



# Moments in 3D



*Shortest distance between two jokes?*

*A straight line.*



## Objectives

- Understand what a moment represents in mechanics
- Understand the vector formulation of a moment



## Tools

- Basic Trigonometry
- Pythagorean Theorem
- Algebra
- Visualization
- Position Vectors
- Unit Vectors



## Three Dimensions

- Clockwise and counter-clockwise really don't have any meaning in three dimensional problems
- Vectors make life much easier in three dimensions



## Three Dimensions

- Once again, we construct a moment arm from the center of rotation to the line of action of the force causing the rotation
- The moment arm is nothing more than a position vector from the moment center to the line of action of the force

5

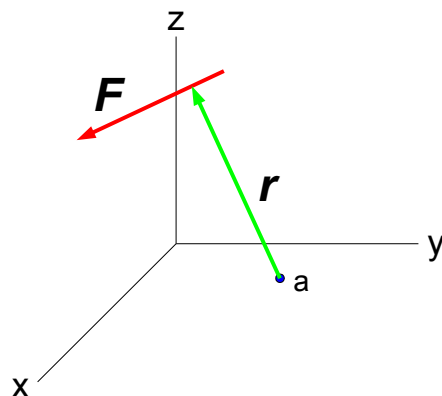
Moments in 3D

Wednesday ,September 19, 2012



## Three Dimensions

- $\mathbf{F}$  is the force vector and  $\mathbf{r}$  is the moment arm vector



6

Moments in 3D

Wednesday ,September 19, 2012

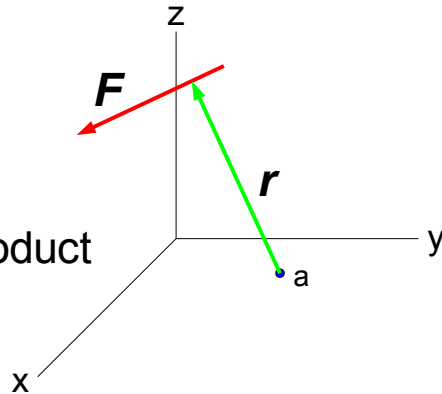


## Three Dimensions

- The moment generated about point a by the force  $F$  is given by the expression

$$\vec{M} = \vec{r} \otimes \vec{F}$$

where  $\otimes$  is the cross product



7

Moments in 3D

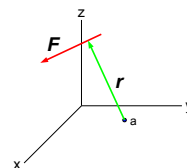
Wednesday, September 19, 2012



## Cross Product

- The cross product is the second type of vector multiplication
- Unlike the dot product which produced a scalar, the cross product produces a vector
- Unlike the dot product, the order in which we write the terms is important

$$\vec{M} = \vec{r} \otimes \vec{F} \neq \vec{F} \otimes \vec{r}$$



8

Moments in 3D

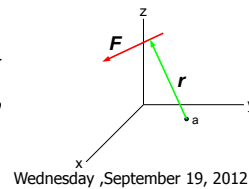
Wednesday, September 19, 2012



## Cross Product

- One of the most commonly made mistakes when dealing with moments in three dimensions is to put the order of the cross product in the incorrect order

$$\vec{M} = \vec{r} \otimes \vec{F} \neq \vec{F} \otimes \vec{r}$$



9

Moments in 3D

Wednesday, September 19, 2012



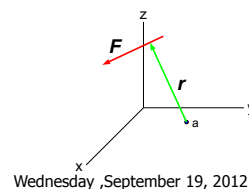
## Cross Product

- For the dot product, the product of two like unit vectors was 1 and any other product equals 0

$$\vec{i} \odot \vec{i} = 1$$

$$\vec{j} \odot \vec{j} = 1$$

$$\vec{k} \odot \vec{k} = 1$$



10

Moments in 3D

Wednesday, September 19, 2012



## Cross Product

- For the cross product, things are a bit more complicated

$$\vec{i} \otimes \vec{i} = 0$$

$$\vec{i} \otimes \vec{j} = \vec{k}$$

$$\vec{i} \otimes \vec{k} = -\vec{j}$$

$$\vec{j} \otimes \vec{i} = -\vec{k}$$

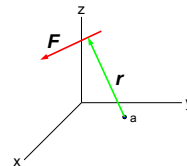
$$\vec{j} \otimes \vec{j} = 0$$

$$\vec{j} \otimes \vec{k} = \vec{i}$$

$$\vec{k} \otimes \vec{i} = \vec{j}$$

$$\vec{k} \otimes \vec{j} = -\vec{i}$$

$$\vec{k} \otimes \vec{k} = 0$$



11

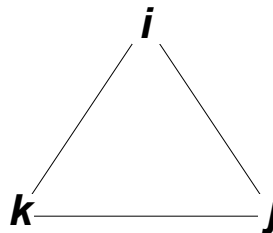
Moments in 3D

Wednesday, September 19, 2012



## Cross Product

- A simple way to remember



$$\vec{i} \otimes \vec{i} = 0$$

$$\vec{i} \otimes \vec{j} = \vec{k}$$

$$\vec{i} \otimes \vec{k} = -\vec{j}$$

$$\vec{j} \otimes \vec{i} = -\vec{k}$$

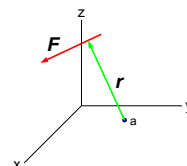
$$\vec{j} \otimes \vec{j} = 0$$

$$\vec{j} \otimes \vec{k} = \vec{i}$$

$$\vec{k} \otimes \vec{i} = \vec{j}$$

$$\vec{k} \otimes \vec{j} = -\vec{i}$$

$$\vec{k} \otimes \vec{k} = 0$$



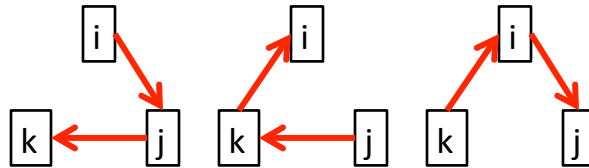
12

Moments in 3D

Wednesday, September 19, 2012

# Cross Product

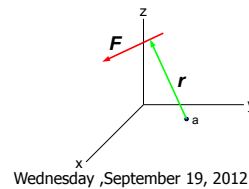
## Positive results



$$\begin{array}{lll} \vec{i} \otimes \vec{i} = 0 & \vec{i} \otimes \vec{j} = \vec{k} & \vec{i} \otimes \vec{k} = -\vec{j} \\ \vec{j} \otimes \vec{i} = -\vec{k} & \vec{j} \otimes \vec{j} = 0 & \vec{j} \otimes \vec{k} = \vec{i} \\ \vec{k} \otimes \vec{i} = \vec{j} & \vec{k} \otimes \vec{j} = -\vec{i} & \vec{k} \otimes \vec{k} = 0 \end{array}$$

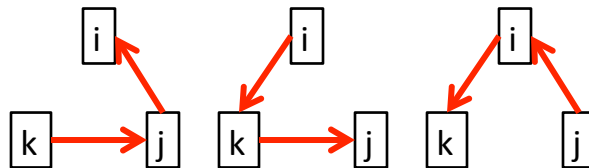
13

Moments in 3D



# Cross Product

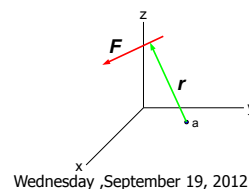
## Negative results



$$\begin{array}{lll} \vec{i} \otimes \vec{i} = 0 & \vec{i} \otimes \vec{j} = \vec{k} & \vec{i} \otimes \vec{k} = -\vec{j} \\ \vec{j} \otimes \vec{i} = -\vec{k} & \vec{j} \otimes \vec{j} = 0 & \vec{j} \otimes \vec{k} = \vec{i} \\ \vec{k} \otimes \vec{i} = \vec{j} & \vec{k} \otimes \vec{j} = -\vec{i} & \vec{k} \otimes \vec{k} = 0 \end{array}$$

14

Moments in 3D



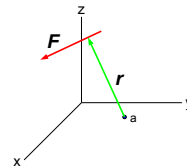


## Cross Product

- o If we have a position vector  $\vec{r}$  and a force vector  $\vec{F}$  defined as

$$\vec{F} = F_x \vec{i} + F_y \vec{j} + F_z \vec{k}$$

$$\vec{r} = r_x \vec{i} + r_y \vec{j} + r_z \vec{k}$$



15

Moments in 3D

Wednesday, September 19, 2012



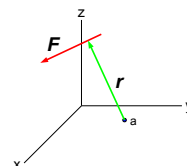
## Cross Product

- o We can calculate the moment of the force about the point by taking the cross product

$$\vec{M} = \vec{r} \otimes \vec{F}$$

$$\vec{M} = (r_x \vec{i} + r_y \vec{j} + r_z \vec{k}) \otimes (F_x \vec{i} + F_y \vec{j} + F_z \vec{k})$$

$$\begin{aligned} \vec{M} = & r_x \vec{i} \otimes (F_x \vec{i} + F_y \vec{j} + F_z \vec{k}) \\ & + r_y \vec{j} \otimes (F_x \vec{i} + F_y \vec{j} + F_z \vec{k}) \\ & + r_z \vec{k} \otimes (F_x \vec{i} + F_y \vec{j} + F_z \vec{k}) \end{aligned}$$



16

Moments in 3D

Wednesday, September 19, 2012



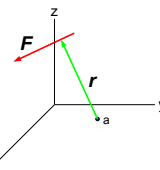


## Cross Product

### Expanding

$$\begin{aligned}\vec{M} &= r_x \vec{i} \otimes F_x \vec{i} + r_x \vec{i} \otimes F_y \vec{j} + r_x \vec{i} \otimes F_z \vec{k} \\ &\quad + r_y \vec{j} \otimes F_x \vec{i} + r_y \vec{j} \otimes F_y \vec{j} + r_y \vec{j} \otimes F_z \vec{k} \\ &\quad + r_z \vec{k} \otimes F_x \vec{i} + r_z \vec{k} \otimes F_y \vec{j} + r_z \vec{k} \otimes F_z \vec{k}\end{aligned}$$

$$\begin{aligned}\vec{M} &= (r_x F_x)(\vec{i} \otimes \vec{i}) + (r_x F_y)(\vec{i} \otimes \vec{j}) + (r_x F_z)(\vec{i} \otimes \vec{k}) \\ &\quad + (r_y F_x)(\vec{j} \otimes \vec{i}) + (r_y F_y)(\vec{j} \otimes \vec{j}) + (r_y F_z)(\vec{j} \otimes \vec{k}) \\ &\quad + (r_z F_x)(\vec{k} \otimes \vec{i}) + (r_z F_y)(\vec{k} \otimes \vec{j}) + (r_z F_z)(\vec{k} \otimes \vec{k})\end{aligned}$$



17

Moments in 3D

Wednesday, September 19, 2012



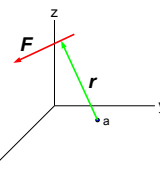
## Cross Product

### Using our cross product rules for unit vectors

$$\begin{aligned}\vec{M} &= (r_x F_x)(0) + (r_x F_y)(\vec{k}) + (r_x F_z)(-\vec{j}) \\ &\quad + (r_y F_x)(-\vec{k}) + (r_y F_y)(0) + (r_y F_z)(\vec{i}) \\ &\quad + (r_z F_x)(\vec{j}) + (r_z F_y)(-\vec{i}) + (r_z F_z)(0)\end{aligned}$$

$$\begin{aligned}\vec{M} &= (r_x F_y)(\vec{k}) - (r_x F_z)(\vec{j}) - (r_y F_x)(\vec{k}) \\ &\quad + (r_y F_z)(\vec{i}) + (r_z F_x)(\vec{j}) - (r_z F_y)(\vec{i})\end{aligned}$$

$$\vec{M} = (r_y F_z - r_z F_y)\vec{i} + (r_z F_x - r_x F_z)\vec{j} + (r_x F_y - r_y F_x)\vec{k}$$



18

Moments in 3D

Wednesday, September 19, 2012

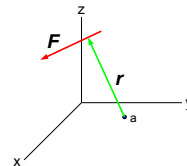


## Cross Product

- One thing to notice here

$$\vec{M} = (r_y F_z - r_z F_y) \vec{i} + (r_z F_x - r_x F_z) \vec{j} + (r_x F_y - r_y F_x) \vec{k}$$

If we are in two dimensions (x and y) there will be no i and j components to the resulting moment. The moment will be either into the page or out of the page. Since we follow the right hand rule for all our axes, into the page would be negative and out of the page would be positive. This corresponds to CW and CCW.



19

Moments in 3D

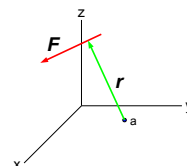
Wednesday, September 19, 2012



## Cross Product

- We can also set up the cross product as a matrix

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$



20

Moments in 3D

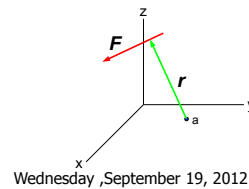
Wednesday, September 19, 2012



## Cross Product

- There are a number of ways to expand this matrix to find the solution, use whatever way you are comfortable with

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$



21

Moments in 3D

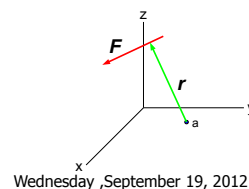
Wednesday, September 19, 2012



## Cross Product

- Since I could never keep the signs straight, I always use what appeared to me to be a very simple technique

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$



22

Moments in 3D

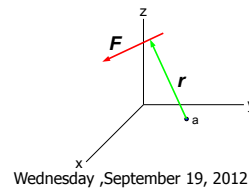
Wednesday, September 19, 2012



## Cross Product

- Copy the first two columns to the end of the matrix

$$\vec{I} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix} \begin{vmatrix} \vec{i} & \vec{j} \\ r_x & r_y \\ F_x & F_y \end{vmatrix}$$



23

Moments in 3D

Wednesday, September 19, 2012

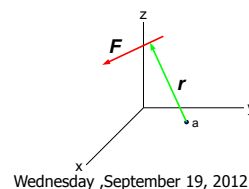


## Cross Product

- Start with the  $\vec{i}$  and move down and right

$$\vec{i} (r_y F_z)$$

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix} \begin{vmatrix} \vec{i} & \vec{j} \\ r_x & r_y \\ F_x & F_y \end{vmatrix}$$



24

Moments in 3D

Wednesday, September 19, 2012

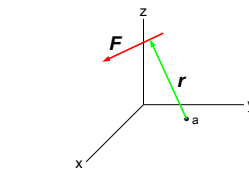


## Cross Product

- Then insert a negative sign and move down and left.

$$\vec{i}(r_y F_z - r_z F_y)$$

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix} = \begin{vmatrix} \vec{i} & \vec{j} \\ r_x & r_y \\ F_x & F_y \end{vmatrix}$$



25

Moments in 3D

Wednesday, September 19, 2012

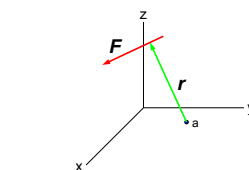


## Cross Product

- Move everything to the right and do the process again.

$$\vec{j}(r_z F_x - r_x F_z)$$

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix} = \begin{vmatrix} \vec{i} & \vec{j} \\ r_z & r_x \\ F_z & F_x \end{vmatrix}$$



26

Moments in 3D

Wednesday, September 19, 2012

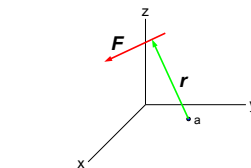


## Cross Product

- Move everything to the right and do the process again.

$$\vec{j}(r_z F_x - r_x F_z)$$

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$



27

Moments in 3D

Wednesday, September 19, 2012

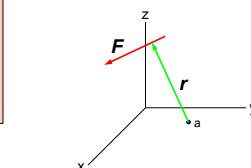


## Cross Product

- Move everything to the right and do the process again.

$$\vec{k}(r_x F_y - r_y F_x)$$

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$



28

Moments in 3D

Wednesday, September 19, 2012

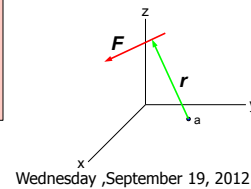


## Cross Product

- Move everything to the right and do the process again.

$$\vec{k}(r_x F_y - r_y F_x)$$

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$



29

Moments in 3D

Wednesday, September 19, 2012

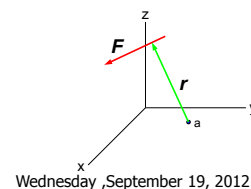


## Cross Product

- Add the individual results.

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$

$$\vec{M} = \vec{i}(r_y F_z - r_z F_y) + \vec{j}(r_z F_x - r_x F_z) + \vec{k}(r_x F_y - r_y F_x)$$



30

Moments in 3D

Wednesday, September 19, 2012



## Problem F4-11

Determine the moment of force  $F$  about point  $O$ . Express the result as a Cartesian vector.

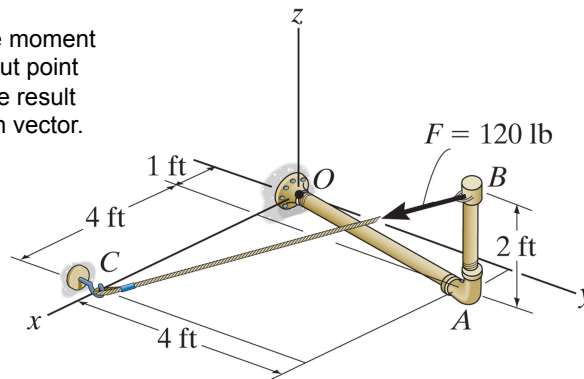


Figure: 04\_FP011

Copyright ©2013 Pearson Education, publishing as Pearson Hall

31

Moments in 3D

Wednesday, September 19, 2012



## Problem F4-12

If  $\mathbf{F}_1 = \{100\mathbf{i} - 120\mathbf{j} + 75\mathbf{k}\}$  lb and  $\mathbf{F}_2 = \{-200\mathbf{i} - 250\mathbf{j} + 100\mathbf{k}\}$  lb, determine the resultant moment produced by these forces about point  $O$ . Express the result as a Cartesian vector.

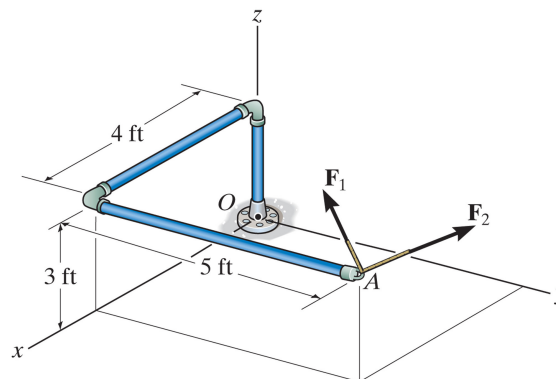


Figure: 04\_FP012

Copyright ©2013 Pearson Education, publishing as Pearson Hall

32

Moments in 3D

Wednesday, September 19, 2012





# Homework

- Problem 4-30
- Problem 4-33
- Problem 4-34