

# Stat 451 Lecture Notes 05<sup>12</sup>

## *Simulating Random Variables*

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<sup>1</sup>Based on Chapter 6 in Givens & Hoeting, Chapter 22 in Lange, and Chapter 2 in Robert & Casella

<sup>2</sup>Updated: March 7, 2016

- 1 Introduction
- 2 Direct sampling techniques
- 3 Fundamental theorem of simulation
- 4 Indirect sampling techniques
- 5 Sampling importance resampling
- 6 Summary

- Simulation is a very powerful tool for statisticians.
- It allows us to investigate the performance of statistical methods before delving deep into difficult theoretical work.
- At a more practical level, integrals themselves are important for statisticians:
  - p-values are nothing but integrals;
  - Bayesians need to evaluate integrals to produce posterior probabilities, point estimates, and model selection criteria.
- Therefore, there is a need to understand simulation techniques and how they can be used for integral approximations.

- Suppose we have a function  $\varphi(x)$  and we'd like to compute  $E\{\varphi(X)\} = \int \varphi(x)f(x) dx$ , where  $f(x)$  is a density.
- There is no guarantee that the techniques we learn in calculus are sufficient to evaluate this integral analytically.
- Thankfully, the law of large numbers (LLN) is here to help:

*If  $X_1, X_2, \dots$  are iid samples from  $f(x)$ , then*  
$$\frac{1}{n} \sum_{i=1}^n \varphi(X_i) \rightarrow \int \varphi(x)f(x) dx \text{ with prob 1.}$$

- Suggests that a generic approximation of the integral be obtained by sampling lots of  $X_i$ 's from  $f(x)$  and replacing integration with averaging.
- This is the heart of the *Monte Carlo method*.

# What follows?

- Here we focus mostly on simulation techniques.
- Some of these will be familiar, others probably not.
- As soon as we know how to produce samples from a distribution, the basic Monte Carlo above can be used to approximate any expectation.
- But there are problems where it is not possible to sample from a distribution exactly.
- We'll discuss this point more later.

- 1 Introduction
- 2 Direct sampling techniques
- 3 Fundamental theorem of simulation
- 4 Indirect sampling techniques
- 5 Sampling importance resampling
- 6 Summary

# Generating uniform RVs

- Generating a single  $U$  from a uniform distribution on  $[0, 1]$  seems simple enough.
- However, there are a number of concerns to be addressed.
- For example, is it even possible for a computer, which is precise but ultimately discrete, to produce *any* number between 0 and 1?
- Furthermore, how can a deterministic computer possibly generate anything that's *really* random?
- While it's important to understand that these questions are out there, we will side-step them and assume that calls of `runif` in R produce bona fide uniform RVs.

- Suppose we want to simulate  $X$  whose distribution has a given cdf  $F$ , i.e.,  $\frac{d}{dx}F(x) = f(x)$ .
- If  $F$  is continuous and strictly increasing, then  $F^{-1}$  exists.
- Then sampling  $U \sim \text{Unif}(0, 1)$  and setting  $X = F^{-1}(U)$  does the job — *can you prove it?*
- This method is (sometimes) called the *inversion method*.
- The assumptions above can be weakened to some extent.



## Example – exponential distribution

- For an exponential distribution with rate  $\lambda$ , we have

$$f(x) = \lambda e^{-\lambda x} \quad \text{and} \quad F(x) = 1 - e^{-\lambda x}.$$

- It is easy to check that the inverse cdf is

$$F^{-1}(u) = -\log(1 - u)/\lambda, \quad u \in (0, 1).$$

- Therefore, to sample  $X$  from an exponential distribution:

- 1 Sample  $U \sim \text{Unif}(0, 1)$ .

- 2 Set  $X = -\log(1 - U)/\lambda$ .

- Can be easily “vectorized” to get samples of size  $n$ .
- This is in the R function `rexp` — be careful about rate vs. scale parametrization.

## Example – Cauchy distribution

- The standard Cauchy distribution has pdf and cdf

$$f(x) = \frac{1}{\pi(1+x^2)} \quad \text{and} \quad F(x) = 1/2 + \arctan(x)/\pi.$$

- This distribution has shape similar to normal, but tails are much heavier — Cauchy has *no finite moments*.
- But its cdf can be inverted:

$$F^{-1}(u) = \tan[\pi(u - 1/2)], \quad u \in (0, 1).$$

- To generate  $X$  from standard Cauchy:
  - Sample  $U \sim \text{Unif}(0, 1)$ .
  - Set  $X = \tan[\pi(U - 1/2)]$ .
- Non-standard Cauchy (location  $\mu$  and scale  $\sigma$ ):  $\mu + \sigma X$ .
- Use `rt(n, df=1)` in R.

## Example – discrete uniform distribution

- Suppose we want  $X$  to be sampled uniformly from  $\{1, \dots, N\}$ .
- Here is an example where the cdf is neither continuous nor strictly increasing.
- The idea is as follows:
  - 1 Divide up the interval  $[0, 1]$  into  $N$  equal subintervals; i.e.,  $[0, 1/N), [1/N, 2/N)$  and so forth.
  - 2 Sample  $U \sim \text{Unif}(0, 1)$ .
  - 3 If  $i/N \leq U < (i+1)/N$ , then  $X = i + 1$ .
- More simply, set  $X = \lfloor nU \rfloor + 1$ .
- This is equivalent to `sample(N, size=1)` in R.

## Example – triangular distribution

- The (symmetric!) pdf of  $X$  is given by

$$f(x) = \begin{cases} 1 + x & \text{if } -1 \leq x < 0, \\ 1 - x & \text{if } 0 \leq x \leq 1. \end{cases}$$

- If we restrict  $X$  to  $[0, 1]$ , then the cdf is simply

$$\tilde{F}(x) = 1 - (1 - x)^2, \quad x \in [0, 1].$$

- For this “sub-problem” the inverse is

$$\tilde{F}^{-1}(u) = 1 - \sqrt{1 - u}, \quad u \in [0, 1].$$

- To sample  $X$  from the triangular distribution:

- 1 Sample  $U \sim \text{Unif}(0, 1)$ .
- 2 Set  $\tilde{X} = 1 - \sqrt{1 - U}$ .
- 3 Take  $X = \pm \tilde{X}$  based on a flip of a coin.

# Sampling normal RVs

- While normal RVs can, in principle, be generating using the cdf transform method, this requires evaluation of the standard normal inverse cdf, which is a non-trivial calculation.
- There are a number of fast and efficient alternatives for generating normal RVs.
- The one below, due to Box and Muller, is based on some trigonometric transformations.

- This method generates a pair of normal RVs  $X$  and  $Y$ .
- The method is based on the following facts:
  - The cartesian coordinates  $(X, Y)$  are equivalent to the polar coordinates  $(\Theta, R)$ , and the polar coordinates have a joint pdf

$$(2\pi)^{-1} r e^{-r^2/2}, \quad (\theta, r) \in [0, 2\pi] \times [0, \infty).$$

- Then  $\Theta \sim \text{Unif}(0, 2\pi)$  and  $R^2 \sim \text{Exp}(2)$  are independent.
- So to generate independent normal  $X$  and  $Y$ :
  - 1 Sample  $U, V \sim \text{Unif}(0, 1)$ .
  - 2 Set  $R^2 = -2 \log V$  and  $\Theta = 2\pi U$ .
  - 3 Finally, take  $X = R \cos \Theta$  and  $Y = R \sin \Theta$ .
- Take a linear function to get different mean and variance.

- Perhaps the simplest RVs are Bernoulli RVs – ones that take only values 0 or 1.
- To generate  $X \sim \text{Ber}(p)$ :
  - 1 Sample  $U \sim \text{Unif}(0, 1)$ .
  - 2 If  $U \leq p$ , then set  $X = 1$ ; otherwise set  $X = 0$ .
- In R, use `rbinom(n, size=1, prob=p)`.

- Since  $X \sim \text{Bin}(n, p)$  is distributionally the same as  $X_1 + \dots + X_n$ , where the  $X_i$ 's are independent  $\text{Ber}(p)$  RVs, the previous slides gives a natural strategy to sample  $X$ .
- That is, to sample  $X \sim \text{Bin}(n, p)$ , generate  $X_1, \dots, X_n$  independently from  $\text{Ber}(p)$  and set  $X$  equal to their sum.



- Poisson RVs can be constructed from a Poisson process, an integer-valued continuous time stochastic process.
- By definition, the number of events of a Poisson process in a fixed interval of time is a Poisson RV with mean proportional to the length of the interval.
- But the time between events are independent exponentials.
- Therefore, if  $Y_1, Y_2, \dots$  are independent  $\text{Exp}(1)$  RVs, then

$$X = \max\{k : \sum_{i=1}^k Y_i \leq \lambda\}$$

then  $X \sim \text{Pois}(\lambda)$ .

- In R, use `rpois(n, lambda)`.

- The chi-square RV  $X$  (with  $n$  degrees of freedom) is defined as follows:
  - $Z_1, \dots, Z_n$  are independent  $N(0, 1)$  RVs.
  - Take  $X = Z_1^2 + \dots + Z_n^2$ .
- Therefore, to sample  $X \sim \text{ChiSq}(n)$  take the sum of squares of  $n$  independent standard normal RVs.
- Independent normals can be sampled using Box–Muller.

- A Student-t RV  $X$  (with  $\nu$  degrees of freedom) is defined as the ratio of a standard normal and the square root of an independent (normalized) chi-square RV.
- More formally, let  $Z \sim N(0, 1)$  and  $Y \sim \text{ChiSq}(\nu)$ ; then

$$X = Z / \sqrt{Y/\nu}$$

is a  $t_\nu$  RV.

- Remember the scale mixture of normals representation...?
- In R, use `rt(n, df=nu)`.

# Multivariate normal RVs

- The  $p$ -dimensional normal distribution has a mean vector  $\boldsymbol{\mu}$  and a  $p \times p$  variance-covariance matrix  $\boldsymbol{\Sigma}$ .
- The techniques above can be used to sample a vector  $Z = (Z_1, \dots, Z_p)'$  of independent normal RVs.
- But how to incorporate the dependence contained in  $\boldsymbol{\Sigma}$ ?
- Let  $\boldsymbol{\Sigma} = \boldsymbol{\Omega}\boldsymbol{\Omega}'$  be the Cholesky decomposition of  $\boldsymbol{\Sigma}$ .
- It can be shown that  $X = \boldsymbol{\mu} + \boldsymbol{\Omega}Z$  is the desired  $p$ -dimensional normal distribution.
- Can you prove it?

- 1 Introduction
- 2 Direct sampling techniques
- 3 Fundamental theorem of simulation**
- 4 Indirect sampling techniques
- 5 Sampling importance resampling
- 6 Summary

- Let  $f$  be a density function on an arbitrary space  $\mathbb{X}$ ; the goal is to simulate from  $f$ .
- Note the trivial identity:

$$f(x) = \int_0^{f(x)} du.$$

- This identity implicitly introduces an *auxiliary variable*  $U$  with a conditionally uniform distribution.
- The intuition behind this viewpoint is that simulating from the joint distribution of  $(X, U)$  might be easy, and then we can just throw away  $U$  to get a sample of  $X \sim f \dots$

# The “theorem”

- **“Theorem.”** Simulating  $X \sim f$  is equivalent to simulating

$$(X, U) \sim \text{Unif}(\{(x, u) : 0 < u < f(x)\})$$

and then throwing away  $U$ .

- *Proof:* Write the density of  $(X, U)$  and integrate out  $U$ .
- How to implement this?
  - One kind-of silly<sup>3</sup> idea:

$$X \sim f \quad \text{and} \quad U \mid (X = x) \sim \text{Unif}(0, f(x)).$$

- A better idea: “conditioning preserves uniformity,” i.e.,

$$Z \sim \text{Unif}(\mathbb{Z}) \implies Z \mid (Z \in \mathbb{Z}_0) \sim \text{Unif}(\mathbb{Z}_0).$$

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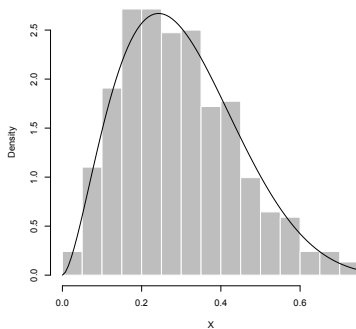
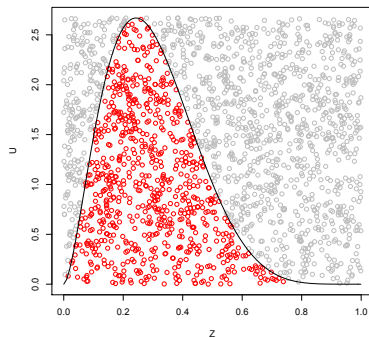
<sup>3</sup>Not actually silly, it’s used in the accept–reject method...

- The “conditioning preserves uniformity” point can be interpreted as follows.
  - Suppose that  $A$  is a set that contains  $\{(x, u) : 0 < u < f(x)\}$ .
  - Simulate  $(X, U)$  uniformly on  $A$ , and keep  $(X, U)$  only if  $U < f(X)$ .
  - Such a pair  $(X, U)$  is uniformly distributed on the constraint set, so  $X$  has the desired distribution  $f$ .
- Efficiency of sampling depends on how tightly  $A$  fits the desired constraint set.
- For a one-dimensional  $X$ , with bounded support and bounded  $f$ , a reasonable choice for  $A$  is a rectangle; see below.
- Idea extends — this is what the next sections are about!



# Example – beta simulation

- Simulate from a Beta(2.7, 6.3) distribution.
- Start with uniforms in a box but keep only those that satisfy the constraint.
- Simulated 2000 uniforms, kept only 744 betas.



- 1 Introduction
- 2 Direct sampling techniques
- 3 Fundamental theorem of simulation
- 4 Indirect sampling techniques**
  - Acceptance–rejection sampling
  - Ratio method
- 5 Sampling importance resampling
- 6 Summary

- 1 Introduction
- 2 Direct sampling techniques
- 3 Fundamental theorem of simulation
- 4 Indirect sampling techniques**
  - Acceptance–rejection sampling
  - Ratio method
- 5 Sampling importance resampling
- 6 Summary

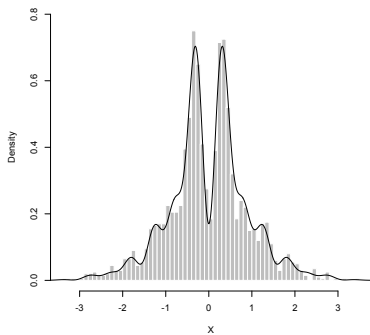
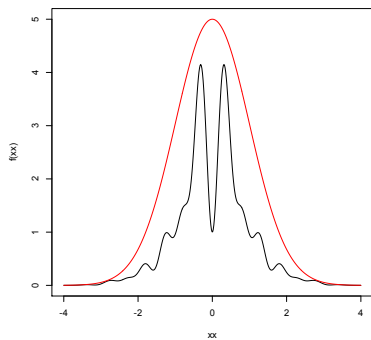
- Suppose we want to sample from a distribution with pdf  $f(x)$ .
- Suppose, further, that  $f(x) \leq h(x) := Mg(x)$  where  $g(x)$  is a (simple) pdf and  $M$  is a constant  $> 1$ .
- We say  $h(x)$  majorizes  $f(x)$ .
- The goal is to use samples from the (easy to sample) pdf  $g(x)$  as “approximate samples” from  $f(x)$ .
- But it is clear that unless  $g(x) \approx f(x)$ , there will be samples from  $g$  that are not representative of  $f$ .
- The idea is to throw away those “bad” samples.

# Acceptance–rejection method

- The rule that determines when a sample is “thrown away” is called the *acceptance–rejection method*.
- To approximately sample  $X$  from  $f(x)$ :
  - 1 Sample  $U \sim \text{Unif}(0, 1)$ .
  - 2 Sample  $X' \sim g(x)$ .
  - 3 Keep  $X = X'$  if  $U \leq f(X')/h(X')$
- Try to prove the following:
  - accept–reject returns a sample from  $f$  (see “theorem”);
  - acceptance probability is  $1/M$ .
- Goal is to make acceptance prob high, i.e.,  $M \approx 1\dots$  (?)
- Note: it is not necessary to know  $f$  exactly—it’s enough to know  $f$  only up to a proportionality constant.

# Example – Robert & Casella book cover

- True density is a weird trig function – see code.
- Majorant is a normal.
- Histogram of  $n = 2000$  samples from trig density.



## Example – von Mises distribution

- Consider the von Mises distribution with pdf

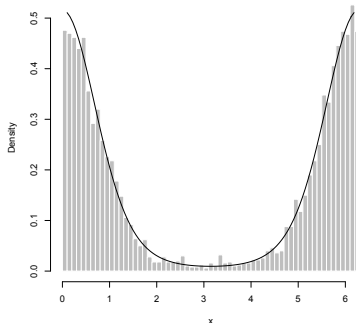
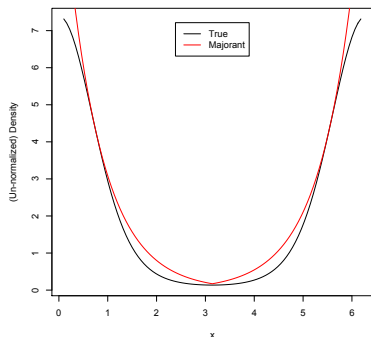
$$f(x) = \frac{\exp\{-\kappa \cos x\}}{2\pi I_0(\kappa)}, \quad x \in [0, 2\pi],$$

where  $I_0(\kappa)$  is a Bessel function.

- This distribution is often referred to as a circular normal distribution, and is a popular model in *directional statistics*.
- To sample from the von Mises distribution for fixed  $\kappa$ , we implement the acceptance-rejection method with majorant made out of exponential pdfs.
- Only trick is to get a “good” envelope/majorant.
- See code for more details.

# von Mises distribution (cont.)

- von Mises distribution with  $\kappa = 2.4$
- Uses two oppositely oriented exponentials for the envelope.
- $n = 5000$  samples; acceptance rate (for  $\kappa = 2$ ) is  $\approx 0.81$ .



<sup>4</sup>For some reason, majorant construction in my code only works for  $\kappa > 1...$



## Example – small-shape gamma distribution

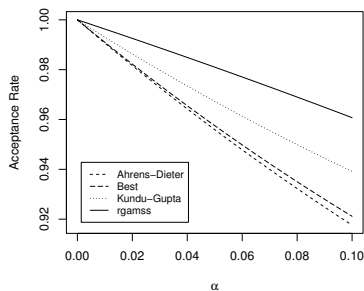
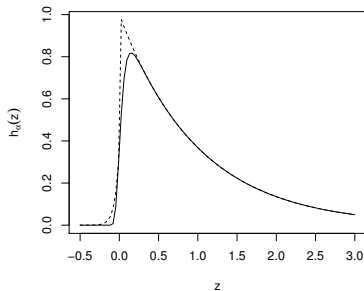
- Suppose we want  $X \sim \text{Gamma}(\alpha, 1)$ , with  $\alpha \leq 0.001$ .
- Try using `rgamma` for this—you'll get lots of *exact zeros*!
- Can we develop a better/more efficient method?
- Towards an accept–reject method, we have the following:

$$-\alpha \log X \rightarrow \text{Exp}(1) \quad \text{in distribution, as } \alpha \rightarrow 0.$$

- Suggests that we can get good samples of  $\log X$  by doing accept–reject with (basically) an exponential envelope.
- This is some work of mine:
  - a version of the paper is at [arXiv:1302.1884](https://arxiv.org/abs/1302.1884);
  - R code is on my research website.

## Example – small-shape gamma (cont.)

- Left panel shows (un-normalized) density of  $Z = -\alpha \log X$ , for  $\alpha = 0.005$ , along with the proposed envelope.
- It turns out that this approach is more efficient than other accept–reject methods for this problem, based on acceptance rate (as a function of  $\alpha$ ).



- 1 Introduction
- 2 Direct sampling techniques
- 3 Fundamental theorem of simulation
- 4 Indirect sampling techniques**
  - Acceptance–rejection sampling
  - Ratio method
- 5 Sampling importance resampling
- 6 Summary

- Suppose we want to sample from a pdf  $f(x)$ .
- All that matters is the shape of  $f(x)$ , so we can remove any constants and consider  $h(x) = cf(x)$ , for some  $c > 0$ .
- Define the set in  $\mathbb{R}^2$ :

$$\mathcal{S}_h = \{(u, v) : 0 < u \leq h(v/u)^{1/2}\}.$$

- If  $\mathcal{S}_h$  is bounded, then we can find a bounding set that encloses it.
- Ideally, the bounding set should be simple, e.g., a rectangle.

- Suppose  $\mathcal{S}_h$  is bounded, in which case we can find a rectangle that encloses it.
- To sample  $X$  from  $f(x)$ , the ratio method goes as follows:
  - 1 Sample  $(U, V)$  uniformly from the bounding rectangle.
  - 2 If  $(U, V) \in \mathcal{S}_h$ , then  $X = V/U$  is a sample from  $f(x)$ .
- The proof is not too hard, but requires some tedious jacobian-type of calculations; see Lange.
- Naturally, some draws from the rectangle will be rejected – the efficiency of the sampling algorithm depends on how closely the bounding set matches  $\mathcal{S}_h$ .

## Example – gamma distribution

- Sample  $X \sim \text{Gamma}(\alpha, 1)$  for non-integer  $\alpha$ .
- To apply the ratio method, take  $h(x) = x^{\alpha-1}e^{-x}$  for  $x > 0$ .
- It can be shown that, in general, if  $h(x) = 0$  for  $x < 0$ , then the rectangle  $[0, k_u] \times [0, k_v]$ , with

$$k_u = \sup_x h(x)^{1/2} \quad \text{and} \quad k_v = \sup_x \{|x|h(x)^{1/2}\},$$

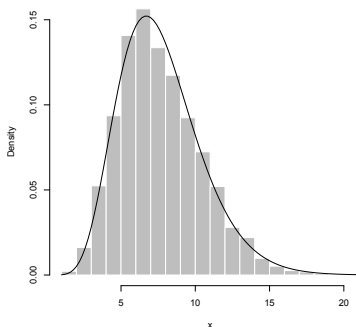
encloses  $\mathcal{S}_h$ .

- For the gamma case,

$$k_u = [(\alpha - 1)/e]^{(\alpha-1)/2} \quad \text{and} \quad k_v = [(\alpha + 1)/e]^{(\alpha+1)/2}.$$

## Example – gamma distribution (cont.)

- Ratio method samples  $X \sim \text{Gamma}(\alpha, 1)$  as follows:
  - 1 Sample  $U', V' \sim \text{Unif}(0, 1)$ , set  $U = k_u U'$  and  $V = k_v V'$ .
  - 2 Set  $X = V/U$ .
  - 3 If  $U \leq X^{(\alpha-1)/2} e^{-X/2}$ , then accept  $X$ .
- Example:  $\alpha = 7.7$ .
- Ratio method has acceptance probability  $\approx 0.44$ .



- 1 Introduction
- 2 Direct sampling techniques
- 3 Fundamental theorem of simulation
- 4 Indirect sampling techniques
- 5 Sampling importance resampling**
- 6 Summary



- Previous methods are “exact” in the sense that the distribution of the draw  $X$  (given that it’s accepted) is the target distribution  $f$ .
- Is it necessary for the sampling to be exact?
- An interesting idea is to sample from a different distribution  $g(x)$ , which is similar to  $f(x)$ , and weight these samples in such a way that a resample according to the given weights looks like a sample from  $f(x)$ .
- This is the idea of *sampling importance resampling* (SIR).
- Not unlike acceptance–rejection sampling.

- Suppose that the target pdf is  $f(x)$ , which may be known only up to a proportionality constant.
- Let  $g(x)$  be another pdf with the same support as  $f(x)$ .
- SIR algorithm:
  - 1 Take an independent sample  $Y_1, \dots, Y_m$  from  $g$ .
  - 2 Calculate the *standardized importance weights*

$$w(Y_j) \propto f(Y_j)/g(Y_j), \quad j = 1, \dots, m.$$

- 3 Resample  $X_1, \dots, X_n$  with replacement from  $\{Y_1, \dots, Y_m\}$  with probabilities  $w(Y_1), \dots, w(Y_m)$ .
- The resulting sample  $X_1, \dots, X_n$  is *approximately* distributed according to  $f(x)$ .

- One can prove that, as  $m \rightarrow \infty$ ,  $P(X_1 \in A) \rightarrow \int_A f(x) dx$ , and it is in this sense that the sampling is approximate.
- The choice of envelope  $g$  is not trivial.
  - Need  $f(x)/g(x)$  to not be too large.
  - If this is violated, then it may happen that one  $w(Y_j)$  will be almost identically 1, meaning that the  $X$ -sample would all be the same value.
- Theory suggests  $m$  should be large, but “large” here depends on the desired size  $n$  of the sample from the target.
- In general, the Monte Carlo estimates based on the SIR sample will have variances larger than could be obtained with other methods (e.g., importance sampling, next).

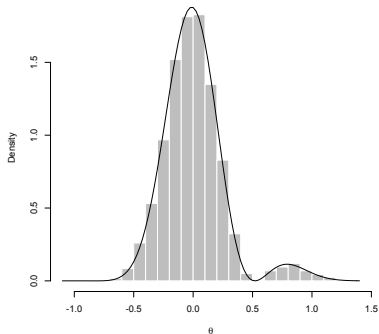
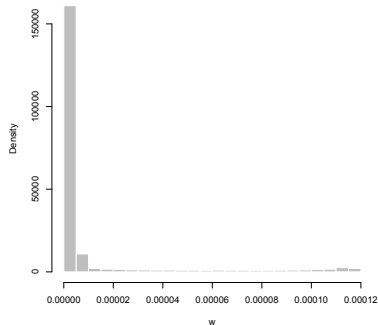
- Consider the problem from old homework, where the likelihood function is

$$L(\theta) \propto \prod_{i=1}^n \{1 - \cos(X_i - \theta)\}, \quad -\pi \leq \theta \leq \pi.$$

- Observed data  $(X_1, \dots, X_n)$  given in the code.
- Assume that  $\theta$  is given a  $\text{Unif}(-\pi, \pi)$  prior distribution.
- Use SIR algorithm, with the prior as the envelope;  $N = 10^3$ .
- Plots below.

# Example – Bayesian inference via SIR (cont.)

- Left is a histogram of the importance weights.
- Right is a histogram the SIR sample (density overlaid).



- 1 Introduction
- 2 Direct sampling techniques
- 3 Fundamental theorem of simulation
- 4 Indirect sampling techniques
- 5 Sampling importance resampling
- 6 Summary**

- Simulating random variables is important for various applications of the Monte Carlo method.
- Some distributions can be easily simulated via the inversion method, while others require more care.
- “Fundamental theorem” provides a general strategy for simulating from non-standard distributions, though its implementation may not be straightforward.
- The accept–reject method is a clever implementation.
  - Method’s efficiency relies on how close the envelope function is to the target density.
  - Not easy to make a good choice.
  - Various automatic/adaptive methods are available.
- The “accept–reject” idea appeared in the SIR context, and will appear again later...