



#### Scilab at a glance Example of implementation at CNES

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# Scilab Positioning and Quick Product Description



# Scilab

#### The open source platform for numerical computation

### Numerical Computation software

#### Scilab

- A growing demand,
- Used in research, simulation, control and embedded software generation processes,
- Key success factors for the development & control of the technologies of the future,
- In limited number on the market.

- Broad spectrum Open Source numerical computation software,
- Cost effective tool integrating latest scientific contributions,
- Produced by a Consortium hosted by INRIA,
- Close to 20,000 remote loadings each month,
- Yearly Growth 20% !,
- A comprehensive personal calculation platform,
- A powerful Numerical Calculation Engine easy to embed into applications,
- A foundation for dedicated toolboxes.

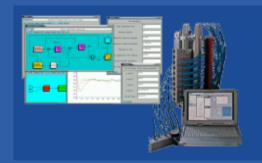


## **Scilab Environment**

#### Runs under:

- Windows 9X/2000/XP
- GNU/Linux (PC, Mac Os X)
- Most UNIX/X Window workstations

#### Large number of toolboxes:



- 2-D and 3-D graphics, animation,
- Linear algebra, sparse matrices,
- Polynomials and rational functions,
- Interpolation, approximation,
- Simulation: explicit and implicit systems of differential, equations solution,
- Scicos: block diagram modeler/simulator,
- Classic and robust control, LMI optimization,
- Differentiable and non-differentiable optimization,
- Signal processing,
- Graphs and networks,
- Parallel Scilab,
- Statistics,
- Interfaces with Computer Algebra (Maple),
- Interfaces with Fortran, LabVIEW, Tcl/Tk, C, C++, Java.

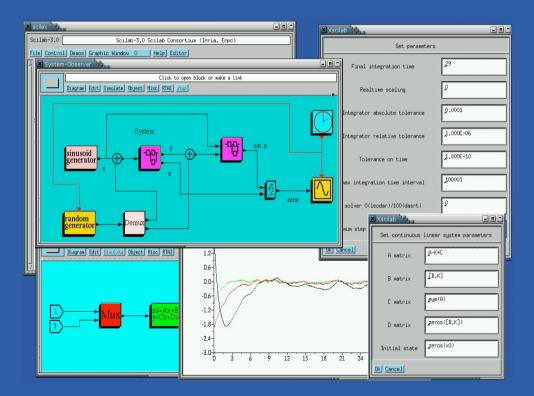




#### Hybrid Dynamic Systems

A user-friendly GUI-based editor for modeling dynamical systems as block diagrams.

Scicos is provided with Scilab





## **Scicos Functionalities**

- Hierarchical block diagram structure (super blocks),
- A large number of standard blocks available in various palettes,
- Possibility of defining new blocks using C, Fortran or Scilab language,
- Powerful formalism for modeling:
  - Hybrid systems
  - Implicit systems
  - Non causal systems using Modelica
- Diagram compilation and fast simulation,
- C code generation.



# **Scilab Major Application Fields**

- Any activity which implies the use of algorithms and/or simulation and control.
- To date, major achievements in:
  - Automotive
  - Aviation & Space
  - Energy
  - Research

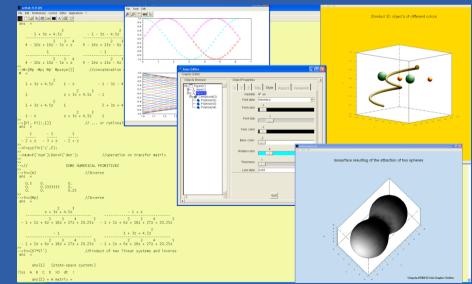


### Current release: Scilab 4.0 (February 15, 2006)

#### **Main features:**

- Improved Windows version:
  - Complete integration, virtual memory
  - Compilers, performance (Atlas libraries)
- Object oriented graphics:
  - Enhanced graphics functions (Matlab<sup>1</sup> syntax)
  - Powerful Graphics Editor
- Java interface,
- Import of Excel<sup>2</sup> files,
- Improved Matlab<sup>1</sup> -> Scilab translator.

<sup>1</sup> Matlab is a trademark of The Mathworks <sup>2</sup> Excel is a trademark of Microsoft





### Next Major Release: Scilab 5 (Autumn, 2007)

• Easier to use,

- Covering numerical computation needs from basic ones up to high performance computing requests,
- Best performance numerical computation software in selected strategic domains,
- Easier to embed in applications and to interoperate in heterogeneous environments,
- Modular,
- Integrating powerful scientific and technical breakthroughs,
- Based on industry-standard libraries and languages ...



# **The Scilab Consortium**



#### The Scilab Consortium Rational & Vision

Created, by INRIA, in 2003 to answer a widely recognized need for an Open Source Numerical Computation Tool of high quality.



### **Scilab Consortium Members**

#### 23 Companies & Academics ...

ANAGRAM TECHNOLOGIES, APPEDGE, ARTENUM, ATMEL, AXS INGENIERIE, CRIL TECHNOLOGY, CEA, CENTRALE, CNES, DASSAULT-AVIATION, EADS, ECOLE POLYTECHNIQUE, EDF, ENPC, ESTEREL TECHNOLOGIES, IFP, INRIA, KLIPPEL, PSA, RENAULT, STYREL, THALES, TNI

... Steadily growing memberships



# **Scilab Key Players**

#### Inria

French National Institute for Research in Computer Science and Control

- Consortium hosting,
- Legal responsibility,
- Main supplier in engineering breakthroughs,
- Funding.

#### **The Consortium**

- Project general management,
- Scilab roadmap decision-making authority,
- Funding.

#### **The Operational Team**

- Activity Management,
- Product management,
- Core development,
- Quality assurance,
- First level assistance,
- Contributors community coordination,
- Marketing and promotion.

#### **External Contributors**

• Specialized toolboxes.



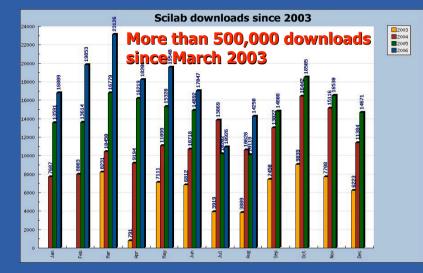
# **International Presence**

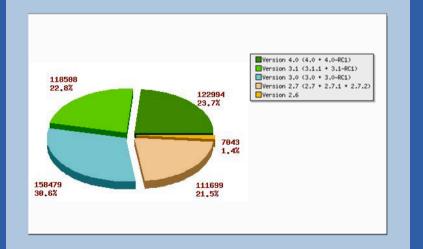


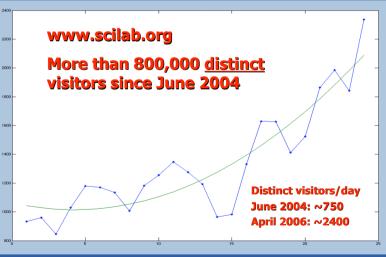
### **An Increasing Market Interest**

Scila

Scilab 4.0: Announced February 15, 2006 More than 120,000 downloads up to now







## **International Presence**



#### **Europe**

- Scilab used in the European integrated project hArtes: ATMEL Roma, THALES ...
- EADS

#### France

- Strong presence in engineering of complex systems: CEA, CNES, Dassault Aviation, EDF, IFP, PSA, Renault, Thales ...
- Scilab used as the numerical calculation platform in RNTL projects OMD and SCOS,
- Scicos used in RNTL projects SIMPA and ECLIPSE.

#### Japan

• Collaboration with NII<sup>1</sup>.

#### China

• Represented by LIAMA<sup>2</sup> since 2001.

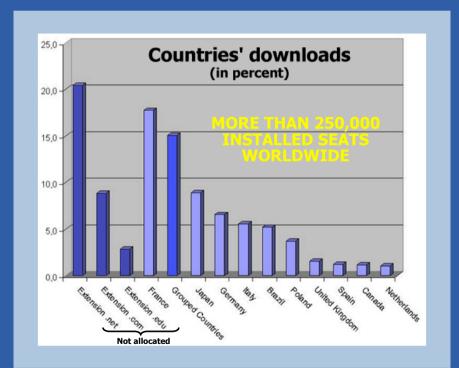
<sup>1</sup> NII: National Institute of Informatics - Japan

 <sup>2</sup> LIAMA: Sino-French Laboratory in Computer Science, Automation and Applied Mathematics
 <sup>3</sup> NMC: Numerical Mathematics

<sup>3</sup> NMC: Numerical Mathematics Consortium

#### **North America**

- Collaboration with National Instruments,
- Involved in NMC<sup>3</sup> numerical calculation standard definition.



# 2 Major Int'l Outcomes



#### The hArtes Project Biggest European funding in Embedded Systems

Develop a tool chain that support automatic or semi-automatic design of complex heterogeneous embedded systems,

Validate the tool chain on a set of innovative applications in the audio and video field.



• Applications:

FAITAL, Fraunhofer, LIA, Thales, Thomson, UNIVPM.

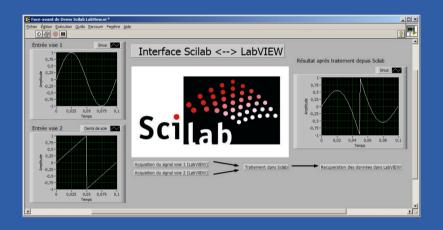
- Tools & Methodologies: Imperial College, INRIA Scilab, LEAFF, PoliMi, TU Delft.
- Hardware:

Atmel, Europe Technologies, UNIFE.

• Integration & Proof of concept: Atmel, FAITAL, Fraunhofer, Thales, Thomson, UNIVPM.



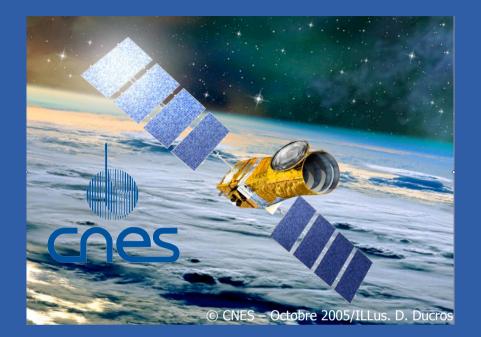
### Scilab and LabVIEW<sup>™</sup>



Scilab / LabVIEW gateway under development (Beta version announced in August 2006)

LabVIEW is a trademark of National Instruments.





# Interfacing Scilab with CNES widely used MSLIB 90 and MADONA libraries

Presentation courtesy of Franck Reinquin & Audrey Jambois CNES



## **MSLIB 90 Overview**

- MSLIB 90 is a Fortran 90 library, part of CNES flight dynamics software repository,
- Along with several other core libraries, it covers a large spectrum of flight dynamics aspects,
- MSLIB 90 is the successor of first generation MSLIB 77 and takes advantage of its robustness gained through years of operations,
- The current version represents 25 000 lines of Fortran for 152 routines, grouped in thematic sections :
  - Orbit propagation
  - Maneuvers and orbital transfers
  - Basic coordinate systems
  - Solar system ephemeredes
  - Orbital parameters and coordinate system conversions
  - Miscellaneous mathematical functions



### **MSLIB 90 Use**

- MSLIB 90 is widely used at CNES in :
  - all ground segments : FDS (Flight Dynamics Centers), missionrelated processing centers such as image processing facilities,
  - all mission preparation and analysis tools.
- Usually used from Fortran 90, the library can also be called from C,
- MSLIB90 is tested/used on many UNIX flavors (Solaris, IRIX, Linux, HP-UX, ...) and on Windows.

Sources freely available at: http://logiciels.cnes.fr (LGPL-like license)



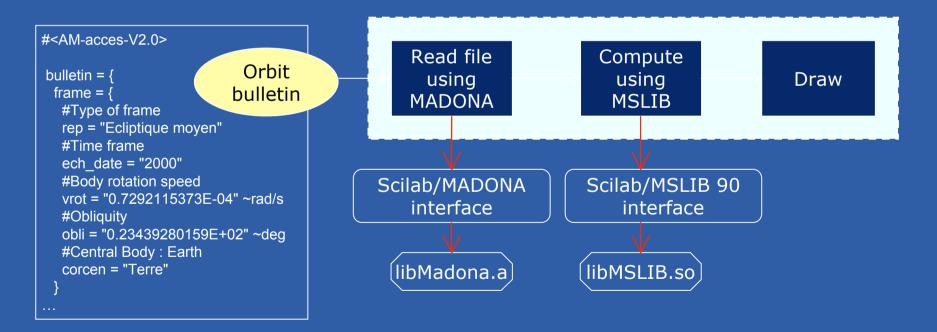
### **Scilab Implementation Project**

- More and more engineers at CNES use Scilab to perform studies,
- They request to be able to use the valuable collection of existing Fortran 90 libraries, so as to build up a new application quickly and painlessly...
- Some Fortran routines have been put together in a lightweight Scilab framework (called SpaceLab) to be used for the ATV mission analysis,
- First step is to interface MSLIB 90 with Scilab, then integrate the library + its interface into the SpaceLab framework. Then proceed with other libraries.



### The way it works

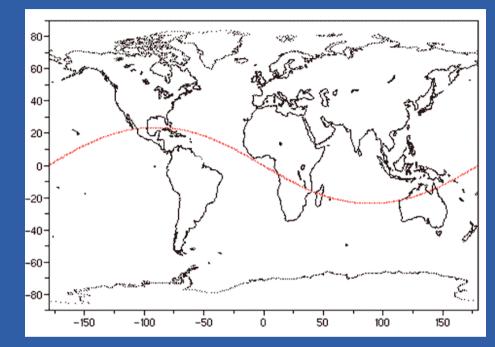
- Illustrative example of a Scilab application which reads an orbit bulletin from a file and displays the trajectory on a map,
- MSLIB 90 library is used for computations, and a dedicated file access library (called MADONA) to read the data.





### Outcome

- The required interface layer is automatically generated from the function signatures,
- Easy to use :
  - LINK command : the library and its interface are dynamically loaded,
  - CALL command : creates entry points for each MSLIB 90/MADONA function.



- Numeric precision checked for each function : identical to original call.
- Role of the interface layer :
  - maps each library routine to a Scilab command named after the library routine, with very close syntax (same argument names) : hides the complexity of the CALL function,
  - The Scilab command arguments are vectors/matrices, the library routines are called in a loop inside the interface function → performances.



### **Side Features**

• In-line comment extraction : the online help is automatically generated.

(This feature is effective with the MADONA library ; some information are currently missing in the MSLIB 90 source code headers).

sci <b>ne</b> Browse Help		
2	mr_EquaUAI_J2000	
RepereOrbitauxLocaux	Scilab fonction	
SeoPhysique	Last update : Juin 2006	
RepereFondamentaux	mr_EquaUAI_J2000 - passage du repère équatorial planétaire UAI au repère EME2000 à la date t	
📓 mr_EquaMoy_EquaVrai	Séquence d'appel	
mr_EquaMoy_J2000	Sans les arguments facultatifs : [pos_J2000,code_retour_valeur,code_retour_routine]=mr_EquaUAI_J2000(indice,planete,modeleUAI,pos_EquaUAI,jul1 950_jour,jul1950_sec)	
mr_EquaVrai_EquaMoy mr_EquaVrai_TerVrai mr_EquaVrai_veis	Avec tous les arguments facultatifs : [pos_J2000,code_retour_valeur,code_retour_routine,vit_J2000,jacob]=mr_EquaUAI_J2000_bis(indice,planete,modeleU Al,pos_EquaUAI,jul1950_jour,jul1950_sec,asc_droite,declinaison,vit_EquaUAI)	
mr_J2000_BBR	Dans tous les cas, vous pouvez ne récupérer que les arguments qui vous intéressent tant que vous conservez l'ordre d'appel	
mr_J2000_EquaMoy mr_J2000_EquaUAI mr_J2000_TerVrai	Entrées obligatoires : • indice : entier qui définit la taille des autres paramètres • planete	
mr_J2000_veis mr_mat_J2000_BBR mr_mat_nuta	<ul> <li>modeleuar modèle UAI définissant le méridien origine (temps sidéral et sa dérivée)</li> <li>pos_Equatar : vecteur position dans le repère équatorial planétaire UAI</li> <li>jul1950_jour</li> <li>jul1950_sec</li> </ul>	
mr_nuta mr_obli_moy mr_Plalner_Pla∨rai	Entrées facultatives : • asc_droite : ascension droite a0 du pôle dans EME2000 • declinaison : déclinaison d0 du pôle dans EME2000 • vit_EquaVAI : vecteur vitesse dans le repère équatorial planétaire UAI	V
mr_PlanetVrai_EquaUAI		0
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### **Project Status**

- Working prototype, not very far from a final version ; this version is made available internally,
- Still, additional work is required, in order to tackle some points originally bypassed during the prototype development :
  - the MSLIB 90 functions must currently be packed with the interface routines and the FORTRAN system libraries as a single shared library,
  - the FORTRAN optional arguments are currently considered mandatory (sort of),
  - MSLIB 90 functions use a few FORTRAN derived types (structures); their Scilab counterpart currently use only simple types (integer, real, ...) because of the CALL syntax,
- Once the process completed with MSLIB 90 and MADONA, other libraries will follow.



# Conclusion



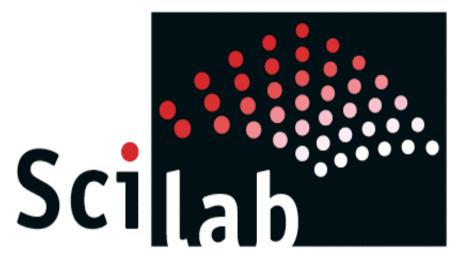
# For your Numerical Computation needs think Scilab !



#### ...and even better, join the Scilab Consortium

- To allow and reinforce further Scilab developments,
- To influence the product roadmap according to your needs,
- To benefit from attractive members rights.





A software produced by The Scilab Consortium

#### **Scilab contacts:**

Web site: www.scilab.org Technical contact: scilab@inria.fr Marketing contact: didier.halgand@inria.fr



