## Lidar Data Processing Using QGIS and GRASS for Processing and Analysing Lidar Data

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## Using QGIS and GRASS for Processing and Analysing Lidar Data

### Pre-requisites

To follow this workshop you will need QGIS 1.7 and GRASS 6.4 installed on your machine. On Windows these programs are best installed via OSGeo4W installer <a href="http://trac.osgeo.org/osgeo4w/">http://trac.osgeo.org/osgeo4w/</a>

To install these packages on linux systems refer to the installation guides for the specific system e.g. https://wiki.ubuntu.com/UbuntuGIS

Detailed instructions on how to do this can be found in the pre-course information and are not repeated here.

## Session 1 - 9:00-11:00

The aim of this lab is familiarise yourself with both QGIS and the GRASS plugin. In this session you will undertake the following tasks:

- view ArcGIS ascii raster files in QGIS
- edit the properties of a raster in QGIS
- create a vector file in QGIS
- edit a vector file in QGIS
- set up a location with the GRASS plugin
- import a vector file using the GRASS plugin
- import an ArcGIS file using the GRASS plugin
- set a region of interest using the GRASS plugin
- create a hill shaded model of the lidar raster using the GRASS plugin
- digitise features identified in the lidar model to a shapefile

Each of these tasks stand alone as useful GIS tools but together they provide a workflow for visualising lidar raster data and recording the features from it. Illustrations in this booklet show the icons on screen for each task. The full menu options are notated as follows: File > Open.

## Task 1 - Opening ArcGIS ascii raster files in QGIS and editing their properties

1. Start QGIS. Familiarise yourself with the layout of the screen. Some of the toolbars at the top of the screen may be compressed. To expand them use the double arrow

»

To move the toolbars so that all the icons are visible use the vertical dotted line to the left of each toolbar. Hover your mouse over this line to get cross-hairs then click and drag to move the menu to another part of the screen. To find out the purpose of any icon hover your mouse over it.

Below are the key toolbars for this session – you should check that all these are visible.

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2. When you are happy that you can see all the icons in the toolbars your first task will be to set the project properties and save the project. From the settings menu select Project Properties 4th International Summer School "3D Modeling in Archaeology and Cultural Heritage 2011", 29 August - 4 September 2011, Grosseto, Italy

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3. To set the units in the General tab of the Project Properties box select metres and click apply

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4. To set the coordinate reference system (CRS) click on the CRS tab. The data for this tutorial is from the UK so we will search through the list for OSGB 1936. A quick way to do this is to type in the EPSG ID code 27700 and click find. Click apply to set the CRS.

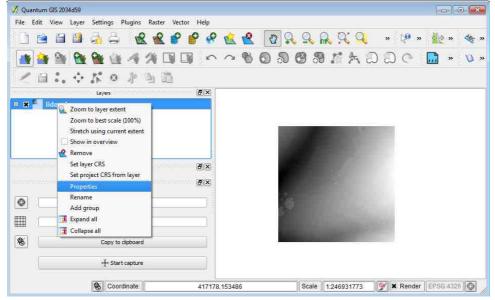
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|                   | NZGD49 / Wanganui Circuit   | 27211 | 2382           |   |
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|                   | OSGB 1936 / British National Grid (EPSG : 27700)  |       |                |   |

- 5. Click OK to close Project Properties and return to the main screen.
- 6. Use File>save to save the project
- 7. Next we will open an ArcGIS ascii raster (lidar\_1.asc) using the tool bar icon (layer > add raster layer). Be sure to select the correct file type from the drop down menu at the bottom right of the "open raster" window.

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8. To improve the raster display we will now edit the raster properties. In the menu bar, right click on the raster's name and select properties.



9. Edit the symbology so that the image is stretched to min and max values. This preference can be saved as the default for the file.

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10. The raster display should now resemble the image below.

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- 11. Return to the properties menu. In this menu can be found a variety of options for colouring the map, editing transparency and viewing metadata. Take some time to familiarise yourself with these options.
- 12. Repeat the steps above for the other three ASCII rasters (lidar\_2.asc, lidar\_3.asc and lidar\_4.asc) until you have all four displayed on screen. Don't forget to save your project!

## Task 2 - Creating a vector file in QGIS

1. For this task you are going to create a shapefile in QGIS that provides a boundary for the area covered by the lidar rasters. From the toolbar select the create new vector layer icon to open the window below



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- 2. Select the type of file you want to create (point / line / polygon). We want to define an area so a polygon will be most appropriate.
- 3. Specify the CRS of the shapefile (OSGB 36 as in Task 1). Notice that the CRS of the project is available for quick selection.

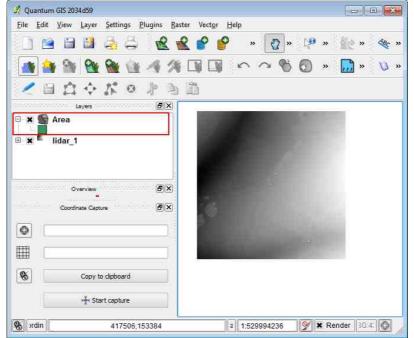
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| NZGD49 / Wanganui Circuit   | 27211                          | 2382              |     |
| NZGD49 / Wellington Circuit   | 27213                          | 2384              |     |
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4. Each shapefile has an attribute table where data about the features can be

stored. Add the attribute fields you want in the New Attribute section. In this case we will make a text field called "field1". Click add to attributes list to save the attribute field then click OK

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5. Name the shapefile "Area" and save it to your Archaeology 3D working area. Click OK to create the shapefile. It will automatically be added to the navigation menu on the left of your screen.

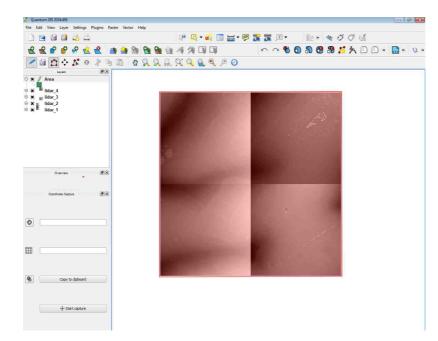


6. To edit the shapefile highlight its name in the menu and click on the Toggle Edit icon in the toolbar.

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| 7. Select the draw polygon   |   |

8. Draw your study area around the four lidar tiles, right click to finish the square.



9. You will be given the option to record attribute data for Field1.

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- 10.Click on the Toggle Edit icon again to finish drawing and save your edits.
- 11.Make the vector file editable again and experiment with moving the area using the move feature icon and editing the nodes using the node tool
- 12.Save your dedits, making sure that the area still represents the coverage of the lidar rasters.
- 13.By right clicking on the name of the file in the navigation bar and selecting Properties you can edit the symbology. Experiment with different display options for your shapefile.

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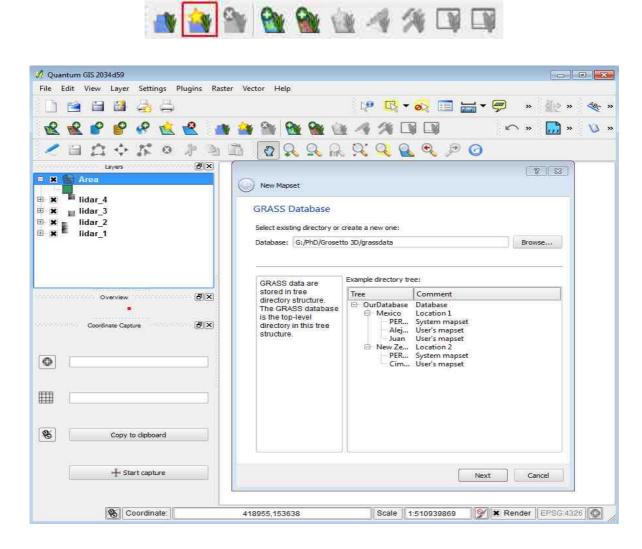
#### Rebecca Bennett

## Task 3 - Creating a GRASS location

1. To create a hill shade from the rasters in QGIS requires use of the GRASS plugin. The toolbar is shown below.



2. The first step is to create Location, which is essentially a directory in which GRASS will store the files you will make. The structure of this directory is very important and can be fiddly to get right in GRASS itself – the QGIS plugin makes the process of establishing a location much easier. Click on the Create new mapset icon to open the window below:



3. Browse to a directory in which to store your data. When using for the first time you should create a directory called "grassdata" to keep all your GRASS locations in. Click next.

4. Select "create a new location", give your location a name (with no spaces or special characters) and click next

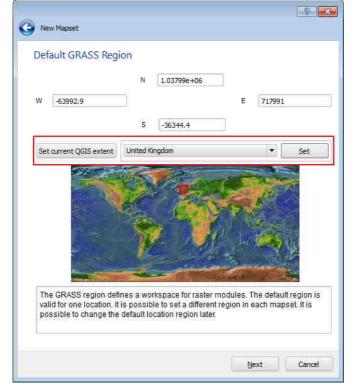
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5. We will now set the CRS for the GRASS location. You will see that the plugin suggests recently used systems at the bottom of the window. Select the OSGB36 CRS (using the same ESPG ID as before). Click next.

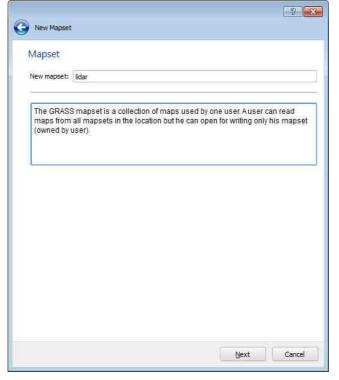
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6. Set the Region of interest. This part is particularly important as GRASS only performs its operations within the bounds of this region of interest. For

simplicity here select the UK as the region form the drop down menu. (For practical reasons we will redefine this later to represent our study area). Click set and the North, South, East and West bounds will change. Click next.

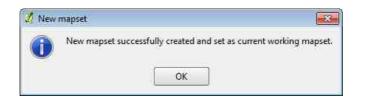


7. Within the location create a mapset to work in. Click next



14. The final screen confirms the location and mapset you have created. Click finish to return to the QGIS main screen. The mapset will now be open and the GRASS toolbar icons active.

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| Create New Mapset                      |               |
| Create New Mapset                      |               |
| Database: G:/PhD/Grosetto 3D/grassdata |               |
| Location: Archaeology_3D               |               |
| Mapset: lidar                          |               |
|  |               |
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|  | Einish Cancel |
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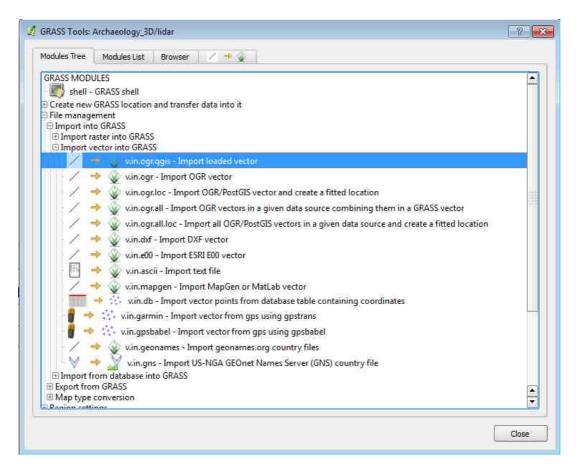


## Task 4 - Changing the GRASS Region

1. We now need to change the region to reflect our study area to ensure any processes we undertake in GRASS function correctly. To do this we will import the vector file we created in task 2 into the GRASS mapset and set the region to match it. On the GRASS tool bar select the GRASS tools icon



2. In the Modules Tree tab navigate to File management>Import Vector into Grass > Import Loaded Vector. Click to open the tool.



3. Select your vector file (created in task 2) from the drop down menu. Give the GRASS vector you will create a name (you may wish to prefix this with "GRASS" if you intend to use the same name as the original shapefile to denote that it is a GRASS vector e.g. GRASSarea). Click "Run" then "View Output" to add the GRASS vector to the navigation menu to the left of the QGIS screen.

| Modules Tree   | Modules List B      | rowser         | 1. 🔹 🖗 | 1     |   |
|----------------|---------------------|----------------|--------|-------|---|
| Module: v.in.o | gr. qgis            |                |        |       |   |
| Options        | Output Manual       |                |        |       |   |
| OGR ve         | tor layer           |                |        |       |   |
| area           | 100.000             |                |        |       |   |
|                |                     |                |        |       |   |
| -Name fo       | r output vector map |                |        |       |   |
| GRASS          | Jarea               |                |        |       |   |
|                |                     |                |        |       |   |
|                |                     |                |        |       |   |
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| Show ad        | vanced options >>   |                |        |       |   |
| Show ad        | vanced options >>   |                |        |       |   |
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| Show ad        | vanced options >>   |                |        |       |   |
| Show ad        | vanced options >>   |                |        |       |   |
| Show ad        |                     | - times as the |        | Class | ; |
| Show ad        | vanced options >>   | View output    | t      | Close |   |
| Show ad        |                     | View output    | t      | Close |   |

4. You can check the source of a file by hovering your mouse over its name in the navigation bar. The symbology of the GRASS vector can be edited in the same way as for QGIS vectors (See task 2).

| Quantum GIS 2034d59<br>File Edit View Laye | r Settings Plugins Raste | r Vector Help           |                                |
|--|--------------------------|-------------------------|--------------------------------|
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| 2 🔍 🔍 🔒                                    | Q Q Q                    | P 🖸 🐴 🕯                 | 🛚 🐿 🐿 💁 🔺                      |
| GRASS are                                  |                          | ð×                      |                                |
| 🗆 🕱 🌑 area                                 | G:/PhD/Grosetto 3D       | //grassdata/Archaeology | _3D/lidar/GRASS_area/1_polygon |
|  |                          |                         |                                |
|  |                          |                         |                                |
|  |                          |                         |                                |

5. To set the region to match this vector select the GRASS tools Icon again and navigate to File >Config > Region > Region Settings > Set Region to match multiple vectors

| Modules Tree   | Modules List  | Browser     | 38                                  | l   |
|--|---|-------------|-------------------------------------|---|
| E Create new<br>File manage<br>Region setti<br>g.re<br>g.re                          | GRASS shell<br>GRASS location<br>ement<br>ings<br>gion.save - Save<br>gion.zoom - Shr | the current | region as a na<br>region until it r | neets non-NULL data                         |
|  | A DECIDENT OF THE OWNER   |             | E ERRO UNICATION                    | ch multiple rasters<br>tch multiple vectors |
| Projection r<br>Raster<br>Vector<br>Imagery<br>Database<br>d'isualiza<br>Convert coo | tion  |             |                                     |   |
|  |   |             |                                     | -   |

6. Type in the name of your vector file. Click Run and close.

| Modules Tree | Modules List      | Browser      | 59 | -     |   |
|--------------|-------------------|--------------|----|-------|---|
| 1            | n.multiple.vector |              |    |       |   |
| Options      | Output Manua      |              |    |       |   |
| Type in m    | iap names separat | ed by a comm | a  |       |   |
| GRASS        | _area             |              |    |       |   |
|              |                   |              |    |       |   |
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|              |                   |              |    |       |   |
|              |                   | 100%         |    |       |   |
| fr.          | Run               | 100%         |    | Close | ĩ |

7. To make sure that the region is set. Close the GRASS mapset using the Close

Mapset Icon



8. Re-open the mapset using the Open Mapset Icon. Select your mapset.

| Gisdbase | rosetto 3D/grassdata | Browse |
|----------|----------------------|--------|
| Location | Archaeology_3D       |        |
| Mapset   | lidar                |        |

9. A red line will now appear on your screen showing the extent of the current GRASS region. Close the vector files by unchecking the box beside them in the navigation menu to see this more clearly.

| 🔏 Quantum GIS 2034d59                                      |  |
|--|--|
| <u>Eile Edit View Layer Settings Plugins Raster Vector</u> | Help                                     |
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| 2 Q Q R X Q Q 9 0  | 🐴 🆄 🖄 🔮 🔮 🍓 🚿 🕅 🖼                        |
| Layers   |  |
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| Copy to dipboard   |  |
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| 8 200rdinate 416629,153414                                 | 3cale 1:382676579 💓 🗙 Render EPSG:4320 💽 |

10.The QGIS /GRASS toolbar gives only a selection of the most common GRASS functions. You can access all the GRASS functions by using the "GRASS shell" to enter commands. We will now use the GRASS shell within QGIS to check the resolution of the region. From the GRASS Tools window, click to open the GRASS shell

| GRASS Tools: Archaeology_3D/lidar   | 8     |
|---|-------|
| Modules Tree Modules List Browser   |       |
| GRASS MODULES   |       |
| shell - GRASS shell   |       |
| <ul> <li>Create new GRASS location and transfer data into it</li> <li>File management</li> <li>Region settings</li> <li>Projection management.</li> <li>Raster</li> <li>Vector</li> <li>Imagery</li> <li>Database</li> <li>3d Visualization</li> <li>Convert coordinates</li> <li>Help</li> </ul> |       |
|   | Close |

11.In the shell window type g.region (the GRASS command for the region settings). Hit return. A new window will open.



12.To check your current settings switch to the "Print" tab and tick "Print the Current region". Click Run.

| Existing    | Bounds                          | Resolution                          | Effects          | Print     | Optional | 4 | 10   |
|-------------|---------------------------------|-------------------------------------|------------------|-----------|----------|---|------|
| Print the o | urrent region                   |                                     |                  |           |          |   | (    |
| Print the a | urrent region in                | lat/long using th                   | e current ellips | old/datum | i        |   |      |
| Print the o | urrent region e                 | xtent                               |                  |           |          |   | (    |
|             |                                 | ap center coordi                    | nates            |           |          |   | - 1  |
|             | urrent region in                | 않았다. 영상에 집에 집에 집에 집에 집에 집에 집에 들어졌다. |                  |           |          |   |      |
|             | urrent region in                |                                     |                  |           |          |   | (    |
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|             |                                 | gle (degrees CC\                    | N)               |           |          |   | (    |
|             | ID settings                     |                                     |                  |           |          |   | -    |
|             |                                 |                                     |                  |           |          |   |      |
|             |                                 | ing box in lat/lon                  | g on wasan       |           |          |   | 9    |
|             | aximum bound<br>Il script style | ing box in lat/lon                  | g on wasa4       |           |          |   | (    |
|             |                                 | ng box in lat/lon                   | g off WG30+      |           |          |   | - 03 |

13. The window will switch to the "Command Output" tab where the current region settings will be displayed. You will see that the resolution settings (nsres and ewres) are set to 1000m. As the data we will be using is of 1m resolution we need to change this setting.

| Resolution               | Effects Print Optional Command output          |   |
|--------------------------|--|---|
| (Sat Aug 06              | 16:57:18 2011)                                 | Π |
| g,region -p              | vect=GRASS_area@lidar                          |   |
| projection:              | 99 (Transverse Mercator)                       |   |
| zone:                    | 0  |   |
| datum:                   | towgs84=446.448,-125.157,542.06,0.15,0.247,0.8 | 4 |
| ellipsoid:               | a=6377563.396 es=0.00667053976159746           |   |
| north:                   | 153361.57152434                                |   |
| south:                   | 152361.57152434                                |   |
| west:                    | 417436.70220781                                |   |
| east:                    | 418436.70220781                                |   |
| nsres:                   | 1000   |   |
| ewres:                   | 1000   |   |
| rows:                    | 1  |   |
| cols:                    | 1  |   |
| cells:                   | 1  | 1 |
| (Sat Aug 06              | 16:57:20 2011) Command finished (1 sec)        | l |
| < III.                   |  |   |
| S. 11. S. 11.            |  | _ |
| Manuscource in Collabert | 16:57:20 2011) Command finished (1 sec)        |   |
|                          |  |   |
| ge                       | ear output                                     |   |

#### 14.In the "Existing" tab select your imported vector from the drop down menu.

| ×                                 |                       |                                      | _            | -       | _        |                                      |
|-----------------------------------|-----------------------|--------------------------------------|--------------|---------|----------|--------------------------------------|
| Existing                          | Bounds                | Resolution                           | Effects      | Print   | Optional | <                                    |
| Set from defa                     |                       |                                      |              |         |          | (d                                   |
| Save as defa                      | energie energie en en |                                      |              |         |          | (s                                   |
| iet current regio                 | n from name           | d region:                            |              |         |          | (region=name                         |
|                                   |                       |                                      |              |         |          | 1                                    |
| multiple] Set reg                 | jion to match         | this raster map:                     |              |         | _        | (rast=name                           |
|                                   |                       |                                      |              |         | -        | I                                    |
|                                   |                       |                                      |              |         |          | 1                                    |
| at region to ma                   | tch thic 3D ra        | eter man (hoth '                     | 20 and 20 va | hart    |          | /ract3d=name                         |
| et region to ma                   | tch this 3D ra        | ster map (both :                     | 2D and 3D va | lues):  |          | )<br>(rast3d=name)                   |
|                                   |                       | 1990                                 |              | lues):  |          | ]<br>(rast3d=name<br>]               |
| multiple] Set reg                 | jion to match         | ister map (both :<br>this vector map |              | ilues): |          | ]<br>(rast3d=name<br>)<br>(vect=name |
|                                   | jion to match         | 1990                                 |              | ilues): |          | ]                                    |
| multiple] Set reg<br>GRASS_area@l | jion to match         | this vector map                      |              | ilues): |          | ]                                    |
| multiple] Set reg                 | jion to match         | this vector map                      |              | ilues): |          | ]<br>(vect=name                      |
| multiple] Set reg<br>GRASS_area@l | jion to match         | this vector map                      |              | ilues): |          | ]<br>(vect=name                      |
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| multiple] Set reg<br>GRASS_area@l | jion to match         | this vector map                      |              | ilues): |          | ]<br>(vect=name                      |
| multiple] Set reg<br>GRASS_area@l | jion to match         | this vector map                      |              | ilues): |          | ] (vect=name<br>] (3dview=name       |

15.In the "Resolution" tab enter the value 1 in the NS and EW grid resolution boxes. Click run

| 😸 g.region [general]                                |                  |       | /[       |               |
|---|------------------|-------|----------|---------------|
| Manages the boundary definitions for the            | e geographic rei | gion. |          |               |
| Existing Bounds Resolution                          | Effects          | Print | Optional | 4 ¥ ×         |
| Number of rows in the new region:                   |                  |       |          | (rows=value)  |
| Number of columns in the new region:                |                  |       |          | (cols=value)  |
| Grid resolution 2D (both north-south and east-      | vest):           |       |          | (res=value)   |
| I<br>3D grid resolution (north-south, east-west and | top-bottom):     |       |          | (res3=value)  |
| North-south grid resolution 2D:                     |                  |       |          | (nsres=value) |
| East-west grid resolution 2D:                       |                  |       |          | (ewres=value) |
| Top-bottom grid resolution 3D:                      |                  |       |          | (tbres=value) |
|   |                  |       |          |               |
|   |                  |       |          |               |
| Close <u>R</u> un                                   | Cop              | y     | Help     |               |
| Close dialog on finish                              |                  |       |          |               |
| g.region -p vect=GRASS_area@lidar nsres=:           | ewres=1          |       |          | 2             |

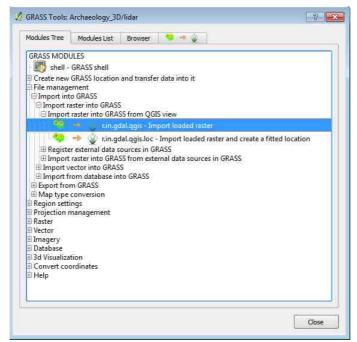
16.The module will switch to the "Command Output" tab where the new resolution settings will be displayed

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17.Close the window and the shell window to return to QGIS.

## Task 5 - Creating a Hill shade of the lidar Rasters

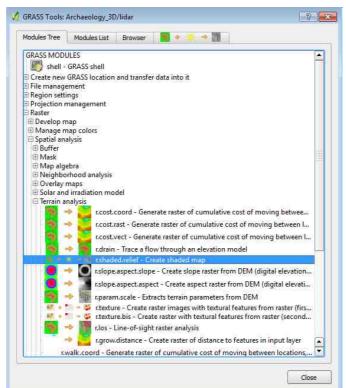
1. For this task we will import the lidar rasters to our GRASS mapset and create a hill shaded image. Open the GRASS tools menu as in Task 4. Navigate to File Management >Import raster into GRASS> Import Raster into GRASS from QGIS view> r.ingdal – Import loaded raster



2. Select the loaded raster you wish to import to GRASS. Click Run then View Output.

| Modules Tree        | Modules List        | Browser | 🛛 🧐 🦘 🖗 🗎    |    |       |       |
|---------------------|---------------------|---------|--------------|----|-------|-------|
| Module: r.in.go     | al.qgis             |         |              |    |       |       |
| Options             | Output Manua        | d.      |              |    |       |       |
| GDAL ra             | ster layer          |         |              |    |       |       |
| lidar_1             |                     |         |              |    |       | -     |
|                     |                     |         |              |    |       | 1.23/ |
| Name fo             | r output raster map | 2       |              |    |       |       |
| lidar_1             |                     |         |              |    |       |       |
| And a second second |                     |         |              |    |       |       |
|                     | -                   |         |              |    |       |       |
|                     |                     |         |              |    |       |       |
|                     | -                   |         |              |    |       |       |
|                     |                     |         |              |    |       |       |
|                     |                     |         |              |    |       |       |
|                     |                     |         |              |    |       |       |
|                     |                     |         |              |    |       |       |
|                     |                     |         | Èconomia     | 10 |       |       |
|                     | Run                 |         | View, output |    | Close |       |

 Now we can use GRASS to create a hill shaded model. In the GRASS tools menu navigate to Raster> Spatial Analysis > Terrain Analysis> Shaded Relief



4. Add the raster map from the drop down menu, give your output map a name. For now leave the default values for the Altitude and Azimuth of the sun. Click Run and wait for the tool to finish (the bar at the bottom of the window will turn green and show 100%). Close GRASS tools.

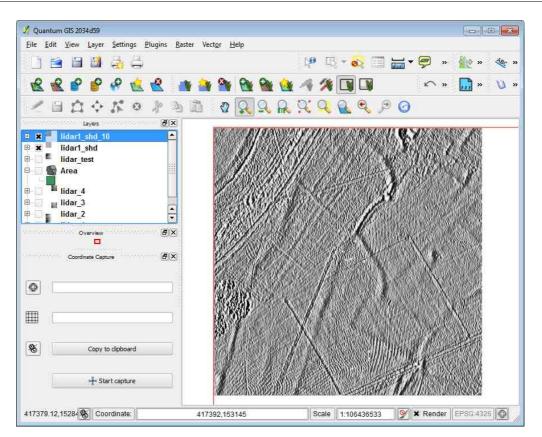
4th International Summer School "3D Modeling in Archaeology and Cultural Heritage 2011", 29 August - 4 September 2011, Grosseto, Italy

| Ma  | dules Tree 🛛 Modules List 🛛 Browser 🛛 🧧 🔶 🔅 🐡 🎆    |
|-----|--|
| Mo  | odule: r.shaded.relief                             |
|     | Options Output Manual                              |
| ſ   | Input elevation map                                |
| l   | lidar_test (lidar_test@lidar)                      |
| L   | Output shaded relief map name                      |
|     | [idar1_shd   |
| l   | Altitude of the sun in degrees above the horizon   |
| L   | 30   |
| L   | Azimuth of the sun in degrees to the east of north |
| L   | 270  |
| L   | Factor for exaggerating relief                     |
| L   | 1  |
| L   |  |
|     |  |
| 1   |  |
| No. |  |
|     | Run View output Close                              |
|     |  |

5. To add the hill shaded raster to QGIS use the Add GRASS Raster Layer icon.

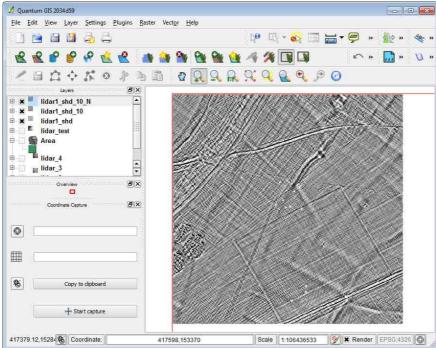


6. Wilson (2000) recommends that archaeological features are best viewed in low light levels. We will now re-run the hill shade altering the altitude of the sun to <30 degrees (the default level). Repeat Steps 1-4 opening the Shaded Relief tool. Alter the altitude value in the box highlighted. Save the raster with the new altitude as part of the name for quick reference e.g. hillshade1\_10. 4th International Summer School "3D Modeling in Archaeology and Cultural Heritage 2011", 29 August - 4 September 2011, Grosseto, Italy



7. By switching these layers on and off in the navigation bar examine the differences between them in terms of the visibility of features. Has the visibility improved unilaterally? What hampers visibility in this image?

8. We will now look at the impact of altering the direction of the sun. Repeat steps 1-4 to open the Hill shade tool. In the Azimuth box change the value to 0 (i.e. North). Save the raster with the new azimuth as part of the name for quick reference e.g. hillshade1\_N and re-run the processing.



- 9. Once again by comparing this layer with the previous hill shaded images what can be said about the differences / similarities between them? Is the visibility of features strongly dependent on the direction of illumination?
- 10. Once you have decided on an "optimal" altitude and azimuth for your hill shade model rerun the process on the other raster images and display them all together in QGIS. How does the tiling of this data affect your interpretations of the archaeological features?

# Task 6 - Digitising Archaeological features from a hill shaded image.

We are now going to look at how you might record archaeological features. This task is technically quite simple repeating the vector file creation and editing we undertook in task 2 but requires you to plan what exactly you wish to record about a feature.

Before we create a new file we need to decide the attributes that it should have and how to standardise our recording so that we can mine the data for our own research aims and crucially so that others can understand it. There is a lot of information on this topic mostly relating to Historic Environment Records. A good starting point for ensuring compatibility are the FISH INSCRIPTION wordlists which can be found here <u>http://www.fish-forum.info/i\_lists.htm</u>.

Use the space below to think about the type of information you would like to record about a feature from the lidar. Think about both its metric properties and its interpretation. Each of these pieces of information will become an attribute.

Once you have decided what you wish to record you need to think about how you will map it. There are three digitising options here - point, line and polygon (though of course you can map features in more than one file to take advantages of different types if you wish). Think carefully about the aims of your research before choosing - if you will need to record the area of a feature this will not be possible with a point or line.

Armed with these decisions you are now ready to start digitising!

1. Click on the Create New Vector



2. Select the type of shape file you wish to create. Add the Attributes you wish to record (ensure you get the correct type of field e.g text, whole number, integer). (TIP: use the instructions in Task 2 to remind yourself

Rebecca Bennett

#### how to do this)

3. Click OK to create your shapefile and use the toggle editing to begin digitising features.

## Session 2 - 11.30 - 13.00

The aim of this session is to introduce GRASS as a tool for processing lidar data. In this session you will undertake the following tasks:

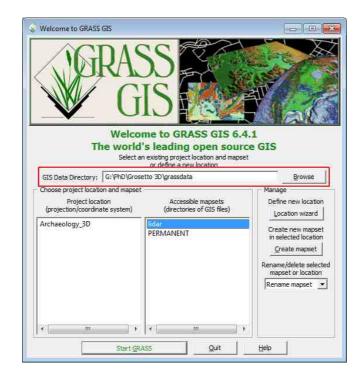
- create a new raster for the study area by combining existing tiled rasters
- import lidar point data
- create an interpolation from lidar point data.
- Export your work in a variety of formats (ESRI, geotiff)
- look at some new techniques for modelling lidar data (LRM and SVF)

## Task 7 - Opening GRASS

1. We will now leave QGIS for a while and take a look at GRASS GIS directly to undertake a number of more complex processing tasks. First open the GRASS wxpython GUI using the icon on your desktop



2. You will need to navigate to the Location and Mapset you created in QGIS during lab 1. When you have browsed to the directory select the location then the mapset. Then click "Start GRASS"

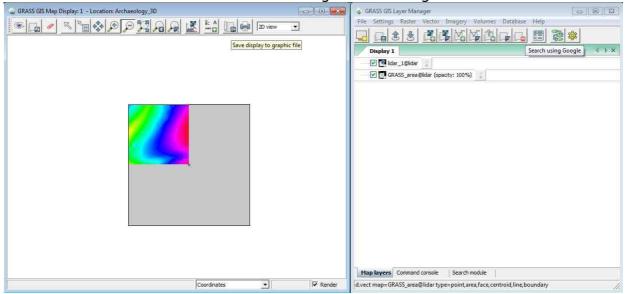


3. Grass will then open two windows as shown below. On the left is the Map Display where graphics are displayed, to the right is the GIS or Layer Manager where layers are added and modified and where the menus are found for each function.

| 418315.24; 152470.88 Coordinates 💌 🔽 Render |
|---|
|---|

- 4. First we will add a vector and a raster to the display. In the GIS Manager click on the Add Vector Icon in the same window and select the vector file representing the study area that you created in the first session (GRASS\_area).
- 5. Then click on the Add Raster icon and pick a raster from the drop down menu.

Your screen should now look something like the image below.



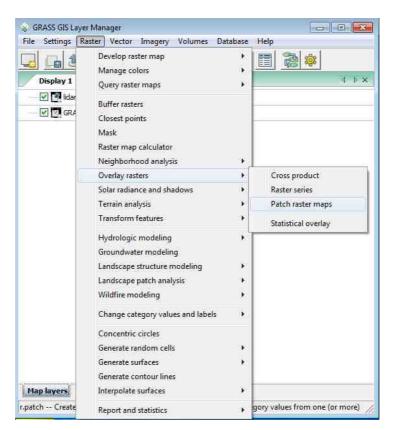
6. By right clicking on the layer name in the Layer manager window you can access the display options for each layer. Take a moment to explore these

## M

options to improve the display.

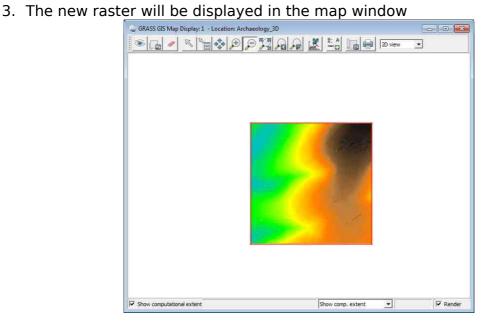
## Task 8 - Combining the Tiled Rasters

 To improve the visualisation of the tiled lidar data it is possible to combine the lidar tiles supplied and re-run the hill shade analysis on the whole study area. In the GIS Manager navigate to Raster> Overlay Rasters > Patch Raster Maps.



2. The r.patch tool will be opened. Add the rasters you wish to patch (use the original rasters not the hill shaded models). Give your new raster a name and

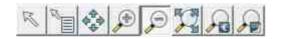
| Required                       | Optional      | Command output                                    | Manual | 4 0.3       |
|--------------------------------|---------------|---|--------|-------------|
|                                |               | o be patched together:<br>r 3@lidar,lidar 4@lidar |        | (input=nam  |
|                                |               | _סיפונים אינים _דפונים                            |        | <u> </u>    |
| ame for resultant<br>all_lidar | t raster map: |   |        | (output=nam |
|                                |               |   |        |             |
|                                |               |   |        |             |
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|                                |               |   |        |             |
|                                |               |   |        |             |
|                                |               |   |        |             |
|                                |               |   |        |             |



4. Next we will run the hill shade analysis. Navigate to Raster> Terrain Analysis > Shaded relief. Enter the base raster and the name of the output raster in the r.shaded.relief window. Choose your Altitude and Azimuth variables in the "Optional" tab. Notice here that you can also exaggerate the Z values of the data to enhance features. When you are happy with the variables selected, run the tool.

| (a r.shaded.relief [raster, elevation]                                  | 😵 r.shaded.relief [raster, elevation]  |
|---|--|
| Creates shaded relief map from an elevation map (DEM).                  | Creates shaded relief map from an elevation map (DEM).   |
| Required Optional Command output Manual 4 b ×                           | Required Optional Command output Manual 4 🕨 🗙  |
| Input elevation map: (map=string)<br>all_lidar@lidar                    | ☐ Allow output files to overwrite existing files     (overwrite)       ☐ Verbose module output     (verbose)       ☐ Quiet module output     (quiet)       Output shaded relief map name:     (shadedmap=string)   |
|   | Iidar_all_shd       Image: Constraint of the sun in degrees above the horizon (valid range 0-90): (altitude=float)         20       E         Azimuth of the sun in degrees to the east of north (valid range 0-360): (azimuth=float)         20       E |
|   | Factor for exaggerating relief: (zmult=float)  |
|   | Scale factor for converting horizontal units to elevation units: (scale=float)   |
| Close Run Copy Help   | Close   Run Copy Help  |
| r.shaded.relief map=all_lidar@lidar shadedmap=lidar_all_shd altitude=20 | r.shaded.relief map=all_lidar@lidar shadedmap=lidar_all_shd altitude=20  |

5. As before the new raster will be added to the display window. Use the navigation tools to explore the raster



run the tool.

## Task 9 - Import Point Data

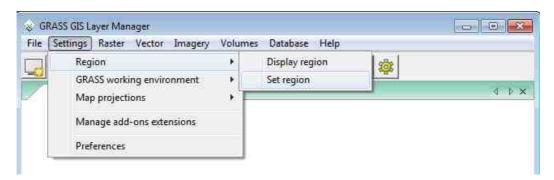
1. For this task we will look at a subset of the data so we need to set up a new region for our mapset. We will do this as in the previous lab by importing a shapefile of our area of interest into GRASS. In the GIS manager window go to File> Import Vector Data> Common Import Formats

| Settings                 | Raster    | Vector    | Imagery | Volumes | Database      | Help  |  |
|--------------------------|-----------|-----------|---------|---------|---------------|---|--|
| Workspac                 | e         |           |         | - 31    |               |   |  |
| Import ra                | ster data |           |         | *       |               |   | N.,                                    |
| Import ve                | ctor data | k.        |         | >       | Comm          | on import formats                                 |  |
| Import 3D<br>Import da   |           |           |         | *       |               | oints/GRASS ASCII vect<br>oints as a vector lines | or import                              |
| Export ras<br>Export vec | tor map   |           |         | *       |               | cal GRASS vector impor<br>cal GRASS vector impor  | 1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1. |
| Export 3D<br>Export dat  | labase ta | ble       |         | *       | DXF im<br>WFS | port  |  |
| Link exter               |           |           |         | *       | ESRI e0       | 0 import  |  |
| Manage r<br>Map type     |           |           |         | *       |               | i GPS import<br>sel GPS import                    |  |
| Georectify               | ł         |           |         |         | Geonar        | nes import  |  |
| Graphical<br>Run mod     |           | ţ.        |         |         |               | t import<br>array and MapGen imp                  | port                                   |
| NVIZ (req<br>NVIZ (nor   |           |           |         |         |               |   |  |
| Bearing/d                | istance t | o coordin | ates    |         |               |   |  |
| Postscript               | plot      |           |         |         |               |   |  |
| Launch so                | ript      |           |         |         |               |   |  |
| Exit GUI                 |           |           | 3       | Ctrl+Q  |               |   |  |

2. In the Import Vector Data window, navigate to the data folder in your Archaeology 3D directory and select the extract. Click Import to run the tool. Add the vector as a layer in the GIS manager and display it on screen. 4th International Summer School "3D Modeling in Archaeology and Cultural Heritage 2011", 29 August - 4 September 2011, Grosseto, Italy

| Import vector data            |                            |                    | ×      |
|-------------------------------|----------------------------|--------------------|--------|
| - Settings                    |                            |                    |        |
| Load settings:                |                            |                    | ▼ Save |
| Load setungs:                 |                            |                    |        |
| Source type                   |                            |                    |        |
|                               | 🗋 Database 🔿 Protocol      |                    |        |
| Source name                   |                            |                    |        |
|                               |                            |                    |        |
| File: extract.shp             |                            |                    | Browse |
| Format: ESRI Shapefile        | 2                          | •                  |        |
| List of OGR layers            |                            |                    |        |
| Layer Layer name              |                            | Name for GRASS map |        |
| ✓ 1 extract.shp               |                            | extract            |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
|                               |                            |                    |        |
| 1                             |                            |                    |        |
| Options                       |                            |                    |        |
|                               |                            |                    |        |
| Do not clean polygons (not    |                            |                    |        |
| Extend location extents based | sed on new dataset         |                    |        |
| Override dataset projection   | (use location's projection | 1)                 |        |
| Limit import to the current r |                            |                    |        |
| Do not create attribute tab   |                            |                    |        |
| Change column names to lo     |                            |                    |        |
| Create 3D output              |                            |                    |        |
| - create ab output            |                            |                    |        |
| Allow output files to overwri | te existing files          |                    |        |
| Add imported layers into lay  | er tree                    |                    |        |
| Add imported layers into lay  | a acc                      |                    |        |
|                               | Command dialog             | Import Cancel      |        |
|                               | Command dialog             | inport Cancer      |        |

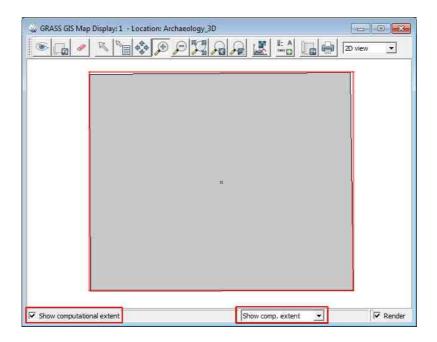
To change the region to match the extract area, navigate to Settings > Region > Set Region settings in the Layer Manager



4. You will see that this opens the same Region tool window as in exercise 4: 12-17 from the previous session. Change the region settings to match the "Extract" vector with a 1m NS and EW resolution. (Return to exercise 4 if you need to remind yourself how to do this. Click run.)

| 💩 g.region [ge        | eneral]        |                         |              |           | 1        | - 0 .         |
|-----------------------|----------------|-------------------------|--------------|-----------|----------|---------------|
| Manages t             | he boundary    | definitions for th      | ne geographi | c region. |          |               |
| Existing              | Bounds         | Resolution              | Effects      | Print     | Optional | 4 🕨 🗙         |
| Set from defa         |                |                         |              |           |          | (d)<br>(s)    |
| Set current regio     |                | d region:               |              |           |          | (region=name  |
| inu ditinda T. Catana | inn ta matak   | this raster map:        |              |           | <u>•</u> | (rast=name    |
| multiple] series      | port to matur  | runs raster map.        |              |           | ×        | (rast-ridirie |
| Set region to ma      | tch this 3D ra | aster map (both :       | 2D and 3D va | lues):    |          | (rast3d=name  |
| white the second      |                | - Hoston and the second | 8            |           | <u>•</u> | 6.1. A.       |
| extract               | jion to match  | this vector map         |              |           | •        | (vect=name    |
| Set region to ma      | tch this 3dvie | ew file:                |              |           |          | (3dview=name  |
|                       |                |                         |              |           | <u>·</u> |               |
|                       |                |                         |              |           |          |               |
|                       | Close          | Run                     | 1 7          | Copy      | Help     | ſ             |
| Close dialog (        |                | 12001                   |              | -907      | Geb      |               |
| j.region vect=e       | xtract         |                         |              |           |          |               |

5. To check that the computation region matches the imported vector change the drop down menu at the bottom of the map display window to "show comp. Extent". Tick the box to the left of the window and the region will be outlined in red. Notice that it does not exactly match the shapefile but uses the mix / max extent to create a bounding box.

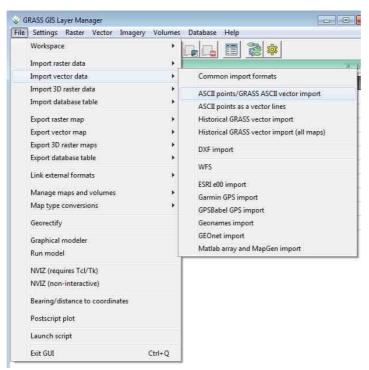


6. We will now import some lidar data in xzyi flight line data from a .txt file, shown below.

Each flightline has over 2 million data points so we will want to work only with those that fall within the region of interest.

| 1.txt - Notepad  |   | < |
|--|---|---|
| <u>F</u> ile <u>E</u> dit F <u>o</u> rmat <u>V</u> iew <u>H</u> elp  |   |   |
| #17440.077723152862.045406128.884356417439.444053152862.147216128.794136417438.784483152862.248776128.770986417438.130463152862.348876128.779836417437.489193152862.450436128.714646417437.430413152863.123046128.704566417438.071683152862.922966128.791926417439.383483152862.922966128.791926417439.383483152862.722406128.888296417440.020203152862.622436128.899436417441.325223152862.520866128.985666417441.960143152862.321286129.103036417443.257193152862.221306129.134216417443.904413152862.120966129.195406 | 163<br>159<br>164<br>158<br>161<br>166<br>161<br>162<br>166<br>166<br>166<br>167<br>158<br>163<br>165 | * |
| •  | Þ   |   |

- 7. There are a number of ways to import point data in GRASS. For this tutorial we will import the point data to a vector file using v.in.ascii and then interpolate this vector to a raster. It is also possible to import the file directly to a raster using r.in.xyz but this method although quicker give less control over the interpolation technique.
- 8. Navigate to File > Import Vector Data > Aggregate ASCII xyz import



| Required                        | Input format         | Points     | Optional        | 4 🕨 🗙        |
|---------------------------------|----------------------|------------|-----------------|--------------|
| SCII file to be imp             | ported, if not giver | reads from | standard input: | (input=name  |
| idar_point.txt                  |                      |            |                 | Browse       |
| enter values int                | teractively          |            |                 |              |
|                                 |                      |            |                 | 1            |
|                                 |                      |            |                 |              |
|                                 |                      |            |                 |              |
|                                 |                      |            |                 |              |
| ame for output v                | ector map:           |            |                 | (output=name |
| ame for output v<br>idar_points | ector map:           |            |                 | (output=name |
|                                 | ector map:           |            |                 | (output=name |

- 9. In the "Required" tab, add the lidar\_point.txt file to be imported from Data folder in Archaeology 3D. Type in a name for your raster.
- 10.In the "Input Format" tab select point from the drop down menu. You will need to specify the format of your xyzi text file. Replace the standard Field Separator (the 'pipe' symbol " | ") with a space.

| Required / Input format                                       | Points       | Optional  | 4 🕨 🗙                  |
|---|--------------|-----------|------------------------|
| Don't expect a header when read<br>nput file format:<br>point | ng in standa | rd format | (n)<br>(format=string) |
| ield separator:   |              |           | (fs=character          |
|   |              |           |                        |
|   |              |           |                        |
|   |              |           |                        |
|   |              |           |                        |
|   |              |           |                        |

11. In the "Points" tab, check the box to only import points in the current region. Check that the x and y columns are correct. We will first create an elevation raster so check that the data values are set to column 3. (If you wanted to create a raster of the intensity values you would change this to column 4)

| 🍪 v.in.ascii [vector, import]   |                    |
|---|--------------------|
| Creates a vector map from ASCII points file or ASCII view                             | ector file.        |
| Required Input format Points Optional   | X ∉ b              |
| 🗖 Do not create table in points mode  | (t)                |
| Do not build topology in points mode  | (b)                |
| Only import points falling within current region (points model)                       |                    |
| Number of header lines to skip at top of input file (points mod 0                     | e): (skip=integer) |
| Column definition in SQL style (points mode):   | (columns=string)   |
| Number of column used as x coordinate (points mode):                                  | (x=integer)        |
| 1 🔄   |                    |
| Number of column used as y coordinate (points mode):                                  | (y=integer)        |
| Number of column used as z coordinate (points mode):                                  | (z=integer)        |
| Number of column used as category (points mode):                                      | (cat=integer)      |
| Close <u>Run</u> Copy<br>Add created map(s) into layer tree<br>Close dialog on finish | Help               |

- 12. When you are happy with the variables run the tool. This will take a few minutes (no more than 3 on an average PC). The output window reports the number of points that fell within the current region points fell within the current area of interest.
- 13. The point data will be automatically added to the layer manager and map window.

# Task 10 - Interpolating the lidar points

 Having successfully imported the lidar points our area of interest, we need create a continuous model by interpolating the point data into a raster. GRASS has a number of options for interpolating point data, we will use the simplest here an Inverse Distance Weighted interpolation. The choice of model you create is important as it will affect the accuracy of your results – more information for each of the interpolation methods this can be found on the GRASS wiki

http://grass.itc.it/gdp/html\_grass63/v.surf.idw.html

http://grass.itc.it/gdp/html\_grass63/v.surf.rst.html

2. Navigate to Raster > Interpolate Surfaces > Bilinear and Bicubic from vector points

| 😵 GRASS GIS La  | yer Manager  |         |   |
|---|--|---------|---|
| File Settings [   | Raster Vector Imagery Volumes Dat  | abase   | Help  |
| Display 1   | Develop raster map<br>Manage colors<br>Query raster maps   | * * *   |   |
| Y         Y         Y         Y           Y         Y         Y         Y         Y           Y         Y         Y         Y         Y         Y           Y | Buffer rasters<br>Closest points<br>Mask<br>Raster map calculator<br>Neighborhood analysis<br>Overlay rasters<br>Solar radiance and shadows<br>Terrain analysis<br>Transform features<br>Hydrologic modeling<br>Groundwater modeling<br>Landscape structure modeling<br>Landscape patch analysis<br>Wildfire modeling<br>Change category values and labels<br>Concentric circles<br>Generate random cells<br>Generate surfaces<br>Generate contour lines | ** **** |   |
|   | Interpolate surfaces   | •       | Bilinear from raster points<br>Bilinear and bicubic from vector points                |
|   | Report and statistics  | •       |   |
|   |  |         | IDW from raster points  |
|   |  |         | IDW from raster points (alternate method for sparse points)<br>IDW from vector points |
|   |  |         | Raster contours<br>Regularized spline tension   |
|   |  |         |   |
|   |  |         | Fill NULL cells   |

3. In the v.surf.bspline tool select the input vector file. Choose the vector data to interpolate, leave all the settings unchanged in the "settings" tab. In the "Optional" tab enter the output raster name. Run the tool.

| Bicubic or bilinear spline interpolation with Tykhonov regularization. |             | Bicubic or bilinear spline interpolation with Tykhonov regularization.  |  |
|--|-------------|---|--|
|  |             |   |  |
| Required Settings Optional Command output Manual                       | 4 Þ 🗙       | Required Settings Optional Command output Manual  | 4 0 ×  |
| Neme of Fingut vector map:   | (nput=name) | Name for output vector map:   | (c<br>(e<br>(overwrite<br>(verbose<br>(quiet<br>(sparse=name<br>(output=name<br>(raster=name |
| Glose <u>Bun</u> Cgpy <u>tickp</u>                                     |             | Idar_ali<br>Close <u>Bun</u> <u>Capy</u> <u>Help</u><br>√ Add greated map(s) into layer tree<br>√ Close dalog on finish |  |

# Remember the resolution of the raster created is determined by the region settings, not in this tool!

- 4. Display the raster and take some time to explore it in the Map Display window.
- 5. To check the metadata of the raster you have created go to Raster > Reports and Statistics > Report Basic File Information. Add the raster file and run the tool. The results will show the method of interpolation and the resolution of the raster.
- 6. Finally create a hill shade of the raster as in Task 8.4. Compare this with the results of the hill shade for the pre-gridded ESRI ASCII data used in session 1. What do you notice about the quality of the results? Which method is preferable as the base data for hill shaded models?

# Task 11 - Using the GRASS profile tool

In this task we will look at the profile tool to examine features. When digitising features from hill shaded images it is important to understand their topography i.e. are the positive or negative features. The best way to do this is by drawing a profile across the feature.

1. In the map display window click on the profile tool and select "Profile surface map"

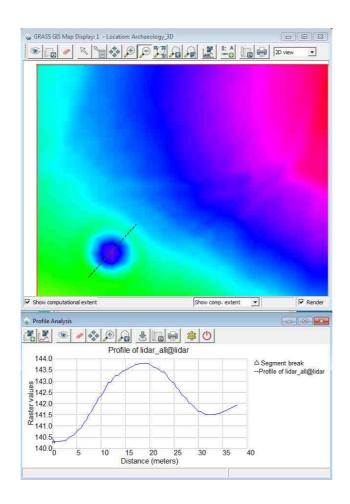
| 5 |   |  |
|---|---|--|
| 7 | _ |  |

2. In the profile window select the lidar\_all elevation map. Note you can select up to three maps to compare with the same profile.

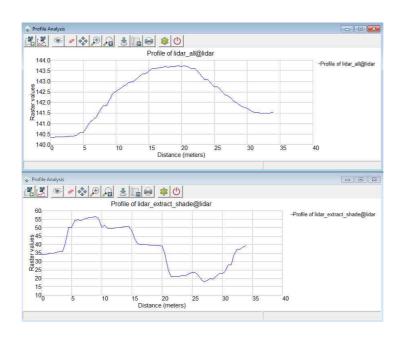
| Select raster map 1 (required):                                    | idar_ali@idar |    | •        |
|--|---------------|----|----------|
| Select raster map 2 (optional):<br>Select raster map 3 (optional): |               |    | <u>*</u> |
|  |               | ОК | Cancel   |

- 3. Click on the draw transect icon (in the "profile analysis" window).
- 4. In the Map Display window, click and drag to draw a transect over the mound feature. Then click on the Draw Profile icon (in the Profile analysis window) to draw the profile. The results are shown on the next page
- 5. Repeat this procedure for other features in the raster until you are familiar with the tool.
- 6. Use the add raster map icon to add the shaded relief model created in Task 10. Why is this view not very helpful? Close the profile tool.



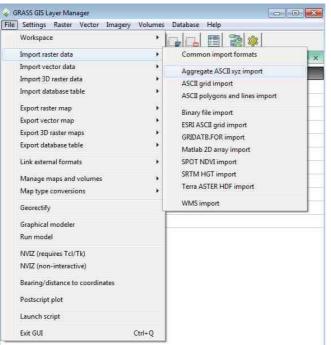


7. To visually compare rasters of different scales more efficiently open two profile tools. They will automatically draw the same profile. What do you notice about the shaded relief model's representation of the topography compared with the original DEM?



# Task 12 - Checking the resolution of the point data

- When receiving lidar in point cloud form it is advisable to check the resolution of the data. In GRASS you can do this quickly by creating a raster map of the number of points per cell. First we will import a sample area on which to work from the shapefile Density. Navigate to File > Import Vector Map > Multiple Formats using OGR. Add the shapefile Density.
- Change the region settings to match the Density vector using Config > Region > Change Region settings. In the resolution tab set the Northsouth and east-west resolutions (cell size) to 1
- 3. We will now create a raster that illustrates the number of points per cell. Navigate to File > Import Raster > Aggregate ASCII xyz



4. In the r.in.xyz tool navigate to the .txt file with the raw lidar data. Enter a name for your output file. In the Statistic tab change the statistic for

| Required                               | Statistic Input Optional                                      | 4 ) ×             |
|--|---|-------------------|
| Statistic to use                       | for raster values:  | (method=          |
|  | f the values (valid range 1-100):                             | <br>(pth=i        |
| 0                                      |   |                   |
| )<br>Discard <trim></trim>             | ہتے<br>percent of the smallest and <trim> percent of t</trim> | fie largest (trim |
| 1-                                     | percent of the smallest and <trim> percent of t</trim>        | he largest (trim  |
| )<br>Discard <trim></trim>             | یت<br>percent of the smallest and <trim> percent of t</trim>  | he largest (trim  |
| )<br>Discard <trim></trim>             | percent of the smallest and <trim>percent of t</trim>         | he largest (trim  |
| )<br>Discard <trim></trim>             | percent of the smallest and <trim>percent of t</trim>         | fhe largest (trim |
| )<br>Discard <trim></trim>             | percent of the smallest and <trim>percent of t</trim>         | he largest (trim  |
| Discard <trim><br/>observations</trim> |   | he largest (trim  |
| )<br>Discard <trim></trim>             | percent of the smallest and <trim>percent of t</trim>         | he largest (trim  |

Rebecca Bennett

#### raster values to n

5. In the Input tab, change the separator to a space and leave the rest of the settings as default. Run the tool.

| Required Statistic Input Optional  | 4 🕨 🗙          |
|--|----------------|
| Field separator:   | (fs=character) |
| Column number of x coordinates in input file (first column is 1):                    | (x=integer)    |
| Column number of y coordinates in input file:  | (y=integer)    |
| Column number of data values in input file:  | (z=integer)    |
| Close <u>Run</u> Copy<br>Add created map(s) into layer tree<br>Close dalog on finish | Help           |

- 6. Now we will look at how many point were found per cell. Navigate to Raster > Reports and Statistics > General statistics
- 7. Add the raster map in the Options tab. In the Print tab check Print Cell Counts and run the tool

| Print averaged values instead of intervals     Print area totals     Print cell counts     Print cell counts     Print APPROXIMATE percents (total percent may not be 100%)     Print category labels     Print grid coordinates (east and north)     Print x and y (column and row)     Print raw indexes of fp ranges (fp maps only) | Required / Print           | Optional       | Command output         | 4 10 3 |
|--|----------------------------|----------------|------------------------|--------|
| Print cell counts     Print APPROXIMATE percents (total percent may not be 100%)     Print category labels     Print grid coordinates (east and north)     Print x and y (column and row)  | Print averaged values ins  | tead of interv | /als                   | (      |
| Print APPROXIMATE percents (total percent may not be 100%)<br>Print category labels<br>Print grid coordinates (east and north)<br>Print x and y (column and row)   | Print area totals          |                |                        | (      |
| Print category labels<br>Print grid coordinates (east and north)<br>Print x and y (column and row)   | Print cell counts          |                |                        | (      |
| Print grid coordinates (east and north)<br>Print x and y (column and row)  | Print APPROXIMATE perc     | ents (total pe | rcent may not be 100%) | (      |
| Print x and y (column and row)   | Print category labels      |                |                        |        |
|  |                            |                |                        | (      |
| Print raw indexes of fp ranges (fp maps only)  | EV 8097                    | 15             |                        | (      |
|  | Print raw indexes of fp ra | anges (fp map  | s only)                |        |
|  |                            |                |                        |        |
|  |                            |                |                        |        |
|  |                            |                |                        |        |
|  |                            |                |                        |        |
|  |                            |                |                        |        |
|  |                            |                |                        |        |
|  | Liose                      | <u>P</u> on    | CODY                   | Teh    |
| Close <u>R</u> un C <u>o</u> py <u>H</u> elp   | stats -c input=Lidar_pder  | is 1@lidar     |                        |        |

In the output window you will see the results of the cell count. What does this tell you about the quality of the data at 1m resolution? At what raster resolution would you have a point in every cell?

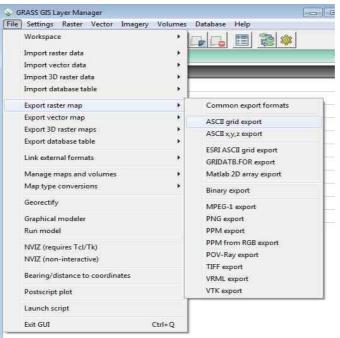
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# Task 14 - Exporting GRASS data

GRASS is able to export vector and raster data in many formats including ESRI (grid and shapefile), Matlab (.mat), DXF, KML, text file and Tiff. Most of the options for export are found in File > Export Raster Map > Multiple Formats using GDAL or File > Export Raster Map > Multiple Formats Using OGR. Some like the ESRI grid require separate tools which are also listed in the menus File > Export Raster / Vector Map.

In this task we will export both vector and raster data. The key thing to remember is to ensure that the region of interest is configured to encompass the whole of the data you wish to export.

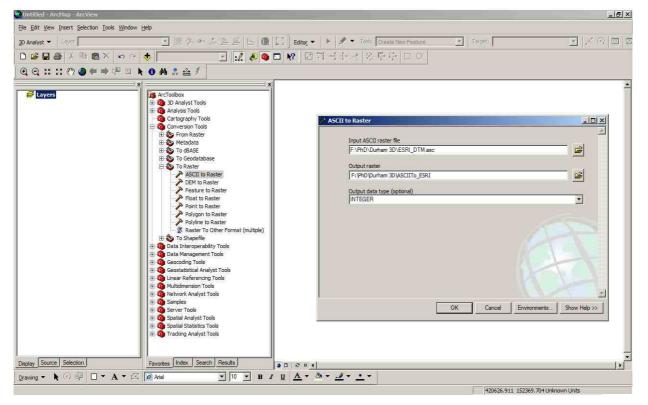
 First we will export the DTM raster we have just created into an ESRI (ArcGIS) raster. In the GIS manager navigate to File > Export Raster Map > ESRI ASCII Grid



2. Select the file to export and chose a location and name for the ESRI raster. Append the file with .asc or .txt

| Required                              | Optional     | Command output           | Manual | 4 Þ 🗙                    |
|---------------------------------------|--------------|--------------------------|--------|--------------------------|
| lame of an existin<br>all_lidar@lidar | g raster map | layer:                   |        | (input=string            |
| lame of an output<br>ESRI_DTM.asc     | ARC-GID ma   | p (use out=- for stdout) | 1      | (output=string<br>Browse |
|                                       |              |                          |        |                          |
|                                       |              |                          |        |                          |
|                                       |              |                          |        |                          |
|                                       |              |                          |        |                          |

3. The ascii file created can now be read by ArcGIS. Open ArcGIS and in the tool box navigate to Conversion Tools > To Raster > ASCII to raster tool.



4. We will also export the filtered vector points as a text file. Navigate to File > Export Vector Map > ASCII Points or GRASS ASCII Vector

| Settings Raster Vector Imag     | gery Volumes | Database Help                              |
|---------------------------------|--------------|--|
| Workspace                       | *            |  |
| Import raster data              | *            |  |
| Import vector data              |              |  |
| Import 3D raster data           | •            |  |
| Import database table           | *            |  |
| Export raster map               |              |  |
| Export vector map               | *            | Common export formats                      |
| Export 3D raster maps           | *            | ASCII points/GRASS ASCII vector export     |
| Export database table           | *            | DXF export                                 |
| Link external formats           | ×            | Multiple GPS export formats using GPSBabel |
| Manage maps and volumes         | *            | POV-Ray export                             |
| Map type conversions            | *            | SVG export                                 |
| Georectify                      | T            | VTK export                                 |
| Graphical modeler               |              |  |
| Run model                       |              |  |
| NVIZ (requires Tcl/Tk)          |              |  |
| NVIZ (non-interactive)          |              |  |
| Bearing/distance to coordinates |              |  |
| Postscript plot                 |              |  |
| Launch script                   |              |  |
| Exit GUI                        | Ctrl+Q       |  |

5. Add the vector to be exported and give the export file a name (appended with .txt)

| Required                | Points                      | Selection       | Optional                | < ▶×           |
|-------------------------|-----------------------------|-----------------|-------------------------|----------------|
| Create old (v           | ersion 4) AS                | CII file        |                         | (a             |
| Verbose mod             | Construction and the second |                 |                         | (verbose       |
| Quiet module            | output                      |                 |                         | (quiet         |
| ath to resulting        | ASCII file or               | ASCII vector na | ame if '-o' is defined: | (output=name   |
| points.txt              |                             |                 |                         | Browse         |
| Dutput format:<br>point |                             |                 | <u> </u>                | (format=string |
|                         |                             |                 |                         |                |

6. In the Points tab, choose the field separator you wish to use (the default is "|")

| Required                         | Points          | Selection        | Optional         |            | 4 🕨 🗙               |
|----------------------------------|-----------------|------------------|------------------|------------|---------------------|
| Only export<br>Field separator ( |                 |                  | 3D region (point | s mode)    | (r<br>(fs=character |
| Number of signif<br>8            | icant digits (f | loating point on | ly) (valid range | 0-32):     | (dp≃integer         |
| multiple] Name                   | of attribute c  | olumn(s) to be   | exported (point  | mode):     | (columns=name       |
| manuprej marme.                  |                 |                  | 12               | <u>.</u>   |                     |
| inerepret reame.                 |                 |                  |                  | <u>.</u> 1 |                     |

7. The .txt file created can be opened in Excel or OpenOffice Calc. In Excel navigate to File > Open. Change the file type to csv.

| OO IN Compare | <ul> <li>HD-CEU2 (F:) + PhD + Durham 3D + Data</li> </ul>  | • 🙆 Search         | <u>1</u>    |
|---------------|--|--------------------|-------------|
| Organize      | New Folder     Name      V Date modified     V Type     V Size     08.txt     09.txt     Veg.txt | txt                |             |
| Folders ^     |  |                    |             |
| File name:    |  | Text Files (*.pm;* | bt;*.csv) 💌 |

8. Choose Delimited and click next

|  | rd - Step 1                                      | of 3   |                                 | <u>?</u> × |
|--|--|--|---------------------------------|------------|
| The Text Wizard has  | determined                                       | that your data is                            | Fixed Width.                    |            |
| If this is correct, cho  | oose Next, or                                    | choose the data                              | type that best describes your   | data.      |
| Original data type   |  |  |                                 |            |
| · · · · · · · · · · · · · · · · · · ·                            | cantas (a )                                      | n en in                                      | 2                               |            |
| Choose the file typ  |  |  |                                 |            |
| Delimited  |  |  | as or tabs separate each field. | 2          |
| C Fixed width  | <ul> <li>Fields are</li> </ul>                   | aligned in column                            | nns with spaces between each f  | ield,      |
|  |  |  |                                 |            |
| Start import at row:   | 1  | ÷ File grigin:                               | MS-DOS (PC-8)                   | *          |
| eren in the sector.  | 1-   | T  | Lesserters                      | التنبير    |
|  |  |  |                                 |            |
|  |  |  |                                 |            |
|  |  |  |                                 |            |
| Drawiew of file F-\L   | DD Durbarn 1                                     | 10\DataWed tyt                               |                                 |            |
| Preview of file F:V  | PhD\Durham (                                     | 3D\Data\Veg.txt.                             |                                 |            |
| Preview of file F:\  |  |  |                                 | <b>`</b>   |
| 1 420523.69 1<br>2 420524.38 1                                   | 152734.06<br>152734.74                           | 154.75 2<br>154.73 3                         |                                 | <b>_</b>   |
| 1 420523.69 1<br>2 420524.38 1<br>3 420525.06 1                  | 152734.06<br>152734.74<br>152735.42              | 154.75 2<br>154.73 3<br>154.78 4             |                                 | ł          |
| 1 420523.69 1<br>2 420524.38 1<br>3 420525.06 1<br>4 420525.79 1 | 152734.06<br>152734.74<br>152735.42<br>152735.11 | 154.75 2<br>154.73 3<br>154.78 4<br>154.61 5 |                                 | <u>+</u>   |
| 1 420523.69 1<br>2 420524.38 1<br>3 420525.06 1                  | 152734.06<br>152734.74<br>152735.42<br>152735.11 | 154.75 2<br>154.73 3<br>154.78 4<br>154.61 5 |                                 | <u> </u>   |
| 1 420523.69 1<br>2 420524.38 1<br>3 420525.06 1<br>4 420525.79 1 | 152734.06<br>152734.74<br>152735.42<br>152735.11 | 154.75 2<br>154.73 3<br>154.78 4<br>154.61 5 |                                 | ×          |
| 1 420523.69 1<br>2 420524.38 1<br>3 420525.06 1<br>4 420525.79 1 | 152734.06<br>152734.74<br>152735.42<br>152735.11 | 154.75 2<br>154.73 3<br>154.78 4<br>154.61 5 |                                 | ×<br>×     |

9. Select the delimiter (in this case a space) and click finish to view the data.

| ext Import W<br>his screen lets<br>elow, |                                     | 10 (N)                        | ta contains. You  | can see how you | text is affected in | the preview |
|--|-------------------------------------|-------------------------------|-------------------|-----------------|---------------------|-------------|
| Delimiters                               |                                     | eat consecutive<br>gualifier: | delimiters as one | ]               |                     |             |
| 420524.38<br>420525.06                   | 152734.06<br>152734.74<br>152735.42 | 154.73 3<br>154.78 4          |                   |                 |                     | <u> </u>    |
|  | 152736.11<br>152736.17              | 154.61 5<br>154.61 6          |                   |                 | 10 <u>1</u>         | <u>_</u>    |

| 9    | Home     | Insert                          | Page Lay |           | nulas                   |             | gitat - Micro<br>view V | iew     |        |      |   | (Q)                      | _ = >    |
|------|----------|---------------------------------|----------|-----------|-------------------------|-------------|-------------------------|---------|--------|------|---|--------------------------|----------|
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|      | A1       |                                 |          | fx 420523 | 3.69                    |             |                         |         |        |      |   |                          | *        |
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| 34   | 420528.7 | 152733.6                        | 154.76   | 35        |                         |             |                         |         |        |      |   |                          |          |
| 35   | 420529.4 | 152734.3                        | 154.69   | 36        |                         |             |                         |         |        |      |   | 1                        | <u> </u> |
| 36   | 420530.1 | 152735                          | 154.74   | 37        |                         |             |                         |         |        |      |   |                          |          |
| 37   | 420530.8 | 152735.6                        | 154.58   | 38        |                         |             |                         |         |        |      |   |                          | <u> </u> |
| 38   | 420531.5 | 152735.9                        | 154.66   | 39        |                         |             |                         |         |        |      |   |                          | l l      |
| 39   | 420530.9 | 152735.3                        | 154.64   | 40        |                         |             |                         |         |        |      |   |                          | <u> </u> |
| 40   | 420530.3 | 152734.7                        | 154.66   | 41        |                         |             |                         |         |        |      |   |                          | L L      |
| 41   | 420529.7 | 152734                          | 154.66   | 42        |                         |             |                         |         |        |      |   |                          |          |
| 42   | 420529   | 152733.4                        | 154.78   | 43        |                         |             |                         |         |        |      |   |                          | l II     |
| 43   | 420528.4 | 152732.8                        | 154.72   | 44        |                         |             |                         |         |        |      |   |                          | I)       |
| 44   | 420527.8 | 152732.2                        | 154.68   | 45        |                         |             |                         |         |        |      |   |                          |          |
| 45   | 420527.3 | 152731.7                        | 154.78   | 46        |                         |             |                         |         |        |      |   |                          | 4 0      |
| 46   | 420526.5 | 152730.9                        | 154.72   | 47        |                         |             |                         |         |        |      |   |                          |          |
| 47   | 420525.9 | 152730.3                        | 154.72   | 48        |                         |             |                         |         |        |      |   |                          |          |
|      | ► H Veg  | 07                              |          |           |                         |             |                         | .i      | 101    | 1.00 |   |                          |          |

# Task 14 - Advanced Data Processing

Recently two techniques have been published that are designed to help view lidar data in a way that is more conducive to mapping microtopographic changes without the bias of hill shading.

#### Sky Factor Modelling

# Kokalj, Z., Zaksek, K., and Ostir, K. 2011. Application of sky-view factor for the visualisation of historic landscape features in lidar-derived relief models. *Antiquity* 85(327): p.263-273.

SVF is a visualisation technique based on diffuse light. The product is a representation of the total amount of light that each pixel is exposed to as the sun angle crosses the hemisphere above it. Consequently the model is not dependent on sun direction (unlike hill shading)

A stand alone SVF module can be downloaded from <u>http://iaps.zrc-sazu.si/?</u> q=en/svf. You can use the raster exported from GRASS as the input for this module

The SVF can also be modelled in GRASS using the tools Raster > Terrain Analysis > Horizon (r.horizon) angle and combining the results of modelling at different angles using the raster calculator Raster > Raster Map Calculator (r.calc).

#### Local Relief Modelling

# Hesse, R. 2010. LiDAR-derived Local Relief Models - a new tool for archaeological prospection. *Archaeological Prospection* 18(2).

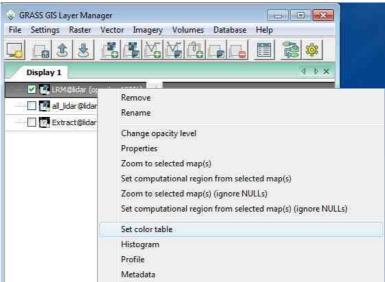
LRM was developed for mountainous regions and produces a model where the affect of the macro-topography is reduced while retaining the integrity of the micro-topography. The model process requires several stages. All of these can be run in GRASS using a combination of tools. In order to make the process easier, a GRASS script will be published at the end of the year allowing users to automate the process. Please email <u>r.bennett@bournemouth.ac.uk</u> if you would like to receive notification of this release.

|   | LRM Model Stage                   | GRASS command   |
|---|-----------------------------------|---|
| 1 | low pass filter                   | r.neighbors   |
| 2 | subtract low pass filter from DTM | r.mapcalc   |
| 3 | extracting zero contours          | r.mapcalc (to create a raster where<br>the Low pass and DTM both equal 0)<br>r.to.vect (to convert this to a vector |

|   |   | file)          |
|---|---|----------------|
| 4 | interpolating purged DTM                        | v.surf.bspline |
| 5 | subtract purged DTM from original to get<br>LRM | r.mapcalc      |

We will explore these two models in GRASS and compare them to the shaded relief and original DTM.

- 1. Import the geotif LRM and SVF models from the data folder using File> Import Raster Data > common import formats.
- 2. Terrain maps are often best analysed in grayscale rather than colour. To edit the properties of the LRM and SVF right click on the file in the Layer Manager and click on "set colour table"



3. Take some time to experiment with the colour options for each raster

| Required Colors Optional Command output           | 4 🕨 🗙        |
|---|--------------|
| Invert colors                                     | (n           |
| Logarithmic scaling                               | (g           |
| Logarithmic-absolute scaling                      | (a           |
| Histogram equalization                            | (e           |
| ype of color table:                               | (color=style |
| grey255   |              |
| ath to rules file ("+" to read rules from stdin): | (rules=name  |
|   | Browse       |
| r enter values interactively                      | 10721-0000   |
| , end (data intracting)                           | 12           |
|   | <u> </u>     |
|   |              |
|   |              |
|   |              |

4. Use the Profile tool (Task 11) to compare the models over archaeological features. Notice particularly the z units. What conclusions can you draw about the different modelling techniques?

# **Useful Information / Resources**

A how to list for QGIS.... <u>http://dl.dropbox.com/u/2858167/Selected%20How</u> <u>%20To\_withEmail.pdf</u>

The QGIS forum - <u>http://forum.qgis.org/</u> full of lovely helpful people.

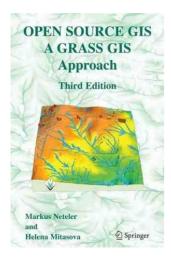
The QGIS project homepage http://www.qgis.org/

The GRASS wiki - <u>http://grass.osgeo.org/wiki/GRASS-Wiki</u> particularly the lidar page <u>http://grass.osgeo.org/wiki/LIDAR</u>

GRASS reference manual, <u>http://grass.itc.it/gdp/html\_grass63/index.html</u> for detailed information, sources and usage tips on each of the tools.

GRASS tutorials http://grass.osgeo.org/gdp/tutorials.php

The GRASS users mailing list - <u>http://grass.ibiblio.org/community/support.php</u> check the archives for useful tips



The GRASS bible – hard work to get through at times but certainly the most comprehensive guide to using GRASS

Markus Neteler and Helena Mitasova, 2008, Open Source GIS: A GRASS GIS Approach. Third Edition. The International Series in Engineering and Computer Science: Volume 773. 406 pages, 80 illus., <u>Springer</u>, New York

ISBN: 038735767X | ISBN-13: 978-0-387-35767-6 | <u>eBook</u> e-ISBN-13: 978-0-387-68574-8 Published 1st Nov. 2007

OSGeo <u>http://www.osgeo.org/</u> - a portal for all thinks OS and Geographical in the UK

OSGeo4W - <u>http://trac.osgeo.org/osgeo4w/</u> where to download QGIS and GRASS for Windows

## **OS GIS Professionals...**

For examples of how OSGeo software is being used commercially in archaeology and heritage management -

http://thehumanjourney.net/index.php?
option=com\_content&task=view&id=316&Itemid=201

## And Finally...LAS Tools

The current version of GRASS does not have native support for las files (though

Rebecca Bennett

GRASS 7 will) LASTOOLS provide a comprehensive set of tools for converting las files and clipping them to your study area before importing them to GRASS. <u>http://www.cs.unc.edu/~isenburg/lastools/</u>