

# Motion Capture

# Virtual Human Animation

- Problem #1: create realistic motions
  - Perceptual/visual realism
  - Behavioural realism (similar to what a real human would have done)
- Problem #2: controlling motions
- Problem #3: computation
  - e.g., for interactive applications

# Virtual Human Animation

- Two main families of approaches
  - Kinematic models : based on joint trajectories
    - Descriptive models
    - Motion capture
    - ...
  - Physical models: based on physical equations of motion (forces, accelerations, masses, etc)
    - Physical controllers
    - Dynamic filters
    - ...

# Descriptive models

- For well known motions
- Based on knowledge of how joint trajectories are influenced by known parameters
  - Based on data averaged over a population
  - New motion requires to determine new laws

Fitts' law



$$T = a + b \cdot I_d = a + b \cdot \log_2\left(\frac{2D}{W}\right)$$

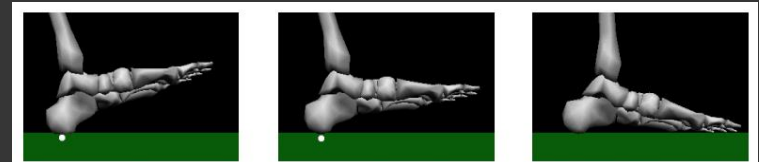
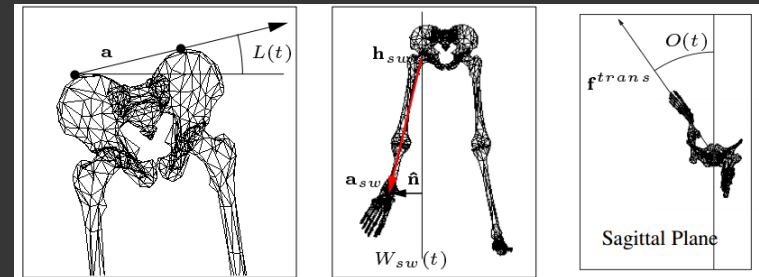
$T$  Average task time

$D$  Distance to target

$W$  Width of the target

$a, b$  empirically estimated constants

Locomotion



E.g., *Automating gait generation*, SIGGRAPH 2001

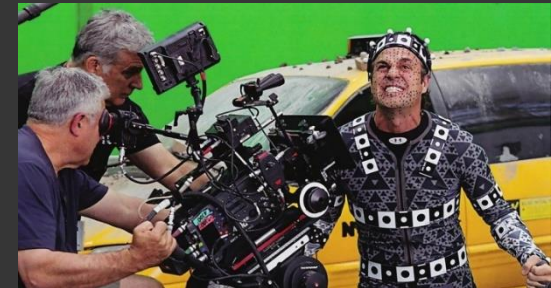
# Motion Capture

- Process of translating a live performance into a digital performance

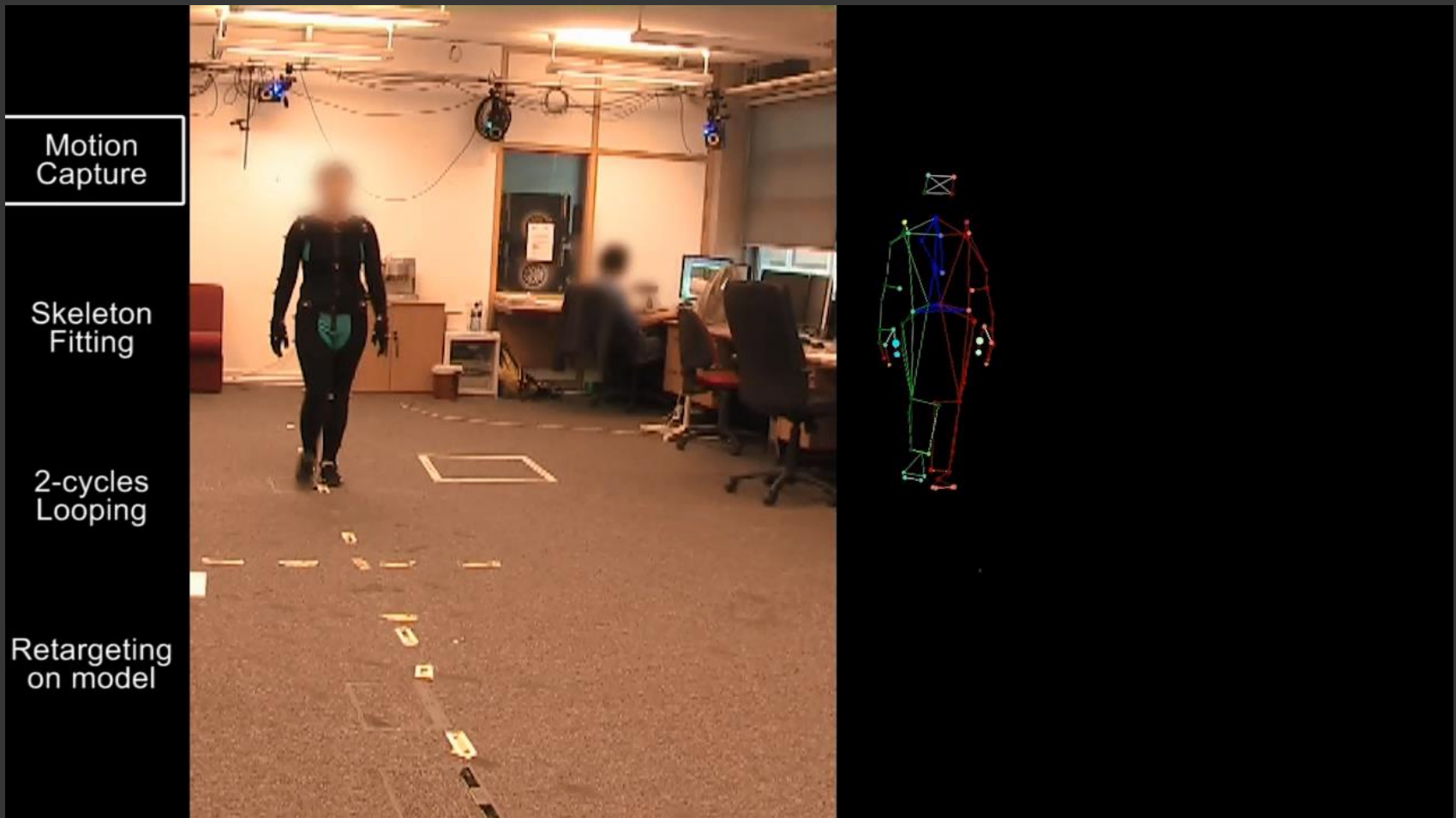


# Motion Capture

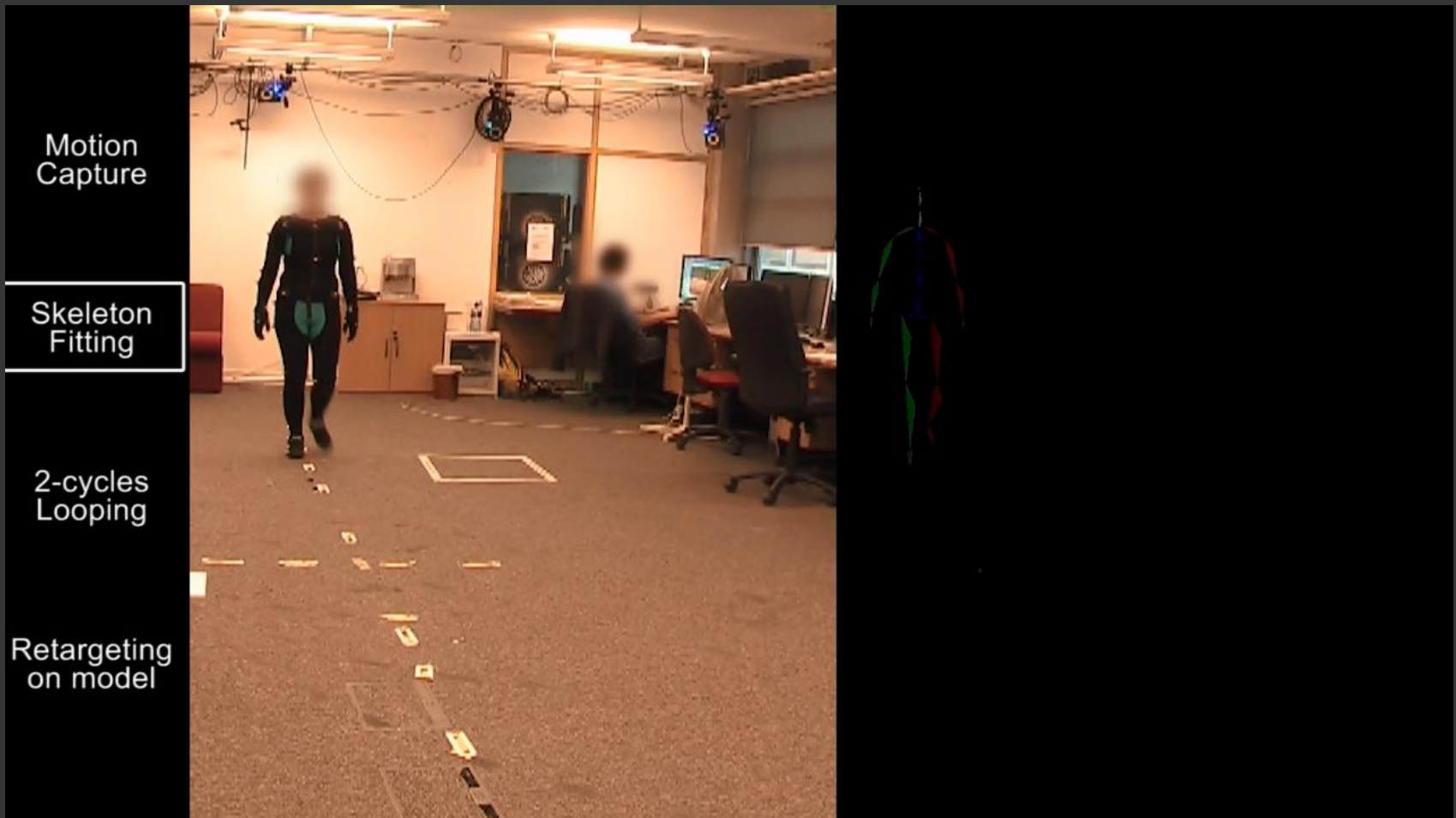
- Advantages
  - Realistic human motion
  - More rapid results can be obtained
  - Complex movement and realistic physical interactions can be easily re-created
- Disadvantages
  - Proprietary hardware and programs
  - Cost & space requirements
  - Reshoot
  - Artifacts may occur if the computer model has different proportions from the actor
    - retargeting
  - The real life performance may not translate on to the computer model as expected



# Motion Capture example

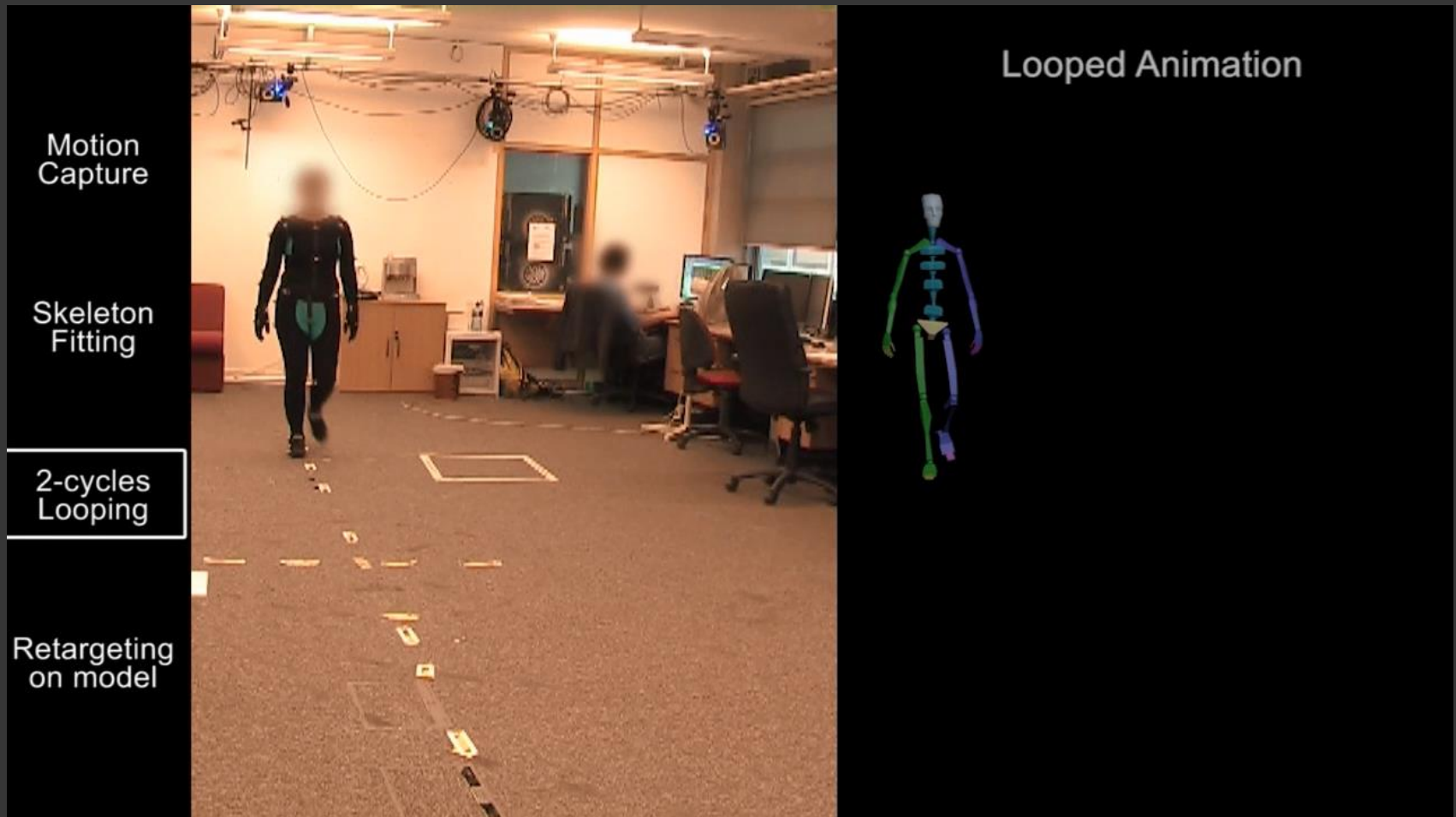


# Motion Capture example

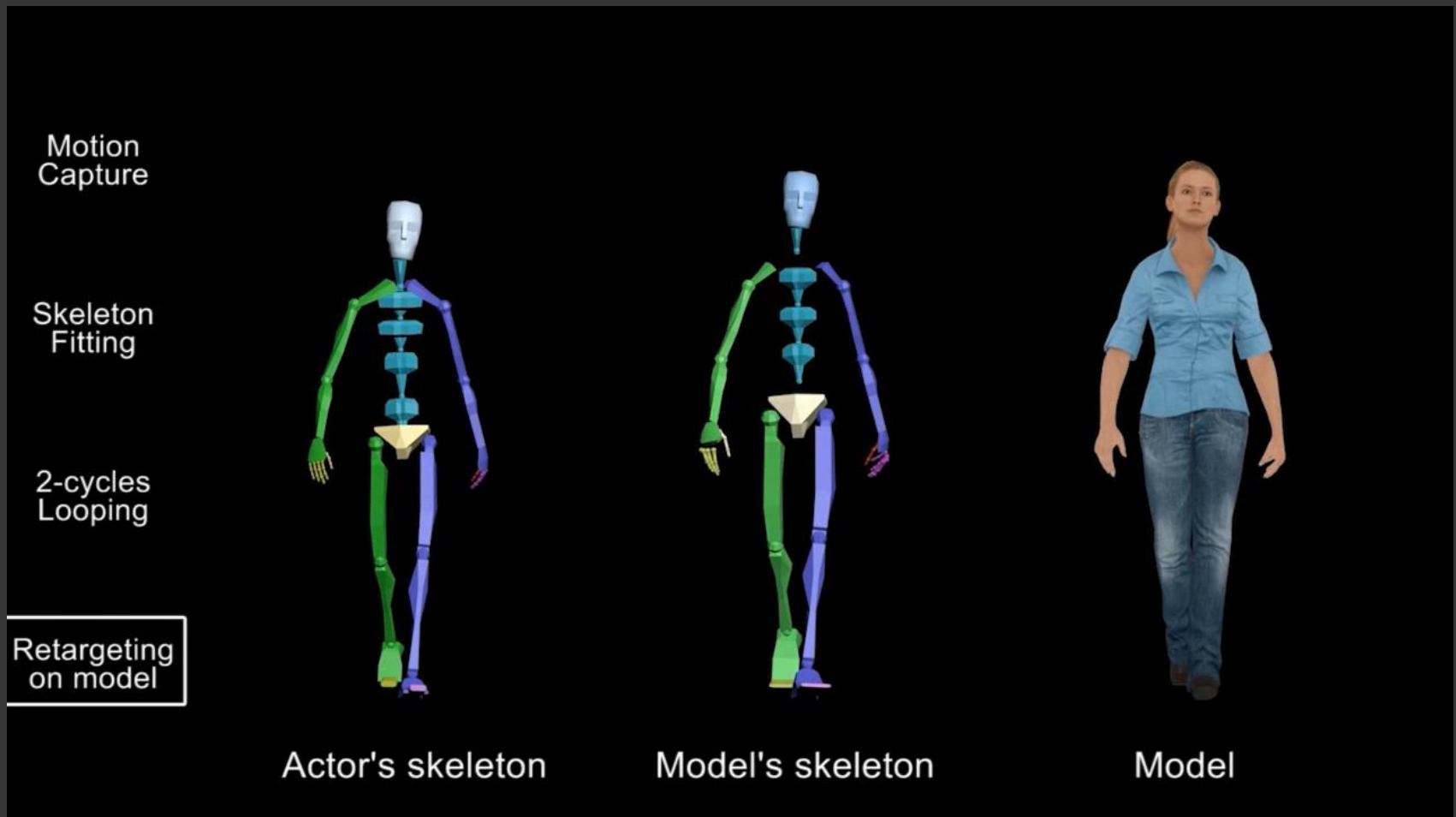




# Motion Capture example

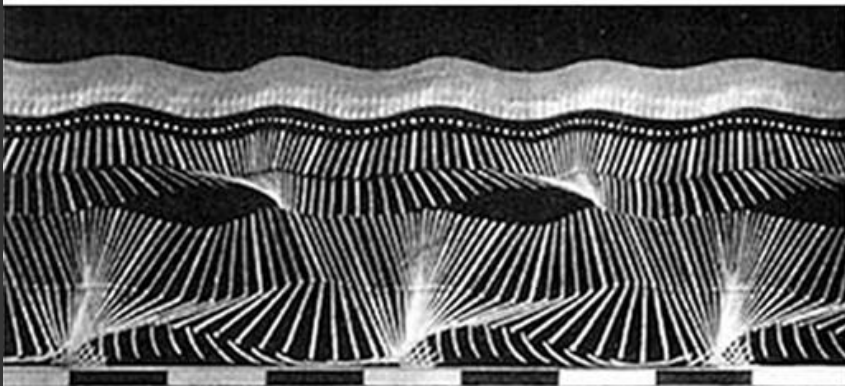
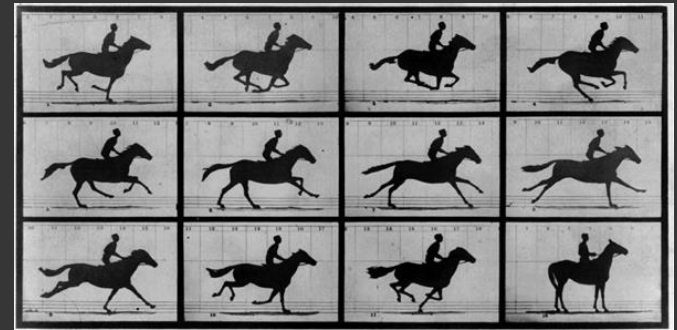
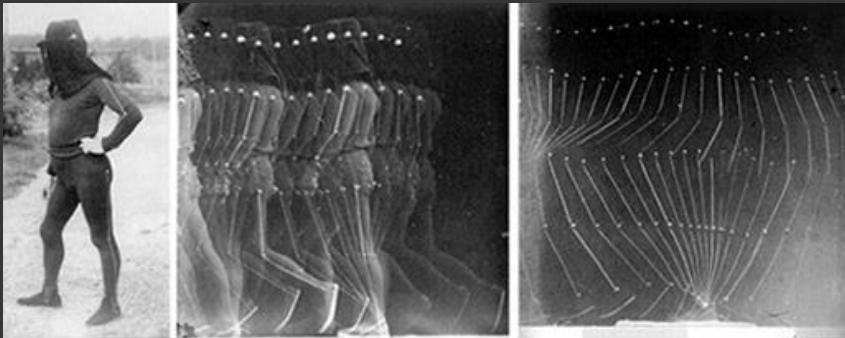


# Motion Capture example



# History of Mocap

- Early attempts to capture motion long before computer technology became available
  - Eadweard Muybridge (1830-1904)
  - Etienne-Jules Marey (1830-1904)

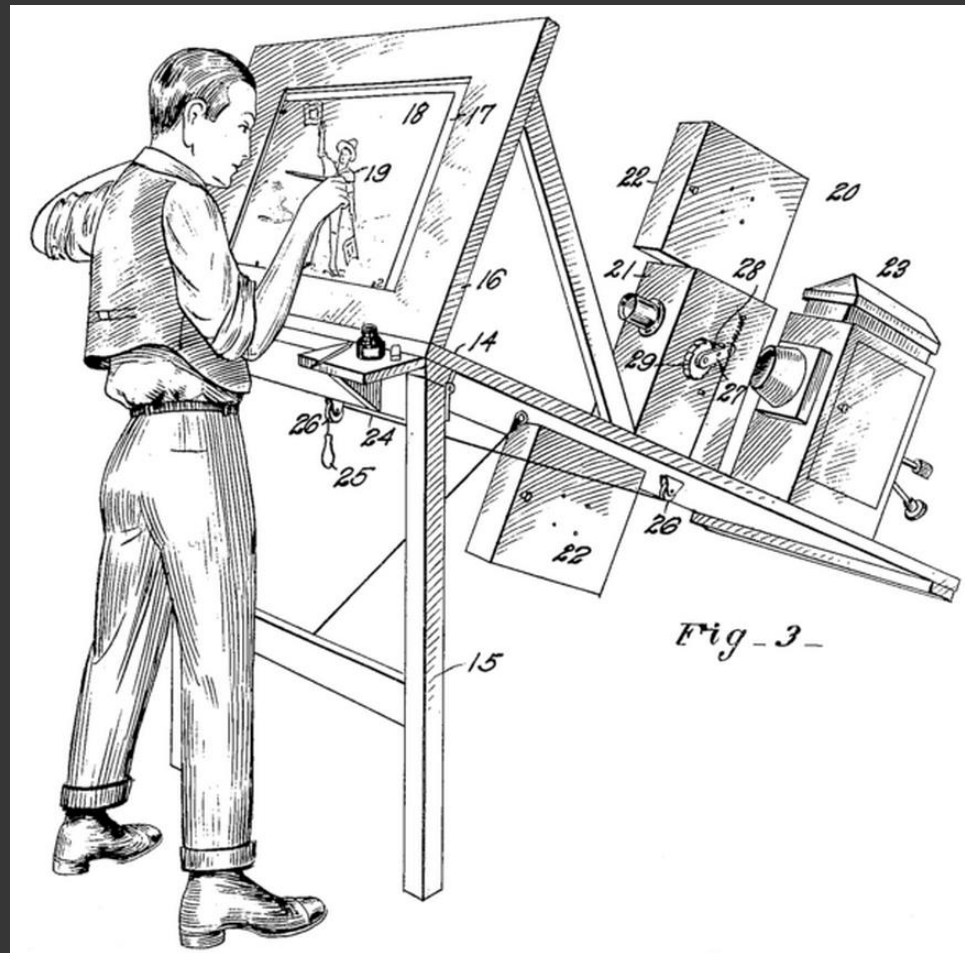


# Rotoscoping

- 1917 Max Fleischer
- Animation technique in which animators trace over live-action film movement, frame by frame, for use in animated films



# Rotoscoping





# Rotoscoping

- Disney
  - Stepmother <-> Eleanor Audley

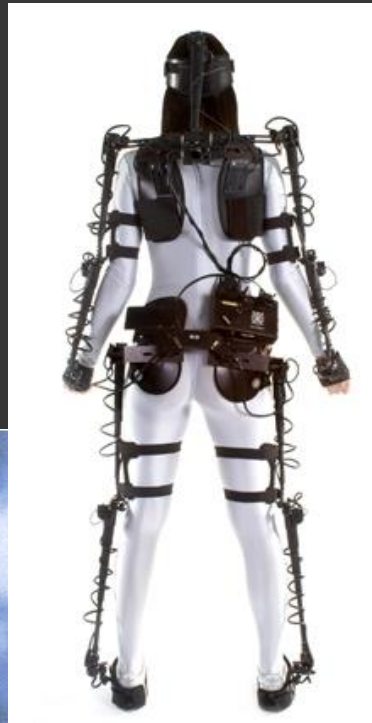
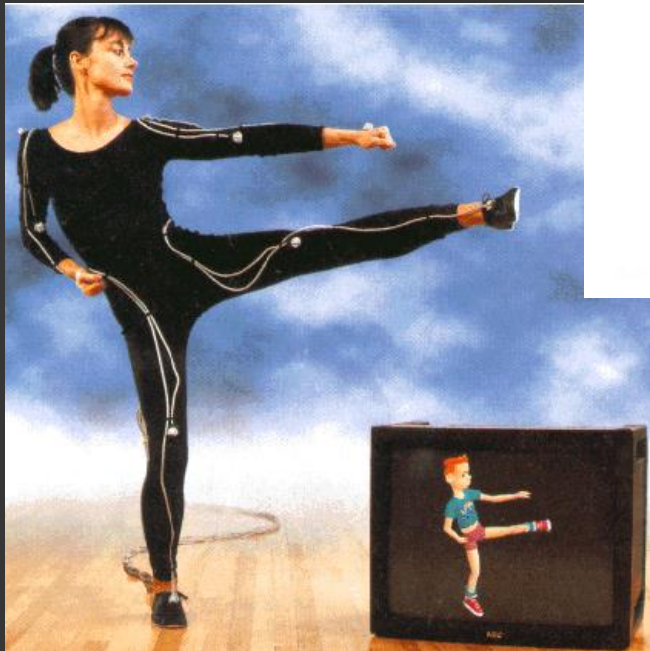


# Applications

- Medicine
  - Gait analysis
  - Prosthetic design
- Sports
  - Improve performance of athletes
  - Golf swing analysis
- Entertainments industry
  - Video games, television, feature films



# Types of Motion Capture

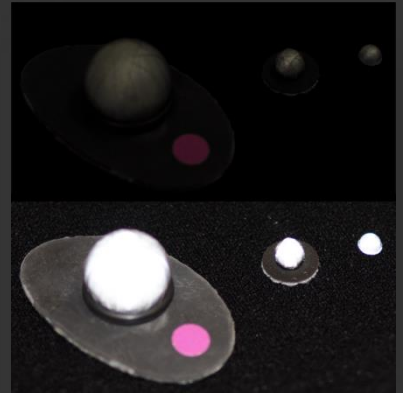


**KINECT**  
for XBOX 360.



# Optical Motion Capture Systems

- Single computer controller
- No wires or electronic equipment necessary
- Cameras have own infrared light sources
- Marker spheres
  - Range in size depending on capture area
  - Reflective material
- Cameras adjusted so
  - Narrow range of sensitivity to light
  - Only the bright markers will be sampled ignoring skin and fabric



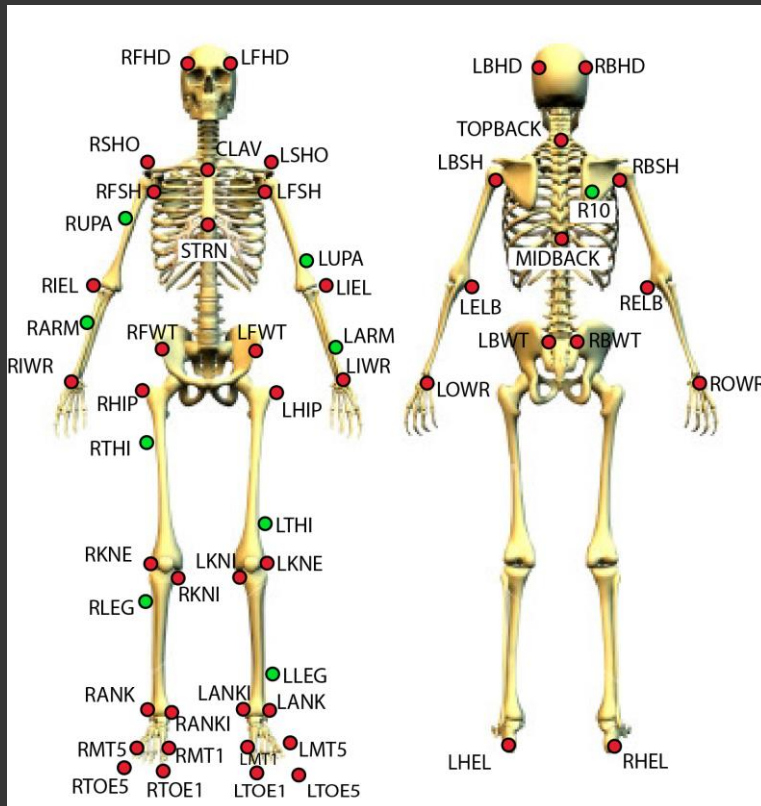
# Calibration

- Object of known dimension
- Tracked by all cameras
- Combines view of object from all cameras
  - Exact position of each camera in space can be calculated



# Markers

- Placing markers
  - Set of 45+ placed on the body of the actor



# Markers

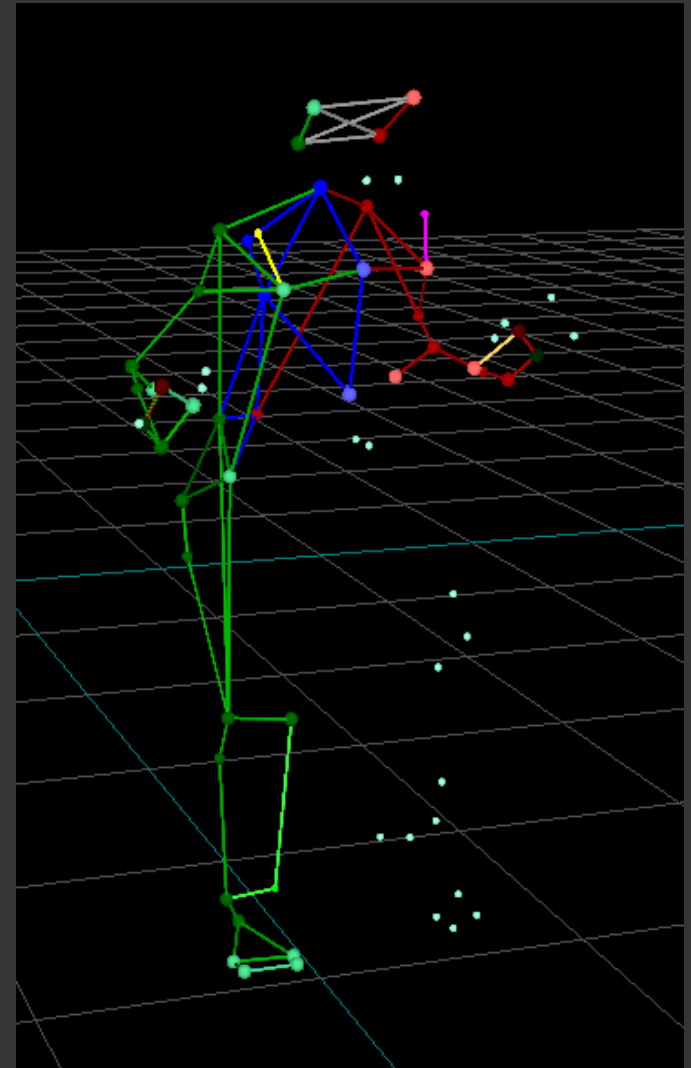
- Set of 45+ markers placed on the body of the actor
  - Usually positioned on anatomical locations
  - Markers define local coordinate system of each segment
  - At least 3 non-aligned markers per segment (define plane)
  - Hypothesis that markers belong to rigid bodies
    - constant distances, but in reality there are skin movements
  - Standards exist: H-ANIM (International Society of Biomechanics)
  - Compute coordinate system of each segment
    - Defines local coordinate systems in hierarchy

# Markers

- Detecting markers
  - Separate all the groups of pixels that exceed a predetermined luminosity threshold
  - Fit a circle to identify marker center
  - Rotational information must be inferred from the relative orientation of three or more markers

# Markers

- Identifying markers
  - Requires operator assistance
  - Label each marker



# Joint Centers & Skeleton

- Define local coordinate system of each segment
  - At least 3 non-aligned markers per segment (define plane)
  - Hypothesis that markers belong to rigid bodies

$$RWT = 0.5 * (RFWT + RBWT)$$

$$LWT = 0.5 * (LFWT + LBWT)$$

$$X = \text{normalize}(LWT - RWT)$$

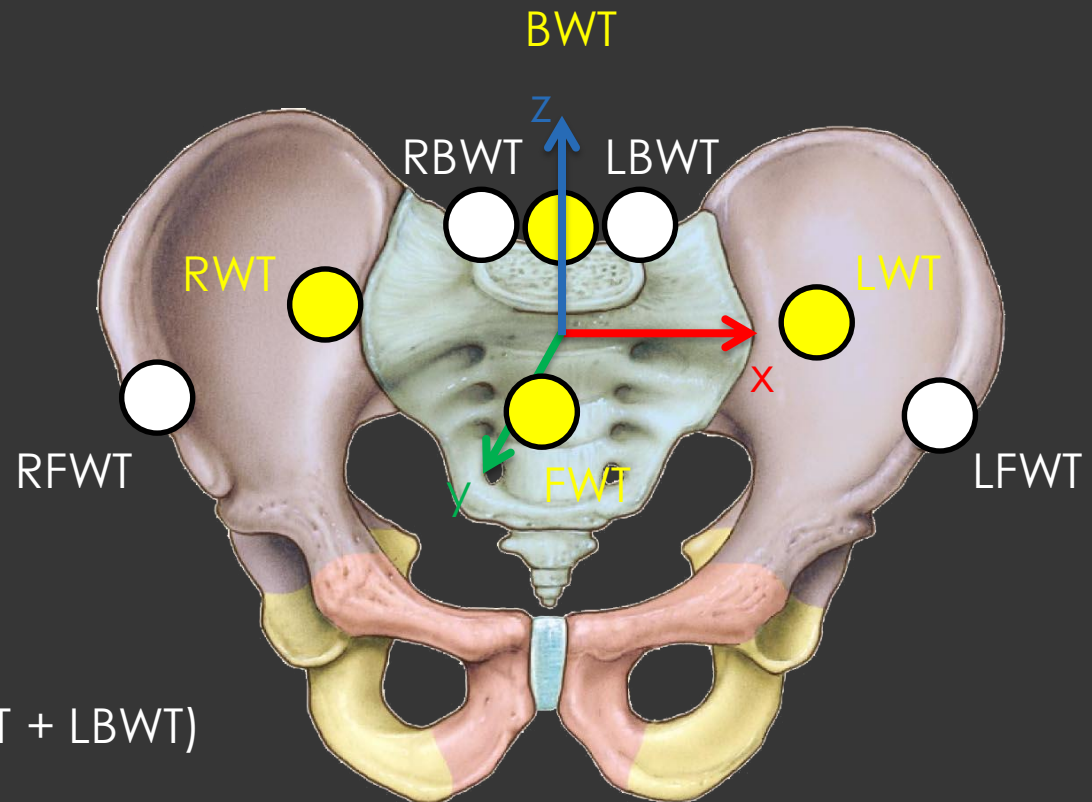
$$FWT = 0.5 * (RFWT + LFWT)$$

$$BWT = 0.5 * (RBWT + LBWT)$$

$$Y = \text{normalize}(FWT - BWT)$$

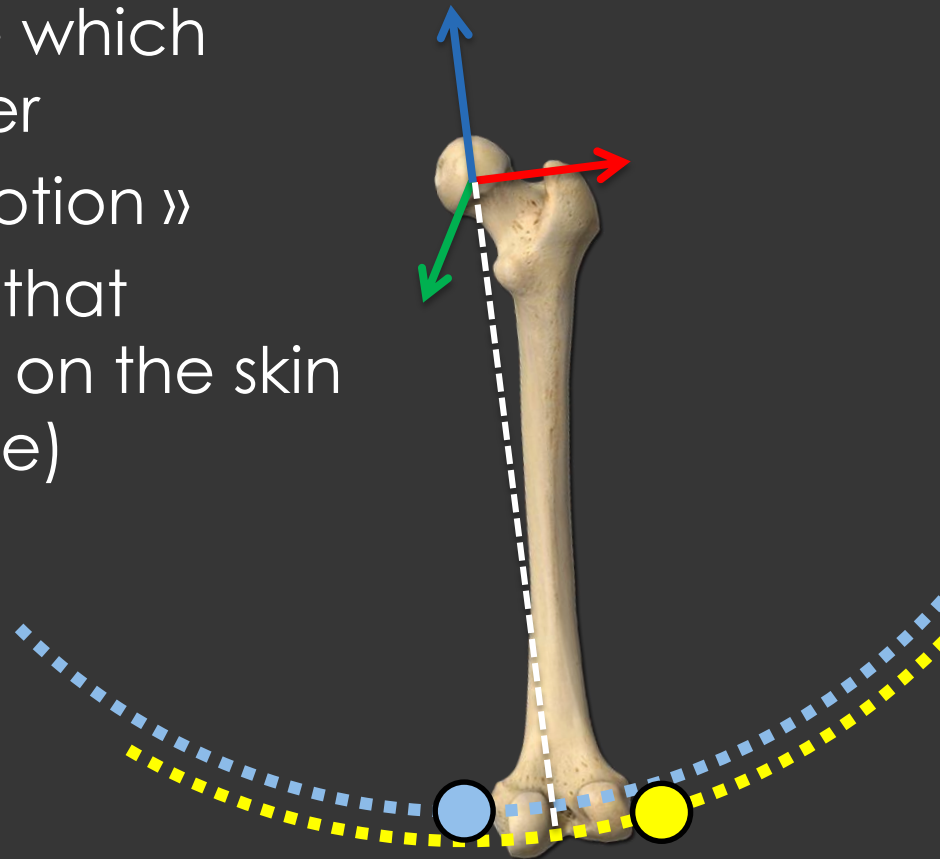
$$Z = \text{cross}(X, Y)$$

$$P_{\text{pelvis}} = 0.5 * (RFWT + RBWT + LFWT + LBWT)$$



# Joint Centers & Skeleton

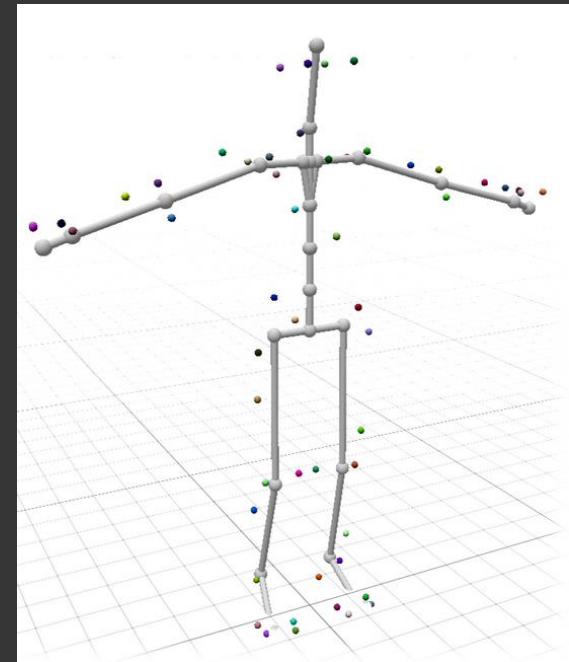
- Optimisation with assumption of articulated rigid bodies (constant length)
  - Markers lie on a sphere which center is the joint center
  - Based on « range of motion »
  - Influenced by the fact that markers are positioned on the skin (and can therefore slide)





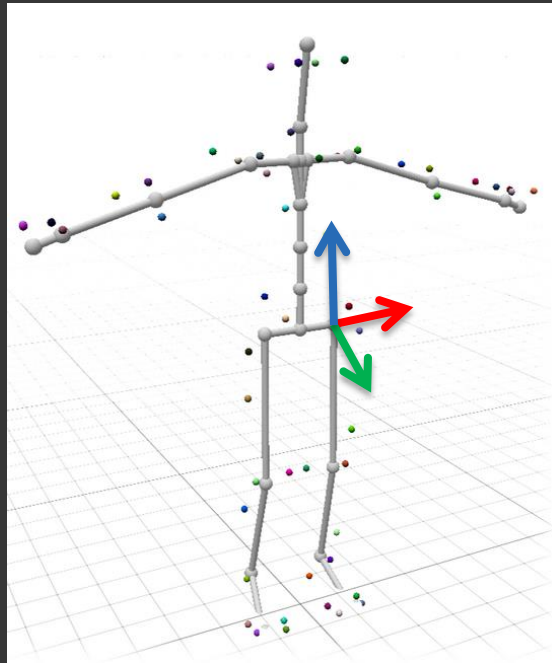
# Fitting a Skeleton

1. Learn/define a skeleton (morphology)
2. Fit skeleton in the data
  - 2 Main approaches
    - Complex optimisation: learning skeleton morphology and relations between segments and markers
      - Least square error optimisation
    - Or done using IK where joint angles are computed based on marker positions



# Animating character

- Can require mapping between motion and character hierarchy



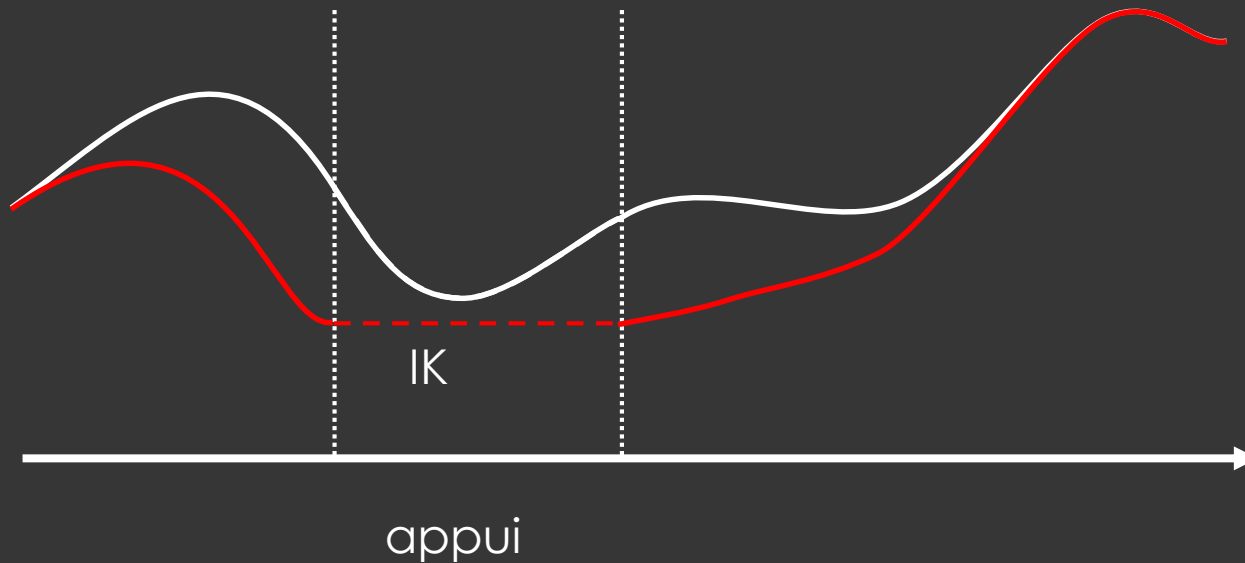
# Retargeting

- Problem if the character skeleton morphology does not match the motion's
  - Correction of the error = retargeting



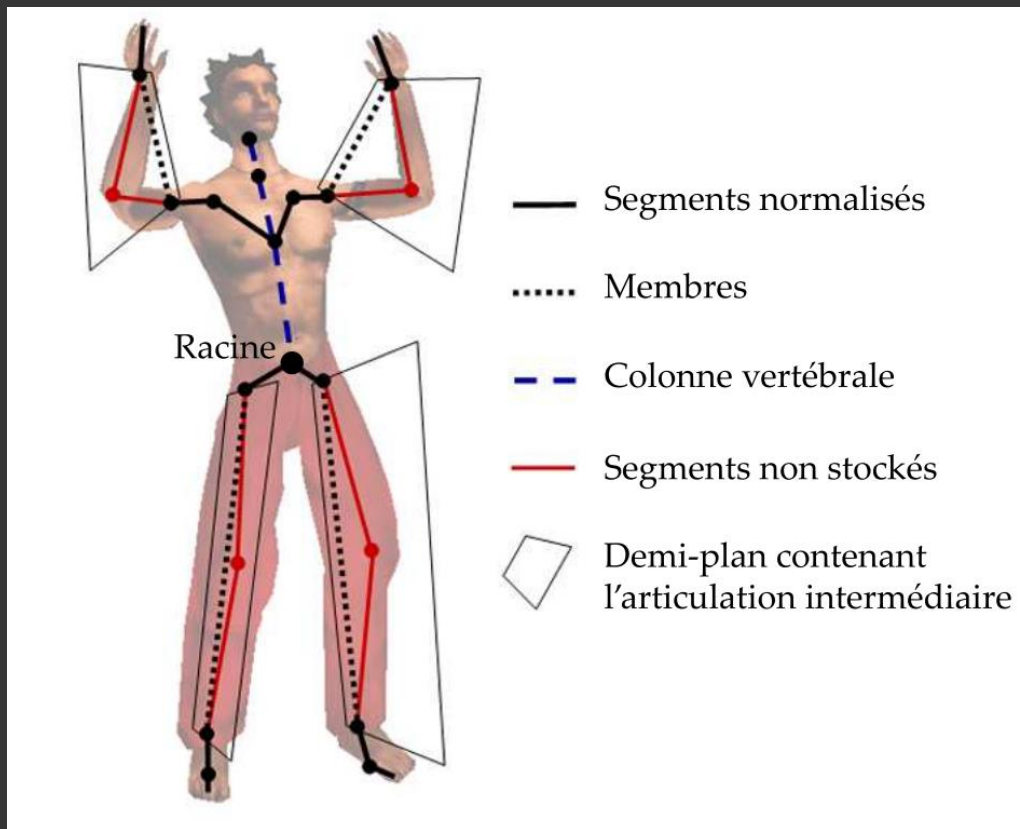
# Retargeting

- Possible solution: use Inverse Kinematics on ankle position

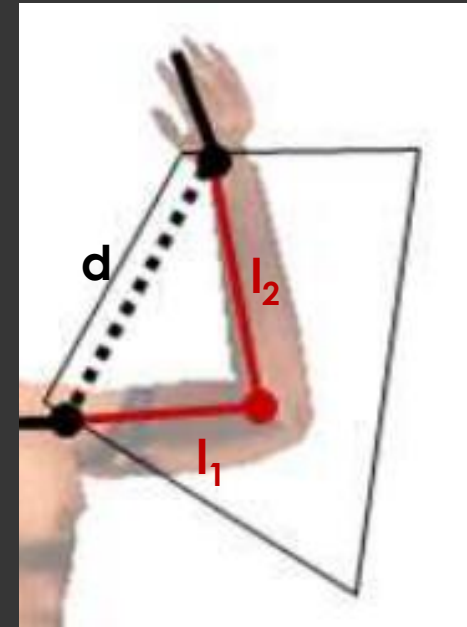


# Retargeting

- Or use representation independent of morphology

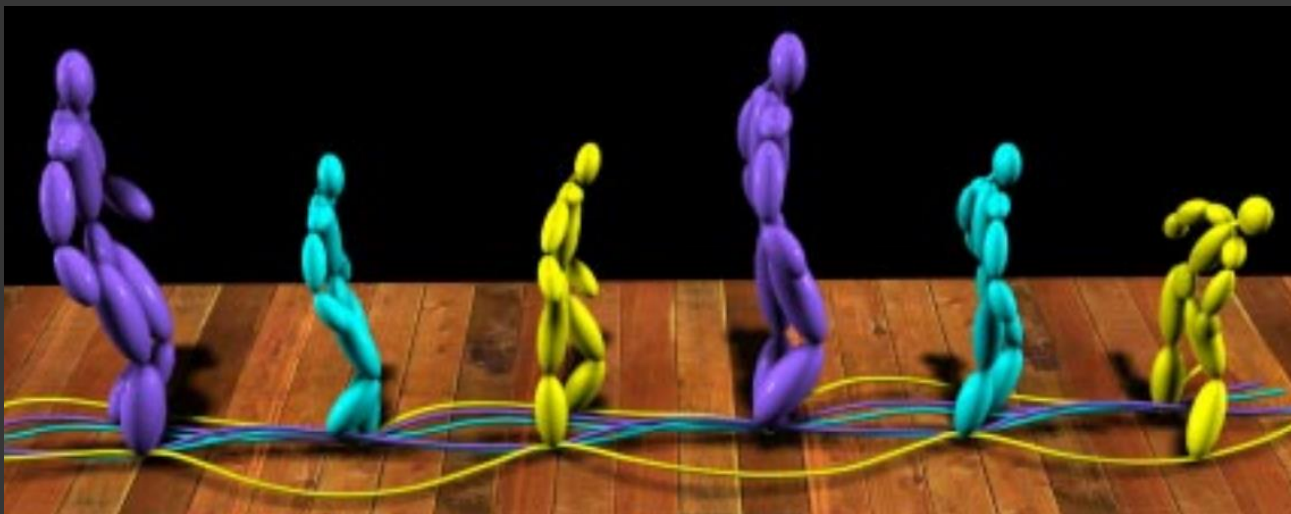
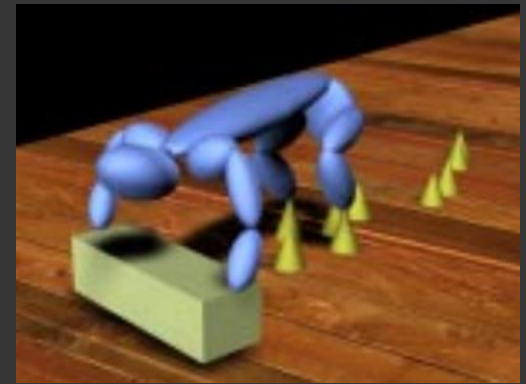
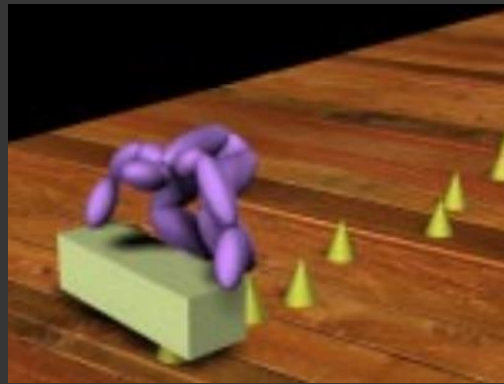
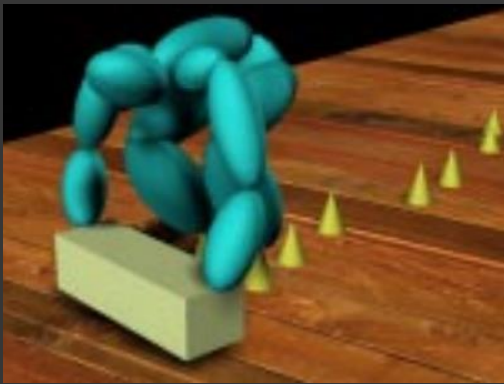


Facteur d'extension  $r$   
Longueur  $l_1$  et  $l_2$   
 $d = r * (l_1 + l_2)$



# Retargeting

- Or optimise a set of constraints



# Summary of Optical systems

- Advantages
  - Extremely accurate
  - Large number of markers can be used
  - Easy to change marker configurations
  - Performers not constrained by cables
  - Large area
  - High frequency of capture (up to 2000fps)
- Disadvantages
  - Hardware is expensive €100,000
  - Occlusions
  - Post-processing necessary

# New Motion Capture Gaming

- Wii uses a combination of built-in accelerometers and infrared detection to sense its position in 3D space when pointed at the LEDs within the Sensor Bar
- Kinect is a motion sensing input device by Microsoft for the Xbox 360
  - RGB camera, depth sensor and multi-array microphone running proprietary software





# Motion Capture in Games

- Game development is the largest market for motion capture
- Generally there are two main types of 3D character animation used in games
  - Real-time playback allows the game player to choose from pre-created moves, thus controlling the character's moves in real-time
  - Cinematics are the fully rendered 'movies' used for intros and 'cut-scenes'



# Motion Capture in Games

- Videogames' ability to tell stories has evolved rapidly over the last 20 years
  - Rolling text is gone, replaced with voice acting and near-photorealistic graphics
- Look and sound real, but don't always feel real
  - Subtle body language missing
- Using motion capture, and in particular performance capture (dialogue is recorded at the same time), games can draw the players into the story more completely

# Motion Capture in Games

- Meaning and emotion are conveyed not only through dialogue, but through facial and body movements
  - A curved lip suggests passion, a furrowed brow indicates fear, a raised arm, anger.



Enslaved: Odyssey to the West

# Motion Capture in Games



Telling stories by having these games display **complex emotions** and **ethical** and moral choices that lead to significant consequences

Beyond Two  
Souls

# Planning & Directing Mocap

- Is motion capture necessary for project?
  - Do you want realistic motion?
  - Is character human shaped?
  - Motions beyond physical boundaries?
  - Will shot fit within capture volume?
  - Blend shots after capture?
- Goal
  - To end up with hundreds of individual moves that connect perfectly to one another

# Controlling motion capture

- Skeleton-based motion capture
  - Apply directly joint angles
    - If actor and character have different sizes, visual artefacts can appear (e.g., footsliding)  
→ retargeting
- Some software use markers directly with retargeting to drive characters (e.g., MotionBuilder)
  - Animation usually less natural
- How to control motions  
→ manipulations/editing in next lecture ;)

