## Predicting Lane Change Intensity within Urban Interchange Influence Areas (IIA)

Webinar

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Nagui M. Rouphail (Principal Investigator) Alan F. Karr, AFK Analytics, LLC (Statistical Consultant)<br>R. Thomas Chase (Research Associate) Ishtiak Ahmed (Research Assistant) Molly Burke (Undergraduate Research Assistant)<br>Dezhong Xu (Graduate Research Assistant)



## Topic Outline 专

- Project motivation and objectives
- Project outcomes
- Methods
- Modeling Results
- Tool demonstration
- Case study
- Q\&A


## Project Motivation and Objectives

- Lane changes - especially discretionary ones-- near interchange influence areas (IIAs) contribute to turbulence and have negative mobility and safety effects
- Lane changes cannot be detected using current infrastructure detection systems, possibly in the future with the advent of AV's
- To develop a tool to predict the expected intensity of lane changes at interchange influence areas (IIAs)
- To enable the identification of variables and control strategies at the IIAs that might induce fewer discretionary lane changes and thus, reduce unnecessary traffic turbulence


## Outcomes: Model and Tool Development

## Results

Predicted Hourly Lane Changes: 1551.75
Approximate Standard Error: 159.74
Confidence Bounds: $(1392.01,1711.49)$


## Research Methodology

- Based on empirical observations of lane changes at IIAs
- Project Tasks
- Data collection
- Data extraction process
- Database summary
- Model development
- Tool architecture
- Tool development and dissemination


## Data Collection

- Collection Method
- Drone videos (untethered, 300-400 ft. above ground)
- Google maps
- Automated extraction and manual verification
- Observations
- Taken in 5 min intervals, expanded to hourly rates
- Freeway Segments and definitions
- Type (basic, merge, diverge, weave)
- Length (ft)
- Number of lanes
- Lane configuration
- Distance to nearby on-ramp $\pm$
$\rightarrow$ ITRE ${ }^{\bullet}$ Distance to nearby off- ramp $\pm$


## Data Collection (continued)

## - Traffic characteristics

- Vehicle counts (at mid-segment)
- Origin-destination volumes (e.g., freeway-to-ramp and ramp-to-freeway volumes)
- Heavy vehicle percentage
- Overall space mean speed (SMS)
- Lane change counts within the segment, including minimum number of lane changes per hour



## Data Collection Sites: ~ 20 hrs. overall

| Serial | Site | Duration (min) | HCM6 Segment type |
| :---: | :---: | :---: | :---: |
| 1 | I-440 EB at Western Blvd (Pilot) | 895 | Upstream of Merge |
| 2 | I-40 WB at Wade (facing east) | 50 | Downstream of Merge |
| 3 | I-40 WB at Wade (facing west) | 55 | Downstream of Merge |
| 4 | I-440 EB at Hillsborough St Exit | 90 | Upstream of Diverge |
| 5 | I-40 EB at S. Saunders St and Hammond Rd | 85 | Weave |
| 6 | I-40 WB at S. Saunders St and Hammond Rd | 85 | Weave |
| 7 | I-440 EB at Poole Rd and US-64 | 35 | Weave |
| 8 | I-440 WB at Poole Rd and US-64 | 30 | Weave |
| 9 | Wade Ave. WB at Blue Ridge \& I-440 | 125 | Weave |
| 10 | I-440 EB at Ridge Rd | 475 | Weave |
| 11 | US-101 in Los Angeles, CA (NGSIM) | 40 | Weave |
| 12 | I-40 EB at I-440 (MM 293) | I-40 WB at I-440 (MM 293) | 35 |
| 13 | I-40 EB at I-440 (MM 309) | 35 | Basic |
| 14 |  | Basic |  |

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## Video Data Extraction

- Automated tool (DataFromSky)
- Fast
- Stabilizes drone videos
- Tracks vehicles
- Accuracy test for lane change count showed satisfactory results for passenger cars
- Manual counting
- Very labor intensive
- Limited to heavy vehicle lane change count
- Also used for accuracy testing of the automated tool


## (O) DATA FROM SKY

## Example of a processed video



## $\Rightarrow$ ITRE

## Extracting Lane Changes

- Method

1. Works with "DFS-Processed Videos"
2. Create gates along and across the lane markings using the offline DFS software
3. Extract gate crossing events and their timestamps
4. Track origin-destination lane for each lane change

- This method works very well for passenger cars (error < 5\%)
- Lane changes by heavy vehicles are manually extracted



## Create the Analysis Database

## - Database summary

- Number of directional sites: 15
- Number of data points: 247, aggregated in 5-minute observations
- Range of 5-minute observations across sites: 6 to 95
- For modeling purpose, all observations expressed in an hourly rate
- Response of interest: Total segment lane changes per hour
- Total lane changes are expressed in two components
- Mandatory (minimum number of) lane changes
- Observed range over all sites: $0 \%$ to $89 \%$ of all lane changes
- Discretionary lane changes
- Observed range over all sites: $11 \%$ to $100 \%$ of all lane changes


## Database Summary

| Variable type | Variable name | Mean | Median | St. deviation | Minimum | Maximum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Geometric | Segment length (ft) | 625 | - | - | 213 | 1,610 |
|  | Number of lanes | 4 | - | - | 3 | 6 |
|  | Min. lane change required (freeway-to-ramp) | 1 | - | - | 0 | 2 |
|  | Min. lane change required (ramp-to-freeway) | 1 | - | - | 0 | 2 |
|  | Signed distance to nearby on-ramp ( $\pm \mathrm{ft}$ ) | -126 | - | - | -2,720 | 3,132 |
|  | Signed distance to nearby off-ramp ( $\pm \mathrm{ft}$ ) | 649 | - | - | -2,960 | 6,369 |
| Traffic | Passenger car flow rate (pc/hr) | 4,965 | 5,200 | 1,598.9 | 1,416 | 8,376 |
|  | Heavy vehicle flow rate (v/hr) | 263 | 192 | 240.5 | 0 | 1,560 |
|  | Total flow rate per lane (v/hr/ln)* | 1,248 | 1,284 | 276.8 | 336 | 1,731 |
|  | VMT per hr* | 562 | 451 | 334.8 | 193 | 1,808 |
|  | Avg. speed (mi/hr) | 50 | 52 | 17.8 | 6 | 81 |
|  | Avg. density (v/mi/ln)* | 33 | 27 | 27.2 | 10 | 206 |
|  | Minimum lane changes per hr. * | 878 | 1,110 | 572.0 | 0 | 1,896 |
|  | Total lane changes per hr. | 1,373 | 1,392 | 828.4 | 108 | 4,128 |

## Modeling Approach for Lane Change Prediction

- Tested various types of statistical models
- Recommended Regression tree approach
- Observations are split into multiple homogeneous sets based on most significant splitters in the input variables
- Validation
- Self-validated as the tree is developed by a 10 -fold cross validation technique
- Site-specific validation

Total Lane changes


## Modeling Results

Partition Model to Predict Total Lane Changes Minimum Lane Changes Present as Predictor 22 Terminal Nodes


Objectives
Outcomes

## Modeling Results



## Model Performance

| Item | No Model | Model with <br> Mandatory Lane <br> Changes | Model without <br> Mandatory Lane <br> Changes |
| :---: | :---: | :---: | :---: |
| Number of terminal <br> nodes in tree | NA | 22 | 11 |
| RMSE* (LC per hour) | $828.4^{* *}$ | 121.9 | 216.3 |
| Relative RMSE*** | $60 \%$ | $8.8 \%$ | $15.8 \%$ |

Mean number of lane changes across all observations: 1,373 lc./hr.

* RMSE= Root Mean Square Error (in lane changes per hour)
** For NO Model, RMSE equivalent to standard deviation
*** Relative RMSE = RMSE / Mean \# of lane changes per hour


## Site-specific Validation

Model with Mandatory Lane Changes
Relative RMSE

| Omitted Site | Relative RMSE |  |
| :---: | :---: | :---: |
|  | Full Model | Omitted Model |
| I-40 S Saunders E | 0.07 | 0.18 |
| I-40 S Saunders W | 0.11 | 0.22 |
| I-40/440 Basic E | 0.28 | 0.29 |
| I-40/440 Basic W | 0.49 | 0.48 |
| I-40/440 East Split | 0.18 | 0.32 |
| I-40W Weave E | 0.34 | 0.33 |
| I-40W Weave W | 0.20 | 0.47 |
| I-440 at Poole Rd E | 0.08 | 0.22 |
| I-440 at Poole Rd W | 0.08 | 0.18 |
| I-440E at Hillsborough Ext. | 0.21 | 0.20 |
| RidgeRd | 0.06 | 0.25 |
| US101_Dnstrm | 0.14 | 0.78 |
| US101_Upstrm | 0.29 | 0.68 |
| US101_Wve | 0.12 | 1.68 |
| Wade W at I-440 | 18 | 0.05 |

## Key Findings from Models

- Overall, low levels of lane changing are associated with:
- Low mandatory lane change frequency, low VMT, and low speed(congested conditions)
- Other important variables effecting the prediction:
- Segment length, distance to nearby ramps, and total and passenger car flow rate
- Range of relative RMSE across all sites:
- With mandatory lane changes known : 0.05-0.49
- Without mandatory lane changes : 0.1-0.98
- Higher values are associated with basic segments as all lane changes are discretionary


## Model Limitations: Statistical

- Most important: sparsity of data
- 247 data points
- 11 input variables
- $2^{11}=2048$
- Discrete (therefore, discontinuous) predictions
- Nearly equal inputs may result in quite different predictions
- Some terminal nodes entail large confidence bounds
- Surrogate standard errors range from 59 to 467
- Potentially unreliable predictions
- Out-of-range inputs produce warnings, inputs near "boundaries" do not


## Model Limitations: Generalizability

- Dataset DOES NOT contain
- Some site geometries (e.g., left entrances)
- Bad weather (reflects use of drones)
- Construction
- Incidents
- Prospective evaluation of treatments should be done with care
- Model does not predict locations of lane changes

Objectives
Outcomes
Methods

Partition Model to Predict Total Lane Changes
Minimum Lane Changes Present as Predictor 22 Terminal Nodes


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## Tool Description and Demonstration

## Tool Description

- Architecture
- Web-based interface of the lane change prediction tool
- User guide for the tool
- Description and explanation of inputs and outputs of the tool
- Excel-based calculator
- HCM-based estimates of minimum lane changes and space mean speed
- Recommended to use only when field data are unavailable
- ReadMe file for the calculator
- Description and explanation of inputs and outputs of the calculator


## Tool Architecture



ITKE
NCSU/ITRE Network

# Web Interface Demonstration http://itredatalab.org/ Password: IIAlcpt2020)\% 

## User Guide \& Excel-based Calculator

## Case Study

- Site Description
- Wade Ave. EB between I-40W \& Edwards Mill Rd.
- Distance to nearest on-ramp: -357.5 ft
- Distance to nearest off-ramp: +357.5 ft



## Data Collection

- 35 minutes of drone footage (=7 data points)
- Total flow rate: 2,300-3,035 vph
- Heavy vehicle: 7-15\%
- Minimum lane changes: 380-694 per hour (65-90\% of total lane changes)
- Avg. speed: 65-69 mph
- Total lane changes: 432-794 per hour


## Model with MLC (Data 6-7)



## Model with MLC (Data 1-5)



## Model without MLC (Data 1-7)



## Demonstrate the Excel-based Calculator



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## THANK YOU

## Questions?



