

Chapter 1

Units, Physical Quantities, and Vectors

PowerPoint® Lectures for
University Physics, Thirteenth Edition
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Lectures by Wayne Anderson

Goals for Chapter 1

- To learn three fundamental quantities of physics and the units to measure them
- To understand vectors and scalars and how to add vectors graphically
- To determine vector components and how to use them in calculations
- To understand unit vectors and how to use them with components to describe vectors
- To learn two ways of multiplying vectors

The nature of physics

- Physics is an *experimental* science in which physicists seek patterns that relate the phenomena of nature.
- The patterns are called *physical theories*.
- A very well established or widely used theory is called a *physical law* or *principle*.

Physics

Divided into five major areas

- Classical Mechanics
- Relativity
- Thermodynamics
- Electromagnetism
- Optics
- Quantum Mechanics

Standards and units

- Length, time, and mass are three *fundamental* quantities of physics.
- The *International System* (SI for *Système International*) is the most widely used system of units.
- In SI units, length is measured in *meters*, time in *seconds*, and mass in *kilograms*.

Fundamental Quantities and Their Units

Quantity	SI Unit
Length	meter
Mass	kilogram
Time	second
Temperature	Kelvin
Electric Current	Ampere
Luminous Intensity	Candela
Amount of Substance	mole

Unit prefixes

- Table 1.1 shows some larger and smaller units for the fundamental quantities.

Table 1.1 Some Units of Length, Mass, and Time

Length	Mass	Time
1 nanometer = 1 nm = 10^{-9} m (a few times the size of the largest atom)	1 microgram = 1 μ g = 10^{-6} g = 10^{-9} kg (mass of a very small dust particle)	1 nanosecond = 1 ns = 10^{-9} s (time for light to travel 0.3 m)
1 micrometer = 1 μ m = 10^{-6} m (size of some bacteria and living cells)	1 milligram = 1 mg = 10^{-3} g = 10^{-6} kg (mass of a grain of salt)	1 microsecond = 1 μ s = 10^{-6} s (time for space station to move 8 mm)
1 millimeter = 1 mm = 10^{-3} m (diameter of the point of a ballpoint pen)	1 gram = 1 g = 10^{-3} kg (mass of a paper clip)	1 millisecond = 1 ms = 10^{-3} s (time for sound to travel 0.35 m)
1 centimeter = 1 cm = 10^{-2} m (diameter of your little finger)		
1 kilometer = 1 km = 10^3 m (a 10-minute walk)		

Prefixes, cont.

TABLE 1.4

Prefixes for Powers of Ten

Power	Prefix	Abbreviation	Power	Prefix	Abbreviation
10^{-24}	yocto	y	10^3	kilo	k
10^{-21}	zepto	z	10^6	mega	M
10^{-18}	atto	a	10^9	giga	G
10^{-15}	femto	f	10^{12}	tera	T
10^{-12}	pico	p	10^{15}	peta	P
10^{-9}	nano	n	10^{18}	exa	E
10^{-6}	micro	μ	10^{21}	zetta	Z
10^{-3}	milli	m	10^{24}	yotta	Y
10^{-2}	centi	c			
10^{-1}	deci	d			

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Unit consistency and conversions

- An equation must be *dimensionally consistent*. Terms to be added or equated must *always* have the same units. (Be sure you're adding “apples to apples.”)
- Always carry units through calculations.
- Convert to standard units as necessary.

Conversion – Ex.1

- Express 200 cubic feet in cubic meters:

$$1ft = 0.305 m$$

$$200 \text{ ft}^3 = 200 \times \frac{(0.305 \text{ m})^3}{(1ft)^3} = 5.67 \text{ m}^3$$

- Express 75 mi/h in m/s

$$1 \text{ mi} = 1609 \text{ m} \quad 1 \text{ h} = 3600 \text{ s}$$

$$75.0 \frac{\text{mi}}{\text{h}} \times \frac{1609 \text{ m}}{1 \text{ mi}} \times \frac{1 \text{ h}}{3600 \text{ s}} = 33.5 \text{ m/s}$$

Uncertainty and significant figures—Figure 1.7

- The uncertainty of a measured quantity is indicated by its number of *significant figures*.
- For multiplication and division, the answer can have no more significant figures than the *smallest* number of significant figures in the factors.
- For addition and subtraction, the number of significant figures is determined by the term having the fewest digits to the right of the decimal point.
- As this train mishap illustrates, even a small percent error can have spectacular results!



Estimates and orders of magnitude

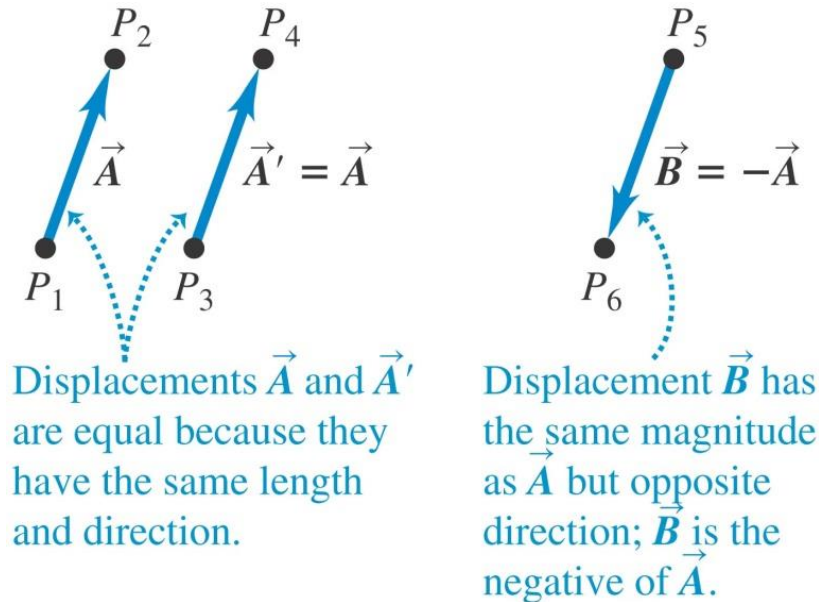
- An *order-of-magnitude estimate* of a quantity gives a rough idea of its magnitude.

Vectors and scalars

- A *scalar quantity* can be described by a *single number*.
- A *vector quantity* has both a *magnitude* and a *direction* in space.
- In this book, a vector quantity is represented in boldface italic type with an arrow over it: \vec{A} .
- The magnitude of \vec{A} is written as A or $|\vec{A}|$.

Drawing vectors—Figure 1.10

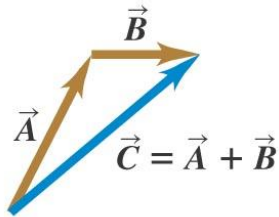
- Draw a vector as a line with an arrowhead at its tip.
- The *length* of the line shows the vector's *magnitude*.
- The *direction* of the line shows the vector's *direction*.



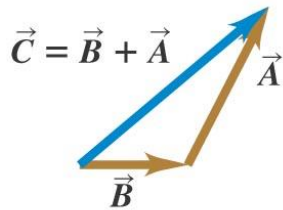
Adding two vectors graphically

- Two vectors may be added graphically using either the *parallelogram* method or the *head-to-tail* method.

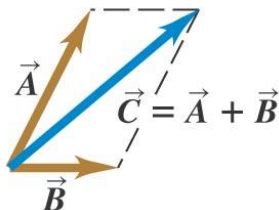
(a) We can add two vectors by placing them head to tail.



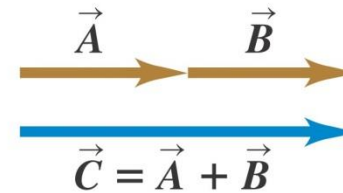
(b) Adding them in reverse order gives the same result.



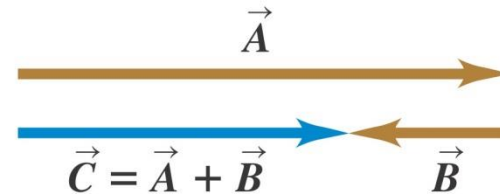
(c) We can also add them by constructing a parallelogram.



(a) The sum of two parallel vectors



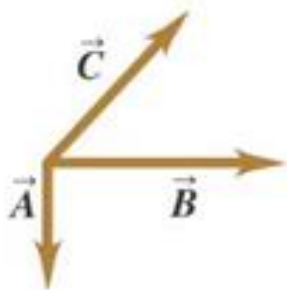
(b) The sum of two antiparallel vectors



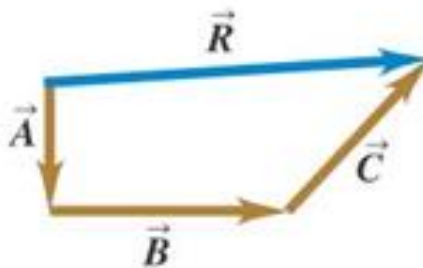
Adding more than two vectors graphically—

- To add several vectors, use the head-to-tail method.
- The vectors can be added in any order.

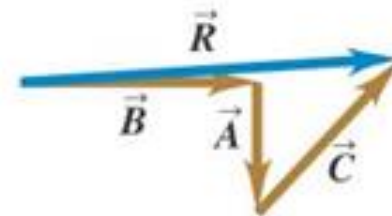
(a) To find the sum of these three vectors ...



(b) we could add \vec{A} , \vec{B} , and \vec{C} to get \vec{R}



(c) or we could add \vec{A} , \vec{B} , and \vec{C} in any other order and still get \vec{R} .



Negative of a Vector

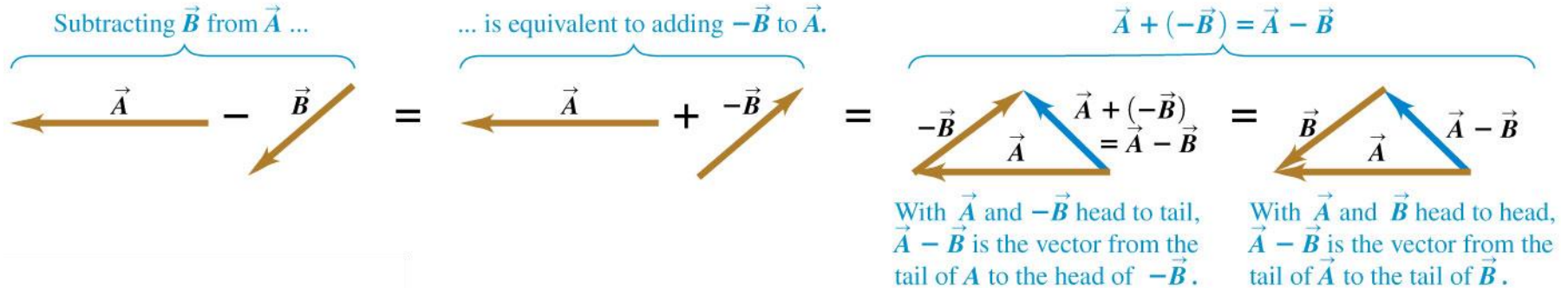
The negative of a vector is defined as the vector that, when added to the original vector, gives a resultant of zero

- Represented as $-\vec{\mathbf{A}}$
- $\vec{\mathbf{A}} + (-\vec{\mathbf{A}}) = 0$

The negative of the vector will have the same magnitude, but point in the opposite direction

Subtracting vectors

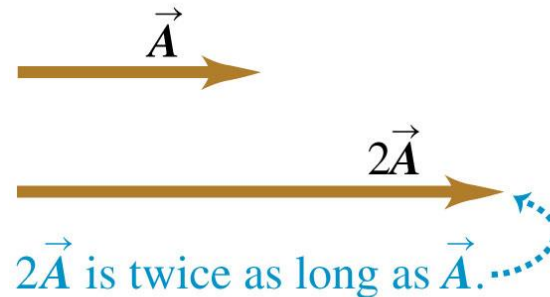
- Figure shows how to subtract vectors.



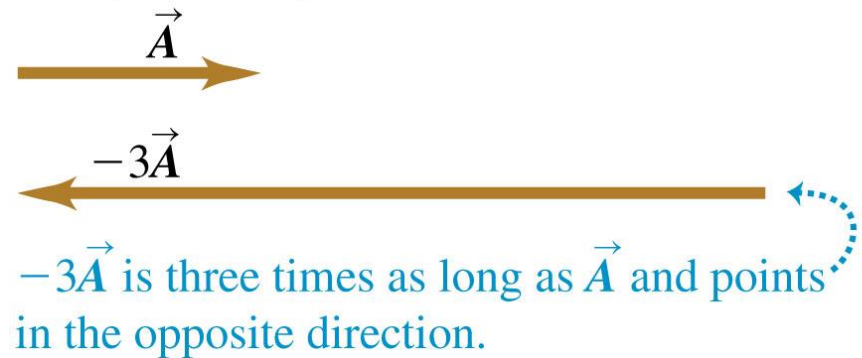
Multiplying a vector by a scalar

- If c is a scalar, the product $c\vec{A}$ has magnitude $|c|A$.
- Multiplication of a vector by a positive scalar and a negative scalar.

(a) Multiplying a vector by a positive scalar changes the magnitude (length) of the vector, but not its direction.

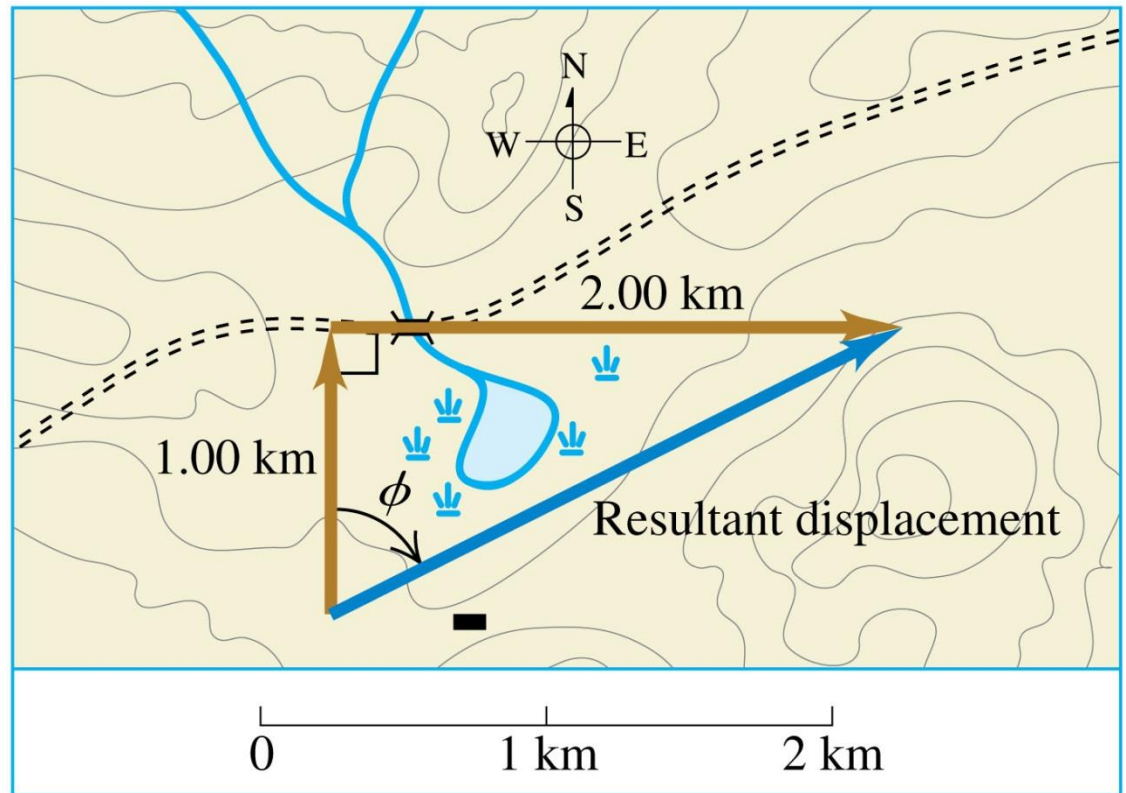


(b) Multiplying a vector by a negative scalar changes its magnitude and reverses its direction.



Addition of two vectors at right angles

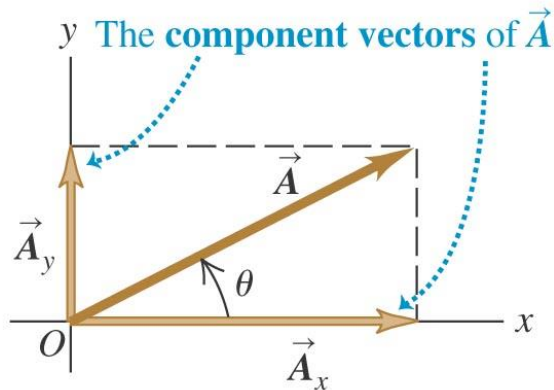
- First add the vectors graphically.
- Then use trigonometry to find the magnitude and direction of the sum:
sum: $R = \sqrt{1 \text{ km}^2 + 2 \text{ km}^2} = 2.2 \text{ km}$



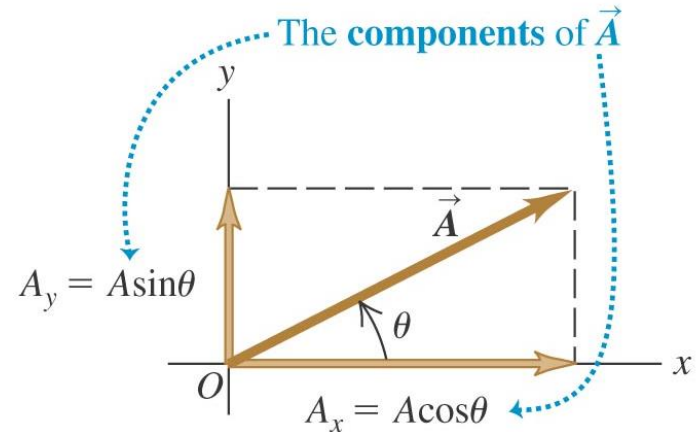
Components of a vector—

- Adding vectors graphically provides limited accuracy. Vector components provide a general method for adding vectors.
- Any vector can be represented by an x -component A_x and a y -component A_y .
- Use trigonometry to find the components of a vector: $A_x = A \cos \theta$ and $A_y = A \sin \theta$, where θ is measured from the $+x$ -axis toward the $+y$ -axis.

(a)



(b)



Components of a Vector

The x-component of a vector is the projection along the x-axis

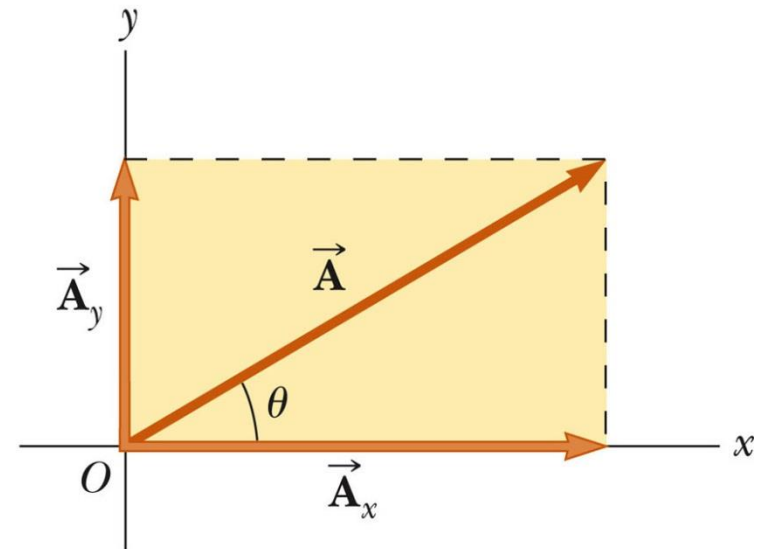
$$A_x = A \cos \theta$$

The y-component of a vector is the projection along the y-axis

$$A_y = A \sin \theta$$

This assumes the angle θ is measured with respect to the positive direction of x-axis

- If not, do not use these equations, use the sides of the triangle directly



(a)

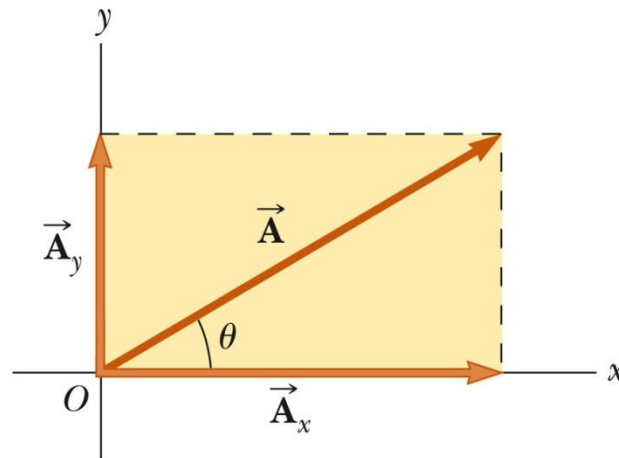
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Components of a Vector, 4

The components are the legs of the right triangle whose hypotenuse is the length of A

$$A = \sqrt{A_x^2 + A_y^2} \quad \text{and} \quad \theta = \tan^{-1} \frac{A_y}{A_x}$$

- May still have to find θ with respect to the positive x -axis



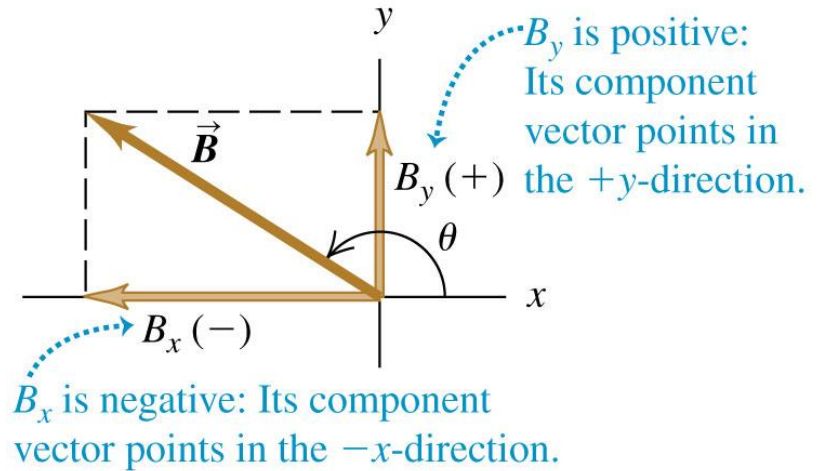
(a)

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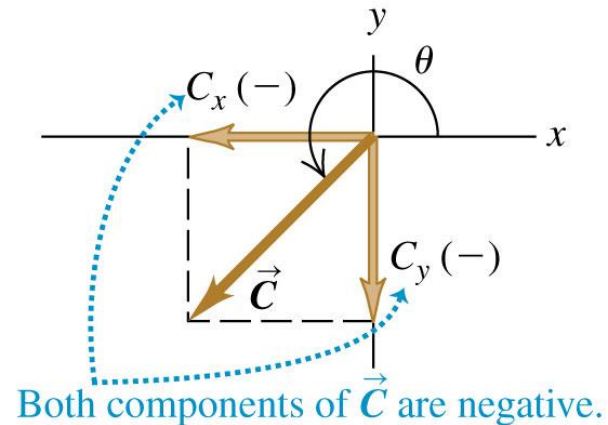
Positive and negative components—Figure 1.18

- The components of a vector can be positive or negative numbers, as shown in the figure.

(a)

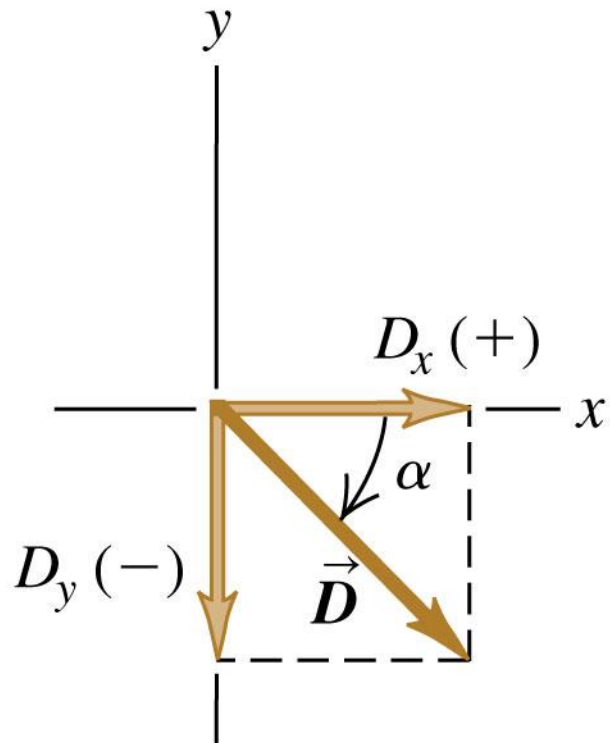


(b)

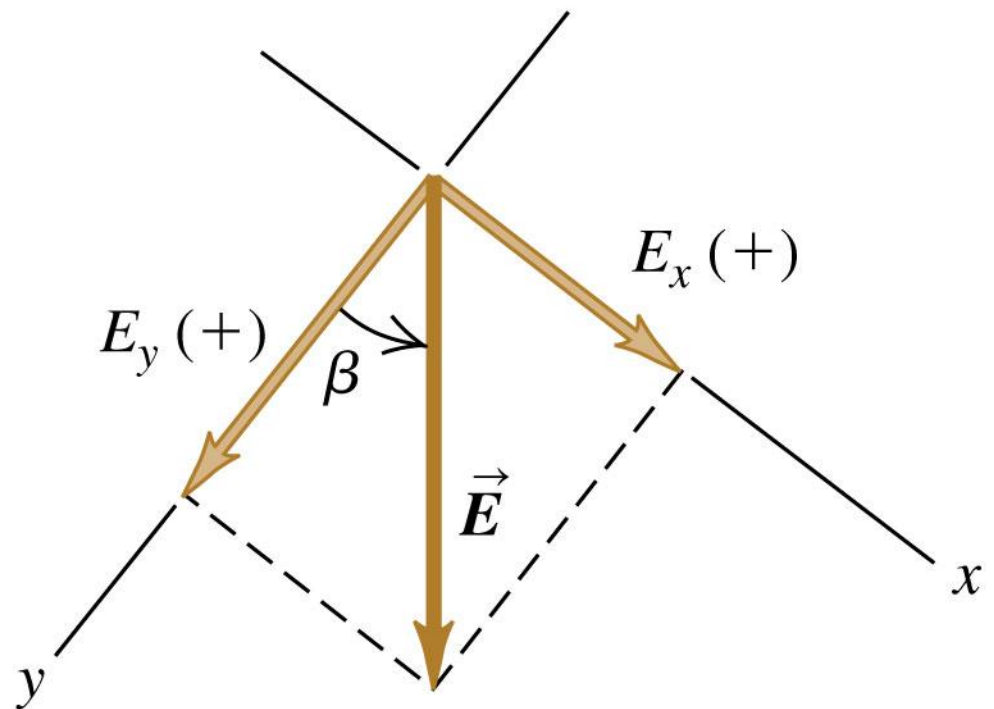


Finding components—Figure 1.19

(a)



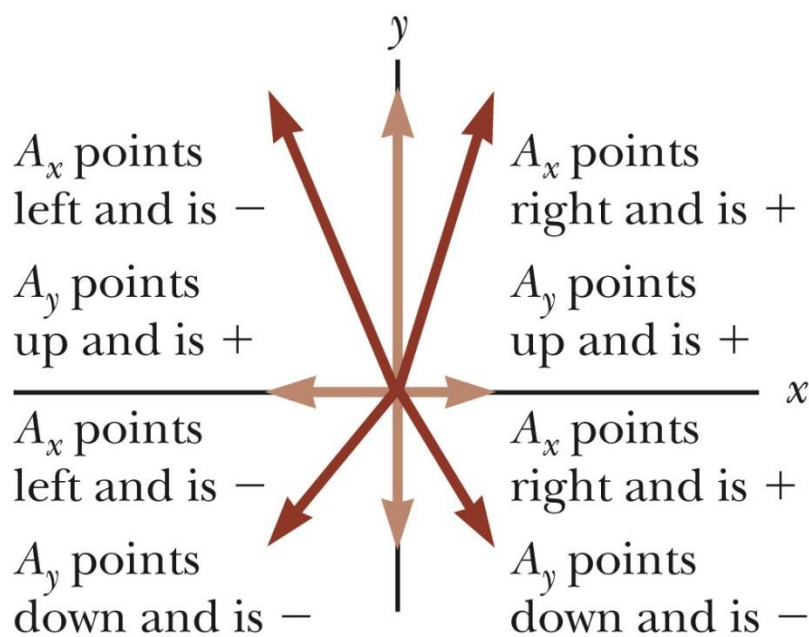
(b)



Components of a Vector, final

The components can be positive or negative

The signs of the components will depend on the angle



A_x negative	A_x positive
A_y positive	A_y positive
A_x negative	A_x positive
A_y negative	A_y negative

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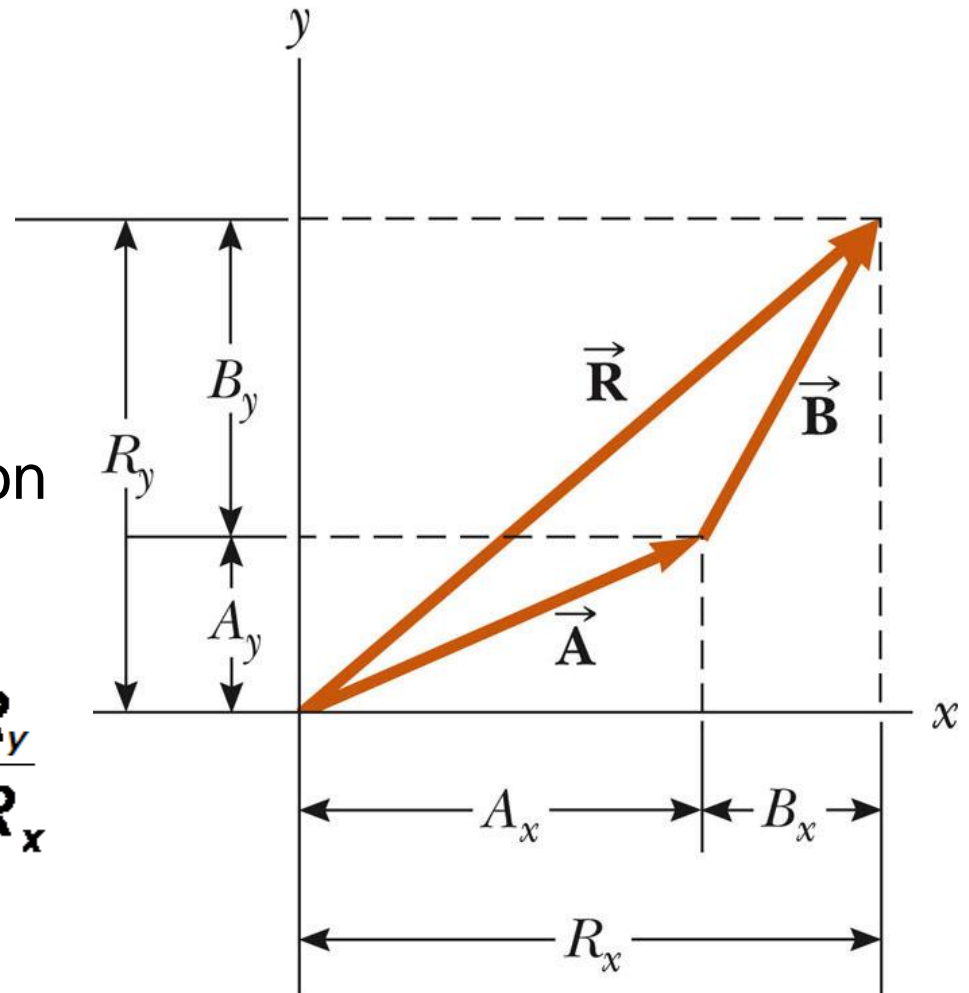
Adding Two Vectors Using Their Components

$$R_x = A_x + B_x$$

$$R_y = A_y + B_y$$

The magnitude and direction of resultant vectors are:

$$R = \sqrt{R_x^2 + R_y^2} \quad \theta = \tan^{-1} \frac{R_y}{R_x}$$



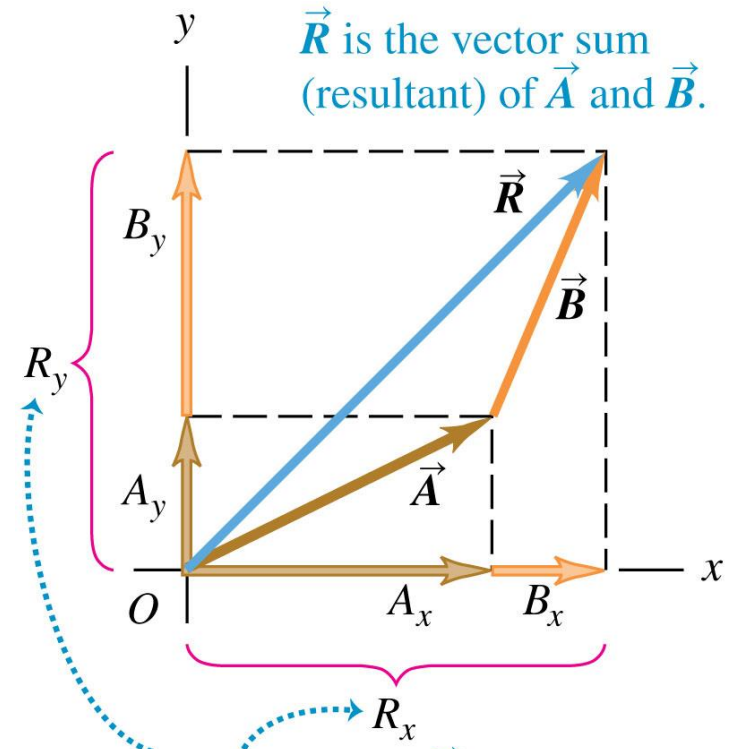
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Adding vectors using their components

- For more than two vectors we can use the components of a set of vectors to find the components of their sum:

$$R_x = A_x + B_x + C_x + \dots, \quad R_y = A_y + B_y + C_y + \dots$$

$$R = \sqrt{R_x^2 + R_y^2} \quad \theta = \tan^{-1} \frac{R_y}{R_x}$$

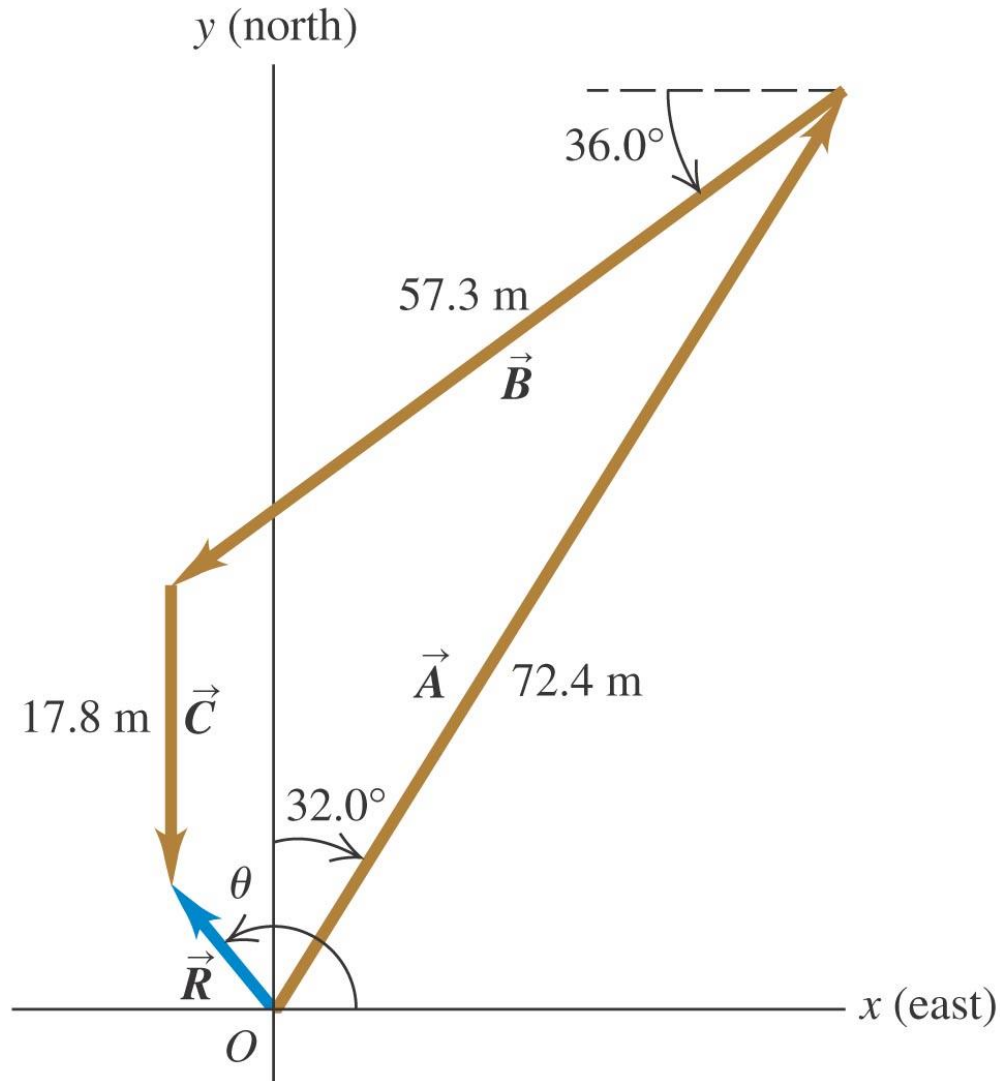


\vec{R} is the vector sum (resultant) of \vec{A} and \vec{B} .

The components of \vec{R} are the sums of the components of \vec{A} and \vec{B} :

$$R_y = A_y + B_y \quad R_x = A_x + B_x$$

Adding vectors using their components—Ex. 2



Example 2

$$A_x = 72.4 \cos 58^\circ = 38.37$$

$$A_y = 72.4 \sin 58^\circ = 61.40$$

$$B_x = 57.3 \cos 216^\circ = -46.36$$

$$B_y = 57.3 \sin 216^\circ = -33.68$$

$$C_x = 17.8 \cos 270^\circ = 0$$

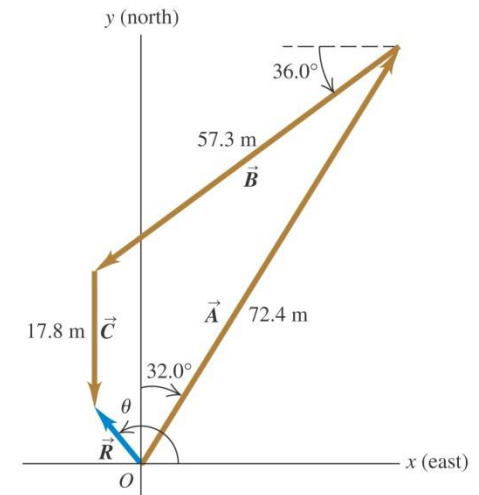
$$A_y = 17.8 \sin 270^\circ = -17.8$$

$$R_x = 38.37 - 46.36 + 0 = -8.00$$

$$R_y = 61.4 - 33.68 - 17.8 = 9.92$$

$$R = \sqrt{(-8)^2 + 9.92^2} = 12.7$$

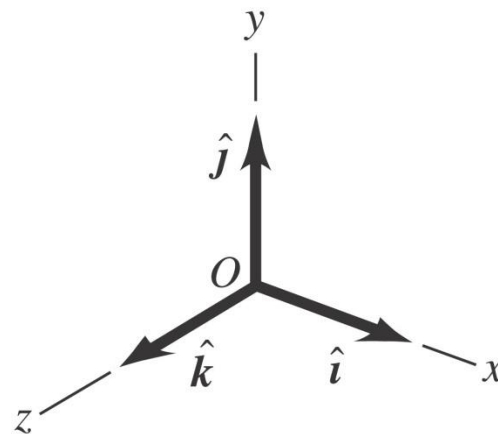
$$\theta = 180^\circ - \tan^{-1} \frac{9.92}{8.00} = 129^\circ$$



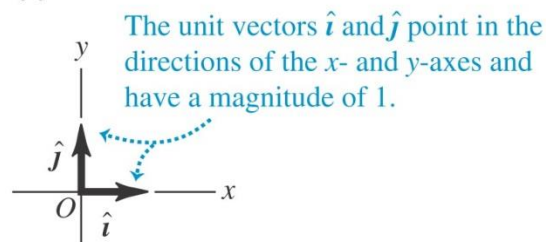
second quadrant

Unit vectors

- A *unit vector* has a magnitude of 1 with no units.
- The unit vector \hat{i} points in the $+x$ -direction, \hat{j} points in the $+y$ -direction, and \hat{k} points in the $+z$ -direction.
- Any vector can be expressed in terms of its components as $\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$

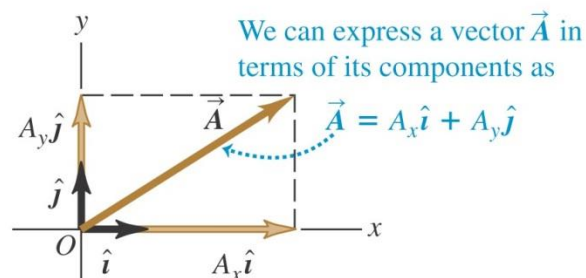


(a)



The unit vectors \hat{i} and \hat{j} point in the directions of the x - and y -axes and have a magnitude of 1.

(b)



We can express a vector \vec{A} in terms of its components as

$$\vec{A} = A_x \hat{i} + A_y \hat{j}$$

Adding vectors using unit-vector notation

In three dimensions if $\vec{\mathbf{R}} = \vec{\mathbf{A}} + \vec{\mathbf{B}}$

then $\vec{\mathbf{R}} = (A_x \hat{\mathbf{i}} + A_y \hat{\mathbf{j}} + A_z \hat{\mathbf{k}}) + (B_x \hat{\mathbf{i}} + B_y \hat{\mathbf{j}} + B_z \hat{\mathbf{k}})$

$$\vec{\mathbf{R}} = (A_x + B_x) \hat{\mathbf{i}} + (A_y + B_y) \hat{\mathbf{j}} + (A_z + B_z) \hat{\mathbf{k}}$$

$$\vec{\mathbf{R}} = R_x \hat{\mathbf{i}} + R_y \hat{\mathbf{j}} + R_z \hat{\mathbf{k}}$$

$$R = \sqrt{R_x^2 + R_y^2 + R_z^2} \quad \theta = \cos^{-1} \frac{R_x}{R}, \text{ etc.}$$

and so $R_x = A_x + B_x$, $R_y = A_y + B_y$, and $R_z = A_z + B_z$

Unit vector notation , adding vectors

In two dimensions, if $\vec{R} = \vec{A} + \vec{B}$

then

$$\vec{R} = (A_x \hat{i} + A_y \hat{j}) + (B_x \hat{i} + B_y \hat{j})$$

$$\vec{R} = (A_x + B_x) \hat{i} + (A_y + B_y) \hat{j} \quad \vec{R} = R_x \hat{i} + R_y \hat{j}$$

and so $R_x = A_x + B_x$, $R_y = A_y + B_y$,

The magnitude and direction are

$$R = \sqrt{R_x^2 + R_y^2} \quad \theta = \tan^{-1} \frac{R_y}{R_x}$$

Example 3

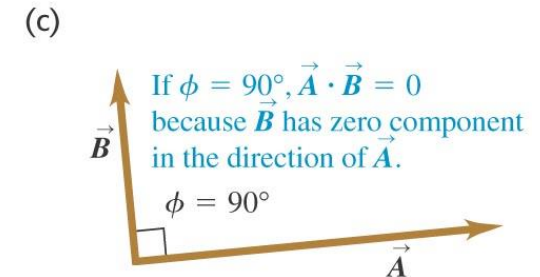
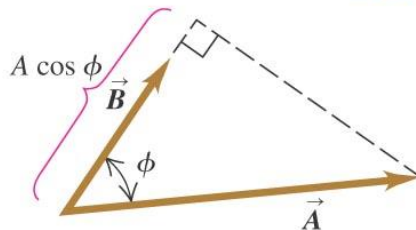
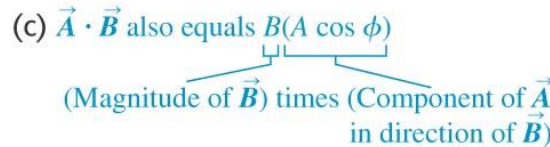
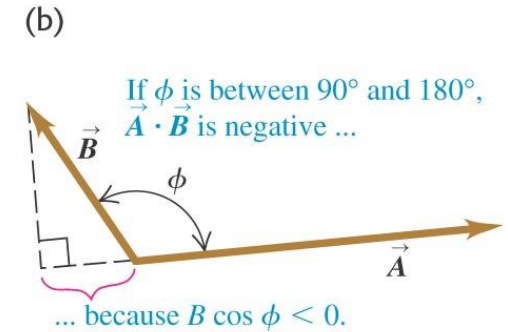
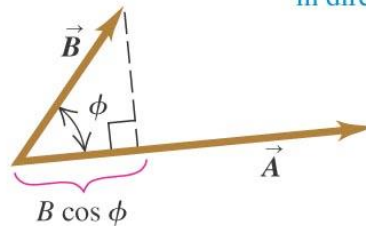
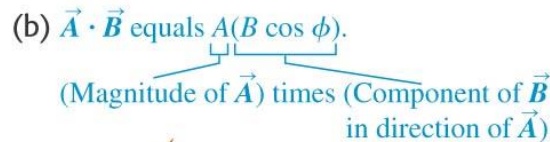
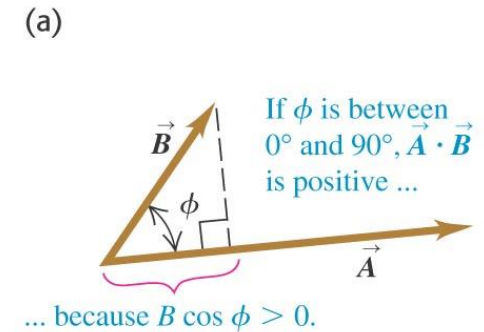
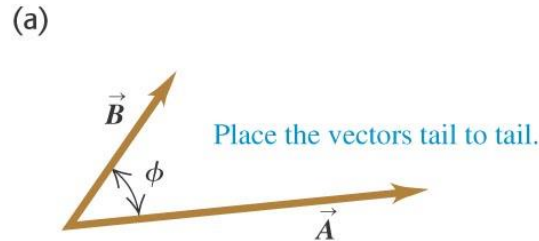
If $\mathbf{A} = 24\mathbf{i} - 32\mathbf{j}$ and $\mathbf{B} = 24\mathbf{i} + 10\mathbf{j}$, what is the magnitude and direction of the vector $\mathbf{C} = \mathbf{A} - \mathbf{B}$?

The scalar product

- The *scalar product* (also called the “dot product”) of two vectors is

$$\vec{A} \cdot \vec{B} = AB \cos \phi.$$

- Figures illustrate the scalar product.



Dot Products of Unit Vectors

$$\hat{\mathbf{i}} \cdot \hat{\mathbf{i}} = \hat{\mathbf{j}} \cdot \hat{\mathbf{j}} = \hat{\mathbf{k}} \cdot \hat{\mathbf{k}} = 1$$

$$\hat{\mathbf{i}} \cdot \hat{\mathbf{j}} = \hat{\mathbf{i}} \cdot \hat{\mathbf{k}} = \hat{\mathbf{j}} \cdot \hat{\mathbf{k}} = 0$$

Using component form with vectors:

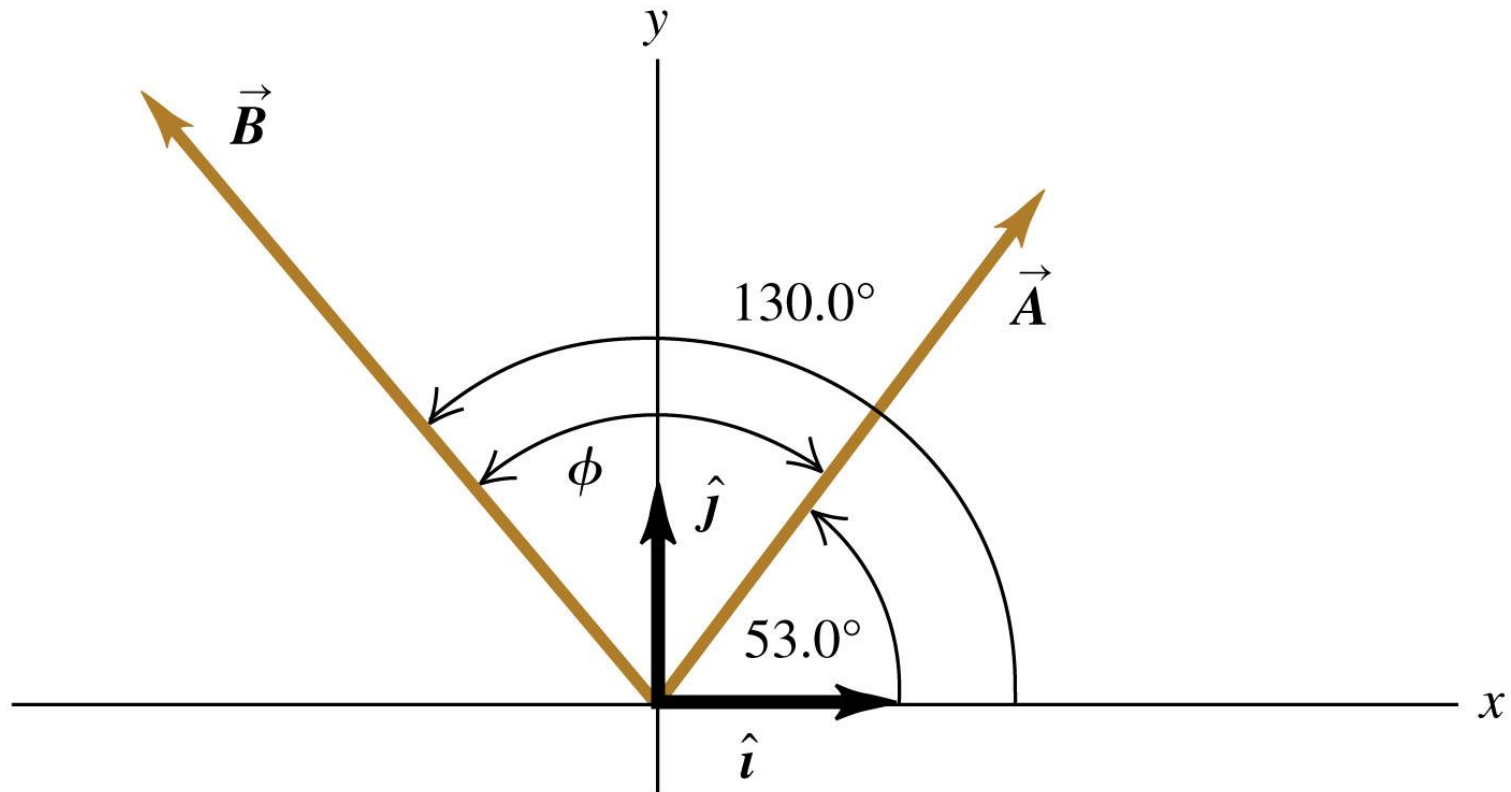
$$\vec{\mathbf{A}} = A_x \hat{\mathbf{i}} + A_y \hat{\mathbf{j}} + A_z \hat{\mathbf{k}}$$

$$\vec{\mathbf{B}} = B_x \hat{\mathbf{i}} + B_y \hat{\mathbf{j}} + B_z \hat{\mathbf{k}}$$

$$\vec{\mathbf{A}} \cdot \vec{\mathbf{B}} = A_x B_x + A_y B_y + A_z B_z$$

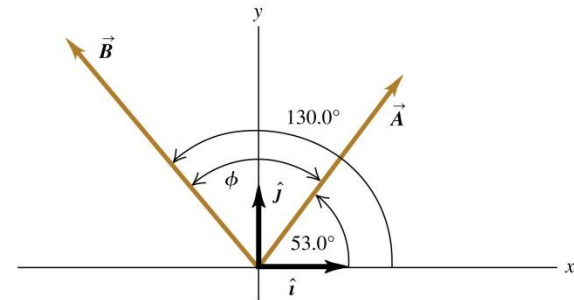
Calculating a scalar product

- $\vec{\mathbf{A}} \cdot \vec{\mathbf{B}} = AB \cos \phi.$ $\vec{\mathbf{A}} \cdot \vec{\mathbf{B}} = A_x B_x + A_y B_y + A_z B_z.$
- Find the scalar product $\vec{\mathbf{A}} \cdot \vec{\mathbf{B}}$ of two vectors shown in the figure. The magnitudes of the vectors are: $A = 4.00$, and $B = 5.00$



Calculating a scalar product – Example 4

- $\vec{\mathbf{A}} \cdot \vec{\mathbf{B}} = AB \cos \phi.$ $\vec{\mathbf{A}} \cdot \vec{\mathbf{B}} = A_x B_x + A_y B_y + A_z B_z.$
- Find the scalar product $\vec{\mathbf{A}} \cdot \vec{\mathbf{B}}$ of two vectors shown in the figure. The magnitudes of the vectors are: $A = 4.00$, and $B = 5.00$



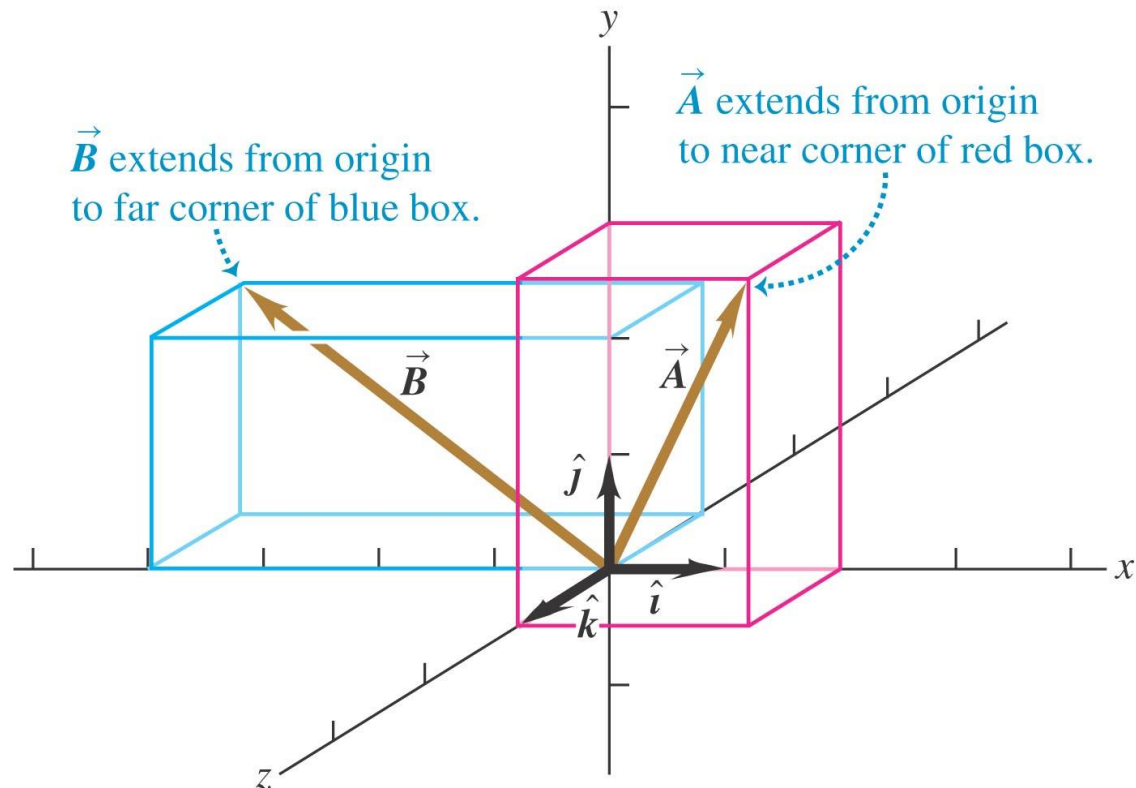
Finding an angle using the scalar product – Ex. 5

- Find the angle between the vectors.

$$\vec{A} = 2.00\hat{i} + 3.00\hat{j} + 1.00\hat{k}$$

$$\vec{B} = -4.00\hat{i} + 2.00\hat{j} - 1.00\hat{k}$$

- Use equation: $\vec{A} \cdot \vec{B} = AB \cos \phi$.



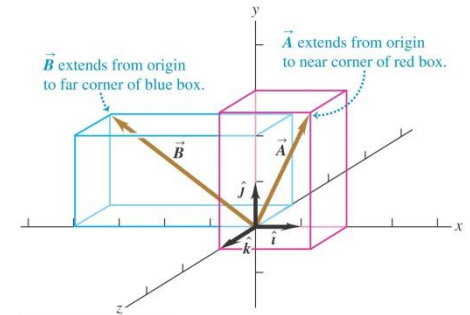
Finding an angle using the scalar product – Ex. 5

- Find the angle between the vectors.

$$\vec{A} = 2.00\hat{i} + 3.00\hat{j} + 1.00\hat{k}$$

$$\vec{B} = -4.00\hat{i} + 2.00\hat{j} - 1.00\hat{k}$$

- Use equation: $\vec{A} \cdot \vec{B} = AB \cos \phi$.



The Vector Product Defined

Given two vectors, $\vec{\mathbf{A}}$ and $\vec{\mathbf{B}}$

The vector (cross) product of $\vec{\mathbf{A}}$ and $\vec{\mathbf{B}}$ is defined as a *third vector*, $\vec{\mathbf{C}} = \vec{\mathbf{A}} \times \vec{\mathbf{B}}$

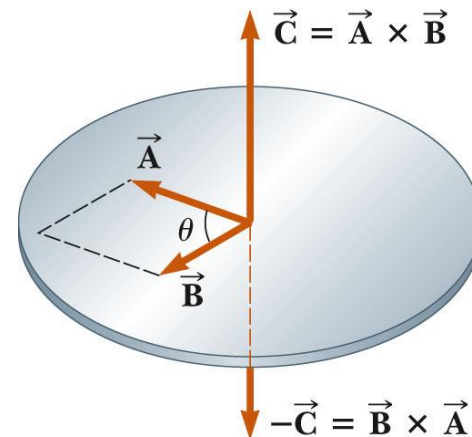
The magnitude of vector C is $AB \sin \theta$

- θ is the angle between $\vec{\mathbf{A}}$ and $\vec{\mathbf{B}}$

More About the Vector Product

The direction of \vec{C} is perpendicular to the plane formed by \vec{A} and \vec{B}

The best way to determine this direction is to use the right-hand rule



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Right-hand rule



Using Determinants

The components of cross product can be calculated as

$$\vec{\mathbf{A}} \times \vec{\mathbf{B}} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix} = \begin{vmatrix} A_y & A_z \\ B_y & B_z \end{vmatrix} \hat{\mathbf{i}} - \begin{vmatrix} A_x & A_z \\ B_x & B_z \end{vmatrix} \hat{\mathbf{j}} + \begin{vmatrix} A_x & A_y \\ B_x & B_y \end{vmatrix} \hat{\mathbf{k}}$$

Expanding the determinants gives

$$\vec{\mathbf{A}} \times \vec{\mathbf{B}} = (A_y B_z - A_z B_y) \hat{\mathbf{i}} - (A_x B_z - A_z B_x) \hat{\mathbf{j}} + (A_x B_y - A_y B_x) \hat{\mathbf{k}}$$

If $A_z = 0$ and $B_z = 0$ then

$$\vec{\mathbf{A}} \times \vec{\mathbf{B}} = (A_x B_y - A_y B_x) \hat{\mathbf{k}}$$

=

Vector Product Example 6

Given $\vec{\mathbf{A}} = 2\hat{\mathbf{i}} + 3\hat{\mathbf{j}}; \vec{\mathbf{B}} = -\hat{\mathbf{i}} + 2\hat{\mathbf{j}}$

Find $\vec{\mathbf{A}} \times \vec{\mathbf{B}} = (A_x B_y - A_y B_x) \hat{\mathbf{k}}$

Result $\vec{\mathbf{A}} \times \vec{\mathbf{B}} = (2\hat{\mathbf{i}} + 3\hat{\mathbf{j}}) \times (-\hat{\mathbf{i}} + 2\hat{\mathbf{j}}) = [2*2 - 3*(-1)] \hat{\mathbf{k}} = 7\hat{\mathbf{k}}$

=

The vector product—Summary

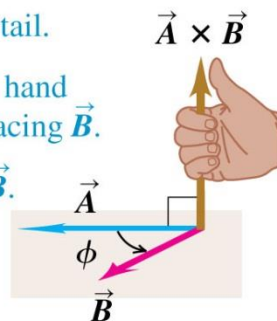
- The vector product (“cross product”) of two vectors has magnitude

$$|\vec{A} \times \vec{B}| = AB \sin \phi$$

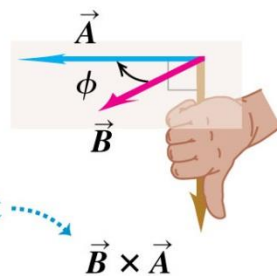
and the *right-hand rule* gives its direction.

(a) Using the right-hand rule to find the direction of $\vec{A} \times \vec{B}$

- Place \vec{A} and \vec{B} tail to tail.
- Point fingers of right hand along \vec{A} , with palm facing \vec{B} .
- Curl fingers toward \vec{B} .
- Thumb points in direction of $\vec{A} \times \vec{B}$.



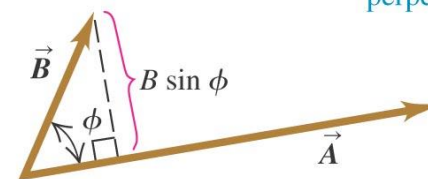
(b) $\vec{B} \times \vec{A} = -\vec{A} \times \vec{B}$ (the vector product is anticommutative)



Same magnitude but opposite direction

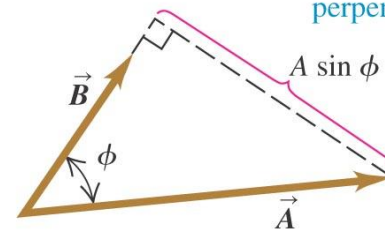
(a)

(Magnitude of $\vec{A} \times \vec{B}$) equals $A(B \sin \phi)$.
 (Magnitude of \vec{A}) times (Component of \vec{B} perpendicular to \vec{A})



(b)

(Magnitude of $\vec{A} \times \vec{B}$) also equals $B(A \sin \phi)$.
 (Magnitude of \vec{B}) times (Component of \vec{A} perpendicular to \vec{B})



Calculating the vector product— ex. 6

- Vector $\vec{\mathbf{A}}$ has magnitude 6 units and is in the direction of the $+x$ axis. Vector $\vec{\mathbf{B}}$ has magnitude 4 units and lies in the xy – plane making an angle of 30° with the x axis. Find the cross product $\vec{\mathbf{A}} \times \vec{\mathbf{B}}$

Use $AB\sin\phi$ to find the magnitude and the right-hand rule to find the direction.

