OPERATING INSTRUCTIONS

EM61-MK2 DATA LOGGING SYSTEM FOR WINDOWS XP BASED FIELD COMPUTER



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Table of Contents

1.	Intro	duction	. 1
	1.1	Program Requirements	. 2
	1.2	Installing EM61MK2xp	. 2
	1.3	Running EM61MK2xp Program	. 2
	1.4	Main Screen	. 3
		Short description of Main Screen options	3
2.	Surve	ey Setup	. 5
3.	Logg	er Setup	. 9
4.	Set P	ort for GPS & Monitoring	13
	4.1	GPS Port Setup	13
	4.1	Monitoring GPS Receiver Output	15
5.	Displ	ay Options	19
6.	Logg	ing Data	21
	6.1	Monitoring Mode	21
		Description of Monitoring Mode Options	.24
	6.2	Stand By Mode	32
	6.3	Logging Mode	34
	6.4	Stand By Mode Field Options	36
Арре	ndix /	۹	45
	A.1	Description of Data File in EM61MK2xp Format	45
	A.2	Conversion Factors	48
	A.3	Example of File in EM61MK2xp Format	50
Арре	ndix l	Β	51
	B.1	Using the EM61MK2xp with a GPS Receiver	51
	B.2	Description of GGA and GSA Data Messages	52

1. Introduction

The Geonics EM61MK2xp Data Logging System (DAS70-XP) consists of a laptop field computer, data logging program EM61MK2xp, and associated cable to connect the computer to the Geonics EM61-MK2 instrument. The program EM61MK2xp is designed for a IBM PC compatible computer and MS Windows XP/2000 operating system.

The EM61MK2xp program acquires and records survey data from the EM61-MK2 system, under the control of the operator. It also records various field information such as survey line number (line name), starting station, increment, comments, etc. Readings are displayed in graphic and numeric mode. Readings are displayed in real time in mV. In addition, the program allows you to monitor the instrument output while data is not recorded. The EM61MK2xp program continuously monitors the condition of the instrument battery, without leaving the program. The EM61MK2 also provides the possibility of automatic nulling of the instrument output at any time during the survey.

The program allows the user to set the EM61-MK2 into a specific instrument mode of operation: AUTO, Wheel, or Manual modes. In AUTO mode readings can be automatically recorded in desired time intervals. In WHEEL mode readings are triggered by a counter installed at the EM61-MK2 wheel assembly, and in MANUAL mode readings are triggered manually by the operator.

The program supports the standard EM61-MK2 instrument as well as EM61-MK2 High Power unit. The program allows you to record data while using various EM61-MK2 antenna (1 x 0.5 m, 1 x 1 m, or 0.5 x 0.5 m sensors) and Geonics EM61HH-MK2 Hand Held sensor.

The EM61MK2xp will accept NMEA-0183 compatible data from a GPS receiver directly connected to an Allegro field computer. GPS data which are embedded in the EM61MK2xp data file can be processed later in the Geonics DAT61MK2 program. The connected GPS must be able to stream NMEA-0183 compatible messages. The EM61MK2xp uses two NMEA messages GGA and GSA. While message GGA is mandatory, the GSA string is used only to provide information related to the GPS signal quality during data collection.

The EM61MK2xp program records data together with a time stamp at each station. Data files created with this program can be used to position a survey according to locations recorded separately by a Global Positioning System (GPS).

Survey setup parameters are saved in a file, therefore they can be automatically used during subsequent data collection sessions.

Data files are saved to the user selected data directory. Data file names, which can be set by the program based on the computer clock or user specified, have extension names R61. Files can be converted to M61 format and viewed in DAT61MK2 program.

Number of readings in a data file is limited only by the hard drive capacity, however it is strongly recomended to avoid huge data files (i..e one to two hours long data files are adequate). The maximum speed of data collection is approximately 17 readings per second assuming 1 Hz (or less) GPS input. In graphic display mode, a profile containing the last 150 data readings is displayed for each channel.

1.1 Program Requirements

To successfully use this software, you will need :

Computer

- PC field computer operating under Windows 2000 Pro, XP, or later,
- Minimum 256 Mb of RAM memory,
- CD drive or other mean to transfer files,
- minimum 800 x 600 pixel display resolution,
- serial Ports:

one serial port per instrument in array plus one serial port if directly connected GPS receiver is to be used (USB to multiple RS-232 ports and PCMCIA RS-232 adapters can be used).

Geonics EM61-MK2

The EM61-MK2 instrument with associated cables.

The EM61MK2xp program is stored on DAT61MK2 CD disk. All necessary initial files (with extension names .INI) are created in your field computer after the program is run for the first time. Check that the file EM61MK2xp.EXE is included on the CD disk.

1.2 Installing EM61MK2xp

The program consists of a standalone file EM61MK2xp.exe, no DDLs nor other libraries are required to run this program. The program is usually installed during data processing program DAT61MK2 installation, it is placed in subdirectory LogData of the selected installation directory.

If the program file is included separately on the DAT61MK2 CD disk, or downloaded from e-mail server it can be installed by copying the EM61MK2xp.exe file to any directory on your hard disk. This can be performed by using Windows Explorer.

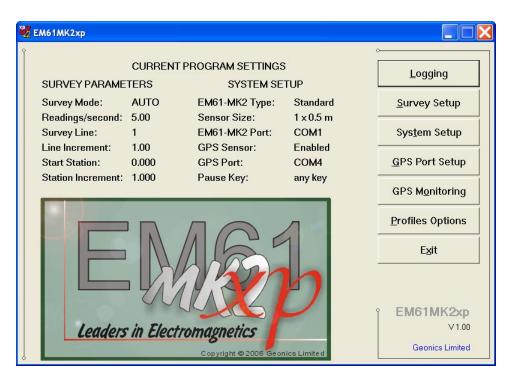
After you run the program for the first time it will create permanent initial files (.INI) which contain some of the program settings. If the above files do not exist on the default drive they will be created with default parameters during the first execution of the program.

The EM61MK2xp data files contain extension name R61 and their base names should be limited to 8 characters.

1.3 Running EM61MK2xp Program

Start EM61MK2xp by double clicking the EM61MK2xp icon in the Start|Programs menu, in Windows Explorer, or on the desktop if a shortcut was created. At the start, EM61MK2xp displays the following screen.

The EM61MK2xp is a command button and dialog driven program. Command buttons can be executed by clicking with the left mouse button, or by pressing the indicated (underlined) character on the keyboard, or by using TAB to scroll through the buttons and ENTER to execute. In the Main Screen of the program Up and Down arrow keys can be also used to scroll through the buttons.



The Main Screen appears always as the first window after the program is started. It contains the name of the program, its version number (right bottom corner), and list of command buttons with available options on the right side. The major, left portion of the window contains information about current survey and system settings. This section is updated in real time as soon as the program parameters are changed in dialogs.

1.4 Main Screen

The Main Screen always appears after the program is started. It contains the name of the program, its version number, and a list of buttons representing the available options. The EM61MK2xp Main Screen is displayed below.

These options are selected by clicking on buttons, or from keyboard using TAB/ENTER or shortcuts indicated by underline label characters. In case of Main Screen buttons the **Down** and **Up** arrow keys and **<ENTER**> can be used as well.

Short description for each of the options follows.

Short description of Main Screen options

Monitor/Log

This option allows to monitor and log the EM61-MK2 output. Monitor/Log screen starts always in Monitor mode, and then after a data file is created Logging mode is available. Monitor mode provides several options: the instrument nulling, performing Internal and External QC coil calibration, monitoring EM61-MK2 battery level, monitoring quality of GPS signal, etc.

Survey Setup

The Survey Setup dialog will be displayed. All survey settings (survey line name, increments, etc.) can be specified in this dialog.

Survey Setup		×
EM61MK2 Mode	Auto 💌	
Readings/second	5.00	
Survey Line	1	
Line Increment	1.00	
Line Sequence	Alternate	
Direction	North	
Start Station	0.000	
Station Increment	1.000	
ОК	Cancel	

System Setup

Dialog window that is associated with this option is used to set the instrument type, antenna size, serial port numbers, battery warning level, and type of pause key.

Set GPS Port

The GPS Port Setup dialog allows to disable and enable GPS data acquisition. This option is also used to set the serial port number used for GPS input and to specify necessary serial port communication settings. GPS monitoring window can be accessed from this dialog as well.

Display Options

The dialog which will allow you to specify colour and thickness of profile lines will appear. This dialog provides also choice of linear or compressed amplitude used for profile display.

E<u>x</u>it

This option will terminate the program execution.

2. Survey Setup

The Survey Setup dialog, presented below, contains several parameters which affect two important procedures: instrument settings (instrument mode, frequency of data collection, etc.) and survey geometry layout (survey line names, line spacing, start station, station increment, etc.).

Survey Setup	X
EM61MK2 Mode	Auto 💌
Readings/second	5.00
Survey Line	1
Line Increment	1.00
Line Sequence	Alternate 💌
Direction	North 💌
Start Station	0.000
Station Increment	1.000
ОК	Cancel

To select any option click on the corresponding drop-down list box or text box, or use TAB key to scroll to the option and then use mouse or the **Down** and **Up** keys in drop-down box (parameters that have only a few possible options), or keyboard for text box entry.

Description of Options and Parameters:

EM61-MK2 Mode

This option allows you to select the type of instrument used. In the drop-down list box select Standard for the EM61-MK2 or High Power if EM61-MK2 High Power (HP) modification is used.

Set the EM61-MK2 mode of operation by selecting an item from the drop-down listbox labeled EM61 Mode. Available modes are: Auto, Wheel, and Manual. These modes of operation are described below.

Auto Mode

Readings will be triggered automatically at a specified frequency (see option Readings/s).

Please note that while in the former data acquisition system (DAS70) Stn Increment (station increment) had only two options: Positive or Negative, in the current program this value is optional.

Wheel Mode

Readings will be triggered automatically by a counter attached to the wheel. Wheel increment is approximately 20 cm (or 0.64 foot) for the EM61-MK2 equipped with 1 x 0.5 m or 1 x 1 m antennas. The Hand Held EM61HH-MK2 has two

Survey Setup	×
EM61MK2 Mode	Wheel 💌
Readings/second	Not Available
Survey Line	1
Line Increment	1.00
Line Sequence	Alternate 💌
Direction	North 🔹
Start Station	0.000
Wheel Increment	0.200
ОК	Cancel

wheel increments 0.1 and 0.2 m. Check the wheel increment setting on the antenna assembly.

When Wheel mode is selected option Reading/second is not available, see figure below. Please note that while in former data acquisition system (DAS70) Stn Increment (station increment) had only two options: Positive or Negative, in the current program this parameter is optional and its value has to be entered according to used wheel increment.

Manual Mode

Readings will be taken only while the manual trigger (switch on the logger cable) is pressed. This mode may be used only in very specific applications since the highly dynamic EM61-MK2 response requires finely spaced data points.

Please note that when Manual mode is selected option Reading/second is not available.

Survey Setup			×
EM61MK2 Mode	Manual	•	
Readings/second	Not Available		
Survey Line	1		
Line Increment	1.00		
Line Sequence	Alternate	•	
Direction	North	-	
Start Station	0.000		
Station Increment	2.000		
ОК	Cancel		

Readings/second

When this option is available (only in Auto mode) activate text box by clicking with a mouse or using TAB key and then enter desired value.

This parameter describes number of readings per second that will be taken. Any number larger than zero can be entered, however the EM61-MK2 maximum frequency of data output is 17 readings per second.

Survey Line (survey line name)

Activate text box by clicking with a mouse left button or using TAB key and then enter desired name (number) for the survey line.

This is a user's tag number/name for the profile line. The length of the name can not exceed 8 characters. The line name is usually used as a coordinate perpendicular to the survey lines direction. For example, when survey lines are laid out along W-E direction stations describe W-E coordinate, while Line names may describe S-N (vertical on a map) coordinate.

Line Incr. (survey line name)

Activate text box by clicking with a mouse or using TAB key and then enter desired for the survey line increment.

This parameter specifies the distance by which survey lines will be separated. This setting will be used to determine number (name) of the next survey line.

Sequence

When this option is highlighted and drop-down box is expanded use mouse or use **Down** or **Up** cursor key to toggle between two available settings: Alternate and One Way.

Survey Setup	
EM61MK2 Mode	Auto 💌
Readings/second	5.00
Survey Line	1
Line Increment	1.00
Line Sequence	Alternate 💌
Direction	Alternate One Way
Start Station	0.000
Station Increment	1.000
ОК	Cancel

<u>Alternate</u> is used when neighboring lines are surveyed in the opposite direction, which is the most common procedure during field surveys.

One Way is used when each survey line is traversed in the same direction.

The choice of this parameter will affect the default start station, a signature of the station increment, and line direction when parameters for the next survey lines is determined.

Direction

Clicking on the down arrow next to the text box opens a drop-down box showing the available options, or when the keyboard is used activate the text box and then by using up or down arrow keys select one of four available settings: East, West, South, and North. This parameter indicates the heading of the survey line.

Survey Setup		×
EM61MK2 Mode	Auto 💌	
Readings/second	5.00	
Survey Line	1	
Line Increment	1.00	
Line Sequence	Alternate 💌	
Direction	North 💌	
Start Station	East North	
Station Increment	South Rest	
ОК	Cancel	

Start Station (start station of a survey line)

Activate text box by clicking or using TAB key and then enter the desired value for the start station.

This parameter specifies the starting station number for the selected survey line. This value is used in conjunction with Station Increment to calculate the current station number for display purposes.

Stn Increment (station increment)

Activate text box by clicking with a mouse or using **TAB** key and then enter the desired value for the station increment.

This parameter specifies the station increment for the selected survey line. This value is used in conjunction with Start Station to calculate the current station number for display purposes.

After all the parameters in the Survey Setup dialog are updated click on the button **OK** or press **ENTER** key to accept the displayed settings. The program will return to the Main Screen. Updated settings will be written to the initial file and they will be given as default parameters in the subsequent Survey Setup dialog.

To return to original settings (state before this dialog was selected) click on the **Cancel** (X) button or press **Esc** key. All parameters will be reset to initial settings and the program will return to the Main Screen.

3. System Setup

This dialog allows you to specify used type of the instrument, EM61-MK2 antenna size and set several parameters in the logging program. The System Setup dialog is presented below.

🧏 EM61MK2xp		
S EM61-MK2 Setup	Program Set	tings
	ndard 💌 Pause Key	r: any key 💌
S Sensor Size: 1x	0.5 m 💌 Audio:	Yes
S Battery Warning: 10.5	0 Volts Display Un	nits: feet 🔹 📊
Serial Ports EM61-MK2 Port: CO GPS Port: CO		
Leaders in Electro		EM61MK2xp ∨1.00 Geonics Limited

Description of Parameters:

EM61-MK2

This option allows you to select type of used instrument. In the drop-down list box select Standard for the EM61-MK2 or High Power if EM61-MK2 High Power (HP) modification is used.

Sensor Size

The Sensor Size option allows you to select the size of the EM61-MK2 sensor. If the EM61HH-MK2 Hand Held antenna is used this option can be ignored. If the standard antennas are used $(1 \times 0.5 \text{ m}, 1 \times 1 \text{ m}, \text{ or } 0.5 \times 0.5 \text{ m})$ the size of the sensor must be speci-

M61-MK2 Setup		-Program Settings	
EM61-MK2 Type:	Standard 💌	Pause Key:	any key 💌
Sensor Size:	1 × 0.5 m ▼	Audio:	Yes
Battery Warning:	1 x 0.5 m 1 x 1 m 0.5 x 0.5 m	Display Units:	feet
Serial Ports			
EM61-MK2 Port:	COM1 -		
GPS Port:	COM4 -	Cancel	ОК

fied before monitoring the instrument output. Select proper size of the EM61-MK2 sensor in the drop-down list box labeled Sensor Size.

Battery Warning

Specify instrument battery warning level. When the EM61-MK2 battery voltage will reach and drop below specified value the program will display battery voltage on the red background.

EM61 Port

The number of serial port that is assigned to the EM61-MK2. Available selections: COM1 to COM12. The program default is COM1. Communication parameters for the selected serial port are set by the program, since the EM61-MK2 operates at fixed settings: Baud Rate (9600), Parity (N), Data Bits (8), and Bit Stop (1).

This port must be different than the port specified in the list box "GPS Port:" (see below) or in the GPS Port Setup dialog window (see chapter 4), otherwise a message will be displayed and ports will have to be reassigned.

Select port number in the drop-down list box (see Figure below).

-		
Sy	stem Setup	<u>~</u>
	EM61-MK2 Setup	Program Settings
	EM61-MK2 Type: Standard 💌	Pause Key: any key 💌
	Sensor Size: 1 x 0.5 m	Audio: Yes 💌
	Battery Warning: 10.50 Volts	Display Units: feet 💌
	Serial Ports	
	EM61-MK2 Port: COM1 -	
	GPS Port: COM1 COM2 COM2	<u>C</u> ancel <u>O</u> K
	COM4 COM5	
	Leaders in Ele	EM61MK2

GPS Port

The number of serial port that is assigned to the GPS receiver. Available selections: COM1 to COM12. The program default is COM2. Communication parameters for the selected serial port can be set in GPS Port Setup dialog. The GPS port can be also assigned in the latter dialog.

This port must be different than the port specified as the EM61-MK2 serial port.

Select port number in the drop-down list box similarly to EM61-MK2 port assignment procedure.

Pause key

Four selections are available: any key, Space Bar, Enter, and P This feature is used to pause data recording during logging session. Default setting any key can be changed to

M61-MK2 Setup		Program Settings	
EM61-MK2 Type:	Standard 💌	Pause Key:	any key
Sensor Size:	1 x 0.5 m ▼	Audio:	any key <enter></enter>
Battery Warning:	10.50 Volts	Display Units:	<space b<sub="">Nr> <p></p></space>
erial Ports]	
EM61-MK2 Port:	COM2 -		
GPS Port:	СОМ4 -	Cancel	ОК

one of the three specific keys for field conditions where a logger key can be accidentally pushed causing unwanted stop of data logging.

Audio

Two selections are available: Yes or No. The audible click will be generated at each reading when this option is enabled. At fast rate (above 5 readings/s) the sound may appear not uniform, however this does not affect quality of data acquisition.

Display Units

Three selections are available: Meters, Feet or US Survey Feet.

After all the parameters in the System Setup dialog are updated click on the button **OK** or press **ENTER** key to accept the displayed settings. The program will return to the Main Screen. Updated settings will be written to the initial file and they will be given as default parameters in the subsequent System Setup dialog.

To return to original settings (state before this dialog was selected) click on the **Cancel** (or window X) button or press **Esc** key. All parameters will be reset to initial settings and the program will return to the Main Screen.

4. GPS Port Setup & Monitoring

The GPS Port Setup dialog allows for enabling GPS input, and setting communication parameters for serial port associated with GPS input. GPS Monitoring window allows you monitoring the GPS output in terminal mode and to send NMEA commands to GPS receivers.

4.1 GPS Port Setup

After the Set Port for GPS button was clicked on (or executed from the keyboard) in the Main Screen the Set Port for GPS dialog window appears on the screen. This dialog allows you to enable and disable the GPS input, select serial port for GPS input, and to specify serial communication parameters matching GPS receiver settings. The dialog is presented below.

GPS Port Setup		
GPS Input	Enabled	•
Serial Port	COM4:	•
Baud Rate	19200	•
Parity	No	•
Data Bits	8	•
Stop Bits	1	•
Cancel	ОК	2

Description of Options and Parameters:

GPS Input

This option allows you to Enable/Disable a serial port for GPS input. When Disabled is chosen logging and monitoring screens will display message "GPS disabled" in place of GPS parameters.

The GPS Input can be Enabled even if there is no GPS system connected to the computer. In such case data file will contain proper sequence of EM61-MK2 readings without any GPS input.

Clicking on the down arrow next to the text box labeled GPS Input opens a drop-down box showing the available settings, or when the keyboard is used activate the text box by pressing TAB key and then by using up or down arrow keys select one of two available items: Enabled and Disabled.

Serial Port

The number of serial port that is assigned to the GPS input. Available selections: COM1 to COM12. The program default is COM2. Communication parameters for the selected serial port can be determined in options described below.

GPS Port Setup		×
GPS Input	Enabled	-
Serial Port	COM4:	•
	COM1:	
Baud Rate	COM2:	
D '1	COM3: 1	
Parity	COM4:	
Data Bits	COM5:	
Data Dits	COM6:	
Stop Dite	COM7:	
Stop Bits	COM8:	
	COM9:	
	COM10:	
Cancel	COM11:	
17. 	COM12:	

This port must be different than the port specified in the System Setup menu (for EM61-MK2), otherwise a message will be displayed and ports will have to be reassigned. Clicking on the down arrow next to the text box labeled Serial Port opens a drop-down box showing the available ports, or when the keyboard is used activate the text box by pressing TAB key and then by using up or down arrow keys select one of available items.

Baud Rate

Specify Baud Rate for the output port, the selected value should match the Baud Rate of the GPS system, default is 9600. Available settings are: 4800, 9600, 19200, 38400, 57600, and 115200.

GPS Por	t Setup		×
GPS	5 Input	Enabled 💌	
Seri	al Port	COM4: •	
Bau	d Rate	9600 👻	
Pari	ty	4800 9600	
Dat	a Bits	19200 38400 57600	
Sto	o Bits	57600 ^パ 115200	
	Cancel	ОК	

Clicking on the down arrow next to the text box labeled Baud Rate opens a drop-down box showing the available parameters, or when the keyboard is used activate this text box by pressing TAB key and then by using up or down arrow keys select one of available items.

Parity

Select Parity for the output port, the parameter should much the Parity set in the GPS serial port settings. Available settings are None, Even, and Odd; default is N.

Clicking on the down arrow next to the text box labeled Parity opens a drop-down box showing the available parameters, or when the keyboard is used activate this text box by pressing TAB key and then by using up or down arrow keys select one of available items.

Data Bits

Specify Data Bits for the output port, the selected value should much settings in the GPS receiver, default is 8. Other available selection is 7.

Clicking on the down arrow next to the text box labeled Data Bits opens a drop-down box showing the available parameters, or when the keyboard is used activate this text box by pressing TAB key and then by using up or down arrow keys select one of available items.

Stop Bits

Specify Stop Bits for the output port, the selected value should much settings in the GPS receiver, default is 1. Available selections are 1 or 2.

Clicking on the down arrow next to the text box labeled Stop Bits opens a drop-down box showing the available parameters, or when the keyboard is used activate this text box by pressing TAB key and then by using up or down arrow keys select one of available items.

After all the parameters in the GPS Port Setup dialog are updated click on the button **OK** or press **ENTER** key to accept the displayed settings. The program will return to the Main Screen. Updated settings will be written to the initial file and they will be given as default parameters in the subsequent Survey Setup dialog.

To return to original settings (state before this dialog was selected) click on the **Cancel** (X) button or press **Esc** key. All parameters will be reset to initial settings and the dialog window will disappear.

4.2 Monitoring GPS Receiver Output

After the Main Screen command button **GPS Monitoring** is clicked or executed by the keyboard the program will display the GPS Monitoring window in terminal mode. In this mode the screen is divided into three parts. The terminal window in the top portion of the screen displays the GPS receiver output. The middle portion labeled NMEA Command is used to display entered NMEA commands previously sent to the GPS receiver, and at the bottom, command buttons with available options (Pause/Go, Send, and Exit) is displayed. These buttons can be clicked on, executed by TAB key and ENTER keys, or by using shortcuts (pressing underlined letter keys). This screen is shown below.

As soon as the EM61MK2xp screen is in terminal mode and the GPS is streaming data, each message transmitted by GPS receiver will appear in the top portion of the display (the end may be cut off if an NMEA message is longer than screen). The display is updated with the frequency the GPS receiver outputs data. This allows you to recognize the GPS update rate and type of messages being sent by the connected GPS. In cases where the GPS data is not received by the logger a message NO DATA and current time will appear in the top window of the display, as shown below.

The message NO DATA is normally updated with a rate of 7 seconds. This may indicate the following: serial port number not correctly specified in Set Port for GPS dialog, GPS receiver not sending any data, and not working or not connected GPS receiver. If the message is updated more often than 7 seconds (i.e. every 1 or 2 seconds) or the display does not show legible characters, it is possible that the GPS is working correctly and is connected to the proper serial port, however communication parameters are not specified correctly. In most cases the Baud Rate or Parity must be adjusted.

The NO DATA message may also appear if the GPS data are received correctly, but the GPS receiver was set to send data with a time interval longer than 7 seconds. In this case the NO DATA message will be displayed in between GPS messages. This indicates that the GPS is working correctly, however the operator should consider adjustment of the GPS receiver output update rate. Most high resolution geophysical surveys require positioning update of 1 or 2 seconds, and a 5 seconds interval can be used only when the survey is carried out at an even pace and along relatively straight survey lines.

The monitoring display can be stopped any time by using button labeled **Pause**. At that time scrolling of the GPS output will be stopped, and the button will be labeled **Go**. The next click (or keyboard

\$GPGSA,	4,3,30,22,2	0,25,,14,,,01,,,,0	936.64985,W,2,6,1 02.2,01.4,01.7*03 936.64985,W,2,6,1 02.2,01.4,01.7*03				
\$GPGG G	PS Messag	e	OK × 6,1				
topod r	\$PASHS,NI	ME,SAT,A,ON	6,1 03				
\$GPGG \$GPGS \$GPGG	Enter G	PS message to	be send 6,1				
\$GPGG \$GPGSA,/	4,3,30,22,2	0,25,,14,,,01,,,,0	02.2,01.4,01.7*03				
\$PASHS,NME,SAT,A,ON							
Pause		<u>S</u> end	E <u>x</u> it				

action) on this button will activate receiving and display of GPS data.

The button labeled **Send** allows you to send a NMEA command to the GPS receiver. It is preferable if the GPS receiver parameters are set using the GPS manufacturer software or controller (GPS logger or panel keys). However, **when the operator is familiar with NMEA protocol and structure of commands for a given GPS system**, this function can be very convenient and useful when the update rate and enabling or disabling messages in the data stream is required.

After the button **Send** is clicked a dialog titled GPS Message is displayed and the beginning of the standard NMEA command, **\$PASHS**, or the last entered command is displayed. After the entire NMEA command is typed in, click **OK** button or press the key **<ENTER>** to send the command to the GPS receiver. Clicking the **Cancel** button or pressing the **<Esc>** key will cancel the command and hide the NMEA Message dialog. An example of a command that will enable the NMEA message **SAT** is given in the below figure (it is assumed that the GPS receiver output serial port is A).

After this command is received by the GPS receiver, the confirmation message will be send by the receiver (\$PASHR, ACK*3D) and data stream will contain the message SAT (\$PASHR, SAT,.... in the above figure).

Please note, that not every GPS system accepts and uses the same standard set of NMEA commands and messages. In addition, some GPS systems do not accept commands sent by the serial port at all. The configuration of these type of receivers can be updated only by the controlling device (usually GPS logger, controller, or the receiver panel keys).

5. Display Options

After the **Display Options** button was clicked (or executed from the keyboard) in the Main Screen the Setup Display Options dialog window appears on the screen. This dialog allows you to enable and disable the display of each channel profile, specify color and thickness of profiles, and select linear or compressed amplitude for profiles. The dialog is presented below.

	Visible	Color (click to change)	Thickness	
Channel 1	•		2 pixels	•
Channel 2	~		2 pixels	•
Channel 3	~		2 pixels	•
Channel 4/T	~		2 pixels	•
profile display	Amplitudi /, numeric	Linear e affects only real time values and readings ways in linear scale.	OK Cancel	

Description of Options and Parameters:

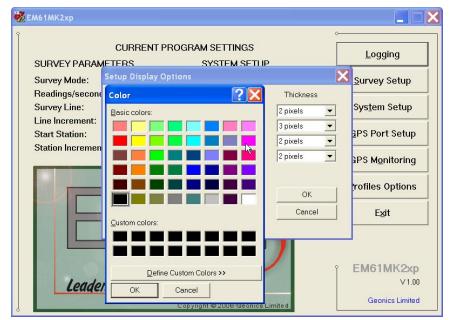
Visible

To enable or disable displaying of each channel profile click on the corresponding button labeled Visible. Profiles of all channels with checked buttons will be displayed during data logging.

Regardless of which channels are chosen to be displayed as profiles, data for all four channels will be displayed in numeric form below profile display.

Color

To change colour of each profile click on the coresponding button (with colour line) labeled **Color (click to change)**. The following dialog titled Color will appear.



Select desired colour by clicking on a colour box (the selected colour box will be high-lighted).

Click on the button **OK** or press **ENTER** key to accept the highlighted colour. The Color dialog will disappear and the colour of the appropriate channel button will updated. To cancel colour selection click **Cancel** (X) button or press **Esc** key.

Thickness

Specify thickness of a profile for a desired channel by using one of four drop-down boxes labeled thickness. Thickness of a profile curve is expressed in pixels. Available settings are: 1, 2, 3, or 4 pixels.

Clicking on the down arrow next to the text box (labeled by number of pixels) opens a dropdown box showing available selection (see Figure below). Select thickness by clicking on the desired selection. If keyboard is used activate text box by pressing TAB key (till the box is highlighted) and then by using up or down arrow keys select one of available items.

	Visible	Color (click to change)	Thickness
Channel 1	~		2 pixels 💌
Channel 2	v		2 pixels 💌
Channel 3	~		1 pixel 2 pixels
Channel 4/T	~]	3 pixels 4 pixels 🛛 😽
Display Amp		Linear	OK
profile displa	y, numeric	e affects only real time values and readings Iways in linear scale.	Cancel

Profile Amplitude

This option allows you to select Linear or Compressed amplitude scale for profiles. The compressed amplitude (squre root function) allows you to display the high dynamic range of the EM61-MK2 data in a legible way and it is recommended.

Clicking on the down arrow next to the text box labeled Profile Amplitude opens a dropdown box showing available parameters, or when keybord is used activate this text box by pressing TAB key and then by using up or down arrow keys select one of available items.

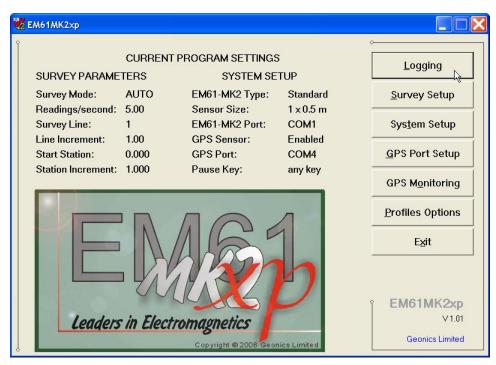
Please note, that readings in numeric form are always given in mV (linear scale) regardless of the Profile Amplitude selection. Further, graphic display in the compressed scale does not affect readings saved in the data file. Data are always written to file in original form.

After all the parameters in the Display Options dialog are updated click the button **OK** or press **ENTER** key to accept the displayed settings. The program will return to the Main Screen. Updated settings will be written to the initial file and they will be given as default parameters in the subsequent Survey Setup dialog.

To return to original settings (state before this dialog was selected) click the **Cancel** (X) button or press **Esc** key. All parameters will be reset to initial settings and the dialog window will disappear.

6. Logging Data

After the **Logging** button (in Main Screen) is clicked or executed by the keyboard, the program enters the logging session which contains three modes: Monitoring, Stand By and Logging. The program starts the logging session always in Monitoring mode. In this mode EM61-MK2 readings



and GPS parameters can be quickly examined and some functions (creating data file, nuling, QC coil check) can be performed. After a data file is created in Monitoring mode, the program switches to Stand By mode and allows access to Logging mode. In Stand By mode instrument output can be monitored and some survey and logging parameters can be changed, and Logging mode is used only to record data. Two modes Stand By and Logging are toggled by **GO** and **Pause** buttons.

6.1 Monitoring Mode

The Monitor mode allows initial inspection of the range of the instrument readings at a particular site, monitoring the instrument performance, quick inspection of the condition of the instrument battery, perform QC Coil check, and setting zero level of the instrument.

It is assumed that the instrument is turned ON prior to using this option. If the instrument is OFF or the instrument console is not connected to the computer the following message shown below will appear.



Check the connection or turn the instrument ON and select the Monitor/Log option again.

Assuming that the instrument works properly the program will display the Monitor mode window and will start normalization session which lasts less than 10 seconds. After the normalization is finished the layout of the Monitor window is as follows:

Ş	EM61MK2xp				
Ŷ	Monitoring	Survey: Auto			2000.0 mV
					L8
	Ch1 [mV]	Ch2 [mV] Ch3 [mV]	Ch4 [mV]	<i>20</i>	0.0 mV
		Normalization: 70 %		Eile	N <u>u</u> ll
	File Parameters File: Tot. Lines: 0	Line Parameters Curr. Line: 1 Station: 0.00		Scale <u>R</u> dgs	Int. QC
	Tot. Stns: 0 Tot. Time: 00:00:0	# of Stns: 0	GPS Disabled	Exit	Ext. QC

The Monitor (as well as Stand by and Logging) window is divided into five sections.

ų	EM61MK2×p					
Ŷ	Monitoring	Survey: Auto	Mode: D	Battery: 12.7 V		2000.0 mV ♀
	Ch1 [mV]	Ch2 [mV]	Ch3 [m∨]	ChT [mV]		0.0 mV
	6052.35	4854.38	6794.84	17840.53	<u>F</u> ile	N <u>u</u> ll
	File Parameters File: Tot. Lines: 0 Tot. Stns: 0	Line Para Curr. Line: Station: # of Stns:	1 0.00	GPS Disabled	Scale <u>R</u> dgs	Int. QC
ļ	Tot. Time: 00:00:01		00:00:00		Exit	<u>Ext. QC</u>

One line of text in the top section provides survey parameters (used in Stand By and Logging modes) and instrument information. In Monitor mode this section displays: instrument mode (4 or D), current display mode (Monitor, Stand By or Logging), Allegro battery level (in % of full charge),

and the EM61-MK2 battery level in Volts (following label B:). When fiducial marker is pressed then M is displayed.

The second, largest graphic section will be used to display profiles during logging data. Numeric labels on the right side of profile window correspond to scale minimum (below the profile window) and maximum (above the profile window).

The remaining bottom section contains a window with current EM61-MK2 readings, three frames (File Parameters, Line Parameters, and GPS information), and command buttons located on the right side of the screen.

If Mode 4 was selected on the instrument panel (it is displayed at the top of the screen) channels 1, 2, 3, and 4 will be displayed under profile window, and when Mode D was selected (for Top and Bottom antennas) channels 1, 2, 3, and T will be given as labels in numeric window. The EM61-MK2 readings are updated approximately 10 times per second during the monitoring session.

When GPS is Disabled in the Set GPS Port dialog a message **GPS Disabled** will be displayed. If the GPS port is Enabled and a working GPS receiver is connected to the field computer the Monitoring screen will display GPS parameters, as presented below.

ą	EM61MK2xp					
9	Monitoring Sur	vey: Auto	Mode: D	Battery: 12.9 V		2000.0 mV 🤉
	Ch1 [mV]	Ch2 [mV]	Ch3 [mV]	ChT [mV]	22	0.0 mV
	-381.91	-301.51	-394.60	-1103.36	<u>F</u> ile	Null
	File Parameters File: Tot Lines: 0	Line Par Curr. Line: Station:		Positions: 0 DGPS • PDOP: 1.7 Sat 8	Scale <u>R</u> dgs	Int. QC
	Tot. Stns: 0 Tot. Time: 00:00:00	# of Stns: Time:	2 2 2 2 3 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	Lat: N43ø36'35.5920" Lon: W079ø36'39.0378"	Exit	<u>E</u> xt. QC

In the above Figure one line of the display is dedicated to show the GPS status. A label **Positions** will be used during data acquisition, it will provide the number of GPS positions saved in the data file. Below, two lines display the parameters describing the quality of GPS positions. A label **DGPS** (Differential Global Positioning System) indicates that GPS readings are differentially corrected in real time, while label **AGPS** (Autonomous Global Positioning System) indicates lack of differential correction. On the right side of **DGPS** or **AGPS** label two green and white circles alternate. These two circles should alternate colours with the frequency of GPS update rate (usually 1 second intervals). If the circles do not change colours for long periods of time it means that the GPS system is not working or that it is not connected to the field computer. The next label **PDOP** with a value varying between 0 and 99.9 represents an index called Position Dilution of Precision (**PDOP**). This value is available only when messages both, GGA and GSA are received from GPS. The last label **Sat** and following number shows number of currently tracked satellites. Refer to section 4 (Set Port for GPS), Appendix B, and to GPS manuals for more information about GPS parameters. Two

bottom lines of the frame give current Latitude and Longitude of the instrument position (datum WGS1984). Position is updated with frequency of GPS receiver stream.

Six command buttons located in the right bottom corner of the Monitor window lists the program functions available directly in the Monitor mode. Available options are as follows: **File** (create data file), **Scale Readings** (change scale for EM61-MK2 readings in profile window), **Exit** (exits the Monitor mode and returns the program to Main Screen, **Null** (perform nulling function), **Int. QC** (internal QC-coi calibration), **Ext.QC** (external QC-coil calibration).

In case of any problems with instrument connection, battery failure, or accidental instrument Turn Off a message "No Communication, trying" will be displayed in numeric values window. The message is highlighted by red background to alert operator as fast as possible. The EM61MK2xp will try to re-establish communication and after the problem is corrected the program will start communication automaticaly. Alternatively, the Monitor mode can be stopped by clicking on the Exit button or executing this function by a keyboard. The Monitoring window with alerting message is shown below.

🐱 EM61MK2xp					
° Monitoring	Survey: Auto	Mode: D	Battery: 12.7 V		5000.0 mV
				~~~~	
				ß	
Ch1 [mV]	Ch2 [mV]	Ch3 [mV]	ChT [mV]		-1000.0 mV
	No connect	ion, trying		<u>F</u> ile	N <u>u</u> ll
File Paramete		rameters	Positions: 0	Carda Dalara	
File: Tot. Lines: 0	Curr. Line Station:	e: 3.00 206.00	DGPS • PDOP: 7.7 Sat 5	Scale <u>R</u> dgs	Int. QC
Tot. Stns: 0	# of Stns	: 0	Lat: N43ø36'35.6820"	Exit	<u>E</u> xt. QC
Tot. Time: 00:0	0:00 Time:	00:00:00	Lon: W079ø36'39.0162''		

**Description of Monitoring Mode Options** 

**Cr.File** (create data file)

The log data file can be created in any directory. The name of the file is given by the field computer clock and it consists of month (2 digits), day (2 digits), hour (2 digits), and one alphabetic character A, B, C, etc. (If all letters during one hour are used use the Overwrite option). The Create Data File dialog is presented below.

The file name can be specified in the Create Data File dialog using the Windows standard interface procedure. The EM61MK2xp data files cannot be appended.

Each data file in the field computer (raw data file) has an extension name R61 and it is created in the directory specified in Create Data File dialog. The R61 files are created in the

Save in:	🥪 Local Disk (C:)		• 🗧 🖆 📰 🔻	
My Recent Documents Desktop My Documents My Computer	Corel DELL Documents and Settings Drakar Stack Dev Files EM68Report EPSON EPSONREG HyperCD Inetpub Inetpub MultTestFiles My Documents My Documents My Documents My Documents My Documents My Documents My Music	ProgramsGeomar ProgramsGeonics Cublications Cafal Cont TEMPBTH TEMPPCI TEMPPCI TestGeomar WIESIO WINDOWS WINDOWS U121409A.R61 U121910A.R61	<ul> <li>121910B.R61</li> <li>121911A.R61</li> <li>121911B.R61</li> <li>122006B.R61</li> <li>122006B.R61</li> <li>122009B.R61</li> </ul>	
My Network Places	File name: 122214 Save as type: EM61M	4 1K2 Files (*.R61)	<b>▼</b>	Sav

instrument binary format. These files can be also converted to ASCII format and processed in the Geonics DAT61MK2 program.

After the file is specified click on the button **OK** or press **ENTER** key to accept and create data file. The program will switch Monitor mode to Stand By mode and the data file will be displayed on the screen.

To cancel selection and return to Monitoring mode tap the Cancel (X) button or press Esc key.

#### Null

To perform a null of the instrument click on the button labeled **Null** or execute this option using the keyboard (navigate to the button by pressing **TAB** key and when highlighted press **ENTER** key, or use shortcut - press key **U**). At this moment the computer takes 50 readings and calculates the instrument offset.

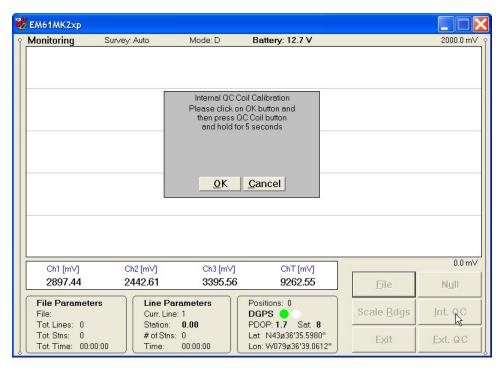
Ş	EM61MK2×p					
Ŷ	Monitoring Su	rvey: Auto	Mode: D	Battery: 12.7 V		2000.0 mV_ o
	Ch1 [mV]	Ch2 [mV] Nulling: 15 of !	Ch3 [mV] 50	ChT [mV]	<u>F</u> ile	0.0 m∨ N <u>u</u> ll
	File Parameters File: Tot Lines: 0	Line Para Curr. Line: 1 Station: 0		Positions: 0 DGPS • PDOP: 1.7 Sat: 8	Scale <u>R</u> dgs	Int. QC
	Tot. Stns: 0 Tot. Time: 00:00:00	# of Stns: 0	Sec. 2007	Lat: N43ø36'35.5932'' Lon: W079ø36'39.0540''	Exit	<u>E</u> xt. QC

The calculated offset is applied to all the readings that follow this operation. If needed, this procedure can be repeated several times until satisfactory results are obtained. However, there is no associated "Undo" function. If original values (without calculated offsets) of the EM61-MK2 readings are needed, exit the EM61MK2 program and run it again. The EM61-MK2 instrument does not have to be turned OFF. Null operation can be also performed later during data collection.

#### Int.QC (Internal QC Coil Calibration)

The Internal QC coil calibration is described in detail in the EM61-MK2 Operating Instructions.

To start the calibration using Internal QC coil click on the key labeled **Int. QC** or execute this option by keyboard (navigate to the button by pressing **TAB** key and when highlighted press **ENTER** key, or use shortcut - press key **I**). This action begins by performing the automatic nulling which in this case is only in effect for the duration of the calibration process. It will not affect EM61-MK2 readings. After the nulling is completed (less than 5 seconds) the Internal QC coil Calibration window is displayed. All command buttons in the bottom right corner of logging windows are disabled during Calibration procedure.



When Calibration window is displayed please use keyboard keys (O or C) rather than a mouse to execute buttons labeled OK and Cancel. Clicking on buttons by mouse will work, however several mouse button clicks may be required.

After **OK** button is clicked (or shortcut key **O** is pressed) the window displays timer with elapsed seconds and EM61-MK2 readings. This display lasts for 60 seconds. During this time please follow the instructions provided on the Allegro screen.

Ş	EM61MK2xp					
Ŷ	Monitoring Su	urvey: Manual	Mode: 4	Battery: 12.3 V		6000.0 mV
			Waiting for Ca (you may can	Coil Calibration libration values cel at any time)		
3 of 60						
	Ch1 [mV]         Ch2 [mV]         Ch3 [mV]         Ch4 [mV]					0.0 mV
	-10.34	7.03	1.50	-3.57	<u>F</u> ile	N <u>u</u> ll
	File Parameters File: Tot. Lines: 0	Line Pa Curr. Line Station:	rameters :: 1.00 0.00	Positions: 0 DGPS • PDOP: 2.9 Sat: 6	Scale <u>R</u> dgs	Int. QC
	Tot. Stns: 0 Tot. Time: 00:00:00	# of Stns: Time:	: 0 00:00:00	Lat: N43ø36'35.6154'' Lon: W079ø36'39.0780''	E <u>x</u> it	<u>E</u> xt. QC

Internal QC coil calibration can end in the following four ways:

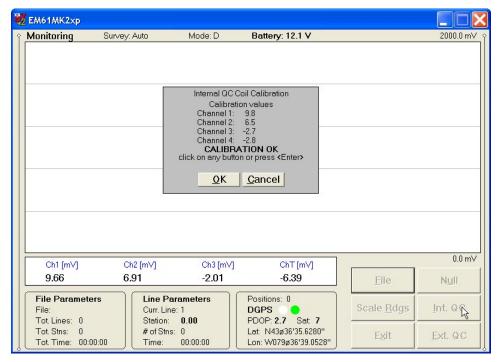
The process can be stopped by an operator at any time by clicking on the **Cancel** button or pressing shortcut key **C**.

The calibration may end by time out (60 seconds) if QC coil button was not pressed or this action did not activate QC coil. The following screen will then be displayed:

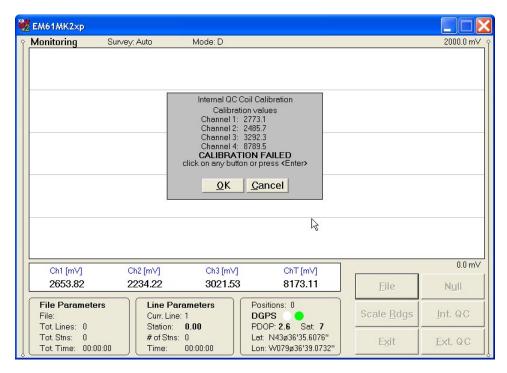
EM61MK2×p					
Monitoring	Survey: Manual	Mode: 4			6000.0 m∖
		Internal QC Ci	oil Calibration		
CALIBRATION TIME OUT					
<u>OK</u> <u>Cancel</u>					
Ch1 [mV]	Ch2 [mV]	Ch3 [mV]	Ch4[mV]		0.0 m ^v
11.56	-13.56	-7.60	-4.43	Eile	N <u>u</u> ll
File Paramet	Curr. Lini		Positions: 0 DGPS	Scale <u>R</u> dgs	Int. QC
Tot. Lines: 0 Tot. Stns: 0	Station: # of Stns		PDOP: <b>2.9</b> Sat. <b>6</b> Lat: N43ø36'35.6034''	Exit	Ext. Q.C

After pressing any key the program returns to Monitoring window. To repeat Internal QC coil calibration please click on the **Int. QC** button again.

The logging program will determine if the instrument has passed test. If after activating the QC coil, the program determines that the reading is inside the standard values within +/- 10% tolerances then a message "CALIBRATION OK" will be displayed (see below).



Otherwise, if the program determines that the reading is outside of the test values range the corresponding message "CALIBRATION FAILED" is displayed.



Regardless of the test result (OK or FAILED) the readings will be saved on screen. The program returns to Monitoring window after any button is tapped or ENTER key is pressed. Then the Internal QC coil calibration process can be repeated.

#### **Ext. QC** (*External QC Coil Calibration*)

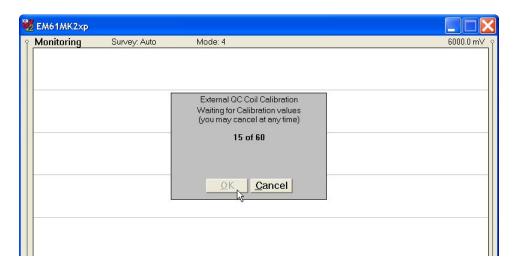
The External QC coil calibration is described in detail in the EM61-MK2 Operating Instructions.

To start the calibration using the External QC coil tap the button labeled **Ext. QC** or execute this option by keyboard (navigate to the button by pressing **TAB** key and when highlighted press **ENTER** key, or use shortcut - press key **E**). This action begins by performing the automatic nulling which in this case is only in effect for the duration of the calibration process. It will not affect EM61-MK2 readings. After the nulling is completed (less than 5 seconds) the External QC coil Calibration window is displayed (Figure below).

ų	EM61MK2xp					
Ŷ	Monitoring S	lurvey: Auto	Mode: 4	Battery: 12.3 V		6000.0 mV
	External QC Coil Calibration Please click on OK button and then press QC Coil button and hold for 5 seconds					
					_	0.0 mV
	Ch1 [mV]	Ch2 [mV]	Ch3 [m∨]	Ch4 [mV]		1
	-3.12	1.56	1.95	0.59	<u>File</u>	N <u>u</u> ll
	File Parameters File: Tot Lines: 0	Line Pa Curr. Line Station:		Positions: 0 DGPS • PDOP: 2.9 Sat 6	Scale <u>R</u> dgs	Int. QC
	Tot. Stns: 0 Tot. Time: 00:00:00	# of Stns		Lat: N43ø36'35.5998" Lon: W079ø36'39.0732'	Exit	<u>E</u> xt. QC

When Calibration window is displayed please use keyboard keys (O or C) rather than a mouse to execute buttons labeled OK and Cancel. Clicking on buttons by mouse will work, however several mouse button clicks may be required.

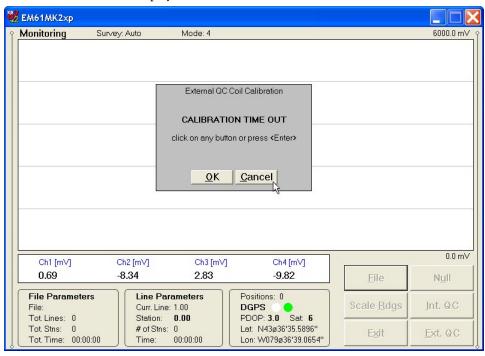
After **OK** button is tapped (or shortcut key **O** is pressed) the window displays timer with elapsed seconds and EM61-MK2 readings. This display lasts for 60 seconds. During this time please follow the instructions provided on the Allegro screen.



External QC coil calibration can end in the following four ways:

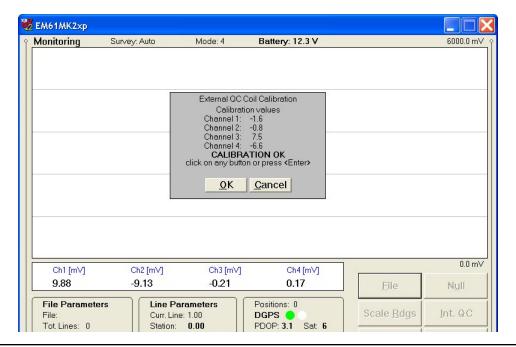
The process can be stopped by an operator at any time by tapping **Cancel** button or pressing shortcut key **C**.

The calibration may end by time out (60 seconds) if the External QC coil button was not pressed or this action did not activate QC coil. The following window will then be displayed (see below).



After pressing any key the program returns to Monitoring window. To repeat External QC coil calibration please tap the **Ext. QC.** button again.

The logger will determine if the instrument has passed test. If after activating the QC coil, the program determines that the reading is inside the standard values within +/- 10% tolerances then a message "CALIBRATION OK" will be displayed.



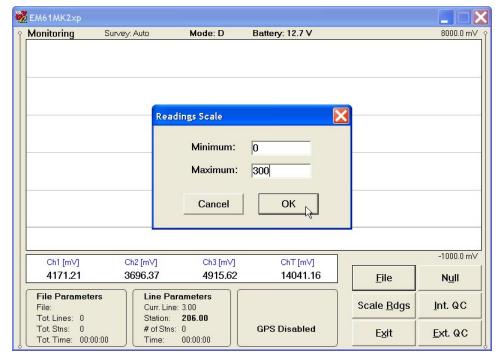
Otherwise, if the program determines that the reading is outside of the test values range the corresponding message "CALIBRATION FAILED" is displayed.

ų,	EM61MK2xp					
Ŷ	Monitoring S	lurvey: Auto	Mode: 4	Battery: 12.6 V		6000.0 mV
			Calibratio Channel 1: - Channel 2: - Channel 3: - Channel 4: - <b>CALIBRATI</b>	oil Calibration on values 8939.8 7941.4 10056.8		
	Ch1 [mV]	Ch2 [mV]	Ch3 [mV]	Ch4 [mV]		0.0 mV
	2760.71	2679.97	3360.76	3354.12	Eile	Null
	File Parameters File: Tot. Lines: 0	Line Pa Curr. Line Station:	rameters e: 1.00 0.00	Positions: 0 DGPS PDOP: 3.1 Sat: 6	Scale <u>R</u> dgs	Int. QC
	Tot. Stns: 0 Tot. Time: 00:00:00	# of Stns		Lat: N43ø36'35.5602" Lon: W079ø36'39.0516	. Exit	Ext. QC

Regardless of the test result (OK or FAILED) the readings will be saved on screen. The program returns to Monitoring window after any button is clicked or ENTER key is pressed. Then the External QC coil calibration process can be repeated.

Scale (New Scale for Profile Plot)

Selecting New Scale option allows the operator to enter new scale parameters for the profile plot. This option is available by clicking on the command button labeled Scale Rdgs. or directly from keyboard by using shortcut key  $< \mathbf{R} >$ .



The Readings Scale dialog will be displayed. It contains two text boxes for Minimum and

Maximum values of a new scale for profile plot. Current settings (minimum and maximum values) for the scale are displayed in the bottom right and top right corners of the plot area.

After minimum and maximum values are specified click on the button **OK** or press **ENTER** key to accept to accept new values and the profile plot area will be redrawn.

To ignore an entry and return to Stand By mode click on the **Cancel** (X) button or press **Esc** key, the dialog window will disappear and measurements can be continued.

Exit (exit Monitor mode)

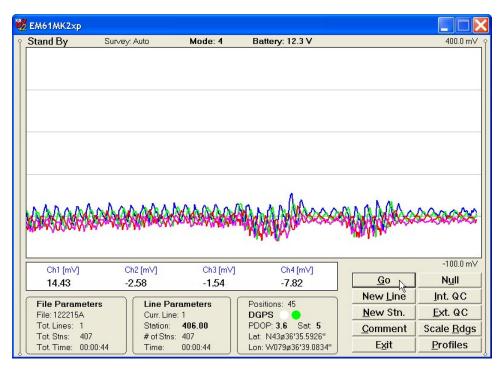
After clicking on the Exit button (or executing this option using keyboard) the program immediately returns to Main Screen.

### 6.2 Stand By Mode

After data file is created in Monitoring mode the program automatically switches logging window to Stand By mode. This windows is similar to Monitor mode however it contains survey parameters (file name, survey line name, etc.) and different set of options represented by buttons displayed at the bottom of the screen. The logging window in Stand By mode in initial state (before any data is recorded) is presented below.

Ð,	2 EM61MK2xp					
Ŷ	Stand By Sur	vey: Auto	Mode: 4	Battery: 12.3 V		2000.0 mV
	Ch1 [mV]	Ch2 [mV]	Ch3 [mV]	Ch4[mV]		0.0 mV
	-3.28	0.51	-0.64	-21.20	<u>G</u> o	N <u>u</u> ll
				Desilianas 0	New Line	Int. QC
	File Parameters File: 122215A	Curr. Line:		Positions: 0 DGPS	New Stn.	Ext. QC
	Tot. Lines: 1 Tot. Stns: 0		0.00	PDOP: 3.2 Sat 6 Lat: N43ø36'35.5602"	Comment	Scale <u>R</u> dgs
	Tot. Time: 00:00:00		00:00:00	Lon: W079ø36'39.0894"	Exit	Profiles

The main portion of the screen is occupied by the plot area which displays profiles (see Figure below which shows Stand By mode after some data were collected). Readings in the plot area can be displayed in compressed amplitude scale, which corresponds to Square Root of the amplitude. In compressed amplitude scale 0 to 100 corresponds to 0 to 10,000 mV, and compressed range 0 to 200 corresponds to 0 to 40,000 mV. Plotting data in compressed amplitude allows you to show details in the low range of amplitude, as well as relatively good resolution in the high range of data on the small screen. Please note, that data displayed in the numeric form are always given in the standard, linear scale. The amplitude scale is divided by four or five grey grid lines. In the case where the amplitude scale starts with a negative value, then the grid line corresponding to zero is always plotted as a thicker line.



Readings for Channels 1, 2, 3, 4 or T are shown in numeric form in a window below the plot area. Values of readings are labeled: **Ch1**, **Ch2**, **Ch3**, **Ch4** or **ChT**. The program checks instrument mode continuosely, therefore label **Ch4** indicates mode 4 while label **ChT** corresponds to instrument mode **D**. EM61-MK2 readings (in numeric form) are updated in Stand By mode approximately 10 times per second. Profiles in the plot area are updated only during Logging mode when data are actually saved in the data file.

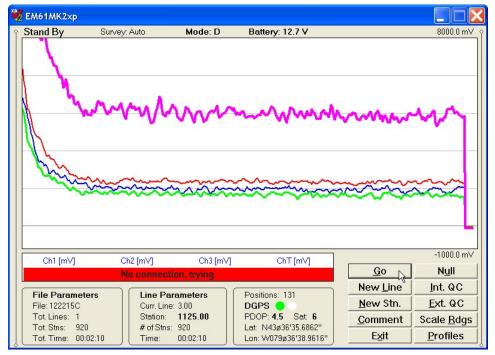
A section of the window at the top of the screen contains one line of text displaying survey and instrument related parameters. These are (from top left): logging mode **Stand By** or **Logging**, survey mode (**Auto**, **Wheel** or **Manual**), instrument mode 4 or **D** (labeled Mode:)), and EM61-MK2 battery level in Volts (labeled **Battery:**). When fiducial marker is active a label **Marker** is displayed in this line.

File and Survey Line parameters, and GPS information are displayed in three framed boxes at the bottom of the Stand By window. File Parameters frame displays: name of the data file, total number of survey lines, total number of stations collected in the file, and total time of surveying. The Line Parameters frame contains: name of current survey line, current station, number of stations in the current survey line, and time of surveying current line. In the Stand By mode the station number will not change. Stations in the EM61MK2xp program are incremented by station increment value after each reading is written to the data file.

The third frame is dedicated to showing the GPS status. A number following the label **Position** provides the number of GPS positions saved in the current data file. In Stand By mode the number of positions is not incremented (it is updated only when GPS position is written to the file). Next two lines in this frame display parameters describing quality of GPS positions. A label **DGPS** (Differential Global Positioning System) indicates that GPS readings are differentially corrected in real time, while label **AGPS** (Autonomous Global Positioning System) indicates lack of differential correction. On the right side of **DGPS** or **AGPS** label two green and white circles alternate. These two circles should alternate colours with the frequency of GPS update rate (usually 1 second intervals). If the circles do not change colours for long periods of time it means that the GPS system is not working or that it is not connected to the field computer. The next label **PDOP** with a value

varying between 0 and 99.9 represents an index called Position Dilution of Precision (**PDOP**). This value is available only when messages both, GGA and GSA are received from GPS. The last label **Sat** and following number shows the number of currently tracked satellites. Two bottom lines of the frame give current Latitude and Longitude of the instrument position (datum WGS1984). Position is updated with frequency of GPS receiver stream.

In case of any problems with instrument connection, battery failure, or accidental instrument Turn Off a message "No Communication, trying" will be displayed in numeric values window. The message is highlighted by red background to alert operator as fast as possible. The EM61MK2xp will try to re-establish communication and after the problem is corrected the program will start communication automaticaly. Alternatively, click on the Exit button or execute this command from a keyboard. The program window in Stand By mode and the alert message is shown below.

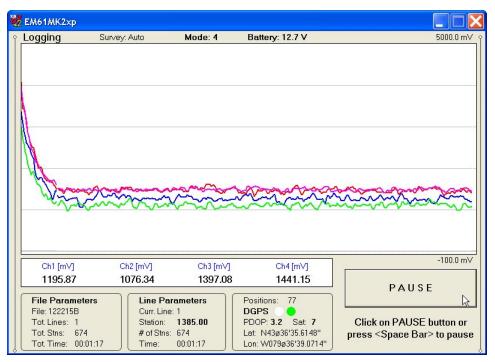


Several available field options (in form of command buttons) are listed at the bottom right corner of the Stand By mode window. They will be described in the following section 6.4.

# 6.3 Logging Mode

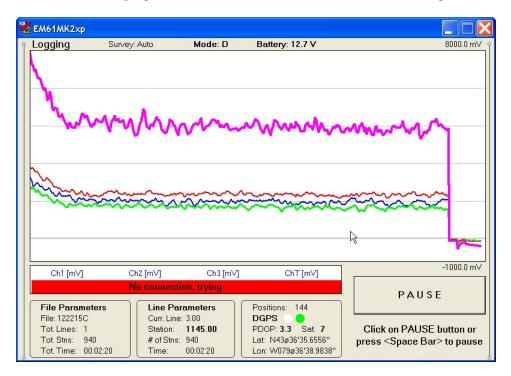
The Logging mode is enabled by clicking on the button labeled **GO** (**log data**) or pressing the shortcut key **G** (or the **<ENTER>** key if button **GO** is highlighted) in Stand By mode. After this button is pressed the list of buttons at bottom of the screen will be replaced by one **PAUSE** button, label Stand By will be replaced by label **Logging** (at the top of the display) and data will be logged in the mode corresponding to the selected EM61-MK2 mode in the Survey Setup menu. All labels and parameters (with the exception of buttons representing Stan By mode options) are the same as in Stand By mode and they are described in the preceding section 6.2. The screen in Logging mode is presented below.

After the screen changes to Logging mode the current station (labeled **Station**:) is updated according to the station interval. Similarly, if GPS Input was enabled, total number of GPS positions (label **Positions**) in the data file is incremented every time (usually once a second) GPS position is written



to the file. Profile curves (for channels selected in Display Options window) are updated after each reading is written to the data file.

In case of any problems with instrument connection, battery failure, or accidental instrument Turn Off a message "No Communication, trying" will be displayed in numeric values window. The message is highlighted by red background to alert operator as fast as possible. The EM61MK2xp will stop collecting data and will try to re-establish communication. After the problem is corrected the program will start communication automaticaly. Alternatively, click on the Pause button to return to Stand By mode. The program window in Stand By mode and the alert message is shown below.



There is only one option available in the Logging mode - pause logging. After a Pause button is clicked or Pause key (any key or other Pause Key selected in Logger Setup window) is pressed the recording is stopped and the Logging mode returns to the Stand By mode. In Stand By mode the EM61-MK2 data will be displayed with the update rate approximately 10 readings per second, however data will not be saved in the log file and profile curves will be not updated.

Exiting from the logging session and access to various field options are available only from the logging window in Stand By mode.

# 6.4 Stand By Mode Field Options

Several field options are available while the Logging window is in the Stand By mode. Options can be accessed directly from command buttons. Command buttons can be used by clicking on the desired button, or from the keyboard by pressing one of the shortcut keys (underlined characters on button labels) or by navigating using **<TAB>** key (sets button as a default button - default button is highlighted) and pressing **<ENTER>** key.

## GO (log data) (start data logging)

Click on the **GO** button, or while using the keyboard press shortcut key <**G**> or if the button is a default button (highlighted) press <**ENTER**>. The logging window in Stand By mode will change to Logging mode and logging data starts immediately.

### New Line (New Survey Line)

The New Survey Line dialog is displayed (see Figure below). Selecting this option allows the operator to enter a new survey line number (name) and associated line parameters (Line Increment, Line Sequence, Direction, Start Station, and Station Increment). The new line number and associated parameters are prompted by the program based on parameters specified in the Survey Setup dialog.

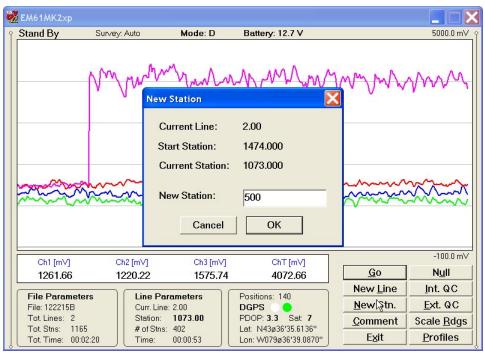
6	EM61MK2xp										
Ŷ	Stand By Su	rvey: Auto	Mode: 4	Ba	attery: 12.7 V			5000.0 mV			
		Ne	w Survey Line			X					
			Current Line: Last Station:		1 1474.000						
			New Line Line Increment		2.00						
		***	Line Sequence Line Direction	.	Alternate South	•	~~~~~				
			Start Station Station Increm		1474.000 -1.000	_					
	Ch1 [mV]	Ch2 [r			1	_		-100.0 mV			
	1142.06	1068		Cance	і ок	R	<u>G</u> o	N <u>u</u> ll			
	File Parameters		Parameters	( Pos	itions: 87	) -	New Line	Int. QC			
	File: 122215B		Line: 1	DG			<u>N</u> ew Stn.	<u>E</u> xt. QC			
	Tot. Lines: 1	Statio			DP: 3.3 Sat: 7		<u>Comment</u>	Scale <u>R</u> dgs			
	Tot. Stns: 763 Tot. Time: 00:01:27	# of S Time	Stns: 763 :: 00:01:27		N43ø36'35.6280 : W079ø36'39.04	Concerne 1	Exit Profiles				

At the top of the dialog the last survey line name and the last logged station are displayed. Default name for the new line is given based on the Line Increment parameter. The default Start Station, direction of the Station Increment, and Direction are determined based on Sequence selection. All these parameters can be overwritten by the user as described in the Survey Setup menu description (chapter 2).

After all the parameters in the New Line dialog are updated click on the button **OK** or press **ENTER** key to accept the displayed settings. The program will return to the Logging window in Stand By mode. Survey line name (**Curr. Line**) name and current station (**Station**) value will be updated and profile curves plot for former survey line will disappear. To return to Stand By mode and current survey line settings (state before this dialog was selected) click on the **Cancel** (X) button or press **Esc** key.

#### New Stn. (New Station)

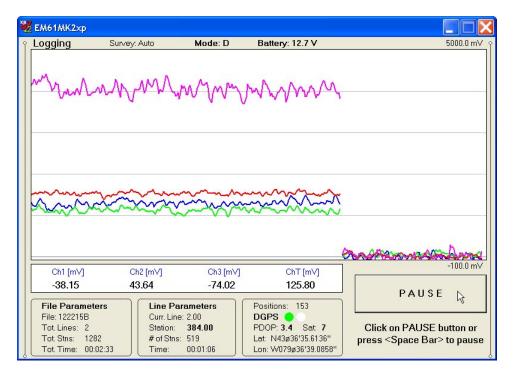
Selecting this option allows the operator to enter a new station number (within the same survey line). The New Station dialog is displayed.



Current survey line, Start and Current station are displayed at the top of the dialog. The New Station can be entered in the provided edit box labeled New Station.

Click on the button **OK** or press **ENTER** key to accept the new value. The program will return to the Logging window in Stand By mode. Current station (**Station**:) value will be updated and after data logging is activated the profile curves will have a small gap (two pixels) showing the new station entry (see Figure below).

To return to Stand By mode and current survey line settings (state before this dialog was selected) click on the **Cancel** (X) button or press **Esc** key, the dialog window will disappear and measurements can be continued.



#### **Comment** (Field Comment)

Selecting this option allows the operator to enter a comment at any point of the survey. A maximum of 11 characters can be entered as a comment. The Enter Comment dialog is displayed.

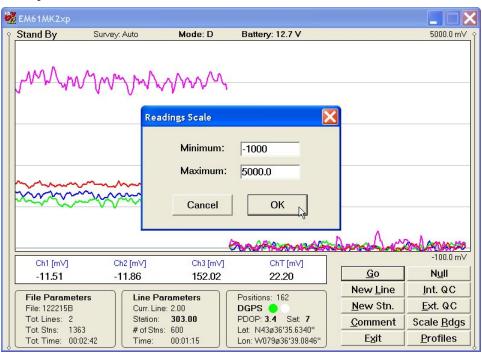
🧏 EM61MK2xp											
Y Stand By Stand By	Survey: Auto	Mode: D	Battery: 12.7 V		5000.0 mV γ						
many	man	$\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma\gamma$									
	Enter Com	ment									
	End of	End of fence									
haven		Maximum 11 characters									
xxxxxx	₩.	Cancel									
			2000 March Contraction	Ama	-100.0 mV						
Ch1 [mV]	Ch2 [mV]	Ch3 [mV]	ChT [mV]								
93.28	132.65	27.37	182.57	<u>G</u> o	N <u>u</u> ll						
File Parameters		rameters	Positions: 162	New Line	Int. QC						
File: 122215B	Curr. Line		DGPS	<u>N</u> ew Stn.	<u>E</u> xt. QC						
Tot. Lines: 2	Station:	303.00	PDOP: 3.4 Sat. 7	Comment	Scale Rdgs						
Tot. Stns: 1363 Tot. Time: 00:02:42	# of Stns	00:01:15	Lat: N43ø36'35.6304'' Lon: W079ø36'39.0612''	Exit	Profiles						

Click on the button **OK** or press **ENTER** key to accept the comment entered in a text box of the dialog. The text of the comment is saved in the file with a corresponding time stamp and the program will return to the Logging window in Stand By mode.

To ignore an entry and return to Stand By mode click on the **Cancel** (X) button or press **Esc** key, the dialog window will disappear and measurements can be continued.

## Scale Rdgs (New Scale for Profile Plot)

Selecting New Scale option allows the operator to enter new scale parameters for the profile plot.



The Enter Scale dialog will be displayed. It contains two text boxes for Minimum and Maximum values of a new scale for profile plot. Current settings (minimum and maximum values) for the scale are displayed in the bottom right and top right corners of the plot area. After minimum and maximum values are specified click on the button **OK** or press **ENTER** key to accept new values and the profile plot area will be redrawn (see Figure below).



To ignore an entry and return to Stand By mode tap the **Cancel** (X) button or press **Esc** key, the dialog window will disappear and measurements can be continued.

#### **Profiles** (new options for profile plot display)

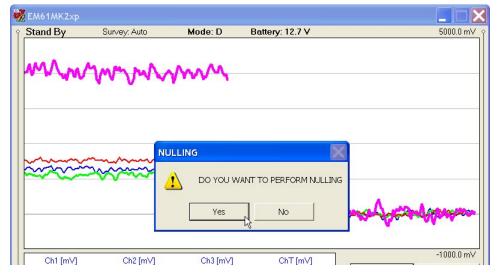
After the **Profiles** button was clicked or executed from the keyboard the Display Options dialog window appears on the screen. This dialog allows you to enable and disable the display of each channel profile, specify color and thickness of profiles, and select linear or compressed amplitude for profiles. The dialog is presented below.

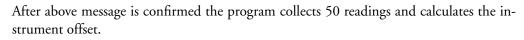
🐱 EM61MK2xp						
Stand By     Stand By	Survey: Auto	Mode: D	Battery: 12.7	۷		5000.0 mV
mmm	Setup Displa	y Options				
		Visible Color (cl	lick to change)	Thicknes	s	
	Channel 1	v		2 pixels	<b>•</b>	
	Channel 2	V		3 pixels	-	
	Channel 3	v		2 pixels	-	
and the second	Channel 4/T	<b>v</b>	- Ç			
		Amplitude affects o		ОК	_ 🚧	maggioren
0115-114		/, numeric values ar file are always in lir		Cance		-1000.0 mV
Ch1 [m∨] 13.85	-62.67	57.47	-259.	12	Go	Null
File Parameter		arameters	Positions: 163	New Line	Int. QC	
File: 122215B	S Line Pa		DGPS		<u>N</u> ew Stn.	<u>E</u> xt. QC
Tot. Lines: 2	Station:			at 6	Comment	Scale <u>R</u> dgs
Tot. Stns: 1370 Tot. Time: 00:02	:43 # of Stn Time:	s: 607 00:01:15	Lat: N43ø36'35 Lon: W079ø36'3	Exit	Profiles	

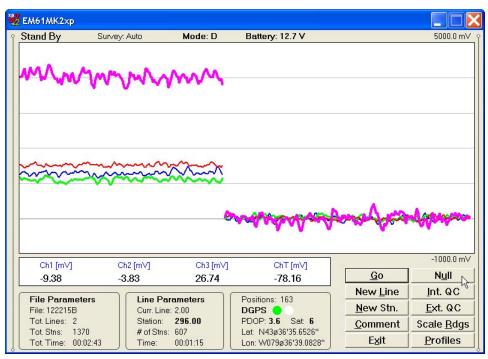
Please refer to chapter 5 where this dialog and its parameters are described in detail. Click on the button **OK** or press **ENTER** key to accept updated display parameters. The dialog will disappear and profile plot area will be redrawn in Stand By mode. To return to Stand By mode and current display options (state before this dialog was selected) click on the **Cancel** (X) button or press **Esc** key, the dialog window will disappear.

#### Null

During data collection (in Stand By mode) a confirmation message will be displayed (there is no such message if Nulling is performed in Monitoring mode) before actual operation is applied.







The calculated offset is applied to all the readings that follow this operation. If needed, this procedure can be repeated several times until satisfactory results are obtained. However, there is no associated "Undo" function. If original values (without calculated offsets) of the EM61-MK2 readings are needed, exit the EM61MK2 program and run it again. The EM61-MK2 instrument does not have to be turned OFF.

#### Int. QC (Internal QC coil calibration)

The Internal QC coil calibration is described in detail in the EM61-MK2 Operating Instructions.

The Internal QC coil procedure in Stand By mode is identical as in Monitoring mode. The Please refer to section 6.2 (Description of Monitoring Mode Options) for more screen shots examples.

To start the calibration using Internal QC coil click on the key labeled **Int. QC** or execute this option by keyboard (navigate to the button by pressing **TAB** key and when highlighted press **ENTER** key, or use shortcut - press key **I**). This action begins by performing the automatic nulling which in this case is only in effect for the duration of the calibration process. It will not affect EM61-MK2 readings dueing later data collection. After the nulling is completed (less than 5 seconds) the Internal QC coil Calibration window is displayed. All command buttons in the bottom right corner of the logging window in Stand By mode are disabled during Calibration procedure.

When Calibration window is displayed please use keyboard keys (O or C) rather than a mouse to execute buttons labeled OK and Cancel. Clicking on buttons by mouse will work, however several mouse button clicks may be required.

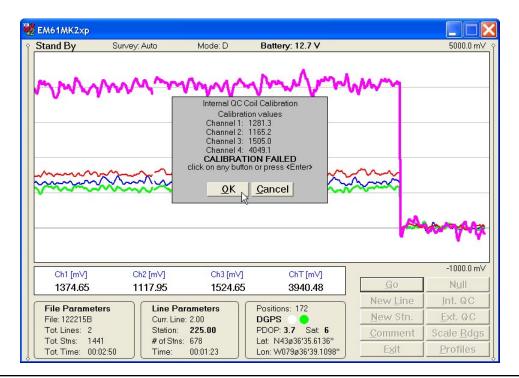
😻 EM61MK2xp					
	Survey: Auto	Mode: D	Battery: 12.7 V		5000.0 mV γ
	<b>^^^^</b>	Internal QC Ci Please click or then press Q and hold for	OK button and C Coil button		vortuta
Ch1 [mV]	Ch2 [m√]	Ch3 [mV]	ChT [mV]		-1000.0 mV
1257.70	963.78	1598.03	3809.57	<u>G</u> o	N <u>u</u> ll
			D V 170	New Line	Int. QC
File Paramet File: 122215B	ers   Line P Curr. Lir	arameters	Positions: 172	New Stn.	<u>E</u> xt. QC
Tot. Lines: 2	Station:	225.00	Comment	Scale <u>R</u> dgs	
Tot. Stns: 14 Tot. Time: 00:		s: 678 00:01:23	Lat: N43ø36'35.6040'' Lon: W079ø36'39.1068''	Exit	Profiles

After **OK** button is clicked (or shortcut key **O** is pressed) the window displays timer with elapsed seconds and EM61-MK2 readings. This display lasts for 60 seconds. During this time please follow the instructions provided on the Allegro screen.

Internal QC coil calibration can end in the following four ways:

The process can be stopped by an operator at any time by clicking on the **Cancel** button or pressing shortcut key **C**.

The calibration may end by time out (60 seconds) if QC coil button was not pressed or this action did not activate QC coil.



After pressing any key the program returns to Monitoring window. To repeat Internal QC coil calibration please click on the **Int. QC** button again.

The logging program will determine if the instrument has passed test. If after activating the QC coil, the program determines that the reading is inside the standard values within +/- 10% tolerances then a message "CALIBRATION OK" will be displayed.

Otherwise, if the program determines that the reading is outside of the test values range the corresponding message "CALIBRATION FAILED" is displayed (see Figure above).

Regardless of the test result (OK or FAILED) the readings will be saved on screen. The program returns to Monitoring window after any button is tapped or ENTER key is pressed. Then the Internal QC coil calibration process can be repeated.

**Ext. QC** (*External QC Coil Calibration*)

The External QC coil calibration is described in detail in the EM61-MK2 Operating Instructions.

The External QC coil procedure in Stand By mode is identical as in Monitoring mode. The Please refer to section 6.2 (Description of Monitoring Mode Options) for more screen shots examples.

To start the calibration using the External QC coil click on the button labeled **Ext. QC** or execute this option by keyboard (navigate to the button by pressing **TAB** key and when highlighted press **ENTER** key, or use shortcut - press key **E**). This action begins by performing the automatic nulling which in this case is only in effect for the duration of the calibration process. It will not affect EM61-MK2 readings. After the nulling is completed (less than 5 seconds) the External QC coil Calibration window is displayed (Figure below).

EM61MK2×p					
Stand By	Survey: Auto	Mode: D	Battery: 12.1 V		5000.0 mV
~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~		External QC C Please click or then press O and hold for	OK button and C Coil button	hum Marine and a	vorgense
Ch1 [mV]	Ch2 [mV]	Ch3 [mV]	ChT [mV]]	-1000.0 m∨
1287.38	1142.22	1578.99	4188.03	Go	N <u>u</u> ll
File Parame		Parameters	Positions: 172	New Line	Int. QC
File: 122215B		ne: 2.00	DGPS	New Stn.	Ext. QC
Tot. Lines: 2 Tot. Stns: 14	Station	ns: 678	PDOP: 3.7 Sat 6 Lat N43ø36'35.5998''	Comment	Scale Rdgs

When External QC Coil Calibration window is displayed please use keyboard keys (O or C) rather than a mouse to execute buttons labeled OK and Cancel. Clicking on buttons by mouse will work, however several mouse button clicks may be required.

After **OK** button is tapped (or shortcut key **O** is pressed) the window displays timer with elapsed seconds and EM61-MK2 readings. This display lasts for 60 seconds. During this time please follow the instructions provided on the Allegro screen.

External QC coil calibration can end in the following four ways:

The process can be stopped by an operator at any time by tapping **Cancel** button or pressing shortcut key **C**.

The calibration may end by time out (60 seconds) if the External QC coil button was not pressed or this action did not activate QC coil.

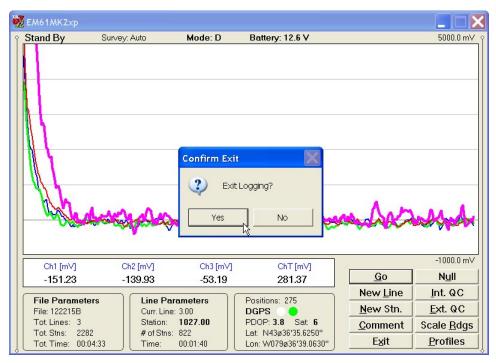
After pressing any key the program returns to Monitoring window. To repeat External QC coil calibration please tap the **Ext. QC.** button again.

The logger will determine if the instrument has passed test. If after activating the QC coil, the program determines that the reading is inside the standard values within +/- 10% tolerances then a message "CALIBRATION OK" will be displayed. Otherwise, if the program determines that the reading is outside of the test values range the corresponding message "CALIBRATION FAILED" is displayed.

Regardless of the test result (OK or FAILED) the readings will be saved on screen. The program returns to Monitoring window after any button is clicked or ENTER key is pressed. Then the External QC coil calibration process can be repeated.

Exit (exit data logging)

During data collection (in Stand By mode) a confirmation message will be displayed (there is no such message if **Exit** is performed in Monitoring mode) before program exits logging window.



After above message is confirmed the program stops logging, closes data file and returns to Main Screen.

Appendix A

A.1 Description of Data File in EM61MK2xp Format

Each record contains 24 characters, including line feed at the end of each record. Header of the file (contains six records starting with characters E, H, O, O, O, and O)

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
Ε	Μ	6	1	Μ	Κ	2		W	1	0	1	Surv	/ey T	Гуре	UT	IT	IM					IP	10
Н				Fil	e N	ame	;				Tin	ne Ir	ncre	mer	nt [s]	(F7	7.3)						10
0		(Offs	et fo	r Cł	nl (F	9.2	2)		IC	(QC coil value for Ch1 (F9.2)											10
0		(Offs	et fo	Ch2 (F9.2) IC QC coil value for Ch2 (F9.2))				10						
0		Offset for Ch3 (F9.2)									(QC coil value for Ch3 (F9.2))				10
0		Offset for Ch4 (F9.2)								IC	G	QC coil value for Ch4/T (F9.2)								10			

EM61MK2 W101	-	identification of program file version number (1.00, W - indicates file created by Windows CE program)
Survey Type	-	GPS (if GPS Input Enabled) or GRD (grid)
UT	-	unit type $(0 = meters, 1 = feet)$
IT	-	instrument type
		$(0 = \text{sensor } 1 \times 0.5 \text{m}, 1 = 1 \times 1 \text{m}, 2 = 0.5 \times 0.5 \text{m}, 3 = \text{HH61})$
IM	-	instrument mode (0 =Auto, 1 =Wheel, and 2 =Manual)
IP		- not used (=1 fixed)
File Name	-	file name, maximum 8 characters
Time Increment	-	time increment (Auto Mode) in seconds
Offset	-	offset for indicated channels in mV
IC	-	QC coil calibration (=N not performed, <>N otherwise)
QC coil value	-	value of QC coil calibration for indicated channels in mV
10	-	Line Feed character

Header at the start of survey line (eight records starting with L, B, A, Z, O, O, O, O)

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
L	L	ine	Nan	ne (8 ch	ara	cter	s)															10
В		C C	Start	Sta	tion	(Fo	rma	tF1	1.2)													10
Α	Dir							S	tatic	on Ir	ncre	mer	nt (F	orm	iat F	11.	2)						10
Ζ	D	D	Μ	М	Y	Y	Y	Y		Н	Н	:	Μ	Μ	:	S	S						10
0		(Offse	et fo	r Ch	nl (F	9.2)			F	orn	ner (Offs	et fo	r Cł	nl (F	-9.2)				10
0		(Offse	et fo	r Ch	n2 (F	9.2)			F	orm	ner (Offs	et fo	r Cł	n2 (F	9.2)				10
0		(Offse	et fo	r Cł	n3 (F	9.2)			F	orm	ner (Offse	et fo	r Cł	n3 (F	9.2)				10
0		(Offse	et fo	r Cł	n4 (F	9.2)			Fo	orme	er O	ffset	t for	Ch	4/T	(F9.:	2)				10

Line Name	-	Line Name, maximum 8 characters
Start Station	-	Start Station for the Line, format F11.2
Dir	-	Direction of the Line (E, W, N, or S)
Station Inc.	-	Station Increment, format F11.3
Date	-	Date when Line was created, format DD-MM-YYYY
Time	-	Real Time when Line was created, format HH:MM:SS
Offset	-	Offset for indicated channels in mV at the start of Line
Former Offset	-	Former offset for indicated channels in mV
10	-	Line Feed character

Timer Relation

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
*		Con	nput	er Ti	me	(For	mat	ΗH	:MN	A:SS	.sss)			Ti	ime	Star	np iı	n mi	illise	con	ds		10

Indicates relation between computer clock and the program timer. This record links timer in milliseconds and computer time (local time) in format HH:MM:SS.sss. This record is written to the file each time a new new line is entered.

Reading

1 2 3 4 5	678	9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24										
I Gn 1h 11 2h 2	21 3h 31	4h 4l 5h 5l 6 Time Stamp in ms (10 digits) 10										
I -		tor T, D, E, F, M, N, P, or Q. Each record representing reading with one of the following character, which indicates type of g: - Standard, Mode 4, channels 1, 2, 3, 4 - Standard, Mode D, channels 1, 2, 3, T - Hand Held, Mode 4, channels 1, 2, 3, 4 - Hand Held, Mode D, channels 1, 2, 3, T - Standard, Mode 4, channels 1, 2, 3, 4 - Standard, Mode 4, channels 1, 2, 3, 4 - Standard, Mode 4, channels 1, 2, 3, 4 - Hand Held, Hande 4, channels 1, 2, 3, 4 - Hande Held, Hande 4, channels 1, 2, 3, 4 - Hande Held, Hande 4, channels 1, 2, 3, 4 - Hande Held, Hande 4, channels 1, 2, 3, 4 - Hande Held										
Gn	Q -	- Hand Held, Mode D, channels 1, 2, 3, T +Marker one character parameter (Hex format), contains Gain, see table of ranges at the end of this section.										
1h 1l 2h 2l 3h 3l 4h 4l 5h 5l 6 Time Stamp		higher byte of the 2's complement Hex number of Channel 1 lower byte of Channel 1 higher byte of the 2's complement Hex number of Channel 2 lower byte of Channel 2 higher byte of the 2's complement Hex number of Channel 3 lower byte of Channel 3 higher byte of the 2's complement Hex number of Channel 4 lower byte of Channel 4 higher byte of the 2's complement Hex number of TX current lower byte of TX current fraction of current (5h 5l), Hex number time in ms from the Windows start (resets every 49.7 days)										
10	-	Line Feed character										

Comment

1		2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
(2	(Con	nme	nt (n	naxi	mun	n 11	ch	arac	ters))			Tin	ne S	tam	p in	ms	(10	digi	ts)		10
N	ew	v Sta	atio	n																				

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
S			Nev	v Sto	atior	n (Fo	ormo	at 1	1.2)					Tin	ne S	tam	p in	ms	(10	digi	its)		10

Nulling

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
0		(Offse	et foi	r Ch	1 (F	9.2)			F	orm	ner (Offs	et fo	r Cł	nl (F	9.2)				10
0		(Offse	et foi	r Ch	2 (F	9.2)			F	orm	ner (Offs	et fo	r Cł	n2 (F	-9.2)				10
0		(Offse	et fo	r Ch	n3 (F	9.2)			F	orm	ier (Offse	et fo	r Cł	n3 (F	9.2)				10
0		(Offse	et fo	r Ch	n4 (F	9.2)			Fc	orme	er O	ffset	t for	Ch	4/T	(F9.:	2)				10

QC Coil Calibration

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
Ι	С		(Offse	et fo	r Cł	n1 (F	9.2	2)														10
Ι	С		(Offse	et fo	r Cł	n2 (F	9.2	:)														10
Ι	С		(Offse	et fo	r Cł	n3 (F	9.2)														10
Ι	С		(Offse	et fo	r Cł	n4 (F	9.2)														10

IC - II indicates Inrenal QC coil calibration, IE indicates External QC coil calibration.

GPS Data Message Records

Each GPS record (GGA Message) is broken in to several 22 characters strings and placed in the EM61MK2 data file which contains 24 characters records, including one character indicator and line feed at the end of each record. The GPS sequence starts at the line which contains character *@* as the first character, then records that contain continuation of the same message start with character *#*. The GPS sequence ends with a line starting with the character !. The last line contains logger time stamp in milliseconds for given GPS reading. A sample of the GPS message written in EM61MK2 format is given below.

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
@	\$	G	Р	G	G	А	,	h	h	m	m	s	S	•	S	S	,	d	d	m	m		10
#	m	m	m	m	m	,	s	,	d	d	d	m	m		m	m	m	m	m	,	s	,	10
#	n	,	q	q	,	р	р		р	,	s	а	а	а	а	а		а	a	,	U	,	10
#	1	x	x	х	x		x	,	М	,	s	s	s	,	a	a	a	*	с	с	CR	LF	10
	±	^	~	~				'		'				'									

The GPS sequence may contain 4 to 6 records. Component of the GGA message may differ in length, however they are placed in the same number of columns. Refer to Appendix B (section B.2) for definition of each component of GGA data message.

A.2 Conversion Factors

EM61MK2 has four channels. Channels 1, 2, and 3 are common for Mode 4 and Mode D. Channel 4 in Mode D is named Channel T (it corresponds to Top coil).

The instrument response is converted to output voltage in mV for each sampling channel as given below.

Channel 1 to 4 -	converted data
DATA1 (to 4) -	instrument output for each channel as recorded in logger
RANGE	- range is controlled by the EM61MK2, it can be 1, 10,

```
100
```

Standard Unit - Mode 4 (One Sensor 1 x 0.5 m or 1 x 1 m) Channel 1=(DATA1 x 4.8333 x 2)/RANGE Channel 2=(DATA2 x 4.8333 x 2)/RANGE Channel 3=(DATA3 x 4.8333 x 2)/RANGE Channel 4=(DATA4 x 4.8333 x 2)/RANGE

Standard Unit - Mode D (Two Sensors 1 x 0.5 m or 1 x 1 m, Top and Bottom coils)) Channel 1=(DATA1 x 4.8333 x 2)/RANGE Channel 2=(DATA2 x 4.8333 x 2)/RANGE Channel 3=(DATA3 x 4.8333 x 2)/RANGE Channel T=(DATA4 x 4.8333 x 4)/RANGE

if coil is 1 x 0.5 m Channel T is further multiplied by a factor 1.114.

Hand Held Unit - Mode 4 (One Sensor)

Channel 1 = 0.902500 x (DATA1 x 4.8333)/RANGE Channel 2 = 1.363000 x (DATA2 x 4.8333)/RANGE Channel 3 = 2.026795 x (DATA3 x 4.8333)/RANGE Channel 4 = 3.018856 x (DATA4 x 4.8333)/RANGE

Hand Held Unit - Mode D (Two Sensors, Top and Bottom coils)) Channel 1 = 0.9025 x (DATA1 x 4.8333)/RANGE Channel 2 = 1.3630 x (DATA2 x 4.8333)/RANGE Channel 3 = 2.0430 x (DATA3 x 4.8333)/RANGE

Channel T = 12.152 x (DATA4 x 4.8333)/RANGE

Further each channel is normalized by current following formula:

Standard Unit

Channel = Channel x 3000/Current

Hand Held Unit

Channel = Channel x 1800/Current

where, current is a value represented by 5h, 5l, and 6 in EM61MK2 data file (see section B.1)

Table of Ranges Determined by the EM61-MK2 Microprocessor

					r	i								
HEX	Ch1	Ch2	Ch3	Ch4	HEX	Ch1	Ch2	Ch3	Ch4	HEX	Ch1	Ch2	Ch3	Ch4
0	1	1	1	1	40	10	1	1	1	со	100	1	1	1
1	1	1	1	10	41	10	1	1	10	C1	100	1	1	10
3	1	1	1	100	43	10	1	1	100	СЗ	100	1	1	100
4	1	1	10	1	44	10	1	10	1	C4	100	1	10	1
5	1	1	10	10	45	10	1	10	10	C5	100	1	10	10
7	1	1	10	100	47	10	1	10	100	C7	100	1	10	100
С	1	1	100	1	4C	10	1	100	1	cc	100	1	100	1
D	1	1	100	10	4D	10	1	100	10	CD	100	1	100	10
F	1	1	100	100	4F	10	1	100	100	CF	100	1	100	100
10	1	10	1	1	50	10	10	1	1	DO	100	10	1	1
11	1	10	1	10	51	10	10	1	10	D1	100	10	1	10
13	1	10	1	100	53	10	10	1	100	D3	100	10	1	100
14	1	10	10	1	54	10	10	10	1	D4	100	10	10	1
15	1	10	10	10	55	10	10	10	10	D5	100	10	10	10
17	1	10	10	100	57	10	10	10	100	D7	100	10	10	100
1C	1	10	100	1	5C	10	10	100	1	DC	100	10	100	1
1D	1	10	100	10	5D	10	10	100	10	DD	100	10	100	10
1F	1	10	100	100	5F	10	10	100	100	DF	100	10	100	100
30	1	100	1	1	70	10	100	1	1	FO	100	100	1	1
31	1	100	1	10	71	10	100	1	10	F1	100	100	1	10
33	1	100	1	100	73	10	100	1	100	F3	100	100	1	100
34	1	100	10	1	74	10	100	10	1	F4	100	100	10	1
35	1	100	10	10	75	10	100	10	10	F5	100	100	10	10
37	1	100	10	100	77	10	100	10	100	F7	100	100	10	100
3C	1	100	100	1	7C	10	100	100	1	FC	100	100	100	1
3D	1	100	100	10	7D	10	100	100	10	FD	100	100	100	10
3F	1	100	100	100	7F	10	100	100	100	FF	100	100	100	100

A.3 Example of Data File in EM61MK2xp Format

The Em61MK2 data file records are written in binary format, therefore the file may have different shape when displayed or printed, depending on particular video or pronter settings.

EM61MK2 W100GPS000 H 042320A 0.200 0 0.00E 0.0 0 0.00E 0.0 0 0.00E 0.0 1 0.00 0.00 0.00 0.00 Ö LO B 0.00E 0.00 $\begin{array}{c} & 0.00 \\ \text{AS} & 1.000 \\ \text{Z23042005} & 20:02:51 \\ 0 & 0.00 & 0.00 \\ 0 & 0.0$ 0.000 *20:02:51.000 4179829 @\$GPGGA,020412.00,4336. #59410,N,07936.64856,W, #2,6,2,141.56,M,-35,M,5 #,119*55 4287423 . 4287423 @\$GPGSA,A,3,30,,25,20 #,,14,,06,,01,02.8,02.1 #,02.0*0D 4287441 EÿØ // "N 4287673 Eÿ †/" "Q 4287879 C comment text 4287983 EY 6/YI "O 4288089 EY 6/YI "O 4288089 EY 6/YI P "W 4288279 @\$GPGGA,020413.00,4336. #59408,N,07936.64857,W, #2,6,2,141.51,M,-35,M,6 #,119*58 Fö ¶ 2288338 Eÿ¶ 5/ # "S 4288488 @\$GPGSA,A,3,30,,25,20 #,,14,,06,,01,02.8,02.1 #,02.0*0D ! 4288419 Eÿþ ⁰/j "O 4288677 EÿL t/k "Q 4288885 @\$GPGGA,020414.00,4336. #59411,N,07936.64846,W, #2,6,2,141.68,M,-35,M,6 #,119*5D 4289337 4289337 Eÿ4 (/± · 4290288 @\$GPGGA,020415.00,4336. #59411,N,07936.64845,W, #2,6,2,141.69,M,-35,M,7 #,119*5F 4290338 4290338 ! 4290338 EÿÈ 1/Y 4290496 @\$GPGSA,A,3,30,,25,,20 #,14,,06,,01,02.8,02.1 #,02.0*0D 4290417 4290687 4291335 Esý3 · 4291502 @\$GPGSA,A,3,30,,,25,,20 #,,14,,06,,01,02.8,02.1 #,02.0*0D Ëÿ*, bŒ "Y C building E 4291414 4291691 4291793 ₩ *â "V E /D "C 4291900 4292299

Appendix B

B.1 Using the EM61MK2xp with a GPS Receiver

The EM61MK2xp program accepts input from GPS receiver that stream NMEA-0183 compatible data through their output port. The program uses two NMEA messages: GGA and GSA. The entire GGA message is used later by the DAT61MK2 program, while the GSA message is used only to display PDOP index on the logger screen.

The GPS system means (control device, receiver panel, or manufacturer software) must be used to set GPS receiver communication parameters, to specify frequency of GPS output, and number and type of NMEA messages sent by the GPS system output port. Any GPS system can send various NMEA messages. It is important to select only two messages (GGA and GSA) that are actually used by EM61MK2. The program will accept any GPS string sent by the GPS receiver, however it uses time to process GPS data that is not being used. Therefore, selecting a larger number of NMEA messages for GPS output will result in slower data acquisition of EM61MK2xp. Normally, the EM61MK2xp running in a Windows XP based computer uses less than 100 ms to process and record GPS data from two NMEA messages, GGA and GSA.

Only message GGA is necessary to position EM61-MK2 data. If message GSA is not available in a particular system, the EM61MK2xp will function and record position data based on GGA message. Lack of GSA message will result in PDOP index displayed as Not Available (N/A) on the logger display. Using message GGA alone will also result in slightly faster operation of the program. The speed can be further improved by setting higher Baud Rate (if it is supported by the employed GPS receiver) in Set GPS Port menu.

The EM61MK2xp dedicates portion of the display and shows GPS status in a frame box. A number following the label **Position** provides the number of GPS positions saved in the current data file. Next two lines in this frame display parameters describing quality of GPS positions. A label **DGPS** (Differential Global Positioning System) indicates that GPS readings are differentially corrected in real time, while label **AGPS** (Autonomous Global Positioning System) indicates lack of differential correction. On the right side of **DGPS** or **AGPS** label two green and white circles alternate. These two circles should alternate colours with the frequency of GPS update rate (usually 1 second intervals). If the circles do not change colours for long periods of time it means that the GPS system is not working or that it is not connected to the field computer.

The next label **PDOP** with a value varying between 0 and 99.9 represents an index called Position Dilution of Precision (**PDOP**). This value is available only when messages both, GGA and GSA are received from GPS. This index measures the strength of satellite coverage for a given area. PDOP is affected by the number of satellites visible and their relative positions in the sky. The smaller the number of PDOP the stronger the satellite coverage is. When there are more than 5 satellites widely spaced visible, the PDOP is 4 or less. However, when there are less satellites visible, or they are unevenly spaced in the sky, PDOP values can be 6 or higher. In most cases, the PDOP in an open sky is less than 3, and most accuracies given for many GPS systems are given for this norm. Refer to GPS documentation and literature for more information related to error sources of GPS positioning.

The last label Sat and following number shows number of currently tracked satellites.

Two bottom lines of the frame give current Latitude and Longitude of the instrument position (datum WGS1984). Position is updated with frequency of GPS receiver stream.

B.2 Description of GGA and GSA Data Messages

GGA Data Message

The GGA message contains the GPS position information and it is the most widely used NMEA data message. This message takes the following form:

\$GPGGA,hhmmss.ss,ddmm.mmmmm,s,dddmm.mmmmm,s,n,qq,pp.p,saaaaa.aa,u, ±xxxx.x,M,sss,aaaa*cc<CR><LF>

Definition of GGA message component:

hhmmss.ss ddmm.mmmmm s	UTC time in hours, minutes, seconds of the GPS position Latitude in degrees, minutes, and decimal minutes s=N or s=S, for North and South latitude
dddmm.mmmmm	Longitude in degrees, minutes, and decimal minutes
S	s=E or s=W, for East and West longitude
n	Quality indicator, 0 = no position, 1 = raw, no differentially corrected
	position, 2 = differentially corrected position, 9 = position computed
	using almanac information
qq	Number of satellites used in position computation
рр.р	HDOP = 0.0 to 99.9
saaaaa.aa	Antenna altitude
u	Altitude units, M=meters
<u>+</u> xxxx.x	Geoidal separation (requires geoidal height option)
Μ	Geoidal separation units, M = meters
SSS	Age of differential corrections in seconds
aaaa	Base station identification
*cc	Checksum
<cr><lf></lf></cr>	Carriage return and Line feed

GSA Data Message

The GSA message contains active satellites and PDOP value. The GSA message is given in the following form:

\$GPG\$A,c1,d1,d2,d3,d4,d5,d6,d7,d8,d9,d10,d11,d12,d13,f1,f2,f3*cc<CR><LF>

Definition of GSA message components:

c1	Mode, M = manual, A = automatic
d1	Mode, 2 = 2D, 3 = 3D
d2-d13	Satellites used in position computation (range 0 to 32)
f1	PDOP (range 0 to 99.9)
f2	HDOP (range 0 to 99.9)
f3	VDOP (range 0 to 99.9)
*cc	Checksum
<cr><lf></lf></cr>	Carriage return and Line Feed