Vector-based navigation using grid-like representations in artificial agents

Andrea Banino, Caswell Barry, Benigno Uria, Charles Blundell, Timothy Lillicrap, Piotr Mirowski, Alexander Pritzel, Martin Chadwick, Thomas Degris, Joseph Modayil, Greg Wayne, Hubert Soyer, Fabio Viola, Brian Zhang, Ross Goroshin, Neil Rabinowitz, Razvan Pascanu, Charlie Beattie, Stig Petersen, Amir Sadik, Stephen Gaffney, Helen King, Koray Kavukcuoglu, Demis Hassabis, Raia Hadsell, and Dharshan Kumaran

Presented by Roman Ring

Grid Cells

Neurons that fire up in a specific pattern

• Hexagonal activations when exploring environment

Located in the entorhinal cortex

- *"Interface" for neo-cortex and hippocampus*
- Used for memory, navigation, time perception
- Crucial discovery in multiple fields
 2014 Nobel Prize in Physiology or Medicine

Grid Cells in Rodents



Mental Maps

Researchers are studying how brain cells in the entorhinal cortex help rats and other mammals build maps of the environment.

A RANDOM WALK

At left, gray lines show the rat's path as it moves around a box eating pieces of food.

IMPOSING A PATTERN

Grid cells in the rat's entorhinal cortex fire when the rat moves through certain locations. The firing pattern of a single grid cell is marked here with dots. Groups of dots form a hexagonal grid, and the firing pattern persists even in darkness, when the rat cannot see where it is.

GRID CELLS

The grid cells seem to form a map of the local environment. Each grid cell, like the one enlarged at left, fires in a hexagonal pattern that helps the rat track where it is in space. Grid cells are thought to be involved with pathfinding, dead reckoning and the formation of mental maps.

THE NEW YORK TIMES

Vector-based Navigation

- Determine position and direction
 Including very noisy observations (e.g. closing eyes)
- Determine distances between objects
 Outilizing Euclidean-like metrics
- Efficiently navigate in an environment
 Find approximate shortest paths "in real time"

Artificial Agents

Brain is the best "computer" we know

• Very complex & massively parallel processing unit

Difficult to investigate hypotheses

• Even with mice experiments are very expensive

Al agents as an approximation
 Relatively fast proof of concept tests (?)

Intuitive Interpretations

Grid cells are used as a map of the world

- Special neurons fire up in a hexagonal grid
- Position self in the environment
- Extending to vectors for navigation
 - Find shortest paths with Euclidean distance
- Artificial agents used as a brain model
 Possible alternative to expensive experiments

Research Objectives

Show similarity between ANN and NN

• In the context of grid cells: positional reasoning

Train an RL agent that utilizes grid cells

• Show that it performs better with grid cells

- Extrapolate results to neuroscience
 - Show grid cells used for vector-based navigation



Showing NN & ANN similarity Based on activations in rodent brains

Artificial Neural Networks

Non-linear function approximators

- Approximate any function with some assumptions
- Very crude model for the actual neurons
 Still using McCulloch-Pitts model from the 50s
- Reccurent ANNs for temporal data
 Hidden state that can add info or "forget" it

Objective: Show Similarity

Generate training data from rat models

- Input: place cells + head direction
- Output: next place cell + head direction
- Train an ANN on the data (supervised)
 Recurrent + Linear + Softmax
- Compare ANN outputs to rat models
 Both visually (via spatial maps) and statistically

ANN Architecture

Small Recurrent ANN

- LSTM with 128 unit hidden cell
- Linear layer with 512 units (no activation!)
- Output heads: offset vector and angle activations
- Probability distribution via softmax
- No special tricks involved
 - Important since goal is to show similarity

ANN Architecture

Generating Training Data

Position centers uniformly sampled

• From some fixed box dimensions

Place activations via 2D Normal distribution

- With fixed mean and standard deviation
- Direction angle via Von Mises distribution
 - With fixed concentration parameters

Emergence of Grid Cells

Artificial (Agent)

Biological (Rat)

Our experiments with artificial agents yielded grid-like representations ("grid units") that were strikingly similar to biological grid cells in foraging mammals.

Training a DRL agent

A3C agent with grid cells navigating in a maze

Deep Reinforcement Learning

- General framework for decision making
 - Evaluate behavior with some reward signal
- Policy is the expected output of training
 A mapping from states to actions
- Algorithms differ by optimization target
 - Value based, policy based, actor-critic hybrids
 - A3C: Asynchronous Actor-Critic Agent

Objective: Train a DRL Agent

- Re-use network trained in previous step
 - Add some noise in the inputs for generalization
- Use "grid cells" network as an encoder
 - Pipe into a much larger network
- Evaluate ability to navigate in mazes
 - Trained with A3C algorithm

DRL Agent Architecture

DRL Agent Navigating

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Effect of Grid Cells

Effect of Grid Cells

Extrapolating to Neuroscience

Emergence of vector-based navigation from grid cells

Objective: Extrapolate Results

- Grid cells emerged in artificial agents
- Disabling grid cells hindered navigation
 - Agent performed significantly worse in known tasks
 - Agent failed to generalize to new tasks
- We can extrapolate that grid cells used for vector-based navigation (in mammals)

Conclusion

Shown emergence of grid cells in ANNs

• Similar activation patterns to rodent models

Utilized grid cells to train an RL agent

• Outperforming agents without grid cells

- Shown use of vector-based navigation
 - Assuming model is correct, can extrapolate that similar patterns emerge in actual grid cells

Recap by DeepMind

References & Related Work

- Microstructure of a spatial map in the entorhinal cortex
- Crystals of the brain
- A Model of the Ventral Visual System Based on Temporal Stability and Local Memory
- Slowness and Sparseness Lead to Place, Head-Direction, and Spatial-View Cells
- Navigating with grid-like representations in artificial agents
- Emergence of grid-like representations by training recurrent neural networks to perform spatial localization