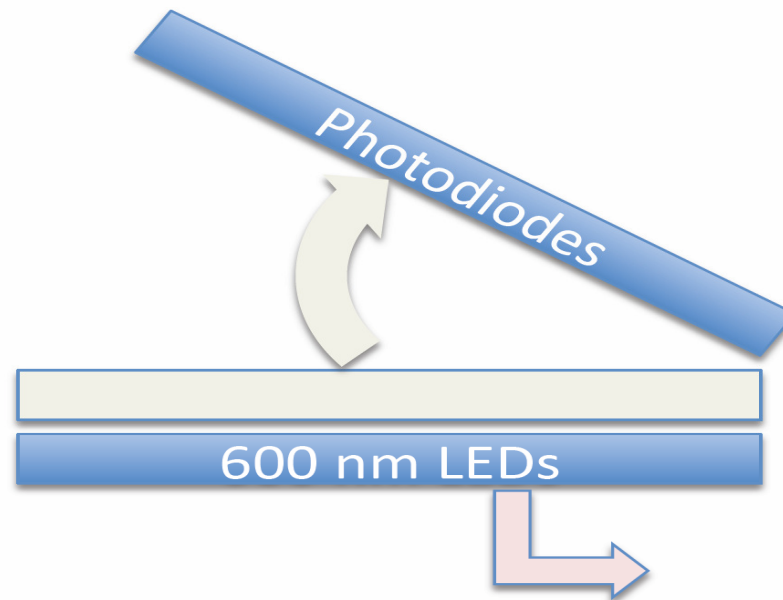


Plate Reader Turbidostat Project Review



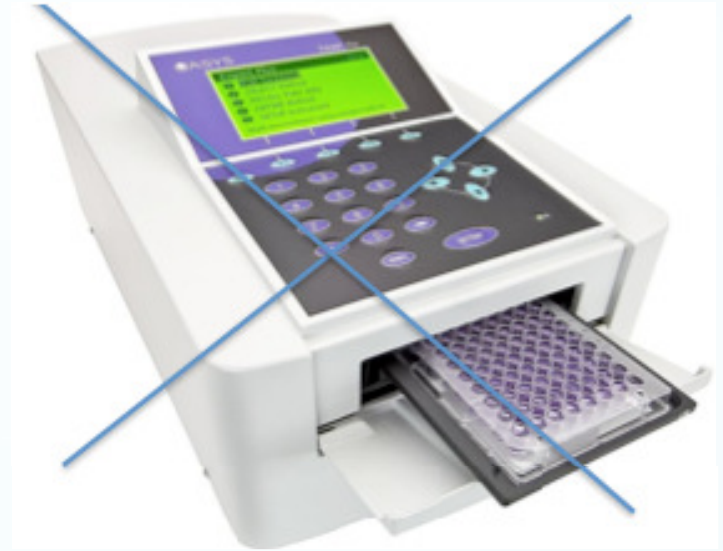
Maxwell Holloway
Peter Harker
Evan Dreveskracht

Contents

- Project Description
 - Customer needs
- Literature and Related Work
- System Model
- Hardware and Software Design
- Code, Diagrams, Photos

Project Description

- Customer Needs:
 - Replacing previous expensive multifunction equipment with simpler plate reader for reading turbidostatic* behavior.



* Turbidostat: a device in which a bacterial culture is maintained at a constant volume and cell density (turbidity) by adjusting the flow rate of fresh medium into the growth tube by means of a photocell.

Related Work

Alex Leone

Self Organizing Systems (SOS) Lab

Undergraduate Research Assistant

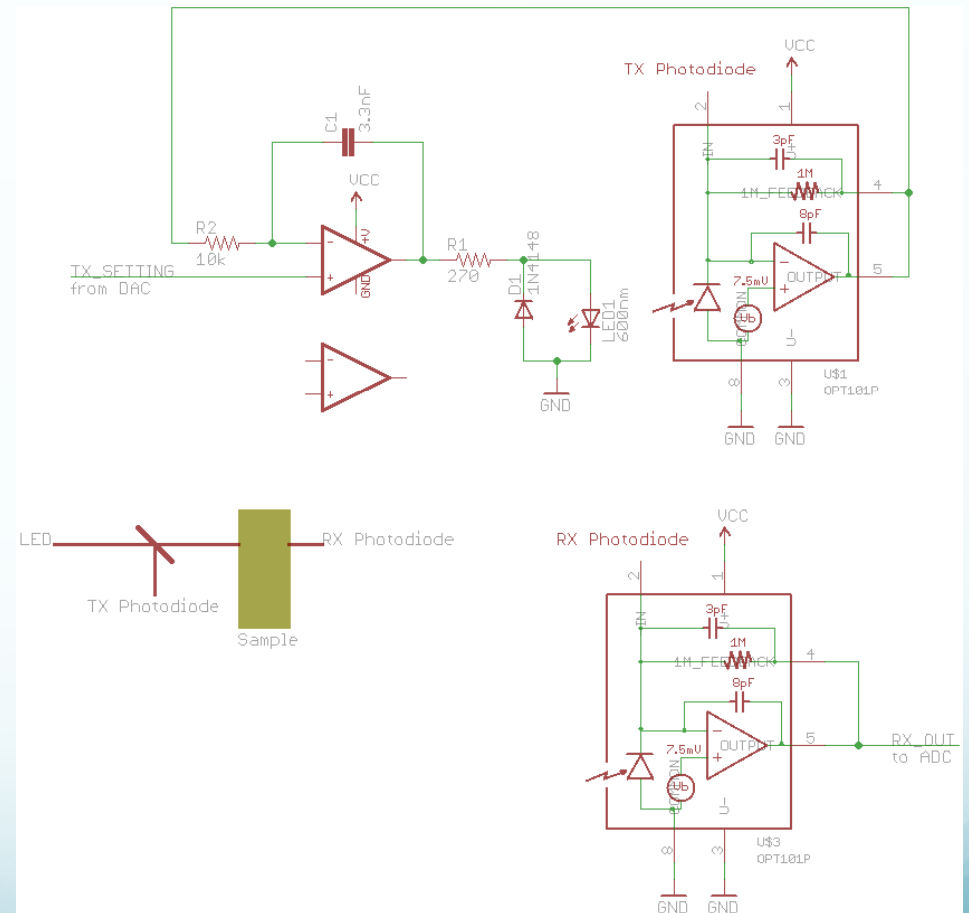
- Created Turbidostat that worked well
- Wanted to Expand on his idea

Limitations of Original:

- One sample at a time
- Laser was noisy

Advantages of Original

- Two photodiodes



System Equations

$$\dot{x} = \frac{vnx}{k+n} - ux$$

$$\dot{n} = -\gamma \frac{vnx}{k+n} + u(n_0 - n)$$

$$y = kx$$

For our simulation:

$v = 2$ generations per hour

$k = 1$

$\gamma = 0.5$

$n_0 = 1$

$x_0 = 0.5$

PARAMETERS

v = maximum growth rate
(generations/hour)

k = half saturation constant (g/L)

γ = nutrient mass used per bacteria
mass grown (unitless because it's a
ratio)

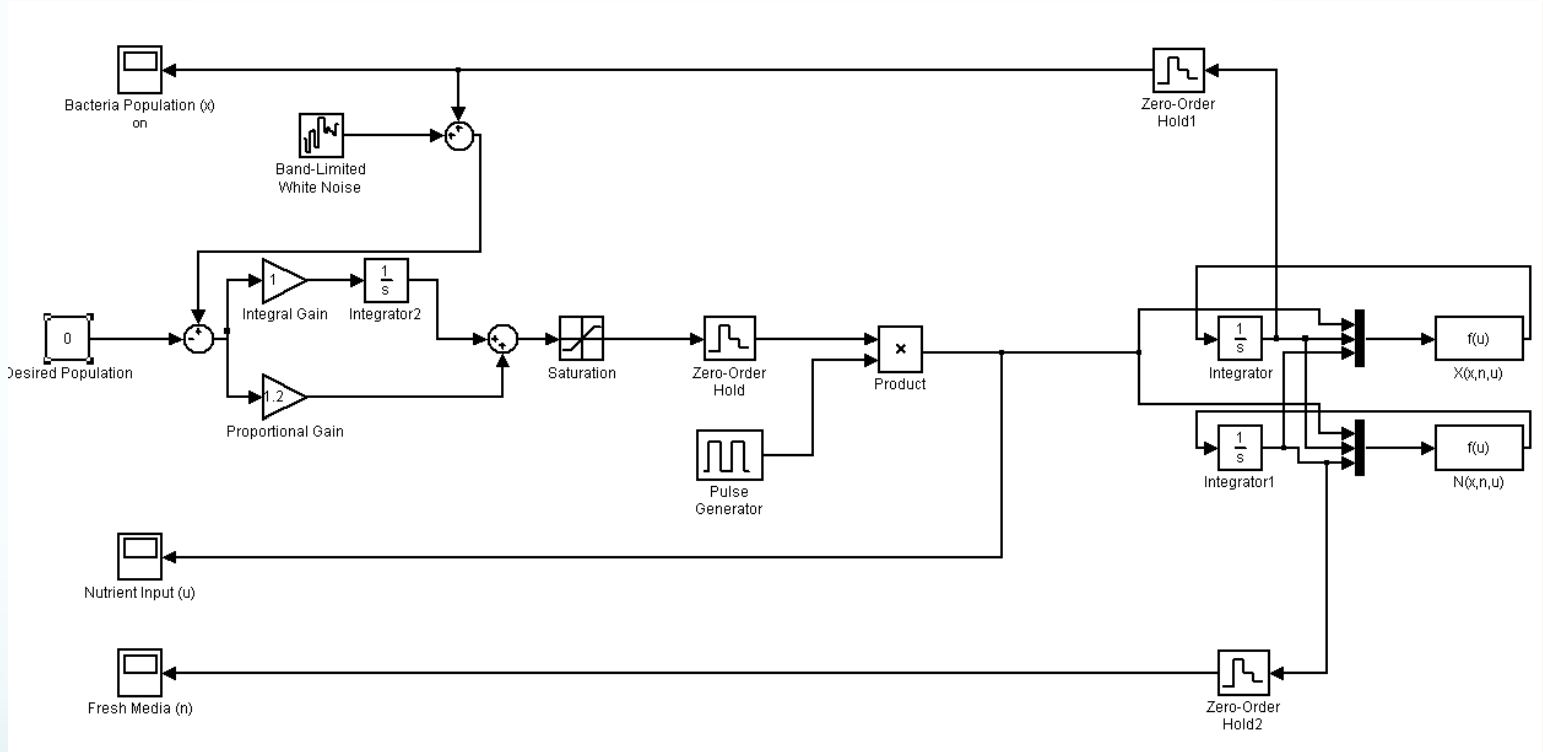
n_0 = nutrient concentration in fresh
media (g/L)

STATES

x = amount of bacteria (g/L)

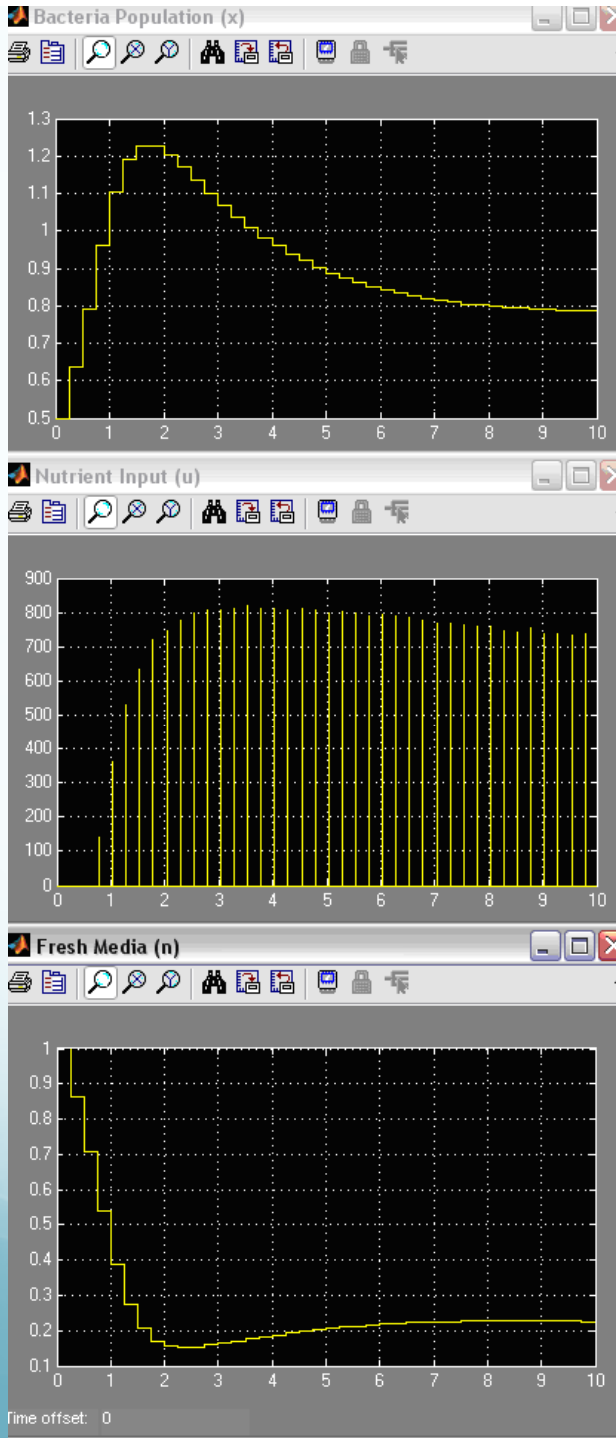
n = amount of nutrients (g/L)

System Model



Simulink Model with Discrete Characteristics

Discrete Simulation Model



Amplitude = $T / T_{on} = \text{Period} / \text{Time on of period}$, $900 / 2 \text{ sec} = 450$

Period is 15 min. Units on simulation are relative to hours but simulink reads them as seconds. This was the mistake made in the presentation that I was not aware of.

Pulse Width is .0556% or about 2 seconds of period.

Phase delay is 2 min (not sure about this yet since we haven't finished the hardware)

PI Controller Code

```
integrator_state[num_wells] := 0
```

```
while 1
```

```
  for each well W error := read_well(W)-ref
```

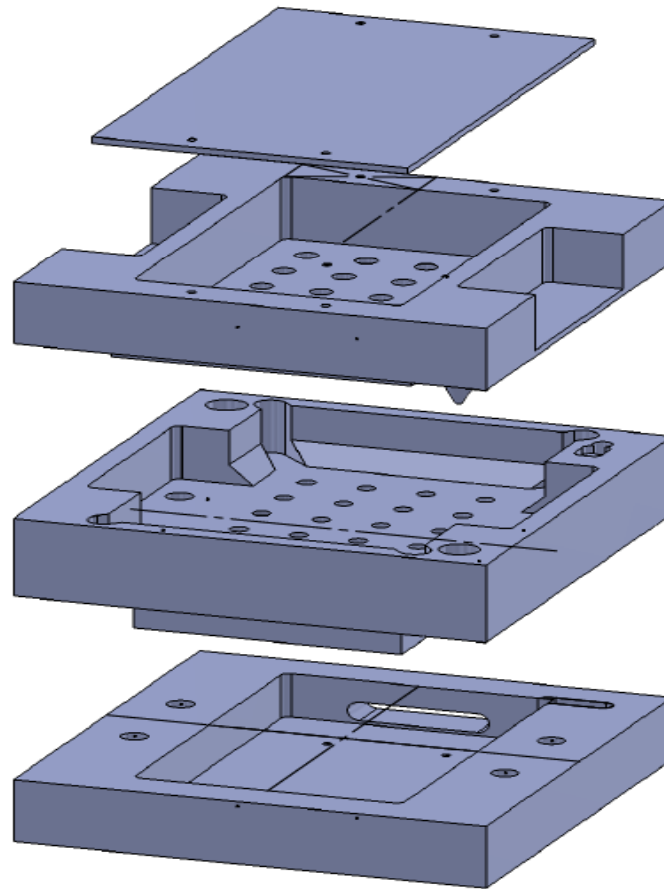
```
    integrator_state[W] := integrator_state[W]+error
```

```
    u[W] := kp*error+ki*integrator_state[W]
```

```
  output(u)
```

```
wait
```


The Making of the Plastic Housing



Step 1: Designing

- Bacteria Culture Plate
- 5.035 x 3.365 in with .844 in tall
- Primary goal: shine light through wells and read optical density



- Created fully dimensioned drawings on Solidworks
 - Generated a detailed visual of design
 - Made easy to get feedback from customer and group
 - Used SW drawings to actually make it.

Step 2: Learning g-code



- The programming language of a computed numerically controlled (CNC) machine tool.
- Sherline Model 5400 Deluxe mill with 12" base fitted with stepper motor mounts on X, Y and Z axes.
- Located in SOS Lab in EE 359

- Example g-code:
- Want to create a 2x2 inch square w/.375 bit with .2 depth
 - %
 - g20 g01 x.375 y0 z0.1 f10
 - z-0.2 f4
 - y2
 - x2
 - y.375
 - x.375
 - z1 x0 y0 f1000
 - %

Step 3: Making the Design

- CNC Mill Video

http://www.youtube.com/watch?v=quh_tLKN4Yk

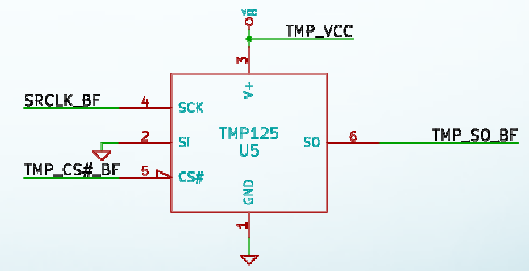
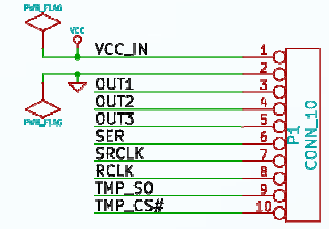
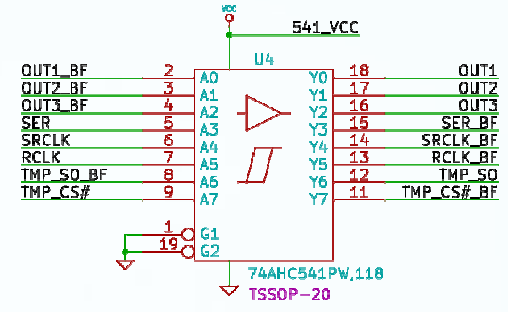
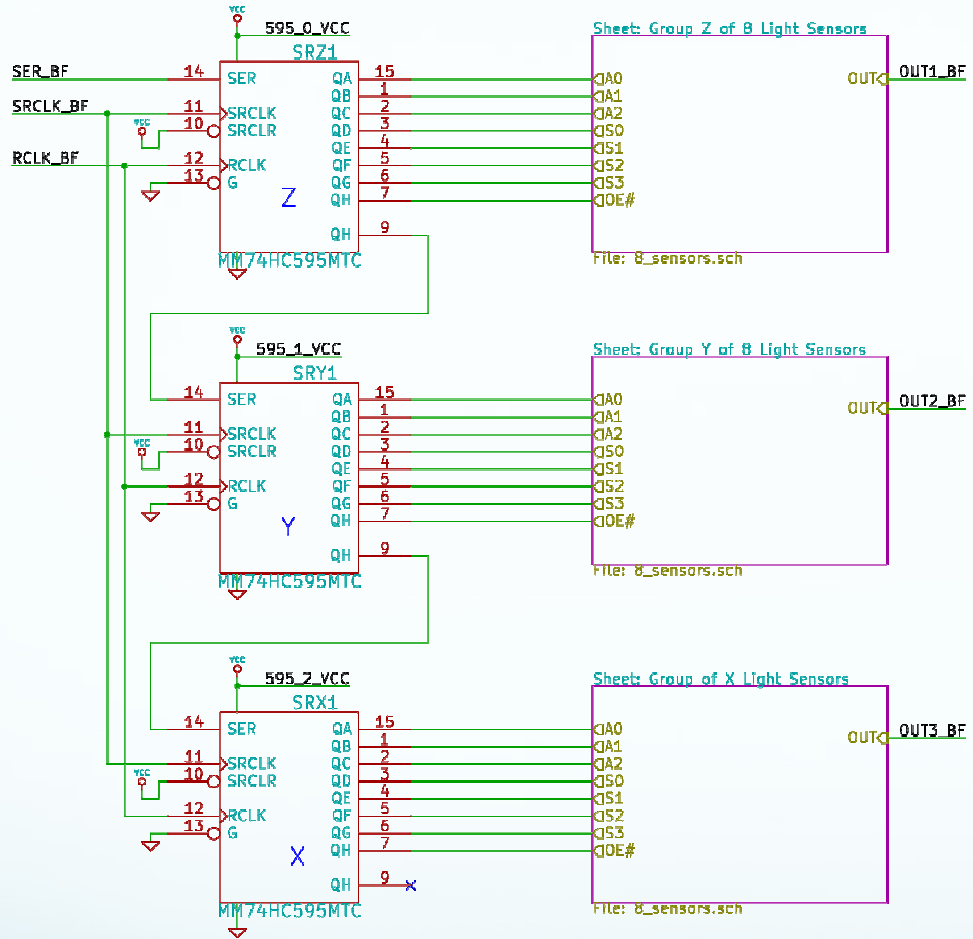
Hardware

Two Main Sections:

- Housing Unit
 - Design
 - Building
- Circuit Design
 - Photodiode
 - LED

Photodiode Board

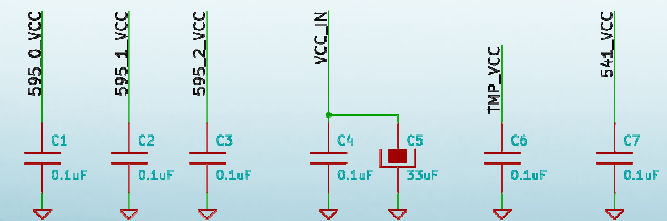
- Photodiodes (24)
 - Light to Frequency Converters
 - Used because there aren't many ADC's on microcontrollers
- Shift Registers (3)
 - Used for control signals of each "block" of eight photodiodes
 - Used Bit Banging to control
- Decoders (3, one for each "block")
 - Used to control the output enables on the photodiodes



```

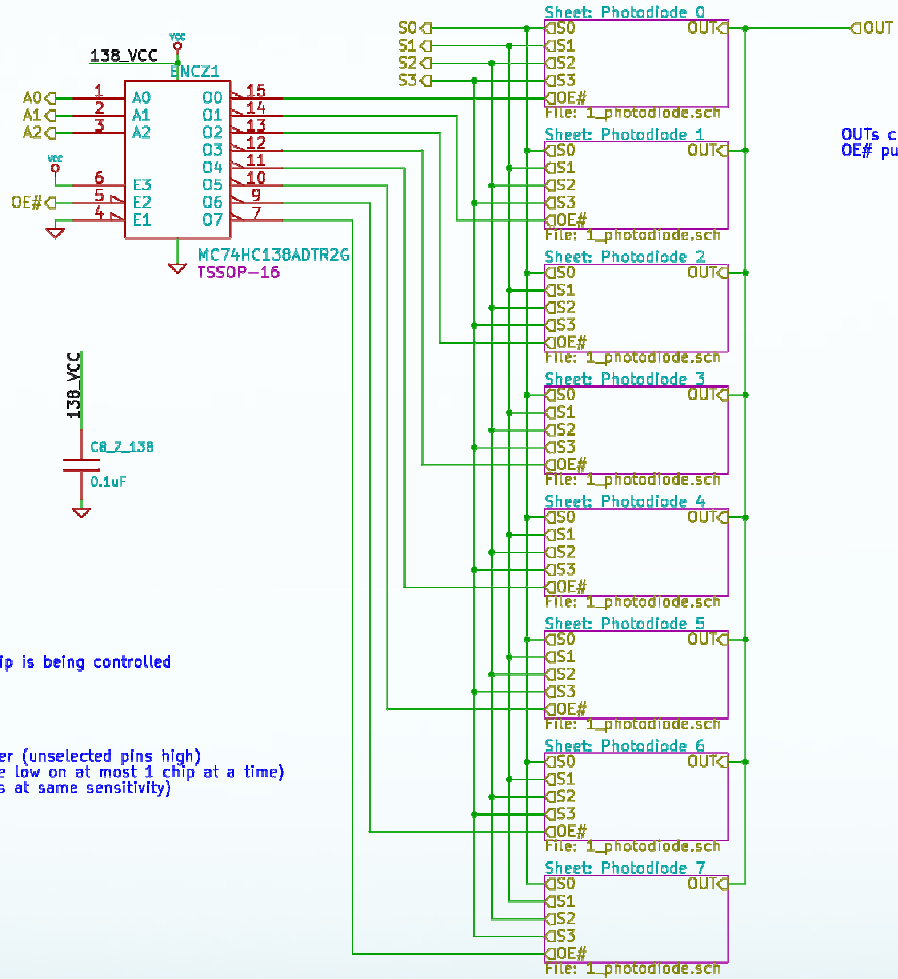
shift8(uint8_t X[OE#..A0]);
shift8(uint8_t Y[OE#..A0]);
shift8(uint8_t Z[OE#..A0]);

```



293D336X9010B2E3

University of Washington, EE449 Spring 2010		
File: photodiodes.sch		
Sheet: /		
Title: Photodiodes for the Mini-Plate Reader for the Liquid Handler		
Size: A4	Date: 19 may 2010	Rev: 1
KiCad E.D.A. eschema (2010-04-19 BZR 23xx)-unstable		Id: 1/28



OUTs can be tied together because OE# puts OUT in a high-Z state

3 groups of 8 chips

For each group:
 5 inputs, 1 output, 3 lines to select which chip is being controlled
 total: $9 \times 3 = 27$ lines to Arduino + pwr/gnd

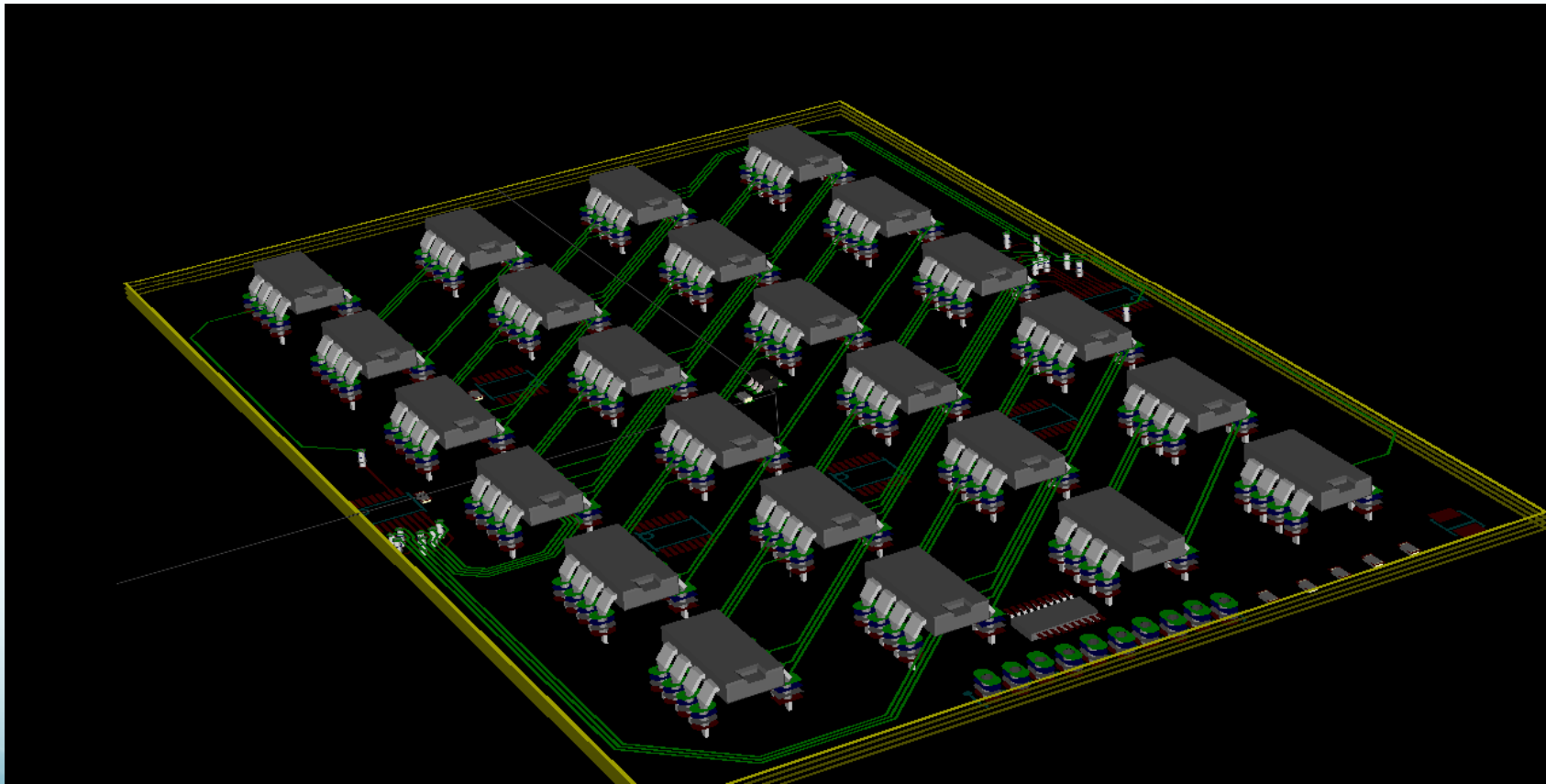
OE# = 1 for de-selected chips

ICs:

1. For OE# pins, 74xx138 – active low decoder (unselected pins high)
2. For outputs, connect together (OE# must be low on at most 1 chip at a time)
3. For S0/S1 pins, connect together (all chips at same sensitivity)
4. For S2/S3 pins, connect together.

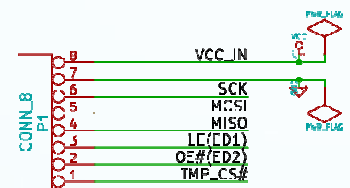
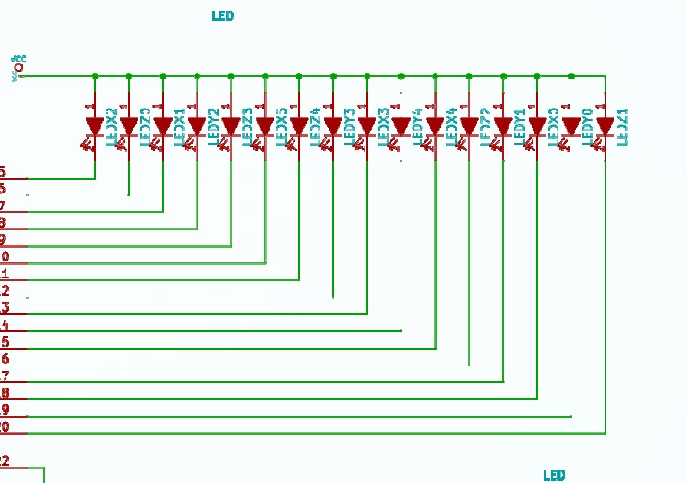
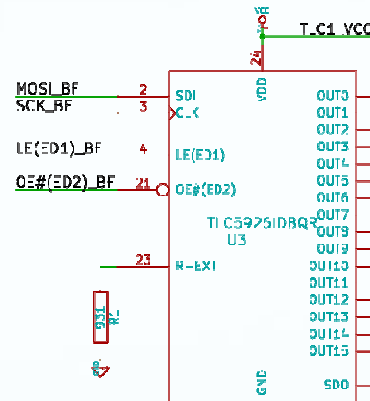
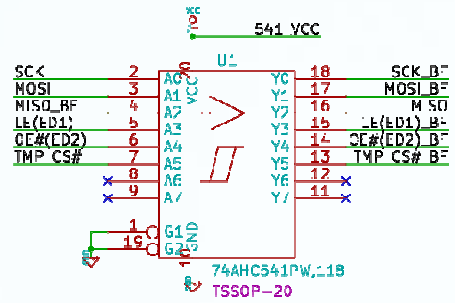
File: 8_sensors.sch		
Sheet: /Group Z of 8 Light Sensors/		
Title:		
Size: A4	Date: 19 may 2010	Rev:
KiCad E.D.A. eeschema (2010-04-19 BZR 23xx)-unstable		Id: 20/28

Photodiode Board

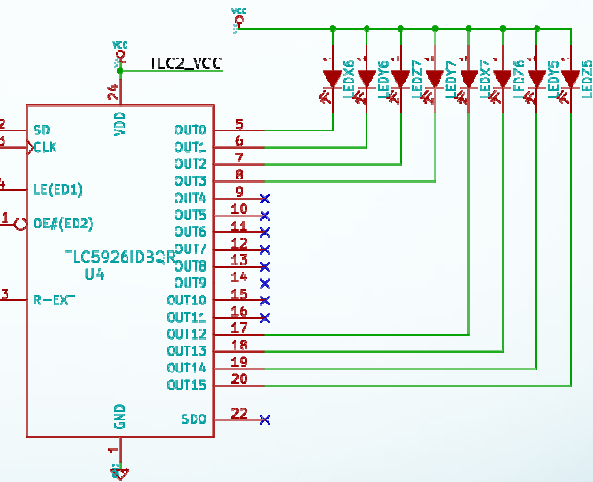
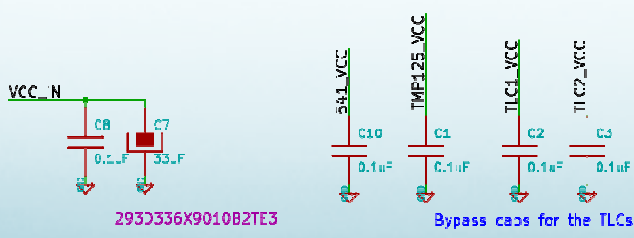
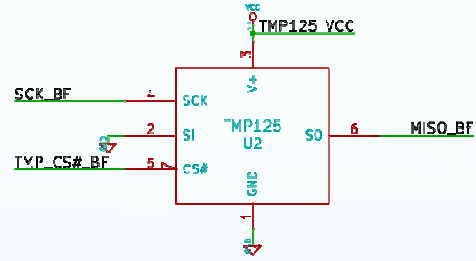


LED Board

- LEDs (24)
 - Primary wavelength output is 600nm (bacteria population absorbs this wavelength)
- Current Drivers (2)
 - Gives constant current to LEDs
 - Takes serial input and sends out parallel output to 16 different LEDs
 - Used SPI (Serial Peripheral Interface) to connect



$V_{r-ext} = 1.25V \cdot V_G$
 $I_{out} = (V_{r-ext}/R_{ext}) \cdot 15 \cdot 3^{(CM - 1)}$
 V_G is $127/128 = 0.992$ on startup
 CM is 2 at startup
 $20.1mA = (1.25V / 931\Omega) \cdot 15$ at startup

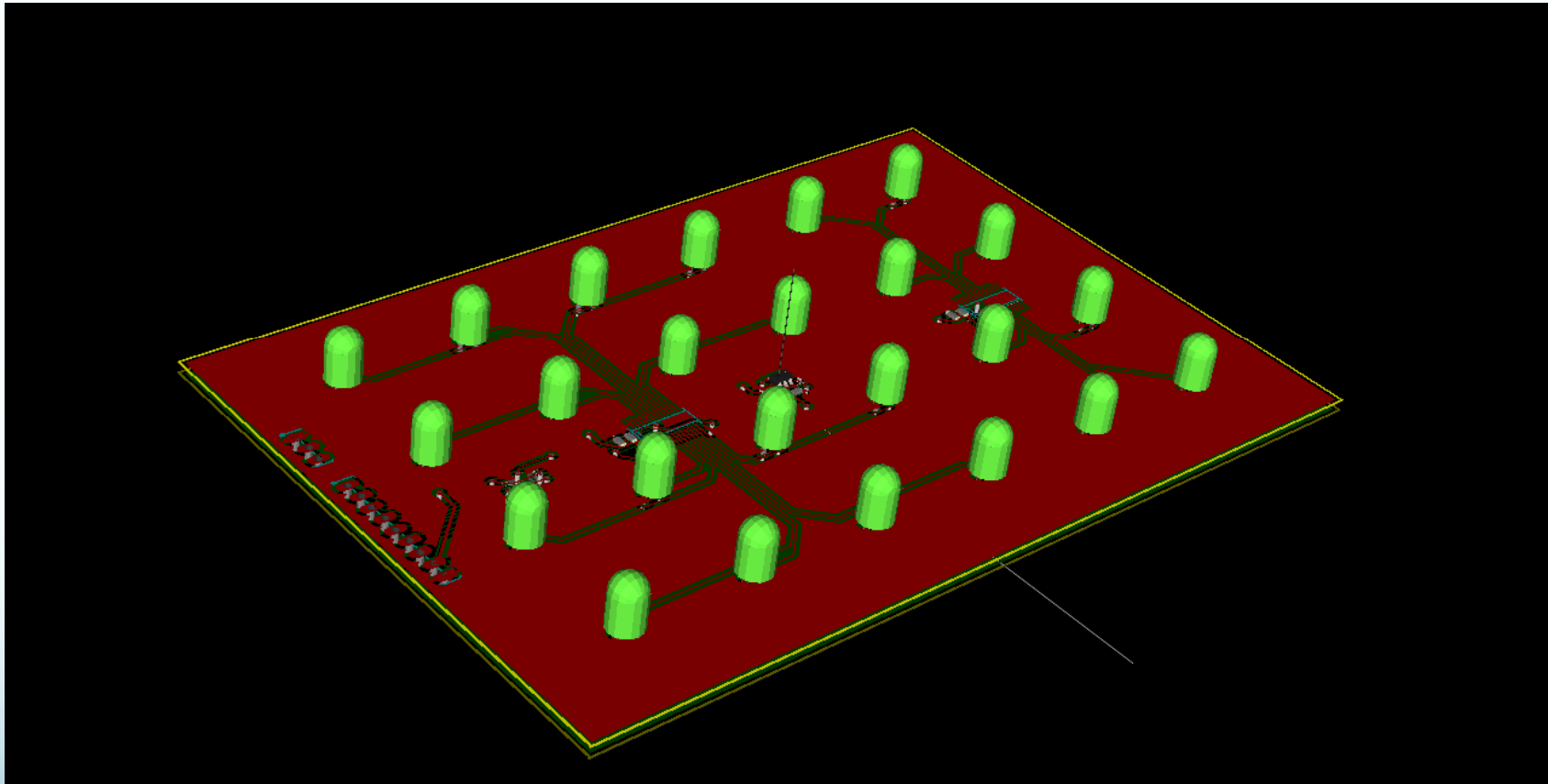


```

uint8_t leds[3]; // {X, Y, Z}
uint8_t diodes[3]; // {X, Y, Z}

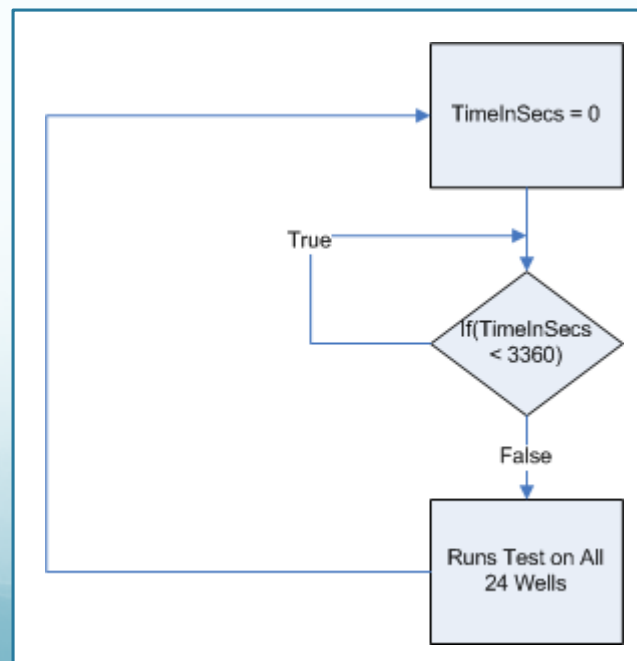
shift8(Linc= LED[23..16]);
shift8(Linc= LED[15..8]);
shift8(Linc= LED[7..0]);
  
```

LED Board



Software Design

- Use an interrupt that fires each second
 - Basically establishes operating system that checks the optical density of the wells every hour
 - Give each LED 5 seconds to warm up
 - Takes 240 seconds to read all 24 wells (10 seconds/well)



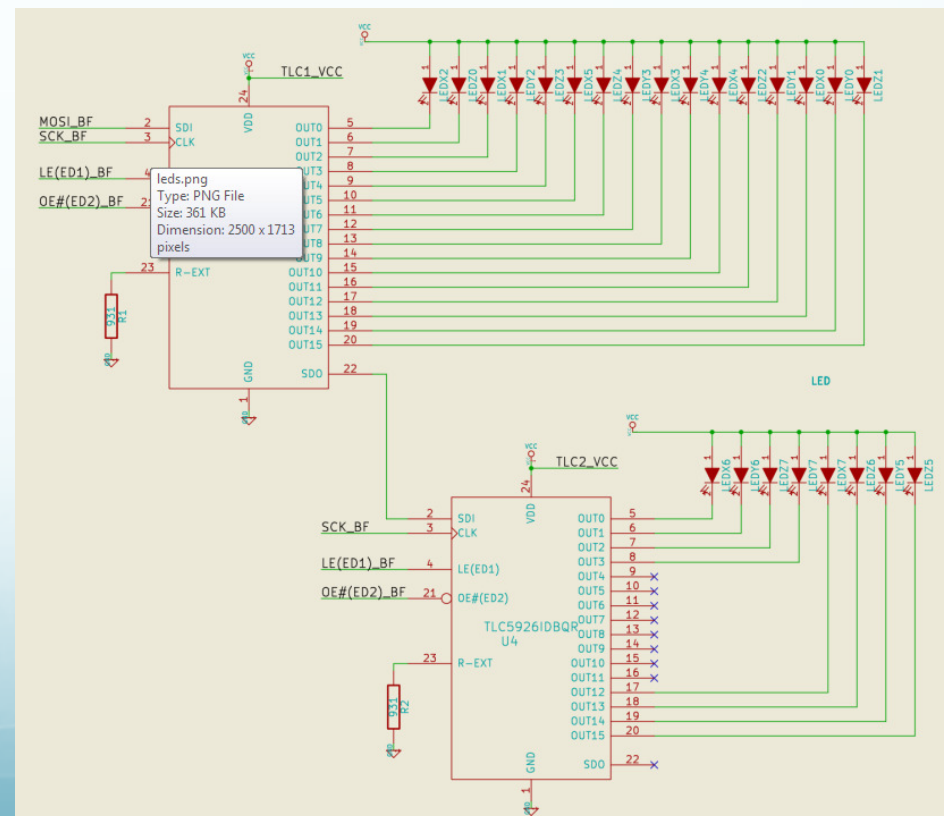
Software Design (photodiodes)

- Originally were going to use 3 UARTs (Universal Asynchronous Receiver/Transmitter) in SPI mode to control each of the blocks for photodiodes
- Arduino breakout does not have all pins of Atmega1280 available (100 pins on Atmega, only 54 on Arduino)
- Had to use “bit-banging” instead

```
for (uint8_t bit = 0x80; bit; bit >>= 1){  
    if (bit & data) {  
    }else{  
    }  
    PULSE_CLK();  
}
```


Software Design (LEDs)

- Used SPI to communicate with current drivers
- Current drivers that are on board can only run 16 LEDs, had to daisy chain current driver ICs
- SPI Command was made to send 8 bits at a time
- Used original, just sent it four times to send out all 32 bits



Goals From Last Time

- Need to modify to add two additional counters so there are a total of three (one for each “block” of photodiodes)
- Need to send outputs to decoders to enable outputs
- Need to add another current driver chip in “series” with current driver chip being used and modify SPI function to send data to second chip
- Need to interface with Shift Registers

Videos of Software and Hardware

- Current Driver Test:
<http://www.youtube.com/watch?v=zd7TAv1FRSw>
- PhotoDiode Test:
http://www.youtube.com/watch?v=UsX3_8-IDD4