

Lexium MDrive®

LMD•M85 programmable Motion Control

Product overview

Robust Lexium MDrive[®] Motion Control products integrate 1.8° 2-phase stepper motors with control electronics. Included are on-board programmable motion controller for stand-alone operation, and optional hMT closed loop performance.

hMT closed loop performance is available in products with either a multi-turn absolute encoder or incremental magnetic encoder. Closed loop performance maintains functional motor control to prevent loss of synchronization, offers variable current control, torque control, and use of the motor's full torque range without derating.

Multi-turn absolute encoders may benefit users by detecting and storing position information, even when powered down. This can eliminate homing routines and reduce setup time at system startup.

Product parameterization, programming and monitoring is through user-friendly software with an RS-422/485 serial interface. Settings can be downloaded and stored in non-volitile memory.

Application areas

Especially well suited for industrial applications, products include an IP65 rated version with circular M12 connectors.

Compact Lexium MDrive products can reduce machine complexity, size and cost in many stepper and servo motor applications. Their high degree of integration can increase system reliability by reducing the number of individual components, eliminating multiple potential failure points.



LMD•M85 Lexium MDrive Motion Control products: integrated NEMA34 motor and controls, IP65 & IP20-rated

Features overview

| General | NEMA34 1.8° 2-phase stepper motor integrated with robust control electronics, including programmable motion controller | | |
|--------------------------|---|--|--|
| | Advanced current control for exceptional performance and smoothness | | |
| Input power | +12 to +70 VDC single supply | | |
| Communication | RS-422/485 serial interface | | |
| | 62 software addresses for multi-drop communications | | |
| | Graphical user interface provided for quick and easy parameter setup | | |
| Encoder options | Multi-turn absolute or incremental magnetic | | |
| Motion | 20 microstep resolutions up to 51,200 steps per rev including: Degrees, Metric, Arc Minutes | | |
| | 336 user program labels / 11,120 bytes flash memory | | |
| | 0 to 2.56 MHz step clock rate selectable in 0.59 Hz increments | | |
| I/O, sourcing or sinking | +5 to +24 VDC signal inputs | | |
| | 12-bit analog input (1) | | |
| | 100ma power outputs | | |
| | 5.5mA high-speed signal output | | |
| Protection | 084°C temperature warning, user selectable | | |
| | IP20, IP65 ratings | | |
| Warranty | 4 year, conditional | | |

(1) Not available on products with multi-turn absolute encoder.

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Specifications

| Communication | Protocol type | | RS-422/485 |
|-------------------------|--------------------------|--------------------------------|--|
| Input power | Voltage | VDC | +12+60 |
| | Current maximum (1) | Amp | 3.5 |
| Motor | Frame size | NEMA | 34 |
| | | inches | 3.4 |
| | | mm | 85 |
| | Performance levels | | standard torque or premium high torque (2) |
| | Holding torque | oz-in | 336920 |
| | | N-cm | 237650 |
| | Length | stack sizes | 1, 2 & 3 |
| Thermal | Operating temp | Heat sink maximum | 85°C |
| | non-condensing | Motor maximum | 100°C |
| Protection | Туре | Temp warning | 084°C, user selectable |
| | | IP rating | IP20, IP65 |
| | | Earth grounding | via product chassis ground lug |
| I/O sourcing or sinking | One analog input (3) | Resolution | 12 bit |
| | | Voltage range | 0+5 VDC, 0+10 VDC, 020 mA, 420 mA |
| | Three signal inputs | Voltage range | +5+24 VDC, TTL level compatible |
| | | Protection | over temp, short circuit, transient, over voltage, inductive clamp |
| | Two power outputs (4) | Current rating | -100+100 mA |
| | | Voltage range | -24+24 VDC |
| | One high-speed signal | Current open collector/emitter | 5.5 mA |
| | output | Voltage open collector | +60 VDC |
| | | Voltage open emitter | +7 VDC |
| Aux. logic input | Voltage range (5) | | +12+24 VDC |
| Encoder options | Multi-turn absolute | Position update / retention | 30 days on internal power; 5 years with optional battery pack |
| · | Incremental magnetic | Line count | 1000 lines / 4000 edges per rev |
| Motion | Microstep resolution | Number of settings | 20 |
| | · | Steps per revolution | 200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 20000, 25000, 25600, 40000, 50000, 51200, 36000 (0.01 deg/µstep), 21600 (1 arc minute/µstep), 25400 (0.001mm/µstep) |
| | Counters | Туре | position, encoder/32 bit |
| | | Edge rate maximum | 5 MHz |
| | Velocity | Range | +/-2,560,000 |
| | | Resolution | 0.5961 steps per second |
| | Accel/Decel | Range | 1.5 x 10 ⁹ steps per second ² |
| | | Resolution | 90.9 steps per second ² |
| | | Types | linear, triangle s-curve, sinusoidal s-curve |
| Software | Program storage | Type/size | flash / 11,120 |
| | User registers | Number/resolution | 4 / 32-bit |
| | Floating point registers | Number/precision | 8 / double |
| | Math functions | Arithmetic | +, -, X, ÷, >, <, =, >=, <= |
| | | Logic | AND, OR, XOR, NOT |
| | | Trigonometric | ABS, COS, ACOS, LOG2, LOG10, PI, SIN, ASIN, SQRT, TAN, ATAN |
| | Branch functions | | Branch & call |
| | I/O functions | Inputs | Home, limit plus, limit minus, go, stop, pause, jog plus, jog minus, general purpose, capture |
| | | Outputs | Moving, error, velocity change,, moving position, trip, attention. general purpose |
| | Trip functions | | Trip on input, trip on position, trip on time, trip capture, trip on relative position, tri on main power loss |
| | Party-mode addresses | | 62 |
| | Encoder functions (6) | | stall detection, position maintenance, find index, hMT |

(2) Contact factory for details.

(3) Not available on products with multi-turn absolute encoder.

(4) Products with multi-turn absolute encoder have one power output.

(5) When input voltage is removed, maintains power only to control and feedback circuits.

(6) Closed-loop models with encoder only.

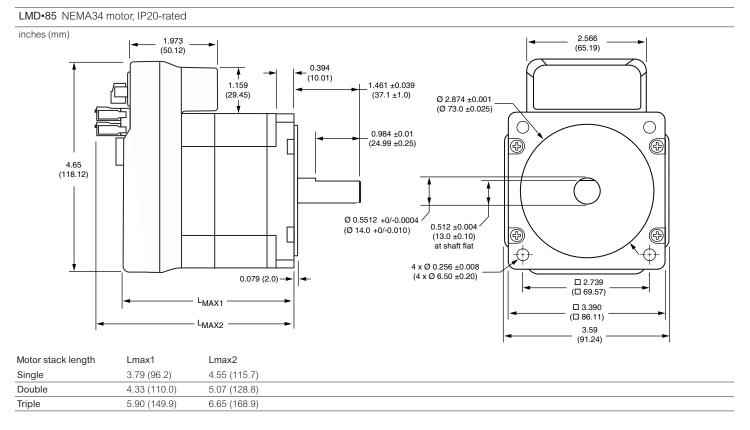
An optional Communication Converter is recommended to facilitate prototyping.



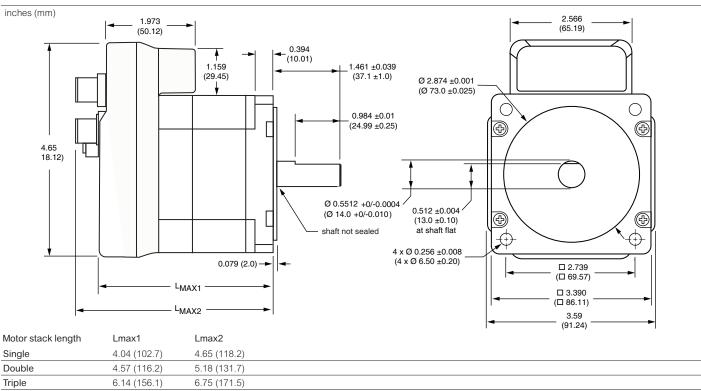
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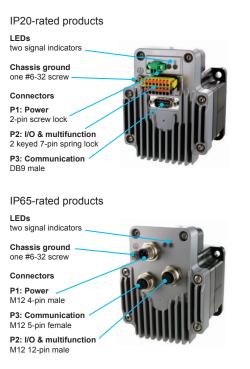
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Dimensions



LMD•85•C NEMA34 motor, IP65-rated







Part numbers

| example part number | L | Μ | D | С | Μ | 8 | 5 | 1 | С |
|--|---|---|---|---|---|---|---|---|---|
| Product LMD = Lexium MDrive with standard hybrid stepper motor LMH = Lexium MDrive with high torque stepper motor (1) | L | Μ | D | С | Μ | 8 | 5 | 1 | С |
| Control type C = Closed loop / with hMT and incremental magnetic encoder (2) A = Closed loop / with hMT and multi-turn absolute encoder (2) O = Open loop / no hMT or encoder | L | М | D | С | М | 8 | 5 | 1 | С |
| Communication type M = programmable Motion Control via RS-422/485 serial interface | L | Μ | D | С | Μ | 8 | 5 | 1 | С |
| Flange size 85 = NEMA 34 3.4" / 85mm | L | Μ | D | С | М | 8 | 5 | 1 | С |
| Motor length 1 = single stack 2 = double stack 3 = triple stack | L | М | D | С | Μ | 8 | 5 | 1 | С |
| Variation — omit from part number if unwanted C = M12 circular connectors and IP65 rating | L | Μ | D | С | Μ | 8 | 5 | 1 | С |

(1) Contact the factory for product details.

(2) Closed loop control delivers encoder feedback and hMT enhanced motor performance.

Accessories

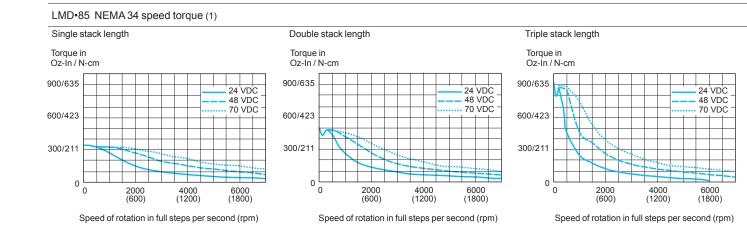
| description | length feet (m) | part number |
|--|--------------------|--------------|
| Communication converter USB-pluggable converter to set/program communication parameters in 32- or 64-bit | | |
| Mates to DB9 connector | 6.0 (1.8) | MD-CC404-00 |
| Mates to M12 5-pin female connector | 6.0 (1.8) | MD-CC405-00 |
| IP65 cordsets Shielded cables pre-wired with straight M12 mating connectors | | |
| Communication cordset mates to 5-pin female connector | 10.0 (3.0) | MD-CS600-00 |
| Power cordset mates to 4-pin male connector | 10.0 (3.0) | MD-CS620-00 |
| I/O cordset mates to 12-pin male connector | 10.0 (3.0) | MD-CS610-00 |
| Back-up battery pack for Absolute Encoder models Extend stored position data up to 5-years for 1 to 6 LMDs with absolute encoder | | |
| Battery pack, DIN-rail mount. Uses 3 AA batteries, not provided | — | ICP0531 |
| LMD mating cable(s) with crimp connector to flying lead end | 3.3 (1.0) | PD02-0531-FL |
| PLC mating cable with crimp connector to flying lead end | 3.3 (1.0) | PD04-0531-FL |
| | | |

Lexium MDrive LMD•M85 programmable Motion Control

Motor performance

LMD•85 NEMA 34 motor specifications

| Motor | Stack length | Single | Double | Triple |
|------------------------------------|------------------------|--------|--------|--------|
| | oz-in | 336 | 480 | 920 |
| Holding torque | N-cm | 237 | 339 | 650 |
| Detent torque | oz-in | 10.9 | 14.16 | 19.83 |
| | N-cm | 7.7 | 10.0 | 14.0 |
| Rotor inertia | oz-in-sec ² | 0.0127 | 0.0191 | 0.0382 |
| | kg-cm ² | 0.90 | 1.35 | 2.70 |
| Radial load limit, center of shaft | lbs | 65 | 65 | 65 |
| Radial load limit, center of shart | kg | 29.4 | 29.4 | 29.4 |
| Axial load limit @ 1500rpm | lbs | 20 | 20 | 20 |
| (5000 full steps/sec) | kg | 9 | 9 | 9 |
| Maight (mater I driver) | lb | 4.45 | 5.65 | 9.0 |
| Weight (motor+driver) | kg | 2.02 | 2.56 | 4.08 |



(1) Test conditions: 100% current with damper simulating load.

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Intelligent motion systems Schneider