

1 **Real-time probabilistic seismic hazard assessment based on seismicity anomaly**

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8

9 **Abstract**

10 Real-time Probabilistic Seismic Hazard Assessment (PSHA) was developed in this study in
11 consideration of its practicability for daily life and the rate of seismic activity with time. Real-time
12 PSHA follows the traditional PSHA framework, but the statistic occurrence rate is substituted by
13 time-dependent seismic source probability. Over the last decade, the Pattern Informatics method
14 (PI) has been developed as a time-dependent probability model of seismic source. We employed
15 this method as a function of time-dependent seismic source probability, and we selected two major
16 earthquakes in Taiwan as examples to explore real-time PSHA. These are the Meinong earthquake
17 (M_L 6.6) of 5 February, 2016, and the Hualien earthquake (M_L 6.2) of 6 February, 2018. The
18 seismic intensity maps produced by the real-time PSHA method facilitated forecasting the

19 maximum expected seismic intensity for the following 90 days. Compared with real ground motion
20 data from the P-alert network, our seismic intensity forecasting maps showed considerable
21 effectiveness. This result indicated that real-time PSHA is practicable and provides useful
22 information that could be employed in the prevention of earthquake disasters.

23

24 **1 Introduction**

25 Currently, research on and the application of seismic hazard analyses focus on two major aspects
26 of seismic activity, namely the pre-earthquake and post-earthquake phases. Post-earthquake
27 seismic hazard assessment is employed mainly in the Earthquake Early Warning (EEW) system
28 (Cooper, 1868; Wu et al., 1998; Wu et al., 2013), which provides people with crucial time to seek
29 refuge before the arrival of larger seismic waves. Pre-earthquake seismic hazard assessment
30 conventionally employs Probabilistic Seismic Hazard Analysis (PSHA; Cornell, 1968; SSHAC,
31 1997) mainly for engineering design. PSHA determines the probability of exceeding the ground
32 motion level over a specified time period based on the occurrence rate of earthquakes and ground
33 motion prediction equations (GMPEs). The occurrence rate of earthquakes is generally described
34 by the truncated exponential model (Cosentino et al., 1977) and the characteristic earthquake
35 model (Schwartz and Coppersmith, 1984; Wang et al., 2016). The earthquake occurrence rate
36 computed from these models will not change with time regardless of whether the data being used

37 are from long-term observations or paleoseismic studies. However, seismic activity is a complex
38 dynamic process in time and space, and usually fluctuates greatly over a short time scale (Chen et
39 al., 2006). Furthermore, the assessment is usually computed by using extremely long recurrence
40 intervals, 475 or 2475 years, for the purpose of engineering design (Iervolino et al., 2011).
41 Consequently, it is difficult to verify the accuracy of seismic hazard assessment in relation to the
42 limited lifespan of humans. Although long recurrence intervals are suitable in building
43 construction, the concept of "catastrophic" over such long intervals does not resonate with the
44 general public. In addition, most ordinary people would find it difficult to comprehend an
45 indication such as "10% probability in 50 years". Statistical long-term seismic hazard assessment,
46 therefore, does not have relevance to the daily life of most people.

47

48 However, we believe that short-term, time-dependent, pre-earthquake hazard assessment is
49 necessary for everyone's daily use. Accordingly, we propose a preliminary method to achieve this
50 goal by employing time-dependent seismic source probability instead of the static probability used
51 in long-term assessment. We used the Pattern Informatics (PI) method developed over the past
52 decade (Rundle et al., 2000; Tiampo et al., 2002; Wu et al., 2008a; Chang et al., 2016) as a time-
53 dependent seismic source probability method.

54

55 Anomalous change in seismicity is used widely as precursory indicator for large earthquakes, and
56 is usually classified into seismic activation or seismic quiescence, depending on an ascending or
57 descending number of seismicity occurrences (Chen et al., 2005; Wu et al., 2008b). In the PI
58 method, large earthquakes tend to occur after precursory anomalous seismic changes, and the
59 occurrence probability can be quantified by the magnitude of the spatiotemporal variation in
60 seismicity. In preliminary research, PI performed well in identifying locations in the vicinity of
61 impending large earthquakes. A modified version of PI developed in recent research has apparently
62 improved the accuracy of identifying the occurrence time interval of large earthquakes. After a
63 series of verifications, an occurrence probability of large earthquakes over the following 90 days
64 was found plausible (Chang et al., 2016; Chang, 2018). Accordingly, we used the modified PI
65 method to compute the time-dependent seismic source probability in Taiwan region.

66

67 We illustrate an uncomplicated method to conduct real-time seismic hazard assessment. The
68 crucial difference is to replace statistical seismic probability by the time-dependent probability
69 from the modified PI method. This real-time seismic hazard assessment is able to produce seismic
70 hazard forecasting maps for the following 90 days. Compared with the forecasting time scale and
71 static seismic rate of traditional PSHA, real-time PSHA can be updated by refreshing the
72 earthquake catalog (time-dependent), and can forecast for the near future (short-term). Thus, it can

73 be referred to as “real-time”.

74

75 We illustrate the real-time assessment process by two recent large earthquake events in Taiwan,
76 namely the 2016 Meinong earthquake (M_L 6.6) (Lee et al., 2016; Chen et al., 2017; Lee et al., 2017)
77 and the 2018 Hualien earthquake (M_L 6.2) (Hsu et al., 2018). Detailed parameters of the two
78 earthquakes are listed in Table 1. Finally, we verified the reliability of the seismic hazard
79 forecasting maps by comparing them with real ground motion data recorded by the P-alert network.

80

81 **2 Data**

82 **2.1 Central Weather Bureau Seismic Network catalog**

83 We used data from the seismic network catalog maintained by the Central Weather Bureau (CWB)
84 of Taiwan (R.O.C.) (<https://www.cwb.gov.tw/V7e/earthquake/seismic.htm> and
85 <http://gdms.cwb.gov.tw/index.php>, last accessed July 2018). The completeness magnitude (M_c) of
86 this catalog is estimated at approximately 2.0 in local magnitude (M_L) (Wu et al., 2008c). In an
87 analysis of focal depth, Wu et al. (2008b) observed that the focal depth of approximately 80% of
88 earthquakes was shallower than 30 km. Accordingly, we used M_L 2.0 and 30 km as the threshold
89 of magnitude and focal depth, respectively, to select the events to be used in the PI calculation.

90

91 2.2 P-alert Network

92 We used the ground motion recordings from the P-alert network to verify the effectiveness of the
93 real-time seismic hazard assessments from our model. The National Taiwan University (NTU)
94 commenced developing the P-alert real-time strong motion network for EEW purposes in 2010
95 with the support of the Ministry of Science and Technology (MOST) (Wu, 2015). The devices of
96 the P-alert network can record real-time three-component acceleration signals, and publish alerts
97 when the peak initial-displacement amplitude (Pd) or the peak ground acceleration (PGA) exceeds
98 predefined thresholds (Wu et al., 2013; Wu, 2015; Wu et al., 2016b). Today, there are more than
99 600 P-alert stations in Taiwan, most located in elementary schools (Wu et al., 2013; Yang et al.,
100 2018). We mainly adopted the P-alert waveform database maintained by the Taiwan Earthquake
101 Research Center (TEC), and we used the data from the NTU as an auxiliary catalog (data from the
102 P-alert network can be downloaded from the Data Center of the TEC at
103 <http://palert.earth.sinica.edu.tw/db/> [last accessed July 2018] or by contacting Prof. Yih-Min Wu
104 at drymwu@ntu.edu.tw for access to the NTU catalog).

105

106 The distribution of the P-alert network is still not uniform (see Fig. 2b and 3b), despite the large
107 number of seismic stations covering Taiwan. Obviously, this could cause problems, which will be
108 discussed later.

109

110 **3 Method**

111 **3.1 Pattern Informatics**

112 Phase dynamics is the physical fundamental of the PI method, which describes changes in a system
113 by rotation of the state vector in the Hilbert space (Rundle et al., 2002; 2003). The evolution of the
114 state vector in a dynamic fault system is suggested to be related to stress accumulation and release
115 (Chen et al., 2006). The computational steps we adopted here are a modified version developed by
116 Chang et al. (2016) and Chang (2018) to improve the spatiotemporal resolution of the PI method.
117 The research area ($119^{\circ}\sim 123^{\circ}$ E, $21^{\circ}\sim 26^{\circ}$ N) was divided into boxes of grid size $0.1^{\circ}\times 0.1^{\circ}$, with
118 each box being indicated by parameter x_i . Because of the M_c and the distribution of the focal
119 depth (mentioned in Section 2.1), we selected all the events with $M_L \geq 2.0$ and depth ≤ 30 km. In
120 PI computation, t_1 and t_2 represent the beginning and the end of a change interval, respectively,
121 with the length of a change interval being 4 years. The start time of calculation, t_0 , is defined as
122 12 years before t_2 . Then, t_b is a sampling reference time between t_0 and t_1 . The t_b starts
123 from t_0 and shifts forward 3 days in each calculation until the length of time between t_b and t_1
124 is a half change interval. The forecasting interval, t_3 , starts after t_2 (Chang, 2018). The
125 seismicity rate in the period t_b to t (t_b to t_1 and t_b to t_2) can be expressed as

126
$$S(x_i, t_b, t) = \frac{1}{t - t_b} \int_{t_b}^t n(x_i, t) dt$$

127 (1)

128 We conservatively considered the earthquake number, n , occurring in the x_i and its eight
 129 neighboring boxes. The rate change during the change interval can be expressed as

130
$$\Delta S(x_i, t_b, t_1, t_2) = S(x_i, t_b, t_2) - S(x_i, t_b, t_1)$$

131 (2)

132 $S(x_i, t_b, t)$ is a vector in a Hilbert space that records present seismic activity, so that ΔS can be
 133 interpreted as an angular drift of S (Rundle et al., 2002; Tiampo 2002). To reduce the time-
 134 dependent background seismicity, we used the temporal standard score normalizing ΔS , and
 135 obtained $\Delta \tilde{S}$. To compare the high and low levels of seismicity rate change in each grid box at the
 136 same t_b , we subsequently used the spatial standard score normalizing $\Delta \tilde{S}$, and obtained $\Delta \hat{S}$. The
 137 average of the absolute value at all t_b points in each x_i is

138
$$\Delta s(x_i) = \frac{1}{|\{t_b\}|} \sum_{t_b=t_0}^{t_b} |\Delta \hat{S}(x_i, t_b, t_1, t_2)|$$

139 (3)

140 Then, the mean squared change in probability

141
$$\Delta P(x_i) = \Delta s^2(x_i)$$

142 was computed (Chen et al., 2005; Chang et al., 2016). We further divided the magnitude range of

143 earthquakes into several segments to separately calculate the relative probabilities $\Delta P(x_i)$. The
 144 divided magnitude range is from magnitude 2.0 with window length 0.5, and it shifts forward by
 145 0.2 each time. Then, we calculated the relative probability each time, such as $\Delta P(x_i)_{2.0\sim 2.5}$,
 146 $\Delta P(x_i)_{2.2\sim 2.7}$. Finally, we multiplied all the relative probabilities.

$$147 \quad \Delta P_M = \prod \Delta P_{i\sim i+0.5} \quad (4)$$

149 ΔP_M to forecast the occurrence of earthquakes is referred to as the modified pattern informatics
 150 method (Chang, 2018). According to Chang et al. (2016), the forecasting interval of the PI method
 151 reaches 90 days. Finally, the PI method produced a forecasting probability distribution of seismic
 152 sources for $M_L \geq 5.0$ within the forecasting interval.

153

154 **3.2 Real-time PSHA**

155 In the traditional PSHA framework (Cornell, 1968; Wang et al., 2016), the probability of an
 156 earthquake occurrence follows the Poisson process and the average recurrence interval for an
 157 annual frequency of exceedance can be expressed as

$$158 \quad v(Z > z) = \sum_{i=1}^{N_s} \dot{N}_i \iint f_{M_i}(m) f_{R_i}(r) P(Z > z | m, r) dm dr \quad (5)$$

160 where $f_{M_i}(m)$ and $f_{R_i}(r)$ are the probability density functions of magnitude and distance,
 161 respectively; $P(Z > z | m, r)$ is the conditional probability of ground motion Z exceeding a
 162 specified value z for a specific magnitude m and distance r . \dot{N}_t is the annual occurrence rate
 163 of earthquakes and is described by the truncated exponential model (Cosentino et al., 1977) and
 164 the characteristic earthquake model (Schwartz and Coppersmith, 1984). Finally, to consider all
 165 scenarios, the total probability of N_s earthquakes is summarized in a given region.

166

167 In real-time PSHA, the occurrence rate of earthquakes used in the traditional PSHA framework is
 168 replaced by seismic forecasting probability to achieve spatiotemporal variability in the hazard
 169 assessment. Then, considering the gridded space, real-time PSHA can be expressed as

$$170 \quad v(Z > z) = \sum_{M_s} \sum_{Loc_s} P_{M_i, Loc_i}(m, loc) P(Z > z | m, loc)$$

171 (6)

172 where $P_{M_i, Loc_i}(m, loc)$, the forecasting probability distribution, is a function of magnitude and
 173 location. It specifies an occurrence probability for specific magnitude, M_i , at each spatial location,
 174 Loc_i . The summations are to consider the whole of the contribution from any possible magnitude,
 175 M_s , and location, Loc_s . We adopted the forecasting probability from the PI method as
 176 $P_{M, Loc}(m, loc)$. Loc refers to x_i in the PI method. The forecasting probability of the PI method

195 Lee (2008), which was adopted in Lin (2012), turns M_L into M_w . Finally, the forecasting
196 maximum PGA from real-time PSHA is transferred to seismic intensity according to the seismic
197 intensity scale of the CWB listed in Table 3 (Wu et al., 2003). This implies that the seismic intensity
198 forecasting map presents the maximum seismic intensity that every site will encounter over the
199 following 90 days.

200

201 **3.3 Performance verification**

202 **3.3.1 Receiver Operating Characteristic curve**

203 The Receiver Operating Characteristic (ROC) diagram is a binary classification model used widely
204 as a tool to quantify the performance of earthquake prediction (Holliday et al., 2006; Nanjo et al.,
205 2006; Wu et al., 2016a). We used the ROC diagram as an objective quantitative indicator to
206 evaluate the performance of the seismic forecasting probability computed by the PI method. For
207 each box, x_i , there are four situations (parameters) when comparing forecasting hotspots and
208 target earthquakes. Namely, a means any target earthquake in a hotspot, b means no target
209 earthquake in a hotspot, c means no hotspot but at least one target earthquake, d means no target
210 earthquake and no hotspot. The true positive rate (TPR) is defined as $a/(a + c)$ and the false
211 positive rate (FPR) is defined as $b/(b + d)$. The values of a , b , c , and d change with the
212 threshold of forecasting probability and, therefore, TPR and FPR change as well. The value of the

213 area under the ROC curve (AUC) varies between 0 and 1. AUC=1 is a perfect prediction and
214 AUC=0.5 is a random guess. For each PI forecasting map, we generated 1000 random test maps
215 by re-distributing the hotspots randomly over the research area to examine the possibility that a
216 specific distribution of hotspots could be generated by chance. In Fig. 1c and 1d, the blue line is
217 the 95% confidence interval based on two standard deviations. The standard deviation is calculated
218 by the random test results in each bin of the x-axis. The 95% confidence interval helps to
219 differentiate the distributing range of random tests and the significance of the forecasting
220 probability.

221

222 3.3.2 Average Percent Hit Rate

223 The success rate of forecasting seismic intensity is a predictive accuracy of classification problems
224 for which the average percent hit rate (APHR) is arguably the most intuitive discrimination
225 measure. The APHR is a rate at which the forecasting data are classified into the correct classes
226 (Sharda and Delen, 2006). We used the APHR to quantify the forecasting performance of real-time
227 seismic hazard assessments. In the APHR, the exact hit rate, which only counts the correct
228 classifications to the exact same class, can be expressed as:

229
$$\text{APHR}_{\text{exact}} = \frac{1}{N} \sum_{i=1}^g p_i$$

230 (8)

231 where, in this study, N is the total number of the P-alert stations or the boxes on the forecasting
232 hazard map, g is the total number of seismic intensity classes (=8, according to the CWB seismic
233 intensity scale), and p_i is the total number of samples classified as class i . In the random test, we
234 generated 1000 random tests by randomly re-distributing the forecasting maximum seismic
235 intensity over the research area and the stations to examine the possibility that a specific
236 distribution of the forecast could be generated by chance.

237

238 4 Results

239 4.1 Forecasting earthquake occurrences

240 Figure 1a and 1b show the forecasting probability maps computed with the PI method, and Fig. 1c
241 and 1d show the corresponding forecasting performance verified by the ROC tests. In the case of
242 the 2016 Meinong earthquake, t_0 , t_1 , and t_2 are 2004/01/31, 2012/01/31, and 2016/01/31. In
243 the case of the 2018 Hualien earthquake, t_0 , t_1 , and t_2 are 2006/01/31, 2014/01/31, and
244 2018/01/31. The forecasting intervals of both cases are 90 days after t_2 . The cyan stars in Fig. 1a
245 and 1b indicate the main shock of the 2016 Meinong and 2018 Hualien earthquakes, and the largest
246 earthquake in the forecasting interval. The gray circles in Fig. 1a and 1b are the earthquakes with
247 magnitude $M_L \geq 5.0$ in the forecasting interval, with more-detailed information about these

248 earthquakes presented in Table 1. Notably, both main shocks and most large earthquakes are
249 located in or in close proximity to hotspots. Overall, simply from visual inspection, the
250 performance of the PI forecasting probabilities appeared satisfactory.

251

252 In Fig. 1c and 1d, the red curves are located far above the blue curves (95% confidence interval).
253 The AUCs of the red curves are 0.91 and 0.94, and are apparently larger than the AUCs of the blue
254 curves, which are 0.73 and 0.70. The ROC tests quantitatively verified that the performance of the
255 PI forecasting probability was significant, and that these patterns were not generated by chance by
256 the random distribution of hotspots. Both distributions of hotspots were found to be physically
257 meaningful. In view of the above, we were able to use these probability maps as the function of
258 earthquake occurrence rate in subsequent calculations for real-time PSHA.

259

260 **4.2 Real-time PSHA**

261 In Figs 2 and 3, panel (a) shows the map forecasting the maximum seismic intensity estimated by
262 real-time PSHA for the forecasting interval, and panel (b) shows the map indicating the maximum
263 seismic intensity recorded by the P-alert network during the forecasting interval. To ensure that it
264 was the absolute maximum intensity during the forecasting interval, we used only the stations that
265 had recorded all the target events ($M_L \geq 5.0$) in the forecasting interval. Although there are over

266 600 P-alert stations distributed widely in Taiwan, some boxes do not contain any station, e.g., the
267 Central Mountain Range (see Fig. 5a and 5b). Therefore, we estimated the intensities in these
268 boxes by interpolating. However, clearly, our strategy generated an artificial effect, which will be
269 shown later.

270

271 Comparing Fig. 2a and 2b, we suggest that both seismic intensity distributions are remarkably
272 similar. An apparent deviation between the forecasted seismic intensities and the recorded values
273 occurs in southwestern Taiwan, particularly the area closer to the 2016 Meinong main shock.
274 Figure 2c shows the difference in seismic intensity between Fig. 2a and 2b, with the blue and red
275 colors indicating that the forecasting value in a box was underestimated or overestimated,
276 respectively. Most boxes have an intensity difference in the range -1 to 1, but some boxes in
277 southwestern Taiwan are underestimated, with the differences being mostly 2 or even up to 3.

278

279 Comparing Fig. 3a and 3b, we suggest that both seismic intensity distributions are still extremely
280 similar. In this instance, an apparent deviation between the forecasted seismic intensities and the
281 recorded values occurs in southern Taiwan and a part of the southwestern area. Figure 3c shows
282 that most boxes in southern Taiwan have a smaller recorded intensity, with the recorded intensities
283 in a part of southwestern Taiwan being larger than the forecasting values.

284

285 Figure 4 shows the verifications generated by the APHR to quantitatively evaluate the performance
286 of forecasting the seismic intensity. We considered the denominator of two classifications in Eq.
287 8, i.e., the total number of P-alert stations and the total number of boxes in the research area. The
288 results are indicated by “P-alert” and “Map”, respectively, in Fig. 4. When comparing forecasting
289 intensity with recorded value, both cases “forecasting = recorded” and “forecasting = recorded +1”
290 indicate “successful forecasting”. However, defining the tolerance range, which depends on the
291 perspectives and allowances of different users, is debatable (Hsu et al., 2018). In this study, we
292 tolerated an overestimation of 1 intensity rather than underestimation, as, in relation to the
293 prevention or mitigation of earthquake disasters, “overestimation” was considered preferable to
294 “underestimation”.

295

296 All the red lines are above the maximum hit rate of the random tests and higher than 0.5, not to
297 mention the random guesses of the eight choices of the seismic intensity scale on each station or
298 box. This implies that the forecasting ability of the generated seismic intensity maps is significantly
299 effective, and that this satisfactory performance could not be ascribed to chance. Furthermore, both
300 hit rates of the “P-alert” cases are higher than the rates of the “map” cases. However, this result
301 could be attributed to the influence of the artificial effect generated by the interpolation of seismic

302 intensity from the P-alert data of nonuniform distribution. Finally, it should be emphasized that we
303 focused only on earthquakes with $M_L \geq 5$ and we cannot deny the possibility that a $M_L < 5$
304 earthquake could cause large seismic intensity in the near field.

305

306 **5 Discussion**

307 The results of the APHR performance test indicated that the maps and stations employed to
308 forecast the maximum seismic intensity by real-time PSHA were significant and effective. Figure
309 5 is a concretization of the APHR verification and provides more detail. It clearly shows the P-
310 alert station distributions of the “hit” and “not hit”, considering only the station-to-station
311 prediction relationship between the forecasts and records. In both instances, most of the P-alert
312 stations are hit (Fig. 5a and 5b), and the hit percentages are distributed along the diagonal and
313 tolerant ranges (Fig. 5c and 5d). However, some locations or stations produced incorrect forecasts.
314 In the case of the 2016 Meinong earthquake, the stations located in southwestern Taiwan do not
315 match the real records and, at high seismic intensities (>3), the forecasting results at some stations
316 are underestimated (Fig. 5c), particularly in the southwestern area. In the case of the 2018 Hualien
317 earthquake, the result from the P-alert APHR appears superior to the former (Meinong), and the
318 distribution of the hit percentage is more concentrated along the diagonal and tolerant ranges (Fig.
319 5d). Nevertheless, the forecasts in southern and part of southwestern Taiwan were not hit.

320

321 In both instances, the differences between the forecasting results and the recorded seismic
322 intensities could be ascribed mainly to three aspects. First, the forecasting model that determines
323 the probability distributions of earthquake occurrences is critical in real-time PSHA. If the
324 probability distribution misses or is a false alarm in somewhere, it directly leads to inaccurate
325 forecasts in real-time PSHA. In the PI results, some differences were located on the hotspots with
326 relatively higher probability, e.g., the area in 22.6° to 23°N and 120.9° to 121.3°E in Fig. 1a, and
327 22.7° to 23.1°N and 120.4° to 120.8°E in Fig. 1b. Compared with the locations of the earthquakes,
328 these hotspots shifted slightly and it appeared acceptable. However, in the results of real-time
329 PSHA, this led to underestimation of the maximum seismic intensity in the area close to the
330 epicenters and overestimation in the area without any earthquake events but with high probability
331 of earthquake occurrence. For instance, in the case of the 2018 Hualien earthquake, the maximum
332 seismic intensity in the southwestern area was underestimated and that in the southern area
333 overestimated (see Figs 3 and 5b). Therefore, in real-time PSHA, a more accurate and precise
334 forecasting model would facilitate obtaining results that are more positive. Furthermore, even if
335 the PI results performed well in the ROC test, the PI method still needed improvement.

336

337 Second, the evaluation of earthquake ground motion is subject to the limitations of GMPEs. We

338 adopted the GMPE produced by Lin et al. (2012), whose data ($M_L \geq 5.0$) within 50 km represent
339 less than 14% of all the data for regression of GMPE. Therefore, when there is shortage of data in
340 the near field and, for larger events, in the regression of GMPEs, the applicability of GMPEs
341 become limited (Edwards and Fäh, 2014). Accordingly, the limited applicability of GMPEs
342 probably caused the deviation in evaluation of the seismic intensity forecasting maps, e.g., the
343 underestimation of the areas around the two main shocks (Figs 2c and 3c). Furthermore, it is
344 difficult to properly and comprehensively evaluate the site effect in GMPEs, but it dramatically
345 affects the behavior of seismic waves. For example, the amplitudes in the Meinong earthquake
346 were amplified extending along the northwest (in Fig. 2b) because the Western Plain is composed
347 of thick and low-velocity sedimentary deposits (see Fig. 4 in Lee et al., 2016). Consequently, the
348 site effect leads to underestimation in the seismic intensity forecast (Figs 2c and 5a).

349

350 In addition, the directivity effect plays a vital role in the distribution of ground motion. As regards
351 the main shocks in the two study cases, the rupture characteristic had a strong directivity effect
352 that caused significant amplification of the ground motion along the rupture direction (Lee et al.,
353 2016; Hsu et al., 2018). However, basically, GMPEs indicate the statistical distribution of PGA
354 generated by all the data at the same radical distance without considering the possible effect of
355 rupture directivity. As a result, GMPEs are only able to provide the ground motion estimation of

356 radial extension. Furthermore, the forecasting model does not include information on the rupture
357 direction. Therefore, we suggest that some differences along the rupture direction could be
358 ascribed to this effect.

359

360 **6 Conclusion**

361 This study presents a method to achieve real-time seismic hazard assessment by replacing the static
362 seismic rate, i.e., the truncated and characteristic earthquake models, with the time-dependent
363 seismic source probability of the PI method. With regard to this time-dependent seismic source
364 probability, ROC tests verified quantitatively that the performance of the PI forecasting
365 probabilities in the forecasting intervals was quite effective. Therefore, we were able to use the
366 significant probability distributions as the function of the earthquake occurrence rate, $P(m, loc)$,
367 in real-time PSHA. The hit rates of our seismic intensity forecasting maps generated with real-
368 time PSHA outperformed the random guesses and were higher than 0.5 for both the Meinong and
369 the Hualien earthquakes. Therefore, we suggest that real-time PSHA maps are effective forecasting
370 tools, and their satisfactory performance cannot be attributed to coincidence. We demonstrated that
371 real-time seismic hazard assessment was attainable and could be realized and updated by time-
372 dependent seismic source probability.

373

374 In future, different time-dependent seismic source probability models of earthquake occurrences
375 could be introduced to provide estimation that is more accurate and robust. In addition, a possible
376 improvement to our results could be from estimated PGA distribution, not only by means of state-
377 of-the-art machine learning tools for an extensive databank of the P-alert network but also by
378 physics-based numerical simulations (PBS) of seismic ground motion, instead of empirical
379 GMPEs. Presumably, a real-time forecasting map of seismic intensity would enable governments
380 or businesses to prepare efficiently for earthquake disasters. Furthermore, the seismicity intensity
381 scale based on PGA is related to the vulnerability level of buildings, which will also change over
382 time because of degradation and upgrades (e.g., obsolescence, retrofitting actions, and climate
383 events). Therefore, real-time PSHA and change in vulnerability should be considered when
384 assessing seismic risk fluctuation with time.

385

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392

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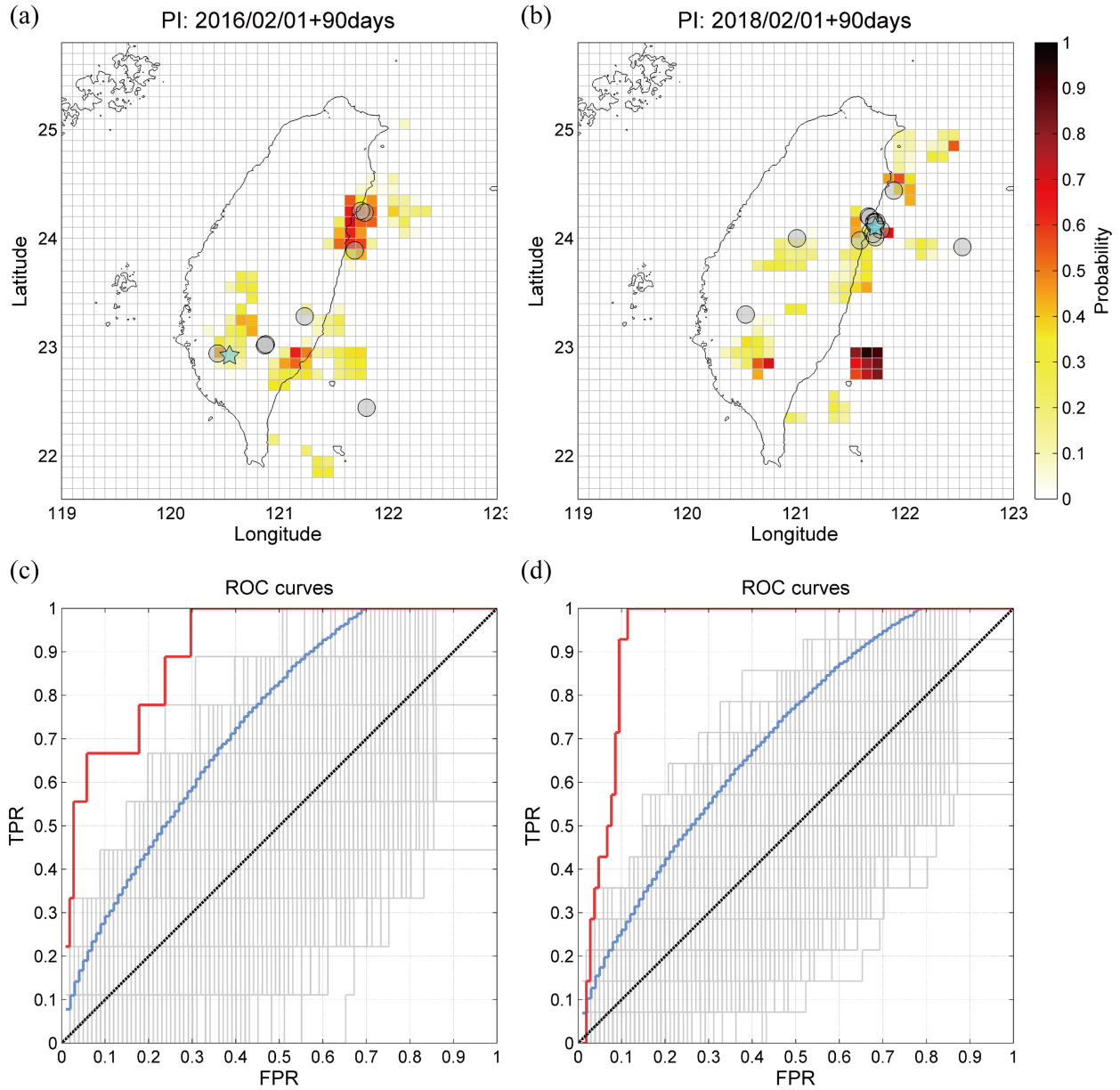
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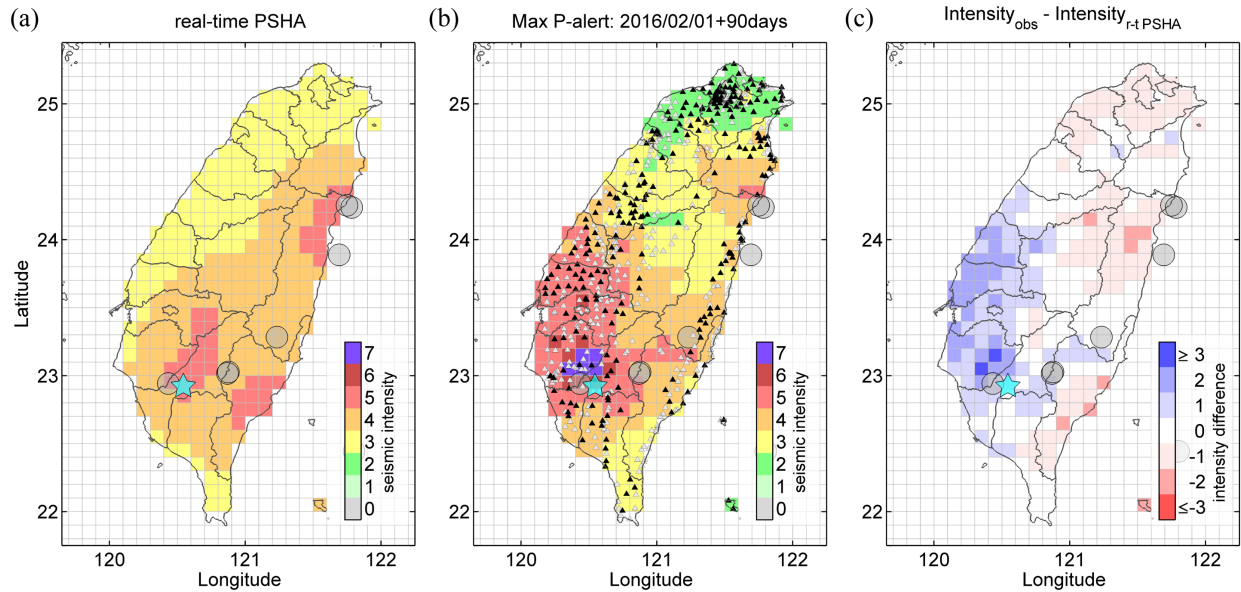
503 **Figure 1.** Panels (a) and (b) show the forecasting probability maps of the Meinong earthquake and

504 the Hualien earthquake, respectively. Panels (c) and (d) are the ROC curves of (a) and (b),

505 respectively. Red, gray, blue, and black curves represent the forecasting probability map, random

506 tests, 95% confidence interval, and the average of random tests, respectively.

507



508

509 **Figure 2.** The 2016 Meinong earthquake: (a) Map of forecasted maximum seismic intensity by
 510 real-time PSHA. The forecasting interval of seismic intensity is 90 days. (b) Map of maximum
 511 seismic intensity recorded by the P-alert network. Black and white triangles indicate the P-alert
 512 stations that we used and did not use, respectively, in the verification. (c) Difference in seismic
 513 intensity between the forecast and the record. The cyan star represents the Meinong earthquake,
 514 and the gray circles represent the earthquakes with magnitude $M_L \geq 5$ in this forecasting interval.

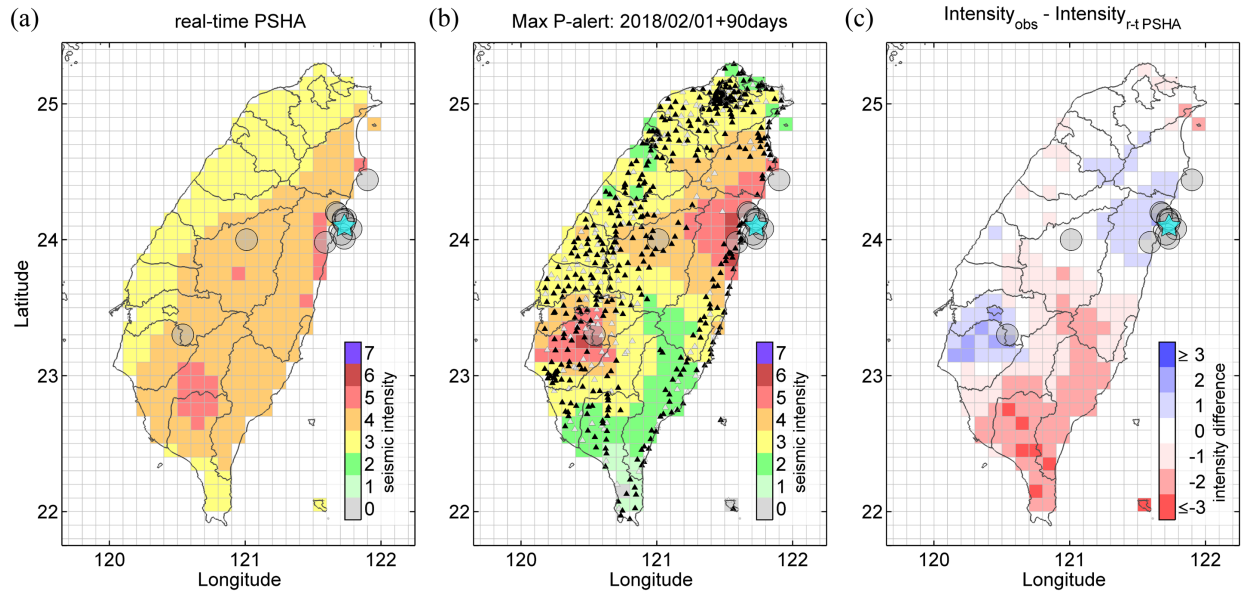
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521 **Figure 3.** The 2018 Hualien earthquake: (a) Map of forecasting maximum seismic intensity. (b)

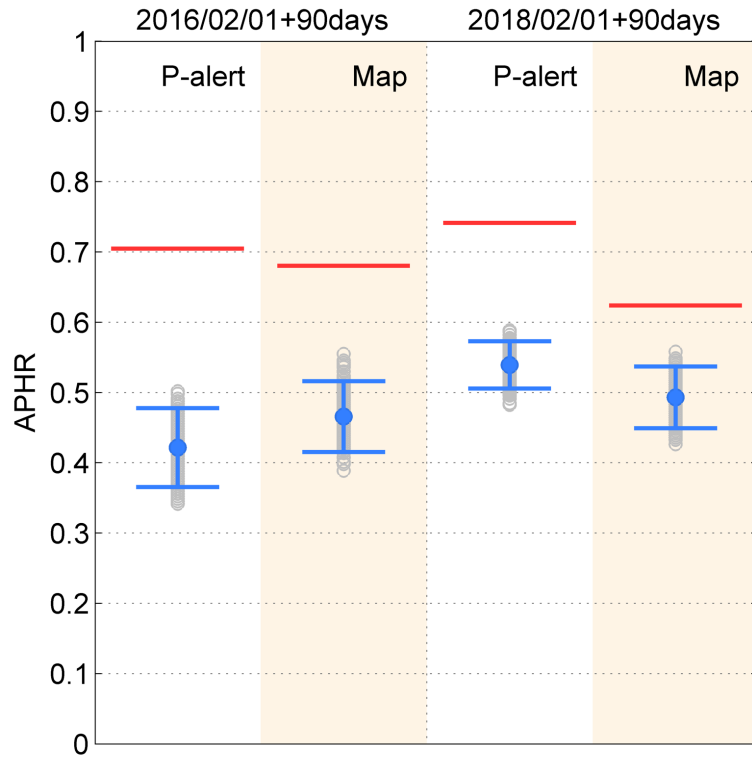
522 Map of maximum seismic intensity recorded by the P-alert network. (c) Difference in seismic

523 intensity between the forecast and the record. The cyan star represents the Hualien earthquake.

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528 **Figure 4.** Performance test of APHR. The red line indicates the forecasts of real-time PSHA, the

529 gray circle indicates the result of a random test by randomly re-distributing seismic intensities, the

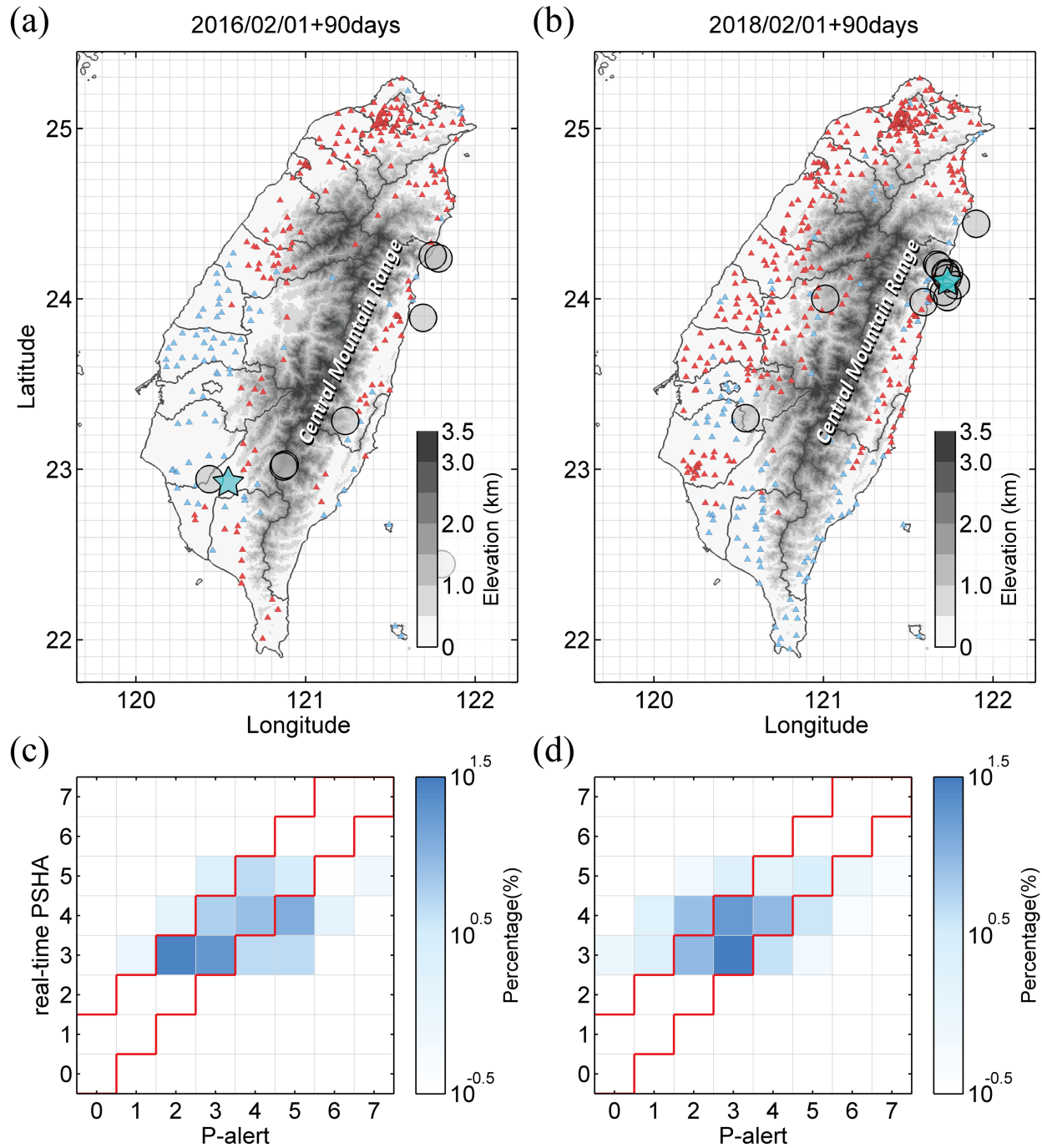
530 blue error bar indicates the interval with two standard deviations over all random tests.

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536 **Figure 5.** Panels (a) and (b) are the P-alert station distributions indicating “hit” and “not hit”. The

537 red and blue triangles represent “hit” and “not hit”, respectively. Panels (c) and (d) are the

538 distributions of the hit percentage for the 2016 Meinong and 2018 Hualien earthquakes,

539 respectively. The red line area represents the acceptable prediction range.

540

541 **Table 1.** Earthquakes occurring in the forecast interval.

(a) Meinong case: 2016/02/01~2016/05/01

Date	Hour	Min.	Lon.	Lat.	Depth	M_L	P-alert	Num.
02/05	19	57	120.54	22.92	14.64	6.60	TEC	338
02/05	19	58	120.43	22.94	18.10	5.26	Nan	Nan
02/09	00	47	121.69	23.89	5.69	5.12	TEC	341
02/18	01	09	120.87	23.02	5.44	5.27	TEC	357
02/18	01	18	120.88	23.03	4.26	5.13	TEC	357
04/16	10	55	121.80	22.44	11.83	5.22	TEC	436
04/27	15	17	121.78	24.24	11.94	5.67	NTU	424
04/27	15	27	121.75	24.25	12.99	5.13	NTU	425
04/27	18	19	121.23	23.28	15.21	5.52	NTU	423

542

(b) Hualian case: 2018/02/01~2018/05/02

Date	Hour	Min.	Lon.	Lat.	Depth	M_L	P-alert	Num.
02/04	13	12	121.67	24.20	15.10	5.10	TEC	543
02/04	13	56	121.74	24.15	10.60	5.80	TEC	519
02/04	13	57	121.68	24.19	11.10	5.10	Nan	Nan
02/04	14	13	121.72	24.15	10.30	5.50	TEC	517
02/05	15	58	121.72	24.14	10.00	5.00	TEC	522
02/06	15	50	121.73	24.10	6.30	6.20	TEC	520
02/06	15	53	121.59	23.98	5.10	5.00	TEC	520
02/06	18	00	121.73	24.12	6.70	5.30	TEC	516
02/06	18	07	121.71	24.04	4.20	5.30	TEC	516
02/06	19	15	121.73	24.01	5.70	5.40	TEC	516
02/07	15	21	121.78	24.08	7.80	5.80	TEC	523
02/25	18	28	121.90	24.44	17.70	5.20	TEC	533
03/20	09	22	120.54	23.30	11.20	5.30	TEC	539
03/29	00	17	121.01	24.00	11.10	5.00	NTU	388

04/23	17	10	122.53	23.92	19.30	5.10	NTU	381
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543 “P-alert” indicates that the P-alert recording was obtained from the Taiwan Earthquake Research
544 Center (TEC) or the National Taiwan University (NTU). “Num.” indicates the number of recording
545 stations. “Nan” indicates no P-alert data were recorded from either TEC or NTU, even if the event
546 was recorded by CWB. Bold font represents the Meinong and Hualian earthquakes.

547

548 **Table 2.** Coefficients in the GMPE.

C_1	C_2	C_3	C_4	C_5	C_6	C_7	C_8	H
1.3979	0.3700	0.0000	-1.2273	0.2086	-0.1934	0.1122	-0.4359	1.4877

549

550 **Table 3.** Seismic intensity scale of CWB.

Intensity Scale		Ground Acceleration (cm/s ² , gal)
Micro	0	<0.8
Very minor	1	0.8~2.5
Minor	2	2.5~8.0
Light	3	8~25
Moderate	4	25~80
Strong	5	80~250
Very Strong	6	250~400
Great	7	≥400