





NOAA Unmanned Aircraft Systems Engineering & Resources/Capabilities

John "JC" Coffey River Forecasting Center Workshop









Purpose and Outline



- Systems Engineering
- Requirements Analysis
- Provide Overview of Unmanned Aircraft Systems available to NOAA Researchers
 - Global Hawk (NASA)
 - Ikhana (NASA)
 - Manta
 - Puma AE
 - md4-1000
 - APQ-16
 - SkyWisp
 - Emily



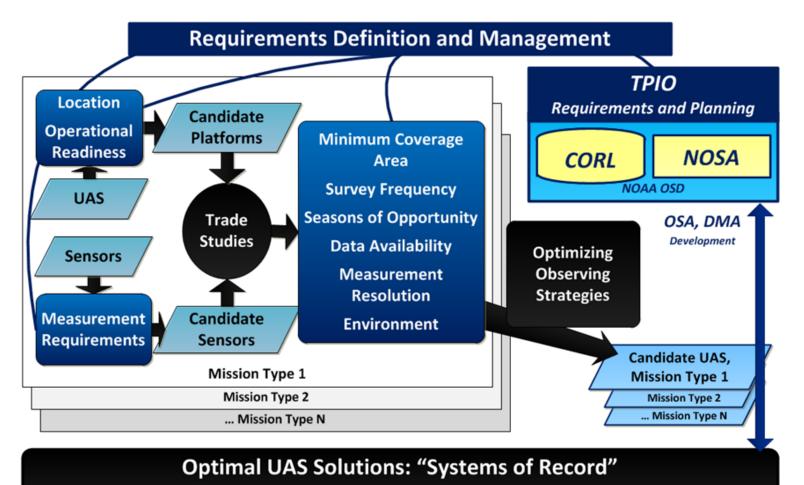


Systems Engineering Process

Technology, Planning, Integration for Observation



Consolidated Observation Requirements List & NOAA Observing System Architecture

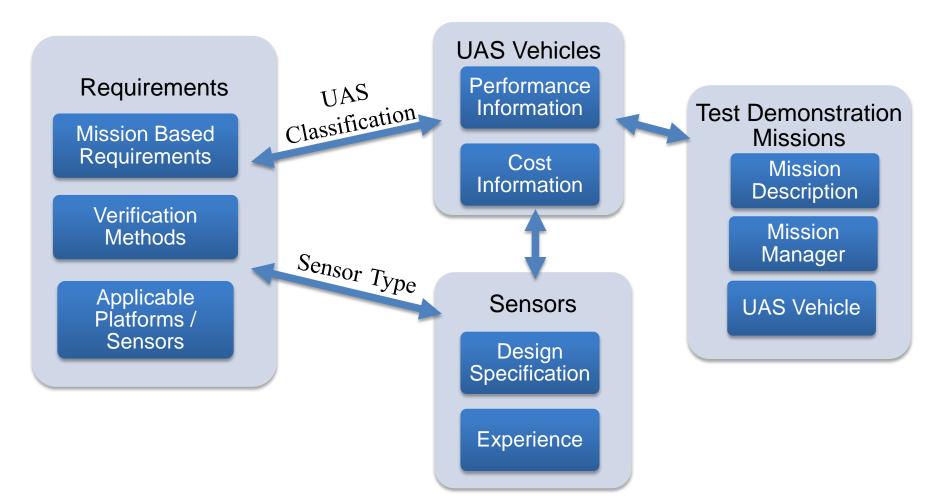


System Specifications, Concepts of Operation, Requirements Traceability



UAS System Engineering Database Overview







RFC Identified Requirements



- Ice flows need to know size, movement, etc. in near realtime
- Ice jams need to know height in near realtime
- Soil moisture before first freeze
- Rapid response for Lidar after a catastrophic flooding event to track changes in river channel structure and morphology
- Vegetation and soil mapping to insure accurate river model parameter settings especially in response to drought
- Rapid response for photos to document extent of inundation to verify flood inundation maps and enable production of flood maps for more locations
- Thermal imagery and other sensor arrays to attempt to measure depth of inundation to verify flood inundation maps and enable production of flood maps for more locations



Global Hawk



• NOAA has partnered with NASA for joint use of the NASA Global Hawk (GH) UAS.

• The GH is built by Northrop Grumman. The NASA GH are initial production (Block 10) aircraft modified for high altitude long endurance (HALE) research missions.

• Currently, NASA has two operational GH with plans to stand up a third aircraft.

•The NASA GH capabilities are summarized in the Table below:

Parameter	Value
Payload	1,500 lb
Endurance	31 hours
Cruise Speed	335 knots
Range	11,000 nm
Ceiling	65,000 ft
Launch/Recovery	Conventional







Ikhana



• The NOAA /NASA partnership includes joint use of the NASA Ikhana UAS.

• The Ikhana was built by General Atomics and is an early version of the military Predator B. It has been modified for medium altitude long endurance (MALE) research missions.

• Currently, NASA has one operational aircraft.

•The NASA Ikhana capabilities are summarized in the Table below:

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Parameter	Value
Payload	2,000 lb
Endurance	24 hours
Cruise Speed	200 knots
Range	4800 nm
Ceiling	40,000 ft
Launch/Recovery	Conventional







- The NOAA currently owns one Manta UAS that includes two aircraft.
- The Manta is built by BAE Systems.
- Currently has observation and carbon sampling sensors integrated.
- •The NOAA Manta capabilities are summarized in the Table below:



Parameter	Value
Payload	15 lb
Endurance	8 hours
Cruise Speed	40 knots
Range	352 nm
Ceiling	16,000 ft
Launch/Recovery	Rail/Conventional



Puma AE



•The NOAA is currently in the process of procuring two Puma AE UAS through the Army PM UAS. Each UAS will include 3 aircraft and 2 GCS.

- The Puma AE is built by AeroVironment.
- •The Puma AE is waterproof and can land in water making it compatible with ship launch and recovery.
- Gimbaled payload, 360 degree continuous pan, +10 to -90 degrees tilt, stabilized EO, IR camera, and IR Illuminator all in one modular payload.
- •The Puma AE capabilities are summarized in the Table below:

Parameter	Value
Payload	2 lb
Endurance	2 hours
Cruise Speed	20-45 knots
LOS Range	8 nm
Ceiling	500 ft
Launch/Recovery	Hand/Deep Stall







md4-1000



- NOAA currently owns one md4-1000 UAS that consists of one aircraft and one GCS.
- The md4-1000 is built by Microdrones GmbH in Germany.
- •The aircraft is a VTOL quadracopter.

•The NOAA md4-1000 capabilities are summarized in the Table below:

Parameter	Value
Payload	1.7 lb
Endurance	1.16 hours
Cruise Speed	29 knots
LOS Range	0.54 nm
Ceiling	3,280 ft
Launch/Recovery	Vertical/Vertical









• NOAA currently owns one APQ-16 UAS that includes one aircraft and one GCS.

- The APQ-16 is built by Aerial Imaging Systems.
- The NOAA APQ-16 capabilities are summarized in the Table below:

Parameter	Value
Payload	1.1 lb
Endurance	0.5 hours
Cruise Speed	25 knots
LOS Range	6.3 nm
Ceiling	4,000 ft
Launch/Recovery	Vertical/Vertical



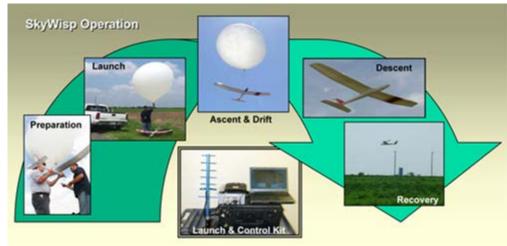






- NOAA currently owns this system.
- The SkyWisp System was developed and built by Southwest Research Institute (SwRI).
- •The NOAA SkyWisp capabilities are summarized as the listed below:
 - Operation to 100,000-feet altitude
 Very low-cost balloon-assisted glider
 Autonomous operation and recovery
 1- or 2-person launch and forget
 Continuous option for positive human control
 Quick reaction capability
 Low observables







E.M.I.L.Y



• NOAA currently owns TBD Emergency Integrated Lifesaving Lanyard (E.M.I.L.Y) USVs.

• The Emily was developed and built by Hydronalix.

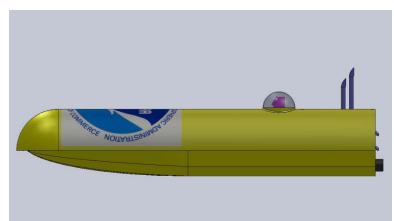
Technology sub-systems will be demonstrated through a series of 3 missions:

1. Marine sanctuaries testing - Channel Islands

2. Coral mapping - Florida Keys

3. Tropical cyclone testing -Florida keys region

Gas engine will increase endurance to 5 days at 2-3 knots.
The NOAA Emily capabilities are summarized in the Table below:



W:	Parameter for 65" hull	Value	
	Tethered Buoy Sleep Mode	100+ hours	
Î	Battery Storage	240 Whrs to 1920Whrs (1 to 8 packs)	
	5mph patrol	600 minutes	
	Speed	13 mph with 46 lbs payload (max of 30 mph)	
	Duration	30 mph - 20 minutes	
		13 mph - 39 minutes with 46 lbs	
		1-2 mph - approximately 20 hours	
	Dimensions	65" length, 15" width, 8" height	
NOAA UAS Program	Payload Capacity	Up to 80 lbs	
	Buoyancy	80.0 L (4882 inch ³) or 170 lbs	1



Turning Vision Into Reality





Buckeye unmanned airborne Lidar System



Resolution UAS NOAA SBIR for debris tagging



Global Hawk dropsonde release over hurricanes & the Arctic



Scan Eagle Operational Testing from NOAA's Oscar Dyson

NOAA UAS Program





- Get a better understanding of your observation requirements and areas of interest.
- Get a better understanding of your current capabilities and unmanned missions flown.
- Get a better understanding of current unmanned platforms, sensors and operators including those used by NOAA and other government agencies.
- Construct the foundation for an unmanned systems strategy for the RFC.



White Paper Outline



- RFC Requirements
- Sample Applicable UAS Assets
 - Operators
 - Platforms
 - Sensors
- Past Missions
 - Goals
 - Process
 - Results
- Potential Missions
 - Requirements, including parameters like coverage rate, data availability, environment, location, measurement, measurement resolution, minimum coverage area, operational readiness, season of opportunity, and survey frequency.



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