

## **OPERATING SYSTEMS:**

# Lesson 1: Introduction to Operating Systems

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### Why study Operating Systems?

- a) OS, and its internals, largely influences general functioning, including security and performance.
- b) Importance of OS choice in an organization is higher and higher. Trend to strategic decision.
- c) Knowledge fundamental to develop applications if good performance is desired and to understand causes of many problems.





#### Understanding OS

- Which OS takes better advantage of a given system capabilities?
- Does the OS support all the devices I intend to connect to the computer? If not, what can I do?
- Is it secure enough for the environment it will be integrated in?
- Will my applications run «smoothly» on the chosen OS? How will my concrete workload adapt to the platform?





- Is it easy to find admins for this OS? Is administration an *obscure* task needing ultra-specialized personnel?
- What support does the OS have? Which is the update publishing rate?
- Besides cost, what future expectations does it have?



# Protect your investment





- Software needs OS services for may tasks.
  - What services does the OS offer and how do I invoke them?
- To take advantage of new architectures multithreading is essential.
  - How do I develop a multithreaded application for my OS?





An engineer must be







# OPERATING SYSTEM AGNOSTIC





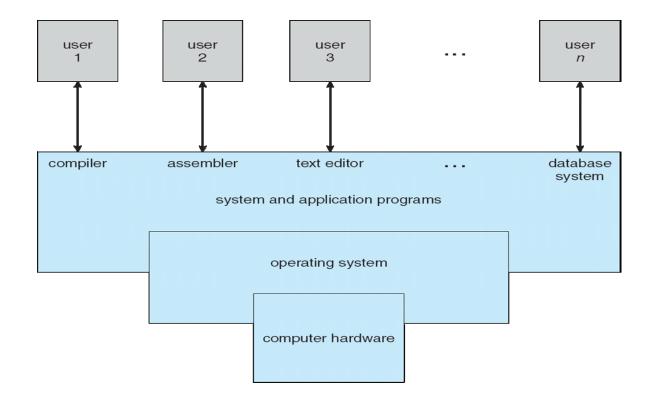
symbian OS







#### Four Components of a Computer System







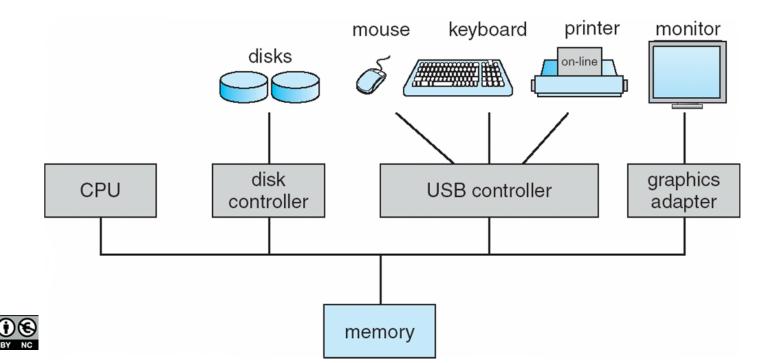
- Computer system can be divided into four components
  - Hardware provides basic computing resources
    - CPU, memory, I/O devices
  - Operating system
    - Controls and coordinates use of hardware among various applications and users
  - Application programs define the ways in which the system resources are used to solve the computing problems of the users
    - Word processors, compilers, web browsers, database systems, video games
  - Users
    - People, machines, other computers





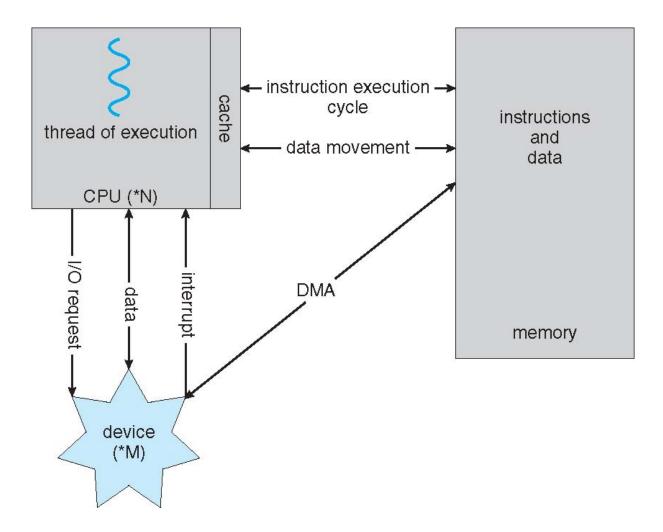
#### **Computer System Organization**

- Computer-system operation
  - One or more CPUs, device controllers connect through common bus providing access to shared memory
  - Concurrent execution of CPUs and devices competing for memory cycles





#### How a Modern Computer Works



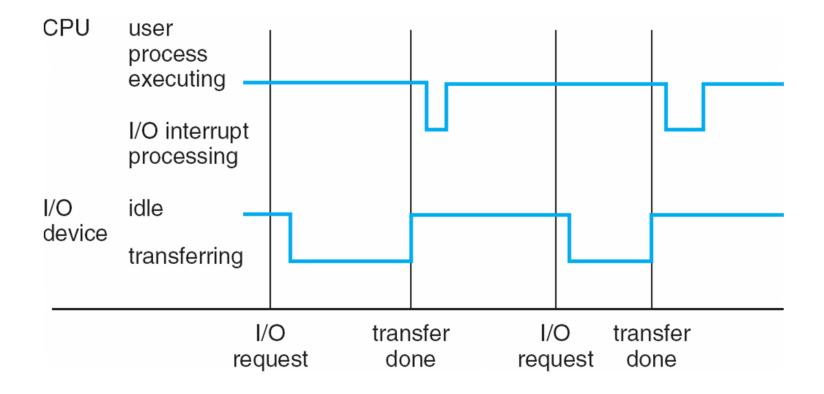




- I/O devices and the CPU can execute concurrently
- Each device controller is in charge of a particular device type
- Each device controller has a local buffer
- CPU moves data from/to main memory to/from local buffers
- I/O is from the device to local buffer of controller
- Device controller informs CPU that it has finished its operation by causing an *interrupt*











- Interrupt transfers control to the interrupt service routine generally, through the interrupt vector, which contains the addresses of all the service routines
- Interrupt architecture must save the address of the interrupted instruction
- Incoming interrupts are *disabled* while another interrupt is being processed to prevent a *lost interrupt*
- A *trap* is a software-generated interrupt caused either by an error or a user request
- An operating system is **interrupt driven**





- The operating system preserves the **CPU state** by storing registers and the program counter
- Determines which type of interrupt has occurred.
- Separate segments of code determine what action should be taken for each type of interrupt





## I/O Structure

- After I/O starts, control returns to user program only upon I/O completion
  - At most one I/O request is outstanding at a time, no simultaneous I/O processing
- System call request to the operating system to allow user to wait for I/O completion
- Device-status table contains entry for each I/O device indicating its type, address, and state
- Operating system indexes into I/O device table to determine device status and to modify table entry to include interrupt

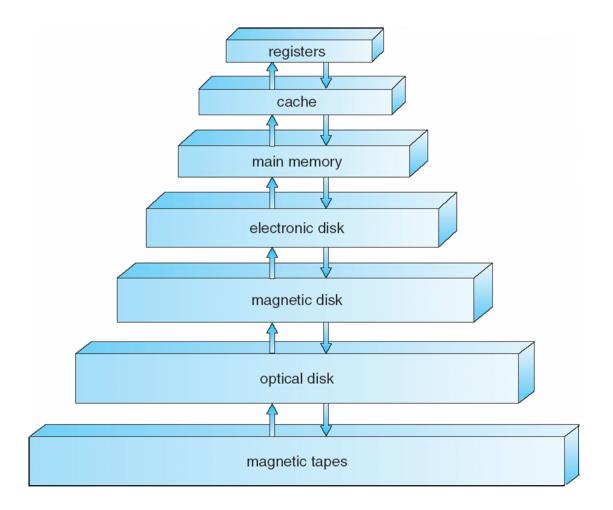




- Used for high-speed I/O devices able to transmit information at close to memory speeds
- Device controller transfers blocks of data from buffer storage directly to main memory without CPU intervention
- Only one interrupt is generated per block, rather than the one interrupt per byte











#### Performance of Various Levels of Storage

 Movement between levels of storage hierarchy can be explicit or implicit

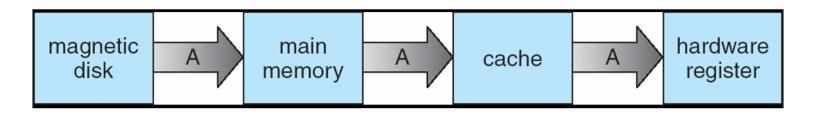
Level	1	2	3	4
Name	registers	cache	main memory	disk storage
Typical size	< 1 KB	> 16 MB	> 16 GB	> 100 GB
Implementation technology	custom memory with multiple ports, CMOS	on-chip or off-chip CMOS SRAM	CMOS DRAM	magnetic disk
Access time (ns)	0.25 - 0.5	0.5 – 25	80 – 250	5,000.000
Bandwidth (MB/sec)	20,000 - 100,000	5000 - 10,000	1000 - 5000	20 – 150
Managed by	compiler	hardware	operating system	operating system
Backed by	cache	main memory	disk	CD or tape





#### Migration of Integer A from Disk to Register

 Multitasking environments must be careful to use most recent value, no matter where it is stored in the storage hierarchy



 Multiprocessor environment must provide cache coherency in hardware such that all CPUs have the most recent value in their cache





- Main memory only large storage media that the CPU can access directly
- Secondary storage extension of main memory that provides large nonvolatile storage capacity
- Magnetic disks rigid metal or glass platters covered with magnetic recording material
  - Disk surface is logically divided into tracks, which are subdivided into sectors
  - The disk controller determines the logical interaction between the device and the computer





- Storage systems organized in hierarchy
  - Speed
  - Cost
  - Volatility
- Caching copying information into faster storage system; main memory can be viewed as a last *cache* for secondary storage





- Important principle, performed at many levels in a computer (in hardware, operating system, software)
- Information in use copied from slower to faster storage temporarily
- Faster storage (cache) checked first to determine if information is there
  - If it is, information used directly from the cache (fast)
  - If not, data copied to cache and used there
- Cache smaller than storage being cached
  - Cache management important design problem
  - Cache size and replacement policy





- A program that acts as an intermediary between a user of a computer and the computer hardware
- Operating system goals:
  - Execute user programs and make solving user problems easier
  - Make the computer system convenient to use
  - Use the computer hardware in an efficient manner





- OS is a **resource allocator** 
  - Manages all resources
  - Decides between conflicting requests for efficient and fair resource use
- OS is a control program
  - Controls execution of programs to prevent errors and improper use of the computer





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- No universally accepted definition
- "Everything a vendor ships when you order an operating system" is good approximation
  - But varies wildly
- "The one program running at all times on the computer" is the kernel. Everything else is either a system program (ships with the operating system) or an application program





#### **Operating System Structure**

- Multiprogramming needed for efficiency
  - Single program cannot keep CPU and I/O devices busy at all times
  - Multiprogramming organizes jobs (code and data) so CPU always has one to execute
  - A subset of total jobs in system is kept in memory
  - One job selected and run via job scheduling
  - When it has to wait (for I/O for example), OS switches to another job
- **Timesharing (multitasking)** is logical extension in which CPU switches jobs so frequently that users can interact with each job while it is running, creating interactive computing
  - Response time should be < 1 second</li>
  - Each user has at least one program executing in memory ⇒ process
  - − If several jobs ready to run at the same time ⇒ CPU scheduling
  - If processes don't fit in memory, swapping moves them in and out to run
  - Virtual memory allows execution of processes not completely in memory





#### **Response time**

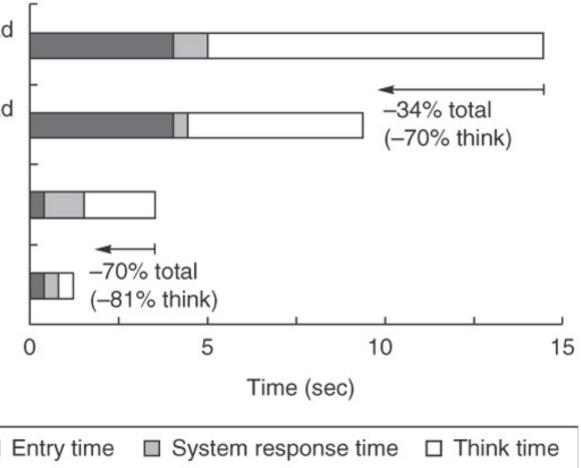
#### Workload

Conventional interactive workload (1.0 sec system response time)

Conventional interactive workload (0.3 sec system response time)

High-function graphics workload (1.0 sec system response time)

High-function graphics workload (0.3 sec system response time)

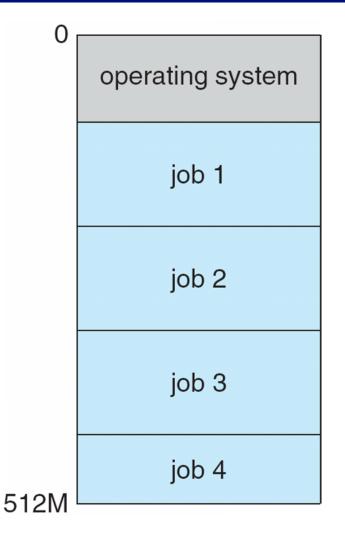






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#### Memory Layout for Multiprogrammed System







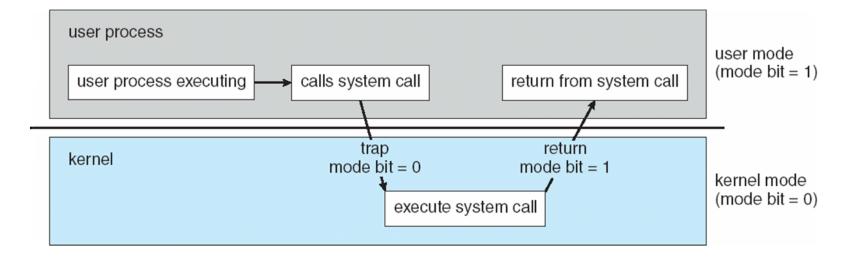
- Interrupt driven by hardware
- Software error or request creates exception or trap

   Division by zero, request for operating system service
- Other process problems include infinite loop, processes modifying each other or the operating system
- Dual-mode operation allows OS to protect itself and other system components
  - User mode and kernel mode
  - Mode bit provided by hardware
    - Provides ability to distinguish when system is running user code or kernel code
    - Some instructions designated as privileged, only executable in kernel mode
    - System call changes mode to kernel, return from call resets it to user





#### Universidad Carlos III de Machinerransition from User to Kernel Mode







- A process is a program in execution. It is a unit of work within the system. Program is a *passive entity*, process is an *active entity*.
- Process needs resources to accomplish its task
  - CPU, memory, I/O, files
  - Initialization data
- Process termination requires reclaim of any reusable resources
- Single-threaded process has one **program counter** specifying location of next instruction to execute
  - Process executes instructions sequentially, one at a time, until completion
- Multi-threaded process has one program counter per thread
- Typically a system has many processes, some users, some operating system running concurrently on one or more CPUs
  - Concurrency by multiplexing the CPUs among the processes / threads





The operating system is responsible for the following activities in connection with process management:

- Creating and deleting both user and system processes
- Suspending and resuming processes
- Providing mechanisms for process synchronization
- Providing mechanisms for process communication
- Providing mechanisms for deadlock handling





- All data in memory before and after processing
- All instructions in memory in order to execute
- Memory management activities
  - Keeping track of which parts of memory are currently being used and by whom
  - Deciding which processes (or parts thereof) and data to move into and out of memory
  - Allocating and deallocating memory space as needed





- OS provides uniform, logical view of information storage
  - Abstracts physical properties to logical storage unit file
  - Each medium is controlled by device (i.e., disk drive, tape drive)
    - Varying properties include access speed, capacity, data-transfer rate, access method (sequential or random)
- File-System management
  - Files usually organized into directories
  - Access control on most systems to determine who can access what
  - OS activities include
    - Creating and deleting files and directories
    - Primitives to manipulate files and dirs
    - Mapping files onto secondary storage
    - Backup files onto stable (non-volatile) storage media





- Usually disks used to store data that does not fit in main memory or data that must be kept for a "long" period of time
- Proper management is of central importance
- Entire speed of computer operation hinges on disk subsystem and its algorithms
- OS activities
  - Free-space management
  - Storage allocation
  - Disk scheduling
- Some storage need not be fast
  - Tertiary storage includes optical storage, magnetic tape
  - Still must be managed
  - Varies between WORM (write-once, read-many-times) and RW (read-write)





- One purpose of OS is to hide peculiarities of hardware devices from the user
- I/O subsystem responsible for
  - Memory management of I/O including buffering (storing data temporarily while it is being transferred), caching (storing parts of data in faster storage for performance), spooling (the overlapping of output of one job with input of other jobs)
  - General device-driver interface
  - Drivers for specific hardware devices





- Protection any mechanism for controlling access of processes or users to resources defined by the OS
- Security defense of the system against internal and external attacks
  - Huge range, including denial-of-service, worms, viruses, identity theft, theft of service
- Systems generally first distinguish among users, to determine who can do what
  - User identities (user IDs, security IDs) include name and associated number, one per user
  - User ID then associated with all files, processes of that user to determine access control
  - Group identifier (group ID) allows set of users to be defined and controls managed, then also associated with each process, file
  - Privilege escalation allows user to change to effective ID with more rights





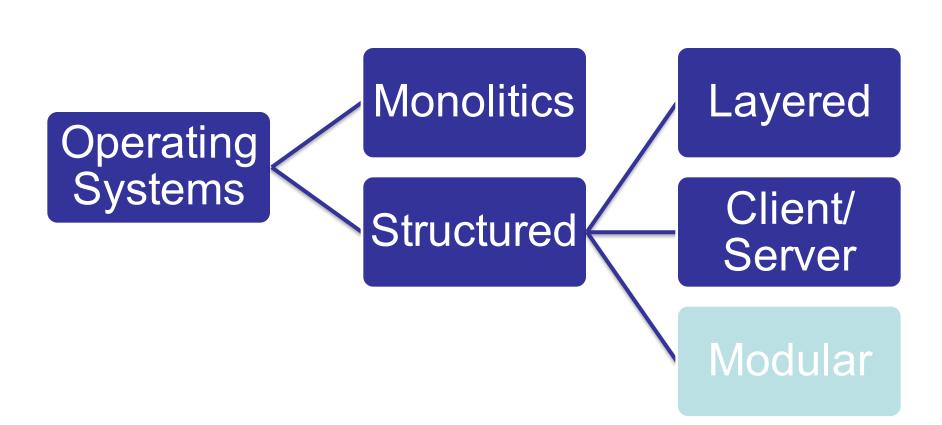
### **Conceptual structure**

- Execution modes:
  - User mode: Executes user processes.
  - Kernel mode: Executes the OS kernel.
- Processes and OS use separate memory spaces.
- When a process needs a service requests it to the OS through a system call.
  - The Operating System enters execution to perform requested function.













# Monolitic OS

- No clear or well defined structure.
- All the OS code linked into a single executable running in kernel mode.
  - Single address space.
  - No data hiding among modules.
- More efficient at the cost of very complex development and maintenance.
- Examples:
  - All OS until '80, including UNIX.
  - MS-DOS and current UNIX variants: Solaris, Linux, AIX, HP-UX,...







- Organization as a set of layers with clear and well defined interfaces.
- Each layer on top of lower layer.
- Advantates:
  - Modularity.
  - Data hiding.
  - Better development and debugging.
- Less efficient due to need to cross many layers to perform an operation.
- Difficult to distribute OS functions into layers.
- Examples:
  - MacOS X kernel
  - OS/2





# Client/Server approach

Most services as user processes with a small amount of functioality into a microkernel.

#### □ Advantages:

- □ Very flexible. Each server can be developed and debugged in isolation.
- Easily extensible to a distributed model
- □ Drawbacks:
  - Overhead in services execution.
- Examples:
  - Minix y Amoeba (Tanenbaum)
  - Mac OS and Windows NT.
    - However services executed in kernel space for performance reasons.





### Modular

- Most modern operating systems implement kernel modules
  - Uses object-oriented approach
  - Each core component is separate
  - Each talks to the others over known interfaces
- $_{\circ}~$  Each is loadable as needed within the kernel
- Overall, similar to layers but with more flexible





### Classifications

Number of processes:Single-Task.Multitaks.

- □Interaction Mode:
  - □Interactive.
  - ■Batch.
- □Number of users:
  - ■Monouser.
  - ■Multiuser.

□ Number of processors: Monoprocessor. □ Multiprocessor. □Threading: ■ Monothread. **D** Multithread.  $\Box$  uses: Client. Server. Embedded. Real-Time.





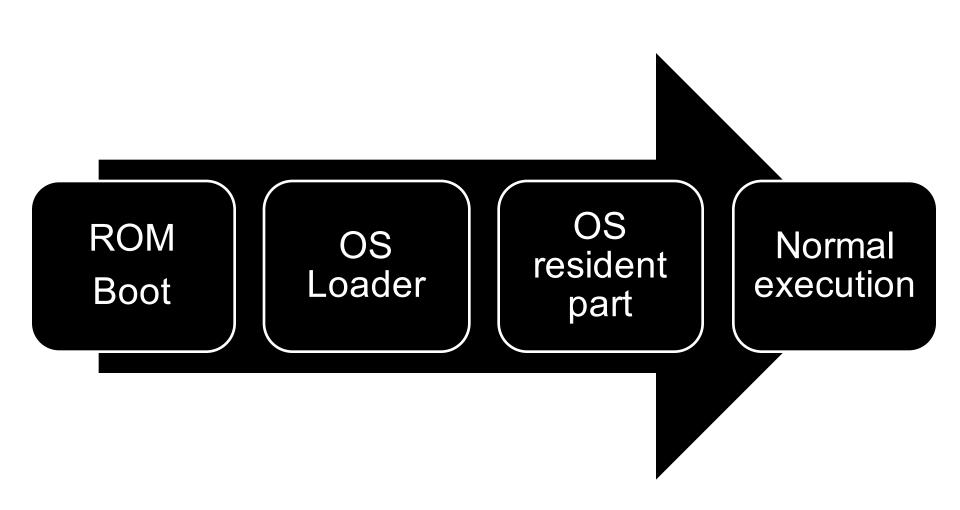
#### OS startup

- OS starts up whe computer is switched on.
  - Initially in secondary storage.
  - How does it come to main memory?
  - How des it start execution after being loaded?













- **bootstrap program** is loaded at power-up or reboot
  - Typically stored in ROM or EPROM, generally known as firmware
  - Initializes all aspects of system
  - Loads operating system kernel and starts execution







### ROM boot

- RESET signal loads predefined values in registers.
  - PC: boot address in room boot.
- Start running ROM boot:
  - System hardware test.
  - Load into memory to OS loader.





#### □ Program loader is in disk boot sector.

□ Responsible for loading the rest of the OS.

 $\Box$  Verifies the magic word in boot sector.





- OS designed for a complete class of machines with several variants of configurations and many supported devices.
- Need to generate OS copy based on characteristics of specific machine configuration.
- Generation performed during initial installation.





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