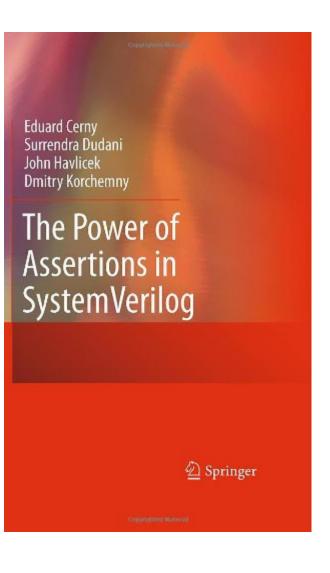
SYSTEMVERILOG ASSERTIONS FOR FORMAL VERIFICATION

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HVC2013, November 4, 2013, Haifa

 Most of the examples used in this tutorial are borrowed from our SVA book

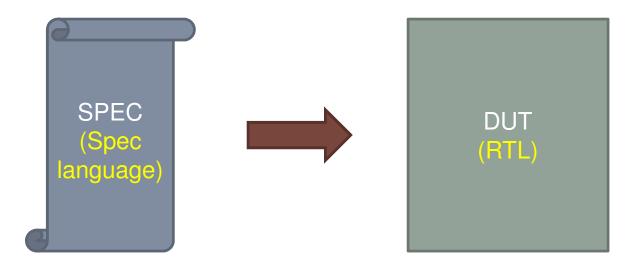


Agenda

- Introduction
- Formal verification model. LTL properties
- Assertion statements
- Sequences and properties
- Clocks and resets
- Assertion system functions
- Metalanguage and checkers
- Local variables
- Recursive properties
- Efficiency and methodology tips
- Future directions and challenges

INTRODUCTION

Hardware Verification Task



- Does DUT meet the spec?
- Simulation
 - Does DUT meet the spec for given input stimuli?
- Formal Verification (FV)
 - Does DUT meet the spec for any legal input stimuli?

SystemVerilog Assertions (SVA)

- SystemVerilog (proliferation of Verilog) is a unified hardware design, specification, and verification language
 - RTL/gate/transistor level
 - Assertions (SVA)
 - Testbench (SVTB)
 - API
- SVA is a formal specification language
 - Native part of SystemVerilog [SV12]
 - Good for simulation and formal verification

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SVA Standardization History

- 2003
 - Basic assertion features defined
- 2005
 - Improved assertion semantics
- 2009
 - Major changes in the language: deferred assertions, LTL support, checkers
- 2012
 - Improved checker usability, final assertions, enhancements in bitvector system functions and in assertion control
- Part of SystemVerilog standardization (IEEE 1800)

SVA vs. PSL

- Formal semantics of SVA is (almost) consistent with the formal semantics of PSL [PSL10]
- Meta-language layers are quite different (e.g., checkers vs. vunits)
- SVA has well-defined simulation semantics; tightly integrated with other parts of SystemVerilog

FORMAL VERIFICATION MODEL. LTL PROPERTIES

Linear Time Model. Global Clock

- We assume that the time is linear:
 - There is one global clock (AKA system clock or reference clock) which always ticks (never stops)
 - All signal changes are synchronized with the ticks of the global clock
 - Global clock introduces the notion of discrete time in the system
 - 0, 1, 2, ...
 - Each number corresponds to a tick of the global clock

Global Clock in SystemVerilog

- In simulation the natural notion of global clock are simulation ticks. But such definition makes global clock very expensive
- In SystemVerilog there is a special construct for global clocking definition

May be declared anywhere in the design Default clocking defines the default clock for assertions May be declared anywhere in the design Default clocking default clocking @\$global_clock; endclocking ... endmodule : m

global clocking is used in simulation, but usually ignored in FV and emulation

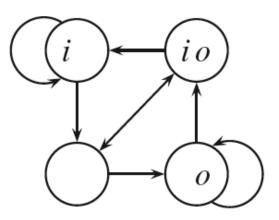
In practice most assertions are written relative to some specific clock, not relative to the global clock. Will be discussed later

Formal Verification Model

- Kripke structure: $M = \langle Q, I, V, R \rangle$
 - Q Finite set of states
 - $I \subseteq Q$ Set of initial states
 - V Set of Boolean variables (labels)
 - L: Q → 2^V Labeling function mapping each state to the set of variables that are true in this state
 - $R \subseteq Q \times Q$ (Left total) transition relation
 - Shows to which states it is possible to transition from given state

Formal Verification Model. Example

module m(input logic i, clk, output o);
 wire a = !i;
 global clocking @(posedge clk); endclocking
 always @(\$global_clock) o <= a;
endmodule : m</pre>



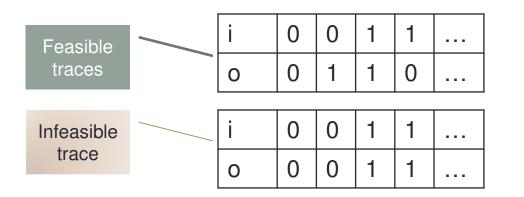
Symbolic Representation

- Each *x* variable is represented as a pair:
 - Current value (its value at the current time moment): x
 - Next value (its value at the next time moment): x'
- Each set and relation is represented by its characteristic function
 - E.g., $R = i \oplus o'$
- In SystemVerilog there is a notation of next value:
 - \$future_gclk(x)
 - E.g., $i \oplus o'$ corresponds to i ^ $future_gclk(o)$
- Other future sampled value functions:
 - \$rising_gclk(x) ⇔ !x & \$future_gclk(x) (for bit variables)
 - \$falling_gclk(x) \IDRARK x & !\$future_gclk(x) (for bit variables)
 - \$steady_gclk(x) ⇔ x === \$future_gclk(x)
 - \$changing-gclk(x) ⇔ x !== \$future_gclk(x)

Linear Time Model

- Linear time FV model defines a number of legal infinite traces
- Specification language describes the properties of these

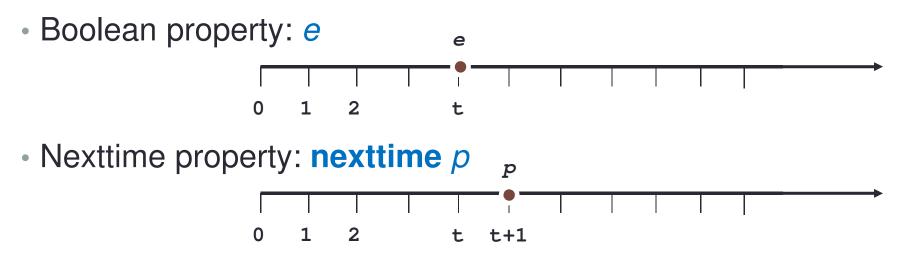
traces module m(input logic clk, i, output logic o); global clocking @(posedge clk); endclocking default clocking @\$global_clock; endclocking always @(posedge clk) o <= !i; assert property (i |=> !o); endmodule_: m



i	0	1	0	1	
0	1	1	0	1	

Linear Time Language (LTL) Properties

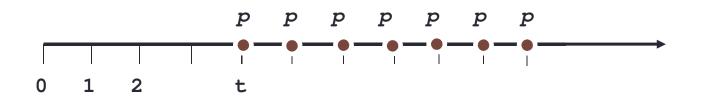
- Properties are temporal statements that can be true or false
 - Properties have a starting point (t), but no end point



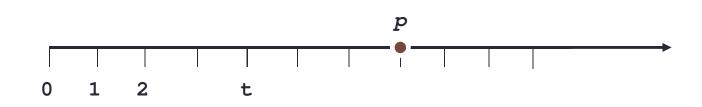
- In SVA there exists also a strong version: s_nexttime
 - Discussed later

LTL Properties (cont.)

Always property: always p



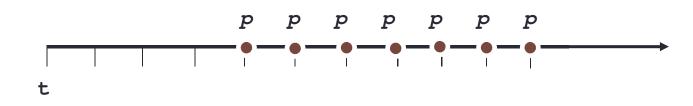
Eventually property: s_eventually p



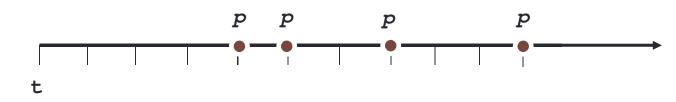
Compound Properties

True from next moment: nexttime always p

True from some moment: s_eventually always p



Infinitely often: always s_eventually p



Boolean Connectives

- Negation: not p
- Conjunction: *p* and *q*
- Disjunction: p or q
- Implication: *p* implies *q*
- Equivalence: p iff q
- Condition: if (e) p else q
- Case

Counterexample

- Counterexample trace witnessing a property failure
- In general case infinite
- May be finite
 - Meaning that any infinite extension of this finite trace is a counterexample

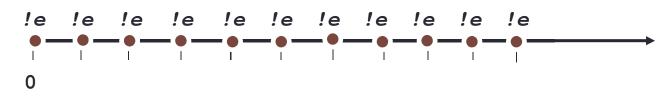
Safety and Liveness

- Safety properties
 - All their counterexample are finite
 - E.g., always e





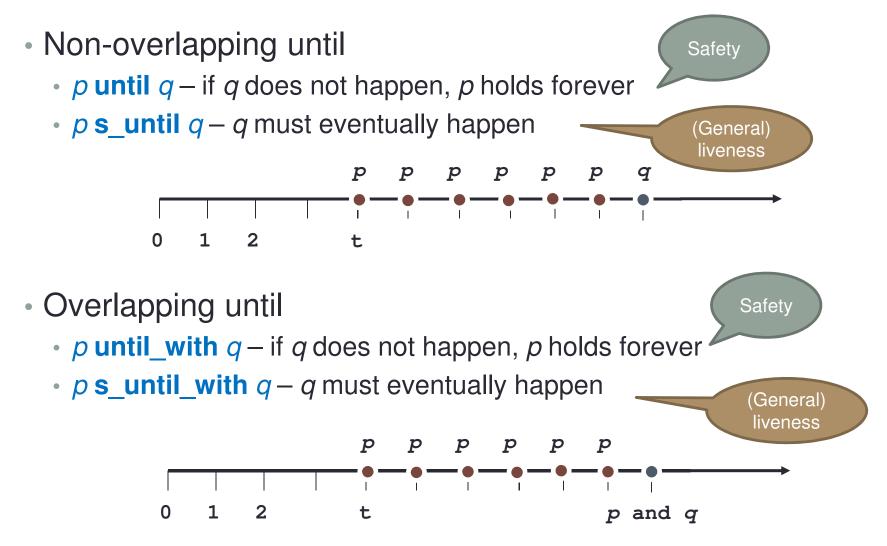
- All their counterexamples are infinite
 - E.g., s_eventually e



!e

- Hybrid properties also exist
 - Sometimes also called "liveness"

LTL Properties. Until



Bounded Versions

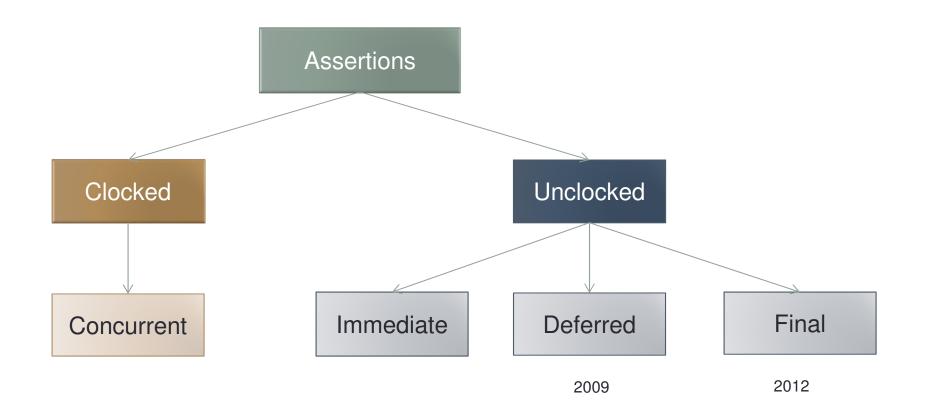
Property	Semantics		
[s_]nexttime [m] p	[s_]nexttime [s_]nexttime p		
[s_]eventually [m:n] p	[s_]nexttime [m] p or or [s_]nexttime [n] p		
s_eventually [m:\$] p	s_nexttime [m] s_eventually p		
[s_]always [m:n] p	[s_]nexttime [m] p and and [s_]nexttime [m] p		
always [<i>m</i> :\$] <i>p</i>	nexttime [m] always p		

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ASSERTION STATEMENTS

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Assertion Kinds



(Concurrent) Assertion Statements

- Assertions
 - Insure design correctness

assert property (p);

- Assumptions
 - Model design environment

assume property (p);

- Cover statements
 - To monitor coverage evaluation

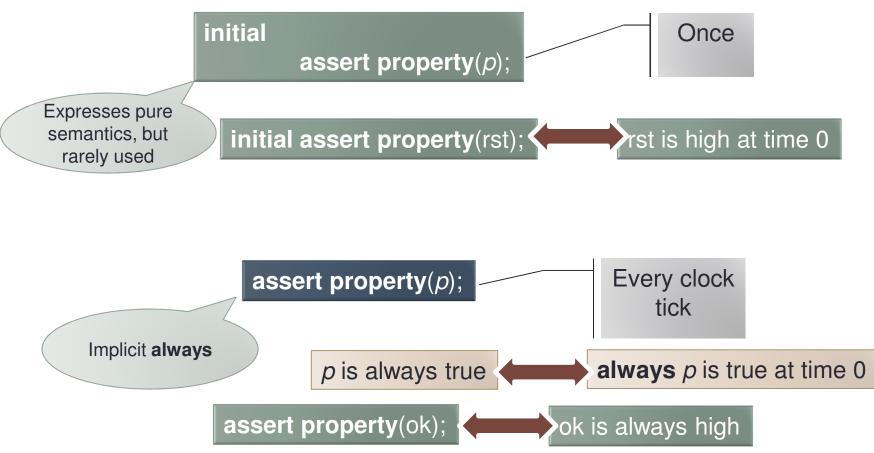
cover property (p);

- Restrictions
 - To specify formal verification constraint

restrict property (p);

Assertion Placement

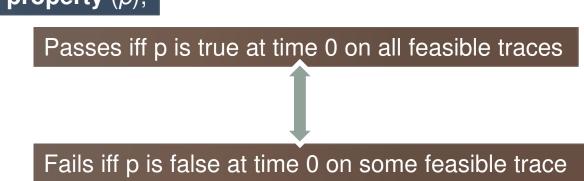
- Inside initial procedure execute only once
- Outside of initial procedure execute continuously



Assertions

- Specify requirements from DUT
- FV
 - Mathematically proves assertion correctness
- DV
 - Checks assertion correctness for given simulation trace





Assumptions

- Specify requirements from environment
- FV
 - Restricts the set of feasible traces in the model
- DV
 - Checks assertion correctness for given simulation trace

assume property (in == !inv_in)
else \$error("Inputs in and inv_in are expected to be inverse");

- From FV point of view, the DUT acts as an assumption
- Contradictory assumptions (with each other or with the model) cause all assertions to pass
 - This is called an *empty model*

Restrictions

Specify condition for which FV has been performed

- FV
 - Restricts the model
 - Same as assumption
- DV
 - Completely ignored

restrict property (opcode == OP_ADD);

Cover

- Specify scenario you wish to observe
- FV
 - Mathematically prove that the property holds on some feasible trace
- DV
 - Capture scenario in simulation trace

cover property (read[*2]);

From FV point of view



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Formal View on Assertions and Assumptions

- Set of assumptions
 - initial assume property (q_1);

• ...

- initial assume property (q_m);
- and assertions
 - initial assert property (p_1);

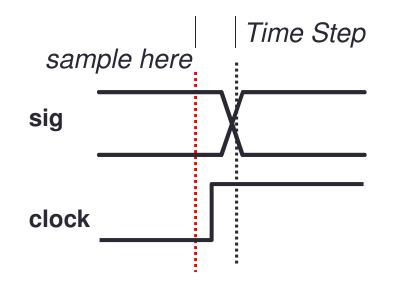
• ...

- initial assert property (p_n);
- is equivalent to the following single assertion
 - initial

```
assert property (q_1 and ... and q_m
implies p_1 and ... p_n);
```

Sampling

Signal values are sampled at the beginning of simulation tick



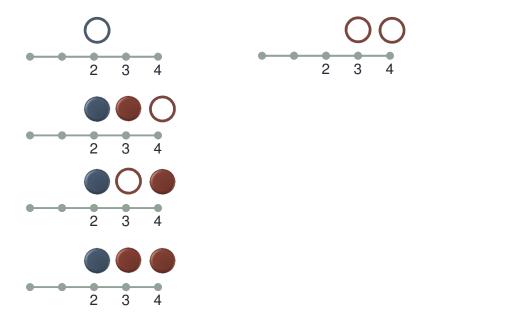
SEQUENCES AND PROPERTIES

Sequence

- Informal definition
 - Sequence is a rule defining a series of values in time
- A sequence does not have a truth value, it has one initial point and zero or more *match* points
- When a sequence is applied to a specific trace, it defines zero or more *finite* fragments on this trace starting at the sequence initial point and ending in its match points
 - Essentially, sequence is a regular expression

Example

- Read is followed by write in one or two clock ticks
 - read ##[1:2] write
 - Let starting point of this sequence be t = 2



No match

Single match at 3

Single match at 4

Two matches (at 3 and 4)

Boolean Sequence

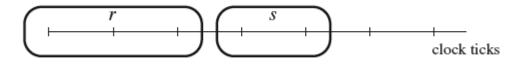
- Boolean expression *e* defines the simplest sequence a Boolean sequence
 - This sequence has a match at its initial point if e is true
 - Otherwise, it does not have any satisfaction points at all



Sequence Concatenation

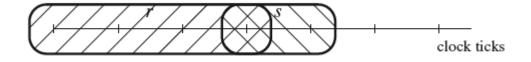
Sequence concatenation: r ##1 s

- There is a match of sequence r ##1 s if there is a match of sequence r and there is a match of sequence s starting from the clock tick immediately following the match of r
 - In other words, a finite trace matches *r ##1 s* iff it can be split into two adjacent fragments, the first one matching *r*, and the second one matching *s*.



Sequence Fusion

- Sequence fusion r ##0 s is an overlapping concatenation
 - The fusion of sequences r and s, is matched iff for some match of sequence r there is a match of sequence s starting from the clock tick where the match of r happened



Zero Repetition (Empty Sequence)

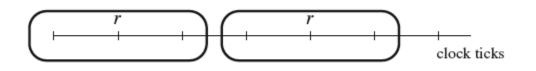
- *s*[*0]
 - sequence admitting only an empty match
 - Matches on any trace but the trace fragment is empty (does not contain clock ticks)

Sequence Disjunction

 Sequence disjunction r or s is a sequence which has a match whenever either r or s (or both) have a match

Consecutive Repetition

- Repetition
 - r[*0] is an empty sequence
 - If *n* > 0 (const.)
 - **r**[*n] ⇔ r[*n-1] ##1 r



- Finite repetition range
 - *r*[**n*:*n*] ⇔ *r*[**n*]
 - r[*m:n] ⇔ r[*m:n-1] or r[*n], m < n

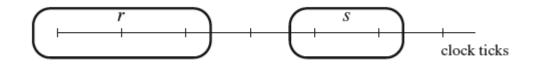
Infinite Repetition Range

- Infinite range: repeat *s n* or more times
- Formal definition
 - Sequence s[*1:\$] matches trace fragment i : j if it is possible to divide this trace fragment into one or more consecutive fragments so that each such fragment matches s
 - *s*[*0:\$] ⇔ *s*[*0] or *s*[*1:\$]
 - s[*n:\$] ⇔ s[*0:n-1] or s[*1:\$], n > 1
- Shortcuts (SVA 2009)
 - *s*[*] ⇔ *s*[*0:\$] Zero or more times
 - *s*[+] ⇔ *s*[*1:\$] One or more times

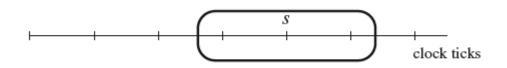
s[*n:\$] does *not* mean that sequence s is repeated infinitely many times, but that it is repeated *n* or more (finite) number of times

Sequence Concatenation and Delay

- r ##0 s is a sequence fusion
- r ##1 s is a sequence concatenation
- *r* ##n *s*, where *n* > 1 is defined recursively
 - *r* ##*n s* ⇔ *r* ##1 1[**n*-1] ##1 *s*



• ##n s ⇔ 1[*n] ##1 s



Delay Ranges

- *r* ##[0:0] *s* ⇔ *r* ##0 *s*
- $r ##[m:n] s \Leftrightarrow (r ##1 1[*m-1:n-1] ##1 s)$, where $n \ge m > 0$
- *r* ##[0:*n*] *s* ⇔ (*r* ##0 *s*) or (*r* ##[1:*n*] *s*), where *n* > 0
- *r* ##[*m*:\$] *s* ⇔ (*r* ##1 1[**m*-1:\$] ##1 *s*), where *m* > 0
- *r* ##[0:\$] *s* ⇔ (*r* ##0 *s*) or (*r* ##[1:\$] *s*), where *n* > 0
- ##[m:n] $s \Leftrightarrow 1$ ##[m:n] s, where $n \ge m \ge 0$
- ##[*m*:\$] *s* ⇔ 1 ##[*m*:\$] *s*, where *m* ≥ 0
- Shortcuts (SVA 2009)
 - ##[*] ⇔ ##[*0:\$]
 - ##[+] ⇔ ##[*1:\$]

Other Sequence Operators

- Go to repetition: *e*[->*n*], *e*[->*m*:*n*]
 - *e* is a Boolean
- Non-consecutive repetition: e[=n], e[=m:n]
 - *e* is a Boolean
- Intersection: r intersect s
- Conjunction: r and s
- Containment: r within s
- Throughout: e throughout s
- First match: first_match(r)
- Sequence methods
 - r.triggered
 - r.matched

Sequential Property

- Strong sequential property
 - strong(s) is true in clock tick *i* iff sequence *s* with initial point *i* has a match
 - Sequence *s* should not admit an empty match
- Weak sequential property
 - weak(s) is true in clock tick *i* iff there is no finite trace fragment *i* : *j* witnessing inability of sequence *s* with the initial point *i* to have a match.
 - Sequence *s* should not admit an empty match
- In assertions, assumptions and restrictions weak may be omitted
- In cover statements **strong** may be omitted

Sequential Properties. Examples

- initial assert property (rst[*2]);
 - Same as initial assert property (weak(rst[*2]));
 - For global clock it is also the same as initial assert property (strong(rst[*2]));

Xinitial assert property (rst[*]);

- Admits empty match
- initial assert property (rst[*] ##1 ready);
 - Same as initial assert property (rst until ready);
- initial assert property (strong(rst[*] ##1 ready));
 - Same as initial assert property (rst s_until ready);
- initial assert property (##[*] ready);
 - Tautology
- initial assert property (strong(##[*] ready));
 - Same as initial assert property (s_eventually ready);

Suffix Implication

- A suffix implication is a property built from a sequence (s) and a property (p)
 - s *antecedent* triggering condition
 - *p consequent* checked when triggering condition holds
 - Suffix implication is true when its consequent is true upon each completion of its antecedent
- Overlapping implication: s |-> p
 - consequent is checked starting from the moment of *every* nonempty match of the antecedent
- Nonoverlapping implication: s |=> p
 - consequent is checked starting from the next clock tick of every match of the antecedent
 - For singly-clocked properties
 - *s* |=>*p* ⇔ *s* ##1 1 |-> *p*

Examples

- Request must be granted
 - assert property (req |-> s_eventually gnt);
 - 2. assert property (req |=> s_eventually gnt);
 - Both assertions allow sending one grant to multiple requests
- Request must be granted in 3 cycles
 - 1. assert property (req |-> ##3 gnt); or
 - 2. assert property (req |=> ##2 gnt);
- Request must be active until grant is asserted
 - assert property(req |-> req until grant);
 - 2. assert property(req |-> req until_with grant);
 - 3. assert property(req |-> req s_until grant);
 - 4. assert property(req |-> req s_until_with grant);
- Two consecutive alerts must be followed by reset
 - assert property (alert[*2] |=> reset);

Vacuity

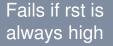
- What do we check in previous assertions if requests cannot be produced by the model?
- Assertion holds vacuously if it is redundant
 - E.g., the previous assertions may be rewritten in this case as assert property (not req);
- FV tools provide vacuity check
 - The cost is rather high

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Suffix Conjunction

- A suffix conjunction is a property built from a sequence (s) and a property (p)
 - s *antecedent* triggering condition
 - *p consequent* checked when triggering condition holds
 - Suffix conjunction is true when its consequent is true upon at least one completion of its antecedent
- Overlapping conjunction: s #-# p
- Nonoverlapping conjunction: s #=# p
- Example:
 - Reset is initially high and when it becomes low it remains low forever
 - initial assert property (rst[+] ##1 !rst |=> always !rst);
 - initial assert property (rst[+] ##1 !rst #=# always !rst);

Passes if rst is always high



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CLOCKS

Clocks

 Assertion clock should be explicitly written or inferred from the default clocking

assert property (@clk p);

assert property (@(posedge clk) p);

```
default clocking @(posedge clk); endclocking
...
assert property (p);
```

Clock Rewriting

- Unless clock is not inferred as a system clock (=global clock) by an FV tool, the corresponding property is rewritten
- Examples

assert property (@(posedge clk) e);

assert property (\$rising_gclk(clk) |-> e);



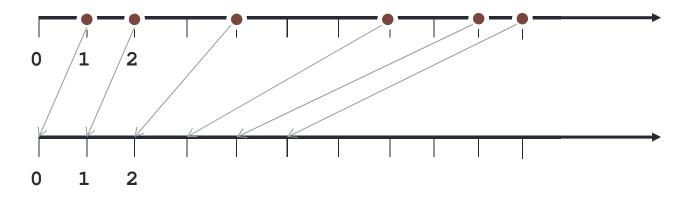
assert property ((\$rising_gclk(clk) & req ##1 \$rising_glck(clk)|-> gnt);

Clock Fairness

- Clock is *fair* if it ticks infinitely many times
- Without any preliminary knowledge clock fairness is not guaranteed
 - Clock may stop ticking at some moment
- Global clock is fair by its definition

Clock Fairness (cont.)

- Clock defines a subtrace
 - Only moments corresponding to clock ticks are retained



- When clock is fair the subtrace is infinite
 - Formal semantics does not change
- When clock is not fair the subtrace is finite
 - Need to define property semantics on finite trace

Weak and Strong Properties

- Weak operators do not require clock to tick
- Strong operators require clock to tick enough times
- Example
 - nexttime weak version
 - s_nexttime strong version

initial assert property (@clk **nexttime** p);

initial assert property (@clk s_nexttime p);

Passes iff either *p* is true at time 1 **or** *clk* ticks less than two times

Passes iff *clk* ticks at least two times **and** *p* is true at time 1

Weak and Strong Properties. Negation

- Negation inverts weakness
 - E.g., **not**, antecedent in **implies**
- Example
 - not always p ⇔ s_eventually not p

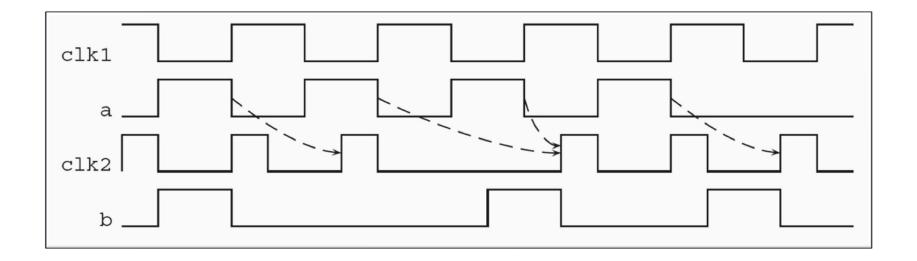
Mixing Weak and Strong Properties

- Mixing weak and strong properties in most cases in nonintuitive and should be avoided
 - Also for performance reasons
- Example
 - s_nexttime always p
 - Clock should tick at least twice and p should true at each clock tick starting from time t + 1
 - In some cases mixing is meaningful
 - s_eventually always p fairness
 - always s_eventually p

Multiply Clocked Properties

SVA supports multiply clocked properties

assert property(@(posedge clk1) a $\mid = > @(posedge clk2) b);$



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RESETS

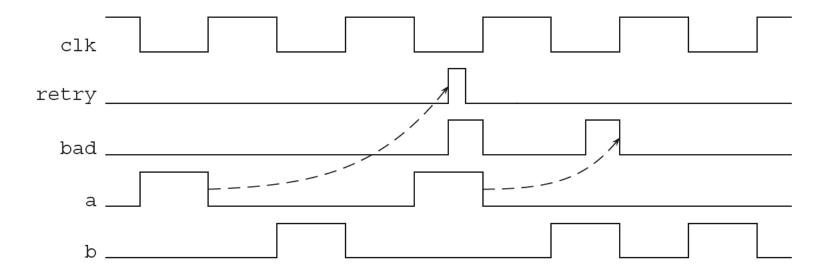
Resets and Aborts

- Reset and abort operators operators to stop property evaluation when some condition is met
 - Simplify writing assertions in presence of hardware resets
- disable iff main reset of an assertion
- Aborts
 - Asynchronous
 - accept_on
 - reject_on
 - Synchronous
 - sync_accept_on
 - sync_reject_on

Aborts

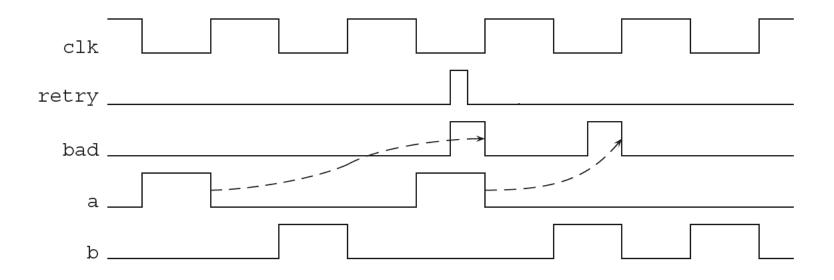
- Asynchronous aborts
 - Ignore the actual clock
 - Checked at each time step
- Synchronous aborts
 - Checked at clock ticks only
- Informal semantics
 - accept_on (cond) p, sync_accept_on (cond) p
 - True if there is no evidence of the failure of p before the abort condition has become true
 - reject_on (cond) p, sync_reject_on (cond) p
 - False if there is no evidence of the success of p before the abort condition has become true

Asynchronous Aborts. Example



Synchronous Aborts. Example

assert property(@(posedge clk)
 sync_accept_on (retry) a |=> sync_reject_on(bad) b[*2]);



One More example

- reject_on(rst) 1[*3]
 - Property 1[*3] can never fail
 - Therefore, reject_on(rst) 1[*3] fails iff rst becomes high any time during first three clock cycles
- sync_reject_on(rst) 1[*3] is equivalent to !rst[*3]

Disable Clause

- Syntax
 - disable iff (expression)
- Specifies top-level assertion reset
 - At most one in the entire assertion
- In FV may be regarded as accept_on in assertions and assumptions, and as reject_on in cover statements
- Formally introduces a notion of disabled evaluation
 - Evaluation is *disabled* if the assertion evaluation has been aborted because the disable condition became true
- Disable condition is checked continuously, and it is not sampled
 - This definition introduces inconsistency between simulation and FV

Disable Clause (cont.)

 default disable iff may be used to specify the default disable condition

module m (**input logic** reset, rst, req, gnt, clk, ...); **default disable iff** reset;

a1: assert property (@(posedge clk) req |=> gnt); a2: cover property (@(posedge clk) req ##1 gnt); a3: assert property (@(posedge clk) disable iff (1'b0) a |=> b); a4: assert property (@(posedge clk) disable iff (rst) a |=> b); endmodule : m

ASSERTION SYSTEM FUNCTIONS

Bit-Vector System Functions

Name	Description
\$onehot0	Check that at most one bit in a vector is high
\$onehot	Check that exactly one bit in a vector is high
\$countones	Count number of bits in a vector with value high
\$countbits	Count number of bits having specific value
\$isunknown	Check whether a vector has a bit with value x or z

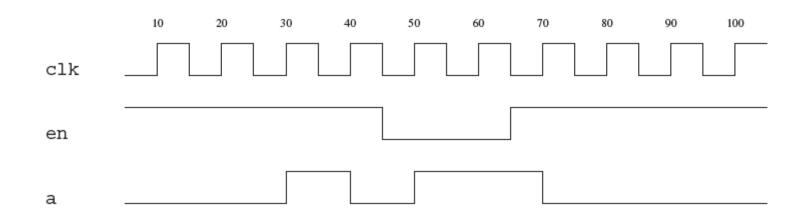
Sampled Value Functions

Name	Description
\$sampled	Return sampled value of expression
\$past	Return past value of expression
\$rose	Check whether expression value rose
\$fell	Check whether expression value fell
\$changed	Check whether expression value changed
\$stable	Check whether expression value remained stable

Past Sampled Values

\$past(e, n, en, @clk)
e – expression
n ≥ 1 – constant expression specifying the number of clock ticks (delay)
en – gating expression for the clocking event
clk – clocking event

		1 I	
	Time	\$sampled(a)	<pre>\$past(a,,,@(posedge clk))</pre>
n	30	0	0
	40	1	0
	42	0	1
	50	0	1
	60	1	0
	70	1	1
	80	0	1
	90	0	0



Values Before Initial Clock Tick

- What happens if for a given time-step there are not enough previous clock ticks?
 - \$past(e) returns an initial value of e
- The initial value of e is that as computed using the initial values stated in the declaration of the variables involved in e
 - If a static variable has no explicit initialization, the default value of the corresponding type is used, even if the variable is assigned a value in an initial procedure

FV tools may ignore variable initialization everywhere, except in **checker** constructs. Also, many FV tools consider all variables to be of two-state value type, and therefore they assume that \$past(e) is 0 in clock tick 0 for any e

Other Sampled Value Functions

- \$rose(e, @clk) ⇔
 \$past(LSB(e),,,@clk)!== 1 && \$sampled(LSB(e))=== 1
- \$fell(e, @clk) ⇔
 \$past(LSB(e),,,@clk)!== 0 && \$sampled(LSB(e))=== 0
- \$changed(e, @clk) <>
 \$past(e,,,@clk)!== \$sampled(e)
- \$stable(e, @clk) ⇔
 \$past(e,,,@clk)=== \$sampled(e)

Global Clocking Sampled Value Functions

- May be used only if global clock has is defined
- Past
 - \$past_gclk(e) \IDR \$past(e, 1, 1, @\$global_clock)
 - \$rose_gclk(e) ⇔ \$rose(e, @\$global_clock)
 - \$fell_gclk(e) ⇔ \$fell(e, @\$global_clock)
 - \$changed_gclk(e) ⇔ \$changed(e, @\$global_clock)
 - \$stable_gclk(e) ⇔ \$stable(e, @\$global_clock)
- Future
 - \$future_gclk(e) Sampled value of e in the next tick of the global clock
 - \$rising_gclk(e) ⇔ \$sampled(LSB(e))!== 1 && \$future_gclk(LSB(e)) === 1
 - \$falling_gclk(e) \IDRedstarrow \$sampled(LSB(e))!== 0 && \$future_gclk(LSB(e)) === 0
 - \$changing_gclk(e) \IDReq \$sampled(e) !== \$future_gclk(e)
 - \$steady_gclk(e) \IDRedsignarrow \$sampled(e) === \$future_gclk(e)
 - Cannot be nested or used in reset conditions

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METALANGUAGE

Let Declaration

let identifier [(port, port, ...)] = expression;

- "Compile-time macro" for integral expressions
- Follow normal scoping rules
- Formal arguments may be typed or untyped
- Formal arguments can have default actual arguments
- May be included in a package
- May easily be processed by tools for linting and statistical reporting
- Typical usage
 - Templates for Boolean assertions
 - Instrumental code
 - Does not introduce new variables
 - Visible to debuggers

Let Example

```
module m (input logic clk, rst, ...);
logic mod1, mod2;
logic req1, req2;
logic rsp;
let req = mod1 & req1 | mod2 & req2;
let gnt = $changed(rsp);
...
a: assert property (@(posedge clk) disable iff (rst) req |=> gnt);
```

endmodule : check

Sequence and Property Declaration

```
module m(input logic clk, rst, ...);
logic my_req;
logic gnt;
sequence two_reqs(req);
    req[*2];
endsequence
property delayed_grant(int n);
    nexttime [n] gnt;
endproperty
...
req_granted: assert property (@(posedge clk) disable iff (rst)
    two_reqs(my_req) |-> delayed_grant(2);
endmodule
```

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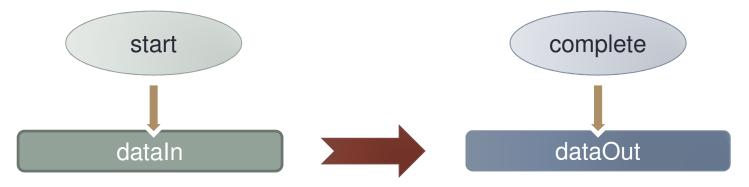
CHECKERS

Checkers

- Checkers are SystemVerilog containers to package verification code
 - Both assertions and modeling
- Checker is a kind of hybrid of module, property and assertion
 - May contain (almost) the same constructs as a module
 - Is instantiated as a property (in place)
 - Placed as an assertion
 - Acts as an assertion with complex internal implementation

Example. Sequential Protocol

- Whenever *start* is high, *dataIn* is valid.
- Whenever complete is high, dataOut is valid.
- If *start* is high, then the value of *dataIn* at that time must equal the value of *dataOut* at the next strictly subsequent cycle in which *complete* is high
- If *start* is high, then *start* must be low in the next cycle and remain low until after the next strictly subsequent cycle in which *complete* is high
- complete may not be high unless start was high in a preceding cycle and complete was not high in any of the intervening cycles



Sequential Protocol Verification Checker

```
checker seq_protocol (start, complete, dataIn, dataOut, event clk);
```

default clocking @clk; **endclocking var type**(dataln) data;

property match (first, last); first |=> !first **until_with** last; **endproperty**

always_ff @clk **if** (start) data <= dataln;

a_data_check: assert property (complete |-> dataOut == data); a_no_start: assert property (match(start, complete)); a no complete: assert property (match(complete, start));

initial

a_initial_no_complete: assert property (!complete throughout start[->1]);
endchecker : seq_protocol

Checker Binding

module top;

logic clock, snda, sndb, sndc, rcva, rcvb, rcvc;

trans ta (clock, snda, rcva); trans tb (clock, sndb, rcvb); trans #(2) tc (clock, sndc, rcvc); endmodule : top

checker eventually_granted (req, gnt, ...);

endchecker : eventually_granted

```
checker request_granted (req, gnt, n, ...);
```

...

```
endchecker : request_granted
```

bind trans eventually_granted check_in2out(in, out, **posedge** clock); **bind** trans: ta, tb request_granted delay1(in, out,, **posedge** clock); **bind** trans: tc request_granted delay2(in, out, 2, **posedge** clock);

Free Variables

- Checker may have free variables
 - Behave non-deterministically (like free or constrained inputs)
 - FV: consider all possible values imposed by assumptions and assignments
 - Simulation: their values are randomized
 - Free variable values are never sampled
- Limitations
 - Continuous and blocking assignments to free variables are illegal

```
rand bit r;

bit [2:0] x;

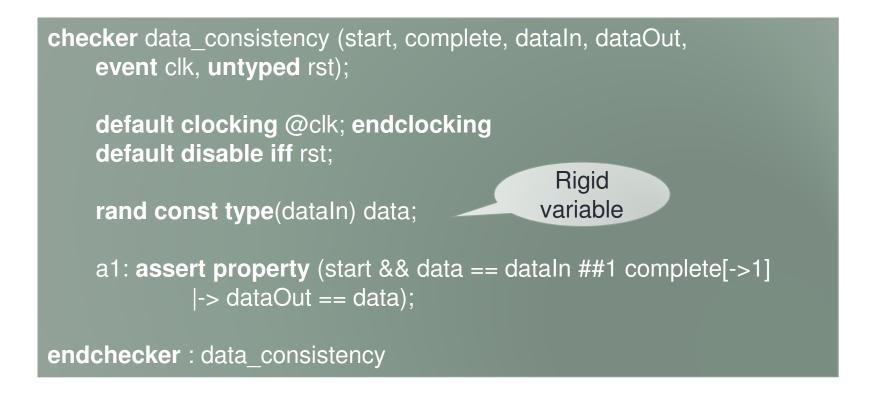
...

assign x = r ? 3'd3 : 3'd5;
```

rand bit a; always_ff @clk a <= !a;

Rigid Variables

• Rigid variables = constant free variables



Modular Assertion Modeling

checker check_fsm(logic [1:0] state, event clk); logic [1:0] astate = IDLE; // Abstract state model_fsm c1(state, clk, astate); check_assertions c2(state, astate, clk); endchecker

```
checker model_fsm(input event clk, output logic [1:0] astate = IDLE);
always @clk
    case (astate)
        IDLE: astate <= ...;
        ...
        default: astate <= ERR;
        endcase
endchecker</pre>
```

```
checker check_ assertions(state, astate, event clk);
    default clocking @clk; endclocking
    a1: assert property (astate == IDLE <-> state inside {IDLE1, IDLE2});
    //...
endchecker
```

Implementing Formal Verification Environment With Checkers

In simulation module input signals are randomized remaining mutually exclusive checker env(event clk, output logic out1, out2);
 rand bit a, b;
 m: assume property (@clk \$onehot0({a, b}));
 assign out1 = a;
 assign out2 = b;
endchecker : env

module m(input logic in1, in2, clock, output ...);

endmodule : m

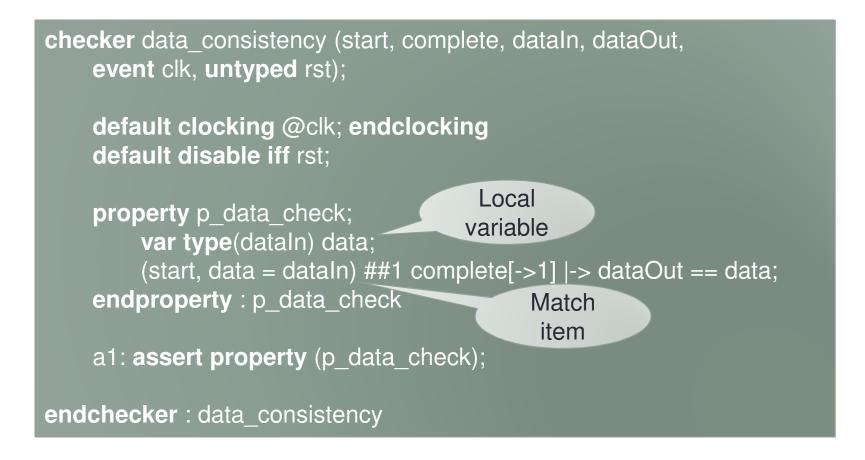
module top();
 logic clock, n1, n2;
 ...
 m m1(n1, n2, clock, ...);
 evn env1(clock, n1, n2);
endmodule : top

LOCAL VARIABLES

Informal Definition

• Local variable is a variable associated with an evaluation attempt

Local variables are not sampled



Example

 Check that the value of *dataIn* when *start* is high coincides with the value of *dataOut* read in *n* clock ticks

• If n = const

assert property (start |-> ##n dataOut == \$past(dataIn, n));

If n is not const

```
property data_check;
var type(n) ctr;
(start, ctr = n - 1) ##1 (ctr > 0, ctr--)[*] ##1 (ctr == 0)
|-> dataOut = dataIn;
endproperty : data_check
assert property (data_check);
```

Local vs. Rigid Variables

- Local variables are "broader" than rigid variables
 - They are mutable
- Local variables are more intuitive
- Local variables are supported in simulation, rigid variables are not
- Rigid variables are FV friendly their implementation is straightforward
 - Efficient implementation of local variables in FV is challenging

RECURSIVE PROPERTIES

Recursive Properties

Properties may be recursive

```
initial assert property (@(posedge clk) prop_always (ok));
```

```
property prop_weak_until (p, q);
        q or (p and nexttime prop_weak_until (p, q));
endproperty
```

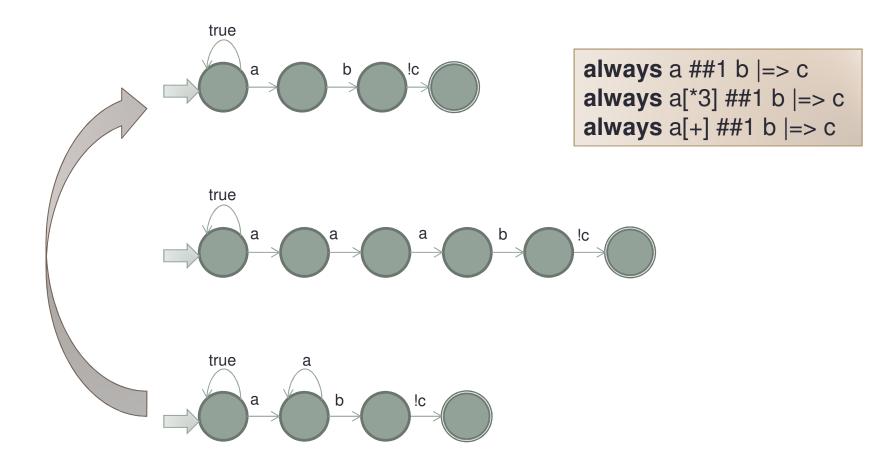
initial assert property (@(**posedge** clk) prop_weak_until (req, gnt));

EFFICIENCY AND METHODOLOGY TIPS

Assertion Compilation for FV

- Assertions are usually compiled into finite automata [Var96]
 - Typical for FV and emulation
 - Sometimes done for simulation as well
- Safety assertions are compiled into (conventional) finite automata on finite words
- Liveness and hybrid assertions are compiled into finite automata on infinite words (e.g., Büchi automata):
 - Finite automata on finite words + fairness conditions
- Complexity of automaton reflects well FV efficiency
- Another factor is the number of state variables in the model

Automaton-Based Compilation. Example



X

Avoid Large and Distant Time Windows

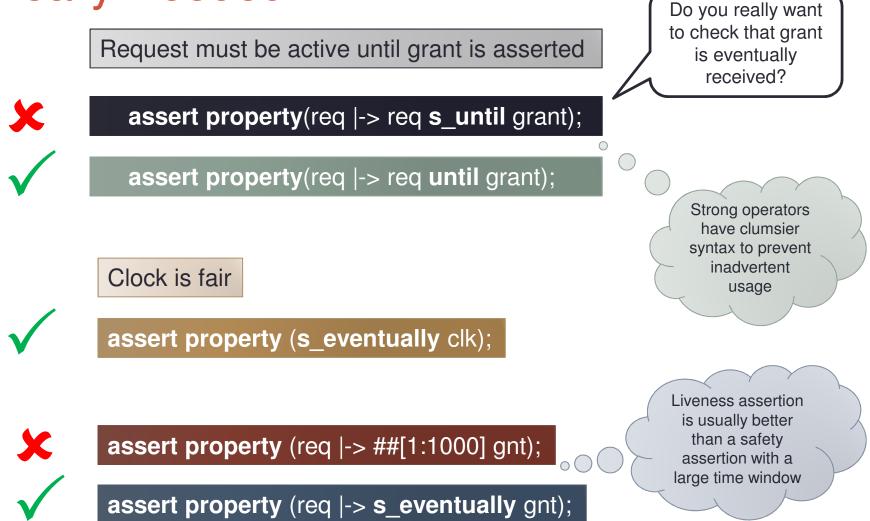
assert property (start ##1 !complete[0:1000] ##1 complete |=> done);

assert property (start ##1 complete[->1] |=> done);

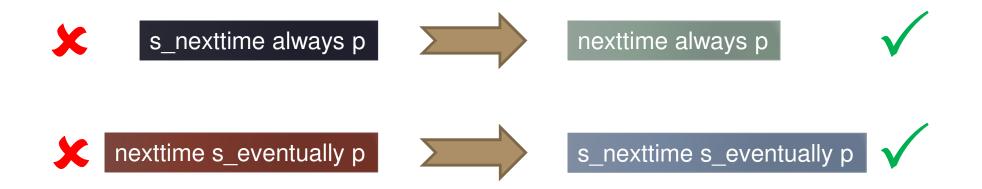
assert property (start ##1 !complete[*] ##1 complete |=> done);

Also applies to bounded property operators and \$past

Avoid Using Liveness Assertions Unless Really Needed



Avoid Mixing Weak and Strong Properties



Sometimes this is unavoidable

always s_eventually p

Past vs. Future

- Future value functions are cheap in FV
 - Recall that each variable is represented as a pair (v, v')
- Past value functions are more expensive
 - They introduce new flip-flops (=variables)
- Need to optimize the usage of \$past

logic check; **logic** [31:0] a, b, c;



assert property (##1 check |-> \$past(c) == \$past(a) + \$past(b));

assert property (##1 check |-> \$past(c == a + b));

Intersection Family

- Sequence operators from *intersection* family (intersect, and, within) are expensive
 - These operators are not inefficient by themselves, but allow to concisely code complex sequences
 - Use only where appropriate

Each transaction should contain two read requests and three write requests

Common case

assert property (start |-> read[=2] **intersect** write[=3] **intersect** complete[->1]);

If known that all reads come after writes

assert property (start |-> write[=3] ##1 read[=2] **intersect** complete[->1]);

Top-level conjunction in a sequence promoted to property is not expensive

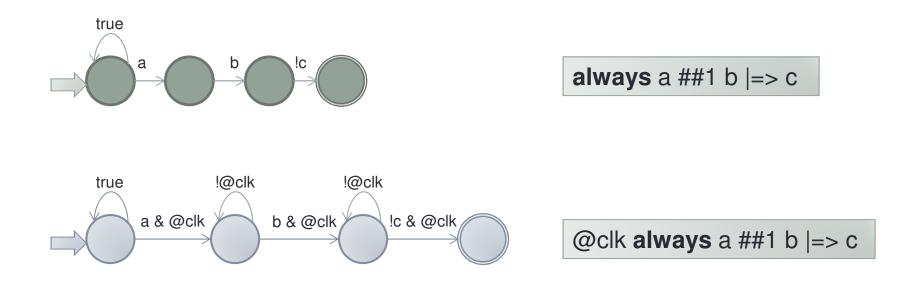
assert property (en |-> r and s);

assert property (en |-> (r and s) ##1 a);

This is rather efficient

Assertion Clock

 Assertions governed by a global clock are more efficient in FV than assertions governed by an arbitrary clock



FV tools may automatically infer the global clock from a singly clocked design

Local vs. Free and Rigid Variables

- Implementing free and rigid variables is straightforward in FV
- Implementing local variables is tricky
- Important advantage of local variables
 - Allow checking assertions in simulation
- Both are usually expensive
- Efficiency is strongly dependent on FV tool
 - May need to experiment

Assignments vs. Assumptions

- Assignments are usually more efficient than assumptions
 - They add directionality to the search

Compare

assign x = !y;

VS.



Overlapping vs. Nonoverlapping Transactions

- Nonoverlapping transactions may be modeled deterministically
- Overlapping transactions usually require nondeterministic modeling
 - E.g., local or rigid variables
- Compare:
 - Sequential protocol vs.

property p_data_check; var type(dataln) data; (start, data = dataln) ##1 complete[->1] |-> dataOut == data; endproperty : p_data_check

If it is known that transactions cannot overlap, model them as nonoverlapping

Be More Specific

- Being more specific usually pays off. Check only what you really need
 - Don't check for eventuality unless this is essential
 - If events are ordered in a sequence specify this order explicitly
 - If you know that transactions do not overlap model this fact explicitly
- Nulla regula sine exceptione
 - Liveness assertions are usually more efficient than safety assertions with large/distant time windows
 - Being more specific comes at a price of generality
 - However, generality does not help if performance problems prevent us from getting result

Efficiency: Simulation vs. FV

- Simulation and FV efficiency requirements may be inconsistent
 - Especially when assertion simulation has a transaction-based implementation
- E.g.
 - Infinite ranges and repetitions are efficient in FV, but not in simulation
 - Sequence intersection is efficient in simulation, but not in FV
 - Liveness does not cost in simulation
 - Future value functions are more efficient than past value functions in FV. The situation with simulation is opposite
 - Local variables are rather efficient in simulation, but not in FV

FUTURE DIRECTIONS AND CHALLENGES

Convergence Between SVA and SVTB

- Coverage features are divided between SVA and SVTB
 - Assertion coverage belongs to SVA
 - Covergroups belong to SVTB
- Currently there is no organic connection between the two
 - Syntax and semantics are absolutely different
- One can consider temporal coverage specification by integrating sequences and covergroups

Standard Packages

- SVA provides basic assertion capabilities and some sugaring
 - There are many useful properties and functions that could be reused, but are not a basic part of the language
 - It makes sense to standardize them by creating standard property packages
 - PSL has some of such common properties embedded into the language, e.g., never, before, next_event, etc.

Assertion Libraries

 Using SVA checker mechanism it is possible to create a powerful and flexible standard assertion library with concise library assertion invocation

Kind of "next generation" OVL

AMS Assertions

- AMS = Analog and Mixed Signals
- The intention is to merge SystemVerilog and Verilog-AMS
 - This includes development of AMS assertions and including them into SVA
 - The initial step was done in SV2012: real type support in SVA
 - No continuous time support yet

TLM Assertions

- SVA covers RTL assertions
- TLM assertions are different
 - Unclocked or approximately clocked
- SVA is too low level for TLM
- Need to extend SVA to cover TLM needs

Checkers for UVM

- UVM Universal Verification Methodology
 - Widely used in verification
- Includes verification level monitors to check design correctness
 - Part of TB
 - Uses completely different mechanism, does not explore the strength of assertions
 - Implemented as class methods
- Challenge
 - Checkers currently cannot be instantiated in classes
 - Need to enhance them to allow their usage in UVM

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