## LECTURE NOTES

# Theoretical plasma physics 

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These lecture notes were presented by Allan N. Kaufman in his graduate plasma theory course and a follow-on special topics course (Physics 242A, B, C and Physics 250 at the University of California Berkeley). The notes follow the order of the lectures. The equations and derivations are as Kaufman presented, but the text is a reconstruction of Kaufman's discussion and commentary. The notes were transcribed by Bruce I. Cohen in 1971 and 1972, and word processed, edited and illustrations added by Cohen in 2017 and 2018. The series of lectures is divided into four major parts: (i) collisionless Vlasov plasmas (linear theory of waves and instabilities with and without an applied magnetic field, Vlasov-Poisson and Vlasov-Maxwell systems, Wentzel-Kramers-Brillouin-Jeffreys (WKBJ) eikonal theory of wave propagation); (ii) nonlinear Vlasov plasmas and miscellaneous topics (the plasma dispersion function, singular solutions of the Vlasov-Poisson system, pulse-response solutions for initial-value problems, Gardner's stability theorem, gyroresonant effects, nonlinear waves, particle trapping in waves, quasilinear theory, nonlinear three-wave interactions); (iii) plasma collisional and discreteness phenomena (test-particle theory of dynamic friction and wave emission, classical resistivity, extension of test-particle theory to many-particle phenomena and the derivation of the Boltzmann and Lenard-Balescu equations, the Fokker-Planck collision operator, a general scattering theory, nonlinear Landau damping, radiation transport and Dupree's theory of clumps); (iv) non-uniform plasmas (adiabatic invariance, guiding-centre drifts, hydromagnetic theory, introduction to drift-wave stability theory).

Key words: plasma confinement, plasma instabilities, plasma waves


Lecture Notes for Physics 242A, B, C and Physics 250 1971-1972
Transcribed, edited, and graphics added by Bruce I. Cohen

## Foreword

Allan Kaufman (b. 1927) grew up in the Hyde Park neighbourhood of Chicago not far from the University of Chicago. Allan attended the University of Chicago for both his undergraduate and doctoral degrees in physics. Chicago was replete with physics luminaries on its faculty and future luminaries among the doctoral students. Allan's doctoral thesis advisor was Murph Goldberger who was relatively new to the faculty at Chicago and just five years older than Allan. Allan did a theoretical thesis on a strong-coupling theory of meson-nucleon scattering. Allan published an autobiographical article entitled 'A half-century in plasma physics' in A.N. Kaufman, Journal of Physics: Conference Series 169 (2009) 012002.

Allan worked at Lawrence Livermore Laboratory from June 1953 through 1963. While at Livermore Laboratory he taught the one-year graduate course in electricity and magnetism in 1959-1963 at UC Berkeley. In 1963 he first taught the first semester of the graduate course in Theoretical Plasma Physics 242A at Berkeley. He taught the plasma theory course at UCLA in the 1964-1965 school year while on leave from Livermore before joining the faculty at UC Berkeley in the 1965 school year. Allan frequently taught the graduate plasma theory course and the graduate statistical mechanics course until his retirement from teaching in 1998.

The lecture notes from Kaufman's graduate plasma theory course and a follow-on special topics course presented here were from the 1971-1972 academic year and the first quarter of the 1972-1973 academic year. The notes follow the chronological order of the lectures as they were presented. The equations and derivations are as Kaufman presented, but the text is a reconstruction of Kaufman's discussion and commentary. The content of Kaufman's graduate plasma theory courses evolved over time motivated by new developments in plasma theory. Thus, the material reported here does not represent the totality of Kaufman's lecture notes on plasma theory. Some of the graphics have been downloaded from material posted as open access on the Internet or from published material with full attributions to the sources.

I joined Kaufman's research group during the 1971-1972 academic year. At that time Allan's group included doctoral students Dwight Nicholson, Michael Mostrom, Gary Smith and myself. Claire Max was a post-doctoral research physicist associated with the group for part of this period. I graduated in August 1975. Harry Mynick, John Cary and Robert Littlejohn did their doctoral theses with Allan shortly thereafter. One can see the influence of Allan Kaufman's formulation of plasma theory in the late Dwight Nicholson's fine textbook Introduction to Plasma Theory (John Wiley \& Sons, 1983).

I am very grateful to Allan Kaufman for his encouragement, interest, and feedback as I prepared these lecture notes and to Alain Brizard for reviewing the manuscript and making suggestions, and corrections. I also thank Gene Tracy, Robert Littlejohn and Jonathan Wurtele for their interest and encouragement. Lastly, I thank various authors for granting me permission to use their graphics.

Bruce I. Cohen

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## PART 1

## 1. Introduction to plasma dynamics

[Editor's note: in the first lecture of Physics 242A Kaufman discussed the syllabus for Physics 242A, B and C. Kaufman used CGS units throughout his notes. The textbook used as a general resource for the class at that time was P.C. Clemmow and J.P. Dougherty, The Electrodynamics of Particles and Plasmas, Addison-Wesley (1969).]

### 1.1. Basic assumptions, definitions and restrictions on scope

DEFInition. An ideal plasma is a charged gas wherein no bound states exist (a 'mythical beast').

Postulate. We exclude the sufficiently dense plasma that requires quantum effects: $\hbar \rightarrow 0$ here.

Postulate. We further ignore special relativity: $\beta \equiv v / c \ll 1$.
For purposes of an introductory study of plasma dynamics we initially assume no applied magnetic field $\boldsymbol{B}=0$ and dispense with the generality of Maxwell's equations in favour of retaining only Coulomb interactions. We assume a gas of $N$ charged particles. Then the force on particle $i$ due to all the other particles is given by

$$
\begin{equation*}
m_{i} \dot{\boldsymbol{v}}_{i}=e_{i} \sum_{j(\neq i)}^{N} \hat{\boldsymbol{r}}_{i j} \frac{e_{j}}{r_{i j}^{2}} \tag{1.1}
\end{equation*}
$$

where $m_{i}$ is mass; $\boldsymbol{v}_{i}$ is velocity; the dot indicates a time derivative; $e_{i}$ is the electric charge; and $r_{i j}$ is the distance from the $j$ th particle to the $i$ th particle and there are $N$ such equations; $\hat{\boldsymbol{r}}_{i j}$ points from particle $j$ to particle $i$. We require an approximation method to solve this system of nonlinear equations. The charges and masses are parameters that have explicit dimensions. We also require initial conditions
on particle positions and velocities, and need a statistical approach because $N$ is large.

DEFINITION. $\ell_{0}$ is the average distance between nearest neighbours; $n \approx 1 / \ell_{0}^{3}$ is the number density of particles; and $\bar{v}$ is an average velocity. These define the state of the plasma, statistically.

### 1.2. Definition of a plasma

Form the dimensionless quantity $e^{2} / m \ell_{0} \bar{v}^{2}$. The classical electron radius is $r_{e}=e^{2} / m c^{2}$; so divide by another length $\ell_{0}$ to form a dimensionless quantity:

DEFINITION.

$$
\frac{e^{2}}{m \ell_{0} \bar{v}^{2}}=\frac{e^{2} / \ell_{0}}{m \bar{v}^{2}}=\frac{\text { avg. nearest neighbour interaction energy }}{\text { avg. kinetic energy }}=\frac{1}{\Lambda^{*}}
$$

Thus, we are comparing the interaction energy to the kinetic energy in the plasma; and we treat the interaction energy as a perturbation. The plasma is said to be weakly coupled.

Postulate. In our plasmas $N$ and $\Lambda^{*} \gg 1$, equivalently $m \bar{v}^{2} \sim k_{B} T \gg e^{2} / \ell_{0}$.
We are not assuming that the total kinetic energy $N k_{B} T \gg N^{2} e^{2} / \ell_{0}$. [Editor's note: in what follows, units are employed for the temperature $T$ such that $k_{B} \equiv 1$.] There are some plasmas in which $\Lambda^{*} \leqslant O(1)$, for instance in a metal where the interaction and the Fermi energies are comparable; and a quantum mechanical treatment is then necessary. In ionic crystals $\Lambda^{*} \ll 1$ is possible.

ExErcise. (i) Find the region in temperature $T$ and density $n$ parameter space such that $\Lambda^{*} \gg 1$. (ii) Impose the additional constraints $v / c \ll 1$ and $n \lambda_{\text {de Broglie }}{ }^{3}=$ $n(h / m v)^{3} \ll 1$.

DEFINITION. The collision frequency is $v \sim n \sigma v$ where $\sigma \sim\left(e^{2} / m v^{2}\right)^{2}$, and the plasma frequency is $\omega_{\mathrm{pe}} \sim\left(4 \pi n e^{2} / m\right)^{1 / 2}$. Then $\nu / \omega_{\mathrm{pe}} \sim\left(\Lambda^{*}\right)^{-3 / 2} \ll 1$, i.e. the relative collisionality of the plasma is weak.

Definition. The Debye length $\lambda_{D} \equiv \bar{v} / \omega_{\mathrm{pe}}=\left(T / 4 \pi n e^{2}\right)^{1 / 2}$ is the characteristic shielding length, i.e. the effective interaction distance. The shielded potential from a test particle is $V \sim(e / r) \exp \left(-r / \lambda_{D}\right)$, and the number of particles in a region around a test particle of order the Debye length in dimension is then $\Lambda \sim n \lambda_{D}^{3}$. We must require that $\Lambda \gg 1$ for the validity of a statistical approach.

ThEOREM. $\Lambda \sim\left(\Lambda^{*}\right)^{3 / 2}$ so that the conditions of weak collisionality and weak interaction energy are closely related. We will use $\Lambda \gg 1$ exclusively and call it the plasma parameter. [Note: sometimes the plasma parameter is defined as $\Lambda \equiv 4 \pi n \lambda_{D}^{3}$.]

We note it is a very good assumption for most plasmas to assume that the Debye length $\lambda_{D}$ is small compared to the plasma macroscopic dimension $L$, so that $N \sim n L^{3} \gg \Lambda \sim n \lambda_{D}^{3}$.


Figure 1. Flow in phase space (cartoon).

## 2. Vlasov-Poisson equation formulation for a collisionless plasma

### 2.1. Equations of motion in phase space, Poisson equation and definition of distribution function

Consider the group collective, microscopic electric field $\boldsymbol{E}$ and the equations of motion

$$
\begin{equation*}
m_{i} \dot{\boldsymbol{v}}_{i}=e_{i} \boldsymbol{E}^{i}=e_{i} \sum_{j(i \neq i)} \hat{\boldsymbol{r}}_{i j} \frac{e_{j}}{\boldsymbol{r}_{i j}^{2}}, \tag{2.1}
\end{equation*}
$$

where $\boldsymbol{E}^{i}$ is the electric field on particle $i$. We coarse-grain average the point charges to smear and smooth the collective electric field,

$$
\begin{equation*}
m_{i} \dot{\boldsymbol{v}}_{i}=e_{i} \boldsymbol{E}^{i}\left(\boldsymbol{r}_{i}\right) \rightarrow e_{i} \overline{\boldsymbol{E}}\left(\boldsymbol{r}_{i}\right) . \tag{2.2}
\end{equation*}
$$

The six-dimensional phase-space equations of motion are then

$$
\left.\begin{array}{c}
m_{s} \dot{\boldsymbol{v}}_{s}=e_{s} \overline{\boldsymbol{E}}(\boldsymbol{r})  \tag{2.3}\\
\dot{\boldsymbol{r}}=\boldsymbol{v}
\end{array}\right\} \frac{\mathrm{d}}{\mathrm{~d} t}(\boldsymbol{r}, \boldsymbol{v})=\left(\boldsymbol{v}, \frac{e_{s}}{m_{s}} \overline{\boldsymbol{E}}(\boldsymbol{r})\right) .
$$

This phase space is not the same as the Gibbs phase space in statistical mechanics. Theorem. Poisson's equation is

$$
\begin{equation*}
\nabla \cdot \boldsymbol{E}=4 \pi \rho(\boldsymbol{r}) \quad \nabla \times \boldsymbol{E}(\boldsymbol{r})=0 \quad \text { where } \rho(\boldsymbol{r})=\sum_{i} e_{i} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{i}\right), \tag{2.4}
\end{equation*}
$$

with the electrostatic constraint on $\boldsymbol{E}$ and the charge density $\rho(\boldsymbol{r})$ needs to be smoothed.

DEFINITION. $f_{s}(\boldsymbol{r}, \boldsymbol{v})$ is the mean density of particles of a species $s$ in six-dimensional phase space; then

$$
\begin{equation*}
\bar{\rho}(\boldsymbol{r}) \equiv \sum_{s} e_{s} \int \mathrm{~d}^{3} \boldsymbol{v} f_{s}(\boldsymbol{r}, \boldsymbol{v}) \tag{2.5}
\end{equation*}
$$

The smoothed version of (2.4) becomes

$$
\begin{equation*}
\nabla \cdot \overline{\boldsymbol{E}}=4 \pi \sum_{s} e_{s} \int \mathrm{~d}^{3} \boldsymbol{v} f_{s}(\boldsymbol{r}, \boldsymbol{v}) \quad \nabla \times \overline{\boldsymbol{E}}=0 \tag{2.6}
\end{equation*}
$$

$f_{s}(\boldsymbol{r}, \boldsymbol{v})$ evolves in time: what is the equation of evolution for $f_{s}(\boldsymbol{r}, \boldsymbol{v} ; t)$ in time? Introduce $\boldsymbol{x}=(\boldsymbol{r}, \boldsymbol{v})$ and $(\mathrm{d} / \mathrm{d} t) \boldsymbol{x} \equiv \boldsymbol{X}(\boldsymbol{x} ; t)$; then $f_{s}(\boldsymbol{r}, \boldsymbol{v} ; t) \equiv f_{s}(\boldsymbol{x} ; t)$.

THEOREM. The number of particles $N_{V}$ for any species in a volume $V$ is

$$
\begin{equation*}
N_{V}(t)=\int_{V} \mathrm{~d}^{6} \boldsymbol{x} f(\boldsymbol{x} ; t) \tag{2.7}
\end{equation*}
$$

Because the number of particles in the volume is conserved, except for net fluxes into or out of the surfaces bounding the volume, it follows that

$$
\begin{equation*}
\frac{\mathrm{d} N_{V}}{\mathrm{~d} t}=\int_{V} \mathrm{~d}^{6} \boldsymbol{x} \frac{\partial f(\boldsymbol{x} ; t)}{\partial t}=-\oint_{\text {surfaces }} \mathrm{d} \hat{\sigma} \cdot \boldsymbol{x} f=-\int_{V} \mathrm{~d}^{6} \boldsymbol{x} \nabla \cdot(\boldsymbol{X} f) \tag{2.8}
\end{equation*}
$$

where $\hat{\sigma}$ points out of the volume and the divergence theorem has been used. Given that the volume integrals in (2.8) are equal for whatever subdomain of phase space is enclosed in $V$, the integrands must be equal; and we arrive at the Vlasov equation.

THEOREM. Vlasov equation

$$
\begin{align*}
\frac{\partial f_{s}(\boldsymbol{x} ; t)}{\partial t} & =-\nabla \cdot\left(\boldsymbol{X} f_{s}\right)=-\frac{\partial}{\partial \boldsymbol{r}}\left(\boldsymbol{v} f_{s}\right)-\frac{\partial}{\partial \boldsymbol{v}}\left(\frac{e_{s}}{m_{s}} \overline{\boldsymbol{E}}(\boldsymbol{r}, t) f_{s}\right) \\
& =-\boldsymbol{v} \cdot \frac{\partial}{\partial \boldsymbol{r}} f_{s}-\frac{e_{s}}{m_{s}} \overline{\boldsymbol{E}}(\boldsymbol{r}, t) \cdot \frac{\partial}{\partial \boldsymbol{v}} f_{s} \tag{2.9}
\end{align*}
$$

which can be rewritten as

$$
\begin{equation*}
\frac{\partial f_{s}(\boldsymbol{x} ; t)}{\partial t}+\boldsymbol{v} \cdot \frac{\partial}{\partial \boldsymbol{r}} f_{s}+\frac{e_{s}}{m_{s}} \overline{\boldsymbol{E}}(\boldsymbol{r}, t) \cdot \frac{\partial}{\partial \boldsymbol{v}} f_{s}=0 . \tag{2.10}
\end{equation*}
$$

In the presence of volumetric sources and sinks, e.g. ionization and recombination, and/or collisions, the right-hand side of (2.10) is no longer zero.

### 2.2. Continuity equation in phase space - Liouville theorem

A number of observations can be made immediately on inspecting the derivation of the Vlasov equation. From (2.7), (2.8) and $\mathrm{d} \boldsymbol{x} / \mathrm{d} t \equiv \boldsymbol{X}(\boldsymbol{x}, t)$ we have

$$
\begin{equation*}
\frac{\partial f(\boldsymbol{x} ; t)}{\partial t}=-\frac{\partial}{\partial \boldsymbol{x}} \cdot(\boldsymbol{X} f)=-\boldsymbol{X} \cdot \frac{\partial f}{\partial \boldsymbol{x}}-f \frac{\partial}{\partial \boldsymbol{x}} \cdot \boldsymbol{X} \tag{2.11}
\end{equation*}
$$

and hence,

$$
\begin{equation*}
\left(\frac{\partial}{\partial t}+\dot{x} \cdot \frac{\partial}{\partial \boldsymbol{x}}\right) f(\boldsymbol{x} ; t)=-f(\boldsymbol{x} ; t) \frac{\partial}{\partial \boldsymbol{x}} \cdot \boldsymbol{X}=-f(x ; t) \nabla \cdot \boldsymbol{X} \tag{2.12}
\end{equation*}
$$

Equation (2.12) is a phase-space continuity equation. The left-hand side of this equation is just a convective derivative, and the right-hand side allows for compressibility. If $\boldsymbol{\nabla} \cdot \boldsymbol{X}<0$ then $\mathrm{D} f / \mathrm{D} t>0$, and $\mathrm{D} f / \mathrm{D} t<0$ if $\boldsymbol{\nabla} \cdot \boldsymbol{X}>0$. We note that as an almost trivial consequence of the independent phase-space variables,

$$
\begin{equation*}
\frac{\partial}{\partial \boldsymbol{r}} \cdot \boldsymbol{v}=0, \quad \frac{\partial}{\partial \boldsymbol{v}} \cdot\left(\frac{e}{m}\left(\boldsymbol{E}+\frac{\boldsymbol{v}}{c} \times \boldsymbol{B}\right)\right)=0 \Rightarrow \boldsymbol{\nabla} \cdot \boldsymbol{X}=\frac{\partial}{\partial \boldsymbol{r}} \cdot \boldsymbol{v}+\frac{\partial}{\partial \boldsymbol{v}} \cdot \dot{\boldsymbol{v}}=0 . \tag{2.13}
\end{equation*}
$$

THEOREM (Liouville theorem). If $\boldsymbol{\nabla} \cdot \boldsymbol{X}=0$, then the right-hand side of (2.12) is zero and (2.8.2) corresponds exactly to the Liouville theorem for Hamiltonian systems:

$$
\begin{equation*}
\left(\frac{\partial}{\partial t}+\dot{\boldsymbol{x}} \cdot \frac{\partial}{\partial \boldsymbol{x}} f(\boldsymbol{x} ; t)=0\right) \tag{2.14}
\end{equation*}
$$

In this limit the phase-space flow is 'incompressible' and $\mathrm{D} f / \mathrm{D} t=0$, i.e. $f$ is conserved along the phase-space trajectories. If the number of particles per unit volume $f$ is conserved then so is $1 / f$, which is the differential volume element per unit particle, i.e. the phase-space volume element is also conserved (although its shape may deform).

### 2.3. Nonlinear Vlasov equation with self-consistent fields

THEOREM. Vlasov-Maxwell equations in a plasma with self-consistent fields

$$
\begin{align*}
\left(\frac{\partial}{\partial t}+\boldsymbol{v} \cdot \frac{\partial}{\partial \boldsymbol{r}}+\frac{e_{s}}{m_{s}}\left(\boldsymbol{E}+\frac{\boldsymbol{v}}{c} \times \boldsymbol{B}\right) \cdot \frac{\partial}{\partial \boldsymbol{v}}\right) f_{s}(\boldsymbol{r}, \boldsymbol{v} ; t)=0  \tag{2.15}\\
\nabla \cdot \boldsymbol{E}=4 \pi \sum_{s} e_{s} \int \mathrm{~d}^{3} \boldsymbol{v} f_{s}(\boldsymbol{r}, \boldsymbol{v} ; t)  \tag{2.16}\\
\boldsymbol{\nabla} \times \boldsymbol{B}-\frac{1}{c} \frac{\partial \boldsymbol{E}}{\partial t}=\frac{4 \pi}{c} \sum_{s} e_{s} \int \mathrm{~d}^{3} \boldsymbol{v} \boldsymbol{v} f_{s}(\boldsymbol{r}, \boldsymbol{v} ; t)+\frac{4 \pi}{c} \boldsymbol{j}_{\mathrm{ext}}  \tag{2.17}\\
\boldsymbol{\nabla} \times \boldsymbol{E}+\frac{1}{c} \frac{\partial \boldsymbol{B}}{\partial t}=0  \tag{2.18}\\
\boldsymbol{\nabla} \cdot \boldsymbol{B}=0 \tag{2.19}
\end{align*}
$$

and we could include the gravitational Poisson equation,

$$
\begin{equation*}
\nabla^{2} \phi_{g}=4 \pi G \rho_{m}=4 \pi G \sum_{s} m_{s} \int \mathrm{~d}^{3} \boldsymbol{v} f_{s} \tag{2.20}
\end{equation*}
$$

where the gravitational field $\boldsymbol{g}=-\nabla \phi_{g}, \phi_{g}$ is the gravitational potential, $\rho_{m}$ is the mass density and $G$ is the universal gravitational constant. The gravitational field $\boldsymbol{g}$ could then be included in (2.15) as an additional acceleration term.

In a Hamiltonian system one can introduce the notation

$$
\begin{equation*}
\boldsymbol{x}=\left(q_{i}, p_{i}\right) \quad \boldsymbol{X}=\left(\frac{\partial H}{\partial p_{i}},-\frac{\partial H}{\partial q_{i}}\right) \tag{2.21}
\end{equation*}
$$

where $H$ is the particle Hamiltonian and the $i$ index represents a phase-space degree of freedom. The Vlasov equation then can be written as

$$
\begin{equation*}
\frac{\partial f}{\partial t}+\sum_{i}\left(\frac{\partial f}{\partial q_{i}} \frac{\partial H}{\partial p_{i}}-\frac{\partial f}{\partial p_{i}} \frac{\partial H}{\partial q_{i}}\right)=\frac{\partial f}{\partial t}+\{f, h\}=0 \tag{2.22}
\end{equation*}
$$

where $\{f, H\}$ denotes the Poisson bracket.
By simplifying the electromagnetic fields to be electrostatic, equations (2.15)-(2.19) become the Vlasov-Poisson equations, which are written as

$$
\begin{align*}
& \boldsymbol{E}=-\nabla \phi, \quad \nabla^{2} \phi=-4 \pi \rho_{c}, \quad \phi(\boldsymbol{r}, t)=\int \mathrm{d}^{3} \boldsymbol{r}^{\prime} \frac{\rho_{c}\left(\boldsymbol{r}^{\prime}, t\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} \\
& \frac{\partial f_{s}}{\partial t}+\boldsymbol{v} \cdot \frac{\partial f_{s}}{\partial \boldsymbol{r}}+\frac{e_{s}}{m_{s}} \frac{\partial f_{s}}{\partial \boldsymbol{v}} \cdot\left(-\frac{\partial}{\partial \boldsymbol{r}}\right) \int \mathrm{d}^{3} \boldsymbol{r}^{\prime} \frac{4 \pi \sum_{s^{\prime}} e_{s^{\prime}} \int \mathrm{d}^{3} \boldsymbol{v}^{\prime} f_{s}\left(\boldsymbol{r}^{\prime}, \boldsymbol{v}^{\prime}, t\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|}=0 \tag{2.23}
\end{align*}
$$

We next consider the qualitative properties of the nonlinear self-consistent Vlasov equation in (2.23). The relative orders of the three terms are $f / \tau: v f / \lambda: f^{2} e^{2} \lambda v^{2} / m$, where $\tau, \lambda$ and $v$ are the characteristic temporal, spatial and particle velocity scales. (i) Balancing the first two terms in the Vlasov equations yields $\tau \sim \lambda / v$ or $\omega / k \sim v$, i.e. $v_{p} \sim v$, where $v_{p}=\omega / k, \omega$ is a characteristic frequency and $k$ is a wavenumber.
(ii) Balancing the second and third terms yields $\omega \sim 4 \pi\left(e^{2} / m\right) f v^{3} \lambda / v \sim\left(4 \pi n e^{2} / m\right) \lambda / v$ which using $\omega \lambda \sim v$ leads to $\omega^{2} \sim 4 \pi n e^{2} / m$, which is the plasma frequency squared. (iii) With $\lambda \sim v / \omega$ and setting $v \sim v_{\text {th }}=(T / m)^{1 / 2}$ the electron thermal velocity, then $\lambda \sim \lambda_{D} \sim\left(T / 4 \pi n e^{2}\right)^{1 / 2}$ where $\lambda_{D}$ is the Debye length. We will see that many plasma phenomena can be characterized in terms of important dimensionless variables, for example, $\omega / \omega_{\mathrm{pe}}, \lambda / \lambda_{D}, m_{e} / m_{i}, T_{e} / T_{i}, \omega / k v, L / \lambda_{D}, \omega_{\mathrm{ps}} / \omega_{\mathrm{cs}}, \Delta \omega / \omega, v_{\mathrm{th}} / c$ and the ratios of $E^{2}$ to $B^{2}$ and to $n m v^{2}$. There are also plasma attributes and phenomena associated with non-uniformity and anisotropy.

### 2.4. Moment equations

### 2.4.1. Conservation of mass density, momentum density, energy density

Rewrite the collisionless Vlasov equation in the alternative form

$$
\begin{equation*}
\frac{\partial}{\partial t} f_{s}+\frac{\partial}{\partial \boldsymbol{r}} \cdot\left(\boldsymbol{v} f_{s}\right)+\frac{\partial}{\partial \boldsymbol{v}} \cdot\left(\boldsymbol{a} f_{s}\right)=0 \tag{2.24}
\end{equation*}
$$

where the acceleration $\boldsymbol{a}$ is

$$
\begin{equation*}
\boldsymbol{a}=\frac{e_{s}}{m_{s}}\left(\boldsymbol{E}+\frac{1}{c} \boldsymbol{v} \times \boldsymbol{B}\right) \tag{2.25}
\end{equation*}
$$

and define the number density $n_{s}$

$$
\begin{equation*}
n_{s}(\boldsymbol{r}, t)=\int \mathrm{d}^{3} \boldsymbol{v} f_{s}(\boldsymbol{r}, \boldsymbol{v} ; t) \tag{2.26}
\end{equation*}
$$

Definition. Moments of the velocity distribution are constructed from

$$
\begin{equation*}
\langle A\rangle_{s}(\boldsymbol{r} ; t) \equiv \frac{\int \mathrm{d}^{3} \boldsymbol{v} A f_{s}(\boldsymbol{r}, \boldsymbol{v} ; t)}{\int \mathrm{d}^{3} \boldsymbol{v} f_{s}(\boldsymbol{r}, \boldsymbol{v} ; t)} . \tag{2.27}
\end{equation*}
$$

Examples. (i) $A=1 \rightarrow$ identity operation.
(ii) $A=\boldsymbol{v} \rightarrow \boldsymbol{u} \equiv\langle\boldsymbol{v}\rangle$ the average velocity.
(iii) $A=(\boldsymbol{v}-\boldsymbol{u})(\boldsymbol{v}-\boldsymbol{u}) \rightarrow n m\langle(\boldsymbol{v}-\boldsymbol{u})(\boldsymbol{v}-\boldsymbol{u})\rangle \equiv \boldsymbol{P}(r, t)$ the pressure tensor.
(iv) $A=e$ then $\sum_{s} e_{s} n_{s} \equiv \rho(\boldsymbol{r} ; t)$ the charge density using (2.26).
(v) $A=\frac{1}{2} m v^{2} \rightarrow K(r ; t) \equiv \int \mathrm{d} 3 v \frac{1}{2} m v^{2} f=n\left\langle\frac{1}{2} m v^{2}\right\rangle$ the kinetic energy density.

THEOREM. A generalized moment equation can be derived directly from the Vlasov equation (the species index $s$ is understood),

$$
\begin{align*}
\frac{\partial}{\partial t}[n\langle A\rangle] & =\int \mathrm{d}^{3} \boldsymbol{v}\left(\frac{\partial f}{\partial t} A+\frac{\partial A}{\partial t} f\right)=n\left\langle\frac{\partial A}{\partial t}\right\rangle+\int \mathrm{d}^{3} \boldsymbol{v} A\left[-\frac{\partial}{\partial \boldsymbol{r}} \cdot(\boldsymbol{v} f)-\frac{\partial}{\partial \boldsymbol{v}} \cdot(\boldsymbol{a} f)\right] \\
& =n\left\langle\frac{\partial A}{\partial t}\right\rangle-\nabla \cdot[n\langle A \boldsymbol{v}\rangle]+n\left\langle\boldsymbol{a} \cdot \frac{\partial A}{\partial \boldsymbol{v}}\right\rangle \tag{2.28}
\end{align*}
$$

EXAMPLES. (i) $A=1 \rightarrow$ continuity equation

$$
\begin{equation*}
\frac{\partial n(\boldsymbol{r} ; t)}{\partial t}=-\nabla \cdot(n \boldsymbol{u}) \tag{2.29}
\end{equation*}
$$

or

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} n(\boldsymbol{r} ; t)=\left(\frac{\partial}{\partial t}+\boldsymbol{u} \cdot \boldsymbol{\nabla}\right) n=-n \boldsymbol{\nabla} \cdot \boldsymbol{u} \tag{2.30}
\end{equation*}
$$

(ii) $A=m \boldsymbol{v} \rightarrow$ momentum conservation

$$
\begin{equation*}
\frac{\partial}{\partial t}\langle n m \boldsymbol{v}\rangle=\frac{\partial}{\partial t} n m \boldsymbol{u}=-\boldsymbol{\nabla} \cdot(n m\langle\boldsymbol{v} \boldsymbol{v}\rangle)+n e\left(\boldsymbol{E}+\frac{1}{c} \boldsymbol{u} \times \boldsymbol{B}\right) . \tag{2.31}
\end{equation*}
$$

We can use the identity $\langle\boldsymbol{v} \boldsymbol{v}\rangle=\langle(\boldsymbol{v}-\boldsymbol{u})(\boldsymbol{v}-\boldsymbol{u})\rangle+\boldsymbol{u} \boldsymbol{u}$, the continuity equation (2.30) and the definition of the pressure tensor $\boldsymbol{P}$ in conjunction with (2.31) to derive the fluid momentum balance equation,

$$
\begin{equation*}
n m \frac{\mathrm{~d}}{\mathrm{~d} t} \boldsymbol{u}=-\boldsymbol{\nabla} \cdot \boldsymbol{P}+n e\left(\boldsymbol{E}+\frac{1}{c} \boldsymbol{u} \times \boldsymbol{B}\right) . \tag{2.32}
\end{equation*}
$$

We can consider the Coulomb case, assume there is no magnetic field, sum over species, and integrate (2.31) over all space to demonstrate the total particle momentum is a constant,

$$
\begin{aligned}
& \int \mathrm{d}^{3} \boldsymbol{r}\left[\frac{\partial}{\partial t} \sum_{s}\left\langle n_{s} m_{s} \boldsymbol{v}\right\rangle\right]=\int \mathrm{d}^{3} \boldsymbol{r}\left[\sum_{x}\left(-\boldsymbol{\nabla} \cdot \boldsymbol{P}_{s}+n_{s} e_{s} \boldsymbol{E}\right)\right] \\
& \quad=\int \mathrm{d}^{3} \boldsymbol{r}\left[\sum_{x}\left(-\boldsymbol{\nabla} \cdot \boldsymbol{P}_{s}\right)+\rho \boldsymbol{E}\right]=\int \mathrm{d}^{3} \boldsymbol{r}\left[\sum_{x}\left(-\boldsymbol{\nabla} \cdot \boldsymbol{P}_{s}\right)+\frac{1}{4 \pi}(\boldsymbol{\nabla} \cdot \boldsymbol{E}) \boldsymbol{E}\right] \\
& \quad=\int \mathrm{d}^{3} \boldsymbol{r}\left[\sum_{x}\left(-\boldsymbol{\nabla} \cdot \boldsymbol{P}_{s}\right)+\boldsymbol{\nabla} \cdot\left(\frac{\boldsymbol{E} \boldsymbol{E}}{4 \pi}-\frac{E^{2} \boldsymbol{I}}{8 \pi}\right)\right]
\end{aligned}
$$

$$
\begin{align*}
& =\int \mathrm{d}^{3} \boldsymbol{r} \boldsymbol{\nabla} \cdot\left[\sum_{x}\left(-\boldsymbol{P}_{s}-\frac{\boldsymbol{E} \boldsymbol{E}}{4 \pi}+\frac{E^{2} \boldsymbol{I}}{8 \pi}\right)\right] \\
& =\oint \mathrm{d} \boldsymbol{S} \cdot\left(-\boldsymbol{P}_{s}-\frac{\boldsymbol{E} \boldsymbol{E}}{4 \pi}+\frac{E^{2} \boldsymbol{I}}{8 \pi}\right), \tag{2.33}
\end{align*}
$$

where $\mathrm{d} \boldsymbol{S}$ is directed out of volume on its surface and we have used the divergence theorem and Gauss' law, and assumed the fields and the velocity distributions vanish at infinity. We can include field stresses and field momentum using Maxwell's equations as in $\S 6.7$ of Jackson's Classical Electrodynamics textbook to demonstrate that the total particle and field momentum is conserved.
(iii) $A=\frac{1}{2} m v^{2} \rightarrow$ energy conservation

$$
\begin{equation*}
\frac{\partial}{\partial t} K_{s}=-\nabla \cdot n_{s}\left\langle\frac{1}{2} m_{s} v^{2} \boldsymbol{v}\right\rangle+n_{s}\left\langle e_{s} \boldsymbol{v}\right\rangle \cdot \boldsymbol{E}=-\nabla \cdot \boldsymbol{S}_{s}^{k}+\boldsymbol{j}_{s} \cdot \boldsymbol{E} . \tag{2.34}
\end{equation*}
$$

We note that the magnetic field does no work and (2.34) can be summed over species to obtain the equation for energy conservation of all particle species. $K$ is an energy density. Equation (2.34) summed over species is extended to include the electromagnetic field energy density as follows:

$$
\begin{equation*}
\frac{\partial}{\partial t}\left(K+\frac{E^{2}+B^{2}}{8 \pi}\right)=\frac{\partial}{\partial t}(K+E)=-\nabla \cdot\left(\boldsymbol{S}^{K}+\frac{c}{4 \pi} \boldsymbol{E} \times \boldsymbol{B}\right)=-\boldsymbol{\nabla} \cdot\left(\boldsymbol{S}^{K}+\boldsymbol{S}^{E M}\right) \tag{2.35}
\end{equation*}
$$

where we recognize $\boldsymbol{S}^{E M}$ as the electromagnetic Poynting flux and note that $\boldsymbol{J} \cdot \boldsymbol{E}$ terms identically cancel. By integrating (2.35) over volume, using the divergence theorem, and assuming all quantities vanish at infinity, we can demonstrate that total energy is conserved.
(iv) $A=m r^{2} \rightarrow$ moment of inertia

$$
\begin{align*}
I(t) & =\frac{1}{2} \int \mathrm{~d}^{3} \boldsymbol{r} \sum_{s} m_{s} r^{2} n_{s}(\boldsymbol{r} ; t) \\
\frac{\partial}{\partial t} I & =-\frac{1}{2} \int \mathrm{~d}^{3} \boldsymbol{r} \sum_{s} m_{s} \boldsymbol{r}^{2} \nabla \cdot\left(n_{s} \boldsymbol{u}_{s}\right)=\int \mathrm{d}^{3} \boldsymbol{r} \sum_{s} m_{s} n_{s} \boldsymbol{u}_{s} \cdot \boldsymbol{r} . \tag{2.36}
\end{align*}
$$

Here, $I$ is the moment of inertia (not to be confused with the identity tensor $I$ ) and is a global scalar quantity that only has a time variation. Equation (2.36) is derived using the continuity equation (2.29), integrating by parts, and using $\boldsymbol{u} \cdot \nabla r^{2}=2 \boldsymbol{u} \cdot \boldsymbol{r}$.

### 2.4.2. Virial theorem

One can deduce a relation from the second time derivative (acceleration) of the moment of inertia relation in (2.36) that provides insight into how a plasma can radiate electromagnetic fields which allows the system to collapse. This is embodied in a virial theorem.

VIRAL THEOREM. We begin by deriving the electromagnetic momentum conservation law from Maxwell's equations,

$$
\begin{align*}
-\frac{\partial}{\partial t}\left(\frac{\boldsymbol{E} \times \boldsymbol{B}}{4 \pi c}\right) & =\rho \boldsymbol{E}+\frac{1}{c} \boldsymbol{j} \times \boldsymbol{B}-\frac{1}{4 \pi} \nabla \cdot\left(\boldsymbol{E} \boldsymbol{E}-\frac{1}{2} E^{2} \boldsymbol{I}+\boldsymbol{B} \boldsymbol{B}-\frac{1}{2} B^{2} \boldsymbol{I}\right) \\
& =\rho \boldsymbol{E}+\frac{1}{c} \boldsymbol{j} \times \boldsymbol{B}-\frac{1}{4 \pi} \nabla \cdot \boldsymbol{P}^{E M} \tag{2.37}
\end{align*}
$$

We then take another time derivative in (2.36), use the momentum conservation equation (2.31) and include the $\boldsymbol{j} \times \boldsymbol{B} /$ c force in (2.33). We next eliminate $\rho \boldsymbol{E}+\boldsymbol{j} \times \boldsymbol{B} / c$ using (2.37) to obtain

$$
\ddot{I}=\int \mathrm{d}^{3} \boldsymbol{r} \boldsymbol{r} \cdot \frac{\partial}{\partial t} \sum_{s} n_{s} m_{s} \boldsymbol{u}_{s}=\int \mathrm{d}^{3} \boldsymbol{r} \boldsymbol{r} \cdot\left[-\nabla \cdot\left(\boldsymbol{P}^{K}+\boldsymbol{P}^{E M}\right)-\frac{\partial}{\partial t}\left(\frac{\boldsymbol{E} \times \boldsymbol{B}}{4 \pi c}\right)\right]
$$

We add the term involving the electromagnetic momentum to both sides of the equation to obtain

$$
\begin{equation*}
\ddot{I}+\frac{\mathrm{d}}{\mathrm{~d} t} \int \mathrm{~d}^{3} \boldsymbol{r} \boldsymbol{r} \cdot\left(\frac{\boldsymbol{E} \times \boldsymbol{B}}{4 \pi c}\right)=\int \mathrm{d}^{3} \boldsymbol{r} \boldsymbol{I}:\left(\boldsymbol{P}^{K}+\boldsymbol{P}^{E M}\right)=\int \mathrm{d}^{3} \boldsymbol{r}\left(2 K+E^{E M}\right)>0 \tag{2.38}
\end{equation*}
$$

where an integration by parts has been performed and I: denotes the resulting double dot product of the identity tensor with the tensor(s) following it. In the absence of the radiation flux $\boldsymbol{S}^{E M}$, one concludes that $\ddot{I}>0$ because the right-hand side of (2.37) is positive. In this limit the moment of inertia can only increase: in the absence of magnetic coils or gravity, the system cannot be contained by its own electromagnetic fields. With a finite radiation flux, the system can collapse and radiate energy away. An important caveat that limits these conclusions is that we did not include gravitation, which would introduce a negative term on the right-hand side.

Exercise. Verify (2.37) and the double dot product in (2.38).

### 2.5. Linear analysis of the Vlasov equation for small-amplitude disturbances in a uniform plasma

We can obtain exact solutions of the linearized Vlasov equation for infinitesimal amplitude perturbations.

Definition. Static solutions correspond to $\partial f / \partial t=0$. This situation applies to a very small, but important, class of solutions. The time-independent Vlasov equation is

$$
\begin{equation*}
\boldsymbol{v} \cdot \frac{\partial}{\partial \boldsymbol{r}} f+\frac{e}{m}\left(\boldsymbol{E}+\frac{1}{c} \boldsymbol{v} \times \boldsymbol{B}\right) \cdot \frac{\partial}{\partial \boldsymbol{v}} f=0 \tag{2.39}
\end{equation*}
$$

Uniform solutions correspond to $\partial f / \partial \boldsymbol{r}=0$.
In the absence of electric and magnetic fields there exists a solution for a spatially uniform $f(\boldsymbol{v})$ that can be an arbitrary function of velocity. For this simple case the solution of the time-dependent Vlasov equation is that $f$ is a constant along the phasespace trajectories and remains fixed at its initial, arbitrary function of velocity,

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} f(\boldsymbol{v})=\frac{\mathrm{d} \boldsymbol{v}}{\mathrm{~d} t} \cdot \frac{\partial}{\partial \boldsymbol{v}} f(\boldsymbol{v})=0 \tag{2.40}
\end{equation*}
$$

This almost trivial result has utility in that we now add a small-amplitude perturbation that can depend on time and space. For simplicity we restrict consideration to the case of a Coulomb model. The equation set for a small-amplitude, linear expansion of the distribution function and the self-consistent electric fields is as follows:

$$
\begin{align*}
& f_{s}(\boldsymbol{r}, \boldsymbol{v} ; t)=f_{0 s}(\boldsymbol{v})+\delta f_{s}(\boldsymbol{r}, \boldsymbol{v}: t)  \tag{2.41a}\\
& \boldsymbol{E}(\boldsymbol{r} ; t)=0+\delta \boldsymbol{E}(\boldsymbol{r} ; t) \quad \nabla \times \boldsymbol{E}=0  \tag{2.41b}\\
& \boldsymbol{\nabla} \cdot \boldsymbol{E}=4 \pi \rho(\boldsymbol{r} ; t)=4 \pi \sum_{s} e_{s} \int \mathrm{~d}^{3} \boldsymbol{v} f_{s}  \tag{2.41c}\\
& \frac{\partial \delta f_{s}}{\partial t}+\boldsymbol{v} \cdot \frac{\partial \delta f_{s}}{\partial \boldsymbol{r}}+\frac{\boldsymbol{e}_{s}}{m_{s}} \delta \boldsymbol{E} \cdot \frac{\partial}{\partial \boldsymbol{v}}\left(f_{0 s}+\delta f_{s}\right)=0 \rightarrow \\
& \quad \frac{\partial \delta f_{s}}{\partial t}+\boldsymbol{v} \cdot \frac{\partial \delta f_{s}}{\partial \boldsymbol{r}}=-\frac{\boldsymbol{e}_{s}}{m_{s}} \delta \boldsymbol{E} \cdot \frac{\partial f_{0 s}}{\partial \boldsymbol{v}} . \tag{2.41d}
\end{align*}
$$

The term on the right-hand side of (2.41d) that is nonlinear in the product of $\delta \boldsymbol{E}$ and $\delta f_{s}$, is dropped because of the linearization, i.e. only first-order terms in a Taylorseries expansion are retained. One must be careful with the vector calculus in (2.41d) when using non-Cartesian coordinates, and canonical coordinates can prove useful. We introduce the perturbed electric potential such that $\delta \boldsymbol{E}=-\nabla \delta \phi$ and follow the prescription: (i) Solve for $\delta f_{s}$ in terms of $\delta \phi$ using ( $2.41 d$ ). (ii) Construct the linearly perturbed charge density $\delta \rho$ from $\delta f_{s}$ using (2.41c). (iii) Solve for $\delta \phi$ using Poisson's equation derived from ( $2.41 b$ ) using suitable boundary conditions.

### 2.5.1. Causality, stationarity and uniformity in the dielectric kernel

We can deduce a linear relation of $\delta \rho$ on $\delta \phi$ for the linearized system. The charges in the plasma respond to the small-amplitude field produced by the perturbed electric potential. The most general linear relation can be represented as

$$
\begin{equation*}
\delta \rho(\boldsymbol{r} ; t)=\int \mathrm{d}^{3} \boldsymbol{r}^{\prime} \int \mathrm{d} t^{\prime} \chi\left(\boldsymbol{r}, \boldsymbol{r}^{\prime} ; t, t^{\prime}\right) \delta \phi\left(\boldsymbol{r}^{\prime} ; t^{\prime}\right) . \tag{2.42}
\end{equation*}
$$

The representation allows $\chi$ to be a generalized function. In fact, it can have some unusual properties, viz., including being a derivative of a delta function. However, $\chi$ is subject to at least three important constraints:
(i) Causality: a perturbation in $\delta \phi$ will cause a later perturbation in $\delta \rho$.
(ii) Stationarity: the effect of $\delta \phi$ on $\delta \rho$ can depend only on the time interval between cause and effect $\left(t-t^{\prime}\right)>0$, and cannot depend on absolute time. This is a consequence of the underlying unperturbed system being stationary, i.e. time independent.
(iii) Uniformity: $\chi$ can only depend spatially on $\boldsymbol{r}-\boldsymbol{r}^{\prime}$ (isotropy would imply $\mid \boldsymbol{r}-$ $\boldsymbol{r}^{\prime} \mid$ ) because the underlying unperturbed system has no dependence on spatial coordinate.

THEOREM. We introduce $\tau \equiv t-t^{\prime}$ and $\boldsymbol{s} \equiv \boldsymbol{r}-\boldsymbol{r}^{\prime}$, and express $\delta \rho$ in terms convolution integrals.

$$
\begin{equation*}
\delta \rho(\boldsymbol{r} ; t)=\int \mathrm{d}^{3} \boldsymbol{s} \int_{0}^{\infty} \mathrm{d} \tau \chi(\boldsymbol{s} ; \tau) \delta \phi(\boldsymbol{r}-\boldsymbol{s} ; t-\tau) . \tag{2.43}
\end{equation*}
$$



Figure 2. Fourier transform integration contour in the complex $\omega$ plane.
2.5.2. Solution of the dielectric function via Fourier transform in time

We introduce the Fourier transform in time.
Definition. The Fourier transform of $g(t)$ is

$$
\begin{equation*}
g(\omega)=\int_{-\infty}^{\infty} \mathrm{d} t g(t) \exp (\mathrm{i} \omega t) \tag{2.44}
\end{equation*}
$$

We need to impose initial conditions on the linear perturbations in the electric potential, velocity distribution function and an externally imposed free charge density $\left\{\delta \phi, \delta f, \delta \rho^{\text {ext }}\right.$ ) to calculate the Fourier transform: $g(t)=0$ for $t<0$ and $g(\omega)=\int_{0}^{\infty} \mathrm{d} t g(t) \exp (\mathrm{i} \omega t)$. The externally imposed free charge density is internal to the plasma domain. $g(t)$ must die out with time in order that $g(\omega)$ converges. However, in general $g(t)$ does not die out and may even grow. If $g(t)$ does not die, then $g(\omega)$ can be made to converge if $\omega$ is complex, i.e. $\omega=\omega^{\prime}+\mathrm{i} \omega^{\prime \prime}$ with $\omega^{\prime \prime}>0$. $g(\omega)$ will converge even if $g(t)$ is growing exponentially. For exponential growth $\omega^{\prime \prime} \geqslant 1 /($ growth time ). If $g(t)$ grows faster than exponentially, no convergence is possible. The integration contour for the Fourier transform is shown in figure 2.

We next calculate the Fourier transform of (2.43) and use the convolution theorem for Fourier transforms to obtain,

$$
\begin{equation*}
\delta \rho(\boldsymbol{r}, \omega)=\int \mathrm{d}^{3} \boldsymbol{s} \chi(\boldsymbol{s}, \omega) \delta \phi(\boldsymbol{r}-\boldsymbol{s}, \omega) \Rightarrow \delta \rho(\boldsymbol{k}, \omega)=\chi(\boldsymbol{k}, \omega) \delta \phi(\boldsymbol{k}, \omega), \tag{2.45}
\end{equation*}
$$

where we have also Fourier transformed in space: $g(k)=\int \mathrm{d}^{3} \boldsymbol{r} g(\boldsymbol{r}) \exp (-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r})$.

## ThEOREM. Inverse Fourier transforms

$$
\begin{equation*}
g(\boldsymbol{r})=\frac{1}{(2 \pi)^{3}} \int \mathrm{~d}^{3} \boldsymbol{k} \exp (\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}) g(\boldsymbol{k}) \quad g(t)=\frac{1}{(2 \pi)} \int \mathrm{d} \omega \exp (-\mathrm{i} \omega t) g(\omega) . \tag{2.46}
\end{equation*}
$$

The Fourier transformed Poisson equation is

$$
\begin{equation*}
-\nabla^{2} \delta \phi(\boldsymbol{r}, t)=4 \pi\left[\delta \rho(\boldsymbol{r}, t)+\delta \rho^{\mathrm{ext}}(\boldsymbol{r}, t)\right] \Rightarrow k^{2} \delta \phi(\boldsymbol{k}, \omega)=4 \pi\left[\delta \rho(\boldsymbol{k}, \omega)+\delta \rho^{\mathrm{ext}}(\boldsymbol{k}, \omega)\right] \tag{2.47}
\end{equation*}
$$

and we then use (2.45) to obtain an equation for $\delta \phi(\omega, \boldsymbol{k})$,

$$
\begin{equation*}
k^{2}\left[1-\frac{4 \pi}{k^{2}} \chi(\boldsymbol{k}, \omega)\right] \delta \phi(\boldsymbol{k}, \omega)=4 \pi \delta \rho^{\mathrm{ext}}(\boldsymbol{k}, \omega)=k^{2} \delta \phi^{\mathrm{ext}}(\boldsymbol{k}, \omega), \tag{2.48}
\end{equation*}
$$

where we introduce the relation $4 \pi \delta \rho^{\mathrm{ext}}(\boldsymbol{k}, \omega)=k^{2} \delta \phi^{\mathrm{ext}}(\boldsymbol{k}, \omega)$ to define $\delta \phi^{\mathrm{ext}}(\omega, \boldsymbol{k})$.
Recall the conventional formulation of Gauss' law in a dielectric medium with free (external) charges present,

$$
\begin{equation*}
\boldsymbol{\nabla} \cdot \boldsymbol{D}=4 \pi \rho^{\mathrm{ext}} \quad \boldsymbol{D}=\boldsymbol{E}+4 \pi \boldsymbol{P}=\varepsilon \boldsymbol{E} \quad \Rightarrow-\boldsymbol{\nabla} \cdot(\varepsilon \boldsymbol{\nabla} \phi)=4 \pi \rho^{\mathrm{ext}} . \tag{2.49}
\end{equation*}
$$

In a uniform plasma $\varepsilon$ is spatially uniform and (2.49) yields $-\varepsilon \nabla^{2} \phi=4 \pi \rho^{\text {ext }}$ which combined with (2.48) leads to the following result.

Theorem. Poisson's equation and plasma dielectric response

$$
\begin{equation*}
\varepsilon k^{2} \delta \phi(\boldsymbol{k}, \omega)=4 \pi \rho^{\mathrm{ext}}(\boldsymbol{k}, \omega) \rightarrow\left[1-\frac{4 \pi}{k^{2}} \chi(\boldsymbol{k}, \omega)\right] \equiv \varepsilon(\boldsymbol{k}, \omega) \rightarrow \delta \phi(\boldsymbol{k}, \omega)=\frac{\delta \phi^{\mathrm{ext}}(\boldsymbol{k}, \omega)}{\varepsilon(\boldsymbol{k}, \omega)} . \tag{2.50}
\end{equation*}
$$

COROLLARY.

$$
\begin{equation*}
\varepsilon(\boldsymbol{k}, \omega)=\frac{k^{2} \delta \phi^{\mathrm{ext}}}{k^{2} \delta \phi}=\frac{\delta \rho^{\mathrm{ext}}}{\delta \rho^{\mathrm{tot}}}=1-\frac{\delta \rho(\boldsymbol{k}, \omega)}{\delta \rho^{\mathrm{tot}}(\boldsymbol{k}, \omega)}, \quad \delta \rho^{\mathrm{tot}}=\delta \rho+\delta \rho^{\mathrm{ext}} \tag{2.51}
\end{equation*}
$$

Fourier transform the linearized Vlasov equation,

$$
\begin{align*}
\left(\frac{\partial}{\partial t}+\boldsymbol{v} \cdot \frac{\partial}{\partial \boldsymbol{r}}\right) \delta f(\boldsymbol{r}, \boldsymbol{v} ; t) & =\frac{e}{m}(\nabla \delta \phi) \cdot \frac{\partial f_{0}}{\partial \boldsymbol{v}} \rightarrow(-\mathrm{i} \omega+\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{v}) \delta f(\boldsymbol{k}, \omega ; \boldsymbol{v}) \\
& =\frac{e}{m} \delta \phi(\boldsymbol{k}, \omega) \mathrm{i} \boldsymbol{k} \cdot \frac{\partial f_{0}}{\partial \boldsymbol{v}} \\
\delta f(\boldsymbol{k}, \omega ; \boldsymbol{v}) & =\frac{\boldsymbol{k} \cdot \frac{\partial f_{0}}{\partial \boldsymbol{v}}}{(\boldsymbol{k} \cdot \boldsymbol{v}-\omega)} \frac{e}{m} \delta \phi(\boldsymbol{k}, \omega) . \tag{2.52}
\end{align*}
$$

THEOREM. Linear susceptibility

$$
\begin{equation*}
\chi(\boldsymbol{k}, \omega)=\frac{\delta \rho(\boldsymbol{k}, \omega)}{\delta \phi(\boldsymbol{k}, \omega)}=\sum_{s} \frac{e_{s}^{2}}{m_{s}} \int \mathrm{~d}^{3} \boldsymbol{v} \frac{\boldsymbol{k} \cdot \frac{\partial f_{0}^{s}(\boldsymbol{v})}{\partial \boldsymbol{v}}}{\boldsymbol{k} \cdot \boldsymbol{v}-\omega} \tag{2.53}
\end{equation*}
$$

DEFINITIONS. $n_{0}^{s}=\int \mathrm{d}^{3} \boldsymbol{v} f_{0}^{s}(\boldsymbol{v}), g^{s}(\boldsymbol{v}) \equiv f_{0}^{s}(\boldsymbol{v}) / n_{0}^{s}, \int \mathrm{~d}^{3} \boldsymbol{v} g^{s}(\boldsymbol{v})=1$.

Theorem. From (2.50)-(2.53) we obtain the linear dielectric function

$$
\begin{equation*}
\varepsilon(\boldsymbol{k}, \omega)=1-\frac{4 \pi}{k^{2}} \chi(\boldsymbol{k}, \omega)=1-\sum_{s} \frac{\omega_{s}^{2}}{k^{2}} \int \mathrm{~d}^{3} \boldsymbol{v} \frac{\boldsymbol{k} \cdot \frac{\partial g^{s}}{\partial \boldsymbol{v}}}{\boldsymbol{k} \cdot \boldsymbol{v}-\omega}, \quad \operatorname{Im} \omega>0 \tag{2.54}
\end{equation*}
$$

where $\omega_{s}^{2} \equiv\left(4 \pi n_{0}^{s} e_{s}^{2}\right) / m_{s}$.
From (2.50) one solves for $\delta \phi(\boldsymbol{k}, \omega)=\varepsilon^{-1}(\boldsymbol{k}, \omega) \delta \phi^{\text {ext }}(\boldsymbol{k}, \omega)$ from which we obtain the following using the convolution theorem:
$\delta \phi(\boldsymbol{k}, t)=\int_{-\infty}^{\infty} \mathrm{d} \tau \varepsilon^{-1}(\boldsymbol{k}, \tau) \delta \phi^{\mathrm{ext}}(\boldsymbol{k}, t-\tau)$ where $\varepsilon^{-1}(\boldsymbol{k}, \tau)=\int \mathrm{d} \omega \exp (-\mathrm{i} \omega \tau) \varepsilon^{-1}(\boldsymbol{k}, \omega)$.

### 2.5.3. Stable and unstable waves/disturbances

Suppose $\delta \phi^{\text {ext }}(\boldsymbol{k}, t)=a(\boldsymbol{k}) \delta(t)$ for a pulse-type forcing function without specifying $a(\boldsymbol{k})$ yet. Hence, $\delta \phi(\boldsymbol{k}, t)=a(\boldsymbol{k}) \varepsilon^{-1}(\boldsymbol{k}, t)$. Consider a specific representation for $a(\boldsymbol{k})$ so that the external forcing function is monochromatic: $a(\boldsymbol{k})=a \delta(\boldsymbol{k}-$ $\left.\boldsymbol{k}_{0}\right)(2 \pi)^{3}$ and $\delta \phi^{\mathrm{ext}}(\boldsymbol{r}, t)=a \mathrm{e}^{\mathrm{i} \boldsymbol{k}_{0} \cdot \boldsymbol{r}} \delta(t)$.

THEOREM. The pulse-response solution for the perturbed electric potential using (2.55) is then

$$
\begin{equation*}
\delta \phi(\boldsymbol{r}, t)=\frac{1}{(2 \pi)^{3}} \int \mathrm{~d}^{3} \boldsymbol{k} \mathrm{e}^{\mathrm{i} \cdot \boldsymbol{r}} a(\boldsymbol{k}) \varepsilon^{-1}(\boldsymbol{k}, t)=a \mathrm{e}^{\mathrm{i} \boldsymbol{k}_{0} \cdot \boldsymbol{r}} \varepsilon^{-1}\left(\boldsymbol{k}_{0}, t\right) \tag{2.56}
\end{equation*}
$$

The stability or instability of the pulse response is determined by $\varepsilon^{-1}(\boldsymbol{k}, t)$. The contour integration in (2.55) is illustrated in figure 3. We make use of analytic continuation and depress the integration contour: $\omega=\omega^{\prime}+\mathrm{i} b$ to remove the line integration and only leave the poles. In so doing, we hope that there are no vertical branch cuts. The integration of the deformed contour integration becomes

$$
\begin{equation*}
\varepsilon^{-1}(\boldsymbol{k}, t)=\int_{-\infty}^{\infty} \frac{\mathrm{d} \omega^{\prime}}{2 \pi} \frac{\exp \left(-\mathrm{i} \omega^{\prime} t-b t\right)}{\varepsilon\left(\boldsymbol{k}, \omega^{\prime}-\mathrm{i} b\right)}-\frac{2 \pi \mathrm{i}}{2 \pi} \sum_{\ell} \frac{\exp \left(-\mathrm{i} \omega_{\ell}(\boldsymbol{k}) t\right)}{\left.\frac{\partial \varepsilon(\boldsymbol{k}, \omega)}{\partial \omega}\right|_{\omega_{\ell}}} \tag{2.57}
\end{equation*}
$$

Consider a perturbative solution of the zeros of the linear dielectric function, $\varepsilon(\boldsymbol{k}, \omega) \approx \varepsilon\left(\boldsymbol{k}, \omega_{\ell}\right)+\left(\omega-\omega_{\ell}\right) \partial \varepsilon /\left.\partial \omega\right|_{\omega_{\ell}}$ where $\varepsilon\left(\boldsymbol{k}, \omega_{\ell}\right)=0$ defines the pole at $\omega_{\ell}$. Define the complex frequency at the pole as $\omega_{\ell}=\Omega_{\ell}+\mathrm{i} \gamma_{\ell}$ so that $\exp \left(-\mathrm{i} \omega_{\ell}(\boldsymbol{k}) t\right)=\exp \left(-\mathrm{i} \Omega_{\ell}(\boldsymbol{k}) t+\gamma_{\ell} t\right)$.

THEOREM. A pole in the upper half-plane corresponds to instability $\gamma_{\ell}>0$, and $a$ pole in the lower half-plane is a stable root $\gamma_{\ell}<0$.

For $b>\gamma$ the first term on the right-hand side of (2.57) damps out after a suitable length of time, which leads to

$$
\begin{equation*}
\varepsilon^{-1}(\boldsymbol{k}, t) \Rightarrow-\mathrm{i} \sum_{\ell} \frac{\exp \left(-\mathrm{i} \omega_{\ell}(\boldsymbol{k}) t\right)}{\left.\frac{\partial \varepsilon(\boldsymbol{k}, \omega)}{\partial \omega}\right|_{\omega_{\ell}}} \tag{2.58}
\end{equation*}
$$



Figure 3. Contour integration for pulse response showing the depressed contour and poles of $\varepsilon^{-1}$ in the region of analytic continuation.

DEFINITION. $g(\boldsymbol{v}) \equiv \sum_{s} \omega_{s}^{2} g^{s}(\boldsymbol{v}) / \sum_{s} \omega_{s}^{2}$ and $\omega_{p}^{2} \equiv \sum_{s} \omega_{s}^{2}$.
The linear dielectric function becomes

$$
\begin{equation*}
\varepsilon(\boldsymbol{k}, \omega)=1-\frac{\omega_{p}^{2}}{k^{2}} \int \mathrm{~d}^{3} \boldsymbol{v} \frac{\boldsymbol{k} \cdot \frac{\partial g}{\partial \boldsymbol{v}}}{\boldsymbol{k} \cdot \boldsymbol{v}-\omega}=1-\frac{\omega_{p}^{2}}{k^{2}} \int \mathrm{~d}^{3} \boldsymbol{v} \frac{\hat{\boldsymbol{k}} \cdot \frac{\partial g}{\partial \boldsymbol{v}}}{\hat{\boldsymbol{k}} \cdot \boldsymbol{v}-\omega / k} \tag{2.59}
\end{equation*}
$$

We note the integral on the right-hand side of (2.59) can be simplified using the definition $u \equiv \hat{\boldsymbol{k}} \cdot \boldsymbol{v}$ so that

$$
\hat{\boldsymbol{k}} \cdot \frac{\partial g}{\partial \boldsymbol{v}}=\frac{\partial g\left(u, \boldsymbol{v}_{2}, \boldsymbol{v}_{3}\right)}{\partial u} .
$$

This allows the velocity-space integral over two of the three dimensions in (2.59) to be done immediately,
$g(u)=\int \mathrm{d} v_{2} \mathrm{~d} v_{3} g\left(u, v_{2}, v_{3}\right) \quad$ where $g(u) \equiv \int \mathrm{d}^{3} \boldsymbol{v} g(\boldsymbol{v}) \delta(\boldsymbol{k} \cdot \boldsymbol{v}-\omega)$ and $\int_{-\infty}^{\infty} \mathrm{d} u g(u)=1$.
Equation (2.54) then becomes

$$
\begin{equation*}
\varepsilon(\boldsymbol{k}, \omega)=1-\frac{\omega_{p}^{2}}{k^{2}} \int_{-\infty}^{\infty} \mathrm{d} u \frac{g^{\prime}(u)}{u-v_{p}}, \quad v_{p}=\frac{\omega}{k}, \tag{2.60}
\end{equation*}
$$

where $v_{p}=\omega / k$ is the phase velocity; and in the following few expressions we drop the ' $p$ ' subscript.

THEOREM. The eigenvalues of the linearized Vlasov-Poisson system are determined by the roots of the linear dielectric function $\varepsilon\left(\boldsymbol{k}, \omega_{\ell}\right)=0 \rightarrow \omega_{\ell}(\boldsymbol{k})$, which are the eigenfrequencies. This follows from $\varepsilon(\boldsymbol{k}, \omega) \phi(\boldsymbol{k}, \omega)=\phi^{\text {ext }}(\boldsymbol{k}, \omega)=0$ and corresponds to free, undriven oscillations.

Definition. The Hilbert transform of $g$ is

$$
\begin{equation*}
\int_{-\infty}^{\infty} \mathrm{d} u \frac{g_{\hat{\boldsymbol{k}}}(u)}{u-v} \equiv \text { Hilbert transform of } g \equiv Z_{\hat{\boldsymbol{k}}}(v) \quad(\operatorname{Im} v>0, k \equiv|\boldsymbol{k}|>0) \tag{2.61}
\end{equation*}
$$

One can differentiate the Hilbert transform with respect to $v$ to obtain,

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} v} Z_{\hat{k}}=\int_{-\infty}^{\infty} \mathrm{d} u g_{\hat{k}}(u) \frac{\partial}{\partial v} \frac{1}{u-v} \equiv \int_{-\infty}^{\infty} \mathrm{d} u \frac{g_{\hat{k}}^{\prime}(u)}{u-v}, \quad g_{\hat{k}}^{\prime} \equiv \frac{\mathrm{d}}{\mathrm{~d} u} g_{\hat{k}}(u) \tag{2.62}
\end{equation*}
$$

using $(\partial / \partial v)(u-v)^{-1}=-(\partial / \partial u)(u-v)^{-1}$ and integrating by parts. Equation (2.60) then yields the following.

THEOREM. The dielectric function is

$$
\begin{equation*}
\varepsilon(\boldsymbol{k}, \omega)=1-\frac{\omega_{p}^{2}}{k^{2}} Z_{\hat{\boldsymbol{k}}}^{\prime}(v) . \tag{2.63}
\end{equation*}
$$

### 2.5.4. Examples of linear dielectrics for a few simple velocity distributions

Table 1 presents examples of five model velocity distributions and the corresponding dielectric responses. We note that the Cauchy velocity distribution does not exist in nature because its energy moment diverges.
2.5.5. Inverse Fourier transform to obtain spatial and temporal response - Green's function for pulse response and cold-plasma example
From (2.55) we have an integral relation for $\delta \phi(\boldsymbol{k}, t)$, i.e.

$$
\delta \phi(\boldsymbol{k}, t)=\int_{-\infty}^{\infty} \mathrm{d} \tau \varepsilon^{-1}(\boldsymbol{k}, \tau) \delta \phi^{\mathrm{ext}}(\boldsymbol{k}, t-\tau)
$$

In configuration space, equation (2.55) becomes

$$
\begin{align*}
\delta \phi(\boldsymbol{r}, t)= & \int \mathrm{d}^{3} s \int_{-\infty}^{\infty} \mathrm{d} \tau \varepsilon^{-1}(\boldsymbol{s}, \tau) \delta \phi^{\mathrm{ext}}(\boldsymbol{r}-\boldsymbol{s}, t-\tau), \\
& \text { where } \varepsilon^{-1}(\boldsymbol{s}, \tau)=\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d} \omega}{2 \pi} \varepsilon^{-1}(\boldsymbol{k}, \omega) \exp (\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{s}-\mathrm{i} \omega \tau) . \tag{2.64}
\end{align*}
$$

EXERCISE. Prove $\varepsilon^{-1}(\boldsymbol{k}, \tau)=0$ for $\tau<0$. See $\S$ 2.5.3.

EXERCISE. Simplify $\varepsilon(k, \omega)$ for hot electrons and cold ions in the limit that $\omega / k=$ $V_{p} \ll v_{\mathrm{th}}$ where $v_{\mathrm{th}}^{2}=T_{e} / m_{e}$ is the square of the electron thermal speed, $T_{e}$ is the electron temperature and $m_{e}$ is the electron mass. Introduce the definition of the Debye length $\lambda_{e} \equiv v_{\text {th }} / \omega_{e}$. Derive the dispersion relation for the ion-acoustic wave,

$$
\begin{equation*}
\omega^{2}=\frac{\omega_{i}^{2}}{1+\frac{1}{k^{2} \lambda_{e}^{2}}}=\frac{k^{2} c_{s}^{2}}{1+k^{2} \lambda_{e}^{2}}, \quad c_{s}^{2} \equiv \frac{m_{e}}{m_{i}} v_{e}^{2}=\frac{k_{B} T_{e}}{m_{i}} \tag{2.65}
\end{equation*}
$$

| Distribution $\rightarrow$ <br> Dielectric Attributes $\downarrow$ | COLD | COLD BEAM | SQUARE | CAUCHY | 2 SPECIES hot e \& cold i |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $g(\mathrm{u})$ | $\delta(\mathrm{u})$ |  |  | $\frac{c}{\pi} \frac{1}{u^{2}+c^{2}}$ | hot electrons $+$ cold ions |
| Z(v) | $-\frac{1}{\mathrm{~V}}$ | $-\frac{1}{v-u_{0}}$ | $\frac{1}{2 \mathrm{c}} \ln \left(\frac{c-\mathrm{v}}{-c-\mathrm{v}}\right)$ | $-\frac{1}{v+i c}$ | hot electrons $+$ cold ions |
| $\mathrm{Z}^{\prime}(\mathrm{V})$ | $\frac{1}{v^{2}}$ | $\frac{1}{\left(v-u_{0}\right)^{2}}$ | $\frac{1}{v^{2}-c^{2}}$ | $\frac{1}{(v+i c)^{2}}$ | hot electrons $+$ cold ions |
| $\varepsilon(\mathbf{k}, \omega)$ | $1-\frac{\omega_{p}^{2}}{\omega^{2}}$ | $1-\frac{\omega_{p}^{2}}{\left(\omega-k u_{0}\right)^{2}}$ | $1-\frac{\omega_{p}^{2}}{\omega^{2}-k^{2} c^{2}}$ | $1-\frac{\omega_{p}^{2}}{(\omega+\mathrm{i} k c)^{2}}$ | $1-\frac{\omega_{e}^{2}}{\omega^{2}-k^{2} c^{2}}-\frac{\omega_{i}^{2}}{\omega^{2}}$ |
| $\omega_{\ell}$ | $\omega_{\ell}= \pm \omega_{p}$ | $\omega_{\ell}= \pm \omega_{p}+k u_{0}$ | $\omega_{\ell}= \pm \sqrt{\omega_{p}^{2}+k^{2} c^{2}}$ | $\omega_{\ell}= \pm \omega_{p}-\mathrm{i} k c$ | $\begin{aligned} & \omega_{1}= \pm \sqrt{a_{1}^{2}, \omega_{p}^{2}}=\sum_{s} \omega_{s}^{2} \\ & \omega_{1}^{2}=-k^{2}\left[c^{2} c^{2}+\omega_{p}^{2} \pm \sqrt{\left(k^{2} c^{2}+\omega_{p}^{2}\right)^{2}-4 \omega_{i}^{2} k^{2} c^{2}}\right] \end{aligned}$ |
| $\mathrm{v}_{g}=\frac{\mathrm{d}}{\mathrm{~d} k} \operatorname{Re} \omega_{\ell}$ | 0 | $u_{0}$ | $c^{2} k / \omega$ | 0 | $c^{2} k / \omega$ |

Table 1. Examples of velocity distributions and resulting dielectric responses.
where $c_{s}$ is the ion sound speed for cold ions. The ions provide the inertia while the electrons provide pressure, and the electric field binds the motion of the two species.

We return to (2.64) to calculate the Green's function for the pulse response of the electric potential in a cold plasma with dielectric function $\varepsilon(\boldsymbol{k}, \omega)=1-\omega_{p}^{2} / \omega^{2}$. If there is no $\boldsymbol{k}$ dependence in $\varepsilon(\boldsymbol{k}, \omega)$ then

$$
\begin{align*}
\varepsilon^{-1}(\boldsymbol{s}, \tau) & =\delta(\boldsymbol{s}) \int \frac{\mathrm{d} \omega}{2 \pi} \exp (-\mathrm{i} \omega \tau)\left(1+\frac{\omega_{p}^{2}}{\left(\omega-\omega_{p}\right)\left(\omega+\omega_{p}\right)}\right) \\
& =\delta(\boldsymbol{s})\left[\delta(\tau)+\omega_{p}^{2} \times\left\{0 \tau<0,-\frac{1}{\omega_{p}} \sin \omega_{p} \tau \tau>0\right\}\right] \tag{2.66}
\end{align*}
$$

The integral over $\omega$ has poles at $\pm \omega_{p}$. The term involving $\delta(\tau)$ is the vacuum response, and the rest is associated with the plasma shielded response.

THEOREM. Using (2.66), (2.64) becomes

$$
\begin{equation*}
\delta \phi(\boldsymbol{r}, t)=\delta \phi^{\mathrm{ext}}(\boldsymbol{r}, t)-\int_{0}^{\infty} \mathrm{d} \tau \omega_{p} \sin \left(\omega_{p} \tau\right) \delta \phi^{\mathrm{ext}}(\boldsymbol{r}, t-\tau) \tag{2.67}
\end{equation*}
$$



Figure 4. Impulse response $\delta \phi(t)$ for $\delta \phi^{\varepsilon e x t}=\delta(\boldsymbol{r}) \delta(t)$.

The excitation in $\delta \phi(\boldsymbol{r}, t)$ depends on all the other excitations and the external potential at $\boldsymbol{r}$ from earlier times. This is partly due to the absence of damping in the cold plasma.

EXAMPLE. The impulse response for $\delta \phi^{\varepsilon \mathrm{ext}}=\delta(\boldsymbol{r}) \delta(t)$ is $\delta \phi(\boldsymbol{r}, t)=-\omega_{p} \delta(\boldsymbol{r}) \sin \left(\omega_{p} t\right)$ for $t>0$. For this response $\omega(\boldsymbol{k})=\omega_{p}$ and $\mathrm{d} \omega / \mathrm{d} \boldsymbol{k}=0$. The plasma response to the $\delta \phi^{\varepsilon \mathrm{ext}}$ impulse is negative over the first half-cycle of the plasma oscillation as the plasma tries to neutralize $\delta \phi^{\varepsilon e x t}$ (figure 4).

Example. $\delta \phi(\boldsymbol{r}, t)$ due to a moving test particle. Consider the external potential for a moving charge: $\delta \phi^{\text {ext }}(\boldsymbol{r}, t)=e_{0} /\left(\boldsymbol{r}-\boldsymbol{r}_{0}(t)\right)$ with $\boldsymbol{r}_{0}(t)=\boldsymbol{v}_{0} t$ and charge $e_{0}>0$. From Poisson's equation one obtains the total charge density,

$$
\begin{align*}
\delta \rho(\boldsymbol{r}, t) & =-\left(\frac{1}{4 \pi}\right) \nabla^{2} \delta \phi(\boldsymbol{r}, t) \\
& =-\left(\frac{1}{4 \pi}\right) \nabla^{2}\left[-\omega_{p} \int_{0}^{\infty} \mathrm{d} \tau \sin \left(\omega_{p} \tau\right) \frac{e_{0}}{\boldsymbol{r}-\boldsymbol{r}_{0}(t-\tau)}+\delta \phi^{\mathrm{ext}}(\boldsymbol{r}, t)\right] \\
& =\delta(x) \delta(y)\left(-\frac{e_{0} \omega_{p}}{v_{0}}\right) \sin \left(-\frac{\omega_{p} z}{v_{0}}\right)+e_{0} \delta(x) \delta(y) \delta\left(z-v_{0} t\right) \tag{2.68}
\end{align*}
$$

A schematic of the one-dimensional charge density and the local charge under the curve in the wake of the moving test particle is presented in figure 5. The total charge exclusive of the test particle is $-e_{0}$ as can be shown from the integral of $\delta \rho$.

$$
\begin{equation*}
\lim _{\lambda \rightarrow 0} \int_{-\infty}^{0} \mathrm{~d} z^{\prime}\left(-\frac{e_{0} \omega_{p}}{v_{0}}\right) \sin \left(\frac{\omega_{p} z^{\prime}}{v_{0}}\right) \exp \left(-\lambda z^{\prime}\right)=-e_{0} \tag{2.69}
\end{equation*}
$$

Thus, the total charge is zero. We can also calculate the dipole moment $\boldsymbol{P}$ of the plasma response similarly by weighting the integrand in (2.69) with $z$ to show that $\boldsymbol{P}=0$.


Figure 5. One-dimensional charge density in the wake of a moving test particle with charge $e_{0}$.

Example. For the more general case where $\varepsilon(\boldsymbol{k}, \omega)$ has $\boldsymbol{k}$ dependence, we use Cauchy's theorem and (2.57), (2.58) and (2.64) to obtain

$$
\begin{equation*}
\varepsilon^{-1}(\boldsymbol{s}, \tau)=-\mathrm{i} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \sum_{\ell} \frac{\exp \left(\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{s}-\mathrm{i} \omega_{\ell}(\boldsymbol{k}) \tau\right)}{\left.\frac{\partial \varepsilon(\boldsymbol{k}, \omega)}{\partial \omega}\right|_{\omega_{\ell}(\boldsymbol{k})}} \tag{2.70}
\end{equation*}
$$

where the summation in (2.70) is over the poles in the complex $\omega$ plane. However, for warm plasmas it is difficult to obtain explicit formulae because we cannot do the integrals in most cases of physical interest.

### 2.6. Streaming instabilities

Consider an infinite uniform plasma with two or more beams:

$$
f_{s}^{0}(\boldsymbol{v})=n_{s} \delta\left(\boldsymbol{v}-\boldsymbol{u}_{s}\right) \quad \text { and } \quad \varepsilon(\boldsymbol{k}, \omega)=1-\sum_{s} \frac{\omega_{s}^{2}}{\left(\omega-\boldsymbol{k} \cdot \boldsymbol{u}_{s}\right)^{2}}, \quad \text { with } \omega_{s}^{2} \equiv \frac{4 \pi n_{s} e_{s}^{2}}{m_{s}}
$$

Restrict this linear analysis to one spatial dimension: $k \hat{\boldsymbol{k}} \cdot \boldsymbol{u}_{s}=k u_{s}$. Then the linear dielectric can be rewritten as

$$
\begin{equation*}
\varepsilon(k, \omega)=1-\sum_{s} \frac{\omega_{s}^{2}}{\left(\omega-k u_{s}\right)^{2}}=1-\frac{1}{k^{2}} \sum_{s} \frac{\omega_{s}^{2}}{\left(V-u_{s}\right)^{2}}, \quad V \equiv \omega / k \tag{2.71}
\end{equation*}
$$

The solution of $\varepsilon(k, \omega)=0$ for the normal modes $\omega_{k}$ is then determined by solving the following order $2 N$ polynomial equation for $V=\omega / k$ :

$$
\begin{equation*}
k^{2}=F(V)=\sum_{s=1}^{N} \frac{\omega_{s}^{2}}{\left(V-u_{s}\right)^{2}} \tag{2.72}
\end{equation*}
$$

EXAMPLE. Consider the graphical solution of (2.72) for $N=3$.
There are resonances at $V=u_{i}, i=1,2$ and 3 and three branches of the dispersion relation with $\operatorname{Re} \omega \sim k u_{i} \pm \omega_{s}$. For very large values of $k^{2}$, e.g. $k_{1}^{2}$, there are $2 N=6$ intersections of $k^{2}$ with $F(V)$, i.e. 6 stable roots. If for smaller values of $k^{2}$, e.g. $k_{2}^{2}$, the $k_{2}^{2}$ horizontal line falls below the locus of $F(V)$, such that there are fewer than $2 N$ intersections; and then there are one or more pairs of complex-conjugate roots. The complex root(s) with $\operatorname{Im} \omega>0$ is the unstable root, and the conjugate root with $\operatorname{Im} \omega<0$ is a damped normal mode. In a finite plasma, boundary conditions must be defined; and there is a lower limit on $k$ corresponding to $2 \pi / L$, where $L$ is the length of the plasma.


Figure 6. Schematic of solution of (2.72) $k^{2}=F(V)$ for $N=3$.


Figure 7. (a) Schematic of the solution of $k^{2}=F(V)$ for $N=2$ and $\omega_{2}=\omega_{b} \ll \omega_{1}=\omega_{p}$, weak-beam instability. (b) Schematic showing the crossing of the plasma frequency and beam branches.

### 2.6.1. Examples - two-stream and weak-beam instabilities

Example. $N=2$, two-stream instability. Suppose $\omega_{1}=\omega_{2}$ and select a reference frame with $u_{1}=-u_{2}$. The infinite-medium normal modes are determined by the solutions of the dispersion relation,

$$
\begin{align*}
\varepsilon\left(k, \omega_{\ell}\right) & =1-\frac{\omega_{1}^{2}}{\left(\omega-k u_{1}\right)^{2}}-\frac{\omega_{1}^{2}}{\left(\omega+k u_{1}\right)^{2}}=0 \\
& \rightarrow \frac{\omega_{\ell}^{2}}{\omega_{p}^{2}}=\frac{1}{2}\left[1+2 \frac{k^{2} u_{1}^{2}}{\omega_{p}^{2}} \pm \sqrt{1+\frac{8 k^{2} u_{1}^{2}}{\omega_{p}^{2}}} \quad \text { with } \omega_{p}^{2}=\omega_{1}^{2}+\omega_{2}^{2}=2 \omega_{1}^{2} .\right. \tag{2.73}
\end{align*}
$$

EXERCISE. Sketch $\omega^{2}$ versus $k^{2}$, Re $\omega$ versus $k$ and $\operatorname{Im} \omega$ versus $k$. Show that for $k<k_{c}$ there is instability; what is $k_{c}$ ? Show that $\max (\operatorname{Im} \omega)=\omega_{p} / \sqrt{ } 8$ for $k_{\max }=(3 / 8)^{1 / 2} \omega_{p} / u_{1}$. Evaluate $\varepsilon^{-1}(x, t)$ approximately and sketch. Show that $\varepsilon^{-1}(x, t)=0$ for $|x / t|>u_{1}$ using analyticity.

Example. $N=2$, weak-beam instability. Assume $\omega_{b} \ll \omega_{1}=\omega_{p}$ where the 'first' component is the 'plasma.' Select the frame in which the plasma component is at rest. The weak-beam instability is diagrammed in figure 7. The dispersion relation for the
normal modes is given by the solution of

$$
\begin{equation*}
\varepsilon(k, \omega)=1-\frac{\omega_{p}^{2}}{\omega^{2}}-\frac{\omega_{b}^{2}}{\left(\omega-k u_{b}\right)^{2}}=\varepsilon_{p}(k, \omega)-\frac{\omega_{b}^{2}}{\left(\omega-k u_{b}\right)^{2}}=0 \tag{2.74}
\end{equation*}
$$

where the beam and plasma wave branches cross, one of the real roots can disappear, giving rise to a pair of complex-conjugate roots and instability. If the plasma is warm, the plasma branches acquire curvature. In general, one uses the warm-plasma dielectric for $\varepsilon_{p}$. For $\omega_{b}^{2} / \omega_{p}^{2} \ll 1$ we solve (2.74) perturbatively,

$$
\begin{align*}
0= & \varepsilon_{p}(k, \omega)-\frac{\omega_{b}^{2}}{\left(\omega-k u_{b}\right)^{2}} \\
= & \varepsilon_{p}\left(k, \omega_{0}\right)+\left.\delta \omega \frac{\partial \varepsilon_{p}}{\partial \omega}\right|_{\omega_{0}, k_{0}}+\left.\delta k \frac{\partial \varepsilon_{p}}{\partial k}\right|_{\omega_{0}, k_{0}}+\left.\frac{1}{2} \delta \omega^{2} \frac{\partial^{2} \varepsilon_{p}}{\partial \omega^{2}}\right|_{\omega_{0}, k_{0}} \\
& +\cdots-\frac{\omega_{b}^{2}}{\left(\omega_{0}+\delta \omega-k_{0} u_{b}-\delta k u_{b}\right)^{2}} \\
& \varepsilon_{p}\left(k, \omega_{0}\right)=0, \quad \omega=\omega_{0}+\delta \omega, \quad k=k_{0}+\delta k \tag{2.75}
\end{align*}
$$

At resonance $\omega_{0}-k_{0} u_{b}=0$, and (2.75) becomes

$$
\begin{align*}
& (\delta \omega-u \delta k)^{2}\left(\delta \omega \varepsilon_{\omega}+\delta k \varepsilon_{k}+O\left(\delta^{2}\right)\right)=\omega_{b}^{2}, \quad \varepsilon_{\omega} \equiv \partial \varepsilon /\left.\partial \omega\right|_{\omega_{0}, k_{0}} \\
& \quad(\delta \omega-u \delta k)^{2}\left(\delta \omega \varepsilon_{\omega}+\delta k \varepsilon_{k}+O\left(\delta^{2}\right)\right)=\omega_{b}^{2}, \quad \varepsilon_{\omega} \equiv \partial \varepsilon_{p} /\left.\partial \omega\right|_{\omega_{0}, k_{0}} \tag{2.76}
\end{align*}
$$

(i) For $\delta k=0: \delta \omega^{3}+O\left(\delta \omega^{4}\right)=\varepsilon_{\omega}^{-1} \omega_{b}^{2}$. For small $\delta \omega$,

$$
\begin{align*}
& \left(\frac{\delta \omega}{\omega_{0}}\right)^{3}=\frac{\omega_{b}^{2}}{\omega_{0}^{2}} \frac{1}{\omega_{0} \varepsilon_{\omega}} \equiv \eta \approx \frac{1}{2} \frac{\omega_{b}^{2}}{\omega_{0}^{2}} \ll 1 \\
\rightarrow & \frac{\delta \omega}{\omega_{0}}=\eta^{1 / 3}=\left|\eta^{1 / 3}\right|\left\{1,-\frac{1}{2} \pm \mathrm{i} \sqrt{\frac{3}{2}}\right\} . \tag{2.77}
\end{align*}
$$

We note for a cold plasma, $\varepsilon_{p}=1-\omega_{p}^{2} / \omega^{2}$ and $\varepsilon_{\omega}=2 / \omega_{p}$. There are three solutions for the frequency shift $\delta \omega$ in (2.77): the coupling of the plasma wave to the weak beam produces a small frequency shift, a damped mode and a weak instability.
(ii) For $\delta k \neq 0$, equation (2.76) is solved in the beam frame $\omega^{\prime} \equiv \omega-k u_{b}=\delta \omega-\delta k u_{b}$. If the plasma is cold, then $\omega^{\prime}$ is given by

$$
\begin{align*}
\omega^{\prime} & =\omega_{p}\left[\left|\eta^{1 / 3}\right| \exp \left(\mathrm{i} \frac{2 \pi}{3}\right)-\frac{1}{3} \frac{\delta k}{k_{0}}+\frac{1}{9}\left(\frac{\delta k}{k_{0}}\right)^{2}\left|\eta^{1 / 3}\right| \exp \left(-\mathrm{i} \frac{2 \pi}{3}\right)+O\left(\delta k^{3}\right)\right] \\
\operatorname{Re} \omega^{\prime} & =\omega_{p}\left[-\frac{1}{2}\left|\eta^{1 / 3}\right|-\frac{1}{3} \frac{\delta k}{k_{0}}-\frac{1}{18}\left(\frac{\delta k}{k_{0}}\right)^{2}\left|\eta^{1 / 3}\right|+\cdots\right] \\
\operatorname{Im} \omega^{\prime} & =\omega_{p}\left[\frac{\sqrt{3}}{2}\left|\eta^{1 / 3}\right|+\frac{1}{9}\left(-\frac{\sqrt{3}}{2}\right)\left(\frac{\delta k}{k_{0}}\right)^{2}\left|\eta^{1 / 3}\right|+\cdots\right] . \tag{2.78}
\end{align*}
$$

In the beam frame there is a small negative shift of the phase velocity given by $\operatorname{Re} \omega^{\prime} / k_{0}=-(1 / 2)|\eta|^{1 / 3} u_{b}$. There is also a shift in the group velocity of the plasma
wave due to the coupling with the beam, which is given by $\mathrm{d} \operatorname{Re} \omega^{\prime} / \mathrm{d} k=\mathrm{d} \operatorname{Re} \omega^{\prime} / \mathrm{d} \delta k=$ $-(1 / 3) u_{b}$, which is also negative but is not small. We note that the dispersion in the real frequency of the instability is given by $\mathrm{d}^{2} \operatorname{Re} \omega^{\prime} / \mathrm{d} \delta k^{2}=-(1 / 9)|\eta|^{1 / 3}\left(\omega_{p} / k_{0}^{2}\right)$, which is small in $|\eta|^{1 / 3}$. From the solution for $\operatorname{Im} \omega^{\prime}$ we see that the growth rate is peaked at a value of $(\sqrt{ } 3 / 2) \eta^{1 / 3} \omega_{p}$ for $\delta k=0$; and

$$
\gamma_{k k} \equiv\left|\frac{\mathrm{~d}^{2} \gamma}{\mathrm{~d} k^{2}}\right|=\frac{\gamma_{0}}{k_{0}^{2}} \frac{2}{9}\left|\eta^{-2 / 3}\right|, \quad \gamma_{0}=\frac{\sqrt{3}}{2} \omega_{p}\left|\eta^{1 / 3}\right| .
$$

From the square root of the ratio of the peak growth rate to $-\mathrm{d}^{2} \operatorname{Im} \omega^{\prime} / \mathrm{d} \delta k^{2}$ at $k_{0}$ we can estimate the half-width in $\delta k_{1 / 2}$ of the peak in the growth rate, which has a scaling $\delta k_{1 / 2} / k_{0} \sim\left|\eta^{1 / 3}\right| \ll 1$. Thus, a very small range in $k$-space is involved in the weak-beam instability; and a long wave packet can be formed that remains coherent over a long distance.

All of the results so far in $\S 2.6$ were derived for a cold plasma. For a 'hot' plasma only numerical coefficients will change for the examples considered. The generalization of the results will involve formulae like the following:

$$
\begin{equation*}
\operatorname{Re} \omega^{\prime}=k_{0} V_{p}^{\prime}+\delta k V_{g}^{\prime}+\frac{1}{2} \delta k^{2} \frac{\mathrm{~d}^{2}}{\mathrm{~d} \delta k^{2}} \omega^{\prime} \quad \gamma \equiv \operatorname{Im} \omega^{\prime}=\gamma_{0}+\frac{1}{2} \delta k^{2} \frac{\mathrm{~d}^{2}}{\mathrm{~d} \delta k^{2}} \gamma \tag{2.79}
\end{equation*}
$$

where $V_{p}^{\prime}=\omega^{\prime}\left(k_{0}\right) / k_{0}, V_{g}^{\prime}=\mathrm{d} \omega^{\prime} / \mathrm{d} k$ at $k_{0}$ and $\gamma_{0}$ is the peak growth rate occurring at $k_{0}$. Finite-temperature effects naturally lead to dispersion, i.e. the phase velocity $V_{p}$ is a function of wavenumber $k$. Thus, in a hot plasma we expect that the $x-t$ response of a growing disturbance will exhibit a growing and spreading wave packet travelling at the group velocity $V_{g}$. The $x-t$ response depends on the content of (2.79) and makes explicit how fast the growing wave packet spreads compared to its advection. The next sub-section elaborates the $x-t$ response of an unstable disturbance.

### 2.6.2. Definition of convective and absolute instability

How fast a growing wave packet spreads compared to how fast it advects past a fixed observation point is an important distinction.
Definition. Absolute versus convective instability. If an unstable wave packet advects faster than it spreads, an observer at a fixed observation point will see a growing signal as the front of the wave packet passes followed by peaking and then decay of the signal. As the packet advects the peak signal continues to grow exponentially in time. The foregoing corresponds to a convective instability. An absolute instability corresponds to when the spreading of the growing response exceeds the advection at the group velocity $V_{g}$ so that the signal at a fixed observation point continues to grow without cessation (until the linear assumption fails and nonlinear effects may come into the problem).

Exercise. Sketch a growing and advecting pulse at two distinct times in one spatial dimension for a convective instability, and make the corresponding sketch for an absolute instability.

The dielectric pulse response in one spatial dimension for an unstable root of the dispersion relation follows from (2.70). To obtain the results in (2.80) we make use of the Taylor-series expansion of the dispersion relation as given in (2.79) for small $\delta k$. Because we perform the integral with respect to $\delta k$ by the method of steepest descents and take advantage of the rapid convergence of that integral with respect to large $\delta k$ due to the term $\exp \left(-\frac{1}{2} \delta k^{2}\left|\gamma_{k k}\right| t\right)$, there is no conflict between the limits of
the $\delta k$ integration being $(-\infty, \infty)$ and Taylor-series expansion in small $\delta k$. The pulse response is then

$$
\begin{align*}
\varepsilon^{-1}(x, t)= & \int_{-\infty}^{\infty} \frac{\mathrm{d} k}{2 \pi} \int_{-\infty}^{\infty} \frac{\mathrm{d} \omega}{2 \pi} \frac{\exp (\mathrm{i} k x-\mathrm{i} \omega t)}{\varepsilon}+\mathrm{c} . \mathrm{c} .=-\mathrm{i} \int_{-\infty}^{\infty} \frac{\mathrm{d} k}{2 \pi} \frac{\exp (\mathrm{i} k x-\mathrm{i} \omega t)}{\left.\frac{\partial \varepsilon}{\partial \omega}\right|_{\omega_{k}(k)}}+\mathrm{c} . \mathrm{c} . \\
\approx & -\mathrm{i} \frac{1}{\left.\frac{\partial \varepsilon}{\partial \omega}\right|_{\omega_{k}\left(k_{0}\right)}} \int_{-\infty}^{\infty} \frac{\mathrm{d}(\delta k)}{2 \pi} \\
& \times \exp \left[\mathrm{i} k_{0} x+\mathrm{i} \delta k x-\mathrm{i}\left(k_{0} V_{p}+\delta k V_{g}+\frac{1}{2} \omega_{k k} \delta k^{2}\right) t+\left(\gamma_{0}-\frac{1}{2}\left|\gamma_{k k}\right| \delta k^{2}\right) t\right]+\mathrm{c.c.} \\
\approx & -\mathrm{i} \frac{\exp \left(\mathrm{i} k_{0}\left(x-V_{p} t\right)\right) \exp \gamma_{0} t}{\left.\varepsilon_{\omega}\right|_{\omega_{k}\left(k_{0}\right)} ^{\infty}} \int_{-\infty}^{\infty} \frac{\mathrm{d}(\delta k)}{2 \pi} \\
& \times \exp \left[\mathrm{i} \delta k\left(x-V_{g} t\right)\right] \exp \left[-\frac{1}{2} \delta k^{2}\left(\left|\gamma_{k k}\right|+\mathrm{i} \omega_{k k}\right) t\right]+\mathrm{c.c.} \\
\approx & -\mathrm{i} \frac{\exp \left(\mathrm{i} k_{0}\left(x-V_{p} t\right)\right) \exp \gamma_{0} t}{\left.\varepsilon_{\omega}\right|_{\omega_{k}\left(k_{0}\right)}} \frac{1}{\sqrt{2 \pi}} \frac{1}{\sqrt{\left(\left|\gamma_{k k}\right|+\mathrm{i} \omega_{k k}\right) t}} \\
& \times \exp \left[\frac{\left.-\frac{1}{2}\left(x-V_{g} t\right)^{2}\right]}{\left(\left|\gamma_{k k}\right|+\mathrm{i} \omega_{k k}\right) t}\right]+\mathrm{c.c.} \\
\approx & -\mathrm{i} \frac{\exp \left(\mathrm{i} k_{0}\left(x-V_{p} t\right)\right) \exp \gamma_{0} t}{\left.\varepsilon_{\omega}\right|_{\omega_{k}\left(k_{0}\right)}} \frac{1}{\sqrt{2 \pi}} \frac{1}{\sqrt{\left(\left|\gamma_{k k}\right|+\mathrm{i} \omega_{k k}\right) t}} \\
& \times \exp \left[\frac{-\frac{1}{2}\left(x-V_{g} t\right)^{2}\left|\gamma_{k k}\right|}{\left(\left|\gamma_{k k}\right|^{2}+\omega_{k k}^{2}\right) t}+\mathrm{i} \frac{\frac{1}{2}\left(x-V_{g} t\right)^{2}\left|\omega_{k k}\right|}{\left(\left|\gamma_{k k}\right|^{2}+\omega_{k k}^{2}\right) t}\right]+\mathrm{c.c.} \tag{2.80}
\end{align*}
$$

We note that the spatial width of the pulse scales as $\Delta x \sim t^{1 / 2}\left(\left|\gamma_{k k}\right|^{2}+\omega_{k k}^{2}\right)^{1 / 2} /\left|\gamma_{k k}\right|$. Hence, the larger (and steeper) $\left|\gamma_{k k}\right|$, the faster the spreading in configuration space. Because the pulse width in the space-time domain is increasing as $t^{1 / 2}$, the pulse in the frequency-wavenumber dual domain is decreasing as $t^{-1 / 2}$; hence, the wave packet is lengthening in space-time and becoming purer in its spectral content as it advects and grows.

To determine whether an instability is absolute or convective, we must compare the spreading $\sqrt{\mathrm{D} t}=\sqrt{\left(\left|\gamma_{k k}\right|^{2}+\omega_{k k}^{2}\right) t / \gamma_{k k}}$ and the exponential growth $\exp \left(\gamma_{0} t\right)$ with the advection of the pulse at the group velocity $V_{g}$. In the frame advecting with the wave packet, $\left|\varepsilon^{-1}(x, t)\right| \propto \exp \left(\gamma_{0} t-x^{2} / 2 \mathrm{D} t\right)$; and the pulse grows exponentially and spreads. In the plasma frame one obtains

$$
\begin{align*}
& \left|\varepsilon^{-1}(x, t)\right| \propto \exp \left(\gamma_{0} t-\frac{\left(x-V_{g} t\right)^{2}}{2 \mathrm{D} t}\right) \\
& \quad \equiv \exp \left(\tau-\frac{(\xi-\sigma \tau)^{2}}{2 \tau}\right), \quad \xi \equiv \sqrt{\frac{\gamma_{0}}{D}} x, \tau \equiv \gamma_{0} t, \sigma \equiv V_{g} \sqrt{\frac{1}{\gamma_{0} D}} \\
& \quad \rightarrow \ln \left|\varepsilon^{-1}(x, t)\right| \sim \gamma_{0} t-\frac{\left(x-V_{g} t\right)^{2}}{2 \mathrm{D} t}=\tau-\frac{(\xi-\sigma \tau)^{2}}{2 \tau} \tag{2.81}
\end{align*}
$$

ThEOREM. For fixed $\xi$, the asymptotics of $\left|\varepsilon^{-1}(x, t)\right|$ in (2.81) as $\tau \rightarrow \infty$ determines whether the pulse is growing absolutely or convectively, i.e.

$$
\begin{equation*}
\lim _{\tau \rightarrow \infty}\left[\ln \left|\varepsilon^{-1}(x, t)\right| \sim \tau-\frac{(\xi-\sigma \tau)^{2}}{2 \tau}\right] \rightarrow \tau\left(1-\frac{\sigma^{2}}{2}\right) \tag{2.82}
\end{equation*}
$$

For $\sigma>\sqrt{ } 2, \ln \left|\varepsilon^{-1}\right| \rightarrow-\infty$ as $\tau \rightarrow \infty$, i.e. the instability is convective; and the disturbance grows at first and then dies away. For $\sigma<\sqrt{ } 2, \ln \left|\varepsilon^{-1}\right| \rightarrow \infty$ as $\tau \rightarrow \infty$, i.e. the instability is absolute and continues to grow exponentially at any fixed position. The condition for absolute (or convective) instability is then

$$
\begin{equation*}
V_{g}<(>) \sqrt{2 \gamma_{0} D}=\sqrt{2 \gamma_{0}\left(\frac{\left|\gamma_{k k}\right|^{2}+\omega_{k k}^{2}}{\left|\gamma_{k k}\right|}\right)} \tag{2.83}
\end{equation*}
$$

EXERCISE. Show that in the plasma frame the group velocity for the weak beam in a cold-plasma instability is $(2 / 3) u_{b}$ and the instability is convective using (2.83) and the analysis in § 2.6.1.

### 2.6.3. Peter Sturrock's method for analysing absolute instability (reference)

Stanford Professor P. A. Sturrock introduced a method for analysing whether a growing instability is convective or absolute (Sturrock 1958). Sturrock's method is reviewed in (Clemmow \& Dougherty 1989) and was assigned as reading but not covered in class lectures.

### 2.6.4. Bers and Briggs' method for analysing absolute instability

Bers (1973) and Briggs (1964) derived a method for calculating the impulse response using contour integration and analytic continuation, from which absolute and convective instability can be distinguished. The calculation begins with consideration of (2.80) in one spatial dimension transformed to the moving reference frame $x=w t$,

$$
\begin{equation*}
\varepsilon^{-1}(x, t)=\int \frac{\mathrm{d} k}{2 \pi} \int \frac{\mathrm{~d} \omega}{2 \pi} \frac{\exp (\mathrm{i} k x-\mathrm{i} \omega t)}{\varepsilon(k, \omega)}=\int \frac{\mathrm{d} k}{2 \pi} \int \frac{\mathrm{~d} \omega}{2 \pi} \frac{\exp \left(\mathrm{i} \omega_{w} t\right)}{\varepsilon\left(k, \omega_{w}+k w\right)} \tag{2.84}
\end{equation*}
$$

where $\omega_{w}=\omega-k w$, which is the Doppler-shifted frequency. There are two contour integrals to perform in (2.84). These are diagrammed in figure 8 for a convective instability and in figure 9 for an absolute instability. In the complex $k$ plane the locus of poles in $k$ of the integrand in (2.84) for fixed $\omega$ is shown by $C_{\omega}$, and the integration contour is $C_{k}$. In the complex $\omega$ plane the locus of poles in $\omega$ of the integrand in (2.84) for fixed $k$ is shown by $C_{k}$, and the integration contour is $C_{\omega}$. Making use of analytic continuation, the integration contour in the complex $\omega$ plane is depressed to lower values on the imaginary axis as shown in figure 6 until poles on $C_{k}$ from below the $C_{\omega}$ contour are encountered. The poles $C_{k}$ in the complex $\omega$ plane are parametrized by the complex value of $k$ swept out by the $C_{k}$ contour in the complex $k$ plane. In order to depress the $C_{\omega}$ contour to lower values of $\operatorname{Im} \omega$, we must move the $C_{k}$ contour down in the complex $k$ plane. In the complex $k$ plane there are a loci of poles $C_{\omega}$ above and below the $C_{k}$ integration contour. For the convectively unstable case, the $C_{\omega}$ contour in the complex $\omega$ plane can be depressed to values of $\operatorname{Im} \omega<0$; and $\varepsilon^{-1}(x, t)$ decays (figure 8 ). In the absolutely unstable case, the $C_{\omega}$ contour in the complex $\omega$


Figure 8. Convective instability: diagrams of contour integral paths $C_{k}$ in complex $k$ plane $(a, c)$, and contour integral paths $C_{\omega}$ in complex $\omega$ plane (b) and depressed in (d) showing the loci of poles of the integrand in (2.84).
plane can be depressed and deformed to lower values of $\operatorname{Im} \omega$ everywhere except as one approaches the pinch point $P$ in figure $9(c)$ because the $C_{k}$ integration contour in the $k$ plane becomes trapped ('pinched') between the $C_{\omega}$ contours above and below it; and part of the $C_{k}$ loci of poles has some values $\operatorname{Im} \omega_{k}>0$ in figure $9(d)$. The asymptotic response for $\varepsilon^{-1}(x, t)$ exhibits exponential growth at the value of $\operatorname{Im} \omega_{k}>0$ at the pinch point.

EXERCISE. Examine the conditions for absolute versus convective instability for the cold beam - cold-plasma instability investigated in $\S 2.6 .1$ in the (a) plasma frame in which $\varepsilon(k, \omega)=1-\omega_{p}^{2} / \omega^{2}-\omega_{b}^{2} /\left(\omega-k u_{b}\right)^{2}$ and (b) the beam frame in which $\varepsilon(k, \omega)=$ $1-\omega_{p}^{2} /\left(\omega+k u_{b}\right)^{2}-\omega_{b}^{2} / \omega^{2}$, and there is absolute instability.

THEOREM. The condition for absolute instability is equivalent to obtaining two pinching roots for $(\omega, k)$ from the simultaneous solution of $\varepsilon(\omega, k)=0$ and $\partial \varepsilon(\omega, k) / \partial k=0$ with $\operatorname{Im} \omega>0$, provided that $\partial \varepsilon(\omega, k) / \partial \omega \neq 0$.

Exercise. Prove this theorem.


FIGURE 9. Absolute instability: diagrams of contour integral paths $C_{k}$ in complex $k$ plane ( $a, c$ ), and contour integral paths $C_{\omega}$ in complex $\omega$ plane ( $b$ ) and depressed in (d) showing the loci of poles of the integrand in (2.84). A pinching of roots occurs at point $P$ in (c).

### 2.7. Linear steady-state response to a fixed-frequency disturbance

We consider here the response of a plasma to a steady-state force at a fixed frequency. We assume that the plasma is quiescent and non-turbulent. There may be transient convective instabilities but no absolute instability. We implant a localized fixed-frequency disturbance and derive the plasma response. Let the implanted disturbance be a planar disturbance, for example a biased grid connected to an oscillator,

$$
\begin{align*}
\delta \phi^{\mathrm{ext}}(\boldsymbol{r}, t) & =\left\{0 t<0, \delta(z) \sin \left(\omega_{0} t\right) \quad t>0\right\} \\
& \rightarrow \delta \phi^{\mathrm{ext}}(\boldsymbol{k}, \omega)=-(2 \pi)^{2} \delta\left(k_{x}\right) \delta\left(k_{y}\right) \frac{\omega_{0}}{\omega^{2}-\omega_{0}^{2}} \tag{2.85}
\end{align*}
$$

The plasma potential is then given by (2.50) and (2.85)

$$
\begin{aligned}
\delta \phi(\boldsymbol{k}, \omega) & =\frac{\delta \phi^{\mathrm{ext}}(\boldsymbol{k}, \omega)}{\varepsilon(\boldsymbol{k}, \omega)} \\
& \rightarrow \delta \phi(\boldsymbol{r}, t)=-\int \frac{\mathrm{d}^{3} k}{(2 \pi)^{3}} \int \frac{\mathrm{~d} \omega}{2 \pi}
\end{aligned}
$$



FIGURE 10. Steady-state response to a fixed-frequency disturbance: diagrams of the contour integral path $C_{k}$ in complex $k$ plane (a) and the contour integral paths $C_{\omega}$ in complex $\omega$ plane (b) showing the loci of poles of the integrand in (2.86).

$$
\begin{align*}
& \times \operatorname{expi}\left(k_{x} x+k_{y} y+k_{z} z-\omega t\right) \frac{(2 \pi)^{2} \delta\left(k_{x}\right) \delta\left(k_{y}\right) \frac{\omega_{0}}{\omega^{2}-\omega_{0}^{2}}}{\varepsilon(\boldsymbol{k}, \omega)} \\
\rightarrow & -\int \frac{\mathrm{d} k_{z}}{2 \pi} \int \frac{\mathrm{~d} \omega}{2 \pi} \exp \left(\mathrm{i} k_{z} z-\mathrm{i} \omega t\right) \frac{1}{\varepsilon(\boldsymbol{k}, \omega)} \frac{\omega_{0}}{\omega^{2}-\omega_{0}^{2}} . \tag{2.86}
\end{align*}
$$

We let any transients associated with initial conditions and any instabilities convect or decay away.

THEOREM. Given that the dielectric is an even function of $z$, then $\varepsilon\left(-k_{z},-\omega_{r}+\mathrm{i} \omega_{i}\right)=$ $\varepsilon\left(k_{z}, \omega_{r}+\mathrm{i} \omega_{i}\right)$.

### 2.7.1. Response for a sinusoidally driven stable system

The contour integrations in (2.86) are diagrammed in figure 10 . For every value of $k$ the $C_{k}$ contour in figure $10(b)$ is below the $\operatorname{Re} \omega$ axis, which dictates that $\delta \phi(\boldsymbol{r}, t)$ is stable. The $\omega$ integration in (2.86) is performed using Cauchy's theorem to obtain,

$$
\begin{equation*}
\delta \phi(\boldsymbol{r}, t)=\frac{\mathrm{i}}{2} \int \frac{\mathrm{~d} k_{z}}{2 \pi} \frac{\exp \left(\mathrm{i} k_{z} z-\mathrm{i} \omega_{0} t\right)}{\varepsilon\left(k_{z}, \omega_{0}\right)}+\text { c.c. } \tag{2.87}
\end{equation*}
$$

and transients that are evanescent. The $k_{z}$ integration is now performed.
Consider the poles of the integrand in (2.87), i.e. the solutions of $\varepsilon\left(k_{z}, \omega_{0}\right)=0$. For the example of a velocity distribution that is a square in velocity space (see table 1) then $\omega_{0}^{2}=\omega_{p}^{2}+k_{z}^{2} c^{2} \rightarrow k_{z}= \pm \sqrt{\omega_{0}^{2}-\omega_{p}^{2}} / c$, which roots lie on the real $k_{z}$ axis. A real physical system will have some finite dissipation. Hence, $\omega(k)= \pm \sqrt{\omega_{p}^{2}+k^{2} c^{2}}-\mathrm{i} v$ and $(\omega+\mathrm{i} \nu)^{2}=\omega_{p}^{2}+k^{2} c^{2}$, where $\nu$ is a damping rate, e.g. due to weak collisions, so that free oscillations are damped and transients will indeed die away. In this
circumstance the solutions for $k_{z}$ become $k_{z}= \pm \sqrt{\left(\omega_{0}+\mathrm{i} v\right)^{2}-\omega_{p}^{2}} / c$. The sign of $k_{z}$ is selected based on whether values of $z$ are negative or positive so that the response of the system dies away for $|z| \rightarrow \infty$. For $\omega_{0}<\omega_{p} k_{z}$ is purely imaginary, and the plasma response is evanescent; and modes do not propagate.

For $z>0$ the contour integral in (2.87) is closed counter-clockwise in the upper half-plane in figure $10(a)$, and we sum over pole contributions,

$$
\begin{equation*}
\delta \phi(\boldsymbol{r}, t)=-\frac{1}{2} \sum_{\ell} \exp \left(\mathrm{i} k_{z l}^{\prime} z-k_{z l}^{\prime \prime} z-\mathrm{i} \omega_{0} t\right) \frac{1}{\left.\frac{\partial \varepsilon\left(k_{z}, \omega_{0}\right)}{\partial k_{z}}\right|_{\ell}}+\text { c.c. } \tag{2.88}
\end{equation*}
$$

where $k_{z l}=k_{z l}^{\prime}+\mathrm{i} k_{z l}^{\prime \prime}$ is a solution of $\varepsilon\left(k_{z l}, \omega_{0}\right)=0$ with $k_{z l}^{\prime \prime}>0$. For $z<0$ the contour integral is closed clockwise in the lower half-plane with $k_{z l}^{\prime \prime}<0$; and the overall sign of the right-hand side of (2.88) changes. For $z$ positive or negative the plasma response is sinusoidal in time with frequency $\omega_{0}$ and damps away from the origin in $z$.

### 2.7.2. Response for a sinusoidally driven convectively unstable system

One can calculate the sinusoidally driven response for a convectively unstable system in the same manner as in $\S 2.7 .1$ Because the system is convectively unstable, the integration contour $C_{\omega}$ can be depressed as in figure 10 ; and the results in (2.87) and (2.88) pertain. However, the solutions of $\varepsilon\left(k_{z}, \omega_{0}\right)=0$ for $k_{z}$ can have $\operatorname{Im} k_{z}<0$ for $z>0$ (and $\operatorname{Im} k_{z}>0$ for $z<0$ ) leading to spatially growing solutions away from the origin in $z$.

EXERCISE. Consider the beam-plasma system in the plasma reference frame (§ 2.6.1) which is convectively unstable. Solve $\varepsilon\left(k_{z}, \omega_{0}\right)=0$ based on (2.74) for $k_{z}$ and evaluate (2.88). Contrast this to the stable case of a beaming plasma,

$$
\varepsilon(k, \omega)=1-\frac{\omega_{p}^{2}}{(\omega+\mathrm{i} v-k u)^{2}}=0
$$

EXERCISE. Consider an external driving potential that is a spherical waveform,

$$
\delta \phi^{\mathrm{ext}}(\boldsymbol{r}, t)=\left\{0 t<0, \delta(r) \sin \left(\omega_{0} t\right) t>0\right\}
$$

in the rest frame of a cold plasma. Find the response for $\omega_{0}>\omega_{p}$ and $\omega_{0}<\omega_{p}$. Contrast this to the case of a mono-energetic velocity distribution: $f_{0}=\delta\left(|\boldsymbol{v}|-v_{0}\right)$ /norm.

### 2.8. Linear stability or instability for a few simple velocity distributions

We return to the consideration of Vlasov stability for more general velocity distributions based on (2.63):

$$
\begin{equation*}
\varepsilon(\boldsymbol{k}, \omega)=1-\frac{\omega_{p}^{2}}{k^{2}} Z^{\prime}(v)=1-\frac{\omega_{p}^{2}}{k^{2}} \int \mathrm{~d} u \frac{g_{\hat{k}}^{\prime}(u)}{u-v} \tag{2.89}
\end{equation*}
$$

where $v=\omega / k$ and $\int \mathrm{d} u g(u)=1$. In figure 11 are shown four examples of velocity distributions. Figure $11(a)$ depicts two warm beams, which is always linearly unstable.


Figure 11. Four examples of finite-temperature velocity distribution functions.

A single-humped velocity distribution is shown in figure $11(b)$, which is stable. The velocity distribution function shown in figure $11(c)$ can be stable or unstable depending on the relative heights $b$ and $a$. In the limit $b \rightarrow 0$, the velocity distribution is single humped and stable. In the limit $b \rightarrow a$, the velocity distribution corresponds to two counter-propagating warm beams and is unstable. Figure $11(d)$ depicts a double Cauchy beam. When the thermal spread $c$ is larger than the beam centroid velocity $u_{0}$, the plasma is stable; and when $c<u_{0}$, the plasma is unstable. The results of these examples give one a hint toward a more general stability condition. A general condition is that it is necessary for $g(u)$ to have a minimum for instability.

EXERCISE. Show that $\omega(k, c)=\omega(k, 0)-\mathrm{i} k c$ for the double Cauchy beam, which illustrates the stabilizing influence of the thermal spread.

### 2.9. General analysis of the dielectric response

### 2.9.1. Perturbative expansion for a fast wave

Equation (2.89) can be evaluated easily when thermal effects are weak. For a 'fast' wave, $V \gg v_{\text {th }}$, where $v_{\text {th }}$ is a characteristic thermal velocity, $v_{\mathrm{th}}^{2}=T / m$. one can expand

$$
\begin{equation*}
\frac{1}{u-v}=-\frac{1}{v}\left(\frac{1}{1-\frac{u}{v}}\right)=-\frac{1}{v}\left(1+\frac{u}{v}+\frac{u^{2}}{v^{2}}+\frac{u^{3}}{v^{3}} \ldots\right) . \tag{2.90}
\end{equation*}
$$

THEOREM. From (2.61) and (2.90) the first thermal correction to $Z(v)$ is then

$$
\begin{equation*}
Z(v)=-\frac{1}{v}\left(1+\frac{v_{\mathrm{th}}^{2}}{v^{2}}+O\left(\frac{v_{\mathrm{th}}^{3}}{v^{3}}\right)\right), \tag{2.91}
\end{equation*}
$$

where $v=\omega / k$ and $\left[1,0, v_{\mathrm{th}}^{2}\right]=\int \mathrm{d} u\left[1, u, u^{2}\right] g(u)$, and

$$
\begin{equation*}
Z^{\prime}(v)=\frac{1}{v^{2}}+\frac{3 v_{\mathrm{th}}^{2}}{v^{4}}+\cdots \tag{2.92}
\end{equation*}
$$

Hence,

$$
\begin{equation*}
\varepsilon(k, \omega)=1-\frac{\omega_{p}^{2}}{\omega^{2}}-\frac{\omega_{p}^{2} 3 k^{2} v_{\mathrm{th}}^{2}}{\omega^{4}}+O\left(\omega^{-5}\right) \tag{2.93}
\end{equation*}
$$

and the Bohm-Gross dispersion relation for the electron plasma wave results from $\varepsilon(k, \omega)=0$,

$$
\begin{equation*}
\omega^{2}=\omega_{p}^{2}+\frac{3 k^{2} v_{\mathrm{th}}^{2}}{\omega^{2}} \omega_{p}^{2}+\cdots \approx \omega_{p}^{2}+3 k^{2} v_{\mathrm{th}}^{2} \tag{2.94}
\end{equation*}
$$

with the inclusion of thermal effects the electron plasma wave has acquired dispersion. THEOREM. The product of the phase and group velocities for the electron plasma wave is given by $v_{p} v_{g}=3 v_{\mathrm{th}}^{2}$ for $k v_{\mathrm{th}} \ll \omega_{p}$, i.e. $k \lambda_{D} \ll 1$, where $\lambda_{D}=v_{\mathrm{th}} / \omega_{p}$ is the Debye length. With $v_{p} \gg v_{\mathrm{th}}$ the group velocity satisfies $v_{g} \ll v_{\mathrm{th}}$.
2.9.2. Use of the Hilbert transform in deriving the dielectric function

We return to the consideration of $Z(v)$, equation (2.61),

$$
\begin{align*}
Z(v)= & \int_{-\infty}^{\infty} \mathrm{d} u \frac{g_{\hat{k}}(u)}{u-v_{R}-\mathrm{i} v_{I}} \\
= & \int_{-\infty}^{\infty} \mathrm{d} u \frac{g_{\hat{k}}(u)}{\left(u-v_{R}\right)^{2}+v_{I}^{2}}\left[u-v_{R}+\mathrm{i} v_{I}\right], \quad v=v_{R}+\mathrm{i} v_{I}, \quad v_{I}>0 \\
\rightarrow & \operatorname{Re} Z(v)=\int_{-\infty}^{\infty} \mathrm{d} u \frac{g_{\hat{k}}(u)}{\left(u-v_{R}\right)^{2}+v_{I}^{2}}\left(u-v_{R}\right), \\
& \operatorname{Im} Z(v)=v_{I} \int_{-\infty}^{\infty} \mathrm{d} u \frac{g_{\hat{k}}(u)}{\left(u-v_{R}\right)^{2}+v_{I}^{2}} . \tag{2.95}
\end{align*}
$$

One notes that $\operatorname{Re} Z(v)$ has odd symmetry with respect to $u-v_{R}$ and goes to zero for $v_{I}=0$ and for $v_{R} \rightarrow \pm \infty$.

ThEOREM. As $v_{I} \rightarrow 0$ there is a singularity in $\operatorname{Re} Z(v)$ at $v_{R}=0$ while $\operatorname{Im} Z(v) \propto$ $v_{I} \rightarrow 0$. In the limit $v_{I} \rightarrow 0, Z(v)$ takes on the following special forms:

$$
\begin{equation*}
Z\left(v_{R}\right)=P \int \mathrm{~d} u \frac{g(u)}{u-v_{R}}+\mathrm{i} \int \mathrm{~d} u g(u) \pi \delta\left(u-v_{R}\right), \tag{2.96}
\end{equation*}
$$

where $P$ denotes the Cauchy principal value of the integral that immediately follows it. The development of (2.96) has a basis in distribution theory (Lighthill 1958),

$$
\begin{equation*}
\lim _{y \rightarrow 0 \pm} \frac{1}{x+\mathrm{i} y}=P\left(\frac{1}{x}\right) \mp \mathrm{i} \pi \delta(x) . \tag{2.97}
\end{equation*}
$$

Corollary. Hilbert transform

$$
\begin{equation*}
Z(v)=\mathrm{i} \int_{0}^{\infty} \mathrm{d} s \exp (\mathrm{i} v s) \int_{-\infty}^{\infty} \mathrm{d} u g(u) \exp (-\mathrm{i} u s)=\int_{-\infty}^{\infty} \mathrm{d} u \frac{g(u)}{u-v}, \tag{2.98}
\end{equation*}
$$

where the first integral is a Laplace transform and the second integral is a Fourier transform.

EXERCISE. Invert the Hilbert transform to obtain $g(u)$ given $Z(v)$.

THEOREM. Relation of the dielectric function to $Z^{\prime}(v)$ from (2.89)

$$
\begin{align*}
\varepsilon(\boldsymbol{k}, \omega) & =1-\frac{\omega_{p}^{2}}{k^{2}} Z^{\prime}(v)=1-\frac{\omega_{p}^{2}}{k^{2}} \int \mathrm{~d} u \frac{g_{\hat{\boldsymbol{k}}}^{\prime}(u)}{u-v} \\
& =1-\frac{\omega_{p}^{2}}{k^{2}} P \int \mathrm{~d} u \frac{g_{\hat{\boldsymbol{k}}}^{\prime}(u)}{u-v}-\frac{\omega_{p}^{2}}{k^{2}} \int \mathrm{~d} u g_{\hat{k}}^{\prime}(u) \mathrm{i} \pi \delta(u-v), \quad v \equiv \frac{\omega}{k} \tag{2.99}
\end{align*}
$$

EXERCISE. Show that $\varepsilon_{R}=\operatorname{Re} \varepsilon$ is an even function of $\omega$ and $\varepsilon_{I}=\operatorname{Im} \varepsilon$ is an odd function of $\omega$.
2.9.3. Dispersion relation for weak damping or growth rate compared to the real part of the frequency
Consider $\omega=\omega_{R}+\mathrm{i} \gamma$ and conditions such that $|\gamma|=|\operatorname{Im} \omega| \ll|\operatorname{Re} \omega|$ and Taylorseries expand $\varepsilon(\boldsymbol{k}, \omega)=0$ for small $\gamma$,

$$
\begin{align*}
\varepsilon\left(\boldsymbol{k}, \omega_{k}\right)= & \varepsilon_{R}\left(\boldsymbol{k}, \omega_{k}\right)+\mathrm{i} \varepsilon_{I}\left(\boldsymbol{k}, \omega_{k}\right)+\left.\mathrm{i} \gamma \frac{\partial}{\partial \omega} \varepsilon(\boldsymbol{k}, \omega)\right|_{\omega_{R}}+O\left(\gamma^{2}\right)=0 \\
\rightarrow & \varepsilon_{R}\left(\boldsymbol{k}, \omega_{k}\right)-\left.\gamma \frac{\partial}{\partial \omega} \varepsilon_{I}(\boldsymbol{k}, \omega)\right|_{\omega_{R}}+O\left(\gamma^{2}\right)=0 \quad \varepsilon_{I}\left(\boldsymbol{k}, \omega_{k}\right)+\left.\gamma \frac{\partial}{\partial \omega} \varepsilon_{R}(\boldsymbol{k}, \omega)\right|_{\omega_{R}} \\
& +O\left(\gamma^{2}\right)=0 \tag{2.100}
\end{align*}
$$

THEOREM. For weak damping or weak growth rates the solution of $\varepsilon(\boldsymbol{k}, \omega)=0$ yields solutions for $\omega_{R}(\boldsymbol{k})$ and $\gamma(\boldsymbol{k})$,

$$
\begin{equation*}
\varepsilon_{R}\left(\boldsymbol{k}, \omega_{R}\right)=0 \rightarrow \omega_{R}=\cdots \gamma(\boldsymbol{k})=-\frac{\varepsilon_{I}\left(\boldsymbol{k}, \omega_{R}\right)}{\left.\frac{\partial}{\partial \omega} \varepsilon_{R}(\boldsymbol{k}, \omega)\right|_{\omega_{R}}} \tag{2.101}
\end{equation*}
$$

$\omega_{k}$ is defined equal to $\omega_{R}(\boldsymbol{k})$. The ratio of the damping rate to the frequency $\gamma(\boldsymbol{k}) / \omega_{R}(\boldsymbol{k})$ is a measure of the ratio of the dissipation (negative or positive) to the wave energy,

$$
\begin{equation*}
\frac{\gamma(\boldsymbol{k})}{\omega_{R}}=-\frac{\pi g^{\prime}(v)}{\frac{\omega_{R}}{k} P \int \mathrm{~d} u \frac{g^{\prime \prime}(u)}{u-v}}=-\frac{\pi g^{\prime}(v)}{v Z_{R}^{\prime \prime}(v)} . \tag{2.102}
\end{equation*}
$$

EXERCISE. Derive the derivative of the principal part of the Hilbert transform.

### 2.9.4. Maxwellian velocity distribution function - electron Landau damping in fast and slow waves

We next construct the dispersion relation for a Maxwellian electron velocity distribution function,

$$
\begin{equation*}
g(u)=\frac{1}{\sqrt{2 \pi v_{\mathrm{th}}^{2}}} \exp \left(-\frac{u^{2}}{2 v_{\mathrm{th}}^{2}}\right), \quad g^{\prime}(u)=-\frac{u}{v_{\mathrm{th}}^{3} \sqrt{2 \pi}} \exp \left(-\frac{u^{2}}{2 v_{\mathrm{th}}^{2}}\right), \quad v_{\mathrm{th}}^{2}=\frac{T_{e}}{m_{e}} \tag{2.103}
\end{equation*}
$$

Waves in a warm plasma can be classified into three categories: fast, intermediate and slow depending on the ratio of the phase velocity to the thermal velocity. For a fast wave $v=\omega / k \gg v_{\text {th }}, \gamma \propto \exp \left(-v^{2} / 2 v_{\text {th }}^{2}\right)$ is exponentially small. For intermediate waves $v \sim v_{\text {th }}, \gamma \sim \omega_{k}$; and $\gamma$ is relatively large, which invalidates the Taylor-series expansion in (2.100) leading to (2.101) and (2.102). For slow waves $v \ll v_{\mathrm{th}}, \gamma \propto v / v_{\mathrm{th}}$ and is linearly small.

Example. Electron plasma wave. For a fast wave in a Maxwellian plasma, the phase velocity falls far out on the high energy tail of the velocity distribution function. From (2.101)-(2.103) one obtains

$$
\begin{equation*}
\varepsilon_{R} \rightarrow 1-\frac{\omega_{p}^{2}}{\omega^{2}}, \quad \omega \frac{\partial \varepsilon_{R}}{\partial \omega} \approx 2 \frac{\omega_{p}^{2}}{\omega^{2}} \approx 2, \quad \frac{\gamma(\boldsymbol{k})}{\omega_{R}}=-\sqrt{\frac{\pi}{8}}\left(\frac{v}{v_{\mathrm{th}}}\right)^{3} \exp \left(-\frac{v^{2}}{2 v_{\mathrm{th}}^{2}}\right) . \tag{2.104}
\end{equation*}
$$

The damping rate given in (2.104) is the Landau damping rate for the electron plasma wave in a Vlasov plasma (collisionless). As elaborated in the next section, particles with velocity nearly equal to the phase velocity (the 'resonant' particles) contribute positive dissipation, because there are fewer particles faster than the wave (which particles are decelerated) than particles slower than the wave (which particles are accelerated). Equation (2.94) gives the thermal correction to the real part of the frequency for the electron plasma wave. For small $k \lambda_{D} \ll 1$, the phase velocity $v=\omega / k \rightarrow \infty$ as $k \rightarrow 0$, while $v_{g} \rightarrow 0$; and $\gamma / \omega \rightarrow 0$ because the number of resonant particles in the tail is exponentially small. For increasing $k$, the wave frequency increases while the phase velocity decreases more rapidly, which increases the damping rate and ultimately invalidates the fast-wave assumption.

Example. Ion-acoustic wave. For a slow wave in a Maxwellian plasma, $v \ll v_{\text {the }}$, the phase velocity falls near the peak of the electron velocity distribution at low velocities. We assume that the ions are singly charged and relatively cold, $T_{i} \ll T_{e}$, and $v_{i} \ll v \ll v_{\text {the }}$. In these limits $v=c_{s}=\left(T_{e} / m_{i}\right)^{1 / 2}$, ion Landau damping is exponentially small and the electron Landau damping is linearly small. In this two-species plasma $g(u)=\sum_{s} \omega_{s}^{2} g_{s}(u) / \omega_{p}^{2}$. For cold ions the ion-acoustic wave dispersion relation is derived from

$$
\begin{align*}
& \varepsilon_{R}(\boldsymbol{k}, \omega)=1-\frac{\omega_{\mathrm{pi}}^{2}}{\omega^{2}}+\frac{1}{k^{2} \lambda_{e}^{2}}=0 \rightarrow \omega_{k}^{2}=\frac{k^{2} \lambda_{e}^{2} \omega_{\mathrm{pi}}^{2}}{1+k^{2} \lambda_{e}^{2}}=\frac{k^{2} c_{s}^{2}}{1+k^{2} \lambda_{e}^{2}} \\
& \left.\omega \frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}}=2\left(1+\frac{1}{k^{2} \lambda_{e}^{2}}\right) \frac{\gamma(k)}{\omega(k)}=-\sqrt{\frac{\pi}{8}}\left(\frac{m_{e}}{m_{i}}\right)^{1 / 2}\left(\frac{1}{1+k^{2} \lambda_{e}^{2}}\right)^{3 / 2} . \tag{2.105}
\end{align*}
$$

The electron Landau damping for the ion-acoustic wave is small for all values of $k \lambda_{e}$.


FIGURE 12. Velocity distribution function for the bump-on-tail instability.

### 2.9.5. Bump-on-tail velocity distribution and resonant instability

The bump-on-tail velocity tail velocity distribution is diagrammed in figure 12. This velocity distribution is obviously related to the weak-beam case studied in $\S 2.6$. However, here both the plasma and the beam have acquired finite thermal spreads. If the phase velocity of an electron plasma wave falls on an interval of the velocity distribution of the beam with positive slope there can be instability. Equations (2.101) and (2.102) can be used to compute the growth or damping rate for the bump-on-tail distribution,

$$
\begin{equation*}
\frac{\gamma}{\omega_{k}} \approx \frac{\omega_{p}^{2}}{k^{2}} \frac{\pi g^{\prime}(v)}{2} \tag{2.106}
\end{equation*}
$$

where we have used $\omega_{k} \partial \varepsilon_{R} / \partial \omega=2 \omega_{p}^{2} / \omega_{k}^{2} \sim 2$, which is good for a relatively small bump on the tail. If $g^{\prime}(v)>0$ then $\gamma>0$, i.e. there is instability.

Definition. Resonant instability or damping. When there are particles whose unperturbed velocity is coincident or nearly coincident with the phase velocity of a wave (velocity resonance), the particles can resonantly interact with the wave and exchange energy. In the wave frame, $\omega-\boldsymbol{k} \cdot \boldsymbol{v}=0$, the resonant particle sees a constant phase and can be steadily accelerated or decelerated by the waves electric field. When there are more resonant particles giving energy to the wave due to deceleration than particles extracting energy from the wave due to acceleration, the wave can grow; and there is resonant instability. The slope of the velocity distribution dictates whether there are more or fewer particles faster or slower than the wave phase velocity. If the slope of the velocity distribution is negative, then there are more particles with velocities slower than the wave phase velocity that are accelerated by the wave; and the wave experiences resonant (Landau) damping.

We can consider the resonant particle interaction with a wave from the quantum mechanical perspective. Suppose there are exchanges of momentum and energy with the wave given by $\Delta \boldsymbol{p}= \pm \hbar \boldsymbol{k}$ and $\Delta \varepsilon= \pm \hbar \omega$ that are small compared to the particle's momentum and energy ( $h$ is Planck's constant, and the over bar indicates $h / 2 \pi)$. Then $\Delta \varepsilon=m v \cdot \Delta \boldsymbol{v}=\boldsymbol{v} \cdot \Delta \boldsymbol{p}$, and substituting the expressions for $\Delta \boldsymbol{p}$ and $\Delta \varepsilon$ one immediately obtains $\omega=\boldsymbol{k} \cdot \boldsymbol{v}$, which is the resonance condition.
[Editor's note: there is a rich literature regarding physical considerations associated with Landau damping and interpretations of Landau damping in terms of the exchange of energy between resonant particles and waves. No attempt here is made to review the literature on Landau damping, but we give two illustrative examples: D.G.

Swanson addresses the applicability of energy-related arguments to linear Landau damping in §§4.2.3 and 4.2.4 D.G. Swanson, Plasma Waves, Second Edition, Series in Plasma Physics, Institute of Physics Publishing, 2003; and D.D. Ryutov gives an historical perspective on Landau damping in D.D. Ryutov, Landau damping: half a century with the great discovery, Plasma Phys. Control. Fusion 41, A1-A12 (1999).]

## 3. Vlasov-Maxwell plasma formulation

In this section the totality of Maxwell's equations are introduced in the context of a collisionless Vlasov plasma theory.

### 3.1. Wave energy and Poynting theorem

Maxwell's equations in a plasma take the form

$$
\begin{equation*}
\nabla \times \boldsymbol{B}-\frac{1}{c} \frac{\partial \boldsymbol{E}}{\partial t}=\frac{4 \pi}{c} \boldsymbol{j} \quad \nabla \times \boldsymbol{E}+\frac{1}{c} \frac{\partial \boldsymbol{B}}{\partial t}=0 \tag{3.1}
\end{equation*}
$$

where the current $\boldsymbol{j}$ is the sum of externally applied currents and the currents due to free charges in the plasma. We will ignore gravity here but otherwise will be as general as possible. We introduce a notation to emphasize that the wave phenomena are spatially and temporally varying perturbations $\delta \boldsymbol{B}, \delta \boldsymbol{E}$ and $\delta \boldsymbol{j}$. If we compute the dot product of $c \delta \boldsymbol{E}$ with the perturbed Ampere's law and combine with the dot product of $c \delta \boldsymbol{B}$ with Faraday's law, we obtain

$$
\begin{equation*}
-\nabla \cdot\left(\frac{c}{4 \pi} \delta \boldsymbol{E} \times \delta \boldsymbol{B}\right)=\frac{\partial}{\partial t}\left(\frac{|\delta \boldsymbol{E}|^{2}}{8 \pi}+\frac{|\delta \boldsymbol{B}|^{2}}{8 \pi}\right)+\delta \boldsymbol{j} \cdot \delta \boldsymbol{E} . \tag{3.2}
\end{equation*}
$$

The left-hand side of (3.2) is the divergence of the Poynting flux. The last term on the right is the rate of work done by the electromagnetic fields on the particles. In obtaining (3.2) only terms that are bilinear in the perturbed fields and currents are retained, and linear terms like $\delta \boldsymbol{B} \cdot \boldsymbol{B}_{0}$ are dropped because they have no finite average value when time averaged over the cycle of the perturbed fields.

Compute the volume integral of (3.2) with vanishing surface terms at $\infty$ to obtain

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} \int \mathrm{~d}^{3} \boldsymbol{r} \frac{|\delta \boldsymbol{E}|^{2}+|\delta \boldsymbol{B}|^{2}}{8 \pi}=-\int \mathrm{d}^{3} \boldsymbol{r} \delta \boldsymbol{j} \cdot \delta \boldsymbol{E} \tag{3.3}
\end{equation*}
$$

Equation (3.3) describes a balance between the change of stored electromagnetic field energy and work done by the electric field on the plasma.

### 3.2. Conductivity tensor

The conductivity tensor relates the perturbed current $\delta \boldsymbol{j}$ to the perturbed electric field $\delta \boldsymbol{E}$. This is a linear relation. The analytic construction of the conductivity tensor typically begins with the assumption that the unperturbed system is stationary, but there are notable exceptions, e.g. when there are slowly varying background fields as in the solar wind and the ionosphere, or when there are rapidly oscillatory finite-amplitude fields as in laser-plasma interactions. As in the development of the dielectric response in $\S 2.5$, we begin by employing causality and writing down the general expression

$$
\begin{equation*}
\delta \boldsymbol{j}(r, t)=\int_{0}^{\infty} \mathrm{d} \tau \int \mathrm{~d}^{3} \boldsymbol{r}^{\prime} \stackrel{\leftrightarrow}{\sigma}\left(\boldsymbol{r} ; \boldsymbol{r}^{\prime} ; \tau\right) \cdot \delta \boldsymbol{E}\left(\boldsymbol{r}^{\prime}, t-\tau\right) \tag{3.4}
\end{equation*}
$$

Next we assume that perturbed electric field can be represented as a superposition of normal modes,

$$
\begin{equation*}
\delta \boldsymbol{E}(\boldsymbol{r}, t)=\sum_{\ell} \exp \left(-\mathrm{i} \omega_{\ell} t\right) \boldsymbol{E}_{\ell}(\boldsymbol{r}, t) \tag{3.5}
\end{equation*}
$$

where $\omega_{\ell}$ is real, $\boldsymbol{E}_{\ell}$ is slowly varying in time, $\omega_{-\ell}=-\omega_{\ell}$ and $\boldsymbol{E}_{-\ell}=-\boldsymbol{E}_{\ell}$. Use of (3.5) in (3.4) yields

$$
\begin{align*}
\delta \boldsymbol{j}(r, t)= & \sum_{\ell} \exp \left(-\mathrm{i} \omega_{\ell} t\right) \int_{0}^{\infty} \mathrm{d} \tau \int \mathrm{~d}^{3} \boldsymbol{r}^{\prime} \stackrel{\leftrightarrow}{\sigma}\left(\boldsymbol{r} ; \boldsymbol{r}^{\prime} ; \tau\right) \cdot \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime}, t-\tau\right) \exp \left(\mathrm{i} \omega_{\ell} \tau\right) \\
= & \sum_{\ell} \exp \left(-\mathrm{i} \omega_{\ell} t\right) \int_{0}^{\infty} \mathrm{d} \tau \int \mathrm{~d}^{3} \boldsymbol{r}^{\prime} \stackrel{\leftrightarrow}{\sigma}\left(\boldsymbol{r} ; \boldsymbol{r}^{\prime} ; \tau\right) \\
& \cdot\left[\boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime}, t\right)-\tau \frac{\partial}{\partial t} \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime}, t\right)+O\left(\tau^{2} \ddot{\boldsymbol{E}}_{\ell}\right)\right] \exp \left(\mathrm{i} \omega_{\ell} \tau\right) \\
= & \sum_{\ell} \exp \left(-\mathrm{i} \omega_{\ell} t\right) \int \mathrm{d}^{3} \boldsymbol{r}^{\prime} \\
& \times\left[\stackrel{\leftrightarrow}{\sigma}\left(\boldsymbol{r} ; \boldsymbol{r}^{\prime} ; \omega_{\ell}\right) \cdot \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime}, t\right)+\left.\mathrm{i} \frac{\partial \stackrel{\sigma}{\sigma}\left(\boldsymbol{r} ; \boldsymbol{r}^{\prime} ; \omega\right)}{\partial \omega}\right|_{\omega_{\ell}} \cdot \frac{\partial}{\partial t} \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime}, t\right)+\cdots\right] \tag{3.6}
\end{align*}
$$

where we have made use of the following definition and identity.
Definition. The Fourier transformed conductivity tensor is given by

$$
\stackrel{\leftrightarrow}{\sigma}\left(\boldsymbol{r}, \boldsymbol{r}^{\prime} ; \omega\right)=\int_{0}^{\infty} \mathrm{d} \tau \overleftrightarrow{\sigma}\left(\boldsymbol{r}, \boldsymbol{r}^{\prime} ; \tau\right) \exp (\mathrm{i} \omega \tau) \quad \text { with } \stackrel{\leftrightarrow}{\sigma}\left(\boldsymbol{r}, \boldsymbol{r}^{\prime} ; \tau<0\right)=0
$$

ThEOREM.

$$
(\partial / \partial \omega) F_{\tau \rightarrow \omega}(g(\tau))=F_{\tau \rightarrow \omega}(\mathrm{i} \tau g(\tau))
$$

where $F_{\tau \rightarrow \omega}(g(\tau))$ is the Fourier transform from $\tau$ to $\omega$.
The conductivity is a three-dimensional tensor and a kernel, but it is not Hermitian in general. One can decompose any tensor into Hermitian and anti-Hermitian parts,

## THEOREM.

$$
\boldsymbol{A}=\boldsymbol{A}^{\iota}+\mathrm{i} \boldsymbol{A}^{u} \quad A_{\mu \nu}^{\iota}=\frac{1}{2}\left(A_{\mu \nu}+A_{\mu \nu}^{*}\right) A_{\mu \nu}^{\iota}=\left(A_{\nu \mu}^{\iota}\right)^{*} \quad A_{\mu \nu}^{u}=\left(A_{\nu \mu}^{u}\right)^{*}
$$

For real $\omega, \sigma_{\mu \nu}^{\iota}\left(\boldsymbol{r}, \boldsymbol{r}^{\prime} ; \omega\right) \equiv \frac{1}{2}\left(\sigma_{\mu \nu}\left(\boldsymbol{r}, \boldsymbol{r}^{\prime} ; \omega\right)+\sigma_{\nu \mu}\left(\boldsymbol{r}^{\prime}, \boldsymbol{r} ; \omega\right)\right)$.
Use of (3.6) in (3.3) yields

$$
\begin{align*}
\frac{\mathrm{d}}{\mathrm{~d} t} \int \mathrm{~d}^{3} \boldsymbol{r} \frac{|\delta \boldsymbol{E}|^{2}+|\delta \boldsymbol{B}|^{2}}{8 \pi}= & -\int \mathrm{d}^{3} \boldsymbol{r} \delta \boldsymbol{j} \cdot \delta \boldsymbol{E} \\
= & -\int \mathrm{d}^{3} \boldsymbol{r} \int \mathrm{~d}^{3} \boldsymbol{r}^{\prime} \sum_{\ell} \exp \left(\mathrm{i} \omega_{\ell} t\right) \boldsymbol{E}_{\ell}^{*}(\boldsymbol{r}, t) \cdot \sum_{\ell^{\prime}} \exp \left(-\mathrm{i} \omega_{\ell^{\prime}} t\right) \\
& \times\left[\stackrel{\leftrightarrow}{\sigma}\left(\boldsymbol{r} ; \boldsymbol{r}^{\prime} ; \omega_{\ell^{\prime}}\right) \cdot \boldsymbol{E}_{\ell^{\prime}}\left(\boldsymbol{r}^{\prime}, t\right)+\left.\mathrm{i} \frac{\partial \stackrel{\rightharpoonup}{\sigma}\left(\boldsymbol{r} ; \boldsymbol{r}^{\prime} ; \omega\right)}{\partial \omega}\right|_{\omega_{\ell^{\prime}}} \cdot \frac{\partial}{\partial t} \boldsymbol{E}_{\ell^{\prime}}\left(\boldsymbol{r}^{\prime}, t\right)\right] \tag{3.7}
\end{align*}
$$

If we perform a coarse-grain time average of (3.7), i.e. we average over the characteristic time scales $\sim 1 / \omega_{\ell}$, but retain the slow time scale variations, and make use of

$$
\left\langle\exp \left(-\mathrm{i}\left(\omega_{\ell}-\omega_{\ell^{\prime}}\right) t\right)\right\rangle=\delta_{\ell \ell^{\prime}}
$$

we can delete the sum over $\ell^{\prime}$ and set $\ell=\ell^{\prime}$. Thus, (3.7) simplifies to

$$
\begin{align*}
\frac{\mathrm{d}}{\mathrm{~d} t} \int \mathrm{~d}^{3} \boldsymbol{r} \frac{|\delta \boldsymbol{E}|^{2}+|\delta \boldsymbol{B}|^{2}}{8 \pi}= & -\int \mathrm{d}^{3} \boldsymbol{r} \delta \boldsymbol{j} \cdot \delta \boldsymbol{E} \\
= & -\int \mathrm{d}^{3} \boldsymbol{r} \int \mathrm{~d}^{3} \boldsymbol{r}^{\prime} \sum_{\ell} \boldsymbol{E}_{\ell}^{*}(\boldsymbol{r}, t) \\
& \cdot\left[\stackrel{\leftrightarrow}{\sigma}\left(r, r^{\prime} ; \omega_{\ell}\right) \cdot \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime} ; t\right)+\left.\mathrm{i} \frac{\partial \stackrel{\sigma}{\sigma}\left(\boldsymbol{r} ; \boldsymbol{r}^{\prime} ; \omega\right)}{\partial \omega}\right|_{\omega \ell} \cdot \frac{\partial}{\partial t} \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime}, t\right)\right] \\
= & -\int \mathrm{d}^{3} \boldsymbol{r} \int \mathrm{~d}^{3} \boldsymbol{r}^{\prime} \sum_{\ell} \boldsymbol{E}_{\ell}^{*}(\boldsymbol{r}, t) \\
& \cdot\left[\stackrel{\rightharpoonup}{\sigma}_{R}\left(r, r^{\prime} ; \omega_{\ell}\right) \cdot \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime} ; t\right)-\left.\frac{\partial \overleftrightarrow{\sigma}_{I}\left(\boldsymbol{r} ; \boldsymbol{r}^{\prime} ; \omega\right)}{\partial \omega}\right|_{\omega_{\ell}} \cdot \frac{\partial}{\partial t} \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime}, t\right)\right] \\
= & -\int \mathrm{d}^{3} \boldsymbol{r} \int \mathrm{~d}^{3} \boldsymbol{r}^{\prime} \sum_{\ell} \boldsymbol{E}_{\ell}^{*}(\boldsymbol{r}, t) \cdot \stackrel{\sigma}{\sigma}_{R}\left(r, r^{\prime} ; \omega_{\ell}\right) \cdot \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime} ; t\right) \\
& +\left.\frac{1}{2} \frac{\mathrm{~d}}{\mathrm{~d} t} \int \mathrm{~d}^{3} \boldsymbol{r} \int \mathrm{~d}^{3} \boldsymbol{r}^{\prime} \sum_{\ell} \boldsymbol{E}_{\ell}^{*}(\boldsymbol{r}, t) \cdot \frac{\partial \overleftrightarrow{\sigma}_{I}\left(\boldsymbol{r} ; \boldsymbol{r}^{\prime} ; \omega\right)}{\partial \omega}\right|_{\omega_{\ell}} \cdot \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime}, t\right), \tag{3.8}
\end{align*}
$$

where $\sigma=\sigma_{R}+\mathrm{i} \sigma_{I}$.
EXERCISE. Prove (3.8) using the hermiticity of $\sigma_{R}$ and $\sigma_{I}$, and the right-hand side of (3.8) is necessarily real.

### 3.3. Energy conservation

THEOREM. Equation (3.8) can be rewritten in the form that expresses energy conservation between the electromagnetic field energy and the plasma

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} \sum_{\ell} U_{\ell}(t)=-\sum_{\ell} Q_{\ell} \rightarrow \frac{\mathrm{d}}{\mathrm{~d} t} U_{\ell}(t)=-Q_{\ell} \tag{3.9}
\end{equation*}
$$

using mode by mode equivalence. Equation (3.8) becomes

$$
\begin{align*}
& \frac{\mathrm{d}}{\mathrm{~d} t}\left[\int \mathrm{~d}^{3} \boldsymbol{r} \sum_{\ell} \frac{\left|\boldsymbol{E}_{\ell}\right|^{2}+\left|\boldsymbol{B}_{\ell}\right|^{2}}{8 \pi}-\left.\frac{1}{2} \int \mathrm{~d}^{3} \boldsymbol{r} \int \mathrm{~d}^{3} \boldsymbol{r}^{\prime} \sum_{\ell} \boldsymbol{E}_{\ell}^{*}(\boldsymbol{r}, t) \cdot \frac{\partial \overleftrightarrow{\sigma}_{I}\left(\boldsymbol{r} ; \boldsymbol{r}^{\prime} ; \omega\right)}{\partial \omega}\right|_{\omega_{\ell}} \cdot \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime}, t\right)\right] \\
& \quad=-\int \mathrm{d}^{3} \boldsymbol{r} \int \mathrm{~d}^{3} \boldsymbol{r}^{\prime} \sum_{\ell} \boldsymbol{E}_{\ell}^{*}(\boldsymbol{r}, t) \cdot \stackrel{\leftrightarrow}{\sigma}_{R}\left(r, r^{\prime} ; \omega_{\ell}\right) \cdot \boldsymbol{E}_{\ell}\left(\boldsymbol{r}^{\prime} ; t\right) \tag{3.10}
\end{align*}
$$

and the equality also holds in a mode by mode sense. The left-hand side of (3.10) is the time derivative of the stored energy summed over the electromagnetic field energy and the plasma kinetic sloshing energy in the waves. The right-hand side of (3.10) is the rate of energy lost or gained due to resistive effects (loss in stable plasma). The imaginary part of the conductivity $\sigma_{I}$ is the reactive component, and the real part $\sigma_{R}$ is the resistive component.

THEOREM. In a uniform medium (3.9) and (3.10) can be Fourier transformed to $\boldsymbol{k}$ space

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \sum_{\ell} U_{\ell}(\boldsymbol{k}, t)=-\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \sum_{\ell} Q_{\ell}(\boldsymbol{k}, t), \tag{3.11a}
\end{equation*}
$$

where

$$
\begin{gather*}
U_{\ell}(\boldsymbol{k}, t)=\frac{\left|\boldsymbol{E}_{\ell}\right|^{2}+\left|\boldsymbol{B}_{\ell}\right|^{2}}{8 \pi}-\left.\boldsymbol{E}_{\ell}^{*}(\boldsymbol{k}, t) \cdot \frac{\partial \stackrel{\rightharpoonup}{\sigma}_{I}(\boldsymbol{k} ; \omega)}{2 \partial \omega}\right|_{\omega_{\ell}(\boldsymbol{k})} \cdot \boldsymbol{E}_{\ell}(\boldsymbol{k}, t) \\
Q_{\ell}(\boldsymbol{k}, t)=\boldsymbol{E}_{\ell}^{*}(\boldsymbol{k}, t) \cdot \stackrel{\sigma}{\sigma}_{R}\left(\boldsymbol{k} ; \omega_{\ell}(\boldsymbol{k})\right) \cdot \boldsymbol{E}_{\ell}(\boldsymbol{k}, t) . \tag{3.11b}
\end{gather*}
$$

$U_{\ell}(\boldsymbol{k}, t)$ is the wave energy, which can be positive or negative depending on the particle energy contribution; $Q_{\ell}(\boldsymbol{k}, t)$ can be positive or negative.

The continuity equation (2.29) relates the charge density and the current, while the charge density and the electric field are related in (2.43). The susceptibility $\chi(\boldsymbol{k}, \omega)$ is related to the dielectric function $\varepsilon(\boldsymbol{k}, \omega)$ in (2.54). Using these relations the dielectric function and the conductivity are related as follows:

$$
\begin{align*}
\stackrel{\leftrightarrow}{\varepsilon}(\boldsymbol{k}, \omega) & =\stackrel{\leftrightarrow}{\boldsymbol{I}}+\mathrm{i} \frac{4 \pi}{\omega} \stackrel{\leftrightarrow}{\sigma}(\boldsymbol{k}, \omega)=\stackrel{\leftrightarrow}{\varepsilon}_{R}+\mathrm{i} \stackrel{\leftrightarrow}{\varepsilon}_{I}=\stackrel{\leftrightarrow}{\boldsymbol{I}}+\mathrm{i} \frac{4 \pi}{\omega}\left(\overleftrightarrow{\sigma}_{R}+\mathrm{i} \stackrel{\leftrightarrow}{\sigma}_{I}\right) \\
\stackrel{\leftrightarrow}{\varepsilon}_{R} & =\stackrel{\leftrightarrow}{\boldsymbol{I}}-\frac{4 \pi}{\omega} \stackrel{\leftrightarrow}{\sigma}_{I} \quad \overleftrightarrow{\varepsilon}_{I}=\frac{4 \pi}{\omega} \overleftrightarrow{\sigma}_{R} \quad \frac{\partial}{\partial \omega}\left(\omega \overleftrightarrow{\varepsilon}_{R}\right)=\stackrel{\leftrightarrow}{\boldsymbol{I}}-4 \pi \frac{\partial}{\partial \omega} \stackrel{\leftrightarrow}{\sigma}^{\prime \prime} \tag{3.12}
\end{align*}
$$

THEOREM. Equations (3.11) and (3.12) can be combined to yield the following alternative form for $U_{\ell}(\boldsymbol{k}, t)$ in terms of the real part of $\varepsilon(\boldsymbol{k}, \omega)$,

$$
\begin{equation*}
U_{\ell}(\boldsymbol{k}, t)=\frac{\left|\boldsymbol{B}_{\ell}\right|^{2}}{8 \pi}+\frac{\left.\boldsymbol{E}_{\ell}^{*}(\boldsymbol{k}, t) \cdot \frac{\partial}{\partial \omega}\left(\omega \stackrel{\leftrightarrow}{\varepsilon}_{R}(\boldsymbol{k} ; \omega)\right)\right|_{\omega_{\ell}(\boldsymbol{k})} \cdot \boldsymbol{E}_{\ell}(\boldsymbol{k}, t)}{8 \pi} \tag{3.13}
\end{equation*}
$$

3.4. Coulomb model examples - cold plasma, Vlasov plasma, beam in hot plasma

In this section we simplify the analysis to the Coulomb model and analyse a few examples. In a Coulomb model the waves are longitudinal, i.e. the electric field is given by the gradient of a scalar potential,

$$
\begin{gather*}
\boldsymbol{E}=-\nabla \phi \quad \boldsymbol{E}(\boldsymbol{k}, \omega)=-\mathrm{i} \boldsymbol{k} \phi(\boldsymbol{k}, \omega) \quad \nabla \times \boldsymbol{E}=0 \\
U_{\ell}(\boldsymbol{k}, t)=\left.\frac{k^{2}}{8 \pi} \frac{\partial}{\partial \omega}\left(\omega \hat{\boldsymbol{k}} \cdot \stackrel{\leftrightarrow}{\varepsilon}_{R}(\boldsymbol{k} ; \omega) \cdot \hat{\boldsymbol{k}}\right)\right|_{\omega_{\ell}(\boldsymbol{k})}\left|\phi_{\ell}(\boldsymbol{k}, t)\right|^{2} . \tag{3.14}
\end{gather*}
$$

DEFINITION. $k^{2} \varepsilon^{L}(\boldsymbol{k}, \omega) \equiv \boldsymbol{k} \cdot \stackrel{\leftrightarrow}{\varepsilon} \cdot \boldsymbol{k}$.
EXERCISE. Prove $\varepsilon^{L}$ is equivalent to $\varepsilon(\boldsymbol{k}, \omega)$ in $\S 2.5$
Corollary.

$$
\begin{equation*}
U_{\ell}(\boldsymbol{k}, t)=\left.\frac{k^{2}\left|\phi_{\ell}(\boldsymbol{k}, t)\right|^{2}}{8 \pi} \frac{\partial}{\partial \omega}\left(\omega \varepsilon_{R}\right)\right|_{\omega_{\ell}(\boldsymbol{k})} \quad Q_{\ell}(\boldsymbol{k}, t)=\frac{\omega k^{2}\left|\phi_{\ell}(\boldsymbol{k}, t)\right|^{2}}{8 \pi} \varepsilon_{I}\left(\boldsymbol{k} ; \omega_{\ell}(\boldsymbol{k})\right) . \tag{3.15}
\end{equation*}
$$

THEOREM. For $U_{\ell} \propto \exp \left(2 \gamma_{\ell}(\boldsymbol{k}) t\right)$ then $\gamma_{\ell}(\boldsymbol{k})$ is determined by the ratio of the dissipation to the wave energy

$$
\begin{equation*}
\gamma_{\ell}(\boldsymbol{k})=-\frac{1}{2} \frac{Q_{\ell}(\boldsymbol{k})}{U_{\ell}(\boldsymbol{k})}=-\frac{\omega \varepsilon_{I}}{\frac{\partial}{\partial \omega}\left(\omega \varepsilon_{R}\right)}=-\frac{\varepsilon_{I}}{\frac{\partial \varepsilon_{R}}{\partial \omega}}, \quad \varepsilon_{R}\left(\omega_{\ell}(\boldsymbol{k})\right)=0 . \tag{3.16}
\end{equation*}
$$

EXAmple. In a Vlasov plasma $\varepsilon_{R}(\boldsymbol{k}, \omega)=1-\omega_{p}^{2} / k^{2} Z^{\prime}(v) \equiv 1-F(v) / k^{2}, v \equiv \omega / k$. The eigenfrequencies are determined by $\varepsilon_{R}=0$, i.e. $F(v)=k^{2}$ introduced in (2.72). We also have the following useful relations:

$$
\begin{gather*}
\frac{\partial \varepsilon_{R}}{\partial \omega}=-\frac{1}{k^{3}} \frac{\mathrm{~d} F}{\mathrm{~d} v} \quad \frac{\mathrm{~d} F}{\mathrm{~d} v}=2 k \frac{\mathrm{~d} k}{\mathrm{~d} v} \quad \frac{\partial \varepsilon_{R}}{\partial \omega}=-\frac{2}{k^{2}}\left(\frac{\mathrm{~d} v}{\mathrm{~d} k}\right)^{-1} \\
\gamma=\frac{-\varepsilon_{I}}{\frac{\partial \varepsilon_{R}}{\partial \omega}}=-\frac{\pi}{2} \omega_{p}^{2} g^{\prime}(v) \frac{\mathrm{d} v}{\mathrm{~d} k} \quad \frac{\mathrm{~d} v}{\mathrm{~d} k}=\frac{1}{k}\left(v_{g}-v\right) \quad v_{g} \equiv \frac{\mathrm{~d} \omega}{\mathrm{~d} k} . \tag{3.17}
\end{gather*}
$$

THEOREM. Examination of (3.14)-(3.17) shows that the wave energy $U_{\ell}$ and the growth/damping rate $\gamma$ are independent of reference frame under Galilean transformation ( $v_{g}-v$ is invariant under Galilean transformation).

Usually $v_{g}<v$, which is referred to as normal dispersion, and then $\partial \epsilon_{R} / \partial \omega>0$ so that the wave energy is positive. When $\partial \epsilon_{R} / \partial \omega<0$ the wave energy is negative. We next summarize some results for a few examples.

EXAMPLES. (i) Electron plasma wave (Langmuir wave): $\omega \partial \epsilon_{R} / \partial \omega=2$ and, hence, $U=2|\boldsymbol{E}|^{2} / 8 \pi$. Energy is partitioned equally between the field energy and the plasma kinetic sloshing energy.
(ii) Ion-acoustic wave: $\omega\left(\partial \epsilon_{R} / \partial \omega\right)=2\left(1+1 / k^{2} \lambda_{e}^{2}\right) \rightarrow \infty$ for $k^{2} \lambda_{e}^{2} \rightarrow 0$. The electrons and ions are in phase with one another, and the plasma kinetic sloshing energy is much larger than the field energy.
(iii) Cold beam: $\epsilon=1-\omega_{b}^{2} /\left(\omega-k u_{b}\right)^{2}$ and $\omega\left(\partial \epsilon_{R} / \partial \omega\right)= \pm 2 k u_{b} / \omega_{b}$. The two branches of the dispersion relation are the fast wave (positive energy wave) and the slow wave (negative energy wave).
(iv) Beam through a hot plasma: $\epsilon=1-\left(\omega_{p}^{2} / k^{2}\right) Z^{\prime}(v)-\omega_{b}^{2} /\left(\omega-k u_{b}\right)^{2}$. For $k u_{b} \gg$ $\omega_{p}$, there are fast and slow beam modes with approximate eigenfrequencies $\omega=$ $k u_{b} \pm \omega_{b}$ and $v=u_{b} \pm \omega_{b} / k$. The beam component is a $\delta$-function in velocity, while the plasma component is a Maxwellian centred at zero velocity. The slope of the velocity distribution for the plasma component is negative at $u_{b} \pm \omega_{b} / k$ and the resonant particles damp the fast wave. However, the wave energy for the slow mode is negative; and the resonant particles destabilize the slow mode in consequence of (3.17). The dissipation $\varepsilon_{I}$ is positive for both the fast and slow modes, but dissipation further decreases the wave energy for negative energy waves which increases the magnitude of the slow-wave amplitude.

### 3.5. Penrose criterion for instability and examples

We note that $F(V)=k^{2}$ in (2.72) generalized to (2.90) depends on the principal value integral of $g^{\prime}$; and the expression for $\gamma$ in (3.17) depends directly on $g^{\prime}(v)$,

$$
\begin{align*}
\varepsilon(\boldsymbol{k}, \omega) & =0 \rightarrow k^{2}=\omega_{p}^{2} Z^{\prime}(V) \equiv F(V)=\omega_{p}^{2} \int \mathrm{~d} u \frac{g^{\prime}(u)}{u-V}, \quad \operatorname{Im} V>0 \\
\gamma(\boldsymbol{k}) & =-\frac{\pi}{2} \omega_{p}^{2} \frac{\mathrm{~d} V}{\mathrm{~d} k} g^{\prime}(V) . \tag{3.18}
\end{align*}
$$

We have analysed the stability of several examples of Vlasov plasmas in the Coulomb model, e.g. two stream, plasma beam, beam and plasma, bump-on-tail and Maxwellian plasmas. Can we look at $g(u)$ and decide whether there is instability? Penrose answered this question in the affirmative (Penrose 1960).

THEOREM. (Penrose criterion) The condition for instability is that as one varies $k$, for some real $k>0, \operatorname{Im}(\omega / k)>0$.

Examine (3.18) in the complex V plane. We are looking for unstable solutions for the complex phase velocity $V$ as a function of $k^{2}$ with $\operatorname{Im} V>0$. For $\operatorname{Im} V>0, F$ in (3.18) is well behaved and cannot go to infinity for any value of $k^{2}$. As $k^{2} \rightarrow \infty$, there are no roots for $\operatorname{Im} V>0$, i.e. there are no unstable roots for $k= \pm \infty$; and $F$ goes to zero for $k= \pm \infty$. Now consider solutions of (3.18) for $V$ with finite $k$ where $V$ crosses the real $V$ axis from below as we vary $k$. Label the point as $k_{0}$ where $\gamma_{0}\left(k_{0}\right)=0$, which implies $g^{\prime}=0$ from (3.18). Consider a positive energy wave $\mathrm{d} V / \mathrm{d} k<0$. As $k$ decreases differentially from $k_{0}, V$ increases differentially from its finite value at $k_{0}$; and $\gamma$ transitions from $\gamma<0$ to $\gamma=0$, i.e. $\mathrm{d} \gamma / \mathrm{d} k<0$ at $k_{0}$ is required for instability. In consequence of $\mathrm{d} \gamma / \mathrm{d} k<0$ and (3.18), $g^{\prime}$ must increase and become positive as $k$ is reduced below $k_{0}$ to support instability, which requires that $g^{\prime \prime}>0$ where $g^{\prime}=0$ at $k_{0}$, i.e. $g$ must have a minimum with respect to $V$. For a negative energy wave $\mathrm{d} V / \mathrm{d} k>0$, and $V$ decreases differentially from its finite value at $k_{0}$ as $k$ is reduced below $k_{0}$. However, $\mathrm{d} \gamma / \mathrm{d} k \propto-(\mathrm{d} V / \mathrm{d} k)^{2} g^{\prime \prime}$ remains negative if $g^{\prime \prime}>0$, as required for instability. We note that with $\mathrm{d} \gamma / \mathrm{d} k<0$ for either sign of $\mathrm{d} V / \mathrm{d} k$, a differential increase in $k$ from $k_{0}$ leads to $\gamma<0$.

THEOREM. A necessary condition for instability is a minimum in $g(u)$. Penrose shows sufficiency as well if (i) $g^{\prime}=0$, (ii) $g^{\prime \prime}>0$ and (iii) $\int \mathrm{d} u g^{\prime}(u) /(u-V)>0$. The implication of this is that a weak minimum may not be unstable, but a deep minimum probably will be unstable.
[Editor's note: there are good discussions of the Penrose criterion in textbooks such as in § 9.6 of Nicholas A. Krall and Alvin W. Trivelpiece, Principles of Plasma Physics, McGrawHill, 1973, and in § 5.3 of P. M. Bellan, Fundamentals of Plasma Physics, Cambridge University Press, 2008 where a nice mathematical argument is given making use of Nyquist's theorem.]

Examples. (i) A single-hump velocity distribution is always stable.
(ii) A double Cauchy beam (§ 2.8) can be unstable if the beam velocity $u_{0}$ exceeds the thermal spread $v_{\text {th }}$.
(iii) Several cold beams are always unstable.
(iv) A cold beam in a hot plasma is unstable.


Figure 13. Hot electron and ion velocity distributions with a relative drift $u_{d}$.
(v) An isotropic single-hump distribution of speed is stable. Some spherical shell distributions of speed are stable.
(vi) Electrons and ions with a finite-temperature Maxwellian velocity distribution and a relative drift between the species can be unstable if the relative drift is sufficiently large (ion-acoustic instability).

EXAMPLE. The velocity distributions for the ion-acoustic instability are diagrammed in figure 13. The electrons have a finite temperature $T_{e}$, and the ion temperature is $T_{i}$. The singly charged ions have a drift $u_{d}$ relative to the electrons. In order to have a minimum in the composite distribution $g(u), g(u)=\sum_{s} \omega_{s}^{2} g_{s}(u) / \sum_{s} \omega_{s}^{2}$, there is some minimum value of $u_{d}$. The condition $\int \mathrm{d} u g^{\prime}(u) /(u-V)>0$ requires an even larger value of $u_{d}$, which we define as $u_{d, \text { crit }}$ which is a function of $T_{e}, T_{i}$ and $m_{e} / m_{i}$. Calculations published by Bernstein and Kulsrud (Bernstein \& Kulsrud 1960) and Fried and Gould (Fried \& Gould 1961) obtained the following results:

$$
\begin{equation*}
\frac{u_{d, \text { crit }}}{V_{i}} \approx\left\{4 \text { for } \frac{T_{e}}{T_{i}} \geqslant 20,\left(\frac{T_{e}}{2 T_{i}}\right)^{1 / 2}\left[1+\sqrt{\frac{m_{i}}{m_{e}}}\left(\frac{T_{e}}{T_{i}}\right) \exp \left(\frac{T_{e}}{2 T_{i}}\right)\right] \text { for } 1 \leqslant \frac{T_{e}}{T_{i}} \leqslant 20\right\} . \tag{3.19}
\end{equation*}
$$

$u_{d, \text { crit }} / V_{i}$ as a function of $T_{i} / T_{e}$ steadily increases from a value equal to 4 for $T_{i} / T_{e}=0$ with $u_{d, \text { crit }}$ saturating at a value $O\left(v_{e}\right)$ for $T_{i} / T_{e}=O(1)$, and the instability evolves into a warm two-stream instability.

### 3.6. Wave momentum

In §3.1 a Poynting theorem was derived that describes the dynamics of field and plasma energy exchange. Here we examine the exchange of momentum between fields and plasma. The starting point is (2.32) summed over species, which we then coarsegrain time average over high frequencies having decomposed all fluid quantities and fields in a linear superposition of modes as in (3.5). Only bilinear terms survive the averaging, and we determine that the irreversible momentum transfer from waves to plasma per unit time and per volume is given by

$$
\begin{align*}
\langle\delta \rho \delta \boldsymbol{E}\rangle+\frac{1}{c}\langle\delta \boldsymbol{j} \times \delta \boldsymbol{B}\rangle & =\langle\delta \rho \delta \boldsymbol{E}\rangle+\left\langle\frac{1}{\omega} \delta \boldsymbol{j} \times(\boldsymbol{k} \times \delta \boldsymbol{E})\right\rangle \\
& =\langle\delta \rho \delta \boldsymbol{E}\rangle+\left\langle\frac{1}{\omega} \boldsymbol{k}(\delta \boldsymbol{j} \cdot \delta \boldsymbol{E})-\frac{1}{\omega} \delta \boldsymbol{E}(\boldsymbol{k} \cdot \delta \boldsymbol{j})\right\rangle \\
& =\langle\delta \rho \delta \boldsymbol{E}\rangle+\left\langle\frac{1}{\omega} \boldsymbol{k}(\delta \boldsymbol{j} \cdot \delta \boldsymbol{E})-\frac{1}{\omega} \delta \boldsymbol{E}(\omega \delta \rho)\right\rangle \\
& =\frac{\boldsymbol{k}}{\omega}\langle\delta \boldsymbol{j} \cdot \delta \boldsymbol{E}\rangle \tag{3.20}
\end{align*}
$$

in a mode by mode sense, and we have made use of Faraday's law $\mathrm{i} \omega \delta \boldsymbol{B}=-c \mathrm{i} \boldsymbol{k} \times \delta \boldsymbol{E}$ and the continuity equation $-\mathrm{i} \omega \delta \rho=-\mathrm{i} \boldsymbol{k} \cdot \delta \boldsymbol{j}$.

THEOREM. The irreversible momentum transfer from waves to the plasma is given by $\boldsymbol{k} / \omega$ times the irreversible energy transfer (Dewar 1970), i.e.

$$
\begin{equation*}
\frac{\boldsymbol{g}_{\text {wave }}}{U_{\text {wave }}}=\frac{\boldsymbol{k}}{\omega} \rightarrow \frac{\mathrm{d}}{\mathrm{~d} t} \boldsymbol{g}_{\text {wave }}=\frac{\boldsymbol{k}}{\omega} \frac{\mathrm{d}}{\mathrm{~d} t} U_{\mathrm{wave}} \tag{3.21}
\end{equation*}
$$

There is an analogy here to quantum mechanics wherein $U=N \hbar \omega$ and $\boldsymbol{g}=N \hbar \boldsymbol{k}$.
THEOREM. ( $U_{\text {wave }}, \boldsymbol{g}_{\text {wave }}$ ) are related as $(E, \boldsymbol{p})$, i.e. these are four-vectors. Thus, if we consider a transformation to a reference frame translating with relative velocity $\boldsymbol{w}$, then $\omega^{(1)}=\omega^{(0)}-\boldsymbol{k} \cdot \boldsymbol{w}, U_{\text {wave }}^{(1)}=U_{\text {wave }}^{(0)}-\boldsymbol{w} \cdot \boldsymbol{g}$, and $(\omega(\partial \epsilon / \partial \omega))^{(1)}=(\omega(\partial \epsilon / \partial \omega))^{(0)}(1-$ $\left.\left(\boldsymbol{k} \cdot \boldsymbol{w} / \omega^{(0)}\right)\right)$, where the dielectric function $\varepsilon$ is an invariant scalar.

## 4. Magnetic fields

In this section we examine the solution of the Vlasov-Maxwell system including both externally applied magnetic fields and perturbed magnetic fields associated with electromagnetic waves.

### 4.1. Response tensor for Vlasov-Maxwell system and general dispersion relation

We Fourier transform Faraday's law and Ampere's equations in space and time to obtain the following relations:

$$
\begin{align*}
& \text { Faraday's law: } \frac{\partial \delta \boldsymbol{B}}{\partial t}=-c \boldsymbol{\nabla} \times \partial \boldsymbol{E} \rightarrow-\mathrm{i} \omega \delta \boldsymbol{B}=-\mathrm{i} c \boldsymbol{k} \times \delta \boldsymbol{E} \rightarrow \\
& \qquad \delta \boldsymbol{B}(\boldsymbol{k}, \omega)=\boldsymbol{n} \times \delta \boldsymbol{E}(\boldsymbol{k}, \omega) \boldsymbol{n} \equiv \frac{\boldsymbol{k} c}{\omega} \\
& \text { Ampere's law: } \boldsymbol{\nabla} \times \delta \boldsymbol{B}-\frac{1}{c} \frac{\partial \delta \boldsymbol{E}}{\partial t}=\frac{4 \pi}{c}\left(\delta \boldsymbol{j}+\delta \boldsymbol{j}^{\mathrm{ext}}\right) \rightarrow \\
& \quad \mathrm{i} \boldsymbol{k} \times \delta \boldsymbol{B}+\frac{\mathrm{i} \omega}{c} \delta \boldsymbol{E}=\frac{4 \pi}{c}\left(\delta \boldsymbol{j}+\delta \boldsymbol{j}^{\mathrm{ext}}\right)=\frac{4 \pi}{c}\left(\stackrel{\leftrightarrow}{\sigma}(\boldsymbol{k}, \omega) \cdot \delta \boldsymbol{E}+\delta \boldsymbol{j}^{\mathrm{ext}}\right) . \tag{4.1}
\end{align*}
$$

THEOREM. From Faraday's law the transverse (divergence-free) component of the linearized electric field $\delta \boldsymbol{E}^{\mathrm{T}}$ satisfies $\delta \boldsymbol{E}^{\mathrm{T}}=-(1 / c) \boldsymbol{V} \times \delta \boldsymbol{B}$ where $\boldsymbol{V} \equiv \hat{\boldsymbol{k}} \omega / k$ is the wave phase velocity. For slow waves $V / c \ll 1$, the transverse waves are mostly magnetic, $|\delta \boldsymbol{B}| /|\delta \boldsymbol{E}| \gg 1$.

THEOREM.

$$
\begin{align*}
\mathrm{i} \boldsymbol{k} & \times(\boldsymbol{n} \times \delta \boldsymbol{E})+\frac{\mathrm{i} \omega}{c}\left[\stackrel{\leftrightarrow}{\boldsymbol{I}}+\frac{4 \pi}{-\mathrm{i} \omega} \stackrel{\leftrightarrow}{\sigma}(k, \omega)\right] \cdot \delta \boldsymbol{E} \\
& =\mathrm{i} \boldsymbol{k} \times(\boldsymbol{n} \times \delta \boldsymbol{E})+\frac{\mathrm{i} \omega}{c} \stackrel{\leftrightarrow}{\varepsilon}(k, \omega) \cdot \delta \boldsymbol{E}=\frac{4 \pi}{c} \delta \boldsymbol{j}^{\mathrm{ext}} \\
& \rightarrow \stackrel{\leftrightarrow}{\varepsilon}(k, \omega) \cdot \delta \boldsymbol{E}+\boldsymbol{n} \times(\boldsymbol{n} \times \delta \boldsymbol{E})=\frac{4 \pi}{\mathrm{i} \omega} \delta \boldsymbol{j}^{\mathrm{ext}} \\
& \rightarrow\left[\stackrel{\leftrightarrow}{\varepsilon}(k, \omega)-n^{2}(\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{k}} \hat{\boldsymbol{k}})\right] \cdot \delta \boldsymbol{E}=\frac{4 \pi}{\mathrm{i} \omega} \delta \boldsymbol{j}^{\mathrm{ext}} . \tag{4.2}
\end{align*}
$$

DEFInITION. $\stackrel{\boldsymbol{I}}{ }^{T} \equiv \stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{k}} \hat{\boldsymbol{k}}$ projects out the transverse part of the vector field.

DEFINITION. The response tensor is defined by (4.2), $\overleftrightarrow{\kappa} \equiv \overleftrightarrow{\varepsilon}-n^{2} \overleftrightarrow{\boldsymbol{I}}^{T}(\hat{\boldsymbol{k}})$ and hence, $\overleftrightarrow{\kappa} \cdot \delta \boldsymbol{E}(\boldsymbol{k}, \omega) \equiv(4 \pi / \mathrm{i} \omega) \delta \boldsymbol{j}^{\text {ext }}(\boldsymbol{k}, \omega)$.

ThEOREM. (i) Normal modes are determined by the solution of (4.2) with $\boldsymbol{j}^{e x t}=0$. From $\overleftrightarrow{\kappa} \cdot \delta \boldsymbol{E}(\boldsymbol{k}, \omega)=0$ one can make some statements regarding polarization. The dispersion relation for normal modes is obtained from $D(\boldsymbol{k}, \omega)=\operatorname{det}|\overleftrightarrow{\kappa}|=$ $0 \rightarrow \omega_{\ell}(\boldsymbol{k})$ or $k_{\ell}(\hat{\boldsymbol{k}}, \omega)$.
(ii) With an external source $\delta^{\text {ext }}, \delta \boldsymbol{E}(\boldsymbol{k}, \omega)$ is determined by matrix inversion:

$$
\begin{equation*}
\delta \boldsymbol{E}(\boldsymbol{k}, \omega) \equiv \frac{4 \pi}{\mathrm{i} \omega} \stackrel{\kappa}{\kappa}^{-1} \cdot \delta \boldsymbol{j}^{\mathrm{ext}}(\boldsymbol{k}, \omega) \quad \stackrel{\leftrightarrow}{\kappa}^{-1}=\frac{\overleftrightarrow{\kappa}^{A}}{D(\boldsymbol{k}, \omega)}, \tag{4.3}
\end{equation*}
$$

where $\overleftrightarrow{\kappa}^{A}$ is the adjoint of the response tensor. To compute the inverse FourierLaplace inverse transform of (4.3) we will need to know the poles of the integrand, i.e. the roots of $D(\boldsymbol{k}, \omega)=0$.

So far the discussion was completely general until we introduced the conductivity tensor and certain simplifying assumptions (see $\S 3.2$ ). In the rest of $\S 4$ we will include an externally applied magnetic field, analyse particle motion and waves in a magnetized plasma, and introduce the study of waves in a nonuniform medium. Topics such as magnetic confinement of a plasma, macro-instabilities and drift waves are addressed in $\S 8$.
4.2. Waves propagating parallel to a magnetic field in a cold, uniformly magnetized plasma with collisions
Consider the linearized fluid equations for cold electrons in a uniform magnetic field

$$
\begin{equation*}
m \dot{\boldsymbol{v}}=e\left(\delta \boldsymbol{E}+\frac{1}{c} \delta \boldsymbol{v} \times \boldsymbol{B}_{0}\right)-m v_{c} \delta \boldsymbol{v} \Rightarrow-\mathrm{i}\left(\omega+\mathrm{i} v_{c}\right) \delta \boldsymbol{v}(\omega)=\frac{e}{m} \delta \boldsymbol{E}(\omega) \mp(\delta \boldsymbol{v} \times \Omega), \tag{4.4}
\end{equation*}
$$

where $\nu_{c}$ is the collision frequency and $\boldsymbol{\Omega}=-e B_{0} \hat{z} / m c$. Negatively charged electrons gyrate counterclockwise around the magnetic field, and ions gyrate clockwise.

DEFINITION (Circular polarization eigenvectors). For a general vector field define

$$
\begin{equation*}
A_{0}=A_{z} \quad A_{ \pm} \equiv \frac{1}{\sqrt{2}}\left(A_{x} \mp A_{y}\right) \quad \hat{\boldsymbol{e}}_{ \pm} \equiv \frac{1}{\sqrt{2}}\left(\hat{\boldsymbol{e}}_{x} \mp \hat{\boldsymbol{e}}_{y}\right) \quad \hat{\boldsymbol{e}}_{0} \equiv \hat{\boldsymbol{e}}_{z} \quad A_{i} \equiv \hat{\boldsymbol{e}}_{i}^{*} \cdot \boldsymbol{A} \quad \hat{\boldsymbol{e}}_{i}^{*} \cdot \hat{\boldsymbol{e}}_{j}=\delta_{i j} \tag{4.5}
\end{equation*}
$$

The linear eigenmodes of any field can be decomposed by using the definitions in (4.5). In this representation $\boldsymbol{A} \cdot \boldsymbol{B}=A_{+} B_{-}+A_{-} B_{+}+A_{0} B_{0}$.

THEOREM. $-\mathrm{i}\left(\omega+\mathrm{i} v_{c}-\ell \Omega\right) \delta v_{\ell}=(e / m) \delta E_{\ell}, \ell=0, \pm 1$ in $\omega$ space and this is diagonal in this representation. The conductivity is

$$
\begin{equation*}
\sigma_{\ell \ell}=\frac{\delta j_{\ell}}{\delta E_{\ell}}=\frac{\sum_{s} n_{s} e_{s} \delta v_{\ell}^{s}}{\delta E_{\ell}}=\mathrm{i} \sum_{s} \frac{n_{s} e_{s}^{2} \delta v_{\ell}^{s}}{m_{s}} \frac{1}{\omega+\mathrm{i} v_{\mathrm{cs}}-\ell \Omega_{s}} \tag{4.6}
\end{equation*}
$$

We note that for electrons and $\ell=+1$ with $\Omega_{e}>0$, then $\sigma$ can diverge when $\omega+$ $\mathrm{i} v_{c e}-\Omega_{e}=0$. With $E_{ \pm} \propto \exp \left(-\mathrm{i} \Omega_{e} t\right)=\cos \left(\Omega_{e} t\right)-\mathrm{i} \sin \left(\Omega_{e} t\right) \propto E_{x}-\mathrm{i} E_{y}$ and $\ell=+1$ corresponds to right-circular polarization. For ions and $\ell=-1$ with $\Omega_{i}<0, \sigma$ can diverge for $\omega+\mathrm{i} v_{c i}+\Omega_{i}=0$ and $\ell=-1$ corresponds to left-circular polarization.

THEOREM. The dielectric function resulting from the conductivity in (4.6) is

$$
\begin{equation*}
\varepsilon_{\ell}(\omega) \equiv 1+\frac{4 \pi \mathrm{i}}{\omega} \sigma_{\ell}(\omega)=1-\sum_{s} \frac{\omega_{s}^{2}}{\omega\left(\omega+\mathrm{i} v_{\mathrm{cs}}-\ell \Omega_{s}\right)} \tag{4.7}
\end{equation*}
$$

Example. For a two-species plasma with $n_{e}=n_{i}$ and $\nu=0$, then $\omega_{p}^{2}=\omega_{e}^{2}+\omega_{i}^{2}$ and

$$
\begin{equation*}
\varepsilon_{\ell}(\omega)=1-\frac{\omega_{p}^{2}}{\left(\omega-\ell \Omega_{e}\right)\left(\omega-\ell \Omega_{i}\right)} \tag{4.8}
\end{equation*}
$$

We examine (4.8) in two limits, viz., low and high frequency,

$$
\begin{equation*}
\varepsilon_{ \pm}(\omega=0)=1-\frac{\omega_{p}^{2}}{\Omega_{e} \Omega_{i}}=1+\frac{4 \pi \rho c^{2}}{B_{0}^{2}}=\varepsilon_{\perp} \quad \text { and } \quad \varepsilon(\omega=\infty)=1 \tag{4.9}
\end{equation*}
$$

At this point we recall certain definitions and expressions derived earlier.

## DEFINITIONS.

$$
\begin{equation*}
\stackrel{\leftrightarrow}{\varepsilon}(\boldsymbol{k}, \omega) \equiv \stackrel{\leftrightarrow}{\boldsymbol{I}}+\frac{4 \pi \mathrm{i}}{\omega} \stackrel{\leftrightarrow}{\sigma}(\boldsymbol{k}, \omega) \quad \text { and } \quad \stackrel{\leftrightarrow}{\boldsymbol{I}}^{T}(\boldsymbol{k})=\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{k}} \hat{\boldsymbol{k}} \tag{4.10}
\end{equation*}
$$

Plasma electrodynamics:

$$
\begin{gather*}
\boldsymbol{K}(\boldsymbol{k}, \omega)=\stackrel{\leftrightarrow}{\varepsilon}(\boldsymbol{k}, \omega)-n^{2}(\boldsymbol{k}, \omega) \stackrel{\leftrightarrow}{\boldsymbol{I}}^{T}(\boldsymbol{k}) \\
\boldsymbol{K}(\boldsymbol{k}, \omega) \cdot \delta \boldsymbol{E}(\boldsymbol{k}, \omega)=\frac{4 \pi}{\mathrm{i} \omega} j^{\operatorname{ext}}(\boldsymbol{k}, \omega) \\
D(\boldsymbol{k}, \omega)=\operatorname{det}|\boldsymbol{K}(\boldsymbol{k}, \omega)|=0 \tag{4.11}
\end{gather*}
$$

An analysis of (4.10) and (4.11) in a cold plasma will elucidate the directional and $\omega$ dependence of $n(\boldsymbol{k}, \omega)=k c / \omega \Leftrightarrow v_{\phi}$ and $n(\theta, \omega)$ where $\theta$ is the angle between $\boldsymbol{k}$ and $\boldsymbol{B}_{0}$. In a cold plasma the frequencies $\omega_{\mathrm{ps}}^{2}=4 \pi n_{s} e^{2} / m_{s}$ and $\Omega_{s}=e_{s} B_{0} / m_{s} c$ are independent of energy, which simplifies the frequency dependence in the linear dielectric functions and dispersion relations. In addition, the Debye length is zero and the wavenumber dependences of the dielectric tensor and the dispersion relation are further simplified. When the phase velocity of a wave in the presence of a beam is comparable to the beam velocity, the physics becomes sensitive to thermal effects. The cold-plasma limit removes the electron pressure and ion waves; and resonant particle effects vanish (Landau damping and cyclotron damping). In addition, cyclotron harmonic effects (§4.6) on the dispersion relations present in a warm plasma are also absent.

EXAMPLE. Consider wave propagation parallel to an applied magnetic field, $\hat{\boldsymbol{k}}=\hat{\boldsymbol{B}}_{0}=$ $\hat{z}=\hat{\boldsymbol{e}}_{0}$. Using $\overleftrightarrow{\boldsymbol{I}}^{T}=\hat{\boldsymbol{e}}_{+} \hat{\boldsymbol{e}}_{+}^{*}+\hat{\boldsymbol{e}}_{-} \hat{\boldsymbol{e}}_{-}^{*}$ to project field vectors onto a plane transverse to the magnetic field, one can show that

$$
\begin{align*}
\boldsymbol{K}(\boldsymbol{k}, \omega) & =\stackrel{\leftrightarrow}{\varepsilon}(\boldsymbol{k}, \omega)-n^{2}(\boldsymbol{k}, \omega) \stackrel{\leftrightarrow}{\boldsymbol{I}}^{T}(\boldsymbol{k}) \rightarrow \boldsymbol{K}=\left[\varepsilon_{+}-n^{2}\right] \hat{\boldsymbol{e}}_{+} \hat{\boldsymbol{e}}_{+}^{*}+\left[\varepsilon_{-}-n^{2}\right] \hat{\boldsymbol{e}}_{-} \hat{\boldsymbol{e}}_{-}^{*}+\varepsilon_{0} \hat{\boldsymbol{e}}_{0} \hat{\boldsymbol{e}}_{0} \\
D(\boldsymbol{k}, \omega) & =\operatorname{det}|\boldsymbol{K}(\boldsymbol{k}, \omega)|=0 \rightarrow D=\left(\varepsilon_{+}-n^{2}\right)\left(\varepsilon_{-}-n^{2}\right) \varepsilon_{0}=0 \tag{4.12}
\end{align*}
$$

### 4.2.1. Right-hand circularly polarized waves: whistler, magnetosonic and extraordinary waves

Consider a right-circularly polarized wave, $l=+1$, with $\omega>0$ and no collisions $v=0$ : the dispersion relation is

$$
\begin{equation*}
n_{R}^{2}(\omega)=\varepsilon_{+}(\omega)=1-\frac{\omega_{p}^{2}}{\left(\omega-\Omega_{e}\right)\left(\omega+\left|\Omega_{i}\right|\right)} \tag{4.13}
\end{equation*}
$$

Definitions. There is a resonance at $\omega=\Omega_{e}$ where $n=\infty$ and $v_{\phi}=0$. As a function of frequency there is an abrupt change at $\omega=\Omega_{e}$ from propagation ( $\omega<\Omega_{e}$ ) to evanescence $\left(\omega>\Omega_{e}\right)$. There is a cutoff where $n=0, v_{\phi}=\infty$, and $\omega_{1}=\omega_{R C}=$ $\left(\Omega_{e} / 2\right)+\sqrt{\left(\Omega_{e} / 2\right)^{2}+\omega_{p}^{2}}$ (ignoring ion contributions to (4.13)).

Figures 14 and 15 sketch solutions for the dispersion relation for right-circularly polarized waves propagating parallel to a uniform applied magnetic field in a cold plasma. The cutoff frequency $\omega_{1}=\omega_{R C}$ in figure 15 .

EXERCISE. Include a finite, but small collision frequency in (4.13). Consider frequencies of the order of $\Omega_{e}$. Sketch the real and imaginary parts of $\varepsilon_{+}$. Calculate and sketch the real and imaginary parts of $k$ for real $\omega$. Calculate $\operatorname{Im}(\omega)$ as a function of real $k$.
4.2.2. Left-hand circularly polarized waves: Alfvén, ion cyclotron and ordinary

Consider left-circularly polarized waves propagating parallel to the magnetic field. Equation (4.8) yields the following dispersion relation.


FIGURE 14. Schematic of the solutions of (4.13) for waves right-circularly polarized wave propagating parallel to $\boldsymbol{B}_{0}$.


Figure 15. Parallel modes with positive helicity. Electron cyclotron resonance ( $k_{\|} \rightarrow \infty$ ) occurs at $\omega \lesssim\left|\Omega_{e}\right|$. The non-dispersive low-frequency mode $\omega \ll \Omega_{i}\left(\ll\left|\Omega_{e}\right|\right)$ is the Alfvén mode described by $\omega=k_{\|} V_{A}$ (due to A. Hirose). A. Hirose, Physics 862 lecture notes, chap. 6, University of Saskatchewan; http://physics.usask.ca/~hirose/P862/notes.htm.

THEOREM. Left-circularly polarized waves, $\ell=-1$, with $\omega>0$ and no collisions $v=0$, resonate with ions and satisfy the dispersion relation

$$
\begin{equation*}
n_{R}^{2}(\omega)=\varepsilon_{-}(\omega)=1-\frac{\omega_{p}^{2}}{\left(\omega+\Omega_{e}\right)\left(\omega-\left|\Omega_{i}\right|\right)} \tag{4.14}
\end{equation*}
$$

Figures 16 and 17 sketch the solutions of the dispersion relation in (4.14). $\omega_{2}$ is the left-circularly polarized cutoff frequency $\omega_{2}=\omega_{L C}=\sqrt{\left(\Omega_{e} / 2\right)^{2}+\omega_{p}^{2}}-\left|\Omega_{e}\right| / 2$.


FIGURE 16. Schematic of the solutions of (4.14) for waves left-circularly polarized wave propagating parallel to $\boldsymbol{B}_{0} \cdot \omega_{L C}=\omega_{2}$.


Figure 17. Parallel modes with negative helicity. The Alfvén mode $\omega=V_{A} k_{\|}$with negative helicity exists in the low-frequency region $\omega \ll \Omega_{i}$. The ion-cyclotron resonance occurs at $\omega \lesssim \Omega_{i}$. The cutoff frequency $\omega_{2}$ is given by $\omega_{2}=\left(\sqrt{4 \omega_{\text {pe }}^{2}}-\left|\Omega_{e}\right|\right) / 2$ (due to A. Hirose). A. Hirose, Physics 862 lecture notes, chap. 6, University of Saskatchewan; http://physics.usask.ca/~hirose/P862/notes.htm.

### 4.2.3. Electron plasma waves

With $\ell=0$ the solution of (4.8) yields longitudinal waves with $\delta \boldsymbol{E} \| \boldsymbol{B}_{0}, \boldsymbol{k}$ and $\varepsilon_{0}(\omega)=0=1-\omega_{p}^{2} / \omega^{2} \rightarrow \omega= \pm \omega_{p}$, i.e. electron plasma waves.

### 4.3. Waves propagating at an angle with respect to the magnetic field

Here we generalize the consideration of waves propagating at an arbitrary angle with respect to an applied magnetic field. Define a polar angle $\theta$ between the vector $\boldsymbol{k}$ and $\boldsymbol{B}_{0}$ with an azimuthal angle $\phi$ with respect to the magnetic field aligned with $z$.

Then $\hat{\boldsymbol{k}}=\cos \theta \hat{\boldsymbol{z}}+\sin \theta(\cos \phi \hat{\boldsymbol{x}}+\sin \phi \hat{\boldsymbol{y}})$, and we express this in terms of $\hat{\boldsymbol{e}}_{ \pm}=$ $(\hat{\boldsymbol{x}} \pm \hat{\boldsymbol{y}}) / \sqrt{2}$ and $\hat{\boldsymbol{e}}_{0}=\hat{\boldsymbol{z}}$ to evaluate $\hat{\boldsymbol{k}} \hat{\boldsymbol{k}}$ in (4.10) and (4.11). The dispersion relation determined by (4.11) becomes

$$
\begin{equation*}
\operatorname{det}(\stackrel{\leftrightarrow}{\boldsymbol{K}})=D\left(\omega, n^{2}, \theta\right)=n^{4} A(\omega, \theta)-n^{2} B(\omega, \theta)+C(\omega) \tag{4.15}
\end{equation*}
$$

which does not depend on the angle $\phi$. We recall the definitions of $\varepsilon_{0}$, $\varepsilon_{+}$and $\varepsilon_{-}$in $\S 4.2$ and introduce $\varepsilon_{1} \equiv \frac{1}{2}\left(\varepsilon_{+}+\varepsilon_{-}\right)=1-\sum_{s}\left(\omega^{\prime} / \omega\right)\left(\omega_{s}^{2} /\left(\omega^{\prime 2}-\Omega_{s}^{2}\right)\right), \omega^{\prime}=\omega+\mathrm{i} v$ to obtain

$$
\begin{gather*}
A(\omega, \theta)=\varepsilon_{1}(\omega) \sin ^{2} \theta+\varepsilon_{0}(\omega) \cos ^{2} \theta \\
B(\omega, \theta)=\varepsilon_{+} \varepsilon_{-} \sin ^{2} \theta+\varepsilon_{1} \varepsilon_{0}\left(1+\cos ^{2} \theta\right) \\
C(\omega, \theta)=\operatorname{det}(\stackrel{\leftrightarrow}{\boldsymbol{e}})=\varepsilon_{+} \varepsilon_{-} \varepsilon_{0} \\
n^{2}(\omega, \theta)=\frac{B \pm \sqrt{B^{2}-4 A C}}{2 A} \tag{4.16}
\end{gather*}
$$

EXERCISE. With $v=0$ show that $B^{2}-4 A C>0$ which implies that (4.15) and (4.16) have real roots for $\omega$.

We can examine the solutions of (4.15) for $n^{2}$ as a function of $\omega$ for finite $\theta$, which is just a quadratic. First one looks for resonances $\left(n^{2} \rightarrow \infty\right)$. One class of resonances corresponds to $A \rightarrow 0$, for which $n_{+}^{2} \rightarrow \infty$ and $n_{-}^{2}=C / B$. We introduce the following useful definitions.

Definitions. The upper and lower hybrid frequencies are

$$
\begin{equation*}
\omega_{\mathrm{uh}}^{2}=\omega_{\mathrm{pe}}^{2}+\Omega_{e}^{2} \quad \text { and } \quad \omega_{\mathrm{lh}}^{2}=\frac{\omega_{\mathrm{pi}}^{2}+\Omega_{i}^{2}}{1+\omega_{\mathrm{pe}}^{2} / \Omega_{e}^{2}} \tag{4.17}
\end{equation*}
$$

where $\omega_{ \pm}$is the lowest-frequency solution at $\theta=\pi / 2$ of $A(\omega) \rightarrow \varepsilon_{1} \equiv \frac{1}{2}\left(\varepsilon_{+}+\varepsilon_{-}\right)=0$. In many laboratory experiments $\Omega_{i}^{2} \ll \omega_{\mathrm{pi}}^{2}$ in the lower hybrid frequency. A schematic of the resonances at $\omega_{\mathrm{I}}, \omega_{\text {II }}$, and $\omega_{\text {III }}$ determined by the solutions of $A=0$ for frequency as a function of angle $\theta$ for $\omega_{\mathrm{pe}}>\Omega_{e}$ is shown in figure 18. Figure 19 is a schematic of the dispersion relation $n^{2}$ versus $\omega$ for $\theta \neq 0$ determined by solutions of (4.15). Figure 19 is a schematic for the solution of $n^{2}$ versus $k$ for $\theta \neq 0$, and figure 20 is a schematic for the solution of $\omega$ versus $k$.

THEOREM. In a cold plasma at low frequencies $\varepsilon_{ \pm} \Rightarrow 1+4 \pi \rho c^{2} / B_{0}^{2}, \varepsilon_{0}=1-\omega_{p}^{2} / \omega^{2}$, $n_{+}^{2} \rightarrow \varepsilon_{\perp} \sec ^{2} \theta$ and $n_{-}^{2} \rightarrow \varepsilon_{\perp}$. For any $k$ there are five branches for $\omega$. There are cutoffs, $n^{2}=k=0$, when $C=0$, i.e. $\omega=\omega_{R C}$ where $\varepsilon_{+}=0, \omega=\omega_{L C}$ where $\varepsilon_{-}=0$, and $\omega=\omega_{\text {pe }}$ where $\varepsilon_{0}=0$. Resonances are determined by $n=k=\infty$ which derive from the poles of $\varepsilon_{ \pm}$. The polarization of the waves is determined by the solutions of $\boldsymbol{K} \cdot \delta \boldsymbol{E}=0$ and $\operatorname{det} \boldsymbol{K}=0$ for the eigenvectors.

EXAmples. (i) What distinguishes the Alfvén from the magnetosonic wave? An Alfvén wave can be viewed as a plucked magnetic field line. The tension in the field line is given by $B_{0}^{2} / 4 \pi$. The dispersion relation is $\omega=k V_{A} \cos \theta=k_{z} V_{A}$, and the group velocity $\boldsymbol{V}_{g}=\partial \omega / \partial \boldsymbol{k}=\hat{\boldsymbol{z}} V_{A}$. The oscillation propagates along the field line.


Figure 18. Schematic of the solutions of $A=0$ in (4.16) for the three frequencies $\omega_{\mathrm{I}}, \omega_{\mathrm{II}}$ and $\omega_{\text {III }}$ versus angle $\theta$ where resonances $n^{2} \rightarrow \infty$ occur.


Figure 19. Schematic of the solutions of (4.15) for $n^{2}$ versus $\omega$ with $\theta \neq 0$.

The magnetosonic wave is a solution of $n_{-}^{2}=\varepsilon_{\perp}: \omega=k V_{A}$. In a cold plasma the magnetosonic wave is dispersionless: the phase and group velocities are equal to $V_{\mathrm{A}}$, and the wave is isotropic. (ii) The ordinary ( O ) and extraordinary ( X ) modes exhibit characteristic birefringence, i.e. their index of refraction $n$ depends on their polarization. At low plasma density, the O and X modes become light waves.

EXERCISE. How does $n^{2}$ depend on $\theta$ for fixed $\omega$ ? Look at textbooks such T. J. M. Boyd and J. J. Sanderson, Plasma Dynamics (1969) or Stix (1962). Of particular interest is the concept of the ray velocity surface (wave normal surface) and the Clemmow-Mullaly-Allis (CMA) diagram. At resonances $n=k=\infty$ show that $\delta \boldsymbol{E}$ is parallel to $\boldsymbol{k}$. Consider the dispersion relation for the whistler


Figure 20. Schematic of solutions of (4.15) for $\omega$ versus $k$ with $\theta \neq 0$.
wave in the frequency range $\Omega_{i} \ll \omega \ll \omega_{\mathrm{pe}}, \Omega_{e}$ in a cold plasma, which is $n^{2}(\omega, \theta)=k^{2} c^{2} / \omega^{2}=\omega_{\mathrm{pe}}^{2} /\left(\omega \Omega_{e} \cos \theta\right)$. Calculate the group velocity $\boldsymbol{V}_{g}=\mathrm{d} \omega / \mathrm{d} \boldsymbol{k}$ and plot it as a function of $\theta$. The group velocity $\boldsymbol{V}_{g}$ makes an angle $\gamma$ with respect to the phase velocity $\boldsymbol{V}_{\phi}=\omega / k$. Show that $\tan \gamma=(\partial / \partial \theta) \ln k(\omega, \theta)$. Show that the energy in a whistler wave is within a $20^{\circ}$ angle with respect to $\boldsymbol{B}_{0}$. Make a polar plot of the phase velocity $\boldsymbol{V}_{\phi}$, as a function of $\theta$, which when rotated around the axis of symmetry is the so-called wave-normal surface in figure $21(a)$. The refraction index surface is shown in figure $21(b)$ (figure and caption due to R. D. Blandford and K. S. Thorne, http://www.pmaweb.caltech.edu/Courses/ph136/yr2012/, § 21.7; K. S. Thorne and R. D. Blandford, Modern Classical Physics (Princeton University Press, 2017), figure 21.6).

### 4.4. Energy transport

Consider the energy transport associated with waves in a magnetized plasma.
Definition. Let $U$ be defined as the energy density of a wave packet and $\boldsymbol{S}=U \boldsymbol{V}_{\boldsymbol{g}}$ is the energy flux density.

THEOREM. It can be shown that

$$
\begin{equation*}
\boldsymbol{S}=-\frac{\omega}{8 \pi} \delta \boldsymbol{E}^{*} \cdot \frac{\partial \boldsymbol{K}}{\partial \boldsymbol{k}} \cdot \delta \boldsymbol{E} \tag{4.18}
\end{equation*}
$$

given $U=\left(|\delta \boldsymbol{B}|^{2} / 8 \pi\right)+\left(\omega \delta \boldsymbol{E}^{*} \cdot(\partial \boldsymbol{K} / \partial \omega) \cdot \delta \boldsymbol{E}\right) / 8 \pi, \boldsymbol{K}=\overleftrightarrow{\varepsilon}-n^{2}(\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{k}} \hat{\boldsymbol{k}}), \boldsymbol{V}_{g}=\partial \omega / \partial \boldsymbol{k}, \boldsymbol{K} \cdot$ $\delta \boldsymbol{E}=0$ and Maxwell's equations.
(a)

(b)


Figure 21. (a) Wave-normal surface for a whistler mode propagating at an angle $\theta$ with respect to the magnetic field direction. The phase velocity $\boldsymbol{V}_{\mathrm{ph}}=(\omega / k) \hat{\boldsymbol{k}}$ as a vector from the origin, with the direction of the magnetic field chosen upward. When we fix the frequency $\omega$ of the wave, the tip of the phase velocity vector sweeps out the figure- 8 curve as its angle $\theta$ to the magnetic field changes. This curve should be thought of as rotated around the vertical (magnetic field) direction to form the figure-8 'wave-normal' surface. Note that there are some directions where no mode can propagate. (b) Refractive index surface for the same whistler mode. Here we plot $c \boldsymbol{k} / \omega$ as a vector from the origin, and as its direction changes with fixed $\omega$, this vector sweeps out the two hyperboloid-like surfaces. Since the length of the vector is $(c \boldsymbol{k} / \omega)=\boldsymbol{n}$, this figure can be thought of as a polar plot of the refractive index $\boldsymbol{n}$ as a function of the wave propagation direction $\theta$ for fixed $\omega$; hence the name 'refractive index surface'. The group velocity $\boldsymbol{V}_{g}$ is orthogonal to refractive index surface. Note that for this whistler mode, the energy flow (along $\boldsymbol{V}_{g}$ ) is focused toward the direction of the magnetic field (from R. D. Blandford and K. S. Thorne, ph136/yr2012; K. S. Thorne and R. D. Blandford, Modern Classical Physics (Princeton University Press, 2017), figure 21.6).

Theorem. It then follows from the definition of $\boldsymbol{K}$ and Maxwell's equations that

$$
\begin{equation*}
\boldsymbol{S}=\frac{c}{4 \pi} \operatorname{Re} \delta \boldsymbol{E}^{*} \times \delta \boldsymbol{B}-\frac{\omega}{8 \pi} \delta \boldsymbol{E}^{*} \cdot \frac{\partial \stackrel{\leftrightarrow}{\varepsilon}}{\partial \boldsymbol{k}} \cdot \delta \boldsymbol{E} \tag{4.19}
\end{equation*}
$$

We note that the first term on the right-hand side of (4.19) is the electromagnetic Poynting flux and the second term is the energy flux density associated with particle motion.

Exercise. In a Coulomb plasma evaluate the dielectric function $\varepsilon(\boldsymbol{k}, \omega)$ and $\boldsymbol{S}$, and apply in a few limiting cases.

### 4.5. Wave propagation in an inhomogeneous cold plasma

Consider small-amplitude waves in an inhomogeneous plasma. We begin with the Maxwell equations and linearize the fields and currents with respect to a field-free and current-free unperturbed system,

$$
\begin{align*}
\boldsymbol{\nabla} & \times \boldsymbol{B}-\frac{1}{c} \frac{\partial \boldsymbol{E}}{\partial t}=\frac{4 \pi}{c} \boldsymbol{j} \quad \boldsymbol{\nabla} \times \boldsymbol{E}+\frac{1}{c} \frac{\partial \boldsymbol{B}}{\partial t}=0 \Rightarrow \\
\nabla & \times \delta \boldsymbol{B}-\frac{1}{c} \frac{\partial \delta \boldsymbol{E}}{\partial t}=\frac{4 \pi}{c} \delta \boldsymbol{j} \quad \boldsymbol{\nabla} \times \delta \boldsymbol{E}+\frac{1}{c} \frac{\partial \delta \boldsymbol{B}}{\partial t}=0 \quad \frac{\partial}{\partial t} \rightarrow-\mathrm{i} \omega \tag{4.20}
\end{align*}
$$

Theorem. Upon Fourier transforming the time dependence we obtain

$$
\begin{gather*}
\nabla \times(\nabla \times \delta \boldsymbol{E}(\boldsymbol{x}, \omega))-\frac{\omega^{2}}{c^{2}} \delta \boldsymbol{E}(\boldsymbol{x}, \omega)=4 \pi \frac{\mathrm{i} \omega}{c^{2}} \delta \boldsymbol{j}(\boldsymbol{x}, \omega) \quad \delta \boldsymbol{j}(\boldsymbol{x}, \omega)=\overleftrightarrow{\sigma}(\boldsymbol{x}, \omega) \cdot \delta \boldsymbol{E}(\boldsymbol{x}, \omega) \\
\nabla \times(\nabla \times \delta \boldsymbol{E}(\boldsymbol{x}, \omega))=\frac{\omega^{2}}{c^{2}} \stackrel{\leftrightarrow}{\varepsilon} \cdot \delta \boldsymbol{E}(\boldsymbol{x}, \omega) \quad \stackrel{\leftrightarrow}{\varepsilon}=\stackrel{\leftrightarrow}{\boldsymbol{I}}+\frac{4 \pi \mathrm{i}}{\omega} \stackrel{\leftrightarrow}{\sigma} \tag{4.21}
\end{gather*}
$$

in which we have introduced the conductivity and dielectric tensors. In some special cases the physical system may possess sufficient symmetry to allow separation of the dependence of the fields on the spatial variables. In the most general circumstances one cannot separate the spatial variables and approximate methods are employed.

### 4.5.1. WKB eikonal method

In the WKB (Wentzel-Kramers-Brillouin or Wentzel-Kramers-Brillouin-Jeffreys) method, all of the field quantities are decomposed in terms of a slowly varying amplitude and a rapidly varying phase factor,
DEFINITIONS. $\delta \boldsymbol{E}(\boldsymbol{x})=A(\boldsymbol{x}) \hat{\boldsymbol{e}}(\boldsymbol{x}) \exp (\mathrm{i} \Phi(\boldsymbol{x}))$
(i) $\hat{\boldsymbol{e}}(\boldsymbol{x})$ is the complex-valued polarization vector and is slowly varying.
(ii) $A(\boldsymbol{x})$ is a slowly varying amplitude.
(iii) $\exp (\mathrm{i} \Phi(\boldsymbol{x}))$ is a phase factor that is a rapidly varying function of $\boldsymbol{x}$.
(iv) The slowly varying spatial scale is $L \gg \lambda$ the rapidly varying spatial scale.

Using the definitions above we obtain

$$
\begin{align*}
\nabla & \times \delta \boldsymbol{E} \approx \mathrm{i} \nabla \Phi \times \delta \boldsymbol{E}=\mathrm{i} \boldsymbol{k}(\boldsymbol{x}) \times \delta \boldsymbol{E}(\boldsymbol{x}) \\
\nabla & \times \boldsymbol{\nabla} \times \delta \boldsymbol{E}=\nabla(\nabla \cdot \delta \boldsymbol{E})-\nabla^{2} \delta \boldsymbol{E} \approx \mathrm{i} \nabla \Phi \times(\mathrm{i} \boldsymbol{k} \times \delta \boldsymbol{E}) \\
& =-\boldsymbol{k} \times \boldsymbol{k} \times \delta \boldsymbol{E}=-\boldsymbol{k} \boldsymbol{k} \cdot \delta \boldsymbol{E}+k^{2} \delta \boldsymbol{E} . \tag{4.23}
\end{align*}
$$

THEOREM. Using (4.5.2), (4.5.3) and (4.5.4), it follows that

$$
\begin{equation*}
\left[\stackrel{\leftrightarrow}{\varepsilon}(\omega, \boldsymbol{x})-n^{2}(\boldsymbol{x})(\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{k}}(\boldsymbol{x}) \hat{\boldsymbol{k}}(\boldsymbol{x}))\right] \cdot \delta \boldsymbol{E}(\boldsymbol{x}) \equiv \stackrel{\leftrightarrow}{\boldsymbol{K}}(\omega, \boldsymbol{k}(\boldsymbol{x}), \boldsymbol{x}) \cdot \delta \boldsymbol{E}(\boldsymbol{x})=0 \tag{4.24}
\end{equation*}
$$

where $n^{2} \equiv k^{2} c^{2} / \omega^{2}$ and we require that $D(\omega, \boldsymbol{k}(\boldsymbol{x}), \boldsymbol{x}) \equiv \operatorname{det}|\stackrel{\leftrightarrow}{\boldsymbol{K}}|=0$.
ThEOREM. $D(\omega, \operatorname{i} \nabla \Phi(\boldsymbol{x}), \boldsymbol{x})=0$ is a differential equation.
EXAMPLE. In a plane-stratified medium with $\omega_{p}^{2}(z)$ and $B_{0}=0, D=0 \rightarrow \omega^{2}=$ $\omega_{p}^{2}(z)+|\nabla \Phi|^{2} c^{2}$ and $\boldsymbol{k}=\nabla \Phi ; \hat{\boldsymbol{k}}$ is parallel to $\hat{\boldsymbol{n}}$, and both are normal to constant phase surface. Given the solution $\omega(\boldsymbol{k}, \boldsymbol{x})$ to $D=0$, wave packets convect at the group velocity $V^{g}=\left.((\partial \omega(\boldsymbol{k}, \boldsymbol{x})) / \partial \boldsymbol{k})\right|_{x}=(\mathrm{d} \boldsymbol{x} / \mathrm{d} t)=(\boldsymbol{k} / \boldsymbol{\omega}) c^{2}=c \sqrt{1-\left(\omega_{p}^{2} / \omega^{2}\right)}$. In the atmosphere the electron charge density increases with vertical altitude going up into the ionosphere above 85 km and then decreases above 300 km . If a wave is launched into the ionosphere at a fixed frequency $\omega_{0}$ then the equation $D=0$ can be solved for $\boldsymbol{k}(\boldsymbol{x})$. The wave will exhibit reflection when $\omega_{p}(\boldsymbol{x})=\omega_{0}$ and will refract where the wave is not evanescent.

Introduce a variation in the transverse direction $x$ in the example of the planestratified medium considered above. Fourier analyse in $x$ and introduce $k_{x}$. From the eikonal dispersion relation one obtains

$$
\begin{align*}
\frac{\mathrm{d} z}{\mathrm{~d} t} & =\frac{\partial \omega}{\partial k_{z}}=\frac{k_{z}(z) c^{2}}{\omega}=c \sqrt{1-\frac{\omega_{p}^{2}(z)}{\omega^{2}}-\frac{k_{x}^{2} c^{2}}{\omega^{2}}} \\
\frac{\mathrm{~d} x}{\mathrm{~d} t} & =\frac{\partial \omega}{\partial k_{x}}=\frac{k_{x} c^{2}}{\omega}=c \sqrt{1-\frac{\omega_{p}^{2}(z)}{\omega^{2}}-\frac{k_{z}^{2} c^{2}}{\omega^{2}}} \\
\frac{\mathrm{~d} z}{\mathrm{~d} x} & =\frac{k_{z}(z)}{k_{x}} \tag{4.25}
\end{align*}
$$

THEOREM. The eikonal dispersion relation $D(\omega, \boldsymbol{k}(\boldsymbol{x}), \boldsymbol{x})=0$ is equivalent to $\omega(\boldsymbol{k}, \boldsymbol{x})=\omega_{0}$ and one can insist the total time derivative of $\omega$ vanishes,

$$
\begin{align*}
& 0=\frac{\mathrm{d} \omega(\boldsymbol{k}, \boldsymbol{x})}{\mathrm{d} t}=\frac{\partial \omega}{\partial \boldsymbol{k}} \cdot \frac{\mathrm{d} \boldsymbol{k}}{\mathrm{~d} t}+\frac{\partial \omega}{\partial \boldsymbol{x}} \cdot \frac{\mathrm{d} \boldsymbol{x}}{\mathrm{~d} t} \rightarrow \frac{\partial \omega}{\partial \boldsymbol{k}} \cdot\left(-\frac{\mathrm{d} \omega}{\mathrm{~d} \boldsymbol{x}}\right)+\frac{\partial \omega}{\partial \boldsymbol{x}} \cdot \frac{\partial \omega}{\partial \boldsymbol{k}} \equiv 0 \\
& \text { if } \frac{\mathrm{d} \boldsymbol{x}}{\mathrm{~d} t}=\frac{\partial \omega}{\partial \boldsymbol{k}} \text { and } \frac{\mathrm{d} \boldsymbol{k}}{\mathrm{~d} t}=-\frac{\mathrm{d} \omega}{\mathrm{~d} \boldsymbol{x}} \text {, the WKBJ wave packet equations. } \tag{4.26}
\end{align*}
$$

For only $z$ dependence, $(\mathrm{d} \boldsymbol{k} / \mathrm{d} t)=\left(\mathrm{d} k_{z} / \mathrm{d} t\right) \hat{\boldsymbol{k}}=-(\mathrm{d} \omega / \mathrm{d} z) \hat{\boldsymbol{k}}$. Because $(\mathrm{d} \omega / \mathrm{d} x)=0$ then $\left(\mathrm{d} k_{x} / \mathrm{d} t\right)=0$, i.e. $k_{x}$ is a constant. The equations in (4.26) are Hamilton's equations. We note that by multiplying the wave packet equations of motion through by $\hbar$ we have the equations of motion for quantum mechanical wave packets. If we identify the Hamiltonian $H=\hbar \omega$, we note that $(\mathrm{d} H / \mathrm{d} t)=(\partial H / \partial t)=\hbar(\partial \omega(\boldsymbol{k}, \boldsymbol{x}, t) / \partial t)$. There is a nice discussion of the WKBJ wave packet equations in T.H. Stix, The Theory of Plasma Waves, 1962.

Consider an infinite-length wave train in the absence of sources and sinks. Then energy flux conservation dictates

$$
\begin{equation*}
\frac{\partial}{\partial t} U(z)=-\frac{\partial}{\partial z} S_{z}=0, \quad S_{z}=\text { const. }=U(z) \frac{\partial \omega}{\partial k}(z) \tag{4.27}
\end{equation*}
$$

where $U(z)$ is the wave energy density, and $S_{z}$ is the $z$-component of the wave energy flux. In consequence of (4.27), the square of the wave packet amplitude scales as $A^{2} \sim$ $U(z) \sim S /\left|\partial \omega / \partial k_{z}\right| \sim$ const. $/\left|\partial \omega / \partial k_{z}\right| ;$ thus, $A(z) \sim 1 / \sqrt{\mid} \partial \omega / \partial k_{z} \mid$, which is useful up to a reflection point where $S_{z}$ and $\partial \omega / \partial k_{z}$ vanish.

### 4.5.2. Reflection, refraction, turning points, Bohr-Sommerfeld quantization

In WKB either reflection or refraction only can occur. Partial reflection, refraction, and transmission at a sharp boundary like a glass plate cannot be described by WKB. How good is WKB? WKB can be applied to a medium with spatial variation that is slow on the scale of the characteristic wavelength of the wave. Consider a onedimensional example (ref. Landau and Lifshitz, Quantum Mechanics, Sec. 23, Problem 3) wherein there is a transition in the square of the index of refraction from a higher value $n_{0}$ to a lower value $n_{1}$ over a length scale $L$. Assume the dispersion relation for an electromagnetic wave in an unmagnetized spatially varying plasma dielectric varies as

$$
\begin{equation*}
\varepsilon(x)=\frac{n_{0}^{2}+n_{1}^{2} e^{x / L}}{1+e^{x / L}} \tag{4.28}
\end{equation*}
$$

THEOREM. For a wave packet incident from $+\infty$ in the profile in (4.28), the reflection coefficient, defined as the reflected power divided by the incident power, is given by (Eckart 1930)

$$
\begin{equation*}
R=\frac{\sinh ^{2}\left[\pi \frac{L}{\bar{\lambda}}\left(n_{0}-n_{1}\right)\right]}{\sinh ^{2}\left[\pi \frac{L}{\bar{\lambda}}\left(n_{0}+n_{1}\right)\right]}, \quad \bar{\lambda} \equiv \frac{c}{\omega} . \tag{4.29}
\end{equation*}
$$

The WKB limit corresponds to $L \gg \bar{\lambda}$, and $R \rightarrow \mathrm{e}^{-4 \pi L / \bar{\lambda}}$; so the reflectivity is exponentially small in this limit. In the sharp-boundary limit, $L \ll \bar{\lambda}, R \rightarrow\left(n_{0}-\right.$ $\left.n_{1}\right)^{2} /\left(n_{0}+n_{1}\right)^{2}$; and the WKB estimate is a very poor approximation.

There are many treatments of reflection of waves in spatially varying media. There are elegant discussions in J. Heading, Introduction to Phase-Integral Methods (Methuen, 1962); K. G. Budden, Radio Waves in the Ionosphere (Dover, 1961); and E. R. Tracy, A. J. Brizard, A. S. Richardson, and A. N. Kaufman, Ray Tracing and Beyond: Phase-space Methods in Plasma Wave Theory (Cambridge University Press, 2014). A simpler approach is presented in J. Mathews and R. Walker, Mathematical Methods of Physics, 2nd ed. (Benjamin, 1970). Here we follow the treatment in Mathews and Walker. Consider the one-dimensional limit of (4.23) and (4.24),

$$
\begin{equation*}
\nabla \times(\nabla \times \delta \boldsymbol{E}(\boldsymbol{x}))=\frac{\omega^{2}}{c^{2}} \stackrel{\leftrightarrow}{\varepsilon}(\boldsymbol{x}) \cdot \delta \boldsymbol{E}(\boldsymbol{x})=\nabla \nabla \cdot \delta \boldsymbol{E}(\boldsymbol{x})-\nabla^{2} \delta \boldsymbol{E} . \tag{4.30}
\end{equation*}
$$

Consider a purely transverse wave $\nabla \cdot \delta \boldsymbol{E}=0$ in one dimension and introduce a specific polarization to obtain a scalar wave equation,

$$
\begin{equation*}
-\frac{\mathrm{d}^{2}}{\mathrm{~d} z^{2}} \delta E(z)=\frac{\omega^{2}}{c^{2}} \varepsilon(z) \delta E(z) \rightarrow k(z)=\frac{2 \pi}{\lambda(z)}=\frac{\omega}{c} \sqrt{\varepsilon(z)} \tag{4.31}
\end{equation*}
$$

Figure 22 illustrates an electromagnetic wave incident from the right in a spatially varying medium with plasma cutoff at $z=0$. Regions away from $z=0$ are accurately described by WKB. Near $z=0$ if the dielectric $\varepsilon$ goes through zero linearly in $z$, solving the differential equation in (4.31) yields an Airy function solution, and the Airy function is related to Bessel functions and modified Bessel functions of fractional order $1 / 3$.

EXAmple. Consider $\epsilon(z)=1-\omega_{p}^{2}(z) / \omega^{2}$ and assume for a model that the WKB dispersion relation is $\omega_{p}^{2}=-n_{1}^{2} \tanh (z / L) \omega^{2}+\omega^{2}$. For the moment select units such that $(\omega / c)=1$ and recall that the WKB solution for the phase function satisfies $\mathrm{d} \Phi / \mathrm{d} z \equiv$ $k(z)$. The WKB solutions of (4.31) are then given by

$$
\begin{equation*}
W_{ \pm}(z)=\frac{1}{\varepsilon^{1 / 4}(z)} \exp \left( \pm \mathrm{i} \int_{0}^{z} \mathrm{~d} z^{\prime} \sqrt{\varepsilon\left(z^{\prime}\right)}\right) . \tag{4.32}
\end{equation*}
$$

The asymptotic WKB solutions for the wave amplitude and phase far from $z=0$ are given by

$$
\left.\begin{array}{l}
z \geqslant \lambda: \delta E(z)=\frac{\beta}{\varepsilon^{1 / 4}(z)} \cos \left(\frac{\omega}{c} \int_{0}^{z} \mathrm{~d} z^{\prime} \sqrt{\varepsilon\left(z^{\prime}\right)}-\alpha\right)  \tag{4.33}\\
z \leqslant-\lambda: \delta E(z)=\frac{1}{\varepsilon^{1 / 4}(z)} \exp \left(-\frac{\omega}{c} \int_{z}^{0} \mathrm{~d} z^{\prime} \sqrt{\left|\varepsilon\left(z^{\prime}\right)\right|}\right)
\end{array}\right\}
$$


(b)


FIGURE 22. (a) Schematic of the dielectric function as function of position $z$ for a wave incident from the right with cutoff at $z=0$. (b) Schematic of electromagnetic wave amplitude for wave incident from the right with cutoff at $z=0$.

The constants $\alpha$ and $\beta$ are to be determined. The normalization of the wave amplitude is arbitrary. We rewrite the differential equation (4.31) as

$$
\begin{equation*}
\left[-\frac{\mathrm{d}^{2}}{\mathrm{~d} z^{2}}+\frac{\omega^{2}}{c^{2}}(-\varepsilon(z))\right] \delta E(z)=0 \tag{4.34}
\end{equation*}
$$

which is analogous to the quantum mechanical problem

$$
\begin{equation*}
[H] \psi=[K+V] \psi=0 \tag{4.35}
\end{equation*}
$$

With $V \propto-\varepsilon$, figure $22(a)$ can be used as a diagram for $V(z)$ (with the sign flipped from that of $\varepsilon(z))$. With total energy $E=0$, the kinetic energy $K$ is positive for $z>0$; and there is a turning point at $z=0$ for $V(0)=0$. We return to the WKB solution of (4.31) with units such that $\omega / c=1$. Assume that

$$
\begin{equation*}
\delta E(z)=A_{+}(z) W_{+}(z)+A_{-}(z) W_{-}(z) \quad W_{ \pm} \propto \exp \left(\mp \int_{0}^{z} \mathrm{~d} z^{\prime}|\epsilon|^{1 / 2}\right) \tag{4.36}
\end{equation*}
$$

Here $W_{+}$is exponentially large in the evanescent region $z<0$, and $W_{+}$is exponentially small in the evanescent region; $A_{ \pm}$are rapidly varying in the neighbourhood of the turning point. We constrain $A_{+}^{\prime} W_{+}+A_{-}^{\prime} W_{-}=0$ so that $(\mathrm{d} / \mathrm{d} z) \delta E(z)=A_{+} W_{+}^{\prime}+A_{-} W_{-}^{\prime}$. Now substitute (4.36) into (4.31) to obtain

$$
\begin{align*}
\frac{\mathrm{d} A_{+}}{\mathrm{d} z}= & -\frac{\mathrm{i}}{2} \frac{\Delta(z)}{\varepsilon^{1 / 2}(z)}\left[A_{+}+A_{-} \frac{W_{-}}{W_{+}}\right] \quad \text { and } \quad \frac{\mathrm{d} A_{-}}{\mathrm{d} z}=\frac{\mathrm{i}}{2} \frac{\Delta(z)}{\varepsilon^{1 / 2}(z)}\left[A_{-}+A_{+} \frac{W_{+}}{W_{-}}\right] \\
& \text {where } \Delta(z)^{2} \equiv \frac{1}{4} \frac{\mathrm{~d}^{2} \varepsilon / \mathrm{d} z^{2}}{\varepsilon}-\frac{5}{16}\left(\frac{\mathrm{~d} \varepsilon / \mathrm{d} z}{\varepsilon}\right)^{2} . \tag{4.37}
\end{align*}
$$

Consider integration of the first-order differential equations in (4.37) in the complex $z$ plane making use of analytic continuation. Far from the turning point at $z=0$ in the evanescent region select a point no. 1 on the real $z$ axis where $A_{+}=0$ and $A_{-}=1$, while in the propagation region $z>0$ far from $z=0$, select a point no. 2 where $A_{+}=1$ and $A_{-}=0$. We can integrate $\mathrm{d} A_{+} / \mathrm{d} z$ from no. 1 on an arc approaching the imaginary axis, and it remains exponentially small. However, $\mathrm{d} A_{-} / \mathrm{d} z \approx \mathrm{i} \Delta /\left(2 \varepsilon^{1 / 2}(z)\right)$ is small, but not exponentially so. Near the imaginary $z$ axis, $z=\mathrm{i}|z|, \varepsilon \sim z$ and $W_{ \pm} \sim \exp \left( \pm z^{3 / 2}\right) \sim \exp \left( \pm \mathrm{i}^{3 / 2}|z|^{3 / 2}\right)$. Thus, $W_{+}$is exponentially small near the imaginary
axis and $W_{-}$is exponentially large near the imaginary axis. The ratio $W_{-} / W_{+}$remains exponentially large until the real axis. We can examine the integration of (4.37),

$$
\begin{gather*}
\frac{\mathrm{d} A_{+}}{\mathrm{d} z}=-\frac{\mathrm{i}}{2} \frac{\Delta(z)}{\varepsilon^{1 / 2}(z)}\left[A_{+}(\text {starts small })+A_{-}(\sim 1) \frac{W_{-}}{W_{+}}(\text {exponentially large })\right]  \tag{4.38a}\\
\frac{\mathrm{d} A_{-}}{\mathrm{d} z}=\frac{\mathrm{i}}{2} \frac{\Delta(z)}{\varepsilon^{1 / 2}(z)}\left[A_{-}(\sim 1)+A_{+}(\text {exponentially small }) \frac{W_{+}}{W_{-}}(\sim \text { exponentially small })\right] . \tag{4.38b}
\end{gather*}
$$

The coefficient in front of the bracket in (4.38a) is small and $A_{+}$starts small, but has a growth rate that is the product of a small quantity and an exponentially large quantity; so $A_{+}$becomes finite, and a more careful analysis is required. $A_{-}$has a small growth rate and remains near unity in WKB. To resolve this, we pick an integration contour from no. 1 to no. 2 following a half-circle in the upper $z$ half-plane back to the real axis where there is a branch cut and a jump condition (rf. Heading). Mathews and Walker's treatment gives the following. In the evanescent region, the solution for wave amplitude is $\delta E \sim W_{-}(z)$, while in the propagation region the wave amplitude is the sum of the incident and reflected wave: $\delta E \sim W_{-}(z)+A_{+} W_{+}(z)$. In the propagation region, the incident wave amplitude physically is $\left|A_{+}\right|=1$; and the reflected wave amplitude should be the same, but the phase needs to be determined. The expressions for $\delta E$ coming from either direction must match where the arc crosses the imaginary $z$ axis:

$$
\begin{equation*}
\frac{\exp \left(-\int_{0}^{|z|} \mathrm{d} z^{\prime}|\varepsilon|^{1 / 2}\left(z^{\prime}\right)\right)}{\mathrm{e}^{\mathrm{i} \pi / 4}|\varepsilon|^{1 / 4}(z)} \rightarrow \frac{\exp \left(-\mathrm{i} \int_{0}^{z} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(z^{\prime}\right)\right)+A_{+} \exp \left(+\mathrm{i} \int_{0}^{z} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(z^{\prime}\right)\right)}{\varepsilon^{1 / 4}(z)} . \tag{4.39}
\end{equation*}
$$

We multiply both sides of (4.39) by $\mathrm{e}^{\mathrm{i} \pi / 4}$

$$
\begin{align*}
& \frac{\exp \left(-(\omega / c) \int_{0}^{|z|} \mathrm{d} z^{\prime}|\varepsilon|^{1 / 2}\left(z^{\prime}\right)\right)}{|\varepsilon|^{1 / 4}(z)} \\
& \rightarrow \frac{\mathrm{e}^{\mathrm{i} \pi / 4} \exp \left(-\mathrm{i}(\omega / c) \int_{0}^{z} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(z^{\prime}\right)\right)+A_{+} \mathrm{e}^{\mathrm{i} \pi / 4} \exp \left(+\mathrm{i}(\omega / c) \int_{0}^{z} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(z^{\prime}\right)\right)}{\varepsilon^{1 / 4}(z)} \\
& \rightarrow \frac{2 \cos \left[\frac{\omega}{c} \int_{0}^{z} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(z^{\prime}\right)-\pi / 4\right]}{\varepsilon^{1 / 4}(z)} . \tag{4.40}
\end{align*}
$$

Because the left-hand side of (4.40) is real, the two terms in the intermediate expression must be complex conjugates, which leads to the final expression on the right-hand side. We see that the phase factor $\pi / 4$ has emerged. Figure $22(b)$ captures the qualitative behaviour of the solution in (4.40) characteristic of single turning-point behaviour. The peak of the wave at relative value of 2 occurs at $z \approx(\pi / 2) c / \omega$.

ExERCISE. For a dielectric function $\varepsilon$ with linear variation in $z$, show that the exact solution of (4.34) is given by the Airy function and compare the Airy function to the WKB solution in (4.40).

If the variation of the dielectric function is such that propagating waves can be trapped between two turning points, the analysis corresponding to (4.40) leads to an
eigenvalue problem for the frequency $\omega$. Given a length $L$ between the turning points, only particular values of $\omega$ will allow the wave forms from either side to link up. Imagine picking a value of $z$ and reflecting the solution for $\delta E(z)$ symmetrically in figure $22(b)$ so that $\delta E(z)$ and its spatial derivative are continuous. This can only be satisfied if the spatial derivative of $\delta E(z)$ vanishes at the mirror point, which quantizes the relationship between the values of $\omega$ and $L$. For the two-turning-point problem we take the solution for the wave amplitude on the right-hand side of (4.40) associated with the turning point at $z_{0}$ and match it to the corresponding mirror image waves associated with the turning point at $z_{1}$ and introduce constant $C$ :

$$
\begin{equation*}
C=\frac{2 \cos \left[\frac{\omega}{c} \int_{z}^{z_{1}} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(z^{\prime}\right)-\pi / 4\right]}{\varepsilon^{1 / 4}(z)}=\frac{2 \cos \left[\frac{\omega}{c} \int_{0}^{z} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(z^{\prime}\right)-\pi / 4\right]}{\varepsilon^{1 / 4}(z)} \tag{4.41}
\end{equation*}
$$

For the left- and right-hand sides of (4.41) to be equal, the arguments of the cosines must be equal or the negative of one another so that $C=1$ or $C=-1$. Hence, we arrive at the relations,

$$
\begin{align*}
& \frac{\omega}{c} \int_{z}^{z_{1}} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(z^{\prime}\right)-\pi / 4=-\left[\frac{\omega}{c} \int_{0}^{z} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(z^{\prime}\right)-\pi / 4\right]+2 \pi \ell, \quad C=1, \ell=0,1,2, \ldots \\
& \quad \rightarrow \frac{\omega}{c} \int_{0}^{z_{1}} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(z^{\prime}\right)=\pi / 2+2 \pi \ell \\
& \quad \text { or } \frac{\omega}{c} \int_{0}^{z_{1}} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(z^{\prime}\right)=\pi / 2+(2 \ell+1) \pi, \quad C=-1 \\
& \quad \Rightarrow \frac{\omega}{c} \int_{0}^{z_{1}} \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(\omega, z^{\prime}\right)=\left(\ell+\frac{1}{2}\right) \pi \quad \text { or } \quad \frac{\omega}{c} \oint \mathrm{~d} z^{\prime} \varepsilon^{1 / 2}\left(\omega, z^{\prime}\right)=(2 \ell+1) \pi . \tag{4.42}
\end{align*}
$$

The final integral in (4.42) is from the turning point $\varepsilon=0$ at $z=0$ to the turning point at $z=z_{1}$ and return. We recognize this expression as the Bohr-Sommerfeld quantization rule. Equation (4.42) is an eigenequation that determines the eigenvalue $\omega$ for each value of $l$.

EXAMPLE. Consider an unmagnetized plasma with dielectric function: $\varepsilon(\omega, z)=1-$ $\omega_{p}^{2}(z) / \omega(\omega+\mathrm{i} v)$ and $\omega_{p}^{2}=\alpha^{2} z^{2}$ where $z=0$ is a reference altitude. Then $\operatorname{Re} \varepsilon=0$ has two symmetric turning points in $z$, and the eigenequation obtained from (4.42) is

$$
\begin{equation*}
\pi \frac{\omega}{c} \frac{\alpha}{\sqrt{\omega(\omega+\mathrm{i} \nu)}} \frac{\omega(\omega+\mathrm{i} \nu)}{\alpha^{2}}=\pi \frac{\omega}{c} \frac{\sqrt{\omega(\omega+\mathrm{i} \nu)}}{\alpha}=(2 \ell+1) \pi . \tag{4.43}
\end{equation*}
$$

For $v \rightarrow 0, \omega_{\ell}=\sqrt{2 l+1} \sqrt{\alpha c}, \ell=0,1,2, \ldots$
WKB breaks down near resonances as well as near turning points. At resonance $n=k c / \omega \rightarrow \infty$, i.e. $k \rightarrow \infty$ and $v_{\phi} \equiv \omega / k \rightarrow 0$. To resolve the difficulties posed by resonances we will abandon the cold-plasma restriction and include warm- or hotplasma effects.

### 4.6. Vlasov-Maxwell equations - linear electrodynamics

In this section we return to the examination of the Vlasov-Maxwell equations including consideration of waves and instabilities in a warm, magnetized plasma, e.g. Bernstein waves, a general dispersion relation and survey of waves, the Harris instability and the effects of gyro-resonance.

### 4.6.1. Bernstein waves (electrostatic model)

Bernstein waves named after Ira Bernstein are an example of a wave in a warm magnetized plasma. The simplest dispersion relation for Bernstein waves satisfies the electrostatic approximation, i.e. the perturbed electric field is oriented parallel to the wave vector and there is no magnetic perturbation associated with the wave. Most generally we can always represent the perturbed electric field as follows.

DEFINITION. $\delta \boldsymbol{E}=\delta E^{L} \hat{\boldsymbol{k}}+\delta \boldsymbol{E}^{T}$ where ' $L$ ' indicates the 'longitudinal' component which is parallel to the wave vector $\hat{\boldsymbol{k}}$ and ' $T$ ' indicates the 'transverse' component relative to the wave vector. (Note that 'perpendicular' will mean at right angles to the applied magnetic field $\boldsymbol{B}_{0}$.)

The general linear dispersion relation derived in $\S 4.2$ (4.11) is

$$
\begin{equation*}
\left(\stackrel{\leftrightarrow}{\varepsilon}-n^{2} \stackrel{\leftrightarrow}{\boldsymbol{I}}^{T}\right) \cdot \delta \boldsymbol{E}=0, \quad n^{2}=\frac{k^{2} c^{2}}{\omega^{2}} \tag{4.44}
\end{equation*}
$$

What are the conditions such that $\delta E^{L} \gg \delta E^{T}$ ? Consider a non-relativistic plasma with $\beta \equiv\left(v_{\text {th }} / c\right) \ll 1$. If $\omega / k \ll c$ so that $n \gg 1$ and $\varepsilon \sim O(1)$, then

$$
\begin{equation*}
\left|\frac{\delta E^{T}}{\delta E^{L}}\right| \approx \frac{1}{n^{2}}=\frac{\omega^{2}}{k^{2} c^{2}} \ll 1 \tag{4.45}
\end{equation*}
$$

The electrostatic dispersion relation for electron Bernstein waves propagating perpendicular to a uniform, applied magnetic field in a warm plasma ignoring ion motion is shown in figure 23 below (Shkarofsky 1966). Here $\Omega_{e}$ is the electron cyclotron frequency and $\omega_{\mathrm{uh}}=\left(\Omega_{e}^{2}+\omega_{\mathrm{pe}}^{2}\right)^{1 / 2}$ is the upper hybrid frequency. In the example shown in figure $23, \omega_{\mathrm{pe}} \approx 2.4 \Omega_{e}$. For the higher harmonics of the electron cyclotron frequency inevitably $\omega / k>c$, and the electrostatic approximation fails, invalidating the solution of the dispersion relation. We recall the solution of the cold-plasma electromagnetic dispersion relation plotted in figure 14.

The longitudinal dielectric function for perpendicular propagation in a warm plasma is derived in many textbooks, e.g. (9.36) of Clemmow and Dougherty,

$$
\begin{equation*}
0=\varepsilon\left(\omega, k_{\perp}\right)=1-\frac{\omega_{p}^{2}}{\Omega_{e}^{2}} \sum_{n=-\infty}^{\infty} \frac{\mathrm{e}^{-\lambda} \mathrm{I}_{n}(\lambda) / \lambda}{\frac{\omega}{n \Omega_{e}}-1}, \quad \lambda \equiv\left(k_{\perp} r_{e}\right)^{2}, \quad r_{e} \equiv \frac{v_{\mathrm{th}}}{\Omega_{e}}=\left(\frac{T_{e}}{m_{e} \Omega_{e}}\right)^{1 / 2} \tag{4.46}
\end{equation*}
$$

where $I_{n}$ are Bessel functions of complex argument and have limiting forms

$$
\begin{equation*}
\mathrm{I}_{n}(\lambda) \xrightarrow[\lambda \ll 1]{ } \frac{1}{n!}\left(\frac{1}{2} \lambda\right)^{n} \quad \text { and } \quad \mathrm{I}_{n}(\lambda) \xrightarrow[\lambda \gg 1]{ } \frac{\mathrm{e}^{\lambda}}{\sqrt{2 \pi \lambda}} . \tag{4.47}
\end{equation*}
$$

For frequencies near a particular cyclotron harmonic $\omega=\omega_{n}$ the sum over harmonics in (4.45) can be reduced to the one 'resonant' term in the series; then

$$
\begin{equation*}
\frac{\omega_{n}-n \Omega_{e}}{n \Omega_{e}}=\frac{\omega_{p}^{2}}{\Omega_{e}^{2}} \frac{\mathrm{e}^{-\lambda} \mathrm{I}_{n}(\lambda)}{\lambda} . \tag{4.48}
\end{equation*}
$$



Figure 23. Electron Bernstein waves $\omega / \Omega_{e}$ versus $k_{\perp}$ (Fitzpatrick 2014).

EXAMPLE. Consider launching a Bernstein wave by inserting a grid attached to power supply driven at a given frequency near the third electron cyclotron harmonic. Furthermore, assume that $\nabla B_{0}<0$ for increasing $x$ propagating into the plasma. Because the cyclotron frequency is decreasing, $\omega / \Omega_{e}$ and $k$ increase; and the group velocity $v_{g} \propto\left(\left(\mathrm{~d} \omega / \Omega_{e}\right) / \mathrm{d} k_{\perp}\right)>0$. As $x$ continues to increase, $k$ continues to increase on the branch and $\omega / \Omega_{e}$ reaches a maximum where the group velocity vanishes, at which point the wave packet must turn around. This is akin to ionospheric reflection of an electromagnetic wave (see §§4.5.1 and 4.5.2). These considerations are significantly relevant to applications such as wave heating of a magnetically confined plasma.

### 4.6.2. Instabilities, e.g. beam-cyclotron instability, ion acoustic, Dory-Guest-Harris

In the preceding subsection the electron Bernstein wave had a real frequency for a given $k_{\perp}$. How might the Bernstein wave be destabilized? Consider injection of a beam resonating with an electron Bernstein wave. For this example consider an injected ion beam. Because the ion-cyclotron frequency is so low $\Omega_{i} \ll \Omega_{e}$, $\omega$, $\gamma$, the unperturbed ion motion can be treated as unmagnetized. As a matter of consistency with the assumption that the ions are unmagnetized the ions should satisfy $r_{i} \equiv\left(u_{i} / \Omega_{i}\right) \gg 1 / k$. Where the beam velocity $u_{i}$ equals the Bernstein phase velocity $\omega / k$, we expect the possibility of complex conjugate roots of the dispersion relation, i.e. one of the roots is unstable. Solution of the dispersion relation yields

$$
\begin{equation*}
\frac{\delta \omega+\mathrm{i} \gamma}{\omega^{(0)}}=\left|\eta^{1 / 3}\right|\left(-\frac{1}{2}+\mathrm{i} \frac{\sqrt{3}}{2}\right), \quad \eta=\frac{\omega_{b}^{2}}{\omega_{p}^{2}} \frac{1}{\omega^{(0)} \frac{\partial \varepsilon}{\partial \omega}} \tag{4.49}
\end{equation*}
$$

in analogy to the weak-beam instability analysis in $\S 2.6 .1$. Here $\omega_{b}$ is the plasma frequency for the beam ions.

EXERCISE. Provide the details in deriving (4.49) and show that

$$
\begin{equation*}
\eta=\frac{\omega_{b}^{2} n \mathbf{I}_{n}(\lambda)}{\lambda \mathrm{e}^{\lambda} \Omega_{e}\left(n \Omega_{e}+\frac{n \omega_{p}^{2}}{\Omega_{e}} \frac{\mathrm{e}^{-\lambda} \mathrm{I}_{n}(\lambda)}{\lambda}\right)}, \quad \lambda \equiv\left(k_{\perp} r_{e}\right)^{2}, \quad r_{e} \equiv \frac{v_{\mathrm{th}}}{\Omega_{e}}=\left(\frac{T_{e}}{m_{e} \Omega_{e}}\right)^{1 / 2} \tag{4.50}
\end{equation*}
$$

EXERCISE (Magnetized ion-acoustic instability). Consider ions with velocity relative to the electrons $u_{i}$ satisfying the inequalities $c_{s}<u_{i}<v_{\text {the }}$. The beat of the ion-acoustic wave with the beam modes produces fast and slow beam modes $u_{i} \pm c_{s}$. From the general analysis leading to (2.96) evaluate the expression

$$
\gamma(\boldsymbol{k})=-\frac{\varepsilon_{I}\left(\boldsymbol{k}, \omega_{R}\right)}{\left.\frac{\partial}{\partial \omega} \varepsilon_{R}(\boldsymbol{k}, \omega)\right|_{\omega_{R}}} \sim \frac{\pi \omega_{p}^{2}}{\sqrt{2 \pi} k^{2} v_{\mathrm{the}}^{2}} \frac{\omega_{p}^{2}}{\Omega_{e}} \frac{n \mathbf{I}_{n}(\lambda)}{\lambda \mathrm{e}^{\lambda}}
$$

where in the numerator we use the contribution from the unmagnetized beam ions and the electron Bernstein formula is used in the denominator.

Example (Dory-Guest-Harris modes (Dory, Guest \& Harris 1965)). Suppose the velocity distribution $f\left(v_{\perp}\right)$ is not a Maxwellian. What happens to the Bernstein modes? Consider a family of velocity distributions: $f \sim\left(v_{\perp}^{2}\right)^{m} \mathrm{e}^{-v_{\perp}^{2} / v_{\text {in }}^{2}}$ Analysis of the electrostatic dispersion relation yields the following results:
(i) $m=1,2$ remains stable.
(ii) $m=3$ unstable if $\left(\omega_{p} / \Omega_{e}\right)>28$ and purely growing $(\operatorname{Re} \omega=0)$.
(iii) $m=4$ unstable if $\left(\omega_{p} / \Omega_{e}\right)>11$ and purely growing ( $\left.\operatorname{Re} \omega=0\right)$.
(iv) $m=6$ unstable if $\left(\omega_{p} / \Omega_{e}\right)>10$ and purely growing $(\operatorname{Re} \omega=0)$; also unstable at $\operatorname{Re} \omega=1.2 \Omega_{e}$.
(v) $m=\infty f \rightarrow \delta\left(v_{\perp}-v_{0}\right)$.

EXAMPLE. $f \sim \delta\left(v_{\perp}-v_{0}\right)$. For a $\delta$-function the longitudinal dielectric is (Crawford \& Tataronis 1965)

$$
\begin{equation*}
\varepsilon\left(\omega, k_{\perp}\right)=1-\frac{\omega_{p}^{2}}{\Omega_{e}^{2}} \sum_{n=-\infty}^{\infty} \frac{\frac{1}{b} \frac{\mathrm{~d}}{\mathrm{~d} b} \mathrm{~J}_{n}^{2}(b)}{\frac{\omega}{n \Omega_{e}}-1}, \quad b \equiv \frac{k_{\perp} v_{0}}{\Omega_{e}} \tag{4.51}
\end{equation*}
$$

with solution to $\varepsilon=0$ for $\omega$ near a cyclotron harmonic,

$$
\begin{equation*}
\frac{\omega-n \Omega_{e}}{n \Omega_{e}}=\frac{\omega_{p}^{2}}{\Omega_{e}^{2}} \frac{1}{b} \frac{\mathrm{~d}}{\mathrm{~d} b} \mathrm{~J}_{n}^{2}(b) \tag{4.52}
\end{equation*}
$$

We note that the wave energy is $\alpha \omega \partial \epsilon / \partial \omega$ can have either sign depending on the nearest harmonic $n$ and the wavenumber. As the left-hand side of (4.52) departs from zero so that the $n$ and $n-1$ neighbouring branches can merge into one another, and complex conjugate roots appear. A very strong interaction can take place, particularly if the wave energies have opposite signs, which leads to instability. Increasing the plasma density increases $\omega_{p}^{2} / \Omega_{e}^{2}$ and the magnitude of the right-hand side of (4.51), which exacerbates the tendency to instability.

EXAMPLE. Ordinary mode destabilized by anisotropy - consider an electromagnetic mode propagating across the magnetic field with electric field perturbation parallel to a uniform, applied magnetic field. With Maxwellian electrons the solution of (4.44) is

$$
\begin{align*}
\omega^{2} & =k^{2} c^{2}+\omega_{p}^{2}\left(1-\tau\left[1-\omega^{2} \sum_{\ell=-\infty}^{\infty} \frac{\mathrm{e}^{-\lambda} \mathrm{I}_{\ell}(\lambda)}{\omega^{2}-\ell^{2} \Omega_{e}^{2}}\right]\right) \\
& \tau \equiv \frac{T_{\|}}{T_{\perp}}, \quad \lambda=\left(\frac{k_{\perp} v_{\perp}^{\mathrm{th}}}{\Omega_{e}}\right)^{2}=\left(k_{\perp} r_{e}\right)^{2} . \tag{4.53}
\end{align*}
$$

The dispersion relation in (4.53) is solved numerically. One can assume that $\omega$ is complex and solve for $\tau$,

$$
\begin{equation*}
\tau=\frac{1+\frac{k^{2} c^{2}-\omega^{2}}{\omega_{p}^{2}}}{1+\omega^{2} \mathrm{e}^{-\lambda} \sum_{\ell=-\infty}^{\infty} \frac{\mathrm{I}_{\ell}(\lambda)}{\ell^{2} \Omega_{e}^{2}-\omega^{2}}} \rightarrow \frac{1+\frac{k^{2} c^{2}+\gamma^{2}}{\omega_{p}^{2}}}{1-\gamma^{2} \mathrm{e}^{-\lambda} \sum_{\ell=-\infty}^{\infty} \frac{\mathrm{I}_{\ell}(\lambda)}{\ell^{2} \Omega_{e}^{2}+\gamma^{2}}} \tag{4.54}
\end{equation*}
$$

for $\omega^{2} \rightarrow-\gamma^{2}$, a non-resonant, absolute instability. Furth analysed this instability from the perspective of the self-pinching of perturbed currents, calling the instability the 'prevalent instability' (Furth 1963).

### 4.6.3. Additional examples of waves in a plasma

Here we return to the subject matter introduced earlier in $\S 4$ and present a few additional examples of waves in a warm plasma. Small-amplitude waves in a plasma are either longitudinal $(\boldsymbol{\nabla} \times \boldsymbol{\delta} \boldsymbol{E}=0)$ or not longitudinal $(\boldsymbol{\nabla} \times \boldsymbol{\delta} \boldsymbol{E} \neq 0)$. Derivations of the equations in this section can be found in textbooks, for example, Clemmow and Dougherty, and Stix.

The dispersion relation for longitudinal waves in a uniform magnetic field was previously derived in $\S \S 2$, 3, and 4 . Using $(v / c) \ll 1,(\omega / k) \ll c$, and $\boldsymbol{k} \| \boldsymbol{\delta} \boldsymbol{E}$, the roots of the dispersion relation $\omega\left(k_{\|}, k_{\perp}\right)$ are determined by the solution of

$$
\begin{align*}
\varepsilon & \equiv \hat{k} \cdot \stackrel{\leftrightarrow}{\varepsilon} \cdot \hat{k}=1+\sum_{s} \chi_{s}(\boldsymbol{k}, \omega)=0  \tag{4.55a}\\
\chi_{s}(\boldsymbol{k}, \omega) & =-\frac{\omega_{s}^{2}}{k^{2}} \int \mathrm{~d}^{3} v \sum_{\ell=-\infty}^{\infty} \mathrm{J}_{\ell}^{2}\left(\frac{k_{\perp} v_{\perp}}{\Omega_{s}}\right) \frac{k_{z} \frac{\partial g}{\partial v_{z}}+\frac{\ell \Omega_{s}}{v_{\perp}} \frac{\partial g}{\partial v_{\perp}}}{k_{z} v_{z}-\left(\omega-\ell \Omega_{s}\right)} \tag{4.55b}
\end{align*}
$$

with $\int \mathrm{d}^{3} v g\left(v_{\|}, v_{\perp}\right)=1$. It is often assumed that $g$ is separable, $g\left(v_{\|}, v_{\perp}\right)=g\left(v_{\|}\right) g\left(v_{\perp}\right)$, e.g. $g\left(v_{\perp}\right)=\left(2 \pi v_{\text {th }}\right)^{-1} \exp \left(-v_{\perp}^{2} / 2 v_{\mathrm{th}}^{2}\right)$ a Gaussian, or $\left(v_{\perp}\right)$ a non-Gaussian as in the Dory-Guest-Harris instability.

For non-longitudinal waves, $\boldsymbol{k}$ and $\boldsymbol{\delta} \boldsymbol{E}$ are not parallel. Much of the existing analysis in the literature treats the plasma as cold with thermal corrections. There are many interesting examples. Calculations have established a relation between either whistler or ordinary waves and pinching instabilities, and a relation between Alfvèn waves and the firehose instability (see discussions in Freidberg (1987) and Krall \& Trivelpiece (1973)).

For $g$ a separable velocity distribution function and $g\left(v_{\perp}\right)$ a Gaussian, the susceptibility $\chi_{s}$ can be partially evaluated and reduced to

$$
\begin{align*}
\chi_{s}(\boldsymbol{k}, \omega) & =-\frac{\omega_{s}^{2}}{k^{2}} \int \mathrm{~d}^{3} v \sum_{\ell=-\infty}^{\infty} \mathrm{J}_{\ell}^{2}\left(\frac{k_{\perp} v_{\perp}}{\Omega_{s}}\right) \frac{k_{z} \frac{\partial g}{\partial v_{z}}+\frac{\ell \Omega_{s}}{v_{\perp}} \frac{\partial g}{\partial v_{\perp}}}{k_{z} v_{z}-\left(\omega-\ell \Omega_{s}\right)} \\
& =-\frac{\omega_{s}^{2}}{k^{2}} \int \mathrm{~d} v_{z} \sum_{\ell=-\infty}^{\infty} \mathrm{e}^{-b} \mathrm{I}_{\ell}(b) \frac{k_{z} \frac{\partial g_{\|}}{\partial v_{z}}-\frac{\ell \Omega_{s}}{v_{\mathrm{th}}^{2}} g_{\|}\left(v_{z}\right)}{k_{z} v_{z}-\left(\omega-\ell \Omega_{s}\right)} \tag{4.56}
\end{align*}
$$

where $b=\left(k_{\perp} v_{\perp \text { th }}\right)^{2}=\left(k_{\perp} r_{\perp}\right)^{2}$. We see the cyclotron resonance in the denominator on the right-hand side of (4.56). Recalling that $Z(V)=\int \mathrm{d} v_{z} g_{\|} /\left(v_{z}-V\right)$ then (4.56) becomes

$$
\begin{align*}
\chi_{s}(\boldsymbol{k}, \omega) & =-\frac{\omega_{s}^{2}}{k^{2}} \int \mathrm{~d} v_{z} \sum_{\ell=-\infty}^{\infty} \mathrm{e}^{-b} \mathrm{I}_{\ell}(b) \frac{k_{z} \frac{\partial g_{\|}}{\partial v_{z}}-\frac{\ell \Omega_{s}}{v_{\mathrm{th}}^{2}} g_{\|}\left(v_{z}\right)}{k_{z} v_{z}-\left(\omega-\ell \Omega_{s}\right)} \\
& =-\frac{\omega_{s}^{2}}{k^{2}} \sum_{\ell=-\infty}^{\infty} \mathrm{e}^{-b} \mathrm{I}_{\ell}(b)\left[Z^{\prime}\left(V_{\ell}\right)-\frac{\ell \Omega_{s}}{k_{z} v_{\mathrm{th}}^{2}} Z\left(V_{\ell}\right)\right], \quad V_{\ell}=\frac{\left(\omega-\ell \Omega_{s}\right)}{k_{z}} . \tag{4.57}
\end{align*}
$$

Some useful asymptotic forms for further evaluation of (4.56) are given in (4.46) for $\mathrm{I}_{n}(b)$ and in (2.91) and (2.92) for $\operatorname{Re} Z^{\prime}(V)$ and $\operatorname{Re} Z(V)$ for $V / v_{\mathrm{th}} \gg 1$.

Examples. (i) For Maxwellian $g_{\|}$and no drift, $V / v_{\text {th }} \rightarrow 0$, $\operatorname{Re} Z(V) \rightarrow 0$ and $\operatorname{Re} Z^{\prime}(V) \rightarrow-1 / v_{\mathrm{th}}^{2}$.
(ii) As $\Omega \rightarrow 0$ for weak magnetic fields, we recover the results in $\S 2.5$.
(iii) As the temperature goes to zero, the cold-plasma limit of the longitudinal susceptibility is recovered,

$$
\begin{equation*}
\chi_{s} \equiv \hat{k} \cdot \overleftrightarrow{\chi}_{s} \cdot \hat{k}=-\frac{\omega_{s}^{2}}{\omega^{2}} \frac{\omega-\Omega_{s}^{2} \cos ^{2} \theta}{\omega^{2}-\Omega_{s}^{2}} \tag{4.58}
\end{equation*}
$$

(iv) For ion waves or other very-low-frequency waves $\omega \rightarrow 0$, the limit in which the electron susceptibility is $\chi_{e}=1 / k^{2} \lambda_{e}^{2}$ can be recovered with some labour.
(v) In the strong field limit, $\Omega \gg \omega$. In this limit with $V$ large, the $\ell=0$ term is dominant in the infinite sum in (4.57); and one obtains

$$
\begin{equation*}
\chi_{s}(\boldsymbol{k}, \omega) \approx-\frac{\omega_{s}^{2}}{k^{2}} \sum_{\ell=-\infty}^{\infty} \mathrm{e}^{-b} \mathrm{I}_{0}(b) \frac{k_{z}^{2}}{\omega^{2}}\left(1+3 \frac{v_{\| \mathrm{th}}^{2}}{V^{2}}+\cdots\right) \tag{4.59}
\end{equation*}
$$

EXAMPLES. (i) Derive the dispersion relation for the electron plasma wave in the strong magnetic field limit: $\omega^{2}=\omega_{p}^{2} \cos ^{2} \theta+3 k_{z}^{2} v_{\| t \mathrm{~h}}^{2}$.
(ii) Derive the electron plasma wave dispersion relation for a finite magnetic field with $\omega \sim \Omega$ for $T_{e} \rightarrow 0$ and compare to electron Bernstein wave dispersion relation.
(iii) Derive the dispersion relation for the ion-acoustic wave in the strong magnetic field limit using the low-frequency limit for $\chi_{e}=1 / k^{2} \lambda_{e}^{2}$,

$$
\omega^{2}=\omega_{i}^{2}\left(1+\frac{1}{k^{2} \lambda_{e}^{2}}\right)^{-1} \cos ^{2} \theta
$$

(iv) Derive the dispersion relation for longitudinal ion-cyclotron waves $\omega \sim \ell \Omega_{i}$ using the low-frequency limit for $\chi_{e}=1 / k^{2} \lambda_{e}^{2}$. Assume that the wave phase velocity $V_{\ell} \gg v_{\mathrm{th}, i}$ to obtain

$$
\frac{\omega-\ell \Omega_{i}}{\ell \Omega_{i}}=\frac{T_{e}}{T_{i}} \mathrm{e}^{-b_{i}} \mathrm{I}_{\ell}\left(b_{i}\right)
$$

## PART 2

## 5. Miscellaneous topics

In this section six miscellaneous topics are covered, some of which were introduced earlier: (i) the Nyquist method for solving dispersion relations, (ii) analytic continuation in applications to solving for the plasma response to an electric field, (iii) the plasma dispersion function, (iv) non-analytic velocity distribution functions, (v) initial-value problems - linear response function and (vi) van Kampen modes.

### 5.1. Nyquist method for solving dispersion relations

One is frequently faced with the task of solving for the roots of a dispersion relation: $D(\omega)=0$, which may be a complicated function of $\omega$. Sometimes it is sufficient just to determine that there are no roots $\omega_{\ell}$ with $\operatorname{Im} \omega_{\ell}>0$. The Nyquist stability criterion is a graphical methodology that only requires evaluating the dispersion function $D$ as a function of complex $\omega$. Figure 24 illustrates the Nyquist stability criteria. In figure 24(a) there is a contour in the complex $\omega$ plane that is closed in the upper halfplane enclosing the possible roots of $D(\omega)=0$. The corresponding contour $D(\omega)$ is drawn in figure $24(b)$. In this example any value of $D$ in the region of the complex $D$ encircled by just one loop that encircles the origin maps to just one value of complex $\omega$ within the $\omega$ contour. Any value of $D$ in the region encircled by two loops maps to two values of complex $\omega$ within the $\omega$ contour.

THEOREM (Nyquist criteria). The number of complex $\omega$ roots in the upper half-plane equals the number of times the origin is encircled by loops in the D plane. This is the number of unstable roots.

### 5.2. Analytic continuation

Analytic continuation was introduced in $\S 2.5$ in the context of analysing the electrostatic plasma response,

$$
\left.\begin{array}{c}
\varepsilon(k, \omega)=1-\frac{\omega_{p}^{2}}{k^{2}} Z^{\prime}(v) \quad(v \equiv \omega / k) \\
Z(v)=\int_{-\infty}^{\infty} \mathrm{d} u \frac{g(u)}{u-v}(\operatorname{Im} v=\operatorname{Im} \omega / k>0)  \tag{5.1}\\
\varepsilon^{-1}(k, t)=\int \frac{\mathrm{d} \omega}{2 \pi} \frac{\mathrm{e}^{-\mathrm{i} \omega t}}{\varepsilon(k, \omega)} .
\end{array}\right\}
$$



Figure 24. (a) Contour in the complex $\omega$ plane encircling all roots $\omega_{\ell}$ with $\operatorname{Im} \omega_{\ell}>0$.
(b) Corresponding contour $D(\omega)$ in the complex $D$ plane encircling the origin twice.

Figure 3 displays the contour integration for the pulse response showing the depressed contour and poles of $\varepsilon^{-1}$ in the region of analytic continuation. When $v$ descends in the lower $\omega$ half-plane we depress the integration contour in $u$ down to loop around the pole in the region of analyticity to calculate $Z(v) . g(u)$ must be given as an analytic function. There are three cases to consider: (i) $v$ in the upper half-plane for which the integration contour remains on the real $u$ axis; (ii) $v$ on the real $u$ axis for which the integration contour takes a semi-circular loop below the pole and picks up a $i \pi g(v)$ contribution in addition to the principal value of the contour integral; (iii) $v$ below the real $u$ axis for which the integration contour takes a full circular loop around the pole (as in figure 3) and picks up a i $2 \pi g(v)$ contribution in addition to the contour integral.

EXERCISE. Show that for $g(u)$ a rational function, one can calculate $Z(v)$ in the upper $\omega$ half-plane and then analytically continue to the lower half-plane.

### 5.3. Plasma dispersion function - Fried-Conte function

Consider the longitudinal dielectric response when the velocity distribution is a Gaussian. Fried and Conte treated this subject in their 1961 book (Fried \& Conte 1961). We introduce the following notation and equations:

$$
\begin{equation*}
g(u)=\frac{1}{\sqrt{2 \pi} v_{\text {th }}} \mathrm{e}^{-u^{2} / 2 v_{\text {th }}^{2}}=\frac{1}{\sqrt{\pi} \bar{c}} \mathrm{e}^{-\eta^{2}}, \quad \eta=\frac{u}{\sqrt{2} v_{\text {th }}}=\frac{u}{\bar{c}}, \quad \bar{c}=\sqrt{2} v_{\text {th }}, \quad \zeta=\frac{v}{\bar{c}} . \tag{5.2}
\end{equation*}
$$

The Fried-Conte function or plasma dispersion function $z(\zeta)$ is then given by

$$
\begin{equation*}
z(v)=\frac{1}{\bar{c}}\left[\frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \mathrm{d} \eta \frac{\mathrm{e}^{-\eta^{2}}}{\eta-\zeta}\right]=\frac{1}{\bar{c}} z(\zeta) \tag{5.3}
\end{equation*}
$$

Limiting expressions are as follows:

$$
\begin{aligned}
\text { For real } \zeta: \quad & \operatorname{Im} z=\sqrt{\pi} \mathrm{e}^{-\zeta^{2}} \quad \operatorname{Im} z^{\prime}=-2 \sqrt{\pi} \zeta \mathrm{e}^{-\zeta^{2}} \\
& \operatorname{Re} z=\frac{1}{\sqrt{\pi}} P \int_{-\infty}^{\infty} \mathrm{d} \eta \frac{\mathrm{e}^{-\eta^{2}}}{\eta-\zeta}
\end{aligned}
$$



Figure 25. Warm velocity distribution function with sharp cutoffs.

$$
\begin{align*}
& \rightarrow-2 \zeta\left(1-\frac{2}{3} \zeta^{2}+\cdots\right), \quad \zeta \rightarrow 0 \\
& \rightarrow-\frac{1}{\zeta}\left(1+\frac{1}{2 \zeta^{2}}+\cdots\right), \quad \zeta \rightarrow \infty \\
\operatorname{Re} z^{\prime} & =\frac{1}{\sqrt{\pi}} P \int_{-\infty}^{\infty} \mathrm{d} \eta \frac{-2 \eta \mathrm{e}^{-\eta^{2}}}{\eta-\zeta} \\
& \rightarrow-2+4 \zeta^{2}, \quad \zeta \rightarrow 0 \\
& \rightarrow \frac{1}{\zeta^{2}}\left(1+\frac{3}{2 \zeta^{2}}+\cdots\right), \quad \zeta \rightarrow \infty \tag{5.4}
\end{align*}
$$

### 5.4. Non-analytic velocity distribution functions

Here we consider two examples of velocity distribution functions that are not analytic.
Example. Consider a warm plasma with sharp cutoffs in velocity (figure 25).

$$
\left.\begin{array}{rl}
g(u) & =\frac{3}{4 c^{3}}\left(c^{2}-u^{2}\right), \quad|u|<c \\
& =0, \quad|u|>c \\
g^{\prime}(u) & =-\frac{3 u}{2 c^{3}}, \quad|u|<c  \tag{5.5}\\
& =0, \quad|u|>c .
\end{array}\right\}
$$

The plasma dielectric response then derives from

$$
\left.\begin{array}{c}
\varepsilon(k, \omega)=1-\frac{\omega_{p}^{2}}{k^{2}} Z^{\prime}(v)  \tag{5.6}\\
Z^{\prime}(v)=\int_{-\infty}^{\infty} \mathrm{d} u \frac{g^{\prime}(u)}{u-v}=-\frac{3}{2 c^{3}} \int_{-c}^{c} \mathrm{~d} u \frac{u}{u-v}=-\frac{3}{2 c^{3}}\left[2 c+v \ln \frac{c-v}{-c-v}\right]
\end{array}\right\}
$$

The dielectric function in (5.6) has singularities at $v= \pm c$ and is symmetric with respect to changing the sign of $v=\omega / k$. The pulse response derives from

$$
\begin{equation*}
\varepsilon^{-1}(k, t)=\int \frac{\mathrm{d} \omega}{2 \pi} \frac{\mathrm{e}^{-\mathrm{i} \omega t}}{\varepsilon(k, \omega)} \tag{5.7}
\end{equation*}
$$



Figure 26. Diagram of contour integration in (5.7) after depressing the contour.

The contour integral in (5.7) is depicted in figure 26 where we show how the contour is depressed in the complex $\omega$ plane. The contributions on the depressed horizontal contour segments contribute negligibly because they rapidly damp, which leaves the contributions from the branch cuts and the two poles corresponding to roots of $\epsilon\left(\omega_{\ell}, k\right)=0$.

Example. Consider a relativistic distribution function that is a Gaussian in energy: $g(u) \propto \exp \left(-\beta m_{e} c^{2} / \sqrt{1-u^{2} / c^{2}}\right)$. This distribution function has an essential singularity at $u=c$.

### 5.5. Initial-value problem - response function

Consider the linear response to an external charge density perturbation $\rho^{\text {ext }}(\boldsymbol{k}, t>0)$ given the initial condition on the velocity distribution function $\delta f(\boldsymbol{k}, \boldsymbol{v} ; t=0)$. We calculate $\delta f(\boldsymbol{k}, \boldsymbol{v} ; t>0)$ from the solution of the linearized Vlasov equation,

$$
\begin{equation*}
\frac{\partial}{\partial t} \delta f_{s}(\boldsymbol{k}, \boldsymbol{v} ; t)+\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{v} \delta f_{s}=\frac{e_{s}}{m_{s}} \mathrm{i} \phi(\boldsymbol{k} ; t) \boldsymbol{k} \cdot \frac{\partial f_{0, s}}{\partial \boldsymbol{v}} . \tag{5.8}
\end{equation*}
$$

Definition. The Laplace transform is defined as $g(\omega)=\int_{0}^{\infty} \mathrm{d} t \mathrm{e}^{\mathrm{i} \omega t} g(t), \operatorname{Im} \omega>\gamma_{\max }$. The inverse Laplace transform is $g(t)=(1 / 2 \pi) \int \mathrm{d} \omega \mathrm{e}^{-\mathrm{i} \omega t} g(\omega), \operatorname{Im} \omega>\gamma_{\max }$ integrated along a contour $C$ in the upper $\omega$ half-plane.

THEOREM. Integrating by parts and Laplace transforming the Vlasov equation,

$$
\begin{align*}
& \int_{0}^{\infty} \mathrm{e}^{\mathrm{i} \omega t} \mathrm{~d}(\delta f)=\left.\left(\mathrm{e}^{\mathrm{i} \omega t} \delta f\right)\right|_{0} ^{\infty}-\int_{0}^{\infty} \delta f \mathrm{~d}\left(\mathrm{e}^{\mathrm{i} \omega t}\right) \Rightarrow \\
& \quad-\delta f(\boldsymbol{k}, \boldsymbol{v} ; t=0)-\mathrm{i} \omega \delta f(\boldsymbol{k}, \boldsymbol{v} ; \omega)+\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{v} \delta f(\boldsymbol{k}, \boldsymbol{v} ; \omega) \\
&=-\frac{e}{m} \delta \boldsymbol{E}(\boldsymbol{k}, \omega) \cdot \frac{\partial f_{0}}{\partial \boldsymbol{v}}  \tag{5.9a}\\
& \Rightarrow \delta f(\boldsymbol{k}, \boldsymbol{v} ; \omega)=\frac{\mathrm{i} \delta f(\boldsymbol{k}, \boldsymbol{v} ; t=0)}{\omega-\boldsymbol{k} \cdot \boldsymbol{v}}-\frac{e}{m} \phi(\boldsymbol{k}, \omega) \frac{\boldsymbol{k} \cdot \frac{\partial f_{0}}{\partial \boldsymbol{v}}}{\omega-\boldsymbol{k} \cdot \boldsymbol{v}} \tag{5.9b}
\end{align*}
$$

If $\rho^{\text {ext }}=0$ then Poisson's equation is

$$
\begin{equation*}
k^{2} \phi(\boldsymbol{k}, \omega)=4 \pi e \int \mathrm{~d}^{3} \boldsymbol{v} \delta f(\boldsymbol{k}, \boldsymbol{v}, \omega) \tag{5.10}
\end{equation*}
$$

We combine (5.9b) and (5.10) to obtain

$$
\begin{equation*}
\varepsilon(\boldsymbol{k}, \omega) \phi(\boldsymbol{k}, \omega)=\mathrm{i} \frac{4 \pi e}{k^{2}} \int \mathrm{~d}^{3} \boldsymbol{v} \frac{\delta f(\boldsymbol{k}, \boldsymbol{v} ; t=0)}{\omega-\boldsymbol{k} \cdot \boldsymbol{v}}, \quad \operatorname{Im} \omega>0 \tag{5.11}
\end{equation*}
$$

The solution of (5.11) for $\phi(\boldsymbol{k}, \omega)$ is obtained by dividing through by $\varepsilon$; and the solution for $\phi(\boldsymbol{k}, t)$ is obtained by taking the inverse Laplace transform of $\phi(\boldsymbol{k}, \omega)$. The contour integration for the inverse Laplace transform involves depressing the integration contour and looking for poles inside the integral, e.g. from the roots of $\varepsilon(\boldsymbol{k}, \omega)$ in (5.7).

## EXAMPLES.

(i) $\delta f(k, u ; t=0)$ an entire function of $u$, for example, $u \mathrm{e}^{-u^{2} / 2 a^{2}}$. The velocity integral in (5.11) yields a principal value contribution and a residue from the simple pole at $\omega-k v=0$. In the inverse Laplace transform the contour is depressed so that the dominant contributions arise from the residues due to the poles corresponding to roots of $\varepsilon(\boldsymbol{k}, \omega)$.
(ii) $\delta f(k, u ; t=0) \sim \delta\left(u-u_{0}\right)$. The velocity integral in (5.11) yields $1 /\left(\omega-k u_{0}\right)$ which is a simple pole on the real $\omega$ axis and never decays. We also note that $\delta f(x, u ; t=0) \sim \delta\left(u-u_{0}\right) \mathrm{e}^{\mathrm{i} k \cdot x}$. Thus, how a disturbance is initially excited can be essentially important, because in this example the initial condition does not decay; it persists forever. The inclusion of collisions is very effective in causing otherwise undamped modes to die off.
(iii) $\delta f(k, u ; t=0)$ is a square function of $u$ extending from $u=u_{1}$ to $u=u_{2}$. In the complex $\omega$ plane there are two branch cuts extending vertically down from $\omega=k u_{1}$ and $\omega=k u_{2}$ that affect $\phi(\boldsymbol{k}, t)$, and the contour integration must go along the branch cuts.

We note that the inverse Laplace transform of (5.9b) has the following form:
plus terms arising from initial conditions and oscillatory terms. If there are unstable roots $\omega_{\ell}$, the second term in (5.12) will overtake the first term and dominate after a short time. In contrast, damped roots will cause the second term to decay exponentially in time; and undamped oscillatory terms associated with initial conditions will survive.

Consider the second moment of $\delta f(\boldsymbol{k}, v ; t)$ for the example of $\delta f(k, v ; t=0)=$ $v \mathrm{e}^{-v^{2} / 2 a^{2}}$,

$$
\begin{equation*}
\int_{-\infty}^{\infty} \mathrm{d} v v^{2} \mathrm{e}^{-\mathrm{i} k v t} v \mathrm{e}^{-v^{2} / 2 a^{2}} \propto t^{n} \mathrm{e}^{-k^{2} a^{2} t^{2} / 2} \tag{5.13}
\end{equation*}
$$

As time progresses the exponential in (5.13) dies off faster than does any power of $t$. This result demonstrates that oscillatory terms when integrated over velocity or $k$ fall off faster than do terms coming from Landau poles which lead to terms $\mathrm{e}^{-() t}$ that evidence Landau damping. This result is referred to as phase mixing and destructive interference. These oscillatory terms can be observed through nonlinear effects as in the echo phenomenon. (Gould, O’Neil \& Malmberg 1967)

### 5.6. Van Kampen modes

Van Kampen modes (Van Kampen 1955) are a special class of normal modes in a plasma. Consider distribution functions and electric fields satisfying the linearized Vlasov and Poisson equations,

$$
\begin{equation*}
\delta f(\boldsymbol{k}, \boldsymbol{v}: t)=\delta f_{\omega}(\boldsymbol{k}, \boldsymbol{v}) \mathrm{e}^{-\mathrm{i} \omega t} \quad \boldsymbol{E}(\boldsymbol{k}: t)=\boldsymbol{E}(\boldsymbol{k})_{\omega} \mathrm{e}^{-\mathrm{i} \omega t}=-\mathrm{i} \boldsymbol{k} \phi_{\omega} \mathrm{e}^{-\mathrm{i} \omega t} . \tag{5.14}
\end{equation*}
$$

From the Vlasov-Poisson equations for a single species, e.g. electrons with infinitely massive ions,

$$
\begin{gather*}
(\omega-\boldsymbol{k} \cdot \boldsymbol{v}) \delta f(\boldsymbol{k}, \omega ; \boldsymbol{v})=-\frac{e}{m} \phi(\boldsymbol{k}, \omega) \boldsymbol{k} \cdot \frac{\partial f_{0}}{\partial \boldsymbol{v}}  \tag{5.15a}\\
k^{2} \phi(\boldsymbol{k}, \omega)=4 \pi e \int \mathrm{~d}^{3} \boldsymbol{v} \delta f(\boldsymbol{k}, \omega ; \boldsymbol{v}) \tag{5.15b}
\end{gather*}
$$

We assume that $\omega$ is not real and divide (5.15a) by $\omega-\boldsymbol{k} \cdot \boldsymbol{v} \neq 0$ to obtain

$$
\begin{equation*}
\delta f(\boldsymbol{k}, \omega ; \boldsymbol{v})=(P) \frac{1}{\omega-\boldsymbol{k} \cdot \boldsymbol{v}}\left(-\frac{e}{m}\right) \phi(\boldsymbol{k}, \omega) \boldsymbol{k} \cdot \frac{\partial f_{0}}{\partial \boldsymbol{v}}+\lambda(\boldsymbol{k}, \omega) \delta(\omega-\boldsymbol{k} \cdot \boldsymbol{v}), \tag{5.16}
\end{equation*}
$$

where $(P)$ denotes the principal value. Note that the inclusion of the $\delta$-function term still satisfies the Vlasov equation because $c(\omega-\boldsymbol{k} \cdot \boldsymbol{v}) \delta(\omega-\boldsymbol{k} \cdot \boldsymbol{v})=0$. This is a singular solution for the distribution function that violates linearization. However, superposition of these $\omega$ Fourier components can eliminate the singularity.

We next substitute (5.16) in (5.15b), integrate over the two velocity directions perpendicular to $\boldsymbol{k}$ and go to one spatial dimension,

$$
\begin{equation*}
k^{2} \phi(k, \omega)=-\frac{4 \pi e^{2}}{m} \phi(k, \omega)(P) \int \mathrm{d} v \frac{k \frac{\partial f_{0}}{\partial v}}{\omega-k v}+4 \pi e \lambda(k, \omega) \int \mathrm{d} v \delta(\omega-k v) \tag{5.17}
\end{equation*}
$$

The integral of the $\delta$-function gives $\int \mathrm{d} v \delta(\omega-k v)=1 / k$. We then solve for $\lambda(k, \omega)$,

$$
\begin{align*}
\lambda(k, \omega) & =\frac{k^{3}}{4 \pi e} \phi(k, \omega)\left[1-\frac{\omega_{p}^{2}}{k^{2}}(P) \int \mathrm{d} v \frac{g^{\prime}(v)}{v-\omega / k}\right] \\
& =\frac{k^{3}}{4 \pi e} \phi(k, \omega)\left[1-\frac{\omega_{p}^{2}}{k^{2}} \operatorname{Re} Z^{\prime}(v)\right]=\frac{k^{3}}{4 \pi e} \phi(k, \omega) \operatorname{Re} \varepsilon(k, \omega) . \tag{5.18}
\end{align*}
$$

Using (5.16) and (5.18) we obtain the distribution function for the van Kampen modes

$$
\begin{equation*}
\delta f(k, \omega ; v)=\frac{k^{3}}{4 \pi e} \phi(k, \omega)\left[\operatorname{Re} \varepsilon(k, \omega) \delta(\omega-k v)-\frac{\omega_{p}^{2}}{k^{2}}(P) \frac{g^{\prime}(v)}{\omega-k v}\right] \tag{5.19}
\end{equation*}
$$

for real $\omega$. We note that there is no eigenvalue for $\omega$; all real values of $\omega$ are allowed. Moreover, $k$ is just a parameter. We can arbitrarily assign the amplitude of a specific Fourier component of $\phi(k, \omega)=1$. The Van Kampen modes are a continuous spectrum in $\omega$ of singular normal modes described by (5.19). A superposition of van Kampen modes can be non-singular and damp due to phase mixing and destructive interference.

Consider the special case that $\omega$ is complex. In this case $\delta(\omega-\boldsymbol{k} \cdot \boldsymbol{v})=0$; we can set $\lambda(k, \omega)=0$ and from the right-hand side of (5.18) we recover the familiar dielectric function and dispersion relation for $\operatorname{Im} \omega>0$

$$
\begin{equation*}
\left[1-\frac{\omega_{p}^{2}}{k^{2}}(P) \int \mathrm{d} v \frac{g^{\prime}(v)}{v-\omega / k}\right]=\left[1-\frac{\omega_{p}^{2}}{k^{2}} \operatorname{Re} Z^{\prime}(v)\right]=0 \tag{5.20}
\end{equation*}
$$

For $\operatorname{Im} \omega<0$ there are difficulties with analytic continuation in the lower half- $\omega$ plane, and there is no proper dielectric function. For $\operatorname{Im} \omega>0$ we have a discrete set of normal modes $\omega_{\ell}$ as a function of $k$.

## 6. Nonlinear Vlasov plasma

### 6.1. Vlasov-Poisson system in one dimension

6.1.1. Stationary nonlinear solutions - Bernstein, Greene and Kruskal (BGK) modes

Our consideration of nonlinear phenomena begins with the Coulomb model, i.e. the Vlasov-Poisson equations model. The Vlasov-Maxwell equations system is significantly more complex.

DEFINITION. The velocity distribution function is $f\left(x, y, z, v_{x}, v_{y}, v_{z}\right)$.

Theorem. The Vlasov-Poisson equations are

$$
\begin{gather*}
\left(\frac{\partial}{\partial t}+\boldsymbol{v} \cdot \nabla_{x}+\frac{e}{m} \boldsymbol{E} \cdot \nabla_{v}\right) f(\boldsymbol{x}, \boldsymbol{v} ; t)=0  \tag{6.1a}\\
\boldsymbol{E}=-\nabla \phi \quad \nabla^{2} \phi=-4 \pi \int \mathrm{~d}^{3} \boldsymbol{v} \sum_{s} e_{s} f_{s}(\boldsymbol{x}, \boldsymbol{v} ; t) \tag{6.1b}
\end{gather*}
$$

The second step of simplification is to reduce the number of variables by going to one dimension,

$$
\begin{gather*}
\left(\frac{\partial}{\partial t}+v_{x} \frac{\partial}{\partial x}+\frac{e}{m} E_{x} \frac{\partial}{\partial v_{x}}\right) f\left(x, v_{x} ; t\right)=0  \tag{6.2a}\\
E_{x}=-\frac{\partial}{\partial x} \phi \quad \frac{\partial^{2}}{\partial x^{2}} \phi=-4 \pi \int \mathrm{~d} v_{x} \sum_{s} e_{s} f_{s}\left(x, v_{x} ; t\right) \tag{6.2b}
\end{gather*}
$$

where we have integrated over the ignorable velocity dimensions $v_{y}$ and $v_{z}$. This is the nonlinear system we hope to solve.

We cannot solve (6.2) analytically for arbitrary initial conditions. However, there are some specific examples where analytic solutions do exist. One such example is due to Bernstein, Greene and Kruskal (Bernstein, Greene \& Kruskal 1957) who constructed solutions of the one-dimensional nonlinear Vlasov-Poisson equations that are stationary in time: $\phi(x, t)=\Phi(x-V t)$. In the wave frame $x-V t=x^{\prime}$ the solutions
for $f$ and $\Phi$ are stationary. Solution of the nonlinear Vlasov equation is obtained by the method of characteristics. In the wave frame the Vlasov equation becomes

$$
\begin{equation*}
\left(v_{x} \frac{\partial}{\partial x}+\frac{e_{s}}{m_{s}} E_{x} \frac{\partial}{\partial v_{x}}\right) f_{s}\left(x, v_{x} ; t\right)=0 . \tag{6.3}
\end{equation*}
$$

A constant of the particle motion is $H=\frac{1}{2} m v^{2}+e \phi$. The most general solution of the Vlasov equation is any function of the constants of the motion: $f_{s}(x, v)=F_{ \pm}^{s}(H)$. The $\pm$ subscript in $F_{ \pm}^{s}$ denotes velocity directionality. For trapped particles $(H<0)$ there is only one solution for $F$, while there are two solutions for untrapped (passing) particles $(H>0)$. The Poisson equation becomes

$$
\begin{equation*}
\frac{\partial^{2}}{\partial x^{2}} \phi=-4 \pi \int \mathrm{~d} v_{x} \sum_{s} e_{s} f_{s}\left(x, v_{x} ; t\right)=-4 \pi \sum_{s} e_{s} \sum_{ \pm} \int_{e \phi(x)}^{\infty} \mathrm{d} H \frac{F_{ \pm}^{s}(H)}{\sqrt{2 m_{s}\left(H-e_{s} \phi(x)\right)}}, \tag{6.4a}
\end{equation*}
$$

where $\left.\mathrm{d} H\right|_{x \text { const. }}=m v \mathrm{~d} v \quad$ and $\quad \mathrm{d} v=\frac{\mathrm{d} H}{m v}=\frac{\mathrm{d} H}{\sqrt{2 m_{s}\left(H-e_{s} \phi(x)\right)}}$.
We now limit ourselves to a periodic potential over a length $\lambda$. Our Fourier representation will retain all harmonics of $k=2 \pi / \lambda$. The frequency in the laboratory $(L)$ frame is related to the frequency in the wave $(W)$ frame by $\omega^{(L)}=\omega^{(W)}+k V$. In the notation used here $e \equiv$ the charge of the electron $=-4.8 \times 10^{-10}$ esu, and singly charged ions have the opposite sign charge. The number density is computed by integrating and summing over $\pm$ to obtain,

$$
\begin{equation*}
n_{s}=\int_{e \phi(x)}^{\infty} \mathrm{d} H \frac{F^{s}(H)}{\sqrt{2 m_{s}\left(H-e_{s} \phi(x)\right)}} \tag{6.5}
\end{equation*}
$$

Example. Consider a velocity distribution function that is constant in a defined band of energy, $F_{ \pm}^{s}(H)=C, H_{1} \leqslant H \leqslant H_{2}$ for electrons (flip order $H_{1}$ and $H_{2}$ for ions), and select the electron energy band so that the electrons are untrapped. For the density computation, $F^{s}=\sum_{ \pm} F_{ \pm}^{s}$, and we obtain

$$
\begin{equation*}
n_{s}(\phi)=C \int_{H_{1}}^{H_{2}} \frac{\mathrm{~d} H}{\sqrt{2 m(H-e \phi(x))}} \tag{6.6}
\end{equation*}
$$

with $x$ fixed so that the number density is a function of electric potential $\phi(x)$

$$
\begin{equation*}
\frac{\mathrm{d}^{2} \phi}{\mathrm{~d} x^{2}}=-4 \pi \rho(\phi) \quad \rho(\phi) \equiv \sum_{s} e_{s} n_{s}(\phi) \tag{6.7}
\end{equation*}
$$

At this point, we identify the potential $\phi$ as the pseudo-position $X$ and $x$ as the pseudotime $T$ for a pseudo-particle in a pseudo-potential $U$

$$
\begin{equation*}
\frac{\mathrm{d}^{2} X}{\mathrm{~d} T^{2}}=-4 \pi \rho(X)=-\frac{\mathrm{d} U}{\mathrm{~d} X} \tag{6.8}
\end{equation*}
$$

DEFINITION. The pseudo-potential is $U(X)=4 \pi \int \mathrm{~d} X^{\prime} \rho\left(X^{\prime}\right)=4 \pi \int \mathrm{~d} \phi^{\prime} \rho\left(\phi^{\prime}\right)$.
We solve (6.132) by introducing the energy

$$
\begin{equation*}
E=\frac{1}{2}\left(\frac{\mathrm{~d} X}{\mathrm{~d} T}\right)^{2}+U(X) \tag{6.9}
\end{equation*}
$$

solving algebraically for $\mathrm{d} X / \mathrm{d} T=\mathrm{d} \phi / \mathrm{d} x$, separating variables and integrating to obtain

$$
\begin{equation*}
T=\int^{X} \frac{\mathrm{~d} X^{\prime}}{\sqrt{2\left(E-U\left(X^{\prime}\right)\right)}} \quad x=\int^{\phi} \frac{\mathrm{d} \phi^{\prime}}{\sqrt{2\left(E-U\left(\phi^{\prime}\right)\right)}} . \tag{6.10}
\end{equation*}
$$

What is the physical significance of $E$ ? The term $\frac{1}{2}(\mathrm{~d} X / \mathrm{d} T)^{2}=\frac{1}{2}(\mathrm{~d} \phi / \mathrm{d} x)^{2}$ is the square of the electric field. The second term $U(\phi)=\sum_{s} 4 \pi \int(\mathrm{~d} H F(H) / \sqrt{2 m}) \int \mathrm{d} \phi$ $(1 / \sqrt{H-e \phi}) \propto-\sum_{s} 4 \pi \int(\mathrm{~d} H F(H) / \sqrt{2 m}) \sqrt{H-e \phi} \propto-\sum_{s} \int m v^{2} f(x, v) \mathrm{d} v \sim-p$ which is the pressure or kinetic energy density, if we recall our earlier consideration of the moment equations in § 2.4 and (2.33)-(2.35).

## THEOREM.

$$
\begin{equation*}
\frac{\mathscr{E}}{4 \pi}=\frac{E^{2}}{8 \pi}-\int \rho \mathrm{d} \phi=\frac{E^{2}}{8 \pi}-p(x) \tag{6.11}
\end{equation*}
$$

EXAmple. Consider a situation in which the particles are relatively cold and the potential is weak so that in the wave frame $H_{s}=\frac{1}{2} m_{s} V^{2}+$ const. and $F^{s}(H)=n_{0} \sqrt{2 m_{s} H_{s}} \delta\left(H-H_{s}\right)$. The electrons are untrapped. Then $p_{s}(\phi)=\int(\mathrm{d} H) /$ $\left(\sqrt{2 m\left(H-e_{s} \phi\right)}\right) 2\left(H-e_{s} \phi\right) F(H) \propto \sum_{s} 2 n_{0} \sqrt{H_{s}\left(H_{s}-e_{s} \phi\right)}$, while the species number density is given by $n_{s}(\phi)=\int\left(\mathrm{d} H / \sqrt{2 m\left(H-e_{s} \phi\right)}\right) F(H) \propto \sum_{s} n_{0} \sqrt{H_{s} /\left(H_{s}-e_{s} \phi\right)}$. There are integration constants in (6.9) and (6.10), which are resolved by boundary and initial conditions, and physical arguments. For small $\phi$ we expand $p_{s}(\phi)$ and $n_{s}(\phi)$ in power series in $e_{s} \phi$ through $\phi^{2}$. Because $e_{s}$ changes sign between ions and electrons, the coefficient of the linear term in $e_{s} \phi$ in $n_{s}$ must vanish (and, hence, in $p_{s}$ also) to guarantee overall charge density neutrality, which constrains an integration constant.

THEOREM. Using $U(\phi)=-4 \pi p(\phi)+$ const. it can be shown that $U(\phi)=$ $\frac{1}{2}\left(\omega_{p} / V\right)^{2} \phi^{2}+O\left(\phi^{3}\right)+$ const. With $U$ a quadratic in $\phi$, equation (6.8) is the equation for a simple harmonic oscillator with pseudo-frequency $\Omega$ given by $\Omega=\omega_{p} / V$ in the wave frame, which corresponds to a period (pseudo-wavelength) $\lambda=2 \pi / \Omega=2 \pi V / \omega_{p}$ or $k=2 \pi / \lambda=\omega_{p} / V$. The Doppler-shifted frequency in the laboratory frame is then $\omega=k V=\omega_{p}$ regardless of wavelength because the solution of the Poisson-Vlasov equation was stationary in the wave frame. This recovers the standard result for a small-amplitude wave in a cold plasma and lays the foundation for using the same machinery for the fully nonlinear problem.

### 6.1.2. Nonlinear electron wave

Consider the case of a nonlinear electron wave. To simplify, consider infinitely massive, stationary ions: $m_{i} \longrightarrow \infty$ and finite mass electrons. Although the ions
are stationary, they are charged and contribute to $U(\phi): U(\phi)=4 \pi n_{0} e \phi-8 \pi n_{0}$ $\sqrt{H_{e}\left(H_{e}-e \phi\right)}, e=-4.8 \times 10^{-10}$ esu. We next introduce a change of variables

$$
\left.\begin{array}{c}
\Phi \equiv \frac{e \phi}{H_{e}} \quad \psi \equiv 1-\Phi \quad \sigma \equiv \sqrt{\psi} \quad \tau \equiv 1+\sigma  \tag{6.12}\\
\alpha \equiv \frac{8 \pi n_{0}}{m_{e} V^{2}} \quad E^{\prime}=\mathrm{E} / \alpha \quad E^{\prime \prime}=E^{\prime}-1
\end{array}\right\}
$$

We substitute (6.12) into (6.10) and integrate to obtain an elementary integral whose result is

$$
\begin{equation*}
x(\phi)=\sqrt{\frac{2}{\alpha}} \frac{H_{e}}{e}\left[\sqrt{E^{\prime \prime}-\tau^{2}}+\sin ^{-1}\left(\frac{\tau}{\sqrt{E^{\prime \prime}}}\right)\right] \tag{6.13}
\end{equation*}
$$

where $E$ is the energy integral of the pseudo-particle above the bottom of the minimum in $U$ as a function of $e \phi$ and is chosen so that at $e \phi=H_{e}, E=U\left(e \phi=H_{e}\right)$. The amplitude of $e \phi$ is limited by $H_{e}$, i.e. $\Phi \leqslant 1$. Near $\Phi=1$ for this choice of $E$, the variation of $\Phi$ as a function of $x$ is cusp like, $\delta \Phi \sim-(\delta x)^{2 / 3}$.

EXERCISE. From (6.13) calculate the periodicity length $\lambda(\Delta \phi)$ for $V$ as $\Delta \phi \rightarrow 0$ and recover the earlier result in the laboratory frame $\omega=\omega_{p}$ independent of wave amplitude. In a one-dimensional cold plasma with charge sheets, there is no change in the characteristic oscillation frequency from $\omega=\omega_{p}$ as long as there is no crossing of the sheets. Sort out the units in (6.8)-(6.13).

Again consider a velocity distribution function that is constant in a defined band of energy, $F_{ \pm}^{s}(H)=C, H_{1} \leqslant H \leqslant H_{2}$ for electrons and zero otherwise (with cold, infinitely massive ions). The electric potential is small, but finite; and the electrons are untrapped. For the density computation, $F^{s}=\sum_{ \pm} F_{ \pm}^{s}$; and we determine $U$ from (6.5)(6.8). On expanding in a Taylor series in powers of $\phi$ we obtain

$$
\begin{equation*}
U(\phi)=\frac{1}{2} \Omega_{0}^{2} \phi^{2}+\frac{1}{3} \alpha \phi^{3}+\frac{1}{4} \beta \alpha \phi^{4}+\cdots, \tag{6.14}
\end{equation*}
$$

where the coefficients in the power series are

$$
\begin{gather*}
\Omega_{0}^{2}=\frac{2 \pi n_{0} e^{2}}{\sqrt{H_{1} H_{2}}}  \tag{6.15a}\\
\alpha=\frac{\pi n_{0} e^{3}}{2\left(H_{1} H_{2}\right)^{3 / 2}}\left(H_{1}+H_{2}+\sqrt{H_{1} H_{2}}\right)  \tag{6.15b}\\
\beta=\frac{\pi n_{0} e^{4}}{4\left(H_{1} H_{2}\right)^{5 / 2}}\left(H_{1}^{2}+H_{1} H_{2}+H_{2}^{2}+\left(H_{1}+H_{2}\right) \sqrt{H_{1} H_{2}}\right) . \tag{6.15c}
\end{gather*}
$$

The presence of higher-order terms in $\phi$ means that the pseudo-potential $U$ is anharmonic. The solutions for the anharmonic oscillator are still given in terms of elliptic functions. From Landau and Lifshitz, Mechanics, 3rd Edition, equation (28.13), the characteristic frequency is given by

$$
\begin{equation*}
\Omega=\Omega_{0}+\left(\frac{3}{8} \frac{\beta}{\Omega_{0}}-\frac{5}{12} \frac{\alpha^{2}}{\Omega_{0}^{3}}\right) \phi_{0}^{2} \tag{6.16}
\end{equation*}
$$

where the turning points are approximately $-\phi_{0}$ and $\phi_{0}$. In the laboratory frame $\omega=$ $k V=2 \pi / \lambda=\Omega V$ where we let $\left(H_{1}+H_{2}\right) / 2=\frac{1}{2} m_{e} V^{2}$ assuming that $\Delta H \equiv H_{2}-H_{1}=$ $m u \Delta u \ll H$. Finally, we obtain the frequency of the BGK mode in the laboratory frame

$$
\begin{equation*}
\omega^{2}=\omega_{p}^{2}\left\{1+\frac{k^{2} \Delta u^{2}}{4 \omega_{p}^{2}}\left[1+\frac{5}{2}\left(\frac{e \phi_{0}}{m_{e} V^{2}}\right)^{2}\right]\right\} \tag{6.17}
\end{equation*}
$$

Recall that the linear dispersion relation for an infinitesimal amplitude electron wave with a square velocity distribution of electrons from $u=-c$ to $u=c$ is $\omega^{2}=\omega_{p}^{2}+k^{2} c^{2}$. Different frequency shifts in the dispersion relation in (6.17) will be produced depending on the distribution of particles relative to the bottom of the periodic potential wells. For example, trapped electrons in the wave potential produce a negative frequency shift.

### 6.1.3. Nonlinear ion wave and solitary pulse solutions

Consider the case of a nonlinear ion wave. We model the electrons to be in thermal equilibrium and responding adiabatically to the low-frequency ion wave. We further assume $\omega \lesssim \omega_{i}$. We recall that from linear theory $\omega^{2}=k^{2} c_{s}^{2} /\left(1+k^{2} \lambda_{D}^{2}\right)$ where $c_{s}^{2}=$ $T_{e} / m_{i}$ for $\widetilde{T}_{i} \ll T_{e}$ and $\lambda_{D}^{2}=T_{e} / 4 \pi n e^{2}$. Here we adopt the convention that the electron charge is $-e$ and the ion charge is $+e$. One can show that

$$
\left.\begin{array}{c}
p(\phi)=n_{0}\left[T_{e} e^{\beta e \phi}+2 \sqrt{H_{i}\left(H_{i}-e \phi\right)}\right]  \tag{6.18}\\
U(\phi)=\text { const. }+\alpha \phi^{2}+\beta \phi^{3}+\cdots
\end{array}\right\}
$$

In the acoustic range $k^{2} \lambda_{D}^{2} \ll 1$ with $\left|e \phi / T_{e}\right| k^{2} \lambda_{D}^{2} \ll 1$, then from (6.18) following the same methodology as in the nonlinear electron wave one obtains the nonlinear dispersion relation for the ion wave

$$
\begin{equation*}
\omega^{2}\left(k, \phi_{0}\right)=k^{2} c_{s}^{2}-\frac{5}{6} \omega_{i}^{2}\left|\frac{e \phi_{0}}{T_{e}}\right|^{2} \tag{6.19}
\end{equation*}
$$

Example. Consider a potential pulse moving at a velocity near the ion sound speed, with $\phi \rightarrow 0$ for $x= \pm \infty$ in the frame moving with the pulse and a maximum $\phi=\phi_{0}$ at $x=0$. Compute $U(\phi)$ as in (6.18). From (6.10) one can compute an elementary integral leading to the results

$$
\left.\begin{array}{c}
\phi(x)=\phi_{0} \operatorname{sech}^{2}\left(x / x_{0}\right) \quad \text { with } x_{0}=\lambda_{D} \sqrt{\frac{3 T_{e}}{\left|e \phi_{0}\right|}},  \tag{6.20}\\
\frac{V^{2}}{c_{s}^{2}}=1+\frac{2}{3} \frac{\left|e \phi_{0}\right|}{T_{e}}>1 .
\end{array}\right\}
$$

DEFINITION. This corresponds to a small-amplitude solitary pulse, called a smallamplitude soliton. This is a particular limiting case of a wave train with $\lambda \rightarrow \infty$.
[Editor's note: at the time of these lectures, there had not been much attention given to electromagnetic BGK modes.]


Figure 27. Phase-space orbits in the wave frame for untrapped ( $W>e \phi_{0}$ ) and trapped ( $W<e \phi_{0}$ ) orbits, where $W$ is the particle energy. The 'separatrix' denotes where the particle energy $W=e \phi_{0}$.

### 6.2. Nonlinear Landau damping

### 6.2.1. Phase-space dynamics

We assume there is a very weakly damped small-amplitude electron wave, $|\gamma| \ll \omega$ and $\left|e \phi / T_{e}\right| \ll 1$. In the wave frame we also assume the wave is a stationary BGK mode. At very small amplitude the wave is close to sinusoidal. Particles with velocities close to the phase velocity of the wave are Landau damped. We focus attention on these resonant particles. A schematic of the ( $x^{\prime}, v^{\prime}$ ) phase-space particle orbits for both trapped and untrapped particles in the wave frame is shown in figure 27. For an arbitrarily small-amplitude wave the trapped particle orbits are elliptic. Finite-amplitude effects introduce anharmonic effects that distort the ellipses.

### 6.2.2. Quasilinear analysis - linear waves and nonlinear particle orbits

Consider a particle with energy near the top of the wave trough, i.e. $H \sim e \phi_{0}$ for $x \sim x_{0}$ where $\phi\left(x_{0}\right)=-\phi_{0}$. The range of velocities around $v=V$ in the laboratory frame in which particles interact strongly with the wave scales as $\Delta v \sim \sqrt{e \phi_{0} / m}$. We note that along any orbit segment in which the magnitude of $v$ grows the particle is extracting energy from the wave, but there is a compensating loss of energy as the magnitude of $v$ decreases. In consequence, there is no net energy exchange in a stationary wave over time to leading order. We proceed with a direct calculation of the energy exchange of a particle with a wave

$$
\left.\begin{array}{c}
\Delta v(t)=\int_{0}^{t} \mathrm{~d} t^{\prime} \dot{v}\left(t^{\prime}\right)=\frac{e}{m} \int_{0}^{t} \mathrm{~d} t^{\prime} E\left(x^{\prime}\right)=\frac{e}{m} k \phi_{0} \int_{0}^{t} \mathrm{~d} t^{\prime} \sin k x^{\prime}, \quad x^{\prime} \equiv x\left(t^{\prime}\right) \\
x^{\prime}=x_{0}+\int_{0}^{t^{\prime}} \mathrm{d} t^{\prime \prime} v\left(t^{\prime \prime}\right)=x_{0}+\int_{0}^{t^{\prime}} \mathrm{d} t^{\prime \prime}\left[v_{0}+\frac{e}{m} k \phi_{0} \int_{0}^{t^{\prime \prime}} \mathrm{d} t^{\prime \prime \prime} \sin k x^{\prime \prime \prime}\right]  \tag{6.21}\\
x^{\prime \prime \prime} \approx x_{0}+v_{0} t^{\prime \prime \prime} .
\end{array}\right\}
$$

After making substitutions, performing the nested time integrations and expanding for small values of the electric field as it influences $x^{\prime}$ in $\sin \left(k x^{\prime}\right)$, we average with respect to $x_{0}$ over a wavelength to obtain

$$
\begin{equation*}
\langle\Delta v(t)\rangle_{x_{0}}=\frac{1}{2}\left(\frac{e}{m} E_{0}\right)^{2} \frac{1}{k^{2} v_{0}^{3}}\left[2\left(\cos k v_{0} t-1\right)+k v_{0} t \sin k v_{0} t\right] . \tag{6.22}
\end{equation*}
$$

In the limit $k v_{0} t \ll 1$, the expression in the square bracket on the right-hand side of (6.22) $[\cdots] \rightarrow-\frac{1}{12}\left(k v_{0} t\right)^{4}$; and $\langle\Delta v\rangle_{x_{0}} \propto-v_{0} t^{4}$. Thus, in the wave frame a resonant particle moving faster than the wave $\left(v_{0}>0\right)$ is decelerated; and a resonant particle moving slower than the wave $\left(v_{0}<0\right)$ ) is accelerated at early times. Recall that for a stable velocity distribution that damps the wave, there are more particles slower than the wave phase velocity than particles faster than the wave. The wave tends to drag resonant particles to its velocity irrespective of whether the particle is trapped or untrapped.

EXERCISE. Verify the calculation leading to (6.22).
Next consider the time dependence of the wave momentum density. The momentum density $P_{W}$ of the wave is related to the energy density $E_{W}$ of a wave,

$$
\begin{equation*}
P_{W}=\frac{k}{\omega} E_{W}=k \frac{\partial \varepsilon}{\partial \omega}\left\langle\frac{|\boldsymbol{E}|^{2}}{8 \pi}\right\rangle_{x}=\frac{k}{\omega_{p}} \frac{E_{0}^{2}}{8 \pi} \quad \varepsilon=1-\frac{\omega^{2}}{\omega_{p}^{2}} \tag{6.23}
\end{equation*}
$$

in the laboratory frame. The derivation of the expression in (6.23) is Galilean invariant and valid in any frame. If the wave is exponentially damped, $E_{0}(t)=E_{0}(0) \mathrm{e}^{\gamma t}, \gamma<0$; and the wave momentum and energy densities inherit this time dependence. At early time $\mathrm{e}^{\gamma t} \approx 1+\gamma t$, and the wave momentum and energy densities vary linearly in time

$$
\begin{equation*}
\Delta P_{W}(t) \approx P_{W}(0) 2 \gamma t \tag{6.24}
\end{equation*}
$$

We now calculate whether the sum of the wave and particle momentum densities is conserved. We integrate over all possible initial velocities of the resonant particles in the wave frame

$$
\begin{align*}
& \left.\Delta P\right|_{\text {resonant }}=\int_{\text {resonant }} \mathrm{d} v_{0} f_{0}\left(v_{0}\right) m\langle\Delta v(t)\rangle_{x_{0}} \\
& \quad=\int_{\text {resonant }} \mathrm{d} v_{0}\left[f_{0}(0)+v_{0} f_{0}^{\prime}(0)+\cdots\right] m\langle\Delta v(t)\rangle_{x_{0}} \\
& \quad=\frac{m}{k^{2}} \int_{\text {resonant }} \mathrm{d} v_{0} \frac{1}{v_{0}^{3}}\left[f_{0}(0)+v_{0} f_{0}^{\prime}(0)+\cdots\right] \frac{1}{2}\left(\frac{e}{m} E_{0}\right)^{2}[2(\cos \eta-1)+\eta \sin \eta] \\
& \approx \frac{m}{k^{2}} \frac{1}{2}\left(\frac{e}{m} E_{0}\right)^{2} \int_{-\infty}^{\infty} \mathrm{d} v_{0} \frac{1}{v_{0}^{3}} v_{0} f_{0}^{\prime}(0)[2(\cos \eta-1)+\eta \sin \eta] \\
& =\frac{m}{k^{2}} \frac{1}{2}\left(\frac{e}{m} E_{0}\right)^{2} f_{0}^{\prime}(0) k t \int_{-\infty}^{\infty} \mathrm{d} \eta \frac{1}{\eta^{2}}[2(\cos \eta-1)+\eta \sin \eta]=-\frac{\pi}{2} \frac{m}{k^{2}}\left(\frac{e}{m} E_{0}\right)^{2} f_{0}^{\prime}(0) k t \\
& \quad \text { where } \eta=k v_{0} t . \tag{6.25}
\end{align*}
$$

We can evaluate the $\gamma$ in (6.24) using $\gamma / \omega_{p}=(\pi / 2)\left(\omega_{p} / k\right)^{2} g^{\prime}(v)=(\pi / 2)\left(\omega_{p} / k\right)^{2}$ $\left(f^{\prime}(0) / n_{0}\right)$. Substituting this into (6.23) and (6.24) we deduce that

$$
\begin{equation*}
\Delta P_{W}+\left.\Delta P\right|_{\text {resonant }}=0 \tag{6.26}
\end{equation*}
$$

6.2.3. Trapped and untrapped particles - evolution of the distribution function

We next consider the trajectories of the trapped and untrapped (passing) particles. In the wave frame, if particle trajectories are localized to a small excursion distance
relative to the bottom of the potential well, $\phi\left(x_{0}\right)=-\phi_{0}$, then the potential can be expanded around $x_{0}$,

$$
\begin{align*}
e \phi(x) & =e \phi_{0} \cos k x \rightarrow e \phi_{0}\left(-1+\frac{1}{2} k^{2} \delta x^{2}+\cdots\right) \\
& \rightarrow H=\frac{1}{2} m v^{2}+e \phi_{0} \frac{1}{2} k^{2} \delta x^{2}+\text { const. } \tag{6.27}
\end{align*}
$$

Equation (6.27) is the Hamiltonian for a simple harmonic oscillator whose characteristic oscillation frequency (bounce frequency $\omega_{B}$ ) is

$$
\begin{equation*}
\omega_{B}=\sqrt{\frac{k^{2} e \phi_{0}}{m}} \tag{6.28}
\end{equation*}
$$

with the restriction that the electric field amplitude temporal variation is negligible on the time scale $1 / \omega_{B}$, i.e. $\gamma / \omega_{B} \ll 1$. We recall that our analysis also requires that $e \phi_{0} \ll T$ and, hence, $\Delta v \ll v_{\text {th }}$ and $\omega_{B} \ll k v_{\text {th }}$. Initially the wave transfers energy and momentum to the resonant particles, but a little later (on the time scale of the trapped particle bounce motion), energy and momentum are transferred back from the particles to the wave. (O'Neil 1965; Morales \& O’Neil 1972). The general solutions of the equations of motion resulting from (6.27) for $e \phi(x)=e \phi_{0} \cos k x$ are given in terms of Jacobi elliptic functions. A useful reference for elliptic functions is Byrd \& Friedman (1971).

For untrapped particles, $H \geqslant e \phi_{0}$, the solution of the equation of motion is given by

$$
\begin{equation*}
v(t)= \pm \sqrt{\frac{2}{m}\left(H+e \phi_{0}\right)} \operatorname{dn}\left(\frac{\omega_{B} t}{\kappa}, \kappa\right), \quad \text { where } \kappa \equiv \sqrt{\frac{2 e \phi_{0}}{H+e \phi_{0}}}<1 \tag{6.29}
\end{equation*}
$$

without being precise about the initial conditions for the velocity of the particle. The passing particle velocity has a periodic variation with period given by

$$
\begin{equation*}
\tau_{t}=\frac{2 \kappa K(\kappa)}{\omega_{B}} \tag{6.30}
\end{equation*}
$$

where $K$ is one of the Jacobi elliptic functions

$$
\begin{align*}
K(\kappa) & \rightarrow \ln \frac{4}{\sqrt{1-\kappa^{2}}}, \quad \text { for } \kappa \rightarrow 1 \\
& \rightarrow \frac{\pi}{2}, \quad \text { for } \kappa \rightarrow 0 \tag{6.31}
\end{align*}
$$

The Jacobi elliptic function $\operatorname{dn}\left(\omega_{B} t / \kappa, \kappa\right)=1$ for $t=0$ and is bounded by

$$
\begin{equation*}
\sqrt{1-\kappa^{2}} \leqslant \operatorname{dn}\left(\frac{\omega_{B} t}{\kappa}, \kappa\right) \leqslant 1 . \tag{6.32}
\end{equation*}
$$

For trapped particles $H<e \phi_{0}$, the solution of the equation of motion is given by

$$
\begin{equation*}
v(t)= \pm \sqrt{\frac{2}{m}\left(H+e \phi_{0}\right)} \mathrm{cn}\left(\omega_{B} t, \kappa\right), \quad \text { where } \kappa \equiv \sqrt{\frac{H+e \phi_{0}}{2 e \phi_{0}}}<1 . \tag{6.33}
\end{equation*}
$$

The trapped particle velocity has a periodic variation with period given by

$$
\begin{equation*}
\tau_{t}=\frac{4 K(\kappa)}{\omega_{B}} \rightarrow \frac{2 \pi}{\omega_{B}} \quad \text { for } \kappa \rightarrow 0 \tag{6.34}
\end{equation*}
$$



Figure 28. Initial particle orbits in phase space in wave frame (ref. figure 6.14 in D. R. Nicholson, Introduction to Plasma Theory (Wiley 1983)).

The Jacobi elliptic function $\mathrm{cn}\left(\omega_{B} t, \kappa\right)$ is bounded by $\pm 1$. A distribution of particles sharing the same energy, but distributed in space, will have different relative phases in the wave frame: $t \rightarrow t-t_{1}$. A distribution of particle energies can be parameterized in velocity by their distribution of initial speeds (initial conditions are trivial constants of the motion).

Figures 28,29 and 30 illustrate the particle orbits and time evolution of quantities associated with the particles and the wave. We know from (6.25) and (6.26) that the momentum in the resonant particles initially grows at the expense of the wave amplitude. Thus, the evolution of the wave amplitude shown in figure 29 and the momentum in the resonant particles mirror one another. The wave amplitude decreases and then increases, but not back to its initial amplitude; and the momentum in resonant particles first increases and then decreases, but not back to its initial amplitude. The period of the oscillations is approximately given by the trapped particle bounce period, equation (6.34). The oscillations in the damping rate are at the bounce frequency and phase mix to zero, while the oscillations in the frequency shift are at twice the bounce frequency and asymptote to a finite value (figure 30).
[Editor' note: there were several other contemporaneous papers in the literature addressing the nonlinear frequency shift of an electron plasma wave in addition to the work of Morales \& O’Neil (1972), e.g. Dewar (1972), Manheimer \& Flynn (1971) and Lee \& Pocobelli (1972).]

THEOREM. Consider a velocity distribution function $f$ that is initially uniform in position $x$ and decreasing in $|v| . f \longrightarrow f_{ \pm}(H)$ where $H=\frac{1}{2} m v^{2}+e \phi(x)$ is a constant of the motion. Hence, $f$ will be a constant of the motion on the phase-space orbits.

Exercise. Read O'Neil's and Morales and O'Neil's seminal papers (O'Neil 1965; Morales \& O'Neil 1972). The Morales and O'Neil paper has an illuminating discussion of the relationship between the nonlinear increments in the damping rate and frequency, and the excursions in the momentum and energy in the wave and the particles.


Figure 29. Langmuir wave amplitude versus time (ref. figure 6.17 in D. R. Nicholson, Introduction to Plasma Theory (Wiley 1983)).


FIG. 1. Damping coefficient shift versus time.


FIG. 2. Frequency shift versus time.

Figure 30. Figures 1 and 2 from G. J. Morales and T. M. O’Neil, Phys. Rev. Lett. 28, 417 (1972) illustrating the self-consistent effects of nonlinear Landau damping on the total damping rate and frequency shift of the electrostatic wave.

### 6.2.4. Effects of trapped particles on longitudinal plasma waves and saturation of instabilities

The interaction of a finite-amplitude wave with a velocity distribution that is decreasing with respect to velocity in the neighbourhood of the velocity equal to the phase velocity of the wave is depicted in figure 31. Particles travelling slower than the wave are accelerated, while particles traveling faster than the wave are decelerated. Because there are more particles slower than the phase velocity, there is net momentum and energy transferred from the wave to the particles. The region of flattening in velocity is centred at the phase velocity of the wave and the width of the region is associated with the trapping width $\backsim \sqrt{e \phi_{0} / m}$. An estimate of the asymptotic field amplitude of the electron plasma wave can be computed from

$$
\begin{equation*}
E_{0}(t)=E_{0}(0) \exp \left(\int_{0}^{t} \mathrm{~d} t^{\prime} \gamma\left(t^{\prime}\right)\right) \sim E_{0}(0)\left(1-\left|\gamma_{L}\right| \tau_{T}\right) \tag{6.35}
\end{equation*}
$$

where $\gamma$ is the total growth rate $\left(\gamma<0\right.$ due to Landau damping, $\left.\gamma_{L}<0\right)$ and is given by $\gamma=\gamma_{L}+\delta \Gamma$ with $\delta \Gamma$ given in figure $30, \gamma_{L} \sim\left(\omega_{p}^{3} / k^{2}\right)\left(f_{0}^{\prime} / n_{0}\right)$ and $\tau_{T} \sim$ $\sqrt{m / e \phi_{0}}(1 / k)$. The sign of $\gamma$ is opposite the sign of the time derivative of the resonant


Figure 31. Schematic showing flattening of the velocity distribution function due to particle trapping.
particles, equations (6.25) and (6.26). Thus, the wave settles down to a BGK mode of constant amplitude over a few bounce times.

The interaction of an unstable wave(s) with resonant particles is expected to evolve as follows. Consider a bump-on-tail velocity distribution function (figure 12). The velocity inversion in the distribution function is a source of free energy to destabilize a wave with phase velocity $v$. There are more resonant particles with $u>v_{\mathrm{ph}}$ than for $u<v_{\mathrm{ph}}$, which allows the wave to grow at the expense of the energy in the resonant particles which decreases (more particles are decelerated than are accelerated). Thus, wave-particle interactions lead to a flattening of the distribution function near the phase velocity of the wave. In contrast to figure 29, the plot of the logarithm of the wave energy versus time for the unstable case shows linear growth in time until there is sufficient flattening of the velocity distribution function (due to mixing) stabilizes the plasma. The wave energy no longer grows, but we expect decaying oscillations similar to those in figure 29. If the wave-particle interaction is relatively coherent because the wave spectrum is dominated by a single wave, then the relative peaks in the oscillations of the wave energy will be separated by the characteristic trapped particle bounce time $\tau_{T}$.

We expect that the growing wave will approach saturation when the trapped particles accumulate $\pi$ radians of phase in the growing wave

$$
\begin{align*}
\pi & =\int_{0}^{t_{\mathrm{sat}}} \omega(t) \mathrm{d} t=k \sqrt{\frac{e}{m}} \int_{0}^{\phi_{\mathrm{sat}}} \frac{\mathrm{~d} \phi_{0}}{\mathrm{~d} \phi_{0} / \mathrm{d} t=\gamma\left(\phi_{0}\right) \phi_{0}} \phi_{0}^{1 / 2}(t) \\
& =k \sqrt{\frac{e}{m}} \int_{0}^{\phi_{\mathrm{sat}}} \frac{\mathrm{~d} \phi_{0}}{\phi_{0}^{1 / 2} \gamma\left(\phi_{0}\right)} \approx 2 k \sqrt{\frac{e}{m} \frac{\phi_{\mathrm{sat}}^{1 / 2}}{\gamma_{L}}} . \tag{6.36}
\end{align*}
$$

Hence,

$$
\begin{equation*}
\frac{\omega_{T}\left(\phi_{0}^{\mathrm{sat}}\right)}{\gamma_{L}} \approx \frac{\pi}{2} \quad \text { and } \quad\left|e \phi_{0}^{\mathrm{sat}}\right|=m\left(\frac{\pi}{2} \frac{\gamma_{L}}{k}\right)^{2} \tag{6.37}
\end{equation*}
$$

Equation (6.36) is derived assuming the growth rate $\gamma$ is well approximated by the linear growth rate $\gamma_{\mathrm{L}}$ up to the point of saturation. This assumption is reasonably good until the last e-folding or two of the growing wave, when the growth rate starts to decrease to zero. Research in Fried et al. (1970) showed numerically that for a broad range of parameters $\omega_{T}\left(\phi_{0}^{\text {sat }}\right) / \gamma_{L} \approx 3.2$. We note that this analysis has assumed
that a single wave grows up to dominate the spectrum so that the wave-particle interaction is coherent. This assumption has eliminated the noise of other waves that might otherwise be expected to grow.

EXERCISE. Using energy conservation, derive a relation between the width in velocity over which the velocity distribution is flattened and the wave amplitude at saturation; and using (6.37) and the results in § 2.6.1 relate the velocity width to the linear growth rate and the plasma parameters for the weak beam-plasma instability. Show for the bump-on-tail velocity distribution subject to flattening, that the distance $\Delta v$ between the two locations where $g^{\prime}=0$ scales as

$$
\begin{equation*}
\frac{v_{T}}{\Delta v} \sim \frac{n_{\text {bump }}}{n_{0}} \frac{V}{v_{\text {th }}}\left(\frac{V}{\Delta v}\right)^{2}, \tag{6.38}
\end{equation*}
$$

where $V$ is the phase velocity and $v_{T}=\left(e \phi / m_{e}\right)^{1 / 2}$ is the trapping velocity. We note that $n_{\text {bump }} / n_{0} \ll 1, V / v_{\text {th }}>1$, and $(V / \Delta v)^{2} \gg 1$, which leaves a good deal of freedom in determining $v_{T} / \Delta v$ in (6.38).

The nonlinear Landau damping of an ion wave ought to be similar to that of the damping of an electron wave considered already. However, in the case of the ion wave one should consider the resonant interactions of both electrons and ions.

There are many calculations and simulations of the saturation of instabilities in a collisionless plasma. Here is brief list:
(i) Bump-on-tail, which leads to a BGK mode.
(ii) Weak-beam instability (linear evolution discussed in § 2.6.1), which leads to a BGK mode (O’Neil, Winfrey \& Malmberg 1971).
(iii) Electron ion two-stream instability, which leads to a chaotic state (Hirose 1978).
(iv) Two-stream instability (equal beams), which leads to a chaotic state (Freidberg \& Marder 1971).
(v) Ion-acoustic instability (Nishikawa \& Wu 1969).
(vi) Cyclotron instability (Aamodt \& Bodner 1969).

The references given here are only representative and by no means complete.
EXAMPLE. Weak-beam instability - we can derive additional results for the saturation of the weak-beam instability. The linear attributes of the weak-beam instability were presented in §2.6.1. In the weak-beam instability there is an approximate resonance between the beam velocity $u_{b}$ and the unstable wave phase velocity $v_{\phi}$. However, a careful analysis shows that $v_{\phi}<u_{b}$ for instability. The results for the dispersion relation of the weak-beam instability in (2.77) are

$$
\begin{equation*}
\frac{\delta \omega}{\omega_{0}}=\eta^{1 / 3}=\left|\eta^{1 / 3}\right|\left\{1,-\frac{1}{2} \pm \mathrm{i} \sqrt{\frac{3}{2}}\right\}, \quad \eta \approx \frac{1}{2} \frac{\omega_{b}^{2}}{\omega_{p}^{2}} \tag{6.39}
\end{equation*}
$$

where $\omega_{0}=k_{0} u_{b}$ and $\omega=\omega_{0}+\delta \omega$, i.e. the unstable wave frequency is slightly downshifted. The wave energy and the wave momentum densities are given by

$$
\begin{equation*}
E_{w}=\omega \frac{\partial \varepsilon}{\partial \omega} \frac{|E|^{2}}{8 \pi}=\omega \frac{2}{\omega_{p}} \frac{|E|^{2}}{8 \pi}, \quad P_{w}=k \frac{2}{\omega_{p}} \frac{|E|^{2}}{8 \pi} \tag{6.40}
\end{equation*}
$$

where $v_{\phi}=\omega / k$. The wave momentum density grows at the expense of the momentum density in the weak beam, and the wave energy density grows as the momentum density grows. Consider a single wave with $k=k_{0}$ the most unstable wave such that

$$
\begin{equation*}
\phi(x, t)=\phi_{0}(t) \mathrm{e}^{\mathrm{i} k_{0} x}+\text { c.c. } \quad \phi_{0}(t)=\phi_{0}(0) \exp \left(-\mathrm{i} \int_{0}^{t} \mathrm{~d} t^{\prime} \omega\left(t^{\prime}\right)\right) . \tag{6.41}
\end{equation*}
$$

The beam can be represented as a sum of particles

$$
\left.\begin{array}{c}
x_{i}(t) \quad i=1, \ldots, N_{B} \quad n_{B}(x, t)=\sum_{i=1}^{N_{B}} \delta\left(x-x_{i}(t)\right)  \tag{6.42}\\
n_{B}\left(k_{0}, t\right) \equiv \int \mathrm{d} x \mathrm{e}^{-\mathrm{i} k_{0} x} n_{B}(x, t)=\sum_{i=1}^{N_{B}} \mathrm{e}^{-\mathrm{i} k_{0} x_{i}(t)} .
\end{array}\right\}
$$

The particle simulation then solves the nonlinear equations of motion given by

$$
\begin{equation*}
m \ddot{x}_{i}(t)=\mathrm{e}\left(-\mathrm{i} k_{0}\right) \phi\left(x_{i}, t\right) \tag{6.43}
\end{equation*}
$$

and the Poisson equation to determine the electric potential $\phi_{0}$ self-consistently:

$$
\begin{equation*}
k_{0}^{2} \phi\left(k_{0}, t\right)=\frac{4 \pi e n_{b}\left(k_{0}, t\right)}{\varepsilon\left(k_{0}, \omega\right)} \quad \varepsilon\left(k_{0}, \omega\right)=1-\frac{\omega_{p}^{2}}{\omega^{2}}-\frac{\omega_{B}^{2}}{\left(\omega-k_{0} u_{b}\right)^{2}} . \tag{6.44}
\end{equation*}
$$

In the beam frame the dielectric function becomes

$$
\begin{equation*}
\varepsilon\left(k_{0}, \omega\right)=1-\frac{\omega_{p}^{2}}{\left(\omega+k_{0} u_{b}\right)^{2}}-\frac{\omega_{b}^{2}}{\omega^{2}} \approx 2 \frac{\omega}{\omega_{p}} \tag{6.45}
\end{equation*}
$$

at resonance using $\omega_{b}^{2} \ll \omega_{p}^{2}$. If we use (6.45) in the Poisson equation, equation (6.44), and Fourier transform from $\omega$ to $t$, one obtains that the wave amplitude grows as the beam density perturbation grows

$$
\begin{equation*}
\mathrm{i} k_{0}^{2} \frac{\mathrm{~d} \phi_{0}\left(x_{0}, t\right)}{\mathrm{d} t}=-\frac{1}{2} \omega_{p} 4 \pi e n_{b}\left(k_{0}, t\right) \tag{6.46}
\end{equation*}
$$

The simulation then advances the nonlinear equations of motion equations (6.42) and (6.43), and the Poisson equation (6.46). A plot of $\ln \phi_{0}$ versus time from simulations shows initial linear growth consistent with (6.39) and then saturation with amplitude oscillations having a period consistent with the trapping frequency $\omega_{T}=k_{0}\left|e \phi_{0} / m\right|^{1 / 2}$. The saturation amplitude and saturation time observed in the simulations scale as

$$
\begin{equation*}
\frac{\left|E_{0}^{\mathrm{sat}}\right|^{2}}{8 \pi} \approx n_{b} m u_{b}^{2}\left|\eta^{1 / 3}\right| \quad \omega_{0} t^{\mathrm{sat}} \approx \eta^{-1 / 3} \gg 1 \tag{6.47}
\end{equation*}
$$

This scaling of the saturation amplitude for the weak-beam instability in (6.47) differs significantly from the scaling in (6.37) for the bump-on-tail instability.
[Editor's note: there is a discussion of the saturation of the weak-beam instability based on particle simulations in § 5-11 of C. K. Birdsall and A. B. Langdon, Plasma Physics via Computer Simulation (McGraw-Hill, New York, 1985).]

### 6.3. Stability of electrostatic BGK modes - sideband instability of Kruer, Dawson and Sudan

Kruer, Dawson \& Sudan (1969) proposed a theory to explain the observation of satellite frequencies in an experiment (Wharton, Malmberg \& O'Neil 1968) in which a large-amplitude electron plasma wave trapped electrons. The instability grows up from noise and results from the interaction of the trapped particles and the large-amplitude primary wave. The derivation considers particles trapped near the bottom of the wave troughs. The electrons oscillate back and forth at the trapping frequency $\omega_{T}=\omega_{B}=k_{0}\left|e \phi_{0} / m\right|^{1 / 2}$. Consider the electron equation of motion in one spatial dimension for the trapped electrons as perturbed by a small-amplitude disturbance,

$$
\begin{equation*}
\ddot{x}_{j}=\frac{e}{m} \delta E\left(x_{j}, t\right)-\omega_{B}^{2} x_{j} \tag{6.48}
\end{equation*}
$$

whose Fourier transform from time to frequency is

$$
\begin{equation*}
-\omega^{2} x_{j}(\omega)=\frac{e}{m} \delta E\left(x_{j}, \omega\right)-\omega_{B}^{2} x_{j}(\omega) \tag{6.49}
\end{equation*}
$$

and

$$
\begin{equation*}
x_{j}(\omega)=\frac{1}{\omega_{B}^{2}-\omega^{2}} \frac{e}{m} \delta E\left(x_{j}, t\right) . \tag{6.50}
\end{equation*}
$$

The charge density for the trapped electrons and the resulting Poisson equation are

$$
\begin{equation*}
n_{T}(x, t)=\sum_{j} \delta\left(x-x_{j}(t)\right) N_{j} \quad \mathrm{i} k \delta E(k, \omega)=\frac{4 \pi e \delta n_{T}(k, \omega)}{\varepsilon(k, \omega)}, \tag{6.51}
\end{equation*}
$$

where $N_{j}$ is the number of trapped electrons in the $j$ th equally spaced wave trough. The spatially averaged unperturbed trapped particle number density is then $n_{T}^{o}=N_{1} / \lambda_{o}$. The Fourier transform of $n_{T}(x, t)$ from $x$ to $k$ space is

$$
\begin{align*}
n_{T}(k, t) & =\lambda_{o} n_{T}^{o} \sum_{j} \int \mathrm{~d} x \mathrm{e}^{-\mathrm{i} k x} \delta\left(x-x_{j}(t)\right) \\
& =\lambda_{o} n_{T}^{o} \sum_{j} \mathrm{e}^{-\mathrm{i} k x_{j}(t)} \approx \lambda_{o} n_{T}^{o} \sum_{j} \mathrm{e}^{-\mathrm{i} k x_{j}^{o}(t)}\left[1-\mathrm{i} k \delta x_{j}(t)\right], \tag{6.52}
\end{align*}
$$

where $x_{j}(t)=x_{j}^{o}+\delta x_{j}(t)$ has been linearized for small oscillations. From (6.51) and (6.52)

$$
\begin{equation*}
\delta E(k, \omega)=-\frac{4 \pi e}{\varepsilon(k, \omega)}\left[\frac{2 \pi}{k_{0}} n_{T}^{o} \sum_{j} \mathrm{e}^{-\mathrm{i} k x_{j}^{o}} \delta x_{j}(\omega)\right] \tag{6.53}
\end{equation*}
$$

from which one obtains

$$
\begin{equation*}
\delta E(k, \omega)=\frac{4 \pi n_{T}^{o} e^{2}}{m} \frac{1}{\left(\omega^{2}-\omega_{B}^{2}\right) \varepsilon(k, \omega)} \frac{2 \pi}{k_{0}} \sum_{j} \mathrm{e}^{-\mathrm{i} k x_{j}^{o}} \int \frac{\mathrm{~d} k^{\prime}}{2 \pi} \delta E\left(k^{\prime}, \omega\right) \mathrm{e}^{\mathrm{i} k^{\prime} x_{j}^{o}} \tag{6.54}
\end{equation*}
$$

where the 'plasma frequency' associated with the trapped electrons is $\omega_{p T}^{2} \equiv$ $4 \pi n_{T}^{o} e^{2} / m \ll \omega_{B}^{2}$. Equation (6.54) can be rewritten using the identity $k_{0}^{-1} \sum_{\ell} \mathrm{e}^{\mathrm{i}\left(k^{\prime}-k\right) 2 \pi \ell / k_{0}}$ $=\sum_{\ell=-\infty}^{\infty} \delta\left(k^{\prime}-k-\ell k_{0}\right)$ :

$$
\begin{equation*}
\left(\omega^{2}-\omega_{B}^{2}\right) \delta E(k, \omega)=\frac{4 \pi n_{T}^{o} e^{2}}{m} \frac{1}{\varepsilon(k, \omega)} \sum_{\ell=-\infty}^{\infty} \int \mathrm{d} k^{\prime} \delta E\left(k^{\prime}, \omega\right) \delta\left(k^{\prime}-k-\ell k_{0}\right) \tag{6.55}
\end{equation*}
$$

One $k$ mode is coupled to all $k+\ell k_{o}$ where $\ell$ is an integer and $k_{0}$ is the effective lattice constant. The integral on the right-hand side of (6.55) is trivial, and one obtains

$$
\begin{align*}
\frac{\left(\omega^{2}-\omega_{B}^{2}\right)}{\omega_{p T}^{2}} \delta E(k, \omega) & =\frac{1}{\varepsilon(k, \omega)} \sum_{\ell=-\infty}^{\infty} \delta E\left(k+\ell k_{0}, \omega\right) \\
& \Rightarrow \sum_{\ell^{\prime}} \delta E\left(k+\ell^{\prime} k_{0}, \omega\right) \\
& =\sum_{\ell^{\prime}}\left[\frac{\omega_{p T}^{2}}{\left(\omega^{2}-\omega_{B}^{2}\right)} \frac{1}{\varepsilon\left(k+\ell^{\prime} k_{0}, \omega\right)} \sum_{\ell} \delta E\left(k+\ell k_{0}, \omega\right)\right] \\
& \Rightarrow 1=\sum_{\ell^{\prime}}\left[\frac{\omega_{p T}^{2}}{\left(\omega^{2}-\omega_{B}^{2}\right)} \frac{1}{\varepsilon\left(k+\ell^{\prime} k_{0}, \omega\right)}\right] \tag{6.56}
\end{align*}
$$

An example of a warm fluid dielectric function in (6.56) in the laboratory frame is

$$
\begin{equation*}
\varepsilon^{(L)}(k, \omega)=1-\frac{\omega_{p}^{2}}{\omega^{2}-3 k^{2} v_{\mathrm{th}}^{2}} . \tag{6.57}
\end{equation*}
$$

In the wave frame this fluid dielectric becomes

$$
\begin{equation*}
\varepsilon^{(W)}(k, \omega)=1-\frac{\omega_{p}^{2}}{\left(\omega+k V_{0}\right)^{2}-3 k^{2} v_{\mathrm{th}}^{2}} . \tag{6.58}
\end{equation*}
$$

The dispersion relation for the sideband instability is given by the last expression in (6.56), which can be rewritten as

$$
\begin{equation*}
\frac{\left(\omega^{2}-\omega_{B}^{2}\right)}{\omega_{p T}^{2}}=\sum_{\ell}\left[\frac{1}{\varepsilon\left(k+\ell k_{0}, \omega\right)}\right] . \tag{6.59}
\end{equation*}
$$

The left-hand side of (6.59) has a small divisor; thus, we look for terms in the sum on the right-hand side that are near resonant, i.e. values of $k$ and $\ell$ such that $\epsilon\left(k+\ell k_{0}, \omega\right)=0$. For $k=k^{\prime}+\ell k_{0}=\left\{k_{0}+\delta k,-k_{0}+\delta k\right\}$ and $\delta k$ small, the two terms $\ell=0,-2$ dominate the sum on the right-hand side of (6.59):

$$
\begin{equation*}
\frac{\left(\omega^{2}-\omega_{B}^{2}\right)}{\omega_{p T}^{2}}=\frac{1}{\varepsilon(k, \omega)}+\frac{1}{\varepsilon\left(k-2 k_{0}, \omega\right)} . \tag{6.60}
\end{equation*}
$$

The dispersion relation in (6.60) using (6.58) in the wave frame is a cubic, which we expand for small $\omega$ and $\delta k$ to quadratic order in small quantities $\omega / \omega_{B}$ and $\delta k / k_{0}$,

$$
\begin{equation*}
\frac{\omega}{\omega_{p}}= \pm \frac{\delta k}{k_{0}}\left[-1+\left\{\frac{\lambda[(1+\lambda)(2 \beta+4)+1] \pm \mathrm{i} \sqrt{\lambda(\lambda+2)(2 \beta+3)}}{(1+\lambda)^{2}(2 \beta+4)-1}\right\}\right] \tag{6.61}
\end{equation*}
$$

where $\beta \equiv \omega_{B}^{2} / \omega_{p T}^{2} \gg 1, \lambda \equiv\left(\omega_{o}^{L}-\omega_{p}\right) / \omega_{p}=3 v_{\mathrm{th}}^{2} / 2 V_{\phi}^{2} \ll 1$, and $\omega_{o}^{L}$ is the frequency of the large-amplitude wave in the laboratory frame (the Bohm-Gross frequency in this case). $\lambda$ must be small, else the primary wave and its sidebands are strongly Landau
damped. Continuing the expansion of (6.61) for large $\beta$ and small $\lambda$, we obtain the simpler expression,

$$
\begin{equation*}
\frac{\omega}{\omega_{p}}= \pm \frac{\delta k}{k_{0}}\left[-1+\lambda \pm \mathrm{i} \sqrt{\frac{\lambda}{\beta}}\right] . \tag{6.62}
\end{equation*}
$$

In the laboratory frame,

$$
\begin{equation*}
\omega^{(L)}=\omega^{(W)}+\left(k_{0}+\delta k\right) V_{0} \approx \omega_{0}\left(k_{0}\right)+\delta k V_{g}^{o}\left(1+\frac{1}{2 \beta}\right)+\mathrm{i} v_{\mathrm{th}}|\delta k| \sqrt{\frac{3}{4 \beta}} \tag{6.63}
\end{equation*}
$$

The symmetric satellite waves in $k$ grow in time and modulate the envelope of the large-amplitude wave. The growth rate scales as $\sqrt{n_{T}^{o}}$. The publication of Kruer, Dawson and Sudan presents numerical solutions of the dispersion relation (6.60) for parameters motivated by the Wharton et al. experiment.

EXERCISE. Why is the sideband instability equivalent to unstable amplitude modulation? Motivated by the structure of (6.63) consider a travelling wave with growing noise superposed on the wave,

$$
\begin{aligned}
\phi(x, t) & =\phi_{0}\left[\mathrm{e}^{\mathrm{i}\left(k_{0} x-\omega_{0} t\right)}+\int \mathrm{d} k A(k) \mathrm{e}^{\gamma(k) t} \mathrm{e}^{\mathrm{i}\left(k_{0}+\delta k\right) x-(\omega+\delta \omega) t}\right] \\
& =\phi_{0} \mathrm{e}^{\mathrm{i}\left(k_{0} x-\omega_{0} t\right)}\left[1+\int \mathrm{d} k A(k) \mathrm{e}^{\gamma(k) t} \mathrm{e}^{\mathrm{i}(\delta k x-\delta \omega t)}\right] \\
& =\phi_{0} \mathrm{e}^{\mathrm{i}\left(k_{0} x-\omega_{0} t\right)}\left[1+\int \mathrm{d} k A(k) \mathrm{e}^{\gamma(k) t} \mathrm{e}^{\mathrm{i} \delta k\left(x-V_{g}^{o} t\right)}\right] \\
& =\phi_{0} \mathrm{e}^{\mathrm{i}\left(k_{0} x-\omega_{0} t\right)} a(x, t) .
\end{aligned}
$$

6.4. Example of the saturation of the two-stream instability due to trapping

A two-stream instability for the simple case of two streams of the same charge and mass is a strong instability with growth rate comparable to the plasma frequency. The wave and centre-of-mass frames coincide. For a one-dimensional periodic simulation model with a system length such that only the fundamental is unstable, we expect that the single unstable mode will grow to a large amplitude such that the wave can trap the beams: $\left|e \phi_{0}\right| \sim \frac{1}{2} m v_{0}^{2}$. This estimate is borne out in direct kinetic simulations that illustrate the growth and saturation of the linearly unstable fundamental. The second harmonic is linearly stable but is excited nonlinearly. The evolution of the phase space in a particle simulation of the relativistic two-stream instability is illustrated in figure 6.D. 1 of Berk \& Roberts (1970) which employed a simplified 'water-bag' model of the two-stream instability, followed the motion of phase-space boundaries, and observed that a large-scale nonlinear wave evolves accompanying the condensation of holes in phase space.

### 6.5. Quasilinear theory of wave-particle interaction

Consider the evolution of the bump-on-tail instability (see § 2.9.5 and figure 12). There is a range of unstable wavenumbers corresponding to an interval of phase velocities


Figure 32. The evolution of the relativistic two-stream instability in the frame of the unstable wave is shown from a simulation with OSHUN produced by Michail Tzoufras, UCLA Particle-in-Cell (PIC) and Kinetic Simulation Software Center (PICKSC), https://picksc.idre.ucla.edu.
with resonant velocities falling on the velocity distribution function where the slope is positive, i.e.

$$
\begin{equation*}
\left|\frac{\omega_{p}}{k^{2}} \Delta k\right|=\left|\Delta\left(\frac{\omega_{p}}{k}\right)\right|=|\Delta u| \quad \rightarrow \quad\left|\frac{\Delta k}{k}\right| \sim\left|\frac{\Delta u}{u}\right| . \tag{6.64}
\end{equation*}
$$

Concentrate on waves that grow to appreciable amplitude: waves with finite growth rates $\gamma_{k}>0$. As a matter of convention, consider only positive frequencies for positive or negative wavenumbers so that the sign of the wavenumber determines the sign of the phase velocity $V_{k}$. The electric potential can be represented by

$$
\begin{equation*}
\phi(x, t)=\sum_{j=1}^{N} \phi_{j} \cos \left(k_{j} x-\omega_{k, j} t+\alpha_{j}\right) . \tag{6.65}
\end{equation*}
$$

What is the evolution of the particle velocity in the presence of a spectrum of waves with initial condition $\left\{x_{0}, v_{0}\right\}$ ? To answer this question we compute $\left\langle\left[\Delta v\left(x_{0}, v_{0} ; t\right)\right]^{2}\right\rangle$ at fixed $x_{0}$. Particles interact weakly with each wave component, but none can trap because of the competition with the other waves. We will show that a random walk in velocity space occurs with attributes

$$
\begin{equation*}
\langle\Delta v\rangle_{x_{0}}=0 \quad\left\langle(\Delta v)^{2}\right\rangle_{x_{0}}\left(v_{0} ; t\right) \propto t \tag{6.66}
\end{equation*}
$$

Definition. The linear growth in time of the variance in the velocity perturbation defines this as a 'diffusion' process.
[Editor's note: Allan Kaufman published two fundamental papers on quasilinear diffusion in plasmas in 1972. (Kaufman 1972a,b)]

### 6.5.1. Diffusion equations, e.g. Fick's law

The mathematical characterization of a diffusion process as defined in (6.66) shares many of the same results as random walk processes associated with Brownian motion. Brownian motion in a colloidal suspension with diffusion into a less dense region has the property that the diffusive flux density of particles is proportional to the gradient in the density.

THEOREM (Fick's law of diffusion). $\boldsymbol{\Gamma}=-D_{x} \nabla n$ and the conservation of particle number is embodied in the continuity equation

$$
\begin{equation*}
\frac{\partial}{\partial t} n(\boldsymbol{x} ; t)=-\nabla \cdot \boldsymbol{\Gamma}=\nabla \cdot\left(D_{x} \nabla n\right) \rightarrow D_{x} \nabla^{2} n \tag{6.67}
\end{equation*}
$$

if $D_{x}$ is a constant, and $D_{x}$ is given by $D_{x}=\lim _{\Delta t \rightarrow \infty}\left\langle(\Delta x)^{2} / 2 \Delta t\right\rangle$ where $\left\langle(\Delta x)^{2}\right\rangle$ is a function of $\Delta t$.

Definition. The velocity diffusion coefficient can be defined analogously

$$
\begin{equation*}
D_{v}=\lim _{\Delta t \rightarrow \infty}\left\langle\frac{(\Delta x)^{2}}{2 \Delta t}\right\rangle \tag{6.68}
\end{equation*}
$$

This is the diffusivity in velocity space.

THEOREM (Velocity-space diffusion equation). The diffusive flux density in velocity space is

$$
\begin{equation*}
\langle\boldsymbol{\Gamma}(v)\rangle_{x}=-D_{v} \frac{\partial\langle f(v)\rangle_{x}}{\partial v} \tag{6.69}
\end{equation*}
$$

and the velocity-space continuity equation yields the kinetic diffusion equation,

$$
\begin{equation*}
\frac{\partial\langle f\rangle}{\partial t}=-\frac{\partial\left\langle\Gamma_{v}\right\rangle}{\partial v}=\frac{\partial}{\partial v}\left(D_{v} \frac{\partial\langle f\rangle}{\partial v}\right) . \tag{6.70}
\end{equation*}
$$

The velocity-space diffusion in (6.70) will deform a bump-on-tail velocity distribution function asymptotically to a uniform plateau over the interval in velocity space that is resonant with the unstable phase velocities.

The wave-particle interaction with a spectrum of waves, absent particle trapping, has the property that $\langle\Delta v\rangle_{x_{0}} \cong 0$ but only to lowest order in $\phi$ and not to second order. The phase average with respect to $x_{0}$ of $\Delta v^{2}$ is finite and determines the velocity diffusion. Let us calculate the diffusion coefficient from consideration of $\Delta v$,

$$
\begin{align*}
\Delta v\left(x_{0}, v_{0}, t\right) & =\frac{e}{m} \int_{0}^{t} \mathrm{~d} t^{\prime} \sum_{k} k \phi_{k} \sin \left[k\left(x_{0}+v_{0} t^{\prime}\right)-\omega_{k} t^{\prime}+\alpha_{k}\right] \\
& =\frac{e}{m} \int_{0}^{t} \mathrm{~d} t^{\prime} \sum_{k} k \phi_{k} \sin \left[\left(k v_{0}-\omega_{k}\right) t^{\prime}+k x_{0}+\alpha_{k}\right] \\
& =\frac{e}{m} \sum_{k} k \phi_{k} \frac{\cos \left[\left(k v_{0}-\omega_{k}\right) t+k x_{0}+\alpha_{k}\right]-\cos \left[k x_{0}+\alpha_{k}\right]}{-\left(k x_{0}-\omega_{k}\right)} \tag{6.71}
\end{align*}
$$

From the definition of the diffusion coefficient in (6.68) and using the identity 1 $\cos \theta=2(\sin \theta / 2)^{2}$, then

$$
\begin{align*}
\left\langle\Delta v^{2}\right\rangle_{x_{0}} & =\left(\frac{e}{m}\right)^{2} \sum_{k} \frac{k^{2} \phi_{k}^{2}\left(\frac{1}{2}+\frac{1}{2}-\cos \left(\left(k v_{0}-\omega_{k}\right) t\right)\right)}{\left(k v_{0}-\omega_{k}\right)^{2}} \\
& =\left(\frac{e}{m}\right)^{2} \sum_{k} \frac{k^{2} \phi_{k}^{2} 2 \sin ^{2} \frac{1}{2}\left(\left(k v_{0}-\omega_{k}\right) t\right)}{\left(k v_{0}-\omega_{k}\right)^{2}} \tag{6.72}
\end{align*}
$$

THEOREM. The velocity diffusion coefficient is then

$$
\begin{equation*}
D\left(v_{0}\right)=\lim _{t \rightarrow \infty} \frac{\left\langle\Delta v^{2}\right\rangle_{x_{0}}}{2 t}=\frac{1}{2 t}\left(\frac{e}{m}\right)^{2} \sum_{k} \frac{k^{2} \phi_{k}^{2} 2 \sin ^{2} \frac{1}{2}\left(\left(k v_{0}-\omega_{k}\right) t\right)}{\left(k v_{0}-\omega_{k}\right)^{2}} \tag{6.73}
\end{equation*}
$$

The evaluation of the limit with respect to large $t$ in (6.73) is clarified in the next several equations. The numerator of the diffusion coefficient of $\left\langle\Delta v^{2}\right\rangle$ grows as $t^{2}$ for small argument of the sin function, i.e. for resonant particles $\omega_{k}-k v_{0} \approx 0$, and otherwise is oscillatory.

We next pass to the limit of a continuum of modes. In a box with length $L$ and with periodic boundary conditions: $k=(2 \pi / L) n, n= \pm 1, \pm 2, \ldots$ In an infinite plasma $L \rightarrow \infty$ and $n$ goes to a continuum. Then

$$
\begin{equation*}
\sum_{k} \equiv \sum_{n=-\infty}^{\infty} \rightarrow \int_{-\infty}^{\infty} \mathrm{d} n=\frac{L}{2 \pi} \int_{-\infty}^{\infty} \mathrm{d} k=L \int_{-\infty}^{\infty} \frac{\mathrm{d} k}{2 \pi} \tag{6.74}
\end{equation*}
$$

The average energy density of the electric field becomes

$$
\begin{align*}
\langle\text { Field Energy Density }\rangle & =\left\langle\frac{E^{2}}{8 \pi}\right\rangle=\frac{1}{8 \pi} \sum_{k} k^{2} \phi_{k}^{2}\left\langle\cos ^{2} \theta_{k}\right\rangle \\
& =\frac{1}{8 \pi} \sum_{k} \frac{k^{2} \phi_{k}^{2}}{2} \rightarrow \frac{L}{16 \pi} \int_{-\infty}^{\infty} \frac{\mathrm{d} k}{2 \pi} k^{2} \phi_{k}^{2} . \tag{6.75}
\end{align*}
$$

DEFINITION. $E(k) \equiv \frac{1}{2} L k^{2} \phi_{k}^{2}$, the energy density per unit $k$ interval, i.e. the spectral density; and $\left\langle E^{2} / 8 \pi\right\rangle=(1 / 8 \pi) \int_{-\infty}^{\infty}(\mathrm{d} k / 2 \pi) E(k)$. Hence,

$$
\begin{equation*}
D(v)=\lim _{t \rightarrow \infty} \frac{1}{t}\left(\frac{e}{m}\right)^{2} \int_{-\infty}^{\infty} \frac{\mathrm{d} k}{2 \pi} \frac{E(k) 2 \sin ^{2} \frac{1}{2}\left(\left(k v-\omega_{k}\right) t\right)}{\left(k v-\omega_{k}\right)^{2}} \tag{6.76}
\end{equation*}
$$

We define $\beta \equiv \frac{1}{2}\left(k v-\omega_{k}\right)$ and use the relation $\int_{0}^{\infty} \mathrm{d} x\left(\sin ^{2} x / x^{2}\right)=\pi$ to demonstrate that

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{\sin ^{2} \beta t}{\beta^{2} t}=\pi \delta(\beta) . \tag{6.77}
\end{equation*}
$$

The diffusion coefficient becomes

$$
\begin{equation*}
D(v)=\left(\frac{e}{m}\right)^{2} \int_{-\infty}^{\infty} \frac{\mathrm{d} k}{2 \pi} E(k) \pi \delta\left(k v-\omega_{k}\right) \tag{6.78}
\end{equation*}
$$

The quasilinear diffusion coefficient in (6.78) describes resonant diffusion in velocity space driven by a spectrum of waves and is used in the velocity-space diffusion equation (6.70). The result is valid to lowest order in the perturbed electric potential and only for weak growth and damping rates.

### 6.5.2. Irreversibility and the $H$ theorem

We introduce the concept of the entropy associated with the velocity distribution as a function of time $S(t)$ :

Definition. Entropy (Boltzmann) $S(t) \equiv-\int \mathrm{d} v\langle f\rangle(v ; t) \ln \langle f\rangle(v ; t)$ and (Gibbs) $S(t) \equiv-\int \mathrm{d} v \int \mathrm{~d} x\langle f\rangle(x, v ; t) \ln \langle f\rangle(x, v ; t)$.

Irreversibility is a macroscopic property and requires coarse-grained averaging. We associate irreversibility with $\mathrm{d} S / \mathrm{d} t>0$.

THEOREM (H Theorem). The time derivative of the coarse-grained entropy is

$$
\begin{align*}
\frac{\mathrm{d}}{\mathrm{~d} t} S & =-\int \mathrm{d} v\left[\frac{\partial\langle f\rangle}{\partial t} \ln \langle f\rangle+\frac{\langle f\rangle}{\langle f\rangle} \frac{\partial\langle f\rangle}{\partial t}\right]=-\int \mathrm{d} v\left[\frac{\partial\langle f\rangle}{\partial t} \ln \langle f\rangle-\frac{\partial}{\partial v} \Gamma\right] \\
& =-\int \mathrm{d} v\left[\left(-\frac{\partial}{\partial v} \Gamma\right) \ln \langle f\rangle\right]=-\int \mathrm{d} v\left[\frac{1}{\langle f\rangle} \frac{\partial\langle f\rangle}{\partial v} \Gamma\right] \\
& =\int \mathrm{d} v\left[\frac{D(v)}{\langle f\rangle}\left(\frac{\partial\langle f\rangle}{\partial v}\right)^{2}\right]>0 \tag{6.79}
\end{align*}
$$

using (6.69) and (6.70), and integrating by parts. That the right-hand side of (6.79) is positive is clear given that $D>0$ from (6.76)-(6.78), $\langle f\rangle>0$ and $(\partial\langle f\rangle / \partial v)^{2}>0$.

The entropy $S$ is always increasing, but is bounded from above using energy conservation. Hence, $S$ has an asymptotic steady state at its maximum value. In consequence, the integrand on the right-hand side of (6.79) must vanish everywhere in velocity space asymptotically in time. This implies that the velocity derivative $\partial\langle f\rangle / \partial v$ vanishes asymptotically over the range of resonant velocities, i.e. the velocity distribution flattens. With the use of the relations $\left|\mathrm{d}\left(k v-\omega_{k}\right)\right| \delta\left(k v-\omega_{k}\right)=$ $|\mathrm{d} k| \delta\left(k-\left(\omega_{k} / v\right)\right.$ ) (or generally $\delta(u(x))=\delta\left(x-x_{r}\right)|\mathrm{d} u / \mathrm{d} x|^{-1}$ where $x_{r}$ is a root of $u$ ) and $\left(\mathrm{d}\left(k v-\omega_{k}\right) / \mathrm{d} k\right)=v-\left(\mathrm{d} \omega_{k} / \mathrm{d} k\right)$, an alternative form for the velocity diffusion coefficient (6.78) is

$$
\begin{equation*}
D(v)=\left(\frac{e}{m}\right)^{2} \int_{-\infty}^{\infty} \frac{\mathrm{d} k}{2 \pi} E(k) \pi \frac{\delta\left(k-\frac{\omega_{k}}{v}\right)}{\left|v-\frac{\mathrm{d} \omega}{\mathrm{~d} k}\right|}=\frac{1}{2}\left(\frac{e}{m}\right)^{2} E\left(\frac{\omega_{k}}{v}\right) /\left|v-V_{g}(k)\right| \tag{6.80}
\end{equation*}
$$

We note that the waves evolve as linear waves while the particles interact with the waves quadratically in the wave amplitudes. Thus, the spectral density $E(k)$ grows or damps linearly.

THEOREM. Recalling (2.96) the linear evolution of the spectral density is

$$
\begin{align*}
\frac{\partial E(k ; t)}{\partial t} & =2 \gamma(k ; t) E(k ; t) \quad \text { where } \gamma(k ; t) \\
& =-\frac{\varepsilon_{I}}{\frac{\partial \varepsilon_{R}}{\partial \omega}}=\frac{e^{2}}{m k} \frac{4 \pi}{\frac{\partial \varepsilon_{R}}{\partial \omega}} \int_{-\infty}^{\infty} \mathrm{d} v \frac{\partial\langle f\rangle}{\partial v} \pi \delta\left(\omega_{k}-k v\right) \tag{6.81}
\end{align*}
$$

and $<f>$ evolves according to (6.70) in the presence of the quasilinear diffusion from the wave-particle interactions.
6.5.3. Validity of the quasilinear treatment and conservation of energy and momentum The conditions for the validity of quasilinear theory are that the waves are linear, i.e. small amplitude with no trapping of particles and no mode coupling. Energy and momentum conservation tells us nothing new but affords a check that things have been done right. The total energy density is a sum of the particle kinetic energy and the field energy densities.

THEOREM. The total energy density is given by

$$
\begin{equation*}
U=\int \mathrm{d} v \frac{1}{2} m v^{2}\langle f\rangle(v ; t)+\left.\frac{1}{8 \pi} \int \frac{\mathrm{~d} k}{2 \pi} E(k) \omega_{k} \frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}} . \tag{6.82}
\end{equation*}
$$

The second term on the right-hand side of (6.82) contains both the electric field energy density (if $\left.\omega_{k}\left(\partial \epsilon_{R} / \partial \omega\right)\right|_{\omega_{k}}=1$ ) and the mechanical or sloshing energy of the particles in the wave (if $\left.\omega_{k}\left(\partial \epsilon_{R} / \partial \omega\right)\right|_{\omega_{k}}>1$ ).

THEOREM. Energy conservation is demonstrated by calculating the time derivative of (6.82) and using expressions derived in § 6.5.2,

$$
\begin{align*}
\frac{\mathrm{d}}{\mathrm{~d} t} U= & \int \mathrm{d} v \frac{1}{2} m v^{2} \frac{\partial}{\partial v}\left(D \frac{\partial\langle f\rangle}{\partial v}\right)+\left.\frac{1}{8 \pi} \int \frac{\mathrm{~d} k}{2 \pi} 2 \gamma E(k) \omega_{k} \frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}} \\
= & -\int \mathrm{d} v m v\left(\frac{e^{2}}{m^{2}} \int \frac{\mathrm{~d} k}{2 \pi} E(k) \pi \delta\left(\omega_{k}-k v\right) \frac{\partial\langle f\rangle}{\partial v}\right) \\
& +\left.\int \frac{\mathrm{d} k}{2 \pi} \frac{e^{2}}{m k} \frac{1}{\frac{\partial \varepsilon_{R}}{\partial \omega}} \int_{-\infty}^{\infty} \mathrm{d} v \frac{\partial\langle f\rangle}{\partial v} \pi \delta\left(\omega_{k}-k v\right) E(k) \omega_{k} \frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}}=0 . \tag{6.83}
\end{align*}
$$

THEOREM. The total momentum density is given by the sum of the particle and wave momentum densities

$$
\begin{equation*}
P=\int \mathrm{d} v m v\langle f\rangle(v ; t)+\left.\frac{1}{8 \pi} \int \frac{\mathrm{~d} k}{2 \pi} E(k) k \frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}} \tag{6.84}
\end{equation*}
$$

THEOREM. Momentum conservation is demonstrated by calculating the time derivative of (6.84) and using expressions derived in § 6.5.2,

$$
\begin{align*}
\frac{\mathrm{d}}{\mathrm{~d} t} P= & \int \mathrm{d} v m v \frac{\partial}{\partial v}\left(D \frac{\partial\langle f\rangle}{\partial v}\right)+\left.\frac{1}{8 \pi} \int \frac{\mathrm{~d} k}{2 \pi} 2 \gamma E(k) k \frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}} \\
= & -\int \mathrm{d} v m\left(\frac{e^{2}}{m^{2}} \int \frac{\mathrm{~d} k}{2 \pi} E(k) \pi \delta\left(\omega_{k}-k v\right) \frac{\partial\langle f\rangle}{\partial v}\right) \\
& +\left.\int \frac{\mathrm{d} k}{2 \pi} \frac{e^{2}}{m k} \frac{1}{\frac{1 \varepsilon_{R}}{\partial \omega}} \int_{-\infty}^{\infty} \mathrm{d} v \frac{\partial\langle f\rangle}{\partial v} \pi \delta\left(\omega_{k}-k v\right) E(k) k \frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}}=0 . \tag{6.85}
\end{align*}
$$

We return to a discussion of the validity of the quasilinear diffusion equations. We consider three issues:
(a) How large should $\Delta t$ be in the definition of the diffusion coefficient (6.68)?
(b) How small must $E$ be so that $\Delta v$ can be calculate just to $O(\phi)$ ?
(c) How small must $\gamma \Delta t$ be in order that the growth or damping of waves during $\Delta t$ is negligible so that the diffusion coefficient can be calculated to lowest order?
(a) $\Delta t$ is long on a microscopic time scale of the wave-particle resonant interaction, but short on the macroscopic time scale over which the spectral density changes by a finite amount. The limit taken in (6.68) must converge for $\gamma \Delta t \ll 1$. Examine the integral in the expression for $D$ in (6.76). Assume that $E \sim E\left(k_{0}\right) \exp -\left(\left(k-k_{0}\right)^{2} / 2 \delta k^{2}\right)$ and expand $\beta \equiv\left(\omega_{k}-k v\right) \approx\left(\omega_{k_{0}}-k_{0} v\right)+((\mathrm{d} \omega / \mathrm{d} k)-v)\left(k-k_{0}\right) \approx((\mathrm{d} \omega / \mathrm{d} k)-v)(k-$ $\left.k_{0}\right)=\delta \beta$, then

$$
\begin{equation*}
D(v) \propto \lim _{\Delta t \rightarrow \infty}\left(\frac{e}{m}\right)^{2} \int_{-\infty}^{\infty} \frac{\mathrm{d} k}{2 \pi} E(k) \frac{\sin ^{2} \beta \Delta t}{\beta^{2} \Delta t} \approx\left(\frac{e}{m}\right)^{2} \int_{-\infty}^{\infty} \frac{\mathrm{d} k}{2 \pi} E(k) \pi \delta(\beta) \tag{6.86}
\end{equation*}
$$

where $\Delta t \gg 1 /|\delta \beta|=1 /(\delta k|\mathrm{~d} \omega / \mathrm{d} k-v|)$ to obtain the result in (6.86), which can be restated as the time $\Delta t$ must be long compared to the time required by the particles to experience phase decorrelation $\delta k \delta x>1$. The particles have to see many waves. If the particles are phase correlated to one wave, they can get trapped.
(b) The spectral density $E$ should be so small that there is no trapping over the time step $\Delta t$. There will be no trapping if the trapping time $\tau_{T}$ is much longer than the correlation time of the particle with a single wave,

$$
\begin{equation*}
\tau_{T} \equiv\left(k \sqrt{\frac{e \phi}{m}}\right)^{-1} \gg \frac{\delta x}{v}=\frac{1}{k \delta v} \Rightarrow \sqrt{\frac{m}{e \phi}} \gg \frac{1}{\delta v} \tag{6.87}
\end{equation*}
$$

In the example of the bump-on-tail instability, the condition (6.87) implies that the electric potential must be weak and the bump relatively broad in order to avoid particle trapping.
(c) There needs to be weak growth or damping in the time over which the waveparticle diffusion coefficient converges, i.e. the growth time is long compared to $\Delta t$ which is long compared to the diffusion and correlation time.

$$
\begin{equation*}
\frac{1}{\gamma} \gg \Delta t \gg \frac{\delta x}{v} \tag{6.88}
\end{equation*}
$$

The validity conditions for quasilinear diffusion can be summarized as follows:

$$
\begin{array}{ll}
|e \phi| \ll m v^{2} & \text { small-amplitude waves } \\
\gamma \ll v \delta k=k \delta v & \text { weak growth or damping } \\
\frac{1}{k} \sqrt{\frac{m}{e \phi}} \gg \frac{1}{v \delta k}=\frac{1}{k \delta v} & \text { no trapping. } \tag{6.89}
\end{array}
$$

In (6.89), we have assumed that Landau growth or damping is weak, $\left(\partial \omega_{k} / \partial k\right) \ll v$, and from consideration of the resonance conditions $(|\delta k| / k)=(|\delta v| / v)$.

Example. The two-stream instability is not amenable to a quasilinear diffusion treatment because $\delta \mathrm{v}=0$, and we cannot satisfy the validity conditions.

Example. Bump-on-tail instability
Consider the descriptions in $\S \S 2.9 .5$ and 6.2.4. The validity conditions for the application of quasilinear diffusion theory are as follows.
(i) Weak growth - define the interval of positive slope $g^{\prime}(v)>0$ to be $\delta v$. Then the condition for weak growth is

$$
\begin{equation*}
\frac{\gamma}{\omega_{k}} \approx \frac{\omega_{p}^{2}}{k^{2}} \frac{\pi g^{\prime}(v)}{2} \rightarrow \frac{\gamma}{\omega_{p}} \approx O(1) \frac{\Delta g}{g_{0}} \frac{v}{\delta v} \frac{v}{v_{\mathrm{th}}} \ll \frac{k \delta v}{\omega_{p}} \Rightarrow\left(\frac{\delta v}{v}\right)^{2} \frac{v_{\mathrm{th}}}{v} \gg \frac{\Delta g}{g_{0}} . \tag{6.90}
\end{equation*}
$$

(ii) No trapping - the trapping time must be long compared to the correlation time,

$$
\begin{equation*}
\frac{\omega_{T}}{\omega_{p}} \sim \frac{k \sqrt{\frac{e \phi}{m}}}{\omega_{p}} \sim \frac{O(1) \gamma}{\omega_{p}} \ll \frac{k \delta v}{\omega_{p}} \Rightarrow\left(\frac{\delta v}{v}\right)^{2} \frac{v_{\mathrm{th}}}{v} \gg \frac{\Delta g}{g_{0}}, \tag{6.91}
\end{equation*}
$$

where we have used as an estimate of the wave amplitude at saturation $\omega_{T} \sim O(1) \gamma$ based on the considerations in §6.2.4. Thus, the conditions in (6.90) and (6.91) are identical.
(iii) Linear waves - that the wave amplitude is small $e \phi \ll m v^{2}$ is easily satisfied:

$$
\begin{equation*}
e \phi / m \ll v^{2} \Rightarrow \frac{v_{T}^{2}}{v^{2}} \approx \frac{\omega_{T}^{2}}{\omega_{p}^{2}}=\frac{O(1) \gamma^{2}}{\omega_{p}^{2}} \ll 1 . \tag{6.92}
\end{equation*}
$$

Example. For the bump-on-tail instability and representative plasma conditions, one might find very approximately

$$
\Delta g / g_{0} \sim 10^{-4}, \quad \delta v / v \sim 10^{-1}, \quad v / v_{\mathrm{th}} \sim 10, \quad \gamma / \omega_{p} \sim 10^{-2}, \quad \omega_{T} / \omega_{p} \sim 10^{-1.2} .
$$

EXERCISES. Check the validity of quasilinear theory for the (i) weak-cold-beam instability and (ii) the ion-acoustic instability.

One can make some general comments and estimates regarding the growth and saturation of instabilities based on quasilinear theory. The electric potential grows at first exponentially at a growth rate that begins at the linear value and then evolves in time until it saturates. The instantaneous growth rate $\gamma(t)$ remains very close to the linear growth rate until that last e-folding or two before saturation,

$$
\begin{align*}
\phi\left(t^{\mathrm{sat}}\right) & =\phi_{0} \exp \left[\int_{0}^{t^{\mathrm{sat}}} \mathrm{~d} t^{\prime} \gamma\left(t^{\prime}\right)\right] \Rightarrow \frac{\phi^{\mathrm{sat}}}{\phi_{0}}=\exp \left[\int_{0}^{t^{\mathrm{sat}}} \mathrm{~d} t^{\prime} \gamma\left(t^{\prime}\right)\right] \\
& \Rightarrow \ln \frac{\phi^{\mathrm{sat}}}{\phi_{0}}=\int_{0}^{t^{\mathrm{sat}}} \mathrm{~d} t^{\prime} \gamma\left(t^{\prime}\right) \Rightarrow t^{\mathrm{sat}} \sim \frac{1}{\gamma_{L}} \frac{1}{2} \ln \frac{k^{2}\left|\phi^{\mathrm{sat}}\right|^{2}}{k^{2}\left|\phi_{0}\right|^{2}} \\
& \sim \frac{1}{2} \frac{1}{\gamma_{L}} \ln \frac{\text { turbulent wave energy }}{\text { thermal wave energy }} . \tag{6.93}
\end{align*}
$$

The ratio of the turbulent wave energy to the thermal wave energy is typically very large. An estimate for the thermal wave energy can be obtained by assuming that the thermal wave energy is set by discreteness effects and that the ratio of kinetic energy to field energy is determined by plasma parameter, i.e. the ratio of the electric field energy to kinetic energy is $\sim n T / \Lambda$ where $\Lambda \sim n \lambda_{D}^{3}$. Based on observational experience
(experiments, simulations and analytical theories) we can estimate the turbulent wave energy at saturation as $\sim n T / \mu$, where $\mu \gg 1$. Hence,

$$
\begin{equation*}
t^{\text {sat }} \sim \frac{1}{2 \gamma_{L}}(\ln \Lambda-\ln \mu) . \tag{6.94}
\end{equation*}
$$

In typical plasma conditions we find that $10<\ln \Lambda<20$ and $5<\ln \mu<8$, so that $t^{\text {sat }} \sim(2$ to 15$) / 2 \gamma_{L}$.

Quasilinear theory has been extended in many directions. Here are a few examples of extensions:
(i) three dimensions instead of one;
(ii) the inclusion of a finite applied magnetic field;
(iii) inclusion of magnetic as well as electric field perturbations (an electromagnetic theory);
(iv) inhomogeneous medium;
(v) formal derivation of quasilinear diffusion theory.
6.5.4. Formal derivation of quasilinear theory using canonical variables and the Liouville equation
Here we present a formal derivation of quasilinear theory using canonical variables that satisfy Hamilton's equations. The value of this formulation is that the resulting equations capture the physics in a more efficient and elegant manner that retains mathematical rigor. In this formulation for a three-dimensional Coulomb plasma with no applied magnetic field, the phase-space variables become $\{x, y, z, \dot{x}, \dot{y}, \dot{z}\} \rightarrow\left\{q_{1}, q_{2}, q_{3}, p_{1}, p_{2}, p_{3}\right\}$ With a finite $\boldsymbol{B}_{0}$ one might employ canonical momentum $\boldsymbol{p}=m \boldsymbol{v}+(e / c) \boldsymbol{A}$. However, we will not use the canonical momentum and instead express the independent phase-space variables in terms of invariants of the motion as much as possible.

A constant of the motion $p$ is determined by the absence of dependence of the Hamiltonian on the variable $q$ conjugate to $p$, i.e.

$$
H_{0}(q, p)=H_{0}(q, p) \quad \dot{p}=-\frac{\partial H_{0}}{\partial q}=0
$$

For example, in a uniform magnetic field in the $z$ direction, with no zero-order electric fields, $v_{\perp}^{2}, v_{\|}$are invariants as well as the guiding-centre positions $X$ and $Y$. In this situation, the conjugate variables to $v_{\perp}^{2}$ and $v_{\|}$are the gyrophase $\phi$ and the position $z$, respectively. The guiding-centre positions $X$ and $Y$ are conjugates to one another. If $\left\{p_{1}, p_{2}, p_{3}\right\}$ are three invariants of the zero-order motion corresponding to $\left\{v_{\|}, v_{\perp}^{2}, X\right\}$ then we can construct the zero-order phase-space distribution function from $f_{0}\left(v_{\|}, v_{\perp}^{2}, X\right)$. Because $Y$ is also a constant of the zero-order motion, then $\left(\partial H_{0} / \partial p_{3}\right)=0$ and $H_{0}(\boldsymbol{p}) \rightarrow H_{0}\left(p_{1}, p_{2}\right)$.

Quite generally, the phase-space distribution function will be a function of all of the canonical variables and time,
$f\left(p_{1}, p_{2}, \ldots, q_{1}, q_{2}, \ldots ; t\right) \quad$ and $\quad \frac{\partial f}{\partial t}+\frac{\partial}{\partial p_{1}}\left(\dot{p}_{1} f\right)+\cdots+\frac{\partial}{\partial q_{1}}\left(\dot{q}_{1} f\right)+\cdots=0$
in the collisionless limit. A formal average of $f$ over $q_{j}$ can be performed by integrating the kinetic equation in (6.95).

THEOREM. Using the property of the perfect differential and appropriate boundary conditions (either zero at $\pm \infty$ or periodic on 0 to $2 \pi), \int \mathrm{d} q_{j}\left(\partial / \partial q_{j}\right)\left(\dot{q}_{j} f\right)=$ $\left.\left(\dot{q}_{j} f\right)\right|_{-\infty, 0} ^{+\infty, 2 \pi}=0$, the kinetic equation for $\langle f\rangle(\boldsymbol{p} ; t)$ becomes

$$
\begin{equation*}
\frac{\partial\langle f\rangle(\boldsymbol{p} ; t)}{\partial t}=-\frac{\partial}{\partial \boldsymbol{p}}(\dot{\boldsymbol{p}}\langle f\rangle) \quad \dot{\boldsymbol{p}}=-\frac{\partial H}{\partial \boldsymbol{q}}=-\frac{\partial \delta H}{\partial \boldsymbol{q}} \quad H=H_{0}(\boldsymbol{p})+\delta H(\boldsymbol{p}, \boldsymbol{q} ; t) \tag{6.96}
\end{equation*}
$$

where we have used $\langle\dot{\boldsymbol{p}}\langle f\rangle\rangle=\langle\dot{\boldsymbol{p}}\rangle\langle f\rangle=0$. Thus,

$$
\begin{equation*}
f(\boldsymbol{q}, \boldsymbol{p} ; t)=\langle f\rangle_{\boldsymbol{q}}(\boldsymbol{p} ; t)+\delta f(\boldsymbol{q}, \boldsymbol{p} ; t) \quad \text { and } \quad\langle\dot{\boldsymbol{p}} f\rangle=\langle\dot{\boldsymbol{p}} \delta f\rangle . \tag{6.97}
\end{equation*}
$$

We use the Liouville equation form of the Vlasov equation (6.95) to obtain

$$
\begin{equation*}
0=\frac{\mathrm{d} f(\boldsymbol{p}, \boldsymbol{q} ; t)}{\mathrm{d} t}=\frac{\mathrm{d}\langle f\rangle}{\mathrm{d} t}+\frac{\mathrm{d} \delta f}{\mathrm{~d} t} \rightarrow \frac{\mathrm{~d} \delta f}{\mathrm{~d} t}=-\left[\frac{\partial\langle f\rangle}{\partial t}+\frac{\partial\langle f\rangle}{\partial \boldsymbol{p}} \cdot \dot{\boldsymbol{p}}\right] . \tag{6.98}
\end{equation*}
$$

Given the Hamiltonian $H=p^{2} / 2 m+e \delta \phi(x, t)$ with $e \delta \phi$ identified as a first-order perturbing field, the first term on the right-hand side of the last expression in (6.98) is second order and the second term is first order. Then to first order in the perturbed electric potential

$$
\begin{equation*}
\frac{\mathrm{d} \delta f}{\mathrm{~d} t}=-\frac{\partial\langle f\rangle}{\partial \boldsymbol{p}} \cdot \dot{\boldsymbol{p}} \tag{6.99}
\end{equation*}
$$

We next integrate (6.99) from $t-\Delta t$ to $t$ along the particle phase-space characteristics to first order using

$$
\begin{equation*}
\left[\frac{\partial}{\partial t}+\dot{\boldsymbol{q}} \cdot \frac{\partial}{\partial \boldsymbol{q}}+\dot{\boldsymbol{p}} \cdot \frac{\partial}{\partial \boldsymbol{p}}\right] \delta f \approx\left[\frac{\partial}{\partial t}+\dot{\boldsymbol{q}} \cdot \frac{\partial}{\partial \boldsymbol{q}}\right] \delta f, \tag{6.100}
\end{equation*}
$$

because $\dot{\boldsymbol{p}}$ is first order and $\dot{\boldsymbol{p}} \cdot(\partial / \partial \boldsymbol{p}) \delta f$ is second order. Hence,

$$
\begin{align*}
\int_{t-\Delta t}^{t} \mathrm{~d} t^{\prime} \frac{\mathrm{d} \delta f(\boldsymbol{q}, \boldsymbol{p} ; t)}{\mathrm{d} t} & =\delta f\left(\boldsymbol{q}^{t}, \boldsymbol{p}^{t} ; t\right)-\delta f\left(\boldsymbol{q}^{t-\Delta t}, \boldsymbol{p}^{t-\Delta t} ; t-\Delta t\right) \\
& \approx \delta f\left(\boldsymbol{q}^{t}, \boldsymbol{p}^{t} ; t\right)-\delta f\left(\boldsymbol{q}^{t-\Delta t}, \boldsymbol{p}^{t} ; t-\Delta t\right) \Rightarrow \delta f\left(\boldsymbol{q}^{t}, \boldsymbol{p}^{t} ; t\right) \\
& =\delta f\left(\boldsymbol{q}^{t-\Delta t}, \boldsymbol{p}^{t} ; t-\Delta t\right)-\int_{t-\Delta t}^{t} \mathrm{~d} t^{\prime} \dot{\boldsymbol{p}} \cdot \frac{\partial\langle f\rangle}{\partial \boldsymbol{p}} \tag{6.101}
\end{align*}
$$

We average the Liouville equation, use (6.98), use (6.101) to evaluate $\delta f(t)$, and subtract off the first-order terms to identify second-order terms,

$$
\begin{align*}
\frac{\partial\langle f\rangle}{\partial t} & +\frac{\partial}{\partial \boldsymbol{p}} \cdot\langle\dot{\boldsymbol{p}} \delta f\rangle=0 \rightarrow \frac{\partial\langle f\rangle}{\partial t}=-\frac{\partial}{\partial \boldsymbol{p}} \cdot\langle\dot{\boldsymbol{p}}(t) \delta f(t)\rangle \\
& =-\frac{\partial}{\partial \boldsymbol{p}} \cdot\{\langle\dot{\boldsymbol{p}}(t) \delta f(t-\Delta t)\rangle\}+\frac{\partial}{\partial \boldsymbol{p}} \cdot\left\{\int_{t-\Delta t}^{t} \mathrm{~d} t^{\prime}\left\langle\dot{\boldsymbol{p}}(t) \dot{\boldsymbol{p}}\left(t^{\prime}\right)\right\rangle \cdot \frac{\partial\langle f\rangle}{\partial \boldsymbol{p}}\left(t^{\prime}\right)\right\} \tag{6.102}
\end{align*}
$$

It can be shown that the first term on the right-hand side of (6.102) falls off with $\Delta t$ and is negligible compared to the second term for $\Delta t \gg \delta x / v$ (the correlation time).

THEOREM. Equation (6.102) leads to a quasilinear diffusion equation for the slowly varying average distribution function where we have defined $t-\tau=t^{\prime}$ :

$$
\begin{equation*}
\frac{\partial\langle f\rangle}{\partial t}=\frac{\partial}{\partial \boldsymbol{p}} \cdot\left\{\int_{0}^{\Delta t} \mathrm{~d} \tau\langle\dot{\boldsymbol{p}}(t) \dot{\boldsymbol{p}}(t-\tau)\rangle \cdot \frac{\partial\langle f\rangle}{\partial \boldsymbol{p}}(t-\tau)\right\} . \tag{6.103}
\end{equation*}
$$

Definition. The quasilinear diffusion tensor is

$$
\begin{equation*}
\boldsymbol{D}(\boldsymbol{p}, t) \equiv \int_{0}^{\Delta t} \mathrm{~d} \tau\langle\dot{\boldsymbol{p}}(t) \dot{\boldsymbol{p}}(t-\tau)\rangle \tag{6.104}
\end{equation*}
$$

The integrand on the right-hand side of (6.104) is the two-time momentum correlation function which is largest for small $\tau$ and falls off for large $\tau$ compared to the correlation time $\delta x / v$. If we expand

$$
\frac{\partial\langle f\rangle}{\partial \boldsymbol{p}}(t-\tau)=\frac{\partial\langle f\rangle}{\partial \boldsymbol{p}}(t)-\tau \frac{\partial}{\partial \boldsymbol{p}} \frac{\partial\langle f\rangle}{\partial t}(t) \approx \frac{\partial\langle f\rangle}{\partial t}(t)+O\left(\tau^{2}\right)
$$

and just keep the lowest-order first term for use in (6.103), then (6.104) becomes

$$
\begin{equation*}
\frac{\partial\langle f\rangle}{\partial t}=\frac{\partial}{\partial \boldsymbol{p}} \cdot\left\{\boldsymbol{D}(\boldsymbol{p} ; t) \cdot \frac{\partial\langle f\rangle(\boldsymbol{p} ; t)}{\partial \boldsymbol{p}}\right\} \tag{6.105}
\end{equation*}
$$

### 6.5.5. Diffusion tensor

We have derived the diffusion tensor in (6.104). For a uniform magnetic field parallel to the $z$ axis, the generalized momentum vector in canonical variables is $\boldsymbol{p}=\left(m v_{z}, \frac{1}{2}\left(m v_{\perp}^{2} / \Omega\right),\left(e B_{0} / c\right) Y\right)$. One of the components of the diffusion tensor is then

$$
\begin{equation*}
D_{\perp}(\boldsymbol{p}, t) \equiv \int_{0}^{\Delta t} \mathrm{~d} \tau\left\langle\dot{p}_{\perp}(t) \dot{p}_{\perp}(t-\tau)\right\rangle \tag{6.106}
\end{equation*}
$$

THEOREM. The standard form for a diffusion coefficient is

$$
\begin{align*}
D_{\perp}(\boldsymbol{p}, t) & \equiv \lim _{\Delta t \rightarrow \infty} \frac{\left\langle\left(\Delta p_{\perp}\right)^{2}\right\rangle}{2 \Delta t}=\lim _{\Delta t \rightarrow \infty} \frac{\left\langle\left[\int_{0}^{\Delta t} \mathrm{~d} t \dot{p}_{\perp}(t)\right]^{2}\right\rangle}{2 \Delta t} \\
& =\lim _{\Delta t \rightarrow \infty} \frac{\int_{0}^{\Delta t} \mathrm{~d} t \int_{0}^{\Delta t} \mathrm{~d} t^{\prime}\left\langle\dot{p}_{\perp}(t) \dot{p}_{\perp}\left(t^{\prime}\right)\right\rangle}{2 \Delta t} \tag{6.107}
\end{align*}
$$

Only near $t=t^{\prime}$ is the integrand in the double integral finite on the right-hand side. Hence,

$$
\begin{align*}
D_{\perp}(\boldsymbol{p}, t) & \approx \frac{\int_{0}^{\Delta t} \mathrm{~d} t \int_{-\infty}^{\infty} \mathrm{d} \tau\left\langle\dot{p}_{\perp}(t) \dot{p}_{\perp}(t-\tau)\right\rangle}{2 \Delta t} \\
& \approx \frac{2 \Delta t \int_{0}^{\infty} \mathrm{d} \tau\left\langle\dot{p}_{\perp}(t) \dot{p}_{\perp}(t-\tau)\right\rangle}{2 \Delta t}=\int_{0}^{\infty} \mathrm{d} \tau\left\langle\dot{p}_{\perp}(t) \dot{p}_{\perp}(t-\tau)\right\rangle \tag{6.108}
\end{align*}
$$

as long at $\Delta t$ is large compared to the correlation time. We note that the integrand is an even function of $\tau$ which is justified by microscopic reversibility arguments.

Example. For a Coulomb model,

$$
\left.\begin{array}{c}
H=\frac{p_{z}^{2}}{2 m}+p_{\perp} \Omega+e \delta \phi(\boldsymbol{r}, t) \quad \rho(\boldsymbol{x} \mid \boldsymbol{r}) \equiv e \delta(\boldsymbol{x}-\boldsymbol{r}) \\
\delta H(p, q ; t)=\int \mathrm{d}^{3} \boldsymbol{x} \delta \phi(\boldsymbol{x}, t) \rho(\boldsymbol{x} \mid \boldsymbol{r})  \tag{6.109}\\
\boldsymbol{r}(\boldsymbol{p}, \boldsymbol{q}) \quad \boldsymbol{q}=\left(z, \phi, \frac{e B_{0}}{c} Y\right) \quad \boldsymbol{R}=(x, y, z)
\end{array}\right\}
$$

With a continuum of waves present

$$
\begin{align*}
& \delta \phi(\boldsymbol{x}, t)=\frac{\int \mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \delta \phi(\boldsymbol{k}, t) \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{x}} \quad \delta H=\frac{\int \mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \delta \phi(\boldsymbol{k}, t) \int \mathrm{d}^{3} \boldsymbol{x} \mathrm{e}_{\perp}^{\mathrm{i} k \cdot \boldsymbol{x}} \rho(\boldsymbol{x} \mid \boldsymbol{p}, \boldsymbol{q}) \\
& \int \mathrm{d}^{3} \boldsymbol{x} \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{x}} \rho(\boldsymbol{x} \mid \boldsymbol{p}, \boldsymbol{q})=\rho(\boldsymbol{k} \mid \boldsymbol{p}, \boldsymbol{q})=e \int \mathrm{~d}^{3} \boldsymbol{x} \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{x}} \delta(\boldsymbol{x}-\boldsymbol{r})=e \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}(p, \boldsymbol{q})} \\
& \quad=e \exp \left[\mathrm{i} k_{z} z+\mathrm{i} k_{x}\left(X+r_{\perp} \cos \theta\right)+\mathrm{i} k_{y}\left(Y+r_{\perp} \sin \theta\right)\right] \\
& =e \mathrm{e}^{\mathrm{i} k \cdot \boldsymbol{R}} \mathrm{e}^{\mathrm{i} k_{\perp} r_{\perp} \cos (\theta-\alpha)}=e \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{R}} \sum_{\ell=-\infty}^{\ell=\infty} \mathrm{i}^{\ell} \mathrm{J}_{\ell}\left(k_{\perp} r_{\perp}\right) \mathrm{e}^{\mathrm{i} \ell(\theta-\alpha)} \tag{6.110}
\end{align*}
$$

Hence,

$$
\left.\begin{array}{rl}
\delta H & =e \frac{\int \mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \delta \phi(\boldsymbol{k}, t) \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{R}} \sum_{\ell=-\infty}^{\ell=\infty} \mathrm{i}^{\ell} \mathrm{J}_{\ell}\left(k_{\perp} r_{\perp}\right) \mathrm{e}^{\mathrm{i} \ell(\theta-\alpha)} \quad \text { and }  \tag{6.111}\\
\dot{p}_{\perp} & =-e \frac{\int \mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \delta \phi(\boldsymbol{k}, t) \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{R}} \sum_{\ell=-\infty}^{\ell=\infty} \mathrm{i}^{\ell+1} \ell \mathrm{~J}_{\ell}\left(k_{\perp} r_{\perp}\right) \mathrm{e}^{\mathrm{i} \ell(\theta-\alpha)}
\end{array}\right\}
$$

using $\dot{p}_{\perp}=-\partial \delta H / \partial q_{\perp}=-\partial \delta H / \partial \theta$.
THEOREM. The integrand on the right-hand side of (6.108) becomes

$$
\begin{align*}
& \left\langle\dot{p}_{\perp}(t) \dot{p}_{\perp}(t-\tau)\right\rangle=\left\langle e^{2} \frac{\int \mathrm{~d}^{3} \boldsymbol{k} \int \mathrm{~d}^{3} \boldsymbol{k}^{\prime}}{(2 \pi)^{3}} \frac{{ }^{3}}{(2 \pi)^{3}} \delta \phi(\boldsymbol{k}, t) \delta \phi^{*}(\boldsymbol{k}, t-\tau) \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{R}^{t}} \mathrm{e}^{\mathrm{i} \boldsymbol{k}^{\prime} \cdot \boldsymbol{R}^{t-\tau}}\right. \\
& \left.\quad \times \sum_{\ell=-\infty}^{\ell=\infty} \sum_{\ell^{\prime}=-\infty}^{\ell^{\prime}=\infty} \ell \ell^{\prime}(-i)^{\ell^{\prime}} \mathrm{i}^{\ell} \mathbf{J}_{\ell}\left(k_{\perp} r_{\perp}^{t}\right) \mathrm{J}_{\ell^{\prime}}\left(k_{\perp}^{\prime} r_{\perp}^{t-\tau}\right) \mathrm{e}^{\mathrm{i}\left(\left(\theta^{t}-\alpha\right)\right.} \mathrm{e}^{-\mathrm{i} l^{\prime}\left(\theta^{t-\tau}-\alpha^{\prime}\right)}\right\rangle . \tag{6.112}
\end{align*}
$$

We use the zero-order orbit for $z^{t-\tau}=z^{t}-v_{z} \tau$ and average over phases,
$\lim _{L \rightarrow \infty}(1 / L) \int_{-L / 2}^{L / 2} \mathrm{~d} z \exp \left[\mathrm{i}\left(k_{z}-k_{z}^{\prime}\right) z\right]=(2 \pi / L) \delta\left(k_{z}-k_{z}^{\prime}\right)$ and similarly in $x, y$, and/or $\theta$ to obtain the following:

$$
\begin{align*}
\left\langle\dot{p}_{\perp}(t) \dot{p}_{\perp}(t-\tau)\right\rangle= & e^{2} \int_{0}^{\infty} \frac{\mathrm{d} \tau}{\operatorname{Vol}} \frac{\int \mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \delta \phi(\boldsymbol{k}, t) \delta \phi^{*}(\boldsymbol{k}, t-\tau) \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{R}^{t}} \mathrm{e}^{\mathrm{i} \boldsymbol{k}^{\prime} \cdot \boldsymbol{R}^{t-\tau}} \\
& \times \sum_{\ell=-\infty}^{\ell=\infty} \ell^{2} \mathrm{~J}_{\ell}\left(k_{\perp} r_{\perp}\right)^{2}\left\langle\mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \Delta \boldsymbol{R}(\tau)+\mathrm{i} \ell \Delta \phi(\tau)}\right\rangle . \tag{6.113}
\end{align*}
$$

We limit the ensemble of waves to only normal modes,

$$
\begin{equation*}
\delta \phi(\boldsymbol{k}, t)=\delta \tilde{\phi}(\boldsymbol{k}, t) \mathrm{e}^{-\mathrm{i} \omega_{k} t}, \quad \delta \phi \delta \phi^{*}=\delta \tilde{\phi}(\boldsymbol{k}, t) \delta \tilde{\phi}^{*}(\boldsymbol{k}, t-\tau) \mathrm{e}^{-\mathrm{i} \omega_{k} \tau}, \tag{6.114}
\end{equation*}
$$

and ignore the slow temporal variation of the mode amplitudes $\delta \tilde{\phi}(\boldsymbol{k}, t)$. Use of $(6.113),(6.114),(6.108)$ and the definition of the spectral density

$$
\begin{equation*}
S_{\phi}(\boldsymbol{k}, t) \equiv \lim _{V o l \rightarrow \infty} \frac{|\delta \tilde{\phi}(\boldsymbol{k}, t)|^{2}}{\mathrm{Vol}} \tag{6.115}
\end{equation*}
$$

yields the expression for the diffusion coefficient

$$
\begin{align*}
D_{\perp} & \approx e^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} S_{\phi}(\boldsymbol{k}, t) \sum_{\ell} \ell^{2} \mathrm{~J}_{\ell}^{2} \int_{0}^{\infty} \mathrm{d} \tau \mathrm{e}^{-\mathrm{i} \omega_{k} \tau+\mathrm{i} k_{z} v_{z} \tau+\mathrm{i} \ell \Omega \tau} \\
& =e^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} S_{\phi}(\boldsymbol{k}, t) \sum_{\ell} \ell^{2} \mathrm{~J}_{\ell}^{2}\left[\pi \delta\left(k_{z} v_{z}+\ell \Omega-\omega_{k}\right)+\frac{P}{\mathrm{i}\left(\omega_{k}-k_{z} v_{z}-\ell \Omega\right)}\right] \tag{6.116}
\end{align*}
$$

EXERCISE. Show that the imaginary part of the diffusion coefficient in (6.116) vanishes using the convention $\omega_{-k}=-\omega_{k}$ and summing over $\boldsymbol{k}$ in the integral.

ExErcise. (i) Show that the other important terms in the diffusion tensor satisfy

$$
\left[\begin{array}{cc}
D_{z z} & D_{z \perp} \\
D_{\perp z} & D_{\perp \perp}
\end{array}\right] \propto\left[\begin{array}{cc}
k_{z}^{2} & k_{z} \ell \\
k_{z} \ell & \ell^{2}
\end{array}\right] .
$$

(ii) Derive the diffusion tensor for electromagnetic waves, $\delta \phi \rightarrow \delta A$.

### 6.5.6. Self-consistent quasilinear diffusion equation and energy conservation

Here quasilinear theory is further elaborated. In terms of momentum variables ( $p_{z}, p_{\perp}$ ) the diffusion tensor is

$$
\begin{equation*}
\stackrel{\leftrightarrow}{\boldsymbol{D}}=e^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \sum_{\alpha} S_{\phi}^{\alpha}(\boldsymbol{k}, t) \sum_{\ell} \mathrm{J}_{\ell}^{2}\left(k_{\perp} r_{\perp}\right) \pi \delta\left(k_{z} v_{z}+\ell \Omega-\omega_{k}^{\alpha}\right) \boldsymbol{k} \boldsymbol{k}, \quad \boldsymbol{k}=k_{z} \hat{\boldsymbol{e}}_{1}+\ell \hat{\boldsymbol{e}}_{2}, \tag{6.117}
\end{equation*}
$$

where $\alpha$ indicates the branches of the dispersion relation, e.g. for electrostatic waves propagating parallel to the magnetic field this corresponds to electron plasma waves and ion-acoustic waves. The diffusion equation for the slowly varying distribution function for a specific branch is then

$$
\begin{align*}
\frac{\partial\langle f\rangle}{\partial t}\left(p_{z}, p_{\perp} ; t\right)= & e^{2} \int \frac{\mathrm{~d}^{3} k}{(2 \pi)^{3}} \sum_{\alpha} S_{\phi}^{\alpha}(\boldsymbol{k}, t) \sum_{\ell}\left(k_{z} \frac{\partial}{\partial p_{z}}+\ell \frac{\partial}{\partial p_{\perp}}\right) \mathrm{J}_{\ell}^{2}\left(k_{\perp} r_{\perp}\right) \\
& \times \pi \delta\left(k_{z} v_{z}+\ell \Omega-\omega_{k}\right)\left(k_{z} \frac{\partial}{\partial p_{z}}+\ell \frac{\partial}{\partial p_{\perp}}\right)\langle f\rangle\left(p_{z}, p_{\perp} ; t\right) . \tag{6.118}
\end{align*}
$$

DEFINITION. We can define an invariant $I$ for a wave with characteristics $\left(k, l, \omega_{k}\right)$ as follows:

$$
\begin{equation*}
I=\frac{\left(p_{z}-m \frac{\omega}{k_{z}}\right)^{2}}{2 m}+\Omega p_{\perp} \tag{6.119a}
\end{equation*}
$$

with momentum-space gradient

$$
\begin{equation*}
\nabla I=\hat{\boldsymbol{e}}_{1}\left(v_{z}-\frac{\omega}{k}\right)+\hat{\boldsymbol{e}}_{2} \Omega . \tag{6.119b}
\end{equation*}
$$

From (6.117) and (6.119b) one concludes the following inner product vanishes,

$$
k \cdot \nabla I=k_{z}\left(v_{z}-\frac{\omega}{k_{z}}\right)+\ell \Omega=0
$$

as a consequence of the resonance condition. Hence, $\boldsymbol{k}$ and $\nabla I$ are perpendicular: $\nabla I$ is directed across the invariant contours, and $\boldsymbol{k}$ is in the direction of the invariant curve. Here $\boldsymbol{k} \cdot \nabla f$ should become uniform because particles diffuse along the invariant curves until $\nabla_{k} \cdot\langle f\rangle=0$.

At this point we return to consideration of the development of (6.113)-(6.116). In this derivation there was an assumed limitation on the rapidity of the temporal variation of slowly varying coefficients: $\tilde{\phi}(\boldsymbol{k}, t) \tilde{\phi}^{*}(\boldsymbol{k}, t-\tau) \approx \tilde{\phi}(\boldsymbol{k}, t) \tilde{\phi}^{*}(\boldsymbol{k}, t)$. Inclusion of the next term in a Taylor series looks like $\tilde{\phi}^{*}(\boldsymbol{k}, t-\tau) \approx \tilde{\phi}^{*}(\boldsymbol{k}, t)-\tau(\partial / \partial t) \tilde{\phi}^{*}(\boldsymbol{k}, t)+$ $\cdots$, where $\tau$ is the order of the correlation time. The linear correction term in the Taylor series is clearly small if $\gamma \ll 1 / \tau_{\text {corr }}$, i.e. if the correlation time is assumed short compared to the linear growth time. This does not imply that $\tilde{\phi}(\boldsymbol{k}, t) \tilde{\phi}^{*}(\boldsymbol{k}, t-\tau) \approx \tilde{\phi}(\boldsymbol{k}, t) \tilde{\phi}^{*}(\boldsymbol{k}, t)$ is time independent: slow variations are explicitly included, and the growth or damping rate of $S_{\phi}^{\alpha}$ is $2 \gamma$ to good approximation. Hence, the quasilinear diffusion equation includes slow temporal variations in both $\langle f\rangle=f_{0}+f_{2}$ and $\boldsymbol{D}$ :

$$
\begin{equation*}
\frac{\partial\langle f\rangle}{\partial t}=\frac{\partial}{\partial \boldsymbol{p}} \cdot\left(\boldsymbol{D} \cdot \frac{\partial\langle f\rangle}{\partial \boldsymbol{p}}\right) \tag{6.120}
\end{equation*}
$$

The temporal variation in $\langle f\rangle$ is a second-order resonant perturbation. We can construct a closed set of equations based on the diffusion equation and energy conservation as follows. The partial time derivative of $\langle f\rangle$ is proportional to $S_{\phi}$, and the spectral density evolves to lowest order according to 'linear theory' determining the growth or damping rate $\gamma$ but using the total perturbed distribution function that evolves in time.

Theorem. Self-consistent quasilinear theory

$$
\left.\begin{array}{c}
\frac{\partial\langle f\rangle}{\partial t}=\frac{\partial}{\partial \boldsymbol{p}} \cdot\left(\boldsymbol{D} \cdot \frac{\partial}{\partial \boldsymbol{p}}\langle f\rangle\right),  \tag{6.121}\\
\boldsymbol{D}=\cdots S_{\phi}(\boldsymbol{k}, t) \\
\frac{\partial S_{\phi}(\boldsymbol{k}, t)}{\partial t}=2 \gamma(\boldsymbol{k}, t) S_{\phi}(\boldsymbol{k}, t),
\end{array}\right\}
$$

THEOREM. Energy conservation

$$
\begin{align*}
& \frac{\mathrm{d}}{\mathrm{~d} t} \int \mathrm{~d}^{3} \boldsymbol{p} \int \mathrm{~d}^{3} \boldsymbol{q} H_{0}(\boldsymbol{p})\langle f\rangle(\boldsymbol{p}, t)+\frac{\mathrm{d}}{\mathrm{~d} t}(\text { field energy })=0 \\
& \quad \Rightarrow \sum_{s} \int \mathrm{~d} p_{z} \int \mathrm{~d} p_{\perp} \int \mathrm{d} z \int \mathrm{~d} \phi \int \mathrm{~d} X H_{0}\left(p_{z}, p_{\perp}\right) \frac{\partial}{\partial \boldsymbol{p}} \cdot\left(\boldsymbol{D} \cdot \frac{\partial}{\partial \boldsymbol{p}}\langle f\rangle\right) \\
& \quad+\mathrm{Vol} \cdot \int \mathrm{~d}^{3} \boldsymbol{k} \omega \frac{\partial \varepsilon^{\prime}}{\partial \omega} \frac{k^{2} S_{\phi}(\boldsymbol{k}, t)}{8 \pi} 2 \gamma=0 . \tag{6.122}
\end{align*}
$$

We integrate the first term in (6.122) and use (6.117) and (6.118) to obtain

$$
\begin{align*}
& -\sum_{s} m^{3} \int \mathrm{~d}^{3} v e^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} S_{\phi}(\boldsymbol{k}, t) \sum_{\ell} \mathrm{J}_{\ell}^{2}\left(k_{\perp} r_{\perp}\right) \pi \delta\left(k_{z} v_{z}+\ell \Omega-\omega_{k}\right) \boldsymbol{K} \boldsymbol{K} \cdot \frac{\partial}{\partial \boldsymbol{p}}\langle f\rangle \\
& \quad+\left.\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \omega \frac{\partial \varepsilon^{\prime}}{\partial \omega}\right|_{\omega_{k}} \frac{k^{2} S_{\phi}(\boldsymbol{k}, t)}{8 \pi} 2 \gamma=0 \tag{6.123}
\end{align*}
$$

where we have divided out a common volume factor. We note that $m^{3}\langle f(\boldsymbol{p})\rangle \rightarrow$ $\langle f(\boldsymbol{p})\rangle=n_{0}\langle g\rangle$ and $\int \mathrm{d} \boldsymbol{v}^{3} g(\boldsymbol{v})=1$. Equation (6.123) can then be used to solve for $\gamma$ inside the integral over $\boldsymbol{k}$ space (and the spectral density $S_{\phi}$ divides out),

$$
\begin{align*}
\gamma(\boldsymbol{k})= & \frac{1}{\left.\frac{\partial \varepsilon^{\prime}}{\partial \omega}\right|_{\omega_{k}}} \sum_{s} \frac{4 \pi e_{s}^{2} n_{0 s}}{m_{s} k^{2}} \int \mathrm{~d}^{3} v \sum_{\ell} \mathrm{J}_{\ell}^{2}\left(k_{\perp} r_{\perp}\right) \pi \delta\left(k_{z} v_{z}+\ell \Omega-\omega_{k}\right) m_{s} \boldsymbol{K} \cdot \frac{\partial}{\partial \boldsymbol{p}}\langle g\rangle \\
= & \frac{1}{\left.\frac{\partial \varepsilon^{\prime}}{\partial \omega}\right|_{\omega_{k}}} \sum_{s} \frac{\omega_{s}^{2}}{k^{2}} \int \mathrm{~d}^{3} v \\
& \times \sum_{\ell} \mathrm{J}_{\ell}^{2}\left(k_{\perp} r_{\perp}\right) \pi \delta\left(k_{z} v_{z}+\ell \Omega-\omega_{k}\right)\left(k_{z} \frac{\partial}{\partial v_{z}}+\frac{\ell \Omega}{v_{\perp}} \frac{\partial}{\partial v_{\perp}}\right)\langle g\rangle\left(v_{z}, v_{\perp}\right) . \tag{6.124}
\end{align*}
$$

In (6.123) and (6.124), $\boldsymbol{K} \equiv k_{z} \hat{\boldsymbol{e}}_{1}+\ell \hat{\boldsymbol{e}}_{2}$. Now we can refer to the relation (2.96)

$$
\gamma(\boldsymbol{k})=-\frac{\varepsilon_{I}}{\left.\frac{\partial \varepsilon_{R}(\omega, \boldsymbol{k})}{\partial \omega}\right|_{\omega_{k}}}
$$

to obtain an explicit formula for $\varepsilon_{I}$, use the Kramers-Kronig relation (Jackson 1999) to determine $\varepsilon_{R}$ and can compare to the results derived in $\S 2.9 .5$. Equations (6.121)(6.124) provide a formalism based on quasilinear theory for evolving both the distribution function and the amplitudes of the waves self-consistently.
6.6. Particle subject to gyroresonance - instabilities and diffusion, invariants of the motion, 'loss-cone’ effects
In the presence of an applied, static, uniform magnetic field, the wave-particle resonance is generalized from Landau resonance to the cyclotron resonance that appears mathematically in the denominator of the susceptibility in (4.55). The physics


Figure 33. A particle with $\omega^{\prime}=\omega-k_{z} v_{z}=2 \Omega$ and with $k_{\perp} r=\pi / 2$ will rotate around the gyro-radius from 0 to 2 in one-half a cyclotron period and see an electric field $\delta E_{y}$ whose phase has advanced in time by $2 \pi$ and in $x$ by $\pi$.
of the cyclotron resonance is that the Doppler-shifted frequency of the wave matches a cyclotron harmonic so that a cyclotron harmonic component of the wave can steadily accelerate or decelerate the particle: in the particle frame $\omega^{\prime}=\omega-k_{z} v_{z}=\ell \Omega$. It is important to take into account the physical effects of a finite spatial variation of the wave field in the plane of the gyro-motion. Consider for example the special case of $k_{\perp} r \sim \pi / 2$ where $r=v_{\perp} / \Omega$. In figure 33 is diagrammed the cyclotron orbit of a charged particle in its zero-order drift frame and the phase of the electric field it sees. The resonance condition is such that the particle's perpendicular velocity vector is co-aligned with the linearly polarized, perturbed electric field $\delta E_{y}$ at both 0 and 2 , and so can continue to be accelerated, while the particle's velocity vector is perpendicular to $\delta \boldsymbol{E}$ at points 1 and 3 .

We will describe the gyro-resonant wave-particle interaction in terms of increments to the particle energy, momentum and angular momentum. We use canonical variables. In a quantum mechanical picture when a photon interacts with a particle, the change in energy satisfies $\Delta H=\hbar \omega$; the change in momentum satisfies $\Delta m v_{z}=\hbar k$; and the change in angular momentum satisfies $\Delta p_{\perp}=\ell \hbar$. We calculate the analogous classical changes in energy and in linear and angular momenta in the following analysis.

Theorem. For a gyrating particle,

$$
\left.\begin{array}{c}
H=\frac{1}{2} m v_{z}^{2}+\frac{1}{2} m v_{\perp}^{2}=\frac{1}{2} m v_{z}^{2}+p_{\perp} \Omega, \quad p_{\perp}=\frac{\frac{1}{2} m v_{\perp}^{2}}{\Omega}  \tag{6.125}\\
\Delta H=m v_{z} \Delta v_{z}+\Omega \Delta p_{\perp}
\end{array}\right\}
$$

Definition. Canonical variables and guiding-centre coordinates (see § 6.5.4)

$$
\begin{align*}
& \left\{x, y, z, p_{x}, p_{y}, p_{z}\right\} \quad p_{x}=m v_{x}+\frac{e}{c} A_{x}^{0}, \text { etc. } \\
& \Rightarrow\left\{z, p_{z}=m v_{z}, p_{\perp}=\frac{\frac{1}{2} m v_{\perp}^{2}}{\Omega}, \phi, X, a Y\right\} \tag{6.126}
\end{align*}
$$

THEOREM. We describe the particle gyration in terms of canonical variables,

$$
\left.\begin{array}{c}
x=X+r_{\perp} \cos \phi,  \tag{6.127}\\
y=Y+r_{\perp} \sin \phi, \\
\dot{x}=-\Omega r_{\perp} \sin \phi, \\
\dot{y}=\Omega r_{\perp} \cos \phi, \\
p_{\perp} \equiv \frac{\frac{1}{2} m v_{\perp}^{2}}{\Omega}, \quad r_{\perp} \equiv \frac{v_{\perp}}{\Omega} .
\end{array}\right\}
$$

In (6.127) $X$ and $Y$ are guiding-centre positions with the magnetic field oriented in the $z$ direction; $\left(p_{\perp}, \phi\right)$ is a canonically conjugate pair; $(X, a Y)$ is also a canonically conjugate pair if $a=e B / c$, which choice is consistent with the conditions on the canonical variables, $\left\{p_{i}, q_{j}\right\}=\delta_{i j}$ and $\left\{q_{i}, q_{j}\right\}=0$ where $\{f, g\}$ is the Poisson bracket.

We next extend the equations in (6.125)-(6.127) to describe gyro-resonance in the presence of a longitudinal wave. The gyro-resonance condition is

$$
\begin{equation*}
\omega-k_{z} v_{z}=\ell \Omega \tag{6.128}
\end{equation*}
$$

where $\ell$ is an integer; $\ell=0$ corresponds to the Landau resonance analysed earlier. Gyro-resonance can occur for $|\ell|>0$ for $k_{\perp} \neq 0$. From a quantum physics point of view, when a particle interacts with a photon, the conservation of energy, momentum and angular momentum leads to the following relations, and implies an invariant $I$,

$$
\left.\begin{array}{cl}
\Delta H=\hbar \omega \quad \Delta p_{z}=\hbar k_{z} & \Delta p_{\perp}=\ell \hbar  \tag{6.129}\\
\Delta\left(k_{z} H-\omega p_{z}\right)=\hbar \omega k_{z}-\hbar k_{z} \omega=0 \quad \Rightarrow \quad I \equiv k_{z} H-\omega p_{z}=\text { invariant. }
\end{array}\right\}
$$

We now construct a quantity $I_{w}$ related to the particle kinetic energy in the frame of a wave,

$$
\begin{equation*}
V_{z} \equiv \frac{\omega}{k_{z}} \quad I_{w}=\frac{1}{2} m\left(v_{z}-V_{z}\right)^{2}+\frac{1}{2} m v_{\perp}^{2}-\frac{1}{2} m V_{z}^{2} \tag{6.130}
\end{equation*}
$$

However, $I_{w}$ needs to include the potential energy due to the wave to be useful in constructing the classical particle Hamiltonian and deducing an invariant of the motion. The classical Hamiltonian including a longitudinal wave is

$$
\begin{align*}
H & =\frac{p_{z}^{2}}{2 m}+p_{\perp} \Omega+e \phi_{0} \sin \left[k_{z} z+k_{\perp} x-\omega t\right] \\
& =\frac{p_{z}^{2}}{2 m}+p_{\perp} \Omega+e \phi_{0} \sin \left[k_{z} z+k_{\perp}\left(X+r_{\perp} \cos \phi\right)-\omega t\right] \tag{6.131}
\end{align*}
$$

Theorem. Using Hamilton's equations and $H$ in (6.131)

$$
\left.\begin{array}{c}
\dot{H}=\frac{\partial}{\partial t} H=-\omega e \phi_{0} \cos \left[k_{z} z+k_{\perp}\left(X+r_{\perp} \cos \phi\right)-\omega t\right]  \tag{6.132}\\
\dot{p}_{z}=-\frac{\partial}{\partial z} H=-k_{z} e \phi_{0} \cos \left[k_{z} z+k_{\perp}\left(X+r_{\perp} \cos \phi\right)-\omega t\right] .
\end{array}\right\}
$$

It follows from (6.132) that there is an invariant $I$ that is analogous to that in (6.129),

$$
\begin{equation*}
I=H-\frac{\omega}{k_{z}} p_{z}, \quad \dot{I}=\dot{H}-\frac{\omega}{k_{z}} \dot{p}_{z}=0 . \tag{6.133}
\end{equation*}
$$

In the wave frame $z^{\prime}=z-\left(\omega / k_{z}\right) t$, there is no explicit time dependence in $H^{(W)}$, i.e. $\omega=0$; and $H^{(W)}$ is then a constant independent of time.

Particles follow trajectories on families of curves in the phase space of $\left(v_{z}, v_{\perp}\right)$ determined by $I=$ constant. The curves are half-ellipses ( $v_{\perp}>0$ ) displaced in $v_{z}$ by $V_{z}$ from the origin, for infinitesimal wave amplitude. Finite wave amplitude distorts the invariant curves from exact ellipses. Particles with velocities

$$
\begin{equation*}
v_{z}^{R}=\frac{(\omega-\ell \Omega)}{k_{z}}=V_{z}-\frac{\ell \Omega}{k_{z}} \tag{6.134}
\end{equation*}
$$

are resonant with the wave. Non-resonant particles have an adiabatic response to the wave. Resonant particles can have an irreversible response. A trapped particle will oscillate around the resonant velocity $v_{z}^{R}$ with characteristics that depend on the finite amplitude of the wave. Nearly resonant velocities $v_{z}$ whose magnitudes are less than $\left|v_{z}^{R}\right|$ will gain energy from the wave and accelerate, and nearly resonant velocities whose magnitudes are greater than $\left|v_{z}^{R}\right|$ will lose energy to the wave and decelerate. Depending on the sign of the slope of the distribution function, which determines if there are more or fewer particles with velocities greater or less than the resonant velocity to exchange energy with the wave, the resonant wave-particle interaction will lead to growth or damping of the wave similar to that discussed earlier in $\S \S 2$ and 3.

THEOREM. (i) If $V_{z}>0$ and $v_{z}>0$, then linear exponential growth $\gamma>0$ is expected if $\partial f / \partial p_{z}>0$; and linear exponential damping $\gamma<0$ is expected if $\partial f / \partial p_{z}<0$. (ii) If $V_{z}>0$ and $v_{z}<0$, then linear exponential growth $\gamma>0$ is expected if $\partial f / \partial p_{z}<0$; and linear exponential damping $\gamma<0$ is expected if $\partial f / \partial p_{z}>0$.

DEFINITION. In mirror machines there is a 'loss cone' determined by the ratio of the axial magnetic field at its maximum to its value at its minimum (the mirror ratio), i.e. particles at the mid-plane with $\left|v_{z} / v_{\perp}\right| \geqslant \operatorname{cotan}\left(\theta_{c}\right)$ will not be confined by the magnetic mirror. The loss cone establishes velocity gradients of the distribution function, and the stability theorem then indicates that instabilities arise. The instabilities produce velocity-space diffusion into the loss cone that exacerbates particle loss out of the mirror, i.e. loss-cone instability (Rosenbluth \& Post 1965).

EXERCISE. Use conservation of energy and magnetic moment to derive the loss-cone condition on $\left|v_{z} / v_{\perp}\right|$ in a simple magnetic mirror configuration.

Consider a set of waves such that $V_{z} \equiv \omega\left(k_{\perp}, k_{z}\right) / k_{z}$ is the same for the range of $k_{z}$ and $k_{\perp}$ in the set. Consider particles with a broad distribution of $v_{\perp}$ values extending to $v_{\perp}=0$ and a narrow band of resonant velocities in $v_{z}$ satisfying (6.134) with $\ell=-1$, i.e.

$$
\begin{equation*}
\Delta v_{z}^{R}=\Omega \Delta\left(\frac{1}{k_{z}}\right), \quad v_{z}^{R}=V_{z}-\frac{\Omega}{k_{z}} \tag{6.135}
\end{equation*}
$$

On any invariant curve there can be quasilinear diffusion in the vicinity of the resonance (assuming the presence of a decorrelation mechanism) that manifests itself by a random walk. The random walks can occur throughout the band of resonant particles. The net result of the diffusion is uniformity of the velocity distribution in the resonant band. If there is a loss cone present, then the resonance band can cross the loss-cone boundary at $v_{\perp}=v_{z}^{R} / \operatorname{cotan}\left(\theta_{c}\right)$; and the diffusion can drive particles into
the loss region. An increase in the amplitude of the turbulent waves will increase the diffusion rate into the loss region.

If we consider other cyclotron harmonics $l$, there are additional resonant bands for the same $V_{z}$; and there will be more resonant bands in phase space. Furthermore, if the wave spectrum contains waves with more than one value of $V_{z}$, the likelihood of diffusion increases. For every value of $V_{z}$ and infinitesimal wave amplitude, there is a new family of invariant curves that are displaced in $v_{z}$ by a unique value of $V_{z}$. A resonant particle can diffuse in its resonant band associated with one value of $V_{z}$, encounter an invariant curve, and then move along the invariant curve a short distance before encountering another unique resonant band in which it diffuses.
[Editor's note: the preceding picture is significantly altered for a spectrum of finite wave amplitudes because the independence of the invariant curves for distinct values of the phase velocity $V_{z}$ becomes invalid. The solution of the invariant curves should come from (6.131) to (6.133) summing over all waves with finite amplitude. However, the solution for 'independent' invariant curves for each wave in a set of waves with distinct phase velocities and infinitesimal amplitudes should be valid and useful for understanding the dynamics in the near vicinity of where an invariant curve for a distinct phase velocity crosses a resonant velocity band for the same phase velocity. Resonant wave diffusion was an active area of research by Kaufman and his students and post-doctoral researchers in the next ten years after these lectures. (Smith \& Kaufman 1975, Smith \& Kaufman 1978, Smith \& Pereira 1978, Smith \& Cohen 1983).]

With a wave spectrum of multiple distinct phase velocities there are bands of resonant velocity. The width of the resonant bands increases with increased wave amplitudes. The possibility of resonance overlap occurs. The consequence of resonance overlap is increased velocity-space transport. If the particle ends up farther from the origin in $\left(v_{z}, v_{\perp}\right)$, then heating has occurred (cooling if the particle ends up closer to the origin). For many waves, more of phase space becomes accessible to diffusion, and $f(\boldsymbol{v})$ tends to uniformity in the diffusive regions subject to the constraint that the overall energy is bounded. As uniformity of $f$ is approached, i.e. $f$ flattens, the growth or damping rate $\gamma$ tends to zero; and waves no longer exchange energy with the particles. The velocity distribution also tends to isotropy. The resulting modifications to $f$ render the system increasingly stable.

### 6.7. Gardner's theorem for stability of a Vlasov plasma - sources of instability and examples

In a plasma described by the Vlasov-Poisson system of equations, it is possible to make a general statement on the stability of the plasma.

ThEOREM (Gardner 1963). For the Vlasov-Poisson system of equations, if $f$ is isotropic and the derivative of $f$ with respect to energy $\partial f / \partial \varepsilon<0$, then the Vlasov-Poisson system is linearly and nonlinearly stable. A spatially uniform, isotropic and monotonic velocity distribution function (no relative drifts, of course) is stable.

Sources of instability:
(i) Non-uniformity - instability derives energy from redistributing plasma in space.
(ii) Anisotropy - instability derives energy from redistributing plasma in velocity space, as in magnetic mirror devices.
(iii) Non-monotonicity - like bump on tail, energy becomes available as a plateau forms in velocity space.
(iv) Relative drift - ordered drift motion can contribute kinetic energy to waves.

A common feature in the preceding list is that instability is driven by some redistribution of the plasma in configuration or velocity space, which allows the conversion of kinetic energy in the plasma into wave energy while relaxing the source of free energy. We have already encountered a few examples of this in earlier lectures, e.g. §§ 6.2 and 2.6 .

Example. The dispersion relation in the ion frame for a longitudinal ion-cyclotron wave is

$$
\begin{equation*}
\omega=\Omega_{i}\left[1+\tau e^{-b_{i}} \mathrm{I}_{1}\left(b_{i}\right)\right], \quad \tau=T_{e} / T_{i}, \quad b_{i}=\left(k_{\perp} r_{\perp}^{i}\right)^{2} \tag{6.136}
\end{equation*}
$$

The ions are assumed to be a Maxwellian, and the electron response is close to adiabatic in the low-frequency limit with $k \lambda_{e} \ll 1$. We further assume that the ion damping is weak, i.e. $\omega-\Omega_{i} \neq k_{z} v_{z}^{i}$ and $k_{z} \ll\left(\left(\omega-\Omega_{i}\right) / v_{\mathrm{th}}^{i}\right) \sim O\left(\Omega_{i} / v_{\mathrm{th}}^{i}\right)=\left(1 / r_{\perp}^{i}\right) \sim k_{\perp}$. Thus, $\boldsymbol{k}$ is nearly perpendicular to $\boldsymbol{B}$. The conditions for electron resonance are $\omega-\ell \Omega_{e}=k_{z} v_{z}^{e}$ which requires $\ell=0$ and admits the possibility of a simple Landau resonance: $\omega / k_{z}=v_{z}^{e} \gg \Omega_{i} r_{\perp}^{i} \sim v_{\mathrm{th}}^{\mathrm{i}}$. It is difficult for the resonant electron velocity to fall in the heart of the electron velocity distribution. Does the electron Landau resonance contribute Landau damping or growth? Using the methods in $\S 2$ one obtains,

$$
\begin{align*}
\gamma\left(k_{z}, k_{\perp}\right) & =\left.\frac{1}{\frac{\partial \varepsilon^{\prime}}{\partial \omega}}\right|_{\omega_{k}} \frac{\omega_{e}^{2}}{k^{2}} \int_{-\infty}^{\infty} \mathrm{d} v_{z} \int_{0}^{\infty} 2 \pi v_{\perp} \mathrm{d} v_{\perp} \mathrm{J}_{0}^{2}\left(k_{\perp} r_{\perp}\right) \pi \delta\left(v_{z}-\frac{\omega_{k}}{k_{z}}\right) \frac{\partial g\left(v_{z}, v_{\perp}\right)}{\partial v_{z}} \\
& =\frac{1}{\left.\left.\frac{\partial \varepsilon^{\prime}}{\partial \omega}\right|_{\omega_{k}}\left(\omega_{e}^{2} / k^{2}\right) \int_{0}^{\infty} 2 \pi v_{\perp} \mathrm{d} v_{\perp} \mathrm{J}_{0}^{2}\left(k_{\perp} r_{\perp}\right) \pi \frac{\partial g\left(v_{z}, v_{\perp}\right)}{\partial v_{z}}\right|_{v_{z}=\left(\omega_{k} / k_{z}\right)}} \\
& =\left.\left(\omega-\Omega_{i}\right) \frac{k^{2} \lambda_{e}^{2} \omega_{e}^{2}}{k^{2}} \pi \frac{\partial g\left(v_{z}, v_{\perp}\right)}{\partial v_{z}}\right|_{v_{z}=\left(\omega_{k} / k_{z}\right)} \\
& \left.\cong \Omega_{i} v_{\text {the }}^{2} \frac{\partial g\left(v_{z}, v_{\perp}\right)}{\partial v_{z}}\right|_{v_{z}=\left(\omega_{k} / k_{z}\right)} \tag{6.137}
\end{align*}
$$

where $k_{\perp} r_{\perp} \ll 1$ and $\mathrm{J}_{0}^{2}\left(k_{\perp} r_{\perp}\right) \approx 1$ because the electron Larmor radius is so small and we have assumed $g=g\left(v_{z}\right) g\left(v_{\perp}\right)$. If $\partial g\left(v_{z}\right) / \partial v_{z}<0$ everywhere in $v_{z}$ there is electron damping. If there is an electron drift $v_{\text {de }}$ in the ion frame and the electron velocity distribution is symmetric about $v_{\mathrm{de}}$ in the ion frame and peaked at $v_{\mathrm{de}}$, then $\partial g\left(v_{z}\right) / \partial v_{z}>0$ for $0<\left(\omega / k_{z}\right)<v_{\mathrm{de}}$; and the electrons are destabilizing. For net instability, the electron destabilizing effects must overcome ion damping. This is the Drummond-Rosenbluth instability (Drummond \& Rosenbluth 1962) with condition for instability, $v_{\mathrm{de}}>5 \tau v_{\text {thi }}$, which is not difficult to achieve. For this instability one can readily construct a theory for quasilinear diffusion following the procedure in $\S 6.5$, and one expects plateau formation in $g_{e}\left(v_{z}\right)$ driven by the ion-cyclotron wave turbulence.

EXERCISE. Consider a wave with $\Omega_{i}, \gamma \ll \omega \ll \Omega_{e}$ driven unstable by an anisotropic ion velocity distribution. Treat the ions as unmagnetized and ignore electron Landau damping. Consider oblique propagation with $k_{z} \ll k_{\perp}$. Project the ion velocity distribution onto $\boldsymbol{k}$ to render the analysis one-dimensional. Instability results from the projected velocity distribution having an interval with positive slope. Qualitatively examine quasilinear diffusion.

### 6.8. Nonlinear three-wave interactions

Energy transfer between modes is dominated by resonant three-wave decay in a nonturbulent plasma, i.e. a plasma in which the energy in waves is still small compared to the particle kinetic energy. From a quantum mechanical point of view, three-wave decay can be described efficiently in terms of conservation laws,

$$
\left.\begin{array}{c}
\text { energy conservation: } \quad \hbar \omega_{1}=\hbar \omega_{2}+\hbar \omega_{3}  \tag{6.138}\\
\text { momentum conservation: } \quad \hbar k_{1}=\hbar k_{2}+\hbar k_{3} .
\end{array}\right\}
$$

A few examples of three-wave decay processes are as follows. An electron plasma wave (Langmuir wave) can decay into another electron plasma wave and an ion acoustic wave. A transverse wave can decay into another transverse wave and either an electron plasma wave or an ion-acoustic wave. In special circumstances a transverse wave can decay into two electron plasma waves. An Alfvén wave can decay into another Alfvén and an ion-acoustic wave. There are many other examples that have been identified experimentally and studied theoretically, and a rich literature exists.

### 6.8.1. Resonance conditions derived from phase matching

There is more than one approach to analysing nonlinear three-wave interactions. There are direct methods using perturbation theory to solve the Maxwell equations and either the Vlasov equations, e.g. Davidson (1972), or fluid equations (e.g. Tsytovich 1967; Drake et al. 1974; Forslund, Kindel \& Lindman 1975) to model the plasma response. Some of these approaches involve a good deal of analytical brute force. There are more elegant theories based on a formal Hamiltonian theory for the plasma fluid response, e.g. Davidson (1972) and very powerful Lagrangian theories for a fluid or Vlasov plasma response, e.g. Dougherty (1970), Galloway \& Kim (1971), Dewar (1972), Dougherty (1974) and others.
[Editor's note: in the more than forty years since these lectures the literature on three-wave interactions in plasmas has grown immensely. A literature survey is beyond the scope of these lecture notes.]

To understand how quadratic nonlinearities in the plasma dynamical equations lead to three-wave coupling and to illustrate how three-wave resonance conditions are derived from phase matching, consider the fluid continuity equation in one dimension,

$$
\begin{equation*}
\frac{\partial n}{\partial t}=-\frac{\partial}{\partial x}(n u), \tag{6.139}
\end{equation*}
$$

where

$$
\begin{align*}
n(x, t) & =\sum_{j=1}^{3}\left|\tilde{n}_{j}\right|(t) \cos \left(k_{j} x-\omega_{j} t+\alpha_{j}(t)\right) \\
& =\operatorname{Re} \sum_{j=1}^{3} \tilde{n}_{j}(t) \exp \left[\mathrm{i}\left(k_{j} x-\omega_{j} t\right)\right] \quad \text { and } \quad \tilde{n}_{j}=\left|\tilde{n}_{j}\right| \exp \left(\mathrm{i} \alpha_{j}(t)\right) . \tag{6.140}
\end{align*}
$$

We assume that $u$ has the same form as $n$. We expand in the wave decomposition in (6.140) and look for the beating of distinct waves on the right-hand side of (6.139) to couple to the remaining of the three waves on the left-hand side,

$$
\begin{equation*}
\mathrm{e}^{\mathrm{i} k_{2} x-\mathrm{i} \omega_{2} t}\left(-\mathrm{i} \omega_{2}+\frac{\partial}{\partial t}\right) \tilde{n}_{2}(t)=-\frac{\partial}{\partial x}\left(\tilde{n}_{1} \tilde{u}_{3} \mathrm{e}^{\mathrm{i} k_{1} x-\mathrm{i} \omega_{1} t} \mathrm{e}^{-\mathrm{i} k_{3} x+\mathrm{i} \omega_{3} t}+\tilde{n}_{0} \tilde{u}_{2} \mathrm{e}^{\mathrm{i} k_{2} x-\mathrm{i} \omega_{2} t}\right) \tag{6.141}
\end{equation*}
$$

We introduce a power-series expansion in the wave amplitudes for $n$ and $u$ to facilitate the bookkeeping in the coupling of terms,

$$
\begin{equation*}
n_{j}(x, t)=\sum_{k} \varepsilon^{k} n_{j k}=n_{j 0}+\varepsilon n_{j 1}+\varepsilon^{2} n_{j 2}+\cdots \tag{6.142}
\end{equation*}
$$

There is an equilibrium density $n_{0}$ with no fast phase variation. The lowest-order wave terms are at first order in $\varepsilon$. Thus, there is a first-order (linear) contribution to $n_{21}$ from $n_{0} u_{21}$ on the right-hand side of (6.141) and a second-order (quadratic) contribution to $n_{22}$ from the beat of bilinear quantities $n_{11} u_{31}$. From the continuity equation we see that there is a linear relation for all three waves,

$$
\begin{equation*}
-\mathrm{i} \omega_{j} n_{j}=-n_{0} \mathrm{i} k_{j} u_{j} . \tag{6.143}
\end{equation*}
$$

Using (6.143) in (6.141) and assuming perfect phase matching, we deduce that there is a second-order contribution to $(\partial / \partial t) n_{2}$

$$
\begin{equation*}
\frac{\partial}{\partial t} n_{22}=-\frac{i k_{2} \omega_{3}}{k_{3} n_{0}} n_{1} n_{3}^{*} \tag{6.144}
\end{equation*}
$$

We note that the quadratic nonlinearity $q(\boldsymbol{E}+\boldsymbol{v} \times \boldsymbol{B} / c) \cdot \partial f / \partial \boldsymbol{v}$ in which the fields beat with the perturbed velocity distribution function $f$ has the same structure as the quadratic term in the continuity equation (and, for that matter, the quadratic terms in the fluid momentum balance equation). If the fast phase variation of the quadratic beat on the right-hand sides of (6.141) does not match the fast phase variation on the left-hand side, then the nonlinear interaction will be non-resonant. If we divide out the phase factor on the left side, the average of the right-hand side over a few wavelengths in space or a few wave periods in time will phase mix to zero unless there is good phase matching, i.e.

$$
\begin{equation*}
\omega_{1}=\omega_{2}+\omega_{3} \quad \boldsymbol{k}_{1}=\boldsymbol{k}_{2}+\boldsymbol{k}_{3} \tag{6.145}
\end{equation*}
$$

EXERCISE. Recover the three-wave phase-matching conditions (6.145) by considering Bragg scattering by a moving grating.

We return to the one-dimensional analysis leading to (6.144) and use Poisson's equation to relate the linear quantities, $\mathrm{i} k_{j} E_{j 1}=4 \pi q n_{j 1}$ so that the following equation coupling electric field amplitudes results:

$$
\begin{equation*}
\frac{\partial}{\partial t} E_{22}=g_{2} E_{1} E_{3}^{*} \tag{6.146}
\end{equation*}
$$

If we systematically reduce the fluid equations or the Vlasov equation in conjunction with the Poisson equation in the same manner as is done for obtaining linear dispersion relations but retaining all bilinear nonlinearities, one obtains

$$
\left.\begin{array}{l}
\varepsilon(\omega) E(\omega)=\left[\varepsilon\left(\omega_{2}\right)+\left.\left(\omega-\omega_{2}\right) \frac{\partial \varepsilon}{\partial \omega}\right|_{\omega_{2}}\right] E\left(\omega_{2}\right)  \tag{6.147}\\
\quad=\left[\varepsilon\left(\omega_{2}\right)+\left.\frac{\partial \varepsilon}{\partial \omega}\right|_{\omega_{2}} \mathrm{i} \frac{\partial}{\partial t}\right] E\left(\omega_{2}\right)=\text { nonlinear driving. }
\end{array}\right\}
$$

Given the inherent symmetries in the dynamical equations, the composite coupledmode equations for three-wave interactions can be shown to take the form

$$
\begin{equation*}
\frac{\partial}{\partial t} E_{1}=-\frac{g}{\left.\frac{\partial \varepsilon}{\partial \omega}\right|_{\omega_{1}}} E_{2} E_{3} \quad \frac{\partial}{\partial t} E_{2}=\left.\frac{g}{\frac{\partial \varepsilon}{\partial \omega}}\right|_{\omega_{2}} E_{1} E_{3}^{*} \quad \frac{\partial}{\partial t} E_{3}=\frac{g}{\left.\frac{\partial \varepsilon}{\partial \omega}\right|_{\omega_{3}}} E_{1} E_{2}^{*} \tag{6.148}
\end{equation*}
$$

where $g$ is real.

### 6.8.2. Conservation laws - wave action

When photons scatter there is a quantum mechanical conservation law that the number of photons is conserved, although the outgoing photon may be shifted in frequency. The number of photons $N_{j}$ of a given frequency is given by the energy $W_{j}$ divided by $\hbar \omega_{j}, N_{j}=W_{j} / \hbar \omega_{j}$; and the action $J_{j}$ is defined by the product $J_{j}=\hbar N_{j}$, i.e. $\hbar$ is the quantum mechanical unit of action. The classical wave action has the same definition: $J_{j}=W_{j} / \omega_{j}$.

DEFINITION. The classical wave energy, momentum and wave-action densities are

$$
\begin{equation*}
W_{j}=\frac{\omega_{j} \bar{\varepsilon}_{j}}{8 \pi} E_{j}^{2}, \quad \boldsymbol{K}_{j}=\frac{\boldsymbol{k}_{j} \bar{\varepsilon}_{j}}{8 \pi} E_{j}^{2}, \quad J_{j}=\frac{W_{j}}{\omega_{j}}, \tag{6.149}
\end{equation*}
$$

where $\bar{\varepsilon} \equiv \partial \varepsilon / \partial \omega$. We will omit the factor of $8 \pi$ in the denominators in (6.149) in the following to reduce clutter in the equations.

THEOREM (Action conservation). Using the definitions in (6.149) and the coupledmode equations in (6.148) one can show

$$
\begin{equation*}
I_{2} \equiv J_{1}+J_{2}=\text { const. } I_{3} \equiv J_{1}+J_{3}=\text { const. } \Rightarrow \dot{J}_{1}=-\dot{J}_{2}=-\dot{J}_{3} . \tag{6.150}
\end{equation*}
$$

THEOREM (Energy and momentum conservation). Using (6.149) and (6.150), and frequency and wavenumber matching (6.145)

$$
\left.\begin{array}{rl}
\frac{\mathrm{d}}{\mathrm{~d} t}\left(W_{1}+W_{2}+W_{3}\right) & =\omega_{1} \dot{J}_{1}+\omega_{2} \dot{J}_{2}+\omega_{3} \dot{J}_{3}=\left(\omega_{1}-\omega_{2}-\omega_{3}\right) \dot{J}_{1}=0  \tag{6.151}\\
\frac{\mathrm{~d}}{\mathrm{~d} t}\left(\boldsymbol{K}_{1}+\boldsymbol{K}_{2}+\boldsymbol{K}_{3}\right) & =\boldsymbol{k}_{1} \dot{J}_{1}+\boldsymbol{k}_{2} \dot{J}_{2}+\boldsymbol{k}_{3} \dot{J}_{3}=\left(\boldsymbol{k}_{1}-\boldsymbol{k}_{2}-\boldsymbol{k}_{3}\right) \dot{J}_{1}=0
\end{array}\right\}
$$

DEFINITION. Introduce the slowly varying wave phase $\theta_{j}$ with definition $E_{j}=\left|E_{j}\right| \mathrm{e}^{\mathrm{i} \theta_{j}}$ and the interaction energy $H^{\prime}$, and use the definitions in (6.149),

$$
\begin{align*}
H^{\prime} & \equiv \frac{2 g}{\left(\bar{\varepsilon}_{1} \bar{\varepsilon}_{2} \bar{\varepsilon}_{3}\right)^{1 / 2}} \sqrt{J_{1} J_{2} J_{3}} \sin \left(\theta_{1}-\theta_{2}-\theta_{3}\right) \\
& =2 g\left|E_{1} E_{2} E_{3}\right| \sin \left(\theta_{1}-\theta_{2}-\theta_{3}\right)=2 g \operatorname{Im}\left(E_{1} E_{2}^{*} E_{3}^{*}\right) \tag{6.152}
\end{align*}
$$

THEOREM. Using (6.148) and (6.152) the interaction energy is a constant in time

$$
\begin{align*}
\dot{H}^{\prime} & =2 g \operatorname{Im}\left(\dot{E}_{1} E_{2}^{*} E_{3}^{*}+E_{1} \dot{E}_{2}^{*} E_{3}^{*}+E_{1} E_{2}^{*} \dot{E}_{3}^{*}\right) \\
& =2 g \operatorname{Im}\left(-\frac{g}{\bar{\varepsilon}_{1}}\left|E_{2}\right|^{2}\left|E_{3}\right|^{2}+\frac{g}{\bar{\varepsilon}_{2}}\left|E_{1}\right|^{2}\left|E_{3}\right|^{2}+\frac{g}{\bar{\varepsilon}_{3}}\left|E_{1}\right|^{2}\left|E_{2}\right|^{2}\right) \equiv 0 \tag{6.153}
\end{align*}
$$

because $\operatorname{Im}($ Real $) \equiv 0$.


Figure 34. Schematic of action conservation in three-wave interactions. (a) Pseudopotential $\Phi\left(J_{1}\right)$ versus $J_{1}$. (b) Three-wave interaction actions versus time.

DEFInition. The total electric field is given as $E(x, t)=\sum_{j}\left|E_{j}\right| \cos \left(k_{j} x-\omega_{j} t+\theta_{j}(t)\right)$.
From this definition and (6.148) we calculate the following relations:

$$
\begin{align*}
\dot{J}_{1} & =\bar{\varepsilon}_{1} E_{1}^{*} \dot{E}_{1}+\text { c.c. }=-g E_{1}^{*} E_{2} E_{3}+\text { c.c. }=-g\left|E_{1} E_{2} E_{3}\right|\left(\mathrm{e}^{-\mathrm{i} \theta_{1}+\mathrm{i} \theta_{2}+\mathrm{i} \theta_{3}}+\mathrm{e}^{\mathrm{i} \theta_{1}-\mathrm{i} \theta_{2}-\mathrm{i} \theta_{3}}\right) \\
& =-g \sqrt{\frac{J_{1} J_{2} J_{3}}{\bar{\varepsilon}_{1} \bar{\varepsilon}_{2} \bar{\varepsilon}_{3}}} 2 \cos \left(\theta_{1}-\theta_{2}-\theta_{3}\right) \equiv-\bar{g} \sqrt{J_{1} J_{2} J_{3}} \cos \left(\theta_{1}-\theta_{2}-\theta_{3}\right) \tag{6.154}
\end{align*}
$$

and we have introduced the definition of $\bar{g}=2 g / \sqrt{\bar{\epsilon}_{1} \bar{\epsilon}_{2} \bar{\epsilon}_{3}}$. We note that the action $J_{j}$ is defined so that it always has the same sign as $\bar{\varepsilon}_{j}$, and the square roots in (6.154) can be considered to have strictly positive arguments. Given (6.152) and (6.154) we can construct the square of the time derivative of $J_{1}$ and identify a pseudo-potential,

$$
\begin{equation*}
\frac{1}{2} \dot{J}_{1}^{2}=\frac{1}{2} \bar{g}^{2}\left|J_{1} J_{2} J_{3}\right|\left[1-\frac{H^{\prime 2}}{\bar{g}^{2}\left|J_{1} J_{2} J_{3}\right|}\right]=\frac{1}{2} \bar{g}^{2}\left|J_{1} J_{2} J_{3}\right|-\frac{1}{2} H^{\prime 2} \tag{6.155}
\end{equation*}
$$

DEfinition. Define a pseudo-potential $\Phi$,

$$
\begin{equation*}
\Phi\left(J_{1}\right)=-\frac{1}{2} \bar{g}^{2} J_{1} J_{2} J_{3}=-\frac{1}{2} \bar{g}^{2} J_{1}\left(I_{2}-J_{1}\right)\left(I_{3}-J_{1}\right) \tag{6.156}
\end{equation*}
$$

THEOREM. Given that $H^{\prime}$ is a constant in time, equation (6.155) leads directly to an equation of motion for the pseudo-particle action $J_{1}$, subject to an action conservation law,

$$
\begin{equation*}
\frac{1}{2} \dot{J}_{1}^{2}+\Phi\left(J_{1}\right)=-\frac{1}{2} H^{\prime 2} \tag{6.157}
\end{equation*}
$$

Figure 34 illustrates (6.157). Initial conditions determine $I_{2}, I_{3}$ and $H^{\prime}$. The solution of $J_{1}$ as a function of time can be expressed in terms of Jacobi elliptic functions. $J_{1}$ is a periodic function of time. The larger the value of $g$, the faster is the oscillation. The exchange of action among the three waves continues unabated in the absence of damping.

### 6.8.3. Parametric and explosive instabilities

In this section we discuss two special three-wave interaction cases of interest. In both examples the initial conditions are comprised of a finite-amplitude high-frequency wave and two lower-frequency waves with infinitesimal initial amplitudes.

EXAMPLE (Parametric instability). Assume that wave no. 1 is a transverse wave with frequency very close to the plasma frequency, but somewhat larger. Wave no. 1 (the pump wave) can decay into a Langmuir wave (wave no. 2) and an ion-acoustic wave (wave no. 3): $\omega_{1}^{t} \approx \omega_{\mathrm{pe}}+\omega_{\text {ion acoustic. }}$. This is called parametric decay and provides a mechanism for anomalous absorption of the transverse wave in a plasma. Given the initial conditions that the decay product waves have infinitesimal initial amplitudes compared to the pump wave, we can use the coupled-mode equations (6.148) with $E_{1}$ approximately constant early in time to derive the exponential growth of the decay product waves,

$$
\begin{equation*}
\frac{\partial}{\partial t} E_{2}=\frac{g}{\bar{\varepsilon}_{2}} E_{1} E_{3}^{*} \quad \frac{\partial}{\partial t} E_{3}=\frac{g}{\bar{\varepsilon}_{3}} E_{1} E_{2}^{*} . \tag{6.158}
\end{equation*}
$$

If we assume exponentially growing solutions $E_{2,3}=E_{2,3}(0) \mathrm{e}^{\gamma t}$ then (6.158) admits the solution for the growth rate of the parametric instability,

$$
\begin{equation*}
\gamma=\frac{g\left|E_{1}\right|}{\sqrt{\bar{\varepsilon}_{2} \bar{\varepsilon}_{3}}} \tag{6.159}
\end{equation*}
$$

Of course this derivation is only formal and schematic as we have not given explicit expressions for $g$ and $\bar{\varepsilon}_{j} \equiv \partial \varepsilon /\left.\partial \omega\right|_{\omega_{j}}$.
[Editor's note: in a plasma with no applied magnetic field, three of the classic references on parametric instabilities are (Drake, et al. 1974), (Liu \& Kaw 1976) and (Kruer 1988). In the presence of an applied magnetic field, some representative references on parametric instability theory are (Porkolab 1974), (Kaw 1976), (Cohen 1987) and (Stefan, Krall \& McBride 1987).]

Example (Explosive instability). Here we consider the decay of wave no. 1 into waves no. 2 and no. 3 where wave no. 1 is a negative energy wave and all three waves have infinitesimal initial amplitude. In this case all three waves can grow in amplitude while the total energy remains infinitesimal. The frequency and wavenumber relations (6.145) and action conservation (6.150) are unchanged, but $\bar{\varepsilon}_{1}<0$ and $J_{1}<0$. Thus, as all three waves grow in amplitude, $\Delta J_{1}=-\left|\Delta J_{1}\right|=-\Delta J_{2}=-\Delta J_{3}$ and $\Delta W_{1}+\Delta W_{2}+\Delta W_{3}=-\left|\Delta W_{1}\right|+\Delta W_{2}+\Delta W_{3} \approx 0$. We return to the relation for the pseudo-potential for the three-wave interaction in (6.156),

$$
\begin{equation*}
\Phi\left(J_{1}\right)=-\frac{1}{2} \bar{g}^{2}\left|J_{1} J_{2} J_{3}\right|=-\frac{1}{2} \bar{g}^{2}\left|J_{1}\right|\left(I_{2}+\left|J_{1}\right|\right)\left(I_{3}+\left|J_{1}\right|\right) \approx-\frac{1}{2} \bar{g}^{2}\left|J_{1}\right|^{3} \tag{6.160}
\end{equation*}
$$

for $I_{2}, I_{3} \ll\left|J_{1}\right|$ and the conserved total pseudo-energy on the right-hand side of (6.157) is likewise small as the instability develops. In this limit (6.157) simplifies to

$$
\begin{align*}
\left|\dot{J}_{1}\right|^{2} & =\bar{g}^{2}\left|J_{1}\right|^{3} \Rightarrow \frac{\mathrm{~d}\left|J_{1}\right|}{\left|J_{1}\right|^{3 / 2}}=\bar{g} \mathrm{~d} t \Rightarrow\left|J_{1}\right|^{-1 / 2}=-\frac{1}{2} \bar{g}(t+\text { const. }) \\
& \Rightarrow\left|J_{1}\right|(t)=\frac{1}{\left(\frac{1}{2} \bar{g}\right)^{2}} \frac{1}{\left(t-t_{0}\right)^{2}} \quad t_{0}^{2}=\frac{1}{\left|J_{1}(0)\right|^{2}\left(\frac{1}{2} \bar{g}\right)^{2}} . \tag{6.161}
\end{align*}
$$

The solution for the growth of the action amplitude in (6.161) approaches infinity at a finite time $t_{0}$, i.e. the amplitude 'explodes'. This is a mathematical singularity and not physically realizable: other physics will come into play at large amplitudes to saturate the instability at finite amplitude.
6.8.4. Including damping and frequency mismatch

The inclusion of damping in the three-wave interactions can significantly change the dynamics from that in the undamped limit. Equations (6.148) acquire additional terms to model dissipation,

$$
\begin{equation*}
\frac{\partial}{\partial t} E_{1}=-\frac{g}{\bar{\varepsilon}_{1}} E_{2} E_{3}-\gamma_{1} E_{1} \quad \frac{\partial}{\partial t} E_{2}=\frac{g}{\bar{\varepsilon}_{2}} E_{1} E_{3}^{*}-\gamma_{2} E_{2} \quad \frac{\partial}{\partial t} E_{3}=\frac{g}{\bar{\varepsilon}_{3}} E_{1} E_{2}^{*}-\gamma_{3} E_{3} \tag{6.162}
\end{equation*}
$$

The inclusion of damping can break most or all of the conservation laws in (6.150) and (6.151).

Consider the simple example in which $\gamma_{3}$ is large and $\gamma_{1}, \gamma_{2} \rightarrow 0$. Such a circumstance can apply to the stimulated scattering of a transverse wave by a longitudinal plasma wave into another transverse wave, $t \rightarrow t+l$, where the longitudinal wave is heavily damped. In this limit (6.162) become

$$
\begin{equation*}
E_{3}=\frac{g}{\gamma_{3} \bar{\varepsilon}_{3}} E_{1} E_{2}^{*} \quad \frac{\partial}{\partial t} E_{1}=-\frac{g}{\bar{\varepsilon}_{1}} E_{2} E_{3}=-\frac{g^{2}}{\gamma_{3} \bar{\varepsilon}_{3} \bar{\varepsilon}_{1}}\left|E_{2}\right|^{2} E_{1} \quad \frac{\partial}{\partial t} E_{2}=\frac{g}{\bar{\varepsilon}_{2}} E_{1} E_{3}^{*}=\frac{g^{2}}{\gamma_{3} \bar{\varepsilon}_{3} \bar{\varepsilon}_{2}}\left|E_{1}\right|^{2} E_{2} \tag{6.163}
\end{equation*}
$$

From (6.163) one concludes that

$$
\begin{gather*}
\dot{J}_{1}=-\dot{J}_{2} \quad J_{1}+J_{2}=I_{2}=\text { const. }  \tag{6.164a}\\
\dot{J}_{1}=-G J_{1} J_{2}=-G J_{1}\left(I_{2}-J_{1}\right) \quad G=\frac{2 g^{2}}{\gamma_{3} \bar{\varepsilon}_{1} \bar{\varepsilon}_{2} \bar{\varepsilon}_{3}},  \tag{6.164b}\\
J_{1}=\frac{I_{2}}{1+\exp \left(I_{2} G t^{\prime}\right)} \quad J_{2}=I_{2} \frac{\exp \left(I_{2} G t^{\prime}\right)}{1+\exp \left(I_{2} G t^{\prime}\right)} \quad t^{\prime}=t-t_{0}, \tag{6.164c}
\end{gather*}
$$

where at $t=t_{0} J_{1}=J_{2}=\frac{1}{2} I_{2}$. Wave action and energy feed steadily from the high-frequency pump wave with action $J_{1}$ to the lower-frequency wave with action $J_{2}$, conserving $I_{2}$. One can displace the time axis to allow for any desired ratio of $J_{2} / J_{1}$ at a given 'initial' time. Thus, beat-wave heating, stimulated Raman scattering or parametric instability can be modelled.

Consider a second example in which $E_{1}$ is large and $E_{2}, E_{3}$ are initially small and have finite damping rates $\gamma_{2}, \gamma_{3}$. We assume that $E_{2}, E_{3} \sim \mathrm{e}^{\Gamma t}$ and $E_{1} \sim$ const. in (6.162) to obtain

$$
\begin{equation*}
\Gamma=\frac{1}{2}\left[-\left(\gamma_{1}+\gamma_{2}\right)+\sqrt{\left(\gamma_{1}-\gamma_{2}\right)^{2}+4 G\left|E_{1}\right|^{2}}\right] \quad G \equiv \frac{g^{2}}{\bar{\varepsilon}_{2} \bar{\varepsilon}_{3}} . \tag{6.165}
\end{equation*}
$$

From the expression for $\Gamma$ we determine that the amplitude $E_{1}$ must exceed a threshold value to overcome the damping in the decay product waves in order that $\Gamma>0$, i.e.

$$
\begin{equation*}
\Gamma>0 \rightarrow\left|E_{1}\right|^{2}>\left|E_{1}\right|_{c}^{2}=\frac{\gamma_{2} \gamma_{3}}{G}=\frac{\bar{\varepsilon}_{2} \bar{\varepsilon}_{2} \gamma_{2} \gamma_{3}}{g^{2}} \tag{6.166}
\end{equation*}
$$

We next consider an example in which there is negligible damping but the threewave resonance condition is subject to a finite-frequency mismatch. Action remains conserved, i.e. $J_{1}+J_{2}=I_{2}=$ const. $J_{1}+J_{3}=I_{3}=$ const.. The total Hamiltonian is

$$
\begin{equation*}
H=\sum_{j=1}^{3} \omega_{j} J_{j}+\bar{g} \sqrt{\left|J_{1} J_{2} J_{3}\right|} \sin \left(\theta_{1}-\theta_{2}-\theta_{3}\right) \tag{6.167}
\end{equation*}
$$

From $H$ in (6.167) and Hamilton's equations we deduce

$$
\left.\begin{array}{c}
\dot{H}=\frac{\partial}{\partial t} H=0, \\
\dot{J}_{1}=-\frac{\partial H}{\partial \theta_{1}}=-\bar{g} \sqrt{\left|J_{1} J_{2} J_{3}\right|} \cos \left(\theta_{1}-\theta_{2}-\theta_{3}\right), \\
\dot{J}_{2}=-\frac{\partial H}{\partial \theta_{2}}=-\dot{J}_{1}, \quad \dot{J}_{3}=-\frac{\partial H}{\partial \theta_{3}}=-\dot{J}_{1},  \tag{6.168}\\
\dot{\theta}_{1}=\frac{\partial H}{\partial J_{1}}=\omega_{1}+\frac{1}{2} \bar{g} \sqrt{\left|\frac{J_{2} J_{3}}{J_{1}}\right|} \sin \left(\theta_{1}-\theta_{2}-\theta_{3}\right), \\
\dot{\theta}_{2}=\frac{\partial H}{\partial J_{2}}=\omega_{2}+\frac{1}{2} \bar{g} \sqrt{\left|\frac{J_{1} J_{3}}{J_{2}}\right|} \sin \left(\theta_{1}-\theta_{2}-\theta_{3}\right), \\
\dot{\theta}_{3}=\frac{\partial H}{\partial J_{3}}=\omega_{3}+\frac{1}{2} \bar{g} \sqrt{\left|\frac{J_{1} J_{2}}{J_{3}}\right|} \sin \left(\theta_{1}-\theta_{2}-\theta_{3}\right) .
\end{array}\right\}
$$

The equations of motion in (6.168) admit oscillatory solutions in terms of Jacobi elliptic functions, and we can derive the following equation for a pseudo-particle:

$$
\left.\begin{array}{c}
\frac{1}{2} \dot{J}_{1}^{2}+\Phi\left(J_{1}\right)=-\frac{1}{2}\left(H-I_{2} \omega_{2}-I_{3} \omega_{3}\right)^{2}  \tag{6.169}\\
\Phi=-\frac{1}{2}\left[\bar{g}^{2}\left|J_{1} J_{2} J_{3}\right|-J_{1}^{2}(\Delta \omega)^{2}+2 J_{1} \Delta \omega\left(H-I_{2} \omega_{2}-I_{3} \omega_{3}\right)\right], \\
\Delta \omega=\omega_{1}-\omega_{2}-\omega_{3} .
\end{array}\right\}
$$

EXERCISE. Compare the structure of (6.167)-(6.169) to (6.155)-(6.157).

Example. Explosive instability with finite mismatch can be deduced from (6.169). Consider $J_{1}<0$ and $J_{2}, J_{3}>0$ all with infinitesimal amplitudes at $t=0$. In this case $I_{2} \omega_{2}+I_{3} \omega_{3}$ and $H$ are negligible in (6.169). For no frequency mismatch $\Delta \omega=0$, $\Phi=-\frac{1}{2} \bar{g}^{2}\left|J_{1} J_{2} J_{3}\right| \approx-\frac{1}{2} \bar{g}^{2}\left|J_{1}\right|^{3}$, i.e. $\Phi$ is negative and can monotonically increase in magnitude while the magnitudes of all three actions and their time derivatives increase: $\frac{1}{2} \dot{J}_{1}^{2}=-\Phi \approx \frac{1}{2} \bar{g}^{2}\left|J_{1}\right|^{3}$. With a finite-frequency mismatch, $\Phi=-\frac{1}{2} \bar{g}^{2}\left|J_{1} J_{2} J_{3}\right|+\Delta \omega^{2} J_{1}^{2} \approx$ $-\frac{1}{2} \bar{g}^{2}\left|J_{1}\right|^{3}+\Delta \omega^{2} J_{1}^{2}$, and $\Phi$ is positive for small values of $\left|J_{1}\right|$ before turning negative at large values of $\left|J_{1}\right|$. Thus, the value of the action $\left|J_{1}\right|$ can remain trapped for values of $\left|J_{1}\right|$ less than some critical value, i.e. a threshold value $\left|J_{1}\right|_{c}$, above which $\Phi$ is monotonically decreasing and the quasi-particle can accelerate downhill in $\Phi$ and grow explosively. The threshold value for explosive instability corresponds to the value of $\left|J_{1}\right|$ at the peak of $\Phi$, which is given by $\left|J_{1}\right|_{c}=\frac{2}{3}\left(\Delta \omega^{2} / \bar{g}^{2}\right)$. The difference between the two cases, with and without the frequency mismatch, is that the frequency mismatch degrades the strength of the coupling leading to a threshold condition.

EXAMPLE. Here we consider parametric instability including a finite-frequency mismatch by analysing (6.162) for infinitesimal $E_{2}, E_{3}$ and $E_{1}$ approximately constant,

$$
\begin{equation*}
\frac{\partial}{\partial t} E_{2}=\frac{g}{\bar{\varepsilon}_{2}} E_{1} E_{3}^{*} \mathrm{e}^{-\mathrm{i} \Delta \omega t} \quad \frac{\partial}{\partial t} E_{3}=\frac{g}{\bar{\varepsilon}_{3}} E_{1} E_{2}^{*} \mathrm{e}^{-\mathrm{i} \Delta \omega t} . \tag{6.170}
\end{equation*}
$$

We assume a time dependence $E_{2}, E_{3} \sim \mathrm{e}^{-\mathrm{i} \Omega t}$ where $\Omega$ is complex. With this ansatz (6.170) yields a quadratic dispersion relation for $\Omega$ with solution,

$$
\begin{equation*}
\Omega=\frac{1}{2} \Delta \omega \pm \mathrm{i} \sqrt{\frac{g^{2}\left|E_{1}\right|^{2}}{\bar{\varepsilon}_{2} \bar{\varepsilon}_{3}}-\left(\frac{1}{2} \Delta \omega\right)^{2}} \tag{6.171}
\end{equation*}
$$

The frequency mismatch reduces the growth rate by reducing the effective strength of the coupling and leads to an amplitude threshold for instability $\left|E_{1}\right|>E_{1 c}=$ $|\Delta \omega / 2 g| \sqrt{\bar{\varepsilon}_{2} \bar{\varepsilon}_{3}}$.

If there is damping in the parametric decay product waves and a frequency mismatch, the solution procedure for solving (6.162) is not so simple as that used in obtaining (6.171). The coupled nonlinear differential equations have time-dependent coefficients, and Mathieu equations result. Nishikawa addressed such a case (Nishikawa 1968). Both damping and frequency mismatch conspire to reduce instability growth rates and introduce a threshold.

### 6.8.5. Extension to many-wave system with three-wave interactions - wave kinetic equation

Here we extend the analysis of nonlinear wave-wave interactions to a sum over many waves supporting three-wave and four-wave interactions (at least formally). We postulate random phases and employ a statistical approach and an action-angle representation. We specify initial conditions with $\left\{J_{i}\right\}$ given and $\left\{\theta_{i}\right\}$ unknown. We extend the Hamiltonian in (6.167) to

$$
\begin{align*}
H= & \sum_{j} \omega_{j} J_{j}+H^{\prime}(\boldsymbol{J}, \boldsymbol{\theta})=\sum_{j} \omega_{j} J_{j}+\sum_{ \pm} \sum_{i j k} \bar{g}_{i j k} \sqrt{\left|J_{i} J_{j} J_{k}\right|} \cos \left( \pm \theta_{i} \pm \theta_{j} \pm \theta_{k}\right) \\
& +\sum_{ \pm} \sum_{i j k l} \bar{g}_{i j k l} \sqrt{\left|J_{i} J_{j} J_{k} J_{l}\right|} \cos \left( \pm \theta_{i} \pm \theta_{j} \pm \theta_{k} \pm \theta_{l}\right) \tag{6.172}
\end{align*}
$$

which includes resonant and off-resonant three-wave and four-wave interactions. Fourwave interactions can satisfy the frequency matching condition $\omega_{1}+\omega_{2}=\omega_{3}+\omega_{4}$. The equations of motion for the action-angle pairs are

$$
\begin{equation*}
\dot{J}_{i}=-\frac{\partial H}{\partial \theta_{i}}=O(g) \quad \dot{\theta}_{i}=\frac{\partial H}{\partial J_{i}}=\omega_{i}+\frac{\partial H^{\prime}}{\partial J_{i}}=\omega_{i}+O(g) \tag{6.173}
\end{equation*}
$$

DEFINITION. In keeping with taking a statistical approach, we introduce a Liouville probability distribution in $\{\boldsymbol{J}, \boldsymbol{\theta}\}$ space,

$$
\begin{equation*}
\rho(\boldsymbol{J}, \boldsymbol{\theta})=\rho_{0}(\boldsymbol{J} ; t)+\delta \rho(\boldsymbol{J}, \boldsymbol{\theta} ; t), \quad \delta \rho \ll \rho_{0} . \tag{6.174}
\end{equation*}
$$

We recall the derivation of the theory of quasilinear diffusion in canonical variables in $\S 6.5 .4$, equations (6.103)-(6.105). In the weak turbulence limit the probability distribution satisfies the equations,

$$
\begin{equation*}
\frac{\partial}{\partial t} \rho_{0}(\boldsymbol{J} ; t)=\frac{\partial}{\partial \boldsymbol{J}} \cdot\left(\boldsymbol{D} \cdot \frac{\partial \rho_{0}}{\partial \boldsymbol{J}}\right) \quad \boldsymbol{D}(\boldsymbol{J})=\int_{0}^{\infty} \mathrm{d} \tau\langle\dot{\boldsymbol{J}}(t) \cdot \dot{\boldsymbol{J}}(t-\tau)\rangle_{\boldsymbol{\theta}} . \tag{6.175}
\end{equation*}
$$

This equation describes the diffusion of the probability distribution function in action space. The averaging bracket $\left\rangle_{\theta}\right.$ denotes averaging with respect to the phase angles at the specified time $t$. Double bracket averaging 《》 denotes averaging with respect to ensembles of all possible initial phases. Hence,

$$
\begin{equation*}
\langle\boldsymbol{J}\rangle(t) \equiv \int \mathrm{d}^{N} J \rho_{0}(J ; t) \boldsymbol{J} . \tag{6.176}
\end{equation*}
$$

We can calculate the $(\partial / \partial t)\langle\boldsymbol{J}\rangle\rangle(t)$ using (6.175) and (6.176),

$$
\begin{align*}
\left.\frac{\partial}{\partial t}\langle\boldsymbol{J}\rangle\right\rangle(t) & =\int \mathrm{d}^{N} J \boldsymbol{J} \frac{\partial}{\partial \boldsymbol{J}} \cdot\left(\boldsymbol{D} \cdot \frac{\partial \rho_{0}}{\partial \boldsymbol{J}}\right)=-\int \mathrm{d}^{N} J \boldsymbol{I} \cdot \boldsymbol{D} \cdot \frac{\partial \rho_{0}}{\partial \boldsymbol{J}} \\
& =-\int \mathrm{d}^{N} J \frac{\partial \rho_{0}}{\partial \boldsymbol{J}} \cdot \boldsymbol{D} \\
& =\int \mathrm{d}^{N} J \rho_{0} \frac{\partial}{\partial \boldsymbol{J}} \cdot \boldsymbol{D}(\boldsymbol{J})=\left\langle\left\langle\frac{\partial}{\partial \boldsymbol{J}} \cdot \boldsymbol{D}(\boldsymbol{J})\right\rangle\right\rangle . \tag{6.177}
\end{align*}
$$

Note that $\boldsymbol{D}$ is symmetric.
Because the $\theta_{i}$ are each cyclic, we can expand $H^{\prime}(\boldsymbol{J}, \boldsymbol{\theta})$ in a Fourier series in $\theta_{i}$,

$$
\begin{equation*}
H^{\prime}(\boldsymbol{J}, \boldsymbol{\theta})=\sum_{l=-\infty}^{\infty} H_{l}(\boldsymbol{J}) \exp (\mathrm{i} \boldsymbol{l} \cdot \boldsymbol{\theta}), \quad \boldsymbol{l}=\left\{l_{i}\right\}, \quad H_{l}(\boldsymbol{J}) \equiv \int \frac{\mathrm{d}^{N} \theta}{(2 \pi)^{N}} H^{\prime}(\boldsymbol{J}, \boldsymbol{\theta}) \exp (-\mathrm{i} \boldsymbol{l} \cdot \boldsymbol{\theta}) \tag{6.178}
\end{equation*}
$$

We note that for $\cos \left(\theta_{1}-\theta_{2}-\theta_{3}\right)$ one has $l_{1}=1, l_{2}=-1, l_{3}=-1, l_{4}=0$. The values of $\left\{l_{i}\right\}$ control the couplings that are included. We use (6.173) and (6.175) and the Fourier series representation to evaluate $\boldsymbol{D}$,

$$
\begin{equation*}
\boldsymbol{D}(\boldsymbol{J})=\int_{0}^{\infty} \mathrm{d} \tau \sum_{l^{\prime}}(-\mathrm{i} \boldsymbol{l})\left(\mathrm{i} \boldsymbol{l}^{\prime}\right)\left\langle H_{l}\left(\boldsymbol{J}^{t}\right) H_{l^{\prime}}^{*}\left(\boldsymbol{J}^{t-\tau}\right) \exp \left(\mathrm{i} \boldsymbol{l} \cdot \boldsymbol{\theta}^{t}-\mathrm{i} \boldsymbol{l}^{\prime} \cdot \boldsymbol{\theta}^{t-\tau}\right)\right\rangle_{\boldsymbol{\theta}} \tag{6.179}
\end{equation*}
$$

The time dependences of $\boldsymbol{\theta}$ and $\boldsymbol{J}$ are determined by Hamilton's equations (6.173). To the lowest order needed in (6.179), $\overline{\boldsymbol{J}}^{t-\tau} \approx \overline{\boldsymbol{J}}^{t}, \boldsymbol{\theta}^{t-\tau}=\boldsymbol{\theta}^{t}-\tau \dot{\boldsymbol{\theta}} \approx \boldsymbol{\theta}^{t}-\tau \boldsymbol{\omega}$, and $\exp (\mathrm{i} \boldsymbol{l}$. $\left.\boldsymbol{\theta}^{t}-\mathrm{i} \boldsymbol{l}^{\prime} \boldsymbol{\theta}^{t-\tau}\right) \approx \exp \left(\mathrm{il} \cdot \boldsymbol{\theta}^{t}-\mathrm{i} \boldsymbol{l}^{\prime} \cdot \boldsymbol{\theta}^{t}+\mathrm{i} \boldsymbol{l}^{\prime} \cdot \boldsymbol{\omega} \tau\right)$. Hence, the following results are obtained.

THEOREM.

$$
\begin{align*}
& \frac{\partial}{\partial t} \rho_{0}(\boldsymbol{J} ; t)=\frac{\partial}{\partial \boldsymbol{J}} \cdot\left(\boldsymbol{D} \cdot \frac{\partial \rho_{0}}{\partial \boldsymbol{J}}\right), \\
& \boldsymbol{D}(\boldsymbol{J})=\int_{0}^{\infty} \mathrm{d} \tau\langle\dot{J}(t) \dot{J}(t-\tau)\rangle_{\theta}=\int_{0}^{\infty} \mathrm{d} \tau \sum_{\boldsymbol{l}} \boldsymbol{l l}\left|H_{l}(\boldsymbol{J})\right|^{2} \mathrm{e}^{\mathrm{i} \cdot \boldsymbol{\omega} \tau} \\
& \quad=\sum_{l} \boldsymbol{l}\left|H_{l}(\boldsymbol{J})\right|^{2}\left[\pi \delta(\boldsymbol{l} \cdot \boldsymbol{\omega})-\frac{1}{\mathrm{i} l}\right]=\sum_{l} \boldsymbol{l}\left|H_{l}(\boldsymbol{J})\right|^{2} \pi \delta(\boldsymbol{l} \cdot \boldsymbol{\omega})  \tag{6.180}\\
& \quad\left[\uparrow \text { even in } l \quad \text { odd in } l \uparrow \quad\left|H_{l}(\boldsymbol{J})\right|^{2} \text { is Hermitian }\right]
\end{aligned}, \begin{aligned}
& \left.\left.\frac{\partial}{\partial t}\langle\boldsymbol{J}\rangle\right\rangle(t)=\sum_{l}\left\langle\left.\left\langle\boldsymbol{l} \cdot \frac{\partial}{\partial \boldsymbol{J}} \cdot\right| H_{l}(\boldsymbol{J})\right|^{2}\right\rangle\right\rangle \boldsymbol{l} \pi \delta(\boldsymbol{l} \cdot \boldsymbol{\omega}) .
\end{align*}
$$

Example. For $\boldsymbol{l}=[1,-1,-1,0, \ldots]$ then $\boldsymbol{l} \cdot \boldsymbol{\omega}=\omega_{1}-\omega_{2}-\omega_{3}=0$ is the resonance condition.

We note that $\left|H_{l}(J)\right|^{2} \propto g^{2}$ is the coupling term representing the strength of the interaction. Consider the case in which there are resonant three-wave interactions. From (6.180) one obtains

$$
\begin{align*}
\left.\frac{\partial}{\partial t}\langle\boldsymbol{J}\rangle\right\rangle(t) & \left.=\sum_{l}\left\langle\left.\left\langle\boldsymbol{l} \cdot \frac{\partial}{\partial \boldsymbol{J}} \cdot\right| H_{l}(\boldsymbol{J})\right|^{2}\right\rangle\right\rangle \boldsymbol{l} \boldsymbol{\pi} \delta(\boldsymbol{l} \cdot \boldsymbol{\omega}) \\
& \rightarrow \frac{\partial}{\partial t}\left\langle J_{1}\right\rangle=-\frac{\partial}{\partial t}\left\langle J_{2}\right\rangle=-\frac{\partial}{\partial t}\left\langle J_{3}\right\rangle \\
& =\pi \delta\left(\omega_{1}-\omega_{2}-\omega_{3}\right)\left\langle\left(\frac{\partial}{\partial J_{1}}-\frac{\partial}{\partial J_{2}}-\frac{\partial}{\partial J_{3}}\right) g_{123}^{2} J_{1} J_{2} J_{3}\right\rangle \\
& =\pi \delta\left(\omega_{1}-\omega_{2}-\omega_{3}\right) g_{123}^{2}\left(\left\langle J_{2} J_{3}\right\rangle-\left\langle J_{1} J_{3}\right\rangle-\left\langle J_{1} J_{2}\right\rangle\right) \tag{6.181}
\end{align*}
$$

We next introduce a decomposition of each of the wave actions in terms of an integral over wavenumber space. We assign $\boldsymbol{k}$ to $\left\langle J_{1}\right\rangle(\boldsymbol{k}), \boldsymbol{k}^{\prime}$ to $\left\langle J_{2}\right\rangle\left(\boldsymbol{k}^{\prime}\right)$ and $\boldsymbol{k}^{\prime \prime}$ to $\left\langle J_{3}\right\rangle\left(\boldsymbol{k}^{\prime \prime}\right)$. Then (6.181) becomes a wave kinetic equation,

$$
\begin{align*}
\frac{\partial}{\partial t}\left\langle J_{1}\right\rangle= & \int \frac{\mathrm{d}^{3} k^{\prime}}{(2 \pi)^{3}} \int \frac{\mathrm{~d}^{3} k^{\prime \prime}}{(2 \pi)^{3}} \pi \delta\left(\omega_{1}^{\boldsymbol{k}}-\omega_{2}^{k^{\prime}}-\omega_{3}^{\boldsymbol{k}^{\prime \prime}}\right) \\
& \times g_{123}^{2}\left(\boldsymbol{k}, \boldsymbol{k}^{\prime}, \boldsymbol{k}^{\prime \prime}\right) \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}-\boldsymbol{k}^{\prime \prime}\right)\left(\left\langle J_{2}\left(\boldsymbol{k}^{\prime}\right) J_{3}\left(\boldsymbol{k}^{\prime \prime}\right)\right\rangle-\left\langle J_{1}(\boldsymbol{k}) J_{3}\left(\boldsymbol{k}^{\prime \prime}\right)\right\rangle-\left\langle J_{1}(\boldsymbol{k}) J_{2}\left(\boldsymbol{k}^{\prime}\right)\right\rangle\right) \\
\Rightarrow & \int \frac{\mathrm{d}^{3} k^{\prime}}{(2 \pi)^{3}} \int \frac{\mathrm{~d}^{3} k^{\prime \prime}}{(2 \pi)^{3}} \pi \delta\left(\omega_{1}^{\boldsymbol{k}}-\omega_{2}^{k^{\prime}}-\omega_{3}^{\boldsymbol{k}^{\prime \prime}}\right) \\
& \times g_{123}^{2}\left(\boldsymbol{k}, \boldsymbol{k}^{\prime}, \boldsymbol{k}^{\prime \prime}\right) \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}-\boldsymbol{k}^{\prime \prime}\right)\left(\left\langle J_{2}\left(\boldsymbol{k}^{\prime}\right)\right\rangle\left\langle J_{3}\left(\boldsymbol{k}^{\prime \prime}\right)\right\rangle\right. \\
& \left.-\left\langle J_{1}(\boldsymbol{k})\right\rangle\left\langle J_{3}\left(\boldsymbol{k}^{\prime \prime}\right)\right\rangle-\left\langle J_{1}(\boldsymbol{k})\right\rangle\left\langle J_{2}\left(\boldsymbol{k}^{\prime}\right)\right\rangle\right) . \tag{6.182}
\end{align*}
$$

In obtaining (6.182) we have made assumptions that many waves are present and statistical independence: $\left\langle J_{2}\left(\boldsymbol{k}^{\prime}\right) J_{3}\left(\boldsymbol{k}^{\prime \prime}\right)\right\rangle=\left\langle J_{2}\left(\boldsymbol{k}^{\prime}\right)\right\rangle\left\langle J_{3}\left(\boldsymbol{k}^{\prime \prime}\right)\right\rangle$.

Consider a quantum mechanics perspective on three-wave interactions. The equation for the time derivative of the number of quanta $N_{1}$ generated by stimulated scattering into $N_{1}$ from $N_{2}$ and $N_{3}$, and stimulated scattering into $N_{2}$ and $N_{3}$ from $N_{1}$ takes the form,

$$
\begin{equation*}
\dot{N}_{1}=g^{2}\left[N_{2} N_{3}\left(N_{1}+1\right)-N_{1}\left(N_{2}+1\right)\left(N_{3}+1\right)\right]=g^{2}\left[N_{2} N_{3}-N_{1} N_{3}-N_{1} N_{2}-N_{1}\right] \tag{6.183}
\end{equation*}
$$

after cancellations. The number of quanta is related to the wave action through the relation $N_{l}=J_{l} / \hbar$. Hence, the last term in (6.183), which is purely spontaneous, is $O(\hbar)$ smaller than the others and can be thrown away with result

$$
\begin{equation*}
\dot{J}_{1}=\frac{g^{2}}{\hbar} g^{2}\left[J_{2} J_{3}-J_{1} J_{3}-J_{1} J_{3}\right] \tag{6.184}
\end{equation*}
$$

We see that (6.184) has the same form as (6.182).
THEOREM. Equations (6.181)-(6.182) and the frequency and wavenumber resonance conditions give rise to the following conservation laws:
(i) Action conservation

$$
\begin{equation*}
\frac{\partial}{\partial t}\left(\left\langle J_{1}\right\rangle+\left\langle J_{2}\right\rangle\right)=\frac{\partial}{\partial t}\left(\left\langle J_{1}\right\rangle+\left\langle J_{3}\right\rangle\right)=0 . \tag{6.185a}
\end{equation*}
$$

(ii) Energy conservation

$$
\begin{equation*}
U \equiv \sum_{l} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} J_{l}(\boldsymbol{k}) \omega_{l}(\boldsymbol{k}), \quad \dot{U}=0 . \tag{6.185b}
\end{equation*}
$$

(iii) Momentum conservation

$$
\begin{equation*}
\boldsymbol{K} \equiv \sum_{l} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} J_{l}(\boldsymbol{k}) \boldsymbol{k}, \quad \dot{\boldsymbol{K}}=0 . \tag{6.185c}
\end{equation*}
$$

We next introduce a reasonable definition of the wave entropy and show that in the absence of phase correlations there is entropy production and irreversibility.

DEfinition. Wave entropy

$$
\begin{equation*}
S=\ln \left(\Pi_{l} J_{l}\right)=\sum_{l} \ln J_{l} . \tag{6.186}
\end{equation*}
$$

We then use the definition of the wave entropy (6.186) and (6.182), sum over the three modes, and integrate over $\boldsymbol{k}$-space to evaluate the time derivative of the entropy,

$$
\begin{align*}
\frac{\partial}{\partial t} S= & \sum_{l} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \frac{\dot{J}_{s}(\boldsymbol{k})}{J_{s}(\boldsymbol{k})}=\sum_{l} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}^{\prime}}{(2 \pi)^{3}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}^{\prime \prime}}{(2 \pi)^{3}} \pi \delta\left(\omega_{1}^{\boldsymbol{k}}-\omega_{2}^{k^{\prime}}-\omega_{3}^{k^{\prime \prime}}\right) \\
& \times g_{123}^{2}\left(\boldsymbol{k}, \boldsymbol{k}^{\prime}, \boldsymbol{k}^{\prime \prime}\right) \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}-\boldsymbol{k}^{\prime \prime}\right)\left[\left(J_{2} J_{3}-J_{1} J_{3}-J_{1} J_{2}\right)\left(\frac{1}{J_{1}}-\frac{1}{J_{2}}-\frac{1}{J_{3}}\right)\right. \\
= & \left.\left|J_{1} J_{2} J_{3}\right|\left(\frac{1}{J_{1}}-\frac{1}{J_{2}}-\frac{1}{J_{3}}\right)^{2}\right] . \tag{6.187}
\end{align*}
$$

The right-hand side of (6.187) is non-negative, $\partial S / \partial t \geqslant 0$, and tends to zero asymptotically in time with the asymptotic state satisfying $\partial S / \partial t=0$,

$$
\begin{equation*}
\frac{1}{J_{1}}=\frac{1}{J_{2}}+\frac{1}{J_{3}} \tag{6.188}
\end{equation*}
$$

We next introduce a quantity analogous to the Helmholtz free energy, i.e. $S-\beta U$. Consider the variation of this quantity about the asymptotic steady state determined in (6.188),

$$
\begin{equation*}
\sum_{l} \delta\left(\ln J_{l}-\beta \omega_{l} J_{l}\right)=\sum_{l} \delta J_{l}\left(\frac{1}{J_{l}}-\beta \omega_{l}\right)=0 \Rightarrow \frac{1}{J_{l}}=\beta \omega_{l} \tag{6.189}
\end{equation*}
$$

If we substitute the result in (6.189) into the asymptotic condition in (6.188), we recover the three-wave frequency resonance condition $\omega_{1}=\omega_{2}+\omega_{3}$. Furthermore, if we use the result in (6.189) in the wave energy, we deduce that the asymptotic wave energy satisfies a Rayleigh-Jeans law, i.e.

$$
\begin{equation*}
U_{j}=\omega_{j} J_{j}=\frac{1}{\beta} \equiv T_{\text {wave-kinetic }} \tag{6.190}
\end{equation*}
$$

Thus, all modes have the same asymptotic energy, which implies that this classical theory can lead to an ultra-violet catastrophe.

Example. Explosive instability - if the three-wave interaction involves $J_{1}<0$ and $J_{2}, J_{3}>0$ as in $\S 6.8 .3$, then (6.188) is never satisfied,

$$
\begin{equation*}
\frac{1}{J_{1}} \neq \frac{1}{J_{2}}+\frac{1}{J_{3}} \tag{6.191}
\end{equation*}
$$

and $\left|J_{1}\right|, J_{2}, J_{3}$ and $S$ can all continue to grow without bound.

## PART 3

## 7. Plasma collisional and discreteness phenomena

This section examines plasma collision processes and discreteness phenomena. This includes test-particle theory of single particles and many particles, radiation transport and Dupree's theory of phase-space granulation and clump formation.

### 7.1. Test-particle formulation in the electrostatic limit

We begin with a theoretical treatment based on a Coulomb model. In the Coulomb model we recall that

$$
\begin{equation*}
\phi(\boldsymbol{k}, \omega)=\frac{\phi_{0}(\boldsymbol{k}, \omega)}{\varepsilon(\boldsymbol{k}, \omega)} . \tag{7.1}
\end{equation*}
$$

To support self-consistent electromagnetic fields within the context of Maxwell's equations the longitudinal dielectric $\varepsilon \rightarrow \boldsymbol{K}$, the conductivity tensor. Consider Poisson's equation for a single charged particle,

$$
\left.\begin{array}{c}
\rho_{0}(\boldsymbol{r}, t)=e_{0} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{0}(t)\right)  \tag{7.2}\\
\rho_{0}(\boldsymbol{k}, \omega) \equiv \int \mathrm{d}^{3} \boldsymbol{r} \mathrm{e}^{-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}} \int \mathrm{~d} t \mathrm{e}^{\mathrm{i} \omega t} \rho_{0}(\boldsymbol{r}, t) \\
k^{2} \phi_{0}(\boldsymbol{k}, \omega)=4 \pi \rho_{0}(\boldsymbol{k}, \omega)
\end{array}\right\}
$$

Using the lowest-order particle trajectory $\boldsymbol{r}_{0}(t)=\boldsymbol{r}_{0}(0)+\boldsymbol{v}_{0} t+\cdots$ we can evaluate the Fourier-transformed charge density in (7.2)

$$
\begin{align*}
\rho_{0}(\boldsymbol{k}, \omega) & \equiv \int \mathrm{d}^{3} \boldsymbol{r} \mathrm{e}^{-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}} \int \mathrm{~d} t \mathrm{e}^{\mathrm{i} \omega t} \rho_{0}(\boldsymbol{r}, t)=e_{0} \int \mathrm{~d} t \mathrm{e}^{\mathrm{i} \omega t} \mathrm{e}^{-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{0}(t)} \\
& =e_{0} \mathrm{e}^{-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{0}(0)} \int_{-\infty}^{\infty} \mathrm{d} t \mathrm{e}^{\mathrm{i} \omega t-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{v}_{0}}=e_{0} \mathrm{e}^{-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{0}(0)} 2 \pi \delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{0}\right) \tag{7.3}
\end{align*}
$$

We substitute the expression in (7.3) into (7.1) and (7.2) to obtain

$$
\begin{equation*}
\phi(\boldsymbol{k}, \omega)=\frac{4 \pi}{k^{2}} \frac{1}{\varepsilon(\boldsymbol{k}, \omega)} 2 \pi e_{0} \delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{0}\right) \mathrm{e}^{-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{0}(0)} \tag{7.4}
\end{equation*}
$$

whose inverse Fourier transform is

$$
\begin{aligned}
\phi(\boldsymbol{r}, t) & =\int \frac{\mathrm{d} \omega}{2 \pi} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}-\mathrm{i} \omega t} \phi(\boldsymbol{k}, \omega) \\
& =\int \frac{\mathrm{d} \omega}{2 \pi} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}-\mathrm{i} \omega t} \frac{4 \pi}{k^{2}} \frac{1}{\varepsilon(\boldsymbol{k}, \omega)} 2 \pi e_{0} \delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{0}\right) \mathrm{e}^{-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{0}(0)}
\end{aligned}
$$

$$
\begin{equation*}
=\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot\left[\boldsymbol{r}-\left(\boldsymbol{r}_{0}(0)+\boldsymbol{v}_{0} t\right)\right]} \frac{1}{\varepsilon\left(\boldsymbol{k}, \boldsymbol{k} \cdot \boldsymbol{v}_{0}\right)} \frac{4 \pi e_{0}}{k^{2}} \equiv \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{s}} \frac{1}{\varepsilon\left(\boldsymbol{k}, \boldsymbol{k} \cdot \boldsymbol{v}_{0}\right)} \frac{4 \pi e_{0}}{k^{2}} \tag{7.5}
\end{equation*}
$$

where $\boldsymbol{s}=\boldsymbol{r}-\left(\boldsymbol{r}_{0}(0)+\boldsymbol{v}_{0} t\right)$, the spatial coordinate in the particle frame to lowest order. To proceed further, one chooses a form for the velocity distribution function $g(\boldsymbol{u})$ as in $\S 2.5 .4$ with which to calculate the dielectric response $\varepsilon$. One can obtain analytic results for square distributions and Cauchy distributions, but not for a Maxwellian. We note that $\operatorname{Re} \varepsilon(-\boldsymbol{k})=\operatorname{Re} \varepsilon(\boldsymbol{k})$ and $\operatorname{Im} \varepsilon(-\boldsymbol{k})=-\operatorname{Im} \varepsilon(\boldsymbol{k})$.

EXERCISE. From (7.3) and the machinery in (7.5) calculate $\rho(\boldsymbol{s})$ and show that the total plasma charge (excludes the charge associated with $\rho_{0}$ ) and the corresponding dipole moment of the plasma are both zero, i.e.

$$
\begin{equation*}
e_{\text {total }}=\int \mathrm{d}^{3} \boldsymbol{s} \rho(\boldsymbol{s})=0 \quad \boldsymbol{p}=\int \mathrm{d}^{3} \boldsymbol{s} \boldsymbol{s} \rho(\boldsymbol{s})=0 \tag{7.6}
\end{equation*}
$$

However, the quadrupole moment is finite: $|\boldsymbol{Q}| \sim e_{0} \lambda_{D}^{2}\left(v_{0} / v_{e}\right)^{2}$. Pick a specific velocity distribution function $g$ and calculate $\boldsymbol{Q}$.

### 7.1.1. Dynamic friction and wave emission at long wavelengths

We return to (7.5) and examine its properties. We expect that if $v_{0}>\omega / k$ there will be a Cerenkov effect. What is the shielded force on a single particle in the frame of the lowest-order particle trajectory (an inertial frame)?

$$
\begin{equation*}
\boldsymbol{F}=e_{0} \boldsymbol{E}(s=0)=e_{0}^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} 4 \pi \frac{(-\mathrm{i} \boldsymbol{k})}{k^{2}} \frac{1}{\varepsilon\left(\boldsymbol{k}, \boldsymbol{k} \cdot \boldsymbol{v}_{0}\right)} \quad \frac{1}{\varepsilon}=\frac{\varepsilon_{R}-\mathrm{i} \varepsilon_{I}}{|\varepsilon|^{2}} . \tag{7.7}
\end{equation*}
$$

We note that $\varepsilon_{R}$ is even with respect to changing the sign of $\boldsymbol{k}$, while $\varepsilon_{I}$ and $\boldsymbol{k} / k^{2}$ are odd. Thus, equation (7.7) yields the following result.

THEOREM (Dynamic friction).

$$
\begin{equation*}
\boldsymbol{F}=e_{0} \boldsymbol{E}(s=0)=-e_{0}^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} 4 \pi \frac{\boldsymbol{k}}{k^{2}} \frac{\varepsilon_{I}}{|\varepsilon|^{2}} . \tag{7.8}
\end{equation*}
$$

The dynamic friction has different characteristics for long and short wavelengths; (i) for $k<k_{D}\left(\lambda>\lambda_{D}\right)$, waves are weakly damped and weakly emitted by the Cerenkov effect $\boldsymbol{k} \cdot \boldsymbol{v}_{0}=\omega_{\boldsymbol{k}}$. There is a radiation reaction, i.e. particles lose energy in emitting waves. (ii) For $k>k_{D}\left(\lambda<\lambda_{D}\right)$, shielding is insufficient and ineffective. Binary interactions (Coulomb collisions) produce friction. We consider the longand short-wavelength limits separately, make appropriate approximations, and obtain analytic results to evaluate the dynamic friction and wave emission.

We examine (7.8) in the long-wavelength limit,

$$
\begin{equation*}
\boldsymbol{F}_{W}=-\boldsymbol{F}=e_{0}^{2} \int_{k<k_{D}} \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} 4 \pi \frac{\boldsymbol{k}}{k^{2}} \int \mathrm{~d} \omega \delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{0}\right) \operatorname{Im} \frac{1}{\varepsilon(\boldsymbol{k}, \omega)} \tag{7.9}
\end{equation*}
$$

where the force on the waves due to the particle is opposite in sign to the force of the waves on the particle. We make use of

$$
\gamma_{k}=-\frac{\left.\varepsilon_{I}\right|_{\omega_{k}}}{\left.\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}}}
$$

for small $k$ and

$$
\lim _{y \rightarrow 0} \frac{1}{x+\mathrm{i} y}=P\left(\frac{1}{x}\right)-\mathrm{i} \pi \delta(x) \operatorname{sgn}(y)
$$

Hence, if $\left|\varepsilon_{I}\right| \ll|\omega \partial \varepsilon / \partial \omega|$, then

$$
\operatorname{Im} \frac{1}{\varepsilon_{R}+\mathrm{i} \varepsilon_{I}}=-\pi \delta\left(\varepsilon_{R}\right) \operatorname{sgn}\left(\varepsilon_{I}\right) \quad \delta\left(\varepsilon_{R}\right)=\delta\left(\varepsilon_{R}(\boldsymbol{k}, \omega)\right)=\sum_{l} \frac{\delta\left(\omega-\omega_{k}^{l}\right)}{\left|\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}^{l}}} \quad \varepsilon_{R}\left(\boldsymbol{k}, \omega_{\boldsymbol{k}}^{l}\right)=0
$$

Thus (7.9) leads to the following result for long wavelengths.

## Theorem.

$$
\begin{equation*}
\boldsymbol{F}_{W}=-e_{0}^{2} \pi \int_{k<k_{D}} \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} 4 \pi \frac{\boldsymbol{k}}{k^{2}} \sum_{l} \frac{1}{\left|\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{\boldsymbol{k}}^{l}}} \delta\left(\omega_{\boldsymbol{k}}^{l}-\boldsymbol{k} \cdot \boldsymbol{v}_{0}\right) \operatorname{sgn}\left(\omega_{\boldsymbol{k}}^{l}\right) \tag{7.10}
\end{equation*}
$$

We next derive the rate of energy loss by the particle, which is equal to the rate of energy in wave emission,

$$
\begin{equation*}
\dot{W}=-\boldsymbol{F}_{W} \cdot \boldsymbol{v}_{0}=e_{0}^{2} \pi \int_{k<k_{D}} \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \frac{4 \pi}{k^{2}} \sum_{l} \frac{\left|\omega_{\boldsymbol{k}}^{l}\right|}{\left|\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}^{l}}} \delta\left(\omega_{\boldsymbol{k}}^{l}-\boldsymbol{k} \cdot \boldsymbol{v}_{0}\right) \tag{7.11}
\end{equation*}
$$

The rate of energy in wave emission is positive for either stable or unstable waves. With no loss of generality we can limit the sum over $l$ in (7.11) to branches for which $\omega>0$ and introduce a factor of 2 to account for the negative frequencies.

DEFInition. The rate of energy in wave-emission per unit volume as a function of $\boldsymbol{k}$ for a particular branch $l$ (with positive frequency - summing over both positive and negative frequencies for the branch will introduce another factor of 2)

$$
\begin{equation*}
\dot{W}^{l}(\boldsymbol{k})=\frac{4 \pi^{2} e_{0}^{2}}{k^{2}} \frac{\left|\omega_{k}^{l}\right|}{\left|\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}^{l}}} \delta\left(\omega_{\boldsymbol{k}}^{l}-\boldsymbol{k} \cdot \boldsymbol{v}_{0}\right) \tag{7.12}
\end{equation*}
$$

We integrate (7.12) over the velocity distribution functions and sum over species to obtain the wave-emission power density per unit volume in $\boldsymbol{k}$ space for all particles ignoring particle-radiation correlations (restriction to incoherent radiation),

$$
\dot{W}^{l}(\boldsymbol{k})=\sum_{s} \int \mathrm{~d}^{3} \boldsymbol{v} g_{s}(\boldsymbol{v}) \frac{\omega_{s}^{2}}{k^{2}} \frac{2 \pi m_{s}\left|\omega_{k}^{l}\right|}{\left|\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}^{l}}} \delta\left(\omega_{k}^{l}-\boldsymbol{k} \cdot \boldsymbol{v}_{0}\right)
$$

$$
\begin{equation*}
=\frac{2 \pi}{k^{3}} \frac{\left|\omega_{k}^{l}\right|}{\left.\left|\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}^{l}} \right\rvert\,} \sum_{s} g_{s}\left(u=V_{k}^{l}\right)_{s} m_{s} \omega_{s}^{2}, \tag{7.13}
\end{equation*}
$$

where $V_{k}^{l}=\omega_{k}^{l} / k$. Equation (7.13) is the spontaneous emission power density per unit volume in $k$ space.
[Editor's note: at this point Kaufman commented that this derivation seems to be in error for negative energy waves for which $\partial \varepsilon^{\prime} \partial \omega<0$. He did not explain the nature of the error. The difficulty in the derivation of the wave emission leading to (7.12) and (7.13) is that these expressions are positive definite: they depend on the magnitude of $\left|\partial \varepsilon_{R} / \partial \omega\right|$ in the denominator instead of just $\partial \varepsilon_{R} / \partial \omega$. For negative energy waves, the emission of energy into the waves is positive according to (7.12) and (7.13), when it should be negative. The resolution to the contradiction is found in Tracy, Kaufman \& Liang (1995) where wave emission is derived in Sections III and IV for either positive or negative energy waves and there is a more careful tracking of signs. The correction in Tracy et al. is well illustrated by comparing the Tracy et al. equation (54) to (7.12) in Kaufman's lecture notes. The editor thanks Alain Brizard and Dmitri Ryutov for assistance in resolving this difficulty.]

The total time derivative of the energy density per unit $\boldsymbol{k}$ volume is a sum including the spontaneous emission, Landau damping or growth and nonlinear effects:

Postulate.

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} W^{l}(\boldsymbol{k})=\dot{W}_{\boldsymbol{k}}^{l}+2 \gamma_{k}^{l} W_{\boldsymbol{k}}^{l}+\text { nonlinear } \tag{7.14}
\end{equation*}
$$

[Editor's note: in these lecture notes the terms on the right-hand side of (7.14) have been derived separately from the Vlasov-Poisson equation so that (7.14) has been built up in pieces.]

If the wave amplitudes are small, then nonlinear effects can be ignored. If we further assume that the plasma is stable, i.e. $\gamma_{k}^{l}<0$, then (7.14) admits a simple steady-state relation for the energy density per unit $\boldsymbol{k}$ volume in branch $l$,

$$
\begin{equation*}
W_{k}^{l}=\frac{\dot{W}_{k}^{l}}{-2 \gamma_{k}^{l}} . \tag{7.15}
\end{equation*}
$$

If we use the relation for $\gamma_{k}^{l}=\left(\pi / k^{2}\right)\left(1 / \partial \varepsilon_{R} /\left.\partial \omega\right|_{\omega_{k}^{l}}\right) \sum_{s} \omega_{s}^{2} s_{\hat{k}}^{\prime \prime}\left(V_{k}^{l}\right)$ in (7.15), we obtain

$$
\begin{equation*}
W_{k, s}^{l}=\frac{\left|V_{k}^{l}\right| m_{s} g_{k}^{s}\left(V_{k}^{l}\right)}{-g_{k}^{s /}\left(V_{k}^{l}\right)} \tag{7.16}
\end{equation*}
$$

for a single resonant species.
Example. For a Maxwellian plasma $g(u)=$ const. $\exp \left(-m u^{2} / 2 T\right)$, then

$$
\begin{equation*}
g^{\prime}(u)=-(m u / T) g \tag{7.17a}
\end{equation*}
$$

and

$$
\begin{equation*}
W^{l}(\boldsymbol{k})=T_{s} \tag{7.17b}
\end{equation*}
$$

for a single resonant species. This is the Rayleigh-Jeans law for a plasma (equipartition law in statistical mechanics). This is only valid for weak damping, i.e. $k<k_{D}=\lambda_{D}^{-1}$.

We integrate (7.17a) over wavenumbers to compute the energy density $W$ in a quiescent plasma,

$$
\begin{equation*}
W=\int_{k<k_{D}} \frac{\mathrm{~d}^{3} k}{(2 \pi)^{3}} \sum_{l} W^{l}(\boldsymbol{k}) \approx 2 T k_{D}^{3} \sim T / \lambda_{D}^{3} \tag{7.18}
\end{equation*}
$$

An estimate of the kinetic energy density in the plasma is the pressure, i.e. $K \sim n T$. Hence,

$$
\begin{equation*}
\frac{W}{K} \sim \frac{T}{\lambda_{D}^{3}} \frac{1}{n T} \sim \frac{1}{n \lambda_{D}^{3}} \equiv \frac{1}{\Lambda} \ll 1 \tag{7.19}
\end{equation*}
$$

We note that the plasma parameter $\Lambda$ is typically large, e.g. $\Lambda \sim 10^{4}-10^{8}$.
Example. In a non-Maxwellian plasma we define an effective temperature $T_{\text {eff }}$ so that in analogy to (7.17a) one has

$$
\begin{equation*}
g^{\prime}(u)=-\left(m u / T_{\mathrm{eff}}(u)\right) g \tag{7.20a}
\end{equation*}
$$

and

$$
\begin{equation*}
W^{l}(\boldsymbol{k})=T_{s, \text { eff }}\left(V_{k}^{l}\right) \tag{7.20b}
\end{equation*}
$$

Equation (7.20b) retains the form of the Rayleigh-Jeans formula. The results in this sub-section can be believed as long as the wave energies are not so large as to invalidate our ignoring the nonlinear terms in (7.14). The extension of (7.19) to the non-Maxwellian limit gives

$$
\begin{equation*}
\frac{W}{K} \sim \frac{T_{\mathrm{eff}}}{\lambda_{D}^{3}} \frac{1}{n T} \sim \frac{1}{\Lambda} \frac{T_{\mathrm{res}}}{T_{\mathrm{avg}}} \sim 10^{-5} \times 10^{3} \sim 10^{-2} \ll 1 \tag{7.21}
\end{equation*}
$$

At this relative amplitude the wave energy density should be quite measurable.
EXERCISE. (i) Examine the generalization to the electromagnetic wave energy densities based on Maxwell's equations. (ii) Calculate the wave energy density in ion-acoustic waves for $T_{e} \gg T_{i}$. Show that for ion waves one can deduce that the plasma parameter has to be quite large, i.e. $\Lambda>\left(m_{i} / m_{e}\right)^{2}$, in order that the wave energy density be small enough to avoid trapping electrons. Electron trapping in ion waves invalidates the neglect of nonlinearities in the theory.

### 7.1.2. Superthermal radiation - Cerenkov radiation and radiation reaction

In (7.10) we calculated the radiation reaction $\boldsymbol{F}_{W}$ to a test particle based on the linear plasma response for long wavelengths modes. If we assume that the plasma is isotropic and unmagnetized $(\boldsymbol{B}=0)$, then we can project the radiation reaction force onto the preferred direction of the test-particle velocity,

$$
\begin{equation*}
\hat{\boldsymbol{v}}_{0} \cdot \boldsymbol{F}_{W}=-\frac{2 e_{0}^{2} \omega_{p}^{2}}{2 v_{0}} \int_{k<k_{D}} \frac{k^{2} \mathrm{~d} k}{(2 \pi)^{3}} \frac{4 \pi^{2}}{k^{2}} 2 \pi \int_{-1}^{1} \mathrm{~d} \mu \delta\left(\omega_{p}-k v_{0} \mu\right)=-\frac{e_{0}^{2} \omega_{p}^{2}}{v_{0}^{2}} \int_{0+}^{k_{D}} \frac{\mathrm{~d} k}{k} \tag{7.22}
\end{equation*}
$$

where we only include electron plasma waves for which $\left|\partial \varepsilon_{R} / \partial \omega\right|_{\omega_{k}}=2 / \omega_{p}, \mu \equiv$ $\cos \theta$ due to the projection of $\boldsymbol{k}$ on $\boldsymbol{v}_{0}$, there are two branches of waves (positive and negative frequencies), and $\delta\left(\omega_{p}-k v_{0} \mu\right)=\left(1 / k v_{0}\right) \delta\left(\mu-\omega_{p} / k v_{0}\right)$. The Cerenkov resonance between the wave and the particle is embodied in the relation $v_{0} \mu=\omega_{p} / k$, which can only be satisfied if $\mu=\omega_{p} / k v_{0}<1 \rightarrow \omega_{p} / v_{0}<k$. This implies the following result.

THEOREM. Wave-particle resonance and emission can exist if

$$
\begin{equation*}
\frac{\omega_{p}}{v_{0, \text { res }}}<k<k_{D} \quad \Rightarrow \quad \frac{\omega_{p}}{v_{0, \text { res }}}<k_{D} \quad \text { or } \quad v_{\mathrm{th}}^{e}=\frac{\omega_{p}}{k_{D}}<v_{0, \text { res }} \tag{7.23}
\end{equation*}
$$

Hence, only superthermal particle particles can emit waves; and the lower limit of the integral with respect to $k$ in (7.22) is $\omega_{p} / v_{0}$.

THEOREM. The magnitude of the resonant radiation reaction force is

$$
\begin{equation*}
\hat{\boldsymbol{v}}_{0} \cdot \boldsymbol{F}_{W}=-\frac{e_{0}^{2} \omega_{p}^{2}}{v_{0}^{2}} \int_{\frac{\omega_{p}}{v_{0}}}^{k_{D}} \frac{\mathrm{~d} k}{k}=-\frac{e_{0}^{2} \omega_{p}^{2}}{v_{0}^{2}} \ln \frac{v_{0}}{v_{\mathrm{th}}^{e}}\left|\hat{\boldsymbol{v}}_{0} \cdot \boldsymbol{F}_{W}\right| \approx \frac{e_{0}^{2}}{\lambda_{D}^{2}}\left(\frac{v_{\mathrm{th}}^{e}}{v_{0}}\right)^{2} \ln \frac{v_{0}}{v_{\mathrm{th}}^{e}} . \tag{7.24}
\end{equation*}
$$

### 7.1.3. Dynamic friction and wave emission at short wavelengths

We return to (7.9) in the short-wavelength limit,

$$
\begin{equation*}
\boldsymbol{F}_{D}=-e_{0}^{2} \int_{k>k_{D}} \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} 4 \pi \frac{\boldsymbol{k}}{k^{2}} \frac{\varepsilon_{I}\left(\boldsymbol{k}, \boldsymbol{k} \cdot \boldsymbol{v}_{0}\right)}{|\varepsilon|^{2}}, \tag{7.25}
\end{equation*}
$$

where

$$
\begin{align*}
\varepsilon & =1-\sum_{s} \frac{\omega_{s}^{2}}{k^{2}} \int \mathrm{~d} u g_{\hat{\boldsymbol{k}}}^{s^{\prime}}(u)\left[\frac{P}{u-\hat{\boldsymbol{k}} \cdot \boldsymbol{v}_{0}}+\mathrm{i} \pi \delta\left(u-\hat{\boldsymbol{k}} \cdot \boldsymbol{v}_{0}\right)\right]  \tag{7.26a}\\
\varepsilon_{I} & =-\pi \sum_{s} \frac{\omega_{s}^{2}}{k^{2}} \int \mathrm{~d} u g_{\hat{\boldsymbol{k}}}^{s \prime}\left(\hat{\boldsymbol{k}} \cdot \boldsymbol{v}_{0}\right) \quad \operatorname{Im} \frac{1}{\varepsilon}=-\frac{\varepsilon_{I}}{|\varepsilon|^{2}} \quad g_{\hat{\boldsymbol{k}}}^{s \prime} \equiv \frac{\partial}{\partial u} g_{\hat{\boldsymbol{k}}}^{s}(u) . \tag{7.26b}
\end{align*}
$$

For short-wavelength modes, e.g. electron plasma waves, the phase velocities fall in the bulk of the electron velocity distribution, which gives rise to strong Landau damping. Thus, the normal mode frequencies $\omega_{k}^{l}$ have large imaginary parts so that $\varepsilon\left(\operatorname{Re} \omega_{k}^{l}\right) \neq 0$ and $\varepsilon=1+O\left(1 / k^{2} \lambda_{D}^{2}\right)$.

THEOREM. For $k>k_{D}$ we assume $|\varepsilon|^{2} \rightarrow O(1)$, in which limit the dynamic friction is

$$
\begin{equation*}
\boldsymbol{F}_{D}=4 \pi^{2} e_{0}^{2} \sum_{s} \omega_{s}^{2} \int_{k>k_{D}} \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \frac{\boldsymbol{k}}{k^{4}} g_{\hat{\boldsymbol{k}}}^{s}\left(\hat{\boldsymbol{k}} \cdot \boldsymbol{v}_{0}\right) \tag{7.27}
\end{equation*}
$$

We next assume that $g$ is isotropic. Then the only preferred direction is the velocity $\boldsymbol{v}_{0}$. Hence, equation (7.27) becomes

$$
\begin{equation*}
\hat{\boldsymbol{v}}_{0} \cdot \boldsymbol{F}_{D}^{s}=-4 \pi^{2} e_{0}^{2} \omega_{s}^{2} \int_{k>k_{D}} \frac{k^{2} \mathrm{~d} k}{(2 \pi)^{3}} \frac{2 \pi}{k^{3}} \int_{-1}^{1} \mathrm{~d} \mu \mu g_{\hat{\boldsymbol{k}}}^{s^{\prime}}\left(v_{0} \mu\right) \quad \mu \equiv \cos \left(\hat{\boldsymbol{k}}, \hat{\boldsymbol{v}}_{0}\right) . \tag{7.28}
\end{equation*}
$$

The lower limit of the $k$-integral in (7.28) is $k_{D}$. The upper limit cutoff is set by physical considerations. Classical considerations become invalid and quantum mechanics must be applied for wavelengths shorter than the de Broglie wavelength, $v i z ., k>m v / \hbar$. Another constraint is set by the assumption of small-amplitude electric fields so that linear theory is valid: $e^{2} / r \ll m v^{2}$ or $r>e^{2} / T \rightarrow k<T / e^{2}$. Hence, we obtain

$$
\begin{equation*}
k_{\max }=\left(\frac{m v}{\hbar}, \frac{T}{e^{2}}\right)_{<} \tag{7.29}
\end{equation*}
$$

where the former condition is set by quantum mechanics and prevails for $T>10 \mathrm{eV}$, and the latter condition is set by nonlinearity and prevails for $T<10 \mathrm{eV}$. For $k>k_{\max }$ one must employ the quantum mechanical Boltzmann equation. In terms of interaction distances, equation (7.28) pertains to interaction distances $r$ satisfying $r_{\min } \sim 1 / k_{\max }<$ $r<\lambda_{D}$ where $k_{\text {max }}$ is given in (7.29).

The results here capture simultaneous, superposable, small-angle collisions. There are no waves here and no zeroes of $\varepsilon$. The lower limit of the integral over $k$ in (7.28) is $k_{D}$, so that the $k$ integral $\int \mathrm{d} k / k=\ln \left(k_{\max } / k_{D}\right)$. In the low-temperature classical limit for $k_{\text {max }}$, equation (7.28) yields

$$
\left.\begin{array}{rl}
\hat{\boldsymbol{v}}_{0} \cdot \boldsymbol{F}_{D}^{s}=- & \frac{e_{0}^{2} \omega_{s}^{2}}{2 \pi} \int_{k_{D}}^{k_{\max }} \frac{\mathrm{d} k}{k} 2 \pi \int_{-1}^{1} \mathrm{~d} \mu \mu g_{\hat{k}}^{s \prime}\left(v_{0} \mu\right)=-e_{0}^{2} \omega_{s}^{2} \ln \frac{k_{\max }}{k_{D}} \int_{-1}^{1} \mathrm{~d} \mu \mu g_{\hat{k}}^{s \prime}\left(v_{0} \mu\right) \\
& \ln \frac{k_{\max }}{k_{D}}=\ln \frac{T \lambda_{D}}{e^{2}}=\ln \frac{4 \pi n T \lambda_{D}}{4 \pi n e^{2}}=\ln 4 \pi n \lambda_{D}^{3}=\ln \Lambda+\ln 4 \pi . \tag{7.30}
\end{array}\right\}
$$

Ten per cent corrections to the upper and lower limits on the $k$-integration are possible but are not important because collisions are already a minor effect compared to collective effects for $n \lambda_{D}^{3} \gg 1$. Hence, we approximately evaluate (7.30)

$$
\begin{equation*}
\hat{\boldsymbol{v}}_{0} \cdot \boldsymbol{F}_{D}^{s} \approx-e_{0}^{2} \omega_{s}^{2} \ln \Lambda \int_{-1}^{1} \mathrm{~d} \mu \mu g_{\hat{\boldsymbol{k}}}^{s \prime}\left(v_{0} \mu\right)=F_{D}^{s}\left(v_{0}\right) \sim \frac{e_{0}^{2} \omega_{s}^{2}}{v_{\mathrm{th}, s}^{2}} \ln \Lambda \sim \frac{e_{0}^{2}}{\lambda_{\mathrm{D} s}^{2}} \ln \Lambda \tag{7.31}
\end{equation*}
$$

We compare the result in (7.31) with the result in (7.24) for the radiation reaction force: $F_{W} \sim e^{2} / \lambda_{D}^{2} \ll F_{D} \sim \ln \Lambda e^{2} / \lambda_{D}^{2} . F_{D}$ is dominant.
Example. Consider a Maxwellian velocity distribution function

$$
\begin{equation*}
g^{s}(u)=\frac{1}{\sqrt{2 \pi} v_{s}} \exp \left(-\frac{u^{2}}{2 v_{s}^{2}}\right) \quad \lambda_{s} \equiv \frac{v_{s}}{\omega_{s}} \quad v_{s} \equiv \sqrt{\frac{T_{s}}{m_{s}}} \tag{7.32}
\end{equation*}
$$

Then the dynamic friction is

$$
\begin{equation*}
F_{D}^{s}\left(v_{0}\right) \approx-\frac{e_{0}^{2}}{\lambda_{s}^{2}} \ln \Lambda \frac{v_{0}}{v_{s}} \frac{1}{\sqrt{2 \pi}} \int_{-1}^{1} \mathrm{~d} \mu \mu^{2} \exp \left(-\frac{\mu^{2}}{2 \mu_{0}^{2}}\right) \quad \mu_{0} \equiv \frac{v_{s}}{v_{0}} \tag{7.33}
\end{equation*}
$$

The integral in (7.33) can be evaluated analytically in two opposite limits,

$$
\begin{aligned}
& \int_{-1}^{1} \mathrm{~d} \mu \mu^{2} \exp \left(-\frac{\mu^{2}}{2 \mu_{0}^{2}}\right) \rightarrow \int_{-1}^{1} \mathrm{~d} \mu \mu^{2}=\frac{2}{3} \text { for } v_{0} \ll v_{s}, \quad \mu_{0} \gg 1 \\
& \rightarrow \mu_{0}^{3} \int_{-1 / \mu_{0}}^{1 / \mu_{0}} \mathrm{~d} x x^{2} \exp \left(-\frac{1}{2} x^{2}\right) \approx \mu_{0}^{3} \int_{-\infty}^{\infty} \mathrm{d} x x^{2} \exp \left(-\frac{1}{2} x^{2}\right)=\sqrt{2 \pi} \mu_{0}^{3} \\
& \quad \text { for } v_{0} \gg v_{s}, \quad \mu_{0} \ll 1
\end{aligned}
$$

Thus, equation (7.33) is evaluated asymptotically as

$$
\begin{equation*}
F_{D}^{s}\left(v_{0}\right) \approx \frac{e_{0}^{2}}{\lambda_{s}^{2}} \ln \Lambda\left\{\frac{2}{3 \sqrt{2 \pi}} \frac{v_{0}}{v_{s}} \approx 0.25 \frac{v_{0}}{v_{s}} \text { for } v_{0} \ll v_{s},\left(\frac{v_{s}}{v_{0}}\right)^{2} \text { for } v_{0} \gg v_{s}\right\} \tag{7.34}
\end{equation*}
$$

EXERCISE. Sketch $F_{D}^{s}$ using (7.34) and $F_{W}$ based on (7.24) as functions of $v_{0}$.

### 7.1.4. Calculation of classical collisional resistivity

In (7.34) we calculated the dynamic friction on a test particle as a function of the test-particle speed $v_{0}$ due to its collisional interaction with the plasma for a Maxwellian electron distribution. Consider ions and electrons subject to an electric field, and the ions and electrons collisionally drag on one another. Newton's law for each particle is

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} m_{s} \boldsymbol{v}=e_{s} \boldsymbol{E}+\boldsymbol{F}_{D}^{s^{\prime}} \tag{7.35}
\end{equation*}
$$

For singly charged ions and a quasi-neutral plasma $n_{e} \approx n_{i}=n$, the fluid current is

$$
\begin{equation*}
\boldsymbol{j}=n e\left(\boldsymbol{u}_{i}-\boldsymbol{u}_{e}\right) \equiv n e \boldsymbol{u}_{D} \equiv \sigma \boldsymbol{E} \tag{7.36}
\end{equation*}
$$

where we have introduced the conductivity $\sigma$ which will be evaluated in the following analysis, $\sigma=n e u_{D} / E$ and $\boldsymbol{u}_{D}$ is a drift of the ions relative to the electrons. The ions are cold, and $u_{D}>0$ is assumed small compared to the electron thermal speed so that the ions are essentially at rest compared to the electrons. Due to Newton's third law there is no drag force of the ion fluid on itself. The equation of motion for the ion fluid is

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t}\left(n_{i} m_{i} u_{i}\right)=e n_{i} E-\left|F_{i}^{e}\right| n_{i} . \tag{7.37}
\end{equation*}
$$

There are more electrons slower than the ions than faster, so that the ion drag on the electrons decelerates the ions. The equation of motion for the electron fluid is

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t}\left(n_{e} m_{e} u_{e}\right)=-e n_{e} E+\left|\left\langle F_{e}^{i}\right\rangle\right| n_{e} \tag{7.38}
\end{equation*}
$$

and in consequence of Newton's third law, $\left|F_{i}^{e}\right|=\left|\left\langle F_{e}^{i}\right\rangle\right|$. At steady state, $\mathrm{D} / \mathrm{D} t=0$ in both (7.37) and (7.38). The force of the electrons on the ions at steady state if $u_{D} \ll v_{e}$ is

$$
\begin{equation*}
\left|F_{D}^{s}\left(v_{0}\right)\right|=\frac{2}{3} \frac{1}{\sqrt{2 \pi}} \frac{v_{0}}{v_{s}} \frac{e_{0}^{2}}{\lambda_{s}^{2}} \ln \Lambda \rightarrow \frac{2}{3} \frac{1}{\sqrt{2 \pi}} \frac{u_{D}}{v_{e}} \frac{e^{2}}{\lambda_{e}^{2}} \ln \Lambda=e E, \tag{7.39}
\end{equation*}
$$

where $\Lambda \equiv n \lambda_{e}^{3}, v_{e}=\sqrt{T_{e} / m_{e}}$ and $\lambda_{e} \equiv \sqrt{T_{e} / 4 \pi n e^{2}}$. Hence, from (7.38) to (7.39) the conductivity is

$$
\begin{equation*}
\sigma=\frac{n e u_{D}}{E}=\frac{3 n \sqrt{2 \pi} v_{e} \lambda_{e}^{3}}{2 \lambda_{e} \ln \Lambda}=\frac{3 \sqrt{2 \pi}}{2} \frac{\Lambda}{\ln \Lambda} \omega_{p} . \tag{7.40}
\end{equation*}
$$

Definition. The resistivity is defined as

$$
\begin{equation*}
\eta \equiv \frac{1}{\sigma}=\frac{1}{\omega_{p}} \frac{1}{3} \sqrt{\frac{2}{\pi}} \frac{\ln \Lambda}{\Lambda} . \tag{7.41}
\end{equation*}
$$

We note that the conductivity is nearly independent of density except for $\ln \Lambda$,

$$
\begin{equation*}
\sigma=\frac{3 \sqrt{2 \pi}}{2} \sqrt{\frac{4 \pi n e^{2}}{m_{e}}} \frac{n T_{e}^{3 / 2}}{(4 \pi)^{3 / 2} n^{3 / 2} e^{3}} \frac{1}{\ln \Lambda}=\frac{3 \sqrt{2}}{8 \sqrt{\pi}} v_{e} \frac{T_{e}}{e^{2}} \frac{1}{\ln \Lambda} . \tag{7.42}
\end{equation*}
$$

[Editor's note: the expression for $\sigma$ in (7.42) derived here for an unmagnetized plasma is the same as the $\sigma$ deduced from (5-34) to (5-36) in L. Spitzer, Physics of Fully Ionized Gases, 2nd Edition, Interscience Publishers (J. Wiley), 1962, apart from the numerical coefficient $3 \sqrt{2} / 8 \sqrt{\pi}=0.299$ in (7.42) and $\gamma_{e} \sqrt{8} / \pi \sqrt{\pi}=0.582 \sqrt{8} / \pi \sqrt{\pi}=0.295$ in Spitzer's book for $Z_{i}=1$. The expressions in Spitzer's book agree with L. Spitzer and R. Harm, Phys. Rev. 89, 977 (1953).]
7.1.5. Definition of collision-dominated parameter regime

We can introduce the concept of the collision frequency $v$ using the analogy

$$
\begin{equation*}
\dot{v}=-\frac{e E}{m}-v v=0 \Rightarrow 0=-\frac{e E}{m}-v \bar{v} \Rightarrow 0=-\frac{e E}{m}+v \bar{u}_{D} \Rightarrow \sigma=\frac{n e u_{D}}{E}=\frac{n e^{2}}{m v}=\frac{\omega_{p}^{2}}{4 \pi v_{e}} \tag{7.43}
\end{equation*}
$$

From (7.42) and (7.43) we can evaluate the collision frequency,

$$
\begin{equation*}
\sigma=\frac{\omega_{p}^{2}}{4 \pi v_{e}} \Rightarrow v_{e}=\frac{\omega_{p}}{\Lambda} \ln \Lambda \frac{1}{6 \pi \sqrt{2 \pi}}=\frac{8}{3} \sqrt{\frac{\pi}{2}} \frac{n_{e} e^{4} \ln \Lambda}{m_{e}^{1 / 2} T_{e}^{3 / 2}} . \tag{7.44}
\end{equation*}
$$

Furthermore, the expression for the basic collision frequency in (7.44) in §7.1.5 agrees with the inverse of Braginskii's basic collision time including numerical factors (Braginskii 1965). An alternate heuristic derivation of (7.44) is as follows:

$$
\begin{equation*}
v=n(\text { cross section }) v \ln \Lambda=n\left(\frac{e^{2}}{T}\right)^{2} v \ln \Lambda=\frac{n_{e} e^{4} \ln \Lambda}{m_{e}^{1 / 2} T_{e}^{3 / 2}} \tag{7.45}
\end{equation*}
$$

where we have used the Rutherford cross-section in (7.45) and have recovered equation (7.44) except for the numerical factors out in front. The characteristic slowing-down time due to electron collisions is $v_{e}^{-1} \sim \Lambda \omega_{p}^{-1}$.

Definition. The characteristic mean free path is

$$
\begin{equation*}
\ell_{\mathrm{coll}} \sim \frac{v_{e}}{v_{e}} \sim \frac{\Lambda}{\ln \Lambda} \frac{v_{e}}{\omega_{p}}=\frac{\Lambda}{\ln \Lambda} \lambda_{D} . \tag{7.46}
\end{equation*}
$$

The strong interaction distance (in the classical sense) is

$$
r_{0}=\frac{\lambda_{D}}{\Lambda} \approx \frac{e^{2}}{T} .
$$

The collisionless Vlasov approximation is so good because $\nu_{e} \ll \omega_{p}$ by $\ln \Lambda / \Lambda$.
7.1.6. Anomalous dynamic friction due to, for example, instabilities

We recall the steady-state relation used to reduce (7.38),

$$
\begin{equation*}
e E=F_{i}^{e}<E_{0} \equiv 0.22 \frac{e^{2}}{\lambda_{D}^{2}} \ln \Lambda \tag{7.47}
\end{equation*}
$$

for $u_{D} \leqslant v_{e}$. If $E>E_{0}$ there can be no balance, and the electrons can runaway because the electrons will continue to accelerate; $E_{0}$ is the runaway electric field limit (Dreicer 1959).

In §7.1.5 we calculated collisional friction due to Coulomb field interactions between test particles and shielding clouds given a relative drift $u_{D}$ between ions and electrons. A relative drift can be the source of free energy that excites collective modes of instability, which in turn provide an anomalous friction that can relax the drift. Here we discuss some of the instabilities that can arise as a function of $u_{D}$. For $u_{D}>v_{e}$ electron plasma waves are destabilized by a modified two-stream instability or Buneman instability (Buneman 1963). At much smaller drift velocities, ion-acoustic
waves can be destabilized. For $u_{D}>5 v_{i}$ ion-acoustic waves are unstable only if $T_{e} \gg T_{i}$, else Landau damping can stabilize the modes. For velocities $u_{D}>c_{s}=\left(T_{e} / m_{i}\right)^{1 / 2}$ there can be a strong ion-acoustic instability if $T_{e} \gg T_{i}$. The wave turbulence due to the instabilities can produce quasilinear diffusion and dynamic friction that affect the particle velocity distributions (see §6.5). As the velocity distributions evolve due to quasilinear diffusion (for example, heating), the Landau resonance effects and Coulomb collisions are changed. The self-consistent evolution of the turbulent fields and the velocity distributions are closely coupled.

Consider the following model problem. Assume there is a given relative drift $u_{D}$ and a driving electric field at $t=0$. At $t=0$ let $E=0$ and turn on the electric field until it exceeds the runaway threshold in magnitude. An approximate power balance relation for the electrons can be expressed as

$$
\begin{align*}
& e E u_{D}=\frac{\partial}{\partial t}\left[\frac{1}{2} m\left(u_{D}^{2}+v_{e}^{2}\right)\right] \approx \frac{\partial}{\partial t}\left[\frac{1}{2} m 2 u_{D}^{2}\right] \approx \frac{\partial}{\partial t}\left[m u_{D}^{2}\right] \\
& \Rightarrow e E=2 m \dot{u}_{D} \quad \Rightarrow u_{D} \approx u_{D}(0)+\frac{e E t}{2 m} \tag{7.48}
\end{align*}
$$

We have assumed that collisional friction between the electrons and ions deposits energy into electron thermal energy. We further assume that the thermal and directed energy grow in equal amounts in (7.48). There is no steady current, only acceleration. In this model the ions do not do much. The electron heating is dominantly parallel to the drift, and $T_{\|}$grows. The heated distribution function develops an anisotropy $\left(T_{\|}>T_{\perp}\right)$ that can excite an electromagnetic instability like the Weibel instability (Weibel 1959).

### 7.2. Extension of test-particle theory to many-particle phenomena

### 7.2.1. Incorporating dynamic friction into Vlasov quasilinear theory to extend the Vlasov equation to the Boltzmann equation

Here we extend our earlier treatment of quasilinear diffusion (§ 6.5) to include the dynamic friction also due to collisions. Recall the Vlasov equation extended to include velocity diffusion,

$$
\begin{equation*}
\frac{\partial}{\partial t} f(\boldsymbol{r}, \boldsymbol{v} ; t)+\frac{\partial}{\partial \boldsymbol{r}}(\dot{\boldsymbol{r}} f)+\frac{\partial}{\partial \boldsymbol{v}}(\dot{\boldsymbol{v}} f)=0 \Rightarrow \frac{\partial}{\partial \boldsymbol{v}} \cdot\left(\boldsymbol{D}(\boldsymbol{v}) \cdot \frac{\partial f}{\partial \boldsymbol{v}}\right) . \tag{7.49}
\end{equation*}
$$

This analysis will ignore large-angle (Boltzmann) collisions and quantum effects. The diffusion tensor $\boldsymbol{D}(\boldsymbol{v})$ was derived in § 6 based either on a random-walk argument or by iterating the Vlasov equation. In a Coulomb model,

$$
\begin{equation*}
\dot{\boldsymbol{v}}=\frac{e}{m} \boldsymbol{E} \rightarrow \boldsymbol{D}(\boldsymbol{v})=\left(\frac{e}{m}\right)^{2} \int_{0}^{\infty} \mathrm{d} \tau\left\langle\boldsymbol{E}\left(\boldsymbol{r}^{t}, t\right) \boldsymbol{E}\left(\boldsymbol{r}^{t-\tau}, t-\tau\right)\right\rangle \tag{7.50}
\end{equation*}
$$

The electric field in the theory of quasilinear diffusion is the Vlasov electric field associated with macroscopic waves and collective effects. In collisional diffusion the electric field is the 'noise' electric field associated with a microscopic picture. Of course, the particles just respond to the total electric field. The relative field energy in microscopic noise fields is $W / n T \approx O\left(\Lambda^{-1}\right) \sim 10^{-6}$, for example. The relative field energy in saturated turbulent fields might be $W / n T \sim 10^{-2}$, for example. We note that one does not put the same electric field in both the diffusion tensor and in the acceleration term on the left-hand side of (7.49), which would double count its effects.
7.2.2. Correlation functions, Bogoliubov approximation and irreversibility

We want to calculate the two-point auto-correlation function for the electric field used in $\boldsymbol{D}(\boldsymbol{v})$ in (7.50). It is useful from a pedagogic perspective to reduce the twopoint auto-correlation tensor in (7.50) to a scalar with respect to the electric potential,

$$
\begin{equation*}
\left\langle\phi(\boldsymbol{r}, t) \phi\left(\boldsymbol{r}^{\prime}, t^{\prime}\right)\right\rangle=\langle\phi(\boldsymbol{r}, t) \phi(\boldsymbol{r}-\boldsymbol{s}, t-\tau)\rangle . \tag{7.51}
\end{equation*}
$$

What is meant by the average in (7.51)? For $s \gg \lambda_{D}$ we are looking at effects due to waves (collective effects). If $s \ll \lambda_{D}$, then discrete particle effects are dominant. Similarly, $\tau \gg 1 / \omega_{p}$ corresponds to waves, while $\tau \ll 1 / \omega_{p}$ is dominated by discrete particle effects.

DEFINITION. The two-point auto-correlation function for the electric potential is

$$
\begin{equation*}
C_{\phi} \equiv C_{\phi}(\boldsymbol{s}, \tau) \equiv\langle\phi(\boldsymbol{r}, t) \phi(\boldsymbol{r}-\boldsymbol{s}, t-\tau)\rangle_{\boldsymbol{r}, t} \tag{7.52}
\end{equation*}
$$

and $\left.\left.C_{\phi}(\boldsymbol{s}=0, \tau=0) \equiv\langle | \phi(\boldsymbol{r}, t)\right|^{2}\right\rangle$ is related to the field energy density.
Averaging in (7.51) and (7.52) over position only makes sense in a uniform plasma, $L \gg \lambda_{D}$. Time averaging makes sense only if the system is stationary in time, $t \gg$ $\omega_{p}^{-1}$. However, if the system is uniform and stationary on the microscopic scales, time and space averaging over the fast scales is allowed while accommodating variations in space and time that are much slower than the microscopic scales. We assume that the fast and slow time scales are well separated (Bogoliubov approximation).

Definition (Truncated Fourier transforms). We define the following truncated Fourier transforms

$$
\begin{equation*}
\phi(\boldsymbol{k}, \omega ; \boldsymbol{r}, t ; V, T) \equiv \int_{V} \mathrm{~d}^{3} \boldsymbol{s} \int_{-T / 2}^{T / 2} \mathrm{~d} \tau \phi(\boldsymbol{r}+\boldsymbol{s}, t+\tau) \exp (-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{s}+\mathrm{i} \omega \tau) \tag{7.53}
\end{equation*}
$$

Later we will let $V, T \rightarrow \infty$ and will average with respect to $r$ and $t$. We construct

$$
\begin{align*}
\lim _{V, T \rightarrow \infty} & \left\langle\phi(\boldsymbol{k}, \omega ; \boldsymbol{r}, t ; V, T) \phi^{*}\left(\boldsymbol{k}^{\prime}, \omega^{\prime} ; \boldsymbol{r}, \boldsymbol{t} ; V, T\right)\right\rangle_{\boldsymbol{r}, t} \\
= & \lim _{V, T \rightarrow \infty}\left\langle\int \mathrm{~d}^{3} \boldsymbol{s} \int \mathrm{~d}^{3} \boldsymbol{s}^{\prime} \int \mathrm{d} \tau \int \mathrm{~d} \tau^{\prime} \phi(\boldsymbol{r}+\boldsymbol{s}, t+\tau) \phi^{*}\left(\boldsymbol{r}+\boldsymbol{s}^{\prime}, t+\tau^{\prime}\right)\right. \\
& \left.\times \exp (-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{s}+\mathrm{i} \omega \tau) \exp \left(+\mathrm{i} \boldsymbol{k}^{\prime} \cdot \boldsymbol{s}^{\prime}-\mathrm{i} \omega^{\prime} \tau^{\prime}\right)\right\rangle_{\boldsymbol{r}, t} \\
= & \lim _{V, T \rightarrow \infty} \int \mathrm{~d}^{3} \boldsymbol{s} \int \mathrm{~d}^{3} \boldsymbol{s}^{\prime} \int \mathrm{d} \tau \int \mathrm{~d} \tau^{\prime}\left\langle\phi(\boldsymbol{r}+\boldsymbol{s}, t+\tau) \phi^{*}\left(\boldsymbol{r}+\boldsymbol{s}^{\prime}, t+\tau^{\prime}\right)\right\rangle_{\boldsymbol{r}, t} \\
& \times \exp (-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{s}+\mathrm{i} \omega \tau) \exp \left(+\mathrm{i} \boldsymbol{k}^{\prime} \cdot \boldsymbol{s}^{\prime}-\mathrm{i} \omega^{\prime} \tau^{\prime}\right) \\
= & \lim _{V, T \rightarrow \infty} \int \mathrm{~d}^{3} \boldsymbol{s} \int \mathrm{~d}^{3} \boldsymbol{s}^{\prime} \int \mathrm{d} \tau \int \mathrm{~d} \tau^{\prime} C_{\phi}\left(\boldsymbol{s}-\boldsymbol{s}^{\prime}, \tau-\tau^{\prime}\right) \\
& \times \exp (-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{s}+\mathrm{i} \omega \tau) \exp \left(+\mathrm{i} \boldsymbol{k}^{\prime} \cdot \boldsymbol{s}^{\prime}-\mathrm{i} \omega^{\prime} \tau^{\prime}\right) \\
= & \lim _{V, T \rightarrow \infty} \int \mathrm{~d}^{3} \boldsymbol{s} \int \mathrm{~d}^{3} \boldsymbol{s}^{\prime \prime} \int \mathrm{d} \tau \int \mathrm{~d} \tau^{\prime \prime} C_{\phi}\left(\boldsymbol{s}^{\prime \prime}, \tau^{\prime \prime}\right) \\
& \times \exp (-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{s}+\mathrm{i} \omega \tau) \exp \left(+\mathrm{i} \boldsymbol{k}^{\prime} \cdot\left(\boldsymbol{s}-\boldsymbol{s}^{\prime \prime}\right)-\mathrm{i} \omega^{\prime}\left(\tau-\tau^{\prime \prime}\right)\right) . \tag{7.54}
\end{align*}
$$

Note that because we let $V, T \rightarrow \infty$ there is no problem with the limits of integration when changing the variables. We next make use of the following identities

$$
\int \mathrm{d}^{3} s \exp \left(-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{s}+\mathrm{i} \boldsymbol{k}^{\prime} \cdot \boldsymbol{s}\right)=(2 \pi)^{3} \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \quad \int \mathrm{d} \tau \exp \left(\mathrm{i} \omega \tau-\mathrm{i} \omega^{\prime} \tau\right)=2 \pi \delta\left(\omega-\omega^{\prime}\right)
$$

to reduce (7.54) to

$$
\begin{align*}
& \lim _{V, T \rightarrow \infty}\left\langle\phi(\boldsymbol{k}, \omega ; \boldsymbol{r}, t ; V, T) \phi^{*}\left(\boldsymbol{k}^{\prime}, \omega^{\prime} ; \boldsymbol{r}, t ; V, T\right)\right\rangle_{\boldsymbol{r}, t} \\
& \quad=(2 \pi)^{4} \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \delta\left(\omega-\omega^{\prime}\right) \int \mathrm{d}^{3} s \int \mathrm{~d} \tau C_{\phi}(\boldsymbol{s}, \tau) \exp (-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{s}+\mathrm{i} \omega \tau) \\
& \quad=(2 \pi)^{4} \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \delta\left(\omega-\omega^{\prime}\right) S_{\phi}(\boldsymbol{k}, \omega) \tag{7.55}
\end{align*}
$$

Definition. In (7.55) we have identified the spectral density $S_{\phi}$ which is the Fourier transform of the auto-correlation function for the electric potential

$$
\begin{equation*}
S_{\phi}(\boldsymbol{k}, \omega)=F_{s, \tau}\left(C_{\phi}(\boldsymbol{s}, \tau)\right) . \tag{7.56}
\end{equation*}
$$

Equation (7.56) is a statement of the Wiener-Khinchin-Einstein theorem. The implication of (7.56) is that space-time averaging is equivalent to phase-space (ergodic) averaging.

The analysis leading to the results in this section employs the linear plasma response and stationarity assumptions. This requires a stable plasma (an unstable plasma violates the stationarity assumption). Large-amplitude phenomena and trapping also invalidate the analysis. Moreover, we have also assumed that the plasma is uniform. Consider the shielded field (Coulomb model) of a collection of bare particles,

$$
\begin{equation*}
\phi(\boldsymbol{k}, \omega)=\sum_{i} \phi^{i}(\boldsymbol{k}, \omega)=\frac{1}{\varepsilon(\boldsymbol{k}, \omega)} \frac{4 \pi}{k^{2}} e_{i} 2 \pi \delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{i}\right) \exp \left(-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{i}\right) \tag{7.57}
\end{equation*}
$$

The rigorous methods to calculate (7.57) are difficult. We have taken an intuitive testparticle point of view. From (7.57) we calculate

$$
\begin{align*}
& \left\langle\phi(\boldsymbol{k}, \omega) \phi^{*}\left(\boldsymbol{k}^{\prime}, \omega^{\prime}\right)\right\rangle \\
& =\sum_{i} \sum_{j} \frac{1}{\varepsilon^{*}\left(\boldsymbol{k}^{\prime}, \omega^{\prime}\right)} \frac{1}{\varepsilon(\boldsymbol{k}, \omega)} \frac{4 \pi}{k^{\prime 2}} \frac{4 \pi}{k^{2}} e_{j} e_{i} \\
& \quad \times\left\langle(2 \pi)^{2} \delta\left(\omega^{\prime}-\boldsymbol{k}^{\prime} \cdot \boldsymbol{v}_{j}\right) \exp \left(\mathrm{i} \boldsymbol{k}^{\prime} \cdot \boldsymbol{r}_{j}\right) \delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{i}\right) \exp \left(-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{i}\right)\right\rangle . \tag{7.58}
\end{align*}
$$

We make a critical assumption in (7.58) that the particle positions are statistically independent of one another. However, the particle position and its corresponding shielding cloud are correlated with one another.

THEOREM (Ergodic theorem).

$$
\begin{equation*}
\left\langle\exp \left(-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{i}\right) \exp \left(\mathrm{i} \boldsymbol{k}^{\prime} \cdot \boldsymbol{r}_{j}\right)\right\rangle=\left\langle\exp \left(-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{i}\right)\right\rangle\left\langle\exp \left(\mathrm{i} \boldsymbol{k}^{\prime} \cdot \boldsymbol{r}_{j}\right)\right\rangle=0 \tag{7.59}
\end{equation*}
$$

unless $\boldsymbol{r}_{i}=\boldsymbol{r}_{j}$.

So far the irreversibility associated with the Bogoliubov hypothesis has been buried. The goal of the analysis here is the derivation of the diffusion tensor and the kinetic equation including dynamic friction and diffusion associated with the shielded plasma fluctuations linked to the test particles. The resulting diffusion equation implies irreversibility (§6.5). To continue the derivation we consider disturbances that are turned on at $t=0$ and restrict the Fourier transforms to the positive $\omega$ half-plane. From (7.55), (7.57), (7.58) and (7.59) we obtain

$$
\begin{align*}
\langle\phi & \left.(\boldsymbol{k}, \omega) \phi^{*}\left(\boldsymbol{k}^{\prime}, \omega^{\prime}\right)\right\rangle \\
= & \sum_{i} \frac{1}{\varepsilon^{*}\left(\boldsymbol{k}^{\prime}, \omega^{\prime}\right)} \frac{1}{\varepsilon(\boldsymbol{k}, \omega)} \frac{4 \pi}{k^{2}} \frac{4 \pi}{k^{\prime 2}} e_{i}^{2}\left\langle(2 \pi)^{2} \delta\left(\omega^{\prime}-\boldsymbol{k}^{\prime} \cdot \boldsymbol{v}_{i}\right) \delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{i}\right)\right\rangle \\
& \times\left\langle\exp \left(-\mathrm{i}\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{r}_{i}\right)\right\rangle \\
= & \sum_{i} \frac{1}{\varepsilon^{*}\left(\boldsymbol{k}^{\prime}, \omega^{\prime}\right)} \frac{1}{\varepsilon(\boldsymbol{k}, \omega)} \frac{4 \pi}{k^{2}} \frac{4 \pi}{k^{\prime 2}} e_{i}^{2}\left\langle(2 \pi)^{2} \delta\left(\omega^{\prime}-\boldsymbol{k}^{\prime} \cdot \boldsymbol{v}_{i}\right) \delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{i}\right)\right\rangle \\
& \times \frac{1}{V} \int \mathrm{~d}^{3} \boldsymbol{r} \exp \left(-\mathrm{i}\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{r}_{i}\right) \\
= & \sum_{i} \frac{1}{\varepsilon^{*}\left(\boldsymbol{k}^{\prime}, \omega^{\prime}\right)} \frac{1}{\varepsilon(\boldsymbol{k}, \omega)} \frac{4 \pi}{k^{2}} \frac{4 \pi}{k^{\prime 2}} e_{i}^{2}\left\langle(2 \pi)^{2} \delta\left(\omega^{\prime}-\boldsymbol{k}^{\prime} \cdot \boldsymbol{v}_{i}\right) \delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{i}\right)\right\rangle \frac{(2 \pi)^{3}}{V} \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \\
= & \sum_{i} \frac{1}{\varepsilon^{*}\left(\boldsymbol{k}, \omega^{\prime}\right)} \frac{1}{\varepsilon(\boldsymbol{k}, \omega)}\left(\frac{4 \pi}{k^{2}}\right)^{2} e_{i}^{2}(2 \pi)^{2} \delta\left(\omega^{\prime}-\omega\right)\left\langle\delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{i}\right)\right\rangle \frac{(2 \pi)^{3}}{V} \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \\
= & \sum_{i} \frac{1}{|\varepsilon(\boldsymbol{k}, \omega)|^{2}}\left(\frac{4 \pi}{k^{2}}\right)^{2} e_{i}^{2}(2 \pi)^{2}\left\langle\delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{i}\right)\right\rangle \frac{(2 \pi)^{3}}{V} \delta\left(\omega^{\prime}-\omega\right) \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \\
= & (2 \pi)^{4} \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \delta\left(\omega-\omega^{\prime}\right) S_{\phi}(\boldsymbol{k}, \omega) . \tag{7.60}
\end{align*}
$$

Hence,

$$
\begin{align*}
S_{\phi}(\boldsymbol{k}, \omega) & =\frac{1}{|\varepsilon(\boldsymbol{k}, \omega)|^{2}}\left(\frac{4 \pi}{k^{2}}\right)^{2} \frac{2 \pi}{V} \sum_{i} e_{i}^{2}\left\langle\delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}_{i}\right)\right\rangle \\
& =\frac{1}{|\varepsilon(\boldsymbol{k}, \omega)|^{2}}\left(\frac{4 \pi}{k^{2}}\right)^{2} 2 \pi \sum_{s} n_{s} e_{s}^{2} \int \mathrm{~d}^{3} \boldsymbol{v} g_{s}(\boldsymbol{v}) \delta(\omega-\boldsymbol{k} \cdot \boldsymbol{v}) \\
& =\sum_{s} n_{s}\left|\frac{4 \pi e_{s}}{k^{2} \varepsilon(\boldsymbol{k}, \omega)}\right|^{2} \int \mathrm{~d}^{3} \boldsymbol{v} g_{s}(\boldsymbol{v}) 2 \pi \delta(\omega-\boldsymbol{k} \cdot \boldsymbol{v}) \tag{7.61}
\end{align*}
$$

If there is no shielding, i.e. no polarization correlation, then $\varepsilon=1$ in (7.61).
We recall the expression for the velocity-space diffusion equation (7.50) which we can relate to the analysis in (7.51)-(7.61),

$$
\begin{aligned}
\boldsymbol{D}(\boldsymbol{v}) & =\left(\frac{e}{m}\right)^{2} \int_{0}^{\infty} \mathrm{d} \tau\left\langle\boldsymbol{E}\left(\boldsymbol{r}^{t}, t\right) \boldsymbol{E}\left(\boldsymbol{r}^{t-\tau}, t-\tau\right)\right\rangle_{\boldsymbol{r}^{t}, t}=\left(\frac{e}{m}\right)^{2} \int_{0}^{\infty} \mathrm{d} \tau\left\langle C_{\boldsymbol{E}}\left(\boldsymbol{r}^{t}-\boldsymbol{r}^{t-\tau}, \tau\right)\right\rangle_{\boldsymbol{r}^{t}, t} \\
& =\left(\frac{e}{m}\right)^{2} \int_{0}^{\infty} \mathrm{d} \tau\left\langle C_{\boldsymbol{E}}(\boldsymbol{s}(\tau)=\boldsymbol{v} \tau, \tau)\right\rangle_{\boldsymbol{r}^{t}, t} \\
& =\left(\frac{e}{m}\right)^{2} \int_{0}^{\infty} \mathrm{d} \tau \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d} \omega}{2 \pi} \exp (\mathrm{i}(\boldsymbol{k} \cdot \boldsymbol{s}-\omega \tau)) \boldsymbol{k} \boldsymbol{k} S_{\phi}(k, \omega)
\end{aligned}
$$

$$
\begin{align*}
& =\left(\frac{e}{m}\right)^{2} \int_{0}^{\infty} \mathrm{d} \tau \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d} \omega}{2 \pi} \exp (\mathrm{i}(\boldsymbol{k} \cdot \boldsymbol{v}-\omega) \tau) \boldsymbol{k} \boldsymbol{k} S_{\phi}(k, \omega) \\
& =\left(\frac{e}{m}\right)^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d} \omega}{2 \pi} \boldsymbol{k} \boldsymbol{k} S_{\phi}(k, \omega)\left(\pi \delta(\boldsymbol{k} \cdot \boldsymbol{v}-\omega)+\frac{\mathrm{i}}{\boldsymbol{k} \cdot \boldsymbol{v}-\omega}\right) \\
& \rightarrow\left(\frac{e}{m}\right)^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d} \omega}{2 \pi} \boldsymbol{k} \boldsymbol{k} \boldsymbol{S}_{\phi}(k, \omega) \pi \delta(\boldsymbol{k} \cdot \boldsymbol{v}-\omega) \tag{7.62}
\end{align*}
$$

owing to the symmetries of the integrals and integrand in (7.62). We note that the field fluctuations arise from the test particles satisfying the resonance $\omega=\boldsymbol{k} \cdot \boldsymbol{v}^{\prime}$, and the fluctuations then interact with the other particles satisfying the resonance $\omega=\boldsymbol{k} \cdot \boldsymbol{v}$. Hence, $\boldsymbol{k} \cdot\left(\boldsymbol{v}-\boldsymbol{v}^{\prime}\right)=0$. Given that the spectral density in (7.61) is additive over species, so also is the diffusion tensor, which we rewrite for the diffusion of the momenta in terms of the un-normalized distribution function $f_{s}$,

$$
\begin{align*}
\boldsymbol{D}_{s}^{s^{\prime}}(\boldsymbol{p}) & =e_{s}^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d} \omega}{2 \pi} S_{\phi}^{s^{\prime}}(k, \omega) \boldsymbol{k} \boldsymbol{k} \pi \delta(\boldsymbol{k} \cdot \boldsymbol{v}-\omega) \\
& =\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}}\left|\frac{4 \pi e_{s} e_{s}^{\prime}}{k^{2} \varepsilon(\boldsymbol{k}, \omega)}\right|^{2} \int \mathrm{~d}^{3} \boldsymbol{p}^{\prime} \pi \delta\left(\boldsymbol{k} \cdot \boldsymbol{v}-\boldsymbol{k} \cdot \boldsymbol{v}^{\prime}\right) \boldsymbol{k} \boldsymbol{k} f_{s^{\prime}}\left(p^{\prime}\right) \tag{7.63}
\end{align*}
$$

Only the $1 /|\varepsilon|^{2}$ evidences the plasma shielding. We also note that $S_{\phi}$ and $\boldsymbol{D}$ diverge at large $k$ where linear theory breaks down.

### 7.2.3. Derivation of the Lenard-Balescu equation

In this section we derive the extension of the Vlasov equation to a collisional kinetic equation that includes both dynamic friction and velocity-space diffusion. We recall the expression for the dynamic friction

$$
\begin{equation*}
\boldsymbol{F}_{s}(\boldsymbol{v})=e_{s}^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{2}} \frac{4 \pi}{k^{2}} \boldsymbol{k} \operatorname{Im} \varepsilon^{-1}(\boldsymbol{k}, \boldsymbol{k} \cdot \boldsymbol{v})=-e_{s}^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{2}} \frac{4 \pi}{k^{2}} \boldsymbol{k} \frac{\operatorname{Im} \varepsilon}{|\varepsilon|^{2}}, \tag{7.64}
\end{equation*}
$$

and we can sum over species assuming that the dynamic friction is simply additive in the other particle species. We can express the dynamic friction in terms of the momentum and evaluate the imaginary part of the dielectric response in terms of the species distribution functions as follows:

$$
\begin{equation*}
\boldsymbol{F}_{s}^{s^{\prime}}(\boldsymbol{p})=\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}}\left|\frac{4 \pi e_{s} e_{s^{\prime}}}{k^{2} \varepsilon(\boldsymbol{k}, \boldsymbol{k} \cdot \boldsymbol{v})}\right|^{2} \int \mathrm{~d}^{3} \boldsymbol{p}^{\prime} \pi \delta\left(\boldsymbol{k} \cdot \boldsymbol{v}-\boldsymbol{k} \cdot \boldsymbol{v}^{\prime}\right) \boldsymbol{k} \boldsymbol{k} \cdot \frac{\partial}{\partial \boldsymbol{p}^{\prime}} f_{s^{\prime}}\left(\boldsymbol{p}^{\prime}\right) \tag{7.65}
\end{equation*}
$$

We now return to the Vlasov equation including friction equation (7.65) and diffusion equation (7.63) terms on the right-hand side.

Theorem. The Lenard-Balescu equation is

$$
\left.\begin{array}{c}
\frac{\mathrm{d}}{\mathrm{~d} t} f_{s}(\boldsymbol{p} ; t)=-\frac{\partial}{\partial \boldsymbol{p}} \cdot\left(\boldsymbol{F}_{s}(\boldsymbol{p}) f_{s}\right)+\frac{\partial}{\partial \boldsymbol{p}} \cdot\left(\boldsymbol{D}_{s}(\boldsymbol{p}) \cdot \frac{\partial}{\partial \boldsymbol{p}} f_{s}\right)=-\frac{\partial}{\partial \boldsymbol{p}} \cdot \boldsymbol{J}_{s}(\boldsymbol{p}), \\
\boldsymbol{F}_{s} \equiv \sum_{s^{\prime}} \boldsymbol{F}_{s}^{s^{\prime}}, \quad \boldsymbol{D}_{s} \equiv \sum_{s^{\prime}} \boldsymbol{D}_{s}^{s^{\prime}} \tag{7.66}
\end{array}\right\}
$$

Definition. $\boldsymbol{J}_{s}$ is defined as a flux density in momentum space,

$$
\begin{equation*}
\boldsymbol{J}_{s}(\boldsymbol{p}) \equiv \boldsymbol{F}_{s}(\boldsymbol{p}) f_{s}-\boldsymbol{D}_{s}(\boldsymbol{p}) \cdot \frac{\partial}{\partial \boldsymbol{p}} f_{s} \tag{7.67}
\end{equation*}
$$

The second term on the right-hand side of (7.67) is Fick's law in momentum space.

Theorem. From (7.63) to (7.67) one derives

$$
\begin{align*}
\boldsymbol{J}_{s}^{s^{\prime}}(\boldsymbol{p}) & =\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}}\left|\frac{4 \pi e_{s} e_{s^{\prime}}}{k^{2} \varepsilon(\boldsymbol{k}, \boldsymbol{k} \cdot \boldsymbol{v})}\right|^{2} \int \mathrm{~d}^{3} \boldsymbol{p}^{\prime} \pi \delta\left(\boldsymbol{k} \cdot \boldsymbol{v}-\boldsymbol{k} \cdot \boldsymbol{v}^{\prime}\right) \boldsymbol{k} \boldsymbol{k} \cdot\left(\frac{\partial}{\partial \boldsymbol{p}^{\prime}}-\frac{\partial}{\partial \boldsymbol{p}}\right) f_{s}(\boldsymbol{p}) f_{s^{\prime}}\left(\boldsymbol{p}^{\prime}\right) \\
& \equiv \int \mathrm{d}^{3} \boldsymbol{p}^{\prime} \boldsymbol{Q}_{s s^{\prime}}\left(\boldsymbol{v}, \boldsymbol{v}^{\prime}\right) \cdot\left(\frac{\partial}{\partial \boldsymbol{p}^{\prime}}-\frac{\partial}{\partial \boldsymbol{p}^{\prime}}\right) f_{s}(\boldsymbol{p}) f_{s^{\prime}}\left(\boldsymbol{p}^{\prime}\right) \tag{7.68}
\end{align*}
$$

where

$$
\begin{equation*}
\boldsymbol{Q}_{s s^{\prime}}\left(\boldsymbol{v}, \boldsymbol{v}^{\prime}\right) \equiv \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \boldsymbol{k} \boldsymbol{k}\left(\frac{4 \pi e_{s} e_{s^{\prime}}}{k^{2}}\right)^{2} \int \frac{\mathrm{~d} \omega}{2 \pi}(2 \pi)^{2} \frac{\delta(\omega-\boldsymbol{k} \cdot \boldsymbol{v}) \delta\left(\omega-\boldsymbol{k} \cdot \boldsymbol{v}^{\prime}\right)}{|\varepsilon(\boldsymbol{k}, \omega)|^{2}} \tag{7.69}
\end{equation*}
$$

and the collisional flux on the right-hand side of (7.68) is in the Landau form (Landau 1937). We note that $\boldsymbol{Q}_{s s^{\prime}}$ is symmetric in $\boldsymbol{v}$ and $\boldsymbol{v}^{\prime}$ owing to the symmetry of the effective force between two particles, and is also symmetric in species $s$ and $s^{\prime}$. However, the difference in momentum derivatives in (7.68) does not identically vanish.

We return to the analysis leading to (7.60) and (7.61) to provide some additional details. Consider the auto-correlation function for the electric field used in the diffusion tensor in (7.62),

$$
\begin{equation*}
\left\langle\boldsymbol{E}\left(\boldsymbol{r}^{t}, t\right) \boldsymbol{E}\left(\boldsymbol{r}^{t-\tau}, t-\tau\right)\right\rangle=\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d} \omega}{2 \pi} \exp (\mathrm{i}(\boldsymbol{k} \cdot \boldsymbol{s}-\omega \tau)) \boldsymbol{k} \boldsymbol{k} S_{\phi}(k, \omega) \tag{7.70}
\end{equation*}
$$

From (7.70) it follows that

$$
\left.\begin{array}{c}
\left\langle\boldsymbol{E}\left(\boldsymbol{r}^{t}, t\right)^{2}\right\rangle_{\boldsymbol{r}, t}=\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d} \omega}{2 \pi} \boldsymbol{k} \boldsymbol{k} S_{\phi}(\boldsymbol{k}, \omega) \equiv \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \boldsymbol{k} \boldsymbol{k} S_{\phi}(\boldsymbol{k})  \tag{7.71}\\
S_{\phi}(\boldsymbol{k}, \omega)=\frac{1}{|\varepsilon(\boldsymbol{k}, \omega)|^{2}}\left(\frac{4 \pi}{k^{2}}\right)^{2} 2 \pi \sum_{s} e_{s}^{2} \int \mathrm{~d}^{3} v f_{s}(\boldsymbol{v}) \delta(\omega-\boldsymbol{k} \cdot \boldsymbol{v})
\end{array}\right\}
$$

Let us discuss the behaviour of $S_{\phi}$. We note that $|\varepsilon|^{2}=\varepsilon_{R}(\boldsymbol{k}, \omega)^{2}+\varepsilon_{I}(\boldsymbol{k}, \omega)^{2}$. For $k>k_{D}$, the linear normal modes are not weakly damped in general, and $\varepsilon=1+O\left(1 / k^{2} \lambda_{D}^{2}\right)$. For $k<k_{D}$, there are weakly damped, linear normal modes such that $\varepsilon_{R}\left(\boldsymbol{k}, \omega_{k}\right) \approx$ $0, \varepsilon_{I}\left(\boldsymbol{k}, \omega_{k}\right)$ is small; and the growth rate or damping rate is deduced from $\gamma_{k}=$ $-\varepsilon_{I} / \partial \varepsilon_{R} / \partial \omega$. However, these formulae are only good for a stable plasma, so $\gamma_{k} \leqslant 0$. In general,

$$
|\varepsilon|^{2}=\left[\varepsilon_{R}(\boldsymbol{k}, \omega)+\left.\left(\omega-\omega_{k}\right) \frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}}+\cdots\right]^{2}+\left.\gamma_{k}^{2}\left|\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}}\right|^{2}
$$

$$
\begin{align*}
& \left.\approx\left|\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}}\right|^{2}\left(\left(\omega-\omega_{k}\right)^{2}+\gamma_{k}^{2}\right) \rightarrow \frac{1}{|\varepsilon|^{2}} \\
& \approx \frac{1}{\left.\left|\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}}\right|^{2}\left(\left(\omega-\omega_{k}\right)^{2}+\gamma_{k}^{2}\right)} \tag{7.72}
\end{align*}
$$

For velocity distributions that are Gaussian we can sketch $S_{\phi}$ based on (7.71) and (7.72), and the foregoing discussion. For $k>k_{D}, S_{\phi}(\omega)$ versus $\omega$ for fixed $k$ is approximately a Gaussian centred at $\omega=0$. For $k<k_{D}, S_{\phi}(\omega)$ versus $\omega$ for fixed $k$ is approximately a Gaussian centred at $\omega=0$ for small $\omega$ with Lorentzian peaks at $\pm \omega_{k}$, and the width of the peaks scales as $\gamma_{k}$.

From (7.71) and (7.72) we can derive

$$
\begin{align*}
S_{\phi}(\boldsymbol{k}) & =\int \frac{\mathrm{d} \omega}{2 \pi} S_{\phi}(\boldsymbol{k}, \omega) \approx \int \frac{\mathrm{d} \omega}{2 \pi} \frac{1}{|\varepsilon(\boldsymbol{k}, \omega)|^{2}}\left(\frac{4 \pi}{k^{2}}\right)^{2} 2 \pi \sum_{s} e_{s}^{2} \int \mathrm{~d}^{3} \boldsymbol{v} f_{s}(\boldsymbol{v}) \delta\left(\omega_{\boldsymbol{k}}-\boldsymbol{k} \cdot \boldsymbol{v}\right) \\
& =\frac{\pi}{\left|\gamma_{k}\right|} \frac{1}{\left(\left.\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}}\right)^{2}}\left(\frac{4 \pi}{k^{2}}\right)^{2} \sum_{s} e_{s}^{2} \int \mathrm{~d}^{3} \boldsymbol{v} f_{s}(\boldsymbol{v}) \delta\left(\omega_{\boldsymbol{k}}-\boldsymbol{k} \cdot \boldsymbol{v}\right) \tag{7.73}
\end{align*}
$$

With the use of (7.71) and (7.73) we can evaluate the wave energy and its time derivative. Recall that

$$
\left.\begin{array}{l}
W(\boldsymbol{k})=\frac{\omega_{k}^{\ell}}{4 \pi} \frac{\partial \varepsilon_{R}}{\partial \omega} k^{2} S_{\phi}(\boldsymbol{k})  \tag{7.74}\\
-\frac{4 \pi}{k^{2}} \frac{\left|\omega_{k}^{\ell}\right|}{\left|\frac{\partial \varepsilon_{R}}{\partial \omega}\right|_{\omega_{k}^{\ell}} \sum_{s} e_{s}^{2} \int \mathrm{~d}^{3} v 2 \pi \delta\left(\omega_{k}^{\ell}-\boldsymbol{k} \cdot \boldsymbol{v}\right) n_{s} g_{s}(\boldsymbol{v}) .}
\end{array}\right\}
$$

The correlation energy density is the electric field energy density minus the electric field energy of the vacuum $(\varepsilon=1)$, which scales as $n T / \Lambda$ times a number. Thus, the Vlasov approximation is very good if $\Lambda \gg 1$ because particle-particle correlations can be ignored. However, we note that as $\gamma_{k} \rightarrow 0$ from below ( $\gamma_{k}<0$ ), correlations become very important; and the approximations in our derivations break down.

### 7.2.4. Consideration of large-angle collisions and the Landau equation

We now focus on large-angle collisions, which correspond to $k>k_{D}$. We ignore $k<k_{D}$ in

$$
\begin{equation*}
\boldsymbol{D}_{s}^{s^{\prime}}(\boldsymbol{p})=\int \mathrm{d}^{3} \boldsymbol{p}^{\prime} f_{s^{\prime}}\left(\boldsymbol{p}^{\prime}\right) \boldsymbol{Q}_{s s^{\prime}}\left(\boldsymbol{v}, \boldsymbol{v}^{\prime}\right) \tag{7.75}
\end{equation*}
$$

where

$$
\begin{equation*}
\boldsymbol{Q}_{s s^{\prime}}\left(\boldsymbol{v}, \boldsymbol{v}^{\prime}\right) \equiv \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \boldsymbol{k} \boldsymbol{k}\left(\frac{4 \pi e_{s} e_{s^{\prime}}}{k^{2} \varepsilon(\boldsymbol{k}, \boldsymbol{k} \cdot \boldsymbol{v})}\right)^{2} \pi \delta(\boldsymbol{k} \cdot \boldsymbol{w}), \quad \boldsymbol{w} \equiv \boldsymbol{v}-\boldsymbol{v}^{\prime} \tag{7.76}
\end{equation*}
$$

For $k>k_{D} \epsilon \rightarrow 1$, and we integrate the right-hand side of (7.76) from $k_{D}$ to $k_{\max }$,

$$
\begin{equation*}
\boldsymbol{Q}_{s s^{\prime}}\left(\boldsymbol{v}, \boldsymbol{v}^{\prime}\right) \equiv 2\left(e_{s} e_{s^{\prime}}\right)^{2} \int \mathrm{~d}^{3} \boldsymbol{k} \frac{\boldsymbol{k} \boldsymbol{k}}{k^{4}} \delta(\boldsymbol{k} \cdot \boldsymbol{w}) \tag{7.77}
\end{equation*}
$$

We note that $\boldsymbol{w} \cdot \boldsymbol{Q}=0$ and $\delta\left(k_{\|} w\right)=\delta\left(k_{\|}\right) / w$ where $k_{\|}$is parallel to $\boldsymbol{w}$. Thus, we can express $\boldsymbol{Q}(\boldsymbol{w})=Q(\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{w}} \hat{\boldsymbol{w}})$ and $\operatorname{Tr} \boldsymbol{Q}(\boldsymbol{w})=2 \mathrm{Q}(w)$. Given this representation of $\boldsymbol{Q}(\boldsymbol{w})$ we can evaluate equation (7.77)

$$
\left.\begin{array}{c}
\boldsymbol{Q}(\boldsymbol{w})=Q(w)(\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{w}} \hat{\boldsymbol{w}})  \tag{7.78}\\
Q \approx \frac{1}{2} 2 e_{s}^{2} e_{s^{\prime}}^{2} \int \mathrm{~d} k_{\|} 2 \pi k_{\perp} \mathrm{d} k_{\perp} \frac{1}{k_{\perp}^{2}+k_{\|}^{2}} \frac{\delta\left(k_{\|}\right)}{w} \rightarrow \frac{2 \pi e_{s}^{2} e_{s^{\prime}}^{2}}{w} \int_{k_{D}}^{k_{\max }} \frac{\mathrm{d} k_{\perp}}{k_{\perp}} \\
=\frac{2 \pi e_{s}^{2} e_{s^{\prime}}^{2}}{w} \ln \frac{k_{\max }}{k_{D}}=\frac{2 \pi e_{s}^{2} e_{s^{\prime}}^{2}}{w} \ln \Lambda .
\end{array}\right\}
$$

Note: the following identity is useful in dealing with the tensor $\boldsymbol{Q}(\boldsymbol{w})=Q(\overleftrightarrow{\boldsymbol{I}}-\hat{\boldsymbol{w}} \hat{\boldsymbol{w}})$,

$$
\begin{equation*}
\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{w}} \hat{\boldsymbol{w}}=w \frac{\partial}{\partial \boldsymbol{w}} \frac{\partial}{\partial \boldsymbol{w}}|\boldsymbol{w}| \tag{7.79}
\end{equation*}
$$

Given $\boldsymbol{Q}$ we can evaluate $\boldsymbol{D}$ in (7.75) and the dynamic friction

$$
\begin{equation*}
\boldsymbol{F}_{s}^{s^{\prime}}(\boldsymbol{p})=\int \mathrm{d}^{3} \boldsymbol{p}^{\prime} \boldsymbol{Q}_{s s^{\prime}}\left(\boldsymbol{v}, \boldsymbol{v}^{\prime}\right) \cdot \frac{\partial}{\partial \boldsymbol{p}^{\prime}} f_{s}\left(\boldsymbol{p}^{\prime}\right) \tag{7.80}
\end{equation*}
$$

If the scatterers are isotropic, i.e. if $f_{s^{\prime}}$ is isotropic, then $\boldsymbol{D}$ only depends on the vector information in $\boldsymbol{p}: \boldsymbol{D}=D_{1}(v) \boldsymbol{I}+D_{2}(v) \hat{\boldsymbol{v}} \hat{\boldsymbol{v}}$. We take traces and work with scalar equations.

Theorem. For $f_{s^{\prime}}$ a Maxwellian then (7.75) yields

$$
\begin{equation*}
\boldsymbol{D}^{s^{\prime}}=\frac{\sqrt{2} \pi n_{s^{\prime}} e_{s}^{2} e_{s^{\prime}} \ln \Lambda}{v_{s^{\prime}}}\left[\frac{\operatorname{erf}(x)}{x}(\boldsymbol{I}-\hat{\boldsymbol{v}} \hat{\boldsymbol{v}})+\frac{1}{2 x} \frac{\mathrm{~d}}{\mathrm{~d} x}\left(\frac{\operatorname{erf}(x)}{x}\right)(\boldsymbol{I}-3 \hat{\boldsymbol{v}} \hat{\boldsymbol{v}})\right], \tag{7.81}
\end{equation*}
$$

where $x \equiv v / \sqrt{2} v_{s^{\prime}}, v_{s^{\prime}} \equiv \sqrt{T_{s^{\prime}} / m_{s^{\prime}}}$ and

$$
\begin{align*}
\operatorname{erf}(x) \equiv \frac{2}{\sqrt{\pi}} \int_{0}^{x} \mathrm{~d} t \mathrm{e}^{-t^{2}} & \rightarrow \frac{2}{\sqrt{\pi}}\left(x-\frac{x^{3}}{3}+\cdots\right) \quad \text { for } x \ll 1 \\
& \rightarrow 1-\frac{\mathrm{e}^{-x}}{\sqrt{\pi} x}(1+\cdots) \quad \text { for } x \gg 1 \tag{7.82}
\end{align*}
$$

(use tables for the error function at intermediate values of $x$ ). The dynamic friction equation (7.80) becomes

$$
\begin{equation*}
\boldsymbol{F}^{s^{\prime}}(\boldsymbol{p})=\hat{\boldsymbol{v}} \frac{e_{s}^{2} \ln \Lambda}{2 \lambda_{s^{\prime}}^{2}} \frac{\mathrm{~d}}{\mathrm{~d} x}\left(\frac{\operatorname{erf}(x)}{x}\right), \quad \lambda_{s^{\prime}}^{2}=\frac{T_{s^{\prime}}}{4 \pi n_{s^{\prime}} e_{s^{\prime}}^{2}} \tag{7.83}
\end{equation*}
$$

We summarize the asymptotic forms for the diffusion tensor,
(i)

$$
\begin{equation*}
v \ll v_{s} \quad \boldsymbol{D}^{s^{\prime}}=\frac{8}{3} \sqrt{\frac{\pi}{2}} \frac{n_{s^{\prime}} e_{s}^{2} e_{s^{\prime}}^{2} \ln \Lambda}{v_{s}^{\prime}} \boldsymbol{I} \quad \text { velocity independent and isotropic. } \tag{7.84}
\end{equation*}
$$

For $s^{\prime}=$ electrons $\boldsymbol{D}^{s^{\prime}}=\left(m_{e} v_{e}\right)^{2} v_{e} \boldsymbol{I}$.
(ii)

$$
\left.\begin{array}{c}
v \gg v_{s}, \quad x \rightarrow \infty, \quad \boldsymbol{w}=\boldsymbol{v}-\boldsymbol{v}^{\prime} \approx \boldsymbol{v} \quad \text { in } \boldsymbol{Q}  \tag{7.85}\\
\boldsymbol{D}^{s^{\prime}} \rightarrow n_{s^{\prime}} \boldsymbol{Q}(\boldsymbol{v})=n_{s^{\prime}} \frac{2 \pi e_{s}^{2} e_{s^{\prime}}^{2} \ln \Lambda}{v}(\boldsymbol{I}-\hat{\boldsymbol{v}} \hat{\boldsymbol{v}}) .
\end{array}\right\}
$$

The faster the particle, the weaker is the diffusion.
EXERCISE. Fill in the intermediate steps in the derivations of (7.81), (7.84) and (7.85).

These simplified asymptotic forms (7.80)-(7.85) for the dynamic friction and diffusion derived in the large- $k$ approximation (large-angle scattering) transform the Lenard-Balescu to the Landau equation. The Lenard-Balescu equation in §7.2.3 is good up to some $k_{\max }$ with a $\sim 10 \%$ error by ignoring large-angle collisions. In the Landau equation derivation there is no $1 /|\epsilon|^{2}$ and $\boldsymbol{Q}$ is given in (7.78). Equations (7.66)-(7.68) still describe the collisional kinetic equation. Using (7.79), (7.75) and (7.78) we obtain the following alternative form for $\boldsymbol{D}$ in the Landau limit:

$$
\begin{align*}
\boldsymbol{D}_{s}^{s^{\prime}}(\boldsymbol{p}) & =\int \mathrm{d}^{3} \boldsymbol{p}^{\prime} f_{s^{\prime}}\left(\boldsymbol{p}^{\prime}\right) \boldsymbol{Q}_{s s^{\prime}}\left(\boldsymbol{v}, \boldsymbol{v}^{\prime}\right)=2 \pi e_{s}^{2} e_{s^{\prime}}^{2} \ln \Lambda \int \mathrm{~d}^{3} \boldsymbol{p}^{\prime} f_{s^{\prime}}\left(\boldsymbol{p}^{\prime}\right) \frac{\partial^{2}}{\partial \boldsymbol{v} \partial \boldsymbol{v}}\left|\boldsymbol{v}-\boldsymbol{v}^{\prime}\right| \\
& =2 \pi e_{s}^{2} e_{s^{\prime}}^{2} \ln \Lambda \frac{\partial^{2}}{\partial \boldsymbol{v} \partial \boldsymbol{v}} \int \mathrm{~d}^{3} \boldsymbol{p}^{\prime} f_{s^{\prime}}\left(\boldsymbol{p}^{\prime}\right)\left|\boldsymbol{v}-\boldsymbol{v}^{\prime}\right| \tag{7.86}
\end{align*}
$$

### 7.2.5. Derivation of the Fokker-Planck equation from the Landau equation and model for Brownian motion

For electron speeds $v \ll v_{e}$ the electron diffusion tensor was given in (7.84), $\boldsymbol{D}^{e}=$ $\left(m_{e} v_{e}\right)^{2} v_{e} I$; and the dynamic friction of electrons on electrons for $v \ll v_{e}$ is given by $\boldsymbol{F}^{e}=-m_{e} v_{e} \boldsymbol{v}_{e}$. The corresponding Fokker-Planck equation is then

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} f_{e}=-\frac{\partial}{\partial \boldsymbol{p}} \cdot\left(\boldsymbol{F}(\boldsymbol{p}) f_{e}\right)+\frac{\partial}{\partial \boldsymbol{p}} \cdot\left(\boldsymbol{D}(\boldsymbol{p}) \cdot \frac{\partial}{\partial \boldsymbol{p}} f_{e}\right) . \tag{7.87}
\end{equation*}
$$

This model for Brownian motion of electrons assumes that the asymptotic forms are good for all cases. This permits analytic solution of the Fokker-Planck equation in closed form.

THEOREM (Brownian motion model).

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} f_{e}=m v_{e} \frac{\partial}{\partial \boldsymbol{p}} \cdot\left(\boldsymbol{v} f_{e}+T_{e} \frac{\partial}{\partial \boldsymbol{p}} f_{e}\right) \tag{7.88}
\end{equation*}
$$

If $f_{e} \sim \exp \left(-p^{2} / 2 m_{e} T_{e}\right)$ then $\mathrm{d} f_{e} / \mathrm{d} t=0$, i.e. the collisions preserve a Maxwellian.

### 7.2.6. Bhatnagar-Gross-Krook model - simplest collision model that conserves particles, momentum and energy

The simplest collision operator that conserves particles, momentum and energy was introduced by Bhatnagar, Gross, \& Krook (1954)

$$
\begin{equation*}
\left(\frac{\partial}{\partial t} f\right)_{c}=-v\left(f-f_{0}\right) \tag{7.89}
\end{equation*}
$$

The simplicity of the BGK collision model lends itself to quickly obtaining some general idea as to the influence of collisional relaxation on the velocity distribution. However, it omits all velocity dependence of the collision frequency and large-angle scattering. It also cannot treat delicate things like the effect of collisions on resonant phenomena.
7.2.7. Generalizations and applications of plasma collision theory, e.g. fast processes
involving waves, slow processes, resonance broadening due to collisions

In this section we touch on a collection of topics associated with collision theory. For some topics only a brief commentary is given, and for others there is significant analysis.
(i) Collision theory in a magnetized plasma.

Norman Rostoker published a treatment of collisions in a plasma with a constant applied magnetic field in 1960 (Rostoker 1960). Consider a Landau collision model for electrons with impact parameter $b$ and Larmor radius $r_{g}$ less than the Debye length $\lambda_{D}$. If the impact parameter $b$ exceeds the Debye length, then the collision is shielded and the electron does not experience a collisional Coulomb force. If the magnetic field is strong and $r_{g}$ is less than the impact parameter, the electron stays on its field line and does not undergo the collision. Only if $b<r_{g}$ can a collision take place. Hence, we can take $\max (b) \rightarrow r_{g}$ and $\ln \Lambda=\ln \lambda_{D} / r_{o} \rightarrow \ln r_{g} / r_{o}$ where $r_{o} \equiv e^{2} / T$ instead of using Rostoker's formulae. If $r_{g}>\lambda_{D}$ the magnetic field is weak; so weak that with respect to collision theory, it is as if there is no magnetic field at all, in which case there are no changes in the collision theory from the unmagnetized case. However, if there are shielding effects included, e.g. as in (7.76), the dielectric function is modified in the presence of the magnetic field.
(ii) Collisions including electromagnetic effects.

When discrete charged particles interact, the most general treatment is based on Maxwell's equations (Jackson 1999). For short-range collisions ( $b<\lambda_{D}$ ), an electromagnetic treatment is needed instead of electrostatic. However, if the plasma is non-relativistic, the electromagnetic corrections to the electrostatic collision theory are small in $v^{2} / c^{2}$; and the electromagnetic corrections are insignificant. Electromagnetic effects are significant for charged-particle collisions in a relativistic plasma, e.g. consider bremsstrahlung. Theory based on Lienard Wiechert potentials is commonly employed, and the collision of two charged particles is sometimes described in terms of photon exchange. In any case, the hotter the plasma the weaker the collisional effects; and collisions in a relativistically hot plasma may not be important in many contexts.
(iii) Large-angle scattering.

In the foregoing we have developed collision theories for small- and large-angle scattering. The Lenard-Balescu theory is valid for larger impact parameters $b>r_{o}$. The Lenard-Balescu theory is accurate to approximately $10 \%$. For $r_{\mathrm{o}}<b<\lambda_{D}$ the Landau collision operator is useful and is accurate to approximately $15 \%$. A Boltzmann collision model ignoring plasma shielding effects is appropriate for $b<\lambda_{D}$ absent quantum mechanical effects. Figure 35 diagrams the regimes for the three classical collision theories.

The region of overlap and the ranges of applicability invite the following practical recipe:

$$
\begin{equation*}
\left(\frac{\partial}{\partial t} f\right)_{c}=\left(\frac{\partial}{\partial t} f\right)_{\text {Len-Bal }}+\left(\frac{\partial}{\partial t} f\right)_{\text {Boltz }}-\left(\frac{\partial}{\partial t} f\right)_{\text {Landau }} \tag{7.90}
\end{equation*}
$$



Figure 35. Diagram of ranges in collisional impact parameter $b$ for classical collision theories in plasmas.

The Lenard-Balescu theory cancels with either the Boltzmann or the Landau theories in the intermediate zone where the theories overlap.
(iv) Quantum mechanical effects.

For $b \leqslant \lambda_{\mathrm{dB}} \equiv \hbar / \mu v$ quantum mechanical effects affect the collisions. When $T>1$ Rydberg $=13.6 \mathrm{eV}$, then $\lambda_{\mathrm{dB}}>e^{2} / T$. This parameter regime is very important in astrophysics. Consideration of quantum mechanical effects on collisions in plasmas is beyond the scope of these lectures. Some of the researchers who have worked in this area are DeWitt, Gould, Lampe and Del Rio (Gould \& Dewitt 1967; Lampe 1968; Del Rio \& Dewitt 1969).
(v) Applications - slow processes involving collisions.

If the electron velocity distribution has finite temperature but is a non-Maxwellian, then electron-electron collisions will relax the velocity distribution toward a Maxwellian on a time scale $\tau_{\text {Maxw }}^{e} \sim 1 / v_{e}$. Similarly, a non-Maxwellian ion velocity distribution will be relaxed by ion-ion collisions on a time scale $\tau_{\text {Maxw }}^{i} \sim 1 / \nu_{i}$. For singly charged ions, $v_{i}$ is $v_{e}$ with $m_{e} \rightarrow m_{i}$ and $T_{e} \rightarrow T_{i}$. We note that the characteristic frequencies or rates fundamentally scale as $v \sim n \sigma v$, where $n$ is the number density of field particles, $\sigma \sim\left(e^{2} / T\right)^{2}$ is the Coulomb cross-section, and $v$ is the relative speed $v \sim \sqrt{T / m}$. Electron collision frequencies are generally faster than ion collision frequencies due to the $1 / \sqrt{m}$ scaling.

When there are two charged species present with different temperatures, collisions will relax the two velocity distributions to have a common temperature. Among collisional relaxation processes, temperature relaxation is very slow. Consider ions and electrons with Maxwellian velocity distributions such that initially $T_{e}>T_{i}$. Electrons will cool, and ions will heat. The kinetic equation for the ions (assumed singly charged, so $n_{e}=n_{i}=n$ ) is

$$
\begin{aligned}
\frac{\partial f^{i}(\boldsymbol{p} ; t)}{\partial t} & =-\frac{\partial}{\partial \boldsymbol{p}} \cdot \boldsymbol{J}_{i}^{e}(\boldsymbol{p} ; t), \quad \text { where } f^{i}(\boldsymbol{p} ; t)=\text { const. exp }\left(-\frac{p^{2}}{2 m_{i} T_{i}(t)}\right) \\
& \rightarrow \int \mathrm{d}^{3} \boldsymbol{p} \frac{p^{2}}{2 m_{i}} \frac{\partial f^{i}(\boldsymbol{p} ; t)}{\partial t}=\frac{\partial}{\partial t}\left[n \frac{3}{2} T_{i}(t)\right] \\
& =-\int \mathrm{d}^{3} \boldsymbol{p} \frac{p^{2}}{2 m_{i}} \frac{\partial}{\partial \boldsymbol{p}} \cdot \boldsymbol{J}_{i}^{e}(\boldsymbol{p} ; t)=\int \mathrm{d}^{3} \boldsymbol{p} \boldsymbol{v} \cdot \boldsymbol{J}_{i}^{e}(\boldsymbol{p} ; t) \\
& =\int \mathrm{d}^{3} \boldsymbol{p} \boldsymbol{v} \cdot\left[\boldsymbol{F}_{i}^{e} f_{i}-\boldsymbol{D}_{i}^{e}(\boldsymbol{p}) \cdot \frac{\partial f_{i}}{\partial \boldsymbol{p}}\right]
\end{aligned}
$$

$$
\begin{align*}
& =-m_{e} v_{e} \int \mathrm{~d}^{3} \boldsymbol{p} v^{2} f_{i}+m_{e} v_{e} \frac{T_{e}}{T_{i}} \int \mathrm{~d}^{3} \boldsymbol{p} v^{2} f_{i} \\
& =3 \frac{m_{e}}{m_{i}} v_{e} n\left(T_{e}-T_{i}\right) \rightarrow \frac{\mathrm{d} T_{i}}{\mathrm{~d} t}=2 \frac{m_{e}}{m_{i}} v_{e}\left(T_{e}-T_{i}\right) \tag{7.91}
\end{align*}
$$

Equation (7.91) describes the temperature relaxation process. The integration of (7.91) for small temperature differences so that the dependence of $v_{e}$ on temperature is frozen yields

$$
\begin{align*}
\frac{\mathrm{d} T_{i}}{\mathrm{~d} t} & =2 \frac{m_{e}}{m_{i}} v_{e}\left(T_{e}-T_{i}\right)=-\frac{\mathrm{d} T_{e}}{\mathrm{~d} t} \rightarrow \frac{\mathrm{~d}\left(T_{e}-T_{i}\right)}{T_{e}-T_{i}}=-4 \frac{m_{e}}{m_{i}} v_{e} \mathrm{~d} t \\
& \rightarrow T_{e}-T_{i}=\left(T_{e 0}-T_{i 0}\right) \exp \left[-4 \frac{m_{e}}{m_{i}} v_{e}\left(t-t_{0}\right)\right] . \tag{7.92}
\end{align*}
$$

(vi) Applications - fast collision processes involving waves.

In $\S 4.2$ we constructed a model for collisional damping of waves. In a simple relaxation model we made the replacement $\omega^{2} \rightarrow \omega(\omega+\mathrm{i} \nu)$ in the linear dispersion relations. For Langmuir waves the imaginary part of the mode frequency due to collisions is $\gamma_{c}=-\frac{1}{2} v_{e}$. For a transverse wave in an unmagnetized plasma $\gamma_{c}=-\frac{1}{2} v_{e}\left(\omega_{p} / \omega\right)^{2}$.

Collisional diffusion alters the wave-particle resonance. In §7.2.2 we derived velocity diffusion in a Coulomb model. In a one-dimensional model the velocity diffusion is given by

$$
\begin{align*}
D(v) & =\left(\frac{e}{m}\right)^{2} \int_{0}^{\infty} \mathrm{d} \tau C_{E}(s(\tau), \tau) \\
C_{E}(s(\tau), \tau) & =\iint \frac{\mathrm{d} k \mathrm{~d} \omega}{(2 \pi)^{2}} k^{2} S_{\phi}(k, \omega) \exp (\mathrm{i} k s-\mathrm{i} \omega \tau) \\
\rightarrow D(v) & =\left(\frac{e}{m}\right)^{2} \iint \frac{\mathrm{~d} k \mathrm{~d} \omega}{(2 \pi)^{2}} k^{2} S_{\phi}(k, \omega) \int_{0}^{\infty} \mathrm{d} \tau \exp (-\mathrm{i} \omega \tau) \exp (\mathrm{i} k s(\tau)) \tag{7.93}
\end{align*}
$$

What is the spatially averaged velocity diffusion? The average of (7.93) with respect to the particle position is

$$
\begin{align*}
\langle D(v)\rangle & =\left(\frac{e}{m}\right)^{2} \iint \frac{\mathrm{~d} k \mathrm{~d} \omega}{(2 \pi)^{2}} k^{2} S_{\phi}(k, \omega) \int_{0}^{\infty} \mathrm{d} \tau \exp (-\mathrm{i} \omega \tau)\langle\exp (\mathrm{i} k s(\tau))\rangle, \\
s(\tau) & =v \tau+s^{\prime}(\tau) \\
\rightarrow\langle D(v)\rangle & =\left(\frac{e}{m}\right)^{2} \iint \frac{\mathrm{~d} k \mathrm{~d} \omega}{(2 \pi)^{2}} k^{2} S_{\phi}(k, \omega) \int_{0}^{\infty} \mathrm{d} \tau \exp (-\mathrm{i} \omega \tau+\mathrm{i} k v \tau)\left\langle\exp \left(\mathrm{i} k s^{\prime}(\tau)\right)\right\rangle, \tag{7.94}
\end{align*}
$$

where $s^{\prime}(\tau)$ is the perturbed particle displacement. For fixed $\tau$ consider the perturbed displacement and its probability of occurring $P\left(s^{\prime} \mid \tau\right)$. If $X \equiv \sum_{i=1}^{N} x_{i}$ and if the $x_{i}$ are independent, then in the limit $N \rightarrow \infty, X$ will be distributed normally (central limit theorem).

THEOREM.

$$
\begin{equation*}
P\left(s^{\prime} \mid \tau\right)=\frac{1}{\sqrt{2 \pi \sigma^{2}(\tau)}} \exp \left(\frac{\left[s^{\prime}-\left\langle s^{\prime}\right\rangle(\tau)\right]^{2}}{2 \sigma^{2}(\tau)}\right) \tag{7.95}
\end{equation*}
$$

Returning to (7.94), consider the time integral. If $s^{\prime}=0$, then the Landau resonance integral results,

$$
\begin{equation*}
R=\operatorname{Re} \int_{0}^{\infty} \mathrm{d} \tau \exp (-\mathrm{i}(\omega-k v) \tau)\left\langle\exp \left(\mathrm{i} k s^{\prime}(\tau) \rightarrow 0\right)\right\rangle \rightarrow \pi \delta(\omega-k v) \tag{7.96}
\end{equation*}
$$

Instead with $s^{\prime}$ distributed as a Gaussian, as in (7.95), one has

$$
\left\langle\exp \left(\mathrm{i} k s^{\prime}(\tau)\right)\right\rangle \equiv \int_{-\infty}^{\infty} \mathrm{d} s^{\prime} \exp \left(\mathrm{i} k s^{\prime}\right) P\left(s^{\prime} \mid \tau\right)=\exp \left[\mathrm{i} k\left\langle s^{\prime}\right\rangle(\tau)-\frac{1}{2} k^{2} \sigma^{2}(\tau)\right]
$$

and

$$
\begin{equation*}
R(\omega, k, v)=\operatorname{Re} \int_{0}^{\infty} \mathrm{d} \tau \exp \left(-\mathrm{i}(\omega-k v) \tau+\mathrm{i} k\left\langle s^{\prime}\right\rangle(\tau)-\frac{1}{2} k^{2} \sigma^{2}(\tau)\right) \tag{7.97}
\end{equation*}
$$

The term $\mathrm{i} k\left\langle s^{\prime}\right\rangle(\tau)$ inside the exponential in (7.97) contributes a frequency shift, which we will ignore, but it can be evaluated easily. Next consider the last term inside the exponential,

$$
\begin{equation*}
\sigma^{2} \equiv\left\langle\left[s^{\prime}-\left\langle s^{\prime}\right\rangle\right]^{2}\right\rangle=\left\langle s^{\prime 2}\right\rangle-\left\langle s^{\prime}\right\rangle^{2} \approx\left\langle s^{\prime 2}\right\rangle \gg\left\langle s^{\prime}\right\rangle^{2} \tag{7.98}
\end{equation*}
$$

and

$$
\left.\begin{array}{c}
s^{\prime}(\tau) \equiv \int_{0}^{\tau} \mathrm{d} t \delta v(t)=\int_{0}^{\tau} \mathrm{d} t \int_{0}^{t} \mathrm{~d} t^{\prime} \dot{v}(t)  \tag{7.99}\\
(\tau)]^{2}=\int_{0}^{\tau} \mathrm{d} t_{1} \int_{0}^{\tau} \mathrm{d} t_{2} \int_{0}^{t_{1}} \mathrm{~d} t_{1}^{\prime} \int_{0}^{t_{2}} \mathrm{~d} t_{2}^{\prime}\left\langle\dot{v}\left(t_{1}^{\prime}\right) \dot{v}\left(t_{2}^{\prime}\right)\right\rangle \\
\equiv \int_{0}^{\tau} \mathrm{d} t_{1} \int_{0}^{\tau} \mathrm{d} t_{2} \int_{0}^{t_{1}} \mathrm{~d} t_{1}^{\prime} \int_{0}^{t_{2}} \mathrm{~d} t_{2}^{\prime} C_{\dot{v}}\left(\left|t_{1}^{\prime}-t_{2}^{\prime}\right|\right),
\end{array}\right\}
$$

where $C_{\dot{v}}$ is the two-time auto-correlation function for the velocity derivative. Examining the innermost area integral with respect to $t_{1}^{\prime}$ and $t_{2}^{\prime}$ over the rectangle 0 to $t_{1}$ and 0 to $t_{2}, C_{\dot{v}}$ is significant only over the diagonal where $\left|t_{1}^{\prime}-t_{2}^{\prime}\right|$ is small because of the randomness of the perturbing fields. Hence,

$$
\begin{equation*}
\left[s^{\prime}(\tau)\right]^{2}=\int_{0}^{\tau} \mathrm{d} t_{1} \int_{0}^{\tau} \mathrm{d} t_{2}\left(t_{1}, t_{2}\right)_{<} \int_{-\infty}^{\infty} \mathrm{d} \tau^{\prime} C_{\dot{v}}\left(\tau^{\prime}\right)=\frac{1}{3} \tau^{3} \int_{-\infty}^{\infty} \mathrm{d} \tau^{\prime} C_{\dot{v}}\left(\tau^{\prime}\right) \tag{7.100}
\end{equation*}
$$

However, from (7.50) $D(v)=\int_{0}^{\infty} \mathrm{d} \tau\langle\dot{v}(t) \dot{v}(t-\tau)\rangle=\int_{0}^{\infty} \mathrm{d} \tau C_{\dot{v}}(\tau)$. Hence,

$$
\begin{equation*}
\sigma^{2}(\tau)=\frac{2}{3} D(v) \tau^{3} \quad \text { and } \quad R(\omega, k, v: D)=\int_{0}^{\infty} \mathrm{d} \tau \exp \left(-\frac{1}{3} k^{2} D(v) \tau^{3}\right) \cos [(\omega-k v) \tau] \tag{7.101}
\end{equation*}
$$

In (7.93)-(7.101) $D$ is the diffusion in velocity space and not momentum space,

$$
\begin{equation*}
D_{e}^{e}(v)=v_{e}^{2} v_{e} \tag{7.102}
\end{equation*}
$$

It then follows that

$$
\begin{align*}
& k^{2} D \tau^{3}=\left(k v_{e}\right)^{2} v_{e} \tau^{3}=\left(\frac{\tau}{\tau_{v}}\right)^{3}, \quad \tau_{v}^{-3} \equiv\left(k v_{e}\right)^{2} v_{e}=k^{2} D \\
& \quad \rightarrow \tau_{v} \equiv D^{-1 / 3} k^{-2 / 3}=v_{e}^{-1 / 3}\left(k v_{e}\right)^{-2 / 3} \sim\left(k_{D} v_{e}\right)^{-2 / 3} v_{e}^{-1 / 3}=v_{e}^{-1}\left(\frac{v_{e}}{\omega_{p}}\right)^{2 / 3}, \tag{7.103}
\end{align*}
$$

for $k \sim k_{D}$, where $\tau_{v}$ is a characteristic time for collisions. For $\nu_{e} \sim \omega_{p} / \Lambda$ then $\tau_{v}^{-1} \sim v_{e} \Lambda^{2 / 3}$ or $\tau_{v}^{-1} \sim \omega_{p} / \Lambda^{1 / 3}$. Hence, the relative frequency broadening width for an electron plasma wave is $\tau_{v}^{-1} / \omega_{p} \sim 1 / \Lambda^{1 / 3}$. We return to (7.101):

$$
\begin{align*}
R\left(\omega, k, v ; \tau_{v}\right) & =\int_{0}^{\infty} \mathrm{d} \tau \exp \left(-\frac{1}{3} k^{2} D(v) \tau^{3}\right) \cos [(\omega-k v) \tau] \\
& =\tau_{v} \int_{0}^{\infty} \mathrm{d} x \exp \left(-\frac{1}{3} x^{3}\right) \cos (\lambda x) \tag{7.104}
\end{align*}
$$

where $\lambda \equiv(\omega-k v) \tau_{v}$ and $x \equiv \tau / \tau_{v}$. The integral in (7.104) is not an elementary integral. We recall from (7.96) that as $D \rightarrow 0 R \rightarrow \pi \delta(\omega-k v)$. For small $\lambda \ll 1$ the integral on the right-hand side of (7.104) is dominated by the exponential and converges quickly to a number of $O(1)$. (Note that $\left.\int_{0}^{\infty} \mathrm{d} x \exp \left(-x^{\mu}\right)=1 / \mu \Gamma(1 / \mu)\right)$. $R / \tau_{v}$ peaks as a function of $\lambda$ at $\lambda=0$ at a value $O(1)$ and decreases for increasing $\lambda$. At large $\lambda$ the integral in (7.104) can be approximated using steepest descents yielding $R / \tau_{v} \sim \exp \left(-\lambda^{3 / 2}\right) \sin \left(\lambda^{3 / 2}\right)$.

EXERCISE. Evaluate the integral in (7.104) for large $\lambda$ using steepest descents.
We see that as $D$ increases the resonance integral $R$ spreads. However, the area under the curve $R$ versus $\omega, \int_{-\infty}^{\infty} \mathrm{d} \omega R=\pi$ is conserved, which can be verified by integrating $R$ with respect to $\omega$ in (7.104) to obtain $\pi \delta(\tau)$ and then doing the $\tau$ integral. We note that $R$ peaks at $\tau_{\nu} O(1)$ and has a full width at half-maximum $\sim O(1) \tau_{v}^{-1}$. We also observe that

$$
\begin{equation*}
\lambda=\left(\frac{\omega-k v}{\omega_{v}}\right)=\left(\frac{v-\omega / k}{\omega_{v} / k}\right), \quad \omega_{\nu} \equiv 1 / \tau_{v} \tag{7.105}
\end{equation*}
$$

Thus, the broadening of the resonance can be considered in the frequency domain for fixed velocity or in the velocity domain for fixed frequency.

THEOREM. The width in velocity space is

$$
\begin{equation*}
w \equiv \frac{\omega_{v}}{k}=\left(\frac{D}{k}\right)^{1 / 3}=\left(\frac{v_{e}^{2} v_{e}}{k}\right)^{1 / 3}=v_{e}\left(\frac{v_{e}}{k v_{e}}\right)^{1 / 3} \sim v_{e}\left(\frac{v_{e}}{\omega_{p}}\right)^{1 / 3}=v_{e} / \Lambda^{1 / 3} \tag{7.106}
\end{equation*}
$$

Similarly, for fixed frequency and velocity there is a resonance in $k$; and there is a corresponding width due to the collisional broadening,

$$
\begin{equation*}
\lambda=\left(\frac{\omega-k v}{\omega_{v}}\right)=\left(\frac{\omega / v-k}{\omega_{v} / v}\right) \rightarrow \text { for } v \sim v_{e} \quad k_{v} \sim \frac{k_{D}}{\Lambda^{1 / 3}} . \tag{7.107}
\end{equation*}
$$

Thus, the scaling of the collisional spreading of the resonances in the frequency, velocity and wavenumber domains is $1 / \Lambda^{1 / 3}$.

Collisions are just one cause of resonance broadening. The relative width of the resonance in frequency or velocity is $\left(v_{e} / \omega_{p}\right)^{1 / 3}$ for collisional diffusion. Quasilinear diffusion in the presence of a spectrum of resonant waves is another cause of resonance broadening. The width in velocity space (particle velocity or phase velocity) scales as $\sqrt{e \phi_{\mathrm{rms}} / m}$. Particle trapping in a monochromatic wave broadens the resonance in velocity space by $O\left(v_{\text {trap }}\right) \sim \sqrt{e \phi / m}$. The adiabatic interaction of many non-resonant waves can broaden the resonance of a particle with a specific wave. In general, the time interval for a resonant interaction is limited by the amount of time it takes for diffusion to drive the interaction off resonant; define it as $\tau_{D}$.

For collisional diffusion, the resonance is detuned when the rms diffusion displacement is comparable to the wavelength of the wave,

$$
\left.\begin{array}{c}
\sqrt{\left\langle s^{\prime}\left(\tau_{D}\right)^{2}\right\rangle} \sim \lambda \rightarrow\left\langle s^{\prime}\left(\tau_{D}\right)^{2}\right\rangle \sim \lambda^{2} \sim \frac{1}{k^{2}}  \tag{7.108}\\
\left\langle s^{\prime}\left(\tau_{D}\right)^{2}\right\rangle \sim\left(D \tau_{D}\right) \tau_{D}^{2} \rightarrow D \tau_{D}^{3} \sim \frac{1}{k^{2}} \rightarrow k^{2} D \tau_{D}^{3} \sim O(1)
\end{array}\right\}
$$

which is when the exponential begins to limit the integrand in (7.104) and $\tau_{v}$ in (7.103).

In quasilinear diffusion driven resonance broadening, the estimates for the diffusion time and the scaling of the resonance width proceed as follows:

$$
\left.\begin{array}{c}
\dot{v}=\frac{e}{m} E \rightarrow\left\langle\left(v^{\prime}\right)^{2}\right\rangle=\left(\frac{e}{m}\right)^{2}\left\langle E^{2}\right\rangle \tau_{D}^{2}  \tag{7.109}\\
\rightarrow\left\langle s^{\prime 2}\right\rangle \sim\left(\frac{e}{m}\right)^{2}\left\langle E^{2}\right\rangle \tau_{D}^{4} \sim \lambda^{2} \rightarrow \frac{e}{m} E_{\mathrm{rms}} \tau_{D}^{2} \sim \lambda \\
\frac{1}{\tau_{D}^{2}} \sim \delta \omega^{2} \rightarrow \frac{e}{m} \phi_{\mathrm{rms}} \sim w^{2}=\frac{\delta \omega^{2}}{k^{2}} \rightarrow \sqrt{\frac{e}{m} \phi_{\mathrm{rms}}} \sim w .
\end{array}\right\}
$$

Example. Resonance broadening due to quasilinear diffusion for a discrete spectrum of waves. For quasilinear diffusion we earlier derived the velocity diffusion coefficient in § 6.5

$$
\begin{equation*}
D(v)=\left(\frac{e}{m}\right)^{2} \int \frac{\mathrm{~d} k}{2 \pi} \int \frac{\mathrm{~d} \omega}{2 \pi} S_{E}(k, \omega) R(\omega-k v, \delta \omega) . \tag{7.110}
\end{equation*}
$$

In (7.110) the resonance function is $R=\pi \delta(\omega-k v)$ in the absence of broadening. With broadening, the resonance function acquires a finite width and height with respect to frequency. Consider a discrete spectrum of normal modes such that

$$
\begin{equation*}
S_{E}(k, \omega)=2 \pi S(k) \delta\left(\omega-\omega_{k}\right) \quad S_{E}(k)=\sum_{i=1}^{N} S_{i} 2 \pi \delta\left(k-k_{i}\right) . \tag{7.111}
\end{equation*}
$$

Despite the discrete spectrum, there are no infinities in the integrand in $D(v)$ in (7.110), and $\sum_{i} S_{i}=\left\langle E^{2}\right\rangle=\sum_{i} k^{2} \phi_{\mathrm{rms}}^{2}$ if there is broadening. In velocity space the structure of $D$ acquires finite-width resonances for each value of $\omega_{k}\left(k_{i}\right) / k_{i}$. Thus, $D$ is a smooth function of velocity with no singularities, which is useful for evaluating $\partial f / \partial t=\partial / \partial v(D(\partial f / \partial v))$.

### 7.3. Radiation transport

In this section we consider the emission of electromagnetic waves in a plasma. We include the effects of gyration in a magnetic field and particle collisions on wave emission. We also examine the scattering of waves in a plasma and derive a general theory for the scattering of particles, fluctuations and waves, including nonlinear Landau damping. We summarize the important processes in radiation transport in a plasma and conclude with a discussion of WKB theory in the context of radiation transport. The consideration of radiation transport here does not include any processes associated with atomic physics, and the theory is purely classical and excludes quantum mechanical effects.
7.3.1. Calculation of emission from Maxwell's equations with arbitrary current sources

We recall from $\S \S 3$ and 4 that the linearized Vlasov-Maxwell system yields the following relation for the electromagnetic response of a plasma to an arbitrary current density:

$$
\begin{equation*}
\boldsymbol{K}(\boldsymbol{k}, \omega) \cdot \boldsymbol{E}(k, \omega)=\frac{4 \pi}{\mathrm{i} \omega} \boldsymbol{j}_{0}(\boldsymbol{k}, \omega) \quad \text { where } \boldsymbol{K}=\stackrel{\leftrightarrow}{\varepsilon}-n^{2}(\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{k}} \hat{\boldsymbol{k}}) \quad \text { and } \quad n=\frac{k c}{\omega} \tag{7.112}
\end{equation*}
$$

When the electric fields do work on the plasma currents, energy comes out of the electromagnetic fields,

$$
\begin{equation*}
-\dot{W}=\int \mathrm{d}^{3} \boldsymbol{x} \boldsymbol{E}(\boldsymbol{x}, t) \cdot \boldsymbol{j}_{0}(\boldsymbol{x}, t)=\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \boldsymbol{j}_{0}^{*}(\boldsymbol{k}, t) \cdot \boldsymbol{E}(\boldsymbol{k}, t) . \tag{7.113}
\end{equation*}
$$

If we invert the relation in (7.112) to solve for the electric field then

$$
\begin{equation*}
\boldsymbol{E}(\boldsymbol{k}, \omega)=\frac{4 \pi}{\mathrm{i} \omega} \boldsymbol{K}^{-1}(\boldsymbol{k}, \omega) \cdot \boldsymbol{j}_{0}(\boldsymbol{k}, \omega) \tag{7.114}
\end{equation*}
$$

from which one obtains

$$
\begin{equation*}
\boldsymbol{E}(\boldsymbol{k}, \omega)=\int_{-\infty}^{\infty} \mathrm{d} \tau \boldsymbol{G}(\boldsymbol{k}, \tau) \cdot \boldsymbol{j}_{0}(\boldsymbol{k}, t-\tau) \tag{7.115}
\end{equation*}
$$

where

$$
\begin{equation*}
\boldsymbol{G}(\boldsymbol{k}, \tau)=\int \frac{\mathrm{d} \omega}{2 \pi} \exp (-\mathrm{i} \omega \tau) \frac{4 \pi}{\mathrm{i} \omega} \boldsymbol{K}^{-1}(\boldsymbol{k}, \omega) \tag{7.116}
\end{equation*}
$$

We assume that there are no poles of the integrand in (7.116) in the upper half of the complex $\omega$ plane (no exponentially growing linear modes), and we use analytic continuation to depress the integration contour while keeping the contour above poles on the real $\omega$ axis. Causality insures that $\boldsymbol{G}=0$ for $\tau<0$. We use (7.114)-(7.116) in (7.113) to obtain

$$
\begin{equation*}
-\dot{W}(t)=\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int_{-\infty}^{\infty} \mathrm{d} \tau \boldsymbol{j}_{0}^{*}(\boldsymbol{k}, t) \cdot \boldsymbol{G}(\boldsymbol{k}, \tau) \cdot \boldsymbol{j}_{0}(\boldsymbol{k}, t-\tau) . \tag{7.117}
\end{equation*}
$$

Consider the product of the plasma currents in (7.117) and posit a sufficient number of sources to average over so that we can calculate the two-time correlation tensor for the plasma currents.

Definition. $\boldsymbol{C}=\boldsymbol{C}(\boldsymbol{k}, \tau) \equiv\left\langle\boldsymbol{j}_{0}^{*}(\boldsymbol{k}, t) \boldsymbol{j}_{0}(\boldsymbol{k}, t-\tau)\right\rangle$. We assume that $\boldsymbol{C}$ is not a function of time, i.e. it is statistically stationary.

Hence, from (7.117)

$$
\begin{align*}
-\dot{W} & =\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int_{-\infty}^{\infty} \mathrm{d} \tau \boldsymbol{C}_{j_{0}}^{*}(\boldsymbol{k}, \tau): \boldsymbol{G}(\boldsymbol{k}, \tau) \\
& =\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int_{-\infty}^{\infty} \frac{\mathrm{d} \omega}{2 \pi} \boldsymbol{S}^{j_{0} *}(\boldsymbol{k}, \omega): \boldsymbol{K}^{-1}(\boldsymbol{k}, \omega) \frac{4 \pi}{\mathrm{i} \omega} . \tag{7.118}
\end{align*}
$$

We take the limit that there are no linearly unstable waves, $\operatorname{Im} \omega \rightarrow 0$. We note that $\boldsymbol{K}=\boldsymbol{K}^{\prime}+\mathrm{i} \boldsymbol{K}^{\prime \prime}$ where $\boldsymbol{K}^{\prime}$ is the reactive part and $\boldsymbol{K}^{\prime \prime}$ is the dissipative part; $\boldsymbol{K}$ is not Hermitian, and $\boldsymbol{K}^{-1}=\boldsymbol{K}^{-1^{\prime}}+\mathrm{i} \boldsymbol{K}^{-1^{\prime \prime}}$ where $\boldsymbol{K}^{-1^{\prime}}$ is the Hermitian part and $\mathrm{i} \boldsymbol{K}^{-1^{\prime \prime}}$ is the anti-Hermitian part.

Theorem. $\boldsymbol{S}^{*}=\boldsymbol{S}^{\prime}$ is Hermitian which follows from $\boldsymbol{C}$ being independent of time.

Exercise. Prove that $\boldsymbol{S}^{*}$ is Hermitian.

$$
\begin{align*}
\boldsymbol{S}^{j_{0} *} & =\int_{-\infty}^{\infty} \mathrm{d} \tau \boldsymbol{C}_{j_{0}^{*}}=\int_{-\infty}^{\infty} \mathrm{d} \tau\left\langle\boldsymbol{j}_{0}(\boldsymbol{k}, t) \boldsymbol{j}_{0}^{*}(\boldsymbol{k}, t-\tau)\right\rangle=-\int_{-\infty}^{\infty} \mathrm{d} \tau\left\langle\boldsymbol{j}_{0}(\boldsymbol{k}, t) \boldsymbol{j}_{0}^{*}(\boldsymbol{k}, \tau-t)\right\rangle \\
& =-\int_{-\infty}^{\infty} \mathrm{d} \tau \lim _{T \rightarrow \infty} \frac{1}{2 T} \int_{-T}^{T} \mathrm{~d} t \boldsymbol{j}_{0}(\boldsymbol{k}, t) \boldsymbol{j}_{0}^{*}(\boldsymbol{k}, \tau-t) \\
& =-\lim _{T \rightarrow \infty} \frac{1}{2 T} \int_{-T}^{T} \mathrm{~d} \tau \int_{-\infty}^{\infty} \mathrm{d} \omega \mathrm{e}^{-\mathrm{i} \omega \tau} \boldsymbol{j}_{0}(\boldsymbol{k}, \omega) \boldsymbol{j}_{0}^{*}(\boldsymbol{k}, \omega) \\
& =-\lim _{T \rightarrow \infty} \frac{1}{2 T} \int_{-T}^{T} \mathrm{~d} \tau \int_{-\infty}^{\infty} \mathrm{d} \omega \mathrm{e}^{-\mathrm{i} \omega \tau} \boldsymbol{j}_{0}^{*}(\boldsymbol{k}, \omega) \boldsymbol{j}_{0}(\boldsymbol{k}, \omega) \Rightarrow \boldsymbol{S}^{*}=\boldsymbol{S}^{\mathrm{T}} \tag{7.119}
\end{align*}
$$

where $S^{\mathrm{T}}$ is the transpose of $S$.
In (7.118) $\boldsymbol{K}^{-1}$ appears, which we evaluate as follows:

$$
\begin{equation*}
\boldsymbol{K}^{-1}=\frac{\boldsymbol{K}^{\mathrm{adj}}}{\operatorname{det}|\boldsymbol{K}|}=\frac{\boldsymbol{K}^{\mathrm{adj}}}{D(\boldsymbol{k}, \omega)}=\frac{\boldsymbol{K}^{\mathrm{adj}}}{D^{\prime}(\boldsymbol{k}, \omega)+\mathrm{i} D^{\prime \prime}(\boldsymbol{k}, \omega)}=\boldsymbol{K}^{\mathrm{adj}}\left(P \frac{1}{D^{\prime}}-\mathrm{i} \pi \delta\left(D^{\prime}\right) \operatorname{sgn} D^{\prime \prime}\right), \tag{7.120}
\end{equation*}
$$

for small $D^{\prime \prime}$. Substituting (7.120) in (7.118), we obtain

$$
\begin{equation*}
\dot{W}=\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int_{-\infty}^{\infty} \frac{\mathrm{d} \omega}{2 \pi} \boldsymbol{S}^{j_{0} *}(\boldsymbol{k}, \omega): \boldsymbol{K}^{\mathrm{adj}}(\boldsymbol{k}, \omega) \frac{4 \pi}{\omega} \pi \delta\left(D^{\prime}(\boldsymbol{k}, \omega)\right) \operatorname{sgn} D^{\prime \prime}, \tag{7.121}
\end{equation*}
$$

where

$$
\begin{equation*}
\pi \delta(D(\boldsymbol{k}, \omega))=\sum_{\ell, \pm} \frac{\delta\left(\omega-\omega_{k}^{\ell}\right)}{\left|\partial D^{\prime}(\boldsymbol{k}, \omega) / \partial \omega\right|_{\omega_{k}^{\ell}}} \tag{7.122}
\end{equation*}
$$

and the sum is over $\ell$ branches and $\pm|\omega|$. In the absence of an applied external magnetic field there are three electron branches (immobile ions): two branches for transverse modes and one branch for longitudinal modes. With mobile ions there are
additional branches, and with an applied magnetic field there are even more branches. Equation (7.121) becomes

$$
\left.\begin{array}{c}
\dot{W}=\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \sum_{\ell, \pm} \frac{2 \pi}{\omega_{k}^{\ell}} \boldsymbol{S}^{\boldsymbol{S}_{0}^{*}}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right): \boldsymbol{K}^{\mathrm{adj}}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right) \frac{\operatorname{sgn} D^{\prime \prime}}{\left|\frac{\partial D}{\partial \omega}\right|_{\omega_{k}^{\ell}} \equiv \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \sum_{\ell, \pm} \dot{W}^{\ell}(\boldsymbol{k})} \\
\dot{W}^{\ell}(\boldsymbol{k})=\frac{2 \pi}{\omega_{k}^{\ell}} \boldsymbol{S}^{\boldsymbol{j}_{0}^{*}}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right): \boldsymbol{K}^{\mathrm{adj}}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right) \frac{\operatorname{sgn} D^{\prime \prime}}{\left|\frac{\partial D}{\partial \omega}\right|_{\omega_{k}^{\ell}} .} \tag{7.123}
\end{array}\right\}
$$

We next eliminate $\boldsymbol{K}^{\text {adj }}$ using the following relations:

$$
\left.\begin{array}{c}
\boldsymbol{K}^{-1}=\frac{\boldsymbol{K}^{\mathrm{adj}}}{D} \quad \boldsymbol{K}^{-1} \cdot \boldsymbol{K}=\boldsymbol{I}=\boldsymbol{K} \cdot \boldsymbol{K}^{-1} \quad \boldsymbol{K}^{\mathrm{adj}}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right) \cdot \boldsymbol{K}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right)=D \boldsymbol{I}=\boldsymbol{K} \cdot \boldsymbol{K}^{\mathrm{adj}} \\
\frac{\partial}{\partial \omega}\left[\boldsymbol{K}^{\mathrm{adj}}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right) \cdot \boldsymbol{K}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right)\right]=\frac{\partial \boldsymbol{K}^{\mathrm{adj}}}{\partial \omega} \cdot \boldsymbol{K}+\boldsymbol{K}^{\mathrm{adj}} \cdot \frac{\partial \boldsymbol{K}}{\partial \omega}=\frac{\partial D}{\partial \omega} \boldsymbol{I} \tag{7.124}
\end{array}\right\},
$$

and the matrix identity $\operatorname{det}\left(\boldsymbol{K}^{\mathrm{adj}}\right)=\operatorname{det}(\boldsymbol{K})^{n-1}=D^{2}$ where $n=3$ is the rank of the matrix $\boldsymbol{K}$. Thus, as $D \rightarrow 0$, $\operatorname{det}\left(\boldsymbol{K}^{\text {adj }}\right)$ goes to zero even faster. We recall that the linear normal modes satisfy the following relations:

$$
\left.\begin{array}{c}
\boldsymbol{K} \cdot \boldsymbol{E}=0 \Rightarrow D\left(\boldsymbol{k}, \omega_{k}^{\ell}\right)=0  \tag{7.125}\\
\boldsymbol{K}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right) \cdot \hat{e}_{k}^{\ell}=0 \Rightarrow \text { polarization } \\
\therefore \boldsymbol{K}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right)=K \hat{\boldsymbol{e}}_{k}^{\ell} \hat{\boldsymbol{e}}_{k}^{\ell} \quad \text { and } \quad \boldsymbol{K}^{\mathrm{adj}}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right)=K \hat{\boldsymbol{e}}_{k}^{\ell} \hat{e}_{k}^{\ell *}
\end{array}\right\}
$$

using that to lowest order $\boldsymbol{K}$ is Hermitian. Given (7.125) then from (7.124)

$$
\begin{align*}
& \hat{\boldsymbol{e}}^{*} \cdot \frac{\partial \boldsymbol{K}^{\mathrm{adj}}}{\partial \omega} \cdot \boldsymbol{K} \cdot \hat{\boldsymbol{e}}+\hat{\boldsymbol{e}}^{*} \cdot \boldsymbol{K}^{\mathrm{adj}} \cdot \frac{\partial \boldsymbol{K}}{\partial \omega} \cdot \hat{\boldsymbol{e}}=\hat{\boldsymbol{e}}^{*} \cdot \boldsymbol{K}^{\mathrm{adj}} \cdot \frac{\partial \boldsymbol{K}}{\partial \omega} \cdot \hat{\boldsymbol{e}}=\frac{\partial D}{\partial \omega} \hat{\boldsymbol{e}}^{*} \hat{\boldsymbol{e}}=\frac{\partial D}{\partial \omega} \\
& \quad \Rightarrow K=\frac{\partial D / \partial \omega}{\hat{\boldsymbol{e}}^{*} \cdot \frac{\partial \boldsymbol{K}}{\partial \omega} \cdot \hat{\boldsymbol{e}}} \tag{7.126}
\end{align*}
$$

We can now return to our evaluation of (7.123) using (7.125) and (7.126) for $\boldsymbol{K}^{\text {adj }}$, and (7.119) for $\boldsymbol{S}$,

$$
\begin{equation*}
\dot{W}^{\ell}(\boldsymbol{k})=\frac{2 \pi}{\omega_{k}^{\ell}} \operatorname{sgn} D^{\prime \prime} \int_{-\infty}^{\infty} \mathrm{d} \tau \exp \left(-\mathrm{i} \omega_{k}^{\ell} \tau\right) \frac{\left\langle\boldsymbol{j}_{0}^{*}(\boldsymbol{k}, t) \cdot \hat{\boldsymbol{e}}_{k}^{\ell} \hat{\boldsymbol{e}}_{k}^{\ell *} \cdot \boldsymbol{j}_{0}(\boldsymbol{k}, t-\tau)\right\rangle}{\left.\hat{\boldsymbol{e}}_{k}^{\ell *} \cdot \frac{\partial \boldsymbol{K}}{\partial \omega}\right|_{\omega_{k}^{\ell}} \cdot \hat{\boldsymbol{e}}_{k}^{\ell}} \tag{7.127}
\end{equation*}
$$

DEFINITION. Define the scalar current density as the projection of the current density onto the unit vector for the electric field polarization determined in (7.125),

$$
\begin{equation*}
j_{0}^{(k, \ell)} \equiv \hat{\boldsymbol{e}}_{k}^{\ell *} \cdot \boldsymbol{j}_{0}(\boldsymbol{x}, t) \tag{7.128}
\end{equation*}
$$

Using the scalar current density we can construct the spectral density for the current density from

$$
\begin{equation*}
\int_{-\infty}^{\infty} \mathrm{d} \tau \exp \left(-\mathrm{i} \omega_{k}^{\ell} \tau\right)\left\langle j_{0}^{(k, \ell) *}(\boldsymbol{k}, t) j_{0}^{(k, \ell)}(\boldsymbol{k}, t-\tau)\right\rangle \equiv \int_{-\infty}^{\infty} \mathrm{d} \tau \exp \left(-\mathrm{i} \omega_{k}^{\ell} \tau\right) C_{j_{k}^{\ell}}^{*} \equiv S_{j_{k}^{\ell}} \tag{7.129}
\end{equation*}
$$

We note that the spectral density for the scalar current is real so that the conjugate can be dropped. With (7.128) and (7.129), (7.127) can be rewritten as

$$
\begin{equation*}
\left|\dot{W}^{\ell}(\boldsymbol{k})\right|=\frac{4 \pi}{\omega_{k}^{\ell}} \frac{S_{j_{k, \ell}}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right)}{\left.\hat{\boldsymbol{e}}_{k}^{\ell *} \cdot \frac{\partial \boldsymbol{K}}{\partial \omega}\right|_{\omega_{k}^{\ell}} \cdot \hat{\boldsymbol{e}}_{k}^{\ell}}, \quad \omega_{k}^{\ell}>0, \tag{7.130}
\end{equation*}
$$

where we have dropped $\operatorname{sgn} D^{\prime \prime}$ and introduced a factor of 2 in the numerator because $\omega_{k}^{l}>0$. A useful relation for $S_{j}$ is given by

$$
\begin{equation*}
\left\langle j_{0}^{(k, \ell)}(\boldsymbol{k}, \omega) j_{0}^{(k, \ell) *}\left(\boldsymbol{k}^{\prime}, \omega^{\prime}\right)\right\rangle=(2 \pi)^{4} \delta\left(\omega-\omega^{\prime}\right) \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) S_{j_{k}^{\prime}} . \tag{7.131}
\end{equation*}
$$

### 7.3.2. Emission by a particle gyrating in a magnetic field

We illustrate the results in the previous sub-section by calculating the electromagnetic wave emission from a gyrating particle in an externally applied magnetic field. The current density from a single particle is

$$
\left.\begin{array}{c}
\boldsymbol{j}(\boldsymbol{r}, t)=e \boldsymbol{v}_{0}(t) \delta\left(\boldsymbol{r}-\boldsymbol{r}_{0}(t)\right) \rightarrow \boldsymbol{j}(\boldsymbol{k}, t)=e \boldsymbol{v}_{0}(t) \exp \left(-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{0}(t)\right)  \tag{7.132}\\
j_{x}(\boldsymbol{k}, t)=e v_{x}(t) \exp \left(-\mathrm{i} k_{x} x(t)-\mathrm{i} k_{y} y(t)-\mathrm{i} k_{z} z(t)\right),
\end{array}\right\}
$$

where the equations of motion for the charged particle in a field $\boldsymbol{B}=B_{0} \hat{z}$ in the absence of any other fields yield

$$
\begin{equation*}
x(t)=X+r_{\perp} \cos \phi(t) \quad y(t)=Y+r_{\perp} \sin \phi(t) \quad z(t)=v_{\|} t+z_{0} \quad v_{x}=-v_{\perp} \sin \phi \tag{7.133}
\end{equation*}
$$

The wavenumber is represented generally by

$$
\begin{equation*}
k_{x}=k_{\perp} \cos \alpha \quad k_{y}=k_{\perp} \sin \alpha \quad k_{z}=k_{\|} . \tag{7.134}
\end{equation*}
$$

We substitute (7.133) and (7.134) into (7.132) and use the Bessel function identity for a cosine inside the exponential to obtain an expression for $S_{j}$ from (7.119),

$$
\begin{equation*}
S_{j}(\boldsymbol{k}, \omega) \propto \mathrm{J}_{\ell}^{2}\left(k_{\perp} r_{\perp}\right) \delta\left(\omega-k_{\|} v_{\|}-\ell \Omega\right) \tag{7.135}
\end{equation*}
$$

ignoring collisional resonance broadening. The expression in (7.135) is averaged over the initial gyro-phase, $X, Y$ and $z_{0}$, and summed over particles.

Exercise. Work out the details in (7.135).
Having calculated the spectral density for the current from (7.135) one can then evaluate the right-hand side of (7.130). To make progress one must evaluate the denominator, which depends on the wave characteristics (response tensor, dispersion relation and polarization). For $\boldsymbol{k}\left|\mid \boldsymbol{B}_{0}\right.$ then $\hat{\boldsymbol{e}}_{k}^{\ell}=(1 / \sqrt{2})(\hat{\boldsymbol{x}} \pm \hat{\boldsymbol{y}})$, and as examples one can consider whistlers, Alfvén waves, or other waves as described in §4.2.

For $\boldsymbol{k} \perp \boldsymbol{B}_{0}$ and $k_{\|}=0$ one might consider ordinary modes (electric field polarized parallel to $\boldsymbol{B}_{0}$ ), extraordinary modes (electric field polarized perpendicular to $\boldsymbol{B}_{0}$ ) or other modes described in $\S 4.3$. An important parameter influencing the intensity of the electromagnetic wave emission is the ratio of the particle energy to its rest mass energy. The more relativistic the particle is the stronger the emission. Relativity affects the equations of motion for the particles doing the emission, and relativity also affects the response tensor. Synchrotron radiation is an interesting example that has received much attention. By considering the emission of a particular electromagnetic wave and the kinetic linear damping of the same mode, as in $\S 7.1 .1$ for electrostatic modes, one can arrive at a balance equation between emission and damping, and recover the Rayleigh-Jeans relation that each wave has energy $W=T$ where $W$ is the energy per unit $\Delta^{3} k \Delta^{3} x$.

Exercise. Outline and sketch the details of one or two of the example calculations in the preceding paragraph. Try some of the algebra. Recover the Rayleigh-Jeans relation for electromagnetic emission and damping.

At this point we digress to consider the question of the influence of including collisions on electromagnetic wave emission in the presence of an applied magnetic field. We will conclude that the magnetic field effectively weakens collisional diffusion of the particle trajectories. We sketch what the analysis would be with the inclusion of collision-induced perturbations to the zero-order particle trajectories. The analysis includes the following relations:

$$
\left.\begin{array}{c}
\left\langle j_{x}(\boldsymbol{k}, t) j_{x}^{*}(\boldsymbol{k}, t-\tau)\right\rangle \rightarrow \exp (-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}(t)+\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}(t-\tau))  \tag{7.136}\\
\equiv \exp (-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{s}(\tau))=\exp \left(-\mathrm{i} k_{x} \Delta x(\tau)+\cdots\right) \\
\Delta x(\tau)=\Delta X(\tau)+r_{\perp}[\cos \phi(t)-\cos \phi(t-\tau)] \quad \Delta y=\cdots \quad \Delta z=\cdots \\
\Delta \phi(\tau) \equiv \phi(t)-\phi(t-\tau)=\Omega \tau+\Delta \phi^{\prime}(\tau)
\end{array}\right\}
$$

After $\Delta x$ is substituted into the exponential and the Bessel function identity is used, the following expression emerges

$$
\begin{equation*}
\left\langle\exp \left(\mathrm{i} \ell \Delta \phi^{\prime}(\tau)\right)\right\rangle \rightarrow \exp \left(-\ell^{2} \sigma_{\phi}^{2}(\tau)\right) \quad \sigma_{\phi}^{2}(\tau) \equiv\left\langle(\Delta \phi)^{2}(\tau)\right\rangle \tag{7.137}
\end{equation*}
$$

Recall the analysis of collision-induced resonance broadening and the use of the central limit theorem in $\S 7.2 .7$. In fact collisions produce diffusive changes to all of the terms in

$$
\begin{equation*}
x(t)=X+\frac{v_{\perp}}{\Omega} \cos \phi(t) \Rightarrow \delta x(t)=\delta X+\frac{\delta v_{\perp}}{\Omega} \cos \phi(t)-\frac{v_{\perp}}{\Omega} \delta \phi \sin \phi(t) \tag{7.138}
\end{equation*}
$$

We can estimate (perhaps naively) the electron velocity diffusion and the diffusion of the various terms in (7.138),

$$
\begin{equation*}
\left\langle(\delta v)^{2}\right\rangle=\left\langle\left(\delta v_{x}\right)^{2}\right\rangle+\left\langle\left(\delta v_{y}\right)^{2}\right\rangle+\left\langle\left(\delta v_{z}\right)^{2}\right\rangle=3\left\langle\left(\delta v_{x}\right)^{2}\right\rangle=2 D_{v} \tau \tag{7.139}
\end{equation*}
$$

and similarly for $\left\langle(\delta x)^{2}\right\rangle$ and $\left\langle(\delta \phi)^{2}\right\rangle$ :

$$
\begin{equation*}
\left\langle(\delta x)^{2}\right\rangle=r_{\perp}^{2} v_{e} \tau \quad\left\langle(\delta \phi)^{2}\right\rangle=2 v_{e} \tau \quad v_{e}=D_{e}^{e} / v_{e}^{2} . \tag{7.140}
\end{equation*}
$$

The first expression in (7.140) is just the classical collisional diffusion across the magnetic field, which scales as the square of the electron Larmor radius. The
collisionless magnetized resonance morphs into a resonance function with collisions,

$$
\begin{equation*}
\delta\left(\omega-k_{\|} v_{\|}-\ell \Omega\right) \Rightarrow R\left(\omega-k_{\|} v_{\|}-\ell \Omega\right), \frac{\delta \omega}{\omega} \sim \frac{v_{e}}{\omega}\left(k_{\perp} r_{\perp}\right)^{2} \tag{7.141}
\end{equation*}
$$

The magnetic field significantly reduces the collisional resonance broadening because of the linear scaling in $\nu_{e}$ (rather than $\nu_{e}^{1 / 3}$ ) and typically $\left(k_{\perp} r_{\perp}\right)^{2} \ll 1$ for electrons. We conclude that the effect of collisions on electron cyclotron and synchrotron radiation is significantly weakened by the applied magnetic field.

### 7.3.3. Emission due to collisions - bremsstrahlung

In this section we calculate collision-induced electromagnetic wave emission, i.e. bremsstrahlung, in the absence of an applied magnetic field. This amounts to calculating the two-time correlation function for the plasma current density including the influence of collisions. The analysis builds on the earlier material in §§7.3.1 and 7.3.2.

## DEFINITION.

$$
\begin{equation*}
\left.\bar{\varepsilon} \equiv \omega_{k}^{\ell} \hat{\boldsymbol{e}}^{*} \cdot \frac{\partial K}{\partial \omega} \cdot \hat{\boldsymbol{e}}\right|_{\omega_{k}^{\ell}}=\frac{\text { Total wave energy }}{\text { Electric field energy }}=O(1) \tag{7.142}
\end{equation*}
$$

From (7.131)

$$
\begin{equation*}
\left\langle\hat{\boldsymbol{e}}_{k}^{\ell *} \cdot j\left(\boldsymbol{k}, \omega_{k}^{\ell}\right) \hat{\boldsymbol{e}}_{k}^{\ell} \cdot j^{*}\left(\boldsymbol{k}^{\prime}, \omega_{k}^{\ell \prime}\right)\right\rangle=(2 \pi)^{4} \delta\left(\omega-\omega^{\prime}\right) \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) S^{j}(\boldsymbol{k}, \omega) . \tag{7.143}
\end{equation*}
$$

Then (7.130) becomes

$$
\begin{equation*}
\left|\dot{W}^{\ell}(\boldsymbol{k})\right|=\frac{4 \pi}{\bar{\varepsilon}} S^{j}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right), \quad \omega_{k}^{\ell}>0 . \tag{7.144}
\end{equation*}
$$

The current density in (7.143) is a sum over the particles,

$$
\begin{equation*}
\boldsymbol{j}(\boldsymbol{x}, t)=\sum_{i} e_{i} \boldsymbol{v}_{i}(t) \delta\left(\boldsymbol{x}-\boldsymbol{r}_{i}(t)\right) \rightarrow \boldsymbol{j}(\boldsymbol{k}, t)=\sum_{i} e_{i} \boldsymbol{v}_{i}(t) \exp \left[-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{i}(t)\right] \tag{7.145}
\end{equation*}
$$

where $\boldsymbol{r}_{i}=\boldsymbol{r}_{0}+\boldsymbol{s}_{i}$. The time derivative of the current density is

$$
\begin{equation*}
\frac{\partial}{\partial t} \boldsymbol{j}(\boldsymbol{k}, t)=\sum_{i} e_{i}\left[\dot{\boldsymbol{v}}_{i}(t)-\mathrm{i}\left(\boldsymbol{k} \cdot \boldsymbol{v}_{i}(t)\right) \boldsymbol{v}_{i}(t)\right] \exp \left[-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{i}(t)\right] \tag{7.146}
\end{equation*}
$$

We restrict our calculation of bremsstrahlung to long-wavelength, non-resonant modes: $k \ll \omega / v$ (dipole approximation). Thus, the second term in the square bracket in (7.146) is negligible; and the particle displacement compared to the wavelength is small inside the exponential in (7.146), i.e.

$$
\begin{equation*}
-\mathrm{i} \omega \mathbf{j}(\boldsymbol{k}, \omega) \approx \sum_{i} e_{i} \dot{\boldsymbol{v}}_{i}(\omega) \exp \left(-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{0 i}\right) \approx \exp \left(-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{0}\right) \sum_{i} e_{i} \dot{\boldsymbol{v}}_{i}(\omega) \tag{7.147}
\end{equation*}
$$

and we further assume that the spread of scattering centres is small compared to a wavelength. We next introduce some additional notation.

## DEFINITION.

$$
\begin{equation*}
\boldsymbol{S}_{i}(t) \equiv \boldsymbol{b}+\boldsymbol{v}\left(t-t_{0}\right), \quad \Pi(t) \equiv \sum_{i} e_{i} \boldsymbol{S}_{i}(t), \quad \ddot{\boldsymbol{\Pi}}(t)=\sum_{i} e_{i} \dot{\boldsymbol{v}}_{i}(t) \equiv \sum_{i} \ddot{\Pi}_{i}, \tag{7.148}
\end{equation*}
$$

where $\boldsymbol{b}$ is the impact parameter and is perpendicular to $\boldsymbol{v}$.
Hence,

$$
\begin{equation*}
-\mathrm{i} \omega \boldsymbol{j}(\boldsymbol{k}, \omega)=\exp \left(-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{0}\right) \ddot{\boldsymbol{\Pi}}(\omega) \tag{7.149}
\end{equation*}
$$

We note that electron-ion collisions produce dipole radiation. However, electronelectron collisions do not result in a net dipole moment in the collision; but the electron-electron collisions can produce quadrupole radiation. We will only consider the bremsstrahlung from electron-ion collisions. We calculate the Coulomb force on an electron colliding with an ion,

$$
\begin{equation*}
\ddot{\boldsymbol{\Pi}}_{i}=-e \dot{\boldsymbol{v}}_{i}=\frac{e^{2}}{m_{e}} \boldsymbol{E}_{e}^{i}=\frac{e^{2} e^{\mathrm{ion}}}{m_{e}} \frac{\boldsymbol{S}_{i}(t)}{S_{i}^{3}(t)} \tag{7.150}
\end{equation*}
$$

and Fourier transforming

$$
\begin{equation*}
\ddot{\boldsymbol{\Pi}}_{i}(\omega)=\frac{e^{2} e^{\mathrm{ion}}}{m_{e}} \exp \left(\mathrm{i} \omega t_{0}\right)\left[\int_{-\infty}^{\infty} \mathrm{d} t^{\prime} \exp \left(\mathrm{i} \omega t^{\prime}\right) \frac{\boldsymbol{b}+\boldsymbol{v} t^{\prime}}{\left(b^{2}+v^{2} t^{\prime 2}\right)^{3 / 2}}\right] . \tag{7.151}
\end{equation*}
$$

This expression is valid for small-angle scattering. For smaller $b$ and large angles, the electron trajectory is hyperbolic (see Panofsky and Phillips), but we will ignore this correction. We scale the variables inside the integral in (7.151) as follows:

$$
\begin{equation*}
\tau_{c} \equiv \frac{b}{v}, \quad \omega_{c} \equiv \frac{1}{\tau_{c}}=\frac{v}{b}, \quad \tau^{\prime}=\frac{t^{\prime}}{\tau_{c}}, \quad \omega^{\prime} \equiv \frac{\omega}{\omega_{c}}=\frac{\omega b}{v} . \tag{7.152}
\end{equation*}
$$

Using (7.152), (7.151) becomes

$$
\begin{equation*}
\ddot{\boldsymbol{\Pi}}_{i}(\omega)=\frac{e^{2} e^{\mathrm{ion}}}{m_{e}} \exp \left(\mathrm{i} \omega t_{0}\right)\left[\frac{\tau_{c}}{b^{2}} \int_{-\infty}^{\infty} \mathrm{d} \tau^{\prime} \exp \left(\mathrm{i} \omega^{\prime} \tau^{\prime}\right) \frac{\hat{\boldsymbol{b}}+\hat{\boldsymbol{v}} \tau^{\prime}}{\left(1+\tau^{\prime 2}\right)^{3 / 2}}\right] \tag{7.153}
\end{equation*}
$$

Lemmas.

$$
\begin{equation*}
\int_{-\infty}^{\infty} \mathrm{d} \tau^{\prime} \frac{\exp \left(\mathrm{i} \omega^{\prime} \tau^{\prime}\right)}{\left(1+\tau^{\prime 2}\right)^{3 / 2}}=2 \omega^{\prime} \mathrm{K}_{1}\left(\omega^{\prime}\right) \quad \int_{-\infty}^{\infty} \mathrm{d} \tau^{\prime} \frac{\tau^{\prime} \exp \left(\mathrm{i} \omega^{\prime} \tau^{\prime}\right)}{\left(1+\tau^{\prime 2}\right)^{3 / 2}}=2 \mathrm{i} \omega^{\prime} \mathrm{K}_{0}\left(\omega^{\prime}\right) \tag{7.154}
\end{equation*}
$$

where $\mathrm{K}_{0}$ and $\mathrm{K}_{1}$ are modified Bessel functions of the second kind. The asymptotic forms for $\mathrm{K}_{0}$ and $\mathrm{K}_{1}$ are

$$
\left.\begin{array}{c}
\mathrm{K}_{0}\left(\omega^{\prime}\right) \approx \ln \frac{1}{\omega^{\prime}} \quad \omega^{\prime} \ll 1,  \tag{7.155}\\
\mathrm{~K}_{1}\left(\omega^{\prime}\right) \approx \frac{1}{\omega^{\prime}}, \quad \omega^{\prime} \ll 1, \\
\mathrm{~K}_{n}\left(\omega^{\prime}\right) \approx \sqrt{\frac{\pi}{2 \omega^{\prime}}} \exp \left(-\omega^{\prime}\right), \quad \omega^{\prime} \gg 1
\end{array}\right\} .
$$

Equation (7.153) becomes

$$
\begin{equation*}
\ddot{\boldsymbol{\Pi}}_{i}(\omega)=\frac{e^{2} e^{\text {ion }}}{\frac{1}{2} m_{e} v^{2}} \exp \left(\mathrm{i} \omega t_{0}\right)\left[\hat{\boldsymbol{b}} \omega^{\prime} \mathrm{K}_{1}\left(\omega^{\prime}\right)+\hat{\boldsymbol{v}} \mathrm{i} \omega^{\prime} \mathrm{K}_{0}\left(\omega^{\prime}\right)\right] \tag{7.156}
\end{equation*}
$$

We introduce the definition $b_{0} \equiv e^{2} /\left(\frac{1}{2} m_{e} v^{2}\right)$ and use (7.149)-(7.156) to obtain

$$
\begin{align*}
\left\langle j(\boldsymbol{k}, \omega) j^{*}\left(\boldsymbol{k}^{\prime \prime}, \omega^{\prime \prime}\right)\right\rangle= & \left(\frac{e^{2} e^{\text {ion }}}{\frac{1}{2} m_{e} v^{2}}\right)^{2} \frac{(2 \pi)^{4}}{V T} \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime \prime}\right) \delta\left(\omega-\omega^{\prime \prime}\right) \\
& \left.\times\left.\langle |\left[\hat{\boldsymbol{e}}^{*} \cdot \hat{\boldsymbol{b}} \mathrm{~K}_{1}\left(\omega^{\prime}\right)+\hat{\boldsymbol{e}}^{*} \cdot \hat{\boldsymbol{v}} \mathrm{i} \mathrm{~K}_{0}\left(\omega^{\prime}\right)\right]\right|^{2}\right\rangle_{\hat{\boldsymbol{b}}, \hat{v}} . \tag{7.157}
\end{align*}
$$

In deriving (7.157) we made use of the independence of the averaging with respect to $\boldsymbol{r}_{0}$ and $t_{0}$ which leads to the following reductions:

$$
\begin{align*}
& \left\langle\exp \left(-\mathrm{i}\left(\boldsymbol{k} \cdot \boldsymbol{r}_{0}-\omega t_{0}\right)+\mathrm{i}\left(\boldsymbol{k}^{\prime} \cdot \boldsymbol{r}_{0}-\omega^{\prime} t_{0}\right)\right)\right\rangle_{\boldsymbol{r}_{0}, t_{0}}=\left\langle\exp \left(-\mathrm{i}\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{r}_{0}+\mathrm{i}\left(\omega-\omega^{\prime}\right) t_{0}\right)\right\rangle_{\boldsymbol{r}_{0}, t_{0}} \\
& = \\
& \quad\left\langle\exp \left(-\mathrm{i}\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{r}_{0}\right)\right\rangle_{\boldsymbol{r}_{0}}\left\langle\exp \left(\mathrm{i}\left(\omega-\omega^{\prime}\right) t_{0}\right)\right\rangle_{t_{0}} \\
& \quad\left\langle\exp \left(-\mathrm{i}\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{r}_{0}\right)\right\rangle_{\boldsymbol{r}_{0}}=\frac{1}{V} \int \mathrm{~d}^{3} r \mathrm{e}^{\mathrm{i}\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{r}}=\frac{(2 \pi)^{3} \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right)}{V}  \tag{7.158}\\
& \quad\left\langle\exp \left(\mathrm{i}\left(\omega-\omega^{\prime}\right) t_{0}\right)\right\rangle_{t_{0}}=\frac{1}{T} \int \mathrm{~d}^{3} t \mathrm{e}^{\mathrm{i}\left(\omega-\omega^{\prime}\right) t}=\frac{(2 \pi)^{3} \delta\left(\omega-\omega^{\prime}\right)}{T} .
\end{align*}
$$

We use (7.131) and (7.158), and sum over the collisions $N_{c}$ that take place in the volume $V$ and time period $T$ with identical values of $\boldsymbol{b}$ and $\boldsymbol{v}$ to deduce

$$
\begin{equation*}
\left.S^{j}(\boldsymbol{k}, \omega)=\left.\left(\frac{e^{2} e^{\text {ion }}}{\frac{1}{2} m_{e} v^{2}}\right)^{2} \frac{N_{c}(V, T)}{V T}\langle |\left[\hat{\boldsymbol{e}}^{*} \cdot \hat{\boldsymbol{b}} \mathrm{~K}_{1}\left(\omega^{\prime}\right)+\hat{\boldsymbol{e}}^{*} \cdot \hat{\boldsymbol{v}} \mathrm{i} \mathrm{~K}_{0}\left(\omega^{\prime}\right)\right]\right|^{2}\right\rangle_{\hat{\boldsymbol{b}}, \hat{\boldsymbol{v}}} . \tag{7.159}
\end{equation*}
$$

We now replace $N_{c} /(V T)$ with $n_{c} \mathrm{~d} v \mathrm{~d} b$ in (7.159) and integrate over $v$ and $b$. In doing this integral, we make use of two identities,

$$
\begin{equation*}
\left\langle\hat{\boldsymbol{e}}^{*} \cdot \hat{\boldsymbol{b}} \hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{b}}^{*}\right\rangle=\frac{1}{3}, \quad\left\langle\hat{\boldsymbol{e}}^{*} \cdot \hat{\boldsymbol{b}} \hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{v}}^{*}\right\rangle=0 \tag{7.160}
\end{equation*}
$$

EXERCISE. Verify the relations in (7.160). Note that $\boldsymbol{b}$ and $\boldsymbol{v}$ are always perpendicular to one another, and $\boldsymbol{b}$ has no preferred direction.

Hence,

$$
\begin{equation*}
S^{j}(\boldsymbol{k}, \omega)=\int \mathrm{d} v \int \mathrm{~d} b\left(\frac{e^{2} e^{\text {ion }}}{\frac{1}{2} m_{e} v^{2}}\right)^{2} n_{c}(v, b)\left[\frac{1}{3} \mathrm{~K}_{1}^{2}\left(\omega^{\prime}\right)+\frac{1}{3} \mathrm{~K}_{0}^{2}\left(\omega^{\prime}\right)\right] \tag{7.161}
\end{equation*}
$$

The number of collisions per unit volume per unit time with speed $v$ and impact parameter $b$ in intervals $\mathrm{d} v$ and $\mathrm{d} b$ is determined by the collision rate and is given by,

$$
\begin{align*}
n_{c} \mathrm{~d} v \mathrm{~d} b & =n_{i} \sigma v=n_{i} v 2 \pi b \mathrm{~d} b \Rightarrow \iint \mathrm{~d} b \mathrm{~d}^{3} v f_{e}(\boldsymbol{v}) n_{i} v 2 \pi b \\
& =\iint \mathrm{d} b \mathrm{~d}^{3} v g_{e}(\boldsymbol{v}) n_{e} n_{i} v 2 \pi b=\iint \mathrm{d} b d v 4 \pi v^{2} g_{e}(v) n_{e} n_{i} v 2 \pi b, \tag{7.162}
\end{align*}
$$

where we have then integrated over velocities and impact parameters. With the use of (7.152) and (7.162), (7.161) becomes

$$
\begin{align*}
S^{j}(\boldsymbol{k}, \omega) & =\frac{32}{3} \pi^{2} \frac{\left(e^{2} e^{\mathrm{ion}}\right)^{2}}{m_{e}^{2}} n_{e} n_{i} \int \frac{\mathrm{~d} v}{v} \int b \mathrm{~d} b\left[\mathrm{~K}_{1}^{2}\left(\omega^{\prime}\right)+\mathrm{K}_{0}^{2}\left(\omega^{\prime}\right)\right] \\
& =\frac{32}{3} \pi^{2} \frac{\left(e^{2} e^{\mathrm{ion}}\right)^{2}}{m_{e}^{2}} n_{e} n_{i} \int \frac{\mathrm{~d} v}{v} \int_{\omega_{\max }^{\prime}}^{\omega_{\min }^{\prime}} \omega^{\prime} \mathrm{d} \omega^{\prime} v^{2}\left[\mathrm{~K}_{1}^{2}\left(\omega^{\prime}\right)+\mathrm{K}_{0}^{2}\left(\omega^{\prime}\right)\right] \tag{7.163}
\end{align*}
$$

We use the identity

$$
\begin{equation*}
\mathrm{K}_{0}^{2}+\mathrm{K}_{1}^{2}=-\frac{1}{\omega^{\prime}} \frac{\mathrm{d}}{\mathrm{~d} \omega^{\prime}}\left(\omega^{\prime} \mathrm{K}_{0} \mathrm{~K}_{1}\right) \tag{7.164}
\end{equation*}
$$

to do the $\omega^{\prime}$ integral in (7.164) and include the effects of Debye shielding to restrict the upper bound of the integral to $b<\lambda_{D}$, i.e. $\omega^{\prime}<(\omega / v) \lambda_{D}$. For large $\omega^{\prime}$ we have

$$
K_{n} \sim \sqrt{\frac{\pi}{2 \omega^{\prime}}} \mathrm{e}^{-\omega^{\prime}} \ll 1
$$

The upper limit $\omega_{\min }^{\prime}$ of the $\omega^{\prime}$ integral in (7.163) (minimum impact parameter) is determined by either the bound electron limit $b \sim e^{2} / m v^{2}$ or quantum mechanics $b \sim$ $\lambda \sim \hbar / m v$ whichever is larger. For temperatures less than 1 Rydberg ( $\sim 13.6 \mathrm{eV}$ ) the former limit pertains, and for higher temperatures the de Broglie wavelength sets the minimum impact parameter. For high-temperature plasmas, quantum mechanics sets the lower limit on $b$; hence,

$$
\begin{equation*}
\frac{1}{\omega_{\min }^{\prime}} \sim \frac{v}{\omega} \frac{m v}{\hbar}=\frac{m v^{2}}{\hbar \omega} \gg 1 \tag{7.165}
\end{equation*}
$$

For small $\omega^{\prime}$ the small argument limits in (7.155) determine that the upper limit of the $\omega^{\prime}$ integral in (7.163) is dominant,

$$
\begin{equation*}
S^{j}(\boldsymbol{k}, \omega)=\frac{32}{3} \pi^{2} \frac{\left(e^{2} e^{\mathrm{ion}}\right)^{2}}{m_{e}^{2} \omega^{2}} n_{e} n_{i} \int v \mathrm{~d} v g_{e}(v) \ln \frac{m v^{2}}{\hbar \omega} \tag{7.166}
\end{equation*}
$$

We see that the integral over impact parameter is insensitive to the maximum impact parameter cutoff; thus, the plasma shielding is irrelevant.

Example. For a Maxwellian plasma we evaluate the integral in (7.166) as follows:

$$
\begin{align*}
& g_{e}(v)=\left(\frac{m}{2 \pi T_{e}}\right)^{3 / 2} \mathrm{e}^{-m v^{2} / 2 T_{e}} \Rightarrow \varepsilon \equiv \frac{\frac{1}{2} m v^{2}}{T_{e}} \\
& \int_{0}^{\infty} \mathrm{d} \varepsilon \mathrm{e}^{-\varepsilon} \ln \left(\varepsilon \frac{2 T_{e}}{\hbar \omega}\right)=\int_{0}^{\infty} \mathrm{d} \varepsilon \mathrm{e}^{-\varepsilon}\left[\ln \varepsilon+\ln \frac{2 T_{e}}{\hbar \omega}\right] \\
& \quad=-0.577+\ln \frac{2 T_{e}}{\hbar \omega}=\ln \frac{2 T_{e}}{1.781 \hbar \omega} \approx \ln \frac{T_{e}}{\hbar \omega} . \tag{7.167}
\end{align*}
$$

We note that 0.577 is Euler's constant. Equation (7.166) then becomes

$$
\begin{equation*}
S^{j}(\boldsymbol{k}, \omega)=\frac{1}{2 \pi} v_{e} T_{e} \frac{\omega_{p}^{2}}{\omega^{2}} \frac{\ln \left(\frac{T_{e}}{\hbar \omega}\right)}{\ln \Lambda}, \quad v_{e} \equiv \frac{4}{3} \sqrt{2 \pi} \frac{n_{i}\left(e e^{\mathrm{ion}}\right)^{2} \ln \Lambda}{\sqrt{m_{e}} T_{e}^{3 / 2}} \tag{7.168}
\end{equation*}
$$

In this treatment we see that bremsstrahlung involves radiation of high-frequency, longwavelength modes in order that the radiation is weakly damped by the plasma. Given (7.168) the wave emission is

$$
\begin{equation*}
\dot{W}_{k}^{\ell}=\frac{4 \pi}{\bar{\varepsilon}} S^{j}\left(\boldsymbol{k}, \omega_{k}^{\ell}\right), \tag{7.169}
\end{equation*}
$$

where $\bar{\varepsilon}$ is given by (7.142). For emission of longitudinal waves $\bar{\varepsilon} \rightarrow \omega \partial \varepsilon / \partial \omega$.
EXAMPLE. The Langmuir wave (electron plasma wave $=\mathrm{EPW}$ ) emission just due to collisions (ignoring Landau emission for the moment) is,

$$
\begin{equation*}
\dot{W}_{k}^{\mathrm{EPW}} \approx \frac{\omega_{p}^{4}}{\omega^{4}} v_{e} T_{e} \frac{\ln \left(\frac{T_{e}}{\hbar \omega_{p}}\right)}{\ln \Lambda}, \tag{7.170}
\end{equation*}
$$

where

$$
\bar{\varepsilon} \rightarrow \omega \partial \varepsilon / \partial \omega \approx 2 \omega_{p}^{2} / \omega^{2} \approx 2, \quad \omega \approx \omega_{p}, \quad \text { and } \quad \Lambda \approx \frac{\lambda_{D}}{\lambda}=\sqrt{\frac{T_{e}}{4 \pi n_{e} e^{2}}} \sqrt{\frac{2 m_{e} T_{e}}{\hbar^{2}}} \approx \frac{T_{e}}{\hbar \omega_{p}}
$$

Hence,

$$
\begin{equation*}
\dot{W}_{k}^{\mathrm{EPW}} \approx \frac{\omega_{p}^{4}}{\omega^{4}} v_{e} T_{e} \approx \nu_{e} T_{e} . \tag{7.171}
\end{equation*}
$$

If resonant effects are negligible, i.e. $g(v=\omega / k) \ll 1$, then the wave damping is solely due to collisions, $\left|\gamma_{k}\right| \approx \frac{1}{2} \nu_{e}$; and collisional damping of the Langmuir waves can balance emission giving a Rayleigh-Jeans law

$$
\begin{equation*}
W_{k}=\frac{\dot{W}_{k}}{2\left|\gamma_{k}\right|}=\frac{\dot{W}_{k}}{v_{e}} \approx T_{e} . \tag{7.172}
\end{equation*}
$$

EXERCISE. Calculate the ratio of the collisional wave emission for Langmuir waves to the corresponding Cerenkov emission (see § 7.1.1).

Example. For transverse waves in a cold plasma

$$
\left.\begin{array}{c}
K \rightarrow \varepsilon-\frac{k^{2} c^{2}}{\omega^{2}}=1-\frac{\omega_{p}^{2}}{\omega^{2}}-\frac{k^{2} c^{2}}{\omega^{2}}=1-\frac{\omega_{p}^{2}+k^{2} c^{2}}{\omega^{2}}  \tag{7.173}\\
\rightarrow \omega \frac{\partial K}{\partial \omega}=2 \frac{\omega_{p}^{2}+k^{2} c^{2}}{\omega^{2}}=2
\end{array}\right\}
$$

The ratio of the wave energy to electric field energy for transverse waves is two, the same as for Langmuir waves; and this ratio is also two in a vacuum where the electric field energy and the magnetic energy are the same. In the plasma there is finite mechanical energy in the particles, but the magnetic energy in the transverse wave decreases. The transverse-wave emission is given by

$$
\begin{equation*}
\dot{W}_{k}^{\mathrm{trans}} \approx \frac{\omega_{p}^{2}}{\omega_{k}^{2}} v_{e} T_{e} \frac{\ln \left(\frac{T_{e}}{\hbar \omega_{k}}\right)}{\ln \left(\frac{T_{e}}{\hbar \omega_{p}}\right)} \tag{7.174}
\end{equation*}
$$

If we amend our definition of the collision frequency in (7.170) as follows:

$$
\begin{equation*}
v_{e}\left(\omega_{k}\right) \equiv v_{e} \frac{\ln \left(\frac{T_{e}}{\hbar \omega_{k}}\right)}{\ln \Lambda=\ln \frac{T_{e}}{\hbar \omega_{p}}}=\frac{4}{3} \sqrt{2 \pi} \frac{n_{i}\left(e e^{\mathrm{ion}}\right)^{2} \ln \frac{T_{e}}{\hbar \omega_{k}}}{\sqrt{m_{e}} T_{e}^{3 / 2}} \tag{7.175}
\end{equation*}
$$

Then, by adjusting the logarithmic factors, the collisional wave damping can be written compactly as

$$
\begin{equation*}
\left|\gamma_{k}^{\text {coll }}\right|=\frac{1}{2} \nu_{e}\left(\omega_{k}\right) \frac{\omega_{p}^{2}}{\omega_{k}^{2}} \tag{7.176}
\end{equation*}
$$

and one recovers the Rayleigh-Jeans law,

$$
\begin{equation*}
0=\frac{\mathrm{d} W_{k}}{\mathrm{~d} t}=\dot{W}_{k}-\left|2 \gamma_{k}\right| W_{k} \rightarrow W_{k}=T_{e} \tag{7.177}
\end{equation*}
$$

Exercise. Calculate the collisional wave emission in a magnetized plasma and check whether the Rayleigh-Jeans law is recovered once again.

Example. Generalization to non-Maxwellian velocity distribution functions - in going from (7.162) to (7.167), there is a velocity-space integration over an isotropic distribution function,

$$
\begin{align*}
S^{j}(\boldsymbol{k}, \omega) & \propto \int \mathrm{d}^{3} v g_{e}(\boldsymbol{v}) \ln \frac{m v^{2}}{\hbar \omega} \sim \int \mathrm{~d} v v g_{e}(v) \ln \frac{m v^{2}}{\hbar \omega} \\
& \sim \int \mathrm{~d}^{3} v \frac{1}{v} g_{e}(v) \ln \frac{2 T_{e}}{\hbar \omega} \sim \ln \frac{2 T_{e}}{\hbar \omega}\left\langle\frac{1}{v}\right\rangle \tag{7.178}
\end{align*}
$$

Hence, the generalization of bremsstrahlung to a non-Maxwellian velocity distribution is

$$
\begin{equation*}
\dot{W}_{\text {Bremss }}=\left(\dot{W}_{\text {Bremss }}\right)^{\text {Maxw }} \frac{\left\langle v^{-1}\right\rangle}{\left\langle v^{-1}\right\rangle^{\text {Maxw }}} . \tag{7.179}
\end{equation*}
$$

How is the collisional damping of the emitted waves modified by a non-Maxwellian velocity distribution? For Coulomb collisions

$$
\begin{equation*}
\gamma_{\mathrm{coll}} \propto v_{e i} \approx n_{i}\langle\sigma v\rangle \propto n_{i}\left\langle\frac{1}{v^{4}} v\right\rangle \propto n_{i}\left\langle v^{-3}\right\rangle \rightarrow \gamma_{\mathrm{coll}} \propto v_{e i}=\left(v_{e i}\right)^{\mathrm{Maxw}} \frac{\left\langle v^{-3}\right\rangle}{\left\langle v^{-3}\right\rangle^{\mathrm{Maxw}}} \tag{7.180}
\end{equation*}
$$

The $\left\langle v^{-3}\right\rangle$ moment would be logarithmically divergent at its lower limit were it not for being cutoff at $v_{\text {th }} / \Lambda$ instead of 0 ,

$$
\begin{equation*}
\left\langle v^{-3}\right\rangle=4 \pi \int_{0}^{\infty} v^{2} \mathrm{~d} v v^{-3} g_{e}(v)=4 \pi \int_{0}^{\infty} \mathrm{d} v v^{-1} g_{e}(v) \rightarrow 4 \pi \int_{v_{\text {lh }} / \Lambda}^{\infty} \mathrm{d} v v^{-1} g_{e}(v) \sim \ln \Lambda . \tag{7.181}
\end{equation*}
$$

We then use the results of (7.179) and (7.180) to obtain

$$
\begin{equation*}
W_{k}=\frac{\dot{W}_{\text {Bremss }}}{2\left|\gamma_{\text {coll }}\right|}=\frac{\left\langle v^{-1}\right\rangle}{\left\langle v^{-3}\right\rangle}\left[\frac{\left\langle v^{-1}\right\rangle^{\text {Maxw }}}{\left\langle v^{-3}\right\rangle^{\text {Maxw }}}\right]^{-1} T_{e} . \tag{7.182}
\end{equation*}
$$

Thus, $W_{k}$ cannot differ significantly from $T_{e}$.

We return to (7.174) and (7.175) to calculate the integrated bremsstrahlung transverse radiation,

$$
\begin{align*}
\dot{W}_{\text {Bremss }} & =\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \dot{W}_{\boldsymbol{k}}=\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} v_{e}(\omega) \frac{\omega_{p}^{2}}{\omega^{2}} T_{e} \times 2 \text { (polarizations) } \\
& =\frac{\omega_{p}^{2}}{(2 \pi)^{3}} 2 T_{e} \int \frac{4 \pi k^{2} \mathrm{~d} k}{\omega^{2}} v_{e}(\omega)=\frac{1}{\pi^{2}} v_{e} T_{e}\left(\frac{\omega_{p}}{c}\right)^{3} \int \frac{\mathrm{~d} \omega}{\omega} \sqrt{\frac{\omega^{2}}{\omega_{p}^{2}}-1 \frac{\ln \left(\frac{\omega_{\hbar}}{\omega}\right)}{\ln \left(\frac{\omega_{\hbar}}{\omega_{p}}\right)}}, \tag{7.183}
\end{align*}
$$

where we have made use of $\omega^{2}=k^{2} c^{2}+\omega_{p}^{2}$ and the quantum cutoff at high frequencies: $\hbar \omega_{\hbar} \equiv T_{e}, \omega_{\hbar} / \omega_{p}=\Lambda=\lambda_{D} / \lambda$. Ordinarily, $\omega_{\bar{h}} \gg \omega_{p}$. Introducing the notation $\dot{W}_{\text {Bremss }} \equiv$ $\int \mathrm{d} \omega \dot{W}_{\text {Bremss }}(\omega)$, we see from (7.183) that $\dot{W}_{\text {Bremss }}(\omega)$ is zero below $\omega=\omega_{p}$ because the transverse waves are evanescent, becomes positive for higher frequencies, and then is relatively flat until it cuts off at $\omega_{\hbar}$. For the frequencies near the cutoff a Bethe-Heitler calculation is needed (Bethe \& Maximon 1954). To do the integral in (7.183) we note that

$$
\int_{1}^{\Lambda} \frac{\mathrm{d} \Omega}{\Omega} \sqrt{\Omega^{2}-1}\left[1-\frac{\ln \Omega}{\ln \Lambda}\right] \approx \frac{\Lambda}{\ln \Lambda}, \quad \Lambda \gg 1, \quad \Omega \equiv \frac{\omega}{\omega_{p}}
$$

Finally, the bremsstrahlung transverse-wave-emission rate can then be expressed as

$$
\begin{equation*}
\dot{W}_{\mathrm{Bremss}} \approx \frac{n_{e} n_{i} T_{e}^{1 / 2} e^{4}\left(e^{\mathrm{ion}}\right)^{2}}{\hbar m_{e}^{3 / 2} c^{3}} \tag{7.184}
\end{equation*}
$$

times a numerical factor due to important quantum mechanical corrections that we have ignored. For an optically thin medium one can observe the bremsstrahlung spectrum. For a thick medium, quantum mechanics takes over, and one gets black-body radiation and the Stefan-Boltzmann law.
[Editor's note: charged particles lose energy in a plasma due to collisional friction, resonant wave emission and radiation. Energy loss for a non-relativistic electron due to bremsstrahlung is less than the kinetic energy loss due to collisional friction.]

### 7.3.4. Dawson-Oberman theory of resistivity including scattering due to waves and particle discreteness

The calculation of the frequency dependence of the plasma resistivity in the presence of electric fields must include wave scattering by discrete fluctuations and particles. We follow the theory of Dawson \& Oberman (1962). Consider a very-long-wavelength wave,

$$
\begin{equation*}
\boldsymbol{E}(\boldsymbol{x}, t)=\boldsymbol{E}_{0} \sin \left(\boldsymbol{k}_{0} \cdot \boldsymbol{x}-\omega_{0} t+\theta\right) \approx \boldsymbol{E}_{0} \sin \left(\omega_{0} t\right), \quad k_{0} \ll k_{D} \tag{7.185}
\end{equation*}
$$

All of the electrons oscillate together in the field, and the ions oscillate the other way. Define the oscillatory frame of the electrons by the velocity coordinate $\boldsymbol{w}(t)$,

$$
\begin{equation*}
\boldsymbol{w}(t)=\frac{e}{m_{e} \omega_{0}} \boldsymbol{E}_{0} \cos \omega_{0} t, \quad m_{e} \dot{\boldsymbol{w}}=-e \boldsymbol{E}_{0} \sin \omega_{0} t \tag{7.186}
\end{equation*}
$$

The electron acceleration in the oscillatory frame will see the real forces and a pseudoforce,

$$
\begin{equation*}
m_{e} \dot{\boldsymbol{v}}=-m_{e} \dot{\boldsymbol{w}}-e \boldsymbol{E}_{0} \sin \omega_{0} t-e \boldsymbol{E}^{\text {other }}=-e \boldsymbol{E}^{\text {other }} \tag{7.187}
\end{equation*}
$$

For the ions we have

$$
\begin{align*}
m_{i} \dot{\boldsymbol{v}} & =-m_{i} \dot{\boldsymbol{w}}+e \boldsymbol{E}_{0} \sin \omega_{0} t+e \boldsymbol{E}^{\text {other }} \rightarrow \dot{\boldsymbol{v}} \\
& =-\dot{\boldsymbol{w}}+\frac{e}{m_{i}} \boldsymbol{E}_{0} \sin \omega_{0} t+\frac{e}{m_{i}} \boldsymbol{E}^{\text {other }}=\frac{e}{m_{e}} \boldsymbol{E}_{0} \sin \omega_{0} t+\frac{e}{m_{i}} \boldsymbol{E}_{0} \sin \omega_{0} t+\frac{e}{m_{i}} \boldsymbol{E}^{\text {other }} \\
& \approx \frac{e}{m_{e}} \boldsymbol{E}_{0} \sin \omega_{0} t+\frac{e}{m_{i}} \boldsymbol{E}^{\text {other }}+O\left(\frac{m_{e}}{m_{i}}\right) \tag{7.188}
\end{align*}
$$

In the laboratory frame of reference the equations of motion for the electrons yield

$$
\begin{equation*}
m_{e} \ddot{\boldsymbol{r}}_{e}=-e \boldsymbol{E}_{0} \sin \omega_{0} t \rightarrow \boldsymbol{r}_{e}(t)=\frac{e}{m_{e} \omega_{0}^{2}} \boldsymbol{E}_{0} \sin \omega_{0} t \tag{7.189}
\end{equation*}
$$

while the ion motion in the oscillatory frame of reference is

$$
\begin{equation*}
\boldsymbol{r}_{i}(t)=-\frac{e}{m_{e} \omega_{0}^{2}} \boldsymbol{E}_{0} \sin \omega_{0} t \tag{7.190}
\end{equation*}
$$

absent 'other fields' and microscopic fields. The 'other fields' satisfy Maxwell's equations combined with the Vlasov or the Lenard-Balsescu equations. In the electron oscillating frame the ions move up and down, with a dipole moment that is $2\left(e^{2} E_{0} / m_{e} \omega_{0}^{2}\right)$. There is dipole radiation in all directions, but due to the randomness of positions (say) the radiation is incoherent. Thus, the original wave has been scattered or partially scattered into dipole radiation in the random-phase approximation.

Suppose one ion wave is present. Then over and above graininess there is a density correlation. Thus, there is some coherence and enhancement of the radiation. An electron wave can scatter off the ion wave into a scattered electron wave. If instead there is turbulence (due to an instability or other mechanism) so that there are many waves present, there will be multi-enhanced scattering in all directions. This is observed in laboratory and ionospheric experiments.

We return to the ion motion in the oscillating frame, equation (7.190), and construct the Fourier-transformed charge density of a singly charged ion,

$$
\begin{equation*}
\rho_{0}(\boldsymbol{k}, t)=e \exp \left(-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{i}(t)\right) \approx e\left(1-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{i}(t)\right) \tag{7.191}
\end{equation*}
$$

where we have expanded the exponential for $k r_{i} \ll 1$ in the dipole approximation. For electrostatic modes, the shielded electric potential can be calculated from the testparticle charge density using Poisson's equation,

$$
\begin{equation*}
\phi(\boldsymbol{k}, \omega)=\frac{4 \pi}{k^{2}} \frac{\rho_{0}(\boldsymbol{k}, \omega)}{\varepsilon(\boldsymbol{k}, \omega)}=\frac{4 \pi}{k^{2}} \frac{e^{2}}{2 m_{e} \omega_{0}^{2}} \frac{\boldsymbol{k} \cdot \boldsymbol{E}_{0}}{\varepsilon(\boldsymbol{k}, \omega)} 2 \pi\left[\delta\left(\omega+\omega_{0}\right)-\delta\left(\omega-\omega_{0}\right)\right] . \tag{7.192}
\end{equation*}
$$

The electric field at the ion position is then

$$
\begin{aligned}
\boldsymbol{E}\left(\boldsymbol{r}_{0}(t), t\right) & =\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d} \omega}{2 \pi} \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{0}(t)} \mathrm{e}^{-\mathrm{i} \omega t}(-\mathrm{i} \boldsymbol{k}) \phi(\boldsymbol{k}, \omega) \\
& \approx \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d} \omega}{2 \pi}\left(1+\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{0}(t)\right) \mathrm{e}^{-\mathrm{i} \omega t}(-\mathrm{i} \boldsymbol{k}) \phi(\boldsymbol{k}, \omega)
\end{aligned}
$$

$$
\begin{equation*}
\approx \frac{4 \pi e^{2}}{2 m_{e} \omega_{0}^{2}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}}\left(-\mathrm{i} \hat{\boldsymbol{k}} \hat{\boldsymbol{k}} \cdot \boldsymbol{E}_{0}\right)\left[\frac{\mathrm{e}^{\mathrm{i} \omega_{0} t}}{\varepsilon\left(\boldsymbol{k},-\omega_{0}\right)}-\frac{\mathrm{e}^{-\mathrm{i} \omega_{0} t}}{\varepsilon\left(\boldsymbol{k}, \omega_{0}\right)}\right] . \tag{7.193}
\end{equation*}
$$

We assume that the unperturbed plasma is isotropic in order to simplify and combine terms in (7.193). Then $\varepsilon\left(\boldsymbol{k},-\omega_{0}\right)=\varepsilon\left(-\boldsymbol{k},-\omega_{0}\right)=\varepsilon^{*}\left(\boldsymbol{k}, \omega_{0}\right)$. Hence,

$$
\begin{align*}
\boldsymbol{E}\left(\boldsymbol{r}_{0}(t), t\right) & \approx-\frac{4 \pi e^{2}}{m_{e} \omega_{0}^{2}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}}\left(\hat{\boldsymbol{k}} \hat{\boldsymbol{k}} \cdot \boldsymbol{E}_{0}\right) \operatorname{Im}\left[\frac{\mathrm{e}^{-\mathrm{i} \omega_{0} t}}{\varepsilon\left(\boldsymbol{k}, \omega_{0}\right)}\right] \\
& =-\frac{4 \pi e^{2}}{m_{e} \omega_{0}^{2}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}}\left(\frac{1}{3} \boldsymbol{I} \cdot \boldsymbol{E}_{0}\right) \operatorname{Im}\left[\frac{\mathrm{e}^{-\mathrm{i} \omega_{0} t}}{\varepsilon\left(k, \omega_{0}\right)}\right] \\
& =\frac{4 \pi e^{2}}{3 m_{e} \omega_{0}^{2}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \boldsymbol{E}_{0} \operatorname{Im}\left[\frac{\mathrm{e}^{-\mathrm{i} \omega_{0} t}}{\varepsilon\left(k, \omega_{0}\right)}\right] . \tag{7.194}
\end{align*}
$$

The work done on the plasma by the fields is

$$
\begin{equation*}
-\dot{W} \equiv e \boldsymbol{E}\left(\boldsymbol{r}_{0}(t), t\right) \cdot \dot{\boldsymbol{r}}_{0}(t) \Longrightarrow \dot{W}=-\frac{2 \pi \mathrm{e}^{4}}{3 m_{e}^{2} \omega_{0}^{3}} \boldsymbol{E}_{0}^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \operatorname{Im}\left[\frac{1}{\varepsilon\left(k, \omega_{0}\right)}\right] . \tag{7.195}
\end{equation*}
$$

The resonant part in (7.195) is interpreted as the wave-emission part (normal modes), while the non-resonant part is interpreted as the resistive component. We first examine the resonant contribution,

$$
\begin{equation*}
\operatorname{Im}\left[\frac{1}{\varepsilon\left(k, \omega_{0}\right)}\right]=\operatorname{Im}\left[\frac{1}{\varepsilon_{R}+\mathrm{i} \varepsilon_{I}}\right]=-\pi \delta\left(\varepsilon_{R}\right) \operatorname{sign} \varepsilon_{I}=-\pi \delta\left(\varepsilon_{R}\left(k, \omega_{0}\right)\right) \tag{7.196}
\end{equation*}
$$

taking the positive $\operatorname{sign} \varepsilon_{I}$ for stable modes. The integral over wavenumber space in (7.195) can be performed by using the relations,

$$
\begin{equation*}
\delta\left(\varepsilon_{R}\left(k, \omega_{0}\right)\right)=\frac{\delta\left(k-k\left(\omega_{0}\right)\right)}{\left|\frac{\partial \varepsilon_{R}(k, \omega)}{\partial k}\right|_{k\left(\omega_{0}\right)}} \quad \text { and } \quad \omega_{0}^{2}=\omega_{p}^{2}+3 k^{2} v_{e}^{2} \Rightarrow k\left(\omega_{0}\right)=\frac{1}{\sqrt{3} v_{e}} \sqrt{\omega_{0}^{2}-\omega_{p}^{2}} \tag{7.197}
\end{equation*}
$$

Hence, the energy radiated into the weakly damped, resonant radiation fields derived from (7.195) to (7.197) is

$$
\begin{equation*}
\dot{W}_{\mathrm{rad}}=\frac{1}{18 \sqrt{3}}\left(\frac{e^{2}}{T_{e}}\right)^{2}\left(\frac{\omega_{p}}{\omega_{0}}\right)^{3} \sqrt{\left(\frac{\omega_{p}}{\omega_{0}}\right)^{2}-1} v_{e} E^{2}, \quad \omega_{0} \geqslant \omega_{p} \tag{7.198}
\end{equation*}
$$

In the oscillating frame we have radiated waves travelling out in all directions. In the limit of small-amplitude fields, the response field and the radiated waves can be superposed.

### 7.3.5. Scattering cross-sections for waves calculated from Dawson-Oberman theory

The scattering cross-section for the incident waves scattering into the emitted radiation can be defined and calculated as follows:

$$
\begin{equation*}
\sigma \equiv \frac{\text { energy radiated per unit time }}{\text { incident energy flux density }}=\frac{\dot{W}_{\mathrm{rad}}}{\frac{1}{2} \frac{E_{0}^{2}}{8 \pi} \bar{\varepsilon} V_{g}^{\mathrm{inc}}} \tag{7.199}
\end{equation*}
$$

where the $1 / 2$ in the denominator takes into account a time average of $\left(\boldsymbol{E}_{0} \sin \omega_{0} t\right)^{2}$ and $V_{g}=3 k^{\mathrm{inc}} v_{e}^{2} / \omega_{p}$ for incident Langmuir waves and $V_{g}=c \sqrt{1-\left(\omega_{p}^{2} / \omega_{0}^{2}\right)}$ for transverse waves.

The scattering cross-section for transverse waves scattered into longitudinal waves is

$$
\begin{equation*}
\sigma_{t \rightarrow \ell}\left(\omega_{0}\right)=\frac{4 \pi}{9 \sqrt{3}}\left(\frac{e^{2}}{T_{e}}\right)^{2}\left(\frac{\omega_{p}}{\omega_{0}}\right)^{2} \frac{v_{e}}{c} \tag{7.200}
\end{equation*}
$$

For longitudinal waves scattered into longitudinal wave the cross-section is

$$
\begin{equation*}
\sigma_{t \rightarrow \ell}\left(\omega_{0}\right)=\frac{4 \pi}{27}\left(\frac{e^{2}}{T_{e}}\right)^{2}\left(\frac{\omega_{p}}{\omega_{0}}\right)^{3} \tag{7.201}
\end{equation*}
$$

In order that the scattered longitudinal wave be weakly damped $\omega_{p} / \omega \approx O(1)$. We note that for comparison the cross-section for particle scattering in a plasma is $O(1)\left(e^{2} / T_{e}\right)^{2} \ln \Lambda$.

The cross-section for transverse waves scattering into transverse waves is calculated with the help of the formalism presented in previous lectures yielding the Thomson cross-section,

$$
\begin{equation*}
\sigma_{t \rightarrow t}\left(\omega_{0}\right)=\frac{8 \pi}{3}\left(\frac{e^{2}}{m_{e} c^{2}}\right)^{2} \tag{7.202}
\end{equation*}
$$

The cross-section for scattering of longitudinal waves into transverse waves is

$$
\begin{equation*}
\sigma_{\ell \rightarrow t}\left(\omega_{0}\right)=\frac{8 \pi}{3}\left(\frac{e^{2}}{m_{e} c^{2}}\right)^{2} \frac{c}{\sqrt{3} v_{e}} \frac{\omega_{p}}{\omega_{0}} \tag{7.203}
\end{equation*}
$$

We return to (7.195) and consider the non-resonant contributions,

$$
\begin{align*}
\dot{W} & =-\frac{2 \pi e^{4}}{3 m_{e}^{2} \omega_{0}^{3}} E_{0}^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \operatorname{Im}\left[\frac{1}{\varepsilon\left(k, \omega_{0}\right)}\right]=-\frac{2 \pi e^{4}}{3 m_{e}^{2} \omega_{0}^{3}} E_{0}^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}}\left[\frac{-\varepsilon_{I}}{|\varepsilon|^{2} \rightarrow 1}\right] \\
& =\frac{1}{3 \sqrt{2 \pi}} \frac{e^{4} \omega_{p}^{2}}{m_{e}^{2} \omega_{0}^{2}} \frac{E_{0}^{2}}{v_{e}^{3}} \int_{0}^{k_{\max } \sim \hbar_{d B}^{-1}} \frac{\mathrm{~d} k}{k} \exp \left(-\frac{\omega_{0}^{2}}{2 k^{2} v_{e}^{2}}\right)=\frac{1}{3 \sqrt{2 \pi}} \frac{e^{4} \omega_{p}^{2}}{m_{e}^{2} \omega_{0}^{2}} \frac{E_{0}^{2}}{v_{e}^{3}} \ln \left(\frac{T_{e}}{\hbar \omega_{0}}\right) \\
& =m_{e} \bar{w}^{2} v_{e} \frac{\ln \left(\frac{T_{e}}{\hbar \omega_{0}}\right)}{\ln \Lambda} \equiv m_{e} \bar{w}^{2} v_{e}(\omega), \quad \bar{w}^{2} \equiv \frac{1}{2}\left(\frac{e E_{0}}{m_{e} \omega_{0}}\right)^{2} . \tag{7.204}
\end{align*}
$$

From (7.204) we can immediately deduce the cross-section for absorption from (7.199),

$$
\begin{equation*}
\sigma_{\mathrm{abs}}=\frac{\dot{W}}{\frac{1}{2} \frac{E_{0}^{2}}{8 \pi} \bar{\varepsilon} V_{g}^{\mathrm{inc}}}=\frac{v_{e}(\omega)}{n V_{g}^{\mathrm{inc}}} \frac{\omega_{p}^{2}}{\omega^{2}} \tag{7.205}
\end{equation*}
$$

where $V_{g}^{\text {inc }}$ is the group velocity of the incident longitudinal or transverse wave and we have specialized to the case of a singly charge ion in an approximately quasi-neutral plasma. We note that the cross-section for collisional absorption is dominant over the other cross-sections by a term of order $\ln \Lambda$. The damping rate for the incident wave energy flux for either longitudinal or transverse waves is

$$
\begin{equation*}
2|\gamma|=n \sigma_{\mathrm{abS}} V_{g}^{\mathrm{inc}}=v_{e}(\omega) \frac{\omega_{p}^{2}}{\omega^{2}} \tag{7.206}
\end{equation*}
$$

This calculation has ignored correlations of the ions due to ion waves present, which Dawson and Oberman have examined.
7.3.6. More general derivation of scattering theory for particles, fluctuations or waves

Here we develop a more general theory of the scattering of an incident wave by particles, shielding clouds, fluctuations or waves, including wave turbulence. If the scattering involves an outgoing wave we have a formalism for wave emission (Tidman \& Dupree 1965):

$$
\begin{equation*}
\dot{W}^{b}(\boldsymbol{k})=\frac{4 \pi}{\bar{\varepsilon}} S^{j^{\cdot \boldsymbol{e}^{*}}}\left(\boldsymbol{k}, \omega_{k}^{b}\right), \quad \boldsymbol{j}(\boldsymbol{x}, t)=\sum_{s} e_{s} n_{s} \boldsymbol{v}_{s}=\sum_{s} e_{s} \int \mathrm{~d}^{3} \boldsymbol{v} \boldsymbol{v} F_{s}(\boldsymbol{x}, \boldsymbol{v} ; t) \tag{7.207}
\end{equation*}
$$

where $b$ denotes a branch of the dispersion relation for the emitted waves. We use the Klimontovich representation for the velocity distribution function assembled from the particles,

$$
\begin{equation*}
F_{s}(\boldsymbol{x}, \boldsymbol{v} ; t)=\sum_{i} \delta\left(\boldsymbol{x}-\boldsymbol{x}_{i}^{s}(t)\right) \delta\left(\boldsymbol{v}-\boldsymbol{v}_{i}^{s}(t)\right) \tag{7.208}
\end{equation*}
$$

which satisfies the Vlasov equation. The time derivative of the current is then

$$
\begin{align*}
\frac{\partial}{\partial t} \boldsymbol{j}(\boldsymbol{x}, t) & =\sum_{s} e_{s} \int \mathrm{~d}^{3} \boldsymbol{v} \boldsymbol{v}\left(-\boldsymbol{v} \cdot \frac{\partial F_{s}}{\partial \boldsymbol{x}}-\frac{\partial}{\partial \boldsymbol{v}} \cdot\left(\frac{e_{s}}{m_{s}} \boldsymbol{E} F_{s}\right)\right) \\
& =-\frac{\partial}{\partial \boldsymbol{x}} \cdot \sum_{s} e_{s} \int \mathrm{~d}^{3} \boldsymbol{v} \boldsymbol{v} \boldsymbol{v} F_{s}+\sum_{s} \frac{e_{s}^{2}}{m_{s}} n_{s} \boldsymbol{E}(\boldsymbol{x}, t) . \tag{7.209}
\end{align*}
$$

We next Fourier transform equation (7.209) in time and space,

$$
\begin{align*}
-\mathrm{i} \omega \boldsymbol{j}(\boldsymbol{k}, \omega)= & -\mathrm{i} \boldsymbol{k} \cdot \sum_{s} e_{s} \int \mathrm{~d}^{3} \boldsymbol{v} \boldsymbol{v} \boldsymbol{v} F_{s}(\boldsymbol{k}, \boldsymbol{v} ; \omega)+\sum_{s} \frac{e_{s}^{2}}{m_{s}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}_{1} \mathrm{~d} \omega_{1}}{(2 \pi)^{4}} \\
& \times \int \frac{\mathrm{d}^{3} \boldsymbol{k}_{2} \mathrm{~d} \omega_{2}}{(2 \pi)^{4}} n_{s}\left(\boldsymbol{k}_{2}, \omega_{2}\right) \boldsymbol{E}\left(\boldsymbol{k}_{1}, \omega_{1}\right)(2 \pi)^{4} \delta\left(\boldsymbol{k}_{1}+\boldsymbol{k}_{2}-\boldsymbol{k}\right) \delta\left(\omega_{1}+\omega_{2}-\omega\right) . \tag{7.210}
\end{align*}
$$

The first term on the right-hand side of (7.210) is of order $\mathrm{i}(\boldsymbol{k} \cdot \boldsymbol{v}) \boldsymbol{j}$, and for $\omega \gg \boldsymbol{k} \cdot \boldsymbol{v}$ this term is negligible compared to the second term. If $\omega / k \gg v$ is not satisfied then one must consider nonlinear Landau damping (last chap. in Davidson 1972).

We recall the development in (7.131)-(7.145) to obtain an expression for the wave emission. Given the relations $-i \omega \boldsymbol{j}(\boldsymbol{k}, \omega) \cdot \hat{\boldsymbol{e}}^{*}=-\mathrm{i} \omega \hat{\boldsymbol{e}}^{*} \cdot \boldsymbol{j}(\boldsymbol{k}, \omega)$ and from (7.131)

$$
\begin{equation*}
\left\langle\hat{\boldsymbol{e}}^{*} \cdot \boldsymbol{j}(\boldsymbol{k}, \omega) \hat{\boldsymbol{e}} \cdot \boldsymbol{j}^{*}\left(\boldsymbol{k}^{\prime}, \omega^{\prime}\right)\right\rangle=(2 \pi)^{4} \delta\left(\omega-\omega^{\prime}\right) \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) S^{\hat{e}^{*} \cdot \boldsymbol{j}}(\boldsymbol{k}, \omega) . \tag{7.211}
\end{equation*}
$$

The analysis can be simplified in special cases. For example, there are no density perturbations for electric fields due to transverse waves. Hence, the electric field and the density perturbations are uncorrelated and following ensemble average can be simplified,

$$
\begin{align*}
& \left\langle\hat{\boldsymbol{e}} \cdot \boldsymbol{E}\left(\boldsymbol{k}_{1}, \omega_{1}\right) \hat{\boldsymbol{e}} \cdot \boldsymbol{E}^{*}\left(\boldsymbol{k}_{1}^{* \prime}, \omega_{1}^{\prime}\right) n_{s}\left(\boldsymbol{k}_{2}, \omega_{2}\right) n_{s^{\prime}}^{*}\left(\boldsymbol{k}_{2}^{* \prime}, \omega_{2}^{\prime}\right)\right\rangle \\
& \quad=\left\langle\hat{\boldsymbol{e}} \cdot \boldsymbol{E}\left(\boldsymbol{k}_{1}, \omega_{1}\right) \hat{\boldsymbol{e}} \cdot \boldsymbol{E}^{*}\left(\boldsymbol{k}_{1}^{* \prime}, \omega_{1}^{\prime}\right)\right\rangle\left\langle n_{s}\left(\boldsymbol{k}_{2}, \omega_{2}\right) n_{s^{\prime}}^{*}\left(\boldsymbol{k}_{2}^{* \prime}, \omega_{2}^{\prime}\right)\right\rangle . \tag{7.212}
\end{align*}
$$

Then using (7.210)-(7.212) with the assumption $\omega \gg \boldsymbol{k} \cdot \boldsymbol{v}$ we obtain the following relation after doing the integrations and making use of the three fourfold delta functions,

$$
\begin{equation*}
S^{S^{*} \cdot j}(\boldsymbol{k}, \omega) \propto \int \frac{\mathrm{d}^{3} \boldsymbol{k}_{1} \mathrm{~d} \omega_{1}}{(2 \pi)^{4}} S^{E \cdot e^{*}}\left(\boldsymbol{k}_{1}, \omega_{1}\right) S^{n_{s} n_{s^{\prime}}}\left(\boldsymbol{k}_{2}=\boldsymbol{k}-\boldsymbol{k}_{1}, \omega_{2}=\omega-\omega_{1}\right) . \tag{7.213}
\end{equation*}
$$

The electron clouds surrounding ions constitute scattering centres. When an electron wave comes by, the ions cannot keep up and the oscillating electron clouds induce positive electron holes that oscillate with the electron clouds. No net oscillating dipole moment results. However, ion fluctuations are accompanied by electron cloud oscillations and there is a net oscillating dipole moment that radiates.

Example. Consider the scattering of transverse waves by a longitudinal wave or a fluctuation. The transverse waves have no accompanying density perturbation (at small amplitude). In an unmagnetized plasma the wave emission given in (7.207) is

$$
\begin{equation*}
\dot{W}^{\hat{e}}(\boldsymbol{k})=\frac{4 \pi}{\bar{\varepsilon}} S^{j \cdot \hat{e}}(\boldsymbol{k}, \omega), \quad \boldsymbol{j}(\boldsymbol{x}, t)=\sum_{s} e_{s} n_{s}(\boldsymbol{x}, t) \boldsymbol{u}_{s}(\boldsymbol{x}, t) \tag{7.214}
\end{equation*}
$$

Here $\hat{\boldsymbol{e}}=\hat{\boldsymbol{e}}^{*}$ and

$$
\begin{equation*}
\hat{\boldsymbol{e}} \cdot \boldsymbol{j}(\boldsymbol{k}, \omega)=\sum_{s} e_{s} \int \frac{\mathrm{~d}^{4} \boldsymbol{k}_{1}}{(2 \pi)^{4}} \int \frac{\mathrm{~d}^{4} \boldsymbol{k}_{2}}{(2 \pi)^{4}} \delta^{(4)}\left(\boldsymbol{k}_{1}+\boldsymbol{k}_{2}-\boldsymbol{k}\right) n_{s}\left(\boldsymbol{k}_{2}^{(4)}\right) \hat{\boldsymbol{e}} \cdot \boldsymbol{u}_{s}\left(\boldsymbol{k}_{1}^{(4)}\right)(2 \pi)^{4}, \tag{7.215}
\end{equation*}
$$

where

$$
\begin{gather*}
\mathrm{d}^{4} \boldsymbol{k}_{1} \equiv \mathrm{~d}^{3} \boldsymbol{k}_{1} \mathrm{~d} \omega_{1}, \quad \delta^{(4)}\left(\boldsymbol{k}_{1}+\boldsymbol{k}_{2}-\boldsymbol{k}\right) \equiv \delta\left(\boldsymbol{k}_{1}+\boldsymbol{k}_{2}-\boldsymbol{k}\right) \delta\left(\omega_{1}+\omega_{2}-\omega\right) \\
\text { and } \quad \boldsymbol{k}_{1}^{(4)}=\left(\boldsymbol{k}_{1}, \omega_{1}\right) . \tag{7.216}
\end{gather*}
$$

Using (7.215) we can now form

$$
\begin{align*}
& \left\langle\hat{\boldsymbol{e}} \cdot \boldsymbol{j}\left(\boldsymbol{k}^{(4)}\right) \hat{\boldsymbol{e}} \cdot \boldsymbol{j}^{*}\left(\boldsymbol{k}^{\prime(4)}\right)\right\rangle \\
& =\sum_{s, s^{\prime}} e_{s} e_{s^{\prime}} \int \frac{\mathrm{d}^{4} \boldsymbol{k}_{1}}{(2 \pi)^{4}} \int \frac{\mathrm{~d}^{4} \boldsymbol{k}_{2}}{(2 \pi)^{4}} \int \frac{\mathrm{~d}^{4} \boldsymbol{k}_{1}^{\prime}}{(2 \pi)^{4}} \int \frac{\mathrm{~d}^{4} \boldsymbol{k}_{2}^{\prime}}{(2 \pi)^{4}}(2 \pi)^{8} \delta^{(4)}\left(\boldsymbol{k}_{1}+\boldsymbol{k}_{2}-\boldsymbol{k}\right) \\
& \quad \times \delta^{(4)}\left(\boldsymbol{k}_{1}^{\prime}+\boldsymbol{k}_{2}^{\prime}-\boldsymbol{k}^{\prime}\right)\left\langle n_{s}\left(\boldsymbol{k}_{2}^{(4)}\right) n_{s^{\prime}}\left(\boldsymbol{k}_{2}^{(4) \prime}\right) \hat{\boldsymbol{e}} \cdot \boldsymbol{u}_{s}\left(\boldsymbol{k}_{1}^{(4)}\right) \hat{\boldsymbol{e}} \cdot \boldsymbol{u}_{s^{\prime}}\left(\boldsymbol{k}_{1}^{(4) \prime}\right)\right\rangle \\
& =\sum_{s, s^{\prime}} e_{s} e_{s^{\prime}} \int \frac{\mathrm{d}^{4} \boldsymbol{k}_{1}}{(2 \pi)^{4}} \int \frac{\mathrm{~d}^{4} \boldsymbol{k}_{2}}{(2 \pi)^{4}} \int \frac{\mathrm{~d}^{4} \boldsymbol{k}_{1}^{\prime}}{(2 \pi)^{4}} \int \frac{\mathrm{~d}^{4} \boldsymbol{k}_{2}^{\prime}}{(2 \pi)^{4}}(2 \pi)^{8} \delta^{(4)}\left(\boldsymbol{k}_{1}+\boldsymbol{k}_{2}-\boldsymbol{k}\right) \\
& \quad \times \delta^{(4)}\left(\boldsymbol{k}_{1}^{\prime}+\boldsymbol{k}_{2}^{\prime}-\boldsymbol{k}^{\prime}\right)\left\langle n_{s}\left(\boldsymbol{k}_{2}^{(4)}\right) n_{s^{\prime}}\left(\boldsymbol{k}_{2}^{(4) \prime}\right)\right\rangle\left\langle\hat{\boldsymbol{e}} \cdot \boldsymbol{u}_{s}\left(\boldsymbol{k}_{1}^{(4)}\right) \hat{\boldsymbol{e}} \cdot \boldsymbol{u}_{s^{\prime}}\left(\boldsymbol{k}_{1}^{(4) \prime}\right)\right\rangle . \tag{7.217}
\end{align*}
$$

The ensemble averages $\left\langle n_{s}\left(\boldsymbol{k}_{2}^{(4)}\right) n_{s}\left(\boldsymbol{k}_{2}^{(4) \prime}\right)\right\rangle$ and $\left\langle\hat{\boldsymbol{e}} \cdot \boldsymbol{u}_{s}\left(\boldsymbol{k}_{1}^{(4)}\right) \hat{\boldsymbol{e}} \cdot \boldsymbol{u}_{s}\left(\boldsymbol{k}_{1}^{(4) \prime}\right)\right\rangle$ force $\boldsymbol{k}_{1}^{(4)}=\boldsymbol{k}_{1}^{(4) \prime}$ and $\boldsymbol{k}_{2}^{(4)}=\boldsymbol{k}_{2}^{(4) \prime}$, which when combined with the two delta functions in (7.217) constrain $\boldsymbol{k}^{(4)}=\boldsymbol{k}^{(4) \prime}$. Hence, all but one of the integrations in (7.217) can be performed yielding

$$
\begin{equation*}
\left\langle\hat{\boldsymbol{e}} \cdot \boldsymbol{j}\left(\boldsymbol{k}^{(4)}\right) \hat{\boldsymbol{e}} \cdot \boldsymbol{j}^{*}\left(\boldsymbol{k}^{\prime(4)}\right)\right\rangle=\sum_{s, s^{\prime}} e_{s} e_{s^{\prime}}(2 \pi)^{4} \delta^{(4)}\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \int \frac{\mathrm{d}^{4} \boldsymbol{k}_{1}}{(2 \pi)^{4}} S^{n_{s} n_{s^{\prime}}}\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) S^{\hat{e} \cdot u_{s} \hat{e} \cdot \boldsymbol{u}_{s^{\prime}}}\left(\boldsymbol{k}_{1}\right) \tag{7.218}
\end{equation*}
$$

Now we can evaluate the wave-emission rate in (7.214),

$$
\begin{equation*}
\dot{W}^{\hat{e}}(\boldsymbol{k})=\frac{4 \pi}{\bar{\varepsilon}} \sum_{s, s^{\prime}} e_{s} e_{s^{\prime}} \int \frac{\mathrm{d}^{4} \boldsymbol{k}_{1}}{(2 \pi)^{4}} S^{n_{s} n_{s^{\prime}}}\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) S^{\hat{e} \cdot u_{s} \hat{e} \cdot \boldsymbol{u}_{s^{\prime}}}\left(\boldsymbol{k}_{1}\right) . \tag{7.219}
\end{equation*}
$$

Because the basic nonlinearity in the current has been incorporated in terms of the bilinearity in $n$ and $\boldsymbol{u}$, we can use linear theory to evaluate $n$ and $\boldsymbol{u}$. The velocity in the transverse wave is

$$
\begin{equation*}
-\mathrm{i} \omega_{1} \boldsymbol{u}^{s}=\frac{e_{s}}{m_{s}} \boldsymbol{E} \quad \hat{\boldsymbol{e}} \cdot \boldsymbol{u}^{s}=\frac{1}{-\mathrm{i} \omega_{1}} \frac{e_{s}}{m_{s}} \hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{e}}_{1} E . \tag{7.220}
\end{equation*}
$$

Because of the inverse mass dependence in the velocity, only the electron contribution to the scattering is important. Hence, equation (7.219) becomes

$$
\begin{align*}
\dot{W}^{\hat{e}}(\boldsymbol{k}) & =\frac{4 \pi}{\bar{\varepsilon}} e^{2} \int \frac{\mathrm{~d}^{4} \boldsymbol{k}_{1}}{(2 \pi)^{4}} S^{n n}\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) S^{\hat{e}_{1} \cdot \hat{e}_{1} \cdot u}\left(\boldsymbol{k}_{1}\right) \\
& =\frac{4 \pi}{\bar{\varepsilon}} \frac{e^{4}}{m^{2}}\left|\hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{e}}_{1}\right|^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}_{1} \mathrm{~d} \omega_{1}}{(2 \pi)^{4}} S^{n n}\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) \frac{1}{\omega_{1}^{2}} S^{E}\left(\boldsymbol{k}_{1}\right) \tag{7.221}
\end{align*}
$$

Suppose the incident wave ' 1 ' has a sharp frequency distribution,

$$
\begin{equation*}
S_{E}\left(\boldsymbol{k}_{1}, \omega_{1}\right)=\pi\left[S_{E}\left(\boldsymbol{k}_{1}\right) \delta\left(\omega_{1}-\omega_{k 1}\right)+S_{E}\left(-\boldsymbol{k}_{1}\right) \delta\left(\omega_{1}+\omega_{\boldsymbol{k} 1}\right)\right], \tag{7.222}
\end{equation*}
$$

which delta functions are a good representation for weak damping $\gamma / \omega_{k 1} \ll 1$. We can then perform the integral over frequency in (7.221) to obtain

$$
\begin{align*}
\dot{W}^{\hat{e}}(\boldsymbol{k})= & \frac{4 \pi}{\bar{\varepsilon}} \frac{e^{4}}{m^{2}}\left|\hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{e}}_{1}\right|^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}_{1}}{(2 \pi)^{3}} S^{n n}\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) \\
& \times \frac{1}{2}\left[\frac{S^{E}\left(\boldsymbol{k}_{1}\right)}{\omega_{k 1}^{2}} S^{n n}\left(\boldsymbol{k}-\boldsymbol{k}_{1}, \omega-\omega_{\boldsymbol{k} 1}\right)+\frac{S^{E}\left(-\boldsymbol{k}_{1}\right)}{\omega_{-k 1}^{2}} S^{n n}\left(\boldsymbol{k}+\boldsymbol{k}_{1}, \omega+\omega_{k 1}\right)\right] . \tag{7.223}
\end{align*}
$$

The first term in the square bracket in (7.223) describes the scattering of the transverse wave with wavenumber $\boldsymbol{k}_{1}$ being scattered by a density fluctuation with wavenumber $\boldsymbol{k}_{2}$ into a scattered transverse wave with wavenumber $\boldsymbol{k}$, satisfying the matching condition $\boldsymbol{k}=\boldsymbol{k}_{1}+\boldsymbol{k}_{2}$. Waves ' 1 ' and ' 2 ' can be considered as incoming waves in a three-wave interaction with the outgoing wave having wavenumber $\boldsymbol{k}$. The second term in the square bracket in (7.223) describes the relatively rare process of induced emission of the wave with wavenumber $\boldsymbol{k}$ in the presence of transverse wave ' 1 ' mediated by a density fluctuation with wavenumber $\boldsymbol{k}_{2}=\boldsymbol{k}_{1}+\boldsymbol{k}$. Thus, the first term in the square bracket is assumed dominant.

In terms of an action representation,

$$
\begin{equation*}
\dot{j}^{\hat{e}}(\boldsymbol{k})=\frac{\dot{W}^{\hat{e}}(\boldsymbol{k})}{\omega_{k}}=\left(\frac{4 \pi e^{2}}{m}\right)^{2} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}_{1}}{(2 \pi)^{3}} \frac{\left|\hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{e}}_{1}\right|^{2}}{\omega_{k} \omega_{k} \bar{\varepsilon}_{k} \bar{\varepsilon}_{\boldsymbol{k}_{1}}} S^{n_{e}}\left(\boldsymbol{k}_{2}, \omega_{2}\right) J^{\hat{e}_{1}}\left(\boldsymbol{k}_{1}\right), \tag{7.224}
\end{equation*}
$$

where

$$
\begin{equation*}
J^{\hat{e}_{1}}\left(\boldsymbol{k}_{1}\right)=(2 \pi)^{3} \delta\left(\boldsymbol{k}_{1}-\boldsymbol{k}_{\mathrm{inc}}\right) J_{\mathrm{inc}} . \tag{7.225}
\end{equation*}
$$

THEOREM. The macroscopic cross-section for scattering of a transverse wave into a scattered transverse wave is defined as

$$
\begin{equation*}
\sigma_{t \rightarrow t} \equiv \frac{\int \frac{\mathrm{~d}^{3} k}{(2 \pi)^{3}} \sum_{\hat{e}} \omega_{k} \dot{J}^{\hat{e}}(\boldsymbol{k})}{V_{g}^{\text {inc }} \omega_{1} J_{\text {inc }}}=\int \frac{\mathrm{d}^{2} \hat{\boldsymbol{k}}}{4 \pi} \sum_{\hat{\boldsymbol{e}}}\left|\hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{e}}_{1}\right|^{2}\left(\frac{e^{2}}{m_{e} c^{2}}\right)^{2} \int_{0}^{\infty} \mathrm{d} \omega \frac{k \omega}{k_{1} \omega_{1}} S^{n_{e}}\left(\boldsymbol{k}_{2}, \omega_{2}\right) . \tag{7.226}
\end{equation*}
$$

The sum is over two polarizations. For transverse waves in an unmagnetized plasma $\omega_{k}^{2}=\omega_{p}^{2}+k^{2} c^{2}$ and $\bar{\varepsilon}=2$. The quantity $k \omega / k_{1} \omega_{1}=O(1)$. We note that the macroscopic cross-section as defined here does not have the units of area, but instead has units of inverse length, i.e. like the product of a density and a microscopic cross-section having units of area. This result is discussed in § 12.9 of Clemmow \& Dougherty (1989).

ExErcise. Modify the result for $\sigma_{t \rightarrow t}$ to obtain $\sigma_{t \rightarrow \ell}$.
Example. Scattering off bare electrons, i.e. for situations in which the Debye length $\lambda_{D}$ is so large that shielding can be ignored.

$$
\begin{align*}
n_{e}(\boldsymbol{k}, \omega) & =\sum_{i} 2 \pi \delta(\omega-\boldsymbol{k} \cdot \boldsymbol{v}) \mathrm{e}^{-\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{r}_{i}} \Rightarrow S_{n_{e}}^{0}\left(\boldsymbol{k}_{2}, \omega_{2}\right) \\
& =2 \pi n \int \mathrm{~d}^{3} \boldsymbol{v} g_{e}(\boldsymbol{v}) \delta\left(\omega_{2}-\boldsymbol{k}_{2} \cdot \boldsymbol{v}\right)=\frac{2 \pi n}{k_{2}} g_{\hat{\boldsymbol{k}}}^{e}\left(\frac{\omega_{2}}{k_{2}}\right) . \tag{7.227}
\end{align*}
$$

For a Maxwellian $g_{\hat{k}}^{e}\left(\omega_{2} / k_{2}\right) \propto \exp \left(-(1 / 2)\left(\omega_{2} / k_{2} v_{e}\right)^{2}\right) \rightarrow \exp \left(-(1 / 2)\left(\omega-\omega_{1} / k_{2} v_{e}\right)^{2}\right)$ for outgoing waves. Thermal effects produce a spread in frequencies of the scattered radiation of order: $\Delta \omega / \omega_{1} \sim k_{2} v_{e} / \omega_{1}$, which is small in a non-relativistic plasma for which $v_{e} /\left(\omega_{1} / k_{1}\right) \sim v_{e} / c \ll 1$. We note that for $k_{1} \approx k, k_{2}=2 k_{1} \sin (\theta / 2)$ where $\theta$ is the angle between $\boldsymbol{k}_{1}$ and $\boldsymbol{k}$. From (7.226) and (7.227) one obtains

$$
\begin{equation*}
\sigma_{t \rightarrow t} \equiv \frac{\int \frac{\mathrm{~d}^{3} k}{(2 \pi)^{3}} \sum_{\hat{e}} \omega_{k} \dot{J}^{\hat{e}}(\boldsymbol{k})}{V_{g}^{\text {inc }} \omega_{1} J_{\text {inc }}}=n_{e} \frac{8 \pi}{3} r_{e}^{2}=n_{e} \sigma_{\text {Thomson }} \tag{7.228}
\end{equation*}
$$

Example (Scattering off shielded particles). We use the linearized Vlasov equation to calculate the response of the electron shielding cloud and the ion perturbations,

$$
\left.\begin{array}{c}
n_{e}^{\text {cloud }}(\boldsymbol{k}, \omega)=\frac{n_{e} e_{e}}{m_{e}} Z_{e}^{\prime}(v) \phi(\boldsymbol{k}, \omega), \quad Z_{s}(v)=\int_{-\infty}^{\infty} \mathrm{d} u \frac{g_{\hat{k}}^{s}(u)}{u-v},  \tag{7.229}\\
(\boldsymbol{k}, \omega)=\frac{4 \pi}{k^{2}} \frac{\sum_{s} e_{s} n_{s}^{0}(\boldsymbol{k}, \omega)}{\varepsilon(\boldsymbol{k}, \omega)}, \quad \varepsilon=1+\chi_{e}+\chi_{i} \quad \chi_{s} \equiv-\frac{\omega_{s}^{2}}{k^{2}} Z_{s}^{\prime}(v) .
\end{array}\right\}
$$

The total electron charge density perturbation is the sum over bare electrons, their shielding clouds and the electron shielding clouds surrounding the ion perturbed charge density,

$$
\begin{align*}
n_{e}(\boldsymbol{k}, \omega) & =n_{e}^{0}(\boldsymbol{k}, \omega)+n_{e}^{\mathrm{cloud}}=n_{e}^{0}(\boldsymbol{k}, \omega)\left[1+\frac{\omega_{\mathrm{pe}}^{2}}{k^{2}} \frac{Z_{e}^{\prime}(v)}{\varepsilon(\boldsymbol{k}, \omega)}\right]+n_{i}^{0}(\boldsymbol{k}, \omega)\left[-\frac{\omega_{\mathrm{pe}}^{2}}{k^{2}} \frac{Z_{e}^{\prime}(v)}{\varepsilon(\boldsymbol{k}, \omega)}\right] \\
& =\frac{1}{\varepsilon}\left[n_{e}^{0}\left(\varepsilon-\chi_{e}\right)+n_{i}^{0} \chi_{e}\right]=\frac{1}{\varepsilon}\left[n_{e}^{0}\left(1+\chi_{i}\right)+n_{i}^{0} \chi_{e}\right] . \tag{7.230}
\end{align*}
$$

We assume that the bare ion and bare electron charge density perturbations are uncorrelated and obtain from (7.227) and (7.231)

$$
\left.\begin{array}{rl}
S_{n_{e}}(\boldsymbol{k}, \omega) & =\frac{1}{|\varepsilon|^{2}}\left[S_{n_{e}}^{0}\left|1+\chi_{i}\right|^{2}+S_{n_{i}}^{0}\left|\chi_{e}\right|^{2}\right]  \tag{7.231}\\
S_{n_{i}}(\boldsymbol{k}, \omega) & =\frac{1}{|\varepsilon|^{2}}\left[S_{n_{i}}^{0}\left|1+\chi_{e}\right|^{2}+S_{n_{e}}^{0}\left|\chi_{i}\right|^{2}\right] \\
\frac{S_{n_{e}}}{S_{n_{i}}} & =\frac{g_{e}\left|1+\chi_{i}\right|^{2}+g_{i}\left|\chi_{e}\right|^{2}}{g_{e}\left|\chi_{i}\right|^{2}+g_{i}\left|1+\chi_{e}\right|^{2}},
\end{array}\right\}
$$

where $S^{0} \equiv(2 \pi n / k) g$. We can compare $g_{e}$ and $g_{i}$ as a function of the phase velocity $v$. First we recall

$$
g_{s}=\frac{1}{\sqrt{2 \pi} v_{s}} \mathrm{e}^{-v^{2} / 2 v_{e}^{2}}
$$

For $v \sim v_{i} \ll v_{e}$, then $g_{e} \ll g_{i}$ in (7.231) and $\chi_{e}=1 / k^{2} \lambda_{e}^{2}$. Hence, $S_{n_{e}} / S_{n_{i}} \cong\left(1+k^{2} \lambda_{e}^{2}\right)^{-2}$. Thus, the electron and ion fluctuations are comparable in this limit. For $v \sim v_{e} \gg v_{i}$ and $\omega \gg \omega_{\mathrm{pi}}$ then $g_{i}$ is exponentially small, $g_{i} \ll g_{e}$ and $\left|\chi_{i}\right| \ll 1$. Hence, $S_{n_{e}} / S_{n_{i}} \gg 1$ for high frequencies.

Our calculations of scattering so far have assumed that the underlying plasma is an isotropic, non-drifting Maxwellian and there is no externally applied magnetic field. With the inclusion of a drift, the approach of instability thresholds alters the dielectric response and the dispersion relations, which modify the density correlation functions. If there is an applied magnetic field, then particle gyration must be included, and the more general $\boldsymbol{K}$ response tensor must be used instead of the scalar longitudinal dielectric function.

EXAMPLE (Wave-wave scattering). Consider an incident transverse wave scattering off a longitudinal wave into a scattered transverse wave. We recall (7.225) for the time derivative of the scattered transverse wave action rewritten as

$$
\begin{equation*}
\dot{J}^{\hat{e}}(\boldsymbol{k})=\frac{\dot{W}^{\hat{e}}(\boldsymbol{k})}{\omega_{\boldsymbol{k}}}=\frac{1}{n^{2}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}_{1}}{(2 \pi)^{3}} \frac{\omega_{p}^{4}}{\omega_{k} \omega_{k 1}} \frac{\left|\hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{e}}_{1}\right|^{2}}{\bar{\varepsilon}_{\boldsymbol{k}} \bar{\varepsilon}_{\boldsymbol{k}_{1}}} S^{n_{e}}\left(\boldsymbol{k}_{2}, \omega_{2}\right) \hat{e}^{\hat{e}_{1}}\left(\boldsymbol{k}_{1}\right), \tag{7.232a}
\end{equation*}
$$

where

$$
\begin{equation*}
S^{n_{e}}\left(\boldsymbol{k}_{2}, \omega_{2}\right)=\pi\left[S^{n_{e}}\left(\boldsymbol{k}_{2}\right) \delta\left(\omega_{2}-\omega_{\boldsymbol{k}_{2}}\right)+S^{n_{e}}\left(-\boldsymbol{k}_{2}\right) \delta\left(\omega_{2}+\omega_{\boldsymbol{k}_{2}}\right)\right] . \tag{7.232b}
\end{equation*}
$$

For the longitudinal wave

$$
\begin{equation*}
4 \pi e \delta n_{e}=\mathrm{i} \boldsymbol{k}_{2} \cdot \boldsymbol{E} \rightarrow S^{n_{e}}\left(\boldsymbol{k}_{2}\right)=\left(\frac{k_{2}}{4 \pi e}\right)^{2} S^{E}\left(\boldsymbol{k}_{2}\right) \rightarrow \frac{8 \pi}{\bar{\varepsilon}_{2}} W\left(\boldsymbol{k}_{2}\right) \rightarrow \omega_{\boldsymbol{k}_{2}} J^{e \ell}\left(\boldsymbol{k}_{2}\right) . \tag{7.233}
\end{equation*}
$$

Hence, from (7.232a)

$$
\begin{align*}
\dot{J}^{\hat{e}}(\boldsymbol{k})= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}_{1}}{(2 \pi)^{3}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}_{2}}{(2 \pi)^{3}}(2 \pi)^{2} \delta\left(\boldsymbol{k}_{1}+\boldsymbol{k}_{2}-\boldsymbol{k}\right) \delta\left(\omega_{1}+\omega_{2}-\omega\right) 8 \pi^{2} \\
& \times\left(\frac{e}{m_{e}}\right)^{2} \frac{k_{2}^{2} \omega_{2}}{\omega \omega_{1}} \frac{\left|\hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{e}}_{1}\right|^{2}}{\bar{\varepsilon}_{\boldsymbol{k}} \bar{\varepsilon}_{\boldsymbol{k}_{1}} \bar{\varepsilon}_{\boldsymbol{k} 2}} J^{\hat{e}_{1}}\left(\boldsymbol{k}_{1}\right) J^{e \ell}\left(\boldsymbol{k}_{2}\right) . \tag{7.234}
\end{align*}
$$

The inverse process is the induced decay of the transverse wave with ( $\omega, \boldsymbol{k}$ ) into decay product waves $\left(\omega_{1}, \boldsymbol{k}_{1}\right)$ and ( $\omega_{2}, \boldsymbol{k}_{2}$ ). We include the additional induced decay terms to obtain

$$
\begin{align*}
\dot{J}^{\hat{e}}(\boldsymbol{k})= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}_{1}}{(2 \pi)^{3}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}_{2}}{(2 \pi)^{3}}(2 \pi)^{2} \delta\left(\boldsymbol{k}_{1}+\boldsymbol{k}_{2}-\boldsymbol{k}\right) \delta\left(\omega_{1}+\omega_{2}-\omega\right) 8 \pi^{2}\left(\frac{e}{m_{e}}\right)^{2} \\
& \times \frac{k_{2}^{2} \omega_{2}}{\omega \omega_{1}} \frac{\left|\hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{e}}_{1}\right|^{2}}{\bar{\varepsilon}_{\boldsymbol{k}} \bar{\varepsilon}_{\boldsymbol{k}_{1}} \bar{k}_{\boldsymbol{k} 2}}\left[\vec{J}^{\hat{U}_{1}}\left(\boldsymbol{k}_{1}\right) J^{e \ell}\left(\boldsymbol{k}_{2}\right)-J^{\hat{e}}(\boldsymbol{k}) J^{e \ell}\left(\boldsymbol{k}_{2}\right)-J^{\hat{e}}(\boldsymbol{k}) J^{\hat{e}_{1}}\left(\boldsymbol{k}_{1}\right)\right] . \tag{7.235}
\end{align*}
$$

The expression beginning with $8 \pi^{2}$ multiplying the square bracket is the coupling coefficient we did not know in $\S 6.8$ for three-wave coupling in the random-phase limit.

### 7.3.7. Nonlinear Landau damping

Nonlinear Landau damping is the name given to the nonlinear scattering of an incident wave by particles. (Note that this is not the nonlinear modification of Landau resonance due to particle trapping.) In this example the incident and scattered waves are transverse waves. Recall the expression in (7.231)

$$
\begin{equation*}
S_{n_{e}}\left(\boldsymbol{k}_{2}, \omega_{2}\right)=\frac{1}{\left|\varepsilon\left(\boldsymbol{k}_{2}\right)\right|^{2}}\left[S_{n_{e}}^{0}\left|1+\chi_{i}\right|^{2}+S_{n_{i}}^{0}\left|\chi_{e}\right|^{2}\right] \tag{7.236}
\end{equation*}
$$

where $S_{n_{s}}^{0}$ is given in (7.227). Then from (7.232a) one obtains

$$
\begin{align*}
\dot{J}^{\hat{e}}(\boldsymbol{k})= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}_{1}}{(2 \pi)^{3}} \frac{2 \pi}{\left|\varepsilon\left(\boldsymbol{k}-\boldsymbol{k}_{1}, \omega-\omega_{1}\right)\right|^{2}} \frac{1}{n^{2}} \frac{\omega_{p}^{4}}{\omega_{\boldsymbol{k}} \omega_{\boldsymbol{k} 1}} \frac{\left|\hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{e}}_{1}\right|^{2}}{\bar{\varepsilon}_{\boldsymbol{k}} \bar{\varepsilon}_{\boldsymbol{k}_{1}}} \\
& \times \int \mathrm{d}^{3} \boldsymbol{v} \delta\left(\omega-\omega_{1}-\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) \cdot \boldsymbol{v}\right)\left[\left|1+\chi_{i}\right|^{2} f_{e}(\boldsymbol{v}) J^{\hat{e}_{1}}\left(\boldsymbol{k}_{1}\right)+\left|\chi_{e}\right|^{2} f_{i}(\boldsymbol{v}) \hat{J}^{\hat{1}_{1}}\left(\boldsymbol{k}_{1}\right)\right] . \tag{7.237}
\end{align*}
$$

The quantum mechanics conservation laws for momentum and energy that describe wave scattering by a particle are

$$
\left.\begin{array}{rl}
\boldsymbol{p}+\hbar \boldsymbol{k}_{1}=\boldsymbol{p}^{\prime}+\hbar \boldsymbol{k} & \Rightarrow \quad \boldsymbol{p}^{\prime}-\boldsymbol{p} \equiv \Delta \boldsymbol{p}=\hbar\left(\boldsymbol{k}_{1}-\boldsymbol{k}\right)  \tag{7.238}\\
\frac{p^{2}}{2 m}+\hbar \omega_{1}=\frac{p^{2}}{2 m}+\hbar \omega & \Rightarrow \Delta\left(\frac{p^{2}}{2 m}\right) \approx \boldsymbol{v} \cdot \Delta \boldsymbol{p}=\hbar\left(\omega_{1}-\omega\right)
\end{array}\right\}
$$

for differential changes in the particle energy due to the scattering. These conservation laws directly lead to the condition

$$
\begin{equation*}
\omega_{1}-\omega=\left(\boldsymbol{k}_{1}-\boldsymbol{k}\right) \cdot \boldsymbol{v} \tag{7.239}
\end{equation*}
$$

which we recognize as the Landau particle resonance condition for wave scattering by a particle. The inverse (not reverse) scattering process has the same coupling due to hermiticity and detailed balance.

In the quantum mechanics calculation the time derivative of the quanta is given by

$$
\begin{align*}
\frac{\mathrm{d}}{\mathrm{~d} t} N(\boldsymbol{k})= & C_{\boldsymbol{k} \boldsymbol{k}_{1} s}\left\{f(\boldsymbol{p}) N\left(\boldsymbol{k}_{1}\right)[1+N(\boldsymbol{k})]-f\left(\boldsymbol{p}^{\prime}\right) N(\boldsymbol{k})\left[1+N\left(\boldsymbol{k}_{1}\right)\right]\right\}  \tag{7.240}\\
& \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \\
\text { no. scatters spont. induced in } & \text { scattering out } \\
= & C_{\boldsymbol{k} \boldsymbol{k}_{1} s}\left\{N\left(\boldsymbol{k}_{1}\right) N(\boldsymbol{k})\left[f(\boldsymbol{p})-f\left(\boldsymbol{p}^{\prime}\right)\right]+N\left(\boldsymbol{k}_{1}\right) f(\boldsymbol{p})-N(\boldsymbol{k}) f\left(\boldsymbol{p}^{\prime}\right)\right\},
\end{align*}
$$

where $N \equiv J / \hbar$ and the rules of Bose statistics apply. We use (7.238) and linearly expand

$$
\begin{equation*}
f(\boldsymbol{p})-f\left(\boldsymbol{p}^{\prime}\right) \approx\left(\boldsymbol{p}-\boldsymbol{p}^{\prime}\right) \cdot \frac{\partial f}{\partial \boldsymbol{p}}=\hbar\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) \cdot \frac{\partial f}{\partial \boldsymbol{p}} \tag{7.241}
\end{equation*}
$$

Hence,

$$
\begin{align*}
\frac{1}{\hbar} \frac{\mathrm{~d}}{\mathrm{~d} t} J(\boldsymbol{k})= & C_{k \boldsymbol{k}_{1} s}\left\{\frac{J\left(\boldsymbol{k}_{1}\right)}{\hbar} J(\boldsymbol{k})\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) \cdot \frac{\partial f}{\partial \boldsymbol{p}}+\frac{J\left(\boldsymbol{k}_{1}\right)}{\hbar} f(\boldsymbol{p})-\frac{J(\boldsymbol{k})}{\hbar} f\left(\boldsymbol{p}^{\prime}\right)\right\} \\
\propto & \left\{J\left(\boldsymbol{k}_{1}\right) J(\boldsymbol{k})\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) \cdot \frac{\partial f}{\partial \boldsymbol{p}}+\left[J\left(\boldsymbol{k}_{1}\right)-J(\boldsymbol{k})\right] f(\boldsymbol{p})+O\left[\left(\boldsymbol{p}^{\prime}-\boldsymbol{p}\right) \cdot \frac{\partial f}{\partial \boldsymbol{p}}\right]\right\} \\
& \times \delta\left(\hbar \omega+\frac{p^{\prime 2}}{2 m}-\left(\hbar \omega_{1}+\frac{p^{2}}{2 m}\right)\right) \delta\left(\hbar \boldsymbol{k}+\boldsymbol{p}^{\prime}-\left(\hbar \boldsymbol{k}_{1}+\boldsymbol{p}\right)\right) \tag{7.242}
\end{align*}
$$

We integrate (7.242) over the spectrum of waves $\boldsymbol{k}_{1}$ and over the distribution function of momentum $\boldsymbol{p}$ to get an expression for $\mathrm{d} J(\boldsymbol{k}) / \mathrm{d} t$. Given (7.237) the coefficient $C_{\boldsymbol{k} \boldsymbol{k}_{1}}$ can be evaluated,

$$
\begin{equation*}
C_{k k_{1} s}=\frac{2 \pi}{\left|\varepsilon\left(\boldsymbol{k}-\boldsymbol{k}_{1}, \omega-\omega_{1}\right)\right|^{2}} \frac{1}{n^{2}} \frac{\omega_{p}^{4}}{\omega_{k} \omega_{k 1}} \frac{\left|\hat{\boldsymbol{e}} \cdot \hat{\boldsymbol{e}}_{1}\right|^{2}}{\bar{\varepsilon}_{\boldsymbol{k}} \bar{\varepsilon}_{\boldsymbol{k}_{1}}}\left[\left|1+\chi_{i}\right|^{2} \text { electrons, }\left|\chi_{e}\right|^{2} \text { ions }\right] \tag{7.243}
\end{equation*}
$$

where $\boldsymbol{k}_{2}=\boldsymbol{k}-\boldsymbol{k}_{1}$.
The scattering considered here involves small changes in the particle momentum consistent with (7.238) and the linear expansion in (7.241). Combined with the assumption of random phases in the scattering processes, the momentum scattering satisfies the conditions for a Fokker-Planck description,

$$
\begin{equation*}
\frac{\partial f^{s}(\boldsymbol{p} ; t)}{\partial t}=-\frac{\partial}{\partial \boldsymbol{p}} \cdot(\boldsymbol{F}(\boldsymbol{p}) f(\boldsymbol{p}))+\frac{\partial}{\partial \boldsymbol{p}} \cdot\left(\boldsymbol{D}(\boldsymbol{p}) \cdot \frac{\partial f(\boldsymbol{p})}{\partial \boldsymbol{p}}\right) \tag{7.244}
\end{equation*}
$$

The first momentum moment of the Fokker-Planck equation summed over species yields the time derivative of the total particle momentum in the plasma,

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} \boldsymbol{P}_{\text {particles }}=\frac{\mathrm{d}}{\mathrm{~d} t} \sum_{s} \int \mathrm{~d}^{3} \boldsymbol{p} \boldsymbol{p} f_{s}(\boldsymbol{p} ; t)=\sum_{s} \int \mathrm{~d}^{3} \boldsymbol{p}\left[\boldsymbol{F} f-\boldsymbol{D} \cdot \frac{\partial f}{\partial \boldsymbol{p}}\right] \tag{7.245}
\end{equation*}
$$

where an integration by parts has been performed. The time derivative of the total wave momentum (fields and particle sloshing in the wave) is

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} \boldsymbol{P}_{\text {waves }}=\frac{\mathrm{d}}{\mathrm{~d} t}\left[\int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \boldsymbol{k} \boldsymbol{J}^{\hat{e}}(\boldsymbol{k} ; t)+\int \frac{\mathrm{d}^{3} \boldsymbol{k}_{1}}{(2 \pi)^{3}} \boldsymbol{k}_{1} J^{\hat{e}_{1}}\left(\boldsymbol{k}_{1} ; t\right)\right] . \tag{7.246}
\end{equation*}
$$

The right-hand side of (7.246) is evaluated using (7.242) and (7.243). One can show that the conservation of the total number of quanta implies that the total wave action is conserved. Conservation of total momentum is dictated by (7.238) and built into the equations. Thus, one can sum (7.245) and (7.246) and assert

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t}\left(\boldsymbol{P}_{\text {particles }}+\boldsymbol{P}_{\mathrm{waves}}\right)=0 \tag{7.247}
\end{equation*}
$$

from which we infer $\boldsymbol{F}(\boldsymbol{p})$ and $\boldsymbol{D}(\boldsymbol{p})$ consistent with conservation of total momentum,

$$
\left.\begin{array}{rl}
\boldsymbol{D}^{s}(\boldsymbol{p})= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}_{1}}{(2 \pi)^{3}} \\
& \times\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) C_{\boldsymbol{k} \boldsymbol{k}_{1} S^{\hat{e}_{1}}}\left(\boldsymbol{k}_{1}\right) \hat{e}^{\hat{e}}(\boldsymbol{k}) \delta\left(\omega-\omega_{1}-\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) \cdot \boldsymbol{v}\right)\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right)  \tag{7.248}\\
\boldsymbol{F}^{s}(\boldsymbol{p})= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}_{1}}{(2 \pi)^{3}} \\
& \times\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) C_{\boldsymbol{k} \boldsymbol{k}_{1} s}\left(J^{\hat{e}}(\boldsymbol{k})-J^{\hat{e}_{1}}\left(\boldsymbol{k}_{1}\right)\right) \delta\left(\omega-\omega_{1}-\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) \cdot \boldsymbol{v}\right)\left(\boldsymbol{k}-\boldsymbol{k}_{1}\right) .
\end{array}\right\}
$$

EXERCISE. Derive (7.248) filling in the intermediate steps.

### 7.3.8. Radiation transport: summary of important processes

This lecture serves as a summary of the important processes in radiation transport.

## Emission processes

(i) Bremsstrahlung (discreteness) - particles scatter off one another or particles scatter off fluctuations, and in so doing produce a time-dependent dipole moment and current, which lead to emission of radiation.
(ii) Cerenkov (resonance) - a particle with velocity satisfying wave-particle resonance $\omega=\boldsymbol{k} \cdot \boldsymbol{v}$ can emit a wave.
(iii) Beat resonance (scattering) - the beat of an incident and scattered wave is resonant with particles $\omega_{1}-\omega_{2}=\left(\boldsymbol{k}_{1}-\boldsymbol{k}_{2}\right) \cdot \boldsymbol{v}$, which can enhance the scattering.
(iv) Gyro-resonance (cyclotron emission) - the classical acceleration of a charged particle gyrating in a magnetic field emits radiation satisfying the gyro-resonance condition: $\omega-k_{\|} v_{\|}=\ell \Omega$.
(v) Three-wave (or more) scattering - an incident wave is scattered by another wave into a third wave subject to the three-wave resonance conditions: $\omega_{1}=\omega_{2}+$ $\omega_{3}, \boldsymbol{k}_{1}=\boldsymbol{k}_{2}+\boldsymbol{k}_{3}$.
(vi) Induced emission - wave emission (single wave and two waves) by the plasma can reinforce itself leading to an instability.
(vii) Radiation emission due to atomic transitions (not covered in these lectures).

## Conditions affecting propagation

(i) Damping or instability.
(a) Anisotropy in velocity space.
(b) Non-monotonicity in energy.
(c) Inhomogeneity in space.
(d) Non-stationarity due to time dependence, e.g. parametric instability.
(ii) Refraction in a plasma with weak inhomogeneity $L \gg \lambda$.
(iii) Reflection in a plasma with sharp inhomogeneity $L \ll \lambda$ or sudden change in polarization of the wave.
(iv) Diffraction when $L \sim \lambda$.

## Absorption processes

(i) Wave scattering.
(ii) Three or more wave interactions.
(iii) Mode conversion from one branch to another.
(iv) Inverse Cerenkov effect, i.e. Landau damping.
(v) Collisional absorption, i.e. inverse bremsstrahlung.
(vi) Atomic transitions.
(vii) Gyro-resonant absorption.
(viii) Two-wave absorption.

A complication in most of the resonant processes is resonance broadening. Particle trapping is a particularly important nonlinear effect and influences the saturation of many instabilities.

### 7.3.9. WKB theory in the context of radiation transport

We return to the WKB theory to include WKB wave propagation in a general theory of wave emission and absorption. Our WKB theory uses the following representation:

$$
\begin{equation*}
\boldsymbol{E}(\boldsymbol{x}, t)=\tilde{\boldsymbol{E}}(\boldsymbol{x}, t) \mathrm{e}^{\mathrm{i} \Phi(\boldsymbol{x}, t)} \quad \Phi=\int^{x}(\boldsymbol{k} \cdot \mathbf{d} \boldsymbol{x}-\omega \mathrm{d} t) \tag{7.249a}
\end{equation*}
$$

and

$$
\begin{equation*}
\boldsymbol{k}(\boldsymbol{x}, t)=\frac{\partial \Phi}{\partial \boldsymbol{x}} \quad \omega(\boldsymbol{x}, t)=-\frac{\partial \Phi}{\partial t} \quad \Rightarrow \quad \frac{\partial}{\partial t} \boldsymbol{k}(\boldsymbol{x}, t)=-\frac{\partial}{\partial \boldsymbol{x}} \omega(\boldsymbol{x}, t) \tag{7.249b}
\end{equation*}
$$

We use Maxwell's equations to obtain the local linear dispersion relation,

$$
\begin{equation*}
D(\omega, \boldsymbol{k} ; \boldsymbol{x}, t)=D\left(-\frac{\partial \Phi}{\partial t}, \frac{\partial \Phi}{\partial \boldsymbol{x}} ; \boldsymbol{x}, t\right) \rightarrow \omega(\boldsymbol{k}(\boldsymbol{x}, t) ; \boldsymbol{x}, t) \tag{7.250}
\end{equation*}
$$

Equation (7.251) is a first-order quasilinear partial differential equation which is solved by the method of characteristics. The equation of motion for the wave packet characteristic determined from (7.249b) is

$$
\begin{equation*}
\frac{\mathrm{d} \boldsymbol{x}}{\mathrm{~d} t}=\frac{\partial}{\partial \boldsymbol{k}} \omega(\boldsymbol{k} ; \boldsymbol{x}, t) \tag{7.251}
\end{equation*}
$$

and there is the companion equation,

$$
\begin{align*}
\frac{\mathrm{d}}{\mathrm{~d} t} \boldsymbol{k} & =\left(\frac{\partial}{\partial t}+\left.\frac{\partial \omega}{\partial \boldsymbol{k}}\right|_{\boldsymbol{x}, t} \cdot \frac{\partial}{\partial \boldsymbol{x}}\right) \boldsymbol{k}=-\frac{\partial \omega(\boldsymbol{x}, t)}{\partial \boldsymbol{x}}+\left.\frac{\partial \omega}{\partial \boldsymbol{k}}\right|_{\boldsymbol{x}, t} \cdot \frac{\partial \boldsymbol{k}}{\partial \boldsymbol{x}} \\
& =-\left.\frac{\partial \omega(\boldsymbol{x}, t)}{\partial \boldsymbol{x}}\right|_{\boldsymbol{k}, t}-\left.\frac{\partial \omega(\boldsymbol{x}, t)}{\partial \boldsymbol{x}}\right|_{\boldsymbol{x}, t} \cdot \frac{\partial \boldsymbol{k}}{\partial \boldsymbol{x}}+\left.\frac{\partial \omega}{\partial \boldsymbol{k}}\right|_{\boldsymbol{x}, t} \cdot \frac{\partial \boldsymbol{k}}{\partial \boldsymbol{x}}=-\left.\frac{\partial \omega(\boldsymbol{x}, t)}{\partial \boldsymbol{x}}\right|_{\boldsymbol{k}, t} \tag{7.252}
\end{align*}
$$

If there is no emission or absorption, then there should be an action conservation theorem. This is entirely analogous to the conservation of photons or plasmons in quantum mechanics if there is no absorption or emission. Recall that the number of photons or plasmons is related to the action by the relation $N=J / \hbar$. Dougherty used a covariant treatment to develop a classical theory of wave-action conservation for small-amplitude waves based on a Lagrangian (Dougherty 1970, 1974).

The total action is derived from the sum over branches of the integral over configuration and $k$ space of the action density in $\boldsymbol{x}$ and $\boldsymbol{k}$ space,

$$
\begin{equation*}
J_{t o t}=\sum_{\alpha} J^{\alpha}(\boldsymbol{x}, \boldsymbol{k} ; t) \frac{\mathrm{d}^{3} \boldsymbol{x} \mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} . \tag{7.253}
\end{equation*}
$$

The Liouville theorem for action density is

$$
\begin{align*}
& \frac{\partial J^{\alpha}(\boldsymbol{x}, \boldsymbol{k} ; t)}{\partial t}+\frac{\partial}{\partial \boldsymbol{x}} \cdot\left(\dot{\boldsymbol{x}} J^{\alpha}\right)+\frac{\partial}{\partial \boldsymbol{k}} \cdot\left(\dot{\boldsymbol{k}} J^{\alpha}\right) \\
& \quad=\frac{\partial J^{\alpha}(\boldsymbol{x}, \boldsymbol{k} ; t)}{\partial t}+\frac{\partial}{\partial \boldsymbol{x}} \cdot\left(\frac{\partial \omega}{\partial \boldsymbol{k}} J^{\alpha}\right)+\frac{\partial}{\partial \boldsymbol{k}} \cdot\left(-\frac{\partial \omega}{\partial \boldsymbol{x}} J^{\alpha}\right) \\
& \quad=\frac{\partial J^{\alpha}(\boldsymbol{x}, \boldsymbol{k} ; t)}{\partial t}+J^{\alpha}\left(\frac{\partial}{\partial \boldsymbol{x}} \cdot \frac{\partial \omega}{\partial \boldsymbol{k}}-\frac{\partial}{\partial \boldsymbol{k}} \cdot \frac{\partial \omega}{\partial \boldsymbol{x}}\right)+\left(\dot{\boldsymbol{x}} \cdot \frac{\partial}{\partial \boldsymbol{x}}+\dot{\boldsymbol{k}} \cdot \frac{\partial}{\partial \boldsymbol{k}}\right) J^{\alpha} \\
& \quad=\left(\frac{\partial}{\partial t}+\dot{\boldsymbol{x}} \cdot \frac{\partial}{\partial \boldsymbol{x}}+\dot{\boldsymbol{k}} \cdot \frac{\partial}{\partial \boldsymbol{k}}\right) J^{\alpha}(\boldsymbol{x}, \boldsymbol{k} ; t)=\frac{\mathrm{d}}{\mathrm{~d} t} J^{\alpha}(\boldsymbol{x}, \boldsymbol{k} ; t)=0 \tag{7.254}
\end{align*}
$$

Equation (7.254) describes the advection of the action density along the characteristics in $(\boldsymbol{x}, \boldsymbol{k})$ space determined by the WKB equations of motion.

The generalization of (7.254) to include emission, absorption and independent damping effects (but do not double count) is then

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} J^{\alpha}=\dot{J}^{\alpha}(\text { emission-absorption })-2 \gamma_{\mathrm{dpg}}(\boldsymbol{k} ; \boldsymbol{x}, t) \tag{7.255}
\end{equation*}
$$

The damping rate $\gamma_{\mathrm{dpg}}$ is a function of wave amplitude if particle trapping effects are included. Otherwise, $\gamma_{\mathrm{dpg}}$ may be independent of wave amplitude in many instances. However, we note that diffraction, coherent effects and departures from WKB are all lost in this formulation.

What about polarization effects? To include polarization effects we must go back to the response tensor,

$$
\begin{equation*}
\boldsymbol{K}(\omega, \boldsymbol{k} ; \boldsymbol{x}, t) \cdot \boldsymbol{E}=0 \Rightarrow \operatorname{det}|\boldsymbol{K}| \equiv D=0 \Rightarrow \omega^{\alpha}(\boldsymbol{k} ; \boldsymbol{x}, t) \quad \boldsymbol{K}(\omega, \boldsymbol{k} ; \boldsymbol{x}, t) \cdot \hat{\boldsymbol{e}}^{\alpha}(\boldsymbol{x}, t)=0 \tag{7.256}
\end{equation*}
$$

As we track a wave packet, we solve continuously for the frequency, wavenumber and polarization evolution.

In a non-uniform plasma, solutions of the dispersion relation for the wavenumber as a function of frequency can exhibit resonances in some instances, i.e. the solution for the index of refraction exhibits a singularity, $n^{2}(\omega, \boldsymbol{x})=k^{2} c^{2} / \omega^{2} \rightarrow \infty$ (see chap. 10 in Stix (1962)). The resonant frequency $\omega_{\text {res }}$ typically depends on the local values of the cyclotron frequency, the plasma frequency and the angle of the wave number with respect to the magnetic field. Consider the special case of a stationary medium. For a given frequency $\omega$ and location $\boldsymbol{x}$ such that the solution for $n^{2}$ is finite, the wave
simply propagates. Propagation continues until the solution for $\omega_{\text {res }}(\boldsymbol{x})=\omega$ at which location $n^{2}(\omega, \boldsymbol{x}) \rightarrow \infty$ and the wave suffers either strong absorption or is evanescent. Including finite temperature and collisional effects in the dispersion relations makes the complex parts of $n^{2}$ non-negligible and removes the infinities. Because finite temperature effects introduce significant analytical complexity, here we will illustrate how the inclusion of collisionality resolves resonances. Clearly WKB theory is no good near a resonance because $k$ is not slowly varying in space as it diverges.

Consider a simple model equation for the index of refraction in a plasma with spatially varying resonance frequency with resonance at $x=0$,

$$
\begin{equation*}
n^{2}(\omega, x)=\frac{k^{2} c^{2}}{\omega^{2}}=\frac{c_{1}}{\omega_{\mathrm{res}}(x)-\omega} \rightarrow \frac{c_{1}}{\omega+\left.\frac{\mathrm{d} \omega_{\mathrm{res}}}{\mathrm{~d} x}\right|_{x=0} x-\mathrm{i} v-\omega}=\frac{c_{1}}{\left.\frac{\mathrm{~d} \omega_{\mathrm{res}}}{\mathrm{~d} x}\right|_{x=0} x-\mathrm{i} v} \tag{7.257}
\end{equation*}
$$

for $c_{1}>0$. Because WKB theory is invalid near resonance we require a field equation, e.g. a Helmholtz equation with a singular point at $x=0$,

$$
\begin{equation*}
\frac{\mathrm{d}^{2} E}{\mathrm{~d} x^{2}}+k^{2}(x) E(x)=\frac{\mathrm{d}^{2} E}{\mathrm{~d} x^{2}}+\frac{c_{1}}{\left.\frac{\mathrm{~d} \omega_{\mathrm{res}}}{\mathrm{~d} x}\right|_{x=0} x-\mathrm{i} v} \frac{\omega^{2}}{c^{2}} E(x)=0 \tag{7.258}
\end{equation*}
$$

The collision rate is assumed small and is important only in the neighbourhood of $x=0$. WKB is good for $x \neq 0$ :

$$
\left.\begin{array}{c}
k^{2}(x)=\frac{c_{1}}{\omega_{R}^{\prime} x-\mathrm{i} v} \frac{c^{2}}{\omega^{2}} \equiv \frac{\mu^{2}}{x-\mathrm{i} \nu^{\prime}}, \quad v^{\prime} \equiv \frac{v}{\omega_{R}^{\prime}}, \quad \mu^{2} \equiv \frac{c_{1}}{\omega_{R}^{\prime}} \frac{c^{2}}{\omega^{2}} \\
\frac{\mathrm{~d}^{2} E}{\mathrm{~d} x^{2}}+k^{2}(x) E(x)=0 \quad E(x)=\sum_{ \pm} c_{ \pm} \frac{1}{\sqrt{k}} \mathrm{e}^{ \pm \mathrm{i} \int k \mathrm{~d} x} . \tag{7.259}
\end{array}\right\}
$$

Let $z \equiv x-\mathrm{i} v^{\prime}$ so that (7.257) becomes

$$
\begin{equation*}
\frac{\mathrm{d}^{2} E}{\mathrm{~d} z^{2}}+\frac{\mu^{2}}{z} E(z)=0 \tag{7.260}
\end{equation*}
$$

which has solutions in terms of Bessel functions,

$$
\begin{equation*}
E \sim z^{1 / 2} \mathbf{J}_{1}\left(2 \mu z^{1 / 2}\right), \quad z^{1 / 2} \mathrm{Y}_{1}\left(2 \mu z^{1 / 2}\right) \rightarrow c_{1} z^{1 / 2} \mathrm{~J}_{1}\left(2 \mu z^{1 / 2}\right)+c_{2} z^{1 / 2} \mathrm{Y}_{1}\left(2 \mu z^{1 / 2}\right) \tag{7.261a}
\end{equation*}
$$

Although these forms are good for $z<0$, there is some ambiguity because of the $z^{1 / 2}$. Therefore we introduce Bessel functions of imaginary argument,

$$
\begin{equation*}
E(z<0)=-c_{1}(-z)^{1 / 2} \mathrm{I}_{1}\left(2 \mu(-z)^{1 / 2}\right)+c_{2}(-z)^{1 / 2}\left[\mathrm{iI}_{1}\left(2 \mu(-z)^{1 / 2}\right)-\frac{2}{\pi} \mathrm{~K}_{1}\left(2 \mu(-z)^{1 / 2}\right)\right] . \tag{7.261b}
\end{equation*}
$$

Here, $\mathrm{I}_{1}$ grows exponentially for large argument while $\mathrm{K}_{1}$ decays exponentially. For simplicity assume that there are no other propagating regions for $x<0$. Then the two factors with $\mathrm{I}_{1}$ must cancel one another at large negative $z$, which leaves only the factor involving $\mathrm{K}_{1}$,

$$
\begin{equation*}
E(x<0)=\frac{2 \mathrm{i}}{\pi}(-z)^{1 / 2} \mathrm{~K}_{1}\left(2 \mu(-z)^{1 / 2}\right) . \tag{7.262}
\end{equation*}
$$

For large negative $x$, the solution in (7.262) matches nicely onto the decaying WKB solution,

$$
\begin{equation*}
E(x<0) \rightarrow \frac{\mathrm{i}}{\sqrt{\pi}} \frac{1}{|k|^{1 / 2}} \exp \left(-\int_{0}^{|z|}|k|^{1 / 2} \mathrm{~d} z\right) \tag{7.263}
\end{equation*}
$$

In the propagating region we have the solution in (7.260), which for $\left|\mu z^{1 / 2}\right| \ll 1$ has the following limiting forms:

$$
\begin{equation*}
z^{1 / 2} \mathbf{J}_{1}\left(2 \mu z^{1 / 2}\right) \propto \mu z \quad z^{1 / 2} \mathrm{Y}_{1}\left(2 \mu z^{1 / 2}\right) \propto \frac{1}{\pi \mu}\left[-1+\mu^{2} z\left(\ln \left(\mu^{2} z\right)+2 \gamma-1\right)\right], \quad \gamma=0.5772 \tag{7.264}
\end{equation*}
$$

We use these limiting forms in (7.261a) and then assert continuity of $E$ at $x=0$ to evaluate constants by equating (7.261a) and (7.262) (note that there is one free constant fixing the amplitude of the incident wave from positive $x$ ). For large positive $x$, there is only an incoming wave and no outgoing wave,

$$
\begin{equation*}
E(x \rightarrow \infty) \sim z^{1 / 2}\left[-\mathrm{J}_{1}-\mathrm{i} \mathrm{Y}_{1}\right] \rightarrow \frac{1}{\sqrt{\pi k}} \exp -\mathrm{i}\left(\int_{0}^{z} k \mathrm{~d} z+\frac{\pi}{4}\right) \tag{7.265}
\end{equation*}
$$

From the constructed solutions we see that there is an incoming wave from positive $x$ that propagates through $x=0$ (without reflection) to negative $x$ where it decays. The absorption length is set by $\Delta x \sim v^{\prime}=v\left|\mathrm{~d} \omega_{R} / \mathrm{d} x\right|^{-1}$. The weaker the collision rate the narrower the absorption length near resonance. This is in contrast to the effect of collisions on absorption far from resonance for which $\operatorname{Im} k \sim\left(\nu / V_{g}\right) \sim(1 / \Delta x)$ so that the absorption length increases with decreasing collision rate. Stix's book has more to say on the subject of resonances.

### 7.4. Dupree's theory of phase-space granulation and clump formation

Trapped particles moving with velocity near the phase velocity of the wave in which they are trapped tend to move as a clump. If there are many waves present with sufficient amplitude to produce trapping, the many waves can dissipate this clump. The particles can radiate in going from trapped to untrapped. The clump does not travel together for a long enough time to radiate at a sharp frequency. However, there is sufficient coherence in the clump to produce some enhancement of the radiation. Some of the early important work on clump theory was due to Dupree (1970, 1972) and Kadomtsev \& Pogutse (1970). Radiation produced by one clump tends to form other clumps, i.e. clumps tend to be 'self-sustaining'. Waves can form and sustain a clump, while other waves tend to diffuse and destroy the clump. Dynamic friction and velocity diffusion due to the waves are clearly present. One must use a finitewidth resonance function in the theory and not $\delta(\omega-k \cdot v)$. The theory includes wave emission by clumps, Landau damping (stable plasma), clump formation by wave trapping and clump destruction by other waves.

The clump phenomena depend on the auto-correlation time and the trapping time. The auto-correlation time is the time required for phase mixing to become complete,

$$
\begin{equation*}
\tau_{\mathrm{ac}} \sim \frac{\delta x}{V} \sim \frac{1}{\delta k V} \tag{7.266}
\end{equation*}
$$

where $\delta k$ is the spectral width and $V$ is the phase velocity $\sim$ the resonant particle velocity. Because the spectral width $\delta k$ induces a spread of phase velocities: $\delta V / V=$ $\delta k / k$, then $\tau_{\mathrm{ac}} \sim 1 / k \delta V$ alternatively. The broader the spectrum, the shorter is $\tau_{\mathrm{ac}}$. We expect that the coherence of the clump radiation to scale as $\Delta \omega \sim 1 / \tau_{\mathrm{ac}}$. Consider three regimes of behaviour for clumps:
(i) $\tau_{\mathrm{ac}} \ll \tau_{B} \equiv 2 \pi / \omega_{B}$ where $\omega_{B}=k \sqrt{e \phi / m}$. The fields experienced by the particles are changing so fast that there is no trapping. There is only quasilinear diffusion.
(ii) $\tau_{\mathrm{ac}} \sim \tau_{B}$. There is a diffusion in velocity space with a tendency to trap. Clumps are short lived.
(iii) $\tau_{\mathrm{ac}} \gg \tau_{B}$. There is well-defined trapping. Eventually trapping is destroyed by diffusion in waves. Clumps are long lived (long-lived eddies).
The velocity distribution function can be decomposed as the sum of the unperturbed lowest-order distribution plus a second term comprising the linear coherent perturbation and the quasilinear perturbation and a third term that is the nonlinear perturbation due to trapping. We can make the following scaling arguments. The velocity diffusion due to scattering by waves is given by

$$
\begin{equation*}
D \sim \frac{\delta v^{2}}{\tau} \tag{7.267}
\end{equation*}
$$

where $\delta v$ is the change in velocity during a time $\tau$ due to scattering by all the waves. Over the lifetime of the clump $\tau_{\text {clump }}$, there is a change in velocity $w \sim \delta v_{\text {rms }} \cong\left(D \tau_{\text {clump }}\right)^{1 / 2}$. As derived earlier the spatial diffusion due to velocity diffusion grows as $s^{\prime 2} \sim D \tau^{3}$. When the displacement is comparable to a wavelength of the wave, $\lambda^{2} \sim s^{\prime 2}$, then the clump has moved out of the trap terminating the clump. Hence, $\tau_{\text {clump }}^{3}=s^{\prime 2} / D \sim \lambda^{2} / D$ and

$$
\begin{equation*}
\tau_{\text {clump }} \sim \frac{w^{2}}{D} \sim\left(\frac{\lambda^{2}}{D}\right)^{1 / 3} \rightarrow w \sim(D \lambda)^{1 / 3} \tag{7.268}
\end{equation*}
$$

where $w$ is the clump width in velocity if the spatial and velocity diffusion times are equal. In general, if the spatial diffusion determines $\tau_{\text {clump }}$, then $w \cong\left(D \tau_{\text {clump }}\right)^{1 / 2}$. Given an estimate for $w$, we can then estimate the corresponding velocity distribution function perturbation $\delta f \sim\left|\left(\partial f_{0} / \partial v\right)\right| w$. We now use the the Liouville theorem to calculate the perturbed velocity distribution in more detail,

$$
\begin{equation*}
\frac{\mathrm{d} f}{\mathrm{~d} t}=\frac{\mathrm{d}}{\mathrm{~d} t}\left(f_{0}+\tilde{f}\right)=0 \rightarrow \frac{\mathrm{~d} \tilde{f}}{\mathrm{~d} t}=-\frac{\mathrm{d} f_{0}}{\mathrm{~d} t}=-\frac{\partial f_{0}}{\partial t}-\dot{v} \frac{\partial f_{0}}{\partial v}=-\dot{v} \frac{\partial f_{0}}{\partial v} \rightarrow \tilde{f} \sim-\int \mathrm{d} t \dot{v} \frac{\partial f_{0}}{\partial v} \tag{7.269}
\end{equation*}
$$

because $f_{0}$ is assumed time independent. We can now form an expression for the twotime correlation function for the perturbed velocity distribution function,

$$
\begin{equation*}
\langle\tilde{f}(1) \tilde{f}(2)\rangle \sim w^{2}\left(\frac{\partial f_{0}}{\partial v}\right)^{2} \Delta\left(\frac{x_{1}-x_{2}}{\lambda}\right) \Delta\left(\frac{v_{1}-v_{2}}{w}\right), \quad \Delta(y) \equiv\{1|y|<1,0|y|>1\} \tag{7.270}
\end{equation*}
$$

Although it does violence to the detailed physics, the following simplifications are adequate for subsequent integrations:

$$
\begin{equation*}
\Delta\left(\frac{x_{1}-x_{2}}{\lambda}\right) \rightarrow \lambda \delta\left(x_{1}-x_{2}\right) \quad \Delta\left(\frac{v_{1}-v_{2}}{w}\right) \rightarrow w \delta\left(v_{1}-v_{2}\right) \tag{7.271}
\end{equation*}
$$

Using (7.268)-(7.271) we can estimate that

$$
\begin{equation*}
\left\langle\tilde{f}\left(x_{1}, v_{1}\right) \tilde{f}\left(x_{2}, v_{2}\right)\right\rangle \sim \lambda^{2} D\left(\frac{\partial f_{0}}{\partial v}\right)^{2} \delta\left(x_{1}-x_{2}\right) \delta\left(v_{1}-v_{2}\right) \tag{7.272}
\end{equation*}
$$

and hence,

$$
\begin{equation*}
\left\langle\tilde{n}\left(x_{1}\right) \tilde{n}\left(x_{2}\right)\right\rangle \sim \lambda^{2} \delta\left(x_{1}-x_{2}\right) \int \mathrm{d} v D(v)\left(\frac{\partial f_{0}}{\partial v}\right)^{2} \tag{7.273}
\end{equation*}
$$

Next we Fourier transform from $x_{1}-x_{2} \rightarrow k$ and make use of $\int \mathrm{d} x \mathrm{e}^{\mathrm{i} k x} \delta(x)=1$ to obtain the spectral density for density fluctuations,

$$
\begin{equation*}
S_{\tilde{n}}(k) \sim\langle\tilde{n} \tilde{n}\rangle(k) \sim \frac{1}{k^{2}} \int \mathrm{~d} v D(v)\left(\frac{\partial f_{0}}{\partial v}\right)^{2} . \tag{7.274}
\end{equation*}
$$

We note that the correlation functions were derived earlier to be evaluated at the same time. If instead they involve two times $t_{1}$ and $t_{2}$, then

$$
\begin{equation*}
\left\langle\tilde{f}\left(x_{1}, v_{1}\right) \tilde{f}\left(x_{2}, v_{2}\right)\right\rangle \sim \lambda^{2} D\left(\frac{\partial f_{0}}{\partial v}\right)^{2} \delta\left(x_{1}-x_{2}\right) \delta\left(v_{1}-v_{2}\right) \Delta\left(\frac{t_{1}-t_{2}}{\tau_{\text {clump }}}\right) . \tag{7.275}
\end{equation*}
$$

If we allow for diffusion and resonance broadening then $\delta(\omega-k v) \rightarrow R(\omega-k v ; D)$. The generalization of (7.274) is then

$$
\begin{equation*}
S_{\tilde{n}}(k, \omega) \sim\langle\tilde{n} \tilde{n}\rangle(k, \omega) \sim \frac{1}{k^{2}} \int \mathrm{~d} v D(v)\left(\frac{\partial f_{0}}{\partial v}\right)^{2} R(\omega-k v ; D) . \tag{7.276}
\end{equation*}
$$

Now use $S_{\tilde{\rho}}(k, \omega)=e^{2} S_{\tilde{n}}(k, \omega)$ and Poisson's equation with plasma shielding $\phi=4 \pi \tilde{\rho} / k^{2} \varepsilon$ to obtain the field spectral density dropping various numerical constants along the way

$$
\begin{equation*}
S_{E}(k, \omega)=k^{2} S_{\phi}(k, \omega) \sim\left(\frac{4 \pi}{k^{2}}\right)^{2} \frac{e^{2}}{|\varepsilon|^{2}} \int \mathrm{~d} v D(v)\left(\frac{\partial f_{0}}{\partial v}\right)^{2} R(\omega-k v ; D) \tag{7.277}
\end{equation*}
$$

From our earlier development of quasilinear theory of diffusion

$$
\begin{equation*}
D_{\mathrm{waves}}(v)=\left(\frac{e}{m}\right)^{2} \iint \frac{\mathrm{~d} k \mathrm{~d} \omega}{(2 \pi)^{2}} S_{E}(k, \omega) R(\omega-k v ; D) \tag{7.278}
\end{equation*}
$$

The equations are not closed without equations for $f_{0}$ and $\mathrm{d} f_{0} / \mathrm{d} t$ :

$$
\begin{equation*}
\frac{\partial f_{0}}{\partial t}=-\frac{\partial}{\partial v}\left(F f_{0}\right)+\frac{\partial}{\partial v}\left(D(v) \frac{\partial f_{0}}{\partial v}\right) \tag{7.279}
\end{equation*}
$$

where $F$ is the dynamic friction (in this case the friction per unit mass, or deceleration) and (7.279) is the Fokker-Planck equation for the quasilinear diffusion of the clumps.

We return to (7.277) and (7.278) to obtain a consistency relation for $f_{0}$. Approximate the resonance function with a $\delta$ function. Then

$$
\begin{align*}
D(v) & =\left(\frac{e}{m}\right)^{2} \iint \frac{\mathrm{~d} k \mathrm{~d} \omega}{(2 \pi)^{2}} S_{E}(k, \omega) \delta(\omega-k v) \\
& =\iint \frac{\mathrm{d} k \mathrm{~d} \omega}{(2 \pi)^{2}}\left(\frac{4 \pi e^{2}}{k^{2} m}\right) \int \mathrm{d} v^{\prime} \frac{D\left(v^{\prime}\right)}{|\varepsilon(k, \omega)|}\left(\frac{\partial f_{0}}{\partial v}\right)^{2} \frac{1}{k} \delta\left(v^{\prime} \frac{\omega}{k}\right) \delta(\omega-k v) \\
& \sim\left(\frac{4 \pi e^{2}}{m}\right)^{2} \int \frac{\mathrm{~d} k}{2 \pi} \frac{1}{k^{5}} \frac{D\left(v^{\prime}=\frac{\omega}{k}=v\right)}{|\omega(k, \omega=k v)|^{2}}\left(\frac{\partial f_{0}}{\partial v}\right)^{2} \tag{7.280}
\end{align*}
$$

We define $f_{0}=n_{0} g$ and divide both sides of (7.280) by $D(v)$ to obtain a consistency relation for $g$,

$$
\begin{equation*}
1 \sim \omega_{p}^{4} \int \frac{\mathrm{~d} k}{k^{5}} \frac{1}{|\varepsilon(k, \omega=k v)|^{2}}\left(\frac{\partial g}{\partial v}\right)^{2} \approx \omega_{p}^{4}\left(\frac{\partial g}{\partial v}\right)^{2} \int \frac{\mathrm{~d} k}{k^{5}} \frac{1}{\left(\frac{\partial \varepsilon^{\prime}}{\partial \omega}\right)^{2}\left[\left(k v-\omega_{k}\right)^{2}+\gamma_{k}^{2}\right]^{2}}, \tag{7.281}
\end{equation*}
$$

where we used $|\varepsilon|^{2}=\varepsilon_{R}^{2}+\varepsilon_{I}^{2} \approx\left(\partial \varepsilon_{R} / \partial \omega\right)^{2}\left[\left(k v-\omega_{k}\right)^{2}+\gamma_{k}^{2}\right]^{2}$ and expanded around resonance. For Langmuir waves (7.281) yields

$$
\begin{align*}
1 & \sim \omega_{p}^{6} \frac{1}{v^{2}}\left(\frac{\partial g}{\partial v}\right)^{2} \int \frac{\mathrm{~d} k}{k^{5}} \frac{1}{\left[\left(k-\frac{\omega_{p}}{v}\right)^{2}+\frac{\gamma_{k}^{2}}{v^{2}}\right]^{2}} \sim \omega_{p}^{6} \frac{1}{v^{2}}\left(\frac{\partial g}{\partial v}\right)^{2} \frac{1}{k^{5}} \pi \frac{v}{\gamma_{k}} \\
& \sim \omega_{p}^{6} \frac{1}{v^{2}}\left(\frac{\partial g}{\partial v}\right)^{2}\left(\frac{v}{\omega_{p}}\right)^{5} \pi \frac{v}{\gamma_{k}} \sim \frac{\omega_{p} v^{4}}{\gamma_{k}}\left(\frac{\partial g}{\partial v}\right)^{2} . \tag{7.282}
\end{align*}
$$

In $\S 2.9$ we derived the relation $\gamma_{k} \sim\left(\omega_{p}^{3} / k^{2}\right) g^{\prime}(v=\omega / k)=\omega_{p}^{3} /\left(\omega_{p} / v\right)^{2} g^{\prime}(v=\omega / k)$ aside from numerical factors. Introduce the definition $A \equiv-v^{2} \mathrm{~d} g / \mathrm{d} v$ where $A$ is a number. Then $\mathrm{d} g / \mathrm{d} v=A / v$.

Finally we can calculate the radiation in Langmuir waves due to clumps.

$$
\begin{equation*}
\dot{W}(k)=S_{\tilde{j}}\left(k, \omega_{k}\right)=\left(\frac{\omega}{k}\right)^{2} S_{\tilde{\rho}}\left(k, \omega_{k}\right)=\frac{\omega_{p}^{2} e^{2}}{k^{5}} D\left(v=\frac{\omega_{k}}{k}\right)\left(\frac{\partial f_{0}}{\partial v}\right)_{\omega_{k} / k}^{2} . \tag{7.283}
\end{equation*}
$$

The expression in (7.283) can be integrated over $k$ and weighted by $k / \omega_{k}$ to calculate the growth of wave momentum to conserve momentum with the dynamic friction,

$$
\begin{align*}
\int \frac{\mathrm{d} k}{2 \pi} \frac{k}{\omega_{k}} \dot{W}(k) & =\int \mathrm{d} v m|F| f_{0} \rightarrow \int \frac{\mathrm{~d} v}{2 \pi} \frac{k}{v^{2}} \dot{W}\left(k=\frac{\omega_{k}}{v}\right) \\
& =\int \mathrm{d} v m|F| f_{0} \rightarrow m|F| f_{0}=\frac{1}{2 \pi} \frac{k}{v^{2}} \dot{W}\left(k=\frac{\omega_{k}}{v}\right) . \tag{7.284}
\end{align*}
$$

Equating the integrands in the integrals over velocity and using (7.283) we deduce

$$
\begin{equation*}
\dot{v}=F(v)=-v^{2} D(v) \frac{\left(g^{\prime}\right)^{2}}{g(v)} . \tag{7.285}
\end{equation*}
$$

Before returning to the Fokker-Planck equation we compare the dynamic friction calculated in (7.285) to the deceleration due to collisions using the resonance width due to clumps $w \sim(D \lambda)^{1 / 3}$,

$$
\begin{equation*}
\frac{\dot{v}}{v} \sim\left\{v \sim \frac{\omega_{p}}{\Lambda} \text { due to collisions, } \omega_{p}\left(\frac{w}{v}\right)^{3} \text { due to dynamic friction from clumps }\right\} \tag{7.286}
\end{equation*}
$$

The dynamic friction is much larger than collisional deceleration if the resonance width is sufficiently large.

Exercise. Fill in the numerical factors in this section and extend the formalism to three dimensions in velocity and configuration space.

The derivation in $\S 7.4$ yields a steady state for $f_{0}$, i.e. $\partial f_{0} / \partial t=0$. For whatever value of $A$ introduced after (7.282) is used, the plasma is stable. Nowhere have we established the turbulence level. We have only determined the velocity range where resonant waves are strong enough to give clumps. In this range, $g \sim A / v$. The characteristic rate for the wave dynamics (for Langmuir waves) is $\sim \omega_{p}$. The characteristic rate for clump evolution is $\sim \omega_{p} w / v$. The characteristic rate of evolution for $g$ is $\sim \omega_{p}(w / v)^{3}$.

Ion-acoustic waves can clump electron and ions more so. Both ion and electron clumps have dynamic friction. Dupree calculated anomalous resistivity associated with clumps and obtained $\sigma \sim 10 \omega_{p} / k \lambda_{D}$ where $k$ is the dominant wavenumber of the ionacoustic instability responsible for the waves (Dupree 1970).

## Part 4

## 8. Non-uniform plasmas: adiabatic invariance, local instabilities driven by nonuniformity and configurational instabilities

In § 8 we address non-uniform plasmas. We present a theory of adiabatic invariance, a Lagrangian approach to guiding-centre drifts, guiding-centre theory and hydromagnetic equations and an introduction to the theory of the stability of drift waves.

### 8.1. Adiabatic invariance

Consider the adiabatic invariance of the magnetic moment using the model problem of a one-dimensional harmonic oscillator. Then we extend the model to a nonlinear, anharmonic oscillator. The approach taken here is due to Dewar (1972). The equation of a harmonic oscillator with a time-dependent restoring force in one dimension is

$$
\begin{equation*}
\ddot{x}(t)+\Omega^{2}(t) x(t)=0, \quad|\dot{\Omega}| / \Omega \ll \Omega . \tag{8.1}
\end{equation*}
$$

Definition. Action $J \equiv H / \Omega=\left((1 / 2) \dot{x}^{2}+(1 / 2) \Omega^{2} x^{2}\right) / \Omega$ with the mass $m \equiv 1$.
Here $J$ is an approximate invariant. In what sense is this true? This is a classic Rayleigh-Lorentz pendulum problem posed by Lorentz and solved by Einstein at the beginning of the 20th century at a Solvay Conference. The WKB solution to (8.1) is

$$
\begin{equation*}
x(t) \approx \frac{a}{\sqrt{\Omega(t)}} \sin \left[\int_{0}^{t} \mathrm{~d} t^{\prime} \Omega\left(t^{\prime}\right)+\alpha\right] . \tag{8.2}
\end{equation*}
$$

Using the definition of $J$ in the preceding, one concludes that $J=\Omega\left\langle x^{2}\right\rangle \approx a^{2} / 2$ is a constant in time. Now suppose we introduce a WKB form for $x(t)$ in terms of a new unknown frequency $\omega(t)$ so that

$$
\begin{equation*}
x(t) \approx \frac{a}{\sqrt{\omega(t)}} \sin \left[\int_{0}^{t} \mathrm{~d} t^{\prime} \omega\left(t^{\prime}\right)+\alpha\right] \equiv \frac{a}{\sqrt{\omega(t)}} \sin \theta(t) \tag{8.3}
\end{equation*}
$$

We use (8.3) to evaluate the first and second time derivatives of $x$ and then the equation of motion (8.1) to obtain

$$
\begin{equation*}
-a\left[\frac{3}{4} \omega^{-5 / 2} \dot{\omega}^{2}-\frac{1}{2} \omega^{-3 / 2} \ddot{\omega}+\omega^{-1 / 2}\left(\Omega^{2}-\omega^{2}\right)\right]=0 \tag{8.4a}
\end{equation*}
$$

or

$$
\begin{equation*}
\frac{3}{4} \omega^{-2} \dot{\omega}^{2}-\frac{1}{2} \omega^{-1} \ddot{\omega}+\left(\Omega^{2}-\omega^{2}\right)=0 \rightarrow \omega^{2}-\Omega^{2}(t)=\omega^{1 / 2} \frac{\mathrm{~d}^{2}}{\mathrm{~d} t^{2}}\left(\omega^{-1 / 2}\right) \tag{8.4b}
\end{equation*}
$$

which is just as difficult to solve. However, what is gained is that (8.4b) gives a recipe for an iterative solution

$$
\begin{equation*}
\omega^{2}=\Omega^{2}(t)+\Omega^{1 / 2} \frac{\mathrm{~d}^{2}}{\mathrm{~d} t^{2}}\left(\Omega^{-1 / 2}\right)+\cdots \tag{8.5}
\end{equation*}
$$

We see the first correction to $\omega^{2} \approx \Omega^{2}(t)$ on the right-hand side of (8.5), which is an asymptotic series. Unfortunately the series diverges. In what sense is this result useful? We answer in an example. Consider the action

$$
\begin{equation*}
\left\langle\omega(t) x^{2}(t)\right\rangle_{\theta}=a^{2}\left\langle\sin ^{2} \theta(t)\right\rangle_{\theta}=\frac{a^{2}}{2} \tag{8.6}
\end{equation*}
$$

If we use a linear expansion of (8.5) for $\omega(t)$, which is just a function of $t$,

$$
\begin{equation*}
\omega \approx \Omega(t)\left[1+\frac{1}{2} \Omega^{-3 / 2} \frac{\mathrm{~d}^{2}}{\mathrm{~d} t^{2}}\left(\Omega^{-1 / 2}\right)+\cdots\right], \tag{8.7}
\end{equation*}
$$

and divide both sides of (8.6) by this expression, we obtain an auxiliary action $I_{0}(t)$,

$$
\begin{equation*}
I_{0}(t)=\left\langle\Omega x^{2}(t)\right\rangle_{\theta} \approx \frac{a^{2}}{2}\left[1-\frac{1}{2} \Omega^{-3 / 2} \frac{\mathrm{~d}^{2}}{\mathrm{~d} t^{2}}\left(\Omega^{-1 / 2}\right)+\cdots\right] . \tag{8.8}
\end{equation*}
$$

The second term on the right-hand side of (8.8) is useful in providing a quantitative estimate of the relative constancy of the lowest-order expression for the action. We note that

$$
\begin{align*}
\ln I_{0}(t) & =\ln \frac{a^{2}}{2}-\frac{1}{2} \Omega^{-3 / 2} \frac{\mathrm{~d}^{2}}{\mathrm{~d} t^{2}}\left(\Omega^{-1 / 2}\right)+\cdots \rightarrow \frac{\dot{I}_{0}}{I_{0}} \\
& =-\frac{\mathrm{d}}{\mathrm{~d} t}\left[\frac{1}{2} \Omega^{-3 / 2} \frac{\mathrm{~d}^{2}}{\mathrm{~d} t^{2}}\left(\Omega^{-1 / 2}\right)+\cdots\right] \ll \frac{\dot{\Omega}}{\Omega} \tag{8.9}
\end{align*}
$$

Thus, the relative rate of change in the action is much smaller than the relative rate of change in $\Omega$.

EXERCISE. Assume $\Omega(t)=\Omega_{0}\left(1+\varepsilon \mathrm{e}^{\gamma t}\right)$ and $\gamma \ll \Omega_{0}$. Evaluate (8.9) and confirm its conclusion.

Example. An example of an asymptotic series. At this point we pause to discuss an example of a potentially divergent asymptotic power series. Useful references for this and related matters are Erdélyi et al. (1954), Dwight (1964) and Abramowitz \& Stegun (1964). Consider the function $f(x)$

$$
\begin{equation*}
f(x)=\int_{0}^{\infty} \mathrm{d} t \frac{\exp (-t)}{1+x t}, \quad \operatorname{Re}(x) \geqslant 0 \tag{8.10}
\end{equation*}
$$

At $x=0, f(0)=1$; and $f$ is monotonically decreasing for increasing $x$. For $x \gg 1, f(x \gg 1) \approx(\ln (x-\gamma) / x) \exp (-x), \gamma=0.577$ (Euler's constant). Note that $1 /(1+x t)=1-x t+x^{2} t^{2}-x^{3} t^{3}+\cdots$, which converges only for $x t<1$. Also $\exp (-x)=\sum_{n} g_{n}=\sum_{n}(-1)^{n}\left(x^{n} / n!\right)$. The power-series representation for $f(x)$ is then

$$
\begin{equation*}
f(x)=\sum_{n} f_{n}(x)=1-x 1!+x^{2} 2!-x^{3} 3!+\cdots(-1)^{n} x^{n} n!+\cdots . \tag{8.11}
\end{equation*}
$$

The ratio of the $n$th term to the $(n-1)$ th term is $(-1) n x$, the magnitude of which is greater than unity for $n>1 / x$. The series is clearly oscillating and diverging. The power-series expansion of $f(x)$ only makes sense for $x \ll 1$. However, the truncated asymptotic power series has an error that is less than the next successive term in the truncated series. For example, if we retain four terms in (8.11), the next term is $x^{4} 4$ !. By choosing $n$ and $x$ carefully, we can minimize the error in the truncated power series. Consider $x=0.1$ for which $f(0.1)=0.91563$. The partial sums are

$$
\begin{gathered}
S_{0}=1, \quad S_{1}=0.9, \quad S_{2}=0.92, \quad S_{3}=0.914, \\
S_{4}=0.9164, \quad S_{5}=0.9152, \quad S_{6}=0.91592, \quad S_{7}=9158700, \\
S_{8}=0.9158736, \quad S_{9}=0.9158700, \quad S_{10}=0.9158736
\end{gathered}
$$

## Definition. The Error $\equiv\left|f(x)-S_{N}\right|<\left|f_{n+1}\right|=\left|x^{n} n!\right|$

In this series the error due to truncation is minimal when the ratio of successive terms is $O(1)$, i.e. $n x=1$. Hence, for $x=0.1$, we truncate the series at $n=10$, for which $x^{n} n!=0.00036$ is the error bound. The actual error is 0.00024 . Thus, there is always an error, but the error can be made tolerably small for a wide range of argument.
8.1.1. Harmonic oscillator model - use of WKB eikonal theory, asymptotic theory and action-angle variables to derive an approximate constant of the motion
Consider the following model problem with a time-dependent magnetic field and a Lagrangian description with a particular choice of gauge:

$$
\begin{equation*}
\boldsymbol{B}=B(t) \hat{\boldsymbol{z}}, \quad B_{z}=\frac{\partial}{\partial x} \boldsymbol{A}_{y}, \quad \boldsymbol{A}=B(t) x \hat{\boldsymbol{y}}, \quad \boldsymbol{E}^{\mathrm{T}}=-\frac{1}{c} \frac{\partial}{\partial t} \boldsymbol{A}=-\frac{1}{c} \frac{\partial}{\partial t} \dot{\boldsymbol{B}} x \hat{\boldsymbol{y}} . \tag{8.12}
\end{equation*}
$$

Motion in $z$ is ignored. The Lagrangian per unit mass for this system is

$$
\begin{align*}
\frac{L}{m} & =\frac{1}{2} \dot{x}^{2}+\frac{1}{2} \dot{y}^{2}+\frac{e}{m c} \boldsymbol{v} \cdot \boldsymbol{A}-\frac{e \phi(x, t)}{m} \\
& =\frac{1}{2} \dot{x}^{2}+\frac{1}{2} \dot{y}^{2}+\frac{e B(t) x \dot{y}}{m c}-\frac{e \phi(x, t)}{m}=\frac{1}{2} \dot{x}^{2}+\frac{1}{2} \dot{y}^{2}+\Omega(t) x \dot{y}-\frac{e \phi(x, t)}{m} . \tag{8.13}
\end{align*}
$$

DEFINITION. The canonical momentum is

$$
\begin{equation*}
p_{y} \equiv \frac{\partial L / m}{\partial \dot{y}}=\dot{y}+\Omega(t) x . \tag{8.14}
\end{equation*}
$$

From the Lagrangian equations

$$
\begin{gather*}
\frac{\mathrm{d}}{\mathrm{~d} t} p_{y}=\frac{\partial L}{\partial y}=0 \rightarrow p_{y}=\text { const. } \equiv \Omega\langle x\rangle=\Omega x_{\text {g.ctr. }}  \tag{8.15a}\\
p_{x}=\dot{x}, \quad \ddot{x}=\frac{\partial L}{\partial x}=\Omega(t) \dot{y}-\frac{e}{m} \frac{\partial \phi}{\partial x}=\Omega(t)\left[p_{y}-\Omega(t) x\right]-\frac{e}{m} \frac{\partial \phi}{\partial x} . \tag{8.15b}
\end{gather*}
$$

The evaluation of $p_{y}=$ const. in (8.15a) follows from time averaging the two oscillatory terms on the right-hand side of (8.14) which obviously sum to the same constant and using $\langle\dot{y}\rangle=0$ so that only the average of the second term remains. Hence, one arrives at the following equation of motion,

$$
\begin{equation*}
\ddot{x}+\Omega^{2}(t) x=\Omega(t) p_{y}-\frac{e}{m} \frac{\partial \phi}{\partial x} \Rightarrow \ddot{x}+\Omega^{2}(t) x=0 \tag{8.16}
\end{equation*}
$$

by choosing the guiding centre on the $y$ axis $\left(p_{y}=0\right)$ and with no perturbing electric potential $(\phi=0)$. With arbitrary initial conditions for the guiding-centre position

$$
\begin{equation*}
\ddot{x}+\Omega^{2}(t) x=\lambda(t)=\Omega(t) p_{y} . \tag{8.17}
\end{equation*}
$$

This is a linear inhomogeneous differential equation with non-constant coefficients.
One possible solution of (8.17) can be constructed iteratively,

$$
\begin{align*}
& \left(D_{t}^{2}+\Omega^{2}(t)\right) x=\Omega(t) p_{y} \rightarrow x=\left(D_{t}^{2}+\Omega^{2}(t)\right)^{-1} \Omega(t) p_{y}=\Omega^{-1}(t) p_{y}(1+\cdots) \\
& \quad \rightarrow \quad x=\frac{\lambda(t)}{\Omega^{2}(t)}-\frac{\ddot{x}}{\Omega^{2}(t)}=\frac{\lambda(t)}{\Omega^{2}(t)}-\frac{1}{\Omega^{2}(t)} \frac{\mathrm{d}^{2}}{\mathrm{~d} t^{2}}\left(\frac{\lambda(t)}{\Omega^{2}(t)}\right)+\cdots \tag{8.18}
\end{align*}
$$

Example. Consider a perturbing electric potential $\phi(x, t)=\phi_{0}(t) \cos k x$ and $k x \ll 1$ so that (8.16) becomes

$$
\begin{align*}
\ddot{x} & +\Omega^{2}(t) x=\frac{e k}{m} \phi_{0}(t) \sin k x \approx \frac{e k^{2}}{m} \phi_{0}(t) x \\
& \Rightarrow \quad \ddot{x}+\left[\Omega^{2}(t)-\frac{e k^{2}}{m} \phi_{0}(t)\right] x=\ddot{x}+\left[\Omega^{2}(t)-\omega_{B}^{2}(t)\right] x=0, \tag{8.19}
\end{align*}
$$

where $\omega_{B}$ is the bounce frequency associated with trapping. We recall (8.7)

$$
\begin{equation*}
\omega(t) \approx \Omega(t)\left[1+\frac{1}{2} \Omega^{-3 / 2} \frac{\mathrm{~d}^{2}}{\mathrm{~d} t^{2}}\left(\Omega^{-1 / 2}\right)+\cdots\right] \tag{8.20}
\end{equation*}
$$

which is an asymptotic series. For $\dot{\Omega} / \Omega$ small, the size of the $n$th term is small; and if the series is asymptotic we can prescribe an error limit and how many terms to retain in the series for $\omega(t)$.

Definition. A power series is formally asymptotic if it satisfies $\left|f(x)-S_{n}(x)\right|<$ $\left|S_{n+1}(x)-S_{n}(x)\right|$. The series can be converging or diverging.

EXAMPLE. $\Omega(t)=\Omega_{0}\left(1+\varepsilon \mathrm{e}^{\gamma t}\right), \varepsilon \mathrm{e}^{\gamma t} \ll 1, \gamma \ll \Omega_{0}$. Then analogous to (8.8)

$$
\begin{equation*}
I_{0}(t)=I_{0}(0)\left[1+\frac{\varepsilon}{4}\left(\frac{\gamma}{\Omega_{0}}\right)^{2} \mathrm{e}^{\gamma t}\right] \tag{8.21}
\end{equation*}
$$

Thus, the action is not conserved: there is a small, exponentially growing perturbation.

Example. Consider a $\Omega(t)$ that is initially constant and then grows smoothly and slowly on the time scale $T \gg \Omega_{0}^{-1}$ and saturates at some higher constant value. The expression for $I_{0}$ from (8.8) is

$$
I_{0}(t)=\left\langle\Omega x^{2}(t)\right\rangle_{\theta} \approx \frac{a^{2}}{2}\left[1-\frac{1}{2} \Omega^{-3 / 2} \frac{\mathrm{~d}^{2}}{\mathrm{~d} t^{2}}\left(\Omega^{-1 / 2}\right)+\cdots\right],
$$

and shows that the action remains essentially constant, although at first order there is a small correction that is at first negative and then positive before relaxing to zero. There is an adiabatic transition of the action from one stable asymptotic state to another. In Clemmow \& Dougherty (1989) it is shown that

$$
\begin{equation*}
\left|\frac{I_{0}(\infty)-I_{0}(-\infty)}{I_{0}}\right| \sim \mathrm{e}^{-\Omega T / 2 \pi} . \tag{8.22}
\end{equation*}
$$

Thus, there is an exponentially small change in the action. In fact, the action is conserved to all powers in $2 \pi / \Omega T$ (we showed only through the first correction in $I_{0}$ ). In the ( $x, \dot{x}$ ) phase space, the particle orbit is an ellipse with radius $a \sim 1 / \sqrt{\Omega}$ in $x$ from (8.2) and radius $\Omega a \sim \sqrt{\Omega}$ in $\dot{x}$, but the area of the ellipse $\pi \Omega(t) a^{2}$ is a constant. Hence, as $\Omega(t)$ varies the particle rides on an evolving ellipse whose eccentricity changes, but the area remains invariant.

### 8.1.2. Phase-space dynamics for trapped and passing particles in a single electrostatic wave

Consider a perturbing electric potential $\phi(x, t)=\phi_{0}(t) \cos k x$ in the wave frame with no applied magnetic field. For $k x \ll 1$ the analysis in (8.20)-(8.22) shows that the phase-space orbits for the trapped particles lie on ellipses. For particle energies such that the particle excursion in the wave is larger, the electric potential cannot be expanded for small $k x$; and the orbits distort from ellipses. For sufficiently large energies, the particles are no longer confined in the potential trough; and the particle trajectories are unconfined (untrapped). The Hamiltonian for particles in the wave frame is

$$
\begin{equation*}
H=\frac{1}{2} \dot{x}^{2}+\frac{e \phi_{0}(t)}{m} \cos k x . \tag{8.23}
\end{equation*}
$$

For slowly varying potential amplitudes relative to the bounce time, there is a conserved action. For trapped particles the action can be constructed from

$$
\begin{equation*}
J \equiv \frac{1}{2 \pi} \oint \dot{x}\left(x ; H, \phi_{0}\right) \mathrm{d} x=J\left(H, \phi_{0}\right) . \tag{8.24}
\end{equation*}
$$

With $J$ an invariant, as $\phi_{0}$ varies, then $H$ must also vary. For an untrapped particle, we define the action based on one pass across the change in the electric potential,

$$
\begin{equation*}
J \equiv \frac{1}{2 \pi} \int_{0}^{2 \pi / k} \dot{x}\left(x ; H, \phi_{0}\right) \mathrm{d} x . \tag{8.25}
\end{equation*}
$$

We use (8.23) to solve for $\dot{x}$ and then evaluate the actions in (8.24) and (8.25). The untrapped particles have action

$$
\begin{equation*}
J\left(H, \phi_{0}\right)=\frac{4}{\pi k} \sqrt{\frac{m H+e \phi_{0}}{2 m}} \mathrm{E}(\kappa), \quad \kappa=\sqrt{\frac{2 e \phi_{0}}{m H+e \phi_{0}}} \equiv \frac{1}{\mu} \tag{8.26}
\end{equation*}
$$

$\kappa=0$ corresponds to infinite energy, while $\kappa=1$ corresponds to a particle on the separatrix between passing and trapped and E is the complete elliptic integral of the second kind. For $\kappa \ll 1, \mathrm{E} \approx(\pi / 2)\left(1-\kappa^{2} / 8+\cdots\right)$. For $\kappa \rightarrow 1$, $\mathrm{E} \approx 1+(1 / 2)(1-$ $\left.\kappa^{2}\right)\left(\ln \left(4 / \sqrt{1-\kappa^{2}}\right)-(1 / 2)\right)$. The trapped particles have action

$$
\begin{equation*}
J\left(H, \phi_{0}\right)=\frac{8}{\pi k} \sqrt{\frac{e \phi_{0}}{m}}\left[\mathrm{E}(\mu)-\left(1-\mu^{2}\right) \mathrm{K}(\mu)\right] . \tag{8.27}
\end{equation*}
$$

The arguments of the complete elliptic integrals of the first and second kind in (8.27) are the inverse of that in (8.26). For $\mu=1 / \kappa \rightarrow 0$, corresponding to the bottom of the potential well, $\mathrm{E}(\mu) \approx(\pi / 2)\left(1+\mu^{2} / 4+\cdots\right)$ and $\mathrm{K}(\mu) \approx \ln \left(4 / \sqrt{1-\mu^{2}}\right)$. The action is a linearly increasing function of $H$ for the trapped particle region, $-e \phi_{0} / m<H<$ $e \phi_{0} / m$, until approaching the separatrix at $H=e \phi_{0}$ where $J$ swings up sharply. For $H \gg e \phi_{0}$ the action increases with $H$ asymptotically as $\sqrt{H}$. We note that at the bottom of the potential well, the particle motion is that of a harmonic oscillator and $J=H / \Omega$. We also note the following relations:

$$
\begin{equation*}
\omega=\dot{\theta}=\frac{\partial H}{\partial J}=\omega(J), \quad \dot{J}=-\frac{\partial H}{\partial \theta}=0, \quad \tau \equiv \frac{2 \pi}{\omega(J)}=2 \pi \frac{\mathrm{~d} J}{\mathrm{~d} H} . \tag{8.28}
\end{equation*}
$$

As the separatrix is approached, $\tau \rightarrow \infty$ and $\mathrm{d} J / \mathrm{d} H \rightarrow \infty$.
We can prove conservation of action quite generally. Consider a particle Hamiltonian in terms of canonically conjugate variables with a slowly varying parameter $\lambda(t)$,

$$
\begin{equation*}
H(q, p ; \lambda(t)), \quad p(q, H ; \lambda(t)) \tag{8.29}
\end{equation*}
$$

We define the action $J$ as

$$
\begin{equation*}
J \equiv \oint \mathrm{~d} q p(q, H ; \lambda) \tag{8.30}
\end{equation*}
$$

Then the time derivative of $J$ is calculated as follows:

$$
\begin{equation*}
\dot{J}=\frac{\partial J}{\partial H} \dot{H}+\frac{\partial J}{\partial \lambda} \dot{\lambda},\left.\quad \frac{\mathrm{~d} H}{\mathrm{~d} t}\right|_{p, q}=\frac{\partial H}{\partial t}=\frac{\partial H}{\partial \lambda} \dot{\lambda} \quad \Rightarrow \quad \dot{J}=\left(\frac{1}{\omega} \frac{\partial H}{\partial \lambda}+\frac{\partial J}{\partial \lambda}\right) \dot{\lambda} . \tag{8.31}
\end{equation*}
$$

At this point the following lemma is helpful:

$$
\begin{equation*}
\left.\frac{\partial p}{\partial \lambda}\right|_{q, H}=\frac{-\left.\frac{\partial H}{\partial \lambda}\right|_{p, q}}{\left.\frac{\partial H}{\partial p}\right|_{q, \lambda}} \tag{8.32}
\end{equation*}
$$

We can then evaluate $\partial J /\left.\partial \lambda\right|_{H}$

$$
\begin{align*}
\left.\frac{\partial J}{\partial \lambda}\right|_{H} & =\left.\frac{1}{2 \pi} \oint \mathrm{~d} q \frac{\partial p(q, H, \lambda)}{\partial \lambda}\right|_{q, H}=-\left.\frac{1}{2 \pi} \oint \frac{\mathrm{~d} q}{\dot{q}(q, p, \lambda)} \frac{\partial H}{\partial \lambda}\right|_{p, q} \\
& =-\left.\frac{\tau}{2 \pi} \oint \frac{\mathrm{~d} t}{\tau} \frac{\partial H}{\partial \lambda}\right|_{p, q}=-\frac{1}{\omega}\left\langle\frac{\partial H}{\partial \lambda}\right\rangle(H, \lambda) \tag{8.33}
\end{align*}
$$

where the average on the right-hand side of (8.33) is over the orbit. We then substitute the result of (8.33) in (8.31) to obtain

$$
\begin{equation*}
\dot{J}=\frac{\dot{\lambda}}{\omega}\left(\frac{\partial H}{\partial \lambda}-\left\langle\frac{\partial H}{\partial \lambda}\right\rangle\right) \quad \rightarrow \quad\langle\dot{J}\rangle \approx \frac{\dot{\lambda}}{\omega}\left(\left\langle\frac{\partial H}{\partial \lambda}\right\rangle-\left\langle\frac{\partial H}{\partial \lambda}\right\rangle\right)=0 \tag{8.34}
\end{equation*}
$$

for $|\dot{\lambda} / \omega \lambda| \ll 1$. Thus, $\langle\dot{J}\rangle_{\text {orbit }}=0$, although $\dot{J} \neq 0$ due to slow variations in $\lambda$ and $H$.
Example. For the Hamiltonian in (8.23), as $\phi_{0}(t)$ changes, $H$ changes, and the separatrix in $(x, v)$ phase space changes its width. A particle will tend to remain on a curve of constant action. Although the average of the time derivative of the action over the phase in (8.34) is zero, the time (not orbit) averaged $\langle\mathrm{d} J / \mathrm{d} t\rangle=O(\lambda)$ from (8.31) is not zero. As a parameter is slowly changed causing an adiabatic transition from one stable orbit to another stable orbit, there is an exponentially small change in $J$. When a particle crosses the separatrix, the change in $J$ is still perturbative. (Gardner 1959).

Example. The examples considered here have implications for the saturation of instabilities. Consider a weakly growing bump-on-tail instability. The phase velocity of an unstable wave falls on a region of the velocity distribution function $f(v)$ with positive slope due to the bump on the tail. As the growing wave traps resonant particles, there are more particles with velocities faster than the wave than slower. Hence, the resonant particles lose momentum; and the non-resonant particles that account for the wave momentum must gain momentum to conserve total momentum. The net deceleration of resonant particles and acceleration of non-resonant particles does not continue indefinitely: the resonant momentum loss and non-resonant momentum gain reach limits. A more careful analysis shows that the energy of the resonant particles changes. Conservation of energy implies that the wave energy must evolve in consequence. However, in the wave frame the wave frequency and energy would be zero were it not for the fact that trapping leads to a frequency shift $\delta \omega$ (Dewar \& Lindl 1972). Dewar (1973) shows that the wave continues to grow until the trapping frequency exceeds the linear growth rate by a certain amount,

$$
\begin{equation*}
\omega_{B} \equiv \sqrt{\frac{k^{2} e \phi_{0}}{m}}=\frac{256}{9 \pi^{2}} \gamma_{L}=2.88 \gamma_{L} . \tag{8.35}
\end{equation*}
$$

Fried, Liu, Means and Sagdeev found in numerical simulation a factor of 3.2 rather than 2.88 in the saturation (Fried et al. 1970).

ExErcise. Suppose that the parameter in the Hamiltonian $\lambda(t)$ has variation $\lambda(t)=$ $\lambda_{0}+\lambda_{1} \sin \Omega_{1} t$ with $\lambda_{1} \ll \lambda_{0}$ and consider three interesting situations in which the particle Hamiltonian has a sinusoidal electrostatic wave with frequency $\omega$ :
(i) $\Omega_{1} \approx \omega$ parametric resonance;
(ii) $\Omega_{1} \approx \omega(\ell / m)$ rational relation;
(iii) $\Omega_{1} \ll \omega$ adiabatic.

EXAMPLE. Anharmonic oscillator - consider a Hamiltonian

$$
\begin{equation*}
H=\frac{1}{2} \dot{x}^{2}+V(x)=\frac{1}{2} \dot{x}^{2}+a_{0}+\frac{1}{2} a_{1}(t) x^{2}+\frac{1}{4} a_{2} x^{4} \tag{8.36}
\end{equation*}
$$

with $a_{1}(t)<0$ and $\left|a_{1}\right|$ increases in magnitude. With $a_{1}(t)=0$ there is a single potential well that is symmetric about $x=0$. For finite $\left|a_{1}\right|$ there are two wells symmetric about $x=0$ that become deeper as $\left|a_{1}\right|$ increases in magnitude. With the inclusion of a term $(1 / 3) a_{3} x^{3}$ in $V$, there is no longer symmetry with respect to $x=0$. There can still be two potential wells that can trap particles, but the wells are asymmetric. The probability of trapping in one or the other well is proportional to the phase-space area encompassed by each well. Under adiabatic changes, the total probability is conserved.

### 8.1.3. Magnetic mirror geometry and derivation of adiabatic invariant using canonical transformations

Consider particle motion in a simple magnetic mirror configuration with two degrees of freedom, i.e. the magnetic field has $x$ and $z$ components and varies in $x$ and $z$ (no $y$ variation). The Lagrangian for a charged particle in this case is

$$
\begin{equation*}
L=\frac{1}{2} \dot{x}^{2}+\frac{1}{2} \dot{y}^{2}+\frac{1}{2} \dot{z}^{2}+\frac{e}{m c} \boldsymbol{v} \cdot \boldsymbol{A} . \tag{8.37}
\end{equation*}
$$

The magnetic field is represented by

$$
\begin{equation*}
\boldsymbol{B}=\nabla \times \boldsymbol{A}, \quad \boldsymbol{A}=\hat{\boldsymbol{y}} A(x, z)=\hat{\boldsymbol{y}} \times B_{0}(z), \quad B_{z}=\frac{\partial A}{\partial x}, \quad B_{x}=-\frac{\partial A}{\partial z}=-x \frac{\partial B_{0}}{\partial z} . \tag{8.38}
\end{equation*}
$$

Assume that $B_{0}(z)=B_{0}\left(1+z^{2} / L^{2}\right)$. Because the Lagrangian in (8.37) has no dependence on $y, p_{y}$ is a constant of the motion,

$$
\begin{equation*}
p_{y} \equiv \frac{\partial L}{\partial \dot{y}}=\dot{y}+\frac{e}{m c} A(x, z)=\dot{y}+\Omega(z) x, \quad \Omega(z) \equiv \frac{e B_{0}(z)}{m c} \tag{8.39}
\end{equation*}
$$

$p_{\mathrm{y}}$ specifies which field line the particle is gyrating around and transiting on. Energy conservation is determined by

$$
\begin{equation*}
E=\frac{1}{2} \dot{x}^{2}+\frac{1}{2} \dot{y}^{2}+\frac{1}{2} \dot{z}^{2}=L=\frac{1}{2} \dot{x}^{2}+\frac{1}{2}\left(p_{y}-\Omega(z) x\right)^{2}+\frac{1}{2} \dot{z}^{2} . \tag{8.40}
\end{equation*}
$$

We choose $p_{y}=0$ and obtain

$$
\begin{equation*}
H\left(x, z ; p_{x}, p_{z}\right)=E=\frac{1}{2} \dot{x}^{2}+\frac{1}{2} \Omega^{2}(z) x^{2}+\frac{1}{2} v_{\|}^{2} \equiv \frac{1}{2} v_{\perp}^{2}+\frac{1}{2} v_{\|}^{2}, \tag{8.41}
\end{equation*}
$$

$E$ is clearly a constant of the motion because $H$ has no explicit time dependence. In consequence, only three of the four variables $\left(x, z ; p_{x}, p_{z}\right)$ are independent, which defines a volume in the four-dimensional phase space. From (8.40) and (8.41)

$$
\begin{equation*}
p_{x}^{2}+\Omega^{2}(z) x^{2}=2 E-p_{z}^{2} \leqslant 2 E \tag{8.42}
\end{equation*}
$$

The surface defined by $p_{x}^{2}+\Omega^{2}(z) x^{2}=2 E$ acts as a bounding surface in $\left(x, z, p_{x}\right)$ space, which contains the particle trajectory. The particle trajectory may be a closed curve (it is exactly periodic) or it may fill the bounded volume eventually, i.e. the orbit may be ergodic. We define the orbit to be ergodic if for any point in the volume one can construct a small neighbourhood around the point and the particle trajectory/orbit will eventually intersect the volume.

Let us construct a conserved action from the particle motion in the simple mirror. Assume that the gyroradius is much smaller than the axial scale length of the magnetic well: $\rho \ll L$. Now freeze $\left(z, p_{z}\right)$. From (8.30) we construct the action

$$
\begin{equation*}
J_{X} \equiv \oint \mathrm{~d} x p_{x}\left(x ; H, z, p_{z}\right) \rightarrow \mu \tag{8.43}
\end{equation*}
$$

which is the magnetic moment except for factors of $e, m$ and $c$. Consider $\mathrm{d} J_{x} / \mathrm{d} t$,

$$
\begin{equation*}
\dot{J}_{x}=\frac{\partial J_{x}}{\partial z} \dot{z}+\frac{\partial J_{x}}{\partial p_{z}} \dot{p}_{z}, \tag{8.44}
\end{equation*}
$$

and

$$
\left.\begin{array}{c}
\frac{\partial J_{x}}{\partial z}=\left.\oint \mathrm{d} x \frac{\partial p_{x}}{\partial z}\right|_{x, H, p_{z}}=\left.\oint \mathrm{d} x \frac{-\frac{\partial H}{\partial z}}{\frac{\partial H}{x p_{x}}}\right|_{x, p_{x}, p_{z}}  \tag{8.45}\\
\left.\right|_{x, z, p_{z}} \\
\frac{\partial J_{x}}{\partial p_{z}}=\oint \mathrm{d} x \frac{\dot{p}_{z}}{\dot{x}} \equiv \tau_{x}\left\langle\dot{p}_{z}\right\rangle_{x \text {-orbit }} \\
\left.\mathrm{d} x \frac{\partial p_{x}}{\partial p_{z}}\right|_{x, z, H}=\oint \mathrm{d} x \frac{-\left.\frac{\partial H}{\partial p_{z}}\right|_{x, z, p_{x}}}{\left.\frac{\partial H}{\partial p_{x}}\right|_{x, z, p_{z}}}=-\oint \mathrm{d} x \frac{\dot{z}}{\dot{x}} \equiv-\tau_{x}\langle\dot{z}\rangle_{x \text {-rbit }}
\end{array}\right\}
$$

Hence, $\mathrm{d} J_{x} / \mathrm{d} t$ from (8.44) becomes

$$
\begin{gather*}
\dot{J}_{x}=\frac{\partial J_{x}}{\partial z} \dot{z}+\frac{\partial J_{x}}{\partial p_{z}} \dot{p}_{z}=\tau_{x}\left[\dot{z}\left\langle\dot{p}_{z}\right\rangle_{x \text {-orbit }}-\dot{p}_{z}\langle\dot{z}\rangle_{x \text {-orbit }}\right] \\
\Rightarrow \quad\left\langle\dot{J}_{x}\right\rangle_{x \text {-orbit }}=0 \tag{8.46}
\end{gather*}
$$

The average over $x$ orbits is equivalent to an average over many particles with different phases in their orbits within the accessible volume of orbits. As in (8.31)-(8.34) the orbit average over phases is zero but the time average $\left\langle\mathrm{d} J_{x} / \mathrm{d} t\right\rangle=0+O\left(\epsilon^{2}\right)$, where $\epsilon=\rho_{g} / L_{z}$ is the ratio of the Larmor radius to the axial scale length of the magnetic field.

We return to (8.43) to calculate the action. We use $p_{x}=\left(2 E-p_{z}^{2}-\Omega^{2}(z) x^{2}\right)^{1 / 2}$ and integrate $J_{x}=\oint \mathrm{d} x p_{x}$ for fixed $z$ and $p_{z}$. One obtains

$$
\begin{align*}
J_{x}\left(H, z, p_{z}\right) & =\oint \mathrm{d} x\left(2 E-p_{z}^{2}-\Omega^{2}(z) x^{2}\right)^{1 / 2}=\oint \mathrm{d} x\left(2\left(\frac{1}{2} m v_{\perp}^{2}\right)-\Omega^{2}(z) x^{2}\right)^{1 / 2} \\
& =\oint \mathrm{d} x\left(2 W_{\perp}-\Omega^{2}(z) x^{2}\right)^{1 / 2} \approx \sqrt{2 W_{\perp}} \oint \mathrm{d} x\left(1-\frac{\Omega^{2}(z) x^{2}}{2 W_{\perp}}\right)^{1 / 2} \\
& =\frac{2 W_{\perp}}{\Omega} \oint \mathrm{d} \theta \sin ^{2} \theta=2 \pi \frac{W_{\perp}}{\Omega} \propto \frac{W_{\perp}}{\Omega} \equiv \mu \tag{8.47}
\end{align*}
$$

where $W_{\perp}$ is approximately constant over the gyro-orbit, $\mathrm{d} x=-\left(\sqrt{2 W_{\perp}} / \Omega\right) \sin \theta \mathrm{d} \theta$, and the integration is over the gyro-orbit. Action and energy conservation constrain the particle orbit in the $\left(x, p_{x}\right)$ plane to be an ellipse with radii $\left(2 E-p_{z}^{2}\right)^{1 / 2} / \Omega(z)=$ $\left(2 J_{x} / \Omega(z)\right)^{1 / 2}$ in $x$ and $\left(2 E-p_{z}^{2}\right)^{1 / 2}=\left(2 J_{x} \Omega(z)\right)^{1 / 2}$ in $p_{x}$.

How well is the magnetic moment conserved over the bounce motion of the particle in the magnetic well? Suppose $\epsilon=\rho_{g} / L_{z} \sim 10^{-2}$. An estimate of the relative change in the action $\mu=J_{x} \equiv J_{g}$ over a bounce is

$$
\begin{equation*}
\frac{\Delta\left\langle J_{g}\right\rangle}{J} \sim \tau_{\text {bounce }} \frac{\left\langle\dot{J}_{g}\right\rangle}{J}=O\left(\frac{\tau_{g}}{\varepsilon}\right) \frac{\left\langle\dot{J}_{g}\right\rangle}{J} \sim O \frac{\left(\varepsilon^{2}\right)}{\varepsilon} \sim O(\varepsilon) \sim 10^{-2} \tag{8.48}
\end{equation*}
$$

If the drift time is one order longer in $\epsilon^{-1}$, i.e. 100 bounces in this example, then the relative change in the action is $O(1)$. Thus, a detailed calculation is needed to quantify the change in action over many bounces.

The Hamiltonian in (8.41) is

$$
\begin{equation*}
H(x, \dot{x}, z, \dot{z}) \rightarrow H\left(x, p_{x} ; z, p_{z}\right)=\frac{1}{2} p_{x}^{2}+\frac{1}{2} \Omega^{2}(z) x^{2}+\frac{1}{2} p_{z}^{2} . \tag{8.49}
\end{equation*}
$$

We introduce a canonical transformation to represent the system using the old coordinates but with new momentum variables, so that the new Hamiltonian will be written in terms of action-angle variables: $\left(x, p_{x} ; z, p_{z}\right) \rightarrow\left(\theta_{g}, J_{g} ; Z, P_{z}\right)$. The generating function for the canonical transformation is

$$
\begin{align*}
S\left(x, z ; J_{g}, P_{z}\right) & =\int_{0}^{x} \mathrm{~d} x^{\prime} \sqrt{2 J_{g} \Omega(z)-\Omega^{2}(z) x^{\prime 2}}+z P_{z} \\
\rightarrow \quad \theta_{g} & =\frac{\partial S}{\partial J_{g}} \\
Z & =\frac{\partial S}{\partial P_{z}}=z \\
p_{x} & =\frac{\partial S}{\partial x}=\sqrt{2 J_{g} \Omega(z)} \cos \theta_{g} \\
p_{z} & =\frac{\partial S}{\partial z}=P_{z}+O(\varepsilon)=P_{z}+\int_{0}^{x} \mathrm{~d} x^{\prime} \frac{J_{g} \Omega^{\prime}-\Omega \Omega^{\prime} x^{\prime 2}}{\sqrt{2 J_{g} \Omega(z)-\Omega^{2}(z) x^{\prime 2}}} \\
& =P_{z}+\frac{\Omega^{\prime}}{2 \Omega} J \sin 2 \theta_{g} \tag{8.50}
\end{align*}
$$

where $\Omega^{\prime}=\mathrm{d} \Omega / \mathrm{d} z=O(\varepsilon) \Omega$ and $x \equiv \sqrt{2 J_{g} / \Omega(z)} \sin \theta_{g}$ from the action orbit in the $\left(x, p_{x}\right)$ plane. The Hamiltonian in the new coordinates is

$$
\begin{equation*}
H\left(\theta_{g}, J_{g}, Z, P_{z}\right)=\Omega(z) J_{g}+\frac{1}{2}\left[P_{z}+\frac{\Omega^{\prime}}{2 \Omega} J_{g} \sin 2 \theta_{g}\right]^{2} \tag{8.51}
\end{equation*}
$$

From the Hamiltonian in (8.51) we can evaluate the time derivative of the action,

$$
\begin{equation*}
\dot{J}_{g}=-\frac{\partial H}{\partial \theta_{g}}=-\left[P_{z}+\frac{\Omega^{\prime}}{2 \Omega} J_{g} \sin 2 \theta_{g}\right] \frac{\Omega^{\prime}}{\Omega} J_{g} \cos 2 \theta_{g}+O\left(\varepsilon^{2}\right)=O(\varepsilon) \tag{8.52}
\end{equation*}
$$

We see that the time derivative of the action has a small $O\left(\Omega^{\prime} / \Omega\right)=O(\epsilon)$ rapid variation. To lowest order the time integral of (8.52) ignoring other derivatives yields

$$
\begin{equation*}
\Delta J_{g}=-P_{z} \frac{\Omega^{\prime}}{2 \Omega^{2}} J_{g} \sin 2 \theta_{g}+O\left(\varepsilon^{2}\right)=O(\varepsilon), \quad \dot{\theta}_{g}=\frac{\partial H}{\partial J_{g}}=\Omega+O(\varepsilon) \tag{8.53}
\end{equation*}
$$

We define a new approximately conserved quantity

$$
\begin{equation*}
I_{g} \equiv J_{g}-\Delta J_{g} \Rightarrow \dot{I}_{g} \equiv \dot{J}_{g}-\Delta \dot{J}_{g}=O\left(\varepsilon^{2}\right) \tag{8.54}
\end{equation*}
$$

We next introduce a new canonical transformation to remove the high-frequency jitter in (8.52): $\left(\theta_{g}, J_{g} ; Z, P_{z}\right) \rightarrow\left(\Theta_{g}, I_{g} ; Z, \mathrm{P}_{z}\right)$ using

$$
\begin{align*}
S\left(\theta_{g}, Z ; I_{g}, \mathrm{P}_{z}\right) & =I_{g} \theta_{g}+\mathrm{P}_{z} \frac{\Omega^{\prime}}{4 \Omega^{2}} I_{g} \cos 2 \theta_{g}+Z \mathrm{P}_{z} \\
\rightarrow \quad J_{g} & =\frac{\partial S}{\partial \theta_{g}}=I_{g}-\mathrm{P}_{z} \frac{\Omega^{\prime}}{2 \Omega^{2}} I_{g} \sin 2 \theta_{g} \\
Z & =\frac{\partial S}{\partial \mathrm{P}_{z}}=Z+\frac{\Omega^{\prime}}{4 \Omega^{2}} I_{g} \cos 2 \theta_{g} \\
P_{z} & =\frac{\partial S}{\partial z}=\mathrm{P}_{z}\left[1+\frac{\mathrm{d}}{\mathrm{~d} z}\left(\frac{\Omega^{\prime}}{\Omega^{2}}\right) \frac{I_{g}}{4} \cos 2 \theta_{g}\right] \\
\Theta_{g} & =\frac{\partial S}{\partial I_{g}}=\theta_{g}+\mathrm{P}_{z} \frac{\Omega^{\prime}}{4 \Omega^{2}} \cos 2 \theta_{g} \tag{8.55}
\end{align*}
$$

With this new canonical transformation the Hamiltonian can be rewritten in terms of the new variables,

$$
\left.\begin{array}{c}
H=I_{g}\left(1-\mathrm{P}_{z} \frac{\Omega^{\prime}(Z)}{2 \Omega^{2}(Z)} \sin 2 \theta_{g}\right) \Omega(Z)+\frac{1}{2}\left[\mathrm{P}_{z}(1+\cdots)+\cdots\right]^{2} \\
\Omega(Z)=\Omega\left(Z-\frac{\Omega^{\prime}(Z)}{4 \Omega^{2}} I_{g} \cos 2 \theta_{g}\right)=\Omega(Z)+O(\varepsilon) \tag{8.56}
\end{array}\right\}
$$

We expand the terms in (8.56) for $H$ and find that the $O(\varepsilon)$ terms cancel leaving

$$
\begin{equation*}
H\left(\Theta_{g}, I_{g}, Z, P_{z}\right)=I_{g} \Omega(Z)+\frac{1}{2} \mathrm{P}_{z}^{2}+O\left(\varepsilon^{2}\right) \tag{8.57}
\end{equation*}
$$

In terms of these action-angle variables the following equations of motion are obtained:

$$
\left.\begin{array}{c}
\dot{I}_{g}=-\frac{\partial H}{\partial \Theta_{g}}=0+O\left(\varepsilon^{2}\right), \quad \dot{\mathrm{P}}_{z}=-\frac{\partial H}{\partial Z}=-\Omega^{\prime}(Z) I_{g}+O\left(\varepsilon^{2}\right) \\
\dot{\Theta}_{g}=\frac{\partial H}{\partial I_{g}}=\Omega(Z)+O\left(\varepsilon^{2}\right), \quad \dot{Z}=\frac{\partial H}{\partial \mathrm{P}_{z}}=\mathrm{P}_{z}+O\left(\varepsilon^{2}\right) \tag{8.58}
\end{array}\right\}
$$

The finite time derivative of $\mathrm{P}_{z}$ represents the mirroring forces on particles as they transit or bounce back and forth along the field line.

Through second order in $\epsilon$ the Hamiltonian in terms of action-angle variables is

$$
\begin{align*}
H\left(\Theta_{g}, I_{g}, Z, \mathrm{P}_{z}\right)= & I_{g} \Omega(Z)+\frac{1}{2} \mathrm{P}_{z}^{2}-\frac{\Omega^{\prime 2}}{4 \Omega^{2}} I_{g}^{2} \cos 2 \theta_{g}+\frac{1}{8} \frac{\Omega^{\prime 2}}{\Omega^{2}} I_{g}^{2} \sin ^{2} 2 \theta_{g} \\
& +\frac{1}{4} \mathrm{P}_{z}^{2} I_{g}\left[\frac{\mathrm{~d}}{\mathrm{~d} z}\left(\frac{\Omega^{\prime}}{\Omega^{2}}\right) \cos 2 \theta_{g}-\frac{\Omega^{\prime 2}}{\Omega^{3}} \sin ^{2} 2 \theta_{g}\right] \tag{8.59}
\end{align*}
$$

where

$$
\begin{equation*}
\theta_{g}=\Theta_{g}-\mathrm{P}_{z} \frac{\Omega^{\prime}}{4 \Omega^{2}} \cos 2 \theta_{g}, \quad z=Z-I_{g} \frac{\Omega^{\prime}}{4 \Omega^{2}} \cos 2 \theta_{g} \tag{8.60}
\end{equation*}
$$

The correction terms in $\theta_{g}$ and $z$ only contribute $O\left(\epsilon^{3}\right)$ and $O\left(\epsilon^{4}\right)$ terms in $H$, so they are superfluous through second order in $\epsilon$ in affecting $H$. We note that

$$
\begin{equation*}
I_{g} \Omega(Z)=\frac{m c}{e} \mu \frac{e B(z)}{m c}=\mu B(z)=\frac{1}{2} m v_{\perp}^{2} \quad \rightarrow \quad H^{(0)}=\frac{1}{2} \dot{z}^{2}+\mu B(z) \tag{8.61}
\end{equation*}
$$

The second term in $H^{(0)}$ gives the standard bouncing motion along the field lines in a magnetic mirror configuration.

EXAmple. Quadratic magnetic well - we make an explicit assumption about the magnetic field,

$$
\begin{equation*}
B(z)=B_{0}\left(1+\frac{1}{2} \frac{z^{2}}{L^{2}}\right) \quad \rightarrow \quad \Omega(Z)=\Omega_{0}\left(1+\frac{1}{2} \frac{Z^{2}}{L^{2}}\right) \tag{8.62}
\end{equation*}
$$

In this magnetic well the equations of motion yield

$$
\begin{equation*}
\dot{I}_{g}=-\frac{\partial H}{\partial \Theta_{g}}=O\left(\varepsilon^{2}\right), \quad \dot{\mathrm{P}}_{z}=-\frac{\partial H}{\partial Z}=O(\varepsilon) \tag{8.63}
\end{equation*}
$$

and

$$
\begin{equation*}
H^{(0)}=I_{g} \Omega_{0}+\frac{1}{2} I_{g} \Omega_{0} \frac{Z^{2}}{L^{2}}+\frac{1}{2} \mathrm{P}_{z}^{2}, \tag{8.64}
\end{equation*}
$$

where the axial motion in the quadratic well satisfies

$$
\begin{equation*}
Z=\sqrt{\frac{2 J_{b}}{\omega_{b}}} \sin \phi_{b}, \quad \mathrm{P}_{z}=\sqrt{2 J_{b} \omega_{b}} \cos \phi_{b}, \quad \omega_{b} \equiv \frac{\sqrt{I_{g} \Omega_{0}}}{L} \tag{8.65}
\end{equation*}
$$

We introduce yet another canonical transformation

$$
\begin{equation*}
\left(I_{g}, \Theta_{g} ; \mathrm{P}_{z}, Z\right) \rightarrow\left(\mu, \phi_{g} ; J_{b}, \phi_{b}\right), \tag{8.66}
\end{equation*}
$$

with the generating function

$$
\begin{equation*}
S\left(\Theta_{g}, Z ; \mu, J_{b}\right)=\int_{0}^{Z} \mathrm{~d} z^{\prime} \sqrt{2 J_{b} \omega_{b}(\mu)-\omega_{b}^{2}(\mu) z^{\prime 2}}+\mu \Theta_{g} \tag{8.67}
\end{equation*}
$$

The transformation from old to new variables is then

$$
\left.\begin{array}{c}
I_{g}=\frac{\partial S}{\partial \Theta_{g}}=\mu, \quad \mathrm{P}_{z}=\frac{\partial S}{\partial Z}=\sqrt{2 J_{b} \omega_{b}} \cos \phi_{b}, \quad \phi_{b}=\frac{\partial S}{\partial J_{b}} \\
\phi_{g}=\frac{\partial S}{\partial \mu}=\Theta_{g}+\frac{J_{b}}{2 \mu} \sin 2 \phi_{b}, \quad Z=\sqrt{\frac{2 J_{b}}{\omega_{b}}} \sin \phi_{b} . \tag{8.68}
\end{array}\right\}
$$

We then rewrite the Hamiltonian,

$$
\begin{equation*}
H\left(I_{g}, \Theta_{g} ; \mathrm{P}_{z}, Z\right)=\mu \Omega_{0}+J_{b} \omega_{b}(\mu)-\frac{\Omega^{\prime 2}}{4 \Omega^{2}} \mu^{2} \cos 2 \theta_{g}+\cdots \tag{8.69}
\end{equation*}
$$

We substitute for $\Omega, \Omega^{\prime}$ and $\theta_{g}$ in (8.69) and expand terms. To make some estimates, we simplify, and use a model Hamiltonian for certain quantities. We have

$$
\begin{align*}
\omega_{b}=\frac{\sqrt{\mu \Omega_{0}}}{L}, & \dot{\mu} \tag{8.70a}
\end{align*}=-\frac{\partial H}{\partial \phi_{g}}=O\left(\varepsilon^{2}\right), \quad \dot{\phi}_{g}=\frac{\partial H}{\partial \mu}=\Omega_{0}\left(1+\frac{1}{2} \frac{J_{b}}{\sqrt{\mu} L}\right)+O\left(\varepsilon^{2}\right), ~\left(\dot{J}_{b}=-\frac{\partial H}{\partial \phi_{b}}=O\left(\varepsilon^{2}\right), \quad \dot{\phi}_{b}=\frac{\partial H}{\partial J_{b}}=\omega_{b}(\mu)+O\left(\varepsilon^{2}\right) .\right.
$$

We note that $\dot{\phi}_{g}=\langle\Omega(z)\rangle_{b}$ and $\dot{\Theta}_{g}=\Omega(z)$ with $O\left(\epsilon^{2}\right)$ corrections. We can select units so that $m=1, \Omega_{0}=1$, and $E=1$. Hence, the Larmor radius $\rho=v_{\perp} / \Omega \sim 1$, $\mu \sim 1, \omega_{g} \sim 1, \omega_{b} \sim \epsilon, J_{b} \sim 1 / \epsilon$ and $\epsilon \equiv 1 / L$. Generally, the second-order terms in the Hamiltonian can be represented as

$$
\begin{equation*}
H^{(2)}\left(\mu, J_{b} ; \phi_{b}, \phi_{g}\right)=\sum_{\ell_{b}, \ell_{g}} H_{\ell_{b}, \ell_{g}}\left(\mu, J_{b}\right) \mathrm{e}^{\mathrm{i}\left(\ell_{b} \phi_{b}+\ell \phi_{g}\right)} \tag{8.71}
\end{equation*}
$$

The Hamiltonian has the following orderings through $O\left(\epsilon^{2}\right)$ :

$$
\begin{equation*}
H=\mu+J_{b} \frac{\sqrt{\mu}}{L}-\frac{\Omega^{\prime 2}}{4 \Omega^{2}} \mu^{2} \cos 2 \theta_{g}+\frac{1}{4} \mathrm{P}_{z}^{2} \mu[\cdots]+\frac{1}{8}\left(\frac{\Omega^{\prime}}{\Omega}\right)^{2} \sin ^{2} 2 \theta_{g} \tag{8.72}
\end{equation*}
$$

and after cancellations $H_{\ell_{b}, \ell_{g}} \sim(1 / 32) \varepsilon^{2}$. Consider a model Hamiltonian with a typical $O\left(\epsilon^{2}\right)$ term,

$$
\begin{align*}
H & =\mu+J_{b} \omega_{b}+\frac{1}{32} \varepsilon^{2} \sin 2 \theta_{g}=\mu+J_{b} \omega_{b}+\frac{1}{32} \varepsilon^{2} \sin 2\left(\phi_{g}-\frac{J_{b}}{2 \mu} \sin 2 \phi_{b}\right) \\
& =\mu+J_{b} \omega_{b}+\frac{1}{32} \varepsilon^{2} \operatorname{Im}\left(\mathrm{e}^{\mathrm{i} 2 \phi_{g}} \mathrm{e}^{-\mathrm{i}\left(J_{b} / \mu\right) \sin 2 \phi_{b}}\right) \\
& =\mu+J_{b} \omega_{b}+\frac{1}{32} \varepsilon^{2} \operatorname{Im}\left(\mathrm{e}^{\mathrm{i} 2 \phi_{g}} \sum_{\ell=-\infty}^{\ell=\infty} \mathrm{J}_{\ell}\left(\frac{J_{b}}{\mu}\right) \mathrm{e}^{-\ell 2 \phi_{b}}\right), \tag{8.73}
\end{align*}
$$

where $\mathrm{J}_{\ell}$ is the Bessel function with argument $J_{b} / \mu$. Thus, at $O\left(\epsilon^{2}\right)$ the Hamiltonian in (8.73) has a phase factor

$$
\begin{equation*}
\sin 2 \theta_{g}=\sum_{\ell=-\infty}^{\ell=\infty} \mathbf{J}_{\ell}\left(\frac{J_{b}}{\mu}\right) \sin 2\left(\phi_{g}-\ell \phi_{b}\right) \tag{8.74}
\end{equation*}
$$

We use the model Hamiltonian in (8.73) with (8.74) to construct the equations of motion,

$$
\left.\begin{array}{c}
\dot{\mu}=-\frac{\partial H}{\partial \phi_{g}}=-\frac{2 \varepsilon^{2}}{32} \sum_{\ell} \mathrm{J}_{\ell} \cos 2\left(\phi_{g}-\ell \phi_{b}\right) \\
\dot{\phi}_{g}=\frac{\partial H}{\partial \mu}=\omega_{g}\left(\mu, J_{b}\right)+O\left(\varepsilon^{2}\right)  \tag{8.75}\\
\dot{\phi}_{b}=\frac{\partial H}{\partial J_{b}}=\omega_{b}(\mu)+O\left(\varepsilon^{2}\right) .
\end{array}\right\}
$$

To lowest order, equation (8.75) implies

$$
\begin{equation*}
\dot{\mu}=-\frac{\varepsilon^{2}}{16} \sum_{\ell} \mathrm{J}_{\ell} \cos 2\left(\omega_{g}-\ell \omega_{b}\right) t \tag{8.76}
\end{equation*}
$$

Given (8.76) we ask under what circumstances there are oscillatory or systematic variations in $\mu$.

THEOREM. If for some integer $\ell_{0}, \omega_{g}-\ell_{0} \omega_{b}=0$ then $\Delta \mu \sim-\left(\varepsilon^{2} / 16\right) \mathbf{J}_{\ell_{0}} t$, i.e. there is a systematic secular variation in the magnetic moment. (Cohen, Rowlands \& Foote 1978). If $\ell_{0}=\omega_{g} / \omega_{b} \sim 1 / \epsilon$, e.g. $\ell_{0}=100$, then $\mathbf{J}_{\ell_{0}}\left(J_{b} / \mu\right) \sim \mathbf{J}_{1 / \epsilon}(1 / \epsilon) \sim \epsilon^{1 / 3}$. From (8.73) $H^{(2)} \rightarrow(1 / 32) \epsilon^{7 / 3}$.

Corollary. For situations close to resonance but not at precise resonance,

$$
\begin{equation*}
\Delta \mu=-\frac{\varepsilon^{2}}{16} \sum_{\ell} \mathrm{J}_{\ell} \frac{\sin \left[2\left(\omega_{g}-\ell \omega_{b}\right) t\right]}{2\left(\omega_{g}-\ell \omega_{b}\right)} \tag{8.77}
\end{equation*}
$$

Example. For the model Hamiltonian with many possible resonances

$$
\left.\begin{array}{c}
H\left(\mu, \phi_{g} ; J_{b}, \phi_{b}\right)=H^{(0)}\left(\mu, J_{b}\right)+H^{(2)}\left(\phi_{g}, \phi_{b}\right)  \tag{8.78}\\
H^{(0)}\left(\mu, J_{b}\right)=\mu+J_{b} \omega_{b}(\mu), \quad \omega_{b}(\mu)=\varepsilon \sqrt{\mu}, \quad \varepsilon \equiv \frac{1}{L} \\
H^{(2)}\left(\phi_{g}, \phi_{b}\right)=\frac{\varepsilon^{7 / 3}}{32} \sum_{\ell} \sin \left[2\left(\phi_{g}-\ell \phi_{b}\right)\right] \approx \frac{\varepsilon^{7 / 3}}{32} \sum_{\ell} \sin \left[2\left(\omega_{g} t-\ell \omega_{b} t\right)\right] \\
\Omega_{0}=1, \quad \omega_{g} \equiv \dot{\phi}=\frac{\partial H}{\partial \mu}=1+\frac{\varepsilon J_{b}}{2 \sqrt{\mu}} .
\end{array}\right\}
$$

We select a fixed energy $E=1$, so that $H^{(0)} \sim 1$. Then the choice of $\mu$ approximately fixes the action $J_{b}$. Hence, for $E=1$

$$
\begin{equation*}
\varepsilon J_{b} \approx \frac{1-\mu}{\sqrt{\mu}}=O(1) \tag{8.79}
\end{equation*}
$$

As a function of $\mu, \mu \in[0,1], \epsilon J_{b}=1$ for $\mu=0$; and $\epsilon J_{b}$ drops monotonically to 0 as $\mu \rightarrow 1$, while $\omega_{b}$ increases as $\sqrt{\mu}$ but is $O(\epsilon)$ compared to $\omega_{g}$ which is $O(1)$ and decreases as $\mu \rightarrow 1$. Examine the resonance condition in $H^{(2)}$,

$$
\begin{equation*}
\omega_{g}=\ell \omega_{b} \quad \Rightarrow \quad 2 \ell \varepsilon=\frac{1+\frac{1}{\mu}}{\sqrt{\mu}} \tag{8.80}
\end{equation*}
$$

For example, if $\epsilon=1 / 100$ and we choose $\langle\mu\rangle \approx 1 / 2$ then the resonance occurs for

$$
\begin{equation*}
\ell \varepsilon=\frac{3 \sqrt{2}}{2} \approx 2.12 \quad \rightarrow \quad \ell \approx 212 \tag{8.81}
\end{equation*}
$$

For a small change in the integer $l$ the resonance occurs at a slightly different value of $\mu$ obtained by calculating the differential of both sides of (8.80),

$$
\begin{equation*}
2 \varepsilon \delta l=-\frac{7}{\sqrt{\mu}} \delta \mu \longrightarrow \delta \mu=-\frac{2 \sqrt{\mu}}{7} \varepsilon \delta l=\mp \frac{2}{7} \varepsilon \longrightarrow \mp 0.00202, \quad \delta l= \pm 1 \tag{8.82}
\end{equation*}
$$

in this example. Thus, the resonances are fairly dense with respect to $\mu$. If the change in magnetic moment $\mu$ from a single near-resonant term in (8.77) is large enough to overcome the spacing to the next resonance in $\mu$ and $l$ based on (8.82), then one can expect a significant diffusive change in $\mu$. This is an example of Chirikov's resonance overlap criterion; if not satisfied, then the magnetic moment is conserved,

$$
\begin{align*}
& \frac{1}{2}\left|\mu_{\ell}-\mu_{\ell \pm 1}\right| \sim \frac{\sqrt{\mu_{\ell}}}{7} \varepsilon>|\Delta \mu(t)| \\
& \quad=\left|\frac{\varepsilon^{7 / 3}}{16} \frac{\sum_{\ell} \sin \left[2\left(\omega_{g} t-\ell \omega_{b} t\right)\right]}{2\left(\omega_{g}-\ell \omega_{b}\right)}\right| \sim \frac{\varepsilon^{7 / 3}}{32} \frac{1}{\frac{1}{2} \omega_{b}} \sim \frac{\varepsilon^{7 / 3}}{32} \frac{1}{\frac{1}{2} \varepsilon \sqrt{\mu}} . \tag{8.83}
\end{align*}
$$

Hence, for this example, the magnetic moment is conserved for

$$
\begin{equation*}
1>\frac{7}{16} \frac{\varepsilon^{1 / 3}}{\mu} \rightarrow \frac{7}{8} \varepsilon^{1 / 3} \tag{8.84}
\end{equation*}
$$

We note that the pre-factor of $1 / 2$ out front of the left-hand side of (8.83) is not precise. If the factor were $1 / 3$ instead, then the factor $7 / 8$ on the right-hand side of (8.85) would become $21 / 16$. If $\epsilon$ is small then the condition in (8.84) is readily satisfied.

Example. For the model Hamiltonian in (8.78) with a single resonance the change in magnetic moment and action can be calculated from

$$
\begin{equation*}
\dot{\mu}=-\frac{\varepsilon^{7 / 3}}{16} \cos 2 \psi, \quad \dot{J}_{b}=\frac{\ell \varepsilon^{7 / 3}}{16} \cos 2 \psi, \quad \psi \equiv \phi_{g}-\ell \phi_{b} \tag{8.85}
\end{equation*}
$$

We note that for a single resonance there is an invariant $I=l \mu+J_{b}$ with zero time derivative based on (8.85). Hence, the $\phi_{b}$ and $\phi_{g}$ degrees of freedom are reduced to the single degree of freedom $\psi$ by using the invariant $I$. We introduce another canonical transformation for the variables and the Hamiltonian,

$$
\begin{equation*}
S\left(\phi_{g}, \phi_{b} ; \mu^{\prime}, I\right)=\left(\mu_{\ell}+\mu^{\prime}\right) \phi_{g}-\ell \mu^{\prime} \phi_{b}, \tag{8.86}
\end{equation*}
$$

from which

$$
\left.\begin{array}{c}
\omega_{g}\left(\mu_{\ell}\right)=\ell \omega_{b}\left(\mu_{\ell}\right), \quad \mu^{\prime} \equiv \mu-\mu_{\ell}, \quad \mu=\frac{\partial S}{\partial \phi_{g}}=\mu_{\ell}+\mu^{\prime},  \tag{8.87}\\
\psi=\frac{\partial S}{\partial \mu^{\prime}}=\phi_{g}-\ell \phi_{b}, \quad \mu_{\ell}=\text { const. }
\end{array}\right\}
$$

Now add $I \phi_{b}$ to $S$ in (8.86) so that

$$
\begin{equation*}
J_{b}=\frac{\partial S}{\partial \phi_{b}}=I-\ell \mu^{\prime} \quad \text { and } \quad \chi \equiv \frac{\partial S}{\partial I}=\phi_{b} . \tag{8.88}
\end{equation*}
$$

Then

$$
\begin{equation*}
H^{(0)}=\mu_{\ell}+\mu^{\prime}+\left(I-\ell \mu^{\prime}\right) \varepsilon \sqrt{\mu_{\ell}+\mu^{\prime}} \approx \text { const. }-\frac{7}{4} \mu^{\prime 2} \tag{8.89}
\end{equation*}
$$

and

$$
\begin{equation*}
H^{(2)}=\frac{\varepsilon^{7 / 3}}{32} \sin 2 \psi \tag{8.90}
\end{equation*}
$$

for $\mu_{\ell}=1 / 2$ and $\ell \epsilon=3 \sqrt{2} / 2$ from (8.78), (8.79), (8.80) and (8.81). With this Hamiltonian the variables $\psi$ and $\mu^{\prime}$ are conjugate and satisfy

$$
\begin{equation*}
\dot{\mu}^{\prime}=-\frac{\varepsilon^{7 / 3}}{16} \cos 2 \psi, \quad \dot{\psi}=-\frac{7}{2} \mu^{\prime} \rightarrow \ddot{\psi}=\frac{7}{32} \varepsilon^{7 / 3} \cos 2 \psi . \tag{8.91}
\end{equation*}
$$

Recall the physics in the definition of the phase variable $\psi$. We are following the motion in phase space over many gyrations. The equation for the second time derivative of $\psi$ is identical to the equation of motion for a quasi-particle in a well defined by

$$
\begin{equation*}
U(\psi)=-\frac{7}{64} \varepsilon^{7 / 3} \sin 2 \psi \tag{8.92}
\end{equation*}
$$

Quasi-particles can be trapped in the periodic wells of $U(\psi)$, or with more 'energy' the quasi-particles are untrapped and pass over the wells. If passing, then the excursions in $\psi$ grow in time without bound. The trapped quasi-particles have limited, periodic excursions in $\psi$. Given the definition of $\psi$ in (8.87) then

$$
\begin{equation*}
\Delta \psi=\Delta \phi_{g}-\ell \Delta \phi_{b} \tag{8.93}
\end{equation*}
$$

For changes in the bounce phase corresponding to an integer number of bounces and for $l$ an integer, then $\Delta \psi=\Delta \phi_{g}$ modulo $2 \pi$. Hence, in the median plane of the mirror $\Delta \psi=\Delta \phi_{g}=\Delta \theta_{g}$.

We note that in the phase space $\left(\mu^{\prime}, \psi\right)$ the periodic excursion of the quasi-particle in $\mu^{\prime}$ in (8.91) is $\Delta \mu=\epsilon^{7 / 6} / 4$. The separation between resonances in $\mu_{\ell}$ and $\mu_{\ell \pm 1}$ for $\mu_{\ell} \approx 1 / 2$ from (8.83) is $\left|\mu_{\ell}-\mu_{\ell \pm 1}\right|=2 \sqrt{\mu_{\ell}} / 7 \sim \epsilon / 5$. Then $\mu$ will be conserved if the excursion in $\mu$ is less than the separation between resonances,

$$
\begin{equation*}
\Delta \mu<\left|\mu_{\ell}-\mu_{\ell \pm 1}\right| \rightarrow \epsilon^{7 / 6} / 4<\epsilon / 5 \rightarrow \epsilon^{1 / 6}<4 / 5 \tag{8.94}
\end{equation*}
$$

A more careful calculation yields 0.77 instead of $4 / 5$, from which one concludes that if $\epsilon<0.77^{6}=0.21 \sim 1 / 5$ the magnetic moment is conserved. If all possible rational resonances are included, the resonances are more densely packed; and $\epsilon$ must be smaller to conserve the magnetic moment. For example, if the spacing of resonances in (8.94) were a factor of two smaller, then $\epsilon^{1 / 6}<0.4$ and $\epsilon<0.004$ to conserve magnetic moment.

Consider a slightly different model to explain the adiabatic invariant $\mu$. We postulate a Hamiltonian evaluated in median plane of the mirror

$$
\begin{align*}
H\left(\mu, \phi_{g} ; J, \phi_{b}\right) & =J \omega_{b}+\frac{1}{2} \mu^{2}+\lambda \sum_{\ell=-\infty}^{\ell=\infty} \cos \left(\phi_{g}-\ell \phi_{b}\right) \\
& =J \omega_{b}+\frac{1}{2} \mu^{2}+\lambda 2 \pi \cos \phi_{g} \sum_{n=-\infty}^{n=\infty} \delta\left(\phi_{b}-2 \pi n\right) \tag{8.95}
\end{align*}
$$

$$
\dot{\phi}_{b}=\frac{\partial H}{\partial J}=\omega_{b}, \quad \dot{\mu}=-\frac{\partial H}{\partial \phi_{g}}=\lambda 2 \pi \sin \phi_{g} \sum_{n=-\infty}^{n=\infty} \delta\left(\phi_{b}-2 \pi n\right), \quad \dot{\phi}_{g}=\frac{\partial H}{\partial \mu}=\mu
$$

where $\lambda=\epsilon^{7 / 4} / 32$ for example. We integrate the equations of motion from bounce to bounce through the median plane, $\Delta \phi_{g}=\mu 2 \pi / \omega_{b}$,

$$
\begin{align*}
\mu_{n+1}= & \mu_{n}+\frac{2 \pi \lambda}{\omega_{b}} \sin \phi_{g}(n) \\
\rightarrow & \mu_{n+1}^{\prime}=\mu_{n}^{\prime}+\Lambda \sin \phi_{g}(n) \\
& \phi_{g, n+1}=\phi_{g, n}+\mu_{n+1}^{\prime} \\
& \mu^{\prime}=\mu \frac{2 \pi}{\omega_{b}}, \quad \Lambda \equiv\left(\frac{2 \pi}{\omega_{b}}\right)^{2} \lambda . \tag{8.96}
\end{align*}
$$

The equations in (8.96) are mapping equations for any point in the ( $\phi_{g}, \mu^{\prime}$ ) plane into another point on the next crossing of the median plane of the mirror. This is an areapreserving standard mapping known as the Chirikov-Taylor or Chirikov standard map. The map is periodic in both $\phi_{g}$ and $\mu^{\prime}$ with periodicity equal to $2 \pi$. For small values of $\Lambda$ the mapping populates the phase space with a periodic, regular pattern that is not chaotic. When $\Lambda$ approaches unity the phase space acquires regions in which the mapping is chaotic, which ergodic regions become relatively larger with increasing $\Lambda$. From the dependency of the ergodicity on the value of $\Lambda$, we can deduce the corresponding value of $\epsilon$.

EXERCISE. A fixed point for the mapping in (8.96) is a point that maps onto itself. (i) Find two fixed points for (8.96). (ii) Linearize the mapping about a fixed point and compute the ratio of increments to $\phi_{g}$ and $\mu^{\prime}$ on successive steps to show stability for $\Lambda<4$.

### 8.1.4. Perturbation of motion in a magnetic mirror due to an electrostatic wave Rosenbluth's concept of superadiabaticity and resonance overlap leading to stochasticity

In a seminal paper, Marshall Rosenbluth analysed adiabatic invariance of the magnetic moment for particle orbits in a magnetic mirror configuration in the presence of an electrostatic wave (Rosenbluth 1972). Rosenbluth introduced the concept of superadiabtaticity to describe the circumstance in which the amplitude of the perturbing electrostatic wave modifies the magnetic moment but does not lead to random changes and particle loss. For larger wave amplitudes chaotic motion can ensue, and the magnetic moment is no longer conserved. Here only an outline of Rosenbluth's calculation is given, and details are left as an exercise.

Consider the Hamiltonian of a charged particle in a magnetic mirror field as in $\S 8.1 .3$ but ignore $O\left(\epsilon^{2}\right)$ effects. Include an oscillating electric field perturbation with frequency near the cyclotron frequency. Is there a new invariant? The outline of the calculation is as follows:
(1) Add to the Hamiltonian $e \phi(z, t)=e \phi_{0} \sin \left(k_{\perp} x-\omega_{0} t\right), \omega_{0}=\Omega\left( \pm z_{0}\right)$;
(2) transform to gyro-variables $\mu, \theta_{g}$;
(3) expand $e \phi(z, t)$ in Bessel functions using the Bessel function identity;
(4) extract the resonant term from the series, $\sin \left(\theta_{g}-\omega_{0} t\right) \sim \sin \left(\Omega(z) t-\omega_{0} t\right)$;
(5) define a canonical transformation $S$ similar to that in (8.86)-(8.90) to introduce $\psi=\theta_{g}-\omega_{0} t$ and find the new Hamiltonian such that;

$$
\begin{equation*}
K=H+\frac{\partial S}{\partial t}, \quad \frac{\partial H}{\partial t} \neq 0, \quad \frac{\partial K}{\partial t}=0 . \tag{8.97}
\end{equation*}
$$

(6) In analogy to (8.95)-(8.96), find the mapping of $\mu, \psi$ from one bounce through the median plane of the mirror to the next and obtain the new $\Lambda$. Investigate the stability of the mapping. Stability corresponds to superadiabaticity, while instability is associated with ergodic orbits and diffusion of the magnetic moment.
[Editor's note: diffusion of the magnetic moment in the presence of cyclotron resonant electrostatic turbulence has received considerable attention (Baldwin, Berk \& Pearlstein 1976; Berk \& Stewart 1977; Smith \& Cohen 1983). The study in Smith \& Cohen (1983) employed a Hamiltonian approach much like that in Kaufman's lectures and research.]

### 8.2. Lagrangian theory of guiding-centre drifts

In this section is presented a Lagrangian theory of guiding-centre drifts. Bob Dewar's methodology making use of Whitham averaging is used (Whitham 1974). Equations of motion and approximate constants of the motion are derived.

### 8.2.1. Dewar's Lagrangian theory relying on Whitham averaging

Dewar systematically derived the guiding-centre Lagrangian (Taylor 1964) from the particle Lagrangian. The particle Lagrangian is

$$
\begin{equation*}
L(\boldsymbol{x}, \dot{\boldsymbol{x}} ; t)=\frac{1}{2}|\dot{\boldsymbol{x}}|^{2}-\frac{e \phi(\boldsymbol{x}, t)}{m}+\frac{e}{m c} \dot{\boldsymbol{x}} \times \boldsymbol{A}(\boldsymbol{x}, t) \tag{8.98}
\end{equation*}
$$

$\boldsymbol{x}(t)$ is the particle location; $\boldsymbol{R}(t)$ is the guiding-centre location; and $\boldsymbol{r}=\boldsymbol{R}-\boldsymbol{x}$. The displacement $\boldsymbol{r}$ is related to the Larmor radius according to

$$
\begin{equation*}
\boldsymbol{r}(t)=\rho(t)\left[\hat{\boldsymbol{e}}_{2} \cos \theta(t)+\hat{\boldsymbol{e}}_{1} \sin \theta(t)\right]+O\left(\varepsilon^{2}\right) \tag{8.99}
\end{equation*}
$$

The time derivative of (8.99) is

$$
\begin{equation*}
\dot{\boldsymbol{r}}=\rho \dot{\theta}\left[-\hat{\boldsymbol{e}}_{2} \sin \theta+\hat{\boldsymbol{e}}_{1} \cos \theta\right]+\varepsilon \frac{\partial \rho}{\partial(\varepsilon t)}\left[\hat{\boldsymbol{e}}_{2} \cos \theta+\hat{\boldsymbol{e}}_{1} \sin \theta\right]+O\left(\frac{\mathrm{~d}}{\mathrm{~d} t} \hat{\boldsymbol{e}}_{1}, \frac{\mathrm{~d}}{\mathrm{~d} t} \hat{\boldsymbol{e}}_{2}\right) . \tag{8.100}
\end{equation*}
$$

The unit vectors $\hat{\boldsymbol{e}}_{1}$ and $\hat{\boldsymbol{e}}_{2}$ change if the direction of the magnetic field changes, but this leads to unnecessary complications in the analysis and adds no new physics. The analysis makes use of

$$
\begin{equation*}
\phi(\boldsymbol{x})=\phi(\boldsymbol{R}+\boldsymbol{r})=\mathrm{e}^{r \cdot \nabla} \phi(\boldsymbol{R}), \quad \boldsymbol{r} \cdot \boldsymbol{\nabla}=\rho\left[\cos \theta \hat{\boldsymbol{e}}_{2} \cdot \nabla+\sin \theta \hat{\boldsymbol{e}}_{1} \cdot \nabla\right] . \tag{8.101}
\end{equation*}
$$

If $\phi$ varies spatially as $\exp (\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{x})$ then

$$
\begin{equation*}
r \cdot \nabla=\rho \cos (\theta-\psi) \sqrt{\partial_{1}^{2}+\partial_{2}^{2}}=\mathrm{i} k_{\perp} \rho \cos (\theta-\psi), \quad \tan \psi=\frac{\partial_{1}}{\partial_{2}} \rightarrow \frac{k_{1}}{k_{2}} \tag{8.102}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathrm{e}^{r \cdot \nabla}=\mathrm{e}^{\mathrm{i} k_{\perp} \rho \cos (\theta-\psi)}=\sum_{\ell=-\infty}^{\ell=\infty} \mathrm{J}_{\ell}\left(k_{\perp} \rho\right) \mathrm{e}^{\mathrm{i} \ell(\theta-\psi+\pi / 2)} \tag{8.103}
\end{equation*}
$$

Then the gyro-average of $\phi(x)$ is

$$
\begin{equation*}
\langle\phi(\boldsymbol{x})\rangle_{\theta}=\left\langle\mathrm{e}^{\boldsymbol{r} \cdot \nabla}\right\rangle_{\theta} \phi(\boldsymbol{R}) \tag{8.104}
\end{equation*}
$$

and only the $l=0$ term in (8.103) survives when used in (8.104).
We can return to the Lagrangian in (8.98) and calculate the gyro-average,

$$
\begin{equation*}
\left.\langle L\rangle=\left.\frac{1}{2}\langle | \dot{\boldsymbol{x}}\right|^{2}\right\rangle-\frac{e\langle\phi(\boldsymbol{x}, t)\rangle}{m}+\frac{e}{m c}\langle\dot{\boldsymbol{x}} \times \boldsymbol{A}(\boldsymbol{x}, t)\rangle . \tag{8.105}
\end{equation*}
$$

Given $\dot{\boldsymbol{x}}=\dot{\boldsymbol{R}}+\dot{\boldsymbol{r}}$ then

$$
\begin{align*}
\left.\left.\langle | \dot{\boldsymbol{x}}\right|^{2}\right\rangle & \left.=|\dot{\boldsymbol{R}}|^{2}+\left.\langle | \dot{\boldsymbol{r}}\right|^{2}\right\rangle+2\langle\dot{\boldsymbol{r}} \cdot \dot{\boldsymbol{R}}\rangle=|\dot{\boldsymbol{R}}|^{2}+\left\langle\rho^{2} \dot{\theta}^{2}\right\rangle+2\langle\dot{\boldsymbol{r}}\rangle \cdot \dot{\boldsymbol{R}} \\
& =|\dot{\boldsymbol{R}}|^{2}+\left\langle\rho^{2} \dot{\theta}^{2}\right\rangle+O\left(\varepsilon^{2}\right) \tag{8.106}
\end{align*}
$$

The surviving Bessel function can be expanded as $\mathrm{J}_{0}\left(k_{\perp} \rho\right) \approx 1-\frac{1}{4}\left(k_{\perp} \rho\right)^{2}$. The last term on the right-hand side of (8.105) is evaluated with the help of

$$
\begin{align*}
\dot{\boldsymbol{x}} \cdot \boldsymbol{A}(\boldsymbol{x})= & (\dot{\boldsymbol{R}}+\dot{\boldsymbol{r}}) \cdot \boldsymbol{A}(\boldsymbol{R}+\boldsymbol{r})=(\dot{\boldsymbol{R}}+\dot{\boldsymbol{r}}) \cdot\left[\boldsymbol{A}(\boldsymbol{R})+\boldsymbol{r} \cdot \nabla \boldsymbol{A}(\boldsymbol{R})+\frac{1}{2}(\boldsymbol{r} \cdot \nabla)^{2} \boldsymbol{A}(\boldsymbol{R})+\cdots\right] \\
& \langle\dot{\boldsymbol{x}} \cdot \boldsymbol{A}(\boldsymbol{x})\rangle=\dot{\boldsymbol{R}} \cdot \boldsymbol{A}(\boldsymbol{R})+\langle\dot{\boldsymbol{r}}\rangle: \nabla \boldsymbol{A}(\boldsymbol{R})+\frac{1}{2}\left\langle(\boldsymbol{r} \cdot \nabla)^{2}\right\rangle \boldsymbol{A}(\boldsymbol{R}) \cdot \dot{\boldsymbol{R}} . \tag{8.107}
\end{align*}
$$

Consider $\boldsymbol{r r}: \nabla \boldsymbol{A}=\boldsymbol{r r}:(\boldsymbol{\nabla} \boldsymbol{A})^{S}$ where $(\nabla \boldsymbol{A})^{s}$ is the symmetric part of $\nabla \boldsymbol{A}$, because the asymmetric part of $\nabla \boldsymbol{A}$ does not contribute when taking the double dot product. The time derivative of $\boldsymbol{r r}: \nabla \boldsymbol{A}$ is

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t}(\boldsymbol{r r}: \boldsymbol{\nabla} \boldsymbol{A})=2 \dot{\boldsymbol{r}} \boldsymbol{r}:(\boldsymbol{\nabla} \boldsymbol{A})^{s}+\boldsymbol{r r}:\left(\boldsymbol{\nabla}\left[\frac{\partial \boldsymbol{A}}{\partial t}+\dot{\boldsymbol{R}} \cdot \boldsymbol{\nabla} \boldsymbol{A}\right]\right)^{s}, \quad \frac{\partial \boldsymbol{A}}{\partial t}=-c \boldsymbol{E}^{\mathrm{T}} \tag{8.108}
\end{equation*}
$$

and hence,

$$
\begin{equation*}
2 \dot{\boldsymbol{r}} r:(\nabla \boldsymbol{A})^{s}=\frac{\mathrm{d}}{\mathrm{~d} t}(\boldsymbol{r r}: \nabla \boldsymbol{A})-\boldsymbol{r r}:\left(\nabla\left[-c \boldsymbol{E}^{\mathrm{T}}+\dot{\boldsymbol{R}} \cdot \nabla \boldsymbol{A}\right]\right)^{s} \tag{8.109}
\end{equation*}
$$

Upon calculating the time average over the cyclotron period and using periodic boundary conditions on the gyro-phase, the first term on the right-hand side of (8.109) will not contribute to the averaged Lagrangian. We also need the contribution from $\dot{\boldsymbol{r}} \boldsymbol{r}:(\boldsymbol{\nabla} \boldsymbol{A})^{a}$ in (8.107),

$$
\begin{equation*}
\dot{\boldsymbol{r}} \boldsymbol{r}:(\boldsymbol{\nabla} \boldsymbol{A})^{a}=\frac{1}{2}(\boldsymbol{r} \times \dot{\boldsymbol{r}}) \cdot \boldsymbol{B} \rightarrow\langle\dot{\boldsymbol{r}} \boldsymbol{r}\rangle:(\nabla \boldsymbol{A})^{a}=\frac{1}{2} \rho^{2} \dot{\theta} B \tag{8.110}
\end{equation*}
$$

The remaining terms in (8.107) and (8.108) are $\boldsymbol{r r}: \nabla\left[\nabla(\boldsymbol{A} \cdot \dot{\boldsymbol{R}})+c \boldsymbol{E}^{\mathrm{T}}-\dot{\boldsymbol{R}} \cdot \boldsymbol{\nabla} \boldsymbol{A}\right]$, which after a little more algebra leads to

$$
\begin{align*}
\langle L\rangle(\rho ; \dot{\theta} ; R, \dot{R} ; t)= & \frac{1}{2}|\dot{\boldsymbol{R}}|^{2}+\frac{1}{2} \rho^{2} \dot{\theta}^{2}-\frac{e \phi(\boldsymbol{R}, \varepsilon t)}{m}+\frac{e}{m c} \dot{\boldsymbol{R}} \cdot \boldsymbol{A}(\boldsymbol{R}, \varepsilon t)-\frac{e}{2 m c} \rho^{2} \dot{\theta} B \\
& +\frac{e}{4 m} \rho^{2} \stackrel{\boldsymbol{I}}{ }_{\perp}: \nabla\left(\boldsymbol{E}^{\mathrm{T}}+\boldsymbol{E}^{\mathrm{L}}+\frac{1}{c} \dot{\boldsymbol{R}} \times \boldsymbol{B}\right) . \tag{8.111}
\end{align*}
$$

The ' $T$ ' and ' $L$ ' in (8.111) are transverse (divergence-free) and longitudinal (curl-free) vector field components. Here $\stackrel{\leftrightarrow}{\boldsymbol{I}}^{\perp} \equiv \stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{b}} \hat{\boldsymbol{b}}$; hence, $\stackrel{\stackrel{\rightharpoonup}{\boldsymbol{I}}}{ } \cdot \nabla=\nabla_{\perp}$. The last term on the right-hand side of (8.111) is $O\left(\epsilon^{2}\right)$. Large-amplitude fields are allowed, but they must be slowly varying.

DEFINITION. We introduce two momentum-like variables,

$$
\begin{gather*}
p_{\rho} \equiv \frac{\partial\langle L\rangle}{\partial \dot{\rho}}=0+O\left(\varepsilon^{2}\right)  \tag{8.112a}\\
p_{\theta} \equiv \frac{\partial\langle L\rangle}{\partial \dot{\theta}}=\rho^{2} \dot{\theta}-\frac{e}{2 m c} \rho^{2} B=\rho^{2}\left(\dot{\theta}-\frac{1}{2} \Omega\right) . \tag{8.112b}
\end{gather*}
$$

From the definition in $(8.112 a)$ we have $p_{\rho}=0$ and, hence, from the Lagrangian equation,

$$
\begin{equation*}
0=\dot{p}_{\rho}=\frac{\partial\langle L\rangle}{\partial \rho}=\rho \dot{\theta}^{2}-\frac{e}{m c} \rho \dot{\theta} B(\boldsymbol{R} ; t) \tag{8.113}
\end{equation*}
$$

which we divide by $\rho \dot{\theta}$ to obtain

$$
\begin{equation*}
\dot{\theta}=\frac{e B(\boldsymbol{R} ; t)}{m c} \equiv \Omega+O\left(\varepsilon^{2}\right) \tag{8.114}
\end{equation*}
$$

With the use of (8.114) in (8.112b) one obtains

$$
\begin{equation*}
p_{\theta} \equiv \frac{\partial\langle L\rangle}{\partial \dot{\theta}}=\rho^{2}\left(\dot{\theta}-\frac{1}{2} \Omega\right)=\frac{1}{2} \Omega \rho^{2} \propto \mu \sim \frac{1}{2} \frac{m v_{\perp}^{2}}{B}, \quad \dot{p}_{\theta}=\frac{\partial}{\partial \theta}\langle L\rangle=0 \tag{8.115}
\end{equation*}
$$

which is a constant of the motion through $O(\epsilon)$.
8.2.2. Orderings, forces, mirroring, drifts, definition of flux tubes

We now introduce a set of orderings as chosen by Dewar.

## Postulate. Orderings

$$
\begin{align*}
& O\left(\varepsilon^{-1}\right): \quad e, c \\
& O(1): \quad m, v, \phi, E_{\perp}, L  \tag{8.116}\\
& O(\varepsilon): \quad \rho, E_{\|} .
\end{align*}
$$

With these orderings $\langle L\rangle$ is

$$
\begin{align*}
\langle L\rangle(\rho ; \dot{\theta} ; R, \dot{R} ; t)= & \frac{1}{2}|\dot{\boldsymbol{R}}|^{2}+\frac{1}{2} \rho^{2} \dot{\theta}^{2}-\frac{e \phi(\boldsymbol{R}, t)}{m}+\frac{e}{m c} \dot{\boldsymbol{R}} \cdot \boldsymbol{A}(\boldsymbol{R}, t)-\frac{e}{2 m c} \rho^{2} \dot{\theta} B+O\left(\varepsilon^{2}\right) \\
& O(1) \quad O(1) \quad O\left(\varepsilon^{-1}\right) \quad O\left(\varepsilon^{-1}\right) \tag{8.117}
\end{align*}
$$

We note that $\langle L\rangle$ has no $O(\epsilon)$ term. We also note that the term $\rho^{2} \dot{\theta}^{2} / 2$ involves the product of $1 / B^{2}$ and $B^{2}$, which cancel and leaves only constants, i.e. this term in the averaged Lagrangian is independent of $R$ and $t$; and we can set it aside. From the Lagrangian equations, (8.113)-(8.115), we deduce the constancy of the gyro-frequency $\Omega$ and the magnetic moment $\mu$ through $O(\epsilon)$.

Definition. Based on the orderings and (8.117), we define the guiding-centre Lagrangian

$$
\begin{align*}
L_{\mathrm{gc}} & =L\left(\varepsilon^{-1}\right)+L(1)=-\frac{e \phi(\boldsymbol{R}, t)}{m}+\frac{e}{m c} \dot{\boldsymbol{R}} \cdot \boldsymbol{A}(\boldsymbol{R}, t)+\frac{1}{2}|\dot{\boldsymbol{R}}|^{2}-\frac{e}{2 m c} \rho^{2} \dot{\theta} B \\
& =-\frac{e \phi(\boldsymbol{R}, t)}{m}+\frac{e}{m c} \dot{\boldsymbol{R}} \cdot \boldsymbol{A}(\boldsymbol{R}, t)+\frac{1}{2}|\dot{\boldsymbol{R}}|^{2}+\mu B \tag{8.118}
\end{align*}
$$

We recognize the $\mu B$ term as a potential energy $-\boldsymbol{\mu} \cdot \boldsymbol{B}$, where $\boldsymbol{\mu}=-\mu \hat{\boldsymbol{b}}$ the magnetic dipole moment of a gyrating particle in a magnetic field.

From the Lagrangian equations applied to the guiding-centre Lagrangian in (8.118) one can derive the properties of the guiding-centre motion at $O\left(\epsilon^{-1}\right)$ and $O(1)$.

## DEFINITION.

$$
\begin{equation*}
\boldsymbol{P}^{\left(\varepsilon^{-1}\right)}=\frac{\partial L^{\left(\varepsilon^{-1}\right)}}{\partial \dot{\boldsymbol{R}}}=\frac{e}{m c} \boldsymbol{A}(\boldsymbol{R}, t), \quad \dot{\boldsymbol{P}}^{\left(\varepsilon^{-1}\right)}=\frac{e}{m c}\left(\frac{\partial}{\partial t} \boldsymbol{A}+\dot{\boldsymbol{R}} \cdot \nabla \boldsymbol{A}\right) . \tag{8.119}
\end{equation*}
$$

Theorem. From the Lagrangian equation at $O\left(\epsilon^{-1}\right)$

$$
\begin{equation*}
\dot{\boldsymbol{P}}^{(-1)}=\frac{\partial L^{(-1)}}{\partial \boldsymbol{R}}=\frac{e}{m} \boldsymbol{E}^{L}+\frac{e}{m c} \nabla \boldsymbol{A} \cdot \dot{\boldsymbol{R}} . \tag{8.120}
\end{equation*}
$$

Equating expressions for $\dot{\boldsymbol{P}}^{(-1)}$ in (8.119) and (8.120) leads to

$$
\begin{align*}
0 & =\frac{e}{m} \boldsymbol{E}^{l}+\frac{e}{m c} \nabla \boldsymbol{A} \cdot \dot{\boldsymbol{R}}-\frac{e}{m c}\left(\frac{\partial}{\partial t} \boldsymbol{A}+\dot{\boldsymbol{R}} \cdot \nabla \boldsymbol{A}\right) \\
& =\frac{e}{m} \boldsymbol{E}+\frac{e}{m c}(\nabla \boldsymbol{A} \cdot \dot{\boldsymbol{R}}-\dot{\boldsymbol{R}} \cdot \nabla \boldsymbol{A}) \\
& =\frac{e}{m} \boldsymbol{E}+\frac{e}{m c} \dot{\boldsymbol{R}} \times(\nabla \times \boldsymbol{A}) \\
& \Rightarrow \quad 0=\boldsymbol{E}+\frac{1}{c} \dot{\boldsymbol{R}} \times \boldsymbol{B}+O(\epsilon) \\
& \Rightarrow \quad \boldsymbol{E}_{\perp}+\frac{1}{c} \boldsymbol{V}_{\perp} \times \boldsymbol{B}=O(\epsilon), \quad \boldsymbol{E}_{\|}=O(\epsilon) \tag{8.121}
\end{align*}
$$

The results for the perpendicular and weaker parallel vector components of the electric field in (8.121) are consistent with the orderings in (8.116). Particles move more freely along the magnetic field lines and can neutralize strong parallel electric fields. Solving (8.121) for the perpendicular velocity

$$
\begin{equation*}
\boldsymbol{V}_{\perp}=c \frac{\boldsymbol{E}(\boldsymbol{R}, t) \times \hat{\boldsymbol{b}}}{B}+O(\varepsilon) \tag{8.122}
\end{equation*}
$$

The leading term in (8.122) is $O(1)$, which is the $\boldsymbol{E} \times \boldsymbol{B}$ drift velocity $\boldsymbol{u}_{\mathrm{E}}$.
To next order,

$$
\begin{equation*}
\boldsymbol{P}=\frac{\partial L}{\partial \dot{\boldsymbol{R}}}=\frac{e}{m c} \boldsymbol{A}(\boldsymbol{R}, t)+\dot{\boldsymbol{R}} . \tag{8.123}
\end{equation*}
$$

We take the time derivative of (8.123) and equate it to $\dot{\boldsymbol{P}}=\partial L_{\mathrm{gc}} / \partial \boldsymbol{R}$ through $O$ (1) to obtain

$$
\begin{gather*}
\frac{1}{c}\left(\frac{\partial}{\partial t} \boldsymbol{A}+\dot{\boldsymbol{R}} \cdot \boldsymbol{\nabla} \boldsymbol{A}\right)+\frac{m}{e} \ddot{\boldsymbol{R}}=\boldsymbol{E}^{L}+\frac{1}{c}(\boldsymbol{\nabla} \boldsymbol{A}) \cdot \dot{\boldsymbol{R}}-\frac{m}{e} \mu \nabla B B \\
\Rightarrow \quad 0=\frac{e}{m}\left(\boldsymbol{E}+\frac{1}{c} \dot{\boldsymbol{R}} \times \boldsymbol{B}\right)-\ddot{\boldsymbol{R}}-\mu \nabla B \tag{8.124}
\end{gather*}
$$

The last two terms on the right-hand side of (8.124) are perturbations. As a consequence of the orderings,

$$
\begin{equation*}
\dot{\boldsymbol{R}}=\dot{\boldsymbol{R}}^{(1)}+\dot{\boldsymbol{R}}^{(\varepsilon)}, \quad \dot{\boldsymbol{R}}^{(1)}=v_{\|} \hat{\boldsymbol{b}}+\boldsymbol{u}_{E}, \quad \dot{\boldsymbol{R}}^{(\varepsilon)}=\boldsymbol{v}_{d} \tag{8.125}
\end{equation*}
$$

Hence, to the lowest required order $\dot{\boldsymbol{R}}^{(1)}=v_{\|} \hat{\boldsymbol{b}}+\boldsymbol{u}_{E}$ can be used in the $\ddot{\boldsymbol{R}}$ term in (8.124).

THEOREM. The guiding-centre drifts result from (8.124) and (8.125), and (8.124) naturally decouples into components parallel and perpendicular to the applied magnetic field,

$$
\begin{gather*}
\hat{\boldsymbol{b}}: \quad m \dot{v}_{\|}=e E_{\|}-\mu \hat{\boldsymbol{b}} \cdot \nabla B-m \hat{\boldsymbol{b}} \cdot \dot{\boldsymbol{u}}_{E}  \tag{8.126a}\\
\hat{\boldsymbol{b}}_{\perp}: \quad \boldsymbol{v}_{\perp}=\boldsymbol{u}_{E}+\boldsymbol{v}_{d}, \quad \boldsymbol{v}_{d}=\frac{1}{\Omega}\left(-\frac{\mu \nabla B}{m}-v_{\|} \dot{\hat{\boldsymbol{b}}}-\dot{\boldsymbol{u}}_{E}+\cdots\right) \times \hat{\boldsymbol{b}} \tag{8.126b}
\end{gather*}
$$

The second term on the right-hand side of (8.126a) is the mirroring force. The first term on the right-hand side of $\boldsymbol{v}_{\mathrm{d}}$ is the $\nabla B$ drift; the second term is the centrifugal drift; the third term is the polarization drift; and the remaining terms could accommodate other accelerations, e.g. gravity and collisional friction. We note $\boldsymbol{u}_{E} \cdot \hat{\boldsymbol{b}}=0$. Hence

$$
\begin{equation*}
\dot{\boldsymbol{u}}_{E} \cdot \hat{\boldsymbol{b}}=-\dot{\hat{\boldsymbol{b}}} \cdot \boldsymbol{u}_{E} \quad \text { and } \quad m \dot{v}_{\|}=e E_{\|}-\mu \hat{\boldsymbol{b}} \cdot \nabla B+\dot{\hat{\boldsymbol{b}}} \cdot \boldsymbol{u}_{E} \tag{8.127}
\end{equation*}
$$

We ascribe the notion of a moving field line to the time derivative (in a Lagrangian sense) of the magnetic unit vector as seen by the particle in its guiding-centre motion.

### 8.2.3. Equations for field lines, Euler potentials and Clebsch representation

To lowest order, the particles are tied to the magnetic field lines; and their trajectories lie on surfaces that enclose the magnetic flux. We define a field-line velocity $\boldsymbol{u}_{L}(\boldsymbol{r}, t)$ such that flux moving with this velocity will be conserved. We will elaborate this notion in the following discussion. First there are some preliminaries. Consider an applied magnetic field in a region of plasma such that $\boldsymbol{\nabla} \times \boldsymbol{B}=0$. Introduce an artificial gravity $g$ such that

$$
\begin{equation*}
\boldsymbol{v}_{g}=\boldsymbol{v}_{\nabla_{\perp} B}+\boldsymbol{v}_{\text {curv }} \Rightarrow \boldsymbol{g}=\frac{v_{\|}^{2}+v_{\perp}^{2}}{R} \hat{\kappa} \tag{8.128}
\end{equation*}
$$

where $\hat{\kappa}$ is the magnetic curvature unit vector and $R$ is the radius of curvature of the magnetic field line.

EXAMPLE. Consider a plasma in pressure balance with an applied magnetic field. When the magnetic field is a minimum (maximum) in the plasma, the plasma is stable (unstable) with respect to perturbations, as shown in the important paper by Rosenbluth and Longmire on interchange instability (Rosenbluth \& Longmire 1957).

Definition. Field lines are be mapped by

$$
\begin{equation*}
\frac{\mathrm{d} x}{B_{x}}=\frac{\mathrm{d} y}{B_{y}}=\frac{\mathrm{d} z}{B_{z}}, \quad \boldsymbol{B}(\boldsymbol{x}, t)=\left(B_{x}, B_{y}, B_{z}\right) . \tag{8.129}
\end{equation*}
$$

Definition. The magnetic flux $\Phi(C)$ is defined by the integral over an area bounded by the curve $C$,

$$
\begin{equation*}
\Phi(C) \equiv \oint_{C} \boldsymbol{B} \cdot \mathrm{~d} \boldsymbol{\sigma} \tag{8.130}
\end{equation*}
$$

Introduce the differential line element $\mathrm{d} \ell$ on the bounding curve $C$. The time derivative of the surface integral in (8.130) has contributions from the time derivative of the magnetic field and from the time derivative of the contour $C$ ( $\mathrm{d} \boldsymbol{\ell} \times \boldsymbol{u}_{L}$ gives the time derivative of the differential parallelogram which can intercept magnetic fields lines and can contribute to the time derivative of the magnetic flux). We calculate the time derivative of (8.130) and constrain it to be zero,

$$
\begin{align*}
\frac{\mathrm{d}}{\mathrm{~d} t} \Phi(C) & =\oint_{C}\left[\left(\boldsymbol{u}_{L} \times \mathrm{d} \boldsymbol{\ell}\right) \cdot \boldsymbol{B}+\frac{\partial \boldsymbol{B}}{\partial t} \cdot \mathrm{~d} \boldsymbol{\sigma}\right]=\oint_{C}\left[-\mathrm{d} \boldsymbol{\ell} \cdot\left(\boldsymbol{u}_{L} \times \boldsymbol{B}\right) \cdot+\frac{\partial \boldsymbol{B}}{\partial t} \cdot \mathrm{~d} \boldsymbol{\sigma}\right] \\
& =\oint_{C} \mathrm{~d} \boldsymbol{\sigma} \cdot\left[-\boldsymbol{\nabla} \times\left(\boldsymbol{u}_{L} \times \boldsymbol{B}\right) \cdot+\frac{\partial \boldsymbol{B}}{\partial t} \cdot\right] \equiv 0 \tag{8.131}
\end{align*}
$$

using Stokes' theorem. The constraint that the time derivative of the magnetic flux vanishes imposes a condition that determines $\boldsymbol{u}_{L}$.

ThEOREM. (Field-line velocity) Setting the terms inside the area integral equal to zero in the final expression on the right-hand side of (8.131) and use of Faraday's law yield

$$
\begin{gather*}
-\nabla \times\left(\boldsymbol{u}_{L} \times \boldsymbol{B}\right)+\frac{\partial \boldsymbol{B}}{\partial t}=0=c \boldsymbol{\nabla} \times \boldsymbol{E}+\frac{\partial \boldsymbol{B}}{\partial t} \\
\rightarrow \boldsymbol{\nabla} \times\left(\boldsymbol{E}+\frac{1}{c} \boldsymbol{u}_{L} \times \boldsymbol{B}\right)=0 \quad \rightarrow \quad \boldsymbol{E}+\frac{1}{c} \boldsymbol{u}_{L} \times \boldsymbol{B}=-\nabla \chi(\boldsymbol{x}, t) . \tag{8.132}
\end{gather*}
$$

Equation (8.132) is only a condition on $\boldsymbol{u}_{L} \perp \boldsymbol{B}$. The component of $\boldsymbol{u}_{L} \| \boldsymbol{B}$ does not matter at all. So we only consider $\boldsymbol{u}_{L} \perp \boldsymbol{B}$ as a postulate. If we take the component of the last expression in (8.132) parallel to the magnetic field

$$
\begin{equation*}
E_{\|}=-\hat{\boldsymbol{b}} \cdot \nabla \chi(\boldsymbol{x}, t) \quad \rightarrow \quad \chi(\ell)=-\int_{0}^{\ell} \mathrm{d} \ell^{\prime} E_{\|}\left(\ell^{\prime}\right) \tag{8.133}
\end{equation*}
$$

integrated along the field line. This determines the order of $\chi$, viz., $\chi$ is the same order as $E_{\|} \sim O(\epsilon)$. The component of $\boldsymbol{u}_{L}$ perpendicular to the magnetic field is then

$$
\begin{gather*}
\boldsymbol{u}_{L}=c \frac{\boldsymbol{E} \times \hat{\boldsymbol{b}}}{B}+c \frac{\boldsymbol{\nabla}_{\perp} \chi \times \hat{\boldsymbol{b}}}{B}  \tag{8.134}\\
\boldsymbol{u}_{E} \sim O(1) \quad O(\varepsilon) .
\end{gather*}
$$

We recall that $\boldsymbol{v}_{\perp}=\boldsymbol{u}_{E}+\boldsymbol{v}_{d}$. Hence, $\boldsymbol{v}_{\perp}-\boldsymbol{u}_{L}=O(\varepsilon)$; and the field lines are then tied to the fluid velocity at leading order. In this sense the plasma is tied to the field lines.

The field-line velocity is a construct. There is significant ambiguity. We know how to relate the values of $\chi$ along the same field line from (8.134), but not across the field lines. We can illustrate the ambiguity of the field-line velocity in the following examples.

Example. Suppose $B$ is uniform and static, and $\boldsymbol{E}=-\nabla \phi$. Further assume that $\phi$ has no spatial derivative along the magnetic field lines so that only $\boldsymbol{E}_{\perp} \neq 0$. Two choices for $\chi$ can be made. (a) $\chi=0$ everywhere, in which case $\boldsymbol{u}_{L}=\boldsymbol{u}_{E}$. (b) $\chi=\phi$, so that both are constant along the field lines. Then from (8.134) $\boldsymbol{u}_{L}=0$. Thus, the possible ambiguity in constructing the field-line velocity is obvious.

It is useful to introduce auxiliary functions to characterize the magnetic field lines. Consider labelling functions $\alpha$ and $\beta$ such that $\mathrm{d} \Phi_{f u x}=\mathrm{d} \alpha \mathrm{d} \beta .(\alpha, \beta)$ labels a field line emerging normally from a curvilinear $(\alpha, \beta)$ surface. A third coordinate $\sigma$ along the field line is needed. These labels (Euler potentials) can be used to calculate the magnetic field.

Definition. The differential length along a field line is $\mathrm{d} \ell=h(\alpha, \beta, \sigma) \mathrm{d} \sigma$. For example, if $\sigma=\theta$ then $h=r$, where $r$ is the local radius of curvature of the field line.

A magnetic field can be represented as

$$
\begin{equation*}
\boldsymbol{B}=(\nabla \alpha \times \nabla \beta) \Lambda(\alpha, \beta, \sigma) \tag{8.135}
\end{equation*}
$$

where $\Lambda(\alpha, \beta, \sigma)$ is a scalar function. Given (8.135) then

$$
\begin{equation*}
\boldsymbol{B} \cdot \nabla \alpha=0, \quad \boldsymbol{B} \cdot \nabla \beta=0, \quad \frac{\mathrm{~d} \alpha}{B_{\alpha}}=\frac{\mathrm{d} \beta}{B_{\beta}}, \tag{8.136}
\end{equation*}
$$

so that $\alpha$ and $\beta$ can be used as field-line labels. The differential magnetic flux is

$$
\begin{equation*}
\mathrm{d} \Phi \equiv \boldsymbol{B} \cdot \mathrm{~d} \boldsymbol{a}=\mathrm{d} x \mathrm{~d} y(\hat{z} \cdot \nabla \alpha \times \nabla \beta) \Lambda=\mathrm{d} x \mathrm{~d} y \mathrm{~J}\left(\frac{\alpha, \beta}{x, y}\right) \Lambda=\mathrm{d} \alpha \mathrm{~d} \beta \Lambda \tag{8.137}
\end{equation*}
$$

where $\mathbf{J}$ is the Jacobian of $\alpha$ and $\beta$ with respect to $x$ and $y$. In this example we can take $\Lambda=1$; and then (8.135) is the Clebsch representation for the magnetic field. The Clebsch representation guarantees that the magnetic field is divergence free, but does not guarantee that the magnetic field has no curl.

EXAMPLES. Magnetic field configurations (figure 36)
(1) Straight wire carrying current $I$

$$
\begin{equation*}
\alpha(r ; I)=2 I \ln r, \quad \beta=z, \quad \sigma=\theta, \quad \rightarrow \boldsymbol{B}=\frac{2 I}{r} \hat{\theta}, \quad \Phi=2 I z \ln \frac{r_{2}}{r_{1}} . \tag{8.138}
\end{equation*}
$$

(2) Axisymmetric poloidal field - magnetic mirror

Select the $z$ dependence of $B_{z}$, e.g. for a simple mirror $B_{z}=B_{0}\left(1+z^{2} / L^{2}\right)$ in the paraxial limit. Then

$$
\begin{equation*}
\alpha=\frac{1}{2} r^{2} B_{0}\left(1+\frac{z^{2}}{L^{2}}\right), \quad \beta=\theta, \quad \sigma=z, \quad B_{r}=-r B_{0} z / L^{2}, \quad B_{\theta}=0 . \tag{8.139}
\end{equation*}
$$

Note that $\nabla \times \boldsymbol{B}=-\left(r B_{0} / L^{2}\right) \hat{\theta}$, which is non-zero, but is higher order in the paraxial limit.
(3) Dipole field

Here, $\alpha(r, z)$ enumerates the field lines; $\sigma=\theta$ is like a latitude along the field line; $\beta=\phi$ is the longitude. The Clebsch representation for the dipole magnetic field with magnetic moment $\mu$ in spherical polar coordinates is

$$
\begin{equation*}
\alpha=\frac{\sin \theta}{r^{2}} \mu, \quad \beta=\phi, \quad B_{r}=\frac{\cos \theta}{r^{3}} \mu, \quad B_{\theta}=\frac{2 \sin \theta}{r^{3}} \mu, \quad B_{\phi}=0 . \tag{8.140}
\end{equation*}
$$

(a)

(b)

(c)


Figure 36. Magnetic field configurations: (a) mirror, (b) dipole and (c) tokamak.
(4) Toroidal magnetic field

In cylindrical coordinates a model toroidal field is described by

$$
\left.\begin{array}{c}
\alpha=\frac{\mu r \sin \theta}{\left(a^{2}+2 a r \sin \theta+z^{2}\right)^{3 / 2}}, \quad \beta=z, \quad \sigma=\theta \\
\boldsymbol{B}(z \approx 0) \approx \mu \cos \theta \frac{(2 a+r \sin \theta)}{(a+2 r \sin \theta)^{5 / 2}} \hat{\boldsymbol{r}}-\mu \sin \theta \frac{(2 a+r \sin \theta)}{(a+2 r \sin \theta)^{5 / 2}}+B_{z} \hat{z}  \tag{8.141}\\
B_{z}(\mathrm{r} \approx 0) \approx \frac{2 \mu}{\left(a^{2}+z^{2}\right)^{3 / 2}} .
\end{array}\right\}
$$

(5) Tokamak magnetic field

In cylindrical coordinates $(R, \phi, z)$ a model axisymmetric tokamak field (Kaufman 1972b) can be derived from

$$
\left.\begin{array}{rl}
\boldsymbol{B}=B_{\phi}(R, z) \hat{\boldsymbol{e}}_{\phi} & +\boldsymbol{B}^{p}(R, z), \quad \boldsymbol{B}^{p}=\nabla \times A_{\phi} \hat{\boldsymbol{e}}_{\phi}, \quad A_{\phi}=-\frac{1}{R} \psi  \tag{8.142}\\
& \rightarrow B_{R}=\frac{1}{R} \frac{\partial \psi}{\partial z}, \quad B_{z}=-\frac{1}{R} \frac{\partial \psi}{\partial R} .
\end{array}\right\}
$$

The toroidal magnetic field $B_{\phi}$ is determined by external current-carrying coils. The poloidal field $B^{p}$ is determined by toroidal plasma currents and an externally imposed vertical magnetic field.

EXERCISE. Show that $A_{\phi} \hat{\boldsymbol{e}}_{\phi}=\alpha \nabla \beta$, determine $\alpha$ and $\beta$, and check against Kaufman (1972b).

We return to the analysis of field-line motion leading to (8.132)-(8.134) to demonstrate that with the Clebsch representation the field-line labels advect with the field-line velocity $u_{L}$ such that

$$
\begin{equation*}
\left.\frac{\mathrm{d} \alpha}{\mathrm{~d} t}\right|_{L}=\frac{\partial \alpha(\boldsymbol{x}, t)}{\partial t}+\boldsymbol{u}_{L} \cdot \nabla \alpha(\boldsymbol{x}, t)=0 \tag{8.143}
\end{equation*}
$$

and similarly for $\beta$. Using the identity $\boldsymbol{B}=\nabla \alpha \times \nabla \beta=\nabla \times(\alpha \nabla \beta)$, then

$$
\begin{equation*}
E=-\nabla \phi-\frac{1}{c} \frac{\partial}{\partial t}(\alpha \nabla \beta)=-\nabla \phi-\frac{1}{c}\left(\frac{\partial \alpha}{\partial t} \nabla \beta+\alpha \nabla \frac{\partial \beta}{\partial t}\right) . \tag{8.144}
\end{equation*}
$$

We then use (8.143) and the equivalent for $\beta$ to evaluate

$$
\begin{align*}
\frac{1}{c} \boldsymbol{u}_{L} \times \boldsymbol{B} & =\frac{1}{c} \boldsymbol{u}_{L} \times(\nabla \alpha \times \nabla \beta)=\frac{1}{c}\left[\nabla \alpha \boldsymbol{u}_{L} \cdot \nabla \beta-\nabla \beta \boldsymbol{u}_{L} \cdot \nabla \alpha\right] \\
& =-\frac{1}{c}\left[\nabla \alpha \frac{\partial \beta}{\partial t}-\nabla \beta \frac{\partial \alpha}{\partial t}\right] \tag{8.145}
\end{align*}
$$

Recalling (8.132)

$$
\begin{align*}
\boldsymbol{E}= & -\frac{1}{c} \boldsymbol{u}_{L} \times \boldsymbol{B}-\nabla \chi(\boldsymbol{x}, t)=\frac{1}{c}\left[\nabla \alpha \frac{\partial \beta}{\partial t}-\nabla \beta \frac{\partial \alpha}{\partial t}\right]-\nabla \chi(\boldsymbol{x}, t) \\
= & -\nabla \phi-\frac{1}{c}\left(\frac{\partial \alpha}{\partial t} \nabla \beta+\alpha \nabla \frac{\partial \beta}{\partial t}\right) \\
& \Rightarrow-\nabla \chi(\boldsymbol{x}, t)=-\nabla \phi-\frac{1}{c} \nabla\left(\alpha \frac{\partial \beta}{\partial t}\right) \Rightarrow \chi(\boldsymbol{x}, t)=\phi+\frac{1}{c} \alpha \frac{\partial \beta}{\partial t}, \tag{8.146}
\end{align*}
$$

up to an arbitrary constant. Equation (8.146) is quite general, and no ordering is involved. However, $\chi \sim O(\epsilon)$; so $\phi$ and $(\alpha / c) \partial \beta / \partial t$ nearly cancel.

Example. For an electrostatic model $\boldsymbol{\nabla} \times \boldsymbol{E}=0$ and $\boldsymbol{E}=-\boldsymbol{\nabla} \phi$, there are two possible choices for the Euler potentials,

$$
\begin{array}{ll}
\text { (1) } \chi=0, & \frac{\partial \beta}{\partial t}=-c \frac{\phi}{\alpha} \\
\text { (2) } \chi=\phi, & \frac{\partial \beta}{\partial t}=0 .
\end{array}
$$

However, for a proper ordering only (1) is consistent; and (2) is inconsistent unless $\phi$ is sufficiently weak.

### 8.2.4. Guiding-centre Lagrangian using Euler potentials and Clebsch representation recovering guiding-centre drifts

We return to the general consideration of field-line motion as in (8.143) and the guiding-centre Lagrangian,

$$
\begin{gather*}
\frac{\mathrm{d}^{\text {g.c. }} \beta}{\mathrm{d} t}=\frac{\partial \beta(\boldsymbol{x}, t)}{\partial t}+\boldsymbol{V} \cdot \nabla \beta(\boldsymbol{x}, t) \\
L_{\text {g.c. }}=-e \phi+\frac{e}{c} \boldsymbol{v} \cdot \boldsymbol{A}+\frac{1}{2} m V^{2}-\mu B(\boldsymbol{R}, t) \\
O\left(\varepsilon^{-1}\right) ? O\left(\varepsilon^{-1}\right) O\left(\varepsilon^{-1}\right) O(1) \quad O(1) \\
\rightarrow L_{\text {g.c. }}=-e\left(\chi-\frac{\alpha}{c} \frac{\partial \beta}{\partial t}\right)+\frac{e \alpha}{c}\left(\dot{\beta}-\frac{\partial \beta}{\partial t}\right)+\frac{1}{2} m V^{2}-\mu B(\boldsymbol{R}, t)  \tag{8.147}\\
=-e \chi+\frac{e \alpha}{c} \dot{\beta}+\frac{1}{2} m V^{2}-\mu B(\boldsymbol{R}, t) \\
O(1) \quad O(1) \quad O(1) \quad O(1)
\end{gather*}
$$

We recall from §8.2.3 that

$$
\begin{equation*}
E_{\|}=-\hat{\boldsymbol{b}} \cdot \nabla \chi, \quad \boldsymbol{V}=\boldsymbol{V}_{\text {g.c. }}=\boldsymbol{V}_{\perp}+V_{\|} \hat{\boldsymbol{b}}=\boldsymbol{u}_{L}+O(\varepsilon)+\hat{\boldsymbol{b}} h \dot{\sigma}, \quad V^{2}=u_{L}^{2}+h^{2} \dot{\sigma}^{2}+O(\varepsilon) \tag{8.148}
\end{equation*}
$$

From (8.147) and (8.148) we have

$$
\begin{equation*}
L_{\mathrm{g} . \mathrm{c.}}=-e \chi(\alpha, \beta, \sigma, t)+\frac{e \alpha}{c} \dot{\beta}+\frac{1}{2} m u_{L}^{2}(\alpha, \beta, \sigma, t)-\mu B(\alpha, \beta, \sigma, t) \tag{8.149}
\end{equation*}
$$

where every term is $O(1)$ and there is no mixing of velocity and coordinates. The first, third, and fourth terms on the right-hand side of (8.149) are potential energy terms (with a minus sign); and the other terms are kinetic energy terms.

There is a problem with the Lagrangian in (8.149), which is revealed when we calculate the $\alpha$ momentum from the Lagrangian equation,

$$
\begin{equation*}
p_{\alpha}=\frac{\partial L}{\partial \dot{\alpha}}=0 . \tag{8.150}
\end{equation*}
$$

This is erroneous. Consider the Hamiltonian derived from the same Lagrangian,

$$
\begin{align*}
H & =p_{\alpha} \dot{\alpha}+p_{\beta} \dot{\beta}+p_{\sigma} \dot{\sigma}-L_{\text {g.c. }}=\frac{e \alpha}{c} \dot{\beta}+m h V_{\|} \dot{\sigma}-\frac{e \alpha}{c} \dot{\beta}+e \chi \\
& =m V_{\|}^{2}-\frac{1}{2} m h^{2} \dot{\sigma}^{2}-\frac{1}{2} m u_{L}^{2}+\mu B+e \chi=\frac{p_{\sigma}^{2}}{2 m h^{2}}+\mu B+e \chi-\frac{1}{2} m u_{L}^{2} . \tag{8.151}
\end{align*}
$$

The last term on the right-hand side of (8.151) is a constraint associated with the moving field line. This $H$ is not equal to the energy associated with the guiding-centre motion.

If instead of the guiding-centre Lagrangian in (8.149), we use

$$
\begin{equation*}
L_{\text {g.c. }}=-e \chi-\mu B+\frac{e \alpha}{c} \dot{\beta}+\frac{1}{2} m V^{2} \tag{8.152}
\end{equation*}
$$

where

$$
\begin{equation*}
\boldsymbol{V}=\frac{\mathrm{d} \boldsymbol{R}}{\mathrm{~d} t}(\alpha, \beta, \sigma, t)=\left.\frac{\partial \boldsymbol{R}}{\partial t}\right|_{\alpha, \beta, \sigma}+\dot{\alpha} \frac{\partial \boldsymbol{R}}{\partial \alpha}+\dot{\beta} \frac{\partial \boldsymbol{R}}{\partial \beta}+\dot{\sigma} \frac{\partial \boldsymbol{R}}{\partial \sigma} . \tag{8.153}
\end{equation*}
$$

The first term on the right-hand side of (8.154) is $\boldsymbol{u}_{L}$ the field-line velocity and is $O(1)$; the second and third terms are $O(\varepsilon)$ drifts off the field line; and the last term is the velocity along the field line which is also $O(1)$. Now proceed to obtain the equations of motion from the Lagrangian equations,

$$
\left.\begin{array}{c}
p_{\beta} \equiv \frac{\partial L}{\partial \dot{\beta}}=\frac{e}{c} \alpha+m \boldsymbol{V} \cdot \frac{\partial \boldsymbol{R}}{\partial \beta} \\
p_{\alpha}=m \boldsymbol{V} \cdot \frac{\partial \boldsymbol{R}}{\partial \alpha}  \tag{8.154}\\
p_{\sigma}=m h^{2} \dot{\sigma} .
\end{array}\right\}
$$

We see that $p_{\alpha}$ is non-zero, and this degree of freedom cannot be removed. Furthermore,

$$
\left.\begin{array}{c}
\dot{p}_{\beta}=\frac{\mathrm{d}}{\mathrm{~d} t}\left(\frac{e}{c} \alpha+m \boldsymbol{V} \cdot \frac{\partial \boldsymbol{R}}{\partial \beta}\right)=\frac{\partial L}{\partial \beta}=-e \frac{\partial \chi}{\partial \beta}-\mu \frac{\partial B}{\partial \beta}+\frac{1}{2} m \frac{\partial V^{2}}{\partial \beta} \\
\dot{\alpha}=\frac{c}{e} \frac{\partial}{\partial \beta}\left(\frac{1}{2} m V^{2}-e \chi-\mu B\right)-\frac{m c}{e} \frac{\mathrm{~d}}{\mathrm{~d} t}\left(\boldsymbol{V} \cdot \frac{\partial \boldsymbol{R}}{\partial \beta}\right)  \tag{8.155}\\
\dot{\beta}=-\frac{c}{e} \frac{\partial}{\partial \beta}\left(\frac{1}{2} m V^{2}-e \chi-\mu B\right)+\frac{m c}{e} \frac{\mathrm{~d}}{\mathrm{~d} t}\left(\boldsymbol{V} \cdot \frac{\partial \boldsymbol{R}}{\partial \alpha}\right) .
\end{array}\right\}
$$

The second and third equations are $O(\epsilon)$ equations and include the polarization drifts. One can recognize terms that derive from the Hamiltonian equations in canonical variables using $H^{(0)} \equiv(1 / 2) m V^{2}-e \chi-\mu B$.

Exercise. Interpret all the relevant drifts that appear in (8.154) and (8.155).
At $O(1)$ the equation of motion along the field line is

$$
\begin{equation*}
m \frac{\mathrm{~d}}{\mathrm{~d} t}\left(h^{2} \dot{\sigma}\right)=\frac{\partial}{\partial \sigma}\left(\frac{1}{2} m V^{2}-e \chi-\mu B\right) . \tag{8.156}
\end{equation*}
$$

In Cartesian form it is straightforward to relate (8.156) to earlier formulae. Once again we note that the motion across the magnetic field lines is $O(\epsilon)$ and $O(1)$ along the field line. So we freeze the motion across the field lines and only study the motion along the field line for the moment. Through $O(1)$

$$
\begin{equation*}
L_{\sigma}(\sigma, \dot{\sigma} ; t ; \alpha, \beta)=-e \chi-\mu B+\frac{1}{2} m u_{L}^{2}+\frac{1}{2} m h^{2} \dot{\sigma}^{2}, \quad p_{\sigma} \equiv \frac{\partial L}{\partial \dot{\sigma}}=m h^{2} \dot{\sigma} \tag{8.157}
\end{equation*}
$$

Theorem. The Hamiltonian through $O(1)$ is then

$$
\begin{equation*}
H_{\sigma}=\dot{\sigma} p_{\sigma}-L_{\sigma}=\frac{p_{\sigma}^{2}}{2 m h^{2}}+e \chi(\sigma, t)+\mu B(\sigma, t)-\frac{1}{2} m u_{L}^{2}(\sigma, t) . \tag{8.158}
\end{equation*}
$$

We require that $H_{\sigma}$ is essentially time independent through $O(1)$, i.e. we require

$$
\begin{equation*}
\frac{\partial}{\partial t}\left(B, \chi, u_{L}, h\right) \sim O(\varepsilon), \quad \text { i.e., } \frac{2 \pi}{\omega_{B}} \ll \frac{B}{\left(\frac{\partial B}{\partial t}\right)} . \tag{8.159}
\end{equation*}
$$

Thus, we postulate that $(\mathrm{d} / \mathrm{d} t) H=(\partial / \partial t) H=O(\epsilon)$; so $H$ is a constant of the motion through $O(1)$. This energy is the sum of the parallel kinetic energy, the electrical potential energy and the perpendicular kinetic energy $(\mu B)$, less the constraint energy $-(1 / 2) m u_{L}^{2}(\sigma, t)$ associated with the moving field line.

### 8.2.5. Canonical transformations, orderings and derivation of approximate constants of

 the motion (adiabatic invariants including bounce action in a magnetic mirror)To further simplify the analysis, we assume that $u_{L} \sim O(\epsilon)$, which loses the polarization drift and is a great restriction. Under this assumption the $O(1)$ guiding-centre Lagrangian is

$$
\begin{equation*}
L_{\text {g.c. }}=-e \chi-\mu B+\frac{e}{c} \alpha \dot{\beta}+\frac{1}{2} m h^{2} \dot{\sigma}^{2} \tag{8.160}
\end{equation*}
$$

which leads to

$$
\begin{equation*}
p_{\beta}=\frac{\partial L}{\partial \dot{\beta}}=\frac{e}{c} \alpha, \quad p_{\alpha}=\frac{\partial L}{\partial \dot{\alpha}}=0, \quad H_{\text {g.c. }}\left(\alpha, \beta ; \sigma, p_{\sigma} ; t\right)=\frac{p_{\sigma}^{2}}{2 m h^{2}}+e \chi+\mu B . \tag{8.161}
\end{equation*}
$$

There are two degrees of freedom for the motion perpendicular to the field lines, $\alpha$ and $\beta$ (which are conjugate), and two degrees of freedom for the motion parallel to the field line, $\sigma$ and $p_{\sigma}$, plus a degree of freedom for the bounce motion, $t$. We have
thrown away the motion associated with the polarization drift. From the Lagrangian equations of motion

$$
\begin{array}{ll}
O(\varepsilon): & \dot{\alpha}=\frac{c}{e} \dot{p}_{\beta}=-\frac{c}{e} \frac{\partial H}{\partial \beta} \quad \dot{\beta}=\frac{\partial H}{\partial p_{\beta}}=\frac{c}{e} \frac{\partial H}{\partial \alpha} \\
O(1): & \dot{\sigma}=\frac{\partial H}{\partial p_{\sigma}}=\frac{p_{\sigma}}{m h^{2}} \quad \dot{p}_{\sigma}=-\frac{\partial H}{\partial \sigma} \tag{8.162}
\end{array}
$$

We note that if we freeze $\alpha, \beta, t$ then $\partial H / \partial t=O(\epsilon)$. With the two degrees of freedom $\sigma$ and $p_{\sigma}$, and other quantities slowly varying, there is an action that is an adiabatic invariant, which we have previously demonstrated.

## DEFINITION.

$$
\begin{equation*}
J_{\sigma}(H, \alpha, \beta) \equiv \frac{1}{2 \pi} \oint p_{\sigma} \mathrm{d} \sigma=\frac{1}{2 \pi} \oint \sqrt{2 m h^{2}(H-e \chi-\mu B)} \mathrm{d} \sigma . \tag{8.163}
\end{equation*}
$$

With $\alpha$ and $\beta$ slowly varying, i.e. $2 \pi / \omega_{B} \ll|B /(\partial B / \partial t)|$, the bounce action $J_{\sigma}$ is conserved through $O(1): \dot{J}_{\sigma}=O(\varepsilon)\left\langle\dot{J}_{\sigma}\right\rangle=O\left(\varepsilon^{2}\right)$. The hierarchy of time scales is as follows: $t / \epsilon^{-1}$ is the gyro time scale; $t$ is the bounce time scale; and $\epsilon^{-1} t$ is the drift time scale, which is the slowest. Over the drift time scale the bounce action is an invariant to $O(\epsilon):\left\langle\dot{J}_{\sigma}\right\rangle \tau_{\text {drift }} \equiv\left\langle\dot{J}_{\sigma}\right\rangle t / \varepsilon=\Delta\left\langle J_{\sigma}\right\rangle=O(\varepsilon)$. Now we can introduce action-angle variables for $H\left(J_{\sigma}, \theta_{\sigma} ; \alpha, \beta\right)$ by constructing a generating function $S$ to perform the canonical transformation as we have done in earlier lectures (see §8.1.3).

### 8.3. Guiding-centre theory and hydromagnetic equations

This section of the lecture notes presents the systematic derivation of a fluid theory of a plasma beginning with the guiding-centre equations of motion and distribution functions. The formalism will include considerations of magnetohydrodynamic (MHD), ballooning and resistive MHD stability.
8.3.1. Derivation of distribution functions and lowest-order velocity moments from guiding-centre theory
We construct particle distribution functions in a six-dimensional phase space representing guiding-centre motion: $\left(\mu, \theta_{g} ; \sigma, p_{\sigma} ; \alpha, \beta\right)$. The actual particle positions corresponding to ( $x, y, z, v_{x}, v_{y}, v_{z}$ ) in phase space are not in the same place! However, we can calculate the number of particles in a small volume of six-dimensional phase space centred around a specific location in either representation,

$$
\begin{align*}
f\left(x, y, z ; v_{x}, v_{y}, v_{z}\right) \mathrm{d}^{6} V & =f\left(x, y, z ; v_{x}, v_{y}, v_{z}\right) \mathrm{d} x \mathrm{~d} y \mathrm{~d} z \mathrm{~d} v_{x} \mathrm{~d} v_{y} \mathrm{~d} v_{z} \\
& =F\left(\mu, \theta_{g}, \sigma, p_{\sigma} ; \alpha, \beta\right) \mathrm{d}^{6} \mathcal{V} \\
& =F\left(\mu, \theta_{g}, \sigma, p_{\sigma} ; \alpha, \beta\right) \mathrm{d} \alpha \mathrm{~d} \beta \mathrm{~d} p_{\sigma} \mathrm{d} \mu \mathrm{~d} \theta_{g} \tag{8.164}
\end{align*}
$$

where

$$
\begin{equation*}
\frac{\mathrm{d}^{6} \mathcal{V}}{\mathrm{~d}^{6} V}=\mathcal{J}\left(\frac{\alpha \beta \sigma p_{\sigma} \mu \theta_{g}}{x y z v_{x} v_{y} v_{z}}\right)=\text { const. } \tag{8.165}
\end{equation*}
$$

for canonical transformations, and the constant in (8.165) has factors like $c / e$. Hence, $f=F$ apart from some numerical constants. We can calculate moments of $f$ and relate them to moments of $F$. For example, the number density is given by

$$
\begin{equation*}
n(x, y, z)=\int \mathrm{d} v_{x} \mathrm{~d} v_{y} \mathrm{~d} v_{z} f \tag{8.166}
\end{equation*}
$$

and similarly for the current density $j(x, y, z)$ with the inclusion of $e v$ inside the integrand on the right-hand side of (8.166). It is significant that $f$ includes the rapid variation due to the gyro-motion, but $F$ should have a much slower variation because we expect that the gyro-phase will be randomly distributed. In order that the moments and fields have a slow temporal variation, we expect $F$ to have a slow variation.

We can calculate the number density using $F$ as follows:

$$
\begin{equation*}
n(\boldsymbol{x})=\int \mathrm{d}^{6} \mathcal{V} \delta\left(\boldsymbol{x}-\boldsymbol{x}\left(\alpha \beta \sigma p_{\sigma} \mu \theta_{g}\right)\right) F \tag{8.167}
\end{equation*}
$$

using the $\delta$ function to obtain a density in the configuration space of the particles and $\boldsymbol{x}\left(\alpha, \beta, \sigma, p_{\sigma}, \mu, \theta_{g}\right)=\boldsymbol{R}(\alpha, \beta, \sigma)+\boldsymbol{r}\left(\mu, \theta_{g}\right)$. We expand inside the integrand in (8.167) in a Taylor series for small $\boldsymbol{r}$,

$$
\begin{align*}
\delta(\boldsymbol{x}-\boldsymbol{R}-\boldsymbol{r}) & =\mathrm{e}^{-\boldsymbol{r} \cdot(\partial / \partial \boldsymbol{x})} \delta(\boldsymbol{x}-\boldsymbol{R}) \\
& =\delta(\boldsymbol{x}-\boldsymbol{R})-\boldsymbol{r} \cdot \frac{\partial}{\partial \boldsymbol{x}} \delta(\boldsymbol{x}-\boldsymbol{R})+\frac{1}{2}\left(\boldsymbol{r} \cdot \frac{\partial}{\partial \boldsymbol{x}}\right)^{2} \delta(\boldsymbol{x}-\boldsymbol{R})+\cdots \tag{8.168}
\end{align*}
$$

to obtain

$$
\begin{align*}
n(\boldsymbol{x})= & \int \mathrm{d}^{6} \mathcal{V} F \delta(\boldsymbol{x}-\boldsymbol{R})-\frac{\partial}{\partial \boldsymbol{x}} \cdot \int \mathrm{d}^{6} \mathcal{V} \boldsymbol{r} F \delta(\boldsymbol{x}-\boldsymbol{R}) \\
& +\frac{1}{2} \nabla \nabla: \int \mathrm{d}^{6} \mathcal{V} \boldsymbol{r} \boldsymbol{r} F \delta(\boldsymbol{x}-\boldsymbol{R})+\cdots \tag{8.169}
\end{align*}
$$

or, alternatively,

$$
\begin{equation*}
n(\boldsymbol{x})=\int \mathrm{d}^{6} \mathcal{V} \mathrm{e}^{-\boldsymbol{r} \cdot(\partial / \partial x)} F \delta(\boldsymbol{x}-\boldsymbol{R}) \rightarrow N(\boldsymbol{x})+\cdots=N(\boldsymbol{x})+\frac{1}{4} \nabla_{\perp}^{2}\left(N\left\langle\rho^{2}\right\rangle\right) \tag{8.170}
\end{equation*}
$$

where $N(x)$ is the density of guiding centres at $x, \nabla_{\perp}^{2} \equiv(\boldsymbol{I}-\hat{\boldsymbol{b}} \hat{\boldsymbol{b}}): \nabla \nabla$ and $\int \mathrm{d} \mu \boldsymbol{r} \cdot \boldsymbol{r} F \rightarrow\left\langle\rho^{2}\right\rangle$. We note the alternative expression for $n(x)$ correct to leading-order terms obtained by expanding the Bessel function after averaging over $\theta_{g}$,

$$
\begin{align*}
n(\boldsymbol{x}) & =\int \mathrm{d}^{6} \mathcal{V} \mathrm{e}^{-\boldsymbol{r} \cdot(\partial / \partial x)} F \delta(\boldsymbol{x}-\boldsymbol{R}) \rightarrow \int \mathrm{d}^{6} \mathcal{V} \mathrm{~J}_{0}\left(k_{\perp} \rho\right) F \delta(\boldsymbol{x}-\boldsymbol{R}) \\
& =\int \mathrm{d}^{6} \mathcal{V} \mathrm{~J}_{0}\left(-\mathrm{i} \nabla_{\perp} \rho\right) F \delta(\boldsymbol{x}-\boldsymbol{R}) . \tag{8.171}
\end{align*}
$$

Now consider the current density. The flux density is

$$
\begin{aligned}
\boldsymbol{\Gamma}(\boldsymbol{x}) & =\int \mathrm{d}^{6} \mathcal{V} F \delta(\boldsymbol{x}-\boldsymbol{x}(\cdots)) \boldsymbol{v}=\int \mathrm{d}^{6} \mathcal{V} F(\delta(\boldsymbol{x}-\boldsymbol{R})-\boldsymbol{r} \cdot \nabla \delta(\boldsymbol{x}-\boldsymbol{R}))(\boldsymbol{V}+\dot{\boldsymbol{r}}) \\
& =N\langle\boldsymbol{V}\rangle(\boldsymbol{x})-\nabla \cdot N\langle\boldsymbol{r} \dot{\boldsymbol{r}}\rangle(\boldsymbol{x})
\end{aligned}
$$

$$
\begin{align*}
& =N\langle\boldsymbol{V}\rangle(\boldsymbol{x})-\frac{1}{2} \boldsymbol{\nabla} \cdot\left[N\left\langle\rho^{2}\right\rangle \Omega\left(\hat{\boldsymbol{e}}_{2} \hat{\boldsymbol{e}}_{1}-\hat{\boldsymbol{e}}_{1} \hat{\boldsymbol{e}}_{2}\right)\right]+\cdots \\
& =N\langle\boldsymbol{V}\rangle(\boldsymbol{x})-\frac{1}{2} \boldsymbol{\nabla} \times\left(N \Omega\left\langle\rho^{2}\right\rangle \hat{\boldsymbol{b}}\right) \tag{8.172}
\end{align*}
$$

using $\dot{\boldsymbol{r}}=\rho \Omega\left(-\hat{\boldsymbol{e}}_{2} \sin \theta_{g}+\hat{\boldsymbol{e}}_{1} \cos \theta_{g}\right)$ and the inner product with the anti-symmetric dyadic $\hat{\boldsymbol{e}}_{2} \hat{\boldsymbol{e}}_{1}-\hat{\boldsymbol{e}}_{1} \hat{\boldsymbol{e}}_{2}$ leads to the cross-product. The first term in the final expression for the flux density in (8.172) is the product of the guiding-centre density and the average guiding-centre velocity. The second term leads to the diamagnetic current or magnetization current.

DEFInItion. The magnetization is

$$
\begin{equation*}
\boldsymbol{M}(\boldsymbol{x}) \equiv N(\boldsymbol{x})\langle-\mu \hat{\boldsymbol{b}}\rangle(\boldsymbol{x}) \quad \text { where } \mu=\frac{e}{2 c} \Omega \rho^{2} \tag{8.173}
\end{equation*}
$$

THEOREM. The current density is given by

$$
\begin{equation*}
\boldsymbol{j}(\boldsymbol{x})=e \boldsymbol{\Gamma}(\boldsymbol{x})=e N\langle\boldsymbol{V}\rangle+c \boldsymbol{\nabla} \times \boldsymbol{M}(\boldsymbol{x}) . \tag{8.174}
\end{equation*}
$$

The first term in (8.174) is the guiding-centre current density and the second term is identified as the diamagnetic current density.

Examples. (i) Consider a plasma with finite gradients $\nabla n$ and $\nabla T$ in the $x$ direction with uniform magnetic field in $z$. In consequence of the particle gyration and the gradient in $n$ there is a net current in the $y$ direction.

$$
\begin{equation*}
\boldsymbol{\Gamma}_{\text {diamagnetic }}=-\frac{1}{2} \nabla \times\left(N \Omega\left\langle\rho^{2}\right\rangle \hat{\boldsymbol{b}}\right)=\frac{1}{2} \Omega \hat{\boldsymbol{b}} \times \nabla\left(N\left\langle\rho^{2}\right\rangle\right) \neq 0 . \tag{8.175}
\end{equation*}
$$

However, there is nothing implied with respect to the guiding-centre flux $\boldsymbol{\Gamma}_{\mathrm{gc}}$ which can be zero.
(ii) Assume $\nabla n=0=\nabla T$, but $\nabla \Omega \neq 0$. The gradient in the magnetic field does not produce a total net flux. However, there is a finite particle drift due to $\nabla B$, which yields a finite guiding-centre flux and a finite diamagnetic flux (8.172) and (8.175).

Exercise. Show the details.
(iii) A stress tensor can be calculated from

$$
\begin{equation*}
\stackrel{\leftrightarrow}{\boldsymbol{P}}(\boldsymbol{x})=n m\langle(\boldsymbol{v}-\langle\boldsymbol{v}\rangle)(\boldsymbol{v}-\langle\boldsymbol{v}\rangle)\rangle(\boldsymbol{x})=p_{\|} \hat{\boldsymbol{b}} \hat{\boldsymbol{b}}+p_{\perp}(\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{b}} \hat{\boldsymbol{b}}) \tag{8.176}
\end{equation*}
$$

EXERCISE. Show that $\boldsymbol{\nabla} \cdot \stackrel{\leftrightarrow}{\boldsymbol{P}}=(1 / c) \boldsymbol{j} \times \boldsymbol{B}+e n \boldsymbol{E}-n m(\mathrm{~d} / \mathrm{d} t)\langle\boldsymbol{u}\rangle$, i.e. momentum balance, where $\boldsymbol{j}=e \boldsymbol{\Gamma}=e\left(\boldsymbol{\Gamma}_{\mathrm{gc}}+\boldsymbol{\Gamma}_{\text {diamagnetic }}\right)$.

### 8.3.2. Hamiltonian theory and Liouville's theorem

In (8.171) an expression was derived for $n(\boldsymbol{x})=N(\boldsymbol{x})+O\left(\epsilon^{2}\right)$ where $N(\boldsymbol{x})$ is the guiding-centre density at $\boldsymbol{x}$. Introducing a coordinate transformation we can express the number of guiding centres in a volume $\mathrm{d} x \mathrm{~d} y \mathrm{~d} z$ as

$$
\begin{equation*}
N(x, y, z) \mathrm{d} x \mathrm{~d} y \mathrm{~d} z=\mathcal{N}(\alpha, \beta, \sigma) \mathrm{d} \alpha \mathrm{~d} \beta \mathrm{~d} \sigma \tag{8.177}
\end{equation*}
$$

The Jacobian relating $\mathrm{d} \alpha \mathrm{d} \beta \mathrm{d} \sigma$ to $\mathrm{d} x \mathrm{~d} y \mathrm{~d} z$ is

$$
\begin{equation*}
\mathcal{J}=\frac{\mathrm{d} \alpha \mathrm{~d} \beta \mathrm{~d} \sigma}{\mathrm{~d} x \mathrm{~d} y \mathrm{~d} z}=\mathcal{J}\left(\frac{\alpha \beta \sigma}{x y z}\right)=\nabla \alpha \times \nabla \beta \cdot \nabla \sigma=B \hat{\boldsymbol{b}} \cdot \nabla \sigma=B \frac{\mathrm{~d} \sigma}{\mathrm{~d} \ell}=\frac{B}{h}, \tag{8.178}
\end{equation*}
$$

where $h$ is the field-line metric. The guiding-centre density is

$$
\begin{equation*}
\mathcal{N}(\alpha, \beta, \sigma) \equiv \int F\left(\mu, \sigma, p_{\sigma}, \alpha, \beta\right) \mathrm{d} \mu \mathrm{~d} p_{\sigma} \tag{8.179}
\end{equation*}
$$

and

$$
\begin{equation*}
N(x, y, z)=\frac{B(\alpha, \beta, \sigma)}{h(\alpha, \beta, \sigma)} \mathcal{N}(\alpha, \beta, \sigma) \tag{8.180}
\end{equation*}
$$

Recall from (8.164) and (8.165) that $F$ has no fast gyro time scale variation, while $f$ does; $F$ differs from $f$ only by some constants, which is a consequence of the canonical transformations. Under certain conditions, $F$ is just a function of canonical variables. Assuming that $\boldsymbol{u}_{L}$ is $O(\epsilon)$ as in (8.161) the lowest-order guiding-centre Hamiltonian is

$$
H_{\mathrm{g} . \mathrm{c.}}\left(\alpha, \beta ; \sigma, p_{\sigma} ; t\right)=\frac{p_{\sigma}^{2}}{2 m h^{2}}+e \chi+\mu B
$$

through $O(1)$. With $\alpha$ and $\beta$ frozen, there is only one degree of freedom corresponding to the bounce motion; and $F\left(\sigma, p_{\sigma}, t\right)$ satisfies a Vlasov equation for one-dimensional motion.

THEOREM. Liouville equation for a Hamiltonian system with one-dimensional motion,

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} F\left(\sigma, p_{\sigma}, t\right) \equiv\left[\frac{\partial}{\partial t}+\dot{\sigma} \frac{\partial}{\partial \sigma}+\dot{p}_{\sigma} \frac{\partial}{\partial p_{\sigma}}\right] F\left(\sigma, p_{\sigma}, t\right)=0 . \tag{8.181}
\end{equation*}
$$

Equation (8.181) and Maxwell's equations with appropriate boundary and initial conditions provide a closed system of equations. With this system of equations one can look for time-independent solutions for equilibrium states. One can linearize about these solutions to assess waves and instabilities. One can also analyse nonlinear, time-dependent solutions, e.g. BGK modes, mode coupling equations and quasilinear equations.

Consider the limit in which there is no explicit time dependence, i.e. $\partial / \partial t=0$. Then (8.181) yields Jeans' theorem for $F\left(H\left(\sigma, p_{\sigma}\right)\right)$

$$
\begin{equation*}
\frac{\mathrm{d} F}{\mathrm{~d} t}=\frac{\partial H}{\partial p_{\sigma}} \frac{\mathrm{d} F}{\mathrm{~d} H} \frac{\partial H}{\partial \sigma}-\frac{\partial H}{\partial \sigma} \frac{\mathrm{~d} F}{\mathrm{~d} H} \frac{\partial H}{\partial p_{\sigma}}=0 . \tag{8.182}
\end{equation*}
$$

In general, the equilibrium guiding-centre distribution function is given by

$$
\begin{equation*}
F\left(\mu, \sigma ; p_{\sigma}\right)=F\left(\mu, H\left(\mu, \sigma, p_{\sigma}\right)\right) \tag{8.183}
\end{equation*}
$$

where $\alpha$ and $\beta$ are implicit. To lowest order the particle density $n(\boldsymbol{x})$ is the same as the guiding-centre density,

$$
\begin{align*}
n(\boldsymbol{x}) & =\frac{B}{h} \int_{0}^{\infty} \mathrm{d} \mu \int_{-\infty}^{\infty} \mathrm{d} p_{\sigma} F(\mu, H) \\
& =\frac{B}{h} \int_{0}^{\infty} \mathrm{d} \mu \int_{e x+\mu B}^{\infty} \mathrm{d} H p_{\sigma}\left(-\left.\frac{\partial F(H, \mu)}{\partial H}\right|_{\mu}\right), \tag{8.184}
\end{align*}
$$

where we have integrated by parts: $F \mathrm{~d} p_{\sigma}=\mathrm{d}\left(F p_{\sigma}\right)-p_{\sigma} \mathrm{d} F$, and used $\int_{-\infty}^{\infty} \mathrm{d}\left(F p_{\sigma}\right)=$ $\left.F p_{\sigma}\right|_{-\infty} ^{\infty}=0$ and $\left.\mathrm{d} F\right|_{\mu}=\left.((\partial F / \partial H) \mathrm{d} H)\right|_{\mu}$. With $p_{\sigma}=\left(2 m h^{2}(H-e \chi-\mu B)\right)^{1 / 2}$ equation (8.184) becomes

$$
\begin{equation*}
n(\boldsymbol{x})=B(\sigma) \int_{0}^{\infty} \mathrm{d} \mu \int_{e \chi+\mu B}^{\infty} \mathrm{d} H(2 m(H-e \chi-\mu B))^{1 / 2}\left(-\left.\frac{\partial F(H, \mu)}{\partial H}\right|_{\mu}\right) \tag{8.185}
\end{equation*}
$$

for a given species.
In the Coulomb plasma (electrostatics) Poisson's equation for a singly charged ion species is

$$
\begin{equation*}
\nabla^{2} \phi=-4 \pi e\left(n_{i}-n_{e}\right) \tag{8.186}
\end{equation*}
$$

In the limit that $L \equiv \mid \phi / \sqrt{\left|\nabla^{2} \phi\right|} \gg \lambda_{D}$, then $n_{i} \approx n_{e}$ to $O\left(\lambda_{D} / L\right)^{2}$, i.e. the plasma is quasi-neutral; and one can solve for $\chi(B)$ from $n_{i}(B, \chi) \approx n_{e}(B, \chi)$. From the solution for $\chi(B)$ one can calculate the parallel electric field,

$$
\begin{equation*}
E_{\|}=-\frac{\mathrm{d} \chi(B)}{\mathrm{d} \sigma}=-\frac{\mathrm{d} \chi}{\mathrm{~d} B} \frac{\partial B}{\partial \sigma} \tag{8.187}
\end{equation*}
$$

Example. Magnetic mirror configuration (figure $36 a$ ). Assume that in the midplane of the mirror $(\sigma=0)$

$$
\begin{equation*}
f\left(\sigma=0 ; v_{\perp}, v_{\|}\right) \sim \mathrm{e}^{-m v_{\|}^{2} / 2 T_{\|}} \mathrm{e}^{-m v_{\perp}^{2} / 2 T_{\perp}}=\mathrm{e}^{-\left(\left(H-\mu B_{0}-e x\right) / T_{\|}\right)} \mathrm{e}^{-\mu B_{0} / T_{\perp}}, \tag{8.188}
\end{equation*}
$$

$B_{0}$ is the magnetic field in the midplane. $\chi(\sigma=0)$ can be set to zero by choice. Recall that $F$ is a function of $H$ and $\mu$, but must be evaluated at a particular value of $\sigma$.

THEOREM.

$$
\begin{equation*}
F(H, \mu) \sim \mathrm{e}^{-\left(H-\mu B_{0}-e x\right) / T_{\|}} \mathrm{e}^{-\mu B_{0} / T_{\perp}} \tag{8.189}
\end{equation*}
$$

DEFINITION. Define $\beta_{\| s} \equiv 1 / T_{\| s}$ and an anisotropy parameter $a_{s} \equiv\left(T_{\|}-T_{\perp}\right) /\left.T_{\perp}\right|_{s}$.

From (8.185) and (8.189) we calculate

$$
\begin{equation*}
n(\sigma)=\text { const. } \mathrm{e}^{-\beta_{\|} e \chi(\sigma)} \frac{b(\sigma)}{a+b(\sigma)}, \quad b \equiv \frac{B(\sigma)}{B_{0}} \tag{8.190}
\end{equation*}
$$

for each species. Then quasi-neutrality imposes

$$
\begin{equation*}
C_{i} \mathrm{e}^{-\beta_{\| i} e \chi(\sigma)} \frac{b}{a_{i}+b}=C_{e} \mathrm{e}^{\beta_{\| e} e \chi(\sigma)} \frac{b}{a_{e}+b} . \tag{8.191}
\end{equation*}
$$

Taking $\chi=0$ at the midplane where $b=1$, then $C_{i} /\left(a_{i}+1\right)=C_{e} /\left(a_{e}+1\right)$ : we choose $C_{i}=a_{i}+1$ and $C_{e}=a_{e}+1$. Elsewhere than the midplane $n_{e} / n_{i}=1$, which leads to

$$
\begin{equation*}
\frac{a_{e}+b}{a_{i}+b} \frac{a_{i}+1}{a_{e}+1}=\mathrm{e}^{\left(\beta_{\| e}+\beta_{\| i}\right) e x} \rightarrow\left(\beta_{\| e}+\beta_{\| i}\right) e \phi=\ln \left[\frac{a_{e}+b}{a_{i}+b} \frac{a_{i}+1}{a_{e}+1}\right] \tag{8.192}
\end{equation*}
$$

which determines $\phi(b)$. We note that if $\left(T_{\|} / T_{\perp}\right)^{i}=\left(T_{\|} / T_{\perp}\right)^{e} \rightarrow a_{e}=a_{i}$ then (8.192) dictates $\phi(b)=0 \rightarrow E_{\|}(b)=0$. Thus, not only must there be anisotropy, but the anisotropies for the species must be different if there is a finite $E_{\|}$.

THEOREM. (i) For $E_{\|} \neq 0$ then anisotropy is necessary and $\partial F(H, \mu) / \partial \mu \neq 0$ (local anisotropy). (ii) For $E_{\|} \neq 0$ then there must be different anisotropies for different species.

We further elaborate the solution for $F$ and $n(\sigma)$ in a magnetic mirror configuration. Consider

$$
\left.\begin{array}{c}
F(\mu, H) \sim \mathrm{e}^{-\beta_{\|}\left(H+a \mu B_{0}\right)}, \quad a \equiv \frac{T_{\|}-T_{\perp}}{T_{\perp}}  \tag{8.193}\\
n(\sigma)=n_{B}(\sigma) n_{\phi}(\sigma) \sim \frac{1+b^{\prime}(\sigma)}{1+b^{\prime}(\sigma) \frac{T_{\|}}{T_{\perp}}} \mathrm{e}^{-e \chi(\sigma) / T_{\|}}, \quad b^{\prime}=\frac{B(\sigma)-B_{0}}{B_{0}} \\
n_{B}(\sigma)=\frac{1+b^{\prime}(\sigma)}{1+b^{\prime}(\sigma) \frac{T_{\|}}{T_{\perp}}}, \quad n_{\phi}(\sigma)=\mathrm{e}^{-e x(\sigma) / T_{\|}} .
\end{array}\right\}
$$

A plot of $n_{b}(\sigma)$ is shown in figure 37 which illustrates that the density variation along the field line depends significantly on the relative anisotropy. We note that the duration of a charged particle in a segment $\mathrm{d} l$ is $\mathrm{d} l / v_{\|}$, which implies that the duration increases near the turning point where $v_{\|} \rightarrow 0$ and the density should increase. However, the smaller $T_{\|}$is relative to $T_{\perp}$, the closer the turning points will be to the midplane of the mirror, which implies that the density will decrease away from the midplane. When the temperatures are isotropic, $n_{b}(\sigma)$ is uniform.

EXERCISE. Assume $f(z=0, v) \sim\left(v_{\perp}^{2} / v^{2}\right)^{\ell} g\left(v^{2}\right)$ and construct $f(H, \mu) \rightarrow n(\sigma)$. Show that $n(\sigma) \sim B^{-l}$. Construct $p_{\|}(\sigma)=n m\left\langle v_{\|}^{2}\right\rangle$ and evaluate $\partial p_{\|}(\sigma) / \partial \sigma$.


Figure 37. Value of $n_{b}(\sigma)$ versus $B(\sigma) / B_{0}$ from (8.193).

### 8.3.3. Derivation of lowest-order hydromagnetic equations

In this section we derive a reduced set of Maxwell and fluid equations, i.e. the lowest-order hydromagnetic equations, magnetohydrodynamics (MHD). We begin by postulating an ordering system. As a first pass, assume

$$
\left.\begin{array}{c}
\epsilon^{-2}: \quad j, p, \omega_{p}  \tag{8.194}\\
\epsilon^{-1}: e, c, B, A, \Omega=e B / m c \\
\epsilon^{0}: \phi, E_{\perp}, m, v, u_{L}, L, T, \beta, m_{e} / m_{i} \quad \text { (temporarily) }, \rho_{c} \\
\epsilon: E_{\|}, \chi, v_{d},\left|\boldsymbol{u}^{i}-\boldsymbol{u}^{e}\right|, \Delta n
\end{array}\right\}
$$

At this point, $\omega_{p}$ and $\Omega$ are not necessarily the same order. However, if $\omega_{p}^{2} \sim \Omega^{2} \sim$ $O\left(\epsilon^{-2}\right)$, consistent with $n e^{2} / m \sim \omega_{p}^{2} \sim \epsilon^{-2}$, then this implies $n \sim O\left(\epsilon^{0}\right)$. Now examine the relative ordering of terms in Ampere's law,

$$
\left.\begin{array}{l}
\boldsymbol{\nabla} \times \boldsymbol{B}=\frac{4 \pi}{c} \boldsymbol{J}  \tag{8.195}\\
O\left(\varepsilon^{0}\right) O\left(\varepsilon^{-1}\right) \\
O(\varepsilon) O(?) \\
O(\varepsilon) \\
\frac{1}{c} \frac{1}{\partial t}(1) O(1) .
\end{array} \Rightarrow \quad \boldsymbol{J} \sim O\left(\varepsilon^{-2}\right)\right\}
$$

The time dependence of all motion is assumed to be slow (adiabatic), and we will throw away the displacement current again as higher order. Thus, $\boldsymbol{J} \sim O\left(\epsilon^{-2}\right)$, which is consistent with $n \sim O\left(\epsilon^{-2}\right)$,

$$
\begin{equation*}
j \sim n e v_{d}+c \nabla(n \mu) \sim O\left(\varepsilon^{-2}\right) O\left(\varepsilon^{-1}\right) O(\varepsilon)+O\left(\varepsilon^{-1}\right) O(1) O\left(\varepsilon^{-2}\right) O(\varepsilon) \sim O\left(\varepsilon^{-2}\right) \tag{8.196}
\end{equation*}
$$

Consider the ordering of $\beta \equiv p / B^{2} \sim n m v^{2} / B^{2} \sim \epsilon^{-2} \epsilon^{0} / \epsilon^{-2}=O(1)$. Returning to the reduced Ampere's law (8.195),

$$
\begin{equation*}
\nabla \times \boldsymbol{B}=\frac{4 \pi}{c} \boldsymbol{J} \quad \Rightarrow \quad \nabla \cdot \boldsymbol{J}=0 . \tag{8.197}
\end{equation*}
$$

Given $J \sim O\left(\epsilon^{-2}\right)$, we can evaluate $u_{\|}^{i}-u_{\|}^{e}=j_{\|} / n e \sim \varepsilon^{-2} / \varepsilon^{-2} \varepsilon^{-1} \sim O(\varepsilon)$. Furthermore, the perpendicular fluid velocities are equal to the field-line velocity to leading order, i.e. $\boldsymbol{u}_{\perp}=\boldsymbol{u}_{E}+O(\varepsilon)$. Hence, $\left|\boldsymbol{u}^{i}-\boldsymbol{u}^{e}\right| \sim O(\epsilon)$.

THEOREM. In MHD ordering, ne $\sim O\left(\epsilon^{-3}\right)$ is appreciable, while the velocity difference between ions and electrons is small, $O(\epsilon)$, to give large currents, $O\left(\epsilon^{-2}\right)$. Electrons, ions, and field lines have the same velocity perpendicular to the field lines to leading order; and the electrons and ions have the same parallel velocity to leading order. Hence, a single-fluid model is justified.

The fluid momentum balance equation is

$$
\begin{equation*}
n_{s} m_{s}\left(\frac{\partial}{\partial t}+\boldsymbol{u}^{s} \cdot \nabla\right) \boldsymbol{u}^{s}=-\nabla \cdot \boldsymbol{p}^{s}+n_{s} e_{s} \boldsymbol{E}+\frac{n_{s} e_{s}}{c} \boldsymbol{u}^{s} \times \boldsymbol{B}+\cdots . \tag{8.198}
\end{equation*}
$$

We sum (8.198) over species using $\left|\boldsymbol{u}^{i}-\boldsymbol{u}^{e}\right| \sim O(\epsilon)$, and the net charge density $\rho_{c}$ and the electric field $\boldsymbol{E}$ are both $O(1)$ to obtain the follow equation retaining only terms at $O\left(\epsilon^{-2}\right)$,

$$
\begin{equation*}
\rho_{m}\left(\frac{\partial}{\partial t}+\boldsymbol{u} \cdot \nabla\right) \boldsymbol{u}=-\nabla \cdot \boldsymbol{p}+\frac{1}{c} \boldsymbol{j} \times \boldsymbol{B}, \tag{8.199}
\end{equation*}
$$

where $\rho_{m}$ is the mass density and $\boldsymbol{p}$ is the total pressure summed over species.
We next examine the ordering of the Poisson equation,

$$
\begin{align*}
&-\nabla^{2} \phi=4 \pi \rho_{c} \sim \frac{1}{L^{2}} O(1) \sim O(1) \\
& \Rightarrow \quad \rho_{c} \sim e\left(n_{i}-n_{e}\right) \sim O(1) \quad \Rightarrow \quad \Delta n \sim O\left(\frac{1}{e}\right) \sim O(\varepsilon) \tag{8.200}
\end{align*}
$$

Hence, the plasma is quasi-neutral.
ThEOREM. Summary of lowest-order hydromagnetic equations

$$
\left.\begin{array}{rl}
\rho_{m}\left(\frac{\partial}{\partial t}+\boldsymbol{u} \cdot \nabla\right) \boldsymbol{u} & =-\nabla \cdot \boldsymbol{p}+\frac{1}{c} \boldsymbol{j} \times \boldsymbol{B}=-\nabla \cdot \boldsymbol{p}+\frac{1}{4 \pi}(\nabla \times \boldsymbol{B}) \times \boldsymbol{B}  \tag{8.201}\\
\frac{\partial \boldsymbol{B}}{\partial t} & =\nabla \times\left(\boldsymbol{u}_{L} \times \boldsymbol{B}\right) \sim \nabla \times(\boldsymbol{u} \times \boldsymbol{B}) \\
\left(\frac{\partial}{\partial t}+\boldsymbol{u} \cdot \nabla\right)^{2} n & =-n \nabla \cdot \boldsymbol{u} \rightarrow\left(\frac{\partial}{\partial t}+\boldsymbol{u} \cdot \nabla\right) \rho_{m}=-\rho_{m} \nabla \cdot \boldsymbol{u}
\end{array}\right\}
$$

along with the constraint $\boldsymbol{\nabla} \cdot \boldsymbol{B}=0$. Equations (8.201) constitute three equations in four unknowns $\left(\rho_{m}, \boldsymbol{u}, \boldsymbol{p}, \boldsymbol{B}\right)$. A fourth equation must be added, which might be either quite ad hoc or derived from a collisional theory. For example, $\boldsymbol{p}$ might be assumed to be isotropic and satisfy an equation of state: $(\mathrm{D} / \mathrm{D} t)\left(p \rho_{m}^{-\gamma}\right)=0, \mathrm{D} / \mathrm{D} t \equiv \partial / \partial t+$ $\boldsymbol{u} \cdot \nabla$. More generally, the pressure is a tensor: $\boldsymbol{p}=p_{\|} \hat{\boldsymbol{b}} \hat{\boldsymbol{b}}+p_{\perp}(\stackrel{\boldsymbol{I}}{ }-\hat{\boldsymbol{b}} \hat{\boldsymbol{b}})$. To clarify the notation, $\mathrm{D} / \mathrm{D} t$ is the Lagrangian time derivative co-moving with the fluid flow; $\mathrm{D} p$ is a Lagrangian differential change in the pressure $p$ accrued in a frame moving with the fluid due to a displacement $\xi$. Eulerian differential changes are indicated with a $\delta f$ or a $\mathrm{d} f$, while $\mathrm{d} f(u) / \mathrm{d} x$ is the derivative.

If we are willing to solve the Vlasov equation in guiding-centre variables for the distribution function $F^{s}\left(\sigma, p_{\sigma} ; \mu ; \alpha, \beta ; t\right)$, where $\alpha$ and $\beta$ are constant for motion fixed to a particular field line, then the density and pressure moments can be calculated from $F^{s}$,

$$
\begin{align*}
& \left(n, p_{\|}, p_{\perp}\right)^{s} \\
& \quad \equiv \frac{B}{h} \int \mathrm{~d} \mu \int \mathrm{~d} p_{\sigma}\left(1, m v_{\|}^{2}=p_{\sigma}^{2} / m h^{2}, \frac{1}{2} m v_{\perp}^{2}=\mu B\right) F^{s}\left(\sigma, p_{\sigma} ; \mu ; \alpha, \beta ; t\right), \tag{8.202}
\end{align*}
$$

where $F^{s}$ satisfies the Vlasov equation

$$
\left.\begin{array}{c}
\frac{\partial F}{\partial t}+\dot{\sigma} \frac{\partial F}{\partial \sigma}+\dot{p}_{\sigma} \frac{\partial F}{\partial p_{\sigma}}=0, \quad \dot{\sigma}=\frac{\partial H^{s}}{\partial p_{\sigma}}, \quad \dot{p}_{\sigma}=-\frac{\partial H^{s}}{\partial \sigma}  \tag{8.203}\\
H^{s}=\frac{p_{\sigma}^{2}}{2 m_{s} h^{2}}+\mu B+e \chi-\frac{1}{2} m u_{L}^{2}
\end{array}\right\}
$$

where

$$
\begin{equation*}
\chi=\phi+\frac{1}{c} \alpha \frac{\partial \beta}{\partial t}, \quad \frac{\partial(\alpha, \beta)}{\partial t}=-\boldsymbol{u} \cdot \nabla(\alpha, \beta) \tag{8.204}
\end{equation*}
$$

and the quasi-neutrality condition determines $\phi$. The analytic solution of (8.201)(8.204) in the most general circumstances is not possible. The numerical solution can even prove difficult. Nevertheless, we wish to apply this formalism to non-uniform plasmas, and we want to do a stability analysis.

### 8.3.4. Perturbation theory and variational principle applied to MHD

MHD theory has received much attention and is nicely reviewed in the books Freidberg (1987), Callen (2003) and Bateman (1978), authored since these lecture notes originated. The basic approach pursued in MHD stability theory is to linearize the equations in all of the variables with respect to a zero-order time-independent solution of the MHD equations. The zero-order equations are nonlinear and are by no means trivial to solve in general circumstances. The MHD equation set admits the application of a variational principle to investigate stability. Theories for ideal (non-resistive) MHD with no flows have been worked out in papers by Bernstein, Frieman, Kulsrud, Kruskal, Oberman, Newcomb, Taylor, Chew, Goldberger and Low and others (Chew, Goldberger \& Low 1956; Bernstein et al. 1958; Kruskal \& Oberman 1958; Newcomb 1960; Taylor \& Hastie 1968) where Frieman \& Rotenberg (1960) extended previous work to include rotation and Coppi, Greene \& Johnson (1966) and Glasser, Greene \& Johnson (1975) extended MHD stability theory to include resistive effects and toroidal geometry.

### 8.3.5. Derivation of an energy principle for MHD stability using self-adjointness

Consider a model problem in which the pressure is an isotropic pressure satisfying

$$
\begin{equation*}
\frac{1}{p} \frac{\mathrm{D}}{\mathrm{~d} t} p=-\gamma \nabla \cdot \boldsymbol{u}, \quad \gamma \equiv \frac{c_{p}}{c_{v}}=\frac{5}{3} \tag{8.205}
\end{equation*}
$$

or equivalently $p \sim \rho^{\gamma}$. Such a relation can be derived from a Chapman-Enskog expansion of the kinetic equations. One can drop electron inertia effects in the electron momentum equation with no lowest-order flow or rotation and in the low-frequency limit to obtain an Ohm's law

$$
\begin{equation*}
\boldsymbol{E}+\frac{1}{c} \boldsymbol{u} \times \boldsymbol{B}=\eta \boldsymbol{J} \tag{8.206}
\end{equation*}
$$

and order the resistivity $\eta$ to zero. There are four equations of evolution for $\boldsymbol{u}, p, \rho$ and $\boldsymbol{B}$. The evolution equations lead to an energy conservation law,

$$
\begin{equation*}
\frac{\mathrm{d} U}{\mathrm{~d} t}=0, \quad U(t)=\int \mathrm{d}^{3} \boldsymbol{x}\left[\frac{|\boldsymbol{B}(\boldsymbol{x}, t)|^{2}}{8 \pi}+\frac{p(\boldsymbol{x}, t)}{\gamma-1}+\frac{1}{2} \rho(\boldsymbol{x}, t)|\boldsymbol{u}(\boldsymbol{x}, t)|^{2}\right] . \tag{8.207}
\end{equation*}
$$

The first two terms on the right-hand side of (8.207) contribute to a potential energy $W(t)$ and the third term is a kinetic energy $K(t)$. There is no electrical energy term related to $E^{2} / 8 \pi$ because the electric energy density is higher order.

The equilibrium is stationary by definition $(\partial / \partial t=0)$ and static $\left(\boldsymbol{u}_{0} \equiv 0\right)$ by assumption. Hence, $\mathrm{D} / \mathrm{D} t=0$ in (8.201) and (8.205). The only remaining equation is

$$
\begin{equation*}
\nabla p=\frac{1}{c} \boldsymbol{J}_{0} \times \boldsymbol{B}_{0}=\frac{1}{4 \pi}\left(\nabla \times \boldsymbol{B}_{0}\right) \times \boldsymbol{B}_{0} . \tag{8.208}
\end{equation*}
$$

Equation (8.208) is a statement that the Lorentz force balances the pressure gradient in establishing an equilibrium. Furthermore, the pressure gradient must be perpendicular to both the equilibrium current and magnetic field,

$$
\begin{equation*}
\boldsymbol{B}_{0} \cdot \nabla p_{0}=0, \quad \boldsymbol{J}_{0} \cdot \nabla p_{0}=0 \tag{8.209}
\end{equation*}
$$

and the equilibrium pressure is constant along the directions of the equilibrium magnetic field lines and the currents.

The linearization of the equations in the stability theory begins with

$$
\begin{equation*}
\boldsymbol{u}=\delta \boldsymbol{u}, \quad \boldsymbol{B}=\boldsymbol{B}_{0}+\delta \boldsymbol{B}, \quad \boldsymbol{J}=\boldsymbol{J}_{0}+\delta \boldsymbol{J}, \quad p=p_{0}+\delta p, \quad \rho=\rho_{0}+\delta \rho . \tag{8.210}
\end{equation*}
$$

The linearized versions of (8.201) and (8.205) become

$$
\left.\begin{array}{c}
\rho_{0} \frac{\partial}{\partial t} \delta \boldsymbol{u}=-\nabla \cdot \delta \boldsymbol{p}+\frac{1}{c} \delta \boldsymbol{j} \times \boldsymbol{B}+\frac{1}{c} \boldsymbol{j} \times \delta \boldsymbol{B}  \tag{8.211}\\
\frac{\partial \delta \boldsymbol{B}}{\partial t}=\nabla \times\left(\delta \boldsymbol{u} \times \boldsymbol{B}_{0}\right) \\
\frac{\partial}{\partial t} \delta p+\delta \boldsymbol{u} \cdot \nabla p_{0}=-\gamma p_{0} \nabla \cdot \delta \boldsymbol{u} .
\end{array}\right\}
$$

The linearized Ampere's law $\nabla \times \delta \boldsymbol{B}=4 \pi \delta \boldsymbol{J} / c$ allows us to substitute for $\delta \boldsymbol{J}$ and reduce the dependent variables to the set ( $\delta \boldsymbol{u}, \delta \boldsymbol{B}, \delta p$ ). Equation (8.211) leads to

$$
\begin{align*}
\rho_{0} \frac{\partial^{2}}{\partial t^{2}} \delta \boldsymbol{u}= & -\boldsymbol{\nabla}\left[-\gamma p_{0} \boldsymbol{\nabla} \cdot \delta \boldsymbol{u}-\delta \boldsymbol{u} \cdot \nabla p_{0}\right]-\frac{1}{4 \pi}\left\{\boldsymbol{\nabla} \times\left[\boldsymbol{\nabla} \times\left(\delta \boldsymbol{u} \times \boldsymbol{B}_{0}\right)\right]\right\} \times \boldsymbol{B}_{0} \\
& +\frac{1}{c} \boldsymbol{j}_{0} \times\left[\boldsymbol{\nabla} \times\left(\delta \boldsymbol{u} \times \boldsymbol{B}_{0}\right)\right] \equiv \boldsymbol{F}(\delta \boldsymbol{u}) \tag{8.212}
\end{align*}
$$

$\boldsymbol{F}$ in (8.212) is a linear, second-order differential operator in space and is self-adjoint. Hence, its eigenvalues are real and its eigenvectors can be made orthonormal.

DEFINITION. A self-adjoint operator satisfies $\int \mathrm{d}^{3} \operatorname{vol} \boldsymbol{\eta} \cdot \boldsymbol{F}(\boldsymbol{\xi})=\int \mathrm{d}^{3} \operatorname{vol} \boldsymbol{\xi} \cdot \boldsymbol{F}(\boldsymbol{\eta})$.
The self-adjointness of the operator $\boldsymbol{F}$ was proven by Kulsrud and shown generally from the Lagrangian nature of the fluid equations (Kulsrud 1968).

We next introduce the linear displacement $\boldsymbol{\xi}(\boldsymbol{x}, t)$ from the equilibrium position of the fluid element in $(\boldsymbol{x}, t)$. In the absence of zero-order flows: $\mathrm{d} \boldsymbol{\xi} / \mathrm{d} t=\partial \boldsymbol{\xi} / \partial t=\delta \boldsymbol{u}$. We replace $\delta \boldsymbol{u}$ with $\delta \boldsymbol{u}=\partial \boldsymbol{\xi} / \partial t$ in (8.212) and integrate in time to obtain

$$
\begin{align*}
\rho_{0} \frac{\partial^{2}}{\partial t^{2}} \boldsymbol{\xi}= & -\nabla\left[-\gamma p_{0} \boldsymbol{\nabla} \cdot \boldsymbol{\xi}-\boldsymbol{\xi} \cdot \nabla p_{0}\right]-\frac{1}{4 \pi}\left\{\boldsymbol{\nabla} \times\left[\boldsymbol{\nabla} \times\left(\boldsymbol{\xi} \times \boldsymbol{B}_{0}\right)\right]\right\} \times \boldsymbol{B}_{0} \\
& +\frac{1}{c} \boldsymbol{j}_{0} \times\left[\boldsymbol{\nabla} \times\left(\boldsymbol{\xi} \times \boldsymbol{B}_{0}\right)\right] \tag{8.213}
\end{align*}
$$

The right-hand side of (8.213) is the force density. The inner product of the force density with the displacement $\boldsymbol{\xi}(\boldsymbol{x}, t)$ integrated over volume is a quadratic in the displacement and is 'virial'. We will come back to this subsequently. We can construct an energy that is quadratic in $\boldsymbol{\xi}(\boldsymbol{x}, t)$,

$$
\left.\begin{array}{c}
U(t) \equiv W(t)+K(t), \quad K(t)=\int \mathrm{d}^{3} x \frac{1}{2} \rho_{0}(\boldsymbol{x})[\dot{\boldsymbol{\xi}}(\boldsymbol{x}, t)]^{2}  \tag{8.214}\\
V[\boldsymbol{\xi}(\boldsymbol{x}, t)]=\sum_{n=0}^{\infty} a_{n}\left[\xi^{n}\right] \quad \text { a functional } \equiv \mathrm{W}_{0}+W_{1}(\boldsymbol{\xi})+W_{2}(\boldsymbol{\xi}, \boldsymbol{\xi})
\end{array}\right\}
$$

From the conservation law (8.207) and the linear expansion with $\boldsymbol{u}_{0}=0$

$$
\left.\begin{array}{c}
0=\dot{U}=\dot{W}+\dot{K}, \quad 0=\dot{W}_{0}+\dot{W}_{1}+\dot{W}_{2}+\dot{K}+O\left(\varepsilon^{2}\right)=\dot{W}_{1}+\dot{W}_{2}+\dot{K}+O\left(\varepsilon^{2}\right) \\
K(t) \equiv \int \mathrm{d}^{3} \boldsymbol{x} \frac{1}{2} \rho u^{2}=\int \mathrm{d}^{3} \boldsymbol{x} \frac{1}{2} \rho \dot{\boldsymbol{\xi}}^{2}+O\left(\xi^{3}\right)  \tag{8.215}\\
W(t)=\int \mathrm{d}^{3} \boldsymbol{x}\left[\frac{B^{2}}{8 \pi}+\frac{p}{\gamma-1}\right]=W_{0}+W_{1}(\boldsymbol{\xi})+W_{2}(\boldsymbol{\xi}, \boldsymbol{\xi})+O\left(\xi^{3}\right)
\end{array}\right\}
$$

We can use (8.211) to express

$$
\begin{equation*}
\delta \boldsymbol{B}(\boldsymbol{\xi}) \equiv \nabla \times\left(\boldsymbol{\xi} \times \boldsymbol{B}_{0}\right) \tag{8.216}
\end{equation*}
$$

and to rewrite (8.213). We note that

$$
\begin{equation*}
\dot{K} \equiv \int \mathrm{~d}^{3} \boldsymbol{x} \rho_{0} \dot{\boldsymbol{\xi}} \cdot \ddot{\boldsymbol{\xi}}=\int \mathrm{d}^{3} \boldsymbol{x} \dot{\boldsymbol{\xi}} \cdot \boldsymbol{F}(\boldsymbol{\xi})=-W_{1}(\dot{\boldsymbol{\xi}})-W_{2}(\boldsymbol{\xi}, \dot{\boldsymbol{\xi}})-W_{2}(\dot{\boldsymbol{\xi}}, \boldsymbol{\xi}) \tag{8.217}
\end{equation*}
$$

We choose as an initial condition $\boldsymbol{\xi}(\boldsymbol{x}, t=0)=0$, but with finite initial velocity $\dot{\boldsymbol{\xi}}$. Hence, $W_{2}(\boldsymbol{\xi}, \dot{\boldsymbol{\xi}})=0$ and $W_{2}(\dot{\boldsymbol{\xi}}, \boldsymbol{\xi})=0$, which leaves $W_{1}(\dot{\boldsymbol{\xi}})=0$ for arbitrary $\dot{\boldsymbol{\xi}} . W_{1}(\dot{\boldsymbol{\xi}})=$ 0 does not depend separately on $\xi$. Thus, $W_{1}(\dot{\xi})=0$ for all time.

We introduce the definition $\boldsymbol{\eta}=\boldsymbol{\xi}$ and note from (8.217)

$$
\begin{equation*}
-\int \mathrm{d}^{3} \boldsymbol{x} \boldsymbol{\eta} \cdot \boldsymbol{F}(\boldsymbol{\xi})=W_{2}(\boldsymbol{\xi}, \boldsymbol{\eta})+W_{2}(\boldsymbol{\eta}, \boldsymbol{\xi})=-\int \mathrm{d}^{3} \boldsymbol{x} \boldsymbol{\xi} \cdot \boldsymbol{F}(\boldsymbol{\eta}) \tag{8.218}
\end{equation*}
$$

This explicitly demonstrates that the operator $\boldsymbol{F}(\boldsymbol{\xi})$ is self-adjoint to the order calculated. For self-adjoint operators any arbitrary displacement can be represented as a sum over normal modes,

$$
\begin{equation*}
\boldsymbol{\xi}(\boldsymbol{x}, t)=\sum_{n} \boldsymbol{\xi}_{n}(\boldsymbol{x}) \mathrm{e}^{-\mathrm{i} \omega_{n} t}, \quad-\omega_{n}^{2} \boldsymbol{\xi}_{n}=\boldsymbol{F}\left(\boldsymbol{\xi}_{n}\right) \tag{8.219}
\end{equation*}
$$

where $-\omega_{n}^{2}$ is real and $\xi_{n}$ are orthogonal, possibly complex-valued eigenfunctions. The eigenvalues $\omega_{n}$ are either real and the solutions for the displacement are oscillatory, or $\omega_{n}$ are imaginary such that the solutions for the displacement are purely growing or decaying. The set of eigenfunctions $\boldsymbol{\xi}_{n}$ are complete for square-integrable modes. Singular solutions of (8.213) are exceptions (Laval, Mercier \& Pellat 1965).

We consider the terms in $W$ at second order in the displacement using (8.213) and (8.215),

$$
\begin{align*}
\delta W & \equiv W_{2}(\boldsymbol{\xi}, \boldsymbol{\xi})=-\frac{1}{2} \int \mathrm{~d}^{3} \boldsymbol{x} \boldsymbol{\xi} \cdot \boldsymbol{F}(\boldsymbol{\xi}) \\
& =\int \mathrm{d}^{3} \boldsymbol{x}\left[\frac{\delta \boldsymbol{B}^{2}}{8 \pi}+\frac{1}{2} \delta \boldsymbol{B} \cdot \boldsymbol{J}_{0} \times \boldsymbol{\xi}+\frac{\gamma}{2} p_{0}(\nabla \cdot \boldsymbol{\xi})^{2}+\frac{1}{2}(\nabla \cdot \boldsymbol{\xi})\left(\boldsymbol{\xi} \cdot \nabla p_{0}\right)\right] . \tag{8.220}
\end{align*}
$$

If there is instability, then as the amplitude for $\boldsymbol{\xi}(\boldsymbol{x}, t)$ grows exponentially, $K(t)$ also grows. Recall that $K(t)$ is positive definite. Hence, $W$ must decrease exponentially if there is instability, which implies that $\delta W$ is negative for some $\boldsymbol{\xi}(\boldsymbol{x}, t)$ for instability when $K(t)$ becomes sufficiently large. This conclusion can be turned around to demonstrate stability. Conclusions about stability based on (8.220) and the self-adjointness of the operator $\boldsymbol{F}(\boldsymbol{\xi})$ are the essence of the MHD energy principle.

Theorem. Suppose $W_{2}$ is positive definite for all $\boldsymbol{\xi}(\boldsymbol{x}, t)$, then the system is stable, i.e. $W_{2}(\boldsymbol{\xi}, \boldsymbol{\xi})>0$ is sufficient for stability. We will prove subsequently that this is also a necessary condition.

It is useful to introduce the following definition:
DEFINITION. $K_{2}(\boldsymbol{\xi}) \equiv \int \mathrm{d}^{3} \boldsymbol{x}(1 / 2) \rho_{0}|\boldsymbol{\xi}|^{2}$ (moment of inertia).

## ThEOREM. Virial theorem

$$
\left.\begin{array}{rl}
\dot{K}_{2}(\boldsymbol{\xi}) \equiv & \int \mathrm{d}^{3} \boldsymbol{x} \rho_{0} \dot{\boldsymbol{\xi}} \cdot \boldsymbol{\xi}  \tag{8.221}\\
\ddot{K}_{2}(\boldsymbol{\xi}) \equiv & \int \mathrm{d}^{3} \boldsymbol{x} \rho_{0}|\dot{\boldsymbol{\xi}}|^{2}+\int \mathrm{d}^{3} \boldsymbol{x} \boldsymbol{\xi} \cdot \boldsymbol{F}(\boldsymbol{\xi})=2 K_{2}(\dot{\boldsymbol{\xi}})-2 W_{2}(\boldsymbol{\xi}, \boldsymbol{\xi}) \\
& \rightarrow \quad \frac{1}{2} \ddot{K}_{2}(\boldsymbol{\xi})=K_{2}(\dot{\boldsymbol{\xi}})-W_{2}(\boldsymbol{\xi}, \boldsymbol{\xi})
\end{array}\right\}
$$

EXERCISE. Use the virial theorem to show that without gravity $g$ or an externally applied magnetic field, a plasma cannot be self-contained by its own electromagnetic fields.

Consider a displacement $\boldsymbol{\eta}(\boldsymbol{x})$ such that $W_{2}(\boldsymbol{\eta})<0$ and define $\gamma^{2} \equiv-W_{2}(\boldsymbol{\eta}) / K_{2}(\boldsymbol{\eta})$. Choose initial conditions

$$
\begin{equation*}
\xi(x, t=0)=\eta(x), \quad \dot{\xi}(x, t=0)=\gamma \eta(x) . \tag{8.222}
\end{equation*}
$$

The energy then becomes

$$
\begin{equation*}
U=W_{2}+K_{2}(\dot{\xi})=-\gamma^{2} K_{2}(\boldsymbol{\eta})+\gamma^{2} K_{2}(\boldsymbol{\eta})=0 \tag{8.223}
\end{equation*}
$$

at all times. Thus, if $W_{2}<0$ then $K_{2}>0$ for all time. From the virial theorem (8.221)

$$
\begin{equation*}
\ddot{K}_{2}(\xi)=4 K_{2}(\dot{\xi}) . \tag{8.224}
\end{equation*}
$$

We use the Schwarz inequality $(\boldsymbol{a} \cdot \boldsymbol{b})^{2} \leqslant a^{2} b^{2}$ and generalize to Hilbert space,

$$
\begin{align*}
\left|\dot{K}_{2}\right|^{2} & =\left|\int \mathrm{d}^{3} \boldsymbol{x} \rho_{0} \boldsymbol{\xi}(\boldsymbol{x}) \cdot \dot{\boldsymbol{\xi}}(\boldsymbol{x})\right|^{2} \leqslant\left[\int \mathrm{~d}^{3} \boldsymbol{x} \rho_{0}|\boldsymbol{\xi}(\boldsymbol{x})|^{2}\right]\left[\int \mathrm{d}^{3} \boldsymbol{x} \rho_{0}|\dot{\boldsymbol{\xi}}(\boldsymbol{x})|^{2}\right] \\
& =2 K_{2}(\boldsymbol{\xi}) 2 K_{2}(\dot{\boldsymbol{\xi}}) . \tag{8.225}
\end{align*}
$$

Then using (8.224) and (8.225)

$$
\begin{equation*}
\ddot{K}_{2}(\xi)=4 K_{2}(\dot{\xi}) \geqslant \frac{\left|\dot{K}_{2}(\xi)\right|^{2}}{K_{2}(\xi)} \geqslant 0 \quad \text { and } \quad K_{2}(\xi) \geqslant \frac{\left|\dot{K}_{2}(\xi)\right|^{2}}{4 K_{2}(\dot{\xi})} \geqslant 0 \tag{8.226}
\end{equation*}
$$

We next define $y(t) \equiv \ln \left[K_{2}(\xi) / K_{2}(\boldsymbol{\eta})\right]=2 \gamma(t)$ which removes the spatial dependence of the initial conditions. Given the definition of $y, y(0)=0$ and $\dot{y}(0)=2 \gamma$; and in consequence of $W_{2}<0$ and (8.226), one can show $\ddot{y}>0$ and $K_{2}(\dot{\xi}) \geqslant\left|W_{2}(\boldsymbol{\eta})\right| \mathrm{e}^{2 \gamma t}$ which implies $\gamma^{2}>0$ and the possibility of instability.

THEOREM. If $W_{2}>0$ for all $\boldsymbol{\xi}$, the system is stable; and if $W_{2}<0$, it is possible to find instability for some choice of $\xi$. Because of the energy principle for this system, $W_{2}<0$ is a necessary and sufficient condition for instability.

### 8.3.6. Interchange instability

Perhaps the most basic example of MHD instability is the interchange instability. We begin the analysis of the interchange by introducing a new expansion parameter $\beta \sim p_{0} /\left(B_{0}^{2} / 4 \pi\right) \ll 1$, i.e. we assume a low- $\beta$ plasma. We expand the relevant quantities in powers of $\beta$,

$$
\left.\begin{array}{c}
\boldsymbol{B}_{0}(\boldsymbol{x})=\boldsymbol{B}_{0}^{(0)}(\boldsymbol{x})+\boldsymbol{B}_{0}^{(1)}(\boldsymbol{x})+\cdots  \tag{8.227}\\
\boldsymbol{j}_{0}(\boldsymbol{x})=\boldsymbol{j}_{0}^{(0)}(\boldsymbol{x})+\dot{\boldsymbol{j}}_{0}^{(1)}(\boldsymbol{x})+\cdots \\
p_{0}(\boldsymbol{x})=p_{0}^{(0)}(\boldsymbol{x})+p_{0}^{(1)}(\boldsymbol{x})+\cdots \\
\boldsymbol{\xi}(\boldsymbol{x})=\boldsymbol{\xi}^{(0)}(\boldsymbol{x})+\boldsymbol{\xi}^{(1)}(\boldsymbol{x})+\cdots \\
W_{2}(\boldsymbol{x})=W_{2}^{(0)}(\boldsymbol{x})+W_{2}^{(1)}(\boldsymbol{x})+\cdots .
\end{array}\right\}
$$

In this example we also assume

$$
\begin{equation*}
\nabla \times \boldsymbol{B}_{0}^{(0)}=\frac{4 \pi}{c} \boldsymbol{j}_{0}^{(0)}=0 \tag{8.228}
\end{equation*}
$$

The plasma is contained by a vacuum magnetic field. Consistent with (8.228), $p_{0}^{(0)}=0$ and

$$
\begin{equation*}
W_{2}^{(0)}=\int \mathrm{d}^{3} \boldsymbol{x} \frac{\left|\nabla \times \delta \boldsymbol{B}^{(0)}\right|^{2}}{8 \pi}=\int \mathrm{d}^{3} \boldsymbol{x} \frac{\left|\nabla \times\left(\boldsymbol{\xi}^{(0)} \times \boldsymbol{B}^{(0)}\right)\right|^{2}}{8 \pi} . \tag{8.229}
\end{equation*}
$$

We minimize $W_{2}^{(0)}$ with respect to $\boldsymbol{\xi}^{(0)}$ to zero order by requiring $\delta \boldsymbol{B}^{(0)}=0$. The lowestorder energy is

$$
\begin{equation*}
W^{(0)}=\int \mathrm{d}^{3} \boldsymbol{x} \frac{\left|\boldsymbol{B}^{(0)}\right|^{2}}{8 \pi} \tag{8.230}
\end{equation*}
$$

The zero-order displacement must satisfy $\nabla \times\left(\boldsymbol{\xi}^{(0)} \times \boldsymbol{B}^{(0)}\right)=0$. Hence,

$$
\begin{equation*}
\boldsymbol{\xi}^{(0)} \times \boldsymbol{B}^{(0)}=\nabla \phi_{B} \quad \rightarrow \quad \boldsymbol{B}^{(0)} \cdot \nabla \phi_{B}=0 . \tag{8.231}
\end{equation*}
$$

The first-order $W_{2}^{(1)}$ is then

$$
\begin{equation*}
W_{2}^{(1)}=\frac{1}{2} \int \mathrm{~d}^{3} \boldsymbol{x}\left\{\gamma p_{0}^{(1)}\left|\nabla \cdot \boldsymbol{\xi}^{(0)}\right|^{2}+\left(\boldsymbol{\xi}^{(0)} \cdot \nabla p_{0}^{(1)}\right) \nabla \cdot \boldsymbol{\xi}^{(0)}\right\} . \tag{8.232}
\end{equation*}
$$

Through this order in the $\beta$ expansion we do not need to know $\boldsymbol{\xi}^{(1)}$ or $\boldsymbol{B}_{0}^{(1)}$. Using (8.231) one can express the displacement as

$$
\begin{equation*}
\boldsymbol{\xi}=\frac{\boldsymbol{B}_{0} \times \nabla \phi_{B}(\alpha, \beta)}{B_{0}^{2}}+\xi_{\|} \hat{\boldsymbol{b}}_{0} \tag{8.233}
\end{equation*}
$$

where $\xi_{\|}$is arbitrary. For $\gamma=5 / 3$ then $p /(\gamma-1)=(3 / 2) p \sim(3 / 2) n k_{B} T . W_{2}^{(1)}$ is primarily associated with changes in the thermal energy content in a volume being converted to a macroscopic displacement. However, flux tubes can interchange with no thermal energy exchange in what we call an interchange instability. If there are no topological constraints, then minimization of $W_{2}^{(1)}$ with respect to $\xi_{\|}$yields $\boldsymbol{\nabla} \cdot \boldsymbol{\xi}$ that is not a function of $\sigma$ and is constant along a field line. We examine (8.205) rewritten for the Lagrangian change in the pressure co-moving with the fluid flow

$$
\begin{equation*}
\mathrm{D} p=-\gamma p_{0} \nabla \cdot \boldsymbol{\xi} \tag{8.234}
\end{equation*}
$$

and conclude that $\mathrm{D} p$ is constant along the field line. This removes the possibility of sound waves along the field line, which waves would contradict our hypothesis of virtual slow (adiabatic) displacements of the plasma.

The Eulerian version of (8.234) is

$$
\begin{equation*}
\delta p(\alpha, \beta)=-\gamma p_{0} \nabla \cdot \xi-\xi \cdot \nabla p_{0} . \tag{8.235}
\end{equation*}
$$

Because the magnetic field is a vacuum magnetic field, $\boldsymbol{B}$ can be represented by a gradient of a potential, i.e. $\boldsymbol{B}=\nabla \sigma$ by choice and is convenient. The differential volume element is given by

$$
\left.\begin{array}{c}
\mathrm{d}^{3} \boldsymbol{x}=\frac{\mathrm{d} \alpha \mathrm{~d} \beta \mathrm{~d} \sigma}{B^{2}(\alpha, \beta, \sigma)}=\mathrm{d} \alpha \mathrm{~d} \beta \frac{\mathrm{~d} \ell}{B}  \tag{8.236}\\
h \equiv \frac{\mathrm{~d} \ell}{\mathrm{~d} \sigma}=\text { metric, } \quad \hat{\boldsymbol{b}} \cdot \boldsymbol{B}=\hat{\boldsymbol{b}} \cdot \nabla \sigma, \quad B=\frac{\mathrm{d} \sigma}{\mathrm{~d} \ell}=\frac{1}{h} .
\end{array}\right\}
$$

THEOREM. Using (8.235) and (8.236) in (8.232) one obtains

$$
\begin{align*}
W_{2}^{(1)} & =-\frac{1}{2} \int \mathrm{~d} \alpha \mathrm{~d} \beta(\nabla \cdot \boldsymbol{\xi}) \delta p \int \frac{\mathrm{~d} \sigma}{B^{2}(\alpha, \beta, \sigma)} \\
& =-\frac{1}{2} \int \mathrm{~d} \alpha \mathrm{~d} \beta(\nabla \cdot \boldsymbol{\xi}) \delta p \int \frac{\mathrm{~d} \ell}{B} \tag{8.237}
\end{align*}
$$

The last integral factor on the right-hand side of (8.237) has special significance as the volume per unit flux.

$$
\begin{equation*}
U_{\mathrm{vol}} \equiv \int \frac{\mathrm{~d} \ell}{B}=\int \frac{\mathrm{d}^{3} \boldsymbol{x}}{\mathrm{~d} \alpha \mathrm{~d} \beta}=\int \frac{\mathrm{d}^{3} \boldsymbol{x}}{\mathrm{~d} \Phi_{B}}=\int \frac{\mathrm{dvol}}{\mathrm{dflux}} \tag{8.238}
\end{equation*}
$$



Figure 38. Plasma equilibrium in which the current density and magnetic field lines lie in nested surfaces of constant pressure which are also constant flux surfaces (Howard 2002).

Definition. The specific volume is the volume per unit flux.
Consider pressure surfaces consistent with momentum balance to leading order. We note that $\hat{\boldsymbol{b}} \cdot \nabla p=0$ and $\boldsymbol{j} \cdot \nabla p=0$ as a consequence of the $\boldsymbol{j} \times \boldsymbol{B}$ force balancing the pressure gradient in equilibrium. A three-dimensional plot of the pressure surfaces, the magnetic fields lines, and the currents shows the following. $\boldsymbol{B}$ and $\boldsymbol{j}$ vector fields lie in surfaces of constant $p$ because $\nabla p$ is perpendicular to both $\boldsymbol{B}$ and $\boldsymbol{j} . \boldsymbol{B}$ and $\boldsymbol{j}$ must have some mutually perpendicular components to balance the pressure gradient. Hence, $\boldsymbol{B}$ and $\boldsymbol{j}$ form a cage for the pressure (figure 38). The constant pressure surfaces are also magnetic flux surfaces, i.e. the pressure can be written as a function of the magnetic flux.

Consider two pressure surfaces an infinitesimal apart, the volume contained within the two pressure surfaces, and the magnetic fluxes associated with the two surfaces: $\operatorname{vol}(p)$ and $\Phi_{B}(p)$. In consequence, $\mathrm{dvol} / \mathrm{d} \Phi_{B}$ is a function of the pressure. One can also show that

$$
\begin{equation*}
\int_{\alpha, \beta} \frac{\mathrm{d} \ell}{B}=\left[\int_{\alpha, \beta} \frac{\mathrm{d} \ell}{B}\right]_{\Phi_{B}} \tag{8.239}
\end{equation*}
$$

is a function of the magnetic flux. In guiding-centre theory, the flux surface is also the drift surface. We use (8.237) and (8.238), and cancel factors of $\mathrm{d} \Phi_{B}$ in the numerator and denominator to express the energy $W_{2}^{(1)}$,

$$
\begin{align*}
W_{2}^{(1)}(\boldsymbol{\xi}) & =-\frac{1}{2} \int \mathrm{dvol} \delta p \nabla \cdot \boldsymbol{\xi}=-\frac{1}{2} \int \mathrm{~d} \alpha \mathrm{~d} \beta U_{\mathrm{vol}} \delta p \nabla \cdot \boldsymbol{\xi} \\
& =-\frac{1}{2} \int \mathrm{~d} \alpha \mathrm{~d} \beta \delta p \mathrm{D} U_{\mathrm{vol}}=\int \mathrm{d} \alpha \mathrm{~d} \beta w_{2}^{(1)}(\alpha, \beta) \tag{8.240}
\end{align*}
$$

where $U_{\mathrm{vol}} \equiv \mathrm{dvol} / \mathrm{d} \Phi_{B}$ is the specific volume, $\boldsymbol{\nabla} \cdot \boldsymbol{\xi}=\mathrm{D} U_{\mathrm{vol}} / U_{\mathrm{vol}}$ and

$$
\begin{equation*}
w_{2}^{(1)}(\alpha, \beta) \equiv-\frac{1}{2} \delta p(\alpha, \beta) \mathrm{D} U_{\mathrm{vol}}(\alpha, \beta) \tag{8.241}
\end{equation*}
$$

is the flux surface density of energy for a virtual displacement $\boldsymbol{\xi}$, i.e. the energy per unit flux. We use $\mathrm{D} p \equiv \delta p+\left(\mathrm{d} p / \mathrm{d} \Phi_{B}\right) \mathrm{D} \Phi_{B}$ to express (8.241) as

$$
\begin{equation*}
w_{2}^{(1)}(\alpha, \beta) \equiv-\frac{1}{2}\left(\mathrm{D} p-\frac{\mathrm{d} p}{\mathrm{~d} \Phi_{B}} \mathrm{D} \Phi_{B}\right) \mathrm{D} U_{\mathrm{vol}}(\alpha, \beta) \tag{8.242}
\end{equation*}
$$

Next we use $\mathrm{D} U_{\text {vol }}=\mathrm{d} U_{\text {vol }} / \mathrm{d} \Phi_{B}$, where $\mathrm{d} U_{\mathrm{vol}} / \mathrm{d} \Phi_{B}$ is the derivative of the specific flux volume with respect to the magnetic flux label, and the adiabatic law $\mathrm{D} p / p_{0}=$ $-\gamma\left(\mathrm{D} U_{\mathrm{vol}} / U_{\mathrm{vol}}\right)$ in (8.242) to obtain

$$
\begin{equation*}
w_{2}^{(1)}(\alpha, \beta) \equiv \frac{1}{2}\left(\mathrm{~d} \Phi_{B}\right)^{2}\left(\frac{\mathrm{~d} U_{\mathrm{vol}}}{\mathrm{~d} \Phi_{B}} \frac{\mathrm{~d} p}{\mathrm{~d} \Phi_{B}}+\gamma \frac{p_{0}}{U_{\mathrm{vol}}}\left(\frac{\mathrm{~d} U_{\mathrm{vol}}}{\mathrm{~d} \Phi_{B}}\right)^{2}\right) \tag{8.243}
\end{equation*}
$$

or alternatively,

$$
\begin{equation*}
w_{2}^{(1)}(\alpha, \beta) \equiv \frac{1}{2}\left(\mathrm{~d} \Phi_{B}\right)^{2} \gamma \frac{p_{0}}{U_{\mathrm{vol}}}\left(\frac{\mathrm{~d} U_{\mathrm{vol}}}{\mathrm{~d} \Phi_{B}}\right)^{2}\left(1+\frac{\mathrm{d} p}{\mathrm{~d} U_{\mathrm{vol}}} \frac{U_{\mathrm{vol}}}{\gamma p_{0}}\right) . \tag{8.244}
\end{equation*}
$$

Stability (instability) is determined by $w_{2}^{(1)}>0\left(w_{2}^{(1)}<0\right)$. Hence, the stability condition is

$$
\begin{equation*}
\frac{\mathrm{d} p}{\mathrm{~d} U_{\mathrm{vol}}} \frac{U_{\mathrm{vol}}}{\gamma p_{0}}>-1 \quad \text { or } \quad \frac{\mathrm{d} p}{\mathrm{~d} U_{\mathrm{vol}}}>-\frac{\gamma p_{0}}{U_{\mathrm{vol}}}, \tag{8.245}
\end{equation*}
$$

which is a statement about the configuration and its pressure gradient. For example, consider a typical situation in which

$$
\begin{equation*}
\frac{\mathrm{d} p}{\mathrm{~d} U_{\mathrm{vol}}}=\frac{\mathrm{d} p / \mathrm{d} \Phi_{B}<0}{\mathrm{~d} U_{\mathrm{vol}} / \mathrm{d} \Phi_{B}>0} \rightarrow \frac{\mathrm{~d} p}{\mathrm{~d} U_{\mathrm{vol}}}<0 \tag{8.246}
\end{equation*}
$$

but how large is $\mathrm{d} p / \mathrm{d} U_{\text {vol }}$ compared to $\gamma p / U_{\text {vol }}$ ?
Theorem. A sufficient condition for stability is $\mathrm{d} p / \mathrm{d} U_{\mathrm{vol}}>0$.
Thus, if $p$ decreases with magnetic flux while $U_{\text {vol }}$ also decreases, then moving pressure from higher to lower down the gradient is accompanied by decreasing $U_{\text {vol }}$ with increasing flux. In this case the plasma is stable. If $U_{\text {vol }}$ can increase with increasing flux while the pressure decreases such that perturbations can grow at the expense of cooling under an adiabatic expansion, then the plasma is unstable. Note that $U_{\text {vol }}$ is always positive by definition of the right-hand coordinate system $\alpha, \beta, \sigma$.

The preceding arguments are predicated on considerations of confined plasmas, i.e. plasma pressure in the interior of a configuration with a vacuum magnetic field external to the plasma: $\mathrm{d} p / \mathrm{d} \Phi_{B}<0$; and a sufficient condition for stability is $\mathrm{d} U_{\text {vol }} / \mathrm{d} \Phi_{B}<0$.

DEFInition. $V^{\prime \prime} \equiv \mathrm{d} U_{\text {vol }} / \mathrm{d} \Phi_{B}<0$ for stability. $V^{\prime \prime}$ is a term seen in the MHD stability literature.

Definition. From (8.239)

$$
\begin{equation*}
U_{\mathrm{vol}} \equiv \int_{\alpha, \beta} \frac{\mathrm{d} \ell}{B} \equiv \frac{L}{\langle B\rangle} \tag{8.247}
\end{equation*}
$$

Thus, in a stable confined plasma where the pressure and the volume per unit flux are maximal then $\langle B\rangle$ is minimal. Minimum average $B$ is equivalent to $V^{\prime \prime}<0$ as a sufficient condition for stability and is well established as a constraint in designing low- $\beta$ magnetic confinement experiments.

THEOREM. In sum, $\mathrm{d} p / \mathrm{d} U_{\mathrm{vol}}>0$, minimum average $B$ and $V^{\prime \prime}<0$ are equivalent conditions for stability with respect to interchange modes.
8.3.7. Interpretation of interchange stability theory in magnetically confined plasmas A physical interpretation of the interchange instability can be given as follows.
(i) There can be an unstable expansion of plasma down a pressure gradient into a region of weaker magnetic field accompanied by a reduction in temperature.
(ii) There is a thermodynamic drive for the instability because the plasma is diamagnetic, i.e. the plasma magnetization is oppositely directed to the applied magnetic field, so that the plasma is attracted to weaker fields.
(iii) Field-line curvature can be stabilizing if the field lines are convex relative to the plasma pressure maximum or destabilizing if the field lines are concave relative to the plasma pressure maximum. The field-line curvature vector is $\boldsymbol{\kappa} \equiv \hat{\boldsymbol{b}} \cdot \nabla \hat{\boldsymbol{b}}$ and is perpendicular to $\boldsymbol{B}$. Greene \& Johnson $(1965,1968)$ showed that the drive term in $w_{2}^{(1)}$ can be rewritten as

$$
\begin{equation*}
-\frac{1}{4 \pi} \xi \cdot \nabla p_{0} \xi \cdot \kappa \tag{8.248}
\end{equation*}
$$

When the curvature and the pressure gradient are anti-parallel, this term is positive and is stabilizing. When the pressure gradient has a component that is parallel to the curvature, there can be displacements such that the drive term is negative and destabilizing if the drive term is sufficiently strong enough to render $w_{2}^{(1)}$ negative.
We return to consideration of (8.247). Recall (8.236) and note that $B=\mathrm{d} \sigma / \mathrm{d} l$ so that it follows

$$
\begin{equation*}
U_{\mathrm{vol}}=\int \frac{\mathrm{d} \sigma}{B^{2}} \rightarrow \frac{\partial U_{\mathrm{vol}}}{\partial \alpha}=\frac{\partial}{\partial \alpha} \int \frac{\mathrm{d} \sigma}{B^{2}}=-2 \int \frac{\mathrm{~d} \sigma}{B^{3}} \frac{\partial B}{\partial \alpha} \tag{8.249}
\end{equation*}
$$

However, $\mathrm{d} \Phi_{B}=\mathrm{d} \alpha \mathrm{d} \beta$ and

$$
\begin{equation*}
\alpha=\frac{\Phi_{B}}{2 \pi}=\frac{B \pi r^{2}}{2 \pi}=\frac{1}{2} B r^{2}, \quad \mathrm{~d} \alpha=B r \mathrm{~d} r, \tag{8.250}
\end{equation*}
$$

along a field line if $\beta$ is the azimuthal angle; and $\alpha$ is constant along the field line. In a cylindrical configuration $\partial B / \partial r=B / R$ where $R$ is the radius of curvature of the magnetic field line. Using (8.250) in (8.249) one obtains

$$
\begin{align*}
\frac{\partial U_{\mathrm{vol}}}{\partial \alpha} & =-2 \int \frac{\mathrm{~d} \sigma}{B^{3}} \frac{\partial B}{\partial \alpha}=-2 \int \frac{\mathrm{~d} \sigma}{B^{4}} \frac{\partial B}{r \partial r}=-2 \int \frac{\mathrm{~d} \sigma}{B^{3}} \frac{1}{r R} \\
& =-2 \int \frac{\mathrm{~d} \ell}{B^{2}} \frac{1}{r R}=-\frac{1}{2 \alpha^{2}} \int \frac{\mathrm{~d} \ell r^{3}}{R} . \tag{8.251}
\end{align*}
$$

If the region along the field line where $R<0$ dominates the integral along the field line in (8.251), then the right-hand side of (8.251) is positive and the plasma is unstable. A positive radius of curvature promotes $V^{\prime \prime}<0$ and is stabilizing.
(iv) Consider the plasma drift motion and magnetic shear. There is a strong analogy between Rayleigh-Taylor instability in which a fluid accelerates due to gravity into a region of lower mass density and the expansion of a plasma into a region of decreasing magnetic field strength. If the plasma starts to flute along the field line, the concomitant electric field across the flutes can drive an $\boldsymbol{E} \times \boldsymbol{B}$ drift that enhances the amplitude of the flute perturbations. The positive contribution
to the potential energy in magnetic tension decreases as the plasma expands into a weaker field region with bad curvature. Magnetic shear can provide a topological constraint that can balance this decrease. In cylindrical geometry as the interchange mode displaces radially in a radially sheared magnetic field, the local magnetic pitch angle incurs a change; and the mode sees a differential increase in restoring force due to the bending of the magnetic field line. Hence, magnetic shear has a stabilizing effect (Bateman 1978). An intuitive argument for flute modes in cylindrical geometry yields an order-of-magnitude estimate for stabilization when the magnetic shearing rate satisfies

$$
\begin{equation*}
|\hat{\boldsymbol{r}} \cdot \nabla \theta|>\frac{2 \gamma_{0}}{c_{A}} \tag{8.252}
\end{equation*}
$$

where $\theta$ is the angle of inclination of the magnetic field, $\gamma_{0} \sim c_{s} / L$ is the ideal MHD growth rate in the absence of shear, $L$ is a radial scale length, and $c_{A}$ is the Alfvén speed.
When the plasma pressure is finite and $\beta$ is no longer low, the pressure perturbation contributes a negative term to the energy,

$$
\begin{equation*}
W_{2}=\int \mathrm{d}^{3} \boldsymbol{x}\left[\frac{\delta B^{2}}{8 \pi}-\delta p+\cdots\right] . \tag{8.253}
\end{equation*}
$$

Symbolically, the contribution of finite pressure to the energy is negative and enhances the instability drive. Magnetic shear does not seem to help against ballooning instability when $\beta \sim 1$.
(v) The inclusion of resistivity adds a qualitatively new character to hydrodynamic instability. Ohm's law becomes

$$
\begin{equation*}
\boldsymbol{E}+\frac{1}{c} \boldsymbol{u} \times \boldsymbol{B}=\eta \boldsymbol{j} . \tag{8.254}
\end{equation*}
$$

Faraday's law becomes

$$
\begin{align*}
\frac{\partial \boldsymbol{B}}{\partial t} & =-c \boldsymbol{\nabla} \times \boldsymbol{E}=\boldsymbol{\nabla} \times(\boldsymbol{u} \times \boldsymbol{B}-c \eta \boldsymbol{j}) \\
& =\nabla \times(\boldsymbol{u} \times \boldsymbol{B})-4 \pi \boldsymbol{\nabla} \times(\eta \boldsymbol{\nabla} \times \boldsymbol{B}) . \tag{8.255}
\end{align*}
$$

Now plasma can move across the field lines, and the magnetic field can diffuse. There is a large body of research on resistive MHD stability theory addressing instabilities such as the resistive interchange, resistive ballooning and resistive tearing instabilities.

### 8.3.8. Chew-Goldberger-Low double-adiabatic theory - accommodating a tensor pressure in MHD theory

A tensor pressure can be represented by

$$
\begin{equation*}
\boldsymbol{p}=p_{\|} \hat{\boldsymbol{b}} \hat{\boldsymbol{b}}+p_{\perp}(\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{b}} \hat{\boldsymbol{b}}) \tag{8.256}
\end{equation*}
$$

Chew, Goldberger and Low (CGL) (Chew et al. 1956) derived a fluid model from consideration of the Vlasov equation in the collisionless limit and with certain
assumptions on the heat flow. They calculated the second velocity moment of the Vlasov equation to obtain

$$
\begin{equation*}
\frac{\partial}{\partial t} \boldsymbol{p}=-\nabla \cdot[\boldsymbol{Q}+\boldsymbol{u p}]-(\nabla \boldsymbol{u}+\boldsymbol{u} \overleftarrow{\nabla}) \cdot \boldsymbol{p}+\frac{e}{m c}(\boldsymbol{p} \times \boldsymbol{B}-\boldsymbol{B} \times \boldsymbol{p}) \tag{8.257}
\end{equation*}
$$

where $\boldsymbol{Q}$ is the heat flow,

$$
\begin{equation*}
\boldsymbol{Q}=n m\langle(\boldsymbol{v}-\boldsymbol{u})(\boldsymbol{v}-\boldsymbol{u})(\boldsymbol{v}-\boldsymbol{u})\rangle_{f} \tag{8.258}
\end{equation*}
$$

The parallel and perpendicular components of the time derivative of the pressure tensor $\boldsymbol{p}$ are obtained by operating on (8.257) with $\hat{\boldsymbol{b}} \hat{\boldsymbol{b}}$ and $\overleftrightarrow{\boldsymbol{I}}_{\perp}=(\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{b}} \hat{\boldsymbol{b}})$. In so doing one must represent the heat flow as

$$
\begin{equation*}
\boldsymbol{Q}=Q_{\|} \hat{\boldsymbol{b}} \hat{\boldsymbol{b}} \hat{\boldsymbol{b}}+Q_{\perp}\left(\hat{\boldsymbol{b}} \boldsymbol{I}_{\perp}+\boldsymbol{I}_{\perp} \hat{\boldsymbol{b}}+\hat{\boldsymbol{e}}_{1} \boldsymbol{b} \hat{\boldsymbol{e}}_{1}+\hat{\boldsymbol{e}}_{2} \boldsymbol{b} \hat{\boldsymbol{e}}_{2}\right) \tag{8.259}
\end{equation*}
$$

The analysis leads to the following pair of evolution equations:

$$
\left.\begin{array}{rl}
\frac{\mathrm{D}}{\mathrm{D} t} \ln \left(\frac{p_{\perp}}{\rho B}\right)= & \left(\frac{\partial}{\partial t}+u \cdot \nabla\right) \ln \left(\frac{p_{\perp}}{\rho B}\right)=-\frac{B^{2}}{p_{\perp}} \frac{\partial}{\partial \ell}\left(\frac{Q_{\perp}}{B^{2}}\right)  \tag{8.260}\\
& \frac{\mathrm{D}}{\mathrm{D} t} \ln \left(\frac{p_{\|} B^{2}}{\rho^{3}}\right)=\cdots\left(Q_{\|}\right)
\end{array}\right\}
$$

where $Q_{\perp} \equiv(1 / 2) n m\left\langle v_{\perp}^{2} v_{\|}\right\rangle$and $Q_{\|} \equiv(1 / 2) n m\left\langle v_{\|}^{2} v_{\|}\right\rangle$. CGL assumed that the right-hand sides of (8.260) are negligible, i.e. negligible heat flow. With this assumption there are two adiabatic invariants that advect with the fluid: $p_{\perp} / \rho B$ and $p_{\|} B^{2} / \rho^{3}$.

Example. For $\perp$ compression - consider a compression of the plasma and the magnetic field lines perpendicular to the field that increase $B$ and $\rho$ together. We then note that

$$
\begin{gathered}
p_{\perp}=n m v_{\perp}^{2} / 2=n \mu B, \quad \mu \approx \text { const. } \rightarrow p_{\perp} \propto n B=\frac{\rho}{m} B \propto \rho^{2} \\
\therefore \frac{\mathrm{D}}{\mathrm{D} t}\left(\frac{p_{\perp}}{\rho B} \propto \frac{\rho^{2}}{\rho^{2}}\right)=0, \quad \text { and } \quad p_{\|} \sim n m v_{\|}^{2} \propto \rho \quad \therefore \frac{p_{\|} B^{2}}{\rho^{3}} \propto \frac{\rho \rho^{2}}{\rho^{3}} \sim 1 .
\end{gathered}
$$

Example. Parallel compression - consider a compression of the plasma along the field line but no compression of the magnetic field strength. Then

$$
p_{\perp} \propto \rho, \quad \int p \mathrm{~d} q=v_{\|} L=\text { const. } \rightarrow v_{\|} \propto \frac{1}{L} \propto \rho \rightarrow p_{\|} \sim \rho v_{\|}^{2} \propto \rho^{3} \quad \therefore \frac{p_{\|} B^{2}}{\rho^{3}} \propto \frac{\rho^{3}}{\rho^{3}}=1
$$

An energy theorem like that in $\S \S 8.3 .5$ and 8.3 .6 can be derived with the CGL anisotropic pressure. One begins with the fluid equation of motion

$$
\begin{equation*}
\rho \frac{\mathrm{D} \boldsymbol{u}}{\mathrm{D} t}=-\nabla \cdot\left[p_{\|} \hat{\boldsymbol{b}} \hat{\boldsymbol{b}}+p_{\perp}(\stackrel{\leftrightarrow}{\boldsymbol{I}}-\hat{\boldsymbol{b}} \hat{\boldsymbol{b}})\right]+\frac{1}{c} \boldsymbol{j} \times \boldsymbol{B} \tag{8.261}
\end{equation*}
$$

and linearizes about an equilibrium. The analysis leads to an equation of the form $\rho \ddot{\boldsymbol{\xi}}=\boldsymbol{F}(\boldsymbol{\xi})$. We can again show that the operator $\boldsymbol{F}(\boldsymbol{\xi})$ is self-adjoint. The analysis involved is three times the amount of formalism as for ideal MHD, where the pressure is assumed to be a scalar. The same theorems result, but the formulae are different. We can make comparisons between the CGL and the ideal MHD energy principles (Freidberg 1987).

THEOREM. Comparison theorem - assume $p_{\|}^{0}=p_{\perp}^{0}$ but allow the perturbations to be anisotropic and render the perturbed pressure to be anisotropic in the CGL theory. The dynamics of $\boldsymbol{\xi}(t)$ is very different in the ideal MHD theory from that in the CGL theory. One finds

$$
\begin{equation*}
W_{2}^{\mathrm{CGL}} \geqslant W_{2}^{\mathrm{MHD}} \tag{8.262}
\end{equation*}
$$

Thus, if the energy theorem for ideal MHD stability indicates stability, then CGL theory is certain to predict stability. Similarly, if CGL theory indicates instability, then MHD theory is certain to do so as well. However, $W_{2}^{\text {CGL }}$ is relatively useless because it is so complicated.

THEOREM. Comparison theorem for low- $\beta$ interchange in an axisymmetric system. In ideal MHD with $p_{\|}^{0}=p_{\perp}^{0}=p$ the analysis in $\S 8.3 .6$ can be used to show that the stability condition for interchange is

$$
\begin{equation*}
\int \frac{\mathrm{d} \ell}{B^{2} r R} \frac{\mathrm{~d} p}{\mathrm{~d} \alpha}<0 \quad \text { ideal } M H D \tag{8.263}
\end{equation*}
$$

where $R$ is the radius of curvature and $r$ is the radial distance from the axis of symmetry. Bad curvature (concave field lines facing the plasma) corresponds to $R<0$, while good curvature (convex field lines facing the plasma) corresponds to $R>0$. For anisotropy $p_{\|}^{0} \neq p_{\perp}^{0}$ one can use CGL theory to derive the stability condition for interchange

$$
\begin{equation*}
\int \frac{\mathrm{d} \ell}{B^{2} r R} \frac{\mathrm{~d}\left(p_{\|}^{0}+p_{\perp}^{0}\right)}{\mathrm{d} \alpha}<0 \quad C G L . \tag{8.264}
\end{equation*}
$$

Mirror plasmas are typically anisotropic, and stability of an axisymmetric mirror is difficult to achieve. Recall that $\left(p_{\|}^{0}+p_{\perp}^{0}\right) / R \propto\left(v_{\|}^{2}+(1 / 2) v_{\perp}^{2}\right) / R \sim v_{d}$. Thus, consideration of the guiding-centre drifts can give the stability condition in (8.264) a physical interpretation (Rosenbluth \& Longmire 1957).
8.3.9. Kulsrud and Kruskal-Oberman extensions to the energy principle

In addition to the CGL theory there have been other important extensions of ideal MHD theory leading to energy principles with added physics content. Some prominent examples of these are the works of (Kruskal \& Oberman 1958; Newcomb 1960; Kulsrud 1962, 1968). Kulsrud derives an energy principle starting from a guiding-centre Vlasov equation for the linearly perturbed guiding-centre distribution function $\delta f^{\text {G.C. }}$. With considerable labour Kulsrud shows that the force $\boldsymbol{F}(\boldsymbol{\xi})$ is self-adjoint, and an energy principle is obtained.

THEOREM. Kulsrud demonstrates that the minimum values of the energy satisfy $w_{2}^{\text {CGL }} \geqslant w_{2}^{\text {G.C. }} \geqslant w_{2}^{\mathrm{MHD}}$. Thus, if the system is MHD stable, then guiding-centre and CGL theories also indicate stability. Conversely, if the system is unstable according to CGL theory, then the other two theories also indicate instability. We retire this approach and go to J. B. Taylor's general ordering scheme in the next section (Taylor 1968).
8.3.10. Taylor's guiding-centre theory and Taylor and Hastie's analysis of linear stability
The guiding-centre Vlasov kinetic equation capturing the motion parallel to the magnetic field is

$$
\begin{equation*}
\frac{\partial F}{\partial t}+\dot{\sigma} \frac{\partial F}{\partial \sigma}+\dot{p}_{\sigma} \frac{\partial F}{\partial p_{\sigma}}=0 \tag{8.265}
\end{equation*}
$$

We introduce the expansion $F=F_{0}(H)+\delta F$. The linearized form of (8.265) becomes

$$
\begin{equation*}
\frac{\partial \delta F}{\partial t}+\delta \dot{\sigma} \frac{\partial F_{0}}{\partial \sigma}+\delta \dot{p}_{\sigma} \frac{\partial F_{0}}{\partial p_{\sigma}}+\dot{\sigma} \frac{\partial \delta F}{\partial \sigma}+\dot{p}_{\sigma} \frac{\partial \delta F}{\partial p_{\sigma}}=0 \tag{8.266}
\end{equation*}
$$

where

$$
\left.\begin{array}{c}
H_{\text {G.C. }}=\frac{p_{\sigma}^{2}}{2 m h^{2}}+\mu B+e \chi, \quad \delta H=\mu \delta B+e \delta \chi+\cdots, \quad \delta \dot{\sigma}=\frac{\partial \delta H}{\partial p_{\sigma}}  \tag{8.267}\\
\delta p_{\sigma}=-\frac{\partial \delta H}{\partial \sigma} \sim \delta E_{\|}
\end{array}\right\},
$$

and the guiding-centre drifts excluding the polarization drift are

$$
\begin{equation*}
\dot{\alpha}=-\frac{c}{e} \frac{\partial H}{\partial \beta}, \quad \dot{\beta}=\frac{c}{e} \frac{\partial H}{\partial \alpha} . \tag{8.268}
\end{equation*}
$$

The theory assumes that $u_{\mathrm{L}} \sim O(\varepsilon)$ and time derivatives are similarly ordered so that to lowest order the particles are confined to field lines, which field lines do not change much. The resulting system has two degrees of freedom with slow time dependence. Despite these simplifications there is lengthy mathematics in the theory.

We recall the longitudinal adiabatic invariant derived earlier,

$$
\begin{equation*}
J_{\sigma}=\oint \mathrm{d} \sigma p_{\sigma}(H, \alpha, \beta, \sigma) \tag{8.269}
\end{equation*}
$$

One can show that $\dot{J}_{\sigma}=O(\varepsilon)$ because $\dot{H}, \dot{\alpha}, \dot{\beta} \sim O(\varepsilon)$. Moreover, it was demonstrated earlier that $\left\langle\dot{J}_{\sigma}\right\rangle=O\left(\varepsilon^{2}\right)$ where the average is over a bounce.

THEOREM. $J_{\sigma}$ is effectively invariant on the drift time scale.
Hence, one can construct a bounce-averaged Hamiltonian such that

$$
\begin{equation*}
H\left(J_{\sigma} ; \alpha, \beta\right), \quad \dot{\alpha}=-\left.\frac{c}{e} \frac{\partial H}{\partial \beta}\right|_{\alpha, J_{\sigma}, t}, \quad \dot{\beta}=\left.\frac{c}{e} \frac{\partial H}{\partial \alpha}\right|_{\beta, J_{\sigma}, t}, \quad \dot{J}_{L}=\left.\frac{\partial H}{\partial \theta_{L}}\right|_{\alpha, \beta, t}=0 \tag{8.270}
\end{equation*}
$$

One must use canonical transformations to obtain $H\left(J_{\sigma} ; \alpha, \beta\right)$.
Before continuing with guiding-centre theory, we digress to identify some of the relevant literature and theoretical results. Taylor and Hastie introduced a theory of equilibrium and stability of a small Larmor-radius plasma in general geometry and derived multi-pole dispersion relations for electrostatic modes (Taylor \& Hastie 1968; Hastie \& Taylor 1971). The modes examined satisfy $\omega_{d}, \omega_{b} \sim \omega \ll \Omega$ and allow for $\lambda \sim \rho_{i}$, but with weak scale lengths for the plasma and the magnetic field so that the magnetic moment is conserved. Liu examined the dynamics of the drift equations and
analysed two instabilities excited by temperature gradients (Liu 1969). In all of these guiding-centre theories there is a requirement on the distribution function $F$ in order to do the mathematics one must assume

$$
\begin{equation*}
F_{0}\left(\mu ; \alpha, \beta ; H\left(\sigma, p_{\sigma}\right)\right),\left.\quad \frac{\partial F_{0}}{\partial H}\right|_{\mu, \alpha, \beta}<0 \tag{8.271}
\end{equation*}
$$

This restriction is rather unsatisfactory and limiting. However, there are two relevant and important examples of kinetic microstability in a collisionless Vlasov plasma.

EXAMPLE. A uniform, one-dimensional, unmagnetized plasma, is stable if $f_{0}(H)$ satisfies $\mathrm{d} f_{0} / \mathrm{d} H<0$. If the inequality is reversed then one can get an unstable bump-on-tail mode associated with Landau resonance when the wave phase velocity falls on an interval of $f_{0}$ with positive slope.

EXAMPLE. In a uniform plasma with a uniform applied magnetic field, there is gyroresonance when $\omega-k_{\|} v_{\|}=l \Omega$. Taylor and Hastie show that modes satisfying bounce resonance $\omega=l \omega_{b}(\mu, H)$ are stable if $\partial F_{0} / \partial H<0$ because the waves transfer energy to the particles rather than vice versa with this sign of the derivative of the distribution function.

Given the values of the magnetic moment $\mu$ and the Hamiltonian $H$, the surfaces of constant $J$ in (8.269) contain the drift surfaces. The gradient of $J$ is normal to the drift surfaces,

$$
\begin{equation*}
\left.\nabla J\right|_{\mu, H}=\frac{\partial J}{\partial \alpha} \nabla \alpha+\frac{\partial J}{\partial \beta} \nabla \beta, \tag{8.272}
\end{equation*}
$$

where $\alpha$ and $\beta$ are the Euler potentials. Using the Hamiltonian, one can show after some algebra

$$
\begin{equation*}
\boldsymbol{v}_{d}=\text { const. } \nabla J \times \hat{\boldsymbol{b}} \quad \rightarrow \quad m \boldsymbol{v}_{d} \equiv\left\langle m \boldsymbol{v}_{d}\right\rangle_{b}=\frac{\omega_{b}}{\langle\Omega\rangle_{b}} \nabla J \times \hat{\boldsymbol{b}} \tag{8.273}
\end{equation*}
$$

where the average is over the bounce motion. Recall the derivation of the guidingcentre drifts in $\S 8.2 .2$ and (8.126). Consider the limit $\omega \ll \omega_{b}$; in fact, let $\omega \rightarrow 0$. Freeze the bounce action and magnetic moment, and look just at the guiding-centre drifts. In the $\alpha \beta$ plane there are nested contours of $H(\alpha, \beta)=E$. These surfaces are characterized by constant energy, bounce action and magnetic moment. The parameters of a guiding-centre particle consist of $\mu, J, H$ for a given species (which specification sets the mass and charge). In this zero frequency limit, we will not worry about the drift phase, bounce phase or gyro-phase, because $\dot{\mu}, \dot{J}, \dot{H}$ depend on $\partial / \partial \theta_{d}, \partial / \partial \theta_{b}, \partial / \partial \theta_{g}$. Thus, the density in phase space better not be dependent on the phases else there will be time dependence: thus $F_{0}(\mu, J, H)$. Given the Hamiltonian $H$ we can calculate the magnetic flux:

$$
\begin{equation*}
\oint \alpha \mathrm{d} \beta=\iint \mathrm{d} \alpha \mathrm{~d} \beta=\Phi(H) . \tag{8.274}
\end{equation*}
$$

We can invert (8.274) to obtain $H(\mu, J, \Phi)$. Because of the ignorable phases $\dot{\mu}, \dot{J}, \dot{H}$ all vanish.

Now we relax the constraint of no time dependence and allow for a weak time dependence: $\omega \ll \omega_{b}$ with $\dot{H} \neq 0$ while $\dot{\mu}, \dot{J}, \dot{\Phi}$ are all zero, i.e. flux is conserved; $J$ is conserved over a bounce; and $\mu$ is conserved over a gyration period. There are some options for how to parameterize the particle motion. We consider the following options: $(\mu, J, H),(\mu, J, \Phi),(\mu, H, \Phi)$, and $\left(B_{\text {T.P. }}=H / \mu, H, \Phi\right)$ where $B_{\text {T.P. }}=v^{2} /\left(v_{\perp}^{2} / B\right)$ at the bounce turning point in terms of quantities at the minimum of the magnetic field along the field line. Here, $\mu$ and $H$ can be measured, but $J$ is not immediately measurable. If we know the symmetry of the configuration and thus can describe the flux surface, then $\Phi$ is measurable. Consider $H(\mu, J, \Phi)$ and

$$
\left.\begin{array}{c}
\langle\Omega\rangle_{b, d}=\left\langle\dot{\theta}_{g}\right\rangle_{b, d}=\left.\frac{\partial H}{\partial \mu}\right|_{J, \Phi}, \quad\left\langle\omega_{b}\right\rangle_{d}=\left\langle\dot{\theta}_{b}\right\rangle_{g, d}=\left.\frac{\partial H}{\partial J}\right|_{\mu, \Phi},  \tag{8.275}\\
\omega_{d}=\left\langle\dot{\theta}_{d}\right\rangle_{g, b}=\left.\frac{\partial H}{\partial \Phi}\right|_{\mu, J},
\end{array}\right\}
$$

with fixed $e, m$ and $c$, where the subscripts for the averaging are defined as $g=$ gyro-period, $b=$ bounce period and $d=$ drift period. In more detail we have

$$
\begin{equation*}
H(\mu ; J ; \alpha, \beta ; t), \quad \dot{\beta}=\frac{c}{e} \frac{\partial H}{\partial \alpha}, \quad \dot{\alpha}=-\frac{c}{e} \frac{\partial H}{\partial \beta}, \quad \dot{H}=\frac{\partial H}{\partial t}, \tag{8.276}
\end{equation*}
$$

where $\alpha$ and $\beta$ are Euler potentials for the magnetic field and serve as labels for the magnetic field lines, $\boldsymbol{A}=\alpha \boldsymbol{\nabla} \beta$ and $\boldsymbol{B}=\boldsymbol{\nabla} \times \boldsymbol{A}$; and

$$
\begin{equation*}
H\left(\mu ; \alpha, \beta ; \sigma, p_{\sigma} ; t\right)=\mu B+e \chi+\frac{p_{\sigma}^{2}}{2 m h^{2}} . \tag{8.277}
\end{equation*}
$$

Example. Take $B=B_{0}(\alpha, \beta)\left(1+\left(\sigma^{2} / 2 L^{2}(\alpha, \beta)\right)\right)$, and we choose $\chi=0$ and $h=1$ for simplicity. Hence,

$$
\begin{equation*}
H\left(\mu ; \alpha, \beta ; \sigma, p_{\sigma} ; t\right)=\frac{p_{\sigma}^{2}}{2 m h^{2}}+\mu B_{0}(\alpha, \beta)+\frac{\frac{1}{2} \mu B_{0}(\alpha, \beta)}{L^{2}(\alpha, \beta)} \sigma^{2} \tag{8.278}
\end{equation*}
$$

which has the structure of a harmonic oscillator. From (8.278) we deduce the bounce frequency

$$
\begin{equation*}
\omega_{b}^{2}=\frac{\mu B_{0}(\alpha, \beta)}{m L^{2}(\alpha, \beta)}, \tag{8.279}
\end{equation*}
$$

which is a function of the field-line label. The bounce-averaged action is

$$
\begin{equation*}
J_{b}=\frac{1}{2 \pi} \oint \mathrm{~d} \sigma p_{\sigma}=\frac{H-\mu B_{0}(\alpha, \beta)}{\omega_{b}(\alpha, \beta)}=J(H, \alpha, \beta) . \tag{8.280}
\end{equation*}
$$

With the use of (8.280) and a canonical transformation to action-angle variables we have

$$
\begin{equation*}
H(\mu, J, \alpha, \beta)=\mu B_{0}(\alpha, \beta)+\omega_{b}(\alpha, \beta, \mu) J \tag{8.281}
\end{equation*}
$$

From (8.276) one derives

$$
\begin{equation*}
\dot{\beta}=\frac{c}{e}\left[\mu \frac{\partial B_{0}}{\partial \alpha}+J \frac{\partial \omega_{b}}{\partial \alpha}\right] . \tag{8.282}
\end{equation*}
$$

We now postulate a time-independent equilibrium with no electric potential,

$$
\begin{equation*}
H_{0}(\mu ; J ; \Phi)=H_{0}\left(\sigma, p_{\sigma} ; \alpha, \beta ; \mu\right), \quad \dot{\alpha}=0, \quad \dot{\beta}=\dot{\beta}(\mu, J, \alpha) \tag{8.283}
\end{equation*}
$$

The total Hamiltonian including a linear perturbation due to a small-amplitude electrostatic field is

$$
\begin{equation*}
H=H_{0}\left(\sigma, p_{\sigma} ; \alpha, \beta ; \mu\right)+\delta H=H_{0}\left(\sigma, p_{\sigma} ; \alpha, \beta ; \mu\right)+e \delta \phi(\alpha, \beta, \sigma, t) \tag{8.284}
\end{equation*}
$$

The bounce action is

$$
\left.\begin{array}{rl}
J_{b}= & \frac{1}{2 \pi} \oint \mathrm{~d} \sigma p_{\sigma}=\frac{1}{2 \pi} \oint \mathrm{~d} \sigma \sqrt{2 m(H-\mu B-e \phi)} \\
& \rightarrow \quad 0=\delta J=\frac{1}{2 \pi} \oint \frac{\mathrm{~d} \sigma}{\dot{\sigma}}(\delta H-e \delta \phi) \quad \therefore \delta H=e\langle\delta \phi\rangle_{b}(\alpha, \beta ; \mu, J), \tag{8.285}
\end{array}\right\}
$$

for $\omega \ll \omega_{b}$. The perturbed equations of motion lead to

$$
\begin{equation*}
\dot{\alpha}=-c \frac{\partial\langle\delta \phi\rangle_{b}}{\partial \beta}, \quad \dot{\beta}=\frac{c}{e} \frac{\partial H_{0}}{\partial \alpha}+\cdots=\dot{\beta}_{0}+\delta \dot{\beta} \tag{8.286}
\end{equation*}
$$

The linearized Vlasov equation for the guiding-centre distribution function

$$
\begin{equation*}
F(\mu ; J ; \alpha, \beta ; t)=F_{0}(\mu, J, \alpha)+\delta F(\mu, J, \alpha) \mathrm{e}^{\mathrm{i} \ell \beta-\mathrm{i} \omega t} \tag{8.287}
\end{equation*}
$$

is then

$$
\begin{align*}
\frac{\mathrm{d} F}{\mathrm{~d} t} & =\frac{\partial F}{\partial t}+\dot{\alpha} \frac{\partial F}{\partial \alpha}+\dot{\beta} \frac{\partial F}{\partial \beta}=\frac{\partial \delta F}{\partial t}+\delta \dot{\alpha} \frac{\partial F_{0}}{\partial \alpha}+\dot{\beta}_{0} \frac{\partial \delta F}{\partial \beta} \\
& =-\mathrm{i} \omega \delta F+\delta \dot{\alpha} \frac{\partial F_{0}}{\partial \alpha}+\dot{\beta}_{0} i \ell \delta F . \tag{8.288}
\end{align*}
$$

Hence,

$$
\begin{equation*}
\delta F=\frac{-\delta \dot{\alpha} \frac{\partial F_{0}}{\partial \alpha}}{-\mathrm{i} \omega+\mathrm{i} \ell \dot{\beta}_{0}(\mu, J, \alpha)}=\frac{\mathrm{i} \ell c\langle\delta \phi(\alpha, \sigma)\rangle_{\sigma}^{s} \frac{\partial F_{0}}{\partial \alpha}(\mu, J, \alpha)}{-\mathrm{i} \omega+\mathrm{i} \ell \dot{\beta}_{0}(\mu, J, \alpha)}, \tag{8.289}
\end{equation*}
$$

using

$$
\begin{equation*}
\delta \phi=\delta \phi(\alpha, \sigma) \mathrm{e}^{\mathrm{i} \ell \beta-\mathrm{i} \omega t}, \quad \dot{\alpha}=-c \frac{\partial\langle\delta \phi\rangle_{b}}{\partial \beta} . \tag{8.290}
\end{equation*}
$$

We next construct the density of guiding centres by integrating the distribution function,

$$
\begin{align*}
N(\alpha, \beta, \sigma ; t) & =\int \mathrm{d} \mu \int \mathrm{~d} p_{\sigma} F\left(\alpha, \beta ; \sigma, p_{\sigma} ; \mu ; t\right) \\
& =-\int \mathrm{d} \mu \int p_{\sigma} \mathrm{d} F=-\int \mathrm{d} \mu \int \mathrm{~d} J p_{\sigma} \frac{\partial F}{\partial J} \tag{8.291}
\end{align*}
$$

with an integration by parts. The linearization of (8.291) yields

$$
\begin{equation*}
\delta N(\alpha, \beta, \sigma ; t)=-\int \mathrm{d} \mu \int \mathrm{~d} J\left(\delta p_{\sigma} \frac{\partial F_{0}}{\partial J}+p_{\sigma}^{(0)} \frac{\partial \delta F}{\partial J}\right)_{s}, \tag{8.292}
\end{equation*}
$$

where $p_{\sigma}^{(0)}=\sqrt{2 m\left[H_{0}(\mu, J, \alpha)-\mu B(\alpha, \beta, \sigma)-e \phi^{(0)}(\alpha, \beta, \sigma)\right]}$ and remember the species labels: $\delta N=\sum_{s} \delta N_{s}$. Given that the particle number density is related to the guiding-centre number density by $n=N+O(\rho / \lambda)^{2}$, so $n \approx N$; and the quasi-neutrality condition becomes

$$
\begin{equation*}
\delta N_{e}=\delta N_{i} \tag{8.293}
\end{equation*}
$$

for singly charged ions. The quasi-neutrality condition is equivalent to Poisson's equation for $\rho \ll \lambda$. Using (8.289)-(8.292) to evaluate (8.293), we obtain a messy integral equation for $\delta \phi(\sigma) . \alpha$ is only a parameter, and $\beta$ appears only through $\ell \dot{\beta}_{0}$. Equation (8.293) is an eigenvalue problem subject to the restriction $\omega \ll \omega_{b}$. We note that there is a pole in the $\delta F$ term on the right-hand side of (8.289) that corresponds to the drift resonance: $\omega=\ell \dot{\beta}_{0}$. In the velocity-space integration we use the Landau prescription for the imaginary part of the contribution from the resonance and the principal value for the real part. We cannot directly solve the eigenvalue equation; so we construct a variational principle for it. We remark on the stability characteristics of two types of perturbations.
(i) Perturbations that conserve $\mu, J$ : long-wavelength modes $\lambda \gg r_{\text {gyro }}$ to conserve $\mu$ and low-frequency $\omega \ll \omega_{b}$ to conserve $J$. Taylor and Hastie (Taylor \& Hastie 1968; Hastie \& Taylor 1971) show

$$
\begin{equation*}
\left.\frac{\partial F_{0}}{\partial H}\right|_{\mu, J}<0 \tag{8.294}
\end{equation*}
$$

is sufficient for stability and

$$
\begin{equation*}
\left.\frac{\partial F_{0}}{\partial H}\right|_{\Phi, \mu}<0 \tag{8.295}
\end{equation*}
$$

ensures stability against bounce resonant modes.
Example. In the Earth's radiation belt the electron density increases and then decreases. Which edge of the band is unstable? Do the gradients drive instabilities that can cause the aurora? Consider

$$
\begin{equation*}
\left.\left.\left.\frac{\partial F_{0}}{\partial \Phi}\right|_{\mu, J} \equiv \frac{\partial F_{0}}{\partial H}\right|_{\mu, J} \frac{\partial H}{\partial \Phi}\right|_{\mu, J}, \tag{8.296}
\end{equation*}
$$

where

$$
\begin{equation*}
\left.\frac{\partial H}{\partial \Phi}\right|_{\mu, J}=-\left.\left.\frac{\partial H}{\partial J}\right|_{\mu, \Phi} \frac{\partial J}{\partial \Phi}\right|_{\mu, H},\left.\quad \frac{\partial H}{\partial J}\right|_{\mu, \Phi}=\left\langle\omega_{b}\right\rangle_{d}>0 \tag{8.297}
\end{equation*}
$$

using the properties of a cyclic chain rule. Hence, from (8.294), (8.296) and (8.297) one obtains

$$
\begin{equation*}
\left.\frac{\partial F_{0}}{\partial H}\right|_{\mu, J}<\left.\left.0 \Rightarrow \frac{\partial F_{0}}{\partial \Phi}\right|_{\mu, J} \frac{\partial J}{\partial \Phi}\right|_{\mu, H}>0 \tag{8.298}
\end{equation*}
$$

for stability. By multiplying the last inequality in (8.298) by $\delta \Phi^{2}$ we obtain a corollary to (8.298),

$$
\begin{equation*}
\delta F_{0} \delta J>0, \tag{8.299}
\end{equation*}
$$

for stability. With $\delta \Phi>0$, i.e. moving outward in the magnetosphere, then one wants maximum density where there is a maximum in $J$. This is called 'maximum $J$ stability' in the literature. From the relation

$$
\begin{equation*}
J=\oint \mathrm{d} \sigma \sqrt{H-\mu B} \tag{8.300}
\end{equation*}
$$

$J$ being a maximum in a region of space implies that $B$ is a minimum. Hence,

$$
\begin{equation*}
\frac{\partial J}{\partial \Phi} \left\lvert\, \propto-\left\langle\frac{\partial B}{\partial \Phi}\right\rangle_{b, d}\right. \tag{8.301}
\end{equation*}
$$

TheOrem. Equations (8.298)-(8.301) imply that

$$
\begin{equation*}
\left.\max J \Leftrightarrow \min \langle B\rangle \Leftrightarrow \frac{\partial F_{0}}{\partial H}\right|_{\substack{\Phi, \mu \\ \mu, J}}<0 \tag{8.302}
\end{equation*}
$$

are equivalent stability conditions.
(ii) Perturbations that conserve $\mu$ but violate $J$ conservation: long-wavelength modes $\lambda \gg r_{\text {gyro }}$ to conserve $\mu$ and but with $\omega \gtrsim \omega_{b}$. No general conclusions are reached for arbitrary distribution functions, but for a so-called Taylor distribution function with two degrees of freedom,

$$
\begin{equation*}
F_{0}(\mu, J, \Phi)=F_{0}(\mu, H(J, \Phi)), \tag{8.303}
\end{equation*}
$$

there is a stability condition

$$
\begin{equation*}
\left.\frac{\partial F_{0}}{\partial H}\right|_{\mu}<0 \tag{8.304}
\end{equation*}
$$

The Taylor distribution function is useful for applications to mirror confinement because its dependence on $\mu$ facilitates anisotropy. The species number density for a Taylor distribution is

$$
\left.\begin{array}{rl}
N_{0}^{s}(\alpha, \beta, \sigma) & =\int \mathrm{d} \mu \int \mathrm{~d} p_{\sigma} F_{0}^{s}(\mu, H(\alpha, \beta, \sigma)) \\
& =\int \mathrm{d} \mu \int \frac{\mathrm{~d} H}{\dot{\sigma}} F_{0}^{s}(\mu, H(\alpha, \beta, \sigma))  \tag{8.305}\\
\rightarrow & N_{0}^{s}\left(B_{0}(\alpha, \beta, \sigma)\right)=\int \mathrm{d} \mu \int \frac{\mathrm{~d} H}{\sqrt{H-\mu B_{0}}} F_{0}^{s}(\mu, H)
\end{array}\right\}
$$

In a minimum- $B$ configuration there are nested surfaces of constant density threaded by the magnetic field lines. Iso-field and iso-density surfaces are coincident.
EXERCISE. (i) Show that $p_{\perp}^{s}$ and $p_{\|}^{s}$ are functions of position only through $B$ for the Taylor distribution. (ii) Show that $N_{0}$ increases as $B$ decreases.

Nested magnetic surfaces facilitate good confinement. If there is also minimum average $B$, then there is stability as well. The analysis for perturbations that violate both $\mu$ and $J$ conservation is more complicated (Taylor 1968; Taylor \& Hastie 1968). Returning to consideration of the magnetosphere, with conditions on the inner side of the layer such that $N_{0}$ is increasing as $B$ is decreasing and with minimum average $B$ there is stability. However, on the outer side of the layer with $N_{0}$ decreasing as $B$ is increasing there can be instability. This may be a mechanism for the aurora.

### 8.4. Introduction to the theory of the stability of drift waves

The theory of drift waves has a very large literature. [Editor's note: a good review paper that was published a few years after these lectures is Tang (1978), but this review is now forty years old.] Here we adopt a slab model and a uniform magnetic field $\boldsymbol{B}=B_{0} \hat{z}$. We assume that the equilibrium quantities vary only in $x$. We also assume that the equilibrium electric field vanishes (or we transform to a frame in which the electric field vanishes). The perturbed fields are assumed to be electrostatic here, i.e.

$$
\begin{equation*}
\nabla \times \delta \boldsymbol{E}=0, \quad \delta \boldsymbol{E}=-\nabla \delta \phi, \quad \delta \boldsymbol{B}=0 . \tag{8.306}
\end{equation*}
$$

We further assume $\lambda \gg \rho$ and $\omega \ll \Omega$ so that the magnetic moment is conserved. The equilibrium distribution function is $F_{0}\left(\mu, v_{z}, X\right)$. The linearly perturbed distribution function is $\delta F\left(\mu ; v_{z}, z ; X, Y ; t\right)$. We choose an electric potential perturbation of the form

$$
\begin{equation*}
\delta \phi(X, Y, z ; t)=\delta \phi(X) \mathrm{e}^{-\mathrm{i} \omega t+\mathrm{i} k_{z} z+\mathrm{i} k_{y} Y}, \tag{8.307}
\end{equation*}
$$

and a perturbed distribution function

$$
\begin{equation*}
\delta F=\delta F\left(\mu ; v_{z} ; X\right) \mathrm{e}^{-\mathrm{i} \omega t+\mathrm{i} k_{z} z+\mathrm{i} k_{y} Y} . \tag{8.308}
\end{equation*}
$$

We ignore finite-Larmor-radius (FLR) effects. The distribution function satisfies the collisionless Vlasov equation:

$$
\begin{equation*}
\frac{\mathrm{D}}{\mathrm{D} t} F\left(\mu ; v_{z}, z ; X, Y ; t\right)=\frac{\partial F}{\partial t}+\dot{z} \frac{\partial F}{\partial z}+\dot{v}_{z} \frac{\partial F}{\partial v_{z}}+\dot{X} \frac{\partial F}{\partial X}+\dot{Y} \frac{\partial F}{\partial Y}=0 \tag{8.309}
\end{equation*}
$$

The linearized Vlasov equation is

$$
\begin{align*}
& \frac{\partial \delta F}{\partial t}+v_{z} \frac{\partial \delta F}{\partial z}+\dot{v}_{z} \frac{\partial F_{0}}{\partial v_{z}}+\dot{X} \frac{\partial F_{0}}{\partial X}+\dot{Y} \frac{\partial F_{0}}{\partial Y} \\
& \quad=\frac{\partial \delta F}{\partial t}+v_{z} \frac{\partial \delta F}{\partial z}+\dot{v}_{z} \frac{\partial F_{0}}{\partial v_{z}}+\dot{X} \frac{\partial F_{0}}{\partial X}=0 \tag{8.310}
\end{align*}
$$

with solution

$$
\begin{equation*}
\delta F\left(v_{z}, X, \mu\right)=\frac{e}{m} \frac{\delta \phi}{v_{z}-\frac{\omega}{k_{z}}}\left(\frac{\partial}{\partial v_{z}}+\frac{1}{\Omega} \frac{k_{y}}{k_{z}} \frac{\partial}{\partial x}\right) F_{0}\left(X, v_{z}, \mu\right) \tag{8.311}
\end{equation*}
$$

where $\Omega_{s} \equiv e_{s} B / m_{s} c$ with signs $\left(\Omega_{e}<0\right)$. We note the Landau-type denominator in (8.311). We use the quasi-neutrality condition or Poisson's equation to determine the electric potential self-consistently and to obtain dispersion relations,

$$
\begin{equation*}
n_{s}(x)=\int \mathrm{d} \mu \int \mathrm{~d} v_{z} F_{s}\left(v_{z}, x, \mu\right) \tag{8.312}
\end{equation*}
$$

In (8.312) we have dispensed with the distinction between $x$ and $X$ because we are ignoring FLR effects. The integral in $v_{z}$ in (8.312) will lead to a Hilbert transform and a Landau pole.

## DEFINITION.

$$
\begin{equation*}
Z^{s}\left(V_{z}=\frac{\omega}{k_{z}}, x\right) n_{0}(x) \equiv \int \mathrm{d} \mu \int \mathrm{~d} v_{z} \frac{F_{0}^{s}\left(v_{z}, x, \mu\right)}{v_{z}-V_{z}} \tag{8.313}
\end{equation*}
$$

With the definition in (8.313) the linearized perturbed number density deduced from the velocity-space integral of (8.311) is

$$
\begin{align*}
\delta n^{s}(x) & =\frac{e_{s}}{m_{s}} \delta \phi(x)\left\{n_{0}(x) \frac{\partial}{\partial V_{z}} Z^{s}\left(V_{z}, x\right)+\frac{k_{y}}{k_{z}} \frac{1}{\Omega} \frac{\partial}{\partial x}\left[Z^{s}\left(V_{z}, x\right) n_{0}(x)\right]\right\} \\
& =\frac{e_{s}}{m_{s}} \delta \phi(x)\left\{\frac{\partial}{\partial V_{z}}+\frac{k_{y}}{k_{z}} \frac{1}{\Omega} \frac{\partial}{\partial x}\right\} Z^{s}\left(V_{z}, x\right) n_{0}(x) \tag{8.314}
\end{align*}
$$

If we use (8.314) and invoke quasi-neutrality for $\omega \ll \omega_{p}$ and $\lambda \gg \lambda_{D}, r_{\text {gyro }}, \delta n^{e}(x)=$ $\delta n^{i}(x)$, we obtain a dispersion relation for $\omega\left(k_{z}, k_{y}, x\right)$ for the frequency of a quasimode. This is a WKB-like expression for the local frequency of the quasi-mode. From (8.314) and the quasi-neutrality relation, we can form

$$
\begin{equation*}
\frac{\delta n^{e}(x)}{\delta \phi(x)}=\chi^{e}(x)=\frac{\delta n^{i}(x)}{\delta \phi(x)}=\chi^{i}(x), \tag{8.315}
\end{equation*}
$$

from which we determine a local dispersion relation for $\omega\left(k_{z}, k_{y}, x\right)$. From this local dispersion relation one can deduce the group velocity for wave packets,

$$
\begin{equation*}
\left.\boldsymbol{V}^{g} \equiv \frac{\partial \omega}{\partial \boldsymbol{k}}\right|_{x}=\hat{\boldsymbol{y}} \frac{\partial \omega}{\partial k_{y}}+\hat{z} \frac{\partial \omega}{\partial k_{z}} . \tag{8.316}
\end{equation*}
$$

Thus, the wave packets move in the surface containing the drifts. For shorterwavelength modes there is also a component of the group velocity across the slab in $x$. Corrections to the local dispersion relation and the group velocity are order $\left(k \lambda_{D}\right)^{2} \ll 1$.

Next consider the role of Landau damping. For $v_{\text {th }} \sim V_{z}$ there is strong Landau damping. There are two limiting cases of interest in evaluating the Hilbert transform of a Gaussian unperturbed velocity distribution function.

Example. $v_{\text {th }} \ll V_{z}$ then

$$
Z_{\text {Gaussian }} \rightarrow-\frac{1}{V_{z}}-\frac{v_{\mathrm{th}}^{2}}{V_{z}^{3}}+\cdots, \quad v_{\mathrm{th}}^{2} \equiv\left\langle v_{z}^{2}\right\rangle .
$$

Example. Where $v_{\text {th }} \gg V_{z}$ then

$$
\begin{gathered}
\frac{\partial}{\partial V_{z}} Z_{\text {Gaussian }} \rightarrow-\frac{1}{v_{\text {th }}^{2}}+\mathrm{i} \pi g^{\prime}\left(V_{z}\right) \quad \rightarrow \quad Z_{\text {Gaussian }} \rightarrow O\left(\frac{v_{z}}{v_{\text {th }}^{2}}\right)+\mathrm{i} \pi g\left(V_{z}\right), \\
g=\frac{1}{n_{0}} \int \mathrm{~d} \mu F_{0}, \quad k_{z}>0
\end{gathered}
$$

EXAmple. For $v_{\mathrm{th}, e} \gg V_{z} \gg v_{\mathrm{th}, i}$ then selecting the dominant terms results in the electron response

$$
\left.\begin{array}{rl}
\frac{\delta n_{e}(x)}{n_{0}(x)} & =\frac{e \delta \phi(x)}{T_{e}}, \quad T_{e} \equiv m_{e} v_{\mathrm{th}, e}^{2}  \tag{8.317}\\
& \rightarrow n_{e}(x)=n_{0} \mathrm{e}^{e \phi / T_{e}}
\end{array}\right\}
$$

We note that (8.317) implies that the results of the Vlasov equation agree with the Boltzmann equation including collisions, but this is somewhat of a coincidence and nothing profound. The ion response includes ion inertia, and the quasi-neutrality relation leads to

$$
\begin{equation*}
\omega^{2}-\omega k_{y} u_{*}^{e}(x)=k_{z}^{2} c_{s}^{2}(x), \quad c_{s}^{2}=\frac{T_{e}(x)}{m_{i}}, \quad u_{*}^{e}(x) \equiv-\frac{c T_{e}(x)}{|e| B} \frac{\mathrm{~d}}{\mathrm{~d} x} \ln n_{0}(x) \tag{8.318}
\end{equation*}
$$

where $u_{*}^{e}(x)$ is called the electron diamagnetic flow velocity. One can derive the diamagnetic flow velocity from consideration of force balance on the electrons,

$$
\begin{equation*}
\nabla p_{e}=\frac{1}{c} \boldsymbol{j}^{e} \times \boldsymbol{B} \quad \rightarrow \quad \hat{\boldsymbol{x}} \frac{\mathrm{d}}{\mathrm{~d} x} n T_{e}=-\frac{1}{c} e n \boldsymbol{u}^{e} \times \boldsymbol{B} \quad \rightarrow \quad \boldsymbol{u}^{e}=\cdots . \tag{8.319}
\end{equation*}
$$

The local dispersion relation in (8.318) leads to the following results in specific limits:

$$
\begin{equation*}
\omega= \pm k_{z} c_{s}+\frac{1}{2} k_{y} u_{*}^{e}, \quad\left|k_{z}\right| \rightarrow \infty, \quad \omega \rightarrow 0, k_{y} u_{*}^{e} \quad\left|k_{z}\right| \rightarrow 0 . \tag{8.320}
\end{equation*}
$$

For propagation parallel to $\hat{\boldsymbol{y}}$, in the electron frame moving with $\boldsymbol{u}_{*}^{e}$ the wave has zero frequency, i.e. an electron drift wave. There is no comparable wave carried by the ions. The interpretation is that the pressure gradient accelerates or retards the ion-acoustic wave and morphs it into a drift wave.

Including the Landau resonance effects contributes an imaginary part to $Z$ and $Z^{\prime}$, i.e. $Z=\operatorname{Re} Z+\mathrm{i} \pi g$ and $Z^{\prime}=\operatorname{Re} Z^{\prime}+\mathrm{i} \pi g^{\prime}$. We calculate the growth rates in the limit $v_{\mathrm{th}, e} \gg V_{z} \gg v_{\mathrm{th}, i}$ and using

$$
\begin{equation*}
\varepsilon=\varepsilon_{R}+\mathrm{i} \varepsilon_{I}=0 \quad \rightarrow \quad \gamma \approx-\frac{\varepsilon_{I}}{\frac{\partial \varepsilon_{R}}{\partial \omega}}, \quad \omega \frac{\partial \varepsilon_{R}}{\partial \omega}>0 \tag{8.321}
\end{equation*}
$$

The waves are positive energy. Consider two limits.
(i) Assume $\mathrm{d} T_{e} / \mathrm{d} x \neq 0$ and $u_{z}^{e}=0$ (no current along magnetic field lines). After re-evaluating the local dispersion relation including imaginary parts of the electron response function in the small $k_{\mathrm{z}}$ limit with $V_{z}^{2} \ll 2 v_{e}^{2}$, one obtains

$$
\begin{equation*}
\frac{\gamma}{\omega}=-\sqrt{\frac{\pi}{2}} \frac{V_{z}}{v_{\mathrm{th}, e}}\left\{\frac{1 \mathrm{~d} \ln T_{e}}{2} \frac{V_{z}^{2}}{\mathrm{~d} \ln n}+\frac{1}{2 v_{\mathrm{th}, e}^{2}}\left(1-\frac{1}{2} \frac{\mathrm{~d} \ln T_{e}}{\mathrm{~d} \ln n}\right)\right\} \ll 1, \quad \omega \sim k_{y} u_{*}^{e} . \tag{8.322}
\end{equation*}
$$

Equation (8.322) implies instability for

$$
\begin{equation*}
\frac{\mathrm{d} \ln T_{e}}{\mathrm{~d} \ln n}<0 \quad \rightarrow \quad \gamma>0 \tag{8.323}
\end{equation*}
$$

(ii) Assume $\mathrm{d} T_{e} / \mathrm{d} x=0$ and $u_{z}^{e} \neq 0$. The local dispersion relation yields

$$
\begin{equation*}
\frac{\gamma}{\omega}=\sqrt{\frac{\pi}{2}}\left[\frac{u_{z}^{e}}{v_{\text {th }, e}}-\frac{1}{2}\left(\frac{V_{z}}{v_{\text {th }, e}}\right)^{3}\right] \tag{8.324}
\end{equation*}
$$

and there is instability for

$$
\begin{equation*}
\frac{u_{z}^{e}}{v_{\mathrm{th}, e}}>\frac{1}{2}\left(\frac{V_{z}}{v_{\mathrm{th}, e}}\right)^{3} \rightarrow \gamma>0 . \tag{8.325}
\end{equation*}
$$

When ion Landau damping is included there is a threshold condition

$$
\begin{equation*}
u_{z}^{e}>\frac{m_{e}}{m_{i}} v_{\mathrm{th}, i} . \tag{8.326}
\end{equation*}
$$

This is a very small threshold for the electron flow velocity along the field line to lead to an unstable drift wave propagating across the field lines. There is a significant cancellation of the Landau damping in this limit.

EXERCISE. Derive the results in (8.322)-(8.326).
There are many possible refinements to the theory of drift-wave instability, and there is a large literature (Mikhaĭlovskiŭ 1974; Tang 1978). Some examples of refinements are as follows.
(i) Allow short wavelengths $\lambda \sim \rho_{i}$ and $\dot{\mu}_{i} \neq 0 ; \nabla n \neq 0$ leads to instability.
(ii) Shear in the magnetic field as a function of $x$ moving across the slab is strongly stabilizing due to ion Landau damping.
(iii) Collisions lead to new instabilities.
(iv) Electromagnetic extension $\delta \boldsymbol{B} \neq 0$ leads to new electromagnetic instabilities, e.g. drift-Alfvén waves.
(v) Curvature of the magnetic field lines introduces magnetically trapped particles and new possible instabilities.
(vi) $\nabla_{\perp} B \neq 0$ may lead to new instabilities?
(vii) Higher-frequency modes, e.g. $\omega \sim \Omega_{i}$, allow for gyro-resonance effects and drift cyclotron instability.
(viii) Higher-frequency modes, e.g. $\omega \sim \Omega_{i}$, and a loss-cone distribution can lead to drift-cone instability. Taylor (1968) and Taylor \& Hastie (1968) have examined some of the physics issues in nos. i, ii, v and vi.

We next present an example of how local theory can be extended to a non-local theory from which normal mode frequencies can be calculated. Consider the inclusion of space-charge effects by using Poisson's equation instead of quasi-neutrality,

$$
\begin{equation*}
-\nabla^{2} \delta \phi=-\left(\frac{\mathrm{d}^{2}}{\mathrm{~d} x^{2}}-k_{y}^{2}-k_{z}^{2}\right) \delta \phi=4 \pi e\left(\delta n_{i}-\delta n_{e}\right) \tag{8.327}
\end{equation*}
$$

We construct a WKBJ solution to (8.327) for a pure drift wave $\left(k_{z}=0\right)$,
$\delta \phi(x)=\frac{1}{\sqrt{k_{x}(x)}} \exp \left( \pm \mathrm{i} \int_{x_{i}}^{x} \mathrm{~d} x^{\prime} k_{x}\left(x^{\prime}\right)\right), \quad k_{x}\left(\omega, k_{y}, k_{z}=0, x\right)=k_{D}^{2}(x)\left(\frac{k_{y} u_{*}^{e}}{\omega}-1\right)-k_{y}^{2}$.

Next we use the Bohr-Sommerfeld prescription for calculating normal modes,

$$
\begin{equation*}
\int_{x_{1}}^{x_{2}} \mathrm{~d} x k_{x}\left(\omega, k_{y}, x\right)=\left(\ell+\frac{1}{2}\right) \pi, \quad \ell=0,1,2, \ldots \quad \rightarrow \quad \omega_{\ell}\left(k_{y}, k_{z}=0\right) \tag{8.329}
\end{equation*}
$$

where $x_{1}$ and $x_{2}$ are two turning points: $k_{x}\left(\omega, k_{y}, x_{1,2}\right)=0$ and $\omega_{\ell}\left(k_{y}, k_{z}\right)$ is the normal mode frequency. When the size of the slab is long compared to the typical wavelengths, the set of discretely spaced $\omega_{\ell}$ is so finely spaced as to approach a continuum.
[Editor's note: there is clearly much more that can be said about both drift waves and non-uniform plasmas in general. However, the series of lectures ended at this point.]


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