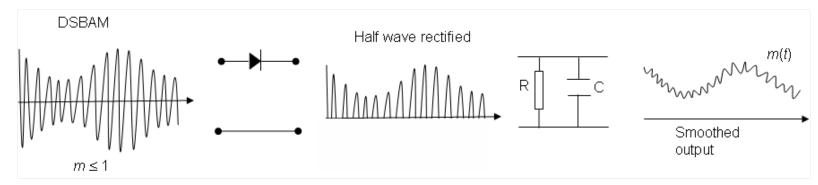
An envelope detector for AM is shown below:



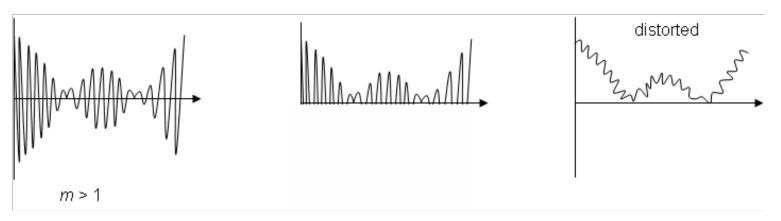
This is obviously simple, low cost. But the AM input <u>must be</u> DSBAM with $m \ll 1$, *i.e.* it does not demodulate DSBDimC, DSBSC or SSBxx.

Large Signal Operation

For large signal inputs, (\approx Volts) the diode is switched *i.e.* forward biased = ON, reverse biased = OFF, and acts as a half wave rectifier. The 'RC' combination acts as a 'smoothing circuit' and the output is m(t) plus 'distortion'.

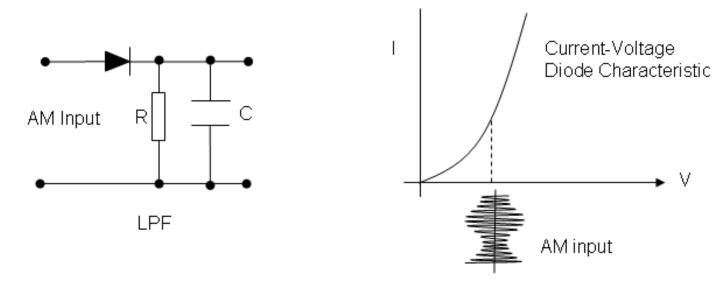


If the modulation depth is > 1, the distortion below occurs



Small Signal Operation – Square Law Detector

For small AM signals (~ millivolts) demodulation depends on the diode square law characteristic.



The diode characteristic is of the form i(t) = av + bv2 + cv3 + ..., where

$$v = (V_{DC} + m(t))\cos(\omega_c t)$$
 i.e. DSBAM signal.

Small Signal Operation – Square Law Detector

i.e.
$$a(V_{DC} + m(t))\cos(\omega_c t) + b((V_{DC} + m(t))\cos(\omega_c t))^2 + ...$$

$$= aV_{DC} + am(t)\cos(\omega_{c}t) + b(V_{DC}^{2} + 2V_{DC}m(t) + m(t)^{2})\cos^{2}(\omega_{c}t) + \dots$$

$$= aV_{DC} + am(t)\cos(\omega_{c}t) + (bV_{DC}^{2} + 2bV_{DC}m(t) + bm(t)^{2}\left(\frac{1}{2} + \frac{1}{2}\cos(2\omega_{c}t)\right)$$

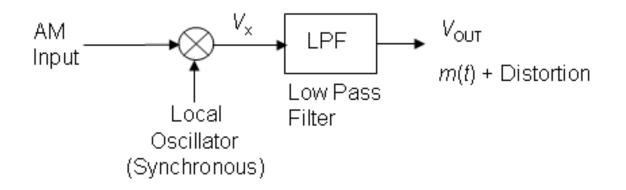
$$= aV_{DC} + am(t)\cos(\omega_{c}t) + \frac{bV_{DC}^{2}}{2} + \frac{2bV_{DC}m(t)}{2} + \frac{bm(t)^{2}}{2} + b\frac{V_{DC}^{2}}{2}\cos(2\omega_{c}t) + \dots$$

'LPF' removes components.

Signal out =
$$aV_{DC} + \frac{bV_{DC}^2}{2} + bV_{DC}m(t)$$
 i.e. the output contains $m(t)$

Synchronous or Coherent Demodulation

A synchronous demodulator is shown below

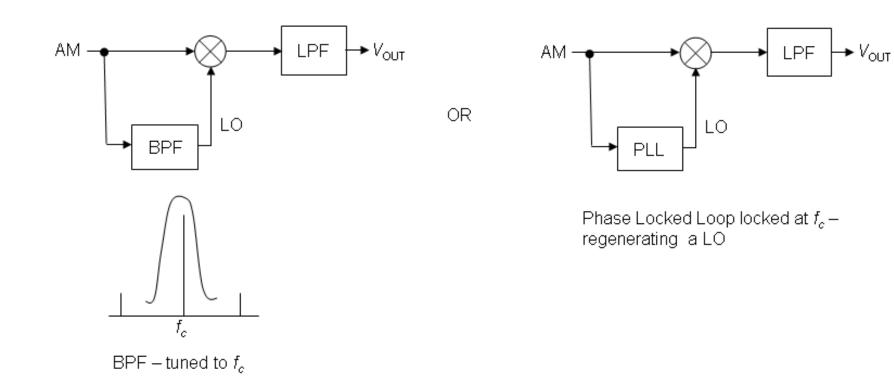


This is relatively more complex and more expensive. The Local Oscillator (LO) must be synchronised or coherent, *i.e.* at the same frequency and in phase with the carrier in the AM input signal. This additional requirement adds to the complexity and the cost.

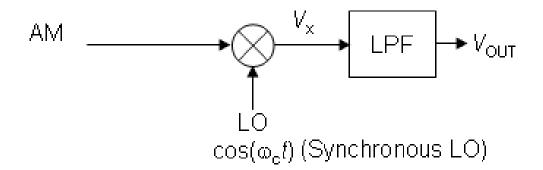
However, the AM input may be <u>any</u> form of AM, *i.e.* DSBAM, DSBDimC, DSBSC or SSBAM, SSBDimC, SSBSC. (Note – this is a 'universal' AM demodulator and the process is similar to correlation – the LPF is similar to an integrator).

Synchronous or Coherent Demodulation

If the AM input contains a small or large component at the carrier frequency, the LO may be derived from the AM input as shown below.



If we assume zero path delay between the modulator and demodulator, then the ideal LO signal is $\cos(\omega_c t)$. Note – in general the will be a path delay, say τ , and the LO would then be $\cos(\omega_c(t - \tau))$, *i.e.* the LO is synchronous with the carrier implicit in the received signal. Hence for an ideal system with zero path delay



Analysing this for a DSBAM input = $(V_{DC} + m(t))\cos(\omega_c t)$

$$V_{\chi}$$
 = AM input x LO

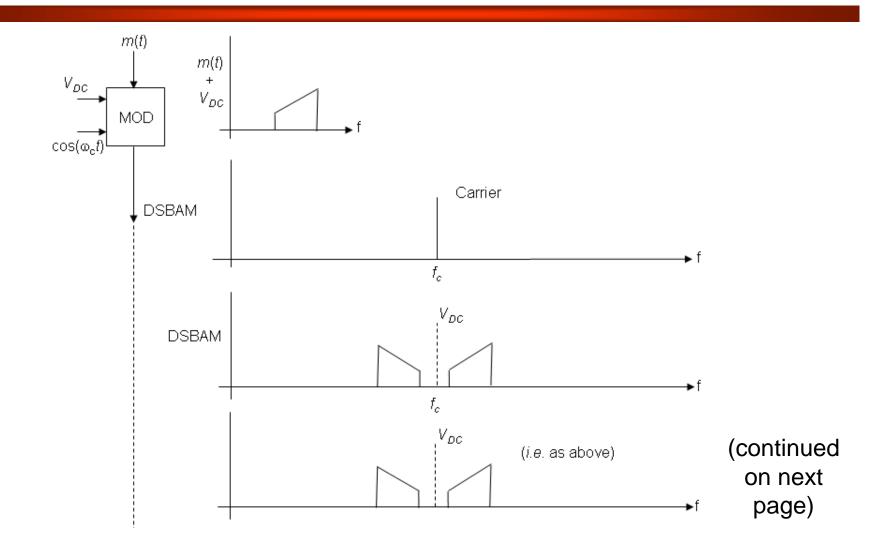
$$= (V_{DC} + m(t))\cos^2(\omega_c t)$$

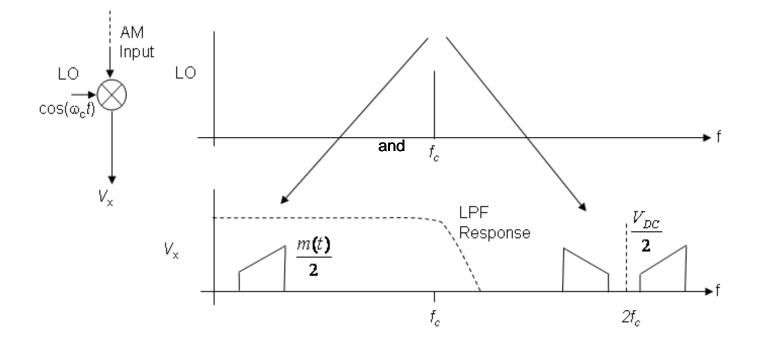
$$= \overline{\left(V_{DC} + m(t)\right)\cos(\omega_{c}t) * \cos(\omega_{c}t)}$$

$$= \overline{\left(V_{DC} + m(t)\right)\left(\frac{1}{2} + \frac{1}{2}\cos(2\omega_{c}t)\right)}$$

$$\overline{V_{x} = \frac{V_{DC}}{2} + \frac{V_{DC}}{2}\cos(2\omega_{c}t) + \frac{m(t)}{2} + \frac{m(t)}{2}\cos(2\omega_{c}t)}$$

We will now examine the signal spectra from 'modulator to $V_{x'}$





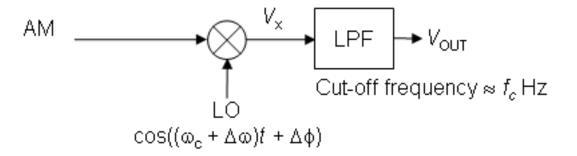
Note – the AM input has been 'split into two' – 'half' has moved or shifted up to

 $\left[2f_c\left(\frac{m(t)}{2}\cos(2\omega_c t)+V_{DC}\cos(2\omega_c t)
ight)
ight]$ and half shifted down to baseband, $\left|\frac{V_{DC}}{2}
ight|$ and $\left|\frac{m(t)}{2}
ight|$

The LPF with a cut-off frequency $\approx f_c$ will pass only the baseband signal i.e.

$$V_{out} = \frac{V_{DC}}{2} + \frac{m(t)}{2}$$

In general the LO may have a frequency offset, $\Delta \omega$, and/or a phase offset, $\Delta \phi$, i.e.



The AM input is essentially either:

- DSB (DSBAM, DSBDimC, DSBSC)
- SSB (SSBAM, SSBDimC, SSBSC)

The equation for DSB is $(V_{DC} + m(t))\cos(\omega_c t)$ where VDC allows full carrier (DSBAM), diminished carrier or suppressed carrier to be set.

Hence, Vx = AM Input x LO
$$V_x = (V_{DC} + m(t))\cos(\omega_c t).\cos((\omega_c + \Delta \omega)t + \Delta \varphi)$$

Since $\cos A\cos B = \frac{1}{2}[\cos(A+B) + \cos(A-B)]$

$$V_{x} = \frac{(V_{DC} + m(t))}{2} \left[\cos((\omega_{c} + \omega_{c} + \Delta\omega)t + \Delta\varphi) + \cos((\omega_{c} + \Delta\omega)t + \Delta\varphi - \omega_{c}t) \right]$$
$$V_{x} = \left(\frac{V_{DC}}{2} + \frac{m(t)}{2}\right) \left[\cos((2\omega_{c} + \Delta\omega)t + \Delta\varphi) + \cos(\Delta\omega t + \Delta\varphi) \right]$$

$$\begin{aligned} \overline{V_x} &= \frac{V_{DC}}{2} \cos((2\omega_c + \Delta\omega)t + \Delta\varphi) + \frac{V_{DC}}{2} \cos(\Delta\omega t + \Delta\varphi) \\ &+ \frac{m(t)}{2} \cos((2\omega_c + \Delta\omega)t + \Delta\varphi) + \frac{m(t)}{2} \cos(\Delta\omega t + \Delta\varphi) \end{aligned}$$

The LPF with a cut-off frequency $\approx f_c$ Hz will remove the components at $2\omega_c$ (i.e. components above ω_c) and hence

$$V_{out} = \frac{V_{DC}}{2} \cos(\Delta \omega t + \Delta \varphi) + \frac{m(t)}{2} \cos(\Delta \omega t + \Delta \varphi)$$

Obviously, if $\Delta \omega = 0$ and $\Delta \varphi = 0$ we have, as previously $V_{out} = \frac{V_{DC}}{2} + \frac{m(t)}{2}$
Consider now if $\Delta \omega$ is equivalent to a few Hz offset from the ideal LO. We may then say

$$V_{out} = \frac{V_{DC}}{2} \cos(\Delta \omega t) + \frac{m(t)}{2} \cos(\Delta \omega t)$$

The output, if speech and processed by the human brain may be intelligible, but would include a low frequency 'buzz' at $\Delta \omega$, and the message amplitude would fluctuate. The requirement $\Delta \omega = 0$ is necessary for DSBAM.

Consider now if $\Delta \omega$ is equivalent to a few Hz offset from the ideal LO. We may then say

$$V_{out} = \frac{V_{DC}}{2} \cos(\Delta \omega t) + \frac{m(t)}{2} \cos(\Delta \omega t)$$

The output, if speech and processed by the human brain may be intelligible, but would include a low frequency 'buzz' at $\Delta \omega$, and the message amplitude would fluctuate. The requirement $\Delta \omega = 0$ is necessary for DSBAM.

Consider now that $\Delta \omega = 0$ but $\Delta \phi \neq 0$, i.e. the frequency is correct at ω_c but there is a phase offset. Now we have

$$\overline{V_{out}} = \frac{V_{DC}}{2} \cos(\varDelta \varphi) + \frac{m(t)}{2} \cos(\varDelta \varphi)$$

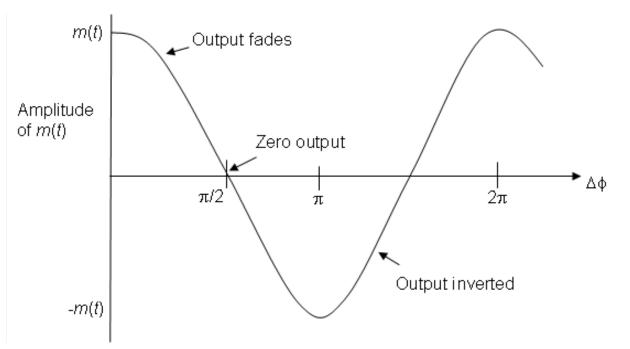
 $\cos(\Delta \phi)$ causes fading (i.e. amplitude reduction) of the output.

The 'V_{DC}' component is not important, but consider for m(t),

• if
$$\Delta \varphi = \frac{\pi}{2}$$
 (90°), $\cos\left(\frac{\pi}{2}\right) = 0$ i.e. $V_{out} = \frac{m(t)}{2}\cos\left(\frac{\pi}{2}\right) = 0$
• if $\Delta \varphi = \frac{\pi}{2}$ (180°), $\cos(\pi) = -1$ i.e. $V_{out} = \frac{m(t)}{2}\cos(\pi) = -m(t)$

The phase inversion if $\Delta \phi = \pi$ may not be a problem for speech or music, but it may be a problem if this type of modulator is used to demodulate PRK However, the major problem is that as $\Delta \phi$ increases towards $\frac{\pi}{2}$ the signal strength output gets weaker (fades) and at $\frac{\pi}{2}$ the output is zero

If the phase offset varies with time, then the signal fades in and out. The variation of amplitude of the output, with phase offset $\Delta \phi$ is illustrated below



Thus the requirement for $\Delta \omega = 0$ and $\Delta \phi = 0$ is a 'strong' requirement for DSB amplitude modulation.

The equation for SSB with a carrier depending on V_{DC} is

$$V_{DC}\cos(\omega_c t) + \frac{V_m}{2}\cos(\omega_c + \omega_m t)$$

i.e. assuming $m(t) = V_m \cos(\omega_m t)$

Hence

$$V_{x} = \left(V_{DC}\cos(\omega_{c}t) + \frac{V_{m}}{2}\cos(\omega_{c} + \omega_{m})t\right)\cos((\omega_{c} + \Delta\omega)t + \Delta\varphi)$$

$$= \frac{V_{DC}}{2}\cos((2\omega_{c} + \Delta\omega)t + \Delta\varphi) + \frac{V_{DC}}{2}\cos(\Delta\omega t + \Delta\varphi)$$
$$+ \frac{V_{m}}{4}\cos((2\omega_{c} + \omega_{m} + \Delta\omega)t + \Delta\varphi) + \frac{V_{m}}{4}\cos((\omega_{m} - \Delta\omega)t - \Delta\varphi)$$

The LPF removes the $2\omega_c$ components and hence

$$\frac{V_{DC}}{2}\cos(\varDelta\omega t + \varDelta\varphi) + \frac{V_m}{4}\cos((\omega_m - \varDelta\omega)t - \varDelta\varphi)$$

Note, if
$$\Delta \omega = 0$$
 and $\Delta \phi = 0$, $\frac{V_{DC}}{2} + \frac{V_m}{4} \cos(\omega_m t)$, i.e. $\overline{m(t) = V_m \cos(\omega_m t)}$ has been

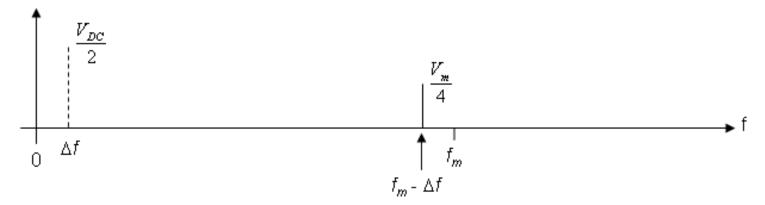
recovered.

Consider first that $\Delta \omega \neq 0$, e.g. an offset of say 50Hz. Then

$$V_{out} = \frac{V_{DC}}{2} \cos(\Delta \omega t) + \frac{V_m}{4} \cos((\omega_m - \Delta \omega)t)$$

If m(t) is a signal at say 1kHz, the output contains a signal a 50Hz, depending on V_{DC} and the 1kHz signal is shifted to 1000Hz - 50Hz = 950Hz.

The spectrum for V_{out} with $\Delta \omega$ offset is shown



Hence, the effect of the offset $\Delta \omega$ is to shift the baseband output, up or down, by $\Delta \phi$. For speech, this shift is not serious (for example if we receive a 'whistle' at 1kHz and the offset is 50Hz, you hear the whistle at 950Hz ($\Delta \omega = +ve$) which is not very noticeable. Hence, small frequency offsets in SSB for speech may be tolerated. Consider now that $\Delta \omega = 0$, $\Delta \phi = 0$, then

$$V_{out} = \frac{V_{DC}}{2} \cos(\Delta \varphi) + \frac{V_m}{4} \cos(\omega_m t - \Delta \varphi)$$

- This indicates a fading V_{DC} and a phase shift in the output. If the variation in Δφ with time is relatively slow, thus phase shift variation of the output is not serious for speech.
- Hence, for SSB small frequency and phase variations in the LO are tolerable. The requirement for a coherent LO is not as a stringent as for DSB. For this reason, SSBSC (suppressed carrier) is widely used since the receiver is relatively more simple than for DSB and power and bandwidth requirements are reduced.

Comments

- In terms of 'evolution', early radio schemes and radio on long wave (LW) and medium wave (MW) to this day use DSBAM with *m* < 1. The reason for this was the reduced complexity and cost of 'millions' of receivers compared to the extra cost and power requirements of a few large LW/MW transmitters for broadcast radio, *i.e.* simple envelope detectors only are required.
- Nowadays, with modern integrated circuits, the cost and complexity of synchronous demodulators is much reduced especially compared to the additional features such as synthesised LO, display, FM *etc.* available in modern receivers.

Amplitude Modulation forms the basis for:

- Digital Modulation Amplitude Shift Keying ASK
- Digital Modulation Phase Reversal Keying PRK
- Multiplexing Frequency Division Multiplexing FDM
- Up conversion Radio transmitters
- Down conversion Radio receivers



Chapter Three: Amplitude Modulation

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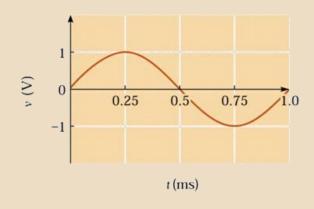


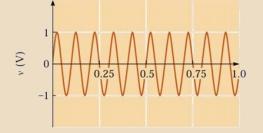
Introduction

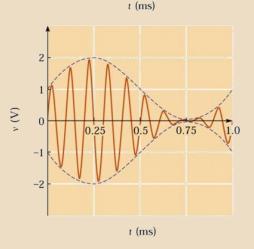
- Amplitude Modulation is the simplest and earliest form of transmitters
- AM applications include broadcasting in medium- and high-frequency applications, CB radio, and aircraft communications

Basic Amplitude Modulation

• The information signal varies the instantaneous amplitude of the carrier









AM Characteristics

- AM is a nonlinear process
- Sum and difference frequencies are created that carry the information

Full-Carrier AM: Time Domain

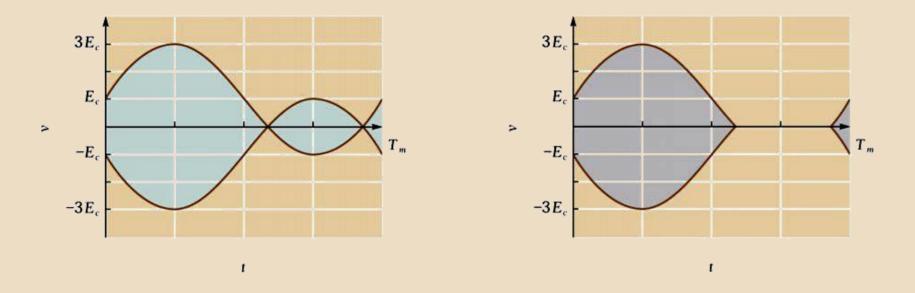
• Modulation Index - The ratio between the amplitudes between the amplitudes of the modulating signal and carrier, expressed by the equation:

$$m = \frac{E_m}{E_c}$$



Overmodulation

• When the modulation index is greater than 1, **overmodulation** is present





Modulation Index for Multiple Modulating Frequencies

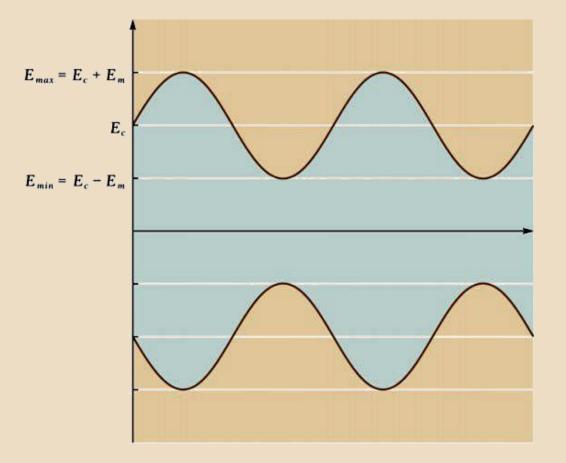
• Two or more sine waves of different, uncorrelated frequencies modulating a single carrier is calculated by the equation:

$$m = \sqrt{m_1^2 + m_2^2 + \bullet \bullet \bullet}$$

2



Measurement of Modulation Index





Full-Carrier AM: Frequency Domain

- Time domain information can be obtained using an oscilloscope
- Frequency domain information can be calculated using *Fourier* methods, but trigonometric methods are simpler and valid
- Sidebands are calculated using the formulas at the right

$$f_{usb} = f_c + f_m$$

$$f_c - f_c - f_c$$

$$f_{lsb} = f_c - f_m$$

$$E_{lsb} = E_{usb} = \frac{mE_c}{2}$$



Bandwidth

- Signal bandwidth is an important characteristic of any modulation scheme
- In general, a narrow bandwidth is desirable
- Bandwidth is calculated by:

$$B = 2F_m$$



Power Relationships

- Power in a transmitter is important, but the most important power measurement is that of the portion that transmits the information
- AM carriers remain unchanged with modulation and therefore are wasteful
- Power in an AM transmitter is calculated according to the formula at the right

 $P_t = P_c \left(1 + \frac{m^2}{2} \right)$

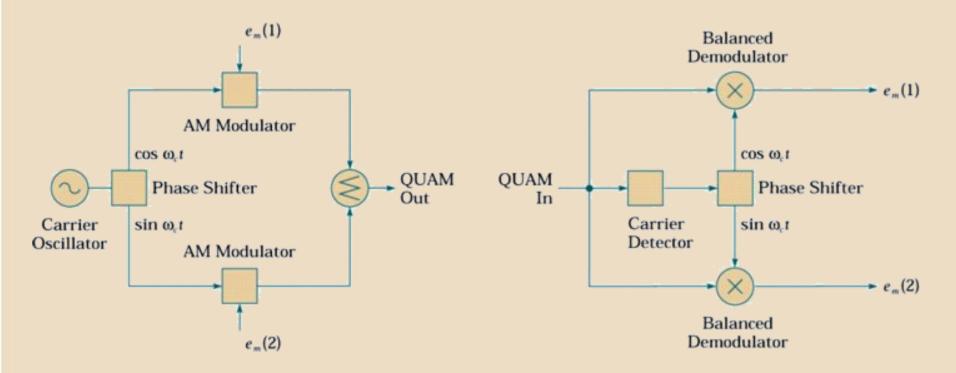


Quadrature AM and AM Stereo

- Two carriers generated at the same frequency but 90° out of phase with each other allow transmission of two separate signals
- This approach is known as Quadrature AM (QUAM or QAM)
- Recovery of the two signals is accomplished by *synchronous detection* by two balanced modulators



Quadrature Operation

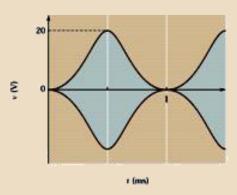


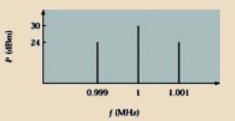
Suppressed-Carrier AM

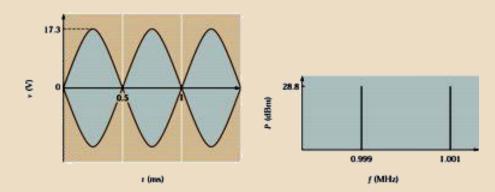
- Full-carrier AM is simple but not efficient
- Removing the carrier before power amplification allows full transmitter power to be applied to the sidebands
- Removing the carrier from a fully modulated AM systems results in a double-sideband suppressed-carrier transmission



Suppressed-Carrier Signal





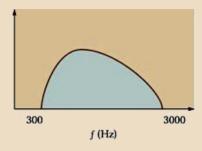




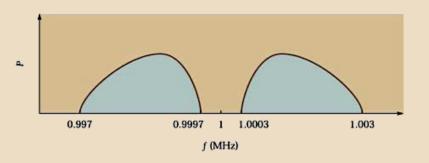
Single-Sideband AM

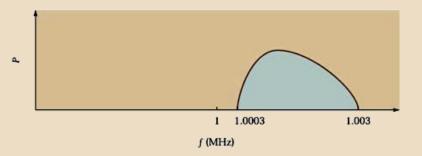
- The two sidebands of an AM signal are mirror images of one another
- As a result, one of the sidebands is redundant
- Using *single-sideband suppressed-carrier* transmission results in reduced bandwidth and therefore twice as many signals may be transmitted in the same spectrum allotment
- Typically, a 3dB improvement in signal-to-noise ratio is achieved as a result of SSBSC

DSBSC and SSB Transmission



۵.







Power in Suppressed-Carrier Signals

- Carrier power is useless as a measure of power in a DSBSC or SSBSC signal
- Instead, the **peak envelope power** is used
- The peak power envelope is simply the power at modulation peaks, calculated thus:

$$PEP = \frac{V_p^2}{2RL}$$





Part 1Introduction

Introduction

Angle modulation is the process by which the angle (frequency or phase) of the carrier signal is changed in accordance with the instantaneous amplitude of modulating or message signal.

Cont'd...

classified into two types such as

- Frequency modulation (FM)
- Phase modulation (PM)

Used for :

- Commercial radio broadcasting
- Television sound transmission
- Two way mobile radio
- Cellular radio
- Microwave and satellite communication system

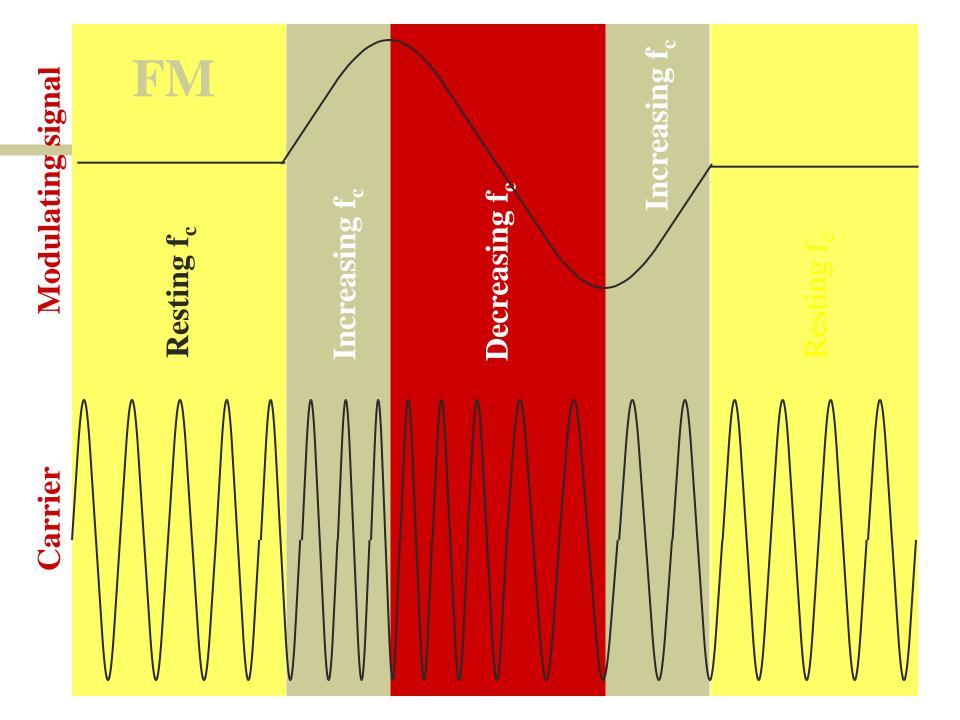
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Advantages over AM:

- Freedom from interference: all natural and external noise consist of amplitude variations, thus receiver usually cannot distinguish between amplitude of noise or desired signal. AM is noisy than FM.
- Operate in very high frequency band (VHF): 88MHz-108MHz
- Can transmit musical programs with higher degree of fidelity.

FREQUENCY MODULATION PRINCIPLES

- In FM the carrier amplitude remains constant, the carrier frequency varies with the amplitude of modulating signal.
- The amount of change in carrier frequency produced by the modulating signal is known as *frequency deviation.*



PHASE MODULATION(PM)

- The process by which changing the phase of carrier signal in accordance with the instantaneous of message signal. The amplitude remains constant after the modulation process.
- Mathematical analysis:

Let message signal:

$$V_m(t) = V_m \cos \varpi_m t$$

And carrier signal: $v_c(t) = V_c \cos[\varpi_c t + \theta]$

PM (cont'd)

• Where θ = phase angle of carrier signal. It is changed in accordance with the amplitude of the message signal;

i.e.
$$\theta = KV_m(t) = KV_m \cos \omega_m t$$

- After phase modulation the instantaneous voltage will be $v_{pm}(t) = V_C \cos(\omega_C t + KV_m \cos \omega_m t)$ or $v_{pm}(t) = V_C \cos(\omega_C t + m_p \cos \omega_m t)$
- Where m_p = Modulation index of phase modulation
- K is a constant and called deviation sensitivities of the phase

FREQUENCY MODULATION (FM)

- A process where the frequency of the carrier wave varies with the magnitude variations of the modulating or audio signal.
- The amplitude of the carrier wave is kept constant.

- Mathematical analysis:
- Let message signal:

$$v_m(t) = V_m \cos \varpi_m t$$

• And carrier signal: $v_c(t) = V_c \cos[\varpi_c t + \theta]$

During the process of frequency modulations the frequency of carrier signal is changed in accordance with the instantaneous amplitude of message signal .Therefore the frequency of carrier after modulation is written as

$$\omega_{i} = \omega_{c} + K_{1} v_{m}(t) = \omega_{C} + K_{1} V_{m} \cos \omega_{m} t$$

To find the instantaneous phase angle of modulated signal, integrate equation above w.r.t. t

$$\phi_{i} = \int \omega_{i} dt = \int \left(\omega_{C} + K_{1} V_{m} \cos \omega_{m} t \right) dt = \omega_{C} t + \frac{K_{1} V_{m}}{\omega_{m}} \sin \omega_{m} t$$

Thus, we get the FM wave as: $v_{FM}(t) = Vc \cos \phi_1 = V_C \cos(\omega_C t + \frac{K_1 V_m}{\omega_m} \sin \omega_m t)$

$$v_{FM}(t) = V_C \cos(\omega_C t + m_f \sin \omega_m t)$$

Where modulation index for FM is given by

$$\mathbf{m}_{\mathrm{f}} = \frac{\mathbf{K}_{1}\mathbf{V}_{\mathrm{m}}}{\boldsymbol{\omega}_{\mathrm{m}}}$$

Frequency deviation: ∆f is the relative placement of carrier frequency (Hz) w.r.t its unmodulated value. Given as:

$$\omega_{\text{max}} = \omega_{\text{C}} + K_{1}V_{\text{m}}$$
$$\omega_{\text{min}} = \omega_{\text{C}} - K_{1}V_{\text{m}}$$
$$\omega_{\text{d}} = \omega_{\text{max}} - \omega_{\text{C}} = \omega_{\text{C}} - \omega_{\text{min}} = K_{1}V_{\text{m}}$$

$$\Delta f = \frac{\omega_d}{2\pi} = \frac{K_1 V_m}{2\pi}$$

Therefore:

$$\Delta f = \frac{K_1 V_m}{2\pi};$$
$$m_f = \frac{\Delta f}{f_m}$$

Type of Modulation	Modulating Signal	Angle-Modulated Wave, m(t)
(a) Phase	$v_m(t)$	$V_c \cos[\omega_c t + K v_{\eta \eta}(t)]$
(b) Frequency	$v_m(t)$	$V_c \cos[\omega_c t + K_1] v_m(t) dt]$
(c) Phase	$V_m \cos(\omega_m t)$	$V_c \cos[\omega_c t + KV_m \cos(\omega_m t)]$
(d) Frequency	$V_m \cos(\omega_m t)$	$V_c \cos \left[\omega_c t + \frac{K_1 V_m}{\omega_m} \sin(\omega_m t) \right]$

Example (FM)

Determine the peak frequency deviation (∆f) and modulation index (m) for an FM modulator with a deviation sensitivity K₁ = 5 kHz/V and a modulating signal,

$$\mathbf{v}_{\mathrm{m}}(t) = 2\cos(2\pi 2000t)$$

Example (PM)

Determine the peak phase deviation (m) for a PM modulator with a deviation sensitivity K = 2.5 rad/V and a modulating signal, $v_m(t) = 2\cos(2\pi 2000t)$

FM&PM (Bessel function)

Thus, for general equation: $v_{FM}(t) = V_C \cos(\omega_C t + m_f \cos \omega_m t)$

$$\cos(\alpha + m\cos\beta) = \sum_{n=-\infty}^{\infty} J_n(m)\cos\left(\alpha + n\beta + \frac{n\pi}{2}\right)$$

$$m(t) = V_{C} \sum_{n=-\infty}^{\infty} J_{n}(m) \cos\left(\omega_{c} t + n\omega_{m} t + \frac{n\pi}{2}\right)$$

Bessel function

$$v(t)_{FM} = V_{C} \{J_{0}(m_{f})\cos\omega_{C}t + J_{1}(m_{f})\cos\left[(\omega_{C} + \omega_{m})t + \frac{\pi}{2}\right] - J_{1}(m_{f})\cos\left[(\omega_{C} - \omega_{m})t - \frac{\pi}{2}\right]$$

+
$$J_2(m_f) \cos[(\omega_c + 2\omega_m)t] + J_2(m_f) \cos[(\omega_c - 2\omega_m)t] + ... J_n(m_f)... \}$$

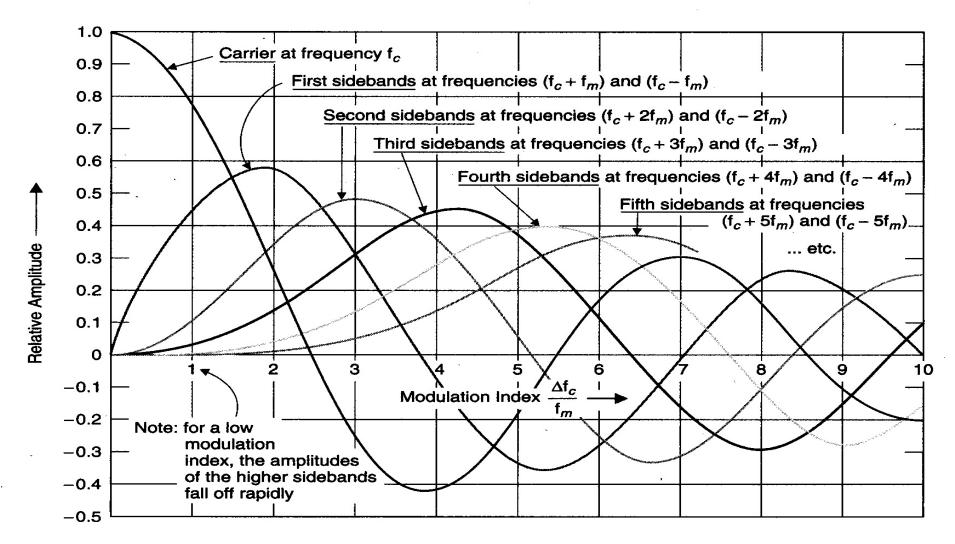
B.F. (cont'd)

It is seen that each pair of side band is preceded by J coefficients. The order of the coefficient is denoted by subscript m. The Bessel function can be written as

$$J_n(m_f) = \left(\frac{m_f}{2}\right)^n \left[\frac{1}{n} - \frac{(m_f/2)^2}{1!(n+1)!} + \frac{(m_f/2)^4}{2!(n+2)!} - \dots\right]$$

- N = number of the side frequency
- M_f = modulation index

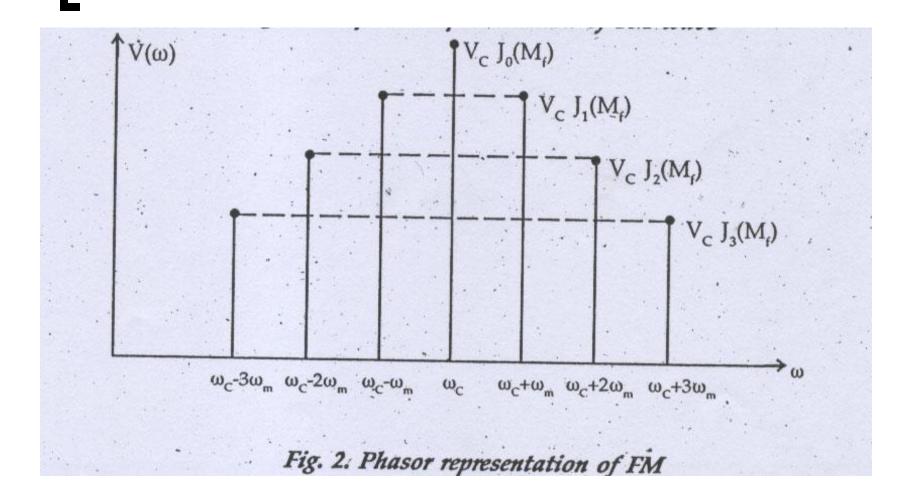
B.F. (cont'd)



Bessel Functions of the First Kind, J_n(m) for some value of modulation index

Modulation Index <i>m</i>	Carrier		Side Frequency Pairs												
	<i>J</i> ₀	<i>J</i> ₁	<i>J</i> ₂	J ₃	<i>J</i> ₄	J ₅	J ₆	J7	<i>J</i> ₈	J_9	J ₁₀	J ₁₁	J ₁₂	J ₁₃	J ₁₄
0.00	1.00	_	_			_	_			_	<u></u>	-		_	2
0.25	0.98	0.12	—	-	7770	_	-	1111	-	-	_		-		-
0.5	0.94	0.24	0.03		-		_		-	_		-	-	—	-
1.0	0.77	0.44	0.11	0.02	_	_	_					_	<u></u>	_	_
1.5	0.51	0.56	0.23	0.06	0.01	_	—		-	—	-	-	—	_	-
2.0	0.22	0.58	0.35	0.13	0.03	—	—		—	—		—	-	-	-
2.4	0	0.52	0.43	0.20	0.06	0.02	—		—	—		—	—	—	-
2.5	-0.05	0.50	0.45	0.22	0.07	0.02	0.01		—	-		-	\rightarrow	\rightarrow	27
3.0	-0.26	0.34	0.49	0.31	0.13	0.04	0.01		-	—		—	_	_	2
4.0	-0.40	-0.07	0.36	0.43	0.28	0.13	0.05	0.02		—	1000		0.000	_	17
5.0	-0.18	-0.33	0.05	0.36	0.39	0.26	0.13	0.05	0.02	—		—	—	—	-
5.45	0	-0.34	-0.12	0.26	0.40	0.32	0.19	0.09	0.03	0.01		_		_	24
6.0	0.15	-0.28	-0.24	0.11	0.36	0.36	0.25	0.13	0.06	0.02		—	—	_	27
7.0	0.30	0.00	-0.30	-0.17	0.16	0.35	0.34	0.23	0.13	0.06	0.02	—	—	—	-
8.0	0.17	0.23	-0.11	-0.29	-0.10	0.19	0.34	0.32	0.22	0.13	0.06	0.03	_		2
8.65	0	0.27	0.06	-0.24	-0.23	0.03	0.26	0.34	0.28	0.18	0.10	0.05	0.02	_	3
9.0	-0.09	0.25	0.14	-0.18	-0.27	-0.06	0.20	0.33	0.31	0.21	0.12	0.06	0.03	0.01	4
10.0	-0.25	0.05	0.25	0.06	-0.22	-0.23	-0.01	0.22	0.32	0.29	0.21	0.12	0.06	0.03	0.0

Representation of frequency spectrum



Example

For an FM modulator with a modulation index m = 1, a modulating signal $v_m(t) = V_m sin(2\pi 1000t)$, and an unmodulated carrier $v_{c}(t)$ $10sin(2\pi 500kt)$. Determine the number of sets of significant side frequencies and their amplitudes. Then, draw the frequency spectrum showing their relative amplitudes.

Angle Modulation Part 2

FM Bandwidth
Power distribution of FM
Generation & Detection of FM
Application of FM

FM Bandwidth

- Theoretically, the generation and transmission of FM requires infinite bandwidth. Practically, FM system have finite bandwidth and they perform well.
- The value of modulation index determine the number of sidebands that have the significant relative amplitudes
- If n is the number of sideband pairs, and line of frequency spectrum are spaced by fm, thus, the bandwidth is:

$$B_{fm} = 2nf_m$$

■ For n≥1

FM Bandwidth (cont'd)

- Estimation of transmission b/w;
- Assume m_f is large and n is approximate m_f + 2; thus

•
$$B_{fm}=2(m_f + 2)f_m$$

$$= 2(\frac{\Delta f}{f_m} + 2)f_m$$

$$B_{fm} = 2(\Delta f + f_m)\dots(1)$$

(1) is called Carson's rule

Example

- For an FM modulator with a peak frequency deviation, $\Delta f = 10$ kHz, a modulating-signal frequency $f_m = 10$ kHz, $V_c = 10$ V and a 500 kHz carrier, determine
 - Actual minimum bandwidth from the Bessel function table.
 - Approximate minimum bandwidth using Carson's rule.

Then

Plot the output frequency spectrum for the Bessel approximation.

Deviation Ratio (DR)

The worse case modulation index which produces the widest output frequency spectrum.

$$DR = \frac{\Delta f_{(\max)}}{f_{m(\max)}}$$

Where

- $\Delta f_{(max)} = max$. peak frequency deviation
- $f_{m(max)} = max$. modulating signal frequency

Example

- Determine the deviation ratio and bandwidth for the worst-case (widest-bandwidth) modulation index for an FM broadcast-band transmitter with a maximum frequency deviation of 75 kHz and a maximum modulating-signal frequency of 15 kHz.
- Determine the deviation ratio and maximum bandwidth for an equal modulation index with only half the peak frequency deviation and modulating-signal frequency.

FM Power Distribution

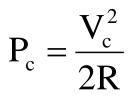
- As seen in Bessel function table, it shows that as the sideband relative amplitude increases, the carrier amplitude, J₀ decreases.
- This is because, in FM, the total transmitted power is always constant and the total average power is equal to the unmodulated carrier power, that is the amplitude of the FM remains constant whether or not it is modulated.

FM Power Distribution (cont'd)

- In effect, in FM, the total power that is originally in the carrier is redistributed between all components of the spectrum, in an amount determined by the modulation index, m_f, and the corresponding Bessel functions.
- At certain value of modulation index, the carrier component goes to zero, where in this condition, the power is carried by the sidebands only.

Average Power

The average power in unmodulated carrier



The total instantaneous power in the angle modulated carrier.

$$P_{t} = \frac{m(t)^{2}}{R} = \frac{V_{c}^{2}}{R} \cos^{2}[\omega_{c}t + \theta(t)]$$
$$P_{t} = \frac{V_{c}^{2}}{R} \left\{ \frac{1}{2} + \frac{1}{2}\cos[2\omega_{c}t + 2\theta(t)] \right\} = \frac{V_{c}^{2}}{2R}$$

The total modulated power

$$P_{t} = P_{0} + P_{1} + P_{2} + \ldots + P_{n} = \frac{V_{c}^{2}}{2R} + \frac{2(V_{1})^{2}}{2R} + \frac{2(V_{2})^{2}}{2R} + \ldots + \frac{2(V_{n})^{2}}{2R}$$

Example

For an FM modulator with a modulation index m = 1, a modulating signal

$$v_{m}(t) = V_{m}sin(2\pi 1000t),$$

and an unmodulated carrier

 $v_{c}(t) = 10sin(2\pi 500kt).$

Determine the unmodulated carrier power for the FM modulator given with a load resistance, $R_L = 50\Omega$. Determine also the total power in the angle-modulated wave.

Quiz

- For an FM modulator with modulation index, m = 2, modulating signal, $V_m(t) = V_m \cos(2\pi 2000t)$, and an unmodulated carrier, $V_c(t) = 10 \cos(2\pi 800 kt)$.
- a) Determine the number of sets of significant sidebands.
- b) Determine their amplitudes.
- c) Draw the frequency spectrum showing the relative amplitudes of the side frequencies.
- d) Determine the bandwidth.
- e) Determine the total power of the modulated wave.

Generation of FM

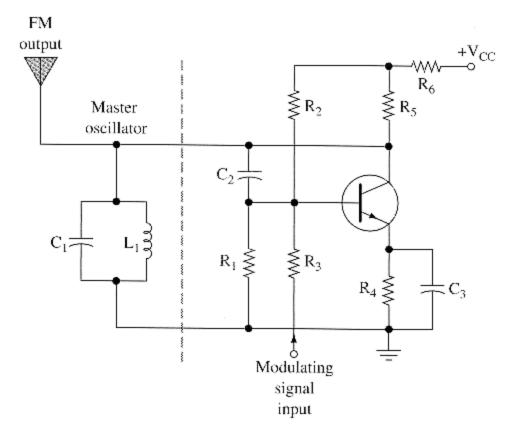
Two major FM generation:

i) **Direct method:**

- i) straight forward, requires a VCO whose oscillation frequency has linear dependence on applied voltage.
- ii) Advantage: large frequency deviation
- iii) Disadvantage: the carrier frequency tends to drift and must be stabilized.
- iv) Common methods:
 - i) **FM Reactance modulators**
 - ii) Varactor diode modulators

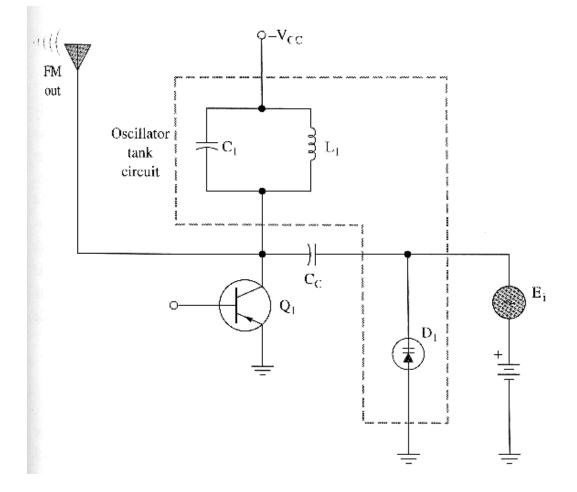
Generation of FM (cont'd)

1) Reactance modulator



Generation of FM (cont'd)

2) Varactor diode modulator

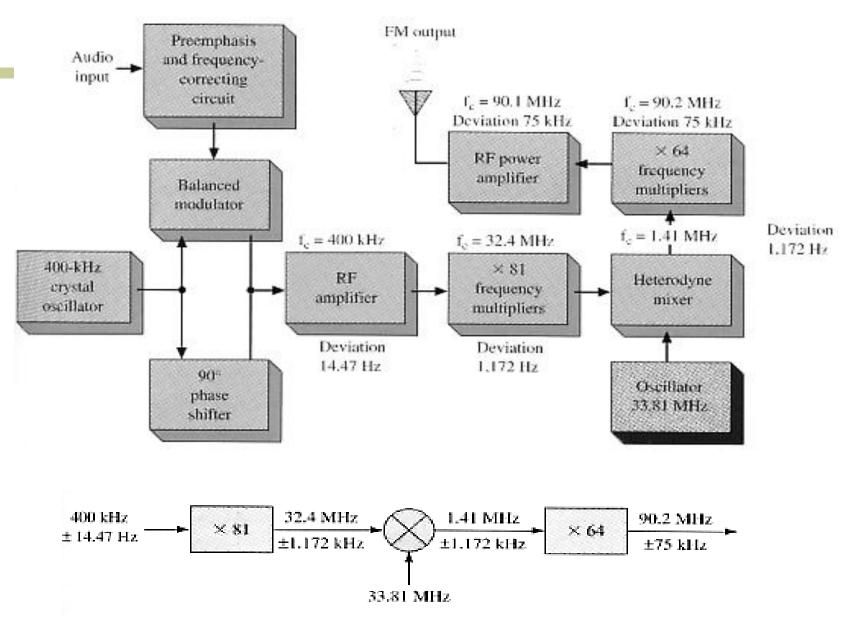


Generation of FM (cont'd)

ii) Indirect method:

- i. Frequency-up conversion.
- ii. Two ways:
 - a. Heterodyne method
 - b. Multiplication method
- iii. One most popular indirect method is the Armstrong modulator

Wideband Armstrong Modulator



Armstrong Modulator

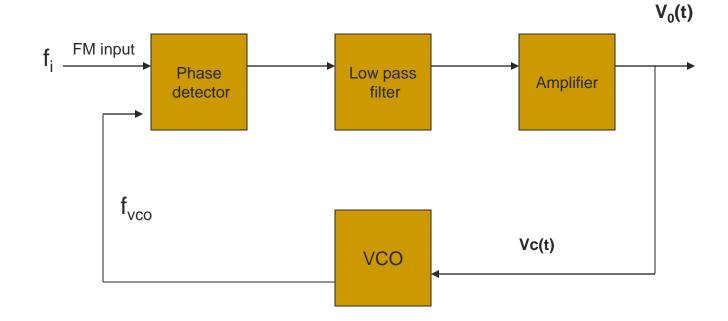
A complete Armstrong modulator is supposed to provide a 75kHz frequency deviation. It uses a balanced modulator and 90° phase shifter to phasemodulate a crystal oscillator. Required deviation is obtained by combination of multipliers and mixing, raise the signal from 400kHz ± 14.47 Hz to 90.2MHz ± 75 kHz suitable for broadcasting.

FM Detection/Demodulation

- FM demodulation
 - is a process of getting back or regenerate the original modulating signal from the modulated FM signal.
 - It can be achieved by converting the frequency deviation of FM signal to the variation of equivalent voltage.
 - The demodulator will produce an output where its instantaneous amplitude is proportional to the instantaneous frequency of the input FM signal.

FM detection (cont'd)

- To detect an FM signal, it is necessary to have a circuit whose output voltage varies linearly with the frequency of the input signal.
- The most commonly used demodulator is the PLL demodulator. Can be use to detect either NBFM or WBFM.



The phase detector produces an average output voltage that is linear function of the phase difference between the two input signals. Then low frequency component is pass through the LPF to get a small dc average voltage to the amplifier.

After amplification, part of the signal is fed back through VCO where it results in frequency modulation of the VCO frequency. When the loop is in lock, the VCO frequency follows or tracks the incoming frequency.

- Let instantaneous freq of FM Input,
 f_i(t)=f_c+k₁v_m(t),
 and the VCO output frequency,
 - $f_{VCO}(t) = f_0 + k_2 V_c(t);$
 - f_0 is the free running frequency.
- For the VCO frequency to track the instantaneous incoming frequency,

 $f_{vco} = f_i$; or

•
$$f_0 + k_2 V_c(t) = f_c + k_1 v_m(t)$$
, so,
 $V_c(t) \propto f_c - f_0 + k_1 v_m(t)$

- If VCO can be tuned so that $f_c=f_0$, then $V_c(t) \propto k_1 v_m(t)$
- Where Vc(t) is also taken as the output voltage, which therefore is the demodulated output

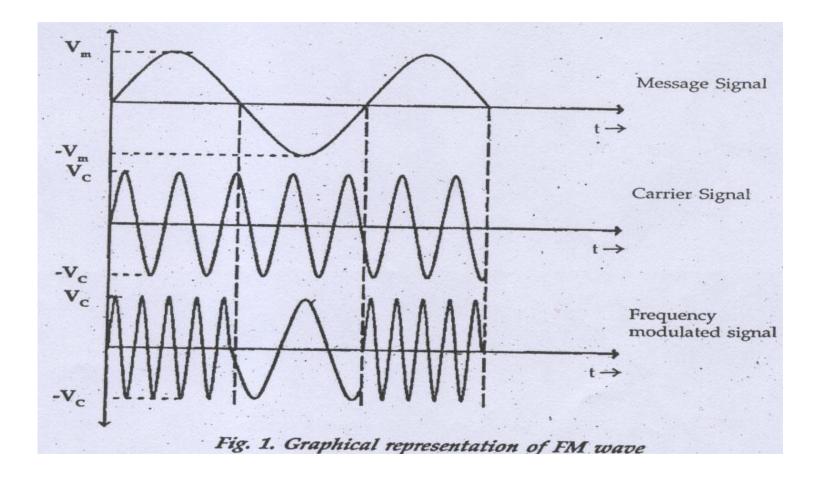
Comparison AM and FM

- Its the SNR can be increased without increasing transmitted power about 25dB higher than in AM
- Certain forms of interference at the receiver are more easily to suppressed, as FM receiver has a limiter which eliminates the amplitude variations and fluctuations.
- The modulation process can take place at a low level power stage in the transmitter, thus a low modulating power is needed.
- Power content is constant and fixed, and there is no waste of power transmitted
- There are guard bands in FM systems allocated by the standardization body, which can reduce interference between the adjacent channels.

Application of FM

- FM is commonly used at VHF radio frequencies for high-fidelity broadcasts of music and speech (FM broadcasting). Normal (analog) TV sound is also broadcast using FM. The type of FM used in broadcast is generally called wide-FM, or W-FM
- A narrowband form is used for voice communications in commercial and amateur radio settings. In two-way radio, narrowband narrow-fm (N-FM) is used to conserve bandwidth. In addition, it is used to send signals into space.

Summary of angle modulation -what you need to be familiar with



	FM	PM
Modulated wave	$m(t) = V_c \cos \left[\omega_c t + \frac{K_1 V_m}{f_m} \sin(\omega_m t) \right]$	$m(t) = V_c \cos[\omega_c t + K V_m]$
$\cos(\omega_m t)$]		
or	$m(t) = V_C \cos[\omega_C t + m \sin(\omega_m t)]$	$m(t) = V_c \cos[\omega_c t + m \cos(\omega_m t)]$
or	$m(t) = V_c \cos \left[\omega_c t + \frac{\Delta f}{f_m} \sin(\omega_m t) \right]$	$m(t) = V_C \cos[\omega_C t + \Delta \theta]$
$\cos(\omega_m t)$]		
Deviation sensitivity	K_1 (Hz/V)	K (rad/V)
Deviation	$\Delta f = K_1 V_m (\mathrm{Hz})$	$\Delta \theta = K V_{m} (\text{rad})$
Modulation index	$m = \frac{K_1 V_m}{f_m} \text{ (unitless)}$	$m = KV_m$ (rad)
or	$m = \frac{\Delta f}{f_m}$ (unitless)	$m = \Delta \theta$ (rad)
Modulating signal	$v_m(t) = V_m \sin(\omega_m t)$	$v_m(t) = V_m \cos(\omega_m t)$
Modulating frequency	$\omega_m = 2\pi f_m \text{ rad/s}$	$\omega_m = 2\pi f_m \text{ rad/s}$
or	$\omega_m/2\pi = f_m$ (Hz)	$\omega_m/2\pi = f_m$ (Hz)
Carrier signal	$V_c \cos(\omega_c t)$	$V_c \cos(\omega_c t)$

- Bandwidth:
- a) Actual minimum bandwidth from Bessel table:

$$B = 2(n \times f_m)$$

b) Approximate minimum bandwidth using Carson's rule:

$$B = 2(\Delta f + f_m)$$

Multitone modulation (equation in general): $\omega_i = \omega_c + Kv_{m1} + Kv_{m2}$

$$\omega_i = \omega_c + 2\pi \Delta f_1 \cos \omega_1 t + 2\pi \Delta f_2 \cos \omega_2 t \dots$$

$$\phi_i = \omega_C t + \frac{\Delta f_1}{f_1} \sin \omega_1 t + \frac{\Delta f_2}{f_2} \sin \omega_2 t \dots$$

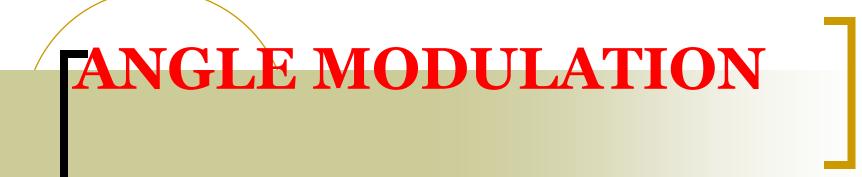
$$v_{fm}(t) = V_C \cos \phi_i$$

$$v_{fm}(t) = V_C \cos[\omega_C t + \frac{\Delta f_1}{f_1} \sin \omega_1 t + \frac{\Delta f_2}{f_2} \sin \omega_2 t]$$

$$= V_C \cos[\omega_C t + m_{f_1} \sin \omega_1 t + m_{f_2} \sin \omega_2 t].....$$

Summary (cont'd)-Comparison NBFM&WBFM

S.No	WBFM	NBFM				
I.	Modulating index is greater than1	Modulation index is less than 1				
П.	Frequency deviation =75 KHz.	Frequency deviation 5 Khz.				
III .	Modulating frequency range from 30Hz-15kHz	Modulation frequency =3 <u>Khz</u>				
IV.	Bandwidth 15 times NBFM.	Bandwidth = 2Fm				
V.	Noise is more suppressed.	Less suppressing of noise				
	Use: Entertainment and broadcasting	Use: Mobile communication.				



Part 3 Advantages
Disadvantages

Advantages

- Wideband FM gives significant <u>improvement in the SNR</u> at the output of the RX which proportional to the square of modulation index.
- Angle modulation is <u>resistant to propagation-induced</u> selective fading since amplitude variations are unimportant and are removed at the receiver using a limiting circuit.
- Angle modulation is very <u>effective in rejecting interference</u>. (minimizes the effect of noise).
- Angle modulation allows the use of <u>more efficient</u> transmitter power in information.
- Angle modulation is capable of <u>handing a greater dynamic range</u> of modulating signal without distortion than AM.

Disadvantages

- Angle modulation requires a transmission bandwidth <u>much larger</u> than the message signal bandwidth.
- Angle modulation requires <u>more</u> <u>complex</u> and expensive circuits than AM.

END OF ANGLE MODULATION

 Determine the deviation ratio and worst-case bandwidth for an FM signal with a maximum frequency deviation
 25 kHz and maximum modulating signal 12.5 kHz.

For an FM modulator with 40-kHz frequency deviation and a modulatingsignal frequency 10 kHz, determine the bandwidth using both Carson's rule and Bessel table.

For an FM modulator with an unmodulated carrier amplitude 20 V, a modulation index, m = 1, and a load resistance of 10-ohm, determine the power in the modulated carrier and each side frequency, and sketch the power spectrum for the modulated wave.

 A frequency modulated signal (FM) has the following expression:

 $v_{fm}(t) = 38\cos(400\pi \times 10^6 t + m_f \sin 10\pi \times 10^3 t)$

The frequency deviation allowed in this system is 75 kHz. Calculate the:

- Modulation index
- Bandwidth required, using Carson's rule