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# Introduction to Python Programming – Part I

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# Why Python?

- Python is a versatile language which is easy to script and easy to read.
- It doesn't support strict rules for syntax.
- Its installation comes with integrated development environment for programming.
- It supports interfacing with wide ranging hardware platforms.
- With open-source nature, it forms a strong backbone to build large applications.

# Python IDE

- Python IDE is a free and open source software that is used to write codes, integrate several modules and libraries.
- It is available for installation into PC with Windows, Linux and Mac.
- Examples: Spyder, PyCharm, etc.

# Starting with Python

- Simple printing statement at the python interpreter prompt,  

```
>>> print "Hi, Welcome to python!"
```

Output: Hi, Welcome to python!
- To indicate different blocks of code, it follows rigid indentation.  
if True:  
    print "Correct"  
else:  
    print "Error"

# Data-types in Python

- There are 5 data types in Python:

- ✓ Numbers

x, y, z = 10, 10.2, " Python "

- ✓ String

x = 'This is Python'

print x

>>This is Python

print x[0]

>>T

print x[2:4]

>>is

# Data-types in Python (contd..)

✓ List

```
x = [10, 10.2, 'python']
```

✓ Tuple

✓ Dictionary

```
d = {1:'item','k':2}
```

# Controlling Statements

- if (cond.):

  - statement 1

  - statement 2

- elif (cond.):

  - statement 1

  - statement 2

- else:

  - statement 1

  - statement 2

- while (cond.):

  - statement 1

  - statement 2

- x = [1,2,3,4]

  - for i in x:

    - statement 1

    - statement 2

# Controlling Statements (contd..)

- Break

```
for s in "string":  
    if s == 'n':  
        break  
    print (s)  
print "End"
```

- Continue

```
for s in "string":  
    if s == 'y':  
        continue  
    print (s)  
print "End"
```



# Functions in Python

- Defining a function

- ✓ Without return value

```
def funct_name(arg1, arg2, arg3):           # Defining the function
    statement 1
    statement 2
```

- ✓ With return value

```
def funct_name(arg1, arg2, arg3):           # Defining the function

    statement 1
    statement 2
    return x                                 # Returning the value
```

# Functions in Python

- Calling a function  
def example (str):  
    print (str + "!")

```
example ("Hi")
```

```
# Calling the function
```

Output:: Hi!

# Functions in Python (contd..)

- Example showing function returning multiple values

```
def greater(x, y):
```

```
    if x > y:
```

```
        return x, y
```

```
    else:
```

```
        return y, x
```

```
val = greater(10, 100)
```

```
print(val)
```

Output:: (100,10)

# Functions as Objects

- Functions can also be assigned and reassigned to the variables.
- Example:

```
def add (a,b)  
    return a+b
```

```
print (add(4,6))  
c = add(4,6)  
print c
```

Output:: 10      10

# Variable Scope in Python

## **Global variables:**

These are the variables declared out of any function , but can be accessed inside as well as outside the function.

## **Local variables:**

These are the ones that are declared inside a function.

# Example showing Global Variable

```
g_var = 10
```

```
def example():  
    l_var = 100  
    print(g_var)
```

```
example()           # calling the function
```

Output:: 10

# Example showing Variable Scope

```
var = 10
```

```
def example():
```

```
    var = 100
```

```
    print(var)
```

```
example()
```

```
# calling the function
```

```
print(var)
```

Output:: 100

10

# Modules in Python

- Any segment of code fulfilling a particular task that can be used commonly by everyone is termed as a module.

- Syntax:

```
import module_name           #At the top of the code
```

```
using module_name.var       #To access functions and values  
                             with 'var' in the module
```



# Modules in Python (contd..)

- Example:

```
import random
```

```
for i in range(1,10):  
    val = random.randint(1,10)  
    print (val)
```

Output:: varies with each execution

# Modules in Python (contd..)

- We can also access only a particular function from a module.
- Example:

```
from math import pi
```

```
print (pi)
```

Output:: 3.14159

# Exception Handling in Python

- An error that is generated during execution of a program, is termed as exception.
- Syntax:

```
try:  
    statements  
except _Exception_:  
    statements  
else:  
    statements
```

# Exception Handling in Python (contd..)

- Example:

```
while True:
```

```
    try:
```

```
        n = input ("Please enter an integer: ")
```

```
        n = int (n)
```

```
        break
```

```
    except ValueError:
```

```
        print "No valid integer! "
```

```
print "It is an integer!"
```

# Example Code: to check number is prime or not

```
x = int (input("Enter a number: "))
def prime (num):
    if num > 1:
        for i in range(2,num):
            if (num % i) == 0:
                print (num,"is not a prime number")
                print (i,"is a factor of",num)
                break
        else:
            print(num,"is a prime number")
    else:
        print(num,"is not a prime number")
prime (x)
```

# Thank You!!





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# Introduction to Python Programming – Part II

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# File Read Write Operations

- Python allows you to read and write files
- No separate module or library required
- Three basic steps
  - Open a file
  - Read/Write
  - Close the file



# File Read Write Operations (contd..)

Opening a File:

- Open() function is used to open a file, returns a file object  
open(file\_name, mode)
- Mode: Four basic modes to open a file
  - r: read mode
  - w: write mode
  - a: append mode
  - r+: both read and write mode

# File Read Write Operations (contd..)

Read from a file:

- `read()`: Reads from a file  
`file=open('data.txt', 'r')`  
`file.read()`

Write to a file:

- `Write()`: Writes to a file  
`file=open('data.txt', 'w')`  
`file.write('writing to the file')`

# File Read Write Operations (contd..)

Closing a file:

- Close(): This is done to ensure that the file is free to use for other resources  
file.close()

Using WITH to open a file:

- Good practice to handle exception while file read/write operation
- Ensures the file is closed after the operation is completed, even if an exception is encountered

```
with open("data.txt","w") as file:  
file.write("writing to the text file")  
file.close()
```

# File Read Write Operations code + image

```
with open("PythonProgram.txt","w") as file:  
    file.write("Writing data")  
file.close()
```

```
with open("PythonProgram.txt","r") as file:  
    f=file.read()  
    print('Reading from the file\n')  
    print (f)  
file.close()
```

```
Reading from the file  
  
Writing data  
>>> |
```

# File Read Write Operations (contd..)

## Comma Separated Values Files

- CSV module supported for CSV files

### Read:

```
with open(file, "r") as csv_file:
    reader = csv.reader(csv_file)
    print("Reading from the CSV File\n")
    for row in reader:
        print(" ".join(row))
csv_file.close()
```

### Write:

```
data = ["1,2,3,4,5,6,7,8,9".split(",")]
file = "output.csv"
with open(file, "w") as csv_file:
    writer = csv.writer(csv_file, delimiter=',')
    print("Writing CSV")
    for line in data:
        writer.writerow(line)
csv_file.close()
```

# File Read Write Operations (contd..)

```
import csv

#writing a csv file
data = ["1,2,3,4,5,6,7,8,9".split(",")]
file = "output.csv"
with open(file, "w") as csv_file:
    writer = csv.writer(csv_file, delimiter=',')
    print("Writing CSV")
    for line in data:
        writer.writerow(line)
csv_file.close()

#reading from a csv file
with open(file, "r") as csv_file:
    reader = csv.reader(csv_file)
    print("Reading from the CSV File\n")
    for row in reader:
        print(" ".join(row))
csv_file.close()
```

```
Writing CSV
Reading from the CSV File
```

```
1 2 3 4 5 6 7 8 9
```

```
>>>
```

# Image Read/Write Operations

- Python supports PIL library for image related operations
- Install PIL through PIP

```
sudo pip install pillow
```

PIL is supported till python version 2.7. Pillow supports the 3x version of python.

# Image Read/Write Operations

Reading Image in Python:

- PIL: Python Image Library is used to work with image files

```
from PIL import Image
```

- Open an image file

```
image=Image.open(image_name)
```

- Display the image

```
image.show()
```



# Image Read/Write Operations (contd..)

Resize(): Resizes the image to the specified size

```
image.resize(255,255)
```

Rotate(): Rotates the image to the specified degrees, counter clockwise

```
image.rotate(90)
```

Format: Gives the format of the image

Size: Gives a tuple with 2 values as width and height of the image, in pixels

Mode: Gives the band of the image, 'L' for grey scale, 'RGB' for true colour image

```
print(image.format, image.size, image.mode)
```

# Image Read/Write Operations (contd..)

Convert image to different mode:

- Any image can be converted from one mode to 'L' or 'RGB' mode

**`conv_image=image.convert('L')`**

- Conversion between modes other than 'L' and 'RGB' needs conversion into any of these 2 intermediate modes

# Output

Converting a sample image to Grey Scale

```
from PIL import Image

im = Image.open('/home/saswati/VRP_Linux/Images/i3.jpg')
im.show()
grey_image=im.convert('L')
grey_image.show()
grey_image.save('GreyScaleImage.jpg')
```

# Output



# Networking in Python

- Python provides network services for client server model.
- Socket support in the operating system allows to implement clients and servers for both connection-oriented and connectionless protocols.
- Python has libraries that provide higher-level access to specific application-level network protocols.

# Networking in Python (contd..)

- Syntax for creating a socket:

```
s = socket.socket (socket_family, socket_type, protocol=0)
```

**socket\_family** – AF\_UNIX or AF\_INET

**socket\_type** – SOCK\_STREAM or SOCK\_DGRAM

**protocol** – default '0'.

# Example - simple server

- The socket waits until a client connects to the port, and then returns a connection object that represents the connection to that client.

```
import socket
import sys
```

```
# Create a TCP/IP socket
```

```
sock = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
```

```
# Bind the socket to the port
```

```
server_address = ('10.14.88.82', 2017)
```

```
print >>sys.stderr, 'starting up on %s port %s' % server_address
```

```
sock.bind(server_address)
```

# Example - simple server (contd..)

```
# Listen for incoming connections
```

```
sock.listen(1)
```

```
connection, client_address = sock.accept()
```

```
#Receive command
```

```
data = connection.recv(1024)
```

```
print(data)
```

```
sock.close()
```



# Example - simple client

```
import socket
import sys

# Create a TCP/IP socket
client_socket = socket.socket(socket.AF_INET, socket.SOCK_STREAM)

#Connect to Listener socket
client_socket.connect(("10.14.88.82", 2017))
print>>sys.stderr,'Connection Established'

#Send command
client_socket.send('Message to the server')
print('Data sent successfully')
```

# Code Snapshot

```
import socket
import sys

# Create a TCP/IP socket
sock = socket.socket(socket.AF_INET, socket.SOCK_STREAM)

# Bind the socket to the port
server_address = ('10.14.88.82', 2017)
print >>sys.stderr, 'starting up on %s port %s' % server_address
sock.bind(server_address)

# Listen for incoming connections
sock.listen(1)

connection, client_address = sock.accept()

#Receive command
data = connection.recv(1024)
print(data)
sock.close()
|
```

```
import socket
import sys

# Create a TCP/IP socket
client_socket = socket.socket(socket.AF_INET, socket.SOCK_STREAM)

#Connect to Listener socket
client_socket.connect(("10.14.88.82", 2017))
print>>sys.stderr, 'Connection Established'

#Send command
client_socket.send('Message to the server')
print('Data sent successfully')
|
```

# Output

```
starting up on 10.14.88.82 port 2017  
Message to the server  
saswati@saswati-BK361AA-ACJ-CQ3236IX:~/Desktop$
```

```
Connection Established  
Data sent successfully  
saswati@saswati-BK361AA-ACJ-CQ3236IX:~/Desktop$
```

# Thank You!!





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# Introduction to Raspberry Pi – Part I

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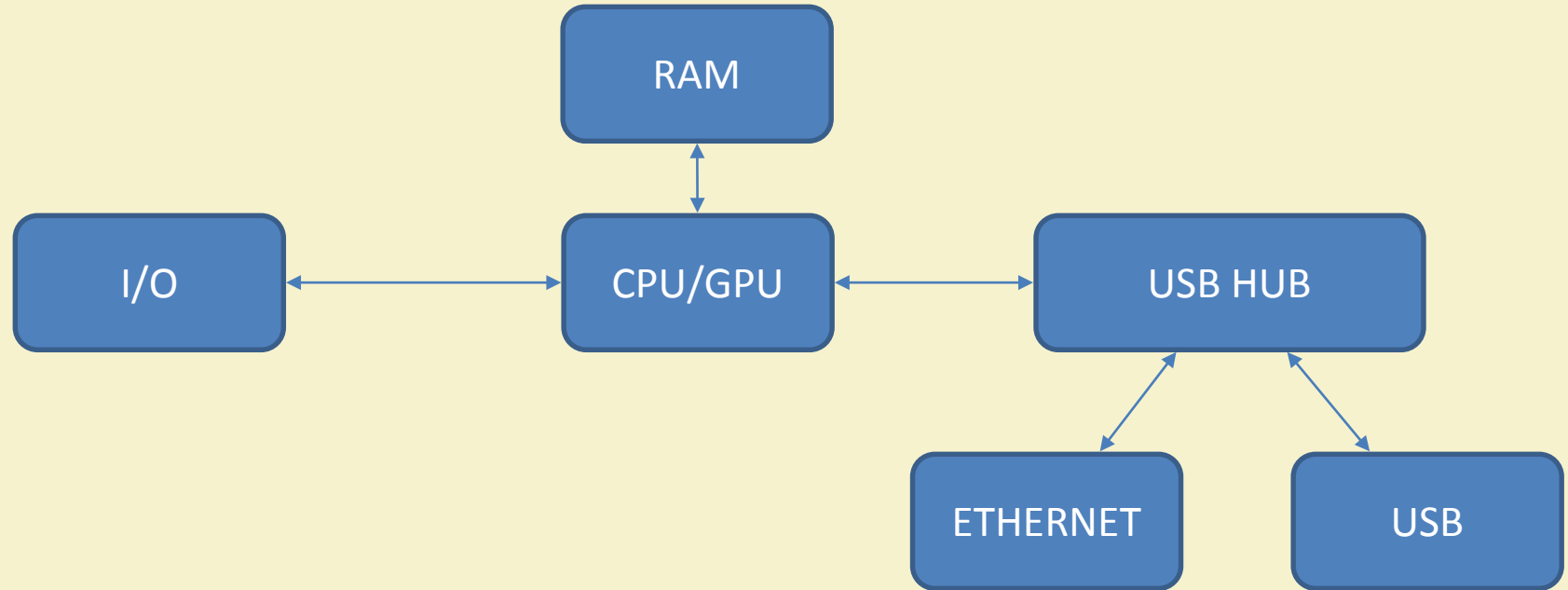
# What is Raspberry Pi?

- Computer in your palm.
- Single-board computer.
- Low cost.
- Easy to access.

# Specifications

Key features	Raspberry pi 3 model B	Raspberry pi 2 model B	Raspberry Pi zero
<b>RAM</b>	<b>1GB SDRAM</b>	<b>1GB SDRAM</b>	<b>512 MB SDRAM</b>
<b>CPU</b>	<b>Quad cortex A53@1.2GHz</b>	<b>Quad cortex A53@900MHz</b>	<b>ARM 11@ 1GHz</b>
<b>GPU</b>	<b>400 MHz video core IV</b>	<b>250 MHz video core IV</b>	<b>250 MHz video core IV</b>
<b>Ethernet</b>	<b>10/100</b>	<b>10/100</b>	<b>None</b>
<b>Wireless</b>	<b>802.11/Bluetooth 4.0</b>	<b>None</b>	<b>None</b>
<b>Video output</b>	<b>HDMI/Composite</b>	<b>HDMI/Composite</b>	<b>HDMI/Composite</b>
<b>GPIO</b>	<b>40</b>	<b>40</b>	<b>40</b>

# Basic Architecture

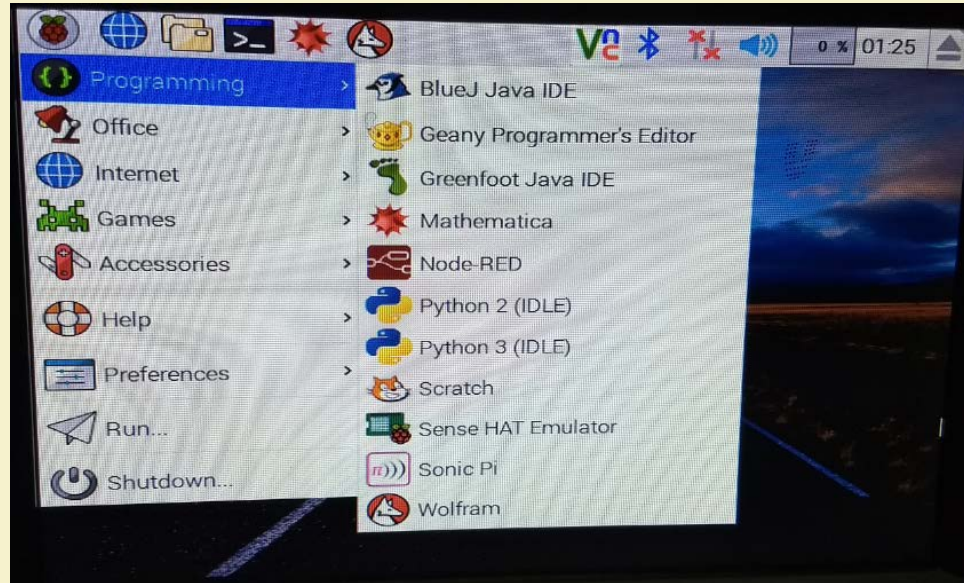




# Raspberry Pi



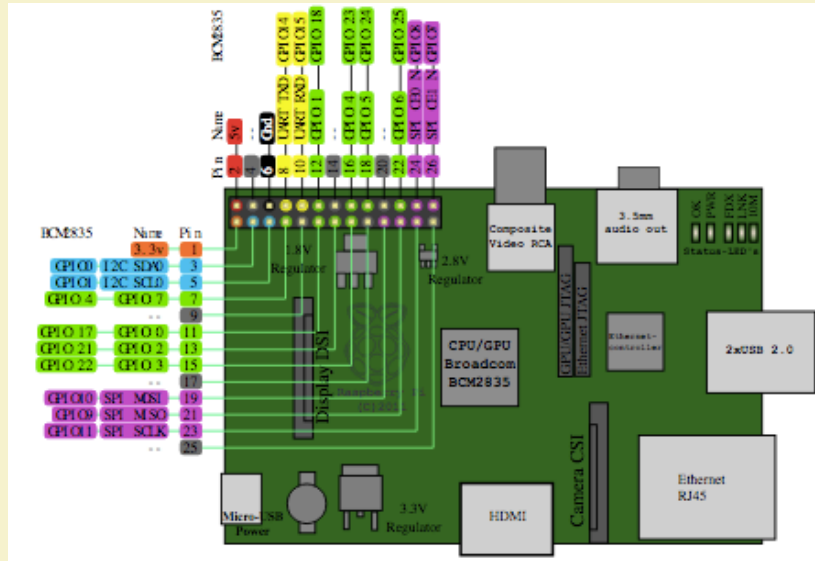
# Start up raspberry pi



# Raspberry Pi GPIO

- Act as both digital output and digital input.
- **Output:** turn a GPIO pin high or low.
- **Input:** detect a GPIO pin high or low.

# Raspberry Pi pin configuration



Source: Raspberry Pi PCB Pin Overview, Wikimedia Commons (Online)



Source: Raspberry Pi GPIO, Wikimedia Commons (Online)

# Basic Set up for Raspberry Pi

- HDMI cable.
- Monitor.
- Key board.
- Mouse.
- 5volt power adapter for raspberry pi.
- LAN cable .
- Min- 2GB micro sd card

# Basic Set up for Raspberry Pi



# Operating System

## Official Supported OS :

- Raspbian
- NOOBS

## Some of the third party OS :

- UBUNTU mate
- Snappy Ubuntu core
- Windows 10 core
- Pinet
- Risc OS

Source: [Downloads](#), Raspberry Pi Foundation

# Raspberry Pi Setup

## Download Raspbian:

- Download latest Raspbian image from raspberry pi official site:  
<https://www.raspberrypi.org/downloads/>
- Unzip the file and end up with an .img file.

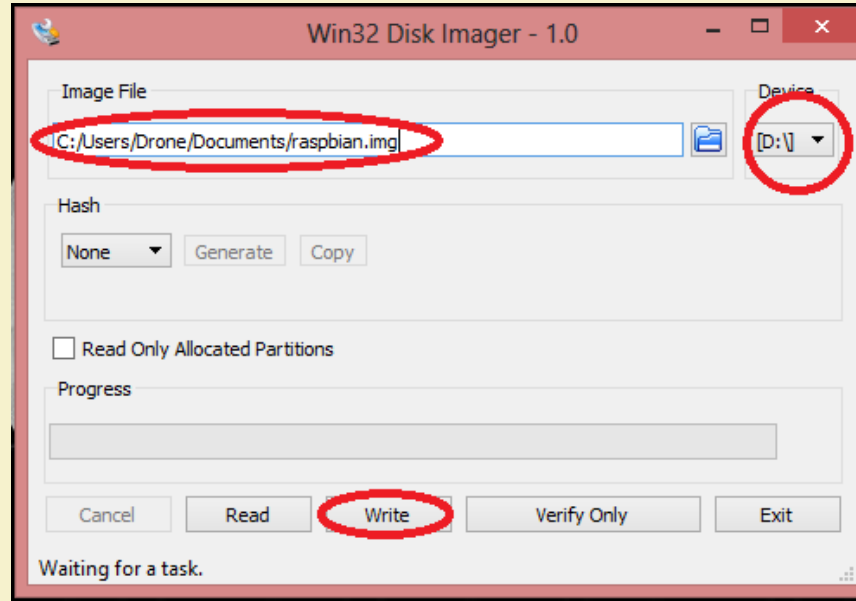


# Raspberry Pi OS Setup

## Write Raspbian in SD card :

- Install “Win32 Disk Imager” software in windows machine .
- Run Win32 Disk Imager
- Plug SD card into your PC
- Select the “Device”
- Browse the “Image File”(Raspbian image)
- Write

# Raspberry Pi OS Setup



# Basic Initial Configuration

## Enable SSH

**Step1** : Open command prompt and type **sudo raspi-config** and press enter.

**Step2**: Navigate to SSH in the Advance option.

**Step3**: Enable SSH

# Basic Initial Configuration

```
File Edit Tabs Help
Raspberry Pi Software Configuration Tool (raspi-config)
1 Expand Filesystem      Ensures that all of the SD card s
2 Change User Password   Change password for the default u
3 Boot Options           Configure options for start-up
4 Internationalisation Options Set up language and regional sett
5 Enable Camera          Enable this Pi to work with the R
6 Overclock              Configure overclocking for your P
7 Advanced Options       Configure advanced settings
8 About raspi-config     Information about this configurat
```

```
Raspberry Pi Software Configuration Tool (raspi-config)
A1 Overscan              You may need to configure oversca
A2 Hostname              Set the visible name for this Pi
A3 Memory Split          Change the amount of memory made
A4 SSH                   Enable/Disable remote command lin
A5 VNC                   Enable/Disable graphical remote a
A6 SPI                   Enable/Disable automatic loading
A7 I2C                   Enable/Disable automatic loading
A8 Serial                Enable/Disable shell and kernel m
A9 Audio                 Force audio out through HDMI or 3
AA 1-Wire                Enable/Disable one-wire interface
```

# Basic Initial Configuration contd.

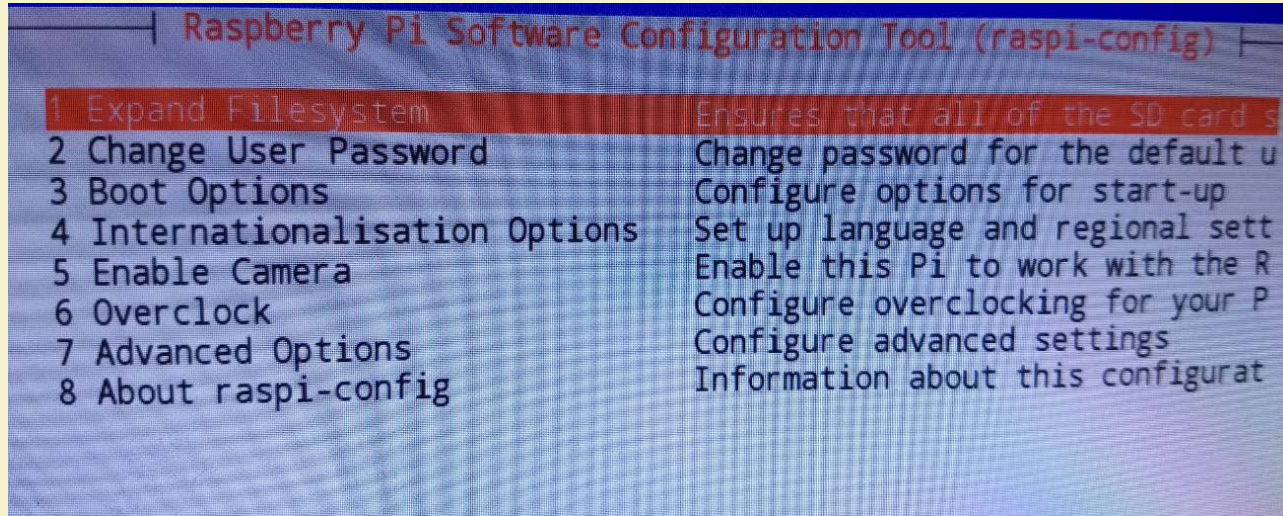
## Expand file system :

**Step 1:** Open command prompt and type **sudo raspi-config** and press enter.

**Step 2:** Navigate to Expand Filesystem

**Step 3:** Press enter to expand it.

# Basic Initial Configuration contd.



The image shows a terminal window displaying the Raspberry Pi Software Configuration Tool (raspi-config) menu. The title bar reads "Raspberry Pi Software Configuration Tool (raspi-config)". The menu items are listed in a two-column format, with the first column containing the item number and name, and the second column containing a brief description of each option. The first item, "1 Expand Filesystem", is highlighted with a red background.

Item	Description
1 Expand Filesystem	Ensures that all of the SD card s
2 Change User Password	Change password for the default u
3 Boot Options	Configure options for start-up
4 Internationalisation Options	Set up language and regional sett
5 Enable Camera	Enable this Pi to work with the R
6 Overclock	Configure overclocking for your P
7 Advanced Options	Configure advanced settings
8 About raspi-config	Information about this configurat

# Programming

## Default installed :

- Python
- C
- C++
- Java
- Scratch
- Ruby

**Note :** Any language that will compile for ARMv6 can be used with raspberry pi.

Source: [Programming languages for Raspberry Pi](#), eProseed, Lonneke Dikmans, August 07, 2015

# Popular Applications

- Media streamer
- Home automation
- Controlling BOT
- VPN
- Light weight web server for IOT
- Tablet computer



# Thank You!!





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# Introduction to Raspberry Pi – Part II

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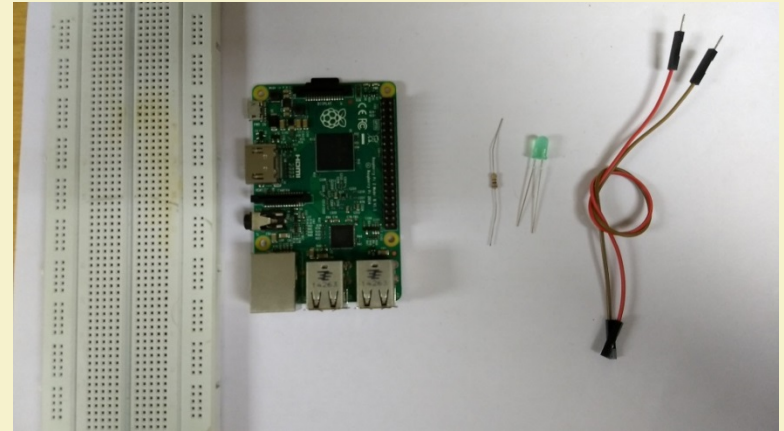
Website: <http://cse.iitkgp.ac.in/~smisra/>

# Topics Covered

- **Using GPIO pins**
- **Taking pictures using PiCam**

# Blinking LED

- Requirement:
- Raspberry pi
- LED
- 100 ohm resistor
- Bread board
- Jumper cables



# Blinking LED (contd..)

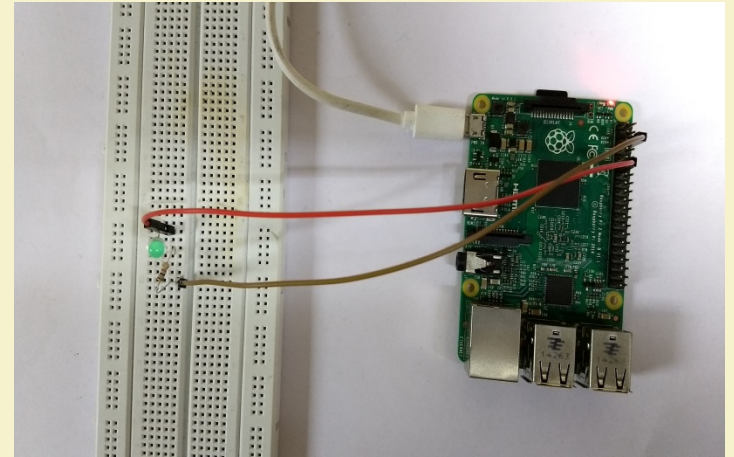
## Installing GPIO library:

- Open terminal
- Enter the command “sudo apt-get install python-dev” to install python development
- Enter the command “sudo apt-get install python-rpi.gpio” to install GPIO library.

# Blinking LED (contd..)

## Connection:

- Connect the negative terminal of the LED to the ground pin of Pi
- Connect the positive terminal of the LED to the output pin of Pi



# Blinking LED (contd..)

Basic python coding:

- Open terminal enter the command  
**sudo nano filename.py**
- This will open the nano editor where you can write your code
- Ctrl+O : Writes the code to the file
- Ctrl+X : Exits the editor

# Blinking LED (contd..)

Code:

```
import RPi.GPIO as GPIO          #GPIO library
import time
GPIO.setmode(GPIO.BOARD)        # Set the type of board for pin numbering
GPIO.setup(11, GPIO.OUT)        # Set GPIO pin 11as output pin
for i in range (0,5):
    GPIO.output(11,True)        # Turn on GPIO pin 11
    time.sleep(1)
    GPIO.output(11,False)
    time.sleep(2)
    GPIO.output(11,True)
GPIO.cleanup()
```



# Blinking LED (contd..)

GNU nano 2.2.6

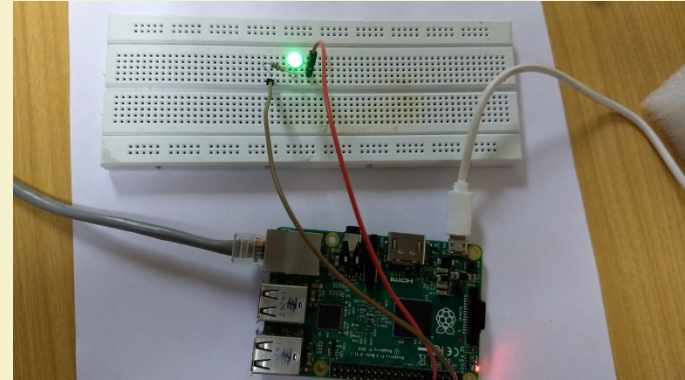
File: BLINK\_LED.py

```
import RPi.GPIO as GPIO ## GPIO library
import time
GPIO.setmode(GPIO.BOARD) ## Set the type of board for pin numbering
GPIO.setup(11, GPIO.OUT) ## Set GPIO pin 11 as output pin
for i in range (0,5):
    GPIO.output(11,True) ## Turn on GPIO pin 11
    time.sleep(1)
    GPIO.output(11,False)
    time.sleep(2)
    GPIO.output(11,True)
GPIO.cleanup()
```

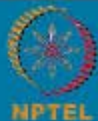


# Blinking LED (contd..)

The LED blinks in a loop with delay of 1 and 2 seconds.

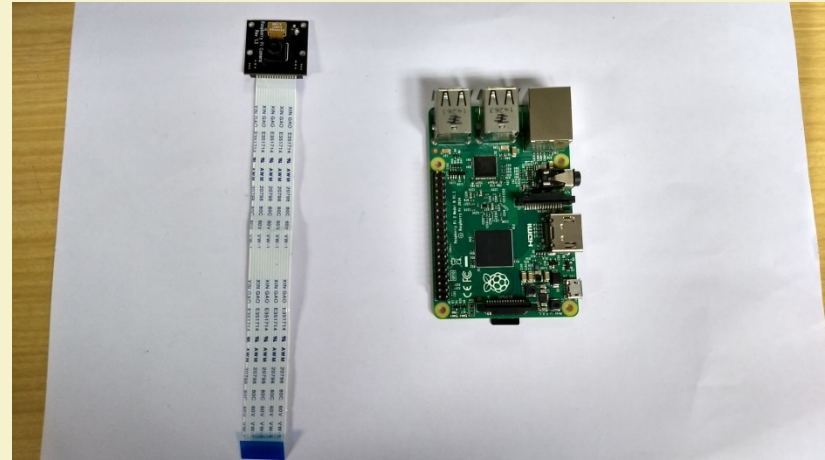


# Capture Image using Raspberry Pi



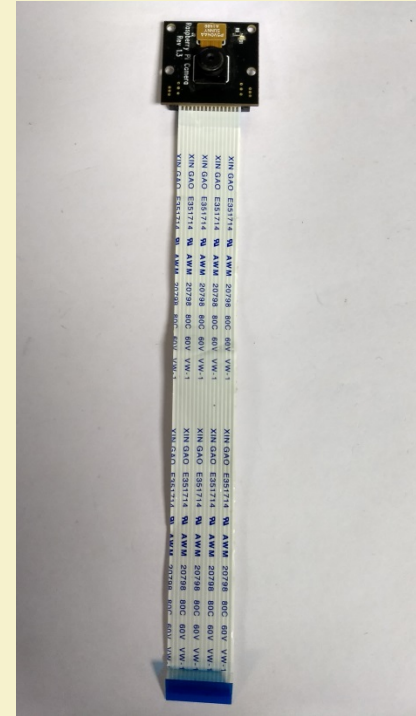
# Requirement

- Raspberry Pi
- Raspberry Pi Camera



# Raspberry Pi Camera

- Raspberry Pi specific camera module
- Dedicated CSI slot in Pi for connection
- The cable slot is placed between Ethernet port and HDMI port



# Connection

Boot the Pi once the camera is connected to Pi



# Configuring Pi for Camera

- In the terminal run the command “sudo raspi-config” and press enter.
- Navigate to “Interfacing Options” option and press enter.
- Navigate to “Camera” option.
- Enable the camera.
- Reboot Raspberry pi.

# Configuring Pi for Camera (contd..)

```
Raspberry Pi Software Configuration Tool (raspi-config)

1 Change User Password      Change password for the default u
2 Hostname                  Set the visible name for this Pi
3 Boot Options              Configure options for start-up
4 Localisation Options      Set up language and regional sett
5 Interfacing Options       Configure connections to peripher
6 Overclock                 Configure overclocking for your P
7 Advanced Options          Configure advanced settings
8 Update                    Update this tool to the latest ve
9 About raspi-config        Information about this configurat

<Select>                    <Finish>
```

```
Raspberry Pi Software Configuration Tool (raspi-config)

P1 Camera                   Enable/Disable connection to the
P2 SSH                      Enable/Disable remote command lin
P3 VNC                      Enable/Disable graphical remote a
P4 SPI                      Enable/Disable automatic loading
P5 I2C                      Enable/Disable automatic loading
P6 Serial                   Enable/Disable shell and kernel m
P7 1-Wire                   Enable/Disable one-wire interface
P8 Remote GPIO              Enable/Disable remote access to G

<Select>                    <Back>
```



# Capture Image

- Open terminal and enter the command-

```
raspistill -o image.jpg
```

- This will store the image as 'image.jpg'

# Capture Image (contd..)

PiCam can also be processed using Python camera module `python-picamera`

```
sudo apt-get install python-picamera
```

## Python Code:

```
import picamera  
camera = picamera.PiCamera()  
camera.capture('image.jpg')
```

Source: [PYTHON PICAMERA](#), Raspberry Pi Foundation

# Capture Image (contd..)

```
pi@raspberrypi:~ $ raspistill -o image.jpg  
pi@raspberrypi:~ $ █
```



# Thank You!!





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# Implementation of IoT with Raspberry Pi: Part 1

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# IOT

## Internet Of Things

- Creating an interactive environment
- Network of devices connected together

# Sensor

- Electronic element
- Converts physical quantity into electrical signals
- Can be analog or digital

# Actuator

- Mechanical/Electro-mechanical device
- Converts energy into motion
- Mainly used to provide controlled motion to other components



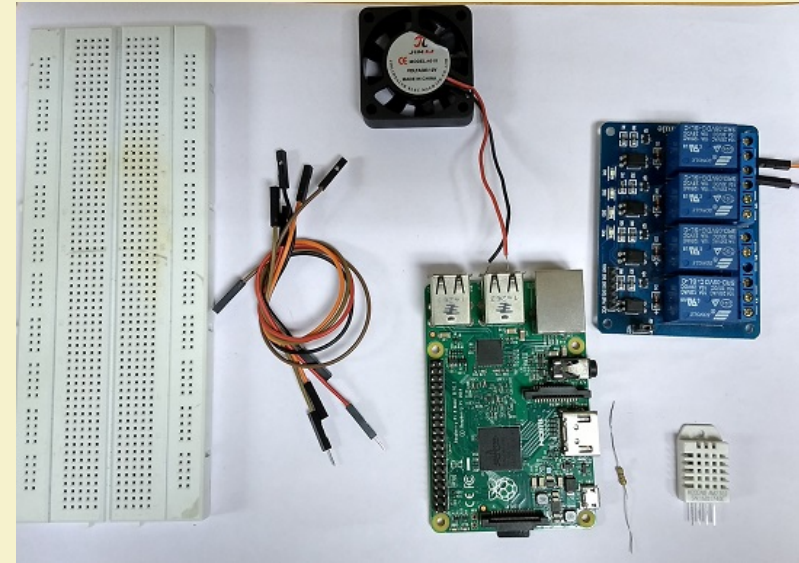
# System Overview

- Sensor and actuator interfaced with Raspberry Pi
- Read data from the sensor
- Control the actuator according to the reading from the sensor
- Connect the actuator to a device

# System Overview (contd..)

## Requirements

- DHT Sensor
- 4.7K ohm resistor
- Relay
- Jumper wires
- Raspberry Pi
- Mini fan



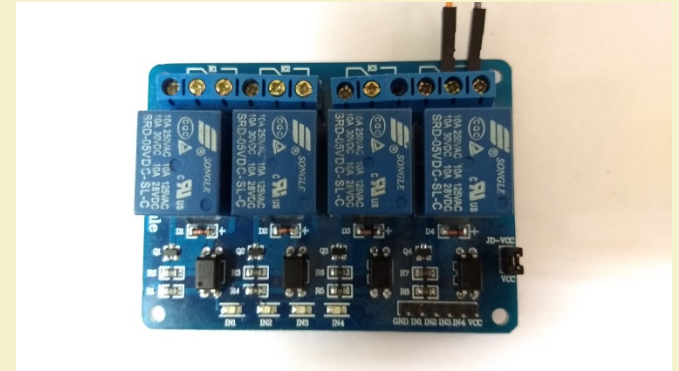
# DHT Sensor

- Digital Humidity and Temperature Sensor (DHT)
- PIN 1, 2, 3, 4 (from left to right)
  - PIN 1- 3.3V-5V Power supply
  - PIN 2- Data
  - PIN 3- Null
  - PIN 4- Ground



# Relay

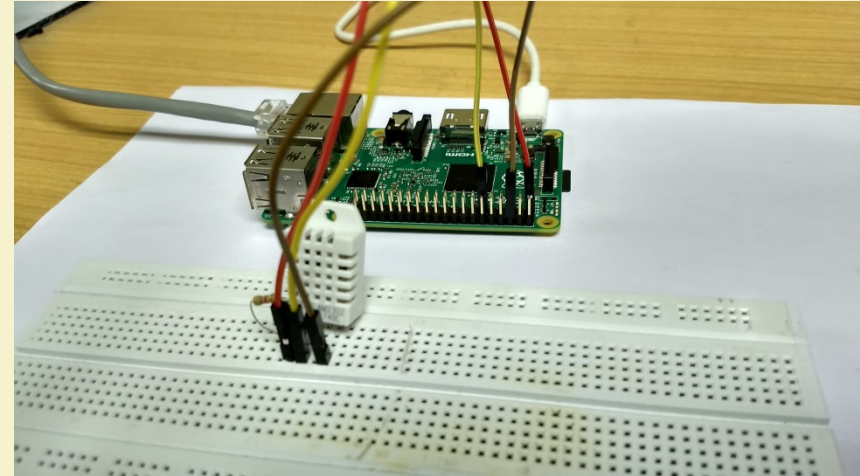
- Mechanical/electromechanical switch
- 3 output terminals (left to right)
  - NO (normal open):
  - Common
  - NC (normal close)



# Temperature Dependent Auto Cooling System

## Sensor interface with Raspberry Pi

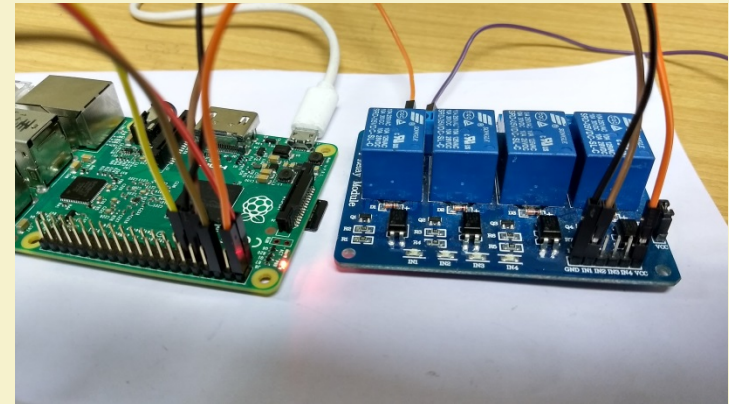
- Connect pin 1 of DHT sensor to the 3.3V pin of Raspberry Pi
- Connect pin 2 of DHT sensor to any input pins of Raspberry Pi, here we have used pin 11
- Connect pin 4 of DHT sensor to the ground pin of the Raspberry Pi



# Temperature Dependent Auto Cooling System (contd..)

## Relay interface with Raspberry Pi

- Connect the VCC pin of relay to the 5V supply pin of Raspberry Pi
- Connect the GND (ground) pin of relay to the ground pin of Raspberry Pi
- Connect the input/signal pin of Relay to the assigned output pin of Raspberry Pi (Here we have used pin 7)



# Temperature Dependent Auto Cooling System (contd..)

Adafruit provides a library to work with the DHT22 sensor

- Install the library in your Pi-
  - Get the clone from GIT  
**git clone https://github.com/adafruit/Adafruit\_Python\_DHT.g...**
  - Go to folder Adafruit\_Python\_DHT  
**cd Adafruit\_Python\_DHT**
  - Install the library  
**sudo python setup.py install**

Source: [ADAFRUIT DHTXX SENSORS](#), Lady Ada, 2012-07-29

# Program: DHT22 with Pi

```
import RPi.GPIO as GPIO
from time import sleep
import Adafruit_DHT                                     #importing the Adafruit library

GPIO.setmode(GPIO.BOARD)
GPIO.setwarnings(False)
sensor = Adafruit_DHT.AM2302                          # create an instance of the sensor type
print ('Getting data from the sensor')
#humidity and temperature are 2 variables that store the values received from the sensor

humidity, temperature = Adafruit_DHT.read_retry(sensor,17)
print ('Temp={0:0.1f}*C humidity={1:0.1f}%'.format(temperature, humidity))
```



# Program: DHT22 interfaced with Raspberry Pi

## Code

```
GNU nano 2.2.6 File: IOTSR.py

import RPi.GPIO as GPIO
from time import sleep

import Adafruit_DHT

GPIO.setmode(GPIO.BOARD)
GPIO.setwarnings(False)

sensor = Adafruit_DHT.AM2302 # create an instance of the sensor type

print ('Getting data from the sensor')

#humidity and temperature are 2 variables that store the values received from the sensor
humidity, temperature = Adafruit_DHT.read_retry(sensor,17)

print ('Temp={0:0.1f}*C humidity={1:0.1f}%'.format(temperature, humidity))
```

## Output

```
pi@raspberrypi:~ $ python IOTSR.py
Getting data from the sensor
Temp=26.1*C humidity=65.9%
pi@raspberrypi:~ $
```

# Connection: Relay

- Connect the relay pins with the Raspberry Pi as mentioned in previous slides
- Set the GPIO pin connected with the relay's input pin as output in the sketch  
**GPIO.setup(13,GPIO.OUT)**
- Set the relay pin high when the temperature is greater than 30  
**if temperature > 30:**
  - GPIO.output(13,0) # Relay is active low**
  - print('Relay is on')**
  - sleep(5)**
  - GPIO.output(13,1) # Relay is turned off after delay of 5 seconds**

# Connection: Relay (contd..)

```
GNU nano 2.2.6                               File: IOTSR.py
import RPi.GPIO as GPIO
from time import sleep

import Adafruit_DHT

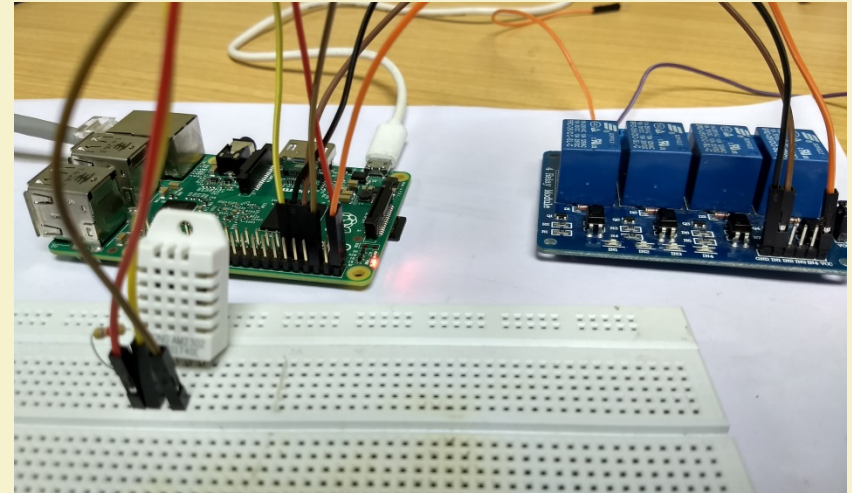
GPIO.setmode(GPIO.BOARD)
GPIO.setwarnings(False)
GPIO.setup(7, GPIO.OUT)

sensor = Adafruit_DHT.AM2302 # create an instance of the sensor type

print ('Getting data from the sensor')

#humidity and temperature are 2 variables that store the values received from the sensor
humidity, temperature = Adafruit_DHT.read_retry(sensor,17)

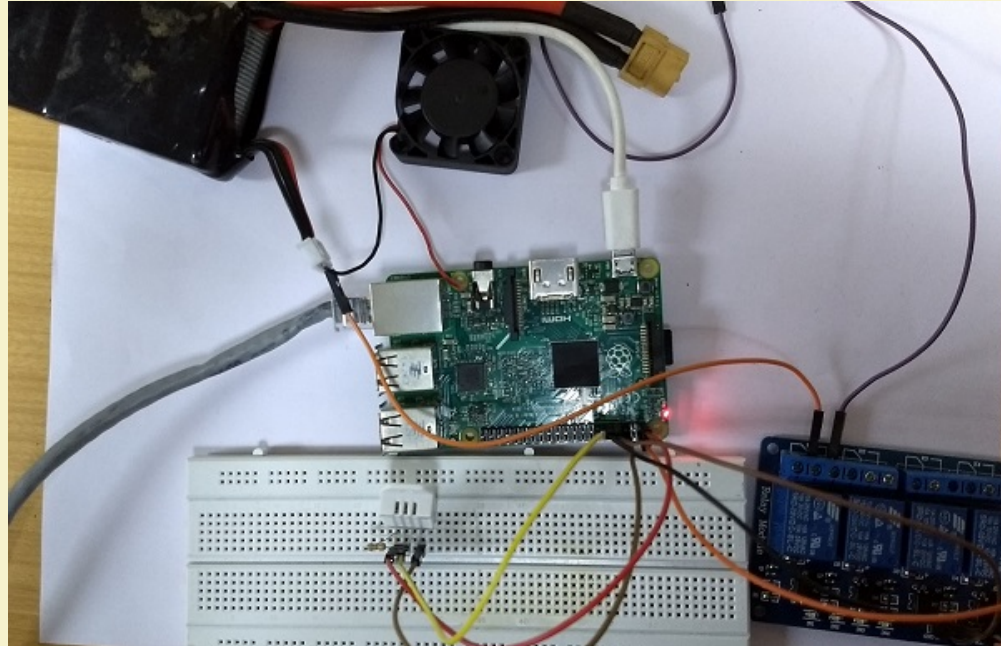
print ('Temp=(0:0.1f)*C humidity=(1:0.1f)%'.format(temperature, humidity))
if temperature > 20:
    GPIO.output(7,0) # Relay is active low
    print('Relay is on')
    sleep(5)
    GPIO.output(7,1) # Relay is turned off after delay of 5 seconds
```



# Connection: Fan

- Connect the Li-po battery in series with the fan
  - NO terminal of the relay -> positive terminal of the Fan.
  - Common terminal of the relay -> Positive terminal of the battery
  - Negative terminal of the battery -> Negative terminal of the fan.
- Run the existing code. The fan should operate when the surrounding temperature is greater than the threshold value in the sketch

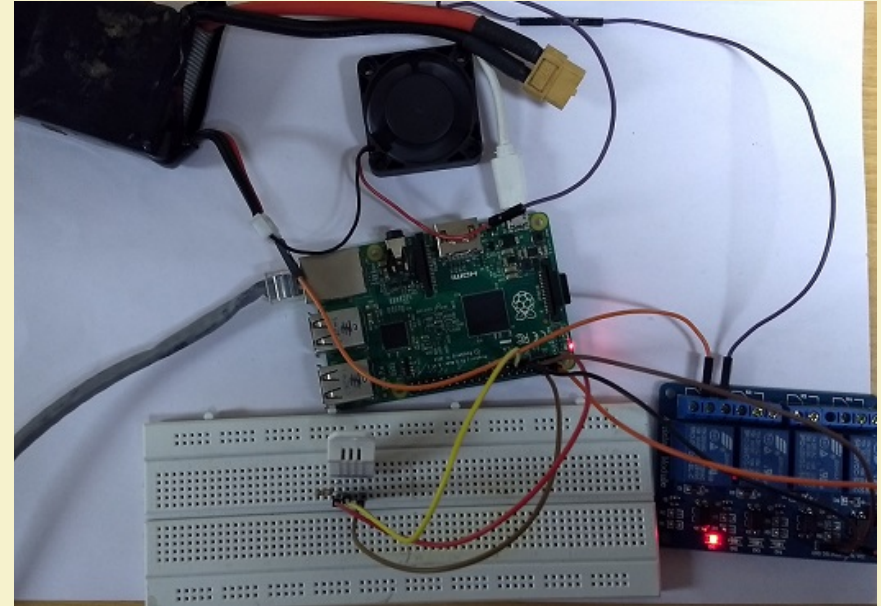
# Connection: Fan (contd..)



# Result

The fan is switched on whenever the temperature is above the threshold value set in the code.

Notice the relay indicator turned on.



# Thank You!!

