### MRC 2020 Tooling and Infrastructure

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Eindhoven University of Technology Department of Mechanical Engineering

April 22, 2020

Final Competition: Bring items to cabinets in a dynamic hospital environment, of which a map is provided



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  - visit an unknown number of cabinets as fast as possible



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  - The Laser Range Finder to detect walls and doors
  - The encoder data from the wheels
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- You can use:
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- Important Dates:
  - Final Presentations: June 3
  - Competition Day: June 10



#### Intermediate Assignment

Escape Room Competition: let a robot escape the room through the door.



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### Intermediate Assignment

Escape Room Competition: let a robot escape the room through the door.

- Goal:
  - try to be as fast as possible
- You can use:
  - The Laser Range Finder to detect walls
  - The encoder data from the wheels
  - The control effort signal to notice touches-
- Competition day: May 13



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# Simple, right?

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## Simple, right?

Don't worry, we supply you with some tools to get you started!

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- Unfortunatly we cannot use it!
- Telepresence Robot from Aldebaran

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Robot type: Jazz



- Unfortunatly we cannot use it!
- Telepresence Robot from Aldebaran
  - Robot type: Jazz
- Sensors:
  - Laser Range Finder (LRF)
  - Wheel encoders (odometry)

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▶ 170° wide-angle camera



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  - 170° wide-angle camera
- Actuators:
  - Holonomic base (omni-wheels)

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Pan-tilt unit for head



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- Pan-tilt unit for head
- ► Computer:
  - Intel I7
  - Running Ubuntu 16.04

Open-source meta-operating system for robots

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Open-source meta-operating system for robots

Won't be using it!



Open-source meta-operating system for robots

#### Won't be using it!

- Instead, we will provide our own 'software layer'
  - It is simpler to understand, and 'cleaner' to use

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However, you are still allowed to use ROS!

#### Ubuntu

Development of PICO's software will be done in Ubuntu.

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- Linux-based operating system
- Use version 16.04 (not 14.10, 15, 17 or 18!)
- 32- and 64-bit (64-bit recommended)

#### Ubuntu

Development of PICO's software will be done in Ubuntu.

- Linux-based operating system
- Use version 16.04 (not 14.10, 15, 17 or 18!)
- 32- and 64-bit (64-bit recommended)
- Easy dual boot installation with *e.g.*, Windows
- Download: see tutorial!
  - Any problems?  $\rightarrow$  Check the wiki.
  - No info?  $\rightarrow$  Send us an email.



#### C++

- ► We will use C++ as programming language
- ► C++ is object-oriented C
  - ▶ "C with Classes"
  - Encapsulate data and functionality within objects

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#### C++

- ► We will use C++ as programming language
- ► C++ is object-oriented C
  - "C with Classes"
  - Encapsulate data and functionality within objects
- It is a powerful but complex programming language.
- However, we provide you the MRC framework to get you started

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### Creating code: Qt Creator

- Integrated Development Environment
  - Advanced code editor
- Many advantages over 'simple editors':
  - Syntax highlighting
  - Code completion
  - Visual compiler feedback
  - Static code checking
  - Refactoring tools
  - Parenthesis matching
  - ▶ ...
- Or your own favorite editor that supports CMake..



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#### Git Version Control

Version Control System:

 'Manages files and directories, and the changes made to them, over time'

Used to store and maintain your code on the server

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- Used to store and maintain your code on the server
  - (Like Dropbox)
- Maintains version history
- Is distributed
  - You always have the full history on your pc
  - You can always go back to a version, show differences, even when off-line

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More info on the Wiki

The simulator will be used to replace the real robot.

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- ► PICO Simulator:
  - Simulates:
    - Sensors (Laser, odometry)
    - Actuators (Base)
    - Environment (walls, objects)

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- The simulator will be used to replace the real robot.
- PICO Simulator:
  - Simulates:
    - Sensors (Laser, odometry)
    - Actuators (Base)
    - Environment (walls, objects)
- Can easily create test environments using height maps
- Integrates well with our provided software
  - If your software runs in the simulator, it runs on the robot





- Full Example: from requirements, through Task-Skill-Motion to Software Executable.
- (far) from perfect!
- Focus on decoupling parts of functionality, explicitly in the code.

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- Full Example: from requirements, through Task-Skill-Motion to Software Executable.
- (far) from perfect!
- Focus on decoupling parts of functionality, explicitly in the code.

Tutorial lectures will introduce robotics concepts in more detail!

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### Wiki

#### MRC Wiki:

- http://cstwiki.wtb.tue.nl /index.php?title=Mobile\_Robot\_Control
- Info on practical assignment, installation, getting started

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Log-in: student account

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- Group pages on EMC Wiki:
  - Each group gets its own page
  - Update at least weekly

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- Log-in: student account
- Group pages on EMC Wiki:
  - Each group gets its own page
  - Update at least weekly
- Overall use:
  - Everyone can edit
  - If you see a mistake: correct it

#### Working together

Because working together face-to-face is not possible:

- ► We recommend using Microsoft Teams within your group
- Meet with your tutor once every week using video call
- Use canvas for asking general MRC questions to tutors and fellow students
- Use canvas for FAQ about problems (e.g. dual boot issues)

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- If you had a problem and know how to fix it: add it
- Use canvas to discuss the video lectures

### Recap

- Robot: Simulator only
- OS: Ubuntu 16.04
- Programming language: C++
- Code editor: Qt Creator
- Version control: git
- Documentation: Wiki
- meetings: Microsoft Teams
- General questions and discussion: Canvas

#### That should get you started!

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#### Groups

#### Each group will be supervised by a tutor:

- 1. Wouter Houtman
- 2. Bob Hendrikx
- 3. Hao Liang Chen
- 4. Marzieh Dolatabadi Farahani
- 5. Jordy Senden
- 6. Wouter Kuijpers

- 7. Elena Torta
- 8. Wouter Houtman
- 9. Bob Hendrikx
- **10.** Hao Liang Chen
- 11. Marzieh Dolatabadi Farahani

- 12. Jordy Senden
- It is your responsibility to get in touch with your tutor (see Wiki)

What should I do now?

Make your own groups of max. 6 people

 By adding your name and contact info to one of the groups on the wiki

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Send an email to your group members to get in touch

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- Send an email to your group members to get in touch
- Send an email to your tutor as a group:
  - to schedule the first meeting,
  - with one username for access to your Git, (tutorial)

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- By adding your name and contact info to one of the groups on the wiki
- Send an email to your group members to get in touch
- Send an email to your tutor as a group:
  - to schedule the first meeting,
  - with one username for access to your Git, (tutorial)
- Check the Wiki & Finish the Tutorials:
  - http://cstwiki.wtb.tue.nl/index.php?title=Mobile\_ Robot\_Control