







## Today

- Review
- Motivation
  - Limitations of Polygonal Models
  - Phong Normal Interpolation
  - Some Modeling Tools & Definitions
- Curves
- Surfaces / Patches
- Subdivision Surfaces
- Procedural Texturing

MIT EECS 6.837, Durand and Cutler























Interpolation Curves
• Curve is constrained to pass through all control points
• Given points P <sub>0</sub> , P <sub>1</sub> , P <sub>n</sub> , find lowest degree polynomial which passes through the points
$\begin{split} x(t) &= a_{n-1}t^{n-1} + + a_2t^2 + a_1t + a_0 \\ y(t) &= b_{n-1}t^{n-1} + + b_2t^2 + b_1t + b_0 \end{split}$
$Q(t) = \mathbf{GBT}(\mathbf{t})$ = Geometry $\mathbf{G} \cdot \text{Spline Basis } \mathbf{B} \cdot \text{Power Basis } \mathbf{T}(\mathbf{t})$
MIT EECS 6.837, Durand and Cutler













## Higher-Order Bézier Curves

- > 4 control points
- · Bernstein Polynomials as the basis functions

$$B_i^n(t) = \frac{n!}{i!(n-i)!} t^i (1-t)^{n-i}, \qquad 0 \le i \le n$$

- Every control point affects the entire curve - Not simply a local effect
  - More difficult to control for modeling

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• But we can convert between the curves using the basis functions:

 $B_{Bezier} = \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$  $B_{B-Spline} = \frac{1}{6} \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 0 & 3 & 0 \\ 1 & 4 & 1 & 0 \end{pmatrix}$  $Q(t) = \mathbf{GBT}(\mathbf{t}) = \text{Geometry } \mathbf{G} \cdot \text{Spline Basis } \mathbf{B} \cdot \text{Power Basis } \mathbf{T(t)}$ MIT ECCS 6.837, Durand and Cutter

## NURBS (generalized BSplines)

- BSpline: uniform cubic BSpline
- NURBS: Non-Uniform Rational BSpline

   non-uniform = different spacing between the blending functions, a.k.a. knots
   rational = ratio of polynomials (instead of cubic)









































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Next Thursday: Animation I: Keyframing