# Transients and Oscillations in RLC Circuits

Professor Jeff Filippini

Physics 401

Spring 2020



#### Goals of this Lab

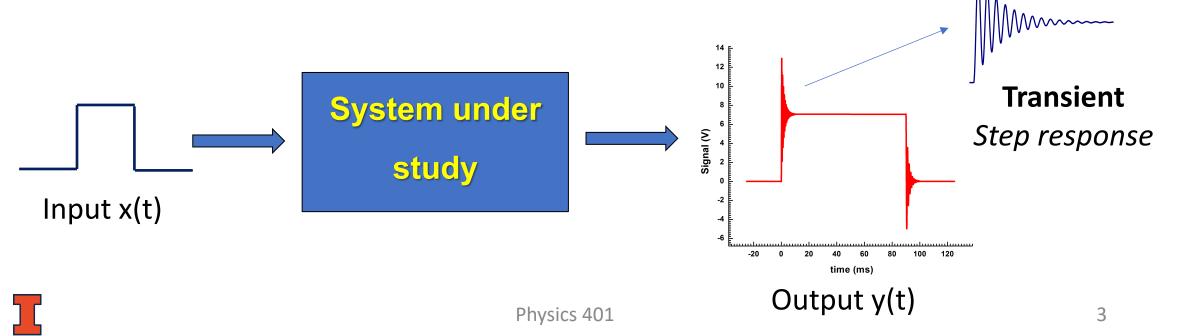
- Concepts: Oscillators in the time domain
  - Transients
  - Resonances
  - Damping regimes

• Implementation: RLC electrical circuits

Data analysis using Origin

#### Driven Systems and Transients

- Consider a **system** that takes an input x(t) and yields output y(t)
  - We'll focus mostly on (approx.) **linear time-invariant (LTI)** systems, governed by constant-coefficient linear homogeneous differential equations
- The transient response of such a system is its ("short-lived") response to a change in input from an equilibrium state
  - Commonly discuss impulse response and step response

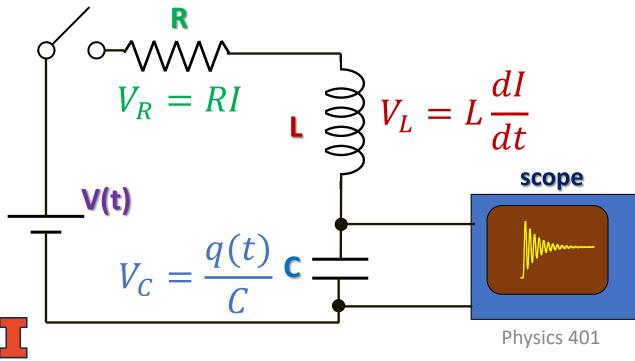


#### From Harmonic Oscillator to RLC Circuit

• A good reference LTI system is a **driven damped harmonic oscillator** 

Inertia 
$$m \frac{d^2 x}{dt^2} + c \frac{dx}{dt} + kx = F(t)$$
 Driving  
Damping force Restoring force

• A useful implementation of this is an RLC circuit



$$V_R + V_L + V_C = V(t)$$
$$L\frac{d^2q}{dt^2} + R\frac{dq}{dt} + \frac{1}{C}q = V(t)$$

M E

Ē

Where...

- q(t) is the charge on the capacitor
- The scope measures  $V_C(t) = \frac{q(t)}{C}$

Damped Oscillation

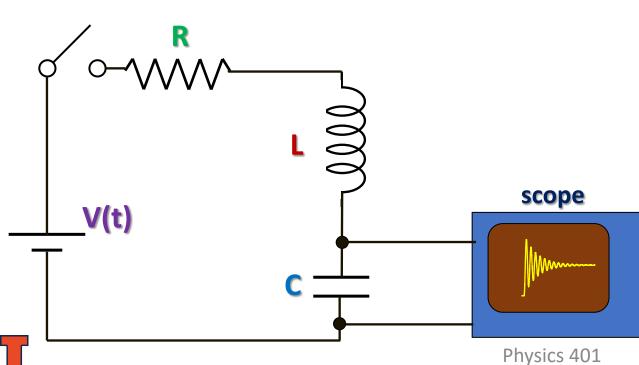
### RLCs in the 401 Lab

- Voltage V V (Volt)
- Resistance R  $\Omega$  (Ohm)
- Inductance L mH (10<sup>-3</sup> Henry)

С

Capacitance

mH (10<sup>-3</sup> Henry μF (10<sup>-6</sup> Farad)





 $L\frac{d^2q}{dt^2} + R\frac{dq}{dt} + \frac{1}{C}q = V(t)$ 

#### RLC Transients: Three Solutions

- What happens after input voltage drops to zero?
- Solutions have the form:  $q(t) = Ae^{st}$

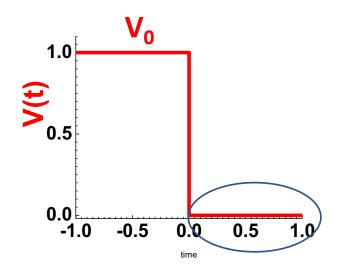
а

• ... with solutions:

 $s_{\pm} =$ 

• This turns our diff. eq. into a quadratic equation:

$$s^2 + \left(\frac{R}{L}\right)s + \frac{1}{LC} = 0$$



b<sup>2</sup>>0: Overdamped b<sup>2</sup>=0: Critically damped Exponential decay

b<sup>2</sup><0: Underdamped Oscillation / ringing

• ... and boundary conditions  $q(0) = CV_0$ ,  $i(0) = \dot{q}(0) = 0$ 

b

 $\left|\frac{R}{2L}\right| \pm \left| \sqrt{\left(\frac{R}{2L}\right)^2 - \left(\frac{1}{LC}\right)} \right| \equiv -a \pm b$ 

#### RLC Transients: Over-Damped Solutions

- $b^2 > 0$  ( $R^2 > \frac{4L}{C}$ ): aperiodic exponential decay
- Solutions have the form:

$$q(t) = e^{-at} (A_1 e^{bt} + A_2 e^{-bt})$$
  
i(t) =  $\dot{q}(t) = -ae^{-at} (A_1 e^{bt} + A_2 e^{-bt}) + be^{-at} (A_1 e^{bt} - A_2 e^{-bt})$ 

• Applying boundary conditions  $q(0) = CV_0$ ,  $i(0) = \dot{q}(0) = 0$ 

$$q(t) = q(0)e^{-at}(\cosh bt + \sinh bt)$$
$$q(t) \xrightarrow[(a-b)t]{} \frac{q(0)}{2} \left(1 + \frac{a}{b}\right)e^{-(a-b)t}$$



#### **RLC Transients: Critical Damping**

- $b^2=0$  ( $R^2 = \frac{4L}{C}$ ): fastest possible exponential decay
- Solutions have the form:

$$q(t) = e^{-at}(A_1 + A_2 t)$$
  
i(t) =  $\dot{q}(t) = -ae^{-at}(A_1 + A_2 t) + A_2 e^{-at}$ 

• Applying boundary conditions  $q(0) = CV_0$ ,  $i(0) = \dot{q}(0) = 0$ 

$$q(t) = q(0)e^{-at}(1 + at)$$
  
$$i(t) = -a^2q(0)te^{-at}$$



#### Ex: Real Data Analysis for Critical Damping

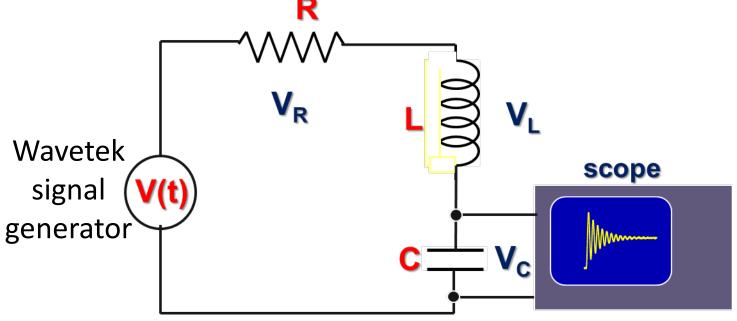
In this experiment:

- R = 300 ohm
- $C = 1 \mu F$
- L = 33.43 mH

... plus practical reality:

- Wavetek has 50 ohm  $\bullet$ output resistance
- Inductor coil has 8.7 ohm measured R

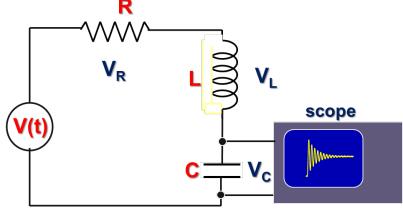
=> Loop R<sub>tot</sub> = 358.7 ohm



**Decay coefficient**  $a = \frac{R_{tot}}{2L} = \frac{358.7}{2*33.43 \times 10^{-3}} \approx 5365 \, s^{-1} \approx \frac{1}{0.2 \, ms}$ 



## Ex: Real Data Analysis for Critical Damping

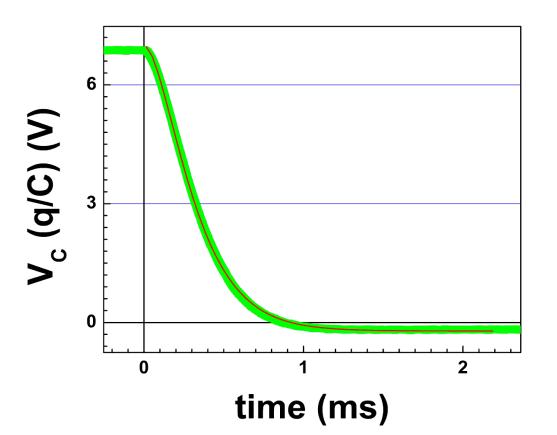


Delay coefficient:

- Calculated: a=5385 s<sup>-1</sup>
- Fitted: a= 5820 s<sup>-1</sup> (+8%)

Possible cause for discrepancy? Perhaps slightly overdamped? Calculated b<sup>2</sup> = 2.99e7 - 2.90e7 > 0

Fitting function for measured  $V_C \propto q$ :  $V_C = V_{c0}(1 + at)e^{-at}$ 



#### RLC Transients: Underdamped Case

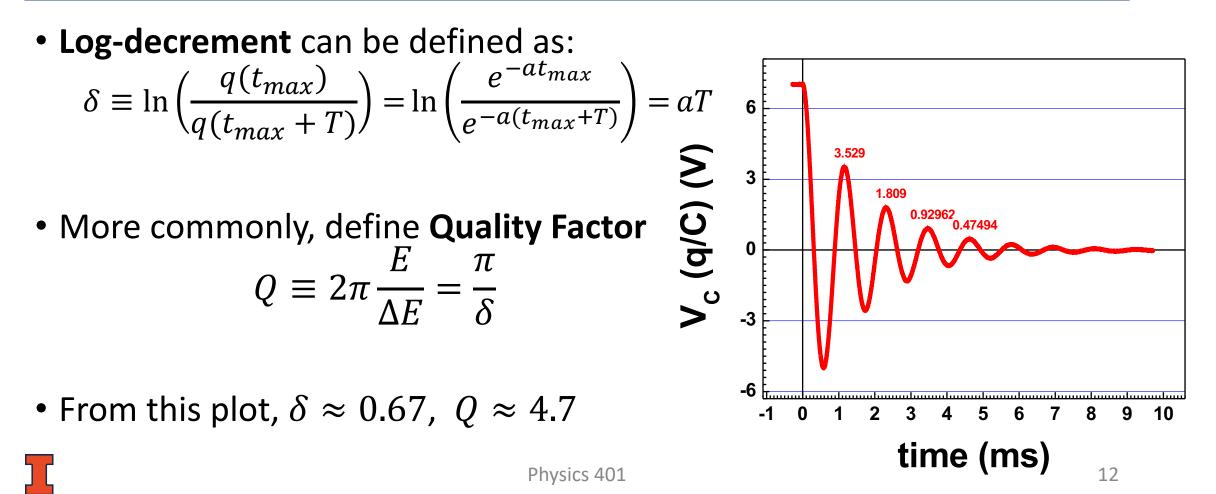
- $b^2 < 0$  ( $R^2 < \frac{4L}{C}$ ): decaying oscillation
- Solutions (*see write-up!*):

$$q(t) = q(0)e^{-at}\sqrt{1 - \frac{a^2}{\omega^2}}\sin(\omega t + \varphi)$$
$$i(t) = q(0)e^{-at}\left(\frac{a^2 - \omega^2}{\omega}\right)\sin\omega t$$
$$a = \frac{R}{2L}; \ \omega = 2\pi f = \sqrt{\left(\frac{1}{LC}\right) - \left(\frac{R}{2L}\right)^2}$$

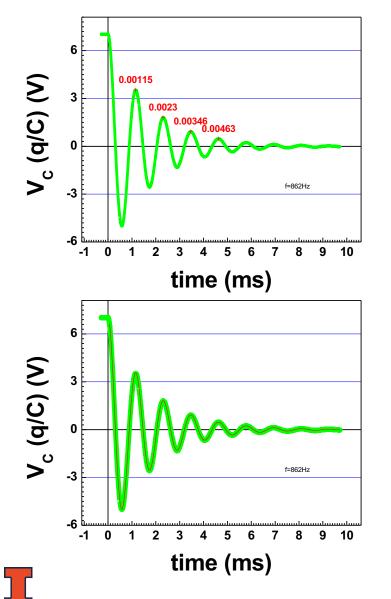


#### Quantifying Damping

**General idea**: How many *oscillation periods* ( $T \equiv 1/f$ ) does it take for the *oscillation amplitude* to decay "substantially"?



#### Analysis Using Origin



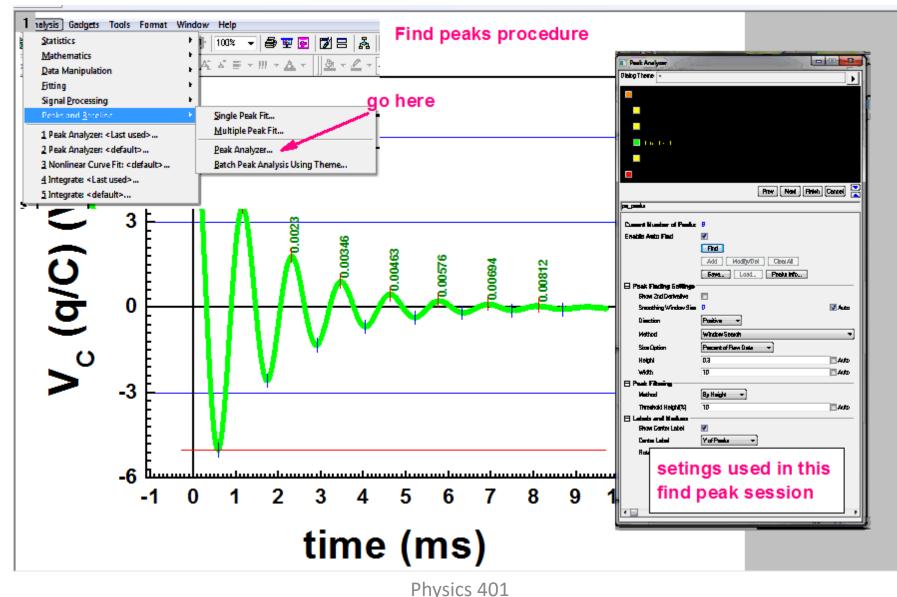
Keep in mind:

- Fitting multi-parameter **linear** models to data is generally pretty robust
- Fitting non-linear models to data is all about making good initial guesses

Practical procedure:

- 1. Identify peaks
- 2. Fit "envelope"
- 3. Perform nonlinear fit

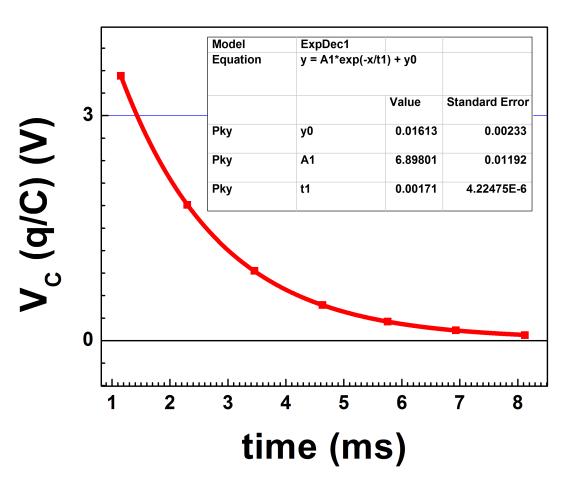
#### Analysis Using Origin: Identify Peaks

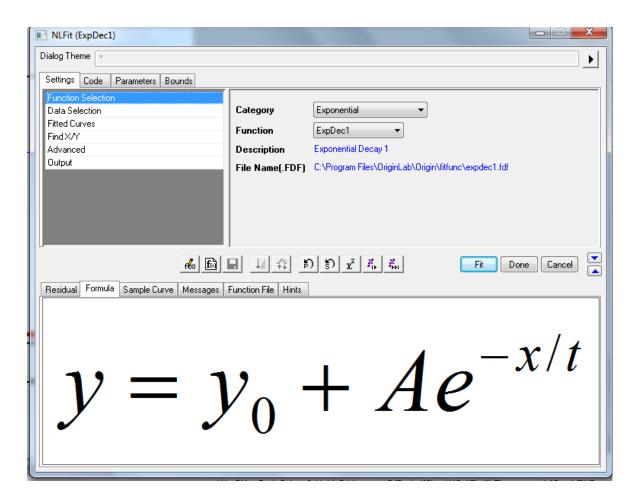


Analysis Using Origin: Fit Decay Envelope **Points found using "Find Peaks" Time-domain trace** V<sub>c</sub> (q/C) (V **Envelope curve** time (ms)

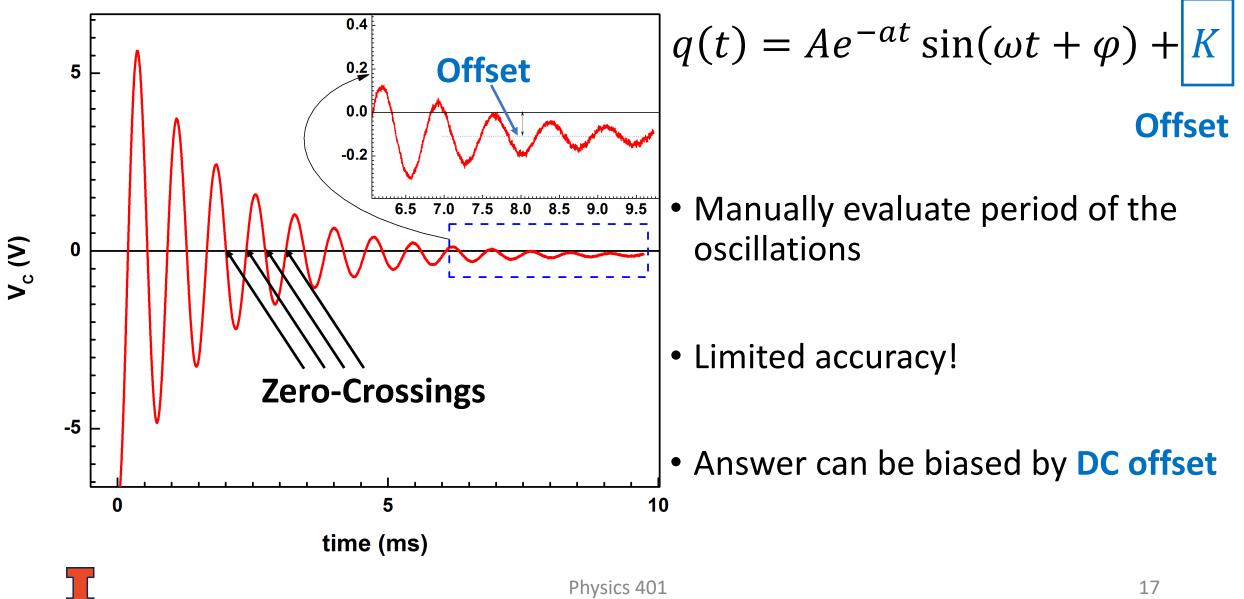


#### Analysis Using Origin: Fit Decay Envelope





#### Analysis Using Origin: Periods and Offsets



#### Analysis Using Origin: Non-Linear Fit

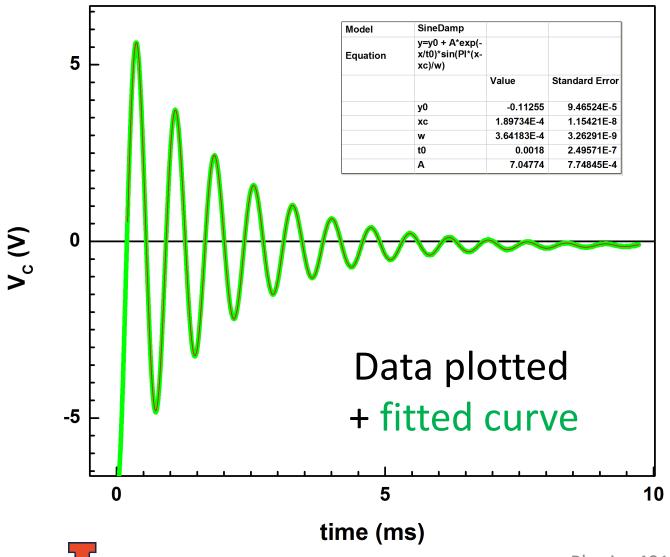
NLFit (SineDamp)				
[	Dialog Theme 🛛 ×			
1	Settings Code Parameters Bounds			
	Function Selection			
	Data Selection C	ategory	Waveform 🔹	
	Fitted Curves	unction	SineDamp 👻	
	Find X/Y		sine damp function	
	Output	escription		
	Fi	ile Name(.FDF)	C:\Program Files\OriginLab\Origin\fitfunc\sinedamp.fdf	
ľ	)			
$\mathcal{H}_0$ $\mathbb{H}$ $\mathbb{H}$ $\mathcal{H}$ $\mathcal{P}$ $\mathcal{P}$ $\mathcal{X}$ $\mathcal{Y}$ $\mathcal{X}$ $\mathcal{X}$ $\mathcal{Y}$ $\mathcal{X}$ $\mathcal{X}$ $\mathcal{X}$ $\mathcal{X}$ $\mathcal{X}$ $\mathcal{Y}$ $\mathcal{X}$				
Residual Formula Sample Curve Messages Function File Hints				
	$y = y0 + Ae^{-\frac{x}{t_0}} \sin\left(\pi \frac{x - xc}{x}\right)$			
	$1  1  t_0  t_$			
	$V = V \mathbf{U}$	+ AC	$\sim$ SIII $\pi$ — [	
	~ ~		142	
Offset				

$$q(t) = Ae^{-at} \sin(\omega t + \varphi)$$
$$U_{C}(t) = \frac{q(t)}{C}$$

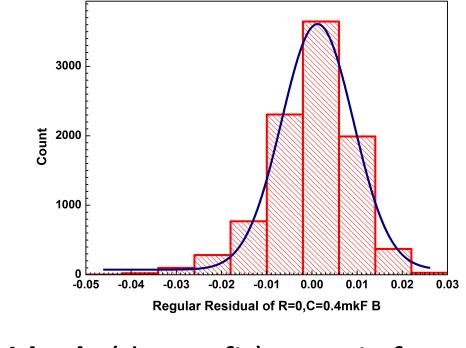
- Use Origin standard function
  - Category: Waveform
  - Function: SineDamp
- Fit parameters: y<sub>0</sub>, A, t<sub>0</sub>, x<sub>c</sub>, w

• From fit we can obtain:  
$$a = \frac{1}{t_0}; T = \frac{1}{f} = 2w$$

#### Analysis Using Origin: Evaluating the Fit

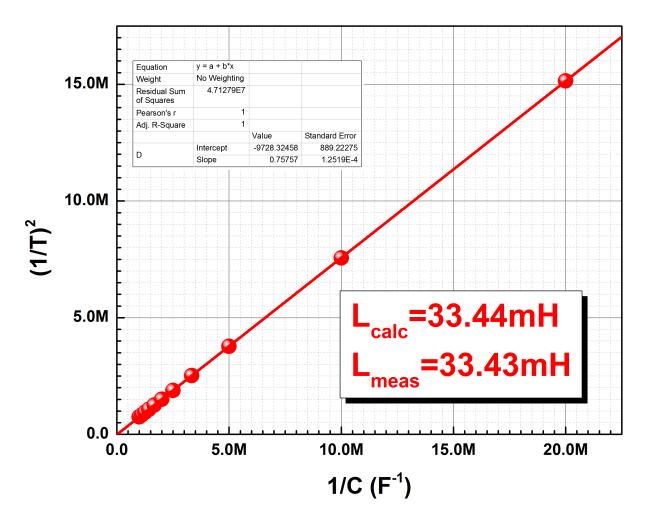


 $q(t) = Ae^{-at}\sin(\omega t + \varphi)$ 



## **Residuals** (data – fit): metric for quality of fit

#### Analysis Using Origin: Interpreting Results



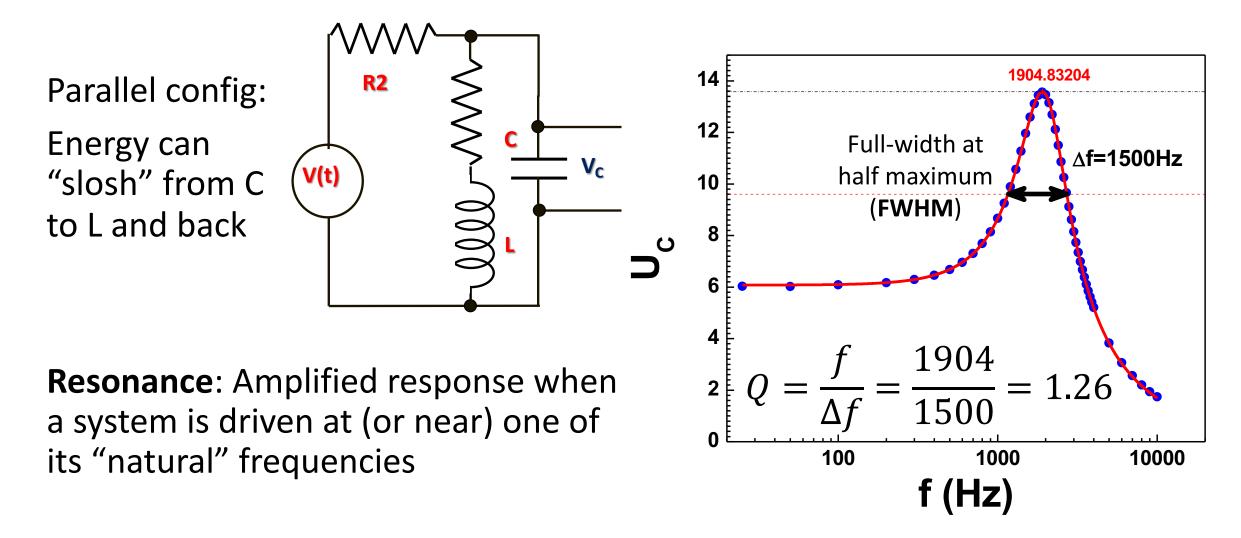
$$q(t) = Ae^{-at}\sin(\omega t + \varphi)$$

$$\boldsymbol{f}^{2} = \left(\frac{1}{\boldsymbol{T}}\right)^{2} = \left(\frac{1}{2\pi}\right)^{2} \left(\left(\frac{1}{\boldsymbol{L}\boldsymbol{C}}\right) - \left(\frac{\boldsymbol{R}}{2\boldsymbol{L}}\right)^{2}\right)$$

#### **Final Results**

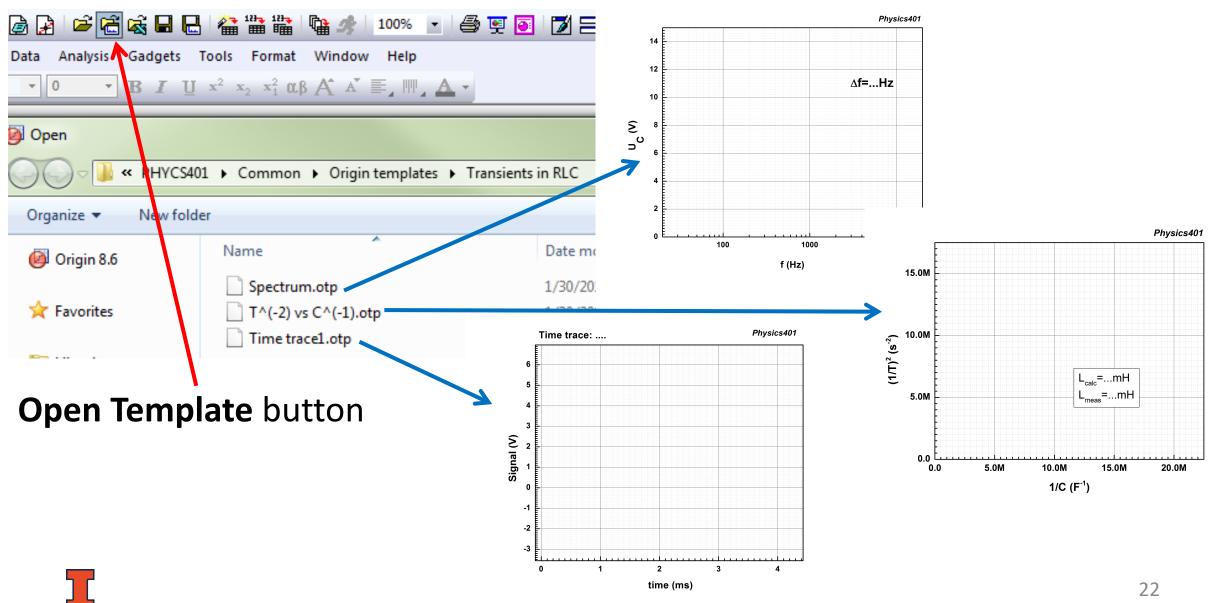
*Not* the fit itself, but constraints on the physical model parameters!

#### Foreshadowing: Resonance in RLC Circuits





#### Origin Templates for This Week's Lab



#### Origin Manuals



Working with Origin 8.6.

Step1. Importing data



Short, simple manual covering only basic operations with Origin (*linked from <u>P401 webpage</u>*)

#### Don't forget about Origin help!

# Video tutorial library on company website



