## Computational Methods for External Flooding PRA

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## Outline of my talk today

- Definition of Computational Risk Assessment
- Computational resources
- Simulating physical phenomena via Smoothed Particle Hydrodynamics
- Performing assessment via CRA



## **Computational Risk Assessment (CRA)**

- Computational Risk Assessment is a focus of current research and development
- CRA is a combination of
  - Probabilistic (i.e., dynamic) scenario creation where scenarios unfold and are not defined a priori
  - Mechanistic analysis representing physics of the unfolding scenarios
- CRA relies on the availability of computational tools
  - Processors (hardware)
  - Methods (software)
- CRA is not simply solving traditional PRA models faster or with higher precision
  - It is a different way of thinking about the safety problem.

Integrating the worlds
of physics and
probability leads us to
predictions based upon
an approach called
"computational risk
assessment"



## **CRA** driving factors

- Computers are improving
- Software is improving
  - And much of it is free
- Analysis characteristics including

Temporal (timing issues)

Spatial (location issues)

Mechanistic (physics issues)

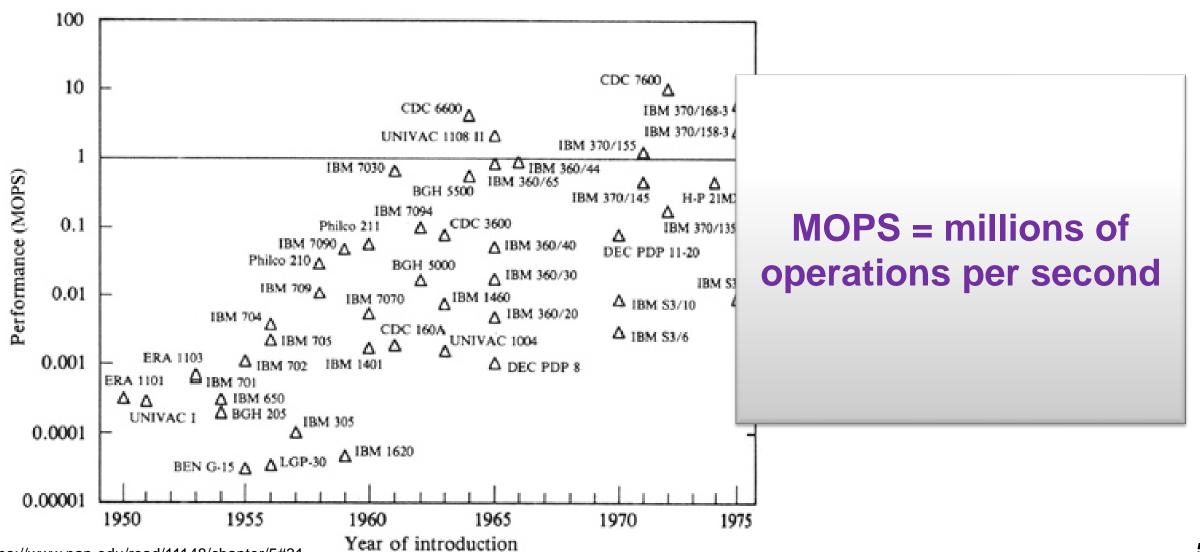
Topology (complexity issues)







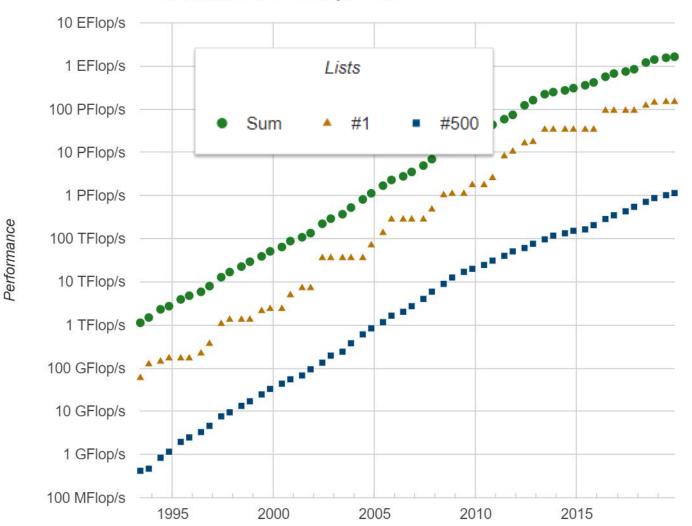
## Computational performance @ dawn of risk and reliability analysis





## Computational performance over time has steadily increased

#### **Performance Development**



#### **Notes:**

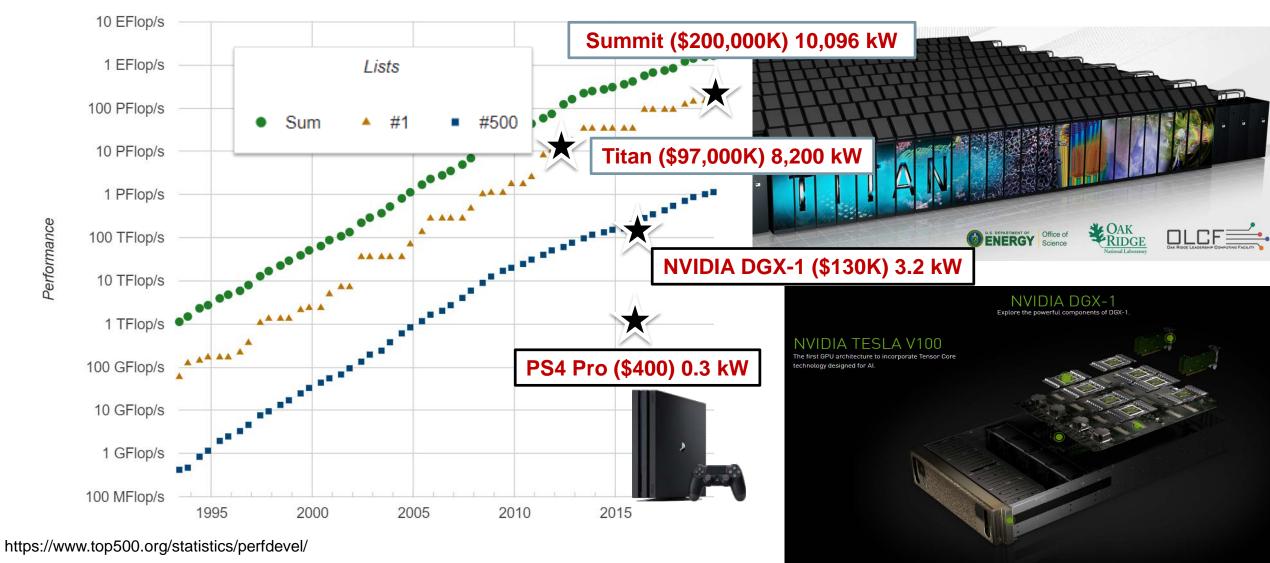
1 EFlop/s = one exaFLOPS, or a billion billion calculations per second (10<sup>18</sup>)

1 MOPS does not even appear on this plot.



## But how available is this "computational performance?"

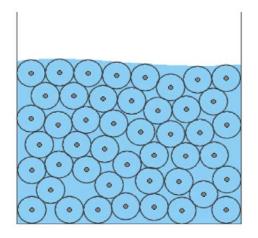
**Performance Development** 

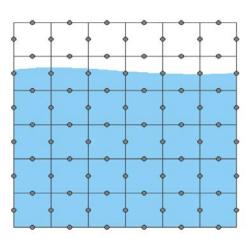




## **Smoothed Particle Hydrodynamics**

- A way to simulate flooding scenarios is needed
- Smoothed Particle Hydrodynamics (SPH)
  - Particle based method
  - Originally developed for astrophysics applications in 1977
  - Later extended for fluid dynamic applications
- SPH allows for flooding scenarios to be simulated
  - Does not confine fluid to meshes
  - Allows for a natural flow to be modeled
- A reliable SPH code is needed
  - Compare to experimental results

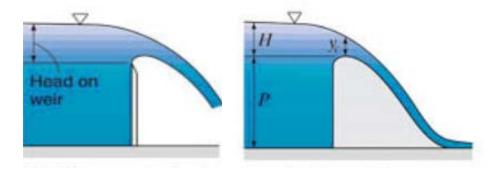


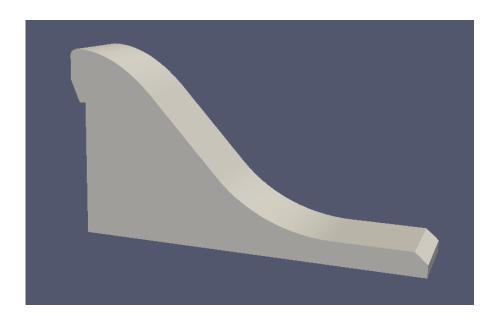




## **Ogee Spillway Comparison**

- Comparison Model
  - Ogee spillway with horizontal apron
  - Details of experiment provided in Flow over Ogee Spillway: Physical and Numerical Model Case Study by Bruce M. Savage and Michael C. Johnson
  - Experiment details (scaled model):
    - Measurements taken 2 m upstream
      - Flow Rate
      - Total Head
    - Ten different runs conducted
  - Prototype scale was used for the SPH comparison which required scaling the model scale up 30 times

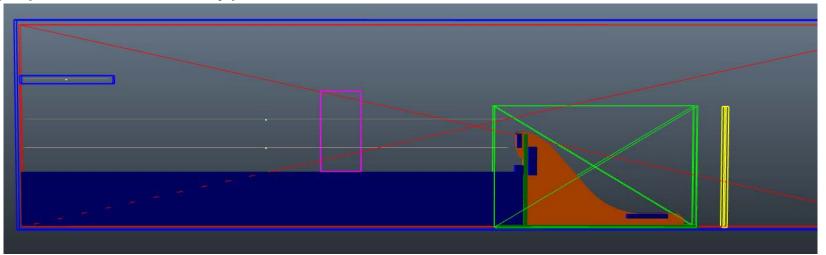






#### **Neutrino Model**

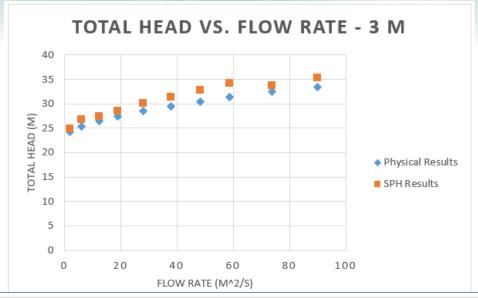
- Developmental SPH code Neutrino was used to conduct the comparison
- Model construction process:
  - Determine how to fill particles behind the spillway
  - Reduce leakage
  - Determine particle emitter location to set total head
  - Determine particle emitter location to set flow rate instead
  - Conduct parametric studies on model width and particle size
  - Reduce leakage again
  - Change particle emitter types

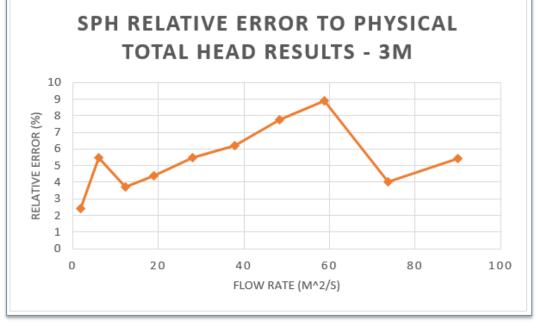




## **Comparison Results**

Run	Flow	Physical	SPH Total	Relative
	Rate	Total Head	Head	Error
		Result	Result	
1	1.9 m <sup>2</sup> /s ± 0.25%	24.3 m	24.9 m	2.4 %
2	$6.0 \text{ m}^2\text{/s} \pm 0.25\%$	25.3 m	26.7 m	5.5 %
3	12.3 m <sup>2</sup> /s ± 0.25%	26.5 m	27.5 m	3.7 %
4	19.0 m <sup>2</sup> /s ± 0.25%	27.4 m	28.6 m	4.4 %
5	27.9 m <sup>2</sup> /s ± 0.25%	28.5 m	30.0 m	5.5 %
6	$37.8 \text{ m}^2/\text{s} \pm 0.25\%$	29.5 m	31.3 m	6.2 %
7	48.2 m <sup>2</sup> /s ± 0.25%	30.4 m	32.8 m	7.7 %
8	$58.9 \text{ m}^2/\text{s} \pm 0.25\%$	31.4 m	34.1 m	8.9 %
9	$73.8 \text{ m}^2/\text{s} \pm 0.5\%$	32.4 m	33.7 m	4.0 %
10	$89.9 \text{ m}^2/\text{s} \pm 0.5\%$	33.5 m	35.3 m	5.4 %



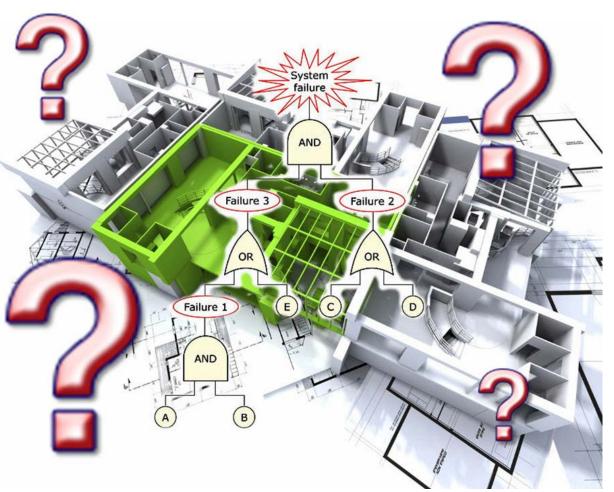




## How to Join Physics Model & System Model

 Good - Run repeated simulations and add the failure information into the existing static models

- Better Dynamic PRA model that can interact with the simulation
  - No corrections needed for time dependent calculations
  - Determine average or mean time of particular outcomes
  - Analyze time order of failures to determine early protection methods





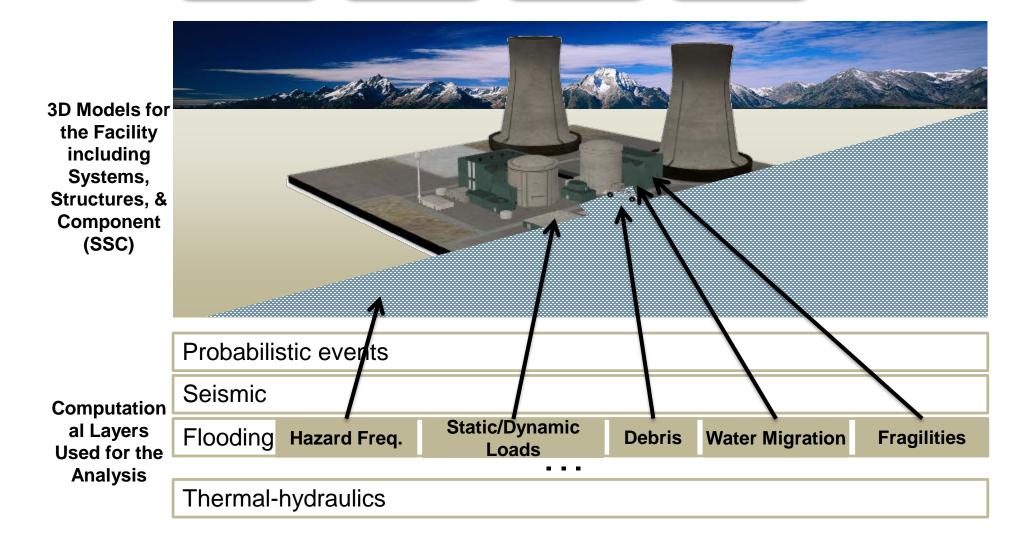
Risk Analysis
Steps for
Scenario
Generation

**Enabling Conditions** 

**Flood** 

Plant SSC Response to Initiator SSC Failures & Successes

**Scenario Simulation** 



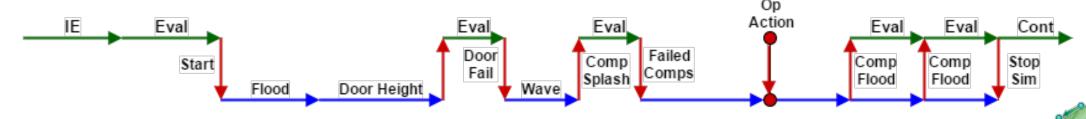


## **Timing is Everything**



- Physics simulation are dynamic and time dependent
- Control logic is not always available in simulations
- Need to modify the behavior of the simulation at during execution.

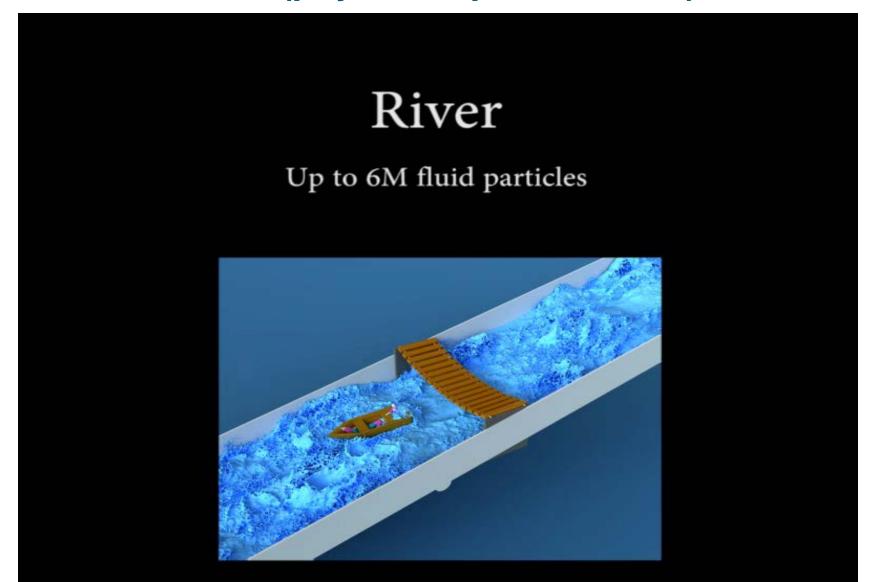
# System Model



Simulation

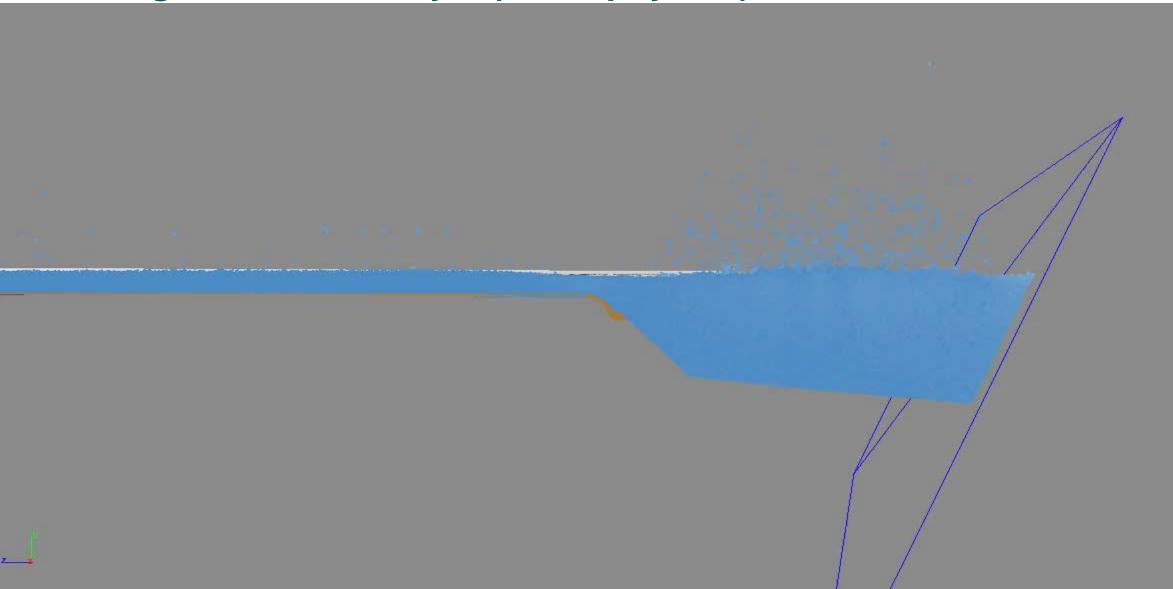


## Example of a fluid solver (physics representation)



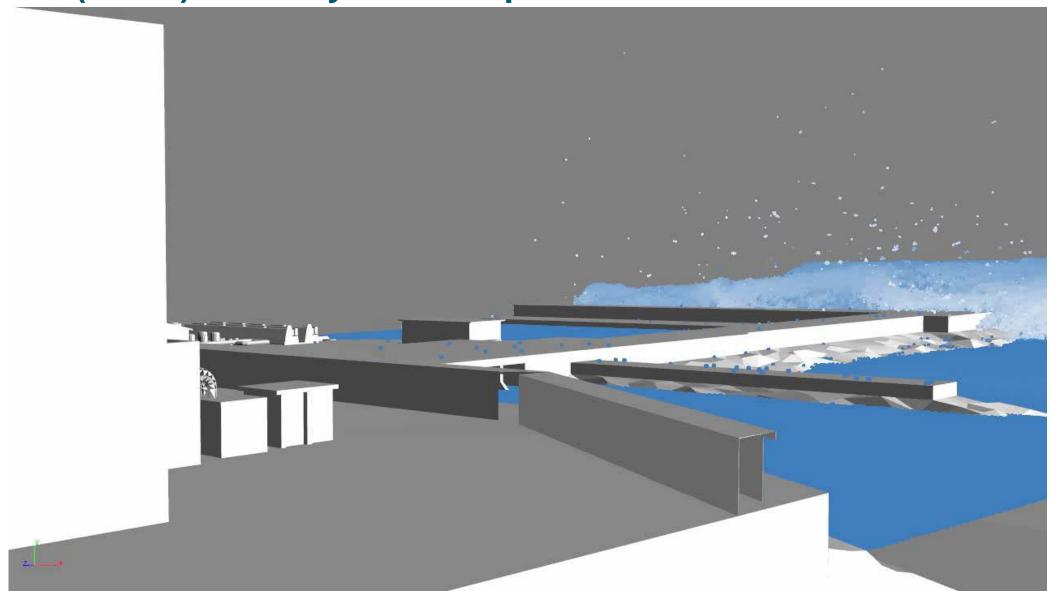


## Making a wave CRA style (water physics)





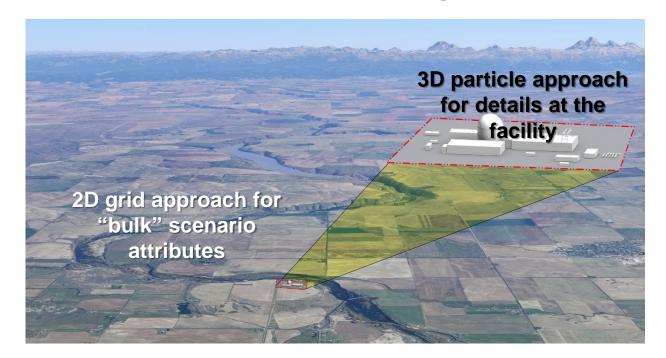
## Physics (water) + facility model + probabilistic failures = CRA





## River flood modeling

- INL/EXT-15-37091, Flooding Capability for River-based Scenarios
- Evaluated two different types of potential river-based flooding tools
  - 1D/2D grid based (GeoClaw, EPA's SWMM code, and Army Corps HEC)
  - 3D particle based
  - Both the 2D and 3D methods have positives and negatives
- Combination of both seems to be best approach moving forward







#### **Conclusions**

- The Idaho National Laboratory is demonstrating a next-generation uncertainty and riskassessment approach that supports PRA and decision-making
- Combines mechanistic physics-based models with probabilistic analysis (CRA)
- Provides new opportunities for the next generation of scientists/engineers to attract talent

