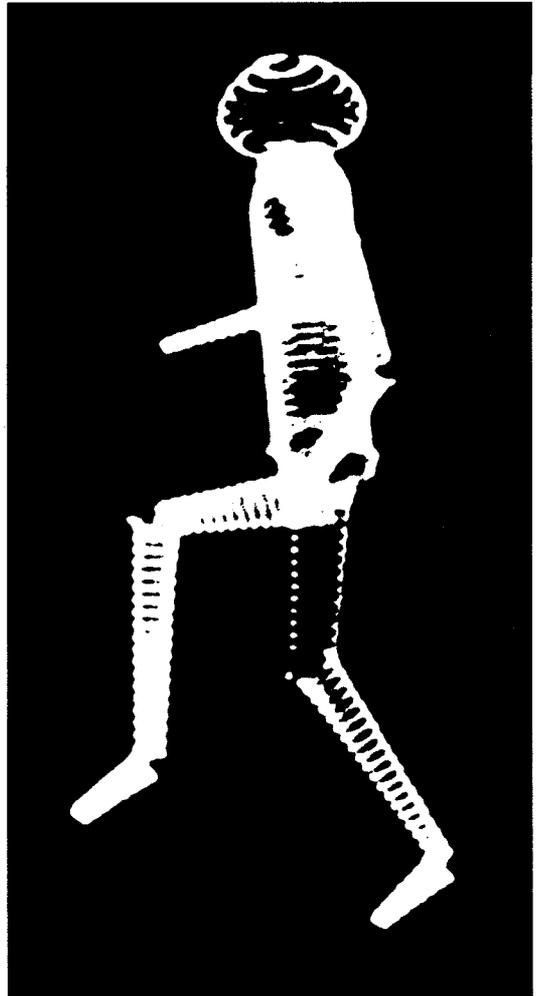


NOTES FOR AN EARLY ANIMATION DEVICE

Lee Harrison

The following paper is reprinted in facsimile form as the most primary and authentic source of Lee Harrison's original concept for electronic animation. These notes eventually materialized as the ANIMAC animation system. —D.D.



Withstand by Indes. Co. 12/29/61

THE CLOCK OR MASTER OSCILLATOR, IS A ~~VERY~~ STABLE, VARIABLE-FREQUENCY WAVEFORM GENERATOR. ~~THE OUTPUT OF THE CLOCK~~
 THERE ARE TWO ~~OR~~ SIGNAL OUTPUTS OF THE CLOCK OR MASTER OSCILLATOR. ONE IS A SQUARE WAVE ~~WAVE~~, ~~THE OTHER~~, A SINE WAVE. ~~THE OUTPUTS ARE AT THE SAME FREQUENCY.~~
 THE FUNCTION OF THE CLOCK IS TO FURNISH THE "DRIVING-SIGNALS" TO THE DEVICE. ~~IT~~ IS ALSO A MEANS BY WHICH THE ^{INNER} WORKINGS OF THE DEVICE ARE "TIME-SYNCHRONIZED."
 WE REFER TO THE OUTPUT OF THE CLOCK AS "HIGH FREQUENCY," ~~BECAUSE~~ BECAUSE WE COUNT DOWN (BY MEANS OF A COUNTER TO BE DESCRIBED LATER) TO THE "FRAME FREQUENCY", ~~OR~~ ~~IS~~ ~~THUS~~ ESTABLISHING A FRAME RATE. FRAME RATE IS ^{THE} ~~THE~~ RATE AT WHICH WE DRAW ONE COMPLETE FIGURE ^{ON} THE DISPLAY SCOPE.
 BECAUSE THE COUNTER PERFORMS A FIXED-RATIO-COUNTDOWN, THE LOW FREQUENCY IS ALWAYS A LOWER MULTIPLE OF THE HIGH FREQUENCY. ~~THUS, BY VARYING THE HIGH FREQUENCY, WE AUTOMATICALLY VARY THE LOW FREQUENCY OR FRAME RATE.~~
 DURING THIS DEVELOPMENTAL PERIOD, WE ^{WE} OPERATING AT FRAME RATES BETWEEN 24 AND 30 CYCLES PER SECOND (CPS). 30 cps IS DESIRABLE AT THIS TIME BECAUSE
 a.) THE LIGHTING IN OUR WORKSHOP IS SUCH THAT AT A LOWER FRAME RATE, WE SEE A BOTHERSOME FLICKER, and
 b.) IT IS VERY EASY TO SYNCHRONIZE THE FREQUENCIES TO "60-CYCLE LINE FREQUENCIES" (JUST TWICE THE FRAME RATE) ^{WITH A HAND ADJUSTMENT} AND THEREBY ELIMINATE WHAT IS KNOWN AS "HUM" OR LINE NOISE, WHICH IF NOT SYNCHRONIZED CAUSES A SLOW WOBBLE OF THE PICTURE.
 IN THE FUTURE, WE WILL INSTALL A FEEDBACK TIMING CONTROL IN THE COUNTER CIRCUIT WHICH WILL AUTOMATICALLY SYNCHRONIZE ALL FREQUENCIES TO THE LINE (60CPS) AND

AND HALF CENTURY OF THE
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 TODAY IS DEC. 29, 1961
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Leuth...

THIS ELIMINATE THE NECESSITY OF HAND ADJUSTMENTS AND ALSO ASSURE AN EXACT 24 CPS FRAME RATE.



DEC 29 1961

THE SQUARE WAVE OUTPUT IS FED DIRECTLY INTO THE COUNTER. IT IS ALSO ^{FED INTO AND IS} THE DRIVING SIGNAL FOR THE HORIZONTAL DEFLECTION GENERATOR OF THE BKIN SCANNER (TO BE DESCRIBED LATER.)

THE SINE WAVE OUTPUT IS FED INTO TWO OF THE ^{TO BE DESCRIBED LATER} SAMPLERS (SAMPLER GATES), ~~AND~~ ALSO INTO A 90 DEGREE PHASE SHIFTER WHOSE OUTPUT NOW BECOMES A COSINE WAVE (IN RELATION TO THE ORIGINAL SINE WAVE) ~~AND~~ WHICH IS SUBSEQUENTLY FED INTO THE OTHER SET OF SAMPLERS. ALSO BOTH SINE AND COSINE WAVES ARE FED INTO MODULATORS (TO BE DESCRIBED LATER)

THE FUNCTION OF THE CLOCK MAY BE TAKEN OVER BY THE TAPE RECORDER, WHERE THE CLOCK SIGNALS ARE RECORDED ON ONE OF THE CHANNELS, AND USED AS DRIVING SIGNALS OF THE DEVICE, THIS SYNCHRONIZING ALL RECORDED SIGNALS WITH THE "TAPE CLOCK".

COUNTER & TIMING CONTROL

Lee Harrison
W18816-2300

THE COUNTER IS A CHAIN OF BISTABLE MULTIVIBRATORS. THE INPUT TO THE FIRST BSMV IN THE CHAIN IS THE HIGH FREQUENCY SQUARE WAVE FROM THE CLOCK. THE OUTPUT OF THE FIRST BSMV IS A SQUARE WAVE WHICH IS EXACTLY $\frac{1}{2}$ THE FREQUENCY OF THE INPUT. THUS EACH BSMV IN THE CHAIN HALVES ITS INPUT FREQUENCY.

AT THE PRESENT TIME WE HAVE 9 BSMV'S IN THE COUNTER CHAIN. THIS GIVES A COUNTDOWN RATIO OF 512:1. THUS FOR A FRAME RATE OF 24 FRAMES/SEC, THE HIGH FREQUENCY MUST BE 12,288 CPS

THERE IS NOTHING MAGIC ABOUT THIS SELECTED RATIO OF 512 TO 1. THE CHOICE OF IT AT THIS TIME WAS GOVERNED BY THE EASE WITH WHICH WE ARE ABLE TO USE THE HIGH FREQUENCY IN THE FUNCTION (SINE-COSINE) GENERATOR NETWORK. IF THE FREQUENCIES USED IN THAT NETWORK GET TOO HIGH, THE GENERATOR DOES NOT PERFORM AS WELL AS WE'D LIKE IT TO. WE HAVE NOT HAD TIME TO REDESIGN THE NETWORK. HOWEVER, IT WORKS WELL UP TO 16 OR 17 KC. EASILY ALLOWING FOR A 30 FPS FRAME RATE.

OF COURSE, THE HIGHER FREQUENCY WE USE, THE GREATER "BONE & SKIN" RESOLUTION WE MAY HAVE (THIS WILL BE EXPLAINED LATER.)

THE OUTPUT OF THE FIRST BSMV, BESIDES BEING FED INTO THE 2ND BSMV, IS ALSO FED INTO THE DELAY MULTIVIBRATORS IN THE AFORE-MENTIONED SINE-COSINE FUNCTION GENERATOR NETWORK AND ACTS AS A DRIVING SIGNAL FOR THOSE DELAY MV'S. IN OTHER WORDS, IT CAUSES THE DELAY MV'S TO ~~BE~~ ^{ALLOW} A SAMPLING OF THE SINE AND COSINE WAVES IN THE SAMPLERS AT $\frac{1}{2}$ THE FREQUENCY OF THE SINE & COSINE WAVES IN THE SAMPLERS. ~~AT THESE ARE 2 CYCLES~~ TO SAMPLE FROM,

1) COUNTER WILL ARRIVE AT 60 CPS (REASONABLY AS THE LINE FREQUENCY IS 60 CPS) AT THE END OF THE COUNTER. FOR USE WITH A TUBE OSCILLATOR THE OSCILLATOR WOULD BE DRIVEN BY A HIGHER SPEED OSCILLATOR, WHICH WOULD ACCURATELY REGULATE THE TIME SPEED AND PLUS THE FREQUENCIES COMING OFF THE FRAME.

THE SIGNIFICANCE OF THIS IS THAT WE CAN GET MORE THAN A 360 ROTATION, ~~IN~~ A BONE. (TO BE DESCRIBED MORE FULLY)

THE TIMING CONTROL IS A FEEDBACK NETWORK WHICH SYNCHRONIZES ^{AUTO-MATICALLY} AT THE ^{ALL OF} ^{DRIVING} FREQUENCIES (A HIGH & LOW) TO THE 60 CPS LINE-FREQUENCY, THUS ~~ASSURING~~ ASSURING AN EXACT 24 FPS FRAME RATE.

[HUM] THE ELECTRONIC EQUIPMENT OPERATES BY POWER RECEIVED FROM A 60 CYCLE SUPPLY LINE. THIS POWER AT 60 CPS IS PRESENT IN WIRES AND CABLES NEAR & THRU THE EQUIPMENT, AND HAS A TENDENCY TO RADIATE A CERTAIN AMOUNT OF THIS POWER TO ADJACENT PARTS, THE RESULT IS THAT THERE IS ALWAYS PRESENT A SLIGHT VOLTAGE RIPPLE ON THE LINES, IN THE AMPLIFIERS, AND EVEN IN THE D.C. REGULATED-VOLTAGE SUPPLIES. THIS MAY BE ELIMINATED BY ~~EXCESSIVE~~ SHIELDING AND ~~SUPPLY~~ ^{CONTROLLED} ^{AN EVEN} ^{MEASURE} OF THE SUPPLIES, OR IT MAY BE COMPENSATED FOR BY SYNCHRONIZING ALL OF THE FREQUENCIES TO THIS HUM. FOR EXAMPLE, LET US SUPPOSE WE ARE OPERATING AT 23.999 FRAMES PER SECOND, AND THE LINE RIPPLE IS AT 60 CPS. THE PICTURE WILL TEND TO SLOWLY UNDULATE BECAUSE OF A BEAT SET UP BY THE TWO, NON-MULTIPLE FREQUENCIES. HOWEVER, BY MAKING THE FRAME RATE EXACTLY 24 FPS, WE WILL DRAW A COMPLETE FRAME FOR EVERY 24 CYCLES OF HUM.

THERE ARE 2 INPUTS TO THE TIMING CONTROL: ONE IS THE 24 CPS FROM THE COUNTER, THE OTHER IS 60 CPS FROM THE LINE. THE 24 CPS FRAME RATE IS FED INTO A BSMV WHOSE OUTPUT IS THEREFORE 12 CPS. THE LINE FREQUENCY (60 CPS) IS FED INTO A 5:1 COUNTER (BINARY FEEDBACK TYPE) AND ITS OUTPUT IS 12 CPS. THESE 2 FREQUENCIES ARE THEN FED INTO A PHASE-COMPARATOR. THE OUTPUT OF THE PHASE-COMPARATOR (A D.C. VOLTAGE) IS FED INTO A D.C.-CONTROLLED OSCILLATOR WHOSE MEAN OUTPUT FREQUENCY WILL BE THE HIGH FREQUENCY WHICH WHEN FED INTO THE FRONT END OF THE

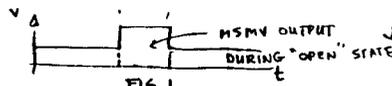
Witnessed by
LHG
12/12/61

ELECTRONIC GATE-COMMUTATOR OR MONOSTABLE MULTIVIBRATOR CHAIN (MSMV)

THE CHAIN OF ~~NECESSARY~~ MONOSTABLE MULTIVIBRATORS (MSMV) IS AN ELECTRONIC COMMUTATOR WHICH OPENS AND CLOSES A SERIES OF "BONE" GATES IN A SEQUENTIAL MANNER. IN OTHER WORDS, THE MSMV'S FURNISH THE DRIVING (OPENING & CLOSING) SIGNALS TO THE GATES.

THE INPUT TO THE FIRST MSMV IN THE CHAIN IS A ^{FRAME-RATE} PULSE (SAY 24 CPS) WHICH COMES FROM THE COUNTER. WHEN THE PULSE ARRIVES, IT CAUSES THE MSMV TO FLIP INTO ~~ITS~~ OTHER (UNSTABLE) STATE, FOR A LENGTH OF TIME AS DETERMINED BY ITS INTEGRAL RC NETWORK. BY VARYING R, THE LENGTH OF TIME DURING WHICH THE MSMV IS IN ITS UNSTABLE STATE MAY BE VARIED. ~~WHEN THIS TIME HAS LAPSED,~~ DURING THIS "OPEN" TIME, A CHANGE IN VOLTAGE OCCURS ON ONE OF ITS OUTPUTS. THIS VOLTAGE IS USED TO OPEN A NUMBER OF GATES CONNECTED TO IT. WHEN THE "OPEN" TIME HAS LAPSED, THE MSMV AUTOMATICALLY FLIPS BACK INTO ITS ORIGINAL STATE (STABLE) AND CHANGES BACK THE OUTPUT VOLTAGE DRIVING THE GATES, THUS CLOSING THEM. DURING THE FLIP-BACK, A PULSE SIMILAR TO THE ONE THAT CAUSED THE ORIGINAL FLIP IS GENERATED AT ANOTHER OUTPUT POINT, AND THENCE IS SENT TO THE NEXT MSMV IN THE CHAIN WHERE A SIMILAR OPERATION OCCURS, THUS OPENING THE NEXT GROUP OF ASSOCIATED GATES FOR A TIME DESCRIBED BY THE R ASSOCIATED WITH THAT 2ND MSMV. THIS COMMUTATING ACTION CONTINUES UNTIL ALL THE MSMV'S IN THE CHAIN HAVE GONE THROUGH THEIR INDIVIDUAL CYCLES.

THE "DRIVING OUTPUT" OF THE MSMV'S (SHOWN IN FIG. 1.) IS USE TO PERFORM A NUMBER OF TASKS. FOR EXAMPLE, THIS OUTPUT MAY BE USED TO CLOSE THE ELECTRONIC SWITCHES ACROSS THE



INTEGRATING CAPACITORS, THUS CAUSING THE DISPLAY BEAM TO "FLY BACK" TO ITS STARTING POINT. ~~THESE SIGNALS ARE USED THEREFORE AS INPUTS TO THE FLYBACK CIRCUIT,~~ ^{AS INPUTS TO THE FLYBACK CIRCUIT,} ~~AS BE DESCRIBED LATER IN MORE DETAIL.~~ ANOTHER USE OF THE MSMV OUTPUT IS TO DIM OR BLANK-OUT THE DISPLAY BEAM. BY APPLYING THE MSMV OUTPUT TO THE GRID OF THE DISPLAY CRT, THE BEAM IS "TURNED -OFF" DURING THE "OPEN" TIME OF THE MSMV SO ENGAGED. IN THIS MANNER, FLYBACK RETRACES, AND CERTAIN BONE-PLACING RETRACES - (AS IN THE ARMS, WHERE THE BEAM MUST MOVE FROM THE STARTING POINT, UP TO THE SHOULDER AND THENCE PROCEED TO DRAW THE ARM, AND DURING THAT "PLACEMENT" BONE DRAWING, THE BEAM IS BLANKED OUT) MAY BE BLANKED OUT AS ~~BEFORE~~.

AS MENTIONED BEFORE, THE LENGTH OF TIME THAT AN MSMV REMAINS IN ITS OPEN POSITION IS DETERMINED BY R OF THE INTEGRAL RC NETWORK. THUS BY VARYING ^{EACH} OF THE RESISTANCES ASSOCIATED WITH EACH MSMV-RC-NETWORK, AN OPERATOR IS ABLE TO "SET-UP" A FIGURE OR CHARACTER TO HAVE THE DESIRE "BONE" LENGTHS, AND OVERALL STRUCTURE. HE ALSO, IN THIS SETUP PROCEDURE, DETERMINES THE SEQUENCE IN WHICH THE PARTICULAR BONES WILL BE DRAWN. IN DETERMINING THIS SEQUENCE HE MAKES THE NECESSARY CONNECTIONS, ~~THE FLYBACK CIRCUIT,~~ ^{AND} BLANKING CIRCUIT. IN ADDITION TO DETERMINING AND SETTING UP THE DESIRED BONE LENGTHS.

THE MSMV CHAIN IS A SWITCHING, COMMUTATING NETWORK WHICH REGULATES THE OPENING AND CLOSING OF THE BONE GATES, ~~THE~~ THE VARIOUS TASKS WHICH IT PERFORMS COULD BE DONE IN OTHER WAYS, SUCH AS (a) MECHANICAL SYSTEMS (b) BINARY COUNTER SYSTEMS WITH AND/OR DIODE NETWORKS (c) OTHER ELECTRONIC ARRANGEMENTS (d) ~~AND~~ MECHANICAL SYSTEMS.

BONE GATES.

ASSOCIATED WITH EACH BONE, AND BEING DRIVEN BY A MSMV OF THE MSMV CHAIN. ARE A NUMBER OF ELECTRONIC GATES. THE GATES ARE NORMALLY CLOSED, BUT ARE OPENED BY THE RECTANGULAR WAVE FORM RECEIVED FROM THEIR DRIVING MULTIVIBRATOR. THERE IS AN OUTPUT FROM THE GATE ONLY DURING THE "OPEN" PERIOD, AND THE NATURE OR CHARACTER OF THIS OUTPUT IS A FAITHFUL REPRODUCTION OF THE GOVERNED BY THE INPUT SIGNAL. IF THE INPUT IS A D.C. SIGNAL, THEN THE OUTPUT WILL BE A CORRESPONDING D.C. SIGNAL, (SIMILARLY IF THE INPUT IS A SINE WAVE OR OTHER SHAPED SIGNAL, THE OUTPUT WILL LOOK LIKE THE INPUT.) IN OTHER WORDS, THE GATE PASSES OR ALLOWS TO PASS THRU IT ANY SIGNAL THAT IS PRESENT AT ITS INPUT DURING THE "OPEN-PERIOD" OF THE GATE.

THE GATES FOR EACH BONE ARE IN PARALLEL, AND OPERATE SIMULTANEOUSLY, AND SEND SIGNALS TO DIFFERENT PARTS OF THE DEVIK IN ORDER TO "MAKE" BONES AND CONTROL THEIR POSITIONS IN SPACE. A GATED D.C. WAVEFORM (AS WILL BE SHOWN LATER) MAKES A STRAIGHT BONE. A GATED "SHAPED" WAVEFORM WILL MAKE A BONE ~~WHOSE~~ WHOSE AXIS IS NOT STRAIGHT, BUT HAS THE INTEGRATED, VECTORIAL DIRECTION (OR SHAPE) PRESCRIBED BY THE SHAPED INPUT.

BY VARYING THE D.C. VOLTAGE APPLIED TO THE FIRST GATE, THE ANGLE (θ) THAT THE BONE MAKES WITH THE X-AXIS OF THE DISPLAY IS VARIED. A VARIABLE POTENTIOMETER MAY BE USED TO VARY THE INPUT VOLTAGE, (OTHER MEANS MAY BE USED, OF COURSE). THE SECOND GATE IS USED TO CONTROL THE ANGLE THAT THE BONE MAKES WITH THE X-Y PLANE, IN SIMILAR FASHION

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Lee Harrison

BY VARYING THAT D.C. INPUT, THE THIRD GATE IS USED TO CONTROL THE ANGULAR POSITION (OR MAY BE CALLED "ROTATIONAL POSITION") OF THE SKIN ON THE BONE.

ADDITIONAL GATES MAY BE USED IN SIMILAR FASHION TO CONTROL OTHER PARAMETERS OF THE BONE - SUCH AS INTENSITY, TEXTURE, ETC.

THE FIRST TWO GATES CALLED " θ " AND " ϕ " SEND THEIR SIGNALS TO ~~THE~~ ^{OUT} SIMILAR, ANGLE-PRODUCING NETWORKS. THESE SIGNALS MAY ALSO BE SENT TO CORRESPONDING CHANNELS OF THE TAPE RECORDER, SO THAT DURING PLAYBACK THESE MULTIPLEXED SIGNALS WILL DRIVE THE BONE AND SKIN PRODUCING MECHANISMS OF THE DEVIK, THIS AUTOMATICALLY PRODUCING THE PREVIOUSLY RECORDED MOVEMENTS OF THE BONE & ASSOCIATED PARTS.

THE OUTPUTS OF CONSECUTIVE θ GATES ARE ALL FED INTO THE θ -SINE-COSINE FUNCTION-GENERATOR AND SIMILARLY THE OUTPUTS OF ϕ GATES INTO THE ϕ SINE-COSINE FUNCTION GEN.

SINE-COSINE FUNCTION GENERATOR

See Hermann TB

THERE ARE 2 SINE-COSINE FUNCTION GENERATORS. ONE RECEIVES ITS INPUT FROM THE Θ -GATES, THE OTHER FROM THE Φ -GATES. EACH GENERATOR HAS 2 OUTPUTS FOR EACH INPUT. THE RANGE OF VOLTAGES AT THE INPUT REPRESENT ANY DESIRED ANGULAR POSITION OF THE BONE, AND THE TWO VOLTAGE OUTPUTS HAVE THE RELATION OF THE SINE AND COSINE RESPECTIVELY (SEE GENERAL THEORY)

IN ORDER TO PRODUCE THE RELATIVE VALUES OF THE SINE AND COSINE, SAMPLES OF SINE AND COSINE WAVES ARE TAKEN AT REGULAR INTERVALS, AND THESE SAMPLES ARE FED INTO CAPACITORS WHICH HOLD THE SAMPLED VOLTAGES TO PRODUCE D.C. VOLTAGES ACROSS THE CAPACITORS WHICH ARE AT THE LEVELS BEING SAMPLED.

A SINE-COSINE FUNCTION GENERATOR HAS IN ITS NETWORK A DELAY MULTIVIBRATOR, A NARROW-OUTPUT MONOSTABLE MULTIVIBRATOR, 2 WAVE-SAMPLING GATES AND A HOLDING CAPACITOR ON THE OUTPUT OF EACH SAMPLING GATE.

THE DELAY MULTIVIBRATOR HAS TWO INPUTS. ONE INPUT COMES FROM THE 2ND STAGE OF THE COUNTER, AT $\frac{1}{2}$ THE HIGH-FREQUENCY AND IS OF THE SQUARE WAVE TYPE. THIS INPUT CAUSES THE DELAY M.V. TO CHANGE STATES. IT WILL REMAIN IN THIS STATE UNTIL IT FLIPS BACK AUTOMATICALLY INTO ITS ORIGINAL STATE. THE LENGTH OF TIME THAT IT REMAINS IN THE UNSTABLE STATE IS DETERMINED BY THE 2ND INPUT. THE 2ND INPUT (WHICH COMES FROM THE GATES) IS A D.C. VOLTAGE WHOSE VALUE DETERMINES THE LENGTH OF TIME THE DELAY M.V. WILL DELAY.

THE DRIVING INPUT... THE HIGH FREQUENCY... THIS MEANS THAT THE DELAY M.V. PERFORMS ITS FUNCTION ONCE FOR EVERY 2 CYCLES OF THE HIGH FREQUENCY. THIS MEANS A SAMPLING OF INTO SQUARE COSINE WAVES TO BE TAKEN OVER 2 CYCLES OF THE WAVES, WHICH ALIGNS FOR A SQUARE-WAVE SIGNAL OF HALF THE PERIOD.

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AND
"WOULD BE REQUIRED THAT THERE BE ONE FOR EACH GATE, CONTROLLING INPUT WOULD BE MECHANICAL."
DEC 29 1954



See Hermann TB

THE OUTPUT OF THE DELAY M.V. IS DIFFERENTIATED AND CLIPPED, SO THAT ONLY A PULSE REPRESENTING THE TRAILING EDGE OF THE CHANGE-OF-STATES IS SENT ON TO THE NARROW-PULSE MSMV.

THE INPUT TO THE NARROW PULSE MSMV IS A NARROW TRIGGER PULSE COMING FROM THE DELAY M.V. THE OUTPUT OF THE MSMV IS A VERY NARROW, STRAIGHT SIDED PULSE WHICH IS USED TO DRIVE (OR OPEN) 2 SAMPLING GATES. THE GATES ARE VERY FAST ACTING. ANOTHER INPUT TO THE GATES IS A SINE WAVE (TO ONE) AND A COSINE WAVE (TO THE OTHER) COMING FROM THE SINE WAVE GENERATOR (CLOCK) AND FROM THE PHASE-SHIFTER RESPECTIVELY, THUS THE OUTPUT OF THE GATES IS A VERY NARROW PULSE WHOSE HEIGHT (OR VALUE OF VOLTAGE) IS DETERMINED BY THE TIME AT WHICH THE SINE AND COSINE WAVES WERE SAMPLED, WHICH TIME WAS DETERMINED BY THE TRAILING EDGE OF THE DELAY M.V., WHICH TIME WAS DETERMINED BY THE D.C. VOLTAGE IMPRESSED UPON IT, THIS VOLTAGE HAVING BEEN DETERMINED BY THE OUTPUT OF THE BONE GATES. THE NUMBER OF SUCH PULSES FOR ANY GIVEN D.C. VALUE IMPRESSED UPON THE DELAY M.V. IS DETERMINED BY THE LENGTH OF ANY GIVEN BONE.

BECAUSE OF THE HOLDING CAPACITOR ASSOCIATED WITH THE OUTPUT OF EACH SAMPLING GATE, THERE APPEARS ACROSS EACH CAPACITOR A D.C. VOLTAGE REPRESENTING A PARTICULAR VALUE OF SINE OR COSINE FOR A NORMAL-LENGTH BONE. THE HOLDING CAPACITOR MAY BECOME 15 OR 20 SAMPLING PULSES DURING THE TIME THE BONE IS BEING GENERATED.

THERE ARE OTHER WAYS OF GENERATING THIS SINE-COSINE FUNCTION, ONE SIMPLE WAY WOULD BE TO LET THE OUTPUT OF THE BONE GATES SUPPLY VOLTAGE TO ASSOCIATED SINE-COSINE POTENTIOMETERS BUT THESE PUTS ARE EXPENSIVE AND...

SINE INTEGRATORS

Lee Harrison

W19918 Z-330

THE INTEGRATOR IS A HIGH GAIN AMPLIFIER WHICH HAS A FEEDBACK CAPACITOR TO ITS INPUT. ITS FUNCTION IS TO PERFORM CONTINUOUS INTEGRATION OF THE SIGNALS PRESENTED TO ITS INPUT. THERE ARE THREE INTEGRATORS IN THE BONE GENERATOR, ONE FOR EACH COORDINATE (X, Y, Z) OF 3-DIMENSIONAL

IF THE INPUT TO AN INTEGRATOR IS A D.C. VOLTAGE, THE OUTPUT IS A RAMP FUNCTION. THE INITIAL CONDITIONS (STARTING VOLTAGES ON THE OUTPUT WHICH DETERMINE THE STARTING POINT OF EACH BONE ON THE DISPLAY) ARE DETERMINED BY THE VOLTAGE ACROSS THE FEEDBACK CAPACITOR. IF THERE IS NO DISCHARGE OF THAT CAPACITOR, THEN THE OUTPUT OF THE INTEGRATION OF

A SEQUENCE OF D.C. VOLTAGES WILL BE JOINED TOGETHER. WHENEVER THE CAPACITOR IS DISCHARGED OR SHORTED OUT, THE INITIAL CONDITION VOLTAGES ARE RETURNS TO A ZERO OR STARTING POSITION.

(THE FLYBACK CIRCUIT TO BE DESCRIBED PERFORMS THE FUNCTION OF SHORTING OUT & DISCHARGING THE CAPACITOR AS DESIRED OR REQUIRED TO DRAW A FIGURE OR IMAGE.)

THE VALUE OF VOLTAGE PRESENTED TO THE INPUT OF AN INTEGRATOR DETERMINES THE RATE OF CHANGE OF VOLTAGE AT THE OUTPUT. (SLOPE). IF THE INPUT D.C. VOLTAGES TO THE X AND Y INTEGRATORS REPRESENT THE COS θ AND SIN θ RESPECTIVELY THEN THE OUTPUT OF THE INTEGRATORS WHEN FED INTO THE HORIZONTAL AND VERTICAL AMPLIFIERS ON A DISPLAY SCOPE WILL CAUSE THE BEAM TO DRAW A LINE ON THE SCOPE WHOSE ANGLE TO THE HORIZONTAL IS θ .

ANY TWO OF THE INTEGRATORS WHEN PRESENTED TO EACH OF THE X AND Y DEFLECTION OF THE DISPLAY WILL GIVE THE PROJECTION OF THE FIGURE (OR IMAGE BEING DRAWN) ON THE PLANE DETERMINED BY THE COMBINATION. FOR EXAMPLE, IF THE X AND Y INTEGRATORS OUTPUTS ARE USED, THEN THE DISPLAY WILL BE A VIEW WHICH IS THE PROJECTION OF THE FIGURE ON THE X, Y PLANE. SIMILARLY, IF THE Y AND Z OUTPUTS ARE USE, THE VIEW WILL BE A PROJECTION OF THE FIGURE ON THE Y, Z PLANE.

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Lee Harrison

INTERMEDIATE VIEWS MAY BE OBTAINED BY COMBINING ALL THREE INTEGRATOR OUTPUTS IN PROPER AMOUNTS; THIS ALLOWING AN OPERATOR OF THE DEVICE TO VIEW THE OBJECT OR FIGURE FROM ANY POSITION, THE FUNCTION OF COMBINING THESE INTEGRATOR OUTPUTS IN A PROPER FASHION IS CARRIED OUT BY THE "CAMERA ANGLE NETWORK" TO BE DISCUSSED LATER,



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THE VALUE OF VOLTAGE PRESENTED TO THE INPUT OF AN INTEGRATOR DETERMINES THE RATE OF CHANGE OF VOLTAGE AT THE OUTPUT. (SLOPE). IF THE INPUT D.C. VOLTAGES TO THE X AND Y INTEGRATORS REPRESENT THE COS θ AND SIN θ RESPECTIVELY THEN THE OUTPUT OF THE INTEGRATORS WHEN FED INTO THE HORIZONTAL AND VERTICAL AMPLIFIERS ON A DISPLAY SCOPE WILL CAUSE THE BEAM TO DRAW A LINE ON THE SCOPE WHOSE ANGLE TO THE HORIZONTAL IS θ .

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EXCESSIVE INTEGRATION

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FLYBACK NETWORK.

THE FUNCTION OF THE FLYBACK NETWORK IS TO SHORT OUT OR DISCHARGE THE CAPACITORS (C) ASSOCIATED WITH THE INTEGRATORS AT DESIRED TIMES DURING THE SEQUENCE OF BONES AND AT THE END OF ONE A CYCLE OF BONE GENERATION. DISCHARGING OF THE CAPACITORS CAUSES THE BEAM OF THE DISPLAY CRT TO FLY BACK TO THE STARTING POSITION.

AN ELECTRONIC SWITCH DISCHARGES THE CAPACITOR. PULSES WHICH CLOSE THE SWITCH COME FROM AN AMPLIFIER WHICH IS IN TURN FED BY PULSES (WHICH ARE SELECTED AS DERIVED) COMING FROM SELECTED MULTIVIBRATORS OF THE MSMB CHAIN. ALSO, A PULSE, WHOSE DURATION IS DETERMINED BY THE TIME OF THE LAST MSMB TO THE BEGINNING OF A NEW CYCLE OF THE FIRST MSMB IS GENERATED BY A BISTABLE MULTIVIBRATOR. THIS FLYBACK BISTABLE MV RECEIVES A PULSE FROM THE LAST MSMB AS IT CLOSSES, THIS PULSE FLIPS THE BSMV AND ITS OUTPUT CAUSES THE SWITCHES TO CLOSE, THIS BSMV STAYS IN THE "CLOSED" STATE UNTIL IT RECEIVES ANOTHER INPUT PULSE WHICH THIS TIME COMES FROM THE COUNTER, THE SAME PULSE WHICH STARTS THE CHAIN OF MSMB'S.

DIODES CONNECT ALL OF THE PULSE INPUTS TO THE AMPLIFIER WHICH ACTIVATES THE SWITCHES SO AS TO PREVENT PULSES FROM FEEDING BACK INTO THE GATES AND THUS OPERATE OUT OF SEQUENCE.

THE ELECTRONIC SWITCHES REMAIN CLOSED DURING THE DURATION OF A PULSE, BE IT LONG OR SHORT.

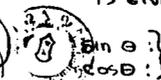
SKIN NETWORK.

THE FUNCTION OF THE SKIN NETWORK IS TO ALGEBRAICALLY COMBINE THE VARIOUS VOLTAGE REPRESENTATIONS OF $\sin \theta$, $\cos \theta$, $\sin \phi$, $\cos \phi$, $k_1 t_x$, $k_1 t_y$, $k_1 t_z$, $\sin k_1 t$ AND THE VIDEO SIGNAL "A" TO GIVE THE PROPER FORMULATIC REPRESENTATIONS OF THE GEOMETRIC PROJECTIONS OF THE FIGURE OR OBJECT BEING GENERATED. FOR QUICK REFERENCE, A TABULAR REPRESENTATION OF THESE VARIOUS SIGNALS IS GIVEN BELOW.

$\sin \theta$
 $\cos \theta$

$k_1 t_x$
 $k_1 t_y$
 $k_1 t_z$

$\sin \phi$
 $\cos \phi$



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$\sin \theta$, $\cos \theta$ } D.C. VALUES OF VOLTAGE WHOSE RELATIONSHIP IS AS THE SINE AND COSINE OF THE ANGLE θ

$\sin \phi$, $\cos \phi$ } D.C. VALUES OF VOLTAGE WHOSE RELATIONSHIP IS AS THE SINE AND COSINE OF THE ANGLE ϕ .

$k_1 t_x$, $k_1 t_y$, $k_1 t_z$ } RAMP FUNCTIONS OF VOLTAGE, THE OUTPUTS OF INTEGRATORS X, Y AND Z RESPECTIVELY, WHERE THE CONSTANT k_1 IS A SCALING FACTOR WHICH IS A DEVICE FUNCTION OF THE

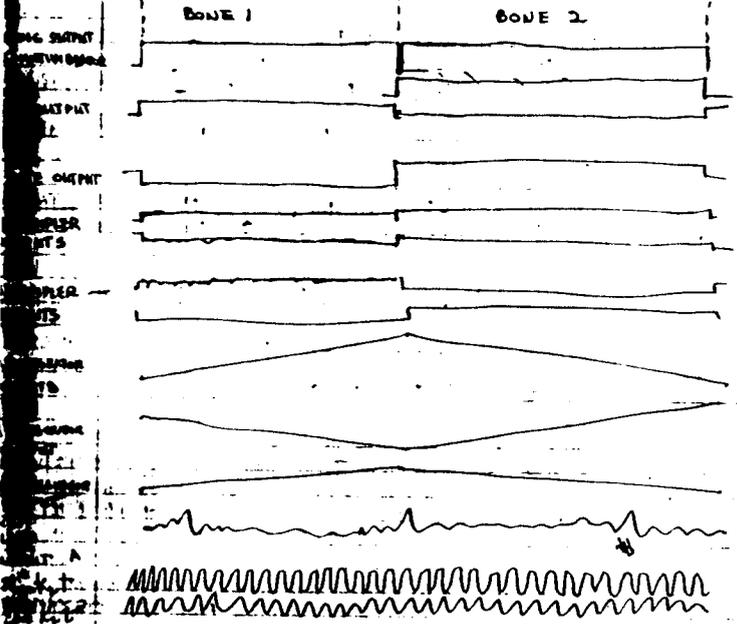
GAINS OF DISPLAY AMPLIFIERS OF THE GAINS OF THE INTEGRATING AMPLIFIERS AND ALSO A FUNCTION OF THE AMPLITUDE OF THE INPUT SINE AND COSINE WAVES TO THE INTEGRATORS. FOR SIMPLICITY THESE EFFECTS ARE ACCOUNTED FOR BY THE USE OF THIS "LUMPED CONSTANT" k_1 .

$\sin k_1 t$, $\cos k_1 t$ } SINE AND COSINE WAVE FUNCTIONS WHOSE FREQUENCY (THE HIGH FREQUENCY) IS DETERMINED BY k_1 , AND WHOSE AMPLITUDE IS CONSIDERED TO BE EQUAL TO 1 (ONE UNIT). (FOR A NORMAL MATHEMATICAL REPRESENTATION WE'D HAVE TO USE "a $\sin k_1 t$ " TO DENOTE THIS WAVE, BUT WE SIMPLIFY THE EXPRESSION BY LETTING $a = 1$ unit, which $\omega = \text{about } 1000 \text{ rps}$.)

Lee Harrison TB

CAPITAL A IS USED TO DENOTE THE VIDEO SIGNAL WHICH COMES FROM THE SKIN SCANNER. THIS IS A WIDE BAND SIGNAL WHOSE UPPER FREQUENCIES ARE VERY HIGH.

TO SHOW THE INTER-RELATIONSHIP OF THE VARIOUS SIGNALS, A PICTOGRAPH IS GIVEN FOR 2 BONES



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TWO ALGEBRAIC FUNCTIONS ARE PERFORMED BY THE PORTION OF THE DEVICE WHICH WE CALL THE SKIN NETWORK, NAMELY MULTIPLICATION AND ADDITION.



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ASSOCIATED WITH EACH MULTIPLIER ARE INPUT AND OUTPUT AMPLIFIERS, WHICH ARE ELECTRONICALLY NECESSARY TO ALLOW AN ANALOGUE MULTIPLIER TO PERFORM THE TASK OF MULTIPLICATION. MULTIPLIERS REQUIRE A "CENTER TAP" INPUT, THUS THE THREE INPUTS TO THE MULTIPLIERS. THE IMPORTANT THING HERE IS NOT HOW WE PERFORM THE PARTICULAR TASK, BUT THAT WE DO PERFORM IT.

ADDEES ARE MERELY RESISTOR NETWORKS WHICH ADD THE VARIOUS SIGNALS PRESENTED TO IT.

ALGEBRAICALLY SPEAKING, THE SKIN NETWORK TAKES THE PREVIOUSLY MENTIONED SIGNALS AND COMBINES THEM SO THAT

$$x = k_1 t_1 \cos \theta \cos \phi + A \cos \theta \sin \phi \cos k_2 t_2 + A \sin \theta \cos k_2 t_2$$

$$y = k_1 t_1 \sin \theta \cos \phi + A \sin \theta \sin \phi \cos k_2 t_2 + A \cos \theta \sin k_2 t_2$$

$$z = k_1 t_2 \sin \phi + A \cos \phi \cos k_2 t_2$$

HERE, X, Y AND Z REPRESENT THE X, Y AND Z VECTORIAL COMPONENTS OF THE FIGURE. BY PRESENTING ANY 2 OF THESE SIGNALS TO THE X AND Y CHANNELS OF A DISPLAY CRT, THE RESULTING DRAWING WILL BE A PROJECTION OF THE 3 DIMENSIONAL FIGURE ON THE PLANE DETERMINED BY THE COMPONENTS SELECTED, BY THE GEOMETRIC SELECTION AND COMBINATION OF ALL THREE OF THESE COMPONENTS, ANY VIEW OR PROJECTION OF THE 3 DIMENSIONAL FIGURE MAY BE SHOWN.

CAMERA-ANGLE NETWORK

THE FUNCTION OF THE CAMERA ANGLE NETWORK IS TO ALGEBRAICALLY (AND THUS GEOMETRICALLY) COMBINE THE X, Y, AND Z COMPONENTS OF THE TARGET DIMENSIONAL FIGURE IN SUCH A MANNER AS TO ALLOW FOR THE PRESENTATION OF ANY PROJECTION OR VIEW OF THE FIGURE WHEN THE OUTPUTS OF THIS NETWORK ARE PRESENTED TO THE X AND Y CHANNELS OF A DISPLAY CRT.

2 ALGEBRAIC FUNCTIONS ARE PERFORMED: THE FIRST IS MULTIPLICATION BY A CONSTANT, THE SECOND IS ADDITION.

THE "MULTIPLICATION BY A CONSTANT" IS IN EFFECT THE "TAKING OF THE SINE AND COSINE" OF THE VECTOR AND IS ACCOMPLISHED BY A NETWORK OF VARIABLE "SINE-COSINE" POTENTIOMETERS. ADDITION IS PERFORMED USING A FIXED RESISTANCE NETWORK.

ANGLES θ' (THETA PRIME) AND ϕ' (PHI PRIME) REPRESENT THE ROTATION OF THE XY PLANE ABOUT THE X AXIS AND THE XZ PLANE ABOUT THE Z AXIS.

2 SIN-COSINE POTS GANGED TOGETHER (AROUND A COMMON SHAFT) IS THE MECHANISM FOR PERFORMING THE PROPERLY-RELATED MULTIPLICATION BY CONSTANTS, OR TAKING THE SINES & COSINES IN THE PROPER RELATIONSHIP.

THERE ARE TWO SUCH MECHANISMS. ROTATION OF THE SHAFT OF ONE, CONTROLS THE VIEWING ANGLE θ' . THE OTHER CONTROLS ϕ' . AMPLIFIERS ASSOCIATED WITH THE NETWORK OF SINE-COSINE POTS ARE AN ELECTRONIC NECESSITY.

THE TWO OUTPUTS OF THIS NETWORK ARE FED INTO THE X AND Y CHANNELS OF THE DISPLAY CRT, AND REPRESENT THE BEAM-POSITIONAL INFORMATION NECESSARY TO DRAW THE

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EVENTUALLY, WE'LL USE CONTROLLING SERVO-MOTORS TO POSITION THE SHAFTS θ' & ϕ' , SO THAT THE CAMERA ANGLES MAY BE RECORDED ON THE CONTROL-TAPE RECORDER ALONG WITH OTHER CONTROLLING INFORMATION. IN OTHER WORDS, WE'LL RECORD SIGNALS TO WHICH THE SERVOS WILL REACT, THUS RECORPING THE CAMERA ANGLES.



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CONTROL OF MOTION & OTHER PARAMETERS OF THE SIGNAL RELATIVE TO THE BONE AXES

BY CONTROLLING THE ~~THE~~ VOLTAGE INPUTS TO THE BONE GATES, THE POSITIONS, ATTITUDES, ^{OR ORIENTATIONS} AND OTHER SPACIAL ^{OR ORIENTATIONAL} PARAMETERS ARE CONTROLLED. THE FUNCTION OF THE CONTROLS IS TO GENERATE THE DESIRED SIGNALS FOR THE VARIOUS MOTIONS. IN GENERAL, THE CONTROLLING SIGNALS ARE VERY LOW FREQUENCY ^{AND IN SOME} CASES PRACTICALLY D.C. (THE SAMPLING RATE FOR EACH BONE SIGNAL TO BE MULTIPLEXED IS 24 TIMES PER SECOND. IN ONE SECOND, UNLESS THE ACTION OF A BONE IS VERY SWIFT, THE VOLTAGE VARIATION FROM THE BEGINNING TO THE END OF ONE DRAWING CYCLE (30 μ sec) OF ONE BONE ($\approx \frac{1}{24}$) IS VERY SLIGHT. THAT IS TO SAY, SUPPOSE THE VOLTAGE VARIES 5 VOLTS IN ONE SECOND, THE VARIATION DUE TO THE TURNING OF A POTENTIOMETER, THEN THE VARIATION ~~FROM~~ ^{AS COMPARED TO} THE BEGINNING TO THE END OF A BONE IS ABOUT $\frac{1}{24}$ VOLTS WHICH IS SUCH A SMALL CHANGE THAT THE BONE APPEARS STRAIGHT.)

NETWORKS OF VARIABLE RESISTORS AND VERY ~~LOW~~ ^{LOW} FREQUENCY GENERATORS MAY BE USED TO GENERATE INTERRELATED BONE-GROUP ACTIONS OR MOTIONS. AS THE MANIPULATION OF THE POTENTIOMETER INPUTS IS SIMPLIFIED, IT MAY BE CONSIDERED THAT THE CONTROLS MAY BECOME MORE AND MORE COMPUTER-LIKE, WHERE MANY ^{BONE} MOTION FUNCTIONS ARE GENERATED AUTOMATICALLY.

~~CONTROLLED~~ BONES MAY BE ~~CONTROLLED~~ BY APPLYING SHAPED WAVEFORMS IN PLACE OF D.C. INPUTS. OTHER THAN STRAIGHT. FOR EXAMPLE, A SAWTOOTH CONTROL INPUT WILL GIVE A WIGGLY

Luckman



A SINUSOIDAL INPUT (IF AT THE PROPER PHASE & FREQUENCY) WILL MAKE A CIRCULAR BONE; A SQUARE (TYPE) WAVE INPUT WILL MAKE A ZIG ZAG \sim OR SAWTOOTH TYPE BONE; A RAMP INPUT TO THE BONE GATES WILL MAKE A CURVED OR ARCHED BONE. SPECIAL WAVEFORMS MAY ALSO BE INSERTED WITHIN BEFORE OR AFTER THE INTEGRATOR, WITHOUT PASSING THROUGH THE SAMPLING NETWORKS. IN ORDER TO PRODUCE DESIRED MUTATIONS ON THE BONES (TECHNIQUES SUCH AS THESE HAVE BEEN DISCUSSED ON MANY OCCASIONS, AND WILL BE EXECUTED WHEN TIME ALLOWS)

JOY-STICKS & FINGER CONTROLS HAVE BEEN DESIGNED FOR EASY, MECHANICAL MANIPULATION OF THE CONTROLS & MAY BE THE SUBJECTS OF LATER PATENTS. SPECIAL INPUTS FOR FACIAL EXPRESSIONS MAY BE THESE TECHNIQUES INCLUDE TRANSDUCED FROM ACTUAL FACIAL & LIP MOTIONS USING A NETWORK OF STRAIN GAGES

SHADING (AND COLOR) NETWORK

Leathner 11

14/29/61

THE ELECTRONIC SIGNALS COMING OUT OF THE CAMERA ANGLE NETWORK ARE BEAM-POSITIONING SIGNALS; (JUST AS FINGERS CONTROL THE POSITION OF A PENCIL ON PAPER). THE FUNCTION OF THE SHADING (AND COLOR) NETWORK IS TO GOVERN THE BEAM INTENSITY AS IT DRAWS THE FIGURE OR OBJECT, ~~AND IS GOVERNED BY THE~~ USE OF (HIGH FREQUENCY) VARIATIONS IN INTENSITY ASSOCIATED WITH SKIN SHADES & SHADOWS, TEXTURES ~~etc.~~ etc. WHICH ARISE FROM THE SURFACE VARIATIONS IN THE SKIN. (COLOR VARIATIONS IN THIS SENSE ARE THOUGHT OF IN TERMS OF A THREE-COLOR (MULTI-COLOR) PROCESS WHERE FOR EXAMPLE ~~THE~~ THREE DISPLAY SCOPE(S), ^(AS IN THE CASE OF) ARE OPTICALLY SUPERIMPOSED, AND EACH SCOPE HAS A COLOR FILTER ON ITS FACE. BY VARYING THE INTENSITIES OF THE 3 BEAMS, THE ~~OPTICAL~~ OPTICAL IMAGE HAS FULL SPECTRUM COLOR CAPABILITY. THIS TOPIC IS CALLED SHADING (AND) COLOR NETWORK.)

THE SKIN VIDEO SIGNAL CONTAINS THE INFORMATION ABOUT THE ~~SPATIALLY INDEPENDENT~~ ORTHOGONAL DISTANCE BETWEEN BONE AND SKIN. IN THE FULL BASIC FORMAT, THE RATE OF CHANGE OF THE VIDEO SIGNAL IS USED TO CONTROL ^{THE BRIGHTNESS (SHADING)} HIGH FREQUENCY SKIN VARIATIONS TO ACCENTUATE SKIN FEATURES WHICH OCCUR BETWEEN THE EDGES OF THE OBJECT BEING DRAWN IN THIS FORMAT. BY DIFFERENTIATING THE SKIN VIDEO A RATE-OF-CHANGE SIGNAL IS OBTAINED. A THRESHOLD NETWORK DETECTS ALL RATES ^{IN CASES} ABOVE OR A PRESCRIBED ABSOLUTE VALUE. THE CLIPPED OUTPUT OF THE THRESHOLD NETWORK IS AMPLIFIED AND SCANNED, ~~thence~~ thence USED TO MODULATE FRONT INTENSITY, EXPANDING, EDGE EFFECTS (EDGE SHADOWS etc.)

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ARE PRODUCED IN ACCORDANCE WITH THE SKIN VECTOR POSITION WHICH IS A FUNCTION OF THE PHASE OF THE HIGH FREQUENCY SINE WAVE FROM THE CLOCK. IN ADDITION, A HIGH FREQUENCY WOBBLE OR A FOCUS-FLARE MAY BE EMPLOYED TO HEAVY-UP OR THICKEN THE EDGES, THE ACTION ALSO BEING IN Synchronization WITH PHASE OF THE SINE WAVE.

DO NOT VARY WITH FLAT COLOR EFFECTS, OR GRAYS OR TEXTURES WHICH MAY BE PRODUCED BY CALCULATING IN THESE INTENSITY-MODULATING SIGNALS ~~THE~~ FUNCTIONAL ~~THE~~ THE BONE GATES DESIGNED FOR THAT PURPOSE. THE INPUT TO THE GATES ^{IS} A HIGH FREQUENCY OF A CERTAIN ^{PATTERN} WHICH WHEN APPLIED TO MODULATE THE BEAM INTENSITY DURING THE DRAWING OF A PARTICULAR BONE WILL GIVE A TEXTURED PATTERN. MORE SPECIFICALLY, VIDEO SIGNALS ~~CONTAINING~~ DESIGNS OF PRESCRIBED DESIGNS MAY BE APPLIED IN THIS MANNER TO GIVE THE ~~THE~~ DESIRED EXTERIOR APPEARANCE OF AN OBJECT ~~AS~~ AS A SOAP BOX OR OTHER CONSUMER PRODUCT, OR A SHIRT PATTERN (ON A FIGURE) OR A FUR PATTERN (ON AN ANIMAL CHARACTER) (TO GENERATE THIS INTENSITY VIDEO, ANOTHER SCANNER WOULD BE REQUIRED, OR A SPLIT-IMAGE ^(BY WAY OF ILLUSTRATION) SCANNING TECHNIQUE WHERE OPTICAL MEANS ARE USED TO HAVE THE SKIN-SCANNING MASTER OF THE FLYING SPOT FOCUSED ON TWO (OR MORE) FILMS - WHERE ONE FILM CONTAINS THICKNESS INFORMATION AND ANOTHER CONTAINS SURFACE COLOR, PATTERN OR TEXTURE INFORMATION.

OVERLAP PREVENTION AND SCAN CONVERSION

BECAUSE THE DISPLAY BEAM IS DRAWING A 2-DIMENSIONAL PROJECTION OF A 3-DIMENSIONAL IMAGE IN A CONTINUOUS MANNER IT IS NECESSARY TO PROVIDE A MEANS OF PREVENTING THE BEAM FROM DRAWING OVER A PORTION OF THE IMAGE WHICH HAS ALREADY BEEN DRAWN. THIS A SPECIAL DEVICE FOR "OVERLAP PREVENTION" HAS THE FUNCTION OF DOING AWAY WITH "GHOST" IMAGE OR ~~AND~~ OVERLAP.

OVERLAP MAY BE ~~CLASSIFIED~~ ^{CLASSIFIED} INTO TWO TYPES. ONE TYPE OCCURS WHEN THE "BACK PART" OR PART OF THE IMAGE ON THE SIDE AWAY FROM THE VIEWER IS DRAWN. THIS OVERLAP IS PREVENTED BY TURNING OFF THE INTENSITY OF THE BEAM ACCORDING TO THE VECTORIAL POSITION OF THE SPIN VECTOR WHICH IS A FUNCTION OF 1) PHASE OF THE HIGH FREQUENCY, AND 2) THE CAMERA ANGLE (WHICH GOVERNS THE POSITION OF THE PLANE OF PROJECTION).

THE 2ND TYPE OF OVERLAP OCCURS WHEN ONE PART OF AN OBJECT OR FIGURE OVERLAP ANOTHER PART, OR WHERE ONE FIGURE IS IN FRONT OF ANOTHER. BY USING A SPECIAL DISPLAY TUBE WHICH HAS IN IT, TWO OR MORE ELECTRON GUNS, ONE OF WHICH IS A "WRITE" GUN, ANOTHER OF WHICH IS AN "ERASE" GUN (HAVING SELECTIVE ERASURE CAPABILITY), AND HAVING THE ERASE GUN PRECEDE THE WRITE GUN BY EMPLOYING A SLIGHT DELAY IN THE "WRITE" SIGNALS (BOTH GUNS GETTING THE SAME ^{PROVIDE} DISPLAY SIGNALS HOWEVER, OVERLAP MAY BE PREVENTED), AS LONG AS THE ~~OBJECT~~ OBJECT OR PART OF THE OBJECT WHICH IS TO BE DISPLAYED IS DRAWN IN THE ~~SEQUENCE~~ SEQUENCE COMPATIBLE WITH THIS METHOD (NAMELY, LAST

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A MULTI-GUN SCOPE THIS EMPLOYED WILL CONTAIN THE IMAGE THUS DRAWN FOR A LENGTH OF TIME ~~OR~~ NECESSARY FOR PHOTOGRAPHING OR SCAN CONVERTING. A SCAN CONVERSION TUBE MAY BE USED TO ~~TRANSDUCE~~ ^{TRANSDUCE} THE ~~IN~~ DRAWN IMAGE INTO A SCANNING PATTERN WHICH IS COMPATIBLE WITH TELEVISION TRANSMISSION OR A CLOSE-LINE RASTER WHICH WOULD BE COMPATIBLE FOR THE SUPERPOSITION OF FIGURES ON A BACKGROUND.

AT THIS POINT IN THE GENERATION OF ANIMATED PICTURES IT IS NECESSARY TO CONSIDER PICTURE QUALITY IN TERMS OF RESOLUTION. THE PROBLEM OF RESOLUTION BECOMES ACUTE WHEN HIGH ~~OR~~ SCANNING SPEED ~~REQUIRES~~ NECESSITATES HIGH BANDWIDTH REQUIREMENTS. THUS IT IS CONTEMPLATED THAT THE SPECIAL PICTURE TECHNIQUES (SUPERIMPOSITION, OVERLAP PREVENTION - SCAN CONVERSION) WILL BE CARRIED ON AT A RELATIVELY SLOW RATE - I.E. NOT AT THE SAME SPEED AT WHICH WE ANIMATE. AN OPERATOR MAY DO HIS ANIMATION IN REAL TIME (WHERE THE DEVICE ~~PUTS~~ PUTS THE SIGNALS INTO A 24/FRAME/SEC FORMAT) BUT THE EVENTUAL FILM-RECORDING OF THE ANIMATED SEQUENCES WILL BE AT A SLOWER RATE, AND OF COURSE ALL AUTOMATICALLY CONTROLLED BY THE PRE-PROGRAMMED ANIMATION WITH LOW, REPRODUCTION SCANNING RATES, HIGH RESOLUTION, COMPATIBLE WITH 35MM. FILM (CAN) MAY BE ATTAINED.