



Telling a robot how to behave

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COS 116: 2/7/2008



Survey results

- Class break-down

- Freshmen: 10
- Sophomore: 10
- Juniors: 10
- Seniors: 4

- Majors

- 6 ECO 1 ORFE
- 6 POL 1 ELE
- 3 ENG 6 Undecided
- 3 East Asian St.
- 2 MAT
- 2 Classics
- 1 WWS
- 1 SOC
- 1 Comp. Litt.
- 1 HIST

- Own a:

- PC: 25
- Mac: 11
- Game console: 17
- Palm: 1
- iPod: 27

- Have a web page: Yes: 4 No: 30

- Ever posted on blog: Yes: 15; No: 19

- Programming: Yes: 8 ; No: 26

- College:

- 9 Forbes
- 4 Mathey
- 2 Butler
- 7 Wilson
- 5 Rocky
- 7 Whitman

Today: Understanding a simple robot

Why?

- Larger goal: work towards an answer to

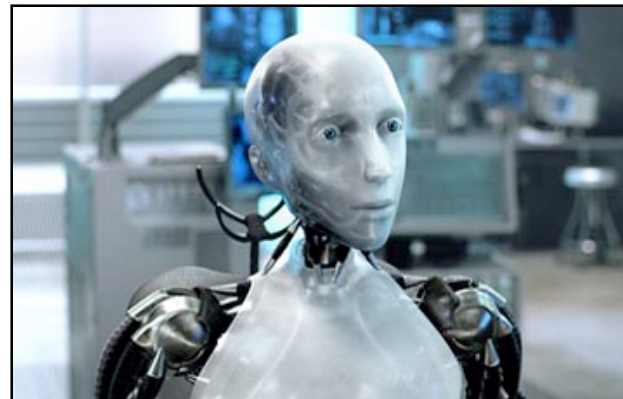
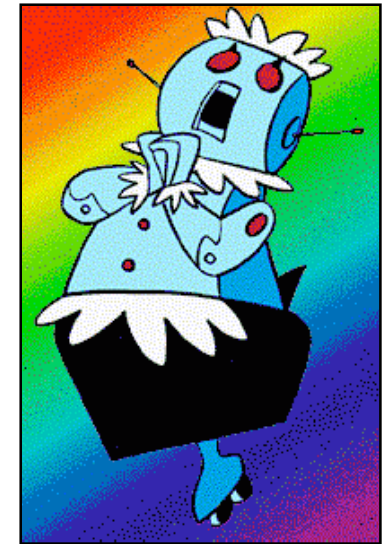
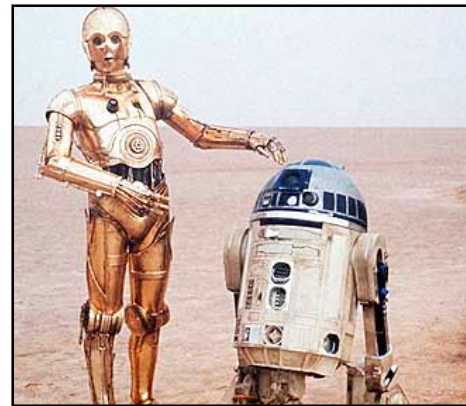
“What is Computation?”

- Acquire insight into technology that will become pervasive within the next decade.

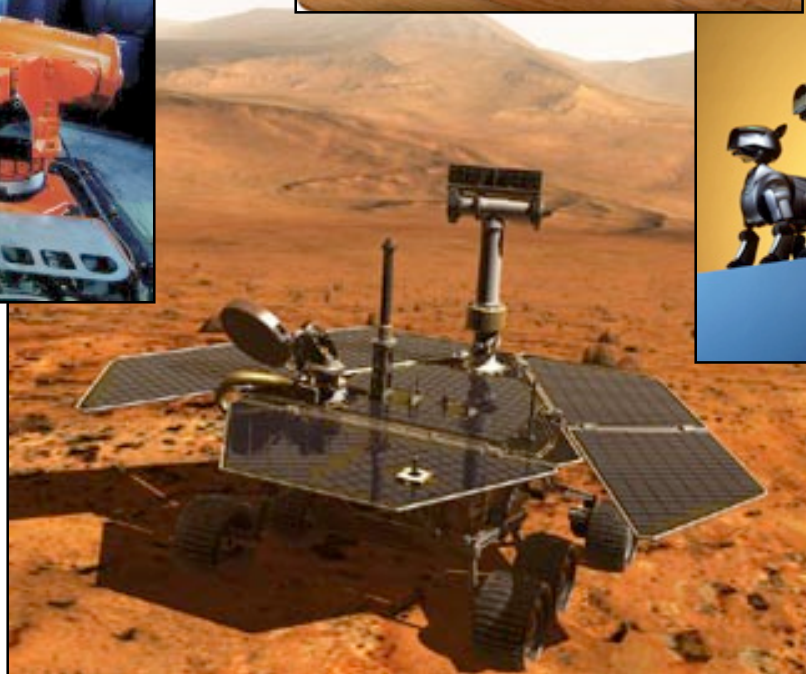
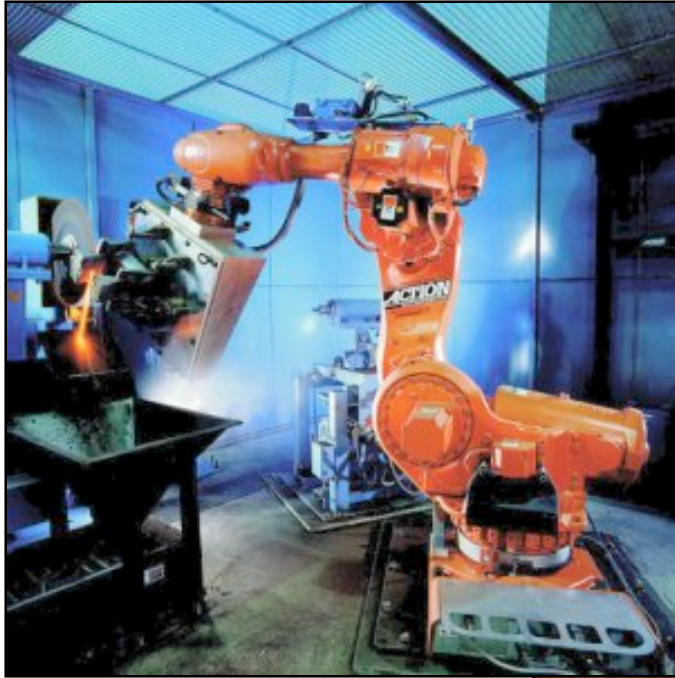
- First encounter with many themes of this course



Robots in culture



Real robots





Discussion Time



How do you think the Mars Rover works?

What are the design principles?

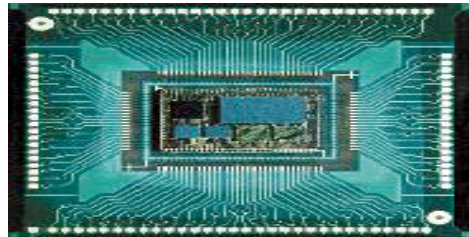


Definition of “Robot”:

- A machine that can be programmed to interact with the physical environment in a desired way.
- Key word: programmed
 - As opposed to cars, televisions, lawnmowers, which are operated by people

Components of a robot

1. Sensors/Inputs: light, sound, motion...



2. Computing Hardware
(programmable)

3. Outputs/Actions: motors, lights, speakers...

Our robot: Scribbler

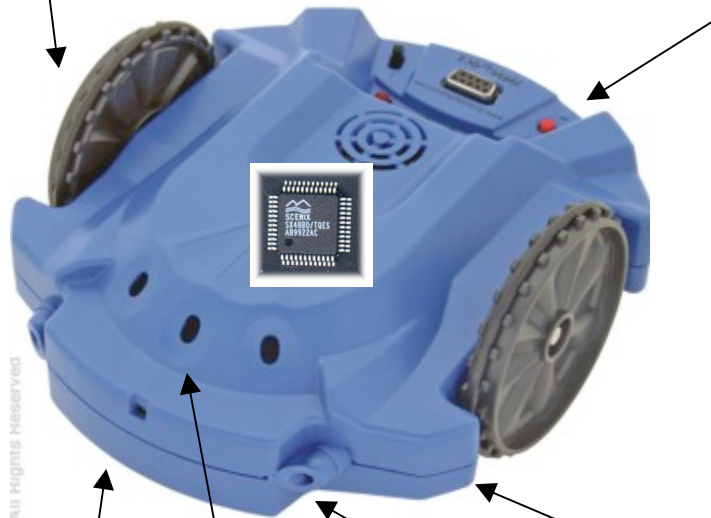
Stall sensor

Inputs

button

Outputs

Speaker



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Line sensor (underneath)

Light sensors

Obstacle sensor emitter

Obstacle sensor detector

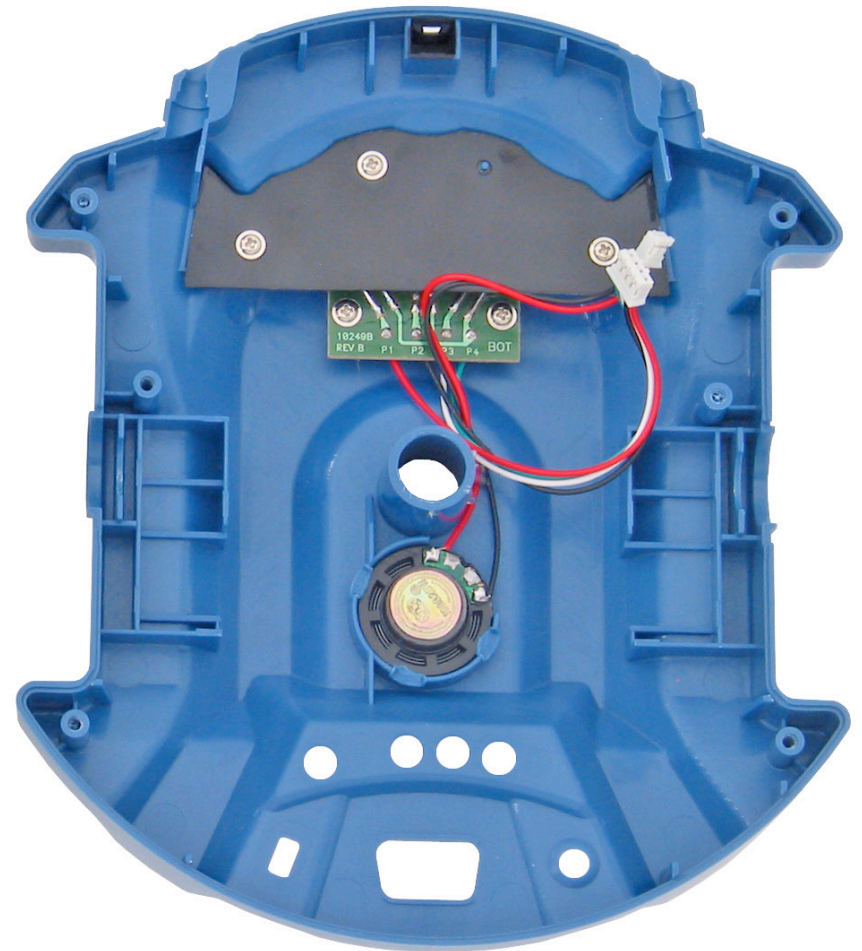
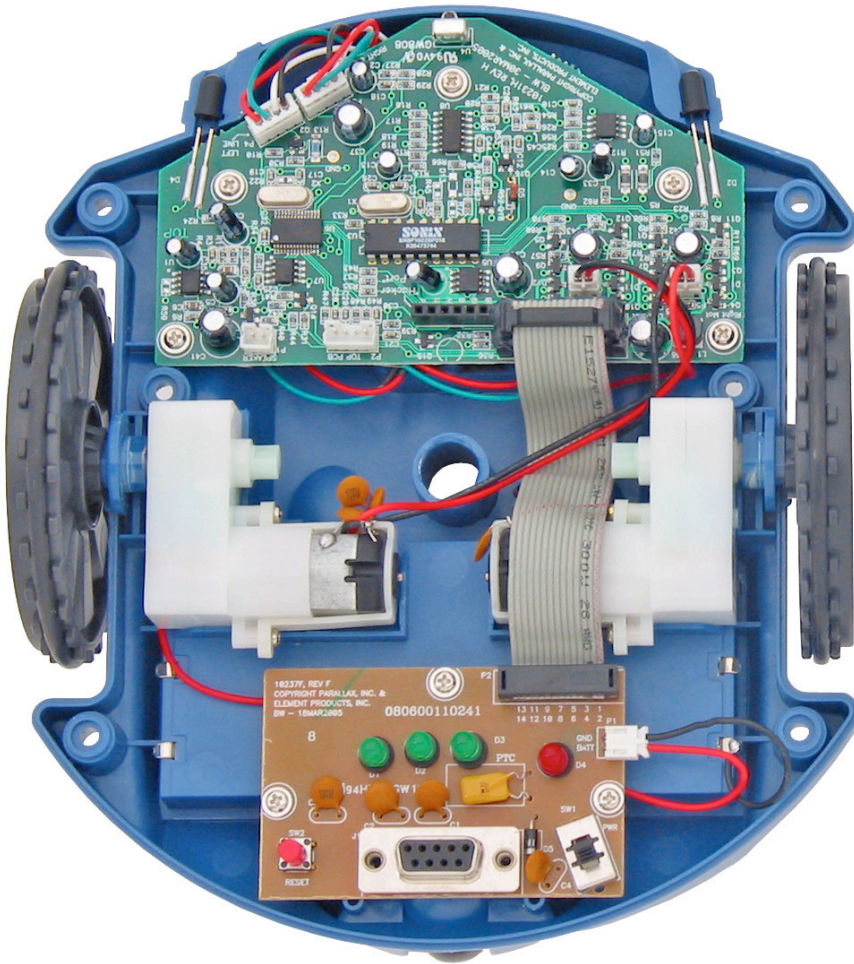
Motor/wheels



Light outputs

Scribbler inside

*(In a few weeks:
How Silicon chips and
microprocessors work)*



How to control a machine's behavior

- Fact of life in computing: hardware is “dumb”
- Forces us to make nebulous concepts precise
 - What is an obstacle? Music?

Running theme in this course

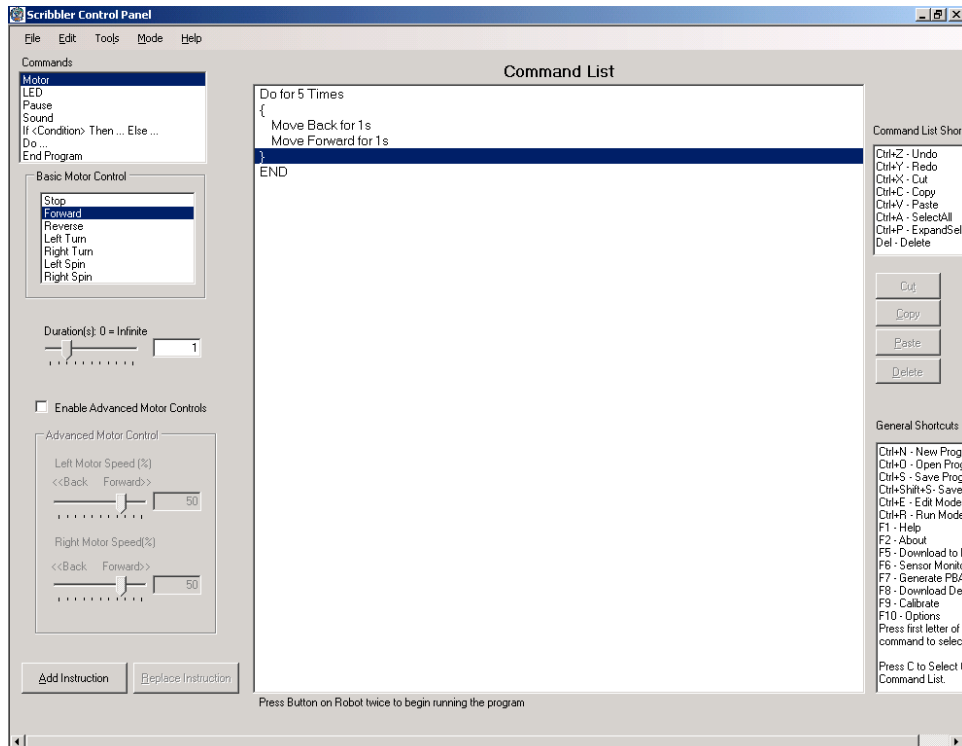
Another running theme:

What is machine “intelligence”?

Are there any limits on machine intelligence?



Controlling Scribbler's behavior



Scribbler Control Panel
(uses "pseudocode")

Let's play with it



Always remember...

(esp. for Scribbler labs):

- Microprocessor can do one thing at a time
- Very fast -- 20 million operations per second!
(desktop PCs do a few billion ops)
- Sequence of instructions within { ... } form a
“compound instruction”

Why programmable?

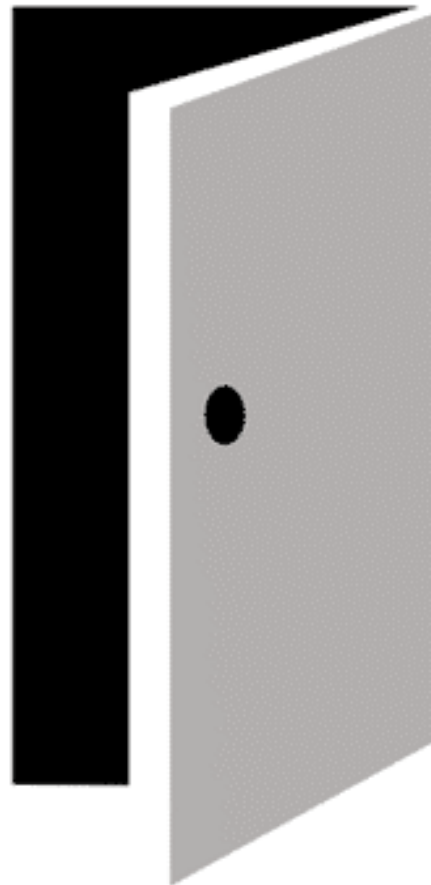
- Benefits of a programmable device:

- Flexible
- Multi-use
- Universal



- Main difference between computers and other technologies

Example 1: As a burglar alarm



If beam interrupted...

Beep!



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Example 2: As an artiste





Interesting note: Scribbler is less smart than is apparent from Control Panel

Do forever

```
{  
  Move Forward for 1s  
  Move back for 1s  
}  
END
```

=

3 pages of instructions for microprocessor

GOTO Main

SenseObs:

FREQOUT ObsTxLeft, 1, 38500

IF (ObsRx = 0) THEN object_left = 1 ELSE

object_left = 0

LOW ObsTxLeft

FREQOUT ObsTxRight, 1, 38500

IF (ObsRx = 0) THEN object_right = 1 ELSE

object_right = 0

LOW ObsTxRight

RETURN

SenseLine:

HIGH LineEnable

line_right = LineRight

line_left = LineLeft

LOW LineEnable

“Translator” written by
Rajesh Poddar ‘08

Where are things going?

- “Small cleaning agents” – Brooks



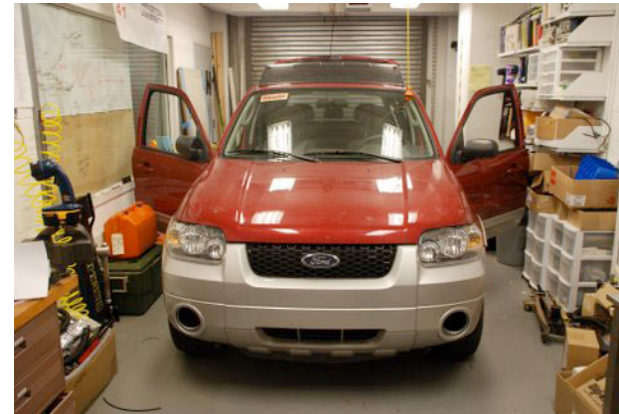
Roomba, the first fully-programmable consumer device

Example: Roomba + bluetooth adapter + software download = a vacuum cleaner controlled by your Wii remote (or iPhone)

Where are things going?



Boss; winner of \$2M DARPA Urban Challenge 2007. Completed urban driving course in 4 hours with no accidents at avg speed of 14mph



Princeton entry; semifinalist



Which of you will be willing to ride in a robocar?



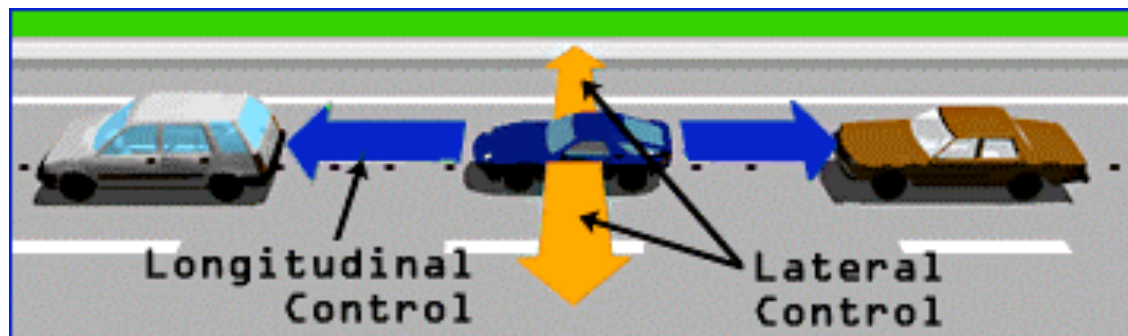
The Future?

- Automated highways



(From Minority Report)

Being actively researched



Why multi-purpose robots have proved so hard to build

- *Need precise instruments akin to human (even animal) eyes, ears, limbs, hands/fingers. Formidable engineering problem!*
- *Need smart ways of using these information from sensors*

(Example: Human vision versus high-resolution video camera)



Another running theme in this course: "Algorithms"

*Reminder: Reading for this week;
p 3-31 from Brooks.*

What is going inside us?

- “Da Vinci” Robotic surgery system
- More precise, though often still controlled by human

