

Lecture Slides

Chapter 7

Shafts and Shaft Components

Tenth Edition in SI Units

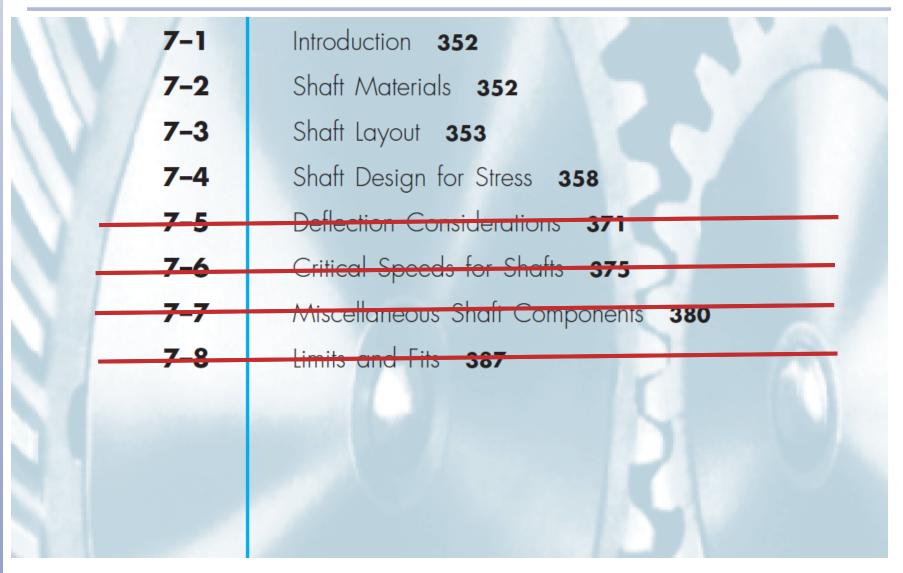
Shigley's Mechanical Engineering Design

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Chapter Outline



- Material Selection
- Geometric Layout
- Stress and strength
 - Static strength
 - Fatigue strength
- Deflection and rigidity
 - Bending deflection
 - Torsional deflection
 - Slope at bearings and shaft-supported elements
 - Shear deflection due to transverse loading of short shafts
- Vibration due to natural frequency

- Deflection primarily controlled by geometry, not material
- Stress controlled by geometry, not material
- Strength controlled by material property

- Shafts are commonly made from low carbon, CD or HR steel, such as AISI 1020–1050 steels.
- Fatigue properties don't usually benefit much from high alloy content and heat treatment.
- Surface hardening usually only used when the shaft is being used as a bearing surface.

- Cold drawn steel typical for d < 3 in.
- HR steel common for larger sizes. Should be machined all over.
- Low production quantities
 - Lathe machining is typical
 - Minimum material removal may be design goal
- High production quantities
 - Forming or casting is common
 - Minimum material may be design goal

Shaft Layout

- Issues to consider for shaft layout
 - Axial layout of components
 - Supporting axial loads
 - Providing for torque transmission
 - Assembly and Disassembly

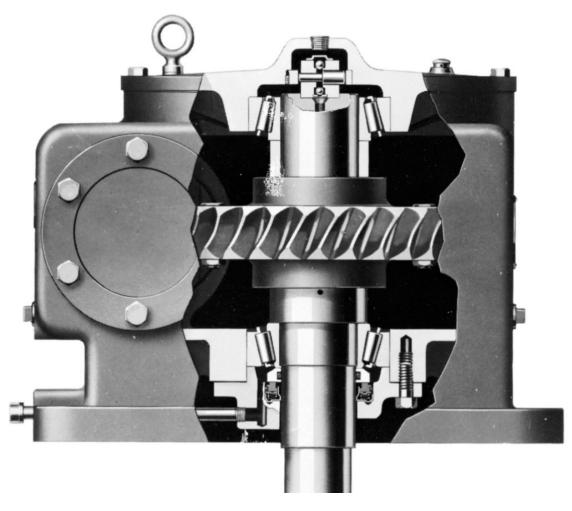
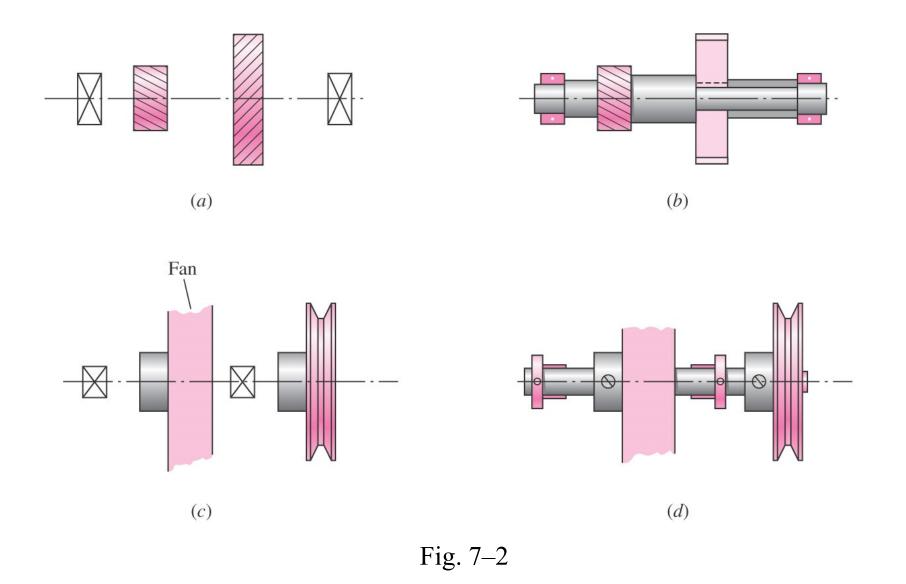


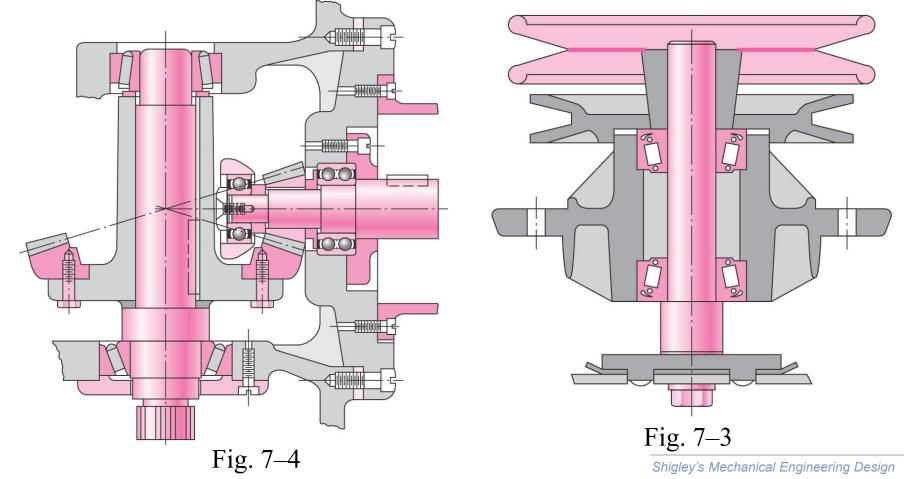
Fig. 7–1

Axial Layout of Components



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- Axial loads must be supported through a bearing to the frame.
- Generally best for only one bearing to carry axial load to shoulder
- Allows greater tolerances and prevents binding



Providing for Torque Transmission

- Common means of transferring torque to shaft
 - Keys
 - Splines
 - Setscrews
 - Pins
 - Press or shrink fits
 - Tapered fits
- Keys are one of the most effective
 - Slip fit of component onto shaft for easy assembly
 - Positive angular orientation of component
 - Can design key to be weakest link to fail in case of overload

Assembly and Disassembly

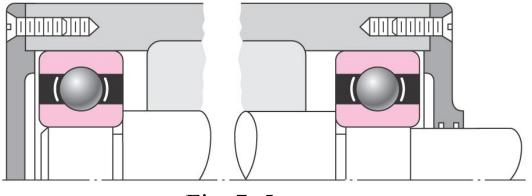


Fig. 7–5

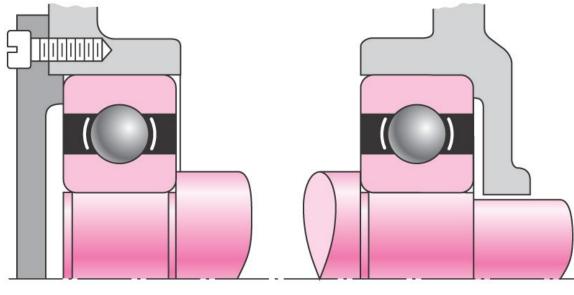


Fig. 7–6

Assembly and Disassembly

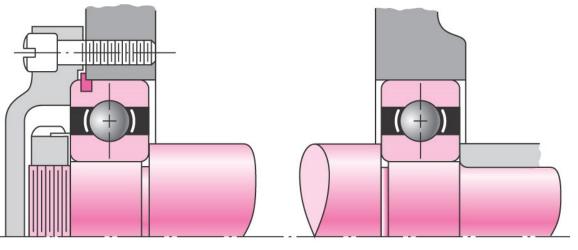


Fig. 7–7

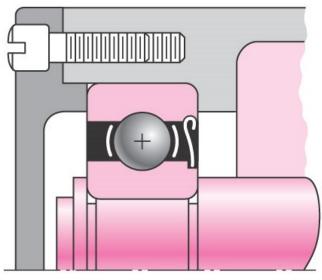


Fig. 7–8

- Stresses are only evaluated at critical locations
- Critical locations are usually
 - On the outer surface
 - Where the bending moment is large
 - Where the torque is present
 - Where stress concentrations exist

- Standard stress equations can be customized for shafts for convenience
- Axial loads are generally small and constant, so will be ignored in this section
- Standard alternating and midrange stresses

$$\sigma_a = K_f \frac{M_a c}{I} \qquad \sigma_m = K_f \frac{M_m c}{I} \qquad (7-1)$$

$$\tau_a = K_{fs} \frac{T_a r}{J} \qquad \tau_m = K_{fs} \frac{T_m r}{J} \qquad (7-2)$$

• Customized for round shafts

$$\sigma_{a} = K_{f} \frac{32M_{a}}{\pi d^{3}} \qquad \sigma_{m} = K_{f} \frac{32M_{m}}{\pi d^{3}}$$
(7-3)
$$\tau_{a} = K_{fs} \frac{16T_{a}}{\pi d^{3}} \qquad \tau_{m} = K_{fs} \frac{16T_{m}}{\pi d^{3}}$$
(7-4)

• Combine stresses into von Mises stresses

$$\sigma_a' = (\sigma_a^2 + 3\tau_a^2)^{1/2} = \left[\left(\frac{32K_f M_a}{\pi d^3} \right)^2 + 3\left(\frac{16K_{fs} T_a}{\pi d^3} \right)^2 \right]^{1/2}$$
(7-5)

$$\sigma'_{m} = (\sigma_{m}^{2} + 3\tau_{m}^{2})^{1/2} = \left[\left(\frac{32K_{f}M_{m}}{\pi d^{3}} \right)^{2} + 3\left(\frac{16K_{fs}T_{m}}{\pi d^{3}} \right)^{2} \right]^{1/2}$$
(7-6)

• Substitute von Mises stresses into failure criteria equation. For example, using modified Goodman line,

$$\frac{1}{n} = \frac{\sigma_a'}{S_e} + \frac{\sigma_m'}{S_{ut}}$$

$$\frac{1}{n} = \frac{16}{\pi d^3} \left\{ \frac{1}{S_e} \left[4(K_f M_a)^2 + 3(K_{fs} T_a)^2 \right]^{1/2} + \frac{1}{S_{ut}} \left[4(K_f M_m)^2 + 3(K_{fs} T_m)^2 \right]^{1/2} \right\}$$

• Solving for *d* is convenient for design purposes

$$d = \left(\frac{16n}{\pi} \left\{ \frac{1}{S_e} \left[4(K_f M_a)^2 + 3(K_{fs} T_a)^2 \right]^{1/2} + \frac{1}{S_{ut}} \left[4(K_f M_m)^2 + 3(K_{fs} T_m)^2 \right]^{1/2} \right\} \right)^{1/3}$$
(7-8)

- Similar approach can be taken with any of the fatigue failure criteria
- Equations are referred to by referencing both the Distortion Energy method of combining stresses and the fatigue failure locus name. For example, *DE-Goodman*, *DE-Gerber*, etc.
- In analysis situation, can either use these customized equations for factor of safety, or can use standard approach from Ch. 6.
- In design situation, customized equations for *d* are much more convenient.

• *DE-Gerber*

$$\frac{1}{n} = \frac{8A}{\pi d^3 S_e} \left\{ 1 + \left[1 + \left(\frac{2BS_e}{AS_{ut}} \right)^2 \right]^{1/2} \right\}$$
(7-9)
$$d = \left(\frac{8nA}{\pi S_e} \left\{ 1 + \left[1 + \left(\frac{2BS_e}{AS_{ut}} \right)^2 \right]^{1/2} \right\} \right)^{1/3}$$
(7-10)

where

$$A = \sqrt{4(K_f M_a)^2 + 3(K_{fs} T_a)^2}$$
$$B = \sqrt{4(K_f M_m)^2 + 3(K_{fs} T_m)^2}$$

• DE-ASME Elliptic $\frac{1}{n} = \frac{16}{\pi d^3} \left[4 \left(\frac{K_f M_a}{S_e} \right)^2 + 3 \left(\frac{K_{fs} T_a}{S_e} \right)^2 + 4 \left(\frac{K_f M_m}{S_y} \right)^2 + 3 \left(\frac{K_{fs} T_m}{S_y} \right)^2 \right]^{1/2}$ (7-11)

$$d = \left\{ \frac{16n}{\pi} \left[4 \left(\frac{K_f M_a}{S_e} \right)^2 + 3 \left(\frac{K_{fs} T_a}{S_e} \right)^2 + 4 \left(\frac{K_f M_m}{S_y} \right)^2 + 3 \left(\frac{K_{fs} T_m}{S_y} \right)^2 \right]^{1/2} \right\}^{1/3}$$
(7-12)

• DE-Soderberg

$$\frac{1}{n} = \frac{16}{\pi d^3} \left\{ \frac{1}{S_e} [4(K_f M_a)^2 + 3(K_{fs} T_a)^2]^{1/2} + \frac{1}{S_y} [4(K_f M_m)^2 + 3(K_{fs} T_m)^2]^{1/2} \right\}$$

$$d = \left(\frac{16n}{\pi} \left\{ \frac{1}{S_e} [4(K_f M_a)^2 + 3(K_{fs} T_a)^2]^{1/2} + \frac{1}{S_y} [4(K_f M_m)^2 + 3(K_{fs} T_m)^2]^{1/2} \right\} \right)^{1/3}$$
(7-14)

(/-13)

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- For rotating shaft with steady bending and torsion
 - Bending stress is completely reversed, since a stress element on the surface cycles from equal tension to compression during each rotation
 - Torsional stress is steady
 - Previous equations simplify with M_m and T_a equal to 0

Checking for Yielding in Shafts

- Always necessary to consider static failure, even in fatigue situation
- Soderberg criteria inherently guards against yielding
- ASME-Elliptic criteria takes yielding into account, but is not entirely conservative
- Gerber and modified Goodman criteria require specific check for yielding

• Use von Mises maximum stress to check for yielding,

$$\sigma_{\max}' = \left[(\sigma_m + \sigma_a)^2 + 3(\tau_m + \tau_a)^2 \right]^{1/2}$$

$$= \left[\left(\frac{32K_f (M_m + M_a)}{\pi d^3} \right)^2 + 3 \left(\frac{16K_{fs} (T_m + T_a)}{\pi d^3} \right)^2 \right]^{1/2}$$
(7-15)
$$n_y = \frac{S_y}{\sigma_{\max}'}$$
(7-16)

• Alternate simple check is to obtain conservative estimate of σ'_{\max} by summing σ'_a and σ'_m

$$\sigma'_{\max} \approx \sigma'_a + \sigma'_m$$

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Example 7–1

At a machined shaft shoulder the small diameter *d* is 28 mm, the large diameter *D* is 42 mm, and the fillet radius is 2.8 mm. The bending moment is 142.4 N·m and the steady torsion moment is 124.3 N·m. The heat-treated steel shaft has an ultimate strength of $S_{ut} = 735$ MPa and a yield strength of $S_y = 574$ MPa. The reliability goal is 0.99.

- (a) Determine the fatigue factor of safety of the design using each of the fatigue failure criteria described in this section.
- (b) Determine the yielding factor of safety.

Solution	(a) $D/d = 42/28 = 1.50$, $r/d = 2.8/28 = 0.10$, $K_t = 1.68$ (Fig. A-15- $K_{ts} = 1.42$ (Fig. A-15-8), $q = 0.85$ (Fig. 6-20), $q_{shear} = 0.92$ (Fig. 6-2)				
	From Eq. (6–32),				
		$K_f = 1 + 0.85(1.68 - 1) = 1.58$			
		$K_{fs} = 1 + 0.92(1.42 - 1) = 1.39$			
	Eq. (6–8):	$S'_e = 0.5(735) = 367.5$ MPa			
	Eq. (6–19):	$k_a = 4.51(735)^{-0.265} = 0.787$			
	Eq. (6–20):	$k_b = \left(\frac{28}{7.62}\right)^{-0.107} = 0.870$			
		$k_c = k_d = k_f = 1$			
Table 6–6:		$k_e = 0.814$			
		$S_e = 0.787(0.870)0.814(367.5) = 205$ MPa			

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For a rotating shaft, the constant bending moment will create a completely reversed bending stress.

 $M_a = 142.4 \text{ N} \cdot \text{m}$ $T_m = 124.3 \text{ N} \cdot \text{m}$ $M_m = T_a = 0$

Applying Eq. (7–7) for the DE-Goodman criteria gives

$$\frac{1}{n} = \frac{16}{\pi (0.028)^3} \left\{ \frac{\left[4\left(1.58 \cdot 142.4\right)^2\right]^{1/2}}{205 \times 10^6} + \frac{\left[3\left(1.39 \cdot 124.3\right)^2\right]^{1/2}}{735 \times 10^6} \right\} = 0.615$$

Answer

n = 1.62 DE-Goodman

Similarly, applying Eqs. (7–9), (7–11), and (7–13) for the other failure criteria,

Answer	n = 1.87	DE-Gerber
Answer	n = 1.88	DE-ASME Elliptic
Answer	n = 1.56	DE-Soderberg

For comparison, consider an equivalent approach of calculating the stresses and applying the fatigue failure criteria directly. From Eqs. (7–5) and (7–6),

$$\sigma_a' = \left[\left(\frac{32 \cdot 1.58 \cdot 142.4}{\pi (0.028)^3} \right)^2 \right]^{1/2} = 104.4 \text{ MPa}$$

$$\sigma_m' = \left[3 \left(\frac{16 \cdot 1.39 \cdot 124.3}{\pi (0.028)^3} \right)^2 \right]^{1/2} = 69.4 \text{ MPa}$$

Taking, for example, the Goodman failure criteria, application of Eq. (6-46) gives

$$\frac{1}{n} = \frac{\sigma'_a}{S_e} + \frac{\sigma'_m}{S_{ut}} = \frac{104.4}{205} + \frac{69.4}{735} = 0.604$$

n = 1.62

which is identical with the previous result. The same process could be used for the other failure criteria.

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(b) For the yielding factor of safety, determine an equivalent von Mises maximum stress using Eq. (7-15).

$$\sigma_{\max}' = \left[\left(\frac{32(1.58)(142.4)}{\pi (0.028)^3} \right)^2 + 3 \left(\frac{16(1.39)(124.3)}{\pi (0.028)^3} \right)^2 \right]^{1/2} = 125.4 \text{ MPa}$$
$$n_y = \frac{S_y}{\sigma_{\max}'} = \frac{574}{125.4} = 4.58$$

Answer

For comparison, a quick and very conservative check on yielding can be obtained by replacing σ'_{max} with $\sigma'_a + \sigma'_m$. This just saves the extra time of calculating σ'_{max} if σ'_a and σ'_m have already been determined. For this example,

$$n_y = \frac{S_y}{\sigma'_a + \sigma'_m} = \frac{574}{104.4 + 69.4} = 3.3$$

which is quite conservative compared with $n_y = 4.58$.

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- Stress analysis for shafts is highly dependent on stress concentrations.
- Stress concentrations depend on size specifications, which are not known the first time through a design process.
- Standard shaft elements such as shoulders and keys have standard proportions, making it possible to estimate stress concentrations factors before determining actual sizes.

Table 7-1

First Iteration Estimates for Stress-Concentration Factors K_t and K_{ts} .

Warning: These factors are only estimates for use when actual dimensions are not yet determined. Do *not* use these once actual dimensions are available.

	Bending	Torsional	Axial
Shoulder fillet—sharp ($r/d = 0.02$)	2.7	2.2	3.0
Shoulder fillet—well rounded ($r/d = 0.1$)	1.7	1.5	1.9
End-mill keyseat ($r/d = 0.02$)	2.14	3.0	
Sled runner keyseat	1.7		_
Retaining ring groove	5.0	3.0	5.0

Missing values in the table are not readily available.

Reducing Stress Concentration at Shoulder Fillet

- Bearings often require relatively sharp fillet radius at shoulder
- If such a shoulder is the location of the critical stress, some manufacturing techniques are available to reduce the stress concentration
 - (a) Large radius undercut into shoulder
 - (b) Large radius relief groove into back of shoulder
 - (c) Large radius relief groove into small diameter of shaft

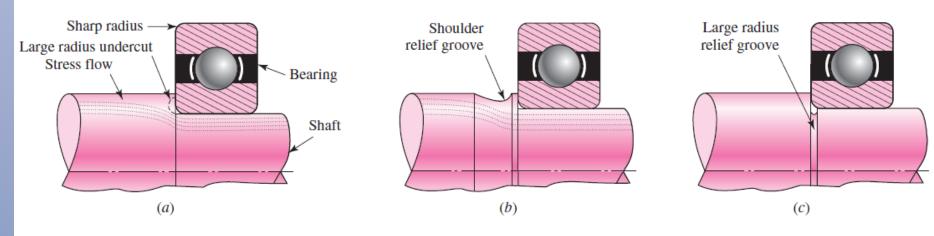


Fig. 7–9

Example 7–2

This example problem is part of a larger case study. See Chap. 18 for the full context.

A double reduction gearbox design has developed to the point that the general layout and axial dimensions of the countershaft carrying two spur gears has been proposed, as shown in Fig. 7-10. The gears and bearings are located and supported by shoulders, and held in place by retaining rings. The gears transmit torque through keys. Gears have been specified as shown, allowing the tangential and radial forces transmitted through the gears to the shaft to be determined as follows.

$$W_{23}^t = 540 \text{ lbf}$$
 $W_{54}^t = 2431 \text{ lbf}$

 $W_{23}^r = 197 \, \text{lbf}$ $W_{54}^r = 885 \, \text{lbf}$

where the superscripts t and r represent tangential and radial directions, respectively; and, the subscripts 23 and 54 represent the forces exerted by gears 2 and 5 (not shown) on gears 3 and 4, respectively. Proceed with the next phase of the design, in which a suitable material is selected, and appropriate diameters for each section of the shaft are estimated, based on providing sufficient fatigue and static stress capacity for infinite life of the shaft, with minimum safety factors of 1.5.

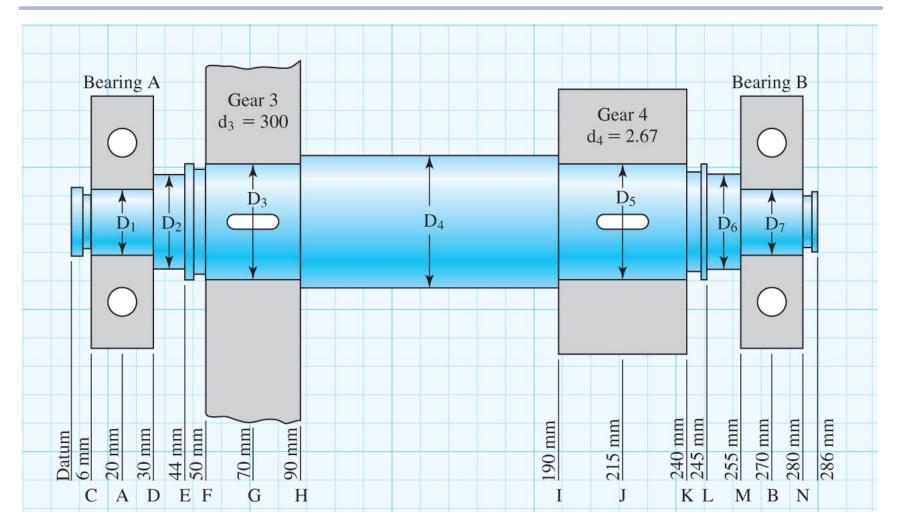
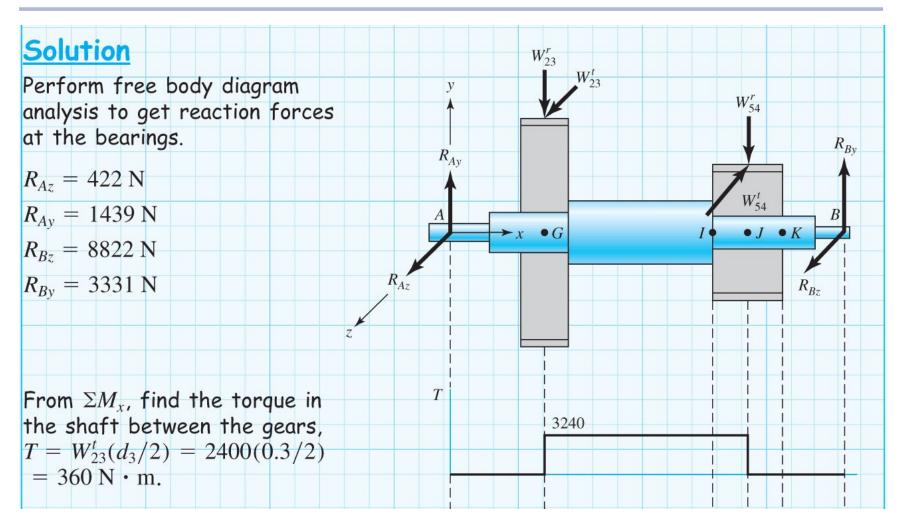
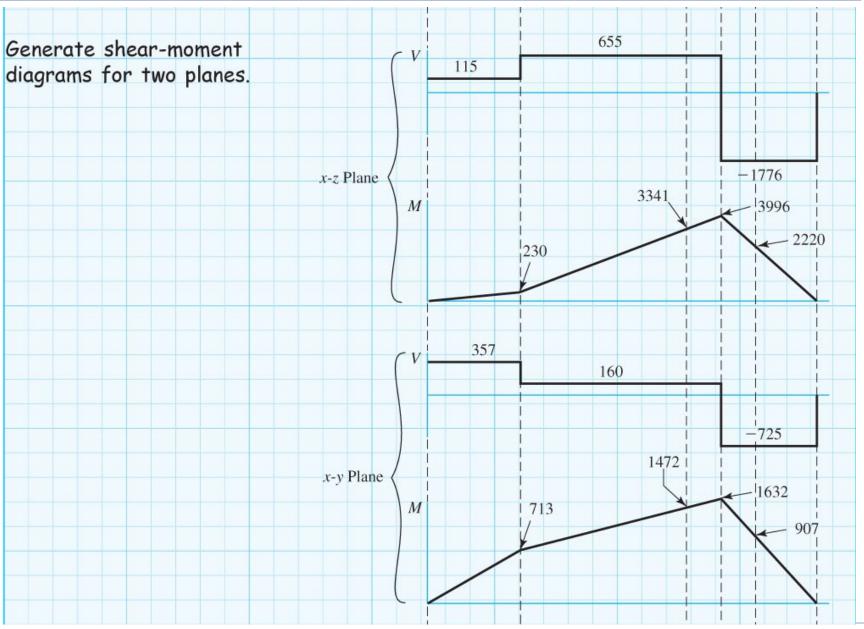
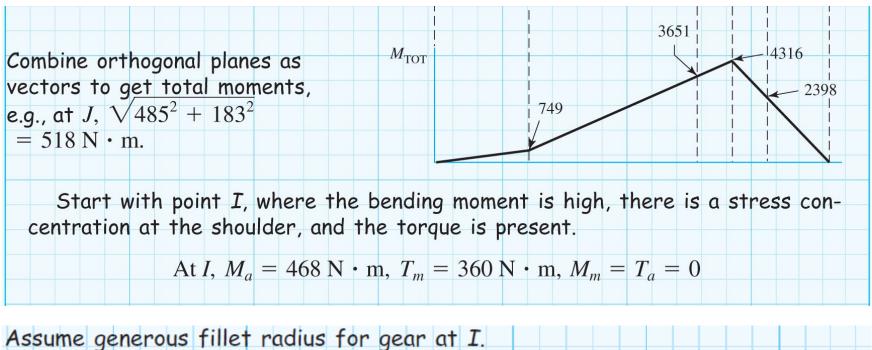


Fig. 7–10

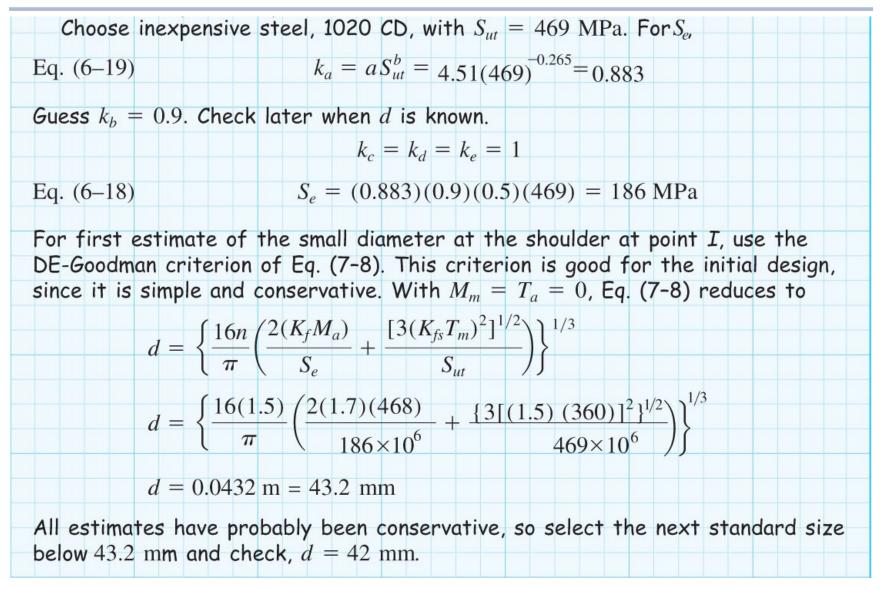




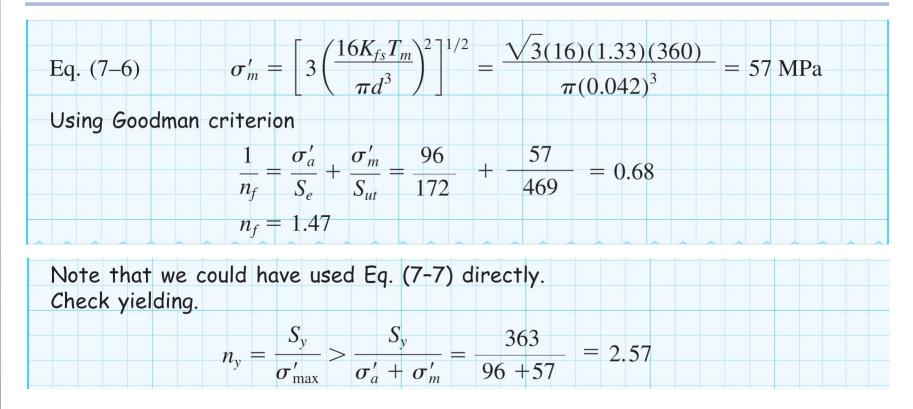
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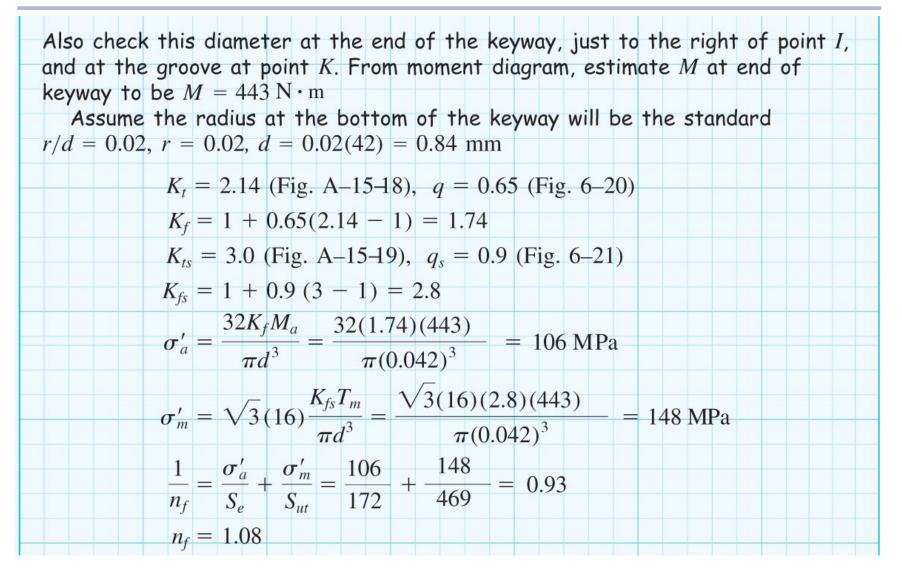


From Table 7-1, estimate $K_t = 1.7$, $K_{ts} = 1.5$. For quick, conservative first pass, assume $K_f = K_t$, $K_{fs} = K_{ts}$.



A typical D/d ratio for support at a shoulder is D/d = 1.2, thus, $D = 1.2 \times 42 =$ 50.4 mm. Use D = 50 mm. A nominal 50 mm cold-drawn shaft diameter can be used. Check if estimates were acceptable. D/d = 50/42 = 1.19Assume fillet radius $r = d/10 \approx 4$ mm, r/d = 0.1 $K_t = 1.6$ (Fig. A-15-9), q = 0.82 (Fig. 6-20) $K_f = 1 + 0.82(1.6 - 1) = 1.49$ Eq. (6–32) $K_{ts} = 1.35$ (Fig. A-15-8), $q_s = 0.95$ (Fig. 6-21) $K_{fs} = 1 + 0.95(1.35 - 1) = 1.33$ $k_a = 0.883$ (no change) $k_b = \left(\frac{42}{7.62}\right)^{-0.107} = 0.833$ Eq. (6–20) $S_e = (0.883)(0.833)(0.5)(469) = 172$ MPa $\sigma'_{a} = \frac{32K_{f}M_{a}}{\pi d^{3}} = \frac{32(1.49)(468)}{\pi (0.042)^{3}} = 96 \text{ MPa}$ Eq. (7–5)

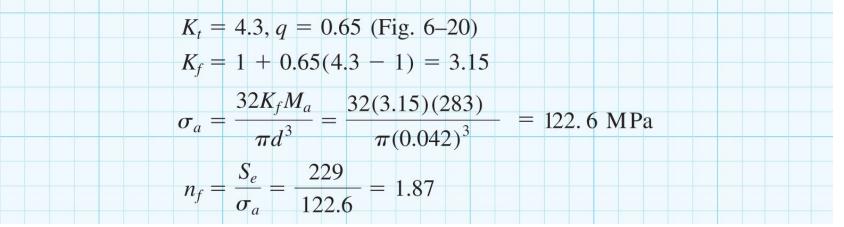




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The keyway turns out to be more critical than the shoulder. We can either increase the diameter or use a higher strength material. Unless the deflection analysis shows a need for larger diameters, let us choose to increase the strength. We started with a very low strength and can afford to increase it to avoid larger sizes. Try 1050 CD with $S_t = 69$ OMPa. Recalculate factors affected by S_{ut} , i.e., $k_a \rightarrow S_e$; $q \rightarrow K_f \rightarrow \sigma'_a$ $k_a = 4.51(690)^{-0.265} = 0.797, S_e = 0.797(0.833)(0.5)(690) = 229 \text{ MPa}$ $q = 0.72, K_f = 1 + 0.72(2.14 - 1) = 1.82$ $\sigma'_a = \frac{32(1.82)(443)}{\pi (0.042)^3} = 110.8 \text{ MPa}$ $\frac{1}{n_f} = \frac{110.8}{229} + \frac{148}{690} = 0.7$ $n_f = 1.43$ Since the Goodman criterion is conservative, we will accept this as close enough to the requested 1.5. Check at the groove at K, since K, for flat-bottomed grooves are often very high. From the torgue diagram, note that no torgue is present at the groove. From the moment diagram, $M_a = 283$ N·m, $M_m = T_a = T_m = 0$. To guickly check if this location is potentially critical, just use $K_f = K_t = 5.0$ as an estimate, from Table 7-1. $\sigma_a = \frac{32K_f M_a}{\pi d^3} = \frac{32(5)(283)}{\pi (0.042)^3} = 194.5 \text{ MPa}$ $n_f = \frac{S_e}{\sigma_a} = \frac{229}{194.5} = 1.18$

This is low. We will look up data for a specific retaining ring to obtain K_f more accurately. With a quick on-line search of a retaining ring specification using the website www.globalspec.com, appropriate groove specifications for a retaining ring for a shaft diameter of 42 mm are obtained as follows: width, a = 1.73 mm; depth, t = 1.22 mm; and corner radius at bottom of groove, r = 0.25 mm. From Fig. A-15-16, with r/t = 0.25/1.22 = 0.205, and a/t = 1.73/1.22 = 1.42



Quickly check if point M might be critical. Only bending is present, and the moment is small, but the diameter is small and the stress concentration is high for a sharp fillet required for a bearing. From the moment diagram, $M_a = 113$ N·m, and $M_m = T_m = T_a = 0$. Estimate $K_t = 2.7$ from Table 7-1, d = 25 mm, and fillet radius r to fit a typical bearing. r/d = 0.02, r = 0.02(25) = 0.5q = 0.7 (Fig. 6–20) $K_f = 1 + (0.7)(2.7 - 1) = 2.19$ $\sigma_a = \frac{32K_f M_a}{\pi d^3} = \frac{32(2.19)(113)}{\pi (0.025)^3} = 161 \text{ MPa}$ $n_f = \frac{S_e}{\sigma_a} = \frac{229}{161} = 1.42$ This should be OK. It is close enough to recheck after the bearing is selected. With the diameters specified for the critical locations, fill in trial values for the rest of the diameters, taking into account typical shoulder heights for bearing and gear support.

$$D_1 = D_7 = 25 \text{ mm}$$

$$D_2 = D_6 = 35 \text{ mm}$$

$$D_3 = D_5 = 42 \text{ mm}$$

$$D_4 = 50 \text{ mm}$$

The bending moments are much less on the left end of the shaft, so D_1 , D_2 , and D_3 could be smaller. However, unless weight is an issue, there is little advantage to requiring more material removal. Also, the extra rigidity may be needed to keep deflections small.